

# Performance Modeling of Computer Systems and Networks

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## Priority scheduling

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Analytical models  
priority scheduling

## Service classes

- (Multimedia traffic)
- Quality of Service (QoS)
- Penalties

The proper scheduling policy can improve performance of a server tremendously.  
It costs nothing to alter your scheduling policy (no money, no new hardware), so the performance gain comes for free.

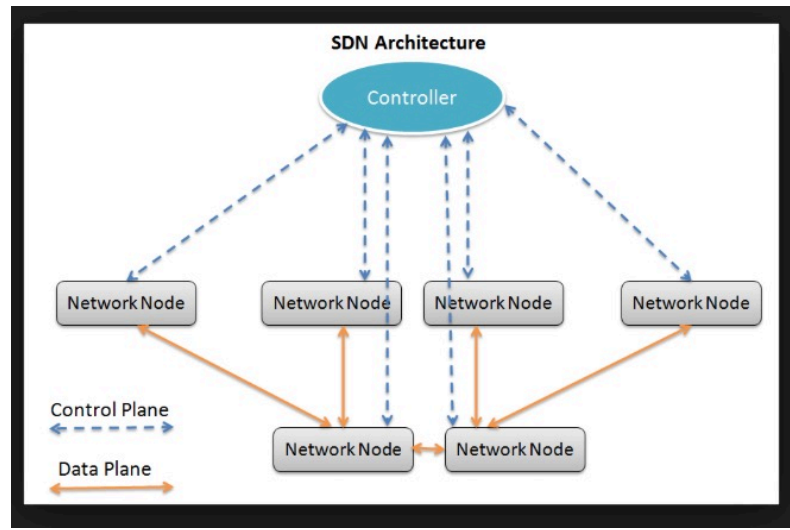
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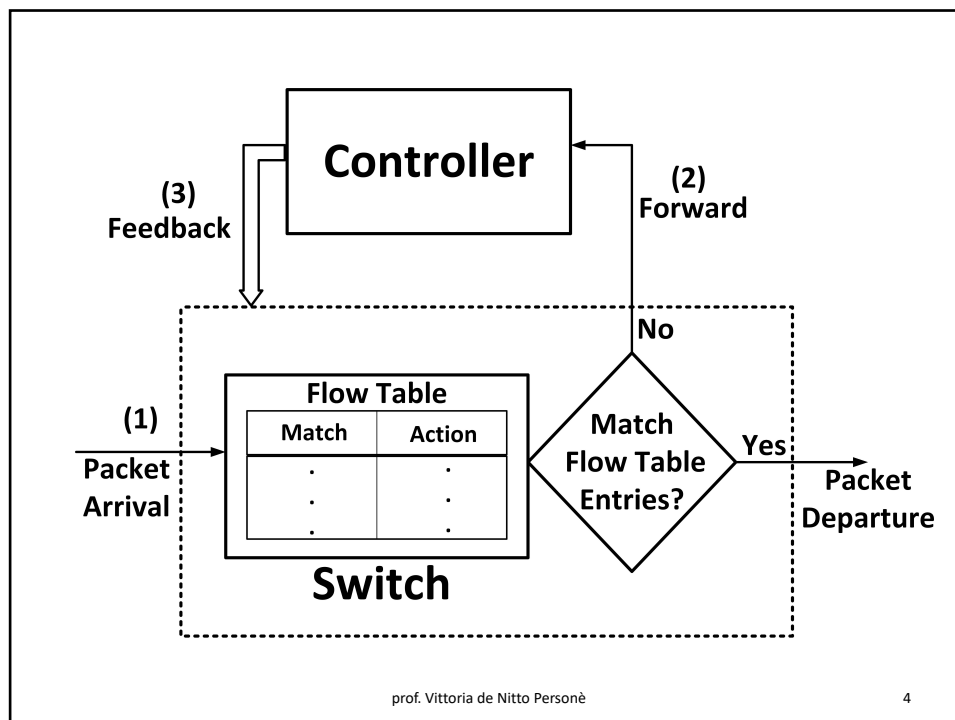
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## SDN

architettura per la realizzazione di reti di telecomunicazioni  
il piano di controllo della rete e quello di trasporto dei dati sono  
separati logicamente



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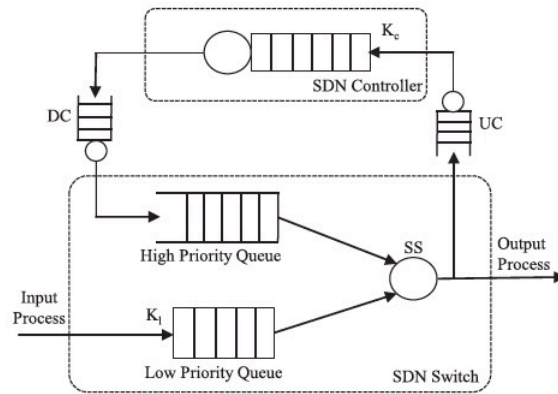


Fig. 1. The PQ-based SDN system architecture.

