COMS31700 Design Verification

Hardware Design Languages

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Hardware Design Languages

- Hardware Design Languages were built with simulation in mind

 Synthesis and other back-end purposes were added at a later stage
- Most popular languages today (both are IEEE standards)
- VHDL Verilog/SystemVerilog
- VHDL:
 - Committee-designed language contracted by U.S. (DoD) (ADA-derived)
 Functional/logic modeling and simulation language
 Main differentiator from Verilog is types (e.g. records)

- Main unresemble.

 Verilog:
 Logic modeling and simulation language
 Logic modeling and simulation language
 Statred in EDA industry in the 80's then owned by Cadence
 Donated to IEEE as a general industry standard
 SystemVerilog (the next generation of Verilog) is designed to improve abstraction of Verilog

 Abstraction levels
- Verilog vs. VHDL: personal preferences. EDA tool availability, commercial.

Modeling Levels - Major Dimensions



Data Abstraction:

- Data Abstraction:

 continuous (analog)

 bit : multiple values

 bit : binary

 abstract value

 composite value ("struct")

 Functional Dimension:

 continuous functions (e.g. differential equations)

 Switch-level (transistors as switches)
- Switch-level (transistors as switches)
 Boolean Logic
 Algorithmic (e.g. sort procedure)
 Abstract mathematical formula (e.g. matrix multiplication)

 Structural Dimension:
 Single black box
 Functional blocks
 Detailed hierarchy with primitive library elements

Modeling Levels - Major Dimensions Temporal Gate Delay Clock Cycle Instruction Cvcl Data ___ _ _ _ _ _ Structural Single Black Box Functional Blocks - VHDL - Extremely inefficient

Verilog for Design Verification

- Assignment calc1 design in Verilog
 - Testbench for calc1 design in Verilog
- Interactive Evita Verilog tutorial (Ch1-4,5-7):
 - Structure of Verilog modules
 - Verilog signal values: 0, 1, x and z (4-valued logic)
 - Verilog signals:
 - nets (used for "connections", no storage capacity)
 - registers (storage capacity, similar to variables in pgr languages)
 - Verilog external signals:
 - ports (input, output or inout, port connecting rules)
 Coding styles:
 - Structural Dataflow
 - Behavioural (best for verification)

Continuous Assignment

- Used in Dataflow coding style.
- Keyword assign followed by optional delay declaration
- LHS (target) can be net (scalar or vector) or concatenation of nets
 - NO registers allowed as target for assignment!
- Assignment symbol: =
- RHS is an expression.
 - assign #4 Out = In1 & In2;
- Implicit continuous assignment: wire x = ...;
- Conditional assignment:

 - assign Out = Sel ? In1 : In0;
 If Sel is 1 then In1 is assigned to Out; if Sel is 0 then Out is In0.
 - If \mathtt{Sel} is x/z, evaluate both \mathtt{Inl} and $\mathtt{In0}$, if they are the same then \mathtt{Out} is assigned this value, otherwise x/z.

Continuous Assignment: Execution

- Continuous assignments are always active.
- Concurrency:
 - When any of the operands on RHS changes, assignment is evaluated.
 - Several assignments can be executed concurrently.
 - Race conditions can occur!
 - Two or more assignments, which operate on the same data, read and write the data concurrently.
 - Result, which might be erroneous, depends on which assignment does what when.
- Delays specify time between change of operand on RHS and assignment of resulting value to LHS target.

```
assign #4 Out = In1 & In2;
```

Behavioural Coding Style

- Most advanced coding style: flexible and high-level

 closest to programming languages
 allows use of conditional statements, case statements, loops, etc. Best for verification, but by no means ideal...

Rehaviour:

- Actions a circuit is supposed to perform when it is active.
- Algorithmic description: Need "variables" similar to PLs!
 - Abstraction of data storage elements register objects:

 reg R; one bit register default value x before first assignment

 time T; can store/manipulate simulation time

 integer N; by default at least 32 bit stores values signed

 - real R; default value is 0
 - [Other data types, e.g. arrays exist, but are out of the scope of this introduction.]

Behavioural Constructs for Coding

```
Conditionals:
```

```
if (expression true) true branch;
 else false branch;
Case:
    case ({_,...,_})
        pattern : ...;
        default : ...;
    endcase
```

- Loops: forever, repeat, while, for
- See Verilog reference card for syntax!

