

Search-Based Software Engineering

Search-based Testing

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Lehrstuhl für Software Engineering II

Alternating Variable Method

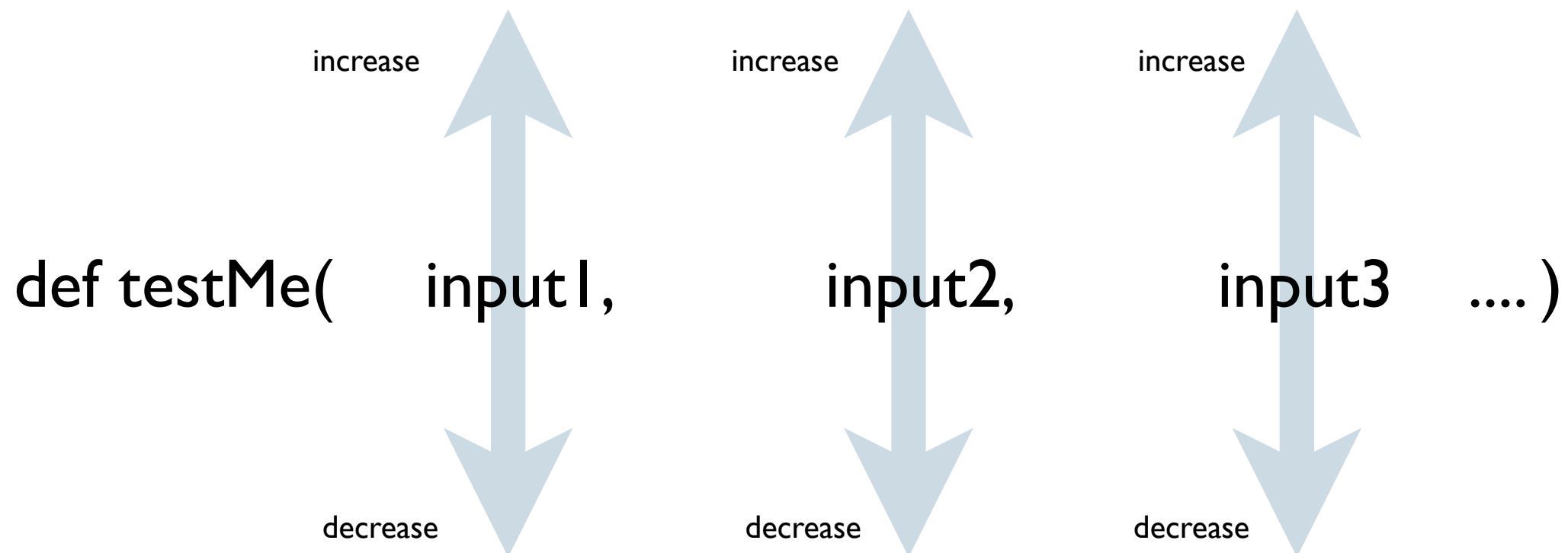
Alternating Variable Method

```
def testMe(x, y, z):  
    if x * z == 2 * (y + 1):  
        return True  
    else:  
        return False
```

Example: Hill climbing applied to the testMe function

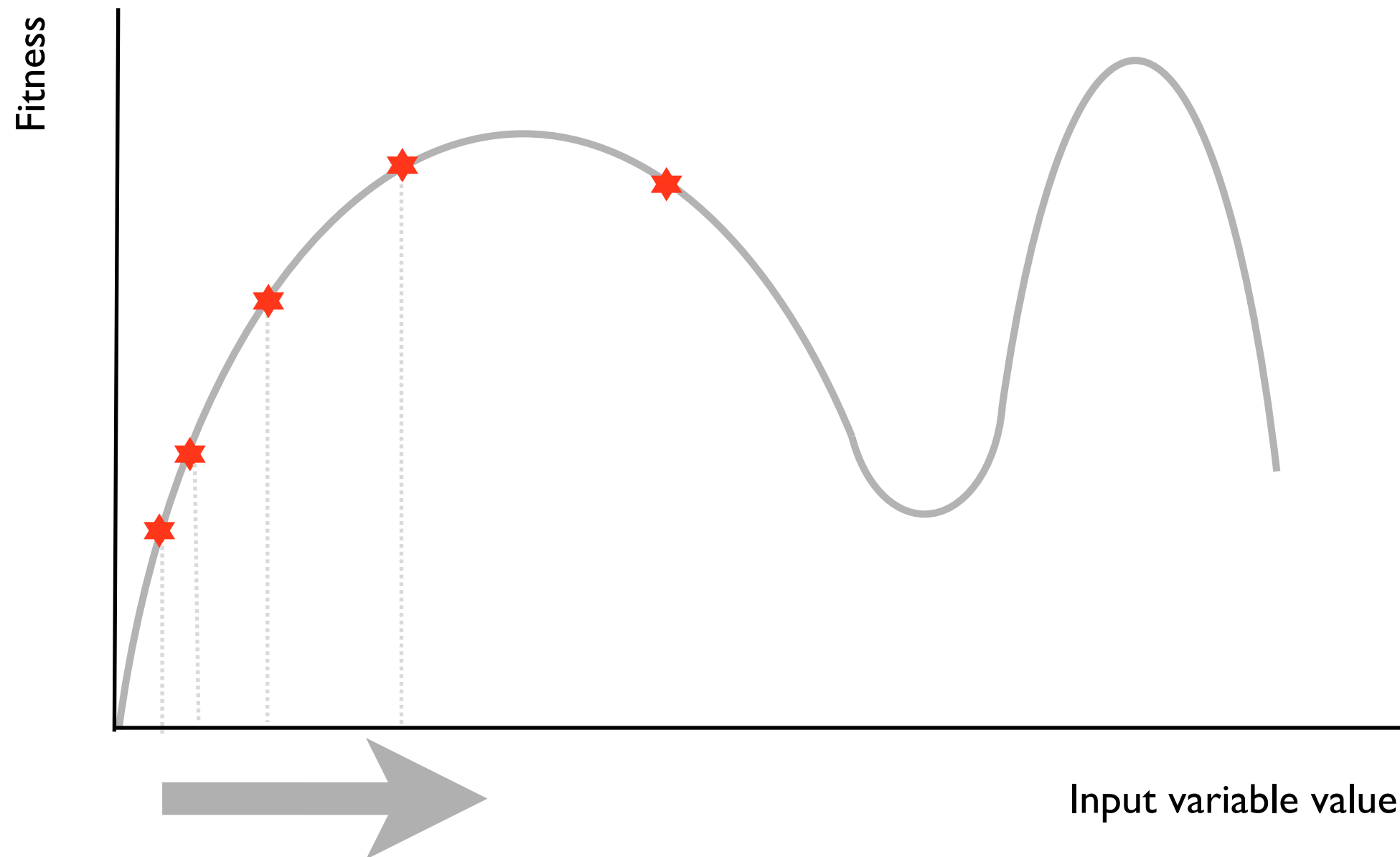
Alternating Variable Method

‘Probe’ moves



Alternating Variable Method

Accelerated hill climb



Alternating Variable Method

1. Randomly generate start point

a=10, b=20, c=30

2. 'Probe' moves on a

a=9, b=20, c=30

a=11, b=20, c=30

no effect

3. 'Probe' moves on b

a=10, b=19, c=30

improved
fitness

4. Accelerated moves in
direction of improvement

```
void example(int a, int b, ...) {  
    if (a == 0) {  
        ...  
    }  
  
    if (b == 0) {  
        // target  
    }  
  
    ...  
}
```

```
def testMe(x, y, z):  
    if x * z == 2 * (y + 1):  
        return True  
    else:  
        return False
```

Example: AVM applied to the testMe function

```
public int gcd(int x, int y) {  
    int tmp;  
    while (y != 0) {  
        tmp = x % y;  
        x = y;  
        y = tmp;  
    }  
    return x;  
}
```


public int gcd(int x, int y) {
int tmp;

while(y != 0) {

tmp = x % y;

x = y;

y = tmp;

