COMS31700 Design Verification

# **Hardware Design** Languages

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### Hardware Design Languages

- Hardware Design Languages were built with simulation in mind

   Synthesis and other back-end purposes were added at a later stage
- Most popular languages today (both are IEEE standards)
- VHDL Verilog/SystemVerilog
- VHDL:
  - Committee-designed language contracted by U.S. (DoD) (ADA-derived)
    Functional/logic modeling and simulation language
    Main differentiator from Verilog is types (e.g. records)
- Main unresemble.

  Verilog:
  Logic modeling and simulation language
  Logic modeling and simulation language
  Statred in EDA industry in the 80's then owned by Cadence
  Donated to IEEE as a general industry standard
  SystemVerilog (the next generation of Verilog) is designed to improve abstraction of Verilog

  \*\*Abstraction levels\*\*
- Verilog vs. VHDL: personal preferences. EDA tool availability, commercial.

#### Modeling Levels - Major Dimensions



- Data Abstraction:
  - Data Abstraction:

     continuous (analog)

     bit : multiple values

     bit : binary

     abstract value

     composite value ("struct")

    Functional Dimension:

     continuous functions (e.g. differential equations)

     Switch-level (transistors as switches)
- Switch-level (transistors as switches)
   Boolean Logic
   Algorithmic (e.g. sort procedure)
   Abstract mathematical formula (e.g. matrix multiplication)

  Structural Dimension:
   Single black box
   Functional blocks
   Detailed hierarchy with primitive library elements

#### Modeling Levels - Major Dimensions Temporal Gate Delay Clock Cycle Instruction Cvcl Data \_\_\_ \_ \_ \_ \_ \_ Structural Single Black Box Functional Blocks - VHDL - Extremely inefficient

## Verilog for Design Verification

- Assignment calc1 design in Verilog
  - Testbench for calc1 design in Verilog
- Interactive Evita Verilog tutorial (Ch1-4,5-7):
  - Structure of Verilog modules
  - Verilog signal values: 0, 1, x and z (4-valued logic)
  - Verilog signals:
    - nets (used for "connections", no storage capacity)
    - registers (storage capacity, similar to variables in pgr languages)
  - Verilog external signals:
  - ports (input, output or inout, port connecting rules)
     Coding styles:
  - - Structural
    - Dataflow
    - Behavioural (best for verification)

#### Continuous Assignment

- Used in Dataflow coding style.
- Keyword assign followed by optional delay declaration
- LHS (target) can be net (scalar or vector) or concatenation of nets
  - NO registers allowed as target for assignment!
- Assignment symbol: =
- RHS is an expression.
- assign #4 Out = In1 & In2;
- Implicit continuous assignment: wire x = ...;
- Conditional assignment:
  - assign Out = Sel ? In1 : In0;
     If Sel is 1 then In1 is assigned to Out; if Sel is 0 then Out is
  - In0.
  - If  $\mathtt{Sel}$  is x/z, evaluate both  $\mathtt{Inl}$  and  $\mathtt{In0}$ , if they are the same then  $\mathtt{Out}$  is assigned this value, otherwise x/z.

#### Continuous Assignment: Execution

- Continuous assignments are always active.
- Concurrency:
  - When any of the operands on RHS changes, assignment is evaluated.
  - Several assignments can be executed concurrently.
  - Race conditions can occur!
    - Two or more assignments, which operate on the same data, read and write the data concurrently.
    - Result, which might be erroneous, depends on which assignment does what when.
- Delays specify time between change of operand on RHS and assignment of resulting value to LHS target.
  - assign #4 Out = In1 & In2;

#### Behavioural Coding Style

- Most advanced coding style: flexible and high-level

 closest to programming languages
 allows use of conditional statements, case statements, loops, etc. Best for verification, but by no means ideal...

- Rehaviour:
  - Actions a circuit is supposed to perform when it is active.
- Algorithmic description: Need "variables" similar to PLs!
  - Abstraction of data storage elements register objects:

     reg R; one bit register default value x before first assignment

     time T; can store/manipulate simulation time

     integer N; by default at least 32 bit stores values signed

  - real R; default value is 0
  - [Other data types, e.g. arrays exist, but are out of the scope of this introduction.]

