



COMP250: Artificial Intelligence

5: Game Tree Search





Game trees

▶ We have already discussed **state-action graphs**

- ► We have already discussed state-action graphs
 - ► Nodes: environment states

- We have already discussed state-action graphs
 - ► Nodes: environment states
 - Edges: actions, which cause transitions from one state to another

- We have already discussed state-action graphs
 - ► Nodes: environment states
 - Edges: actions, which cause transitions from one state to another
- ► Such graphs could contain cycles or transpositions

- ► We have already discussed state-action graphs
 - ▶ Nodes: environment states
 - Edges: actions, which cause transitions from one state to another
- Such graphs could contain cycles or transpositions
 - ► Cycle: a sequence of actions which takes us from a state s_0 back to the same state s_0

- We have already discussed state-action graphs
 - Nodes: environment states.
 - Edges: actions, which cause transitions from one state to another
- Such graphs could contain cycles or transpositions
 - ► Cycle: a sequence of actions which takes us from a state s_0 back to the same state s_0
 - ► Transpositions: two different sequences of actions which both take us from a state s_1 to a state s_2

 Searching graphs with cycles and transpositions is tricky

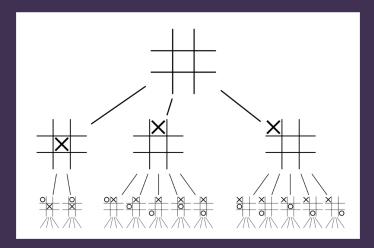
- Searching graphs with cycles and transpositions is tricky
- Compare with pathfinding needing to store a closed set of already searched nodes

- Searching graphs with cycles and transpositions is tricky
- Compare with pathfinding needing to store a closed set of already searched nodes
- ▶ So we often use a **tree** representation instead

- Searching graphs with cycles and transpositions is tricky
- Compare with pathfinding needing to store a closed set of already searched nodes
- ▶ So we often use a **tree** representation instead
- Same state may appear multiple times in the tree

- Searching graphs with cycles and transpositions is tricky
- Compare with pathfinding needing to store a closed set of already searched nodes
- ▶ So we often use a tree representation instead
- Same state may appear multiple times in the tree
- However, there are guaranteed no cycles or transpositions

Example







► Terminal game states have a **value**

- ► Terminal game states have a **value**
 - ightharpoonup E.g. +1 for a win, -1 for a loss, 0 for a draw

- ► Terminal game states have a **value**
 - ightharpoonup E.g. +1 for a win, -1 for a loss, 0 for a draw
- ▶ I want to **maximise** the value

- Terminal game states have a value
 - ightharpoonup E.g. +1 for a win, -1 for a loss, 0 for a draw
- ▶ I want to **maximise** the value
- My opponent wants to minimise the value

- ► Terminal game states have a value
 - ightharpoonup E.g. +1 for a win, -1 for a loss, 0 for a draw
- ▶ I want to **maximise** the value
- My opponent wants to minimise the value
- Therefore I want to maximise the minimum value my opponent can achieve

- ► Terminal game states have a value
 - ▶ E.g. +1 for a win, -1 for a loss, 0 for a draw
- ▶ I want to **maximise** the value
- My opponent wants to minimise the value
- Therefore I want to maximise the minimum value my opponent can achieve
- This is generally only true for two-player zero-sum games

Recursively defines a value for non-terminal game states

- Recursively defines a value for non-terminal game states
- Consider each possible "next state", i.e. each possible move

- Recursively defines a value for non-terminal game states
- Consider each possible "next state", i.e. each possible move
- If it's my turn, the value is the maximum value over next states

- Recursively defines a value for non-terminal game states
- Consider each possible "next state", i.e. each possible move
- If it's my turn, the value is the maximum value over next states
- If it's my opponent's turn, the value is the minimum value over next states

