



# Performance Modeling of Computer Systems and Networks

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## Sample statistics

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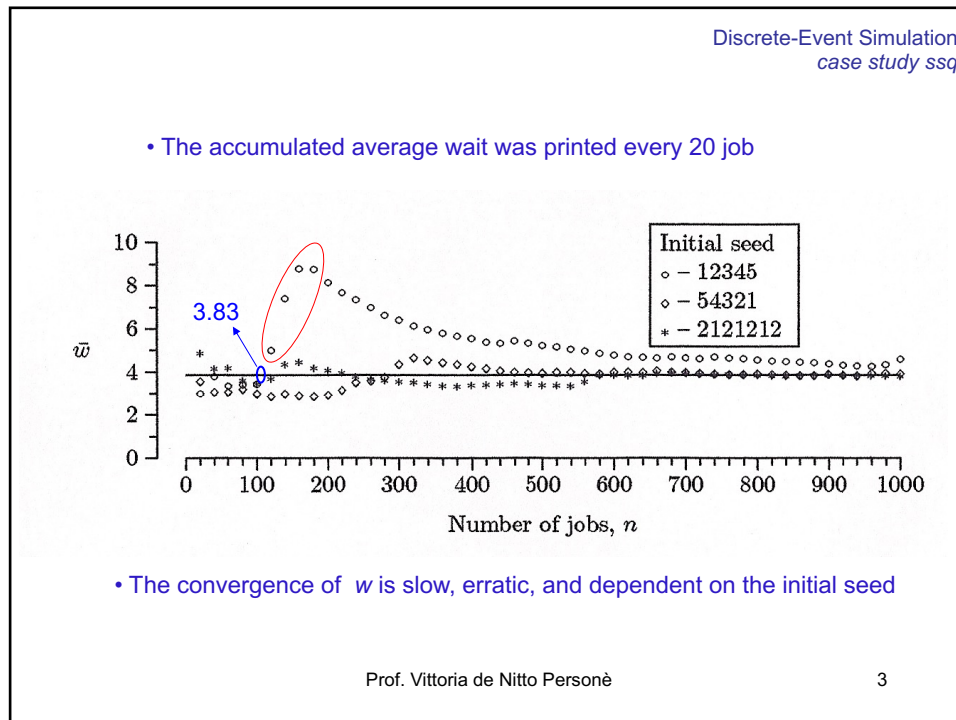
Discrete-Event simulation  
*Sample statistics*

- Simulation involves *a lot* of data
- Must “compress” the data into meaningful statistics
- Collected data is a *sample* from a much larger *population*
- Two types of statistical analysis
  - “Within-the-run”
  - “Between-the-runs” (replication)
- Essence of statistics: analyze a sample and draw inferences

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arrival and service processes are *uncoupled*

stream 0 for arrivals, stream 1 for services

for 10025 jobs

average interarrival time =	1.99
average wait .....	3.92
average delay .....	2.41
average service time ....	1.50
average # in the node ...	1.96
average # in the queue ..	1.21
utilization .....	0.75

stream 0 for arrivals, stream 2 for services (or e.g. stream 128 to get more separation)

for 10025 jobs

average interarrival time =	1.99
average wait .....	3.86
average delay .....	2.36
average service time ....	1.50
average # in the node ...	1.93
average # in the queue ..	1.18
utilization .....	0.75

Theoretical values						
$\bar{r}$	$\bar{w}$	$\bar{d}$	$\bar{s}$	$\bar{l}$	$\bar{q}$	$\bar{x}$
2.00	3.83	2.33	1.50	1.92	1.17	0.75

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## Sample Mean and Standard Deviation

Consider a sample  $x_1, x_2, \dots, x_n$  (continuous or discrete), let us define:

- *sample mean*  $\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$
- *sample variance*  $s^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$
- *sample standard deviation*  $s = \sqrt{s^2}$
- *coefficient of variation*  $s / \bar{x}$

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- *mean*: a measure of central tendency
- *variance and deviation*: measures of dispersion about the mean
  - easier math  
(no square root)
  - same units as data,  
mean
- note that *coefficient of variation (CV)* is unit-less, but a common shift in data changes the CV