Miao W., Min G., Wu Y., Wang H. and Hu J., 2016. Performance Modelling and Analysis of Software-Defined Networking under Bursty Multimedia Traffic. *ACM Trans. Multimedia Comput. Commun. Appl.*, Vol. 12, No. 5s, Article 77.

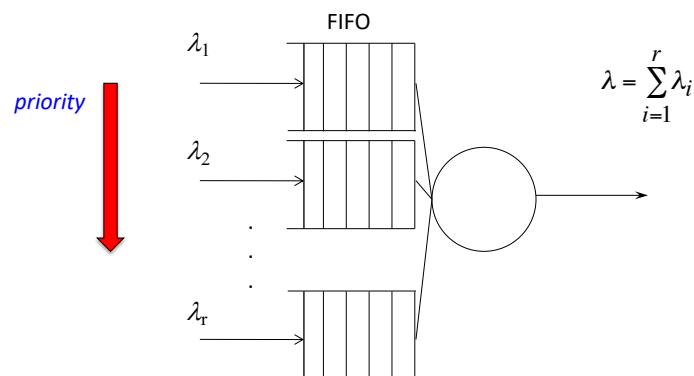
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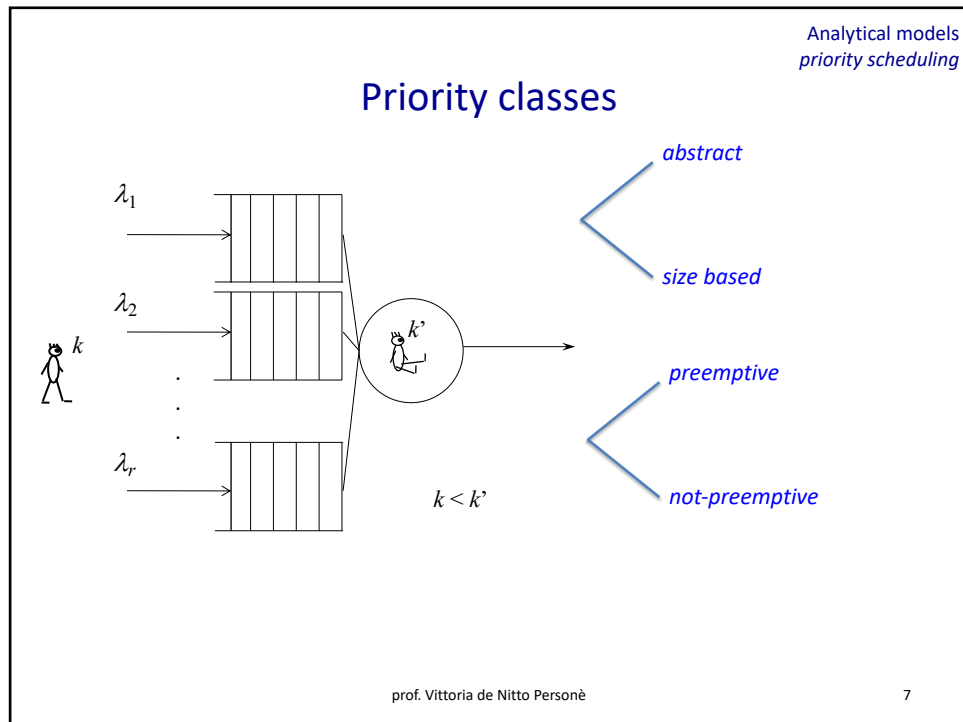
## Priority classes



