

# COMS31700 Design Verification: **Checking**

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(Acknowledgement: Avi Ziv from the IBM Research Labs in Haifa has kindly permitted the re-use of some of his slides.)

# Checking - Outline

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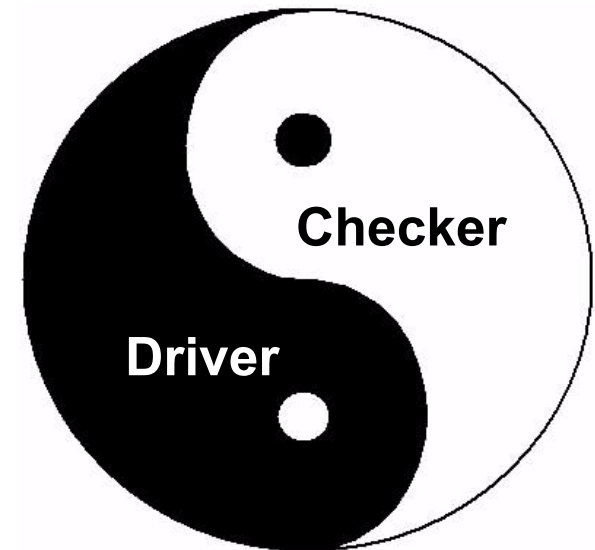
- Motivation
- Issues in checking
  - When to check
  - What to check
- Checking technologies
  - Reference models
  - Scoreboards
  - (Rule-based checking)
    - (Assertions)
- Assertion-based verification (ABV) – later 😊



# The Yin-Yang of Verification

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- Driving and checking are the yin and yang of verification
  - We cannot find bugs without creating the failing conditions
  - We cannot find bugs without detecting the incorrect behavior



# Ideal Checking

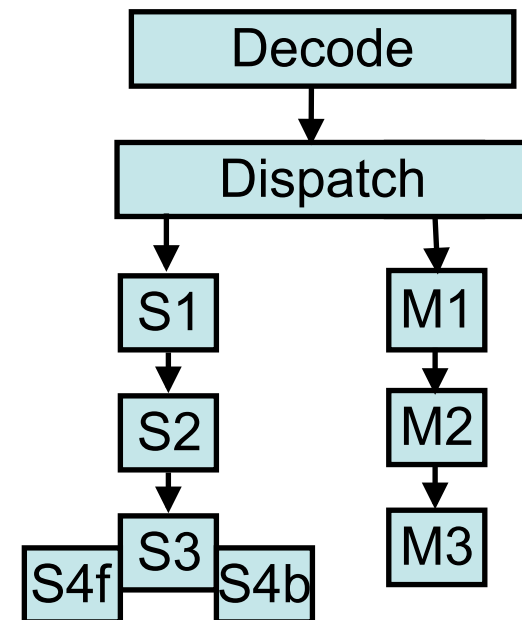
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- In theory – detect deviation from expected behavior as soon as it happens and where it happens
  - No need to worry about “disappearing errors”
  - Easy to debug – the checker points to the bug
- This is not easy (even if we ignore many practical aspects) because in many cases we understand that something bad happened only in retrospect
  - Several “good” behaviors collide to create a bad behavior
- And what about the bugs we are not looking for

# “Good” Behavior Collision

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- At cycle 1000 fdiv F1, F2, F3 is dispatched to the M unit
  - It reaches stage M2 at cycle 1001
  - Its execution time is 60 cycles
- At cycle 1023 fld F1,100(G2) is dispatched to the S unit
  - It reaches stage S2 at cycle 1024
- The data returns from the cache at cycle 1060
- At cycle 1061 the fdiv is ready to write
  - It moves to stage M3
- At cycle 1061 the fld is ready to write
  - It moves to stage S3
- Both instruction write to the same register together



# “Good” Behavior Collision

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- There are many possible causes for the problem

# Practical Aspects

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Consider:

- The cost of implementation and maintenance
  - Against the cost of debugging
  
- The cost of mistakes
  - Misdetection
    - We failed to detect a bug that was exposed by the stimuli.
  - False alarm
    - We mistakenly flagged a good behavior as bad.
  - Which is more expensive?

When to check



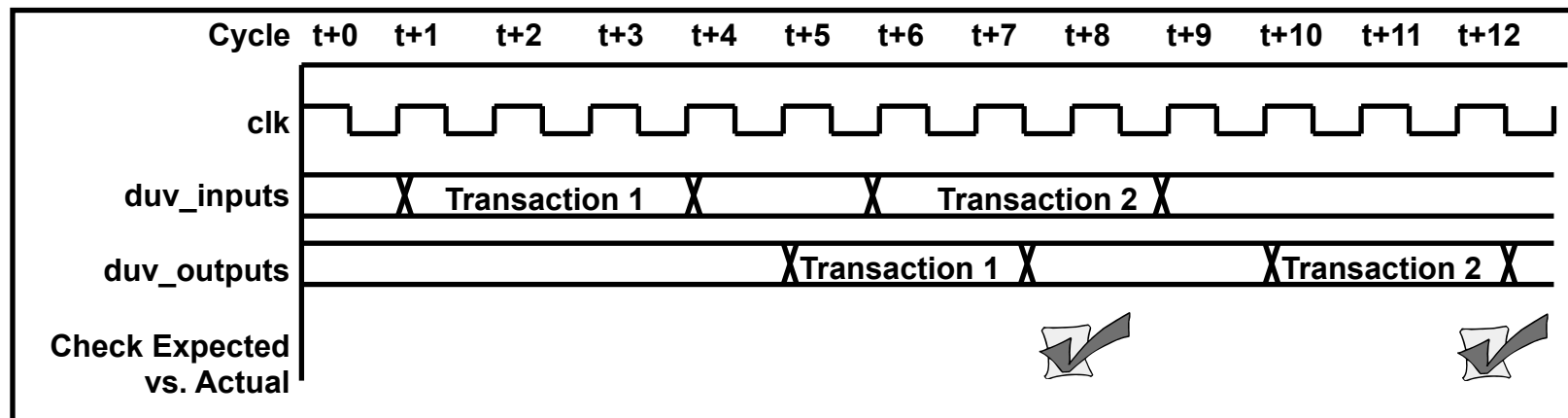
# When to Check?