#### Mux421: Behavioural Coding Example

```
module mux421_behavioural (Out, In0, In1, In2, In3, Sel0, Sel1);
  output Out;
input In0, In1, In2, In3, Sel0, Sel1;
  reg Out;
always @ (Sel1 or Sel0 or In0 or In1 or In2 or In3)
      case ({Sell.Sel0})
     case ((Sel1, Sel0))
2'b00 : Out = In0;
2'b01 : Out = In1;
2'b10 : Out = In2;
2'b11 : Out = In3;
default : Out = 1'bx;
  endcase
end
endmodule // mux421 behavioural
```

#### Mux421: Behavioural Coding Example

```
module mux421_behavioural (Out, In0, In1, In2, In3, Sel0, Sel1);
   output Out;
input In0, In1, In2, In3, Sel0, Sel1;
   reg Out;
always @ (Sel1,Sel0,In0,In1,In2,In3) // Verilog 2001 style
      case ({Sell.Sel0})
     case ({Sel1,Sel0})
2'b00: Out = In0;
2'b01: Out = In1;
2'b10: Out = In2;
2'b11: Out = In3;
default: Out = 1'bx;
      endcase
endmodule // mux421 behavioural
```

#### **Behavioural Blocks**

- initial and always
  - Can't be nested.
  - Block containing several statements must be grouped using:
    - begin ... end (sequential) or
    - fork ... join (concurrent)
- initial block:
  - Used to initialise variables (registers).
  - Executed at (simulation) time 0. Only once!
- always block:
  - Starts executing at time 0.
  - Contents is executed in infinite loop.
  - Means: Executing repeats as long as simulation is running.
  - Multiple blocks are all executed concurrently from time 0.

## Assignment in Behavioural Coding

Assignment in behavioural coding style is procedural

- LHS (target) must be a register (reg, integer, real or time) not a net, a bit or part of a vector of registers.
- NO assign keyword!
- Must be contained within a behavioural (i.e. initial or always) block.
- NOT always active!
  - Target register value is only changed when procedural assignment is executed according to sequence contained in block.
- Delays: indicate time that simulator waits from "finding" the assignment to executing it.

## Blocking Assignment

(... as opposed to continuous assignment from dataflow coding style.)

```
reg A:
reg [7:0] Vector;
integer Count:
initial
begin
 A = 1'b0;
  Vector = 8'b0;
 Count = 0;
end
```

Sequential initialisation assignment.

#### **Timing Control Evaluation**

```
#5 C = #10 A+B;
```

Assignment delay

Intra-assignment delay

- 1. Find procedural assignment
- 2. Wait 5 time units
- 3. Perform A+B
- 4. Wait 10 time units
- 5. Assign result to C
- So, what is the difference between:
  - #10 C = A+B and
  - C = #10 A+B?

#### **Events and Wait**

- Events mark changes in nets and registers, e.g. raising/falling edge of clock.
  - @ negedge means from any value to 0
  - @ posedge means from any value to 1
  - @ clk always activates when clock changes
- Wait statement:

```
wait (condition) stmt;

    wait (EN) #5 C = A + B;
    waits for EN to be 1 before #5 C = A + B;
```

 Use wait to block execution by not specifying a statement!

```
wait (EN); ...
```

### Sensitivity List

```
always @(sensitivity list) <begin>  procedural stments> <end>
always @ (posedge Clk or EN)
begin ... end
always @ (Sel1,Sel2) // Verilog 2001 style
```

- Allows to suspend always blocks.
- Block executes and suspends until signal (one or more) in sensitivity list changes.
- NOTE: or is used to make statement sensitive to multiple signals or events.
- (Don't use sensitivity list to express a logical condition!)
- Common mistake:
  - Forgetting to add relevant signals to sensitivity list!

# Non-blocking Assignments

- Concurrency can be introduced into sequential statements
  - Delay is counted down before assignment,
     BUT control is passed to next statement immediately.
- Non-blocking Assignments allow to model multiple concurrent data transfers after common event.
   A blocking assignment would force sequential execution.

```
A <= #1 1; B <= #2 0; (non-blocking)
                                             A x 1 1 1
                                             B x x 0 0
                                        Time: 0 1 2 3
A = #1 1; B = #2 0; (blocking)
                                             A x 1 1 1
                                        Time: 0 1 2 3
```

#### Approaches to Assignment - I

```
reg [7:0] MyReg;
  fork
     #50 MvReg = 8'hFF;
     #100 MyReg = 8'h01;
     #150 MyReg = 8'h2F;
#200 MyReg = 8'h00;
     #250 $finish;
  ioin
• Concurrent blocking (=)

Time: 0 50 100 150 200 250

MyReg[7:0] XX FF 01 2F 00 00
Important when driving input into a DUV in a testbench!
```