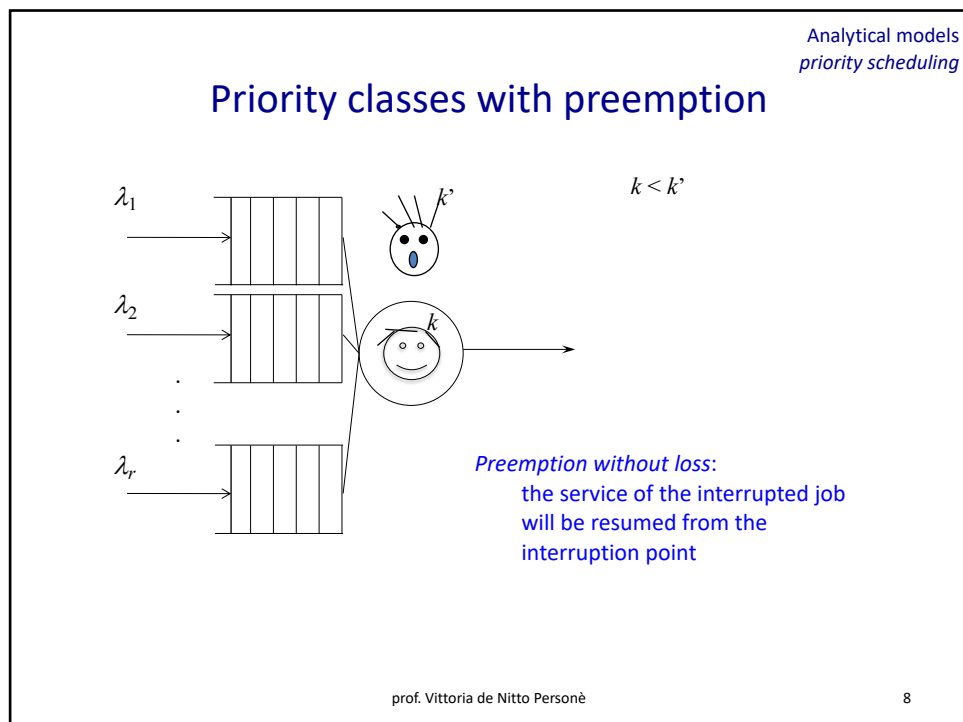
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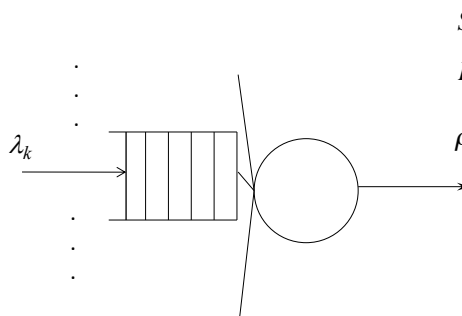
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Analytical models  
priority scheduling

## Abstract priority without preemption



$$S_k$$

$$E(S_k) = \frac{1}{\mu_k} \quad \sigma^2(S_k)$$

$$\rho_k = \lambda_k E(S_k) \quad \rho = \sum_{i=1}^r \rho_i$$

abstract

↓

$$E(S_k) = E(S) = \frac{1}{\mu}, \quad \sigma^2(S_k) = \sigma^2(S), \quad \forall k$$

$$\rho_k = \lambda_k E(S)$$

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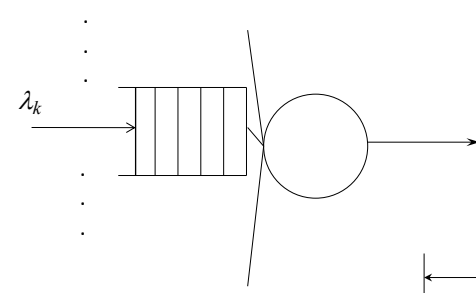
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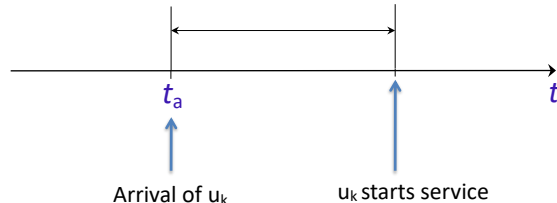
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priority scheduling