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- Checking can be done at various stages of the verification job
  - During simulation
    - On-the-fly checking
  - At the end of simulation
    - End-of-test checking
  - After the verification job finishes
    - External checking
- Checking at each stage has its own advantages and disadvantages

# On-the-fly Checking

- Checking is done **while the simulation is running**
- The DUV is continuously monitored to detect erroneous behavior



# On-the-fly Checking

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- Advantages

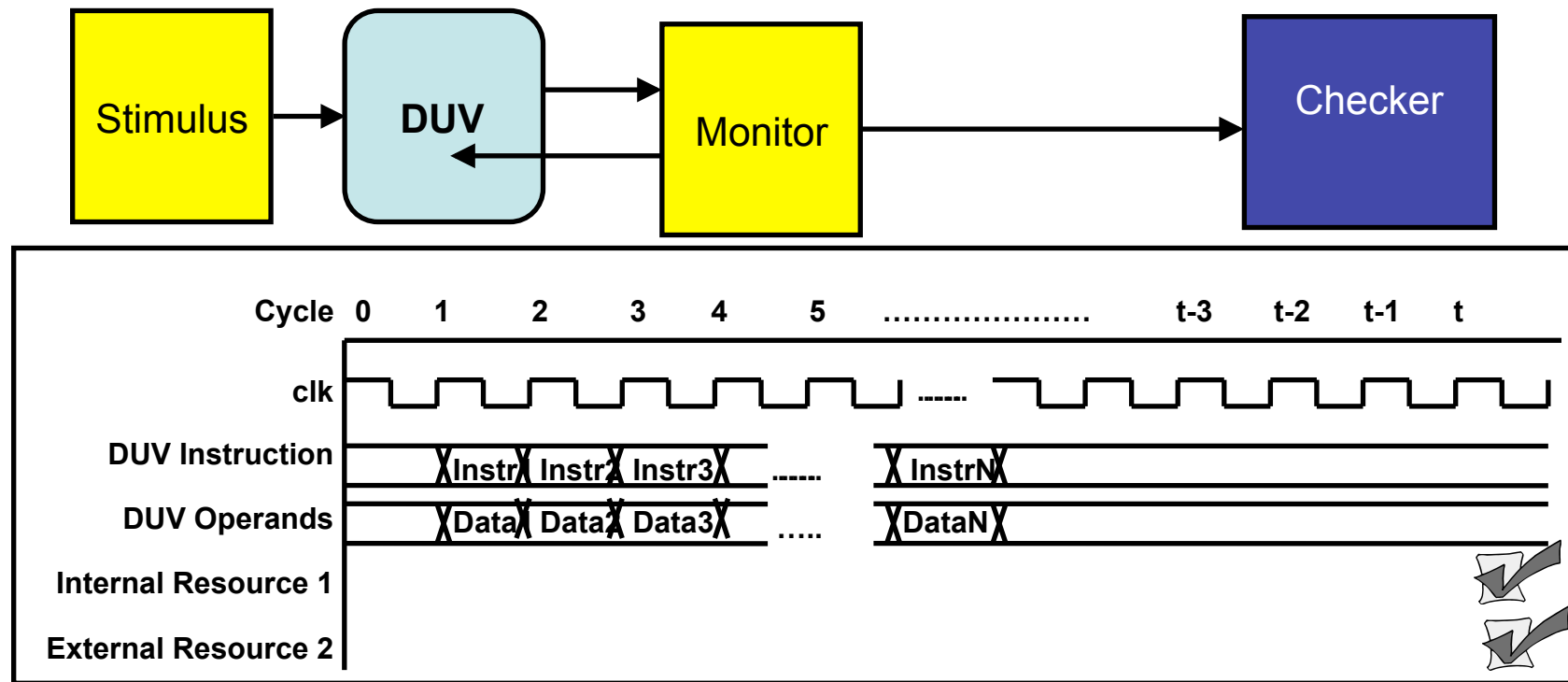
- Detection can be as close as possible (in time and space) to the bug source
- Can stop test as soon as bug occurs; no wasted simulation cycles
- Do not require large traces and external tools to do the checking

- Disadvantages

- May **slow down simulation**
- Checking is limited to allowed time and space complexity
- Need to **plan the checking in advance**
  - To add a new checker, we need to rerun simulation

# End-of-test Checking

- Checking is done **at the end of simulation**
- The checker checks the state of internal and external resources and makes sure that they are correct



