

Project 1

LF CH

26 september 2022

$$\begin{aligned} u_{tt} &= c^2 D_2 u & t &\geq 0, \\ Lw &= 0 & t &\geq 0, \\ u &= f, \quad u_t = 0 & t &= 0, \end{aligned} \tag{1}$$

$$\begin{aligned} u^T H u_{tt} &= c^2 u^T H P D_2 P u = c^2 P^T H P D_2 P U = c^2 (P u)^T H D_2 P u = \\ &= c^2 (P u)^T H H^{-1} (-M + B D) P u = c^2 (P u)^T (-M + B D) P u = \\ &= -c^2 (P u)^T M P u + c^2 (P u)^T B D P u \\ &+ u_{tt}^T H u = -c^2 (P u)^T M^T P u + c^2 (P u)^T B D^T P u \\ \hline &= u^T H u_{tt} + u_{tt}^T H u = -c^2 (P u)^T (M + M^T) P u + c^2 (P u)^T (B D + B D^T) P u \\ &= \frac{d}{dt} \|u_t\|_H^2 = -2c^2 (P u)^T M P u + c^2 (P u)^T B D P u + c^2 B D^T P u \end{aligned}$$

$B = e_m d_m - e_1 d_1$ and let $w = P V$.

$$\begin{aligned} \frac{d}{dt} \|v_t\|_H^2 &= -2c^2 w^T M w + c^2 w^T (e_m d_m - e_1 d_1) w + c^2 w^T (e_m d_m^T - e_1 d_1^T) w = \\ &= -2c^2 w^T M w + c^2 w^T e_m d_m w - c^2 w^T e_1 d_1 w + c^2 w^T e_m d_m^T w - c^2 w^T e_1 d_1^T w \end{aligned}$$

1 The system

When introducing u_t to the boundary operator we cant use the previous form of semi-discrete approximation. We therefore introducing the variable substitution $v = u_t$. By creating a system of first order equations we can solve it with RK4.

$$\begin{aligned} \begin{bmatrix} u \\ v \end{bmatrix}_t &= \begin{bmatrix} 0 & I \\ c^2 D_2 & 0 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} \\ L \begin{bmatrix} u \\ v \end{bmatrix} &= 0 \\ \begin{bmatrix} u \\ v \end{bmatrix} &= \begin{bmatrix} f \\ 0 \end{bmatrix} \end{aligned} \tag{2}$$

We introduce $e^{(1)}$, $e^{(2)}$ and the Kronecker-operator to form the boundary operator

$$e^{(1)} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, e^{(2)} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \tag{3}$$

$$L \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} \alpha_l(e^{(2)} \otimes e_1) + \beta_l(e^{(1)} \otimes e_1) + \gamma_l i(e^{(1)} \otimes d_1) \\ \alpha_r(e^{(2)} \otimes e_m) + \beta_r(e^{(1)} \otimes e_m) + \gamma_r(e^{(1)} \otimes d_m) \end{bmatrix} \quad (4)$$

Apply the projection and energy method to verify stability. We multiply with $\begin{bmatrix} u \\ v \end{bmatrix}^T \bar{H}$ and let: $\bar{H} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} H$

$$\begin{aligned} \begin{bmatrix} u \\ v \end{bmatrix}^T \bar{H} \begin{bmatrix} u \\ v \end{bmatrix}_t &= \begin{bmatrix} u \\ v \end{bmatrix}^T \bar{H} P \begin{bmatrix} 0 & 1 \\ c^2 D_1 & 0 \end{bmatrix} P \begin{bmatrix} u \\ v \end{bmatrix} = \left(P \begin{bmatrix} u \\ v \end{bmatrix} \right)^T \bar{H} \begin{bmatrix} 0 & 1 \\ c^2 D_2 & 0 \end{bmatrix} P \begin{bmatrix} u \\ v \end{bmatrix} = \\ &= \left(P \begin{bmatrix} u \\ v \end{bmatrix} \right)^T \begin{bmatrix} 0 & H \\ c^2 D_2 H & 0 \end{bmatrix} P \begin{bmatrix} u \\ v \end{bmatrix} = \left(P \begin{bmatrix} u \\ v \end{bmatrix} \right)^T \begin{bmatrix} 0 & H \\ c^2 H H^{-1}(-M + BD) & 0 \end{bmatrix} P \begin{bmatrix} u \\ v \end{bmatrix} \\ &= \left(P \begin{bmatrix} u \\ v \end{bmatrix} \right)^T \begin{bmatrix} 0 & H \\ c^2(-M + BD) & 0 \end{bmatrix} P \begin{bmatrix} u \\ v \end{bmatrix} \\ &+ \left(P \begin{bmatrix} u \\ v \end{bmatrix} \right)^T \begin{bmatrix} 0 & H \\ c^2(-M + BD^T) & 0 \end{bmatrix} P \begin{bmatrix} u \\ v \end{bmatrix} \\ \hline \frac{d}{dt} \left\| \begin{bmatrix} u \\ v \end{bmatrix} \right\|_H &= \left(P \begin{bmatrix} u \\ v \end{bmatrix} \right)^T \begin{bmatrix} 0 & H \\ c^2(-2M - BD - BD^T) & 0 \end{bmatrix} P \begin{bmatrix} u \\ v \end{bmatrix} = \\ &= PHuPv + c^2 Pv(-2M - BD - BD^T)Pu = \\ &= PHuPv - c^2 Pv2MPu + Pc^2 vBDPu + pc^2 vBDPu = \\ &= PHuPv - c^2 Pv2MPu + Pc^2 v(e_m d_m - e_1 d_1)Pu + c^2 Pv(e_m d_m^T - e_1 d_1^T)Pu = \\ &= PHuPv - c^2 Pv2MPu + Pc^2 v e_m d_m Pu - Pc^2 v e_1 d_1 Pu + Pc^2 v e_m d_m^T Pu - Pc^2 v e_1 d_1^T Pu \end{aligned}$$

Using that $d_1 u = \frac{1}{c} e_1^T v$ and $d_m = -\frac{1}{c} e_m^T v$

$$PHuvP - c^2 Pv2MuP + cPve_m e_m^T vP - cPve_1 e_1^T vP + c^2 Pve_m d_m^T uP - c^2 Pve_1 d_1^T uP =$$