CompleteThat: A python package for low-rank matrix completion

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Abstract

We have developed a Python package (CompleteThat) to perform low rank matrix completion. Given a low rank matrix with partial entries we implemented different methods to solve the matrix completion problem: First, for "small" problems we implemented two memory-based algorithms following the work by Tanner and Wei [TW14] to find, given a number r, the matrix with rank r that best fits the data using the Frobenius norm. Second, when the problem does not fit into memory, we implemented a memory-fitting algorithm (stochastic gradient descent) following the approach in Zhang [Zha04] and Bottou [Bot12]. The package is available at https://pypi.python.org/pypi/completethat/0.1dev.

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1 Introduction

Matrix factorization has recently seen a large growth in popularity within the mathematics, statistics, and computer science communities as industry continues to apply machine learning techniques on a wide array of problems and scenarios. For our convex optimization project, we decided to take some of the more interesting and applicable topics and algorithms of our class and develop a python package to implement them. We briefly discuss the theory behind matrix factorizing, the models and approaches we choose to use and the algorithms for the optimization. Later, we walk through two case studies illustrating the usefulness and applicability in the context of image processing and a recommendation system for Yahoo music and movie data.

2 Matrix Completion Problem

The matrix completion problem can be formally stated as follows. We are interested in recovering a matrix $M \in \mathbf{R}^{n_1 \times n_2}$ but only get to observe a number $m \ll n_1 n_2$ of its entries. Thus, we want to find a solution to the following optimization problem

minimize
$$\operatorname{rank}(X)$$

subject to $X_{ij} = M_{ij}$ $(i, j) \in \Omega$ (1)

where $X \in \mathbf{R}^{n_1 \times n_2}$ is the decision variable and $\mathbf{rank}(X)$ is equal to the rank of the matrix X. The problem (1) seeks the simplest matrix fitting the observed data. Of course, if there were only one low-rank object fitting the data, this would recover M. In order to fix the notation correctly define the projector $P_{\Omega}: \mathbf{R}^{n_1 \times n_2} \to \mathbf{R}^{n_1 \times n_2}$ as

$$P_{\Omega}(A) = \begin{cases} A_{ij} & : (i,j) \in \Omega \\ 0 & : \text{ otherwise} \end{cases}$$

Using the projector, Problem (1) can be rewritten as

minimize
$$\operatorname{rank}(X)$$

subject to $P_{\Omega}(X) = P_{\Omega}(M)$ (2)

Unfortunately, this optimization problem has been shown to be NP-hard and all know algorithms which provide exact solutions require time doubly exponential in the dimension of the matrix both in theory and in practice [CR09]. Also, the $\mathbf{rank}(X)$ makes the problem non-convex.

Several approximations to the problem exists. One, the "tightest convex relaxation of $\operatorname{rank}(X)$ " [Faz02] is the following problem

minimize
$$||X||_* := \sum_{i=1}^r \sigma_i(X)$$

subject to $P_{\Omega}(X) = P_{\Omega}(M)$ (3)

where $\sigma_i(X)$ denotes the *i*th largest singular value of X and $||X||_*$ is the called the nuclear norm. The main point of this relaxation is that the nuclear norm is a convex function and thus can be optimized efficiently via semidefinite programming or by iterative soft thresholding algorithms [CCS10] [GM11].

Alternative to nuclear norm minimization there have been many algorithms which are designed to target the following optimization problem

$$\operatorname{minimize}_{Y,Z} \quad \frac{1}{2} \| P_{\Omega}(YZ) - P_{\Omega}(M) \|_F^2 \tag{4}$$

where X = YZ is the completed matrix and $Y \in \mathbf{R}^{n_1 \times r}, Z \in \mathbf{R}^{r \times n_2}$ and r represents the (hopefully small) rank of the matrix X.

3 Implementation

CompleteThat is a python package that solves the low rank matrix completion problem. Given a low rank matrix with partial entries the package solves an optimization problem to estimate the missing entries. We allow the user to choose between several optimization algorithms including two in memory based algorithms, alternating steepest descent and scaled alternating steepest descent, and one out of memory fitting procedure using stochastic gradient descent. We use extensively the numerical libraries spicy and numpy, and the current implementation includes two classes, MatrixCompletion for in memory based algorithms and MatrixCompletionBD for the memory fitting procedure. The package is available worldwide and can be downloaded from https://pypi.python.org/pypi/completethat/0.1dev.

CVX

Problem (3) can be easily solved directly using CVX, a package for specifying and solving convex programs [GB14], [GB08], with the following code:

```
index = find(~isnan(M));
cvx_begin
    variable X(size(M));
    minimize norm_nuc(X)
    % s.t.
    X(index) == M(index);
cvx_end
```

Where M is a MATLAB matrix with nan on the missing entries and X(index) == M(index) corresponds to the $P_{\Omega}(X) = P_{\Omega}(M)$ restriction. However, the computation is very slow and for any matrix greater than 100×100 the computational time is too high. Since this is clearly unsatisfactory for practical purposes, specific algorithms were implemented on the package.

