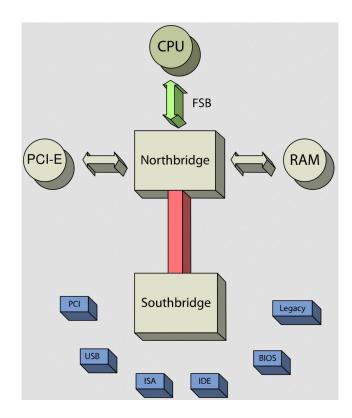
Lecture 11

Device Drivers

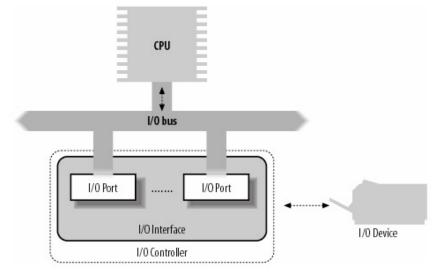
Input-Output

- Any subsystem output of processor and memory is considered I/O
 - Flexible configuration by user
 - OS must handle and abstract diversity
- A typical arrangement in a PC:



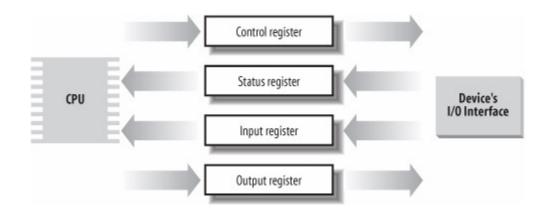
I/O Port I/O on x86

- Intel x86 uses 16 bits to address I/O devices and 8, 16 or 32 bit for data
 - Each of the addressed location is called a "I/O port"
- Four special x86 instructions perform I/O
 - in, ins, out, outs
- Transfers data from a device to a register in the processor



Source: Bovet, Daniel P., Understanding the Linux Kernel.

Generic I/O Device



Source: Bovet, Daniel P., Understanding the Linux Kernel.

Resource

How can one find which I/O port is for what?

- Linux manage this in a tree-like structure rooted at ioport_resource
 - Use a tree to reflect hierarchy of the device connections
- API's for resource management:
 - request resource()
 - allocate resource()
 - release_resource()

I/O interface

 An I/O interface is a hardware circuitry inserted between a group of I/O ports and their corresponding device controller

 Translates the values in the I/O ports into commands and data for the device

 Detects changes in the device state and correspondingly updates the I/O port

May involve a IRQ line to the PIC so as to issue hardware interrupts

Types of I/O interface

- Custom interface devoted to one specific hardware
 - Example: keyboard, graphics, disk, mouse, network
- General purpose interface
 - Example: parallel port, serial port, PCMCIA, SCSI, USB

Device Controllers

 Interprets the high-level commands received from the I/O interface and forces the device to execute specific actions by sending proper sequences of electrical signals to it

• Converts and properly interprets the electrical signals received from the device and modifies (through the I/O interface) the value of the status register

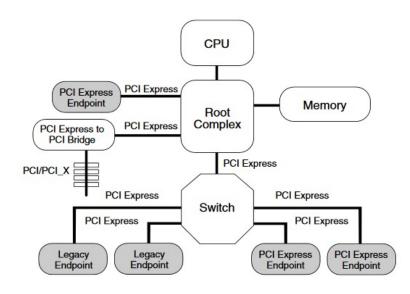
Memory-mapped I/O

- Instead of a distinct space, I/O is embedded inside the memory space
 - Uses loads and stores

Suitable for fast devices and DMA

PCI Express

- Goal: high performance I/O
- Created in 2004 by a consortium
- Introduces a lane
 - Up to 32 lanes (x1, x2, x4, x8, x12, x16, x32)
 - Each lane is full-duplex transport for a byte
- Complex communication protocol resembling a network protocol



Device Drivers

Device Drivers

- Device drivers
 - Black boxes to hide details of hardware devices
 - Use standardized calls
 - Independent of the specific driver
 - Main role
 - Map standard calls to device-specific operations
 - Can be developed separately from the rest of the kernel
 - Plugged in at runtime when needed

The Role of the Device Driver

- Implements the *mechanisms* to access the hardware
 - E.g., show a disk as an array of data blocks
- Does not force particular policies on the user
 - Examples
 - Who many access the drive
 - Whether the drive is accessed via a file system
 - Whether users may mount file systems on the drive

