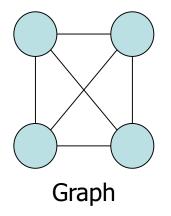
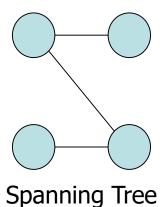
Data Structures Instructor: Hafiz Tayyeb Javed Week-15-Lecture-02

22. Minimum Spanning Tree (MST) Prims Algorithm

Spanning Trees

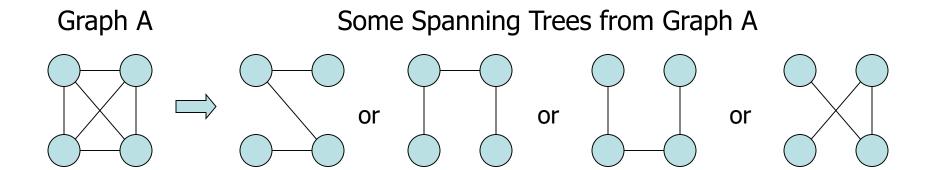
- A spanning tree of a graph is a subgraph that contains all the vertices and is a tree
- Formal definition
 - Given a connected graph with |V| = n vertices
 - A spanning tree is defined a collection of n 1 edges which connect all n vertices
 - The n vertices and n 1 edges define a connected sub-graph



