

COMS31700 Design Verification Hardware Design Languages

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Hardware Design Languages

- Hardware Design Languages were built with simulation in mind
 - Synthesis and other back-end purposes were added at a later stage
- Most popular languages today (both are IEEE standards)
 - VHDL
 - Verilog/SystemVerilog
- VHDL:
 - Committee-designed language contracted by U.S. (DoD) (Ada-derived)
 - Functional/logic modeling and simulation language
 - Main differentiator from Verilog is types (e.g. records)
- Verilog:
 - Logic modeling and simulation language
 - Started in EDA industry in the 80's then owned by Cadence
 - Donated to IEEE as a general industry standard
 - SystemVerilog (the next generation of Verilog) is designed to improve abstraction of Verilog
 - Abstraction levels
 - Data types
 - Verification constructs
- Verilog vs. VHDL: personal preferences, EDA tool availability, commercial, business and marketing issues.

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Modeling Levels – Major Dimensions

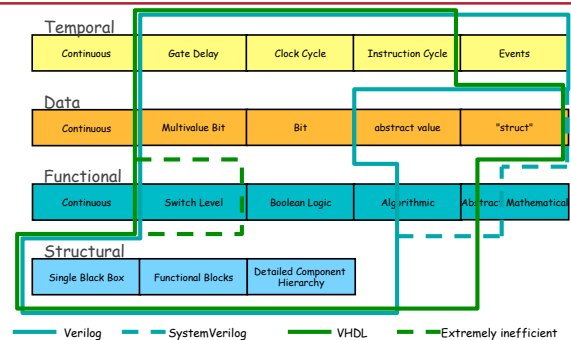
- Temporal Dimension:**
 - continuous (analog)
 - gate delay
 - clock cycle
 - instruction cycle
 - events

discrete time
- Data Abstraction:**
 - continuous (analog)
 - bit : multiple values
 - bit : binary
 - abstract value
 - composite value ("struct")

discrete value
- Functional Dimension:**
 - continuous functions (e.g. differential equations)
 - Switch-level (transistors as switches)
 - Boolean Logic
 - Algorithmic (e.g. sort procedure)
 - Abstract mathematical formula (e.g. matrix multiplication)
- Structural Dimension:**
 - Single black box
 - Functional blocks
 - Detailed hierarchy with primitive library elements

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Modeling Levels – Major Dimensions



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Verilog for Design Verification

- Assignment calc1 design in Verilog
 - Testbench for calc1 design in Verilog
- Interactive Evita Verilog tutorial (Ch1-4,5-7):
 - Structure of Verilog modules
 - Verilog signal values: 0, 1, x and z (4-valued logic)

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and	0	1	x	z
0	0	0	0	0
1	0	1	x	x
x	0	x	x	x
z	0	x	x	x

or	0	1	x	z
0	0	1	x	x
1	1	1	1	1
x	x	1	x	x
z	x	1	x	x

xor	0	1	x	z
0	0	1	x	x
1	1	0	x	x
x	x	x	x	x
z	x	x	x	x

- 0 represents logic zero, or false
- 1 represents logic one, or true
- x represents an unknown logic value
- z represents a high-impedance state, i.e. signal not driven or not connected

Verilog for Design Verification

- Assignment calc1 design in Verilog
 - Testbench for calc1 design in Verilog
- **Interactive Evita Verilog tutorial** (Ch1-4,5-7):
 - Structure of Verilog modules
 - Verilog signal values: 0, 1, x and z (4-valued logic)
 - Verilog signals:
 - nets (used for "connections", no storage capacity)
 - registers (storage capacity, similar to variables in pgr languages)
 - Verilog external signals:
 - ports (input, output or inout, port connecting rules)
 - Coding styles:
 - Structural
 - **Dataflow**
 - **Behavioural** (best for verification)

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Continuous Assignment

- **Used in Dataflow coding style.**
 - `assign #4 Out = In1 & In2;`
- Keyword **assign** followed by optional delay declaration
- **LHS** (target) can be net (scalar or vector) or concatenation of nets
 - NO registers allowed as target for assignment!
- Assignment symbol: **=**
- **RHS** is an expression.
- **Implicit continuous assignment:** `wire x = ...;`
- **Conditional assignment:**
 - `assign Out = Sel ? In1 : In0;`
 - If Sel is 1 then In1 is assigned to Out; if Sel is 0 then Out is In0.
 - If Sel is x/z, evaluate both In1 and In0, if they are the same then Out is assigned this value, otherwise x/z.

