

# 4: Newtonian Mechanics

COMP270: MATHEMATICS FOR 3D WORLDS & SIMULATIONS



# Trigonometric identities

---

# Silly Old Harry Caught A Herring Trawling Off America

---

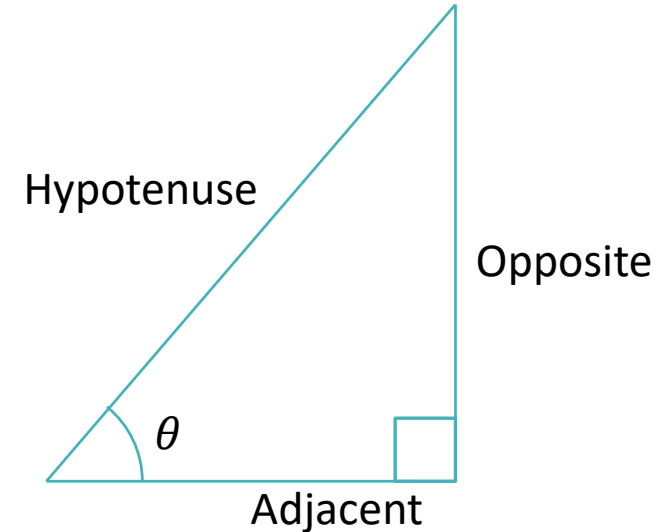
$$\sin \theta = \frac{\text{Opposite}}{\text{Hypotenuse}}$$

$$\cos \theta = \frac{\text{Adjacent}}{\text{Hypotenuse}}$$

$$\tan \theta = \frac{\text{Opposite}}{\text{Adjacent}}$$

- Therefore

$$\tan \theta = \frac{\sin \theta}{\cos \theta}$$



# Other trigonometric functions

---

- Secant:  $\sec \theta = \frac{1}{\cos \theta}$
- Cosecant:  $\csc \theta = \frac{1}{\sin \theta}$
- Cotangent:  $\cot \theta = \frac{1}{\tan \theta}$

Named after Pythagoras of Samos  
(c570 – c495 BC), Greek philosopher

# Pythagorean identities

---

$$\sin^2 \theta + \cos^2 \theta = 1$$

Divide through by  $\cos^2 \theta$ :

$$1 + \tan^2 \theta = \sec^2 \theta$$

Divide through by  $\sin^2 \theta$ :

$$1 + \cot^2 \theta = \csc^2 \theta$$

# Sum, difference, double angle formulae

---

$$\sin(\alpha + \beta) = \sin \alpha \cos \beta + \cos \alpha \sin \beta$$

$$\sin(\alpha - \beta) = \sin \alpha \cos \beta - \cos \alpha \sin \beta$$

$$\cos(\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta$$

$$\cos(\alpha - \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta$$

$$\sin 2\theta = 2 \sin \theta \cos \theta$$

$$\cos 2\theta = \cos^2 \theta - \sin^2 \theta$$

# Calculus

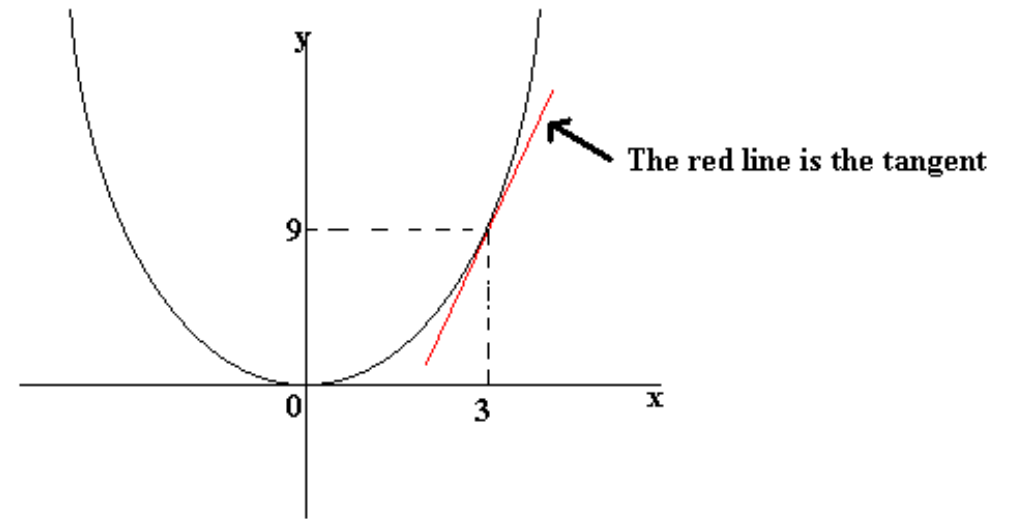
---

# Rates of change

---

- Consider a quantity that changes over time
- Rate of change =  $\frac{\text{Change in quantity}}{\text{Change in time}}$
- Same as the gradient of a graph:

$$\text{radient} = \frac{\text{Change in } y}{\text{Change in } x}$$





# Derivatives

---

- The **derivative** of a quantity  $x$  with respect to time  $t$  is the rate of change of  $x$  with respect to  $t$
- Denoted  $\frac{dx}{dt}$
- The mathematical process of finding  $\frac{dx}{dt}$  given  $x$  is called **differentiation**

# Derivatives: example

---

- A car drives along a straight road at a constant speed
- In half an hour, it covers a distance of 20 miles
- Its speed (which we know is constant) is  $\frac{20 \text{ miles}}{0.5 \text{ hours}} = 40 \text{ miles per hour}$
- In other words...
  - “Distance travelled” is a quantity varying with time
  - We call the rate of change (the derivative) of this quantity “speed”
  - If  $x$  is distance travelled and  $t$  is time, then

$$\frac{dx}{dt} = \frac{20}{0.5} = 40$$

# Integration

---

- Given  $\frac{dx}{dt}$ , find  $x$
- $x$  is the **integral** of  $\frac{dx}{dt}$
- The process of finding this is called **integration** – the opposite of differentiation

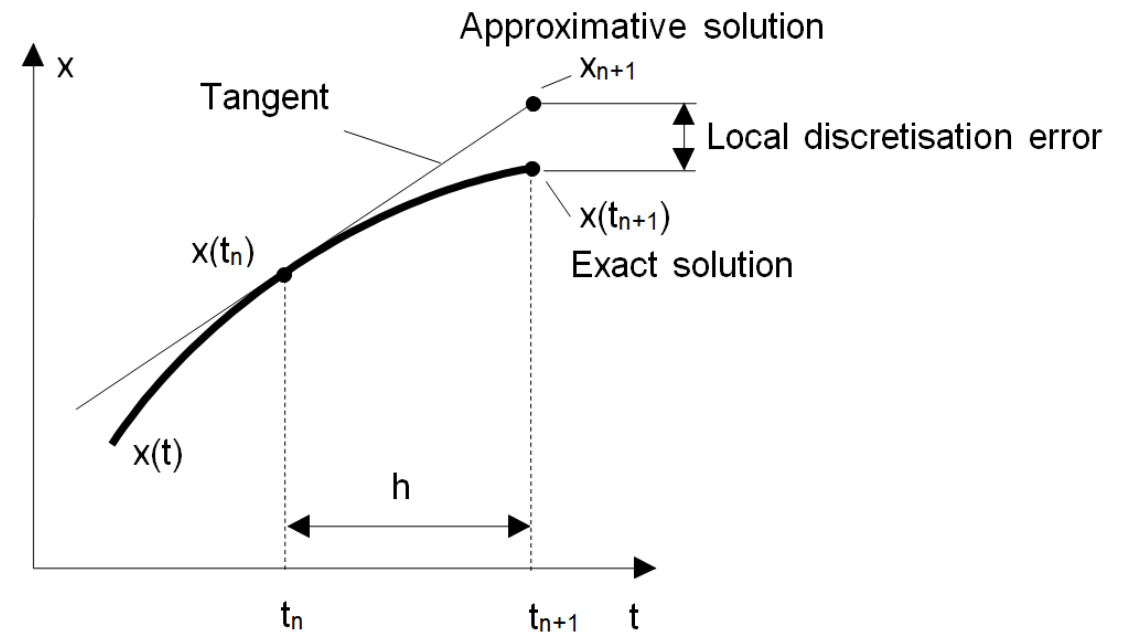
Leonhard Euler (1707-1783),  
Swiss mathematician

Pronounced “oiler”

# Numerical integration – Euler’s method

- Given the values of  $x$  and  $\frac{dx}{dt}$  at time  $t$ , we can estimate the value of  $x$  at time  $t + h$  for small  $h$ :

$$x(t + h) \approx x(t) + h \frac{dx}{dt}$$



# Calculus with vectors

---

- The rate of change of a vector is also a vector
- If  $\mathbf{v} \in \mathbb{R}^n$  then  $\frac{d\mathbf{v}}{dt} \in \mathbb{R}^n$
- Differentiate component-wise: if  $\mathbf{v} = \begin{pmatrix} x \\ y \end{pmatrix}$  then

$$\frac{d\mathbf{v}}{dt} = \begin{pmatrix} dx/dt \\ dy/dt \end{pmatrix}$$

# Basic mechanics

---

# Basic quantities of mechanics

---

- **Position** describes an object's location in space
- **Velocity** is rate of change of position
- **Acceleration** is rate of change of velocity

