

COMP110: Principles of Computing

8: Data Structures

Learning outcomes

- ▶ **Define** the key concepts of graph theory
- ▶ **Distinguish** advanced data structures such as trees, DAGs and graphs
- ▶ **Determine** the complexity of accessing and manipulating data in these data structures
- ▶ **Choose** the correct data structure for a given task

Exercise Sheet iii

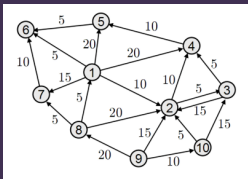
Due **next week**

Graphs

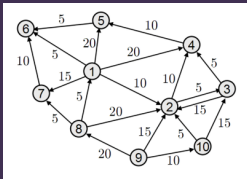


Graphs

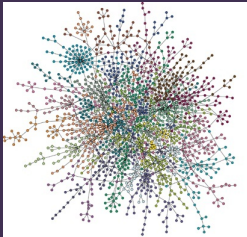
Graphs



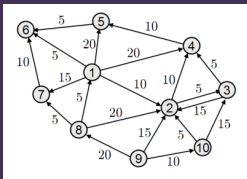
Graphs



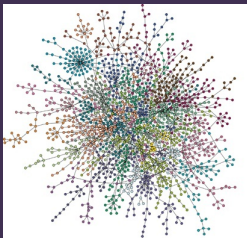
► A **graph** is defined by:



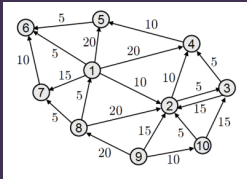
Graphs



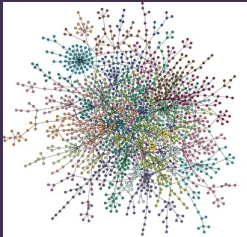
- ▶ A **graph** is defined by:
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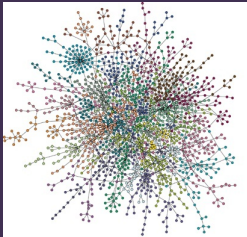
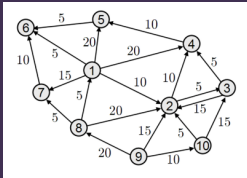
Graphs



- ▶ A **graph** is defined by:
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 - ▶ A collection of **edges** or **arcs** (lines or arrows between points)

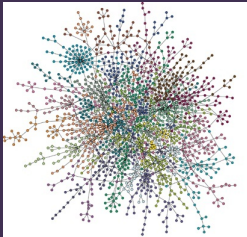
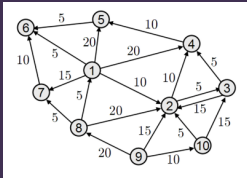


Graphs



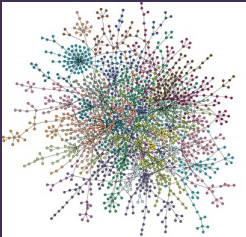
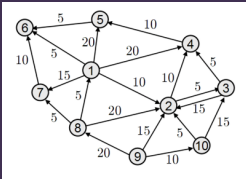
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- ▶ **Directed** graph: edges are arrows

Graphs



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- ▶ Often used to model **networks** (e.g. social networks, transport networks, game levels, automata, ...)
- ▶ **Directed** graph: edges are arrows
- ▶ **Undirected** graph: edges are lines

Implementing graphs

Implementing graphs

- ▶ A graph has a **set of nodes** and a **set of edges**

Implementing graphs

- ▶ A graph has a **set of nodes** and a **set of edges**
- ▶ Each edge has exactly **two nodes** associated with it (e.g. “from” and “to”)

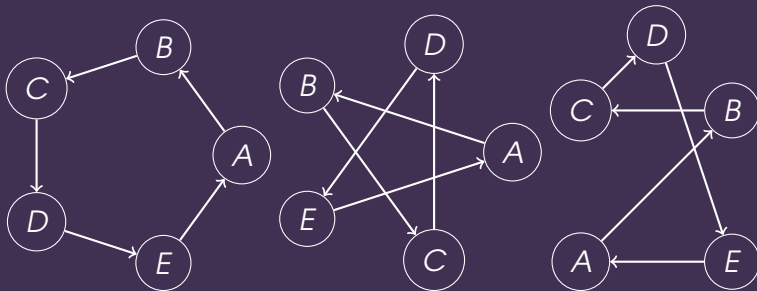
Drawing graphs

Drawing graphs

- ▶ A graph does not necessarily specify the physical **positions** of its nodes

Drawing graphs

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- ▶ E.g. these are technically the same graph:



Planar graphs

Planar graphs

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Planar graphs

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- ▶ A region enclosed by edges is called a **faces**

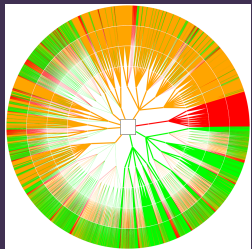
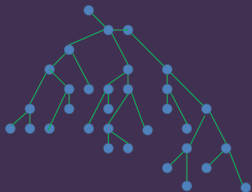
Planar graphs