Algorithms

Low rank matrix completion by alternating steepest descent methods

Low rank matrix completion by stochastic gradient descent

Code Example

For matrices that fit into memory use the MatrixCompletion module. Otherwise, use MatrixCompletionBD module.

MatrixCompletion

Given a numpy matrix M with numpy nan on the missing entries, the matrix completion problem can be solved (using ASD) as:

```
>>> from completethat import MatrixCompletion
>>> problem = MatrixCompletion(M)
>>> problem.complete_it("ASD")
>>> X = problem.get_matrix() #Desired matrix
>>> out_info = problem.get_out() #Extra information
```

MatrixCompletionBD

Given a csv file with the input data, the matrix completion problem can be solved as:

4 Case Studies

Yahoo movies and music reviews database

The Yahoo music and movie data sets are publicly available datasets published by Yahoo for use to the public for recreational and research purposes. The music training data set is a small 4 mb pipe-delimited file consisting of roughly 210,000 user-movie ratings. The test set has roughly 10,000 records. There are two ratings schemas available, one on a 5-point scale and the other on a 13-point scale and we arbitrarily chose to use the 5-point scale. The Yahoo music data is a larger 2.2 gb file of 115 million user-song ratings. The ratings are on a 100 point scale.

We look to evaluate the performance of our algorithms on these two datasets, comparing the various algorithms implemented versus a naive benchmark estimate where we used the mean of the training set as our estimator for all records in the test set. Then we compared how well the algorithms performed versus the benchmark.

The benchmark for the yahoo music data is 4.088. This is the mean value of the ratings in the training set so we will compute the MSE on the test set using the benchmark which yields an RMSE of 1.10. A quick run of Mahout yields 1.17 and CompleteThat's sgd model yielded a 1.19. So our model yielded a pretty similar RMSE as the MAHOUT package. Note that for both of these instances we used a factorization of rank equal to seven and the Complete that sgd algorithm ran slightly faster than Mahout's (.537 minutes vs 1.4 minutes).

Step size	Iterations	Minutes	Train MSE	Test RMSE
1	8	0.585	1.411	1.757
2	8	0.598	1.304	1.550
3	8	0.628	1.235	1.483
4	8	0.617	1.180	1.397
5	7	0.538	1.136	1.351
6	7	0.534	1.100	1.244
7	7	0.534	1.071	1.194
8	7	0.541	1.046	1.127
9	7	0.537	1.027	1.128
10	7	0.529	1.010	1.102
15	7	0.551	0.971	1.063
20	7	0.540	0.976	1.075
30	8	0.614	1.045	1.359

Table 1: RMSE vs Step Size vs Rank

Columbia University photographs

In this section, we demonstrate the applicability of the package to image processing problems. By randomly erasing a predefined proportion of the pixels of an image the problem of completing the image can be cast as a matrix completion problem. For illustration we used three 512×512 grayscale photographs taken by one of the authors of the Columbia University campus on December, 2014. The reconstructed images can be seen on Figure 1, where we erased 65% of the pixels of each image.

In addition, to illustrate the ease of use of the package we also present the script used to solve all the problems in what follows:

```
import numpy as np
from scipy import misc
from completethat import MatrixCompletion
def blur (imgpath, delta = 0.65):
        Function to blur the image
    photo = scipy.misc.imread(imgpath, flatten=True).astype(float) #Read as
   grayscale
   m, n = photo.shape
    p = round(delta * (m * n - 1)) #Number of blanks
    A = np.zeros((m * n, 1), dtype=bool)
    A[0:p] = True
    ind = np.random.permutation(range(m*n))
    A = A[ind]
    A = A. reshape((m, n))
    return photo, A
if __name__ = '__main__':
    # Read image and randomly erase 65% of the pixels
    photo, A = blur('./columbia_1.png')
   M = np.copy(photo)
   M[^{\sim}A] = np.nan
    problem = MatrixCompletion(M)
   # Solve the problem
    problem.complete_it('ASD')
    X = np.copy(problem.get_optimized_matrix())
```



Figure 1: ASD method applied three different Columbia University photographs using random sampling

5 Future Work

We have plans for various improvements as we continue working with the CompleteThat python package. Overall, we would like to test the software and integrate automated testing cases into the software developing cycle. Also, documentation for the package and its functions, including examples, is high in our priority list. In addition, we hope to incorporate more rigorous error checking and make available more customization to the user.