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## Relating the mean and standard deviation

Consider the root-mean-square (rms) function

$$d(x) = \sqrt{\frac{1}{n} \sum_{i=1}^n (x_i - x)^2}$$

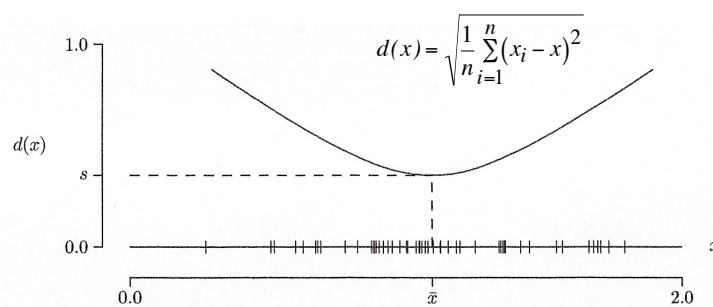
- $d(x)$  measures dispersion about any value  $x$
- the mean  $\bar{x}$  gives the smallest possible value for  $d(x)$  (Theorem 4.1.1)
- The standard deviation  $s$  is that smallest value

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50 samples from program buffon



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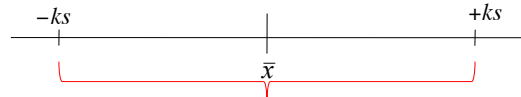
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## Chebyshev's inequality

DE simulation  
Sample statistics

Consider the number of points that lie within  $k$  standard deviations of the mean



- Points farthest from the mean make the most contribution to  $s$

Define the set  $S_k = \{x_i | \bar{x} - ks < x_i < \bar{x} + ks\}$

Let  $p_k = |S_k|/n$  be the proportion of  $x_i$  within  $\pm ks$  of  $\bar{x}$

$$p_k \geq 1 - \frac{1}{k^2} \quad (k > 1)$$

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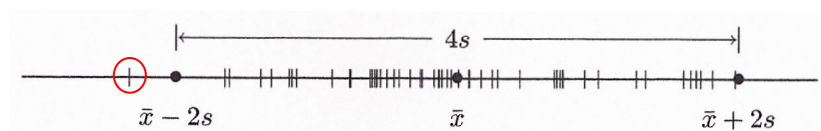
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## Chebyshev's inequality

DE simulation  
Sample statistics

- for any sample, at least 75% of the points lie within  $\pm 2s$  of  $\bar{x}$
- for  $k=2$ , the inequality is very conservative:  
typically 95% lie within  $\pm 2s$  of  $\bar{x}$
- $\bar{x} \pm 2s$  defines the "effective width" of a sample



- most (but not all) points will lie in this interval
- outliers should be viewed with suspicion

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## Linear data transformations

- Often need to convert to different units after data has been collected

- let  $x'_i$  be the "new data":  $x'_i = ax_i + b$

- *sample mean*

$$\bar{x}' = \frac{1}{n} \sum_{i=1}^n x'_i = \frac{1}{n} \sum_{i=1}^n (ax_i + b) = \frac{a}{n} \left( \sum_{i=1}^n x_i \right) + b = a\bar{x} + b$$

- *sample variance*  $(s')^2 = \frac{1}{n} \sum_{i=1}^n (x'_i - \bar{x}')^2 = \dots = a^2 s^2$

- *sample standard deviation*  $s' = |a|s$

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## Examples of Linear Data Transformations

- suppose  $x_1, x_2, \dots, x_n$  measured in seconds

- to convert to minutes, let  $x'_i = x_i/60$

(a=1/60, b=0)

$$\bar{x}' = \frac{45}{60} = 0.75$$

$$s' = \frac{15}{60} = 0.25 \quad (\text{minutes})$$

- *standardize data*  
(a=1/s, b=- $\bar{x}/s$ )

$$x'_i = \frac{1}{s} x_i - \frac{\bar{x}}{s}$$

$$x'_i = \frac{x_i - \bar{x}}{s}$$

Then

$$\bar{x}' = 0$$

$$s' = 1$$

Used to avoid problems with very large (or small) valued samples

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## Nonlinear data transformations

