

Definitions and General Principles

Inverse of a Matrix

- $(A^{-1})^{-1} = A$
- $(AB)^{-1} = B^{-1}A^{-1}$
- $AA^{-1} = A^{-1}A = I$

LDU Decomposition

- For a symmetric matrix A : $A = LDL^T$
- L : lower triangular with unit diagonal
- D : diagonal matrix

Vector Space Axioms

- Addition: commutativity, associativity, identity, inverses
- Scalar Multiplication: distributivity, compatibility, identity

Subspaces

- Closed under addition and scalar multiplication

Linear Dependence and Independence

- Dependent: \exists scalars, not all zero, s.t. $a_1v_1 + \dots + a_nv_n = 0$
- Independent: only solution is $a_1 = \dots = a_n = 0$

Basis and Dimension

- Basis: linearly independent spanning set
- Dimension: number of vectors in a basis

General Principles for Subspaces

- Closed under vector addition
- Closed under scalar multiplication

Linear Transformation

- Preserves vector addition and scalar multiplication

Image and Kernel

- $\text{im}(A)$: span of column vectors of A
- $\text{ker}(A)$: $\{x \in \mathbb{R}^n : Ax = 0\}$

Basis Transformation

- Unique representation of a vector in terms of basis vectors

Determining Linear Independence (Standard Case)

Given vectors $v_1 = (1, 2, 3)$, $v_2 = (0, 1, 1)$, and $v_3 = (2, 5, 7)$, determine if they are linearly independent.

Solution:

1. Arrange the vectors as columns in a matrix A :

$$A = \begin{bmatrix} 1 & 0 & 2 \\ 2 & 1 & 5 \\ 3 & 1 & 7 \end{bmatrix}$$

2. Perform row reduction on A :

$$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

3. Since there are no rows of all zeros in the reduced row echelon form, the vectors are linearly independent.

Determining Linear Independence (Linearly Dependent Case)

Given vectors $v_1 = (1, 2, 3)$, $v_2 = (2, 4, 6)$, and $v_3 = (3, 6, 9)$, determine if they are linearly independent.

Solution:

1. Arrange the vectors as columns in a matrix A :

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{bmatrix}$$

2. Perform row reduction on A :

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

3. The presence of rows of all zeros indicates that the vectors are linearly dependent.

Finding a Basis for a Subspace (Polynomial Space)

Find a basis for the subspace of P_3 consisting of polynomials $p(x) = ax^3 + bx^2 + cx + d$ such that $p(1) = 0$.

Solution:

1. The condition $p(1) = 0$ gives $a + b + c + d = 0$. To find a basis, express this condition in terms of the coefficients and set up a system.
2. Considering the standard basis $\{1, x, x^2, x^3\}$ for P_3 , impose the condition for $p(1) = 0$:

$$\begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} d \\ c \\ b \\ a \end{bmatrix} = 0$$

This implies $a = -b - c - d$.

3. A basis satisfying this condition is $\{x^3 - x^2, x^2 - x, x - 1\}$ as these polynomials nullify at $x = 1$ and are linearly independent.

Finding the Matrix Inverse

Find the inverse of the matrix $A = \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix}$.

Solution:

1. Set up the augmented matrix for A and the identity matrix: $\begin{bmatrix} 1 & 3 & | & 1 & 0 \\ 2 & 7 & | & 0 & 1 \end{bmatrix}$.
2. Perform row operations to get the identity matrix on the left side of the augmented matrix. Subtract twice the first row from the second row to start: $\begin{bmatrix} 1 & 3 & | & 1 & 0 \\ 0 & 1 & | & -2 & 1 \end{bmatrix}$.
3. Then, subtract 3 times the second row from the first row: $\begin{bmatrix} 1 & 0 & | & 7 & -3 \\ 0 & 1 & | & -2 & 1 \end{bmatrix}$.
4. The matrix on the right side is now $A^{-1} = \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix}$.

Eigenvalues and Eigenvectors

Find the eigenvalues and corresponding eigenvectors

for the matrix $B = \begin{bmatrix} 4 & 1 \\ 1 & 4 \end{bmatrix}$.