return x; }

A

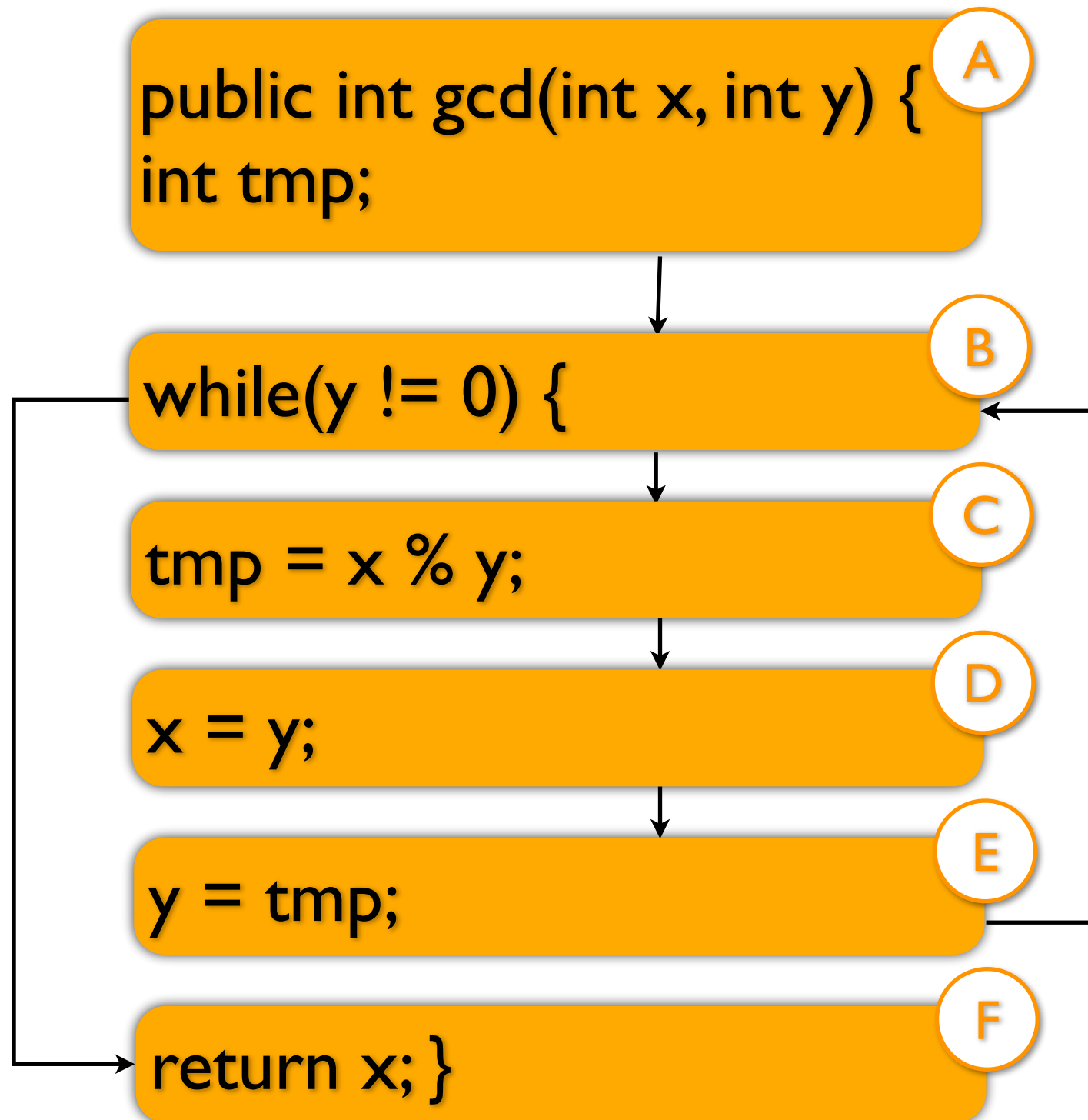
B

C

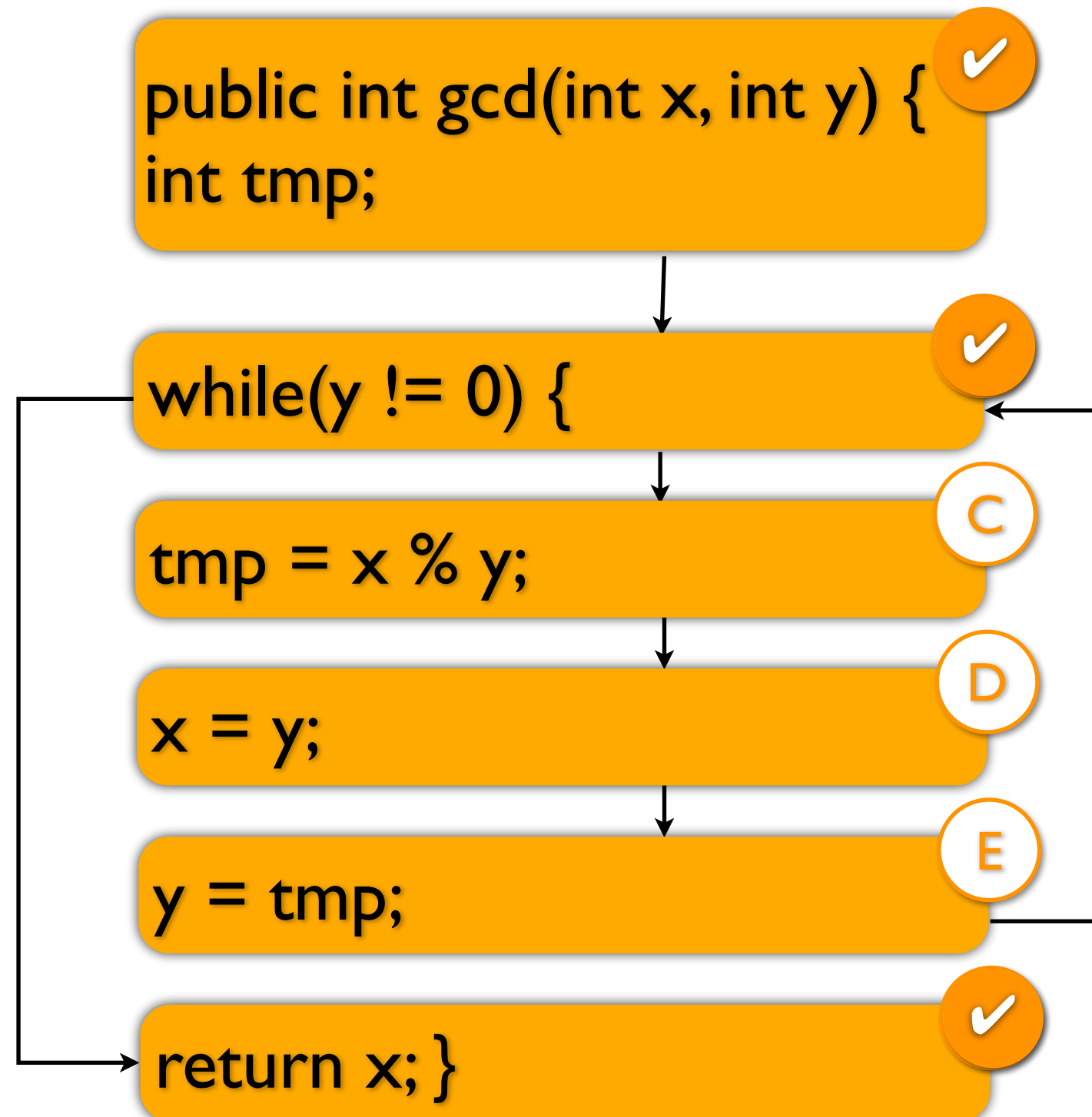
D

E

F



gcd(0, 0)



```
public int gcd(int x, int y) {  
    int tmp;
```



gcd(0, 0)

```
while(y != 0) {
```



```
    return x; }
```



Approach Level

```
    tmp = x % y;
```

C

```
    y = tmp;
```

E

```
    x = y;
```

D

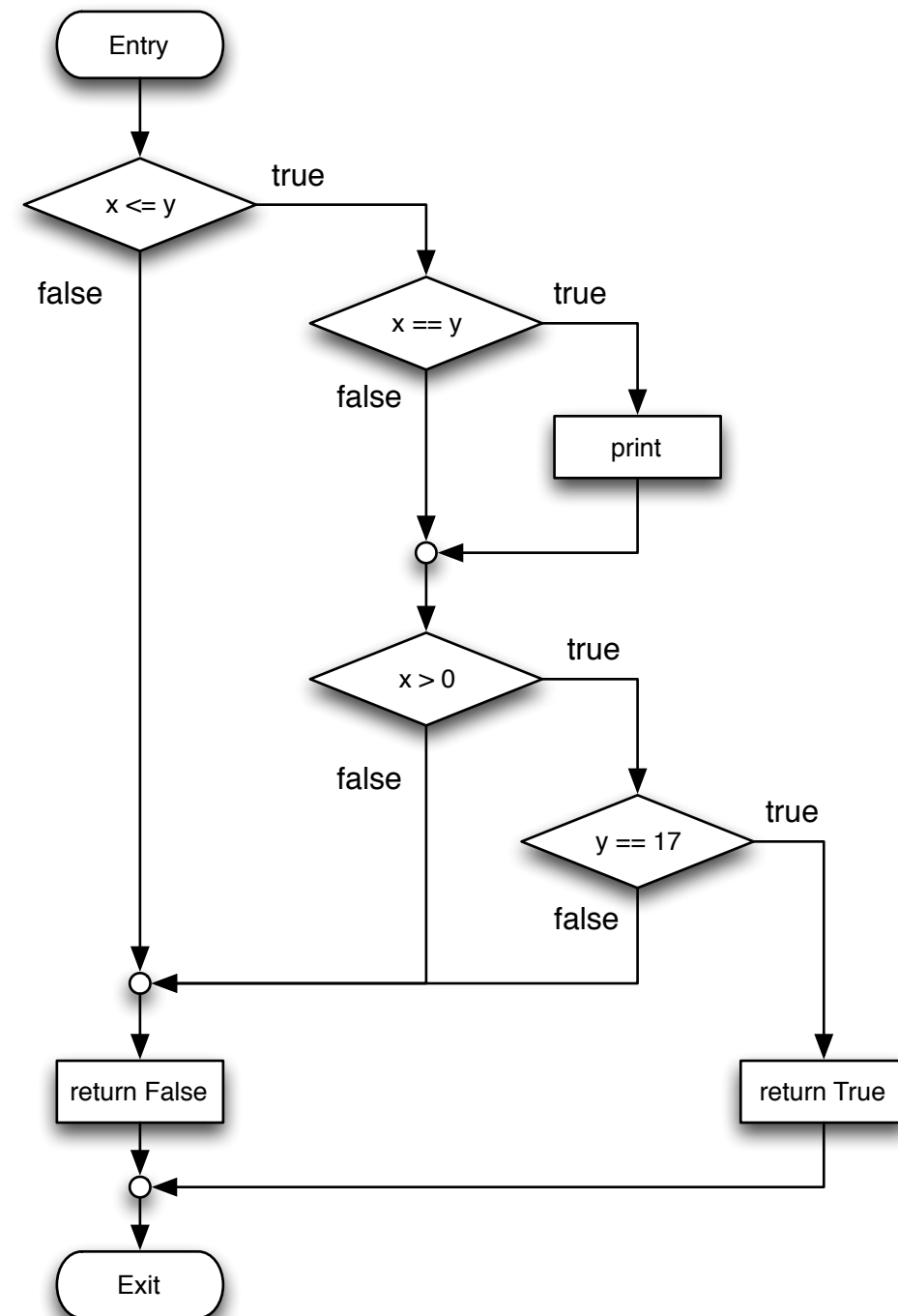


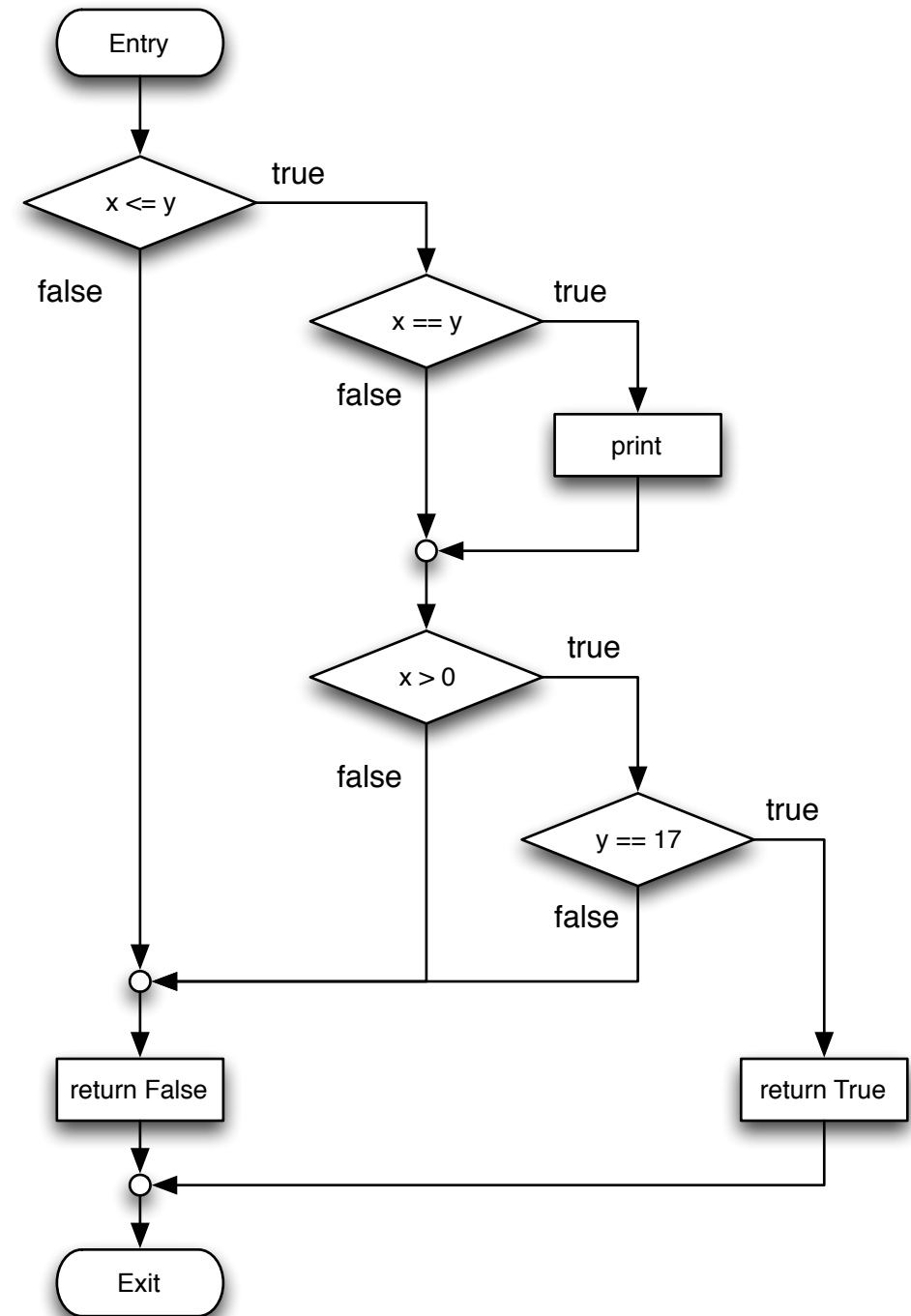
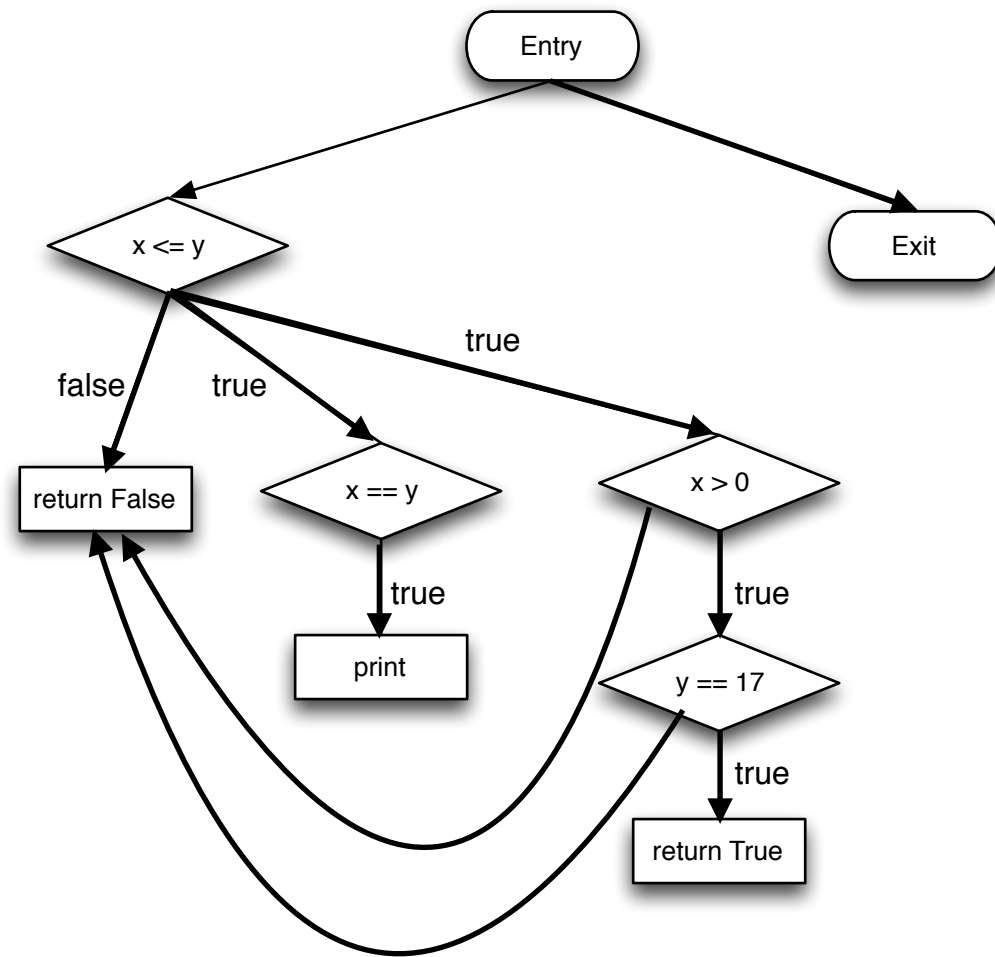
```
