

# Assignment 1

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## 1 Assignment 1

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## 2 Problem 1

In [1]: `using` Plots

```
x = linspace(-1, 1, 500)

# Function
y = 1 - exp(-2x)

# First-order
t1 = 2x

# Second-order
t2 = 2x - 2x.^2

plot(x, [y t1 t2],
label=["Original Function" "First-Order" "Second-Order"])
```

See the plot at the end

## 3 Problem 2

### 3.1 Exercise 2.1

The speed of the computations will be similar. However, some functions may work while others won't if the polynomial has values  $a$ ,  $b$  or  $c$  leaving a zero term in the denominator.

The following function only returns real roots of degree 2 polynomial inputs.

```
In [2]: function findRoot(a, b, c)
        if a!=0 && b!=0
```

```

        posRoot = (-b + sqrt(b^2 - 4*a*c))/2*a
        negRoot = (-b - sqrt(b^2 - 4*a*c))/2*a
    elseif a !=0 && (4*a*c)/b^2 < 1
        posRoot = (-b/(2*a)) * (1+ sqrt((1-4*a*c)/b^2))
        negRoot = (-b/(2*a)) * (1- sqrt((1-4*a*c)/b^2))
    end
    return [posRoot, negRoot]
end

```

Out[2]: findRoot (generic function with 1 method)

### 3.2 Exercise 2.2

```

In [3]: A = [54 14 11 2;
            14 50 4 29;
            11 4 55 22;
            2 29 22 95]

```

```

b = [1,1,1,1]

```

```

# This returns the solution to Ax=b
x = \ (A, b)
print(x)

```

[0.0120453,0.0138627,0.0136088,0.00288944]

```

In [4]: using IterativeSolvers

```

```

b = [1.0, 1.0, 1.0, 1.0]

```

```

# Solves Ax=b using Gauss-Jacobi method
x, result = jacobi(A, b, tol=0.0001)

```

```

print("results are: ", x)
result

```

results are: [0.0120329,0.0138428,0.013594,0.0028755]

Out[4]: IterativeSolvers.ConvergenceHistory{Float64,Array{Float64,1}}(false,0.0002,

```

In [5]: b = [1.0, 1.0, 1.0, 1.0]

```

```

# Solves Ax=b using Gauss-Seidel method
x, result = gauss_seidel(A, b, tol=0.0001)

```

```

print("results are: ", x)
result

```

results are: [0.0120419,0.0138654,0.0136108,0.00288822]

```
Out[5]: IterativeSolvers.ConvergenceHistory{Float64,Array{Float64,1}}(true,0.0002,6)
```

We can see from the results above, the Gauss-Jacobi method took 16 iterations, and the Gauss-Seidel method took 6.

## 4 Problem 3

For problem 3, we start by writing an iterative function where  $x_{k+1} = g(x_k, b)$

```
In [6]: function iterate(g::Function, x0, b, tol=1e-4, maxit=1000)
    x = x0
    for i in 1:maxit
        x_old = copy(x)
        x = g(x, b)

        # Stop algorithm if absolute or relative tolerance are smaller than
        if abs(x - x_old) < tol || abs(1 - x_old/x) < tol
            break
        end

        # Stop algorithm if we reach max iteration without convergence
        if i == maxit
            x = "No convergence"
        end
    end
    return(x)
end
```

```
Out[6]: iterate (generic function with 3 methods)
```

Then we use  $g(x, b) = 1 - b + bx$

```
In [7]: g(x, b) = 1 - (b) + (b)*x

print("input -2 fixed point at: ", iterate(g, 0.5, -2), "\n")
print("input 0 fixed point at: ", iterate(g, 0.5, 0), "\n")
print("input 1 fixed point at: ", iterate(g, 0.5, 1), "\n")
print("input 2 fixed point at: ", iterate(g, 0.5, 2), "\n")

input -2 fixed point at: No convergence
input 0 fixed point at: 1.0
input 1 fixed point at: 0.5
input 2 fixed point at: No convergence
```

Note that for -2 and 2 there's no convergence. Therefore, for  $g(x, b)$  with  $b = 2, -2$ , there's no fixed point.

## 5 Problem 4

```
In [8]: function newton(f::Function, df::Function , x0, tol = 1e-4 ,maxit = 10000)

    # Give error if inital guess is negative
    if x0 <= 0
        error("Need positive inital guess")
    end

    x = x0
    for i in 1:maxit

        x_old = copy(x)
        x = x - f(x) / df(x)

        # If new guess x is negative reduce step by half until new guess is
        while x <= 0
            x = x_old + (x - x_old)/2
        end

        # Stop algorithm if absolute or relative tolerance are smaller than
        if abs(x - x_old) < tol || abs(1 - x_old/x) < tol
            break
        end

        # Stop algorithm if we reach max iteration without convergence
        if i == maxit
            x = "Reached maximum iteration"
        end
    end
    return(x)
end
```

