# 6th Homework

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Exercise 1

2, 3

Exercise 2

3

Exercise 3

4

Exercise 4

4

Exercise 5

1

Exercise 6

1

Exercise 7

1

Exercise 8

2

**Exercise 9** 

# Exercise 10

1,3

# **Exercise 11**

4

### Exercise 12

2,3

# Exercise 13

The Lagrangian function is:

$$L(P_1, P_2, P_3) = \sum_{i=1}^{N} \sum_{j=1}^{3} P(j|x_i) ln P_j + \lambda(\sum_{j=1}^{3} P_j - 1)$$

Solving the equation  $\frac{\partial (L(P_1,P_2,P_3))}{\partial (P_i)}=0$ 

$$rac{1}{P_1} \sum_{i=1}^N P(1|x_i) + \lambda = 0 \Rightarrow P_1 = -rac{1}{\lambda} \sum_{i=1}^N P(1|x_i)$$
 (13.1)

the same apply for the rest of the  $P_j$ 

Using the equation  $\sum_{j=1}^3 P_j = 1$ 

$$P_1 + P_2 + P_3 = 1 \Rightarrow -rac{1}{\lambda} \sum_{i=1}^N P(1|x_i) + -rac{1}{\lambda} \sum_{i=1}^N P(2|x_i) + -rac{1}{\lambda} \sum_{i=1}^N P(3|x_i) = 1$$

$$\Rightarrow \lambda = -(\sum_{i=1}^N P(1|x_i) + \sum_{i=1}^N P(2|x_i) + \sum_{i=1}^N P(3|x_i)) = -\sum_{i=1}^N \sum_{j=1}^3 P(j|x_i)$$
 (13.2)

Substituting 13.2 to 13.1 we have

$$P_1 = -rac{1}{\lambda} \sum_{i=1}^N P(1|x_i) = rac{1}{\sum_{i=1}^N \sum_{j=1}^3 P(j|x_i)} \sum_{i=1}^N P(1|x_i)$$

it holds that  $\sum_{j=1}^3 P(j|x_i) = 1$  thus

$$\Rightarrow P_1=rac{1}{\sum_{i=1}^N 1}\sum_{i=1}^N P(1|x_i)=rac{1}{N}\sum_{i=1}^N P(1|x_i)$$
 generalising this expression  $\Rightarrow P_j=rac{1}{N}\sum_{i=1}^N P(j|x_i)$ 

# Exercise 14

Since we are working with normal distributions

$$p(x_i|j;\mu_j) = rac{1}{(2\pi)^j |\Sigma_j|^{1/2}} exp\left(-rac{(x-\mu_j)^T \Sigma_j^{-1} (x-\mu_j)}{2}
ight)$$

for diagonal covariance matrix

$$\begin{split} &p(x_i|j;\mu_j) = \prod_{i=1}^N \left(\frac{1}{\sqrt{2\pi\sigma_j^2}} exp(-\frac{(x_i-\mu_j)^2}{2\sigma_j^2})\right) \Rightarrow \\ &\Rightarrow lnp(x_i|j;\mu_j) = -\sum_{i=1}^N \left(ln\frac{1}{\sqrt{2\pi\sigma_j^2}} + \frac{(x_i-\mu_j)^2}{2\sigma_j^2}\right) \\ &\frac{\partial \sum_{i=1}^N P(j|x_i)ln(p(x_i|j;m_j)}{\partial \mu_j} = 0 \Rightarrow \\ &\Rightarrow \frac{\partial \sum_{i=1}^N P(j|x_i)ln(p(x_i|j;m_j)}{\partial \mu_j} = \frac{\partial \sum_{i=1}^N P(j|x_i)\left(-ln\frac{1}{\sqrt{2\pi\sigma_j^2}} + \frac{(x_i-\mu_j)^2}{2\sigma_j^2}\right)}{\partial \mu_j} = \sum_{i=1}^N P(j|x_i)\left(\frac{(x_i-\mu_j)}{\sigma_j^2}\right) = \\ &\Rightarrow \sum_{i=1}^N P(j|x_i)x_i - \sum_{i=1}^N P(j|x_i)\mu_j = 0 \Rightarrow \sum_{i=1}^N P(j|x_i)x_i = \sum_{i=1}^N P(j|x_i)\mu_j \Rightarrow \\ &\Rightarrow \mu_j = \frac{\sum_{i=1}^N P(j|x_i)x_i}{\sum_{i=1}^N P(j|x_i)} \end{split}$$

## Exercise 15

#### $X_1$ dataset Parametric approach

```
import scipy.io as sio
import numpy as np
import matplotlib.pyplot as plt
from sklearn.mixture import GaussianMixture
from mpl_toolkits import mplot3d
from sklearn.neighbors import KernelDensity

Dataset = sio.loadmat('Dataset.mat')
X1 = Dataset['X1']
X2 = Dataset['X2']
```

Our data looks like they are gathered around one cluster. Therefore in the Gaussian Mixture function we will set n\_components equal to 1.

