X random variable
$p(x)$ X x
expected value X

£10.05
£50.03
£100.02
0.9

£0.40
NN $N \times £0.40$
GOAP
goal set
priority
actions
cost
same goals **different action sets**
different ways
emerges
$_a ction_s ets$
layered
$_l ayering$
abstracted
programmatic
tree
queue
replan
authored behaviour
computational intelligence