# Velocity and speed

---

- Velocity is a **vector** quantity – has a **magnitude** and a **direction**
- We call the magnitude of velocity the **speed**



*Système international*, or the  
International System of Units

# Units

---

- In SI units:
- Position is usually measured in metres (m)
- Velocity is measured in metres per second (m/s or  $\text{ms}^{-1}$ )
- Acceleration is measured in metres per second per second ( $\text{m/s}^2$  or  $\text{ms}^{-2}$ )
- Other units are possible (e.g. pixels, miles, hours) but be consistent!

Named after Isaac Newton (1642-1726/27),  
English mathematician

# Force

---

- SI unit: Newtons (N)
- Forces occur when objects interact
- E.g. gravity, air resistance, friction
- E.g. reaction force
- E.g. car engine, rocket engine, launched projectile, muscle, ...

# Newton's Laws of Motion

---

- 1: An object remains at rest or moves at constant velocity unless acted upon by an external force
- 2: The sum of forces acting upon an object is equal to its mass multiplied by its acceleration ( $\mathbf{F} = m\mathbf{a}$ )
- 3: When one body exerts a force on another, the second body exerts an equal and opposite force on the first

# Simulating Newtonian physics

---

- For each object, store its position and velocity
- On each time step:
- Apply numerical integration to the velocity to determine the new position
- Calculate the forces acting upon the object, and thus the acceleration from Newton's 2<sup>nd</sup> law
- Apply numerical integration to the acceleration to determine the new velocity

# Gravity

---

- A force which pulls all objects with mass towards each other
- Tiny unless one or both objects has huge mass (e.g. a planet)
- Near the surface of a planet, gravity pulls objects downwards (towards the centre of the planet) with a force called weight
- $w = mg$ , where  $w$  is weight,  $m$  is mass and  $g$  is the acceleration due to gravity
- Near Earth's surface,  $g \approx 9.81\text{ms}^{-2}$  -- same for all objects on Earth, but differs on other planets

# Gravity

---

- Gravity applies the same acceleration ( $9.81\text{ms}^{-2}$ ) to all objects on Earth, regardless of weight
- The only reason that some objects fall faster than others is air resistance – in a vacuum all objects fall at the same rate



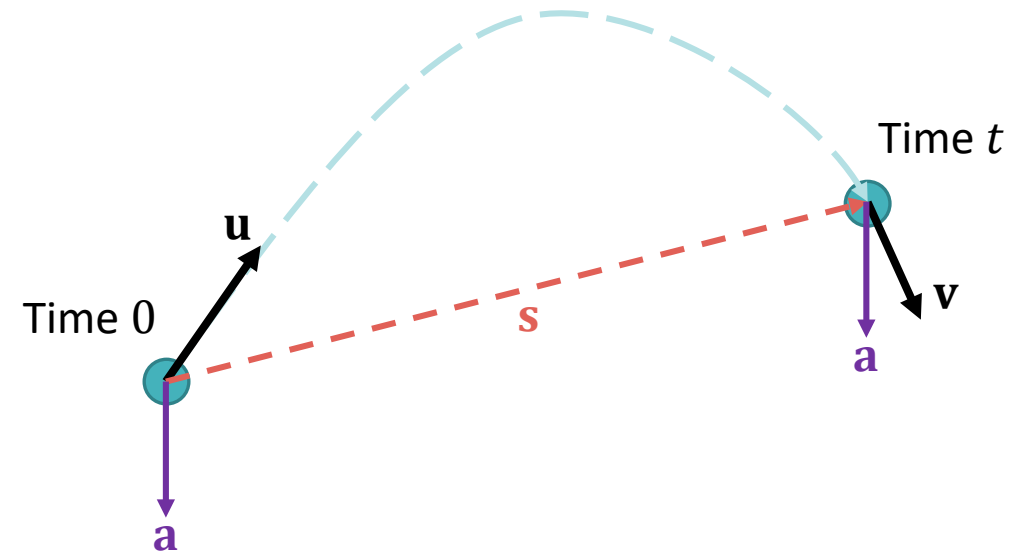
# Equations of motion

---

# Setup

---

- Consider a particle under **constant acceleration**
- E.g. under gravity with no other forces acting
- At all times, the acceleration of the particle is  $\mathbf{a}$
- At time 0, assume the particle is at the origin and has velocity  $\mathbf{u}$
- At time  $t$ , let  $\mathbf{s}$  be the particle's position and let  $\mathbf{v}$  be its velocity