def testMe(x, y) :  
    if x <= y:  
        if x == y:  
            print("Some output")  
        if x > 0:  
            if y == 17:  
                # Target Branch  
                return True  
    return False
```

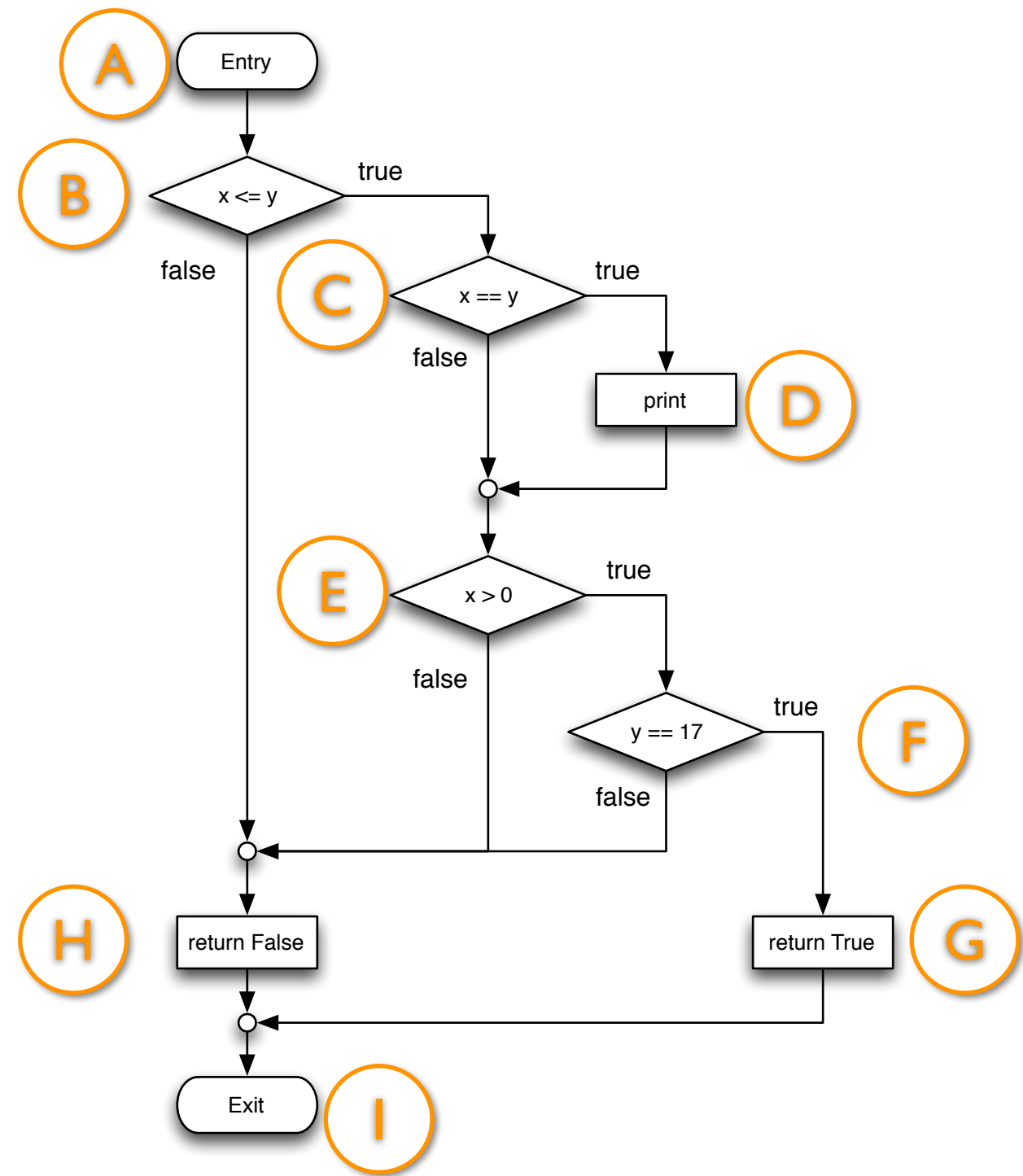
```

def testMe(x, y):
    if x <= y:
        if x == y:
            print("Some output")
        if x > 0:
            if y == 17:
                # Target Branch
                return True
    return False

