PROGRAM

```
* Approach: The idea is to compare x with the last element in arr[].
* If an element is found at the last position, return it.
* Else recur elmntSrch() for remaining array and element x.
#include <stdio.h>
// Recursive function to search x in arr[]
int elmntSrch(int arr[], int size, int x) {
       int rec;
        size--;
       if (size \geq = 0) {
        if (arr[size] == x)
               return size;
        else
               rec = elmntSrch(arr, size, x);
       else
               return -1;
        return rec;
int main(void) {
        int arr[] = {12, 34, 54, 2, 3};
       int size = sizeof(arr) / sizeof(arr[0]);
       int x = 3;
       int indx;
       indx = elmntSrch(arr, size, x);
        if (indx != -1)
                printf("Element %d is present at index %d", x, indx);
       else
                printf("Element %d is not present", x);
        return 0;
}
```

Output

Element 3 is present at index 4

PROGRAM:

```
#include<stdio.h>
void mergesort(int a[],int i,int j);
void merge(int a[],int i1,int j1,int i2,int j2);
int main() {
        int a[30], n, i;
        printf("Enter no of elements:");
        scanf("%d",&n);
        printf("Enter array elements:");
        for(i=0;i< n;i++)
               scanf("%d",&a[i]);
               mergesort(a,0,n-1);
               printf("\nSorted array is :");
        for(i=0;i< n;i++)
               printf("%d ",a[i]);
        return 0;
}
void mergesort(int a[],int i,int j) {
        int mid;
        if(i<j) {
               mid=(i+j)/2;
               mergesort(a,i,mid); //left recursion
               mergesort(a,mid+1,j); //right recursion
               merge(a,i,mid,mid+1,j); //merging of two sorted sub-arrays
        }
}
void merge(int a[],int i1,int j1,int i2,int j2) {
int temp[50]; //array used for merging
       int i,j,k;
        i=i1; //beginning of the first list
       j=i2; //beginning of the second list
        k=0:
        while(i <= j1 \&\& j <= j2) //while elements in both lists
               if(a[i] < a[j])
               temp[k++]=a[i++];
               else
               temp[k++]=a[j++];
        while(i<=j1) //copy remaining elements of the first list
               temp[k++]=a[i++];
        while(j<=j2) //copy remaining elements of the second list
               temp[k++]=a[j++];
        //Transfer elements from temp[] back to a[]
        for(i=i1,j=0;i<=j2;i++,j++)
               a[i]=temp[j];
}
```

Output
Enter Number of Element 5 Enter array element 7 5 9 4 1 Sorted array is 1 4 5 7 9

```
Algorithm Quicksort (p, q)
// Sorts the elements a[p],.....,a[q] which reside in the global array a[1:n] into
ascending order.
{
        if (p < r) then // if there are more than one element
                // divide P into two sub problems
                j=Partition (a, p,q+1);
                // j is the position of the partitioning element
                // solve the sub problems
                QuickSort (p, j 1);
                QuickSort (j + 1, q);
        }
}
Partitioning the Array
Partitioning procedure rearranges the sub arrays inplace.
Algorithm Partition (a, m, p)
// Within a[m], a[m+1], ..., a[p1]
the elements are rearranged in such a manner that if
initially t=a[m] then after completion a[q]=t for some q between m and p1,
a[k] \le t for
m \le k \le q, and a[k] \ge t for q \le k \le p. q is returned. Set a[p] = \infty.
{
        v = a[m]; i=m; j=p;
        repeat
                repeat i=i+1;
                until a[i] >= v;
                repeat j = j1;
                until a[i] \le v;
                if i < j then exchange A[i] \leftrightarrow A[j]
        } until ( i \ge j);
        a[m]=a[j]; a[j]=v; return j;
}
```

```
PROGRAM:
/*c program for quick sorting*/
#include<stdio.h>
#include<conio.h>
void gsort(int arr[20], int fst, int last);
int main() {
       int arr[30];
        int i, size;
        printf("Enter total no. of the elements : ");
        scanf("%d",&size);
        printf("Enter total %d elements : \n",size);
        for(i=0; i<size; i++)
               scanf("%d",&arr[i]);
               qsort(arr,0,size-1);
               printf("Quick sorted elements are as : \n");
        for(i=0; i<size; i++)
               printf("%d\t",arr[i]);
        getch();
        return 0;
}
void qsort(int arr[20], int fst, int last) {
        int i,j,pivot,tmp;
        if(fst<last) {
               pivot=fst;
               i=fst;
               i=last;
               while(i< j) {
                       while(arr[i]<=arr[pivot] && i<last)
                               i++;
                       while(arr[j]>arr[pivot])
                               j--;
                       if(i < j) \{
                               tmp=arr[i];
                               arr[i]=arr[j];
                               arr[j]=tmp;
                       }
               tmp=arr[pivot];
               arr[pivot]=arr[j];
               arr[i]=tmp;
               qsort(arr,fst,j-1);
               qsort(arr,j+1,last);
        }
Output -
        Enter total no. of the elements: 5
        Enter total -28787 elements:
        Quick sorted elements are as:
        Enter total no. of the elements: 5
        Enter total 5 elements:
        76134
```