For the memory-based algorithms it is well know that noise in the data introduces over-fitting on the estimated matrix. Following the approach taken by Mazumder et al. [MHT10] where they solve the same objetive function as the problems above (using the Frobenious norm) but introducing the nuclear norm as regularizer to account for overfitting, we would introduce a regularization option into the matrix completion procedure.

For the stochastic gradient descent method, we plan to add a lambda penalty feature for combatting overfitting as well as considering options for more advanced versions of our basic latent factor model as demonstrated by Koren [Kor08] in his paper on the prize-winning Netflix models. For all algorithms, we would like to explore and research various hardware and software optimization techniques for faster code.

Finally, given the similarities between matrix completion and robust principal component analysis one further extension to the functionality of the package could be implementing the robust-PCA procedure outlined by Candés [CLMW11], et al.

References

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6 Source code

On the whole, the package directory structure looks like the Figure 2. In the following we present the source code for the package.

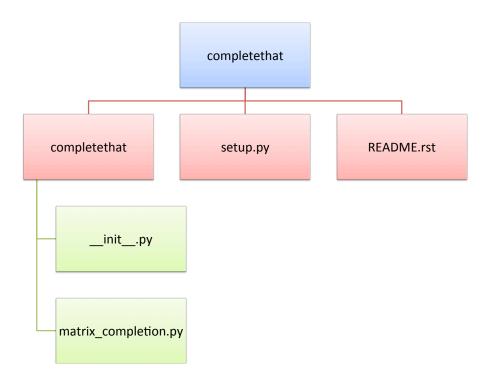


Figure 2: CompleteThat structure

complete that / matrix_completion.py

```
1 import numpy as np
2 from scipy.sparse import csc_matrix
3 from scipy.sparse import linalg as linalg_s
4 import os, random, time
   from scipy import linalg
6
   class MatrixCompletion:
7
8
       """ A general class to represent a matrix completion problem
9
10
       Data members
11
12
       M:= data matrix (numpy array).
       X:= optimized data matrix (numpy array)
13
```

```
14
        out_info:= output information for the optimization (list)
15
16
17
        Class methods
18
        complete_it():= method to complete the matrix
19
        get_optimized_matrix():= method to get the solution to the problem
20
        get_matrix():= method to get the original matrix
21
22
        \operatorname{\mathtt{get\_out}}() := \operatorname{\mathtt{method}} to \operatorname{\mathtt{get}} extra information on the optimization (iter
        number, convergence, objective function)
23
24
25
        def = init_{--}(self, X, *args, **kwargs):
26
27
            """ Constructor for the problem instance
28
29
                 Inputs:
30
                  1) X: known data matrix. Numpy array with np.nan on the unknow
       entries.
31
                     example:
32
                          X = np.random.randn(5, 5)
33
                          X[1][3] = np.nan
                          X[0][0] = np.nan
34
                          X[4][4] = np.nan
35
36
37
            # Initialization of the members
38
            self.M = X
39
            self. X = np.array(X, copy = True) #Initialize with ini data matrix
40
41
            self._out_info = []
42
43
        def get_optimized_matrix(self):
             """ Getter function to return the optimized matrix X
44
45
46
                 Ouput:
47
                  1) Optimized matrix
48
            return self._X
49
50
51
        def get_matrix(self):
            """ Getter function that returns the original matrix M
52
53
54
                 Output:
                 1) Original matrix M
55
56
57
            return self._M
58
59
        def get_out(self):
60
             """ Getter function to return the output information
                 of the optimization
61
62
63
                 Output:
```

```
64
                   1) List of length 2: number of iterations and relative residual
65
66
             return self._out_info
67
68
69
         def \_ASD(self, M, r = None, reltol=1e-5, maxiter=5000):
70
71
72
             Alternating Steepest Descent (ASD)
73
             Taken from Low rank matrix completion by alternating steepest descent
        methods
             Jared Tanner and Ke Wei
74
75
             SIAM J. IMAGING SCIENCES (2014)
76
77
             We have a matrix M with incomplete entries,
             and want to estimate the full matrix
78
79
80
             Solves the following relaxation of the problem:
81
             \label{eq:minimize_XY} $$ \inf z_{X,Y} \cdot frac_{1}_{2} = \|P_{-}(Omega_{X,Y}) - P_{-}(Omega_{X,Y})\|_{F^{2}} $$
             Where \Omega represents the set of m observed entries of the matrix M
82
             and P<sub>-</sub>{\Omega}() is an operator that represents the observed data.
83
84
             Inputs:
85
86
              M := Incomplete matrix, with NaN on the unknown matrix
87
              r := hypothesized rank of the matrix
88
89
             Usage:
90
              Just call the function ASD(M)
91
92
93