## Abstract priority without preemption

local performance measures



$E(T_{Q_k})?$

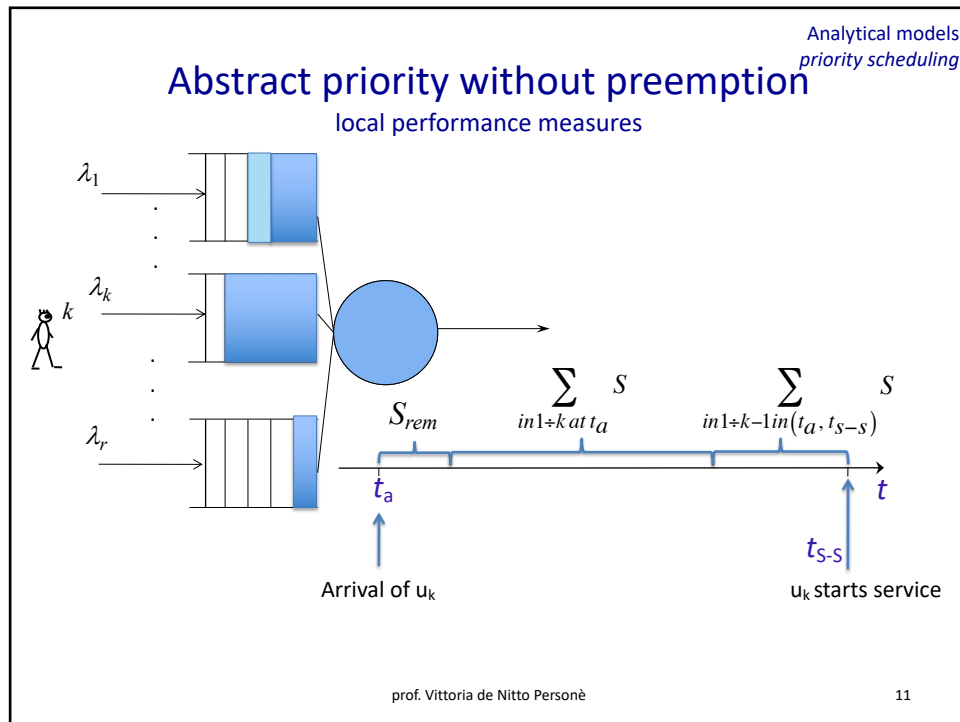


Arrival of  $u_k$        $u_k$  starts service

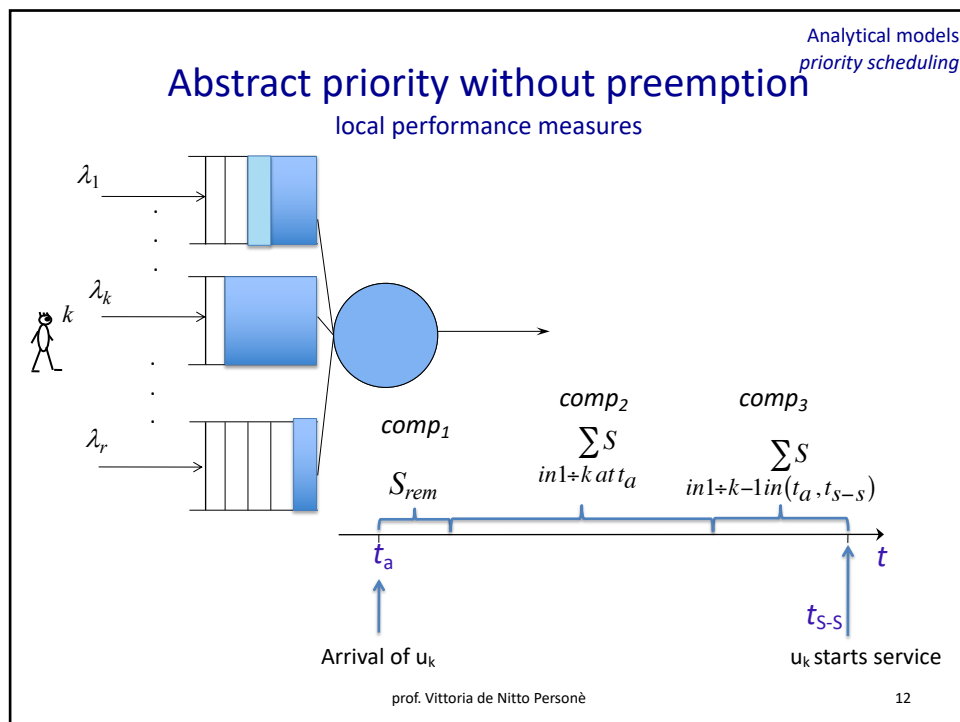
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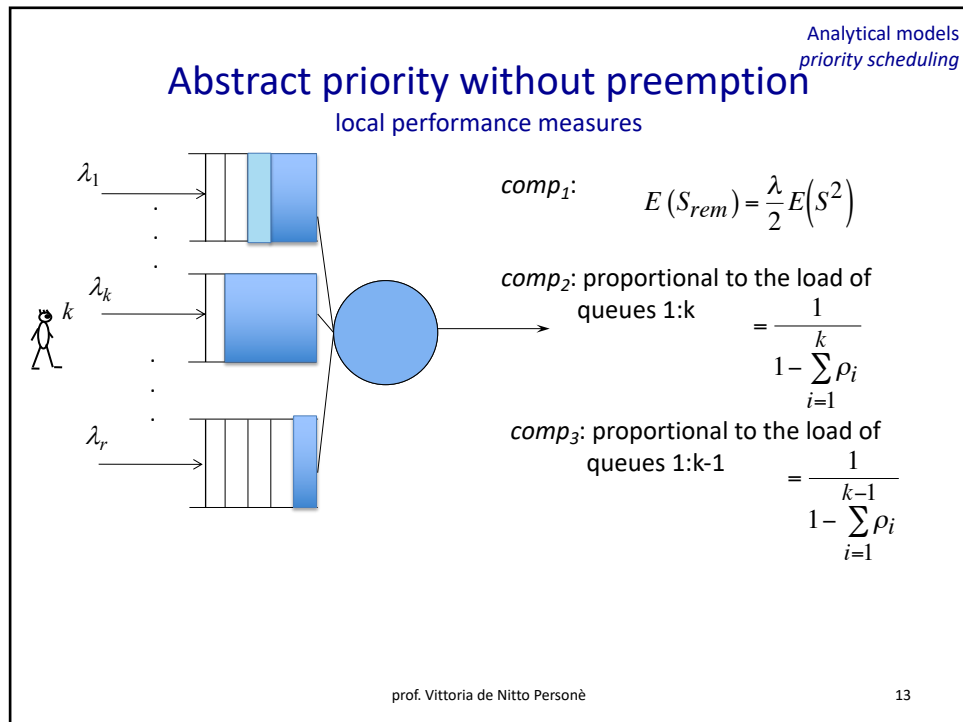
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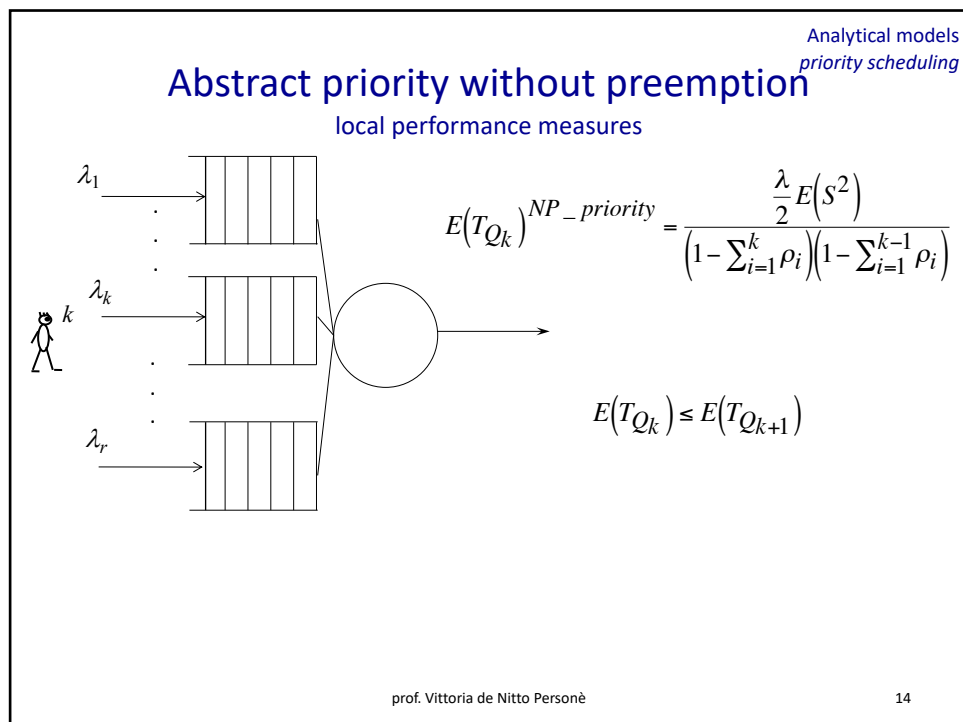
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## Abstract priority without preemption