- usually involves a Boolean (two-state) outcome
- the *value* of  $x_i$  is not as important as the *effect*
- let  $A$  be a fixed set; then

$$x'_i = \begin{cases} 1 & x_i \in A \\ 0 & \text{otherwise} \end{cases}$$

- let  $p$  be the proportion of  $x_i$  that fall in  $A$ :

$$p = \frac{\text{the number of } x_i \text{ in } A}{n}$$

then

$$\bar{x}' = p \quad s' = \sqrt{p(1-p)}$$

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## Examples of Nonlinear Data Transformations

For the single server service queue

- let  $x_i = d_i$  be the delay for job  $i$
- let  $A = \mathbb{R}^+$ , then  $x'_i = 1$  iff  $d_i > 0$
- from exerc. 1.2.3 proportion of job delayed is  $p = 0.723$
- then  $\bar{x}' = 0.723$  and  $s = \sqrt{(0.723)(0.277)} = 0.448$

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## Computational considerations

Consider the sample standard deviation equation

$$s = \sqrt{\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2}$$

Requires two passes through the data:

1. Compute the mean  $\bar{x}$
2. Compute the squared differences about  $\bar{x}$

Must store or re-create the entire sample!  
bad when  $n$  is large!

## The conventional one-pass Algorithm

Consider the sample standard deviation equation

$$\begin{aligned} s^2 &= \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2 \\ &= \frac{1}{n} \sum_{i=1}^n (x_i^2 - 2\bar{x}x_i + \bar{x}^2) \end{aligned}$$

by separating and simplifying

$$= \left( \frac{1}{n} \sum_{i=1}^n x_i^2 \right) - \bar{x}^2$$

round-off error, overflow



## Welford's one-pass algorithm

- running sample mean until  $i$

$$\bar{x}_i = \frac{1}{i}(x_1 + x_2 + \dots + x_i)$$

- running sample sum of squared deviations until  $i$

$$v_i = (x_1 - \bar{x}_i)^2 + (x_2 - \bar{x}_i)^2 + \dots + (x_i - \bar{x}_i)^2$$

- $\bar{x}_i$  and  $v_i$  can be computed recursively ( $\bar{x}_0 = 0, v_0 = 0$ ) :

$$\bar{x}_i = \bar{x}_{i-1} + \frac{1}{i}(x_i - \bar{x}_{i-1})$$

$$v_i = v_{i-1} + \left(\frac{i-1}{i}\right)(x_i - \bar{x}_{i-1})^2$$

- $\bar{x}_n$  is the sample mean,  $v_n / n$  is the variance

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## Welford's Algorithm (program uvs)

- No *a priori* knowledge of the sample size  $n$  required
- Less prone to accumulated round-off error

$\bar{x}_i = \bar{x}_{i-1} + \frac{1}{i}(x_i - \bar{x}_{i-1})$

```

n = 0;
x = 0.0;
v = 0.0;
while (more data) {
    x = GetData();
    n++;
    d = x - x_bar;
    v = v + d * d * (n - 1) / n;
    x_bar = x_bar + d / n;
}
s = sqrt(v / n);
return n, x_bar, s;

```

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## Welford's Algorithm (program `uvs`)

- No *a priori* knowledge of the sample size  $n$  required
- Less prone to accumulated round-off error

```

n = 0;
x̄ = 0.0;
v = 0.0;
while (more data) {
    x = GetData();
    n++;
    d = x - x̄;
    v = v + d * d * (n - 1) / n;
    x̄ = x̄ + d / n;
}
s = sqrt(v / n);
return n, x̄, s;

