

Homework -1

1. Consider the discrete-time system with input $x(k)$ and output $y(k)$. The system is described by the difference equation $y(k+1) = 2y(k) + x(k)$. Find the transfer function $\frac{Y(z)}{X(z)}$ and the poles and zeros of the system.

2.2-2

$$\frac{Y(z)}{X(z)} = \frac{(T/2)(z+1)}{z-1}$$

Solution:

$$(a) y(k+1) = y(k) + T \frac{x(k) + x(k+1)}{2}$$

$$(b) zY(z) = Y(z) + \frac{T}{2}[X(z) + zX(z)] \Rightarrow Y(z) = \frac{T}{2} \frac{z+1}{z-1} X(z)$$

2.4-1

Solution:

$$(a) \mathcal{Z}[e(t-2T)u(t-2T)] = \frac{(z^3 - 2z)z^{-2}}{z^4 - 0.9z^2 + 0.8}$$

$$(b) e(0) = 0, e(1) = 1$$

$$\therefore \mathcal{Z}[e(t+T)u(t)] = z[E(z) - e(0) - e(1)z^{-1}]$$

$$= z \left[\frac{z^3 - 2z}{z^4 - 0.9z^2 + 0.8} - \frac{1}{z} \right] = \frac{-1.1z^2 + 0.8}{z^4 - 0.9z^2 + 0.8}$$

$$(c) \mathcal{Z}[e(t-T)u(t-2T)] = e(T)z^{-2} + e(2T)z^{-3} + \dots$$

$$= z^{-1}[E(z) - e(0)] = z^{-1}E(z), \text{ since } e(0) = 0$$

$$= \frac{z^2 - z}{z^4 - 0.9z^2 + 0.8}$$

2.6-2. Given the difference equation

$$y(k+2) - \frac{3}{4}y(k+1) + \frac{1}{8}y(k) = e(k)$$

where $y(0) = y(1) = 0$, $e(0) = 0$, and $e(k) = 1$, $k = 1, 2, \dots$

(a) Solve for $y(k)$ as a function of k , and give the numerical values of $y(k)$, $0 \leq k \leq 4$.

(b) Solve the difference equation directly for $y(k)$, $0 \leq k \leq 4$, to verify the results of part (a).

(c) Repeat parts (a) and (b) for $e(k) = 0$ for all k , and $y(0) = 1$, $y(1) = -2$.

Solution:

$$(a) E(z) = z[u(k-1)] = z^{-1} \left[\frac{z}{z-1} \right] = \frac{1}{z-1}$$

$$\left[z^2 - \frac{3}{4}z + \frac{1}{8} \right] Y(z) = E(z)$$

$$\frac{Y(z)}{z} = \frac{1}{z \left(z - \frac{1}{2} \right) \left(z - \frac{1}{4} \right)} \cdot \frac{1}{z-1} = \frac{-8}{z} + \frac{8/3}{z-1} + \frac{-16}{z-1/2} + \frac{64/3}{z-1/4}$$

$$\therefore y(k) = -8\delta(0) + \frac{8}{3} - 16 \left(\frac{1}{2} \right)^k + \frac{64}{3} \left(\frac{1}{4} \right)^k$$

$$\therefore y(0) = 0; y(1) = 0; y(2) = 0; y(3) = 1; y(4) = \frac{7}{4}$$

$$(b) y(k+2) = e(k) + \frac{3}{4}y(k+1) - \frac{1}{8}y(k)$$

$$y(2) = 0 + \frac{3}{4}(0) - \frac{1}{8}(0) = 0$$

$$y(3) = 1 + \frac{3}{4}(0) - \frac{1}{8}(0) = 1$$

$$y(4) = 1 + \frac{3}{4}(1) - \frac{1}{8}(0) = 7/4$$

$$(c) \quad (a) \quad y(k+2) - \frac{3}{4}y(k+1) + \frac{1}{8}y(k) = 0$$

$$\therefore z^2[Y(z) - y(0) - y(1)z^{-1}] - \frac{3}{4}z[Y(z) - y(0)] + \frac{1}{8}Y(z) = 0$$

$$\therefore \left[z^2 - \frac{3}{4}z + \frac{1}{8} \right] Y(z) = z^2 - 2z - \frac{3}{4}z$$

$$\therefore Y(z) = z \left[\frac{z - 1/4}{(z - 1/2)(z - 1/4)} \right] = z \left[\frac{-9}{z - 1/2} + \frac{10}{z - 1/4} \right] \Rightarrow y(k) = -9 \left(\frac{1}{2} \right)^k + 10 \left(\frac{1}{4} \right)^k$$

$$y(0) = 1, \quad y(1) = -2, \quad y(2) = -13/8, \quad y(3) = -31/32, \quad y(4) = -67/128$$

$$(b) \quad y(k+2) = \frac{3}{4}y(k+1) - \frac{1}{8}y(k)$$

$$y(2) = \frac{3}{4}(-2) - \frac{1}{8}(1) = -13/8$$

$$y(3) = \frac{3}{4} \left(-\frac{13}{8} \right) - \frac{1}{8}(-2) = -31/32$$

$$y(4) = \frac{3}{4} \left(-\frac{31}{32} \right) - \frac{1}{8} \left(-\frac{13}{8} \right) = -67/128$$

2.6-3. Given the difference equation

$$x(k) - x(k-1) + x(k-2) = e(k)$$

where $e(k) = 1$ for $k \geq 0$.