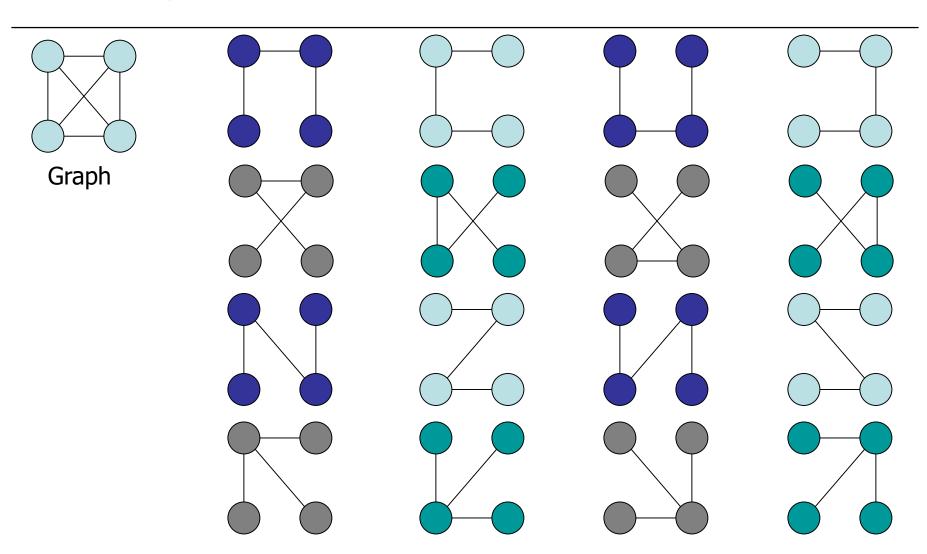


Spanning Trees

• A spanning tree is not necessarily unique



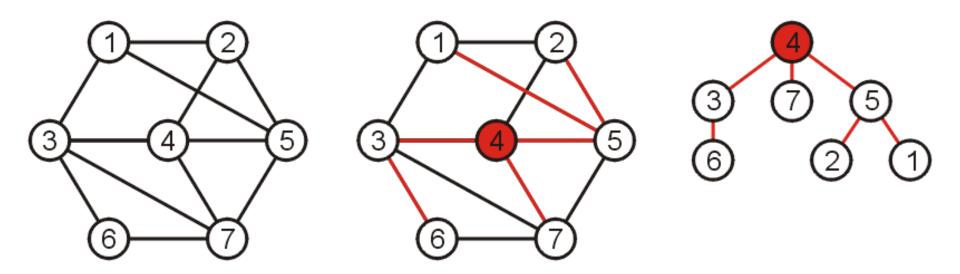
Spanning Trees – Example



All 16 of its Spanning Trees

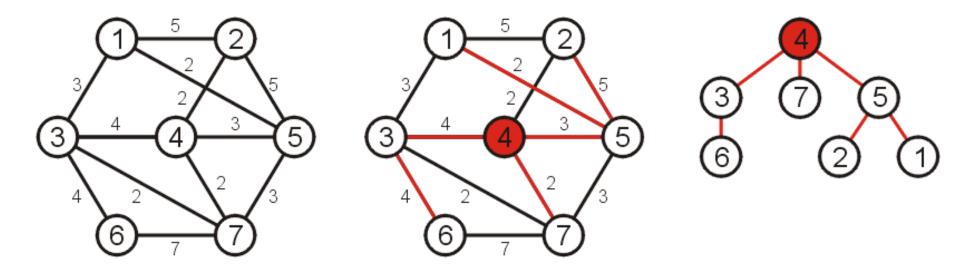
Spanning Trees

- Why such a collection of |V|-1 edges is called a tree?
 - If any vertex is taken to be the root, we form a tree by treating the adjacent vertices as children, and so on...



Spanning Tree on Weighted Graphs

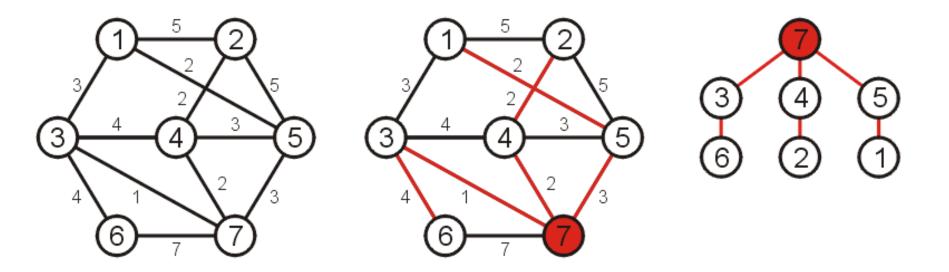
- Weight of a spanning tree
 - Sum of the weights on all the edges which comprise the spanning tree



• The weight of this spanning tree is 20

Minimum Spanning Tree (MST)

- Which spanning tree which minimizes the weight?
 - Such a tree is termed a minimum spanning tree



The weight of this spanning tree is 14

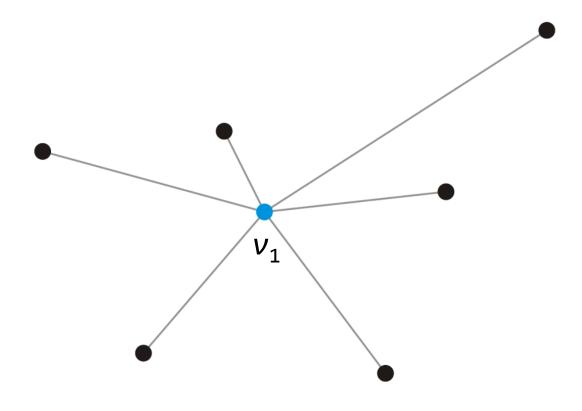
Algorithms For Obtaining MST

- Kruskal's Algorithm
- Prim's Algorithm
- Boruvka's Algorithm

Prim's Algorithm

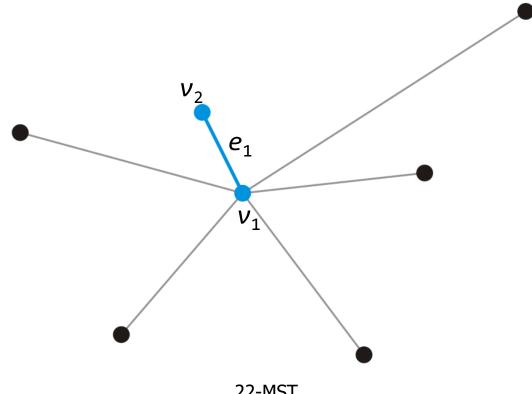
Idea

- Suppose we take a vertex v₁
 - It forms a minimum spanning tree on one vertex



Idea

- Add that adjacent vertex v₂ that has a connecting edge e₁ of minimum weight
 - This forms a minimum spanning tree on our two vertices
 - e_1 must be in any minimum spanning tree containing the vertices v_1 and v_2



