

COMS31700 Design Verification: Coverage

Kerstin Eder

(Acknowledgement: Avi Ziv from the IBM Research Labs in Haifa has kindly permitted the re-use of some of his slides.)



Department of
COMPUTER SCIENCE

Last Time

- Verification Cycle
- Verification Methodology &
- Verification Plan

Previously: **Verification Tools**

Coverage is part of the Verification Tools.

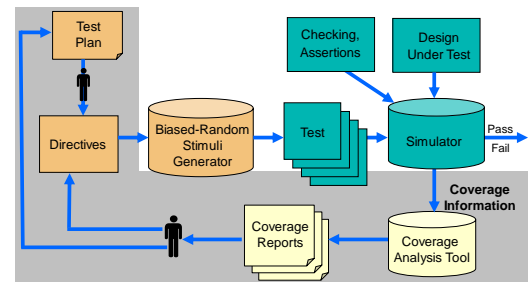
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Outline

- Introduction to coverage
- Code coverage models
- Structural coverage models
- Functional coverage
- Case study and lessons to learn
- Coverage closure

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Simulation-based Verification Environment



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Why Coverage?

- Simulation is based on limited execution samples
 - Cannot run all possible scenarios, but
 - Need to know that all (important) areas of the DUV are verified
- Solution: **Coverage measurement and analysis**
- The main ideas behind coverage
 - Features (of the specification and implementation) are identified
 - Coverage models capture these features

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Coverage Goals

- Measure the "quality" of a set of tests
 - NOTE: Coverage gives ability to see what **has not been verified!**
 - Coverage completeness does not imply functional correctness of the design! Why?
- Help create regression suites
 - Ensure that all parts of the DUV are covered by regression suite
- Provide a stopping criteria for unit testing
- Improve understanding of the design

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Coverage Types

- **Code** coverage
- **Structural** coverage
- **Functional** coverage
- Other classifications
 - Implicit vs. explicit
 - Specification vs. implementation

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Code Coverage - Basics

- Coverage models are based on the HDL code
 - Implicit, implementation coverage
- Coverage models are **syntactic**
 - Model definition is based on syntax and structure of the HDL
- **Generic models** – fit (almost) any programming language
 - Used in both software and hardware design

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Code Coverage - Scope

Code coverage can answer the question:

“Is there a piece of code that has not been exercised?”

- Method used in software engineering for some time.
- Have you used gcov?

Main problem:

- **False positive answers can look identical to true positive answers.**
False positive: A bad design is thought to be good.
- **Useful for profiling:**
 - Run coverage on testbench to indicate what areas are executed most often.
 - **Gives insight on what to optimize!**
- Many types of code coverage report metrics/models.

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Types of Code Coverage Models

- **Control flow**
 - Check that the control flow of the program has been fully exercised
- **Data flow**
 - Models that look at the flow of data in, and between, programs/modules
- **Mutation**
 - Models that check directly for common bugs by mutating the code and comparing results

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Control Flow Models

- **Routine (function entry)**
 - Each function / procedure is called
- **Function call**
 - Each function is called from every possible location
- **Function return**
 - Each return statement is executed
- **Statement (block)**
 - Each statement in the code is executed
- **Branch/Path**
 - Each branch in branching statement is taken
 - if, switch, case, when, ...
- **Expression/Condition**
 - Each (sub-)expression in Boolean expression takes true and false values
- **Loop**
 - All possible number of iterations in (Bounded) loops are executed

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Statement/Block Coverage

Measures which lines (statements) have been executed by the verification suite.

```
✓ if (parity==ODD || parity==EVEN) begin
□ parity_bit = compute_parity(data,parity);
end
✓ else begin
✓ parity_bit = 1'b0;
end
✓ #(delay_time);
✓ if (stop_bits==2) begin
✓ end_bits = 2'b11;
✓ #(delay_time);
end
```

What do we need to do to get statement coverage to 100%?

- Why has this never occurred?
- Is it a condition that can never occur? Was it simply forgotten?
- (Dead code can be “ok!”) WHY?

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Path/Branch Coverage

Measures all possible ways to execute a sequence of statements.