```

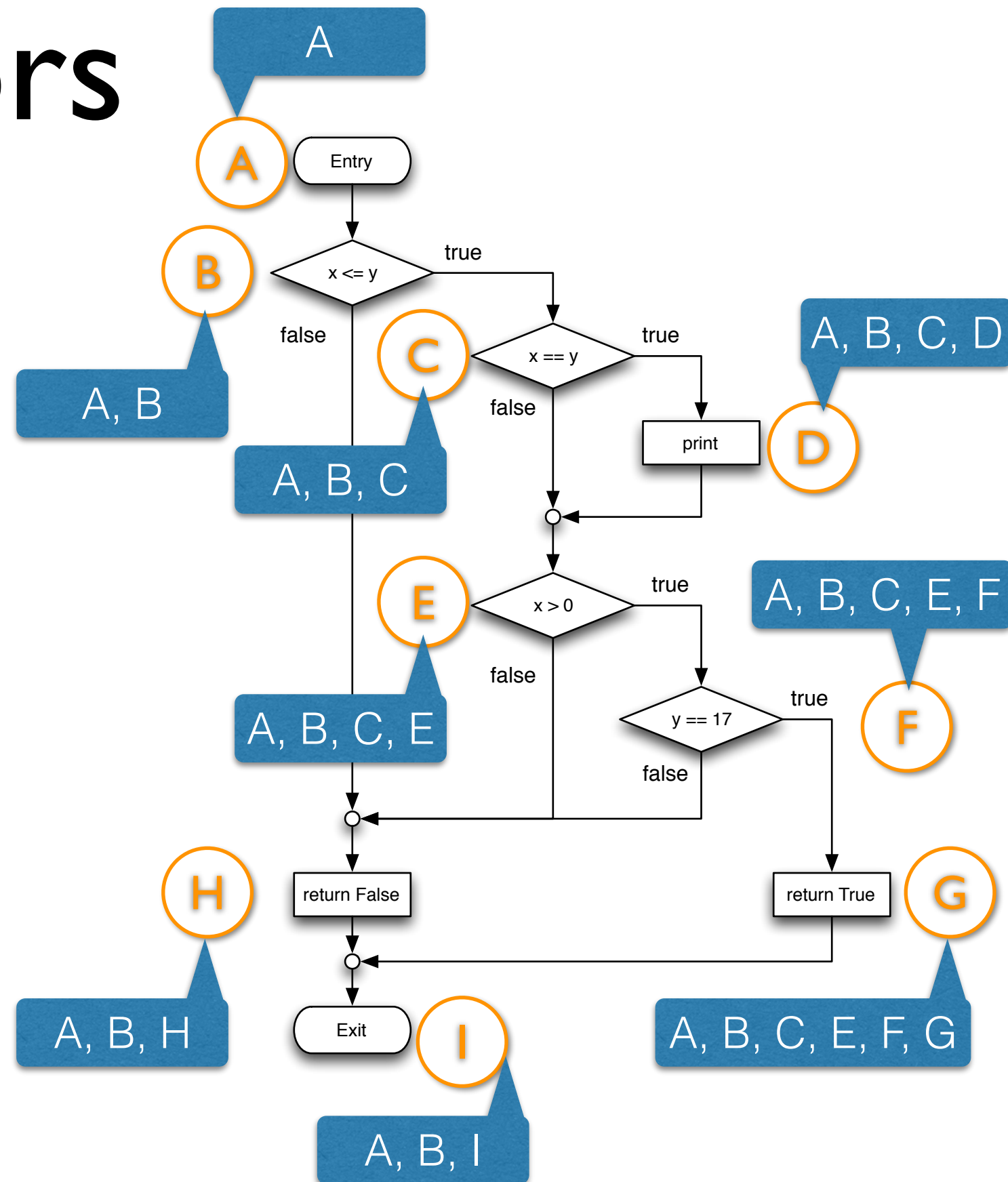






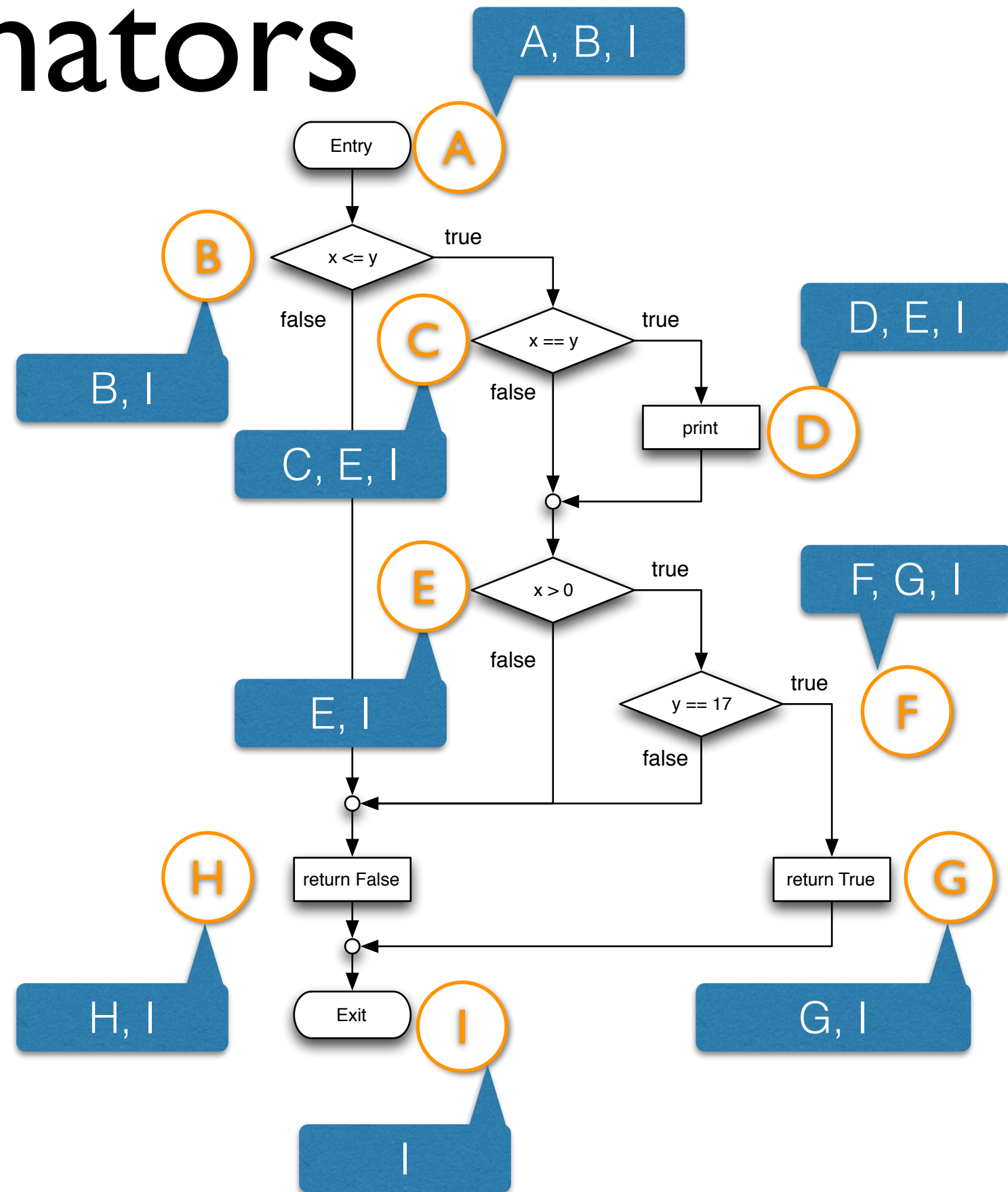
Dominators

- Node A dominates B if every path to B goes through A