# Equations of motion (SUVAT equations)

---

$$\mathbf{v} = \mathbf{u} + \mathbf{a}t$$

$$\mathbf{s} = \mathbf{u}t + \frac{1}{2}\mathbf{a}t^2$$

$$\mathbf{s} = \frac{1}{2}(\mathbf{u} + \mathbf{v})t$$

$$\|\mathbf{v}\|^2 = \|\mathbf{u}\|^2 + 2\mathbf{a} \cdot \mathbf{s}$$

$$\mathbf{s} = \mathbf{v}t - \frac{1}{2}\mathbf{a}t^2$$

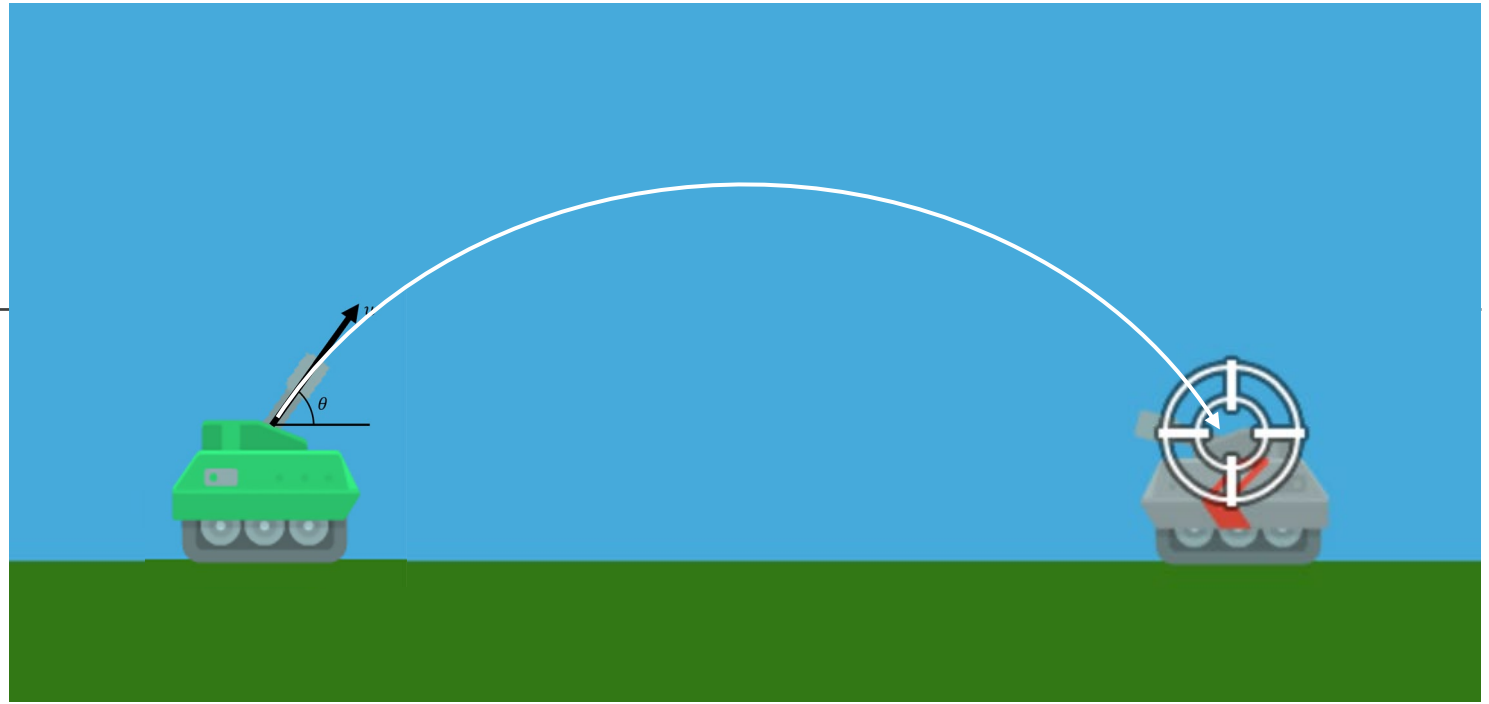
# Example

---

- A particle is dropped and falls under gravity:  $\mathbf{u} = 0$ ,  $\mathbf{a} = \begin{pmatrix} 0 \\ -9.81 \end{pmatrix}$
- At time  $t = 5$  seconds:
- $\mathbf{v} = \mathbf{u} + \mathbf{a}t = \begin{pmatrix} 0 \\ 5 \times -9.81 \end{pmatrix}$  -- the particle is falling downwards at 49.05 metres per second