- ▶ A graph is **planar** if it can be drawn with no overlapping edges
- ▶ A region enclosed by edges is called a **faces**
- ▶ A connected planar graph obeys **Euler's formula**:

$$n_{\text{nodes}} - n_{\text{edges}} + n_{\text{faces}} = 2$$

Trees

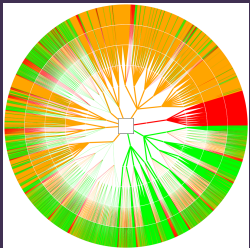
Trees



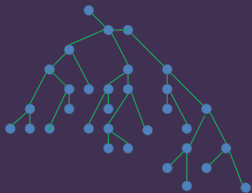
Trees



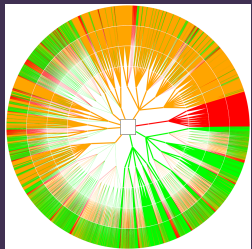
- A **tree** is a special type of directed graph where:



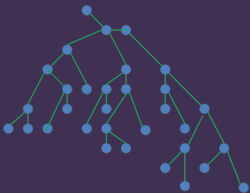
Trees



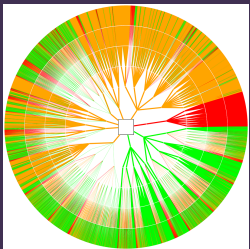
- ▶ A **tree** is a special type of directed graph where:
 - ▶ One node (the **root**) has no incoming edges



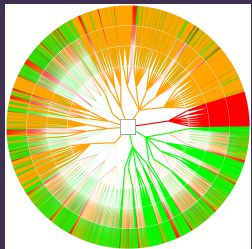
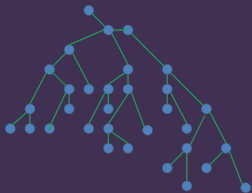
Trees



- ▶ A **tree** is a special type of directed graph where:
 - ▶ One node (the **root**) has no incoming edges
 - ▶ All other nodes have exactly 1 incoming edge

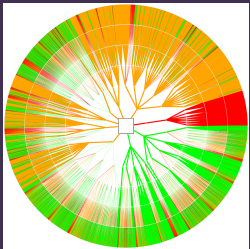
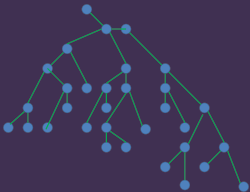


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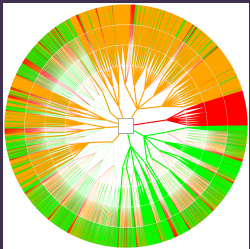
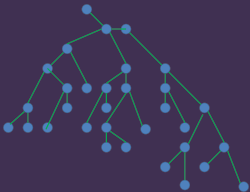
- ▶ A **tree** is a special type of directed graph where:
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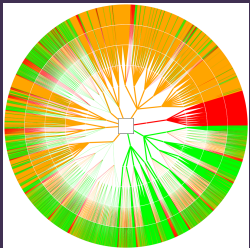
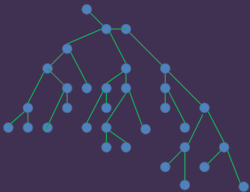
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 - ▶ All nodes except the root have exactly one parent
 - ▶ Nodes can have 0, 1 or many children
- ▶ Used to model **hierarchies** (e.g. file systems, object inheritance, scene graphs, state-action trees, ...)

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Implementing trees

- ▶ A graph has a **root node**
- ▶ Each node has a **collection of children**
- ▶ Each node other than the root has a **single parent**

Stacks and queues



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- ▶ Items can be **dequeued** from the **front** of the queue

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- ▶ Provides methods `append`, `appendleft`, `pop`, `popleft`
 - ▶ All of which are $O(1)$

Stacks and function calls

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Stacks and function calls

- ▶ Stacks are used to implement **nested function calls**
- ▶ Each invocation of a function has a **stack frame**
- ▶ This specifies information like **local variable values** and **return address**
- ▶ Calling a function **pushes** a new frame onto the stack
- ▶ Returning from a function **pops** the top frame off the stack

Graph traversal



Tree traversal

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Tree traversal

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end while

end procedure

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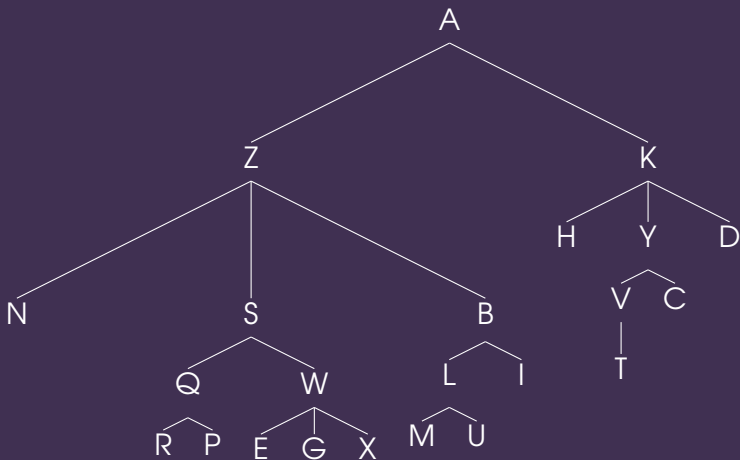
print n

enqueue children of n into Q

end while

end procedure

Tree traversal example



Recursive depth first search

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procedure DEPTHFIRSTSEARCH(n)

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```
procedure DEPTHFIRSTSEARCH( $n$ )  
  print  $n$ 
```


Recursive depth first search

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Recursive depth first search

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```

- Compare to the pseudocode on the previous slide.
Where is the stack?