

COMSM0115 Design Verification: Tools for Simulation- based Verification

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(Acknowledgement: Avi Ziv from the IBM Research Labs in Haifa has kindly permitted the re-use of some of his slides.)



Department of
COMPUTER SCIENCE

Last Time

- Verification hierarchy
 - Levels of verification
- Fundamentals of Simulation-based Verification:
 - Strategy
 - Driving principles
 - Checking strategies



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Achieving Automation

Task of Verification Engineer:

- Ensure product is not a Type II mistake (false positive) - as fast and as cost-effective as possible.
- (... and of Verification Team Leader):
 - Select/Provide appropriate tools.
 - Select a verification team.
 - Decide when cost of finding next bug violates **law of diminishing returns**.
- Parallelism, Abstraction and **Automation** can reduce the duration of verification. (Automation is currently the least applicable!)
- Automation reduces human factor, improves efficiency and reliability.
- Verification TOOLS** are used to achieve automation.
 - Tool providers: Electronic Design Automation (EDA) industry

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Functional Verification Tools

Tools used for simulation-based verification:

- Linting Tools
- General purpose HDL Simulators**
 - Event-driven simulation
- Improving simulation performance**
 - Raising the abstraction level
 - Cycle-based simulation
 - Synchronous design methodology
 - Hardware accelerators
- Waveform Viewers**
 - Third Party Models
 - For programming: **Verification Languages** (Non-HDL!)
 - Version Control(!)
 - Issue Tracking(!)
 - Metrics
 - Coverage** (later in more detail)

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Linting Tools

- Linters are **static** checkers.
- Assist in finding common coding mistakes
 - Linters exist for software and also for hardware.
 - `gcc -Wall` (Did you know this existed?)
- Only identify certain classes of problems
 - Many false negatives are reported.
 - Use a **filter** program to reduce false negatives.
 - Careful - don't filter true negatives though!
- Does assist in enforcing **coding guidelines!**
- Rules for coding guidelines can be added to linter.

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General HDL Simulators

- Most Popular Simulators in Industry
 - Mentor Graphics ModelSim - MTI VSIM**
 - Cadence NCSim - Verilog XL**
 - Synopsys VCS
- Support for full language coverage
 - "EVENT DRIVEN" algorithms
- VHDL's execution model is defined in detail in the IEEE LRM (Language Reference Manual)
- Verilog's execution model is defined by Cadence's Verilog-XL simulator ("reference implementation")

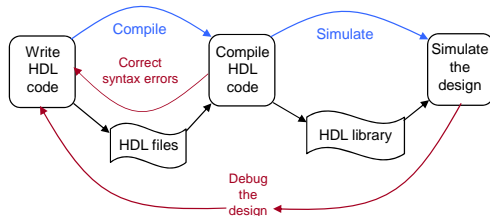
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Simulation based on Compiled Code

- To simulate with **ModelSim**:
 - Compile HDL source code into a library.
 - Compiled design can be simulated.



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Simulation-based Design Verification

- Simulate the design (not the implementation) **before** fabrication.
- Simulating the design relies on simplifications**:
 - Functional correctness/accuracy can be a problem.

Verification Challenge: "What input patterns to supply to the Design Under Verification (DUV) ..."

- Simulation requires **stimulus**. It is dynamic, not just static!
- Requires to reproduce environment in which design will be used.
 - Testbench** (Remember: Verification vs Testing!)

Verification Challenge: "... and knowing what is expected for the output for a properly working design."

- Simulation outputs are validated externally** against design intent (specification)
 - Errors cannot be proven not to exist!

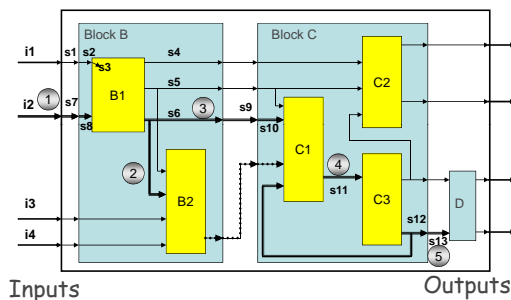
Two types of simulators: **event-based** and **cycle-based**

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Event Flow Example



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Event-based Simulators

Event-based simulators are driven based on **events**. ☺

- Outputs are a function of inputs:
 - The outputs change only when the inputs do.
 - The event is the input changing.**
 - An event causes the simulator to re-evaluate and calculate new output.
- Outputs (of one block) may be used as inputs (of another) ...
- Re-evaluation happens until no more changes propagate through the design.**
- Zero delay cycles are called **delta cycles**!