Mux421: Behavioural Coding Example

```
module mux421_behavioural (Out, In0, In1, In2, In3, Sel0, Sel1);
   output Out;
input In0, In1, In2, In3, Sel0, Sel1;
   reg Out;
always @ (Sel1 or Sel0 or In0 or In1 or In2 or In3)
      case ({Sell.Sel0})
     case ({Sel1,Sel0})
2'b00: Out = In0;
2'b01: Out = In1;
2'b10: Out = In2;
2'b11: Out = In3;
default: Out = 1'bx;
      endcase
endmodule // mux421 behavioural
```

Mux421: Behavioural Coding Example

```
module mux421_behavioural (Out, In0, In1, In2, In3, Sel0, Sel1);
  output Out;
input In0, In1, In2, In3, Sel0, Sel1;
   reg Out;
always @ (Sel1,Sel0,In0,In1,In2,In3) // Verilog 2001 style
   begin
case ({Sel1,Sel0})
     case ({Sel1,Sel0})
2'b00 : Out = In0;
2'b01 : Out = In1;
2'b10 : Out = In2;
2'b11 : Out = In3;
default : Out = 1'bx;
      endcase
endmodule // mux421 behavioural
```

Behavioural Blocks

- initial and always
 - Can't be nested.
 - Block containing several statements must be grouped using:
 - begin ... end (sequential) or
 - fork ... join (concurrent)
- initial block:
 - Used to initialise variables (registers).
 - Executed at (simulation) time 0. Only once!
- always block:
 - Starts executing at time 0.
 - Contents is executed in infinite loop.
 - Means: Executing repeats as long as simulation is running.
 - Multiple blocks are all executed concurrently from time 0.

Assignment in Behavioural Coding

Assignment in behavioural coding style is procedural:

- LHS (target) must be a register (reg, integer, real or time) - not a net, a bit or part of a vector of registers.
- NO assign keyword!
- Must be contained within a behavioural (i.e. initial or always) block.
- NOT always active!
 - Target register value is only changed when procedural assignment is executed according to sequence contained in
- Delays: indicate time that simulator waits from "finding" the assignment to executing it.

Blocking Assignment

(... as opposed to continuous assignment from dataflow coding style.)

```
reg A;
reg [7:0] Vector;
integer Count:
initial
begin
  A = 1'b0;
  Vector = 8'b0;
 Count = 0;
end
```

Sequential initialisation assignment.

Timing Control Evaluation

```
#5 C = #10 A+B;
                          Intra-assignment delay
Assignment delay
```

- 1. Find procedural assignment
- 2. Wait 5 time units
- 3. Perform A+B
- 4. Wait 10 time units
- 5. Assign result to C
- So, what is the difference between:
 - #10 C = A+B and

C = #10 A+B?

Events and Wait

- Events mark changes in nets and registers, e.g. raising/falling edge of clock.
 - e negedge means from any value to 0
 - @ posedge means from any value to 1
 - @ clk always activates when clock changes
- Wait statement:

```
wait (condition) stmt;
  wait (EN) #5 C = A + B;
    - waits for EN to be 1 before #5 C = A + B;
```

 Use wait to block execution by not specifying a statement!

- wait (EN); ...

Sensitivity List

```
always @(sensitivity list) <begin>  cedural stments> <end>
always @ (posedge Clk or EN)
begin ... end
always @ (Sel1,Sel2) // Verilog 2001 style
```

- Allows to suspend always blocks.
- Block executes and suspends until signal (one or more) in sensitivity list changes.
- NOTE: or is used to make statement sensitive to multiple signals or events.
- (Don't use sensitivity list to express a logical condition!)
- Common mistake:
 - Forgetting to add relevant signals to sensitivity list!

Non-blocking Assignments

- Concurrency can be introduced into sequential statements
- Delay is counted down before assignment, BUT control is passed to next statement immediately.
- Non-blocking Assignments allow to model multiple concurrent data transfers after common event.
- A blocking assignment would force sequential execution.

```
A <= #1 1; B <= #2 0; (non-blocking)
                                           A x 1 1 1
                                            в х х 0 0
                                       Time: 0 1 2 3
A = #1 1; B = #2 0; (blocking)
                                            A x 1 1 1
                                           вххх 0
                                       Time: 0 1 2 3
```

Approaches to Assignment - I

```
reg [7:0] MyReg;
initial
  fork
     #50 MyReg = 8'hFF;
     #100 MyReg = 8'h01;
     #150 \text{ MyReg} = 8'h2F;
     #200 MyReg = 8'h00;
     #250 $finish;

    Concurrent but using blocking assignment (=)

       Time: 0 50 100 150 200 25
MyReg[7:0] XX FF 01 2F 00 00
Important when driving input into a DUV in a testbench!
```

