# Advanced probabilistic machine learning

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# 1 Introduction

This course bla bla bla

# 2 Probability review

Let first take a look at the Sample space:

- Dice:  $\Omega = \{1,2,3,4,5,6\}$
- Coin flip:  $\Omega = \{\text{heads, tails}\}\$

There are also *Events* which is a subset of the sample space:

- Dice:  $A = \{1,2\}$
- Coin flip = {tails}

Three important axioms to remember are.

- 1.  $P(A) \ge 0$
- 2.  $P(\Omega) = 1$
- 3. For disjoint sets,  $A_1, A_2, ...$  $P(A_1 \cup A_2 \cup ...) = P(A_1) + P(A_2) + ...$

To sum it up here are some examples:

- 1.  $A \subseteq B \Rightarrow P(A) \le P(B)$
- 2.  $P(A^c) = 1 P(B)$
- 3.  $P(\emptyset) = 0$
- 4.  $0 \le P(A) \le 1$
- 5.  $P(A \cup B) = P(A) + P(B) P(A \cap B)$

# 2.1 Conditional probability

The definition of conditional probability for two events are the following:

$$P(B|A) = \frac{P(A \cap B)}{P(A)} \tag{1}$$

Provided that the probability of event A is greater than 0, P(A) > 0. From this we can derive the **product rule:**  $P(A \cap B) = P(B|A)P(A)$ 

# 2.2 Bayes theorem

Given two events called A and B:

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)} \tag{2}$$

#### Example: medical test paradox

Let's characterize a medical test:

- Sensitivity(True positive rate) = P(+|Disease)
- Specificity (True negative rate) = P(-|No Disease)

Then characterize a medical condition in a population:

• Prevalence = "proportion of a particular population found to be affected by a medical condition."

Question: Assume that for a certain disease the Sensitivity is 0.99, Specificity is 0.99 and Prevalence = 0.01 If you pick someone randomly from the population and test the person for this disease, obtaining a positive result. What is the probability of the person actually having the disease?

Using Bayes theorem:

$$P(\text{Disease}|+) = \frac{P(+|\text{Disease})P(\text{Disease})}{P(+)} = \frac{\text{tpr} \cdot p}{P(+)}$$
(3)

and by the law of total probability:

 $P(+) = P(+ \cap \text{Disease}) + P(+ \cap \text{No disease})$ 

P(+) = P(+|disease)P(disease) + (1 - P(-|No disease))(1 - P(disease))

$$P(+) = tpr\dot{p} + (1 - tnr)\dot{(1 - p)}$$

Hence we have:

$$P(disease|+) = \frac{0.99 \cdot 0.01}{0.99 \cdot 0.01 + 0.01 \cdot 0.99} = 0.5$$
 (4)

#### 2.3 Random variables

The definition of a random variable  $\mathcal{X}$  is a quantity that depends on a random event. Where a discrete random variable is a countable number of values. Described by the probability mass function p(x) = P(X = x). An **example:** 6-sided dice with p(x) = 1/6, x = 1, ..., 6. A continuous random variable is an uncountable number of values. Ex: any value in  $\mathbb{R}$ . **Example:**  $\mathcal{X}$  is the height of an adult randomly sampled from the population. It is described by the probability density function: p(x).

A probability density function p(x) describes the probability for a *continuous* random variable x falling into a given interval:

$$P(a < X < b) = \int_{a}^{b} p(x) dx \tag{5}$$

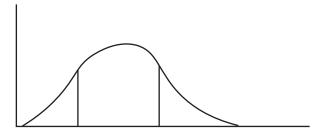


Figure 1: Example of caption

## 2.4 Joint probability

Given two random variables: X and Y:

- Discrete: probability mass function p(x, y) = P(X = x, Y = y)
- Continuous: (probability density function)  $P(a < X \le b, c < Y \le d) = \int_a^b \int_c^d p(x, y) \, dy dx$