Minimax search – example

minimax.pptx

procedure MINIMAX(state, currentPlayer)

procedure MINIMAX(state, currentPlayer) **if** state is terminal **then**

procedure MINIMAX(state, currentPlayer)
if state is terminal then
return value of state

procedure MINIMAX(state, currentPlayer)
if state is terminal then
return value of state
else if currentPlayer = 1 then

procedure MINIMAX(state, currentPlayer) if state is terminal then return value of state else if currentPlayer = 1 then bestValue $= -\infty$

procedure MINIMAX(state, currentPlayer) if state is terminal then return value of state else if currentPlayer = 1 then bestValue = $-\infty$ for each possible nextState do

```
procedure MINIMAX(state, currentPlayer)
if state is terminal then
return value of state
else if currentPlayer = 1 then
bestValue = -\infty
for each possible nextState do
V = MINIMAX(nextState, 3- currentPlayer)
```

```
procedure Minimax(state, currentPlayer)
  if state is terminal then
    return value of state
  else if currentPlayer = 1 then
    bestValue = -∞
    for each possible nextState do
    v = Minimax(nextState, 3- currentPlayer)
    bestValue = Max(bestValue, v)
```

```
procedure MINIMAX(state, currentPlayer)
if state is terminal then
return value of state
else if currentPlayer = 1 then
bestValue = -\infty
for each possible nextState do
v = MINIMAX(nextState, 3- currentPlayer)
bestValue = MAX(bestValue, v)
return bestValue
```

```
procedure MINIMAX(state, currentPlayer)
if state is terminal then
return value of state
else if currentPlayer = 1 then
bestValue = -∞
for each possible nextState do
v = MINIMAX(nextState, 3- currentPlayer)
bestValue = MAX(bestValue, v)
return bestValue
else if currentPlayer = 2 then
```

```
procedure Minimax(state, currentPlayer)
   if state is terminal then
      return value of state
   else if currentPlayer = 1 then
      bestValue = -\infty
      for each possible nextState do
         v = MINIMAX(nextState, 3 - currentPlayer)
         bestValue = Max(bestValue, v)
      return bestValue
   else if currentPlayer = 2 then
      bestValue = +\infty
      for each possible nextState do
         v = MINIMAX(nextState, 3 - currentPlayer)
         bestValue = Min(bestValue, v)
      return bestValue
```

for each possible nextState do
 v = MINIMAX(nextState, 3- currentPlayer)
 bestValue = MAX(bestValue, v)

for each possible nextState do
 v = MINIMAX(nextState, 3- currentPlayer)
 bestValue = MAX(bestValue, v)

ightharpoonup State values are always between -1 and +1

for each possible nextState do
 v = MINIMAX(nextState, 3- currentPlayer)
 bestValue = MAX(bestValue, v)

- \blacktriangleright State values are always between -1 and +1
- So if we ever have bestValue = 1, we can stop early

for each possible nextState do
 v = MINIMAX(nextState, 3- currentPlayer)
 bestValue = MAX(bestValue, v)

- \blacktriangleright State values are always between -1 and +1
- ▶ So if we ever have bestValue = 1, we can stop early
- ightharpoonup Similarly when minimising if bestValue = -1

► To decide what move to play next...

- ► To decide what move to play next...
- Calculate the minimax value for each move

- ► To decide what move to play next...
- Calculate the minimax value for each move
- Choose the move with the maximum score

- To decide what move to play next...
- Calculate the minimax value for each move
- Choose the move with the maximum score
- If there are several with the same score, choose one at random

► For a two-player zero-sum game with perfect information and sequential moves

- ► For a two-player zero-sum game with perfect information and sequential moves
- ► Minimax search will always find a Nash equilibrium

- ► For a two-player zero-sum game with perfect information and sequential moves
- Minimax search will always find a Nash equilibrium
- ► I.e. a minimax player plays **perfectly**

- ► For a two-player zero-sum game with perfect information and sequential moves
- Minimax search will always find a Nash equilibrium
- ► I.e. a minimax player plays **perfectly**
- ▶ But...