- Are all **if/case** branches taken?
- How many execution paths?

```

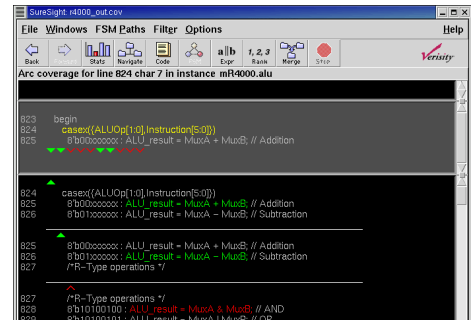
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✓ end
✓ #(delay_time);
✓ if (stop_bits==2) begin
✓ end_bits = 2'b11;
✓ #(delay_time);
✓ end
    
```

Note: 100% statement coverage but only 75% path coverage!

- Dead code: default branch on exhaustive **case**
- Don't measure coverage for code that was not meant to run! (tags)

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Branch Coverage Report



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Expression/Condition Coverage

Measures the various ways paths through the code are executed.

- Where a branch condition is made up of a Boolean expression, want to know which of the subexpressions have been covered.

```

✓ if (parity==ODD || parity==EVEN) begin
✓ parity_bit = compute_parity(data,parity);
✓ end
✓ else begin
✓ parity_bit = 1'b0;
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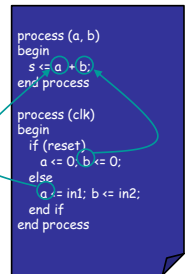
Note: Only 50% expression coverage!

- Analysis: Understand WHY part of an expression was not executed
- Reaching 100% expression coverage is extremely difficult.

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Data Flow Models

- Coverage models that are based on flow of data during execution
- Each coverage task has two attributes
 - Define** – where a value is assigned to a variable (signal, register, ...)
 - Use** – where the value is being used
- Types of dataflow models
 - C-Use – Computational use
 - P-Use – Predicate use
 - All Uses – Both P and C-Uses



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Mutation Coverage

- Mutation coverage is designed to detect simple (typing) mistakes in the code
 - Wrong operator
 - + instead of -
 - >= instead of >
 - Wrong variable
 - Offset in loop boundaries
- A mutation is considered covered if we found a test that can distinguish between the mutation and the original
 - Strong mutation – the difference is visible in the primary outputs
 - Weak mutation – the difference is visible inside the DUV
- For more on Mutation Coverage see: *J Offutt and R.H. Untch. "Mutation 2000: Uniting the Orthogonal"*
- Commercial tools: Certitude by SpringSoft
<http://www.springsoft.com/products/functional-qualification/certitude>

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Code Coverage Models for Hardware

- Toggle coverage
 - Each (bit) signal changed its value from 0 to 1 and from 1 to 0
- All-values coverage
 - Each (multi-bit) signal got all possible values
 - Used only for signals with small number of values
 - For example, state variables of FSMs

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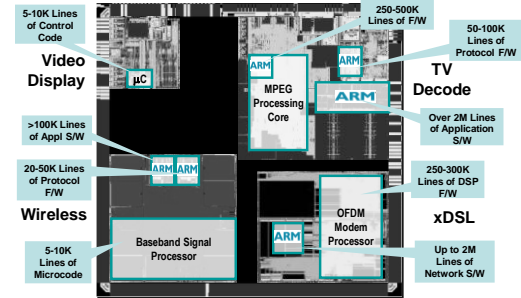
Code Coverage Strategy

- Set **minimum % of code coverage** depending on available verification resources and importance of preventing post tape-out bugs.
 - A failure in low-level code may affect multiple high-level callers.
 - Hence, set a higher level of code coverage for unit testing than for system testing.
- Generally, **90% or 95% goal for statement, branch or expression coverage**.
 - Some feel that less than 100% does not ensure quality.
 - Beware: Reaching full code coverage closure can cost a lot of effort!
 - This effort could be more wisely invested into other verification techniques.
- Avoid setting a goal lower than 80%.

Literature: [J Barkley. *Why Statement Coverage Is Not Enough. A practical strategy for coverage closure.*, TransEDA.]

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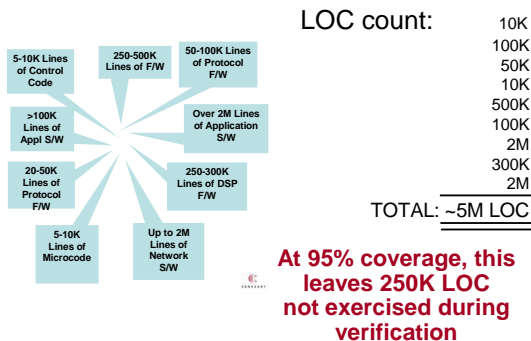
Increasing Design Complexity



Multiple Power Domains, Security, Virtualisation
Nearly five million lines of code to enable Media gateway

