LAB 05

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Exercise 1:

```
# Solve the linear system A·a = b using Gauss-Seidel
def gauss_seidel(A, b, max_iterations=1000, tolerance=1e-10):
    n = len(b)
    a = np.zeros(n)

for iteration in range(max_iterations):
    a_new = np.copy(a)
    for i in range(n):
        sum_ = np.dot(A[i, :i], a_new[:i]) + np.dot(A[i, i+1:], a[i+1:])

        a_new[i] = (b[i] - sum_) / A[i, i]

if np.linalg.norm(a_new - a) < tolerance:
        print(f"Gauss-Seidel converged after {iteration + 1} iterations.")
        break

a = a_new

return a</pre>
```

```
coefficients = gauss_seidel(A, b)
a0, a1, a2, a3 = coefficients
y_pred = a0 + a1*x_data + a2*x_data**2 + a3*x_data**3

residuals = y_data - y_pred
SSE = np.sum(residuals**2)
y_mean = np.mean(y_data)
SST = np.sum((y_data - y_mean)**2)
R_{squared} = 1 - (SSE / SST)
n = len(x_data)
p = 4
Syx = np.sqrt(SSE / (n - p))
print("\nFitted cubic equation coefficients:")
print(f"a0 (constant term) = {a0:.6f}")
print(f"a1 (linear term) = {a1:.6f}}
print(f"a2 (quadratic term) = {a2:.6f}'
print(f"a3 (cubic term) = {a3:.6f}")
print("\nGoodness of fit:")
print(f"Sum of squared errors (SSE) = {SSE:.6f}")
print(f"Coefficient of determination (R2) = {R_squared:.6f}")
print(f"Standard error of estimate (Sy/x) = {Syx:.6f}")
```

Result:

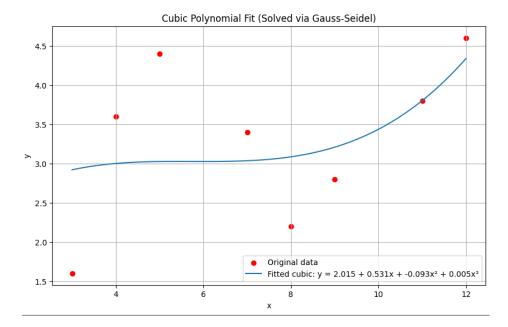
```
Fitted cubic equation coefficients:
a0 (constant term) = 2.015115
a1 (linear term) = 0.531267
a2 (quadratic term) = -0.092815
a3 (cubic term) = 0.005390

Goodness of fit:
Sum of squared errors (SSE) = 5.141713
Coefficient of determination (R<sup>2</sup>) = 0.323459
Standard error of estimate (Sy/x) = 1.133767
```

Plot:

```
import matplotlib.pyplot as plt

plt.figure(figsize=(10, 6))
plt.scatter(x_data, y_data, color='red', label='Original data')
x_smooth = np.linspace(min(x_data), max(x_data), 100)
y_smooth = a0 + a1*x_smooth + a2*x_smooth**2 + a3*x_smooth**3
plt.plot(x_smooth, y_smooth, label=f'Fitted cubic: y = {a0:.3f} + {a1:.3f}x + {a2:.3f}x² + {a3:.3f}x³')
plt.xlabel('x')
plt.ylabel('y')
plt.title('Cubic Polynomial Fit (Solved via Gauss-Seidel)')
plt.legend()
plt.grid(True)
plt.show()
```



Exercise 2:

```
import numpy as np
import matplotlib.pyplot as plt

x_data = np.array([0.1, 0.2, 0.4, 0.6, 0.9, 1.3, 1.5, 1.7, 1.8])
y_data = np.array([0.75, 1.25, 1.45, 1.25, 0.85, 0.55, 0.35, 0.28, 0.18])
```

```
def model(x, alpha, beta):
    return alpha * x * (1 - np.exp(beta * x))
def compute_jacobian(x, alpha, beta):
    df_dalpha = x * (1 - np.exp(beta * x))
df_dbeta = alpha * x**2 * np.exp(beta * x)
    return np.vstack((df_dalpha, df_dbeta)).T
def compute_residuals(x, y, alpha, beta):
    return y - model(x, alpha, beta)
def jacobi(A, b, tol=1e-6, max_iter=100):
    n = len(b)
    x = np.zeros_like(b)
    for it in range(max_iter):
        x_new = np.zeros_like(x)
         for i in range(n):
            s = sum(A[i, j] * x[j] for j in range(n) if j != i)
             x_{new[i]} = (b[i] - s) / A[i, i]
         if np.linalg.norm(x_new - x, ord=np.inf) < tol:</pre>
            return x_new
        x = x_new
```

```
def nonlinear_fit(x, y, alpha_init, beta_init, iterations=10):
    alpha, beta = alpha_init, beta_init

for i in range(iterations):
    D = compute_residuals(x, y, alpha, beta)
    Z = compute_jacobian(x, alpha, beta)
    ZT_Z = Z.T @ Z
    ZT_D = Z.T @ D

    delta = jacobi(ZT_Z, ZT_D)
    alpha += delta[0]
    beta += delta[1]

return alpha, beta
```

Result:

```
Fitted parameters:
a4 = 0.3895
beta4 = 164.2917
R-squared = -2.0471
```

Plot:

