

LAB2

turtlesim_plus package

```
turtlesim_plus_node.py
/turtlesim_plus
-----
Publisher

Subscriber

-----
Service Server

Service Client
-----
```

Terminal

```
-----
Publisher
Subscriber
-----
Service Server
Service Client
-----
```

lab2 package

```
eater.py
/eater_node
-----
Publisher      /turtle1/cmd_vel
Subscriber
               /turtle1/pose
               /mouse_position
               /turtle1/pizza_count
-----
Service Server
Service Client
```

```
killer.py
/killer_node
-----
Publisher
Subscriber

-----
Service Server
Service Client
-----
```

```
turtlesim_pose.py
/odom_pub
-----
Publisher

Subscriber

-----
Service Server
Service Client
-----
```

```
rviz2
/rviz
-----
Publisher

Subscriber

-----
Service Server

Service Client
-----
```