Solution:

1. Find the characteristic polynomial: $\det(B - \lambda I) = \det \begin{bmatrix} 4 - \lambda & 1 \\ 1 & 4 - \lambda \end{bmatrix} = (4 - \lambda)^2 - 1$.
2. Solve for λ : $(4 - \lambda)^2 - 1 = 0 \Rightarrow \lambda^2 - 8\lambda + 15 = 0$. The eigenvalues are $\lambda_1 = 3$ and $\lambda_2 = 5$.
3. Find eigenvectors for each eigenvalue: - For $\lambda_1 = 3$: Solve $(B - 3I)x = 0$. This gives $x_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$. - For $\lambda_2 = 5$: Solve $(B - 5I)x = 0$. This gives $x_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

Diagonalization

Determine if the matrix $C = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix}$ is diagonalizable. If it is, find a matrix P that diagonalizes C .

Solution:

1. Find the eigenvalues of C : The characteristic polynomial is $(2 - \lambda)^2 = 0$, so the only eigenvalue is $\lambda = 2$.
2. Since C is a 2×2 matrix with only one distinct eigenvalue, we need to check if there are two linearly independent eigenvectors corresponding to $\lambda = 2$.
3. Solve $(C - 2I)x = 0$: This leads to the system $x_2 = 0$, indicating that every eigenvector has the form $\begin{bmatrix} t \\ 0 \end{bmatrix}$, which does not provide two independent eigenvectors.
4. Since we cannot find two linearly independent eigenvectors, C is not diagonalizable.

Perform LDU decomposition

Perform LDU decomposition on the matrix $H = \begin{bmatrix} 4 & 12 & -16 \\ 12 & 37 & -43 \\ -16 & -43 & 98 \end{bmatrix}$.

Solution:

1. First, we find the matrix L such that $H = LDU$ where L is a lower triangular matrix with unit diagonal, D is a diagonal matrix, and U is an upper triangular matrix.
2. Decompose H into LDU :

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ -4 & 5 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 9 \end{bmatrix},$$

$$U = \begin{bmatrix} 1 & 3 & -4 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{bmatrix}.$$

3. Verify the decomposition by calculating LDU and comparing it with H :
$$LDU = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ -4 & 5 & 1 \end{bmatrix} \begin{bmatrix} 4 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 9 \end{bmatrix} \begin{bmatrix} 1 & 3 & -4 \\ 0 & 1 & 5 \\ 0 & 0 & 1 \end{bmatrix}$$
4. The result confirms the LDU decomposition of H .

Section 3

Problem 7: Determinant Calculation

Calculate the determinant of the matrix $D = \begin{bmatrix} 6 & 1 & 2 \\ 1 & 3 & 1 \\ 2 & 0 & 4 \end{bmatrix}$.

Solution:

- 1. Apply the Laplace expansion using the first row:

$$\det(D) = 6 \begin{vmatrix} 3 & 1 \\ 0 & 4 \end{vmatrix} - 1 \begin{vmatrix} 1 & 1 \\ 2 & 4 \end{vmatrix} + 2 \begin{vmatrix} 1 & 3 \\ 2 & 0 \end{vmatrix}$$

- 2. Calculate each minor:

$$6(3 \cdot 4 - 0 \cdot 1) - 1(1 \cdot 4 - 1 \cdot 2) + 2(1 \cdot 0 - 3 \cdot 2) = 72 - 2 - 12 = 58$$

- 3. Thus, $\det(D) = 58$.

Problem 8: Using Cramer’s Rule

Solve the following system of equations using Cramer’s Rule:

$$\begin{aligned} x + 2y - z &= 4, \\ 2x - y + 3z &= -2, \\ x + 3y + z &= 3. \end{aligned} \tag{1}$$

Solution:

- 1. Write the coefficient matrix and calculate its determinant:

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 2 & -1 & 3 \\ 1 & 3 & 1 \end{bmatrix}, \quad \det(A) = -16.$$