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Continuous Assignment: Execution

- Continuous assignments are **always active**.
- **Concurrency:**
 - When any of the operands on RHS changes, assignment is evaluated.
 - Several assignments can be executed concurrently.
 - **Race conditions can occur!**
 - Two or more assignments, which operate on the same data, read and write the data concurrently.
 - Result, which might be erroneous, depends on which assignment does what when.
- **Delays** specify time between change of operand on RHS and assignment of resulting value to LHS target.
 - `assign #4 Out = In1 & In2;`

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Behavioural Coding Style

- **Behaviour:**
 - Actions a circuit is supposed to perform when it is active.
- Most advanced coding style: flexible and high-level
 - closest to programming languages
 - allows use of conditional statements, case statements, loops, etc.
- **Best for verification, but by no means ideal...**
- **Algorithmic description:** Need "variables" similar to PLs!
 - Abstraction of data storage elements - register objects:
 - `reg R;` one bit register - default value x before first assignment
 - `time T;` can store/manipulate simulation time
 - `integer N;` by default at least 32 bit - stores values signed
 - `real R;` default value is 0
 - [Other data types, e.g. arrays exist, but are out of the scope of this introduction.]

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Behavioural Constructs for Coding

- **Conditionals:**
 - `if (expression true) true branch;`
 - `else false branch;`
- **Case:**
 - `case ({_,...,_})`
 - `pattern : ...;`
 - `...`
 - `default : ...;`
 - `endcase`
- **Loops:** `forever`, `repeat`, `while`, `for`
- See Verilog reference card for syntax!

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Mux421: Behavioural Coding Example

```
module mux421_behavioural (Out, In0, In1, In2, In3, Sel0, Sel1);
    output Out;
    input In0, In1, In2, In3, Sel0, Sel1;
    reg Out;
    always @ (Sel1 or Sel0 or In0 or In1 or In2 or In3)
    begin
        case ({Sel1,Sel0})
            2'b00 : Out = In0;
            2'b01 : Out = In1;
            2'b10 : Out = In2;
            2'b11 : Out = In3;
            default : Out = 1'bx;
        endcase
    end
endmodule // mux421_behavioural
```

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Mux421: Behavioural Coding Example

```
module mux421_behavioural (Out, In0, In1, In2, In3, Sel0, Sel1);
output Out;
input In0, In1, In2, In3, Sel0, Sel1;
reg Out;
always @ (Sel1,Sel0,In0,In1,In2,In3) // Verilog 2001 style
begin
    case ({Sel1,Sel0})
        2'b00 : Out = In0;
        2'b01 : Out = In1;
        2'b10 : Out = In2;
        2'b11 : Out = In3;
        default : Out = 1'bx;
    endcase
end
endmodule // mux421_behavioural
```

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Behavioural Blocks

- **initial** and **always**
 - Can't be nested.
 - Block containing several statements must be grouped using:
 - **begin ... end (sequential)** or
 - **fork ... join** (concurrent)
- **initial** block:
 - Used to initialise variables (registers).
 - Executed at (simulation) time 0. Only once!
- **always** block:
 - Starts executing at time 0.
 - Contents is executed in infinite loop.
 - Means: Execution repeats as long as simulation is running.
 - Multiple blocks are all executed **concurrently** from time 0.