Quick sorted elements are as: 1 3 4 6 7

```
// A divide and conquer program in C/C++ to find the smallest distance from a
// given set of points.
#include <stdio.h>
#include <float.h>
#include <stdlib.h>
#include <math.h>
// A structure to represent a Point in 2D plane
struct Point {
     int x, y;
};
/* Following two functions are needed for library function qsort().
Refer: http://www.cplusplus.com/reference/clibrary/cstdlib/gsort/ */
// Needed to sort array of points according to X coordinate
int compareX(const void * a,
     const void * b) {
     Point * p1 = (Point *) a, *p2 = (Point *) b;
     return (p1 -> x - p2 -> x);
}
// Needed to sort array of points according to Y coordinate
int compareY(const void * a,
     const void * b) {
     Point * p1 = (Point *) a, * p2 = (Point *) b;
     return (p1 -> y - p2 -> y);
}
// A utility function to find the distance between two points
float dist(Point p1, Point p2) {
     return sqrt((p1.x - p2.x) * (p1.x - p2.x) +
          (p1.y - p2.y) * (p1.y - p2.y)
     );
// A Brute Force method to return the smallest distance between two points
// in P[] of size n
float bruteForce(Point P[], int n) {
     float min = FLT MAX;
     for (int i = 0; i < n; ++i)
          for (int j = i + 1; j < n; ++j)
               if (dist(P[i], P[i]) < min)
                    min = dist(P[i], P[j]);
     return min:
// A utility function to find a minimum of two float values
float min(float x, float y) {
     return (x < y)? x : y;
// A utility function to find the distance between the closest points of
// strip of a given size. All points in strip[] are sorted according to
// y coordinate. They all have an upper bound on minimum distance as d.
// Note that this method seems to be a O(n^2) method, but it's a O(n)
// method as the inner loop runs at most 6 times
```

```
float stripClosest(Point strip[], int size, float d) {
     float min = d: // Initialize the minimum distance as d
     gsort(strip, size, sizeof(Point), compareY);
     // Pick all points one by one and try the next points till the difference
     // between y coordinates is smaller than d.
     // This is a proven fact that this loop runs at most 6 times
     for (int i = 0; i < size; ++i)
          for (int j = i + 1; j < \text{size && (strip[j].y - strip[i].y)} < \text{min; ++j)}
                if (dist(strip[i], strip[i]) < min)
                     min = dist(strip[i], strip[i]);
     return min:
// A recursive function to find the smallest distance. The array P contains
// all points sorted according to x coordinate
float closestUtil(Point P[], int n) {
     // If there are 2 or 3 points, then use brute force
     if (n <= 3)
          return bruteForce(P, n);
     // Find the middle point
     int mid = n / 2;
     Point midPoint = P[mid];
     // Consider the vertical line passing through the middle point
     // calculate the smallest distance dl on left of middle point and
     // dr on right side
     float dl = closestUtil(P, mid);
     float dr = closestUtil(P + mid, n - mid);
     // Find the smaller of two distances
     float d = \min(dl, dr);
     // Build an array strip[] that contains points close (closer than d)
     // to the line passing through the middle point
     Point strip[n];
     int i = 0;
     for (int i = 0; i < n; i++)
          if (abs(P[i].x - midPoint.x) < d)
                strip[j] = P[i], j++;
     // Find the closest points in strip. Return the minimum of d and closest
     // distance is strip[]
     return min(d, stripClosest(strip, j, d));
}
// The main function that finds the smallest distance
// This method mainly uses closestUtil()
float closest(Point P[], int n) {
     qsort(P, n, sizeof(Point), compareX);
     // Use recursive function closestUtil() to find the smallest distance
     return closestUtil(P, n);
// Driver program to test above functions
int main() {
     Point P[] = {
          {
                2,
                3
          },
```

```
{
                     12,
                     30
              },
{
                     40,
                     50
              },
                     5,
                     1
              },
                     12,
                     10
                     3,
              }
       };
       int n = sizeof(P) / sizeof(P[0]);
printf("The smallest distance is %f ", closest(P, n));
return 0;
}
Output
```

The smallest distance is 1.414214

PROGRAM

```
/* A Naive recursive implementation
of 0-1 Knapsack problem */
#include <stdio.h>
// A utility function that returns maximum of two integers
int max(int a, int b) {
     return (a > b)? a : b;
}
// Returns the maximum value that can be
// put in a knapsack of capacity W
int knapSack(int W, int wt[], int val[], int n) {
     // Base Case
     if (n == 0 || W == 0)
          return 0;
     // If weight of the nth item is more than
     // Knapsack capacity W, then this item cannot
     // be included in the optimal solution
     if (wt[n-1] > W)
          return knapSack(W, wt, val, n - 1);
     // Return the maximum of two cases:
     // (1) nth item included
     // (2) not included
     else
          return max(
               val[n-1] +
               knapSack(W - wt[n - 1],
                    wt, val, n - 1),
               knapSack(W, wt, val, n - 1));
// Driver program to test above function
int main() {
     int val[] = {
                        60.
                                      100.
                                                     120
                                                             };
                          10,
                                                     30
     int wt[] = {
                                        20,
                                                             };
     int W = 50;
     int n = sizeof(val) / sizeof(val[0]);
     printf("%d", knapSack(W, wt, val, n));
     return 0;
}
```

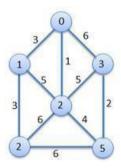
Output

220

Kruskal's Algorithm

```
MST-KRUSKAL(G, w)
        A \leftarrow \emptyset
1.
2.
         for each vertex v V[G]
                  do MAKE-SET(v)
3.
         sort the edges of E into nondecreasing order by weight w
4.
         for each edge (u, v) E, taken in nondecreasing order by weight
5.
                  do if FIND-SET(u) # FIND-SET(v)
6.
                           then A \leftarrow A \{(u, v)\}
7.
                                    UNION(u, v)
8.
9.
         return A
```

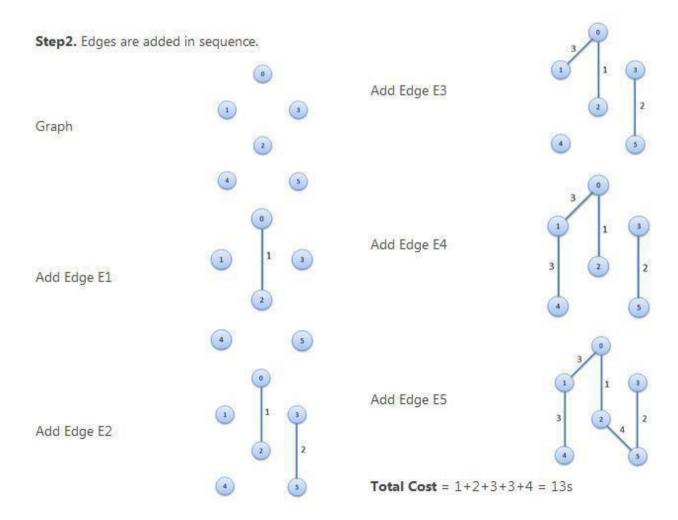
Example



Procedure for finding Minimum Spanning Tree

Step1. Edges are sorted in ascending order by weight.

Edge No.	Vertex Pair	Edge Weight
E1	(0,2)	1
E2	(3,5)	2
E3	(0,1)	3
E4	(1,4)	3
E5	(2,5)	4
E6	(1,2)	5
E7	(2,3)	5
E8	(0,3)	6
E9	(2,4)	6
E10	(4,5)	6



