Software Development for Data Science – Coursework 2 Resit 22/23

Convolutional Neural Networks for Image Classification

Introduction:

In this report, we delve into the realm of Convolutional Neural Networks (CNN) for image classification. Our primary objective is to conduct a comparative study between two prominent CNN-based algorithms: LeNet and MobileNetV2. The essence of our analysis involves in-depth research, algorithm selection justification, concise explanations of their operational mechanisms, and a critical evaluation of their performance on the CIFAR-10 dataset. The integration of the CIFAR-10 dataset through TensorFlow ensures seamless compatibility within the Google Colab environment, given its constrained GPU training time of 12 hour.

Selected Dataset:

The CIFAR-10 dataset emerges as the cornerstone of our investigation. This section underscores the rationale behind its selection, its unique characteristics, relevance to image classification, and its advantageous features for our algorithmic evaluation.

Dataset Characteristics

The CIFAR-10 dataset boasts a curated collection of 60,000 32x32 color images, evenly distributed among 10 distinct classes. The dataset's balanced nature provides 6,000 images per class, encompassing a diverse range of objects – from animals to vehicles and everyday items. This diversity imbues real-world relevance, making the dataset an ideal testbed for assessing image classification algorithms.

Relevance to Image Classification

The dataset's alignment with image classification is evident, given its labeled images designed for categorization. With its compact image size of 32x32 pixels, it stimulates

scenarios where limited spatial information necessitates the extraction of intricate features from constrained data.

Advantages for Algorithmic Evaluation

The CIFAR-10 dataset offers numerous merits that render it an excellent choice for our comparative analysis:

Realism:

The dataset mirrors practical image classification scenarios, enhancing the applicability of our findings.

Benchmarking:

CIFAR-10 holds the status of a benchmark dataset in computer vision. This recognition facilitates standardized performance comparison.

Complexity:

Despite its modest dimensions, the dataset's diverse classes and intricate object patterns challenge algorithms, providing a robust platform for assessing their adaptability.

Resource Efficiency:

The dataset's manageable image size enables efficient experimentation within Google Colab's GPU time constraints.

The selection of CIFAR-10 aligns harmoniously with our pursuit of comprehensive and relevant insights. Its realism, benchmarking status, complexity, and resource efficiency culminate in an ideal choice for evaluating the performance of LeNet and MobileNetV2.

Algorithms and Justification

This section delves into the core of our study by meticulously scrutinizing the two chosen CNN algorithms: LeNet and MobileNetV2. LeNet, a historical landmark, holds its significance, while MobileNetV2, a contemporary choice, is selected for its relevance and performance potential. We provide robust justifications for our selections and succinctly elucidate their operational mechanisms.

LeNet: The Historical Landmark

Algorithm Overview:

LeNet, introduced by LeCun et al. in 1998 [LeCun98], marks a pivotal moment in deep learning history. Comprising seven layers, LeNet serves as the precursor to modern CNN architectures. It incorporates convolutional layers, sub-sampling layers, and fully connected layers. LeNet's origin in handwritten digit recognition reflects its hierarchical design, mirroring the visual cortex's information processing.

Justification:

LeNet's selection stems from dual purposes. First, it pays homage to the genesis of CNNs and their transformative impact on machine learning. Second, evaluating LeNet against a contemporary algorithm provides insights into CNN architecture evolution, contrasting historical advancements with modern designs.

MobileNetV2: The Contemporary Choice

Algorithm Overview:

MobileNetV2, our selected contemporary algorithm, offers alignment with our research goals. Renowned for its architecture breakthrough, MobileNetV2 excels in image classification. With numerous layers, it features residual blocks comprising convolutional layers, batch normalization, and skip connections.

Justification:

MobileNetV2's selection is rooted in its synergy with our research objectives. Its distinctive attribute, residual connections, addresses vanishing gradient challenges, facilitating deeper model training. By juxtaposing MobileNetV2 with LeNet, we gain insights into its strengths – handling vanishing gradients and capturing intricate features – and its potential limitations compared to simpler architectures. This comparison enriches our understanding of contemporary CNN dynamics.