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Increasing Design Complexity



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Structural Coverage

- Implicit coverage models that are based on **common structures in the code**
 - FSMs, Queues, Pipelines, ...
- The **structures are extracted automatically** from the design and pre-defined coverage models are applied to them
- Users may refine the models
 - Define illegal events

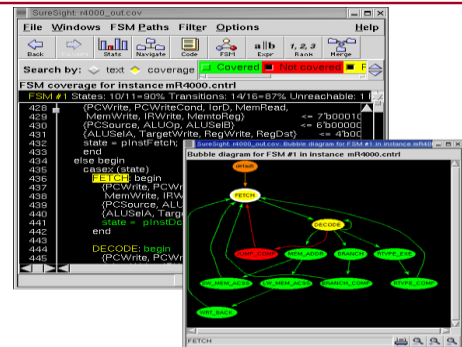
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State-Machine Coverage

- State-machines are the essence of RTL design
- FSM coverage models are the most commonly used structural coverage models
- Types of coverage models
 - State
 - Transition (or arc)
 - Path

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FSM Coverage Report



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Code Coverage - Limitations

- Coverage questions not answered by code coverage tools
 - Did every instruction take every exception?
 - Did two instructions access the register at the same time?
 - How many times did cache miss take more than 10 cycles?
 - Does the implementation cover the functionality specified?
 - ... (and many more)
- Code coverage indicates how thoroughly the test suite exercises the source code!
 - Can be used to identify outstanding corner cases
- Code coverage lets you know if you are not done!
 - It does not indicate anything about the functional correctness of the code!
- 100% code coverage does not mean very much. ☹
- Need another form of coverage!

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Functional Coverage

- It is important to cover the **functionality** of the DUV.
 - Most functional requirements can't easily be mapped into lines of code!
- **Functional coverage models** are designed to assure that various aspects of the functionality of the design are verified properly, they link the requirements/specification with the implementation
- Functional coverage models are specific to a given design or family of designs
- Models cover
 - The inputs and the outputs
 - Internal states or microarchitectural features
 - Scenarios
 - Parallel properties
 - Bug Models

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Functional Coverage Model Types

- **Discrete set of coverage tasks**
 - Set of unrelated or loosely related coverage tasks often derived from the requirements/specification
 - Often used for corner cases
 - Driving data when a FIFO is full
 - Reading from an empty FIFO
 - In many cases, there is a close link between functional coverage tasks and **assertions**
- **Structured coverage models**
 - The coverage tasks are defined in a structure that defines relations between the coverage tasks
 - Allow definition of **similarity and distance** between tasks
 - Most commonly used model types
 - Cross-product
 - Trees
 - Hybrid structures

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Cross-Product Coverage Model

[O Lachish, E Marcus, S Ur and A Ziv. Hole Analysis for Functional Coverage Data. In proceedings of the 2002 Design Automation Conference (DAC), June 10-14, 2002, New Orleans, Louisiana, USA.]

A cross-product coverage model is composed of the following parts:

1. A semantic **description** of the model (story)
2. A list of the **attributes** mentioned in the story
3. A set of all the **possible values** for each attribute (the attribute value **domains**)
4. A list of **restrictions** on the legal combinations in the cross-product of attribute values

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Example: Cross-Product Coverage Model 1

Design: switch/cache unit

[G Nativ, S Mittermaier, S Ur and A Ziv. Cost Evaluation of Coverage Directed Test Generation for the IBM Mainframe. In Proceedings of the 2001 International Test Conference, pages 793-802, October 2001.]

