## Internet of Things Assignment Code

Aggregation Algorithm

Faiz Ahmad Khan
University of Surrey
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## Contents:

- Section-1: Libraries (Line 3)
- Section-2: Constants (Line 11)
- Section-3: Functions, Structures & Global Variables (Line 23)
- Section-4: Start Processes (Line 119)
- Section-5: Sensor Reading Process (Line 126)
- Section-6: Advanced Feature (Line 208)
- Section-7: Aggregation Process (Line 267)

```
----- IOT Assignment -----
  4 #include "contiki.h"
5 #include "dev/light-sensor.h"
6 #include "dev/sht11-sensor.h"
  7 #include <stdio.h>
 12 #define Advance Feature 1
13 /* 1- Run advance feature
14    0- Skip advance feature */
 15 #define BUFFER_SIZE 12
 16 #define K 12
 17 // For Cooja Sim
18 #define Light_Lower_Threshold 400
 19 #define Light_Upper_Threshold 1000
 20
 23 //---- Section-3: Functions, Structures & Global Variables
 24 static process_event_t Buffer_full_event; // Event for passing full Buffers
 27 typedef struct Buffer {
              float Array[BUFFER_SIZE];
 28
              int Length;
 30
              float Mean;
              float SD;
 32 } Buffer;
 33
 35 float getTemperature(void)
 36 {
 37
38
              tempData = sht11_sensor.value(SHT11_SENSOR_TEMP_SKYSIM); // For Cooja Sim
              float so_temp = tempData;
              // transfer function
float temp = (0.04 * so_temp) - 39.6;
 40
 41
 42
 43 }
 45 // Read Light function
46 float getLight(void)
 47 {
 48
              float lightData = light_sensor.value(LIGHT_SENSOR_PHOTOSYNTHETIC);
              // transfer function
float V_sensor = (1.5 * lightData) / 4096;
float I = V_sensor / 100000;
float light_lx = 0.625 * 1e6 * I * 1000;
 49
 50
51
 52
 53
              return light_lx;
 54 }
 55
 56 // Calculate mean function
 57 float getmean(float arr[],int length)
 58 {
59
              float sum = 0;
 60
              int i;
              for(i=0; i<length; i++)</pre>
 61
 63
64
                        sum += arr[i];
             float mean;
mean = sum / length;
 66
 67
              return mean;
 68 }
 69
 71 float getSD(float arr[],int length,float mean)
 72 {
 73
74
              float deviation;
 75
              float sqdev = 0;
 76
77
              for(i=0; i<length; i++)</pre>
 78
79
                        deviation = arr[i] - mean;
                        sqdev += deviation*deviation;
              float SD;
SD = sqrt(sqdev/length);
 81
82
 83
              return SD;
 84 }
 85
 86 // Calculate square root function
 87 float sqrt(float num)
              float sqrt = num/2;
float t = 0;
 89
 90
91
92
              while(sqrt != t)
                        t = sqrt;
 94
                       sqrt = (num/t + t) / 2;
 95
              return sqrt;
 97 }
 99 // Convert Float to Int function
100 int d1(float f) // Integer part
101 {
              return((int)f);
102
103 }
104
105 unsigned int d2(float f) // Fractional part
              if (f>0)
107
108
              {
109
                       return(100*(f-d1(f)));
110
111
112
              {
                       return(100*(d1(f)-f));
```

```
116
117 /
118
119
              Section-4: Start Processes
120 PROCESS(sensor_reading_process, "Sensor reading process");
121 PROCESS(aggregation_process, "Aggregation process");
122 AUTOSTART_PROCESSES(&sensor_reading_process,&aggregation_process);
124
125
              Section-5: Sensor Reading Process
127 PROCESS_THREAD(sensor_reading_process, ev, data)
129
               static struct etimer timer;
130
               PROCESS_BEGIN();
131
132
133
                // Set time
               etimer_set(&timer, CLOCK_SECOND/2);
135
137
               SENSORS_ACTIVATE(light_sensor);
               SENSORS ACTIVATE(sht11_sensor);
138
139
               // Allocate alobal event number
140
141
               Buffer_full_event = process_alloc_event();
142
143
144
               static struct Buffer Light_Buffer;
145
               static struct Buffer Temp_Buffer;
146
147
               static int counter = 0;
148
               while(1)
149
               {
150
                         PROCESS_WAIT_EVENT_UNTIL(ev=PROCESS_EVENT_TIMER);
151
152
                          // Take readings and print
                         float temp = getTemperature();
float light_lx = getLight();
Light_Buffer.Array[counter] = light_lx;
153
154
155
156
                         Temp_Buffer.Array[counter] = temp;
                        printf("\nLight = %d.%u lux\n",d1(light_lx), d2(light_lx));
printf("Temp = %d.%u C\n ",d1(temp), d2(temp));
158
160
161
                         counter++:
                          if (counter == K)
163
164
                                     / Get Length of Buffer
                                   Light_Buffer.Length = sizeof(Light_Buffer.Array)/sizeof(Light_Buffer.Array[0]);
Temp_Buffer.Length = sizeof(Temp_Buffer.Array)/sizeof(Temp_Buffer.Array[0]);
165
166
168
                                   int i:
169
                                   // Print Light Bufffer
printf("\nLight Buffer = [ ");
170
171
                                   for(i=0; i<K; i++)</pre>
173
174
                                             printf("%d.%u",d1(Light Buffer.Arrav[i]), d2(Light Buffer.Arrav[i]));
175
                                              if(i<(K-1))
176
                                             {
177
                                                       printf(", ");
178
                                             }
179
180
                                   printf(" ] ");
181
                                    // Print Temperature Buffer