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Assignment in Behavioural Coding

Assignment in behavioural coding style is **procedural**:

#5 C = #10 A+B;

- LHS (target) must be a register (reg, integer, real or time) - not a net, a bit or part of a vector of registers.
- **NO assign keyword!**
- Must be contained within a behavioural (i.e. **initial** or **always**) block.
- **NOT always active!**
 - Target register value is only changed when procedural assignment is executed according to **sequence** contained in block.
- **Delays**: indicate time that simulator waits from "finding" the assignment to executing it.

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Blocking Assignment

(... as opposed to continuous assignment from dataflow coding style.)

- Sequential initialization assignment.

```
reg A;
reg [7:0] Vector;
integer Count;
initial
begin
    A = 1'b0;
    Vector = 8'b0;
    Count = 0;
end
```

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Timing Control Evaluation

#5 C = #10 A+B;

Assignment delay Intra-assignment delay

1. Find procedural assignment
2. Wait 5 time units
3. Perform A+B
4. Wait 10 time units
5. Assign result to C

- So, what is the difference between:
 - **#10 C = A+B** and
 - **C = #10 A+B?**

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Events and Wait

- **Events** mark changes in nets and registers, e.g. raising/falling edge of clock.
 - @ **negedge** means from any value to 0
 - @ **posedge** means from any value to 1
 - @ **clk** always activates when clock changes
- **Wait statement:**
 - **wait** (condition) stmt;
 - **wait (EN) #5 C = A + B;**
 - waits for EN to be 1 before #5 C = A + B;
- Use **wait** to block execution by not specifying a statement!
 - **wait (EN); ...**

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Sensitivity List

```
always @(sensitivity list) <begin> <procedural stments> <end>

always @ (posedge Clk or EN)
begin ... end

always @ (Sel1,Sel2) // Verilog 2001 style
begin ... end
```

- Allows to **suspend always blocks**.
- Block executes and suspends until signal (one or more) in **sensitivity list** changes.
- NOTE: Old **or** notation is used to make statement **sensitive to multiple signals or events**.
 - (Don't use sensitivity list to express a logical condition!)
- Common mistake:
 - Forgetting to add relevant signals to sensitivity list!

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Non-blocking Assignments

- Can be used to introduce **concurrency** into sequential statements.
 - Delay is counted down before assignment,
 - BUT control is passed to next statement immediately.
- Non-blocking Assignments** allow to model multiple concurrent data transfers after common event.
 - A blocking assignment would force sequential execution.

```
A <= #1 1; B <= #2 0; (non-blocking)      A x 1 1 1
                                           B x x 0 0
                                           Time: 0 1 2 3
```

```
A = #1 1; B = #2 0; (blocking)             A x 1 1 1
                                           B x x x 0
                                           Time: 0 1 2 3
```

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Approaches to Assignment - I

```
reg [7:0] MyReg;
initial
fork
    #50 MyReg = 8'hFF;
    #100 MyReg = 8'h01;
    #150 MyReg = 8'h2F;
    #200 MyReg = 8'h00;
    #250 $finish;
join
```

- Concurrent but using blocking assignment (=)

```
Time:      0   50  100 150 200 250
MyReg[7:0] XX  FF  01  2F  00  00
```

Important when driving input into a DUV in a testbench!

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Approaches to Assignment - II

```
reg [7:0] MyReg;
initial
begin
    MyReg <= #50 8'hFF; // pass control, wait, assign
    MyReg <= #50 8'h01;
    MyReg <= #50 8'h2F;
    MyReg <= #50 8'h00;
    #250 $finish;
end
```

Race Condition!

- Sequential with non-blocking assignment (<=)

```
Time:      0   50  100 150 200 250
MyReg[7:0] XX  ??  ??  ??  ??  ??
```

Important when driving input into a DUV in a testbench!

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Approaches to Assignment - III

```
reg [7:0] MyReg;
initial
begin
    MyReg <= #50 8'hFF; // pass control, wait, assign
    MyReg <= #100 8'h01;
    MyReg <= #150 8'h2F;
    MyReg <= #200 8'h00;
    #250 $finish;
end
```

- Sequential with non-blocking assignment (<=)

```
Time:      0   50 100 150 200 250
MyReg[7:0] XX  FF  01  2F  00  00
```

Important when driving input into a DUV in a testbench!

