

Homework -1

This work should be the student's original solution to the problem. It should not be a copy of any standardizing document and it should not be published or used for any other purpose. It should be clearly marked as the student's work and it should be clearly marked as the student's work.

2.2-2

$$\frac{Y(z)}{X(z)} = \frac{(T/2)(z+1)}{z-1}$$

Solution:

$$(a) \ y(k+1) = y(k) + T \frac{x(k) + x(k+1)}{2}$$

$$(b) \ zY(z) = Y(z) + \frac{T}{2} [X(z) + zX(z)] \Rightarrow Y(z) = \frac{T}{2} \frac{z+1}{z-1} X(z)$$

2.4-1

Solution:

$$(a) \mathcal{Z}[e(t-2T)u(t-2T)] = \frac{(z^3 - 2z)z^{-2}}{z^4 - 0.9z^2 + 0.8}$$

$$(b) e(0) = 0, e(1) = 1$$

$$\begin{aligned} \therefore \mathcal{Z}[e(t+T)u(t)] &= z[E(z) - e(0) - e(1)z^{-1}] \\ &= z \left[\frac{z^3 - 2z}{z^4 - 0.9z^2 + 0.8} - \frac{1}{z} \right] = \frac{-1.1z^2 + 0.8}{z^4 - 0.9z^2 + 0.8} \end{aligned}$$

$$\begin{aligned} (c) \mathcal{Z}[e(t-T)u(t-2T)] &= e(T)z^{-2} + e(2T)z^{-3} + \dots \\ &= z^{-1}[E(z) - e(0)] = z^{-1}E(z), \text{ since } e(0) = 0 \\ &= \frac{z^2 - z}{z^4 - 0.9z^2 + 0.8} \end{aligned}$$

2.6-2. Given the difference equation

$$y(k+2) - \frac{3}{4}y(k+1) + \frac{1}{8}y(k) = e(k)$$

where $y(0) = y(1) = 0$, $e(0) = 0$, and $e(k) = 1$, $k = 1, 2, \dots$

(a) Solve for $y(k)$ as a function of k , and give the numerical values of $y(k)$, $0 \leq k \leq 4$.

(b) Solve the difference equation directly for $y(k)$, $0 \leq k \leq 4$, to verify the results of part (a).

(c) Repeat parts (a) and (b) for $e(k) = 0$ for all k , and $y(0) = 1$, $y(1) = -2$.

Solution:

$$(a) \quad E(z) = \mathcal{Z}[u(k-1)] = z^{-1} \left[\frac{z}{z-1} \right] = \frac{1}{z-1}$$

$$\left[z^2 - \frac{3}{4}z + \frac{1}{8} \right] Y(z) = E(z)$$

$$\frac{Y(z)}{z} = \frac{1}{z \left(z - \frac{1}{2} \right) \left(z - \frac{1}{4} \right)} \cdot \frac{1}{z-1} = \frac{-8}{z} + \frac{8/3}{z-1} + \frac{-16}{z-1/2} + \frac{64/3}{z-1/4}$$

$$\therefore y(k) = -8\delta(0) + \frac{8}{3} - 16 \left(\frac{1}{2} \right)^k + \frac{64}{3} \left(\frac{1}{4} \right)^k$$

$$\therefore y(0) = 0; \quad y(1) = 0; \quad y(2) = 0; \quad y(3) = 1; \quad y(4) = \frac{7}{4}$$

$$(b) \quad y(k+2) = e(k) + \frac{3}{4}y(k+1) - \frac{1}{8}y(k)$$

$$y(2) = 0 + \frac{3}{4}(0) - \frac{1}{8}(0) = 0$$

$$y(3) = 1 + \frac{3}{4}(0) - \frac{1}{8}(0) = 1$$

$$y(4) = 1 + \frac{3}{4}(1) - \frac{1}{8}(0) = 7/4$$

$$(c) \quad (a) \quad y(k+2) - \frac{3}{4}y(k+1) + \frac{1}{8}y(k) = 0$$

$$\therefore z^2[Y(z) - y(0) - y(1)z^{-1}] - \frac{3}{4}z[Y(z) - y(0)] + \frac{1}{8}Y(z) = 0$$

$$\therefore \left[z^2 - \frac{3}{4}z + \frac{1}{8} \right] Y(z) = z^2 - 2z - \frac{3}{4}z$$

