COMP110: Principles of Computing

10: Machine Architecture

Learning outcomes

- Explain the difference between interpretation, just-in-time compilation and ahead-of-time compilation
- Describe how common high-level code structures translate to machine code
- Explain how floating-point numbers are represented in the computer

How programs are executed

Executing programs

- CPUs execute machine code
- Programs must be translated into machine code for execution
- ► There are three main ways of doing this:
 - An interpreter is an application which reads the program source code and executes it directly
 - An ahead-of-time (AOT) compiler, often just called a compiler, is an application which converts the program source code into executable machine code
 - A just-in-time (JIT) compiler is halfway between the two — it compiles the program on-the-fly at runtime

Examples

Interpreted:

- ► Python
- ▶ Lua
- JavaScript (in old web browsers)
- Bespoke scripting languages

Compiled:

- ► C
- ▶ C++
- Swift
- ► Rust

JIT compiled:

- Java
- ► C#
- JavaScript (in modern web browsers)
- Jython

NB: technically any language could appear in any column here, but this is where they typically are

- ► Run-time efficiency: compiler > interpreter
 - ► The compiler translates the program in advance, on the developer's machine
 - The interpreter translates the program at runtime, on the user's machine — this takes extra time

- ► Portability: compiler < interpreter
 - A compiled program can only run on the operating system and CPU architecture it was compiled for
 - An interpreted program can run on any machine, as long as a suitable interpreter is available

- ▶ Ease of development: compiler < interpreter</p>
 - Writing an AOT or JIT compiler (especially a good one) is hard, and required in-depth knowledge of the target machine
 - Writing an interpreter is easy in comparison

- ► Dynamic language features: compiler < interpreter
 - The interpreter is already on the end user's machine, so programs can use it e.g. to dynamically generate and execute new code
 - The AOT compiler is not generally on the end user's machine, so this is more difficult

- ► JIT compilers have similar pros/cons to interpreters
 - Runtime efficiency: JIT > interpreter (e.g. code inside a loop only needs to be translated once, then can be executed many times)
 - Ease of development: JIT < interpreter</p>

Virtual machines

- Many modern interpreters and JIT compilers translate programs into bytecode
- Bytecode is essentially machine code for a virtual machine (VM)
- Translation from source code to bytecode can be done ahead of time
- At runtime, translate the bytecode (by interpretation or JIT compilation) into machine code for the physical machine
- E.g. a Java JAR file, a .NET executable, a Python .pyc or .pyo file all contain bytecode for their respective VMs

Assemblers

- Assembly language is designed to translate directly into machine code
- An ahead-of-time compile for assembly language is called an assembler
- Generally much simpler than an AOT compiler for a higher-level language

The MIPS architecture

MIPS

- An example of a Reduced Instruction Set Computer (RISC) architecture
 - Small number of simple instructions computational power comes from executing many instructions per second
 - Compare with Complex Instruction Set Computer (CISC) architecture (e.g. Intel x86) — large number of complex instructions — fewer instructions per second, but shorter programs
- ► MIPS was popular in 1980s 2000s
 - Embedded systems
 - Consoles (Nintendo 64, PlayStation 1 and 2)
- Easier to understand than most CPU instruction sets in common use today

Online MIPS simulator

http://rivoire.cs.sonoma.edu/cs351/wemips/

Registers

- Memory locations inside the CPU
- Faster to access than main memory
- Registers in MIPS architecture include:
 - \$zero: constant 0
 - ▶ \$t0-\$t9: temporary storage
 - \$s0-\$s7: saved temporary storage
- Each register holds a single 32-bit value

Adding register values

```
add $d, $s, $t
```

- ▶ \$a, \$s and \$t are register names
- ► This adds the value of \$s to the value of \$t, and stores the result in \$d

```
sub $d, $s, $t
```

 Subtracts the value of \$t from the value of \$s, and stores the result in \$a

Adding a constant

addi \$d, \$s, C

- ▶ \$a and \$s are register names, c is an integer constant
- ► This adds the value of \$s to c, and stores the result in \$a
- addi = "add immediate" as in c is specified immediately in the code, not looked up from a register
- ▶ There is no subi instruction to subtract c, add -c