local performance measures

$$E(T_{Q_k}) \leq E(T_{Q_{k+1}})$$

$$\frac{\frac{\lambda}{2} E(S^2)}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right)} \leq \frac{\frac{\lambda}{2} E(S^2)}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k+1} \rho_i\right)}$$

$$\frac{1}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right)} \leq \frac{1}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k+1} \rho_i\right)}$$

$$\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right) \geq \left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k+1} \rho_i\right)$$

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## Abstract priority without preemption

local performance measures

$$\cancel{\left(1 - \sum_{i=1}^k \rho_i\right)} \left(1 - \sum_{i=1}^{k-1} \rho_i\right) \geq \cancel{\left(1 - \sum_{i=1}^k \rho_i\right)} \left(1 - \sum_{i=1}^{k+1} \rho_i\right)$$

$$\cancel{1} - \sum_{i=1}^{k-1} \rho_i \geq \cancel{1} - \sum_{i=1}^{k+1} \rho_i$$

$$\sum_{i=1}^{k+1} \rho_i \geq \sum_{i=1}^{k-1} \rho_i \quad \rho_i \geq 0, \forall i$$

$$E(T_{Q_k}) \leq E(T_{Q_{k+1}})$$

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## Abstract priority without preemption

local performance measures

$$E(T_{S_k}) = E(T_{Q_k}) + E(S) \quad E(T_{S_k}) \leq E(T_{S_{k+1}})$$

$$E(N_{Q_k}) = \lambda_k E(T_{Q_k})$$

$$E(N_{S_k}) = \lambda_k E(T_{S_k}) \quad E(N_{S_k}) = E(N_{Q_k}) + \rho_k$$

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## Abstract priority without preemption

global performance measures

And the “global” performance?

$$E(T_Q)^{NP\_priority} = E(E(T_{Q_k})) = \sum_{k=1}^r p_k E(T_{Q_k})$$

$$p_k = \frac{\lambda_k}{\lambda}$$

and similarly for  $E(T_S)^{NP\_priority}$

$$E(T_S)^{NP\_priority} = E(T_Q)^{NP\_priority} + E(S)$$

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## Abstract priority without preemption

$$\lambda_k = p_k \lambda$$

$$\rho_k = \lambda_k E(S) = p_k \lambda E(S) = p_k \rho$$

## priority vs no-priority

How are the performance improved in respect of a simple abstract scheduling not-considering the priority classes?