```

$$v_i = v_{i-1} + \left(\frac{i-1}{i}\right)(x_i - \bar{x}_{i-1})^2$$

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## Example

- let  $x_1, x_2, \dots, x_n$  be  $Uniform(a, b)$  random variates

- in the limit as  $n \rightarrow \infty$   

$$\bar{x} \rightarrow \frac{a+b}{2} \qquad s \rightarrow \frac{b-a}{\sqrt{12}}$$

- using  $Uniform(0, 1)$   $\bar{x}$  and  $s$  should converge to

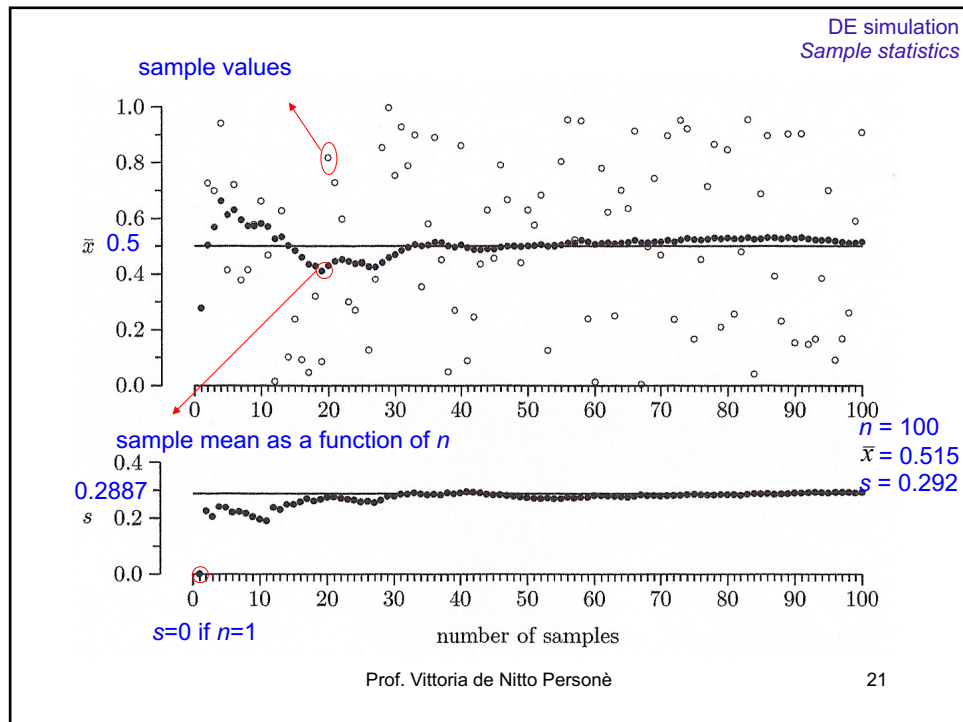
$$\frac{0+1}{2} = 0.5 \qquad \frac{1-0}{\sqrt{12}} \cong 0.2887$$

- The convergence to theoretical values is not necessarily monotone

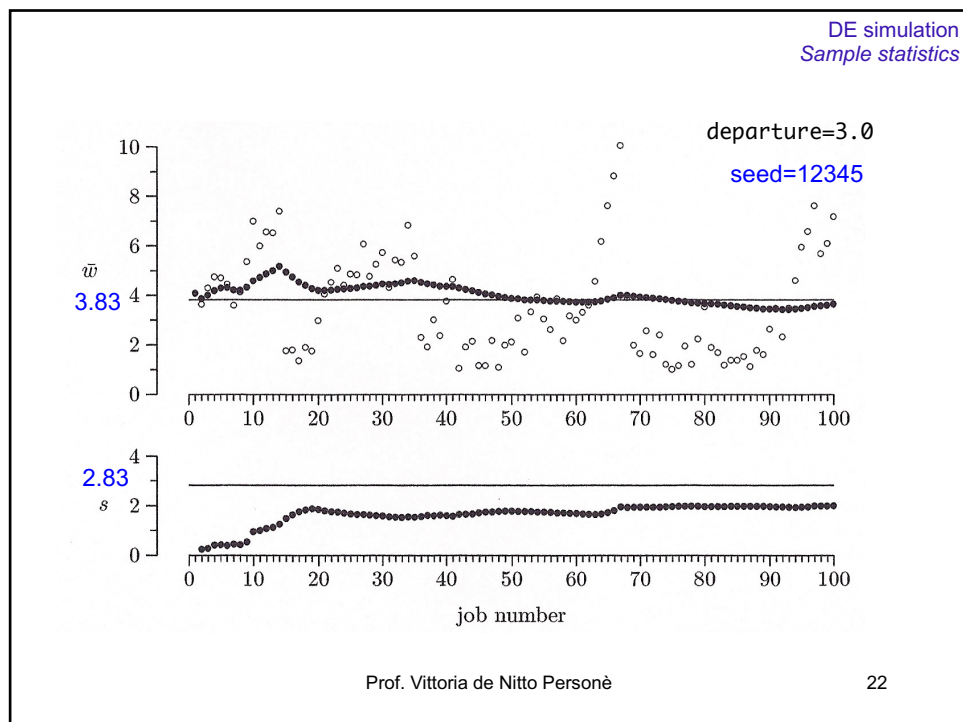
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## time-averaged sample statistics

