



COMP250: Artificial Intelligence

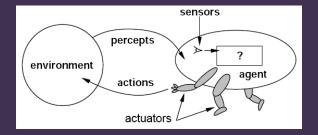
2: Designing Al behaviours



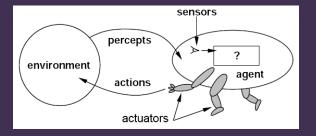


Agents

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An **agent** is anything which perceives an **environment** through **sensors**, and acts upon that environment through **actuators**.



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- A performance measure evaluates a given state for how well it fits the goal

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- ▶ A human

Types of environment

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- These properties influence the choice of Al architecture we use to build agents

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- E.g. a chess game is fully observable, a poker game is partially observable

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- Competitive: agents' performance measures are in opposition to each other (i.e. if one agent "wins", another "loses")



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- Stochastic: there is some aspect of randomness in determining the next state
- E.g. chess is deterministic; any board game involving dice rolls or random card draws is stochastic

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- Dynamic: the environment changes constantly
- E.g. most board games are static, most (non turn-based) video games are dynamic

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- Continuous problems are hard so we sometimes discretise them

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- For a game or simulation: probably yes (unless someone else made it and we don't have the source code)
- For the real world: technically no (but we have physics, sociology, economics etc to give us good approximations)

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- All(?) Al problems can be expressed in terms of creating an agent that optimises some performance measure in some environment
- Agent design boils down to: given a percept (and possibly some memory of past percepts/actions), choose the best action to take now





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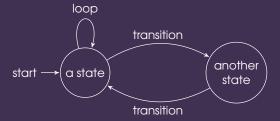
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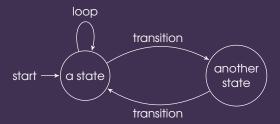
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- Which state the FSM is in dictates what actions the agent takes

State transition diagrams

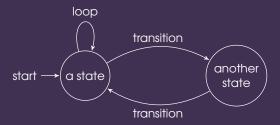


State transition diagrams



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- Reminiscent of flowcharts and certain types of UML diagram

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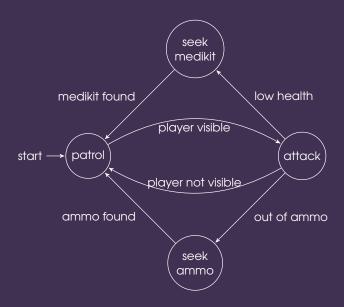
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- If you are low on ammo, run away and find ammo.
 Then resume patrolling



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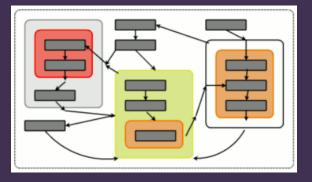
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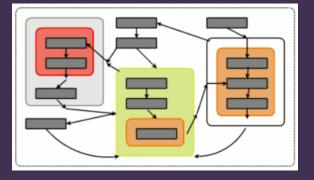
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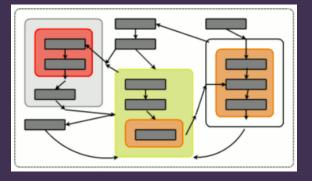
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- Coroutine approach: encode your FSM logic as a procedure which runs as a coroutine (requires either refactoring logic into structured loops, or using goto...)

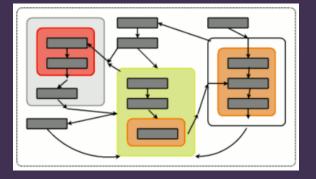




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- Hierarchical FSMs allow to group states into super-states to simplify defining transitions

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- However other techniques such as behaviour trees are more flexible and better suited to designing complex behaviours