Policy-Free Drivers

- A common practice
 - Support for synchronous/asynchronous operation
 - Be opened multiple times
 - Exploit the full capabilities of the hardware
- Easier user model
- Easier to write and maintain
- To assist users with policies, release device drivers with user programs

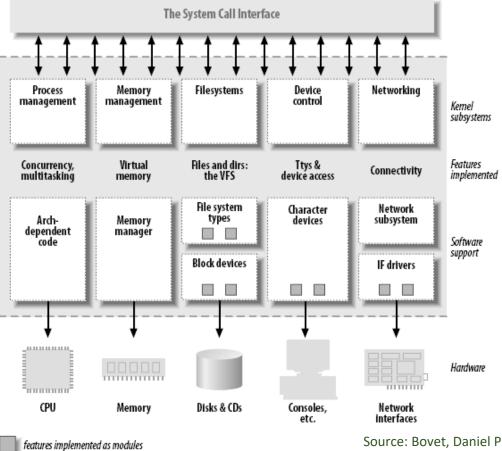
Splitting the Kernel

- Process management
 - Creates, destroys processes
 - Supports communication among processes
 - Signals, pipes, etc.
 - Schedules how processes share the CPU
- Memory management
 - Virtual addressing

Splitting the Kernel

- File systems
 - Everything in UNIX can be treated as a file
 - Linux supports multiple file systems
- Device control
 - Every system operation maps to a physical device
 - Few exceptions: CPU, memory, etc.
- Networking
 - Handles packets
 - Handles routing and network address resolution issues

Splitting the Kernel



Source: Bovet, Daniel P., Understanding the Linux Kernel.

Loadable Modules

- The ability to add and remove kernel features at runtime
- Each unit of extension is called a module
- Use insmod program to add a kernel module
- Use **rmmod** program to remove a kernel module

Classes of Devices and Modules

- Character devices
- Block devices
- Network devices
- Others

Character Devices

- Abstraction: a stream of bytes
 - Examples
 - Text console (/dev/console)
 - Serial ports (/dev/ttyS0)
 - Usually supports open, close, read, write
 - Accessed sequentially (in most cases)
 - Might not support file seeks
 - Exception: frame grabbers
 - Can access acquired image using mmap or lseek

Block Devices

Abstraction: array of storage blocks

- However, applications can access a block device in bytes
 - Block and char devices differ only at the kernel level
 - A block device can host a file system

Network Devices

- Abstraction: data packets
- Send and receive packets
 - Do not know about individual connections
- Have unique names (e.g., eth0)
 - Not in the file system
 - Support protocols and streams related to packet transmission (i.e., no read and write)

Other Classes of Devices

- Examples that do not fit to previous categories:
 - USB
 - SCSI
 - FireWire
 - MTD

File System Modules

- Software drivers, not device drivers
- Serve as a layer between user API and block devices
- Intended to be device-independent

- Deliberate vs. incidental damage
- Kernel modules present possibilities for both
- System does only rudimentary checks at module load time
- Relies on limiting privilege to load modules
 - And trusts the driver writers
- Driver writer must be on guard for security problems

- Do not define security policies
 - Provide mechanisms to enforce policies
- Be aware of operations that affect global resources
 - Setting up an interrupt line
 - Could damage hardware
 - Setting up a default block size
 - Could affect other users

- Beware of bugs
 - Buffer overrun
 - Overwriting unrelated data
 - Treat input/parameters with utmost suspicion
 - Uninitialized memory
 - Kernel memory should be zeroed before being made available to a user
 - Otherwise, information leakage could result
 - Passwords

- Avoid running kernels compiled by an untrusted friend
 - Modified kernel could allow anyone to load a module

Version Numbering

- Every software package used in Linux has a release number
 - You need a particular version of one package to run a particular version of another package
 - Prepackaged distribution contains matching versions of various packages