MobileNetV2's innovative architecture and significance in deep learning render it an ideal contender for this comparative exploration, contributing to the ongoing discourse on CNNs. Our analysis proceeds by unveiling the training and testing processes of LeNet and MobileNetV2 on the CIFAR-10 dataset, unraveling their performance intricacies and enhancing our comprehension of their capabilities. As we conclude this report, the comparative analysis of LeNet and MobileNetV2 on the CIFAR-10 dataset elucidates the evolution of CNN architectures. By contrasting historical and contemporary designs, we unravel performance nuances, strengths, and limitations. Our exploration enhances the collective understanding of CNN dynamics, laying the groundwork for continued advancements in image classification and deep learning. Through this endeavor, we contribute to the discourse on convolutional neural networks, drawing valuable insights

The Training and Testing Process

Both LeNet and MobileNetV2 models are trained and tested on the CIFAR-10 dataset. The training process involves compiling the models with appropriate optimizers and loss functions. We utilize the GPU provided by Google Colab for faster training. After training, we evaluate the performance of the models using accuracy metrics

Algorithmic Performance Evaluation and Comparison

In this study, we conducted a comprehensive evaluation and comparison of the performance of two popular convolutional neural network (CNN) architectures, LeNet and MobileNetV2, on the challenging CIFAR-10 dataset. Our goal was to analyze their training and testing results over the course of 25 epochs and draw insights into their accuracy and validation performance.

LeNet, a classic CNN architecture, exhibited promising results during training and testing. Over the 25 epochs, we observed a steady improvement in accuracy and validation scores. At the outset, LeNet achieved an accuracy of 40.01% and a validation accuracy of 47.62%. However, as the training progressed, these metrics demonstrated noticeable enhancements. By the final epoch, LeNet's accuracy had reached an impressive 81.08%, while the validation accuracy stabilized at 59.71%. These results highlight LeNet's capability to learn intricate patterns within the CIFAR-10 dataset and generalize well to previously unseen data.

On the other hand, our analysis revealed that MobileNetV2 faced certain challenges when dealing with the CIFAR-10 dataset. Despite an initial accuracy of 42.91%, MobileNetV2 struggled to maintain competitive performance throughout the training process. The model exhibited fluctuations in both accuracy and validation scores, indicating difficulties in learning and generalization. By the end of the 25 epochs, MobileNetV2's accuracy reached 23.47%, with a corresponding validation accuracy of 23.47%, underscoring the need for further investigation and optimization to harness the potential of MobileNetV2 for this specific dataset.

The observed differences in performance between LeNet and MobileNetV2 can be attributed to their architectural dissimilarities and complexities. LeNet, with its simpler design, demonstrated a more consistent and reliable learning curve. In contrast, MobileNetV2, with its emphasis on efficiency and reduced computational cost, seemed to struggle in capturing the intricate features present in the CIFAR-10

Conclusion:

In conclusion, this study provides valuable insights into the algorithmic performance of LeNet and MobileNetV2 on the CIFAR-10 dataset. While LeNet showcased its prowess in image classification tasks, MobileNetV2's performance indicated the need for potential modifications or adaptations to better suit the dataset. Further research could involve fine-tuning MobileNetV2's hyperparameters or exploring alternative architectures to enhance its performance. This comparative analysis contributes to the broader understanding of CNN architectures and their suitability for specific tasks and datasets.

Tthis coursework has successfully compared the performance of LeNet and MobileNetV2 algorithms for image classification using the CIFAR-10 dataset. The insights gained from this comparative analysis contribute to the ongoing discourse on convolutional neural networks and their evolution over time. Both LeNet and MobileNetV2 have their strengths and weaknesses, highlighting the importance of selecting appropriate CNN architectures for specific tasks. Further comparisons and experiments can be conducted to explore different model architectures and hyperparameter configurations for improved performance

References:

LeCun, Y., Bottou, L., Bengio, Y., and Haffner, P. (1998d). Gradient-based learning applied to document recognition. Proceedings of the IEEE, 86(11), 2278–2324. datasets..from the past and present to inform future endeavors.m the past and present to inform future endeavors.

Implementation of LeNet & MobileNetV2:

```
In [1]: import tensorflow as tf
        from tensorflow.keras.datasets import cifar10
        # Load and preprocess CIFAR-10 dataset
        (x_train, y_train), (x_test, y_test) = cifar10.load_data()
        x_train, x_test = x_train / 255.0, x_test / 255.0
In [2]: from tensorflow.keras.models import Sequential
        from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten, Dense
        # Build LeNet model
        leNet_model = Sequential([
            Conv2D(6, kernel_size=(5, 5), activation='relu', input_shape=(32, 32, 3)),
            MaxPooling2D(pool_size=(2, 2)),
            Conv2D(16, kernel_size=(5, 5), activation='relu'),
            MaxPooling2D(pool_size=(2, 2)),
            Flatten(),
            Dense(120, activation='relu'),
            Dense(84, activation='relu'),
            Dense(10, activation='softmax')
        ])
```

```
Epoch 1/25
y: 0.4001 - val_loss: 1.4370 - val_accuracy: 0.4762
y: 0.5204 - val_loss: 1.2819 - val_accuracy: 0.5384
Epoch 3/25
y: 0.5724 - val loss: 1.2407 - val accuracy: 0.5585
Epoch 4/25
y: 0.5993 - val_loss: 1.1976 - val_accuracy: 0.5810
Epoch 5/25
y: 0.6231 - val_loss: 1.1385 - val_accuracy: 0.6002
Epoch 6/25
y: 0.6426 - val_loss: 1.1170 - val_accuracy: 0.6042
Epoch 7/25
y: 0.6562 - val_loss: 1.0966 - val_accuracy: 0.6202
Epoch 8/25
y: 0.6711 - val_loss: 1.0963 - val_accuracy: 0.6166
Epoch 9/25
y: 0.6848 - val_loss: 1.1323 - val_accuracy: 0.6095
Epoch 10/25
y: 0.6952 - val_loss: 1.1114 - val_accuracy: 0.6187
Epoch 11/25
y: 0.7048 - val_loss: 1.1288 - val_accuracy: 0.6240
Epoch 12/25
y: 0.7155 - val_loss: 1.2021 - val_accuracy: 0.6083
Epoch 13/25
y: 0.7259 - val_loss: 1.1375 - val_accuracy: 0.6263
Epoch 14/25
y: 0.7327 - val_loss: 1.1603 - val_accuracy: 0.6143
Epoch 15/25
y: 0.7433 - val_loss: 1.2274 - val_accuracy: 0.6108
Epoch 16/25
y: 0.7522 - val_loss: 1.2188 - val_accuracy: 0.6140
Epoch 17/25
y: 0.7586 - val_loss: 1.2804 - val_accuracy: 0.6083
Epoch 18/25
y: 0.7670 - val_loss: 1.2554 - val_accuracy: 0.6217
```

```
y: 0.7741 - val_loss: 1.2750 - val_accuracy: 0.6156
     Epoch 20/25
     y: 0.7813 - val_loss: 1.2790 - val_accuracy: 0.6159
     Epoch 21/25
     y: 0.7857 - val_loss: 1.3275 - val_accuracy: 0.6124
     Epoch 22/25
     y: 0.7940 - val_loss: 1.3665 - val_accuracy: 0.6099
     Epoch 23/25
     y: 0.8012 - val_loss: 1.4543 - val_accuracy: 0.6065
     y: 0.8065 - val_loss: 1.4436 - val_accuracy: 0.6076
     Epoch 25/25
     y: 0.8108 - val_loss: 1.4963 - val_accuracy: 0.5971
Out[2]: <keras.src.callbacks.History at 0x1e8b540f7f0>
In [6]: import tensorflow as tf
      from tensorflow.keras.datasets import cifar10
      from tensorflow.keras.models import Sequential
      from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten, Dense
      from tensorflow.keras.optimizers import Adam
      from tensorflow.keras.applications import MobileNetV2
      from sklearn.metrics import accuracy_score
      # Load and preprocess CIFAR-10 dataset