182
183
                                   printf("\nTemperature Buffer = [ ");
184
                                   for(i=0; i<K; i++)</pre>
185
                                   {
186
                                             printf("%d.%u",d1(Temp\_Buffer.Array[i]),\ d2(Temp\_Buffer.Array[i]));
187
                                             if(i<(K-1))
188
                                             {
189
                                                       printf(", ");
                                             }
191
                                   printf(" ] \n");
192
193
194
                                   Light_Buffer.Mean = getmean(Light_Buffer.Array, K);
196
                                   Temp_Buffer.Mean = getmean(Temp_Buffer.Array, K);
197
                                   Light_Buffer.SD = getSD(Light_Buffer.Array, K, Light_Buffer.Mean);
Temp_Buffer.SD = getSD(Temp_Buffer.Array, K, Temp_Buffer.Mean);
199
200
201
                                   // Print Standard Deviation
202
                                   printf("\nStandard Deviation of Light = %d.%u ",d1(Light_Buffer.SD), d2(Light_Buffer.SD));
printf("\nStandard Deviation of Temperature = %d.%u \n",d1(Temp_Buffer.SD), d2(Temp_Buffer.SD));
204
205
206
207
                                   //---- Section-6: Advance Feature
209
                                   \slash 8 To find Linear Regression using Least Squares and the Pearson Correlation Coefficient.
210
211
                                   v -> Dependant Variable (Temperature)
212
213
                                   x -> Independant Variable (Light)
214
                                   m -> SLope
215
                                   c -> Intercept
216
                                    r = Covariance(x,y) \ / \ SD(x) \ * \ SD(y)   Covariance(x,y) \ - \ Mean(x^*y) \ - \ Mean(x) \ * \ Mean(y)   r \ - \ Pearson \ correlation \ coefficient \ */ 
217
218
219
220
                                   if(Advance_Feature == 1)
222
223
                                             printf("\nAdvance Feature\n");
224
                                              float m:
225
227
                                             float num = 0; // numerator
float den = 0; // denominator
228
                                              for(i=0; i<K; i++)
```

115 }

```
{
231
                                                    num += (Light_Buffer.Array[i] - Light_Buffer.Mean) * (Temp_Buffer.Array[i] - Temp_Buffer.Mean);
                                                   den += (Light_Buffer.Array[i] - Light_Buffer.Mean) * (Light_Buffer.Array[i] - Light_Buffer.Mean);
232
233
234
                                          m = num / den:
                                          c = Temp_Buffer.Mean - m * Light_Buffer.Mean;
235
                                          printf("Slope (m) = %d.%u \n",d1(m), d2(m));
printf("Intercept (c) = %d.%u \n",d1(c), d2(c));
237
238
239
                                           // Pearson correlation coefficient
240
                                          float r;
                                           float xy[K];
242
                                          for(i=0; i<K; i++)</pre>
243
244
                                                   xy[i] = Light_Buffer.Array[i] * Temp_Buffer.Array[i];
245
                                           float mean_xy; // Mean of Product of Vectors
                                          mean_xy = getmean(xy,K);
float cov; // Covariance
247
248
                                          cov = mean_xy - (Light_Buffer.Mean * Temp_Buffer.Mean);
r = cov / (Light_Buffer.SD * Temp_Buffer.SD);
printf("Pearson correlation coefficient (r) = %d.%u \n",d1(r), d2(r));
249
250
252
253
255
256
                                 // Send Buffer to Aggregation Process
257
                                 process_post(&aggregation_process, Buffer_full_event, &Light_Buffer);
258
                                 counter = 0:
259
260
                       etimer_reset(&timer);
261
262
              PROCESS_END();
263 }
264
265
266
267
             Section-7: Aggregation Process
268 PROCESS_THREAD(aggregation_process,ev,data)
269 {
270
              PROCESS_BEGIN();
271
              while(1)
273
              {
                       PROCESS_WAIT_EVENT_UNTIL(ev == Buffer_full_event); //Wait for Buffer to fill
275
                       Buffer Light_Buffer = *(Buffer *)data; // Cast to a Buffer pointer
276
278
                       if(Light_Buffer.SD > Light_Upper_Threshold)
279
280
                                 printf("\nAggregation = No Aggregation \n");
281
                                 printf("Light_X = [ ");
282
283
                                 int i:
284
                                 for(i=0; i<K; i++)</pre>
285
286
                                          printf("%d.%u",d1(Light\_Buffer.Array[i]),\ d2(Light\_Buffer.Array[i]));
                                           if(i<(K-1))
288
289
                                                   printf(", ");
                                          }
291
                                printf(" ] \n");
292
293
294
295
                        // Some Activity 4-into-1 Aggregation
296
                       else if(Light_Buffer.SD > Light_Lower_Threshold && Light_Buffer.SD <Light_Upper_Threshold)</pre>
297
298
                                 printf("\nAggregation = 4-into-1 \n");
299
                                 // For K less than 4, aggregate entire buffer
300
                                 if(K<<mark>4</mark>)
301
