

COMP110: Principles of Computing

# **11: Data Structures II**

# Learning outcomes

- ▶ **Define** the key concepts of graph theory
- ▶ **Distinguish** advanced data structures such as trees, DAGs and graphs
- ▶ **Determine** the complexity of accessing and manipulating data in these data structures
- ▶ **Choose** the correct data structure for a given task

# Quiz D

Due **this time next week**

# Stacks and queues

# Stacks and queues



- ▶ A **stack** is a **last-in first-out (LIFO)** data structure
- ▶ Items can be **pushed** to the **top** of the stack
- ▶ Items can be **popped** from the **top** of the stack



- ▶ A **queue** is a **first-in first-out (LIFO)** data structure
- ▶ Items can be **enqueued** to the **back** of the queue
- ▶ Items can be **dequeued** from the **front** of the queue

# Stacks in Python

- ▶ Stacks can be implemented efficiently as lists
- ▶ `append` method adds an element to the end of the list
  - ▶ What is the time complexity?
- ▶ `pop` method removes and returns the last element of the list
  - ▶ What is the time complexity?

# Queues in Python

- ▶ Queues can be implemented as lists, but not efficiently
- ▶ Could use `append(item)` to enqueue and `pop(0)` to dequeue
  - ▶ What is the time complexity of `pop(0)`?
- ▶ Could use `insert(0, item)` to enqueue and `pop()` to dequeue
  - ▶ What is the time complexity of `insert(0, item)`?
- ▶ `deque` (from the `collections` module) implements an efficient **double-ended queue**
- ▶ Provides methods `append`, `appendleft`, `pop`, `popleft`
  - ▶ All of which are  $O(1)$

# Stacks and function calls

- ▶ Stacks are used to implement **nested function calls**
- ▶ Each invocation of a function has a **stack frame**
- ▶ This specifies information like **local variable values** and **return address**
- ▶ Calling a function **pushes** a new frame onto the stack
- ▶ Returning from a function **pops** the top frame off the stack



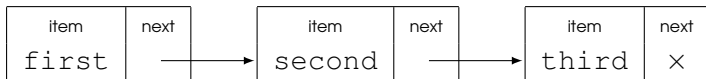
## **Linked lists**

# Lists in Python

- ▶ Implemented as a (variable-sized) **array**
- ▶ Appending is  $O(1)$
- ▶ Inserting is  $O(n)$
- ▶ Deleting is  $O(n)$
- ▶ Changing size sometimes requires the entire array to be reallocated and copied

# Linked list

- ▶ Composed of a number of **nodes**
- ▶ Each node contains:
  - ▶ An **item** — the actual data to be stored
  - ▶ A pointer or reference to the **next node** in the list (null for the last item)



# Linked lists vs arrays

Operation	Array	Linked list
Append	$O(1)$	$O(1)$ <sup>1</sup>
Pop	$O(1)$	$O(1)$ <sup>1</sup>
Index lookup	$O(1)$	$O(n)$
Count elements	$O(1)$	$O(n)$
Insert	$O(n)$	$O(1)$ <sup>2</sup>
Delete	$O(n)$	$O(1)$ <sup>2</sup>

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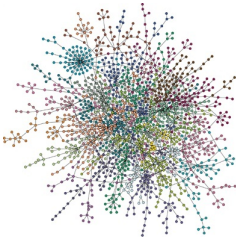
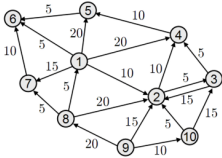
<sup>1</sup>If we already have a reference to the last node

<sup>2</sup>If we already have a reference to the relevant node

# Implementing a linked list

# Graphs

# Graphs



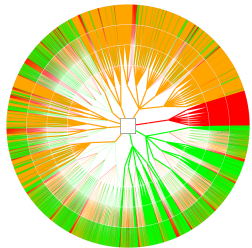
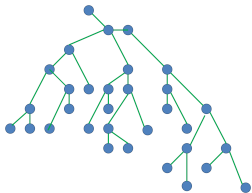
- ▶ A **graph** is defined by:
  - ▶ A collection of **nodes** or **vertices** (points)
  - ▶ A collection of **edges** or **arcs** (lines or arrows between points)
- ▶ Often used to model **networks** (e.g. social networks, transport networks, game levels, automata, ...)
- ▶ **Directed** graph: edges are arrows
- ▶ **Undirected** graph: edges are lines

# Implementing graphs

- ▶ A graph is a **collection of nodes**
- ▶ Each node has a **collection of edges**
- ▶ Each edge has exactly **two nodes** associated with it



# Trees



- ▶ A **tree** is a special type of directed graph where:
  - ▶ One node (the **root**) has no incoming edges
  - ▶ All other nodes have exactly 1 incoming edge
- ▶ Edges go from **parent** to **child**
  - ▶ All nodes except the root have exactly one parent
  - ▶ Nodes can have 0, 1 or many children
- ▶ Used to model **hierarchies** (e.g. file systems, object inheritance, scene graphs, state-action trees, ...)

# Implementing trees

- ▶ A graph has a **root node**
- ▶ Each node has a **collection of children**
- ▶ Each node other than the root has a **single parent**

# Tree traversal

- ▶ **Traversal:** visiting all the nodes of the tree
- ▶ Two main types
  - ▶ Depth first
  - ▶ Breadth first

# Tree traversal

**procedure** DEPTHFIRSTSEARCH

let  $S$  be a stack

push root node onto  $S$

**while**  $S$  is not empty **do**

pop  $n$  from  $S$

print  $n$

push children of  $n$  onto  $S$

**end while**

**end procedure**

**procedure** BREADTHFIRSTSEARCH

let  $Q$  be a queue

enqueue root node into  $Q$

**while**  $Q$  is not empty **do**

dequeue  $n$  from  $Q$

print  $n$

enqueue children of  $n$  into  $Q$

**end while**

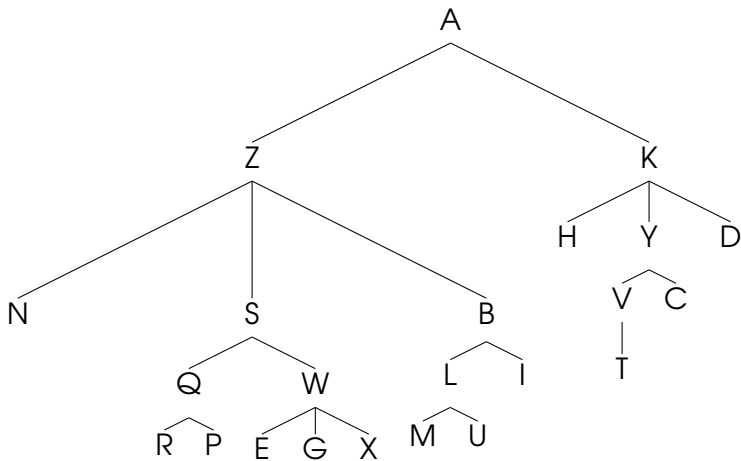
**end procedure**

# Recursive depth first search

```
procedure DEPTHFIRSTSEARCH( $n$ )  
  print  $n$   
  for each child  $c$  of  $n$  do  
    DEPTHFIRSTSEARCH( $c$ )  
  end for  
end procedure
```

- Compare to the pseudocode on the previous slide.  
Where is the stack?

# Tree traversal example



# Worksheet D