The game tree for noughts and crosses has only a few thousand states

- The game tree for noughts and crosses has only a few thousand states
- Most games are too large to search fully

- The game tree for noughts and crosses has only a few thousand states
- Most games are too large to search fully
 - ► Connect 4 has $\approx 10^{13}$ states

- The game tree for noughts and crosses has only a few thousand states
- Most games are too large to search fully
 - ► Connect 4 has $\approx 10^{13}$ states
 - ► Chess has $\approx 10^{47}$ states





Heuristics for search

Standard minimax needs to search all the way to terminal (game over) states

- Standard minimax needs to search all the way to terminal (game over) states
- Depth limiting is a common technique to apply minimax to larger games

- Standard minimax needs to search all the way to terminal (game over) states
- Depth limiting is a common technique to apply minimax to larger games
- \blacktriangleright Still evaluate terminal states as +1/0/-1

- Standard minimax needs to search all the way to terminal (game over) states
- Depth limiting is a common technique to apply minimax to larger games
- ightharpoonup Still evaluate terminal states as +1/0/-1
- ► For nonterminal states at depth *d*, apply a heuristic evaluation instead of searching deeper

- Standard minimax needs to search all the way to terminal (game over) states
- Depth limiting is a common technique to apply minimax to larger games
- ightharpoonup Still evaluate terminal states as +1/0/-1
- ► For nonterminal states at depth *d*, apply a heuristic evaluation instead of searching deeper
- ► Evaluation is a number between -1 and +1, estimating the probable outcome of the game

▶ Case *d* = 1

- ► Case d = 1
- For each move, evaluate the state resulting from playing that move

- ightharpoonup Case d=1
- For each move, evaluate the state resulting from playing that move
- ► This is computationally fast

- ightharpoonup Case d=1
- For each move, evaluate the state resulting from playing that move
- ► This is computationally fast
- Often easier to design a "which state is better" heuristic than to directly design a "which move to play" heuristic

1-ply search

- ► Case d = 1
- For each move, evaluate the state resulting from playing that move
- ► This is computationally fast
- Often easier to design a "which state is better" heuristic than to directly design a "which move to play" heuristic
- ► This is essentially a utility-based AI

► Minimax can stop early if it sees a value of +1 for maximising player or -1 for minimising player

- ► Minimax can stop early if it sees a value of +1 for maximising player or -1 for minimising player
- Modifications to minimax algorithm (e.g. alpha-beta pruning) lead to more of this

- Minimax can stop early if it sees a value of +1 for maximising player or −1 for minimising player
- Modifications to minimax algorithm (e.g. alpha-beta pruning) lead to more of this
- Thus ordering moves from best to worst means faster search

- ► Minimax can stop early if it sees a value of +1 for maximising player or -1 for minimising player
- Modifications to minimax algorithm (e.g. alpha-beta pruning) lead to more of this
- Thus ordering moves from best to worst means faster search
- How do we know which moves are "best" and "worst"? Use a heuristic!

► The playing strength of depth limited minimax depends heavily on the design of the heuristic

- ► The playing strength of depth limited minimax depends heavily on the design of the heuristic
- Good heuristic design requires in-depth knowledge of the tactics and strategy of the game

- ► The playing strength of depth limited minimax depends heavily on the design of the heuristic
- Good heuristic design requires in-depth knowledge of the tactics and strategy of the game
- ▶ What if we don't possess such knowledge?