Out[8]: newton (generic function with 3 methods)

We try our algorithm for  $f(x) = \log(x)$  and starting value equal to 1000

```
In [9]: f(x) = log(x)
        df(x) = 1/x

        newton(f, df , 1000)
```

Out[9]: 1.0

Note that even if the starting guess is rather bad, we still converge to the right value of 1

## 6 Problem 5

### 6.1 Exercises 3.3

In this problem note that the implied volatility solve the problem  $V(\sigma) = \bar{V}$ , where  $V(\sigma)$  is value function for some  $\sigma$  and  $\bar{V}$  is some specified value of our option. Therefore, if we write the problem in the following way,  $F(\sigma) = V(\sigma) - \bar{V} = 0$ , we can solve it using Newton's method.

In [10]: **using** Distributions

```
# Set value function
function BSVal(S,K,tau,r,delta,sigma)
    d = (log(exp(-delta*tau)*S)-log(exp(-r*tau)*K))/(sigma*sqrt(tau))
    + 0.5*sigma*sqrt(tau)
    V = exp(-delta*tau)*S*cdf(Normal(), d)
    - exp(-r*tau)*K*cdf(Normal(), d-sigma*sqrt(tau))
    return (V)
end

# Set implied volatility function
function ImpVol(S,K,tau,r,delta, V, tol = 1e-3, maxit = 1000)

    # Set starting value for sigma
    sigma = 1

    # Set function equal to the derivative of the value function
    function dBSVal(S,K,tau,r,delta,sigma)
        d = (log(exp(-delta*tau)*S)-log(exp(-r*tau)*K))/(sigma*sqrt(tau))
        + 0.5*sigma*sqrt(tau)
        dV = S*exp(-delta*tau)*sqrt(tau/(2*pi))*exp(-0.5*d^2)
    end

    # Use Newton's method to solve for sigma
    for i in 1:maxit
        ImpV = BSVal(S,K,tau,r,delta,sigma)
        dImpV = dBSVal(S,K,tau,r,delta,sigma)

        sigma = sigma - (ImpV - V)/dImpV

        # Stop algorithm if absolute or relative tolerance are smaller than
        if abs(V - ImpV) < tol || abs(1 - ImpV/V) < tol
            break
        end

        # Stop algorithm if we reach max iteration without convergence
        if i == maxit
            sigma = "No convergence"
        end
    end
```

```

        return(sigma)
    end

```

```

ImpVol(1, 1.1, 1, 0.08, 0, 0.0728)

```

```

Out[10]: 0.20002397692365345

```

Thus for  $V = 0.0728$ , we have  $\sigma = 0.20$ .

## 6.2 Exercises 3.5

For this exercise, we used MATLAB and the CompEcon toolbox with the code:

```

function [fval, fjac] = fun(x)
    f1 = 200*x(1)*(x(2) - x(1)^2)-x(1)+1;
    f2 = 100*(x(1)^2 - x(2));

    fval = [f1; f2];

    df11 = 200*x(2) - 600*x(1)^2 - 1;
    df12 = 200*x(1);
    df21 = 200*x(1);
    df22 = -100;

    fjac = [df11 df12; df21 df22];
end

% Netwon
newton('fun',[0;2])
% Broyden
broyden('fun',[0;2])

```

The code gives the following output.

```

ans =

```

```

    1.0000
    1.0000

```

```

ans =

```

```

    1.0000
    1.0000

```

Hence, we have  $x_1 = x_2 = 1$  as a solution in both cases.

### 6.3 Exercises 3.7

First note that for a CDF  $F(x) \rightarrow U$ , where  $U \in [0, 1]$  and its inverse  $F^{-1}(U) = x$ , the problem can be recast as a root finding problem where  $F(x) - U = 0$ , where given a particular  $U$ , we want to find the corresponding  $x$ . This can be done using the Newton function written in problem 4.

In [11]: **using** Distributions

```
function icdf(p::Float64, F::Function, x0=1.0, args...)
    # p::float [0,1] is a probability
    # F is a function (CDF)
    # x0 is an initial guess
    # F(x) should be formed as returning a tuple
    #      (CDF(x), pdf(x))
    # args... are args for F
    f(x) = F(x, args...)[1] - p
    fPrime(x) = F(x, args...)[2]
    result = newton(f, fPrime, x0)
return result
end

function cdfnormal(x,mu,sigma)
    dist = Normal(mu, sigma)
    z=(x-mu)./sigma;
    F=cdf(dist,x);
    f=exp(-0.5*z.^2)./(sqrt(2*pi)*sigma)
    return F, f
end

test = 5

testResult = test-icdf(cdfnormal(test,0,1)[1], cdfnormal, 3, 0, 1)
```

Out [11]: 4.966773659020873e-10

$4.97 * 10^{-10}$  is indeed close to 0