- $\mathbf{s} = \mathbf{u}t + \frac{1}{2}\mathbf{a}t^2 = \frac{25}{2} \begin{pmatrix} 0 \\ -9.81 \end{pmatrix}$  -- the particle has fallen down a distance of 122.625 metres

# Projectile motion

---



- A tank fires a bullet with initial speed  $u$  at angle  $\theta$
- $\mathbf{u} = \begin{pmatrix} u \cos \theta \\ u \sin \theta \end{pmatrix}$ ,  $\mathbf{a} = \begin{pmatrix} 0 \\ -g \end{pmatrix}$

# Projectile motion

---

- At time  $t$ , the position of the bullet relative to the tank is

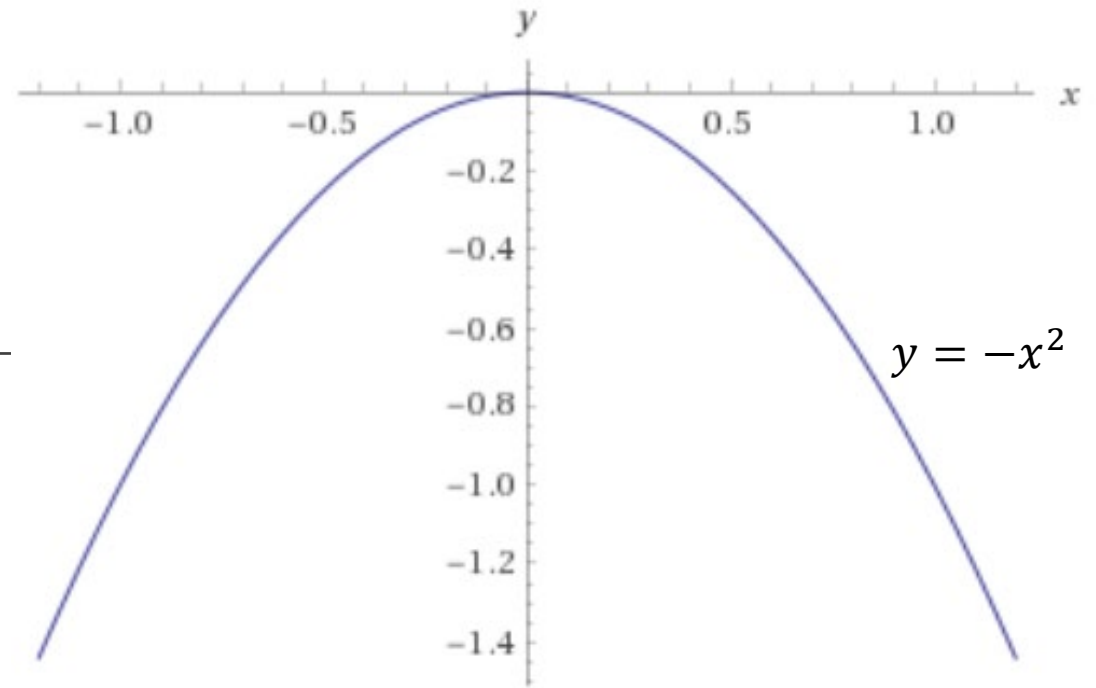
$$\begin{aligned}\mathbf{s} &= \mathbf{u}t + \frac{1}{2}\mathbf{a}t^2 \\ &= \begin{pmatrix} u \cos \theta \\ u \sin \theta \end{pmatrix} t + \frac{1}{2} \begin{pmatrix} 0 \\ -g \end{pmatrix} t^2 \\ &= \begin{pmatrix} u \cos \theta t \\ u \sin \theta t - \frac{gt^2}{2} \end{pmatrix}\end{aligned}$$

