view_frames Result Recorded at time: 1651313657.050 world Broadcaster: /static_transform_publisher_1651313533407305650 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 195.566 Hz Most recent transform: 1651313657.053 (-0.003 sec old) Most recent transform: 0.000 (1651313657.050 sec old) Buffer length: 4.945 sec Buffer length: 0.000 sec base_link table Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1651313657.050 sec old) Most recent transform: 0.000 (1651313657.050 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base_link_inertia base Broadcaster: /robot_state_publisher Broadcaster: /ur_hardware_interface Average rate: 41.875 Hz Average rate: 125.008 Hz Most recent transform: 1651313657.009 (0.042 sec old) Most recent transform: 1651313657.041 (0.010 sec old) Buffer length: 4.944 sec Buffer length: 4.872 sec tool0_controller shoulder_link Broadcaster: /robot_state_publisher Average rate: 41.875 Hz Most recent transform: 1651313657.009 (0.042 sec old) Buffer length: 4.872 sec upper_arm_link Broadcaster: /robot_state_publisher Average rate: 41.875 Hz Most recent transform: 1651313657.009 (0.042 sec old) Buffer length: 4.872 sec forearm_link Broadcaster: /robot_state_publisher Average rate: 41.875 Hz Most recent transform: 1651313657.009 (0.042 sec old) Buffer length: 4.872 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 41.875 Hz Most recent transform: 1651313657.009 (0.042 sec old) Buffer length: 4.872 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 41.875 Hz Most recent transform: 1651313657.009 (0.042 sec old) Buffer length: 4.872 sec wrist_3_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1651313657.050 sec old) Most recent transform: 0.000 (1651313657.050 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_bottom_screw_frame flange Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1651313657.050 sec old) Most recent transform: 0.000 (1651313657.050 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_link tool0 Broadcaster: /static_transform_publisher_1651313633458303846 Average rate: 195.675 Hz Most recent transform: 1651313657.051 (-0.001 sec old) Buffer length: 4.921 sec realsense_link Broadcaster: /realsense/realsense2_camera_manager Broadcaster: /realsense/realsense2 camera manager Broadcaster: /realsense/realsense2_camera_manager Broadcaster: /realsense/realsense2_camera_manager Broadcaster: /realsense/realsense2_camera_manager Average rate: 10000.000 Hz Most recent transform: 0.000 (1651313657.050 sec old) Buffer length: 0.000 sec realsense_depth_frame realsense_color_frame realsense_aligned_depth_to_color_frame realsense_infra1_frame realsense_infra2_frame Broadcaster: /realsense/realsense2_camera_manager Broadcaster: /realsense/realsense2_camera_manager Broadcaster: /realsense/realsense2_camera_manager Broadcaster: /realsense/realsense2_camera_manager Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1651313657.050 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec realsense_depth_optical_frame realsense_color_optical_frame realsense_infra1_optical_frame realsense_infra2_optical_frame