Monte Carlo evaluation

▶ In computing, a Monte Carlo method is an algorithm based on averaging over random samples

- ▶ In computing, a Monte Carlo method is an algorithm based on averaging over random samples
- The average over a large number of samples is a good approximation of the expected value

- In computing, a Monte Carlo method is an algorithm based on averaging over random samples
- The average over a large number of samples is a good approximation of the expected value
- Used for quickly approximating quantities over large domains

- In computing, a Monte Carlo method is an algorithm based on averaging over random samples
- The average over a large number of samples is a good approximation of the expected value
- Used for quickly approximating quantities over large domains
- Generally designed to converge in the limit

- ▶ In computing, a Monte Carlo method is an algorithm based on averaging over random samples
- The average over a large number of samples is a good approximation of the expected value
- Used for quickly approximating quantities over large domains
- Generally designed to converge in the limit
 - An infinite number of samples would give an exact answer

- ▶ In computing, a Monte Carlo method is an algorithm based on averaging over random samples
- The average over a large number of samples is a good approximation of the expected value
- Used for quickly approximating quantities over large domains
- Generally designed to converge in the limit
 - An infinite number of samples would give an exact answer
 - As the number of samples increases, the accuracy of the answer improves

- ▶ In computing, a Monte Carlo method is an algorithm based on averaging over random samples
- The average over a large number of samples is a good approximation of the expected value
- Used for quickly approximating quantities over large domains
- Generally designed to converge in the limit
 - An infinite number of samples would give an exact answer
 - As the number of samples increases, the accuracy of the answer improves
- Applications in physics, engineering, finance, weather forecasting, graphics, ...

▶ Digital computers are deterministic, so there's no such thing as true randomness

- Digital computers are deterministic, so there's no such thing as true randomness
 - Cryptographically secure systems use an external source of randomness e.g. atmospheric noise, radioactive decay

- ▶ Digital computers are deterministic, so there's no such thing as true randomness
 - Cryptographically secure systems use an external source of randomness e.g. atmospheric noise, radioactive decay
- What we actually have are pseudo-random number generators (PRNGs)

- ▶ Digital computers are deterministic, so there's no such thing as true randomness
 - Cryptographically secure systems use an external source of randomness e.g. atmospheric noise, radioactive decay
- What we actually have are pseudo-random number generators (PRNGs)
- ▶ A PRNG is an algorithm which gives an unpredictable sequence of numbers based on a seed

- ▶ Digital computers are deterministic, so there's no such thing as true randomness
 - Cryptographically secure systems use an external source of randomness e.g. atmospheric noise, radioactive decay
- What we actually have are pseudo-random number generators (PRNGs)
- A PRNG is an algorithm which gives an unpredictable sequence of numbers based on a seed
- Sequence is uniformly distributed, i.e. all numbers have equal probability

- ▶ Digital computers are deterministic, so there's no such thing as true randomness
 - Cryptographically secure systems use an external source of randomness e.g. atmospheric noise, radioactive decay
- What we actually have are pseudo-random number generators (PRNGs)
- A PRNG is an algorithm which gives an unpredictable sequence of numbers based on a seed
- Sequence is uniformly distributed, i.e. all numbers have equal probability
- Seed is generally based on some source of entropy, e.g. system clock, mouse input, electronic noise

► Based on random rollouts

► Based on random rollouts

while s is not terminal dolet m be a random legal move from supdate s by playing m

- ► Based on random rollouts
- while s is not terminal do
 let m be a random legal move from s
 update s by playing m
- ► The value of a rollout is the value of the terminal state it reaches (i.e. 1 for a win, -1 for a loss, 0 for a draw)

- ► Based on random rollouts
- while s is not terminal do
 let m be a random legal move from s
 update s by playing m
- ► The **value** of a rollout is the **value** of the terminal state it reaches (i.e. 1 for a win, -1 for a loss, 0 for a draw)
- ► Averaging gives the **expected value** of the initial state

- ► Based on random rollouts
- while s is not terminal do
 let m be a random legal move from s
 update s by playing m
- ► The value of a rollout is the value of the terminal state it reaches (i.e. 1 for a win, -1 for a loss, 0 for a draw)
- Averaging gives the expected value of the initial state
- ► Higher expected value = more chance of winning

► Flat Monte Carlo search: 1-ply search with Monte Carlo evaluation

- ► Flat Monte Carlo search: 1-ply search with Monte Carlo evaluation
- How about minimax with d > 1 and Monte Carlo evaluation?