Approaches to Assignment - II

```
Race Condition!
reg [7:0] MyReg;
initial
  begin
     MyReg <= #50 8'hFF; // pass control, wait, assign
    MyReg <= #50 8'h01;
MyReg <= #50 8'h2F;
     MyReg <= #50 8'h00;
     #250 $finish;

    Sequential with non-blocking assignment (<=)</li>

       Time: 0 50 100 150 200 250 MyReg[7:0] XX ?? ?? ?? ?? ??
Important when driving input into a DUV in a testbench!
```

Approaches to Assignment - III

```
reg [7:0] MyReg;
  begin
     MyReg <= #50 8'hFF; // pass control, wait, assign
     MyReg <= #100 8'h01;
MyReg <= #150 8'h2F;
     MyReg <= #200 8'h00;
     #250 $finish;
  end

    Sequential with non-blocking assignment (<=)</li>

            Time: 0 50 100 150 200 25
MyReg[7:0] XX FF 01 2F 00 00
Important when driving input into a DUV in a testbench!
```

Approaches to Assignment - IV

```
reg [7:0] MyReg;
initial
  begin
     #50 MyReg = 8'hFF; // wait, assign, pass control
     #50 MyReg = 8'h01;
#50 MyReg = 8'h2F;
#50 MyReg = 8'h00;
     #250 $finish;

    Sequential with blocking assignment (=)

            Time: 0 50 100 150 200 250
MyReg[7:0] XX FF 01 2F 00 00
Important when driving input into a DUV in a testbench!
```

HDL vs. Programming Languages

3 major new concepts of HDLs compared to PLs:

- Connectivity:
 - Ability to describe a design using simpler blocks and then connecting them together.
- - Can specify a delay (in time units of simulator): (WHY?)
 and #2 (Y3, In3, Sel1, Sel0);
- Concurrency is always assumed! (for structural style this is)
 - No matter in which order primitives/components are specified, a change in value of any input signal activates the component.

 If 2 or more components are activated concurrently, they perform their actions concurrently.

 Order of specification does not influence order of activation!

 - (NOTE: Statements inside behavioural blocks may be sequential -more later.)

Tasks and Functions

Tasks and Functions

- Both are purely behavioural.
 - Can't define nets inside them.
 - Can use logical variables, registers, integers and reals.
- Must be declared within a module.
 - Are local to this module.
 - To share tasks/functions in several modules, specify declaration in separate module and use 'include directive
- **Timing** (simulation time)
 - Tasks:
 - No restriction on use of timing; engineer specifies execution.
 - - Execute in ZERO sim time units; no timing/event control allowed.

Comparing Tasks with Functions

	Tasks	Functions
Timing	can be non-zero sim time	execute in 0 sim time
Calling other tasks or functions	no limit; may enable functions	may not call tasks but may call another function No recursion!
Arguments	any number; any type; can't return result	at least one input; no output/inout; always results in single return value
Purpose	modularize code	react to some input with single response; only combinatorial code; use as operands in expressions

Example Task

```
task factorial;
  output [31:0] f;
  input [3:0] n;
  integer count; // local variable
  begin
    f = 1:
    for (count=n; count>0; count=count-1)
      f = f * count;
endtask
```

- Invoke task: < task name > (list of arguments);
 - Declaration order determines order of arguments when task is called!

Example Function

```
function ParityCheck;
  input [3:0] Data;
  begin
    ParityCheck = ^Data; // bit-wise xor reduction
  end
endfunction
```

- Result is by default a 1 bit register assigned to implicitly declared local variable that has same name as function.
- Function calls:
 - Are either assigned to a variable, or
 - occur in an expression that is assigned to a variable,
 or occur as an argument of another function call.

System Tasks and Functions

- More than 100 Verilog system tasks/functions.
 - (See Evita Verilog Reference Guide for more information.)
- Can be used in any module without explicit include directive.
- Syntax: \$< keyword >
- Most important tasks for verification:
 - \$display, \$monitor
 - \$time, \$stop, \$finish
 - (Also with files: \$fopen, \$fdisplay)

Summary

- Evita Verilog Tutorial [Ch1-7]
- Verilog HDL IEEE Standard 1364-2001
 - Signals: internal and external (ports)
 - Different coding styles:
 - structural
 - dataflow behavioural
- SystemVerilog builds on IEEE 1364-2005
- HDLs: Connectivity, Time and Concurrency
- BOOK: Verilog HDL by Samir Palnitkar [in QB Library]
- Next: Specification of Assignment 1!