# End-of-test Checking

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- Disadvantages

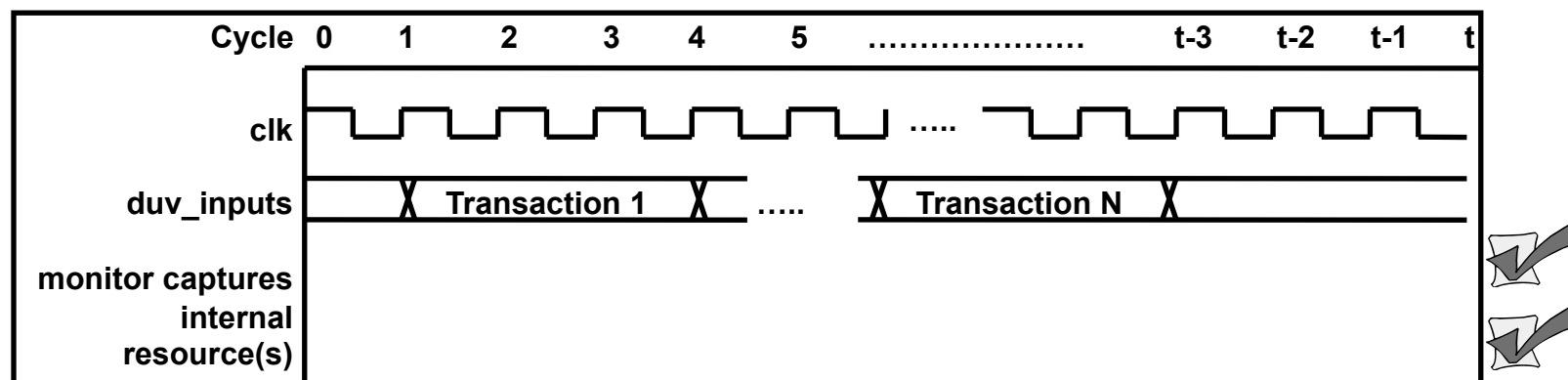
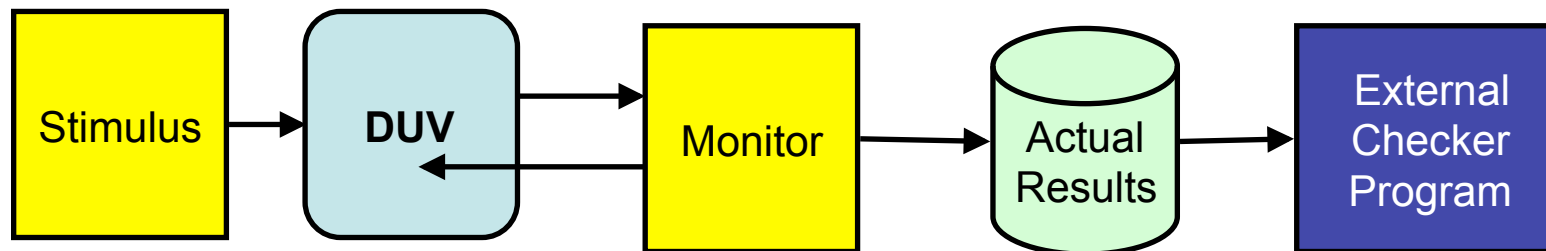
- Provides limited checking capabilities
  - Static look at the state of resources at the end of the test
- High probability of **masking bugs** by rewriting to the resources
- **Hard to detect performance bugs**
  - Correct things are happening, but not at the right time
- Hard to correlate symptoms to bugs
  - **Hard to debug**

- Advantages

- Simpler than other forms
  - May not require a deep understanding of the DUV
- Reduces probability of false alarms
  - Caused by disappearing bad effects

# External Checking (Monitors)

- **Monitors** keep internal resources values and behaviors in trace files
- Checking is done by an external program that examines these files



# External Checking

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- External checking **separates the checking from the simulation**
  - We can perform any check we want without rerunning the simulation
    - As long as the data is in the trace files
  - We can perform more complicated checks
    - Use longer history, process events out-of-order
  - We can combine information coming from different sources
    - For example, different verification environments

In theory, external checking has all the powers of on-the-fly checking plus end-of-test checking - plus more

(Trace size and amount of traced facilities is a practical limitation.)

What to check



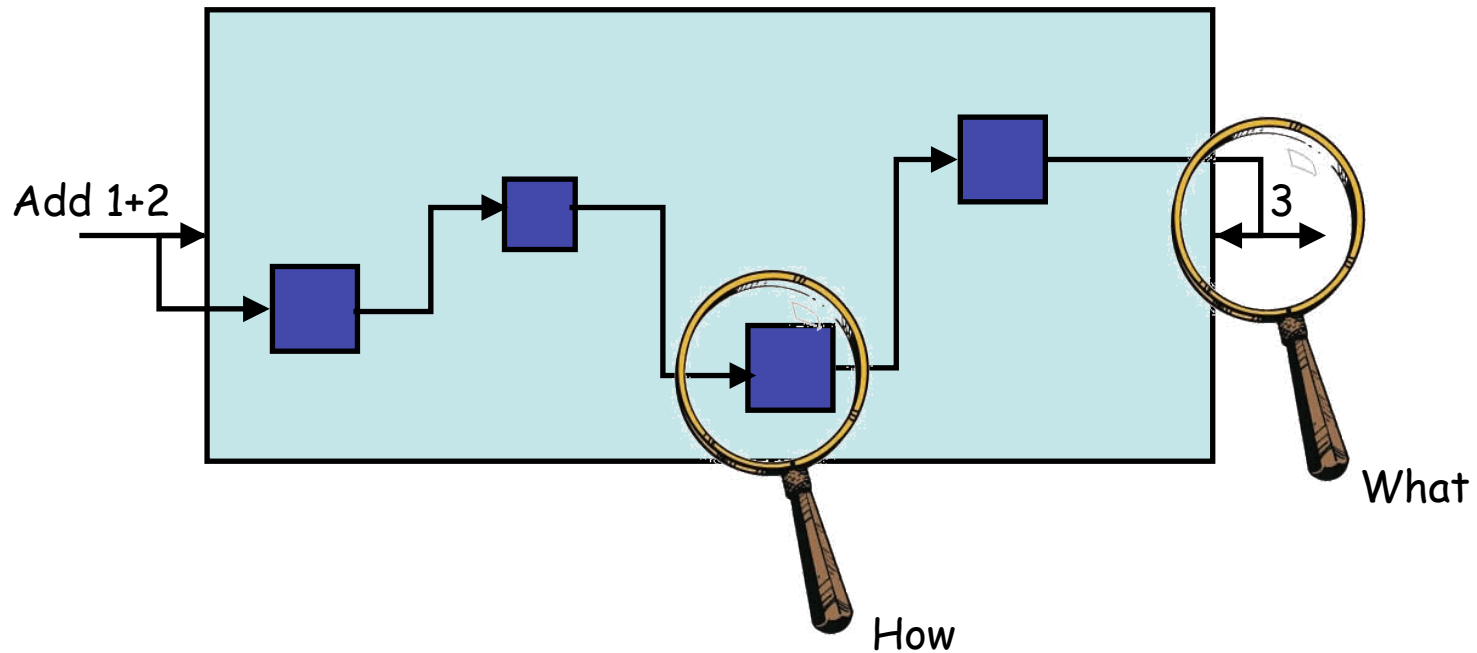
# What to Check

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- There are five main sources of checkers
  - The inputs and outputs of the design (specification)
  - The architecture of the design
  - The microarchitecture of the design
  - The implementation of the design
  - The context of the design
    - e.g. protocol compliance
- Note that the **source** of checkers and their **implementation** are two different issues