Motivation: Interactions of core processor unit **command-response** sequences can create complex and potentially unexpected conditions causing contention within the **pipes** in the switch/cache unit when many **core processors** (CPs) are active.

All conditions must be tested to gain confidence in design correctness.

Attributes relevant to command-response events:

- Commands - CPs to switch/cache [31]
- Responses - switch/cache to CPs [16]
- Pipes in each switch/cache [2]
- CPs in the system [8]
- (Command generators per CP chip [2])

How big is the coverage space, i.e. how many coverage tasks?

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Example: Cross-Product Coverage Model 2

Size of coverage space:

- Coverage space is formed by **cross-product over all attribute value domains**.
- Size of cross-product is product of domain sizes:
 - $31 \times 16 \times 2 \times 8 \times 2 = 15872$
- Hence, there are 15872 coverage tasks.

Example coverage task:

(Command=20, Response=01, Pipe=1, CP=5, CG=0)

Are all of these tasks reachable/legal?

- Restrictions on the coverage model are:
 - possible responses for each command
 - unimplemented command/response combinations
 - some commands are only executed in pipe 1
- After applying restrictions, there are 1968 legal coverage tasks left.
- **Make sure you identify & apply restrictions before you start!**

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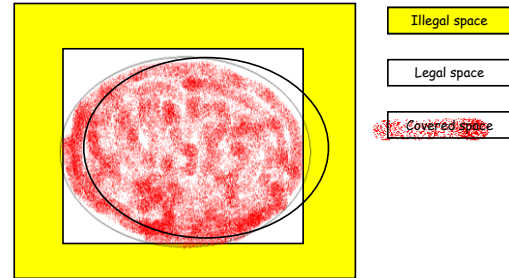
Defining the Legal and Interesting Spaces

In Practice:

- Boundaries between legal and illegal coverage spaces are often not well understood
- The design and verification team create initial spaces based on their understanding of the design
- Coverage feedback modifies the space definition
- Sub-models are used to economically check and refine the spaces
 - Easy to define as these are sub-crosses!
- Interesting spaces tend to **change often** due to shift in focus in the verification process

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Legal Spaces Are Self-correcting



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Cross-Product Coverage more formally

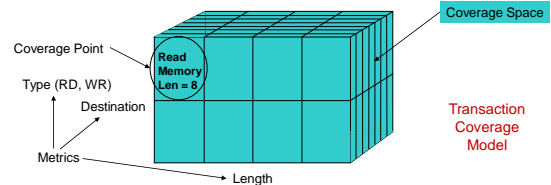
- Functional cross-product coverage models can be defined using **multi-dimensional coverage spaces**.
- A **functional coverage space** C_m is defined as the Cartesian product over m signal domains $D_0; \dots; D_{m-1}$.
 - $C_m = D_0 \times \dots \times D_{m-1}$
- Let $\|D_k\| = d_k$ denote the **size of domain** D_k .
- The functional coverage space C_m contains $\|C_m\| = \|D_0\| * \dots * \|D_{m-1}\| = d$ distinct **coverage points** $p_0; \dots; p_{d-1}$.
- A **coverage point** p_i with $i \in \{0; \dots; d-1\}$ is characterized by an **m -tuple of values** $p_i = (v_0; \dots; v_{m-1})$, where $p_i[k] = v_k$ and each $v_k \in D_k$ for $k \in \{0; \dots; m-1\}$.

Formalization facilitates automation of coverage analysis e.g. identification of coverage gaps.

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Coverage Terminology

- coverage model** n . 1. A set of legal and interesting coverage points in the coverage space.
- coverage point** n . 1. A point within a multi-dimensional coverage space. 2. An event of interest that can be observed during simulation.



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Cross-Product Models In e

Verification Languages such as e support cross-product coverage models:

- The **story** is hidden in the **event**
- The **attributes** and their **values** are defined in the **coverage items**
- Legal and interesting space** are defined using the **illegal** and **ignore** constructs
 - Restrictions can be defined on the coverage items and the cross itself

