

COMP110: Principles of Computing







 Read some seminal papers in computing (listed on the assignment brief)

- Read some seminal papers in computing (listed on the assignment brief)
- ► Choose one of them

- Read some seminal papers in computing (listed on the assignment brief)
- ► Choose one of them
- Research how this paper has influenced the field of computing

- Read some seminal papers in computing (listed on the assignment brief)
- ► Choose one of them
- Research how this paper has influenced the field of computing
- ▶ Write up your findings

- Read some seminal papers in computing (listed on the assignment brief)
- ► Choose one of them
- Research how this paper has influenced the field of computing
- Write up your findings
  - ► Maximum 1500 words

- Read some seminal papers in computing (listed on the assignment brief)
- ► Choose one of them
- Research how this paper has influenced the field of computing
- ▶ Write up your findings
  - ► Maximum 1500 words
  - With reference to appropriate academic sources



# Marking rubric

See assignment brief on LearningSpace/GitHub

#### Timeline

- ► Peer review next week! (4th December)
- ▶ Deadline shortly after! (check MyFalmouth)



Pass by reference



 Our picture of a variable: a labelled box containing a value

- Our picture of a variable: a labelled box containing a value
- ► For "plain old data" (e.g. numbers), this is accurate

- Our picture of a variable: a labelled box containing a value
- ▶ For "plain old data" (e.g. numbers), this is accurate
- ► For **objects** (i.e. instances of classes), variables actually hold **references** (a.k.a. **pointers**)

- Our picture of a variable: a labelled box containing a value
- ▶ For "plain old data" (e.g. numbers), this is accurate
- For objects (i.e. instances of classes), variables actually hold references (a.k.a. pointers)
- It is possible (indeed common) to have multiple references to the same underlying object

Variable	Value
X	
У	
Z	

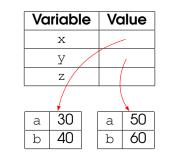
Variable	Value
	a 30
X	b 40
У	
Z	

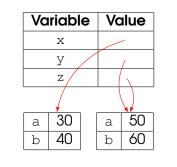
Variable	Vc	alue	
	a	30	
X	b	40	
	a	50	
У	b	60	
Z			

Variable	Vo	alue
	а	30
X	b	40
У	а	50
	b	60
7	a	50
Z	b	60

Variable	Value
X	
У	
Z	

Variable	Value
X	
У	
z/	
<b></b>	
a 30	
b 40	





## Values and references

#### Socrative room code: FALCOMPED

```
a = 10
b = a
a = 20
print("a:", a)
print("b:", b)
```

#### Values and references

Socrative room code: FALCOMPED

```
class X:
    def __init__(self, value):
        self.value = value

a = X(10)
b = a
a.value = 20
print("a:", a.value)
print("b:", b.value)
```

#### Values and references

Socrative room code: FALCOMPED

```
class X:
    def __init__(self, value):
        self.value = value

a = X(10)
b = X(10)
a.value = 20
print("a:", a.value)
print("b:", b.value)
```

In function parameters, "plain old data" is passed by value

In function parameters, "plain old data" is passed by value

```
def double(x):
    x *= 2

a = 7
double(a)
print(a)
```

In **function parameters**, "plain old data" is passed by **value** 

```
def double(x):
    x *= 2

a = 7
double(a)
print(a)
```

double does not actually do anything, as x is just a local copy of whatever is passed in!

# Pass by reference

## Pass by reference

However, instances are passed by reference

```
class Box:
    def __init__(self, v):
        self.value = v

def double(x):
        x.value *= 2

a = Box(7)
double(a)
print(a.value)
```

### Pass by reference

However, instances are passed by reference

```
class Box:
    def __init__(self, v):
        self.value = v

def double(x):
        x.value *= 2

a = Box(7)
double(a)
print(a.value)
```

double now has an effect, as x gets a reference to the

# Lists are objects too

# Lists are objects too

```
a = ["Hello"]
b = a
b.append("world")
print(a) # ["Hello", "world"]
```

### Lists are objects too

```
a = ["Hello"]
b = a
b.append("world")
print(a) # ["Hello", "world"]
```

... which means you should be careful when passing lists into functions, because the function might actually change the list!

#### References can be circular

```
class X:
    pass

foo = X()
foo.x = foo
foo.y = "Hello"

print(foo.x.x.x.x.x.y)
```

Some languages (e.g. C, C++) use pointers

- ▶ Some languages (e.g. C, C++) use pointers
- Pointers are a type of reference, and have the same semantics

- ▶ Some languages (e.g. C, C++) use pointers
- Pointers are a type of reference, and have the same semantics
- C++ also has something called references...