Prim's Algorithm

- Start with an arbitrary vertex to form a minimum spanning tree on one vertex
- At each step, add that vertex v not yet in the minimum spanning tree
 - That has an edge with least weight that connects v to the existing minimum spanning sub-tree
- Continue until we have n 1 edges and n vertices

Prim's Algorithm – Pseudocode

```
MST-Prim(G, w, r) // w is the weight matrix of edges, r is root
    S = \emptyset
    Q = V[G]; // Insert graph vertices to a Queue
     for each u \in \mathbb{Q} // Set distance of all vertices as \infty
          key[u] = \infty;
     key[r] = 0; // Distance of root is set to 0
    p[r] = NULL; // Parent of root is NULL
     while (Q not empty) {
          u = ExtractMin(Q); // Get the vertex u with min key[u]
          S = SU\{u\}
          for each v ∈ Adj[u] { // Adj is the adjacency list
                  if (\mathbf{v} \notin \mathbf{S} \text{ and } \mathbf{w}(\mathbf{u}, \mathbf{v}) < \text{key}[\mathbf{v}]) 
                    p[v] = u;
                    \text{key}[v] = w(u,v); // \text{ weight of an edge } (u,v)
                                      22-MST
```

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Prim's Algorithm – Data Structure

- Associate with each vertex two items of data
 - The minimum distance to the partially constructed tree
 - > For a given vertex v, key[v] represent minimum distance
 - Pointer to the vertex that will form the parent node in resulting tree
 - > For a given vertex v, p[v] represent parent node

Initialization

- Set the distance of all vertices as ∞ , e.g., for all u ∈ G, key[u]= ∞
- Set all vertices to being unvisited
 - > Add vertices to the Queue
- Select a root node and set its distance as 0, i.e., key[r] = 0
- Set the parent pointer of root to NULL, i.e., p[r] = NULL

```
MST-Prim(G, w, r)
   S = \emptyset
   Q = V
   for each u \in Q
       key[u] = \infty;
   key[r] = 0;
   p[r] = NULL;
                                     Run on example graph
   while (Q not empty)
       u = ExtractMin(Q);
       S = SU\{u\}
       for each v \in Adj[u]
           if (v \notin S \text{ and } w(u,v) < \text{key}[v])
              key[v] = w(u,v);
              p[v] = u;
                                22-MST
                                                                   19
```

```
MST-Prim(G, w, r)
   S = \emptyset
   Q = V
                              14
   for each u \in Q
       key[u] = \infty;
   key[r] = 0;
                                         \infty
    p[r] = NULL;
                                       Run on example graph
   while (Q not empty)
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                                22-MST
                                                                    20
```

```
MST-Prim(G, w, r)
   S = \emptyset
   Q = V
   for each u \in Q
       key[u] = \infty;
   key[r] = 0;
                                          \infty
    p[r] = NULL;
                                         Pick a start vertex r
   while (Q not empty)
       u = ExtractMin(Q);
       S = SU\{u\}
       for each v \in Adj[u]
           if (v \notin S \text{ and } w(u,v) < \text{key}[v])
               key[v] = w(u,v);
               p[v] = u;
                                                                    21
```

```
MST-Prim(G, w, r)
   S = \emptyset
   Q = V
   for each u \in Q
       key[u] = \infty;
   key[r] = 0;
                                         \infty
   p[r] = NULL;
                                       Black vertices have been
   while (Q not empty)
                                            removed from Q
       u = ExtractMin(Q);
       S = SU\{u\}
       for each v \in Adj[u]
           if (v \notin S \text{ and } w(u,v) < \text{key}[v])
               key[v] = w(u,v);
               p[v] = u;
                                22-MST
                                                                    22
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MST-Prim(G, w, r)
   S = \emptyset
   Q = V
   for each u \in Q
       key[u] = \infty;
   key[r] = 0;
   p[r] = NULL;
                                     Black arrows indicate parent
   while (Q not empty)
                                                pointers
       u = ExtractMin(Q);
       S = SU\{u\}
       for each v \in Adj[u]
           if (v \notin S \text{ and } w(u,v) < \text{key}[v])
              key[v] = w(u,v);
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                                22-MST
                                                                   23
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                                22-MST
```