```
struct instruction {
  opcode: [NOP, Add, SUB,
           AND, XOR];
  operand1 : byte;

  event stimulus;

  cover stimulus is {
    item opcode;
    item operand1;
    cross opcode, operand1
      using ignore = (opcode == NOP);
  };
};
```

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Summary: Functional Coverage

Determines whether the functionality of the DUV was verified.

- Functional coverage models are **user-defined**.
 - (specification driven)
 - This is a skill. It needs (lots of) experience!
 - Focus on **control signals**. WHY?
- Strengths:**
 - High expressiveness: cross-correlation and multi-cycle scenarios.
 - Objective measure of progress against verification plan.
 - Can identify coverage holes by crossing existing items.
 - Results are easy to interpret.
- Weaknesses:**
 - Only as good as the coverage metrics.
 - To implement the metrics, engineering effort is required and a lot of expertise.

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Summary: Code Coverage

Determines if all the **implementation** was verified.

- Models are implicitly defined by the source code.
 - (implementation driven)
 - statement, path, expression, toggle, etc.
- Strengths:**
 - Reveals unexercised parts of design.
 - May reveal gaps in functional verification plan.
 - No manual effort is required to implement the metrics. (Comes for free!)
- Weaknesses:**
 - No cross correlations.
 - Can't see multi-cycle/concurrent scenarios.
 - Manual effort required to interpret results.

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Summary: Coverage Models

- Do we need both code and functional coverage? YES!

Functional Coverage	Code Coverage	Interpretation
Low	Low	There is verification work to do.
Low	High	Multi-cycle scenarios, corner cases, cross-correlations still to be covered.
High	Low	Verification plan and/or functional coverage metrics inadequate. Check for "dead" code.
High	High	High confidence in quality.

- Coverage models complement each other!
- No single coverage model is complete on its own.

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Case Studies

The Coverage Process in Practice

Examples:

- [Verifying interdependency in a PowerPC processor](#)
- [Pipeline of Branch unit in S/390 system](#)

(Thanks to Avi Ziv from IBM Research Labs in Haifa for sharing these.)



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Example 1: Interdependency in a PowerPC Processor

- Interdependencies between instructions in the pipeline of a processor create interesting testing scenarios
 - They activate many **microarchitectural mechanisms**, such as forwarding and stalling
 - Studies have shown that they are the **source of many bugs** in processor designs
 - Functionality at this level is often related to increasing **processor performance**



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First Approach – Black Box Model

- The motivation (story):
Verify all dependency types of a resource (register) relating to all instructions
- The **semantics** of the coverage tasks:
A coverage task is a quadruplet (I_i, I_k, R, DT) , where Instruction I_i is followed by Instruction I_k , and both share Resource R with Dependency Type DT
- The attributes:
 - I_i, I_k - Instruction: add, sub, ...
 - R - Register (resource): G1, G2, ...
 - DT - Dependency Type: WW, WR, RW, RR and None

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More Semantics

- The semantics provided so far is too coarse
 - What if I_i is the first instruction in the test and I_k is the 1000 instruction?
- Need to refine the semantics to improve probability of hitting interesting events
- Additional semantics
 - The distance between the instructions is no more than 5
 - The first instruction is at least the 6th

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The Legal Space

- Not all combinations are valid
 - Not all instructions read from registers
 - Not all instructions write to registers
 - Fixed point instructions cannot share FP (floating point) registers
 - ... and more

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Space and Model Size

- PowerPC has