$$E(T_{Q_k})^{NP\_priority} = \frac{\frac{\lambda}{2} E(S^2)}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right)} \quad ? \quad E(T_Q)^{KP} = \frac{\frac{\lambda}{2} E(S^2)}{1 - \rho}$$


The highest priority class:

$$E(T_{Q_1})^{NP\_priority} = \frac{\frac{\lambda}{2} E(S^2)}{(1 - \rho_1)} \leq E(T_Q)^{KP} \quad \text{😊}^1$$

## priority vs no-priority

How are the performance improved in respect of a simple abstract scheduling not-considering the priority classes?

The lowest priority class:

$$E(T_{Q_r})^{NP\_priority} = \frac{\frac{\lambda}{2} E(S^2)}{(1-\rho)(1-\sum_{i=1}^{r-1} \rho_i)} \geq E(T_Q)^{KP}$$


And what about the “global” performance?

$$E(T_Q)^{NP\_priority} = E(T_Q)^{KP}$$

↓

$$E(T_S)^{NP\_priority} = E(T_S)^{KP}$$

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## priority vs no-priority

$$E(T_Q)^{NP\_priority} = E(E(T_{Q_k})) = \sum_{k=1}^r p_k E(T_{Q_k}) = E(T_Q)^{KP}$$

$r=2$

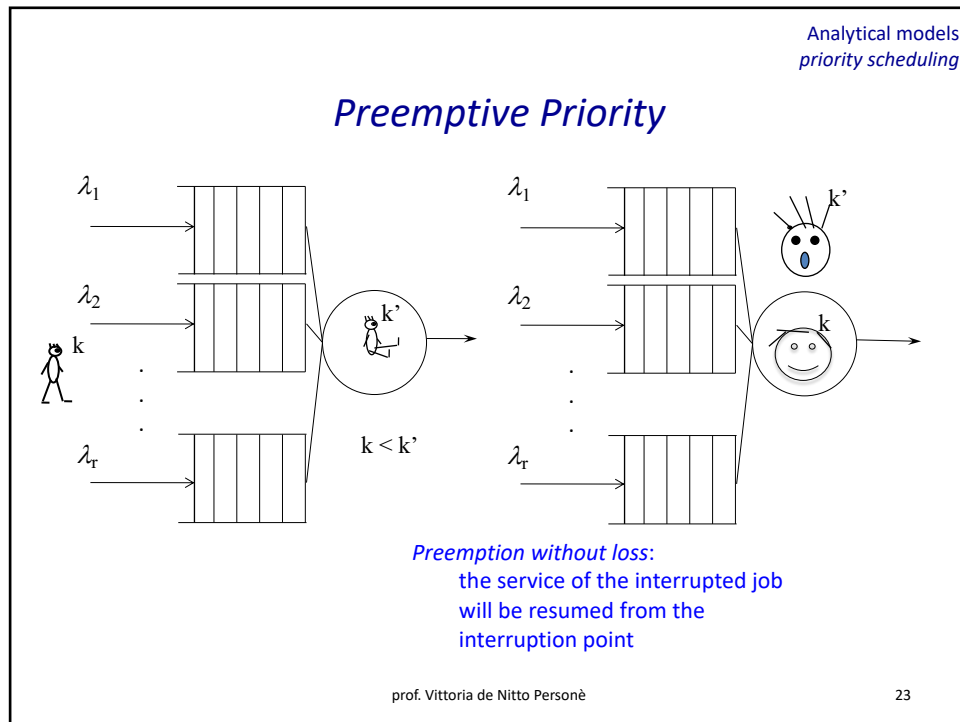
$$E(T_Q) = p_1 E(T_{Q_1}) + p_2 E(T_{Q_2}) = p_1 \frac{\frac{\lambda}{2} E(S^2)}{(1-\rho_1)} + p_2 \frac{\frac{\lambda}{2} E(S^2)}{(1-\rho)(1-\rho_1)}$$

$$= \frac{\lambda}{2} E(S^2) \left[ \frac{p_1}{(1-\rho_1)} + \frac{p_2}{(1-\rho)(1-\rho_1)} \right] = \frac{\lambda}{2} E(S^2) \frac{p_1(1-\rho) + p_2}{(1-\rho)(1-\rho_1)} = \frac{\frac{\lambda}{2} E(S^2)}{1-\rho}$$