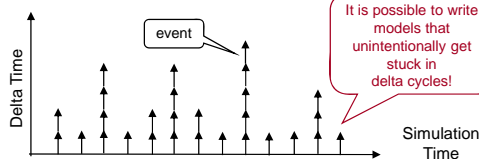
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Delta Cycles

- Event propagation** may cause new values being assigned after **zero** delays.
 - (Remember, this is only a **model** of the physical circuit.)
- Although **simulation time** does **not advance**, the **simulation makes progress**.



- NOTE:** Simulation progress is first along the zero/delta-time axis and then along the simulation time axis.

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Event Driven Principles

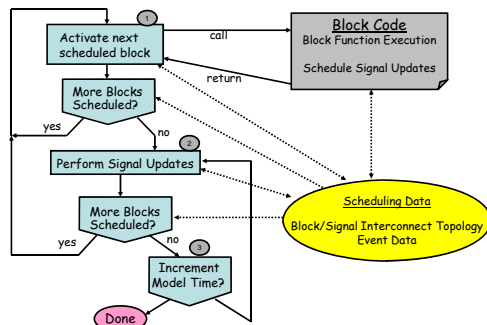
- The event simulator maintains many lists:
 - A list of all **atomic** executable blocks
 - Fanout lists: A data structure that represents the interconnect of the blocks via signals
 - A **time queue** – points in time when events happen
 - Event queues** – one queue pair for each entry in the time queue
 - Signal update queue
 - Computation queue
- The simulator needs to process all these queues at simulation time.

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Core Algorithm of an Event-Driven Simulation Engine



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Improving Simulation Speed

- The most obvious **bottle-neck** for functional verification is **simulation throughput**
- There are several ways to improve throughput
 - Parallelization
 - Compiler optimization techniques
 - Changing the level of abstraction
 - Cycle-based simulation
 - Special simulation machines

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Parallelization

- Efficient parallel simulation algorithms are hard to develop
 - Much parallel event-driven simulation research
 - Has not yielded a breakthrough
 - Hard to compete against "trivial parallelization"
- Simple solution – run independent testcases on separate machines
 - Workstation "SimFarms"
 - 100s - 1000s of engineer's workstations run simulation in the background

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Compiler Optimization Techniques

- Treat sequential code constructs like general programming language
- All optimizations for language compilers apply:
 - Data/control-flow analysis
 - Global optimizations
 - Local optimizations (loop unrolling, constant propagation)
 - Register allocation
 - Pipeline optimizations
 - etc.
- Global optimizations are limited because of model-build turn-around time requirements
 - Example: modern microprocessor is designed w/ ~1Million lines of HDL
 - Imagine the compile time for a C-program w/ 1M lines!

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Changing the Level of Abstraction

- Common theme:
 - Cut down of number of scheduled events
 - Create larger sections of un-interrupted sequential code
 - Use less fine-grain granularity for model structure
 - Smaller number of schedulable blocks
 - Use higher-level operators
 - Use zero-delay wherever possible
- Data abstractions
 - Use binary over multi-value bit values
 - Use word-level operations over bit-level operations

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Changing the Level of Abstraction

```

s(0) <= a(0) xor b(0);
c(0) <= a(0) and b(0);
s(1) <= a(1) xor b(1) xor c(0);
c(1) <= (a(1) and b(1)) or (b(1) and c(0)) or (c(0) and a(1));
sum_out(1 to 0) <= s(1 to 0);
carry_out <= c(1);

s(2 to 0) <= ('0' & a(1 to 0)) + ('0' & b(1 to 0));
sum_out(1 to 0) <= s(1 to 0);
carry_out <= s(2);

process(a, b)
begin
    s(2 to 0) <= ('0' & a(1 to 0)) + ('0' & b(1 to 0));
    sum_out(1 to 0) <= s(1 to 0);
    carry_out <= s(2);
end process
    
```