- Let  $x(t)$  be the sample path of a stochastic process for  $0 < t < \tau$

- Sample-path mean  $\bar{x} = \frac{1}{\tau} \int_0^\tau x(t) dt$

- Sample-path variance  $s^2 = \frac{1}{\tau} \int_0^\tau (x(t) - \bar{x})^2 dt$

- Sample-path standard deviation  $s = \sqrt{s^2}$

- One-pass equation for variance 
$$s^2 = \left( \frac{1}{\tau} \int_0^\tau x^2(t) dt \right) - \bar{x}^2$$

$$s^2 = \left( \frac{1}{n} \sum_{i=1}^n x_i^2 \right) - \bar{x}^2$$

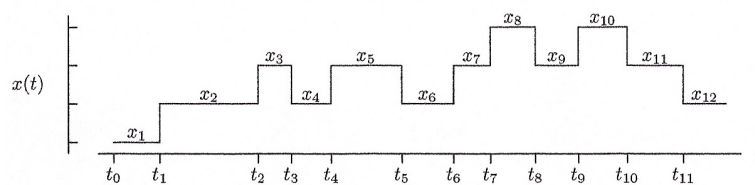
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## Computational considerations

- For DES, a sample path is *piecewise constant*
- Changes in the sample path occur at *event times*  $t_0, t_1, \dots$



- For computing statistics, integrals reduce to summations

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## Computational sample-path formulas

Consider a piecewise constant sample path

$$x(t) = \begin{cases} x_1 & t_0 < t \leq t_1 \\ x_2 & t_1 < t \leq t_2 \\ \vdots & \vdots \\ x_n & t_{n-1} < t \leq t_n \end{cases}$$

- **Sample-path mean**  $\bar{x} = \frac{1}{\tau} \int_0^\tau x(t) dt = \frac{1}{t_n} \sum_{i=1}^n x_i \delta_i$  with  $\delta_i = t_i - t_{i-1}$  inter-event time
- **Sample-path variance**

$$s^2 = \frac{1}{\tau} \int_0^\tau (x(t) - \bar{x})^2 dt = \frac{1}{t_n} \sum_{i=1}^n (x_i - \bar{x})^2 \delta_i = \left( \frac{1}{t_n} \sum_{i=1}^n x_i^2 \delta_i \right) - \bar{x}^2$$

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## Welford's sample path Algorithm

- based on the definitions

$$\bar{x}_i = \frac{1}{i} (x_1 \delta_1 + x_2 \delta_2 + \dots + x_i \delta_i)$$

$$v_i = (x_1 - \bar{x}_i)^2 \delta_1 + (x_2 - \bar{x}_i)^2 \delta_2 + \dots + (x_i - \bar{x}_i)^2 \delta_i$$

- $\bar{x}_i$  is the sample-path mean of  $x(t)$  for  $t_0 \leq t \leq t_i$
- $v_i / t_i$  is the sample-path variance
- $\bar{x}_i$  and  $v_i$  can be computed recursively ( $\bar{x}_0 = 0, v_0 = 0$ )

$$\bar{x}_i = \bar{x}_{i-1} + \frac{\delta_i}{t_i} (x_i - \bar{x}_{i-1})$$

$$v_i = v_{i-1} + \frac{\delta_i t_{i-1}}{t_i} (x_i - \bar{x}_{i-1})^2$$

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DE simulation  
Sample statistics

# Exercises

- Exercises: 4.1.7, 4.1.8

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