 - ~400 instructions
 - (actually this is an old number, current PowerPC has close to 1000 instructions)
 - ~100 registers
- Coverage space size is $400 \times 400 \times 100 \times 5 = 80,000,000$ tasks
- Even after all restrictions are applied, the model size is still 200,000 tasks



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Coverage Results

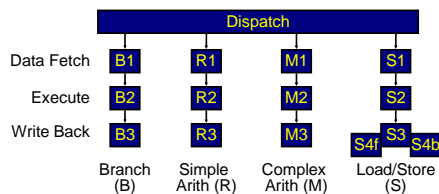
- A random test generator was used to generate tests that achieved 100% coverage
- Testing the generated tests against the forwarding and stalling mechanisms of a specific processor showed that many such mechanisms were not activated by the tests



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Grey Box Model

- Microarchitectural model for a specific Processor
 - Multithreaded
 - In-order execution
 - Up to four instructions dispatched per cycle



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Model Details

- Model contains 7 attributes
 - Type, pipe and stage of first instruction (I_1, P_1, S_1)
 - Same attributes for second instruction (I_2, P_2, S_2)
 - Type of dependency between the instructions
 - RR, RW, WR, WW, None
- Grouping is done in a similar way to the architectural model
- Many restrictions exist
 - I_1 is simple fixed point $\rightarrow P_1$ is R or M
 - P_1 is not S $\rightarrow S_1$ is 1, 2, or 3
- After restrictions, 4418 tasks are legal

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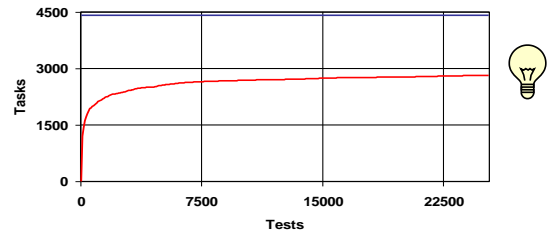
Coverage Measurement

- Make sure that you measure what you really want and what really happens
- Use simpler environment and models to **test and debug the measurement system**
 - Hierarchy of models
 - All instructions
 - All pipe stages
 - Controlled simulation

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Analysis of Interdependency Model

- After 25,000 tests 2810 / 4418 tasks were covered (64%)



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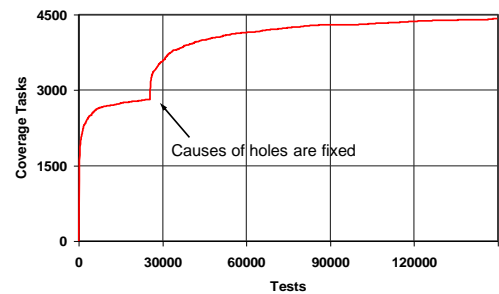
Analysis of Interdependency Model

- Hole analysis detected two major areas that are lightly covered
 - Stages S4f and S4b that are specific to thread switching are almost always empty
 - Reason: not enough thread switches during tests
 - The address-base register in the store-and-update instruction is not shared with other registers in the test
 - Reason: bug in the test generator that didn't consider the register as a modified register



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Coverage Progress



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Architecture vs. Microarchitecture

- Architecture
 - No implementation details
 - Easy to share between designs
 - Temporal model
- Microarchitecture
 - Pipe implementation knowledge is needed
 - Access to microarchitectural mechanisms is needed
 - White box or at least grey box
 - More for observability than for controllability (Why?)
 - Snapshot model



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Example 2: S/390 Branch Unit

- Unit handles branch prediction and execution of branch instructions
- Contains
 - Nine stage complex pipe
 - More than one instruction at the same time in some stages
 - Instructions can enter the pipe at two places
 - Branch history tables
 - and more
- 2 PY spent on verification
- Done by experts with experience with similar designs
- About 100,000 tests per day

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Coverage Models for Branch Unit

- Several models defined

- Access to branch tables
- Flow of a branch in the pipe
- State of the pipe

- State of the pipe model

- Attributes contain
 - Location and type of each branch in the pipe in a given cycle
 - Reset signal
- Model size:
 - Without restrictions ~ 15,000,000
 - With restrictions ~ 1400



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Coverage Closure

Using Coverage – What can go wrong?

- Low coverage goals
- Some coverage models are ill-suited to deal with common problems
 - Missing code
 - Use Requirements-based Methodology to overcome this!
- Generating simple tests just to cover specific uncovered tasks