# Coarser Classification – The What And the How

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# Checking the What

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- Check the **final outcome** of a behavior
  - Data oriented
    - But not limited to data
  - Usually based on higher level of abstraction
    - Checking is less tight
    - Requires less familiarity with the DUV
    - Less false alarms, more misdetections
  - Low correlation between failure and bugs
    - Harder for debugging
    - Can find “unexpected” bugs

# Checking the How

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- Check *how* things are done internally
  - Control oriented
  - Usually at lower levels of abstraction
    - Closer to implementation
  - More false alarms, less misdetections
  - Tighter relations between failure and bugs

# Stimuli Generation and Checking

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- In general, checking should be isolated from the stimuli generation
  - **Modularity** – ability to replace the stimuli generator
  - **Reusability** – ability to use the checkers at higher level of the design hierarchy
  - **Independence of Checking from Generation**
- Exceptions
  - Self-checking tests
  - Golden vectors
- The stimuli generation can assist checking by improving observability
  - Help transfer events from dark corners to the spotlight

# Self-Checking Testbenches

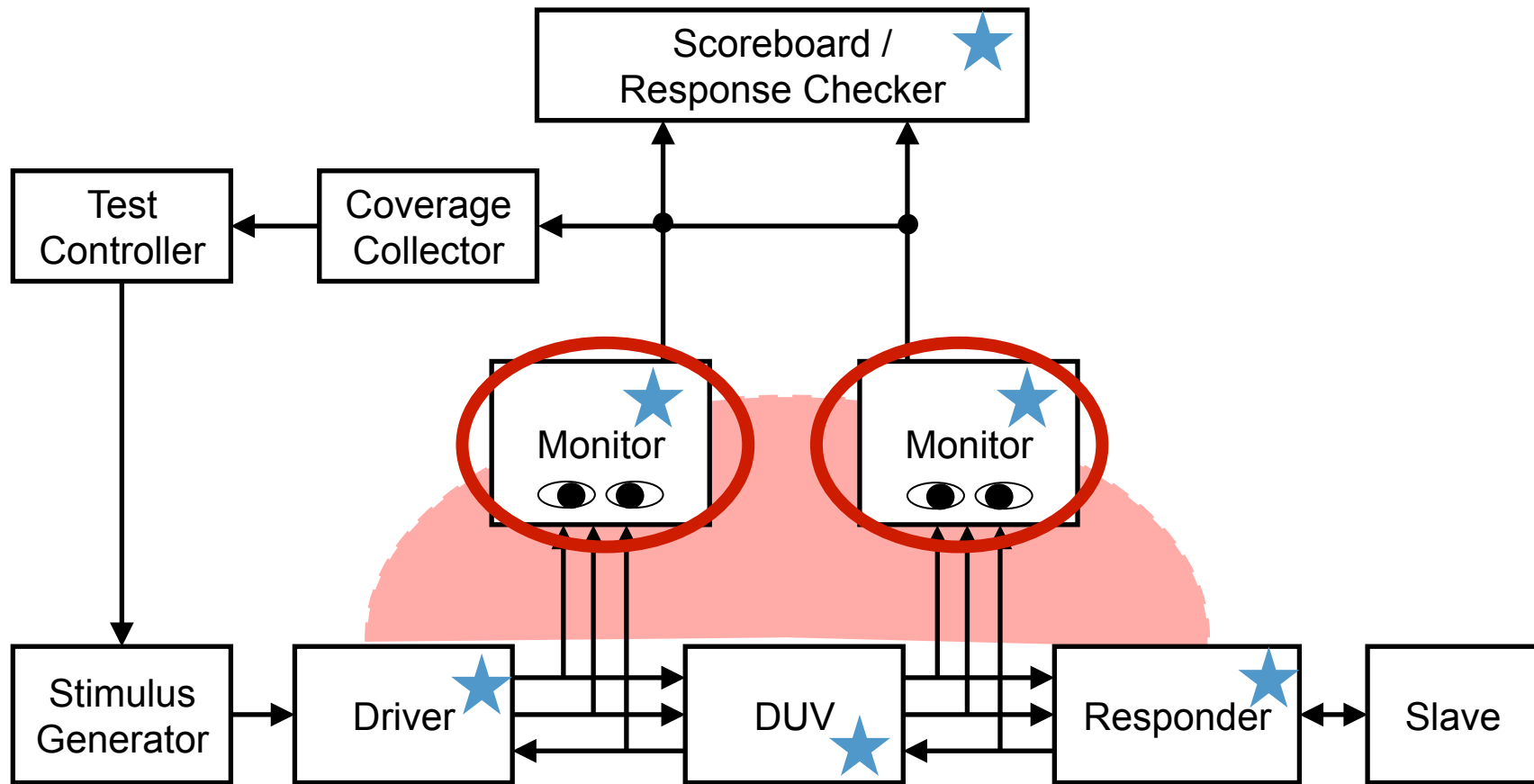
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- Knowledge of the DUV functionality can be built into the TB.
  - This automates the checking process.
  - Verification engineers encode their knowledge of correct DUV functionality into the checkers, monitors and scoreboard using:
    - Golden Vectors,
    - Reference Models,
    - Protocols or Transactions.
- This results in a **“self-checking” TB.**
  - Checkers are “always” active.

# Contemporary TB Architecture

# Contemporary Testbench Architecture

H. Foster: "Response checkers, monitors and assertions". In Practical Design Verification by Pradhan and Harris (editors). Cambridge, 2009.



★ Assertions



# Monitors

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- Monitors are TB components that observe the inputs, outputs, or internals of the DUV.
  - Monitors watch activity of the DUV.
    - Black box: DUV inputs and outputs
    - Grey box: potentially selected internals
  - Monitors can convert low-level signals to transactions.
  - Monitors can flag simple timing and protocol errors.
  - Monitors collect functional coverage.
  - Monitors update the scoreboard.
  - Monitors don't drive DUV pins; they are “passive”.
    - Monitors are self-contained and don't cause “side effects”.
    - Monitors are re-usable at different levels of abstraction.

