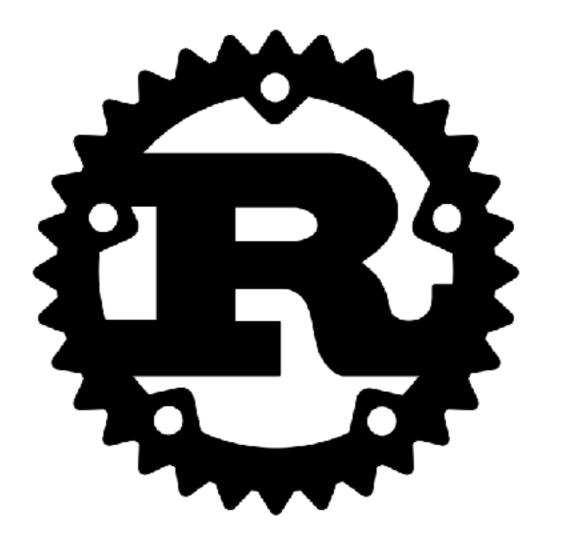
µcore 在 arm 架构下的 Rust 移植



Rust

### Rust

#### C++

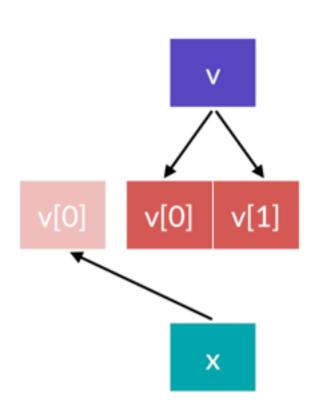
```
int main() {
   vector<string> v;

   v.push_back("Hello, ");

   string &x = v[0];

   v.push_back(" world!");

   cout << x;
}</pre>
```



- 1. 目标
- 2. 进度
- 3. Demo

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- 2. 进度
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- \* Rust!
- \* Raspberry Pi!
- \* µcore!
  - ▶ 中断、异常、系统调用
  - ▶ 内核线程管理、用户进程管理
  - ▶ 进程调度
  - ▶ 物理内存管理
  - ▶ 虚拟内存管理
  - ▶ 文件系统
- \* Peripherals!
  - USB
  - ▶ 网卡

- 1. 目标
- 2. 进度
- 3. Demo

- 完成 arm 平台硬件部分 调研
- bootloader
- xmodem uart ttywrite

#### 1 日标

- 2. 进度
- 3. Demo

- bootloader
- interrupt and exception
- physical memory management
- file system

### 1. 目标

- 2. 进度
- 3. Demo

- interrupt and exception
  - EL0 (user)
    Typically used to run untrusted user applications.
  - EL1 (kernel)

    Typically used to run privileged operating system kernels.
  - EL2 (hypervisor)
     Typically used to run virtual machine hypervisors.
  - EL3 (monitor)

    Typically used to run low-level firmware.

#### 1 日标

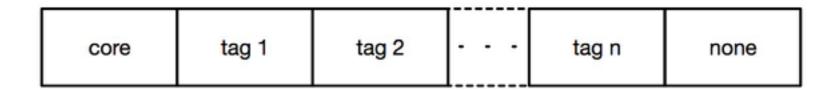
- 2. 进度
- 3. Demo

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### 调研

physical memory management



Name	Type ( tag )	Size	Description
CORE	0x54410001	5 or 2 if empty	First tag used to start list
NONE	0x00000000	2	Empty tag used to end list
MEM	0x54410002	4	Describes a physical area of memory
CMDLINE	0x54410009	variable	Command line to pass to kernel

#### 1 日标

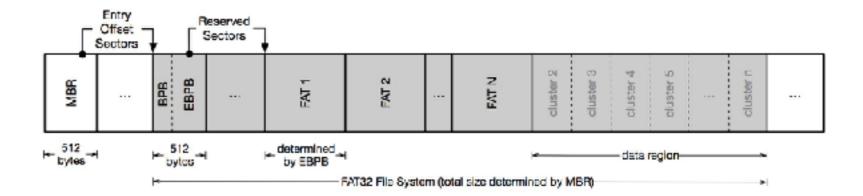
- 2. 进度
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- 1. 目标
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### 调研

file system



### 1. 目标

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#### bootloader

- 1. 目标
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	0x400000
kernel	0x80000
	0x0

### 1. 目标

- 2. 进度
- 3. Demo

#### bootloader

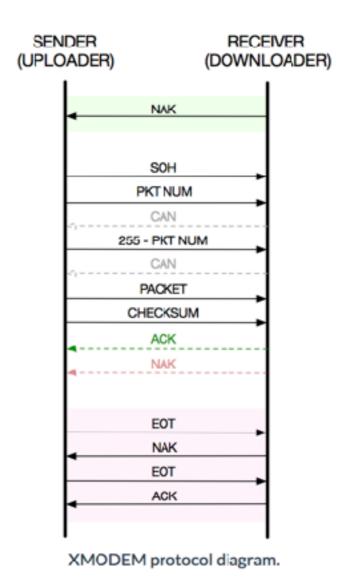
```
uart-bootloader
----- 0x400000
kernel
----- 0x80000
```

- 1. 目标
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- 完成 arm 平台硬件部分 调研
- bootloader
- xmodem uart ttywrite

- 1. 目标
- 2. 进度
- 3. Demo

### xmodem uart ttywrite



- 1. 目标
- 2. 进度
- 3. Demo

- 完成 arm 平台硬件部分 调研
- bootloader
- xmodem uart ttywrite

- 1. 目标
- 2. 进度
- 3. Demo

Demo

- 1. 目标
- 2. 进度
- 3. Demo