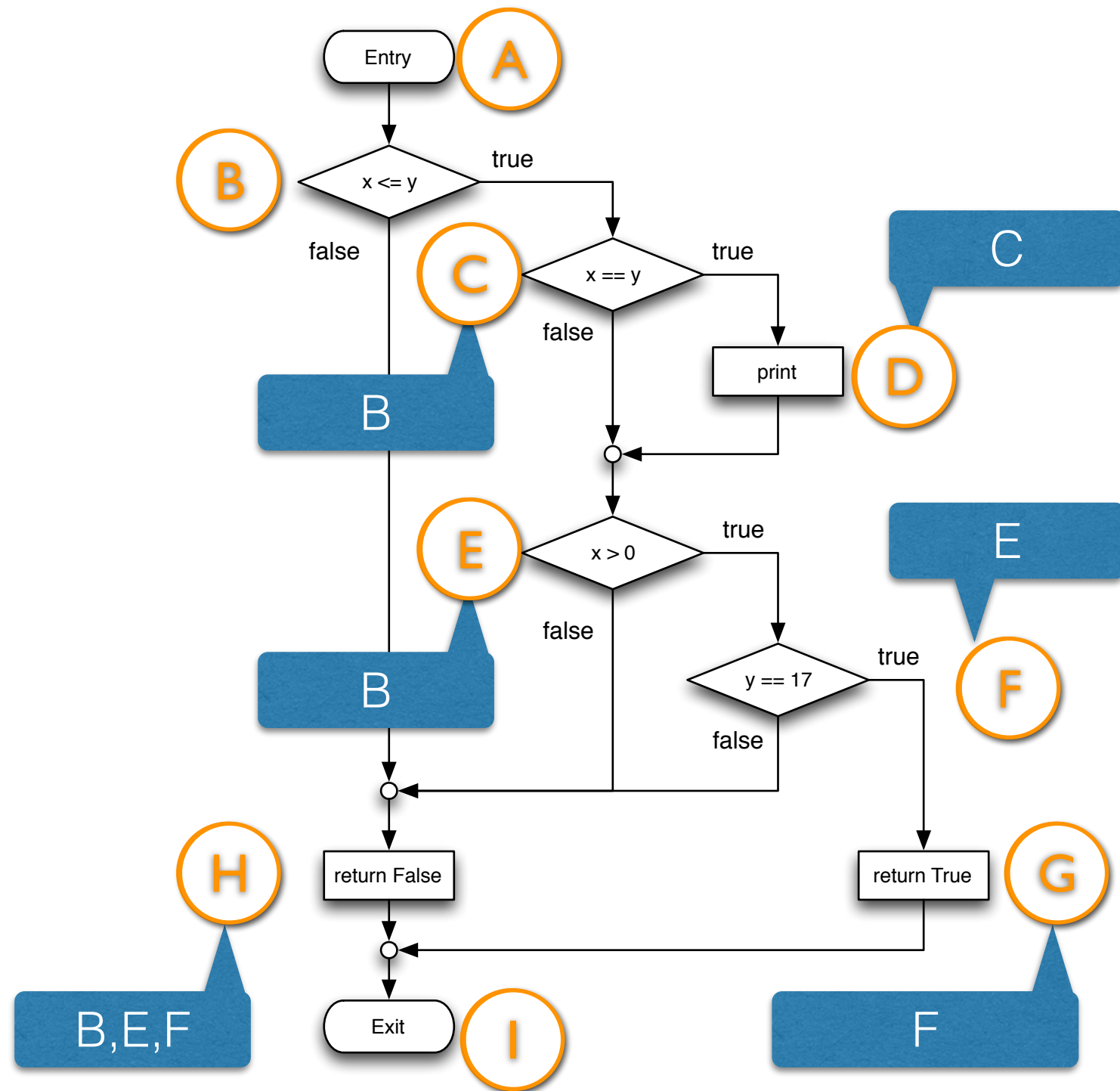
Post-Dominators

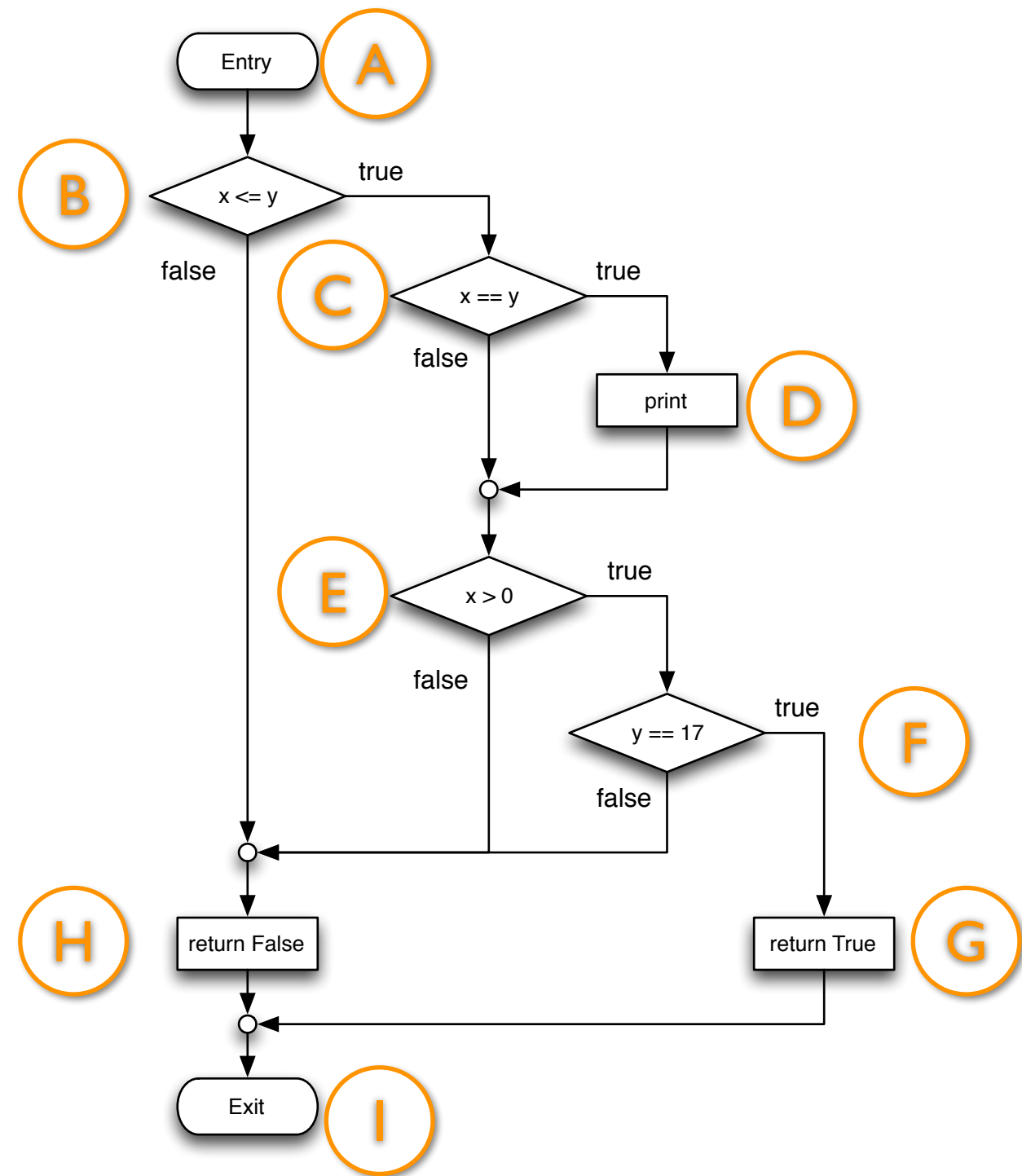
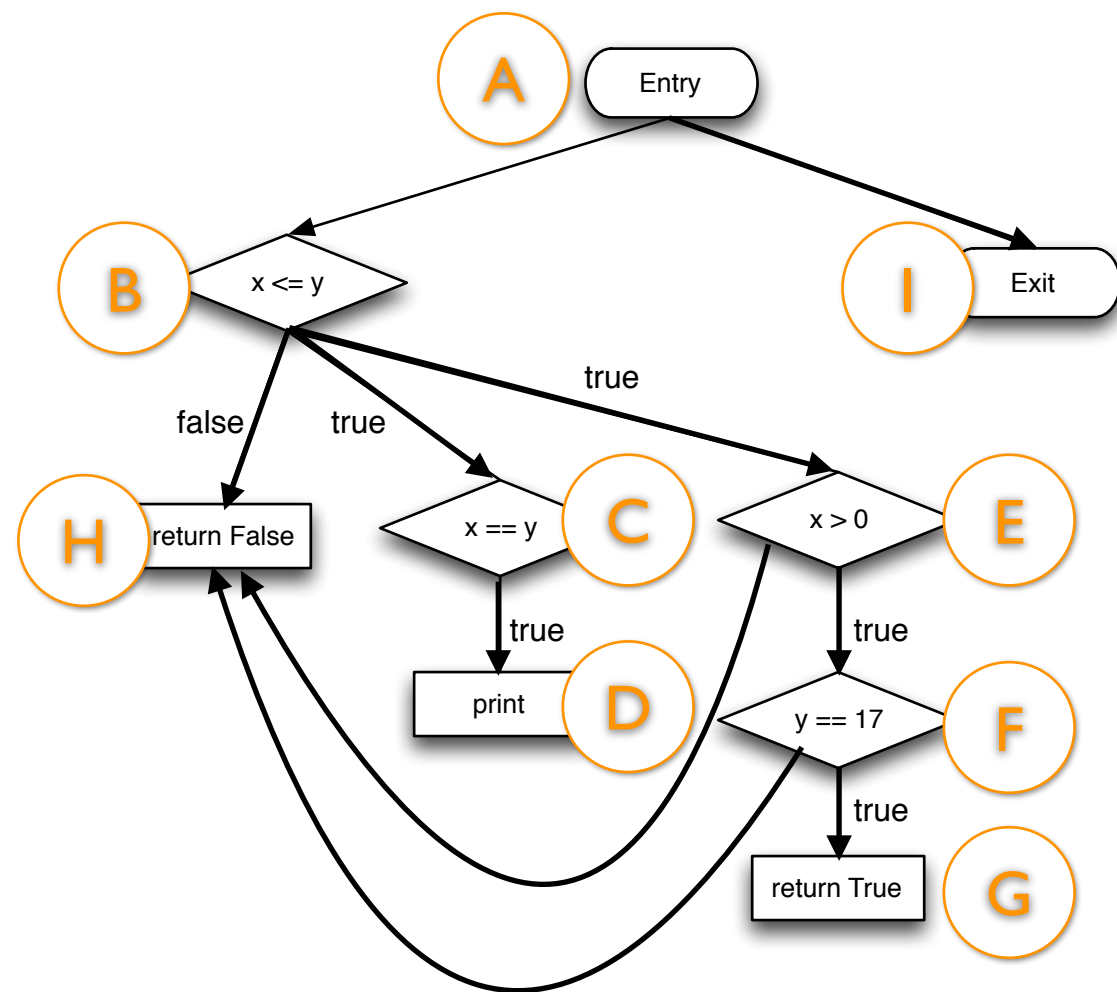
- Dominators viewed in reverse (paths from exit node)