More fun with addi

- ► Socrative FALCOMPED
- ▶ What does this code do?

```
addi $s0, $s1, 0
```

What does this code do?

```
addi $s0, $zero, 12
```

 MIPS does not have dedicated instructions for setting a register value to a constant or to the value of another register — it has to be done with addi

Control flow in MIPS

Labels and jumping

▶ In assembly code, can set a label on any line:

```
MyLabel: add $s0, $s1, 1
```

- Some instructions use labels to refer to a location in the code
- E.g. the j instruction simply jumps (backwards or forwards) to the specified line:

```
j MyLabel
```

Branching

Branching is conditional jumping

```
beq $s, $t, Label
```

► This jumps to Label if and only if the value of \$s equals the value of \$t

```
bne $s, $t, Label
```

► This jumps to Label if and only if the value of \$s does not equal the value of \$t

Conditionals

Branching allows us to implement if statements

```
if s0 != 0:
    s1 += 1
else:
    s2 += 1
```

```
beq $s0, $zero, Else
addi $s1, $s1, 1
j End
Else: addi $s2, $s2, 1
End:
```

Loops

Branching allows us to implement while loops

```
i = 0
total = 0
limit = 10

while i != limit:
    total += i
    i += 1
# end while
```

```
addi $s0, $zero, 0
addi $s1, $zero, 0
addi $s2, $zero, 10

Loop: beq $s0, $s2, LoopEnd
add $s1, $s1, $s0
addi $s0, $s0, 1
j Loop
LoopEnd:
```

Exercise

Write a piece of Python code equivalent to the following:

```
addi $s0, $zero, 10
addi $s1, $zero, 0

Loop: beq $s0, $zero, LoopEnd
add $s1, $s1, $s0
addi $s0, $s0, -1
j Loop
LoopEnd:
```

Not quite a while loop

- ► Socrative FALCOMPED
- What is the difference between these two programs?
- (NB: assume $$s0 \ge 0$)

```
addi $s1, $zero, 0

Loop: add $s1, $s1, $s0

addi $s0, $s0, -1

bne $s0, $zero, Loop
```

The code on the right implements a **do-while** loop (which Python doesn't have, but other languages do)

Function calls

- Function calls can be implemented using the jump instruction:
 - To call the function: save the address of the instruction after the current one, then jump to the function
 - To return from the function: jump to the previously saved address
- ► MIPS has jal and jr instructions and \$ra register for this purpose
- ➤ Socrative FALCOMPED: why save the return address? Why not just hard-code it into the program?
- Nested function calls require a stack of return addresses

MIPS machine code

MIPS instructions

- Each line of MIPS assembly code can be translated into a machine code instruction
- ▶ 1 line of assembly = 1 instruction
- ► Each instruction is a 32 bit value
- ► First 6 bits specify the **opcode**; how the remaining 26 bits are interpreted depends on which opcode it is

Anatomy of an instruction

R-type instruction:

opcode	\$s	\$t	\$d	shift	function
6 bits	5 bits	5 bits	5 bits	5 bits	6 bits

- opcode and function together specify the operation to execute
 - ▶ E.g. add has opcode 000000 and function 100000
 - ▶ E.g. sub has opcode 000000 and function 100010
- ► Some instructions specify a **shift** amount
 - ▶ For add sub etc these 5 bits are ignored
- Registers are identified by a 5-bit number
 - E.g. $\$zero \rightarrow 00000$, $\$s0 \rightarrow 01000$, $\$s1 \rightarrow 01001$
 - ► There are 32 registers

Example

add \$s0, \$s0, \$s1



opcode s t d shift function 000000 01000 01001 01001 00000 100000 $^{\circ}$

Anatomy of an instruction

I-type instruction:

opcode	\$s	\$t	С
6 bits	5 bits	5 bits	16 bits

- ▶ opcode specifies the operation to execute
 - ► E.g. addi has opcode 001000
- ▶ c is specified as a 16-bit number

Example

addi \$s0, \$s1, 123



opcode s t C
001000 01001 01000 0000000001111011

Anatomy of an instruction

J-type instruction:

opcode	address
6 bits	26 bits

- ▶ opcode specifies the operation to execute
 - ► E.g. J has opcode 000010
- address is specified as a 26-bit number