- (a) Solve for $x(k)$ as a function of k , using the z -transform. Give the values of $x(0), x(1)$, and $x(2)$.

- (b) Verify the values $x(0), x(1)$, and $x(2)$, using the power-series method.

- (c) Verify the values $x(0), x(1)$, and $x(2)$ by solving the difference equation directly.

- (d) Will the final-value property give the correct value for $x(\infty)$?

Solution:

$$(a) [1 - z^{-1} + z^{-2}]X(z) = E(z) = \frac{z}{z-1}$$

$$X(z) = \frac{z^3}{(z-1)(z^2-z+1)}, \quad \text{poles: } z = \frac{1}{2} \pm j\frac{\sqrt{3}}{2} = 1 \angle \pm 60^\circ$$

$$\frac{X(z)}{z} = \frac{1}{z-1} + \frac{k_1}{z-p_1} + \frac{k_1^*}{z-p_1^*} \quad \text{with } p = 1 \angle 60^\circ$$

$$k_1 = \left. \frac{z^2}{(z-1)(z-1 \angle -60^\circ)} \right|_{z=1 \angle 60^\circ} = \frac{1 \angle 120^\circ}{(.5 + j.866 - 1)(.5 + j.866 - .5 + j.866)}$$

$$= \frac{1 \angle 120^\circ}{1 \angle 120^\circ [j2(0.866)]} = 0.5774 \angle -90^\circ$$

$$\therefore aT = \ln(|p_1|) = 0; \quad bT = \arg p_1 = \frac{\pi}{3}$$

$$A = 2|k_1| = 1.155; \quad \theta = \arg k_1 = -90^\circ$$

$$\therefore x(k) = 1 + 1.155 \cos\left(\frac{\pi}{3}k - 90^\circ\right) = 1 + 1.155 \sin\left(\frac{\pi}{3}k\right)$$

$$x(0) = 1, \quad x(1) = 2, \quad x(2) = 2$$

$$(b) \quad \begin{array}{r} 1 + 2z^{-1} + 2z^{-2} + \dots \\ z^3 - 2z^2 + 2z - 1 \end{array} \quad \begin{array}{l} \therefore x(0) = 1 \\ x(1) = 2 \\ x(2) = 2 \end{array}$$

$$\begin{array}{r} z^3 \\ z^3 - 2z^2 + 2z - 1 \\ \hline 2z^2 - 2z + 1 \\ 2z^2 - 4z + 4 - 2z^{-1} \\ \hline 2z + \dots \end{array}$$

$$(c) \quad x(k) = 1 + x(k-1) - x(k-2)$$

$$x(0) = 1 + 0 - 0 = 1$$

$$x(1) = 1 + 1 - 0 = 2$$

$$x(2) = 1 + 2 - 1 = 2$$

(d) No, 3 poles for $X(z)$ on the unit circle.

2.9-1. Find two different state-variable formulations that model the system whose difference equation is given by:

$$(a) y(k+2) + 6y(k+1) + 5y(k) = 2e(k)$$

$$(b) y(k+2) + 6y(k+1) + 5y(k) = e(k+1) + 2e(k)$$

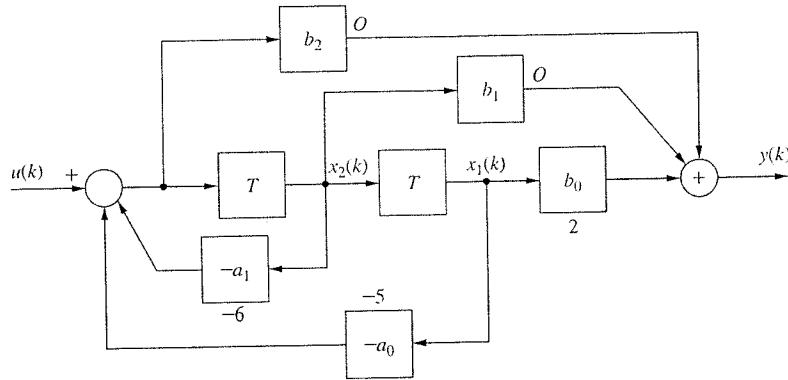
$$(c) y(k+2) + 6y(k+1) + 5y(k) = 3e(k+2) + e(k+1) + 2e(k)$$

Solution:

$$(a) \frac{Y(z)}{U(z)} = \frac{2}{z^2 + 6z + 5}$$

(1) control canonical:

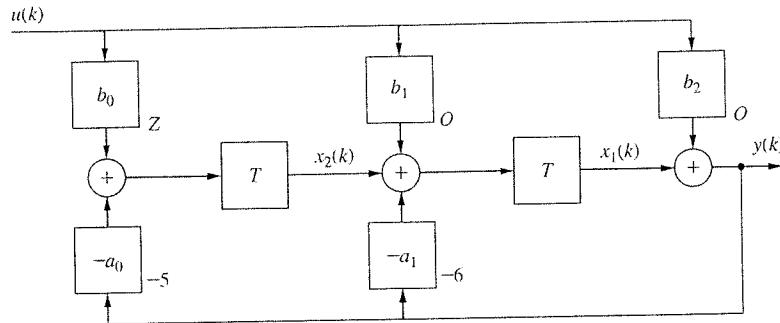
Given the system $\dot{x}(k+1) = Ax(k) + Bu(k)$ and output $y(k) = Cx(k)$, where $A = \begin{bmatrix} 0 & 1 \\ -5 & -6 \end{bmatrix}$, $B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, $C = \begin{bmatrix} 2 & 0 \end{bmatrix}$. The state-space representation is $\dot{x}(k+1) = Ax(k) + Bu(k)$.



$$\mathbf{x}(k+1) = \begin{bmatrix} 0 & 1 \\ -5 & -6 \end{bmatrix} \mathbf{x}(k) + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u(k)$$

$$y(k) = [2 \ 0] \mathbf{x}(k)$$

(2) observer canonical:



$$\mathbf{x}(k+1) = \begin{bmatrix} -6 & 1 \\ -5 & 0 \end{bmatrix} \mathbf{x}(k) + \begin{bmatrix} 0 \\ 2 \end{bmatrix} u(k)$$

$$y(k) = [1 \ 0] \mathbf{x}(k)$$

(b) $\frac{Y(z)}{U(z)} = \frac{z+2}{z^2+6z+5}$ (1) control canonical: $\mathbf{x}(k+1) = \text{same as (a)}$
 $y(k) = [2 \ 1] \mathbf{x}(k)$

(2) observer canonical:

$$\mathbf{x}(k+1) = \begin{bmatrix} -6 & 1 \\ -5 & 0 \end{bmatrix} \mathbf{x}(k) + \begin{bmatrix} 1 \\ 2 \end{bmatrix} u(k)$$

$$y(k) = [1 \ 0] \mathbf{x}(k)$$

(c) $\frac{Y(z)}{U(z)} = \frac{3z^2+z+2}{z^2+6z+5}$ (1) control canonical: $\mathbf{x}(k+1) = \text{same as (a)}$
 $y(k) = [-13 \ -17] \mathbf{x}(k) + 3u(k)$

(2) observer canonical:

$$\mathbf{x}(k+1) = \begin{bmatrix} -6 & 1 \\ -5 & 0 \end{bmatrix} \mathbf{x}(k) + \begin{bmatrix} 1 \\ 2 \end{bmatrix} u(k)$$

$$y(k) = [1 \ 0] \mathbf{x}(k) + 3u(k)$$

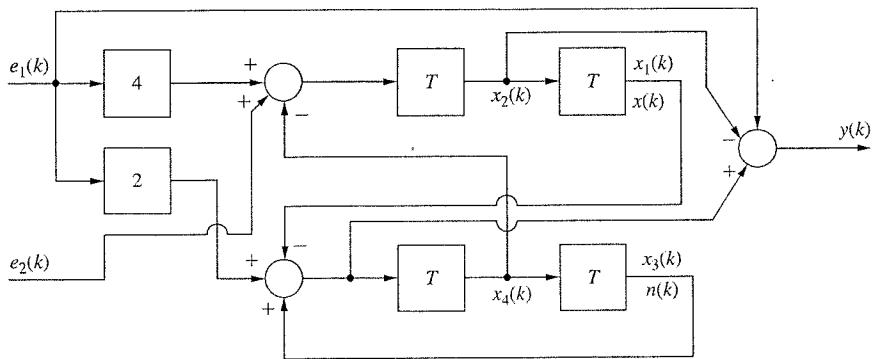
2.10-1. Find a state-variable formulation for the system described by the coupled second-order difference equations given. The system output is $y(k)$, and $e_1(k)$ and $e_2(k)$ are the system inputs. Hint:
Draw a simulation diagram first.

$$x(k+2) + v(k+1) = 4e_1(k) + e_2(k)$$

$$v(k+2) - v(k) + x(k) = 2e_1(k)$$

$$y(k) = v(k+2) - x(k+1) + e_1(k)$$

Solution:



$$\mathbf{x}(k+1) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 1 & 0 \end{bmatrix} \mathbf{x}(k) + \begin{bmatrix} 0 & 0 \\ 4 & 1 \\ 0 & 0 \\ 2 & 0 \end{bmatrix} e(k)$$

$$y(k) = x_4(k+1) - x_2(k) + e_1(k) = -x_1(k) + x_3(k) - x_2(k) + e_1(k)$$

$$\therefore y(k) = [-1 \quad -1 \quad 1 \quad 0] \mathbf{x}(k) + [1 \quad 0] e(k)$$