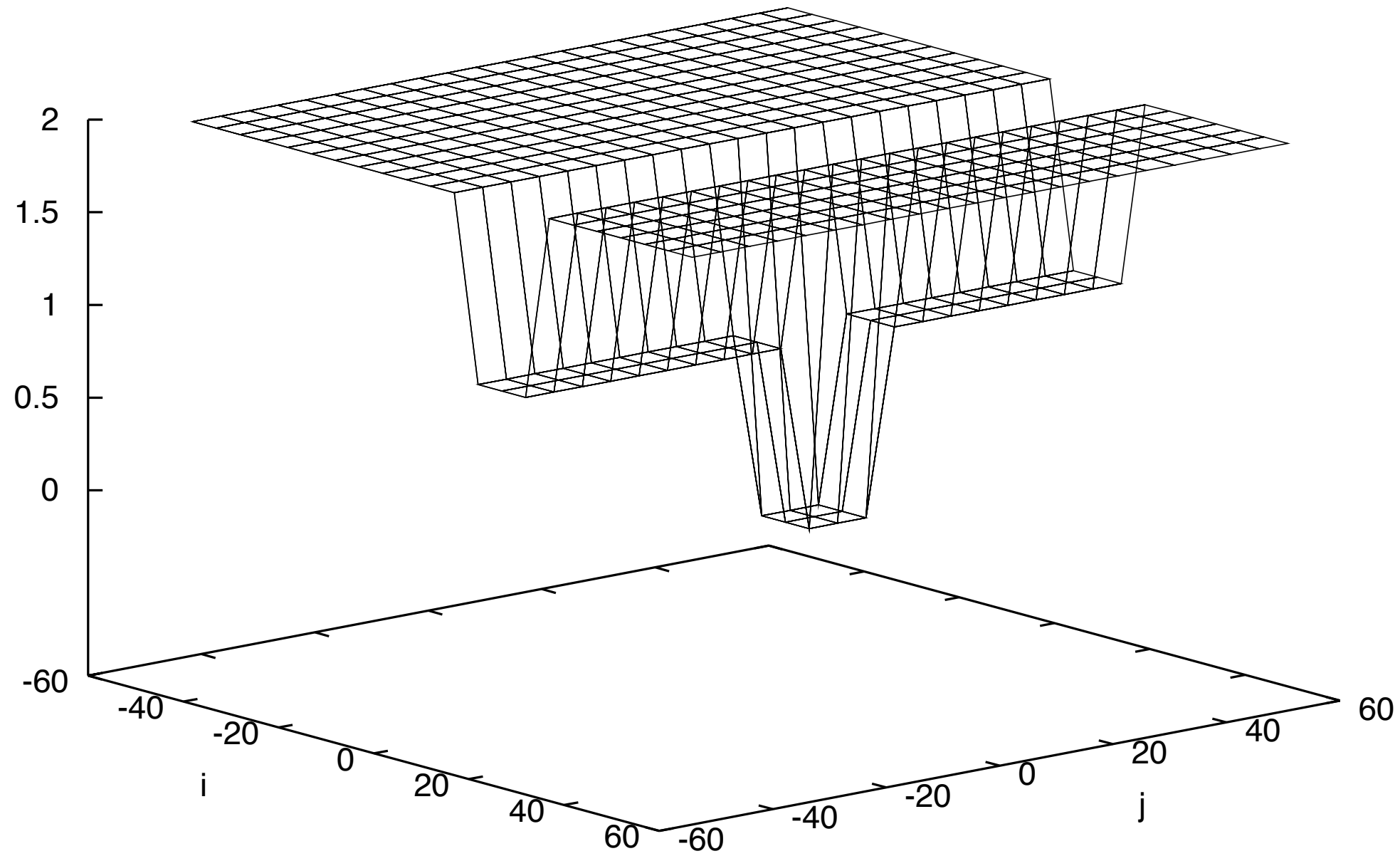
Control Dependence

- A is control dependent on B if:
- B has at least two successors in the CFG
- B dominates A
- B is not post-dominated by A
- There is a successor of B that is post-dominated by A





```
void landscape_example(int i, int j) {  
    if (i >= 10 && i <= 20) {  
        if (j >= 0 && j <= 10) {  
            // target statement  
            // ...  
        }  
    }  
}
```



```
public int gcd(int x, int y) {  
    int tmp;
```



gcd(0, 0)

```
    while(y != 0) {
```



```
        return x; }  
}
```



Approach Level

```
    tmp = x % y;
```

C

```
    y = tmp;
```

E

How close was this predicate
to being true?

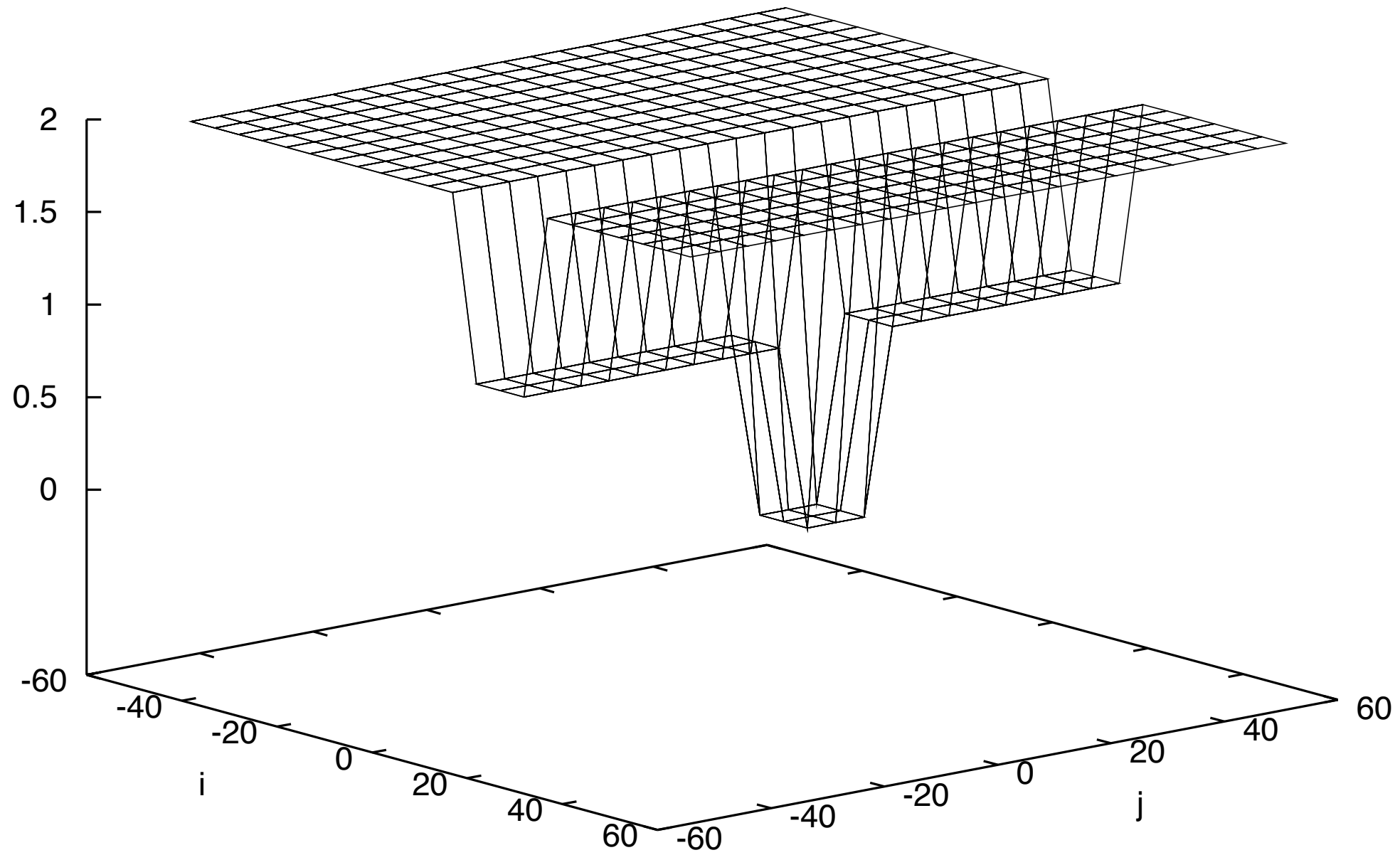
D

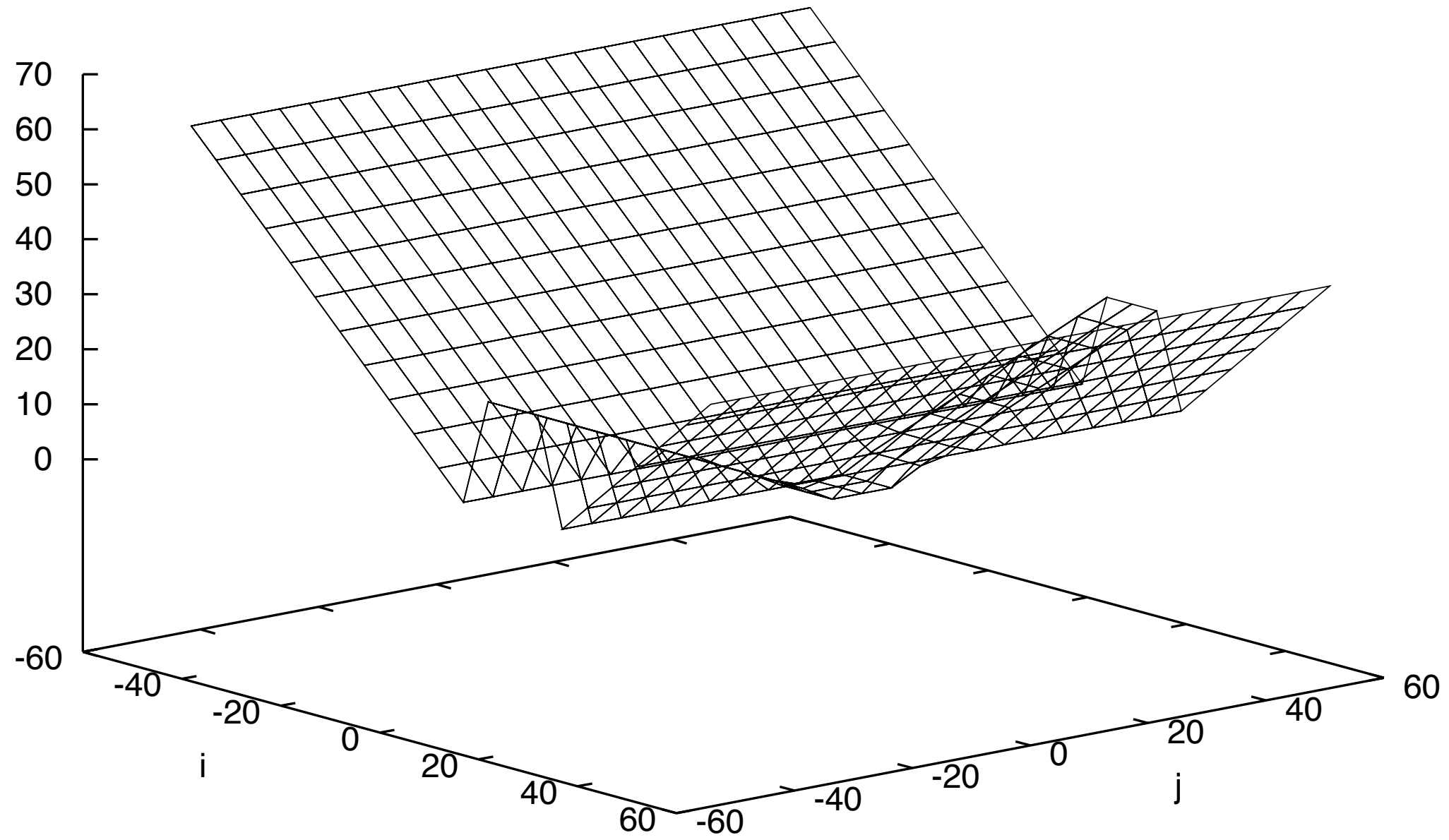
```
public int gcd(int x, int y) {  
    int tmp;  
    while (y != 0) {  
        tmp = x % y;  
        x = y;  
        y = tmp;  
    }  
    return x;  
}
```