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Approaches to Assignment - IV

```
reg [7:0] MyReg;
initial
begin
    #50 MyReg = 8'hFF; // wait, assign, pass control
    #50 MyReg = 8'h01;
    #50 MyReg = 8'h2F;
    #50 MyReg = 8'h00;
    #250 $finish;
end
```

- Sequential with blocking assignment (=)

```
Time:      0   50 100 150 200 250
MyReg[7:0] XX  FF  01  2F  00  00
```

Important when driving input into a DUV in a testbench!

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HDL vs. Programming Languages

3 major new concepts of HDLs compared to PLs:

- **Connectivity:**
 - Ability to describe a design using simpler blocks and then connecting them together.
- **Time:**
 - Can specify a delay (in time units of simulator): (WHY?)
 - `and #2 (Y3, In3, Sel1, Sel0);`
- **Concurrency is always assumed!** (for structural style this is)
 - No matter in which order primitives/components are specified, a change in value of any input signal **activates** the component.
 - If two or more components are activated **concurrently**, they perform their actions **concurrently**.
 - **Order of specification does not influence order of activation!**
 - (NOTE: Statements inside behavioural blocks may be sequential -more later.)

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Tasks and Functions

Tasks and Functions

- Both are **purely behavioural**.
 - Can't define nets inside them.
 - Can use logical variables, registers, integers and reals.
- **Must be declared within a module.**
 - Are local to this module.
 - To share tasks/functions in several modules, specify declaration in separate module and use `'include` directive.
- **Timing (simulation time)**
 - **Tasks:**
 - No restriction on use of timing; engineer specifies execution.
 - **Functions:**
 - Execute in **ZERO sim time units**; no timing/event control allowed.

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Example Task

```
task factorial;
  output [31:0] f;
  input [3:0] n;
  integer count; // local variable
  begin
    f = 1;
    for (count=n; count>0; count=count-1)
      f = f * count;
  end
endtask
```

- **Invoke task:** `< task name > (list of arguments);`
 - Declaration order determines order of arguments when task is called!

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Example Function

```
function ParityCheck;
  input [3:0] Data;
  begin
    ParityCheck = ^Data; // bit-wise xor reduction
  end
endfunction
```

- **Result** is by default a 1 bit register assigned to **implicitly declared local variable** that has **same name as function**.
- **Function calls:**
 - Are either assigned to a variable, or
 - occur in an expression that is assigned to a variable,
 - or occur as an argument of another function call.

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Comparing Tasks with Functions

	Tasks	Functions
Timing	can be non-zero sim time	execute in 0 sim time
Calling other tasks or functions	no limit; may enable functions	may not call tasks but may call another function No recursion!
Arguments	any number; any type; can't return result	at least one input; no output/inout; always results in single return value
Purpose	modularize code	react to some input with single response; only combinatorial code; use as operands in expressions

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System Tasks and Functions

- More than 100 Verilog system tasks/functions.
 - (See Evita Verilog Reference Guide for more information.)
- Can be used in any module without explicit include directive.
- **Syntax:** `$< keyword >`
- **Most important tasks for verification:**
 - `$display`, `$monitor`
 - `$time`, `$stop`, `$finish`
 - (Also with files: `$fopen`, `$fdisplay`)

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Summary

- Evita Verilog Tutorial [Ch1-7]
- **Verilog HDL IEEE Standard 1364-2001**
 - Signals: internal and external (ports)
 - Different coding styles:
 - structural
 - dataflow
 - behavioural
- SystemVerilog builds on IEEE 1364-2005
- HDLs: **Connectivity, Time and Concurrency**
- BOOK: Verilog HDL by Samir Palnitkar [in QB Library]
- **Next:** Specification of Assignment 1!

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