## **Vectors**

► A 2D vector is represented by a pair of numbers

- ► A **2D vector** is represented by a **pair** of **numbers**
- Often represented as a column vector

- ► A **2D vector** is represented by a **pair** of **numbers**
- Often represented as a column vector

► E.g. 
$$\begin{pmatrix} 3 \\ 2 \end{pmatrix}$$
 or  $\begin{pmatrix} 0 \\ -4 \end{pmatrix}$  or  $\begin{pmatrix} -3.7 \\ 6.2 \end{pmatrix}$ 

- ► A **2D vector** is represented by a **pair** of **numbers**
- Often represented as a column vector

► E.g. 
$$\begin{pmatrix} 3 \\ 2 \end{pmatrix}$$
 or  $\begin{pmatrix} 0 \\ -4 \end{pmatrix}$  or  $\begin{pmatrix} -3.7 \\ 6.2 \end{pmatrix}$ 

► General form: 
$$\begin{pmatrix} x \\ y \end{pmatrix}$$

- A 2D vector is represented by a pair of numbers
- Often represented as a column vector

► E.g. 
$$\begin{pmatrix} 3 \\ 2 \end{pmatrix}$$
 or  $\begin{pmatrix} 0 \\ -4 \end{pmatrix}$  or  $\begin{pmatrix} -3.7 \\ 6.2 \end{pmatrix}$ 

- ► General form:  $\begin{pmatrix} x \\ y \end{pmatrix}$
- ► Can also have 3,4,5,... dimensional vectors

 $ightharpoonup \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  is the **origin** 

- $ightharpoonup \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  is the **origin** 
  - $\begin{pmatrix} x \\ y \end{pmatrix}$  represents a point x units to the right and y units up from the origin

- $ightharpoonup \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  is the **origin**
- $\binom{x}{y}$  represents a point x units to the right and y units up from the origin
  - Negative values represent left and down

- $ightharpoonup \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  is the **origin**
- $\begin{pmatrix} x \\ y \end{pmatrix}$  represents a point x units to the right and y units up from the origin
  - Negative values represent left and down
  - In computer graphics, sometimes y points down instead of up

## Operations on vectors

# Operations on vectors

► Addition and subtraction work **element-wise** 

### Operations on vectors

Addition and subtraction work element-wise

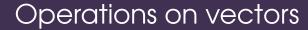


Addition and subtraction work element-wise

$$\begin{pmatrix}
x_1 \\
y_1
\end{pmatrix} + \begin{pmatrix}
x_2 \\
y_2
\end{pmatrix} = \begin{pmatrix}
x_1 + x_2 \\
y_1 + y_2
\end{pmatrix}$$

$$\begin{pmatrix}
x_1 \\
y_1
\end{pmatrix} - \begin{pmatrix}
x_2 \\
y_2
\end{pmatrix} = \begin{pmatrix}
x_1 - x_2 \\
y_1 - y_2
\end{pmatrix}$$

$$\qquad \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} - \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} x_1 - x_2 \\ y_1 - y_2 \end{pmatrix}$$



- Addition and subtraction work element-wise
  - $\begin{pmatrix}
    x_1 \\
    y_1
    \end{pmatrix} + \begin{pmatrix}
    x_2 \\
    y_2
    \end{pmatrix} = \begin{pmatrix}
    x_1 + x_2 \\
    y_1 + y_2
    \end{pmatrix}$   $\begin{pmatrix}
    x_1 \\
    y_1
    \end{pmatrix} \begin{pmatrix}
    x_2 \\
    y_2
    \end{pmatrix} = \begin{pmatrix}
    x_1 x_2 \\
    y_1 y_2
    \end{pmatrix}$
- Multiplication by a scalar (a number) also works element-wise



Addition and subtraction work element-wise

$$\begin{pmatrix}
x_1 \\
y_1
\end{pmatrix} + \begin{pmatrix}
x_2 \\
y_2
\end{pmatrix} = \begin{pmatrix}
x_1 + x_2 \\
y_1 + y_2
\end{pmatrix}$$

$$\begin{pmatrix}
x_1 \\
y_1
\end{pmatrix} - \begin{pmatrix}
x_2 \\
y_2
\end{pmatrix} = \begin{pmatrix}
x_1 - x_2 \\
y_1 - y_2
\end{pmatrix}$$

$$\qquad \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} - \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} x_1 - x_2 \\ y_1 - y_2 \end{pmatrix}$$

 Multiplication by a scalar (a number) also works element-wise

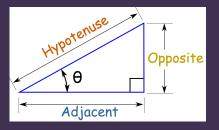
$$\triangleright c \times \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} c \times x \\ c \times y \end{pmatrix}$$

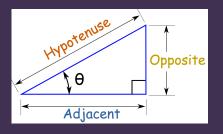
•  $\begin{pmatrix} x \\ y \end{pmatrix}$  represents an offset of x units to the right and y units up