$$\therefore Y(z) = z \left[\frac{z - 1/4}{\left(z - 1/2\right)\left(z - 1/4\right)} \right] = z \left[\frac{-9}{z - 1/2} + \frac{10}{z - 1/4} \right] \Rightarrow y(k) = -9\left(\frac{1}{2}\right)^k + 10\left(\frac{1}{4}\right)^k$$

$$y(0) = 1, \quad y(1) = -2, \quad y(2) = -13/8, \quad y(3) = -31/32, \quad y(4) = -67/128$$

$$(b) \quad y(k+2) = \frac{3}{4}y(k+1) - \frac{1}{8}y(k)$$

$$y(2) = \frac{3}{4}(-2) - \frac{1}{8}(1) = -13/8$$

$$y(3) = \frac{3}{4}\left(-\frac{13}{8}\right) - \frac{1}{8}(-2) = -31/32$$

$$y(4) = \frac{3}{4}\left(-\frac{31}{32}\right) - \frac{1}{8}\left(-\frac{13}{8}\right) = -\frac{67}{128}$$

2.6-3. Given the difference equation

$$x(k) - x(k-1) + x(k-2) = e(k)$$

where $e(k) = 1$ for $k \geq 0$.

(a) Solve for $x(k)$ as a function of k , using the z -transform. Give the values of $x(0)$, $x(1)$, and $x(2)$.

(b) Verify the values $x(0)$, $x(1)$, and $x(2)$, using the power-series method.

(c) Verify the values $x(0)$, $x(1)$, and $x(2)$ by solving the difference equation directly.

(d) Will the final-value property give the correct value for $x(\infty)$?

Solution:

$$(a) [1 - z^{-1} + z^{-2}]X(z) = E(z) = \frac{z}{z-1}$$

$$X(z) = \frac{z^3}{(z-1)(z^2 - z + 1)}, \quad \text{poles: } z = \frac{1}{2} \pm j\frac{\sqrt{3}}{2} = 1 \angle \pm 60^\circ$$

$$\frac{X(z)}{z} = \frac{1}{z-1} + \frac{k_1}{z-p_1} + \frac{k_1^*}{z-p_1^*} \quad \text{with } p = 1 \angle 60^\circ$$

$$k_1 = \left. \frac{z^2}{(z-1)(z-1 \angle -60^\circ)} \right|_{z=1 \angle 60^\circ} = \frac{1 \angle 120^\circ}{(.5 + j.866 - 1)(.5 + j.866 - .5 + j.866)}$$

$$= \frac{1 \angle 120^\circ}{1 \angle 120^\circ [j2(0.866)]} = 0.5774 \angle -90^\circ$$

$$\therefore aT = \ln(|p_1|) = 0; \quad bT = \arg p_1 = \frac{\pi}{3}$$

$$A = 2|k_1| = 1.155; \quad \theta = \arg k_1 = -90^\circ$$

$$\therefore x(k) = 1 + 1.155 \cos\left(\frac{\pi}{3}k - 90^\circ\right) = 1 + 1.155 \sin\left(\frac{\pi}{3}k\right)$$

$$x(0) = 1, \quad x(1) = 2, \quad x(2) = 2$$

$$(b) \quad \begin{array}{l} z^3 - 2z^2 + 2z - 1 \overline{\left) \begin{array}{l} 1 + 2z^{-1} + 2z^{-2} + \dots \\ z^3 \\ \hline z^3 - 2z^2 + 2z - 1 \\ \hline 2z^2 - 2z + 1 \\ \hline 2z^2 - 4z + 4 - 2z^{-1} \\ \hline 2z + \dots \end{array} \right.} \end{array} \quad \begin{array}{l} \therefore x(0) = 1 \\ x(1) = 2 \\ x(2) = 2 \end{array}$$

$$(c) \quad x(k) = 1 + x(k-1) - x(k-2)$$

$$x(0) = 1 + 0 - 0 = 1$$

$$x(1) = 1 + 1 - 0 = 2$$

$$x(2) = 1 + 2 - 1 = 2$$

(d) No, 3 poles for $X(z)$ on the unit circle.

2.9-1. Find two different state-variable formulations that model the system whose difference equation is given by:

$$(a) \ y(k+2) + 6y(k+1) + 5y(k) = 2e(k)$$

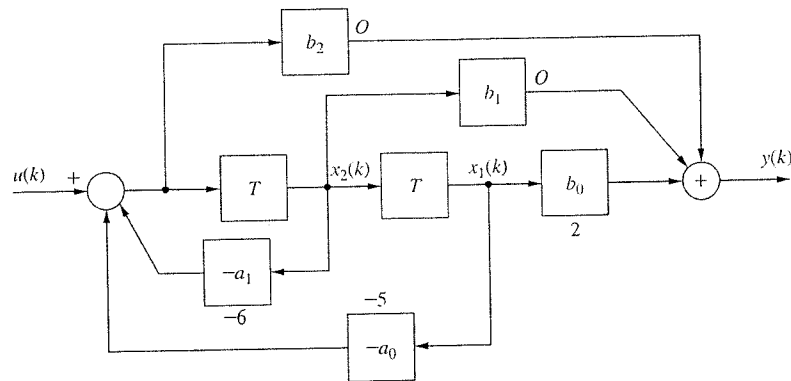
$$(b) \ y(k+2) + 6y(k+1) + 5y(k) = e(k+1) + 2e(k)$$

$$(c) \ y(k+2) + 6y(k+1) + 5y(k) = 3e(k+2) + e(k+1) + 2e(k)$$

Solution:

$$(a) \ \frac{Y(z)}{U(z)} = \frac{2}{z^2 + 6z + 5}$$

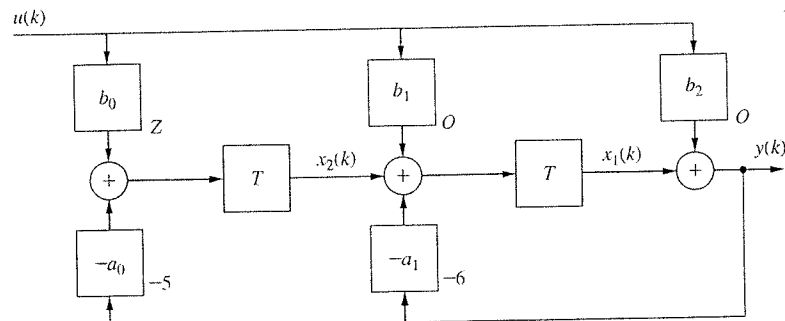
(1) control canonical:



$$\mathbf{x}(k+1) = \begin{bmatrix} 0 & 1 \\ -5 & -6 \end{bmatrix} \mathbf{x}(k) + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u(k)$$

$$y(k) = [2 \ 0] \mathbf{x}(k)$$

(2) observer canonical:



$$\mathbf{x}(k+1) = \begin{bmatrix} -6 & 1 \\ -5 & 0 \end{bmatrix} \mathbf{x}(k) + \begin{bmatrix} 0 \\ 2 \end{bmatrix} u(k)$$

$$y(k) = [1 \ 0] \mathbf{x}(k)$$

(b) $\frac{Y(z)}{U(z)} = \frac{z+2}{z^2+6z+5}$ (1) control canonical: $\mathbf{x}(k+1) = \text{same as (a)}$
 $y(k) = [2 \ 1] \mathbf{x}(k)$

(2) observer canonical:

$$\mathbf{x}(k+1) = \begin{bmatrix} -6 & 1 \\ -5 & 0 \end{bmatrix} \mathbf{x}(k) + \begin{bmatrix} 1 \\ 2 \end{bmatrix} u(k)$$

$$y(k) = [1 \ 0] \mathbf{x}(k)$$

(c) $\frac{Y(z)}{U(z)} = \frac{3z^2+z+2}{z^2+6z+5}$ (1) control canonical: $\mathbf{x}(k+1) = \text{same as (a)}$
 $y(k) = [-13 \ -17] \mathbf{x}(k) + 3u(k)$

(2) observer canonical:

$$\mathbf{x}(k+1) = \begin{bmatrix} -6 & 1 \\ -5 & 0 \end{bmatrix} \mathbf{x}(k) + \begin{bmatrix} 1 \\ 2 \end{bmatrix} u(k)$$

$$y(k) = [1 \quad 0] \mathbf{x}(k) + 3u(k)$$

2.10-1. Find a state-variable formulation for the system described by the coupled second-order difference equations given. The system output is $y(k)$, and $e_1(k)$ and $e_2(k)$ are the system inputs. *Hint:* Draw a simulation diagram first.

$$x(k+2) + v(k+1) = 4e_1(k) + e_2(k)$$

$$v(k+2) - v(k) + x(k) = 2e_1(k)$$

$$y(k) = v(k+2) - x(k+1) + e_1(k)$$

Solution:

$$\therefore y(k) = [-1 \quad -1 \quad 1 \quad 0] \mathbf{x}(k) + [1 \quad 0] e(k)$$