# Projectile motion

---

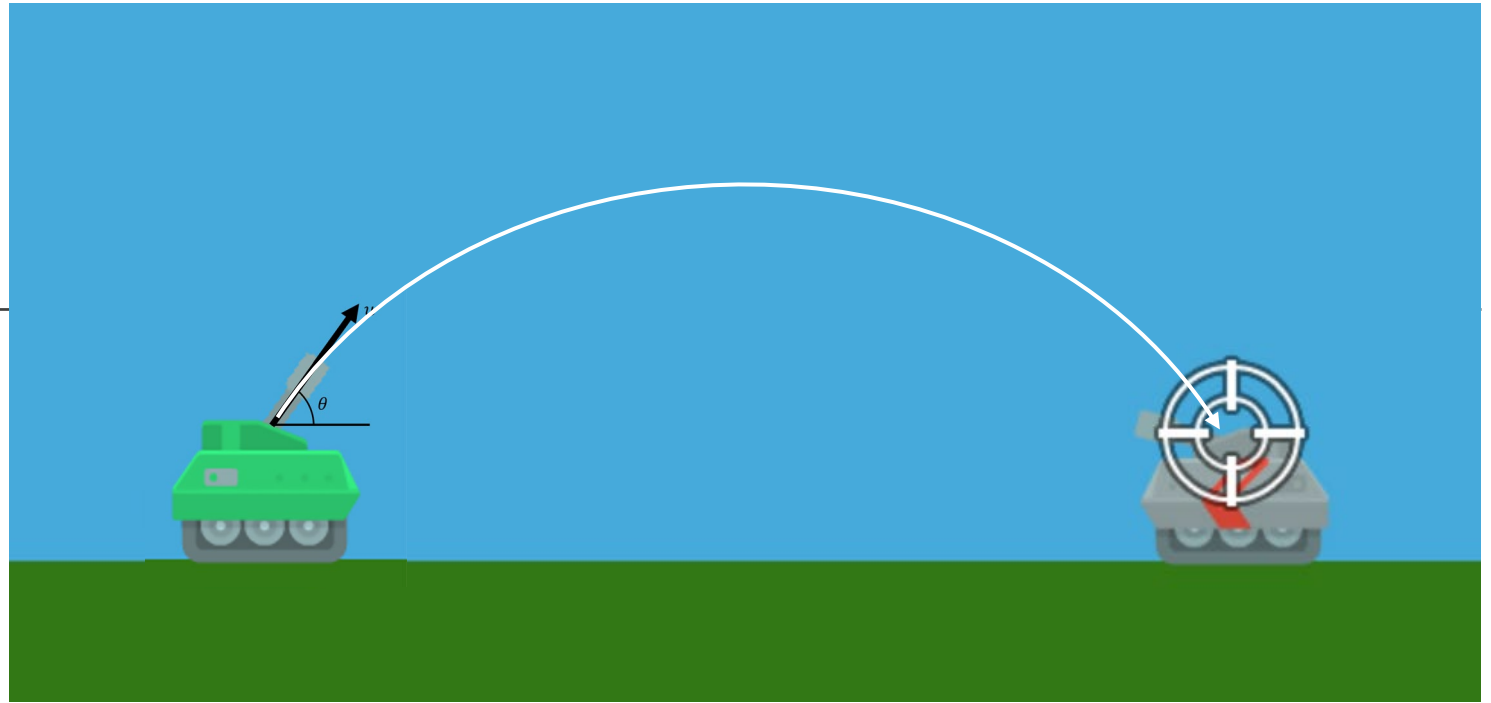
$$\mathbf{s} = \begin{pmatrix} u \cos \theta t \\ u \sin \theta t - \frac{gt^2}{2} \end{pmatrix}$$

- Horizontally: position changes **linearly** with  $t$
- Vertically: position is a **quadratic**
- The shape of motion is a **parabola**



# Projectile motion

---



- The enemy tank is a distance of  $x$  units away, at the same elevation
- Given angle  $\theta$ , what shot speed  $u$  is needed to hit the enemy tank?

# Finding the shot speed

---

$$\mathbf{s} = \begin{pmatrix} x \\ 0 \end{pmatrix} = \begin{pmatrix} u \cos \theta t \\ u \sin \theta t - \frac{1}{2}gt^2 \end{pmatrix}$$

- Considering x and y components gives simultaneous equations:

$$x = u \cos \theta t$$

$$y = u \sin \theta t - \frac{1}{2}gt^2$$

- Solving for  $u$  gives

$$u = \sqrt{\frac{xg}{\sin 2\theta}}$$

# Worksheet B

---



# Worksheets

---

- Worksheet A: due today!
- Worksheet B: now available on LearningSpace
- Due in 2 weeks (28<sup>th</sup> October)