 - There is merit in generating tests outside the coverage!
- Collecting coverage without analyzing and interpreting the results

WHY?

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Coverage Closure

Coverage closure is the process of:

- Finding areas of coverage not exercised by a set of tests.
 - Coverage Holes!
- Creating additional tests to increase coverage by targeting these holes.
 - Beware: Aim to “balance” coverage!

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Controllability Problems

If the cases to be hit contain internal states/signals of the DUV, directed tests that exercise all combinations are hard to find.

- Processor pipeline verification: Control logic, Internal FSMs
 - Generate biased random tests automatically. [RTPG]
 - [ISC](#)
 - Typically tests are filtered to retain only those that add to coverage.
 - Coverage analysis indicates **hard-to-reach** cases.
 - Don't waste engineers time on what **automation** can achieve.
 - Combine automatically generated stimulus with coverage.
 - Gives rise to [Coverage DRIVEN Verification Methodology](#)
- BUT:**
- **Hard-to-reach cases (may) need manual attention.**
 - Bias tests towards certain conditions or corner cases.
 - **Supplying bias requires significant engineering skill.**
 - Often only trial-and-error approach.

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80/20 Split

In practice: 80/20 (20/80) split wrt coverage progress.

Good news:)

- 80% of coverage is achieved (relatively quickly/easily) driving randomly generated tests.
- This takes about 20% of total time/effort/sim runs spent on verification.

Bad news:(

- Gaining the remaining 20% coverage,
 - i.e. filling the remaining coverage holes (which often needs to be done manually and requires a lot of skill plus design understanding),
- can take as much as 80% of the total time/effort/sim runs spent on verification.

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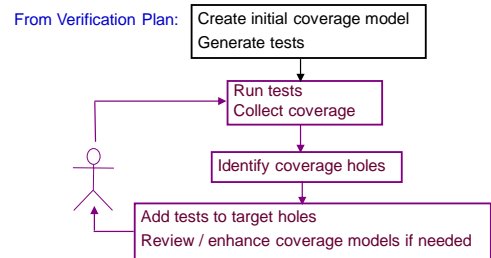
Benefits of Coverage DRIVEN Verification Methodology

Benefits:

- Shortens implementation time
 - (Initial setup time)
 - Random generation covers many “easy” cases
- Improves quality
 - Focus on goals in verification plan
 - Encourages exploration/refinement of coverage models
- Accelerates verification closure
 - Refine/tighten constraints to target coverage holes

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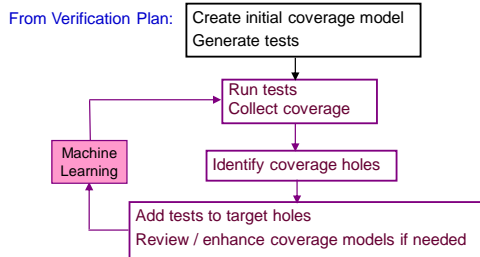
Coverage DRIVEN Verification Methodology



Current research: How can we automate this further?

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Coverage DIRECTED Test Generation



Current research: How can we automate this further?

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CDG: Coverage DIRECTED Test Generation

How can we make better use of coverage data to automate stimulus generation?

Latest Research:

Coverage DIRECTED (stimulus/test) generation [IBM]

- BY CONSTRUCTION
 - Require description of design as FSM.
 - Use formal methods to derive transition coverage.
 - Automatically translate paths through FSM to test vectors.
 - Fall over in practice: FSMs are prohibitively large!
- BY FEEDBACK
 - (Exploit Machine Learning techniques)
 - GAs/GP - Need to find suitable encoding (e.g. of instructions).
 - Bayesian Networks - Need to design and train BN.
 - Data Mining in coverage spaces

No significant breakthrough in CDG yet!

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Summary: Coverage

- Coverage is an important verification tool.
 - Code coverage: statement, path, expression
 - Structural coverage: FSM
 - Functional coverage models: story, attributes, values, restrictions
 - (Assertion coverage will be introduced during the lecture on Assertion-based Verification.)
- Combination of coverage models required in practice.
 - Code coverage alone does not mean anything!
- Verification Methodology should be **coverage driven**.
- **Automation**: Research into **coverage directed test generation**
- **Delays in coverage closure** are the main reason why verification projects fall behind schedule!

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