Upcoming state	$P(s_{t+1}   s_{t-1}, s_t=1, a_t)$																
	S <sub>t-1</sub> =1				S <sub>t-1</sub> =2					S <sub>t-1</sub>	=3		S <sub>t-1</sub> =4				
	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	
S <sub>t+1</sub> = 1	0.1	0.3	0.2	0.1	0.7	0.2	0.2	0.2	0.4	0.2	0.2	0.3	0.2	0.1	0.1	0.1	
S <sub>t+1</sub> = 2	0.7	0.2	0.1	0.5	0.1	0.4	0.2	0.5	0.2	0.2	0.1	0.2	0.2	0.3	0.1	0.1	
S <sub>t+1</sub> = 3	0.1	0.4	0.2	0.2	0.1	0.2	0.2	0.2	0.1	0.3	0.1	0.1	0.5	0.4	0.1	0.5	
S <sub>t+1</sub> = 4	0.1	0.1	0.5	0.2	0.1	0.2	0.4	0.1	0.3	0.3	0.6	0.4	0.1	0.2	0.7	0.3	

Upcoming state		$P(s_{t+1}   s_{t-1}, s_t=2, a_t)$															
	S <sub>t-1</sub> =1				S <sub>t-1</sub> =2					S <sub>t-1</sub>	=3		S <sub>t-1</sub> =4				
	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	
S <sub>t+1</sub> = 1	0.8	0.4	0.1	0.1	0.2	0.6	0.2	0.1	0.1	0.2	0.4	0.2	0.2	0.1	0.5	0.3	
S <sub>t+1</sub> = 2	0.1	0.4	0.2	0.2	0.2	0.2	0.1	0.1	0.1	0.2	0.4	0.1	0.3	0.2	0.2	0.1	
S <sub>t+1</sub> = 3	0.05	0.1	0.3	0.1	0.3	0.1	0.1	0.6	0.1	0.3	0.15	0.6	0.2	0.4	0.1	0.1	
S <sub>t+1</sub> = 4	0.05	0.1	0.4	0.6	0.3	0.1	0.6	0.2	0.7	0.3	0.05	0.1	0.3	0.3	0.2	0.5	

Upcoming state	$P(s_{t+1}   s_{t-1}, s_t=3, a_t)$															
	S <sub>t-1</sub> =1				S <sub>t-1</sub> =2					S <sub>t-1</sub>	=3		S <sub>t-1</sub> =4			
	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4
S <sub>t+1</sub> = 1	0.4	0.2	0.1	0.2	0.4	0.1	0.3	0.2	0.2	0.1	0.2	0.1	0.1	0.1	0.1	0.2
S <sub>t+1</sub> = 2	0.2	0.7	0.7	0.2	0.1	0.8	0.3	0.1	0.1	0.2	0.2	0.1	0.2	0.2	0.1	0.2
S <sub>t+1</sub> = 3	0.1	0.05	0.1	0.3	0.1	0.05	0.1	0.4	0.5	0.4	0.3	0.5	0.4	0.2	0.5	0.5
S <sub>t+1</sub> = 4	0.3	0.05	0.1	0.3	0.4	0.05	0.3	0.3	0.2	0.3	0.3	0.3	0.3	0.5	0.3	0.1

Upcoming state	$P(s_{t+1}   s_{t-1}, s_t=4, a_t)$																
	S <sub>t-1</sub> =1				S <sub>t-1</sub> =2					S <sub>t-1</sub>	=3		S <sub>t-1</sub> =4				
	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	a <sub>t</sub> =1	a <sub>t</sub> =2	a <sub>t</sub> =3	a <sub>t</sub> =4	
S <sub>t+1</sub> = 1	0.1	0.2	0.6	0.5	0.1	0.1	0.1	0.1	0.1	0.1	0.2	0.1	0.3	0.4	0.1	0.1	
S <sub>t+1</sub> = 2	0.7	0.2	0.2	0.1	0.1	0.2	0.4	0.3	0.1	0.1	0.2	0.2	0.3	0.2	0.1	0.2	
S <sub>t+1</sub> = 3	0.1	0.1	0.1	0.1	0.1	0.1	0.2	0.4	0.7	0.1	0.2	0.5	0.2	0.2	0.4	0.5	
S <sub>t+1</sub> = 4	0.1	0.5	0.1	0.3	0.7	0.6	0.3	0.2	0.1	0.7	0.4	0.2	0.2	0.2	0.4	0.2	