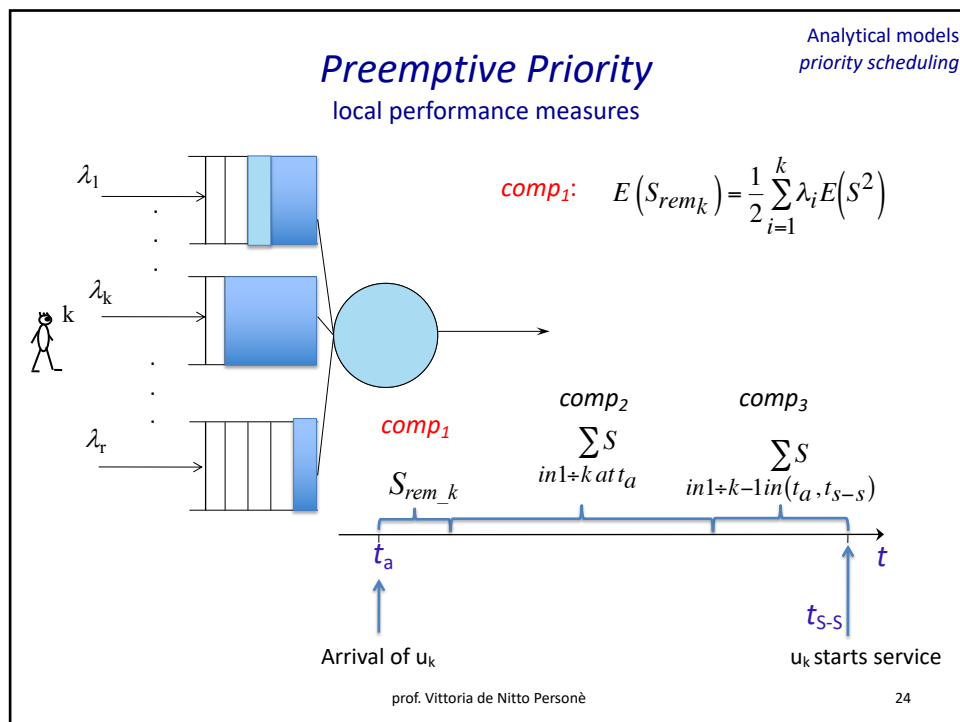
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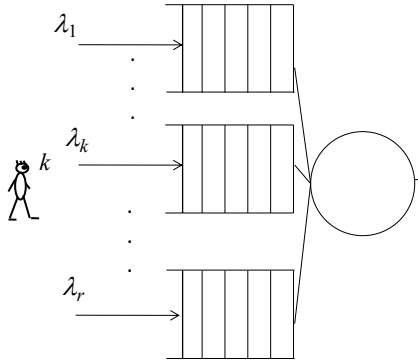
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Analytical models  
priority scheduling

### Preemptive Priority



$$E(T_{Q_k})^{P\_priority} = \frac{\frac{1}{2} \sum_{i=1}^k \lambda_i E(S^2)}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right)}$$

$$E(T_{Q_k})^{P\_priority} \leq E(T_{Q_{k+1}})^{P\_priority}$$

$$E(T_{Q_k})^{P\_priority} \leq E(T_{Q_k})^{NP\_priority}$$

$$E(T_Q)^{P\_priority} \leq E(T_Q)^{NP\_priority} = E(T_Q)^{KP}$$

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Analytical models  
priority scheduling

### Preemptive Priority

$$\frac{\frac{1}{2} \sum_{i=1}^k \lambda_i E(S^2)}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right)} \leq \frac{\frac{1}{2} \sum_{i=1}^{k+1} \lambda_i E(S^2)}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k+1} \rho_i\right)}$$

$$\frac{\sum_{i=1}^k \lambda_i}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right)} \leq \frac{\sum_{i=1}^{k+1} \lambda_i}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k+1} \rho_i\right)}$$

$$\frac{\sum_{i=1}^k \lambda_i}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right)} \leq \frac{\sum_{i=1}^{k+1} \lambda_i}{\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right)}$$

$$\left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k-1} \rho_i\right) \geq \left(1 - \sum_{i=1}^k \rho_i\right) \left(1 - \sum_{i=1}^{k+1} \rho_i\right)$$

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## Preemptive Priority

$$E(T_Q)^{X\_priority} = E(E(T_{Q_k})) = \sum_{k=1}^r p_k E(T_{Q_k})$$

$$= p_1 E(T_{Q_1}) + p_2 E(T_{Q_2}) + \dots + p_r E(T_{Q_r})$$

$$E(T_Q)^{NP\_priority} = p_1 E(T_{Q_1}) + p_2 E(T_{Q_2}) + \dots + p_r E(T_{Q_r})$$

$$E(T_Q)^{P\_priority} = p_1 E(T_{Q_1}) + p_2 E(T_{Q_2}) + \dots + p_r E(T_{Q_r})$$