Program:

```
#include<stdio.h>
#include<conio.h>
#include<stdlib.h>
int i, j, k, a, b, u, v, n, ne = 1;
int min, mincost = 0, cost[9][9], parent[9];
int find(int);
int uni(int, int);
void main() {
     clrscr();
     printf("\n\tImplementation of Kruskal's algorithm\n");
     printf("\nEnter the no. of vertices:");
     scanf("%d", & n);
     printf("\nEnter the cost adjacency matrix:\n");
     for (i = 1; i \le n; i++)
          for (j = 1; j \le n; j++) {
                scanf("%d", & cost[i][j]);
               if (cost[i][j] == 0)
                     cost[i][j] = 999;
           }
     printf("The edges of Minimum Cost Spanning Tree are\n");
     while (ne < n) {
          for (i = 1, min = 999; i \le n; i++)
                for (j = 1; j \le n; j++) {
                     if (cost[i][j] < min) {
                          min = cost[i][j];
                          a = u = i;
                          b = v = i;
                     }
                }
          }
          u = find(u);
          v = find(v);
          if (uni(u, v)) {
                printf("%d edge (%d,%d) =%d\n", ne++, a, b, min);
               mincost += min;
          cost[a][b] = cost[b][a] = 999;
     printf("\n\tMinimum cost = %d\n", mincost);
     getch();
int find(int i) {
     while (parent[i])
          i = parent[i];
     return i;
int uni(int i, int j) {
     if (i != j) {
          parent[j] = i;
```

```
return 1;
     }
     return 0;
}
Output:
       Enter the no. of vertices:6
       Enter the cost adjacency matrix:
       031600
       305030
       150564
       605002
       306006
       004260
       The edges of Minimum Cost Spanning Tree are
       1 edge (1,3) = 1
       2 \text{ edge } (4,6) = 2
       3 \text{ edge } (1,2) = 3
       4 \text{ edge } (2,5) = 3
       5 \text{ edge } (3,6) = 4
```

Minimum cost = 13

```
PROGRAM
#include<stdio.h>
#include<conio.h>
int a,b,u,v,n,i,j,ne=1;
int visited[10] = \{0\}, min, mincost = 0, cost[10][10];
void main() {
     clrscr();
     printf("\nEnter the number of nodes:");
     scanf("%d", & n);
     printf("\nEnter the adjacency matrix:\n");
     for (i = 1; i \le n; i++)
          for (j = 1; j \le n; j++) {
               scanf("%d", & cost[i][j]);
               if (cost[i][j] == 0)
                     cost[i][j] = 999;
     visited[1] = 1;
     printf("\n");
     while (ne < n) {
          for (i = 1, min = 999; i \le n; i++)
               for (j = 1; j \le n; j++)
                     if (cost[i][j] < min)
                          if (visited[i] != 0) {
                               min = cost[i][j];
                               a = u = i;
                               b = v = j;
          if (visited[u] == 0 \parallel visited[v] == 0)
          {
               printf("\n Edge %d:(%d %d) cost:%d", ne++, a, b, min);
               mincost += min;
               visited[b] = 1;
          }
          cost[a][b] = cost[b][a] = 999;
     printf("\n Minimun cost=%d", mincost);
     getch();
Output
```

Program

```
#include<conio.h>
#include<stdio.h>
#define V 4 // Number of vertices
/* Define Infinite as a large enough value. This value will be used
for vertices not connected to each other */
#define INF 999
void printSolution(int dist[][V]);
void floydWarshall(int graph[][V]) {
     int dist[V][V], i, j, k;
     for (i = 0; i < V; i++)
          for (j = 0; j < V; j++)
                dist[i][j] = graph[i][j];
     for (k = 0; k < V; k++) {
          for (i = 0; i < V; i++) {
                for (j = 0; j < V; j++) {
                     if (dist[i][k] + dist[k][j] < dist[i][j])
                          dist[i][j] = dist[i][k] + dist[k][j];
                }
     printSolution(dist);
void printSolution(int dist[][V]) {
     printf("The following matrix shows shortest distances between every pair of vertices \n\n");
     for (int i = 0; i < V; i++) {
          for (int i = 0; i < V; i++) {
                if (dist[i][j] == INF)
                     printf("%7s", "INF");
                else
                     printf("%7d", dist[i][j]);
          printf("\n");
     }
}
int main() {
     clrscr();
     int graph[V][V] = {
          {
                0,
                5,
                INF,
                10
          },
                INF,
                0.
                3,
                INF
          },
```

Output

INF INF INF 0

}

The following matrix shows shortest distances between every pair of vertices 0 5 8 9 INF 0 3 4 INF INF 0 1