## Approaches to Assignment - II

```
reg [7:0] MyReg; Race Condition!
  begin
     MyReg <= #50 8'hFF; // pass control, wait, assign
     MyReg <= #50 8'h01;
     MyReg <= #50 8'h2F;
MyReg <= #50 8'h00;
     #250 $finish;
  end

    Sequential non-blocking (<=)</li>

       Time: 0 50 100 150 200 250 MyReg[7:0] XX ??
Important when driving input into a DUV in a testbench!
```

### Approaches to Assignment - III

```
reg [7:0] MyReg;
initial
  begin
      egin

MyReg <= #50 8'hFF; // pass control, wait, assign

MyReg <= #100 8'h01;

MyReg <= #150 8'h2F;

MyReg <= #200 8'h00;
      #250 $finish;
• Sequential non-blocking (<=)

Time: 0 50 100 150 200 250

MyReg[7:0] XX FF 01 2F 00 00
Important when driving input into a DUV in a testbench!
```

## Approaches to Assignment - IV

```
reg [7:0] MyReg;
  begin
     #50 MyReg = 8'hFF; // wait, assign, pass control
     #50 MyReg = 8'h01;
#50 MyReg = 8'h2F;
      #50 MyReg = 8'h00;
     #250 $finish;
   end
• Sequential blocking (=)

Time: 0 50 100 150 200 250

MyReg[7:0] XX FF 01 2F 00 00
Important when driving input into a DUV in a testbench!
```

# HDL vs. Programming Languages

3 major new concepts of HDLs compared to PLs:

- Connectivity:
  - Ability to describe a design using simpler blocks and then connecting them together.
- Time:
  - Can specify a delay (in time units of simulator): (WHY?)
     and #2 (Y3, In3, Sel1, Sel0);
- Concurrency is always assumed! (for structural style this is)
  - No matter in which order primitives/components are specified, a change in value of any input signal activates the component.

    If 2 or more components are activated concurrently, they perform their actions concurrently.

    Order of specification does not influence order of activation!

  - (NOTE: Statements inside behavioural blocks may be sequential -more later.)

#### **Tasks and Functions**

#### Tasks and Functions

- Both are purely behavioural.
  - Can't define nets inside them.
  - Can use logical variables, registers, integers and reals.
- Must be declared within a module.
  - Are local to this module.
  - To share tasks/functions in several modules, specify declaration in separate module and use 'include directive.
- **Timing** (simulation time)
  - Tasks:
  - · No restriction on use of timing; engineer specifies execution.
  - Functions:
    - Execute in ZERO sim time units; no timing/event control allowed.

# Comparing Tasks with Functions

	Tasks	Functions
Timing	can be non-zero sim time	execute in 0 sim time
Calling other tasks or functions	no limit; may enable functions	may not call tasks but may call another function  No recursion!
Arguments	any number; any type; can't return result	at least one input; no output/inout; always results in single return value
Purpose	modularize code	react to some input with single response;
		only combinatorial code; use as operands in expressions

#### **Example Task**

```
task factorial;
  output [31:0] f;
  input [3:0] n;
  integer count; // local variable
  begin
    f = 1:
    for (count=n; count>0; count=count-1)
      f = f * count;
endtask
 Invoke task: < task name > (list of arguments);
```

Declaration order determines order of arguments when task is called!

### **Example Function**

```
function ParityCheck;
  input [3:0] Data;
  begin
    ParityCheck = ^Data; // bit-wise xor reduction
  end
endfunction
```

- Result is by default a 1 bit register assigned to implicitly declared local variable that has same name as function.
- Function calls:
  - Are either assigned to a variable, or
  - occur in an expression that is assigned to a variable,
     or occur as an argument of another function call.

## System Tasks and Functions

- More than 100 Verilog system tasks/functions.
  - (See Evita Verilog Reference Guide for more information )
- · Can be used in any module without explicit include directive.
- Syntax: \$< keyword >
- Most important tasks for verification:
  - \$display, \$monitor
  - \$time, \$stop, \$finish
  - (Also with files: \$fopen, \$fdisplay)

# Summary

- Evita Verilog Tutorial [Ch1-7]
- Verilog HDL IEEE Standard 1364-2001
  - Signals: internal and external (ports)
  - Different coding styles:
    - structural
    - dataflow behavioural
- SystemVerilog builds on IEEE 1364-2005
- HDLs: Connectivity, Time and Concurrency
- BOOK: Verilog HDL by Samir Palnitkar [in QB Library]
- Next: Specification of Assignment 1!