$$E(T_Q)^{P\_priority} \leq E(T_Q)^{NP\_priority} = E(T_Q)^{KP}$$

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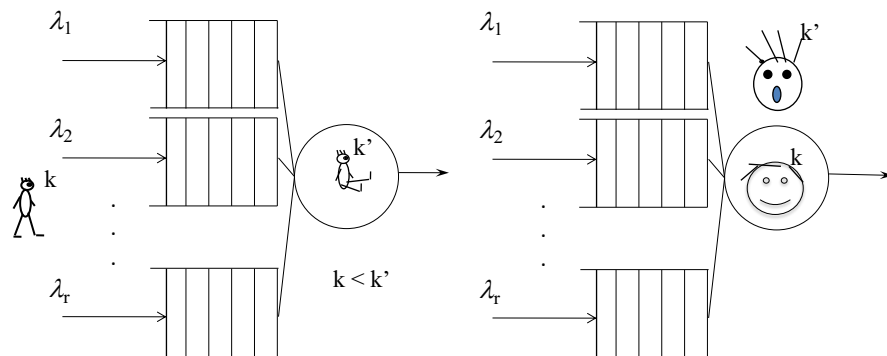
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## Preemptive Priority

Analytical models  
priority scheduling

Due to preemption, the service time of a job of class  $k$  may increase for the arrivals of higher priority classes



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## Preemptive Priority

Due to preemption, the service time of a job of class  $k$  may increase for the arrivals of higher priority classes

**Virtual service time**  $E(S_{virt\_k})$

$$E(S_{virt\_k}) = \frac{E(S)}{1 - \sum_{i=1}^{k-1} \rho_i}$$

$$E(T_{S_k})^{P\_priority} = E(T_{Q_k})^{P\_priority} + E(S_{virt\_k})$$

$$E(T_{S_k})^{NP\_priority} = E(T_{Q_k})^{NP\_priority} + E(S)$$

?

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## Preemptive Priority global response time

And what about the “global” performance?

$$E(T_{Q_k})^{P\_priority} + E(S_{virt\_k})$$

$$E(T_S)^{P\_priority} = E(E(T_{S_k})) = \sum_{k=1}^r p_k E(T_{S_k})$$

$$\begin{aligned} E(T_S)^{P\_priority} &= \sum_{k=1}^r p_k [E(T_{Q_k}) + E(S_{virt\_k})] \\ &= \sum_{k=1}^r p_k E(T_{Q_k}) + \sum_{k=1}^r p_k E(S_{virt\_k}) \\ &= E(T_Q)^{P\_priority} + \sum_{k=1}^r p_k E(S_{virt\_k}) \end{aligned}$$

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## preemption vs no-preemption

$$E(T_S)^{P\text{-priority}} = E(T_Q)^{P\text{-priority}} + \sum_{k=1}^r p_k E(S_{\text{virt}_k})$$

$\wedge$   $\vee$

?

$$E(T_S)^{NP\text{-priority}} = E(T_Q)^{NP\text{-priority}} + E(S) = E(T_S)^{KP}$$

In general

$$E(T_S)^{P\text{-priority}} \neq E(T_S)^{KP}$$

For exponential service time

$$E(T_S)^{P\text{-priority}} = E(T_S)^{KP} \quad !!!$$

## preemption vs no-preemption

 $r=2$ 

$$\begin{aligned}
 E(T_S)^{P\text{-priority}} &= p_1 E(T_{S1}) + p_2 E(T_{S2}) \\
 &= p_1 \left[ \frac{\frac{\lambda_1}{2} E(S^2)}{(1-\rho_1)} + E(S) \right] + p_2 \left[ \frac{\frac{\lambda}{2} E(S^2)}{(1-\rho)(1-\rho_1)} + \frac{E(S)}{1-\rho_1} \right]
 \end{aligned}$$

from the expo assumption

$$\begin{aligned}
 &= p_1 \left[ \frac{\rho_1 E(S)}{(1-\rho_1)} + E(S) \right] + p_2 \left[ \frac{\rho E(S)}{(1-\rho)(1-\rho_1)} + \frac{E(S)}{1-\rho_1} \right] \\
 &= E(S) \left\{ p_1 \left[ \frac{\rho_1 + 1 - \rho_1}{(1-\rho_1)} \right] + p_2 \left[ \frac{\rho + (1-\rho)}{(1-\rho)(1-\rho_1)} \right] \right\}
 \end{aligned}$$



## preemption vs no-preemption

$$r=2$$

$$\begin{aligned} E(T_S)^{P\text{-priority}} &= p_1 E(T_{S_1}) + p_2 E(T_{S_2}) \\ &= E(S) \left[ \frac{p_1}{(1-\rho_1)} + \frac{p_2}{(1-\rho)(1-\rho_1)} \right] \\ &= E(S) \frac{p_1(1-\rho) + p_2}{(1-\rho)(1-\rho_1)} = \frac{E(S)}{1-\rho} = E(T_S)^{KP} \end{aligned}$$