## 2.5 Marginalization and conditioning

Marginalization (also called the sum rule) is defined as

$$p(\mathbf{x}) = \int_{y} p(\mathbf{z}, y) \, \mathrm{d}y \quad \text{if y is continuous}$$

$$p(\mathbf{x}) = \sum_{y} p(\mathbf{x}, y) \quad \text{if y is discrete}$$
(6)

Conditional probability also called the product rule is defined as:

$$p(\mathbf{x}, y) = \frac{p(\mathbf{x}, y)}{p(y)} \quad \text{where} p(y) \neq 0$$
  
$$\Rightarrow p(\mathbf{x}, y) = p(\mathbf{x}|y)p(y)$$
(7)

### 2.6 Bayes theorem: random variables

Both for probability mass functions and probability density functions:

$$p(x|y) = \frac{p(y|x)p(x)}{p(y)} \tag{8}$$

### 2.7 Probabilistic modelling

In probabilistic modelling we consider two types of variables:

$$\mathcal{D} = \{x_1, x_2, \dots, X_N\} : \text{ observed variables}$$
  

$$\Theta = \{x_1, x_2, \dots, X_N\} : \text{ latent variables}$$
(9)

In probabilistic modelling we treat both the observed variables and the latent variables as random variables

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We model this relationship between  $\mathcal{D}$  and  $\Theta$  with its **Joint distribution** 

$$p(\mathcal{D}, \Theta) = p(x_1, \dots, X_N, z_1, \dots, z_M) \tag{10}$$

#### 2.8 Bayes theorem in Probabilistic modelling

The joint distribution factorizes into likelihood and a prior

$$p(\mathcal{D}, \Theta) = p(\mathcal{D}|\Theta)p(\Theta) \tag{11}$$

We can now find  $p(\Theta|\mathcal{D})$  using **Bayes' theorem** 

$$p(\Theta|\mathcal{D}) = \frac{p(\mathcal{D}|p(\Theta))}{p(\mathcal{D})}$$
 (12)

 $\bullet$   $\mathcal{D}$ : observed data

 $\bullet$ : latent variables explaining the data

•  $p(\Theta)$ : **prior** belief of latent variables before seeing data

•  $p(\mathcal{D}|\Theta)$ : likelihood of the data in view of the latent variables

•  $p(\Theta|\mathcal{D})$ : **posterior** belief of latent variables in view of data

•  $p(\mathcal{D})$ : The marginal likelihood (presented in lecture 3)

## Example: Coin flip (Bayesian viewpoint)

•  $x \in \{0,1\}$  represent the outcome of flipping a damaged coin

•  $p(x=1|\mu) = \mu$ , which is also a random variable.

• Probability distribution  $p(\mu)$ : our prior belief

**Question:** After we observe N coin flips  $\{x_1, \ldots, x_N\}$ , what is our belief  $p(\mu|x_1, \ldots, x_N)$ ? **Solution:** Bayes theorem states that:

$$p(\mu|x_1,\dots,x_N) \propto p(x_1,\dots,x_N|\mu)p(\mu) \tag{13}$$

We will continue with this example next lecture...

## 2.9 Condluding remarks

Probabilistic/Bay inference is a flexible way of dealing the machine learning problems. Some properties to remember:

- Treat not only the data, but also the model and its parameters (if they are parametric) as random variables
- After learning you not only get a single model, you get a distribution of likely models.
- You can also encode prior knowledge you might have about the model and its parameters.

## 2.10 Summary

**Probability distribution** is a function that describes the likelihood of obtaining the possible values that a random variable can assume. **Conditional and marginalization** are two basic rules for manipulating probability distributions. **Frequentist vs Bayesian**: the first assume true values underlying some experiment and the second require some initial belief to be set on possible values.

- Bayes theorem: p(x|y) = p(y|x)p(x)/p(y)
- Prior, belief of parameters before we have seen any data
- Likelihood, belief of data in view of the parameters
- Posterior, belief of parameters after inferring data