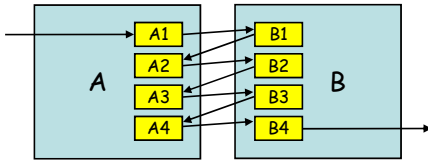
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Changing the Level of Abstraction

- Scheduling the small blocks
 - {A1, B1, A2, B2, A3, B3, A4, B4}
 - Each small block is executed once
- Scheduling the big blocks
 - {A, B, A, B, A, B, A, B}
 - A = A1 and A2 and A3 and A4
 - Each small block is executed 4 times

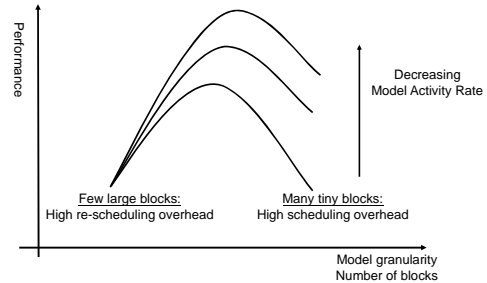


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Changing the Level of Abstraction



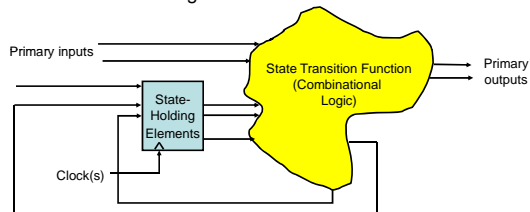
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Synchronous Design Methodology

- The design is comprised of
 - State-holding (storage) elements
 - Combinational logic for state transition function



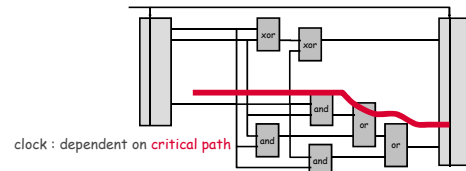
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Synchronous Design Methodology

- Clock the design only so fast as the longest possible combinational delay path settles before cycle is over
- Cycle time depends on the **longest topological path**
 - Hazards/Races do not disturb function
 - Longest topological path can be analytically calculated w/o using simulation -> stronger result w/o sim patterns



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Cycle Based Model Build Flow

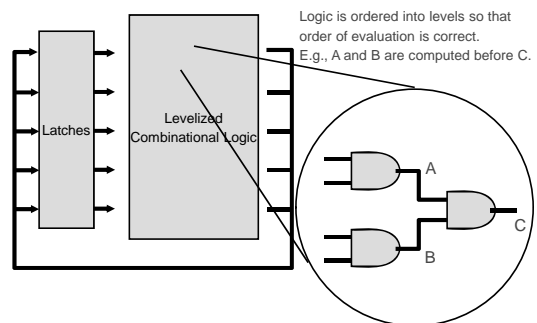
- Language **compile** – **synthesis**-like process
 - Logic mapped to a non-cyclic network of Boolean functions
 - Hierarchy is preserved
- **Flatten hierarchy** – crush design hierarchy to increase optimization potential
- **Optimization** – minimize the size of the model to increase simulation performance
- **Levelize logic**
- **Translate to instructions**

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Model Build – Levelization

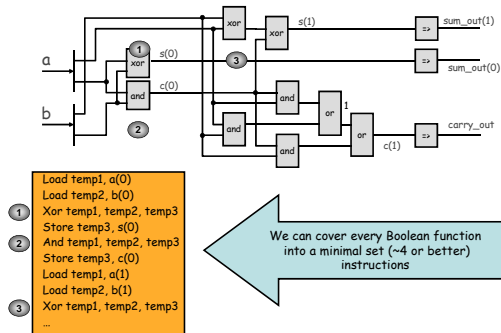


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Translate to Instructions



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Parallelism in Generated Code Cycle-Sim