Program

```
#include<stdio.h>
#include<conio.h>
int a[20][20], q[20], visited[20], n, i, j, f = 0, r = -1;
void bfs(int v) {
     for (i = 1; i \le n; i++)
          if (a[v][i] && !visited[i])
               q[++r] = i;
     if (f <= r) {
          visited[q[f]] = 1;
          bfs(q[f++]);
     }
}
void main() {
     clrscr();
     int v;
     printf("Enter the number of vertices: ");
     scanf("%d", & n);
     for (i = 1; i \le n; i++)
          q[i] = 0;
          visited[i] = 0; }
     printf("\nEnter graph data in matrix form:\n");
     for (i = 1; i \le n; i++) {
          for (j = 1; j \le n; j++)
                scanf("%d", & a[i][j]);
     printf("Enter the starting vertex: ");
     scanf("%d", & v);
     bfs(v);
     printf("\nThe node which are reachable are:");
     for (i = 1; i \le n; i++) {
          if (visited[i])
                printf(" %d", i);
          else {
                printf("\nBFS is not possible. All nodes are not reachable!");
                break;}
     getch();
Output
Enter the number of vertices 3
Enter graph data in matrix form:
2
4
5
2
3
4
1
7
Enter the starting vertex: 2
The node which are reachable are: 1 2 3
```

```
Program
```

```
#include<stdio.h>
#include<conio.h>
int a[20][20], reach[20], n;
void dfs(int v) {
     int I;
     reach[v] = 1;
     for (i = 1; i \le n; i++)
          if (a[v][i] && !reach[i]) {
               printf("\n % d -> % d", v, i);
               dfs(i);
          }
}
void main() {
     clrscr();
     int I, j, count = 0;
     printf("\nEnter number of vertices: ");
     scanf(" % d", & n);
     for (i = 1; i \le n; i++) {
          reach[i] = 0;
          for (j = 1; j \le n; j++)
               a[i][j] = 0;
     printf("Enter the adjacency matrix: \n");
     for (i = 1; i \le n; i++)
          for (j = 1; j \le n; j++)
               scanf(" % d", & a[i][j]);
     dfs(1);
     printf("\n");
     for (i = 1; i \le n; i++) {
          if (reach[i])
               count++;
     if (count == n)
          printf("Graph is connected");
     else
          printf("Graph is not connected");
     getch();
}
Output
Enter number of vertices: 5 Enter the adjacency matrix: 0 1 1 1 1 1 0 0
001000010000100001->21->31->41->5 Graph is connected
```

```
Program Code
#include<conio.h>
#include<math.h>
#include<time.h>
#include<stdlib.h>
/* For printing the Grid */
void print_grid(int n, int x[]) {
     char arr[20][20];
     int i, j;
     clrscr();
     for (i = 1; i \le n; i++)
          for (j = 1; j \le n; j++) {
                arr[i][j] = '-';
          }
     for (i = 1; i \le n; i++) {
          arr[i][x[i]] = 'Q';
     for (i = 1; i \le n; i++) {
          for (j = 1; j \le n; j++) {
                printf("\t%c", arr[i][j]);
          printf("\n");
     }
}
/* For checking Queens placement is safe or not */
int safetoplace(int x[], int k) {
     int i;
     for (i = 1; i < k; i++)
          if (x[i] == x[k] || i - x[i] == k - x[k] || i + x[i] == k + x[k]) {
                return 0; /* False*/
          }
     }
     return 1; /*true*/
}
/* For printing the Queens and Placing them in Grid */
void nqueens(int n) {
     int x[20];
     int count = 0;
     int k = 1;
     x[k] = 0;
     while (k != 0) \{
          x[k] = x[k] + 1;
          while ((x[k] \le n) \&\& (!safetoplace(x, k))) {
                x[k] = x[k] + 1;
          if (x[k] \le n) {
                if (k == n) {
                     count++;
                     printf("\n\tPlacement %d is : \n\n\n", count);
                     print_grid(n, x);
```

```
getch();
            } else {
               k++;
               x[k] = 0;
            }
       } else {
           k--;
        }
    }
   return;
}
int main() {
   int n;
    clrscr();
   printf("-----\n");
    printf("-----\n\n");
   printf("\t C PROGRAM OF N-QUEEN PROBLEM\n\n");
   printf("\nEnter the no. of Queens : ");
   scanf("%d", & n);
   printf("\n\n\tUSING %d QUEEN'S STRATEGY \n\n", n);
    nqueens(n);
   system("pause");
   getch();
}
Output
```