# Types of Monitors

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- Input monitors:
  - Collect inputs to the DUV and pass them to scoreboard.
  - Can have checker components.
- Output monitors:
  - Observe the outputs from the DUV and pass them to the scoreboard.
  - Can have checker components.
- Coverage monitors
  - Collects inputs, outputs and selected internal signals.
  - Permit analysis of stimulus and functionality coverage.

# Checking Technologies

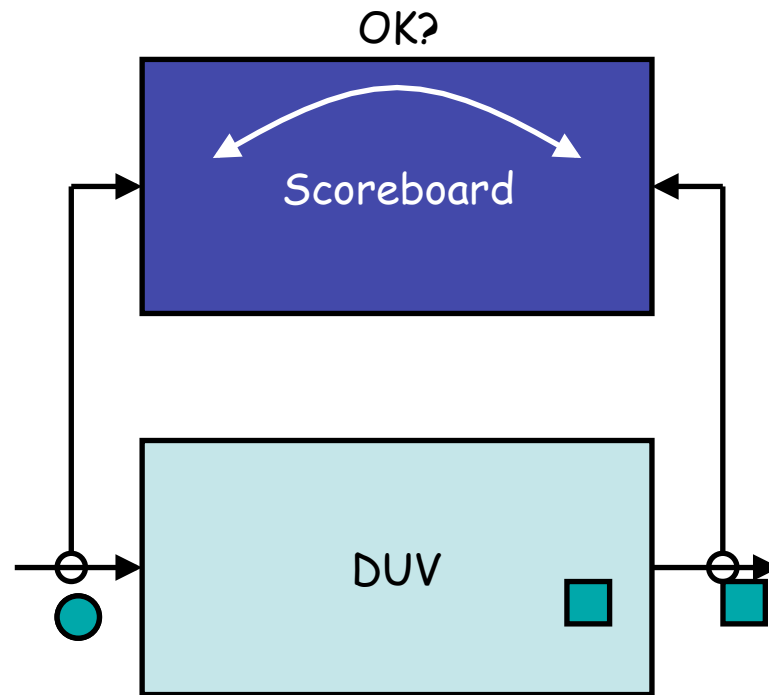
# Scoreboards

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- Scoreboards are **smart data structures** that keep track of events in the DUV during simulation
- Usually, scoreboards are global
  - **One scoreboard per verification environment**
- Scoreboard are not checking mechanisms, but
  - The main purpose of using scoreboards is for checking
  - In practice, many checkers are implemented inside scoreboards
  - There are many typical checks that are done with scoreboards

# Scoreboard Operation

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# Scoreboards Overview

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- Scoreboards source information from
  - the inputs and outputs of the DUV, and
  - occasionally also from internal events in the DUV.
- Scoreboards are very useful in dataflow designs
  - Routers, cache designs, queues
- Types of checks enabled using a scoreboard:
  - Matching outputs with inputs
    - No loss of data
      - Detect inputs with no matching output.
    - No creation of data
      - Detect output with no matching input.
    - No unintended modification of data
  - Timing specification
    - Delay from input to output remains within specified limits.
  - Data order

# Scoreboarding in e - 1

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- Assume: DUV does not change order of packets.
  - Hence, first packet on scoreboard has to match received packet.

```
import packet_s;
unit scoreboard {
  !expected_packets : list of packet_s;
  add_packet(p_in : packet_s) is {
    expected_packets.add(p_in);
  };
  check_packet(p_out : packet_s) is {
    var diff : list of string;
    -- Compare physical fields of first packet on scb with p_out.
    -- Report up to 10 differences.
    diff = deep_compare_physical(expected_packets[0], p_out, 10);
    check that (diff.is_empty())
    else dut_error("`Packet not found on scoreboard'",
diff);
    -- If match was successful, continue.
    out("`Found received packet on scoreboard.'");
    expected_packets.delete(0);
  };
};
```

# Scoreboarding in e - 2

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## Recording a packet on the scoreboard:

Extend driver such that

- When packet is driven into DUV call **add\_packet** method of scoreboard.
  - Current packet is copied to scoreboard.
- It is useful to define an **event** that indicates when packet is being driven.

## Checking for a packet on the scoreboard:

Extend receiver such that

- When a packet was received from DUV call **check\_packet**.
  - Try to find the matching packet on scoreboard.
- It is useful to define an **event** that indicates when a packet is being received.



# Side Note – Graceful End-of-test

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- Checking that nothing is lost is very important
- If an input does not have a matching output, how can we distinguish between two cases
  - The input is lost or hopelessly stuck in the DUV
  - The DUV did not have enough time to handle the input
- Possible solution – Start a timer when a new input enters the DUV
  - If the timer expires, that input is lost or stuck
  - But, what if the delay cannot be bound?
- Alternative (or complementary) solution – stop the inputs before the end of the test and let the design clean itself
  - Because there are no new inputs, things that are stuck inside have a chance to get free