Branch Distance

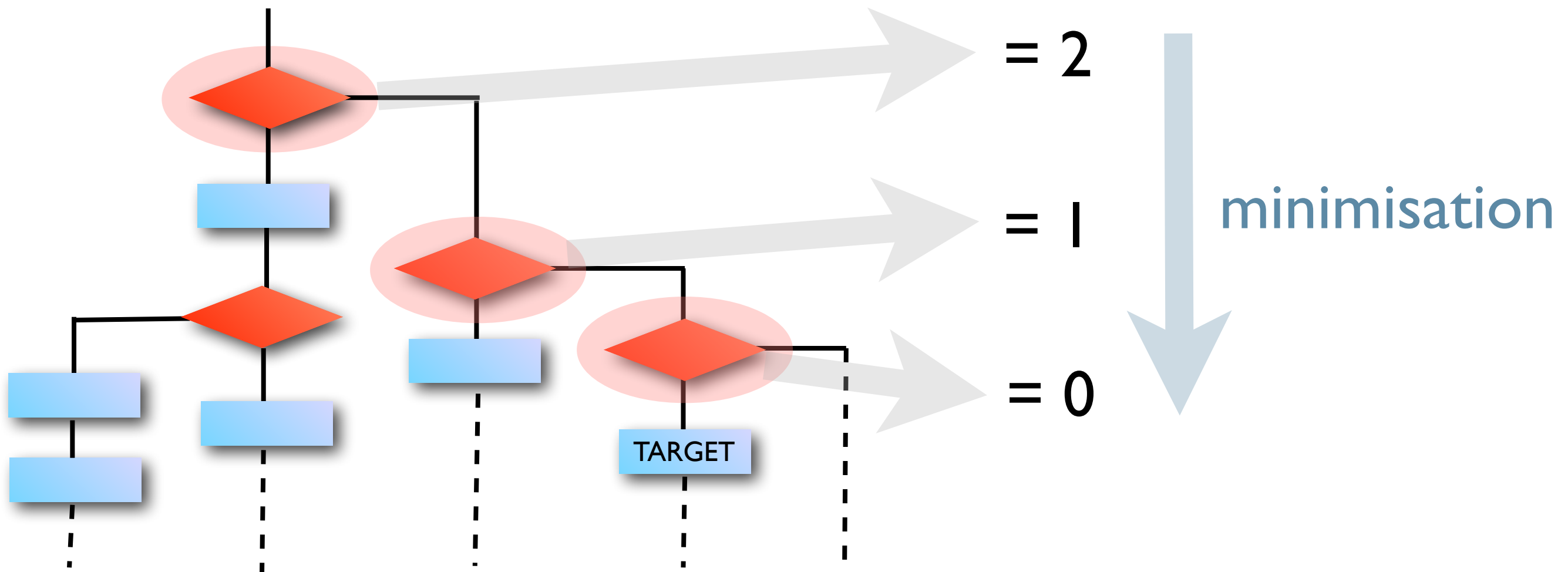
Expression	Distance True	Distance False
$x == y$	$ x - y $	1
$x != y$	1	$ x - y $
$x > y$	$y - x + 1$	$x - y$
$x >= y$	$y - x$	$x - y + 1$
$x < y$	$x - y + 1$	$y - x$
$x <= y$	$x - y$	$y - x + 1$


```
void landscape_example(int i, int j) {  
    if (i >= 10 && i <= 20) {  
        if (j >= 0 && j <= 10) {  
            // target statement  
            // ...  
        }  
    }  
}
```





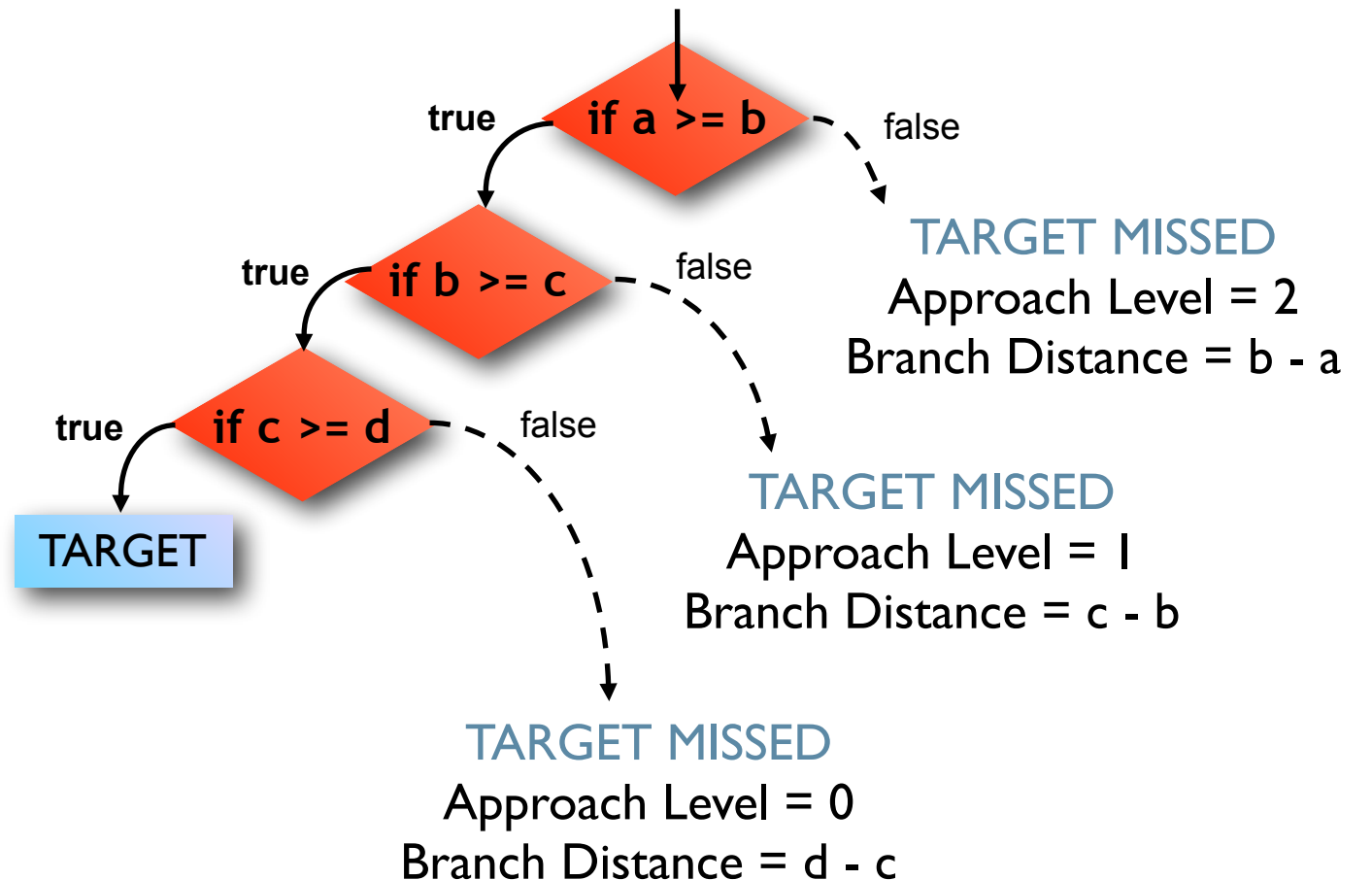
Approach Level



Putting it all together

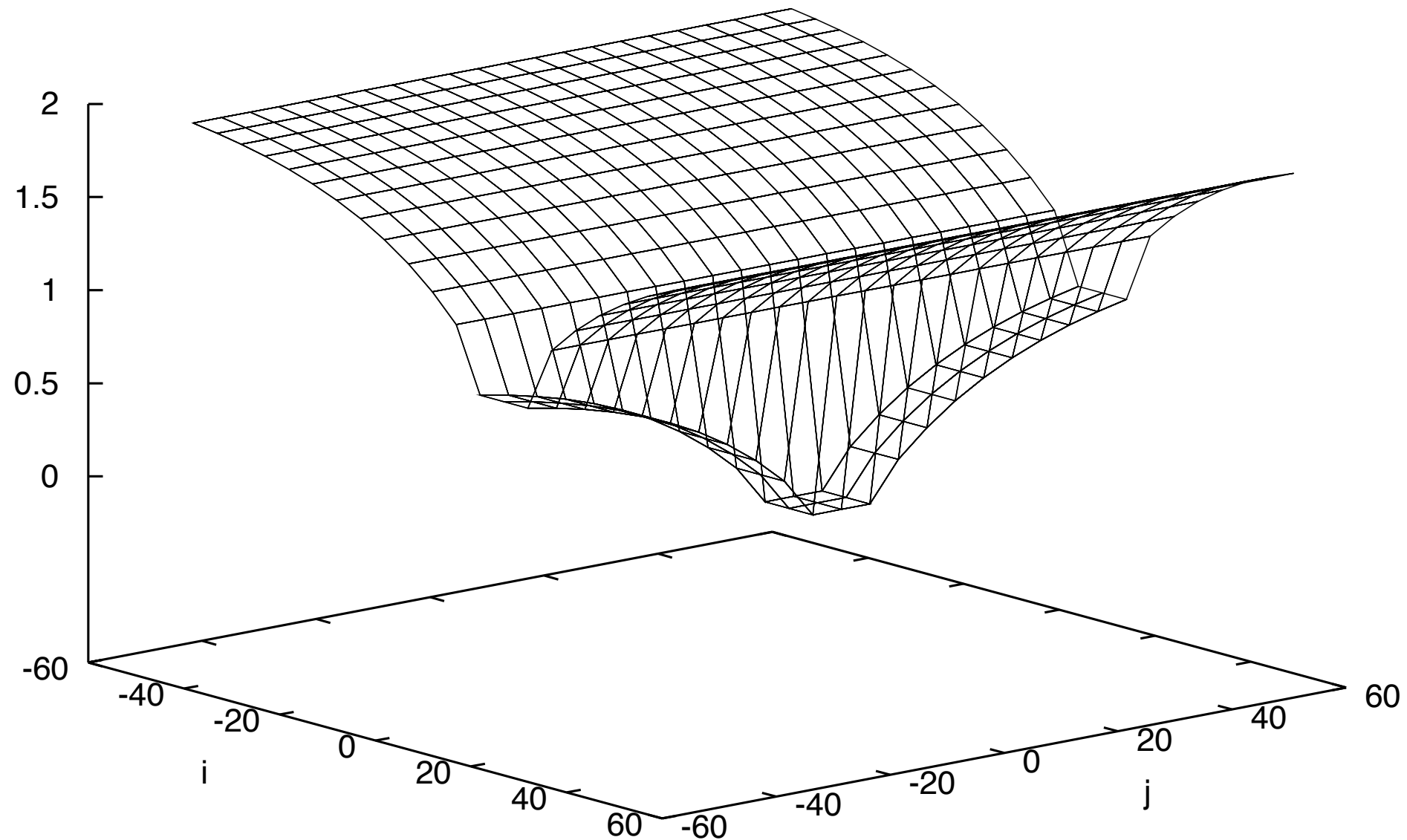
Fitness = approach Level + *normalised* branch distance

```
void f1(int a, int b, int c, int d)
{
    if (a > b)
    {
        if (b > c)
        {
            if (c > d)
            {
                // target
            }
        }
    }
    . . .
}
```



normalised branch distance between 0 and 1
indicates how close approach level is to being penetrated