- $\begin{pmatrix} x \\ y \end{pmatrix}$  represents an offset of x units to the right and y units up
- Subtraction: if p and q are points, then q − p is the offset of q relative to p

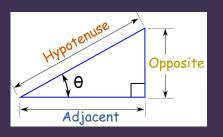
- $\begin{pmatrix} x \\ y \end{pmatrix}$  represents an offset of x units to the right and y units up
- Subtraction: if p and q are points, then q − p is the offset of q relative to p
- ► Addition: if p is a point and u is an offset, then p + u is the point at an offset of u from p

- $\begin{pmatrix} x \\ y \end{pmatrix}$  represents an offset of x units to the right and y units up
- ➤ Subtraction: if p and q are points, then q p is the offset of q relative to p
- ► Addition: if p is a point and u is an offset, then p + u is the point at an offset of u from p
- Addition: if u and v are offsets, then u + v is the combined offset

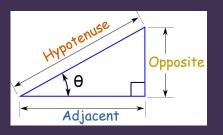




ightharpoonup  $\sin heta = rac{ ext{opposite}}{ ext{hypotenuse}}$ 

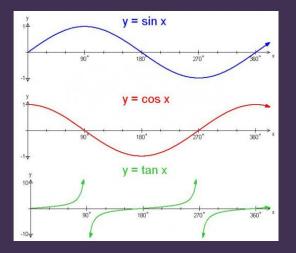


- $ightharpoonup \sin \theta = \frac{\text{opposite}}{\text{hypotenuse}}$
- ightharpoonup  $\cos heta = rac{ ext{adjacent}}{ ext{hypotenuse}}$



- ightharpoonup  $\sin \theta = \frac{\text{opposite}}{\text{hypotenuse}}$
- ightharpoonup  $\cos heta = rac{ ext{adjacent}}{ ext{hypotenuse}}$
- ightharpoonup tan  $heta=rac{ ext{opposite}}{ ext{adjacent}}$

## Sine, cosine and tangent



► We often measure angles in **radians** 

- ► We often measure angles in **radians**
- $\pi = 3.14159...$

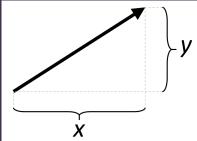
- ► We often measure angles in radians
- $\pi = 3.14159...$
- $\pi$  radians = 180 degrees = half a circle

- ► We often measure angles in radians
- $\rightarrow \pi = 3.14159...$
- $\pi$  radians = 180 degrees = half a circle
- $\frac{\pi}{2}$  radians = 90 degrees = right angle

A vector has **components** 



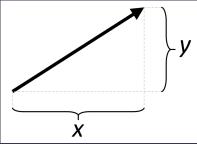
A vector has components



A vector also has **direction** and **magnitude** (or **length**)

A vector has **components** 

A vector has components

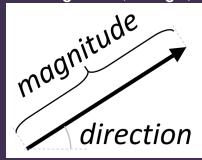


A vector also has direction and **magnitude** (or **length**)



A vector has **components** 

A vector also has **direction** and **magnitude** (or **length**)



(Direction is measured as an angle from the positive *x*-axis)

► The magnitude of  $\begin{pmatrix} x \\ y \end{pmatrix}$  is  $\sqrt{x^2 + y^2}$ 



- ► The magnitude of  $\begin{pmatrix} x \\ y \end{pmatrix}$  is  $\sqrt{x^2 + y^2}$
- ► The direction of  $\begin{pmatrix} x \\ y \end{pmatrix}$  is  $\tan^{-1} \left( \frac{y}{x} \right)$



- ► The magnitude of  $\begin{pmatrix} x \\ y \end{pmatrix}$  is  $\sqrt{x^2 + y^2}$
- ► The direction of  $\begin{pmatrix} x \\ y \end{pmatrix}$  is  $tan^{-1} \begin{pmatrix} \frac{y}{x} \end{pmatrix}$
- ► The vector with magnitude r and direction  $\theta$  is  $\begin{pmatrix} r\cos\theta\\r\sin\theta \end{pmatrix}$

- ► The magnitude of  $\begin{pmatrix} x \\ y \end{pmatrix}$  is  $\sqrt{x^2 + y^2}$
- ► The direction of  $\begin{pmatrix} x \\ y \end{pmatrix}$  is  $tan^{-1} \begin{pmatrix} \frac{y}{x} \end{pmatrix}$
- ► The vector with magnitude r and direction  $\theta$  is  $\begin{pmatrix} r\cos\theta\\r\sin\theta \end{pmatrix}$
- Multiplication: if u is a vector with magnitude r and direction θ, then c × u has magnitude c × r and direction θ





**Worksheet D**