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                                                                   27
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                                22-MST
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              key[v] = w(u,v);
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                                                                   31
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                                22-MST
                                                                   32
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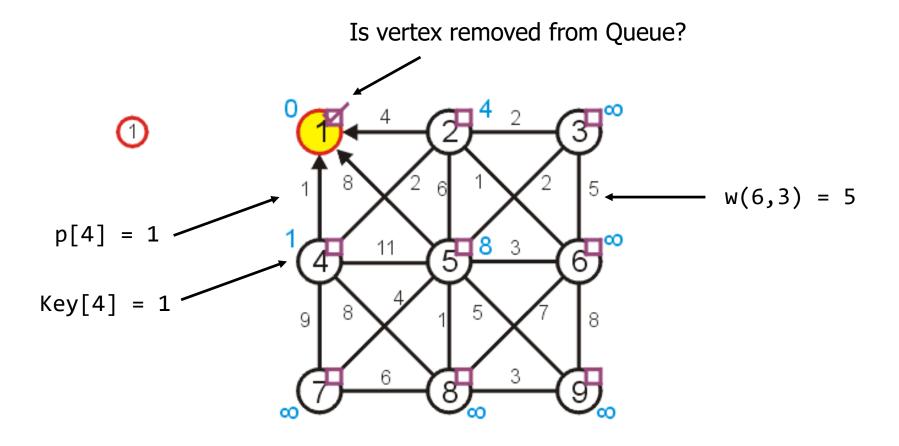
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                                                                   35
```

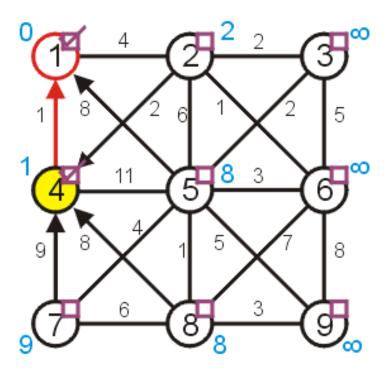
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MST-Prim(G, w, r)
                           u
   S = \emptyset
   Q = V
                             14
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   p[r] = NULL;
   while (Q not empty)
       u = ExtractMin(Q);
       S = SU\{u\}
       for each v \in Adj[u]
           if (v \notin S \text{ and } w(u,v) < \text{key}[v])