Approach level + normalised(Branch distance)



Many-Objective Optimisation

- **Single Objective Formulation:** Minimise sum of branch distances for all branches
- **Many-Objective Formulation:** For each branch, find test that minimises branch distance
- **Problem:** The proportion of non-dominated solutions increases exponentially with the number of objectives, i.e., all or most of the individuals are non-dominated.
- **Domain specific knowledge** is needed to impose an order of preference over test cases that are non-dominated according to traditional nondominance
 - For branch coverage, this means focusing the search effort on the test cases that are closer to one or more uncovered branches of a program

Dominance vs. Preference

- **Dominance:** A test case x dominates another test case y if and only if the values of the objective functions satisfy the following conditions:
 - $\forall i \in \{1, \dots, m\} f_i(x) \leq f_i(y)$ and $\exists j \in \{1, \dots, m\}$ such that $f_j(x) < f_j(y)$
- **Preference:** Given a branch b_i , a test case x is preferred over another test case y if and only if the values of the objective function for b_i satisfy the following condition:
 - $f_i(x) < f_i(y)$ where $f_i(x)$ denotes the objective score of test case x for branch b_i
- The best test case for a branch b_i is the one preferred over all other tests for b_i
- The set of best test cases across all uncovered branches defines a subset of the Pareto front that is given priority over the other non-dominated test cases.
- When there are multiple test cases with the same minimum fitness value for a given branch b_i , we use the test case length as a secondary preference criterion

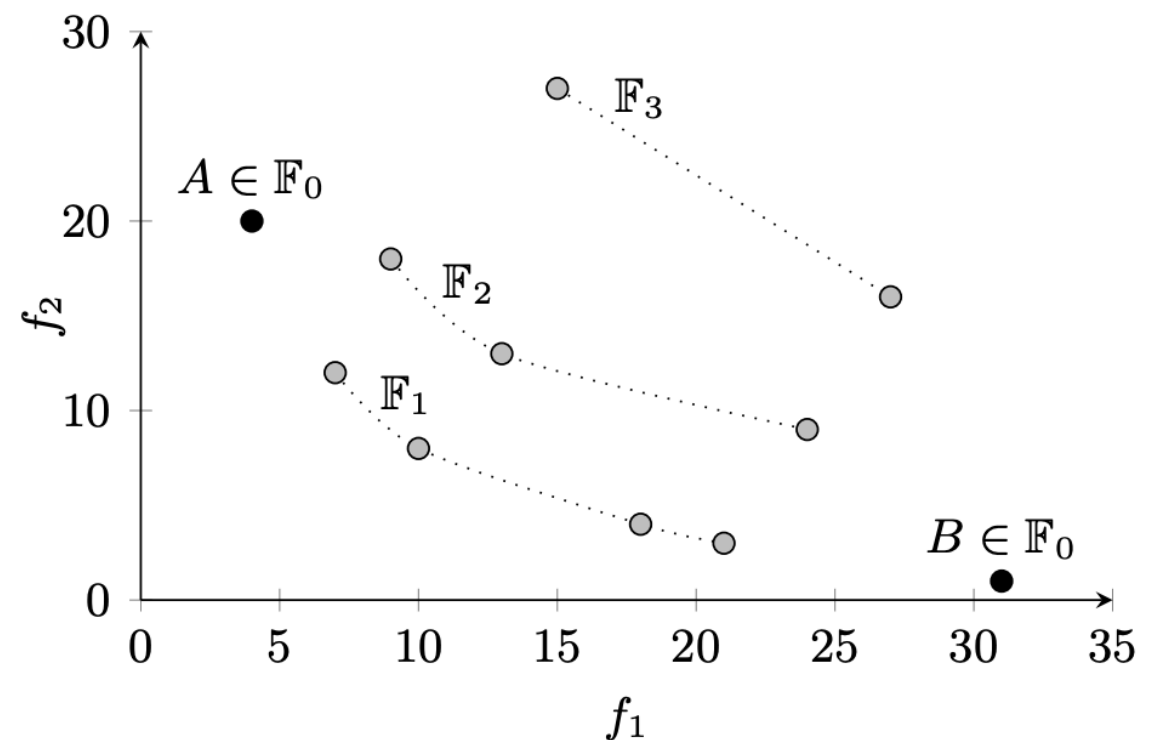
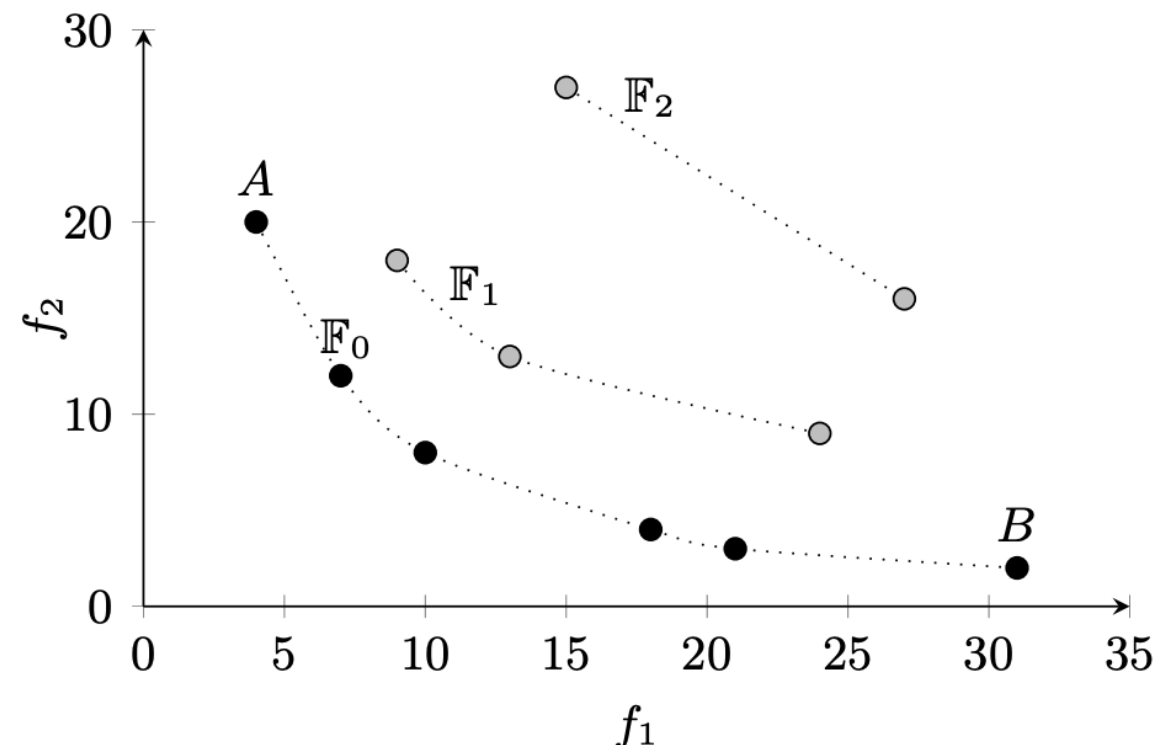
Many-Objective Sorting Algorithm (MOSA)

- Based on NSGA-II
- Rank 0 (First non-dominated front): For each uncovered branch b_i the test case that is closest to covering b_i
- The remaining test cases are ranked according to the traditional non-dominated sorting algorithm used by the NSGA-II, starting with a rank equal to 1
 - Ranks are calculated by considering only the non-dominance relation for the *uncovered* branches, i.e., by focusing the search toward the interesting sub-region of the search space
- Once a rank is assigned to all candidate test cases, the crowding distance is used in order to make a decision about which test case to select
- MOSA uses a second population (archive), to keep track of the best test cases
 - After each generation MOSA stores every test case that covers previously uncovered branches in the archive as a candidate test case to form the final test suite
 - This function considers both the covered branches and the length of test cases when updating the archive: for each covered branch b_i it stores the shortest test case covering b_i in the archive.

MOSA: Example

```
int example(int a, int b, int c) {  
1   if (a == b)  
2       return 1;  
3   if (b == c)  
4       return -1;  
5   return 0;  
}
```

- Assume that the uncovered goals are the true branches of nodes 1 and 3, whose branch predicates are $(a == b)$ and $(b == c)$ respectively.
- I.e. there are two residual optimisation goals, which are:
 - $f_1 = al(b_1) + bd(b_1) = \text{abs}(a - b)$
 - $f_2 = al(b_2) + bd(b_2) = \text{abs}(b - c)$



Input: Stopping condition C , Fitness function δ , Population size p_s , Crossover function c_f , Crossover probability c_p , Mutation probability m_p

Output: Archive of optimised individuals A

```
1:  $p \leftarrow 0$ 
2:  $N_p \leftarrow \text{GENERATERANDOMPOPULATION}(p_s)$ 
3:  $\text{PERFORMFITNESSEVALUATION}(\delta, N_p)$ 
4:  $A \leftarrow \{ \}$ 
5: while  $\neg C$  do
6:    $N_o \leftarrow \text{GENERATEOFFSPRING}(c_f, c_p, m_p, N_p)$ 
7:    $R_t \leftarrow N_p \cup N_o$ 
8:    $r \leftarrow 0$ 
9:    $F_r \leftarrow \text{PREFERENCESORTING}(R_t)$ 
10:   $N_{p+1} \leftarrow \{ \}$ 
11:  while  $|N_{p+1}| + |F_r| \leq p_s$  do
12:     $\text{CALCULATECROWDINGDISTANCE}(F_r)$ 
13:     $N_{p+1} \leftarrow N_{p+1} \cup F_r$ 
14:     $r \leftarrow r + 1$ 
15:  end while
16:   $\text{DISTANCECROWDINGSORT}(F_r)$ 
17:   $N_{p+1} \leftarrow N_{p+1} \cup F_r$  with size  $p_s - |N_{p+1}|$ 
18:   $\text{UPDATEARCHIVE}(A, N_{p+1})$ 
19:   $p \leftarrow p + 1$ 
20: end while
21: return  $A$ 
```

MOSA

- Annibale Panichella, Fitsum Meshesha Kifetew, and Paolo Tonella. "Reformulating branch coverage as a many-objective optimization problem." IEEE 8th International Conference on Software Testing, Verification and Validation (ICST). IEEE, 2015.