- ► Flat Monte Carlo search: 1-ply search with Monte Carlo evaluation
- How about minimax with d > 1 and Monte Carlo evaluation?
 - Minimax assumes the evaluation is deterministic, but Monte Carlo is not

Monte Carlo search

- ► Flat Monte Carlo search: 1-ply search with Monte Carlo evaluation
- How about minimax with d > 1 and Monte Carlo evaluation?
 - Minimax assumes the evaluation is deterministic, but Monte Carlo is not
 - Not commonly used, mainly because there's something better...





► Like Monte Carlo evaluation, based on **rollouts**

- ► Like Monte Carlo evaluation, based on **rollouts**
- ► First few rollouts are random

- Like Monte Carlo evaluation, based on rollouts
- First few rollouts are random
- However, statistics from these rollouts are used to bias future rollouts

- Like Monte Carlo evaluation, based on rollouts
- First few rollouts are random
- However, statistics from these rollouts are used to bias future rollouts
- Bias rollouts towards plausible lines of play, i.e. where each player is trying to play the best move

► MCTS builds a **subtree** of the game tree

- ▶ MCTS builds a subtree of the game tree
- Initially, the tree consists of a single root node

- ▶ MCTS builds a **subtree** of the game tree
- Initially, the tree consists of a single root node
- Each rollout has four stages:

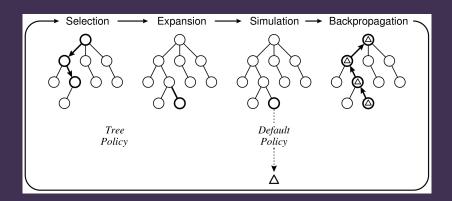
- MCTS builds a subtree of the game tree
- Initially, the tree consists of a single root node
- Each rollout has four stages:
 - Selection: Starting from the root, descend the tree by choosing moves. Continue until we reach a node which does not yet have children for all legal moves.

- ► MCTS builds a **subtree** of the game tree
- Initially, the tree consists of a single root node
- Each rollout has four stages:
 - Selection: Starting from the root, descend the tree by choosing moves. Continue until we reach a node which does not yet have children for all legal moves.
 - ► **Expansion**: Choose a random legal move for which the current node does not have a child node. Add this new node to the tree.

- MCTS builds a subtree of the game tree
- Initially, the tree consists of a single root node
- Each rollout has four stages:
 - Selection: Starting from the root, descend the tree by choosing moves. Continue until we reach a node which does not yet have children for all legal moves.
 - ► **Expansion**: Choose a random legal move for which the current node does not have a child node. Add this new node to the tree.
 - ▶ **Simulation**: Perform a Monte Carlo rollout, playing random moves until a terminal state is reached.

- MCTS builds a subtree of the game tree
- Initially, the tree consists of a single root node
- Each rollout has four stages:
 - Selection: Starting from the root, descend the tree by choosing moves. Continue until we reach a node which does not yet have children for all legal moves.
 - ► **Expansion**: Choose a random legal move for which the current node does not have a child node. Add this new node to the tree.
 - Simulation: Perform a Monte Carlo rollout, playing random moves until a terminal state is reached.
 - ▶ Backpropagation: For each node visited during selection and expansion, update the node's statistics based on the result of the simulation.