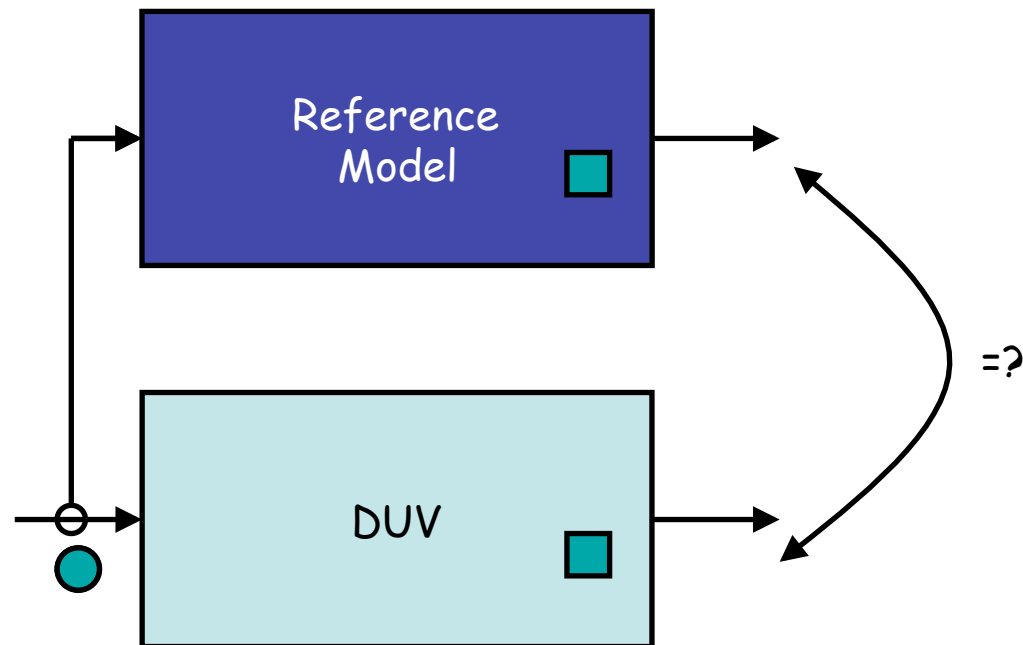
# Reference Models

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- A reference model is an oracle that tells how the DUV should behave
  - Usually in the form of an alternative implementation
- It runs in parallel to the DUV, using the same inputs and provides the checking mechanisms with information about the expected behavior
  - Checking is done by comparing the expected behavior to the actual one
- Pure reference models can run independently of the DUV
  - But not all reference models are pure (example later)

# Reference Model Operation

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# Reference Models

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- Reference models have many uses
  - Checking
  - Aids for stimuli generation
  - “Smart” BFM – imitate the function of the DUV
  - Vehicles for SW development
- What can we check with a reference model
  - In principal, anything
  - In practice it depends on the level of details and accuracy of the reference model
    - And how much of its behavior we are willing to expose

# Levels of Abstraction

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- The level of abstraction in a reference model dictates the type of information we can get out of it for checking
  - **Functionally accurate models** can be used only to check correctness of data, usually at the end of the test or at well defined points in time
    - Timing, order, and other checks need other means
  - **Cycle accurate models** can be used for checking all aspects of I/O behavior
  - **Cycle accurate and latch accurate models** can be used also for checking the internal state of the DUV
    - The book calls this type of model deep function reference model

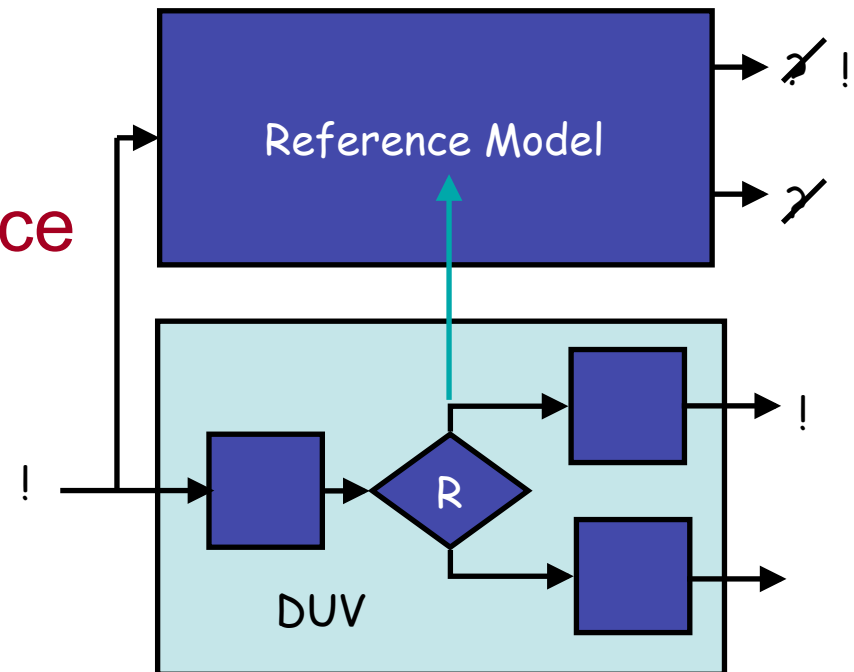
# Impure Reference Model

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- Sometimes it is impossible (or very hard) for the reference model to duplicate significant decisions made by the DUV

- Possible solution:

Use information from the DUV to assist the reference model!



# Rule-based Checking

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- Checks that a set of rules hold in the DUV
- Essentially, all checking is rule-based

if (not something) then error

- Something can be
  - Value of a register matches value in reference model
  - Data in a packet at the DUV output matches data in the input as stored in the scoreboard
  - `response_out == 0`  $\rightarrow$  `data_out == 0`
- Rule-based checking usually refers to the last case

# Rule-based Checking

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- Rules can come from many sources
  - All levels of the design process
    - Spec, high-level design, implementation
  - Behavior of neighboring units
- Rules checking can be implemented in many places
  - External checking tools
  - Various places in the verification environment
    - Interface monitors
    - Scoreboards
    - End-of-test checkers
  - In the DUV itself
- Rule-based checking that is embedded in the DUV code is called **assertions**
- Lecture on **Assertion-Based Verification**



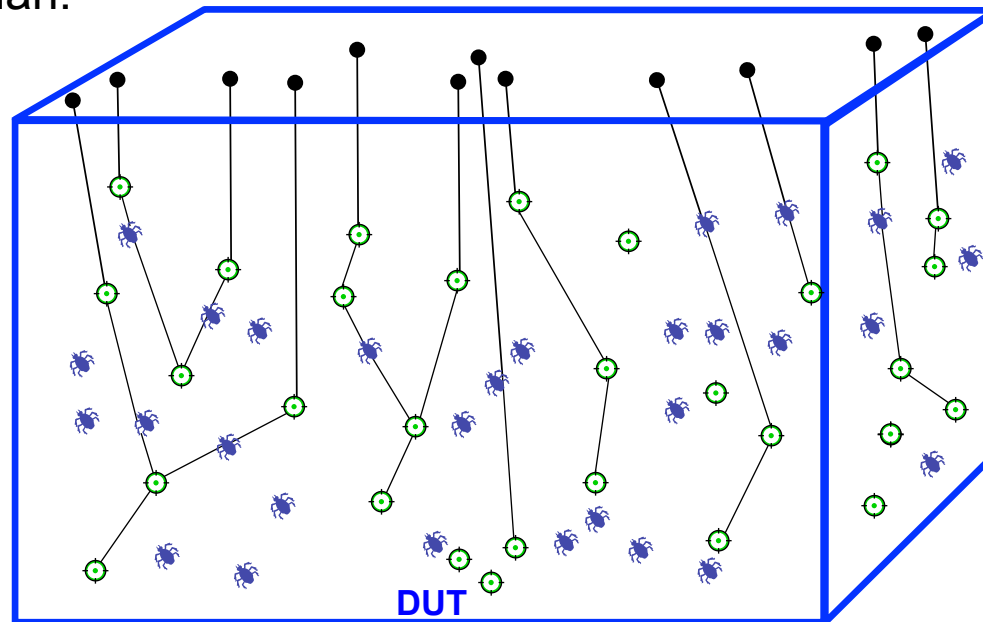
Putting Coverage, Generation and  
Checking together:

# **The Verification Environment**

(With many thanks to Cadence for providing the animations in this section.)

# Traditional Approach: Directed Testing

Verification engineer sets goals and writes directed test for each item in the Verification Plan:



**Automation**

Significant manual effort to write all the tests

**Automation**

Work required to verify each goal was reached

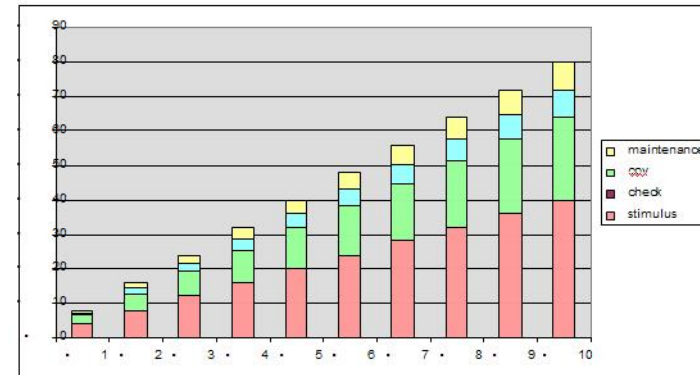
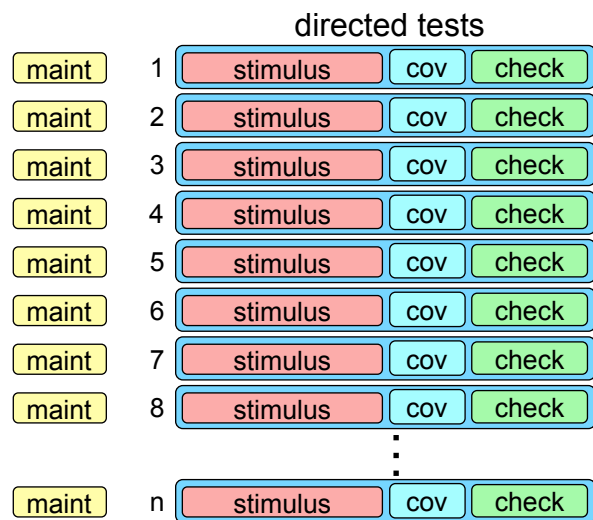
**Completeness**

Poor coverage of non-goal scenarios  
... especially the cases that you didn't "think of"

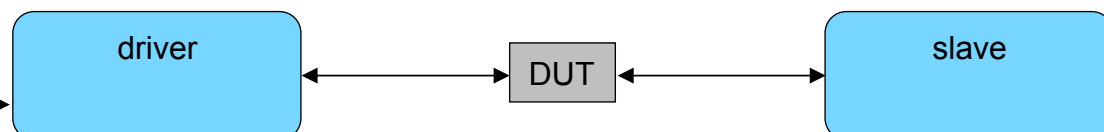
Redo if design changes

# Directed Test Environment

- Composition of a directed test
  - Directed tests contain more than just stimulus.
  - Checks are embedded into the tests to verify correct behavior.
  - The passing of each test is the indicator that a functionality has been exercised.
- Reusability and maintenance
  - Tests can become quite complex and difficult to understand the intent of what functionality is being verified
  - Since the checking is distributed throughout the test suite, it is a lot of maintenance to keep checks updated
  - It is usually difficult or impossible to reuse the tests across projects or from module to system level
- The more tests you have the more effort is required to develop and maintain them