Representing numbers

Powers of 10

$$10^{6} = 1 \underbrace{000000}_{6 \text{ zeroes}}$$

$$10^{1} = 10$$

$$10^{0} = 1$$

$$10^{-1} = 0.1$$

$$10^{-6} = 0. \underbrace{00000}_{5 \text{ zeroes}} 1$$

Scientific notation

- A way of writing very large and very small numbers
- $a \times 10^b$, where
 - a (1 < |a| < 10) is the **mantissa**
 - (a is a positive or negative number with a single non-zero digit before the decimal point)
 - b (an integer) is the exponent
- ► E.g. 1 light year = 9.461×10^{15} metres
- ► E.g. Planck's constant = 6.626×10^{-34} joules
- ► Socrative FALCOMPED

Scientific notation in code

Instead of writing $\times 10$, write \bigcirc (no spaces)

```
lightYear = 9.461e15
plancksConstant = 6.626e-34
```

Floating point numbers

- Similar to scientific notation, but base 2 (binary)
- ► +mantissa × 2^{exponent}
- ► Sign is stored as a single bit: 0 = +, 1 = -
- Mantissa is a binary number with a 1 before the point;
 only the digits after the point are stored
- Exponent is a signed integer, stored with a bias

IEEE 754 floating point formats

Туре	Sign	Exponent	Mantissa	Total
Single precision	1 bit	8 bits	23 bits	32 bits
Double precision	1 bit	11 bits	52 bits	64 bits

Exponent is stored with a bias:

- ► Single precision: store exponent + 127
- ► Double precision: store exponent + 1023
- Python uses double precision
- ▶ Other languages have float (single) and double types

Example

0 10000001 101000000000000000000000

- ▶ Exponent: 129 127 = 2
- ► Mantissa: binary 1.101
- ► $1 + \frac{1}{2} + \frac{1}{8} = 1.625$
- ► $1.625 \times 2^2 = 6.5$
- ► Alternatively: $1.101 \times 2^2 = 110.1$
- $\blacktriangleright = 4 + 2 + \frac{1}{2} = 6.5$

Socrative FALCOMPED

What is the value of this number expressed in IEEE 754 single precision format?

0 01111100 100110000000000000000000

You have **5 minutes**, and you **may** use a calculator! (Unless your calculator does IEEE 754 conversion...)

Precision of floating point numbers

- ► Precision varies by magnitude
- Numbers near 0 can be stored more accurately than numbers further from 0
- ► Analogy: in scientific notation with 3 decimal places
 - ▶ Around 3.142×10^{0} : can represent a difference of 0.001
 - Around 3.142×10^3 : can represent a difference of 1
 - Around 3.142 × 10⁶: can represent a difference of 1000

Range of floating point numbers

/ 1	Smallest value	Largest value
Single precision	$\pm 1.175 \times 10^{-38}$	$\pm 3.403 \times 10^{38}$
Double precision	$\pm 2.225 \times 10^{-308}$	$\pm 1.798 \times 10^{308}$

Rounding errors

- Many numbers cannot be represented exactly in IEEE float
 - Similar to how decimal notation cannot exactly represent $\frac{1}{3} = 0.3333333...$ or $\frac{1}{7} = 0.142857...$
- ▶ Decimal: can represent $\frac{a}{b}$ exactly iff $b = 2^m 5^n$
- ▶ Binary: can represent $\frac{a}{b}$ exactly iff $b = 2^n$
- ► In particular, IEEE float can't represent $\frac{1}{10} = 0.1$ exactly!
- This can lead to rounding errors with some calculations
 - ▶ E.g. according to Python, $0.1 + 0.2 0.3 = 5.551 \times 10^{-17}$

Testing for equality

- Due to rounding errors, using == or != with floating point numbers is almost always a bad idea
- ► E.g. in Python, 0.1 + 0.2 == 0.3 evaluates to False
- Better to check for approximate equality: calculate the difference between the numbers, and check that it's smaller than some threshold

```
THRESHOLD = 1e-5
def is_approx_equal(a, b):
    return abs(b - a) < THRESHOLD</pre>
```

Decimal types

- ▶ Python (and other languages) provide a decimal type
- Uses base 10 rather than base 2, so avoids some of the gotchas with IEEE float
- ... however not natively supported by the CPU, hence much slower