- 2. For x , replace the first column of A with the constant terms and calculate its determinant:

$$A_x = \begin{bmatrix} 4 & 2 & -1 \\ -2 & -1 & 3 \\ 3 & 3 & 1 \end{bmatrix}, \quad \det(A_x) = -16.$$

- 3. For y , replace the second column of A :

$$A_y = \begin{bmatrix} 1 & 4 & -1 \\ 2 & -2 & 3 \\ 1 & 3 & 1 \end{bmatrix}, \quad \det(A_y) = -32.$$

- 4. For z , replace the third column of A :

$$A_z = \begin{bmatrix} 1 & 2 & 4 \\ 2 & -1 & -2 \\ 1 & 3 & 3 \end{bmatrix}, \quad \det(A_z) = -16.$$

- 5. Compute the solutions: $x = \frac{\det(A_x)}{\det(A)} = 1, y = \frac{\det(A_y)}{\det(A)} = 2, z = \frac{\det(A_z)}{\det(A)} = 1.$

Section 4

Problem 9: Finding the Rank of a Matrix

Find the rank of the matrix $E = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{bmatrix}$.

Solution:

- 1. Perform row reduction on E :

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

- 2. The rank is equal to the number of non-zero rows in the reduced row echelon form. Hence, $\text{rank}(E) = 1$.

Problem 10: LU Decomposition

Perform LU decomposition on the matrix $F = \begin{bmatrix} 4 & 3 \\ 6 & 3 \end{bmatrix}$.

Solution:

- 1. Express F as the product of a lower triangular matrix L and an upper triangular matrix U .

- 2. Choose L with 1s on the diagonal: $L = \begin{bmatrix} 1 & 0 \\ l_{21} & 1 \end{bmatrix}$.

- 3. Let $U = \begin{bmatrix} u_{11} & u_{12} \\ 0 & u_{22} \end{bmatrix}$.

- 4. Since $F_{21} = l_{21} \cdot u_{11}$ and $F_{21} = 6, u_{11} = 4$, we get $l_{21} = \frac{6}{4} = \frac{3}{2}$.

- 5. Solve for U using the first row of F : $U = \begin{bmatrix} 4 & 3 \\ 0 & u_{22} \end{bmatrix}$. The second element of the second row gives $u_{22} = 3 - \frac{3}{2} \cdot 3 = -\frac{3}{2}$.

- 6. The LU decomposition is $L = \begin{bmatrix} 1 & 0 \\ \frac{3}{2} & 1 \end{bmatrix}, U = \begin{bmatrix} 4 & 3 \\ 0 & -\frac{3}{2} \end{bmatrix}$.

Section 5

Problem 11: Orthogonal Diagonalization

Orthogonally diagonalize the matrix $F = \begin{bmatrix} 3 & -1 \\ -1 & 3 \end{bmatrix}$.

Solution:

- 1. Find the eigenvalues by solving $\det(F - \lambda I) = 0$: $\lambda^2 - 6\lambda + 8 = 0$ gives $\lambda_1 = 2$ and $\lambda_2 = 4$.

- 2. Find the eigenvectors: For $\lambda_1 = 2$, solve $(F - 2I)x = 0$ to get $x_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ (after normalization). For $\lambda_2 = 4$, solve $(F - 4I)x = 0$ to get $x_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ (after normalization).

- 3. Construct $P = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix}$ and verify $P^T F P = \begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix}$.

Problem 12: Singular Value Decomposition (SVD)

Find the singular value decomposition of the matrix $G = \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix}$.

Solution:

- 1. Compute the eigenvalues of $G^T G$: Since $G^T G = \begin{bmatrix} 9 & 0 \\ 0 & 4 \end{bmatrix}$, the eigenvalues are 9 and 4.

- 2. The singular values are the square roots of the eigenvalues: $\sigma_1 = 3$ and $\sigma_2 = 2$.

- 3. The right singular vectors are the eigenvectors of $G^T G$, which correspond to $v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.

- 4. The left singular vectors are obtained by normalizing the columns of GU , where U is the matrix of right singular vectors. In this case, they remain the same as v_1 and v_2 .

- 5. Assemble the SVD: $G = U \Sigma V^T$ with $U = V = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ and $\Sigma = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$.