



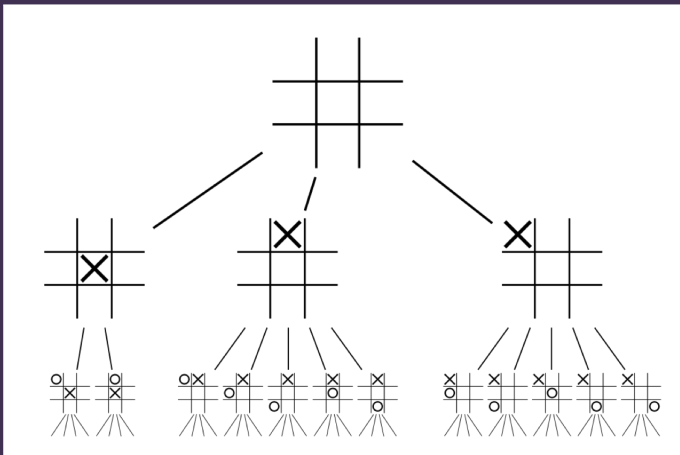
COMP250: Artificial Intelligence

5: Game Tree Search

Minimax search



Game trees



Minimax

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- ▶ I want to **maximise** the value
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- ▶ Therefore I want to **maximise** the **minimum** value my opponent can achieve
- ▶ This is generally only true for **two-player zero-sum** games

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Minimax search – example

Minimax search pseudocode

procedure MINIMAX(state, currentPlayer)

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  else if currentPlayer = 2 then
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- ▶ Similarly when minimising if $\text{bestValue} = -1$

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- ▶ If there are several with the same score, choose one at random

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- ▶ Minimax search will always find a **Nash equilibrium**
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- ▶ **But...**

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 - ▶ Connect 4 has $\approx 10^{13}$ states
 - ▶ Chess has $\approx 10^{47}$ states

Heuristics for search



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- ▶ For nonterminal states at depth d , apply a heuristic evaluation instead of searching deeper
- ▶ Evaluation is a number between -1 and $+1$, estimating the probable outcome of the game

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- ▶ Often easier to design a “which state is better” heuristic than to directly design a “which move to play” heuristic

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- ▶ Modifications to minimax algorithm (e.g. **alpha-beta pruning**) lead to more of this
- ▶ Thus ordering moves from **best to worst** means faster search
- ▶ How do we know which moves are “best” and “worst”? Use a heuristic!

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- ▶ Next time we will look at what we can do if we don't possess such knowledge

Monte Carlo evaluation



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Recap

- ▶ It is useful to have a **heuristic evaluation function** for nonterminal states
- ▶ Allows 1-ply search, depth-limited minimax, ...
- ▶ Designing a good heuristic requires in-depth knowledge of the game
- ▶ What if you don't have such knowledge?

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- ▶ Applications in physics, engineering, finance, weather forecasting, graphics, ...

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- ▶ Seed is generally based on some source of **entropy**, e.g. system clock, mouse input, electronic noise

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- ▶ Higher expected value = more chance of winning

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- ▶ How about minimax with $d > 1$ and Monte Carlo evaluation?
 - ▶ Minimax assumes the evaluation is **deterministic**, but Monte Carlo is not
 - ▶ Not commonly used, mainly because there's something better...

Monte Carlo Tree Search



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- ▶ First few rollouts are **random**
- ▶ However, statistics from these rollouts are used to **bias** future rollouts
- ▶ Bias rollouts towards **plausible** lines of play, i.e. where each player is trying to play the best move

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- ▶ Each rollout has four stages:
 - ▶ **Selection:** Starting from the root, descend the tree by choosing moves. Continue until we reach a node which does not yet have children for all legal moves.
 - ▶ **Expansion:** Choose a random legal move for which the current node does not have a child node. Add this new node to the tree.

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 - ▶ **Simulation:** Perform a Monte Carlo rollout, playing random moves until a terminal state is reached.

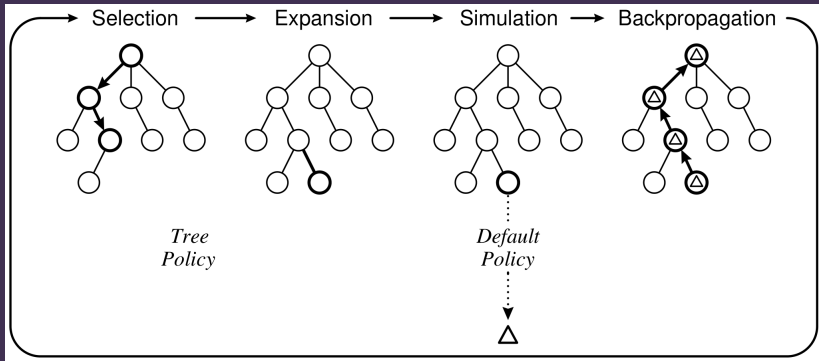
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 - ▶ **Simulation**: Perform a Monte Carlo rollout, playing random moves until a terminal state is reached.
 - ▶ **Backpropagation**: For each node visited during **selection** and **expansion**, update the node's statistics based on the result of the simulation.
- ▶ Perform many rollouts, then use the statistics at the top level of the tree to choose the best move

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 - ▶ **Exploration** of moves that have not often been tried
- ▶ This can be modelled as a **multi-armed bandit problem**

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 - ▶ **Exploitation** of machines that are known to have a high expected payout
 - ▶ **Exploration** of machines that have not been tried often, to get a better estimate of their expected payout

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- ▶ $\frac{V_m}{n_m}$ is the **exploitation** part: average payout from this machine so far

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 - ▶ n_m : the number of plays of this machine
 - ▶ V_m : the total winnings from playing this machine
 - ▶ $n = \sum_m n_m$, total number of plays across all machines
- ▶ At each stage, play the machine for which

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- ▶ c is a parameter for adjusting the balance between exploitation and exploration

UCB demo

`http://orangehelicopter.com/academic/bandits.
html?ucb`

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- ▶ From node p , choose the child q such that

$$\frac{V_q}{n_q} + c \sqrt{\frac{\log n_p}{n_q}}$$

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UCT demo

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