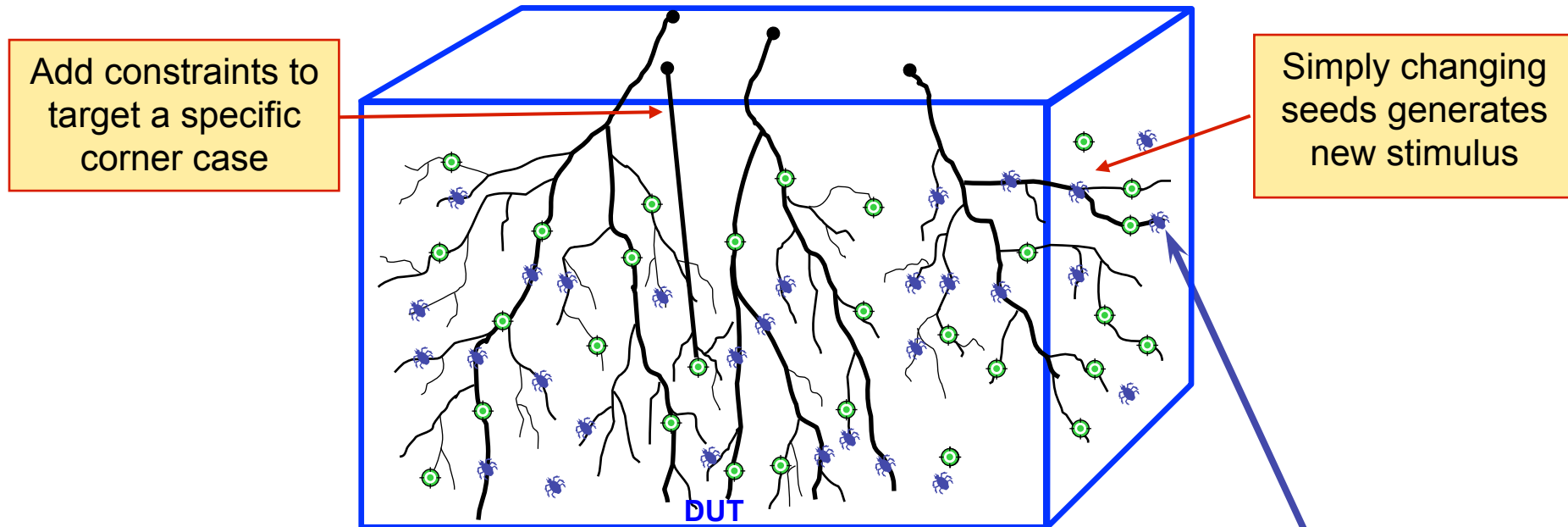


Directed test approach



# Coverage Driven Verification Methodology: *Defining Coverage “Goals” Enables Automation*

Focuses on reaching **goal areas** (*versus execution of test lists*):



Constrained-random stimulus **generation** explores goal areas (& beyond).

**Coverage** shows which **goals** have been exercised and which need attention

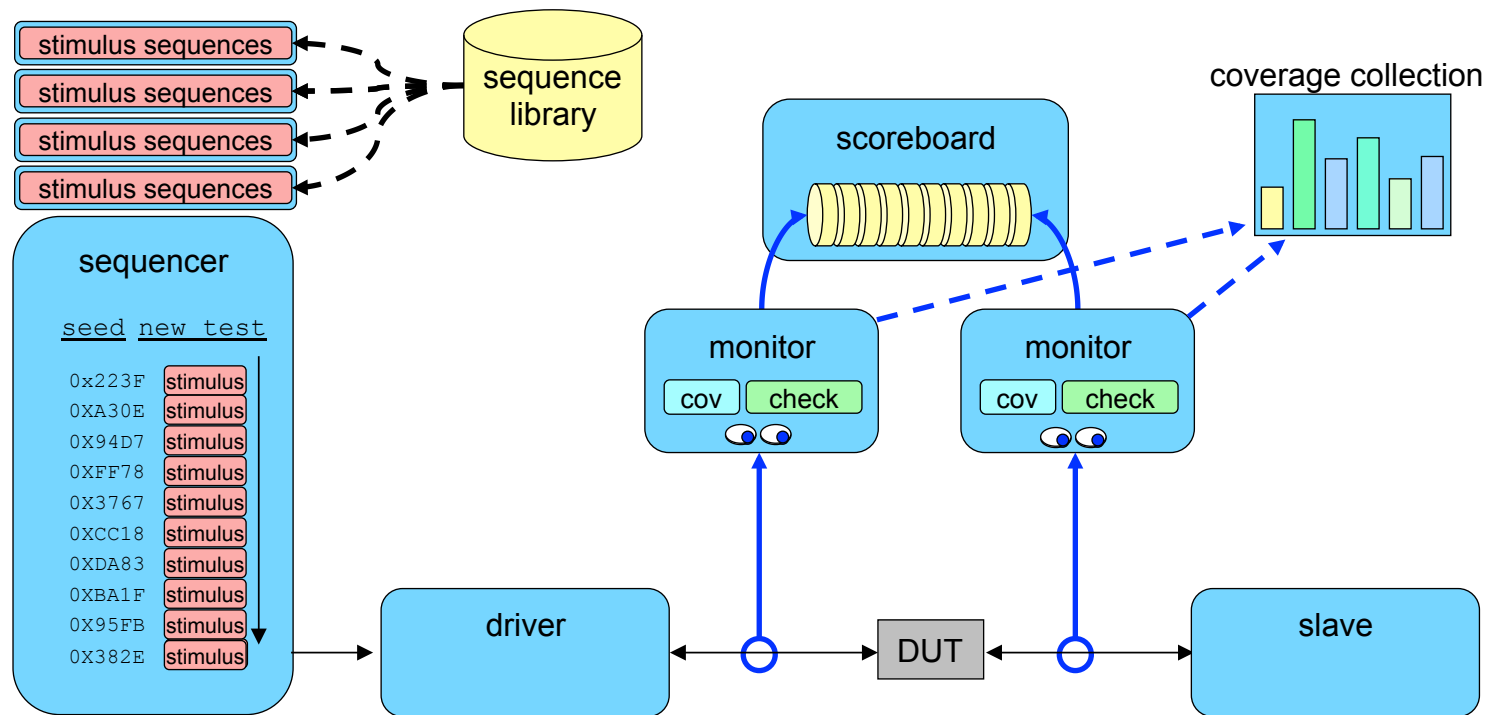
(Self-Checking ensures proper DUT response.)

*Even for non-goal states!*

**Automation** – Constrained-random stimulus accelerates hitting coverage goals and exposing bugs. Coverage and checking results indicate effectiveness of each simulation, which enables scaling many parallel runs.

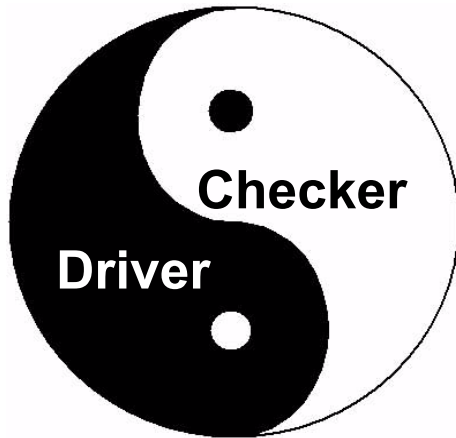
# Coverage Driven Environment

- Composition of a coverage driven environment
  - Reusable stimulus sequences developed with “constrained random” generation
  - Running unique seeds allows the environment to exercise different functionality
  - Monitors independently watch the environment
  - Independent checks ensure correct behavior.
  - Independent coverage points indicate which functionality has been exercised.



# Summary

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- Stimuli Generation
- Coverage and
- Checking

Coverage Driven Verification  
Methodology