Version Numbering

- Different throughout the years
- After version 1.0 but before 3.0
 - <major>.<minor>.<release>.<bugfix>
 - Time based releases (after two to three months)
- 3.x
 - Moved to 3.0 to commemorate 20th anniversary of Linux
 - <version>.<release>.<bugfix>
 - https://lkml.org/lkml/2011/5/29/204

sysfs

The Linux Driver Model

- The big idea: everything is a file
 - Leverage on VFS
 - Exception: network cards
- Expose the hierarchical relationships between devices
- The components of sysfs
 - block block devices
 - devices all hardware devices recognized by the kernel
 - bus buses
 - **drivers** the device drivers
 - class the main category of devices
 - **power** for power management
 - firmware handle firmware

```
SSH Secure Shell 3.2.9 (Build 283)
Copyright (c) 2000-2003 SSH Communications Security Corp - http://www.ssh.com/
This copy of SSH Secure Shell is a non-commercial version.
This version does not include PKI and PKCS #11 functionality.

Last login: Thu Apr 5 09:54:39 2018 from prajna.dl.comp.nus.edu.sg
[wongwf@naga = ]$ cd /sys
[wongwf@naga sys]$ 1s
block class devices fs kernel power
bus dev firmware hypervisor module
[wongwf@naga sys]$
```

Examples

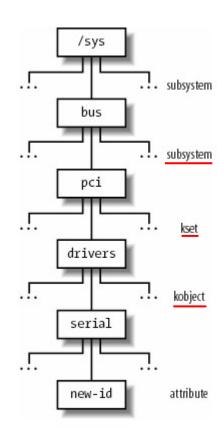
Name	Туре	Major	Minor	Description
/dev/fd0	block	2	0	Floppy disk
/dev/hda	block	3	0	First IDE disk
/dev/hda2	block	3	2	Second primary partition of first IDE disk
/dev/hdb	block	3	64	Second IDE disk
/dev/hdb3	block	3	67	Third primary partition of second IDE disk
/dev/ttyp0	char	3	0	Terminal
/dev/console	char	5	1	Console
/dev/lp1	char	6	1	Parallel printer
/dev/ttyS0	char	4	64	First serial port
/dev/rtc	char	10	135	Real-time clock
/dev/null	char	1	3	Null device (black hole)

Character vs block devices

- The data of a block device can be addressed randomly, and the time needed to transfer a data block is small and roughly the same
 - Examples: hard disks, floppy disks, CD-ROM drives, and DVD players
- The data of a character device either
 - cannot be addressed randomly,
 - or they can be addressed randomly, but the time required to access a random datum largely depends on its position inside the device

Kobjects

- Core data structure for device drivers
- Each kobject corresponds to a directory in sysfs
- Embedded inside containers
 - Descriptors for buses, devices, and drivers
- Kobjects are grouped into ksets of the same type (container)
- Ksets may form subsystems (hierarchy)
- All the above must be registered with the kernel



Source: Bovet, Daniel P., Understanding the Linux Kernel.

Components of the Linux device model (1)

- Each device has a **device** object
 - Associates with a kobject
- Each driver has a **device_driver** object

Туре	Field	Description
char *	name	Name of the device driver
struct bus_type *	bus	Pointer to descriptor of the bus that hosts the supported devices
struct semaphore	unload_sem	Semaphore to forbid device driver unloading; it is released when the reference counter reaches zero $$
struct kobject	kobj	Embedded kobject
struct list_head	devices	Head of the list including all devices supported by the driver
struct module *	owner	Identifies the module that implements the device driver, if any (see Appendix B
int (*)(struct device *)	probe	Method for probing a device (checking that it can be handled by the device driver)
int (*)(struct device *)	remove	Method invoked on a device when it is removed
void (*)(struct device *)	shutdown	Method invoked on a device when it is powered off (shut down)
int (*)(struct device *, unsigned long, unsigned long)	suspend	Method invoked on a device when it is put in low-power state
int (*)(struct device *, unsigned long)	resume	Method invoked on a device when it is put back in the normal state (full power)

Fields in device driver

Components of the Linux device model (2)

Buses are represented by bus_type objects

Туре	Field	Description
char *	name	Name of the bus type
struct subsystem	subsys	Kobject subsystem associated with this bus type
struct kset	drivers	The set of kobjects of the drivers
struct kset	devices	The set of kobjects of the devices
struct bus_attribute *	bus_attrs	Pointer to the object including the bus attributes and the methods for exporting them to the sysfs filesystem
struct device_attribute *	dev_attrs	Pointer to the object including the device attributes and the methods for exporting them to the <i>sysfs</i> filesystem
struct driver_attribute *	drv_attrs	Pointer to the object including the device driver attributes and the methods for exporting them to the sysfs filesystem
<pre>int (*)(struct device *, struct device_driver *)</pre>	match	Method for checking whether a given driver supports a given device
<pre>int (*)(struct device *, char **, int, char *, int)</pre>	hotplug	Method invoked when a device is being registered

Fields in bus_type

Components of the Linux device model (3)

- Each class of devices has a class object
- All class objects belong to the class_subsys subsystem associated with /sys/class
- One class_device descriptor for each logical device of the class
- A device can belong to multiple class device
 - Example: a sound card is a hardware device that usually includes a DSP, a mixer, a game port interface, and so on.
- Device drivers in the same class are expected to offer the same functionalities to the user mode applications

Device number

- Linux maintains an official list of allocated device numbers
 - Documentation/devices.txt
- Major number
 - 12 bits
- Minor number
 - 20 bits
- Each logical device in the system should have an associated device file with a well-defined device number
- When a device driver registers, it will specify (static) or request to be allocated (dynamic) a range of device numbers that it will handle

Dynamic device file creation

Simply too many possible devices

• From kernel 2.6 – create on demand dynamically

• Uses the **udev** toolset

Supports device hotplugging

The role of VFS

- Device files exist in the system directory but are intrinsically different from ordinary files
 - VFS hides the difference

 VFS changes the default file operations of a device file when it is opened to do the appropriate device operations

Monitoring I/O

- Duration of I/O is unpredictable
 - Question: how do we know an I/O request is terminated or completed?
- Two modes:
 - Polling

```
for (;;) {
   if (read_status( device) & DEVICE_END_OPERATION) break;
     if (--count = = 0) break;
}
```

- Interrupt
 - Lower overhead
 - Can only be done if device has hardware for doing a IRQ

Character Device Drivers

Character devices

- Usually simpler hardware
- No caching
- No re-reads of same bytes
- No sophisticated communication protocol involved

Character device drivers

- Kernel maintains a hash table chrdevs containing intervals of device numbers with handlers
- On initialization, a character device driver much specify what range of device numbers it will handle, or ask for that range to be dynamically allocated
- Character devices can transfer large number of bytes in a single I/O
 - Use buffering
 - Good news: same buffer never refused makes for easier management

Block Device Drivers

Block devices

Usually more complex hardware

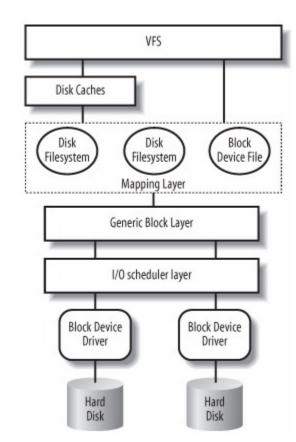
- Access is slow
 - Situation is changing

Applications can repeatedly read or write the same block of data

Example: disks

Block I/O

- VFS needs to check if block is already in some kind of caches
 - If yes, serves request from memory cache
- If no, determine physical location of block via mapping layer
 - From block size, compute file block numbers
 - From file's inode data determine position on disk in terms of logical block number
- Issues operations to a generic block layer which issues block I/O requests
- I/O scheduler layer implements I/O policies
- Finally, block device drivers perform actual operation on device



Source: Bovet, Daniel P., Understanding the Linux Kernel.

Size matters

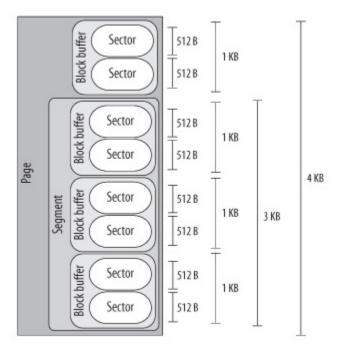
Hardware transfers data in sectors

VFS uses logical units called blocks

Block device drivers can work with adjacent data in segments

Disk caches work with pages

Source: Bovet, Daniel P., Understanding the Linux Kernel.



Typical sizes

The Generic Block Layer

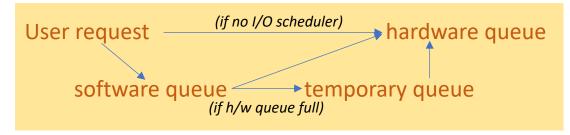
- Put data into buffers
- "Zero copy" directly put data into user space
- Manage logical volumes
 - LVM, RAID
- Exploit advance features in modern disk controllers
- The bio structure contains all information regarding an ongoing block I/O operation

Multi-Queue Block IO Queueing (blk-mq)

- Slow devices like hard disk
 - A single queue to store block IO requests with a single lock
- SSD, NVMe, supports parallelism well
 - Need for multiple queues with reduced synchronization overhead

Two types of queues in blk-mq

- Hardware dispatch queues
 - A struct (struct blk_mq_hw_ctx) used by device drivers to map the device submission queues (or device DMA ring buffer)
 - The last step of the block layer submission code before the low level device driver takes over
- Software staging queues
 - If there is an IO scheduler attached or
 - If we want to try to merge requests
 - Example: requests for sector 3-6, 6-7, 7-9 can become one request for sectors 3-9



The I/O Scheduler

- Generic block layer fires off random block I/O operations. But random access is bad for performance
- I/O Scheduler tries to group I/O operations for best performance
- However, deferring some I/O operations can lead to complications
 - Throw in the fact that block I/O are asynchronous and interrupt driven and you see the complications that the I/O scheduler has to deal with
- In implementing any scheduling policies, I/O scheduler must ensure deadlocks etc. won't arise
- Also, tries to implement fairness of resource usage
- \$ cat /sys/block/<device>/queue/scheduler

How I/O scheduling works

 Generic block layer invokes I/O scheduler to determine where a new request should be added to a request queue

- I/O scheduler tries to keep request queue sorted by sector
 - Reduces disk seeking
 - Resembles elevator scheduling: hence the I/O schedulers are known as elevators

 After computing priorities, I/O scheduler will finally insert into a dispatch queue – the actual ordering of requests that a device driver should process

The I/O Scheduler Algorithms (Basic)

NOOP elevator: simplest, no sorting, either FIFO or LIFO

- Complete Fairness Queuing (CFQ) elevator: maintains a large number of queues (default 64)
 - Processes are hashed to queues by process IDs
 - Each queue is sorted by sectors
 - Deprecated

Budget Fair Queueing I/O Scheduler (BFQ)

Built from CFQ elevator code

- Guarantees a high system and application responsiveness, and a low latency for time-sensitive applications, such as audio or video players
 - Prioritizes latency over throughput

- Distributes bandwidth, and not just time, among processes or groups
 - Switch back to time distribution when needed to keep throughput high

How BFQ works (1)

- Each process doing I/O on a device has a weight and a queue
 - Every queue has a budget, measured in number of sectors
- A queue (process) is given exclusive access to a device, and issues requests to the device until
 - 1. The queue becomes empty
 - Not immediately, will wait a while to give the process chance to issue more requests
 - 2. The budget is exhausted
 - 3. A timeout (to take care of random access)
- If queue is marked "low latency", special heuristics are used instead to ensure low latency

How BFQ works (2)

- Early Queue Merge (EQM): used to merge requests to a device
 - A request targeting a device is checked with the next in line on the current active queue of the device (which may belong to another process). If hit, merge!
- Queues are scheduled (selected) based on Worst-case Weighted fair Queueing (WF2Q+)
 - Completely Fair Scheduler also based on similar idea
 - Also uses a red-black tree

Multiqueue Deadline Elevator (mq-deadline)

- 4 queues (1 read sorted by sector, 1 write sorted by sector, 1 read sorted by deadline, 1 write sorted by deadline)
 - A read (write) request will enter BOTH the read-by-sector (write-by-sector) and read-by-deadline (write-by-deadline)
 - A read request expires in 500 ms after entry into queue; 5 sec for write
 - First (using heuristic) determine whether to do read or write for the next batch of entries in the dispatch queue
 - Reads preferred, unless writes skipped over for too long
 - If, say, read is chosen, check read deadline queue. If head of that queue has expired, dispatch that. Then try to choose requests adjacent to this from the sector queue.
 - If no expired request, dispatch from where last left out in sector queue

Reset to head when end of queue is reached

Kyber I/O Scheduler

Designed for fast storage like SSD, NVMe

Self-tuning

Key to speed is to keep overheads low, operations simple

 Two primary queues, one for synchronous requests (reads) and one for asynchronous requests (writes)

How Kyber works

- Controls the number of entries of each type in a hardware queue
 - Using tokens
- Aim: keep the queue short for better response time
 - Simple merging attempted

 Tunes the actual number of requests allowed (#tokens) into the dispatch queues by measuring the completion time of each request and adjusting the limits to achieve the desired latencies

END