### **Productivity and Efficiency Analysis**

#### 7) Productivity growth

b) Malmquist index

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#### **Index theory**

- Requires prices of all inputs and outputs
- Some problems with prices:
  - Opportunity cost of capital
  - Quality change (e.g., ICT capital, labor skills)
  - New goods and obsolete goods
  - Nonmarket goods (e.g., environmental bads, public goods)
  - Imperfect competition (e.g., natural monopolies)
  - Government interventions (e.g., taxes, subsidies, tariffs)
- When reliable price information is not available, we can use shadow prices (i.e., marginal rates of substitution; multiplier weights β,γ)



#### **Shadow-price Fisher index**

Recall that the Fisher TFP index can be stated as'

$$F_{\text{TFP}}(p^{0,1}, w^{0,1}, y^{0,1}, x^{0,1}) = \frac{F_o(p^{0,1}, y^{0,1})}{F_i(w^{0,1}, x^{0,1})} = \prod_{j=0}^1 \prod_{t=0}^1 \left(\frac{p^j y^t}{w^j x^t}\right)^{t-1/2}.$$

Kuosmanen, Post and Sipiläinen (2003) propose the shadow-price Fisher index that does not require price data:

$$F_s(y^{0,1}, x^{0,1}) \equiv \prod_{i=0}^{1} \prod_{t=0}^{1} (\tilde{\mathbf{D}}^j(y^t, x^t))^{t-1/2},$$

# **Shadow-price Fisher index:** illustration with 2 outputs

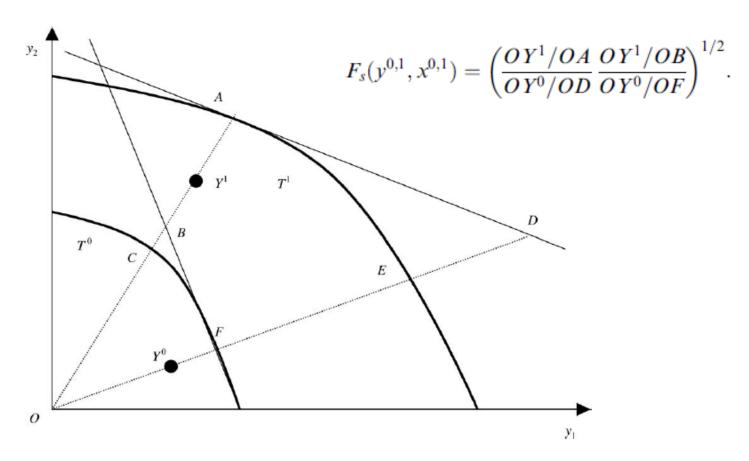


Figure 1. Illustration of the shadow-price Fisher index.



Source: Kuosmanen, Post, Sipiläinen (2003) *JPA* 

#### **Shadow-price Fisher index**

#### Kuosmanen, Post and Sipiläinen (2003)

THEOREM 2 ("The 2nd equivalence theorem"): The following conditions are equivalent if the shadow price vectors determine unique relative prices:

- 1. Production vector  $(y^t, x^t)$ ,  $t \in \{0, 1\}$  is allocatively efficient with respect to prices  $(p^t, w^t)$  and technology  $T^t$ .
- 2. The shadow-price Fisher index  $F_s(y^{0,1}, x^{0,1})$  and the Fisher ideal index  $F_{TFP}(p^{0,1}, w^{0,1}, y^{0,1}, x^{0,1})$  are identical.

If the two indices differ, which prices are more reliable: market prices or shadow prices?



#### Malmquist index

- Introduced by Caves, Christensen & Diewert (1982), Econometrica
- Can be stated in terms of Shephard's output distance functions (relative to CRS benchmark) as

$$M_{y}(\mathbf{x}^{0,1},\mathbf{y}^{0,1}) \equiv \left(\frac{D_{y}^{0,CRS}(\mathbf{x}^{1},\mathbf{y}^{1})}{D_{y}^{0,CRS}(\mathbf{x}^{0},\mathbf{y}^{0})} \cdot \frac{D_{y}^{1,CRS}(\mathbf{x}^{1},\mathbf{y}^{1})}{D_{y}^{1,CRS}(\mathbf{x}^{0},\mathbf{y}^{0})}\right)^{1/2},$$

Remark: why this is not "Shephard index"?

## Malmquist vs Shadow-price Fisher indices: illustration

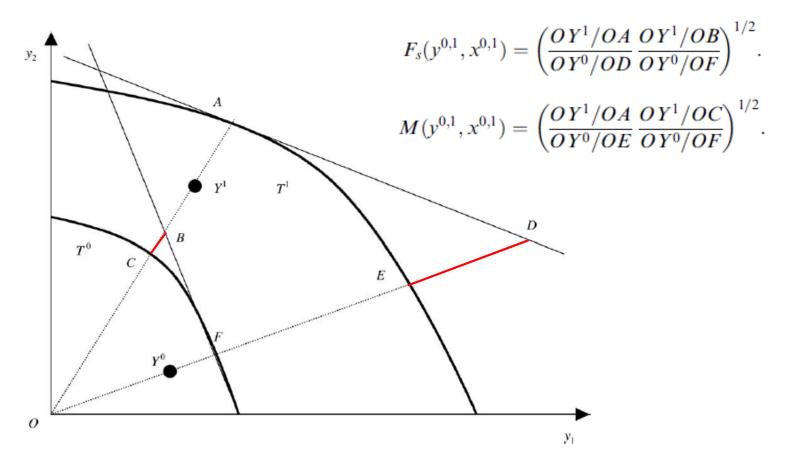


Figure 1. Illustration of the shadow-price Fisher index.



Source: Kuosmanen, Post, Sipiläinen (2003) *JPA* 

#### **Decomposing the Malmquist index**

- Nishimizu and Page (1982), Econ. J.
- Färe, Grosskopf, Norris, Zhang (1994) AER

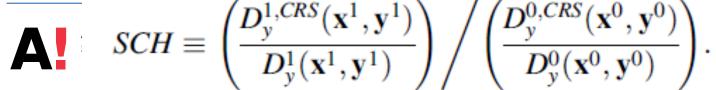
$$M_{y}(\mathbf{x}^{0,1},\mathbf{y}^{0,1}) = TECHCH \cdot PEFFCH \cdot SCH,$$

where

$$TECHCH \equiv \left(\frac{D_y^{0,CRS}(\mathbf{x}^0, \mathbf{y}^0)}{D_y^{1,CRS}(\mathbf{x}^0, \mathbf{y}^0)} \cdot \frac{D_y^{0,CRS}(\mathbf{x}^1, \mathbf{y}^1)}{D_y^{1,CRS}(\mathbf{x}^1, \mathbf{y}^1)}\right)^{1/2},$$

$$PEFFCH \equiv D_y^1(\mathbf{x}^1, \mathbf{y}^1)/D_y^0(\mathbf{x}^0, \mathbf{y}^0),$$

and





#### **Efficiency change:**

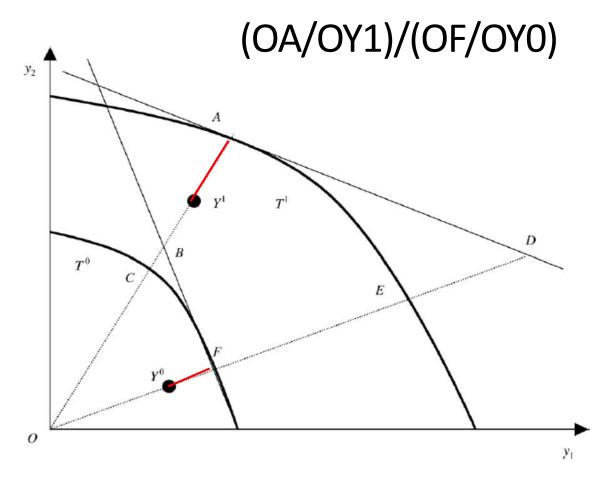


Figure 1. Illustration of the shadow-price Fisher index.

#### **Technical change:**

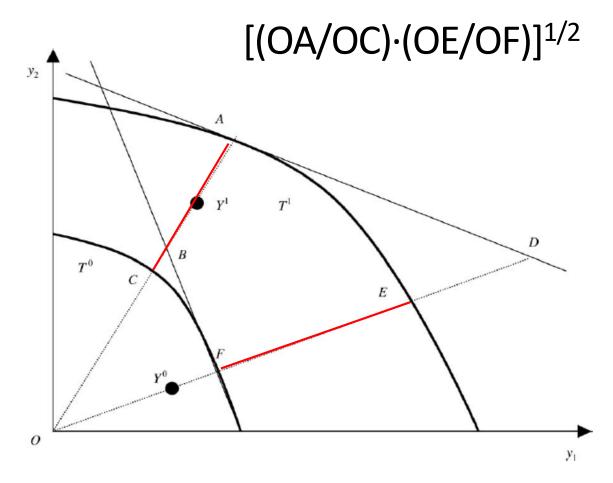


Figure 1. Illustration of the shadow-price Fisher index.

#### Scale efficiency change

- First introduced by Färe et al. (1994) AER
- Ray and Desli (1997) critique:
  - Why technical change is measured using CRS technology?
  - Propose alternative decomposition based on VRS technology, but then other components become less intuitive
- Several authors have further proposed their own solutions to this decomposition dilemma



#### **Decomposition of the Fisher index**

**Proposition 2** The Fisher ideal TFP index is the product of the technical efficiency ( $\Delta TEff$ ), technical change ( $\Delta Tech$ ), scale efficiency ( $\Delta SEff$ ), allocative efficiency ( $\Delta AEff$ ), and the price effect ( $\Delta PE$ ) components:

$$F_{TFP} = \Delta T E f f \cdot \Delta T e c h \cdot \Delta S E f f \cdot \Delta A E f f \cdot \Delta P E, \qquad (21)$$

where

$$\Delta T E f f \equiv (\Delta I T E f f \cdot \Delta O T E f f)^{1/2}$$
(22)

$$\Delta ITEff \equiv D_x^1(\mathbf{x}^1, \mathbf{y}^1) / D_x^0(\mathbf{x}^0, \mathbf{y}^0)$$
 (22a)

$$\Delta OTEff \equiv D_y^1(\mathbf{x}^1, \mathbf{y}^1) / D_y^0(\mathbf{x}^0, \mathbf{y}^0)$$
 (22b)



Source: Kuosmanen & Sipiläinen (2009)

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#### **Next lesson**

7c) Application of Malmquist index