- MCTS builds a subtree of the game tree
- Initially, the tree consists of a single root node
- Each rollout has four stages:
 - Selection: Starting from the root, descend the tree by choosing moves. Continue until we reach a node which does not yet have children for all legal moves.
 - ► **Expansion**: Choose a random legal move for which the current node does not have a child node. Add this new node to the tree.
 - Simulation: Perform a Monte Carlo rollout, playing random moves until a terminal state is reached.
 - ▶ Backpropagation: For each node visited during selection and expansion, update the node's statistics based on the result of the simulation.
- ► Perform many rollouts, then use the statistics at the top level of the tree to choose the best move



► Selection must balance:

- ► Selection must balance:
 - Exploitation of moves that are known to be good

- Selection must balance:
 - Exploitation of moves that are known to be good
 - Exploration of moves that have not often been tried

- Selection must balance:
 - Exploitation of moves that are known to be good
 - Exploration of moves that have not often been tried
- This can be modelled as a multi-armed bandit problem

► We have a row of one-armed bandits (slot machines)

- We have a row of one-armed bandits (slot machines)
- We do not know the payout probabilities of any of them, and they're all different

- We have a row of one-armed bandits (slot machines)
- We do not know the payout probabilities of any of them, and they're all different
- ► How to maximise our winnings?

- We have a row of one-armed bandits (slot machines)
- We do not know the payout probabilities of any of them, and they're all different
- How to maximise our winnings?
- ► Again must balance

- ▶ We have a row of one-armed bandits (slot machines)
- We do not know the payout probabilities of any of them, and they're all different
- ► How to maximise our winnings?
- Again must balance
 - Exploitation of machines that are known to have a high expected payout

- ▶ We have a row of one-armed bandits (slot machines)
- We do not know the payout probabilities of any of them, and they're all different
- ▶ How to maximise our winnings?
- Again must balance
 - Exploitation of machines that are known to have a high expected payout
 - Exploration of machines that have not been tried often, to get a better estimate of their expected payout

► For each machine *m*, record:

- ► For each machine *m*, record:
 - $ightharpoonup n_m$: the number of plays of this machine

- ► For each machine *m*, record:
 - $ightharpoonup n_m$: the number of plays of this machine
 - $ightharpoonup V_m$: the total winnings from playing this machine

- ► For each machine *m*, record:
 - $ightharpoonup n_m$: the number of plays of this machine
 - $ightharpoonup V_m$: the total winnings from playing this machine
 - $ightharpoonup n = \sum_m n_m$, total number of plays across all machines

- For each machine *m*, record:
 - \triangleright n_m : the number of plays of this machine
 - $ightharpoonup V_m$: the total winnings from playing this machine
 - $ightharpoonup n = \sum_m n_m$, total number of plays across all machines
- At each stage, play the machine for which

$$\frac{V_m}{n_m} + C\sqrt{\frac{\log n}{n_m}}$$

is largest

- For each machine *m*, record:
 - $ightharpoonup n_m$: the number of plays of this machine
 - $ightharpoonup V_m$: the total winnings from playing this machine
 - $ightharpoonup n = \sum_m n_m$, total number of plays across all machines
- At each stage, play the machine for which

$$\frac{V_m}{n_m} + C\sqrt{\frac{\log n}{n_m}}$$

is largest

 $ightharpoonup rac{V_m}{n_m}$ is the **exploitation** part: average payout from this machine so far

Upper Confidence Bound (UCB)

- For each machine *m*, record:
 - $ightharpoonup n_m$: the number of plays of this machine
 - $ightharpoonup V_m$: the total winnings from playing this machine
 - $ightharpoonup n = \sum_m n_m$, total number of plays across all machines
- At each stage, play the machine for which

$$\frac{V_m}{n_m} + C\sqrt{\frac{\log n}{n_m}}$$

is largest

- $V_m = V_m / V_m$ is the **exploitation** part: average payout from this machine so far
- \blacktriangleright $\sqrt{\frac{\log n}{n_m}}$ is the **exploration** part: large if n_m is small

Upper Confidence Bound (UCB)