      (x_train, y_train), (x_test, y_test) = cifar10.load_data()
      x_train, x_test = x_train / 255.0, x_test / 255.0
      # MobileNetV2 architecture
      base_model = MobileNetV2(input_shape=(32, 32, 3), include_top=False, weights='image
      x = base_model.output
      x = tf.keras.layers.GlobalAveragePooling2D()(x)
      output = Dense(10, activation='softmax')(x)
      mobileNetV2_model = tf.keras.Model(inputs=base_model.input, outputs=output)
      # Compile and train MobileNetV2 model
      mobileNetV2_model.compile(optimizer='adam',
                           loss='sparse_categorical_crossentropy',
                           metrics=['accuracy'])
      mobileNetV2_model.fit(x_train, y_train, epochs=25, validation_data=(x_test, y_test)
      mobileNetV2_test_loss, mobileNetV2_test_accuracy = mobileNetV2_model.evaluate(x_tes
      mobileNetV2_predictions = mobileNetV2_model.predict(x_test)
      mobileNetV2_predictions = [tf.argmax(pred).numpy() for pred in mobileNetV2_predicti
      mobileNetV2_accuracy = accuracy_score(y_test, mobileNetV2_predictions)
```

```
WARNING:tensorflow:`input_shape` is undefined or non-square, or `rows` is not in [9
6, 128, 160, 192, 224]. Weights for input shape (224, 224) will be loaded as the def
ault.
Epoch 1/25
cy: 0.4291 - val_loss: 2.5432 - val_accuracy: 0.2115
cy: 0.4501 - val loss: 2.0647 - val accuracy: 0.3937
Epoch 3/25
cy: 0.4228 - val_loss: 3.1114 - val_accuracy: 0.2045
Epoch 4/25
cy: 0.3712 - val_loss: 2.6011 - val_accuracy: 0.2292
Epoch 5/25
cy: 0.3724 - val_loss: 3.1134 - val_accuracy: 0.2380
Epoch 6/25
cy: 0.3552 - val_loss: 2.7855 - val_accuracy: 0.1598
Epoch 7/25
cy: 0.3171 - val_loss: 2.2296 - val_accuracy: 0.2888
Epoch 8/25
cy: 0.3475 - val_loss: 2.4841 - val_accuracy: 0.3338
Epoch 9/25
cy: 0.3540 - val_loss: 2.8278 - val_accuracy: 0.1562
Epoch 10/25
cy: 0.3832 - val_loss: 1.7361 - val_accuracy: 0.3576
Epoch 11/25
cy: 0.3577 - val_loss: 2.8389 - val_accuracy: 0.2244
1563/1563 [================= ] - 308s 197ms/step - loss: 1.8712 - accura
cy: 0.3340 - val_loss: 2.0252 - val_accuracy: 0.2828
Epoch 13/25
cy: 0.3740 - val_loss: 1.6142 - val_accuracy: 0.4074
Epoch 14/25
cy: 0.2636 - val_loss: 2.1477 - val_accuracy: 0.1709
Epoch 15/25
cy: 0.2641 - val_loss: 2.0838 - val_accuracy: 0.2278
Epoch 16/25
cy: 0.2681 - val_loss: 3.5265 - val_accuracy: 0.2155
Epoch 17/25
cy: 0.3106 - val_loss: 2.0580 - val_accuracy: 0.2364
```

```
cy: 0.3051 - val_loss: 2.1005 - val_accuracy: 0.2514
Epoch 19/25
y: 0.3003 - val_loss: 2.1545 - val_accuracy: 0.2546
Epoch 20/25
cy: 0.2902 - val_loss: 1.9709 - val_accuracy: 0.2592
Epoch 21/25
cy: 0.3152 - val_loss: 2.1350 - val_accuracy: 0.2517
Epoch 22/25
cy: 0.3324 - val_loss: 1.7226 - val_accuracy: 0.3568
cy: 0.3330 - val_loss: 1.8985 - val_accuracy: 0.3246
Epoch 24/25
cy: 0.3163 - val_loss: 2.1107 - val_accuracy: 0.2496
Epoch 25/25
cy: 0.3290 - val loss: 2.1399 - val accuracy: 0.2347
313/313 - 9s - loss: 2.1399 - accuracy: 0.2347 - 9s/epoch - 27ms/step
313/313 [=========== ] - 10s 29ms/step
```

In []: