Lab 2: Uniformed Search in Pac-Man

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 Implement the depth-first search algorithm in the depthFirstSearch function in search.py. Although DFS and BFS ignore the costs, you'll need them for later search methods

Function Depth first search

Implement

tinyMaze

```
PS C:\Source\AI\Lab2\search> python pacman.py -l tinyMaze -p SearchAgent -a fn=dfs
[SearchAgent] using function dfs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 10 in 0.0 seconds
Search nodes expanded: 15
Pacman emerges victorious! Score: 500
Average Score: 500.0
Scores: 500.0
Win Rate: 1/1 (1.00)
Record: Win
```

mediumMaze

```
PS C:\Source\AI\Lab2\search> python pacman.py -l mediumMaze -p SearchAgent -a fn=dfs
[SearchAgent] using function dfs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 130 in 0.0 seconds
Search nodes expanded: 146
Pacman emerges victorious! Score: 380
Average Score: 380.0
Scores: 380.0
Win Rate: 1/1 (1.00)
Record: Win
```

bigMaze

```
PS C:\Source\AI\Lab2\search> python pacman.py -l bigMaze -p SearchAgent -a fn=dfs
[SearchAgent] using function dfs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 210 in 0.0 seconds
Search nodes expanded: 390
Pacman emerges victorious! Score: 300
Average Score: 300.0
Scores: 300.0
Win Rate: 1/1 (1.00)
Record: Win
```

Implement the breadth-first search algorithm in the breadthFirstSearch function in search.py. Use the same algorithm as shown in the above pseudocode. Test your code the same way you did for depth-first search

Function Breadth first search

```
def breadthFirstSearch(problem): 2 usages
    frontier = Queue()
    visited = set()
    start = problem.getStartState()
    frontier.push((start, []))
    visited.add(start)
    while not frontier.isEmpty():
        state, path = frontier.pop()
        if problem.isGoalState(state):
            return path
        for successor, action, stepCost in problem.getSuccessors(state):
            if successor not in visited:
                  visited.add(successor)
                  frontier.push((successor, path + [action]))
        return []
```

Implement

ttinyMaze

```
PS C:\Source\AI\Lab2\search> python pacman.py -l tinyMaze -p SearchAgent -a fn=bfs
[SearchAgent] using function bfs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 8 in 0.0 seconds
Search nodes expanded: 15
Pacman emerges victorious! Score: 502
Average Score: 502.0
Scores: 502.0
Win Rate: 1/1 (1.00)
Record: Win
```

mediumMaze

```
PS C:\Source\AI\Lab2\search> python pacman.py -l mediumMaze -p SearchAgent -a fn=bfs
[SearchAgent] using function bfs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 68 in 0.0 seconds
Search nodes expanded: 269
Pacman emerges victorious! Score: 442
Average Score: 442.0
Scores:
              442.0
Win Rate:
             1/1 (1.00)
Record:
bigMaze
PS C:\Source\AI\Lab2\search> python pacman.py -l bigMaze -p SearchAgent -a fn=bfs
[SearchAgent] using function bfs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 210 in 0.0 seconds
Search nodes expanded: 620
Pacman emerges victorious! Score: 300
Average Score: 300.0
               300.0
Scores:
Win Rate:
               1/1 (1.00)
Record:
             Win
```

3. Implement the uniform-cost search algorithm in the uniformCostSearch function in search.py. Does UCS find a least cost solution? How many nodes are expanded? Yes, Uniform-Cost Search (UCS) always finds the least-cost solution when all step costs are positive. This is because it expands the lowest-cost node first, ensuring that once a node is expanded, the shortest path to it has been found.

Function Uniformed cost search

```
def uniformCostSearch(problem):
    frontier = PriorityQueue()
    visited = {}
    start = problem.getStartState()
    frontier.push( item: (start, []), priority: 0)
    visited[start] = 0
    while not frontier.isEmpty():
        state, path = frontier.pop()
        if problem.isGoalState(state):
            return path
        cost = visited[state]
        for successor, action, stepCost in problem.getSuccessors(state):
            newCost = cost + stepCost
            if successor not in visited or newCost < visited[successor]:</pre>
                visited[successor] = newCost
                frontier.push( item: (successor, path + [action]), newCost)
    return []
```

Implement **t**tinyMaze

```
PS C:\Source\AI\Lab2\search> python pacman.py -l tinyMaze -p SearchAgent -a fn=ucs
[SearchAgent] using function ucs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 8 in 0.0 seconds
Search nodes expanded: 15
Pacman emerges victorious! Score: 502
Average Score: 502.0
Scores: 502.0
Win Rate: 1/1 (1.00)
Record: Win
```

mediumMaze

```
PS C:\Source\AI\Lab2\search> python pacman.py -l mediumMaze -p SearchAgent -a fn=ucs
[SearchAgent] using function ucs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 68 in 0.0 seconds
Search nodes expanded: 269
Pacman emerges victorious! Score: 442
Average Score: 442.0
Scores: 442.0
Win Rate: 1/1 (1.00)
Record: Win
```

bigMaze

```
PS C:\Source\AI\Lab2\search> python pacman.py -l bigMaze -p SearchAgent -a fn=ucs
[SearchAgent] using function ucs
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 210 in 0.0 seconds
Search nodes expanded: 620
Pacman emerges victorious! Score: 300
Average Score: 300.0
Scores: 300.0
Win Rate: 1/1 (1.00)
Record: Win
```

4. Compare table

	De	Depth-First Search			Breadth-First Search			Uniform-Cost Search		
Maze	Nodes explored	Solution length	Is it optional	Nodes explored	Solution length	Is it optional	Nodes explore	Solution length	Is it optional	
Tiny	15	~10	No	15	9	Yes	~15	9	Yes	
Medium	~146	130	No	~269	68	Yes	~269	68	Yes	

Ī	Big	~390	210	No	~620	210	Yes	~620	210	Yes

- **DFS:** Expands fewer nodes quickly in some cases, but can wander around and produce a suboptimal (longer) path
- BFS: Guarantees the shortest path in number of actions for uniform step costs, typically expands more nodes than DFS on these mazes but yields an optimal solution
- UCS: Identical path length to BFS under uniform cost = 1, but more general (handles varying step costs). It also expands about the same or sometimes slightly more nodes than BFS