- ► For each machine *m*, record:
 - $ightharpoonup n_m$: the number of plays of this machine
 - $ightharpoonup V_m$: the total winnings from playing this machine
 - $ightharpoonup n = \sum_m n_m$, total number of plays across all machines
- At each stage, play the machine for which

$$\frac{V_m}{n_m} + C\sqrt{\frac{\log n}{n_m}}$$

is largest

- $ightharpoonup rac{V_m}{n_m}$ is the **exploitation** part: average payout from this machine so far
- $ightharpoonup \sqrt{\frac{\log n}{n_m}}$ is the **exploration** part: large if n_m is small
- $\stackrel{\cdot}{c}$ is a parameter for adjusting the balance between exploitation and exploration



UCB demo

http://orangehelicopter.com/academic/bandits.
html?ucb

▶ Use UCB as the selection policy

- Use UCB as the selection policy
- ▶ In each node x, record:

- Use UCB as the selection policy
- ▶ In each node x, record:
 - $ightharpoonup n_x$: the number of visits to this node

- Use UCB as the selection policy
- ▶ In each node x, record:
 - $ightharpoonup n_x$: the number of visits to this node
 - $ightharpoonup V_x$: the total value of rollouts through this node

- ► Use UCB as the selection policy
- ► In each node x, record:
 - $ightharpoonup n_x$: the number of visits to this node
 - $ightharpoonup V_x$: the total value of rollouts through this node
- ightharpoonup From node p, choose the child q such that

$$\frac{V_q}{n_q} + c\sqrt{\frac{\log n_p}{n_q}}$$

is largest

UCT demo

InteractiveDemo.exe

► "Vanilla" MCTS is game independent

- ▶ "Vanilla" MCTS is game independent
- ▶ But if game-specific heuristics are available, they can be used to enhance MCTS

- ▶ "Vanilla" MCTS is game independent
- But if game-specific heuristics are available, they can be used to enhance MCTS
- ► MCTS is **anytime**

- "Vanilla" MCTS is game independent
- But if game-specific heuristics are available, they can be used to enhance MCTS
- ► MCTS is **anytime**
 - Can stop it after any amount of computation (within reason) and get a reasonably good answer

- "Vanilla" MCTS is game independent
- But if game-specific heuristics are available, they can be used to enhance MCTS
- MCTS is anytime
 - Can stop it after any amount of computation (within reason) and get a reasonably good answer
 - ► Compare with minimax: $O(e^d)$ for depth d

- "Vanilla" MCTS is game independent
- But if game-specific heuristics are available, they can be used to enhance MCTS
- MCTS is anytime
 - Can stop it after any amount of computation (within reason) and get a reasonably good answer
 - ► Compare with minimax: $O(e^d)$ for depth d
- Does not suffer from horizon effect

- "Vanilla" MCTS is game independent
- But if game-specific heuristics are available, they can be used to enhance MCTS
- MCTS is anytime
 - Can stop it after any amount of computation (within reason) and get a reasonably good answer
 - ► Compare with minimax: $O(e^d)$ for depth d
- Does not suffer from horizon effect
 - Minimax at depth d cannot "see" what happens d+1 moves in the future

- "Vanilla" MCTS is game independent
- But if game-specific heuristics are available, they can be used to enhance MCTS
- MCTS is anytime
 - Can stop it after any amount of computation (within reason) and get a reasonably good answer
 - ► Compare with minimax: $O(e^d)$ for depth d
- Does not suffer from horizon effect
 - Minimax at depth d cannot "see" what happens d+1 moves in the future
 - MCTS can build the tree as deep as it likes

- "Vanilla" MCTS is game independent
- But if game-specific heuristics are available, they can be used to enhance MCTS
- MCTS is anytime
 - Can stop it after any amount of computation (within reason) and get a reasonably good answer
 - ► Compare with minimax: $O(e^d)$ for depth d
- Does not suffer from horizon effect
 - Minimax at depth d cannot "see" what happens d+1 moves in the future
 - MCTS can build the tree as deep as it likes
 - Selects which parts of the tree to expand more deeply