

COMP250: Artificial Intelligence

4: Planning

Logic



Logical operations

Python	C family	Mathematics	Behaviour tree
<code>not</code> a	<code>!a</code>	$\neg A$ or \overline{A}	Inverter
a <code>and</code> b	a <code>&&</code> b	$A \wedge B$	Sequence
a <code>or</code> b	a <code> </code> b	$A \vee B$	Selector

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- ▶ E.g. `LivesIn(Bob, Falmouth)` could be a predicate for “Bob lives in Falmouth”

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 - ▶ $\forall x : \text{InCornwall}(x) \wedge \text{IsCity}(x) \implies x = \text{Truro}$

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- ▶ And if someone lives in Cornwall then they live in England
- ▶ Therefore if someone lives in Falmouth then they live in England

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- ▶ $\exists x : \text{LivesIn}(x, \text{Cornwall}) \wedge \neg \text{Likes}(x, \text{Cider})$

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- ▶ The agent wants to change the state so as to achieve a **goal**
- ▶ Problem: find a sequence of actions that leads to the goal

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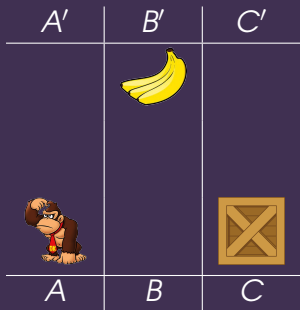
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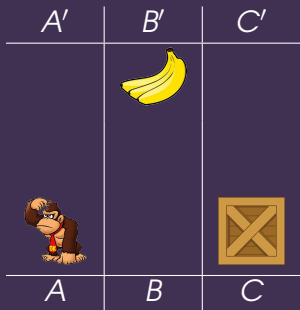
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STRIPS example



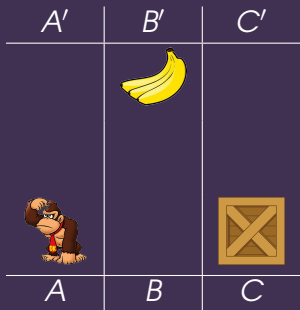
STRIPS example



Initial state:

At (A) ,
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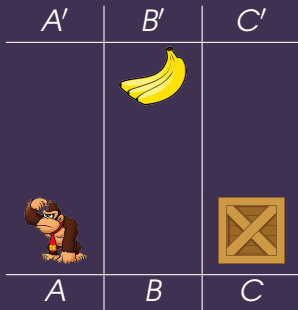
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Goal:

HasBananas

STRIPS example — Actions



Move(x, y)

Pre: At(x)

Post: !At(x), At(y)

ClimbUp(x)

Pre: At(x), BoxAt(x)

Post: !At(x), At(x')

ClimbDown(x')

Pre: At(x'), BoxAt(x)

Post: !At(x'), At(x)

PushBox(x, y)

Pre: At(x), BoxAt(x)

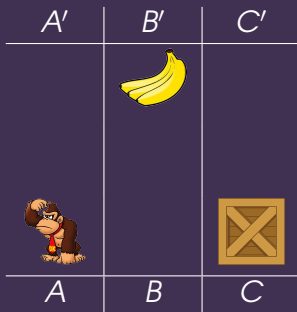
Post: !At(x), At(y),
!BoxAt(x), BoxAt(y)

TakeBananas(x)

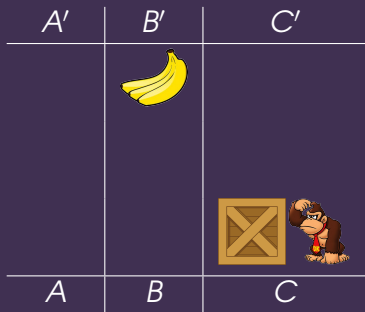
Pre: At(x), BananasAt(x)

Post: !BananasAt(x), HasBananas

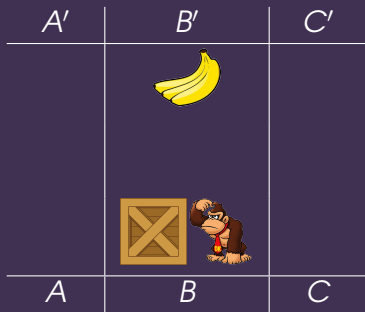
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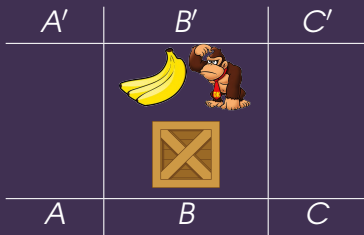
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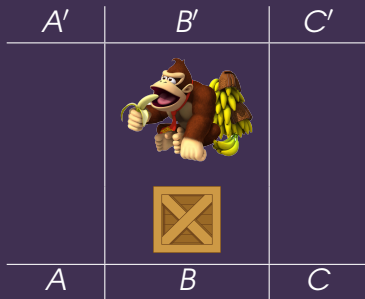
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- ▶ We can then **search** this tree to find a goal state

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