              key[v] = w(u,v);
              p[v] = u;
```

```
u
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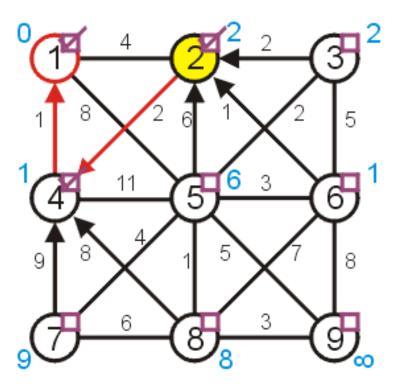
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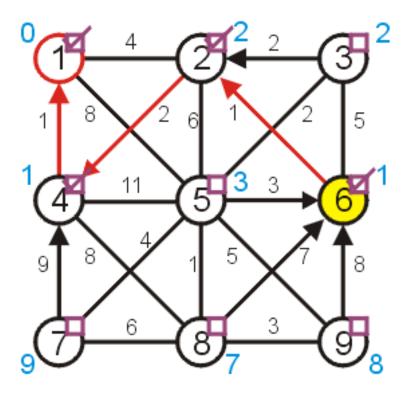


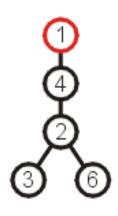


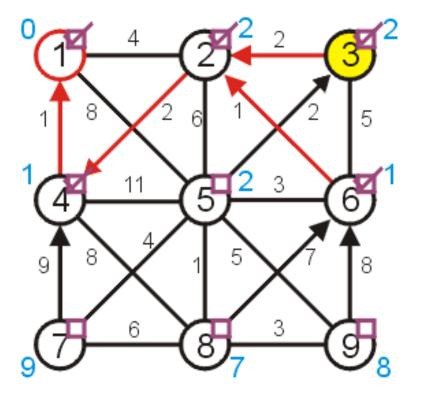


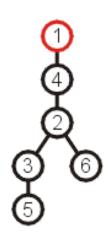


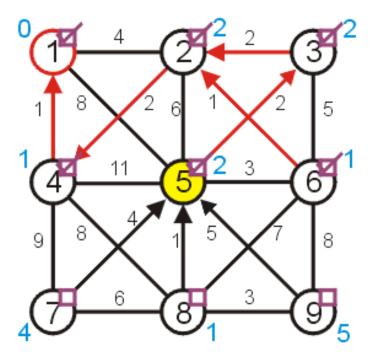


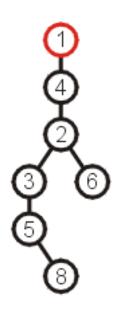


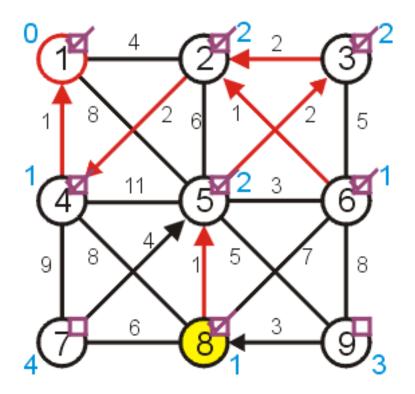


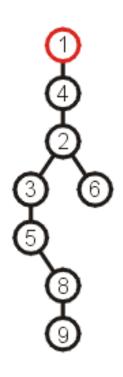


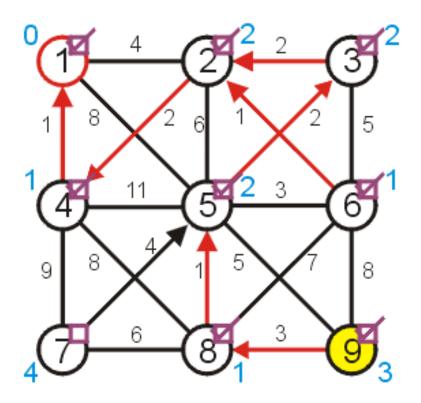


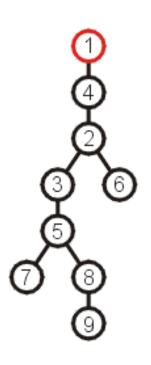


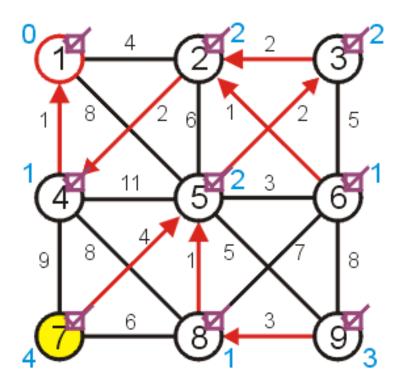


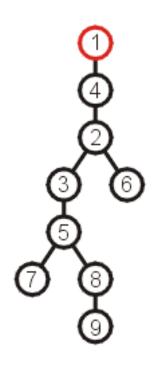


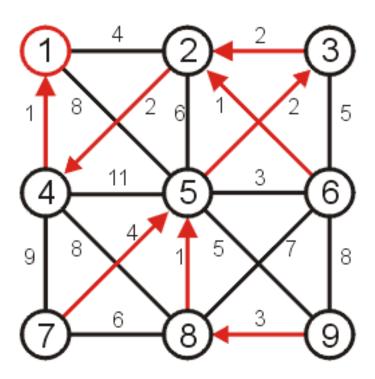












Kruskal's Algorithm vs Prim's Algorithm

- In prim's algorithm, graph must be connected
- Kruskal's algorithm can function on disconnected graphs too
- Prim's algorithm is significantly faster for dense graphs with more number of edges than vertices
 - No pre-processing required
- Kruskal's algorithm runs faster in the case of sparse graphs
 - N² cost for pre-processing (sorting)

Any Question So Far?