                                          printf("4-into-1 Aggregation not possible!");
printf("\nAggregation = K-into-1 \n");
302
303
304
                                          float Output_Buffer[1];
Output_Buffer[0] = Light_Buffer.Mean;
305
                                          // Print Output Buffer
printf("Light_X = [ ");
printf("%d.%u ] \n",d1(Output_Buffer[0]), d2(Output_Buffer[0]));
306
307
                                }
// For K equal to 4 or greater
309
310
311
                                 else
312
                                          int Q = K / 4; // Quotient
int R = K % 4; // Remainder
314
315
                                          float sum;
316
                                          float mean;
317
                                          int j = 0;
                                          int i;
319
                                          // For values of K, divisible by 4
320
                                          if(R == 0)
321
322
                                                    float Output_Buffer[Q];
                                                    while(j<K)
324
325
                                                               // Mean of 4 values set to appropriate slot in output buffer
                                                             sum = Light_Buffer.Array[j]+Light_Buffer.Array[j+1]+Light_Buffer.Array[j+2]+Light_Buffer.Array[j+3];
327
                                                             mean = sum / 4;
328
                                                             Output_Buffer[j/4] = mean;
329
330
331
                                                    // Print Output Buffer
                                                   printf("Light_X = [ ");
332
333
                                                    for(i=0; i<Q; i++)</pre>
334
335
                                                             printf("%d.%u",d1(Output\_Buffer[i]),\ d2(Output\_Buffer[i]));\\
                                                             if(i<(Q-1))
337
338
                                                                      printf(", ");
339
                                                             }
340
                                                   printf(" ] \n");
342
                                          }
// For values of K, not divisible by 4
343
```

```
{
346
                                                            // Adjust Output Buffer to include extra readings within Light Buffer
                                                           Q = Q + 1;
float Output_Buffer[Q];
347
348
349
                                                           while(j<(K-R))</pre>
350
                                                                       // Mean of 4 values set to appropriate slot in output buffer
352
                                                                       sum = Light\_Buffer.Array[j] + Light\_Buffer.Array[j+1] + Light\_Buffer.Array[j+2] + Light\_Buffer.Array[j+3]; \\
                                                                      mean = sum / 4;
Output_Buffer[j/4] = mean;
353
354
355
                                                                      j = j+<mark>4</mark>;
357
358
                                                            if(R == 1)
                                                                      // Insert final value of Light Buffer into Output Buffer
Output_Buffer[Q-1] = Light_Buffer.Array[K-1];
359
360
361
                                                            else if(R == 2)
362
363
                                                                      // Insert mean of Last 2 values of Light Buffer into Output Buffer
sum = Light_Buffer.Array[K-1] + Light_Buffer.Array[K-2];
mean = sum / R;
365
366
367
368
                                                                       Output_Buffer[Q-1] = mean;
                                                            else if(R == 3)
370
                                                                       // Insert mean of last 3 values of Light Buffer into Output Buffer
sum = Light_Buffer.Array[K-1] + Light_Buffer.Array[K-2] + Light_Buffer.Array[K-3];
371
372
373
374
                                                                       Output_Buffer[Q-1] = mean;
375
                                                           // Print Output Buffer
printf("Light_X = [ ");
for(i=0; i<Q; i++)</pre>
376
377
378
379
                                                                       printf("%d.%u",d1(Output_Buffer[i]), d2(Output_Buffer[i]));
if(i<(Q-1))</pre>
380
381
                                                                                 printf(", ");
383
384
                                                                       }
385
386
                                                           printf(" ] \n");
                                                }
388
                                     }
389
                          }
390
391
                           // No Activity K-into-1 Aggregation
                           else
393
394
                                     printf("\nAggregation = K-into-1 \n");
395
                                      float Output_Buffer[1];
                                     float Output_Buffer[1];
Output_Buffer[0] = Light_Buffer.Mean;
// Print Output Buffer
printf("Light_X = [ ");
printf("%d.%u ] \n",d1(Output_Buffer[0]), d2(Output_Buffer[0]));
396
397
398
399
400
                           printf("-----\n");
401
402
403
                PROCESS_END();
404 }
406
```