- Word-level operations can be easily parallelized

$A(0 \text{ to } 31) \leq B(0 \text{ to } 31) \text{ and } C(0 \text{ to } 31) \text{ and } D(0 \text{ to } 31)$

Is translated into

```
LoadWord R1, B(0 to 31)
LoadWord R2, C(0 to 31)
AND R1, R1, R2
LoadWord R2, D(0 to 31)
AND R1, R1, R2
StoreWord R1, A(0 to 31)
```

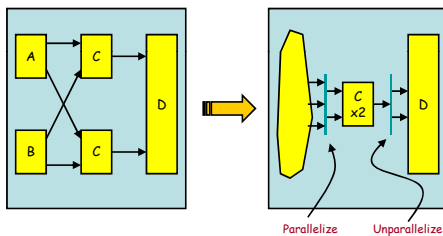
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Parallelism in Generated Code Cycle-Sim

- Across similar blocks in the hierarchy



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Hardware Acceleration

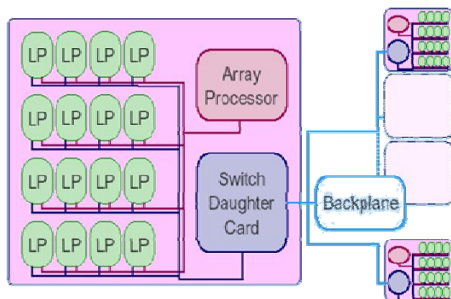
- Programs created for **cycle simulation** are very simple
 - Small set of instructions
 - Simple control – no branches, loops, functions
- Operations at the same level can be executed in parallel**
- Hardware acceleration** uses these facts for fast simulation by utilizing
 - Very large number of small and simple special-purpose processors
 - Efficient communication and scheduling

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Accelerator Basic Structure



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Accelerator: Principle of Operation

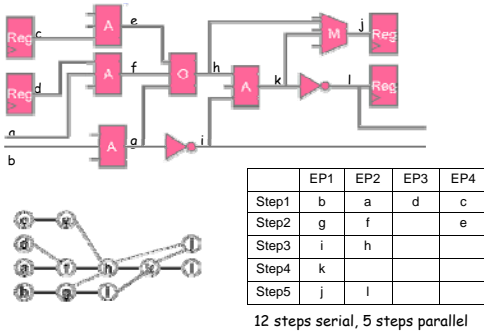
- Compiler** transforms combinational logic into Boolean operations
- Compiler** schedules interprocessor communications using a fast broadcast technique
- Emulation performance dictated by:
 - Number of processors
 - Number of levels in the design

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Scheduling Example



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Simulation Speed Comparison

Event Simulator	1
Cycle Simulator	20
Event driven cycle Simulator	50
Acceleration	1000
Emulation	100000

Why do Event-based Simulators still exist?

What is the cost of the speedup?

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Co-Simulation

- Co-simulators are a combination of event, cycle and other tools, e.g. accelerators, emulators.
- Performance is decreased** due to inter-tool communication overhead.
- Ambiguities arise** during translation from one simulator to the other.
 - Verilog's 128 possible states to VHDL's 9!
 - Analog current and voltage into digital logic value and strength.

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Waveform Viewers

- Often considered as part of a simulator.
- Most common verification tools used...**
- Used to **visually inspect** design/testbench/verification environment.
 - Recording waves decreases performance of simulator. (Why?)
- Don't use viewer to determine if design passes or fails a test.**
- Use waveform viewer for debugging.** (Assignment 1)
- Advanced waveform viewers can **compare** waveforms.
 - Problem is how to determine what is the "golden wave".
 - Most applicable to redesign, where design must maintain cycle by cycle compatibility. (Assumes previous design was correct!)
 - Pitfall when doing comparisons:** Comparison fails when...
 - Absolute value** of signals is not so important - **relative relationship between events** is (often) more important.

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Third Party Models

- Chip needs to be verified in its **target environment**.
 - Board/SoC Verification
- Do you develop or purchase behavioural models (specs) for board parts?
 - Buying them may seem expensive!
 - Ask yourself:
 - "If it was not worth designing on your own to begin with, why is writing your own model now justified?"
 - The model you develop is not as reliable as the one you buy.
 - The one you buy is used by many others - not just yourself.
- Remember: In practice, it is often more expensive to develop your own model to the **same degree of confidence** than licensing one.

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Verification Languages

- Need to be designed to address **verification** principles.
- Deficiencies in RTL languages (HDLs such as Verilog and VHDL):
 - Verilog** was designed with focus on describing low-level hardware structures.
 - No support for **data structures** (records, linked lists, etc).
 - Not object-oriented. Useful when several team members develop testbenches.
 - (VHDL was designed for large design teams.)
- Limitations inhibit **efficient** implementation of verification strategy.
- High-level verification languages are (currently):
 - e-language used for Specman Elite** [IEEE P1647]
 - Synopsys' Vera, System C, SystemVerilog

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Any other *verification* Languages?

Tommy Kelly, CEO of Verilab:

“Above all else, the Ideal Verification Engineer will know how to construct software.”

- Toolkit contains not only **Verilog**, VHDL, Vera and e, but also: Python, Lisp, MySQL, Java, ... ☺

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Version Control Software

- **Concepts for version control:**
 - Files must be centrally managed.
 - It must be easy to get the files. (Simplify access.)
 - Files are owned by team - not by one individual!
 - (Advanced: Automatic notification of changes via e-mail.)
 - History is kept for each file.
 - Examples: Subversion (see <http://subversion.tigris.org/>) or CVS.
- HDL design/verification is similar to managing a large software project!
- Software Engineers can bring valuable skills to design/verification.

Why is version control considered a verification tool?

- To ensure that what is being verified is actually what is being implemented. Wouldn't you hate to spend a month verifying something that is out of date...?

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Issue Tracking

- Another tool often not considered a verification tool.
 - Verification engineer's job is to **find bugs**. :)
 - Issue tracking is used to deal with the bugs that are found – **bugs must be fixed!**
- Two things to consider:
 - **What is an issue?**
 - **How to track it?**

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What is an issue?

- The cost of tracking an issue should not be greater than the cost of the issue itself!
- An **issue** is anything that can effect the functionality of the design!
 - Bugs found during execution of testbench.
 - Ambiguities or incompleteness of a specification.
 - Architectural decisions/trade-offs.
 - Errors found at all stages of the design (in the design or the verification environment).
 - New but relevant stimuli (corner cases) that are not part of the **verification plan**.
- Basic principle: **When in doubt - track it!**
- Some bugs might not be worth fixing in the current product, but we want to capture the issue so that they are fixed in next revision of chip.

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How to track an issue?

- Different methods - more or less successful...
 - “Grapevine”, Post-It, Procedural, ...
- **Computerised system:** e.g. track (see <http://trac.edgewall.org/>)
 - **Use a computer system (usually database) to track issues!**
 - Issues are seen through to resolution.
 - Issues can be assigned and/or reassigned to individuals or small teams.
 - Automatic e-mail notification:
 - of new issues, of status of top issues, etc.
 - **Contains a history.**
 - Provides **lessons-learned database** for others.

Some computerised issue tracking systems fail - why?

Biggest problem: **Ease of use!!!**

– **It should not take longer to submit an issue than to fix it!**

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Metrics

- Not really a verification tool - but managers love metrics and measurements!
 - Managers often have little time to personally assess progress.
 - They want something measurable.
- **Coverage** is one metric - will be introduced later.
- **Others metrics include:**
 - Number of lines of code;
 - Ratio of lines of code (between design and verifier);
 - Drop of source code changes;
 - Number of outstanding issues.

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Summary

Now we have (Ch2 of WTB)

- Investigated **verification tools**
 - **Linting tools** are static code checkers.
 - **Simulators** exercise design to find functional errors.
 - **Waveform viewers** display simulation results graphically.
 - **Version control** and **issue tracking** help manage design data.
 - **Metrics** help management to understand/monitor progress of design project and to measure productivity gains.
- TODO: **Coverage** - e.g. code coverage, functional coverage.
- **Next:**
 - Intro to Calculator Calc1 design for Assignment A1.
 - **Verilog brief introduction – You need to do the tutorial!**