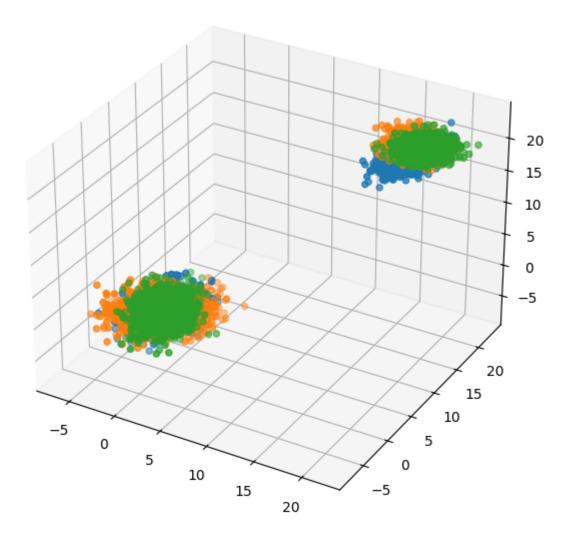
#### Non Parametric approach

We will use the Krnel Density Method from scikit-learn library.

```
In [39]: def parzen_window_est(x_samples, h, center):
             dimensions = x_samples.shape[1]
             assert (len(center) == dimensions), 'Number of center coordinates have t
             k = 0
             for x in x_samples:
                 is inside = 1
                 for axis,center_point in zip(x, center):
                     if np.abs(axis-center_point) > (h/2):
                         is inside = 0
                 k += is_inside
             return f"{(k / len(x_samples)) / (h**dimensions):.4f}"
         for i, x_i in enumerate(x_1):
             # print('p(x) = ', parzen_window_est(X1, h=1))
             print(f''p(x{i+1}) = ", parzen window est(X1, 1, x i))
        p(x1) = 0.0060
        p(x2) = 0.0000
        p(x3) = 0.0020
```

### $X_2$ dataset Parametric approach

```
In [26]: fig = plt.figure(figsize = (10, 7))
    ax = plt.axes(projection ="3d")
    ax.scatter3D(X2[:,0], X2[:,1], X2[:,2])
    ax.scatter3D(X2[:,0], X2[:,2], X2[:,3])
    _ = ax.scatter3D(X2[:,1], X2[:,2], X2[:,3])
```



```
In [35]: gm_2 = GaussianMixture(n_components=2, random_state=0).fit(X2)
    mean = gm_2.means_
    cov = gm_2.covariances_

x_2 = np.array([[0.05,0.15,-0.12,-0.08],[7.18,7.98,9.12,9.94],[3.48,4.01,4.5]

for i, x_i in enumerate(x_2):
    p1 = gm_2.predict_proba([x_2[0]])[0][0]
    p2 = gm_2.predict_proba([x_2[0]])[0][1]

    cov_norm_1, cov_norm_2 = np.linalg.norm(cov[0])**1/2, np.linalg.norm(cov cov_inv_1, cov_inv_2 = np.linalg.inv(cov[0]), np.linalg.inv(cov[1])

    x_mu_1, x_mu_2 = x_i - mean[0], x_i - mean[1]
    p_x_1 = 1/((2*np.pi)**2 * cov_norm_1) * np.exp(-0.5 * (x_mu_1).dot(cov_1) + (2*np.pi)**2 * cov_norm_2) * np.exp(-0.5 * (x_mu_2).dot(cov_1) + (2*np.pi)**2 * np.exp(-0.5 * (x_mu_2).dot(cov_1) + (x_mu_2).dot
```

```
p(x1): 0.0050
p(x2): 0.0000
p(x3): 0.0000
p(x4): 0.0000
```

Non Parametric approach

We will use the Krnel Density Method from scikit-learn library.

```
In [40]: for i, x_i in enumerate(x_2):
    print(f"p(x{i+1}) = ", parzen_window_est(X2, 1, x_i))

p(x1) = 0.0005
p(x2) = 0.0000
p(x3) = 0.0000
p(x4) = 0.0000
```