             # Get shape and Omega
94
             m, n = M. shape
             if r == None:
95
                  r = \min(m, n, 50)
96
97
             # Set relative error
98
             Omega = \tilde{n}p.isnan(M)
99
             frob_norm_data = linalg.norm(M[Omega])
100
             relres = reltol * frob_norm_data
101
102
103
             # Initialize
104
             I, J = np. where (Omega)
             M_{\text{-}}omega = csc_{\text{-}}matrix ((M[Omega], (I, J)), shape=M. shape)
105
             U, s, V = linalg_s.svds(M_omega, r)
106
107
             S = np.diag(s)
             X = np.dot(U, S)
108
             Y = V
109
             itres = np.zeros((maxiter+1, 1))
110
111
             XY = np.dot(X, Y)
112
             diff_on_omega = M[Omega] - XY[Omega]
113
```

```
114
             res = linalg.norm(diff_on_omega)
             iter = 0
115
116
             itres [iter] = res/frob_norm_data
117
             while iter < maxiter and res >= relres:
118
119
120
                 # Gradient for X
121
                 diff_on_omega_matrix = np.zeros((m,n))
                 diff_on_omega_matrix [Omega] = diff_on_omega
122
123
                 grad_X = np.dot(diff_on_omega_matrix, np.transpose(Y))
124
                 # Stepsize for X
125
126
                 delta_XY = np.dot(grad_X, Y)
                 {\tt tx = linalg.norm(grad\_X, 'fro')**2/linalg.norm(delta\_XY)**2}
127
128
                 # Update X
129
130
                 X = X + tx*grad_X;
131
                 diff_{on\_omega} = diff_{on\_omega} - tx*delta_XY [Omega]
132
                 # Gradient for Y
133
                 diff_on_omega_matrix = np.zeros((m,n))
134
                 diff_on_omega_matrix [Omega] = diff_on_omega
135
136
                 Xt = np.transpose(X)
137
                 grad_Y = np.dot(Xt, diff_on_omega_matrix)
138
                 # Stepsize for Y
139
                 delta_XY = np.dot(X, grad_Y)
140
                 ty = linalg.norm(grad_Y, 'fro')**2/linalg.norm(delta_XY)**2
141
142
143
                 # Update Y
                 Y = Y + ty*grad_Y
144
                 diff_on_omega = diff_on_omega-ty*delta_XY [Omega]
145
146
147
                 res = linalg.norm(diff_on_omega)
                 iter = iter + 1
148
149
                 itres [iter] = res/frob_norm_data
150
             M_{\text{out}} = \text{np.dot}(X, Y)
151
152
153
             out_info = [iter, itres]
154
             return M_out, out_info
155
156
         def \ \_sASD(self, M, r = None, reltol=1e-5, maxiter=10000):
157
158
             Scaled Alternating Steepest Descent (ScaledASD)
159
160
             Taken from:
161
             Low rank matrix completion by alternating steepest descent methods
162
             Jared Tanner and Ke Wei
             SIAM J. IMAGING SCIENCES (2014)
163
164
```

```
165
             We have a matrix M with incomplete entries,
             and want to estimate the full matrix
166
167
             Solves the following relaxation of the problem:
168
             minimize_{X,Y} \setminus frac_{1}_{2} \mid P_{\bullet} \setminus Omega_{Z^0} - P_{\bullet} \setminus Omega_{XY} \mid F^2
169
             Where \Omega represents the set of mobserved entries of the matrix M
170
171
             and P<sub>-</sub>{\Omega}() is an operator that represents the observed data.
172
             Inputs:
173
174
              M := Incomplete matrix, with NaN on the unknown matrix
175
              r := hypothesized rank of the matrix
176
177
             Usage:
178
              Just call the function _sASD(M)
179
180
181
182
             # Get shape and Omega
183
             m, n = M. shape
             if r == None:
184
                  r = \min(m, n, 50)
185
186
             # Set relative error
187
188
             Omega = np.isnan(M)
189
             frob_norm_data = linalg.norm(M[Omega])
             relres = reltol * frob_norm_data
190
191
192
             # Initialize
193
             identity = np.identity(r);
194
             I, J = np.where(Omega)
195
             M_{\text{-}}omega = csc_{\text{-}}matrix((M[Omega], (I, J)), shape=M.shape)
196
             U, s, V = linalg_s.svds(M_omega, r)
             S = np.diag(s)
197
198
             X = np. dot(U, S)
             Y = V
199
200
             itres = np.zeros((maxiter+1, 1))
201
202
             XY = np.dot(X, Y)
             diff_on_omega = M[Omega] - XY[Omega]
203
204
             res = linalg.norm(diff_on_omega)
205
             iter = 0
206
             itres [iter] = res/frob_norm_data
207
208
             while iter < maxiter and res >= relres:
209
                  # Gradient for X
210
211
                  diff_{on\_omega\_matrix} = np. zeros((m, n))
212
                  diff_on_omega_matrix[Omega] = diff_on_omega
213
                  grad_X = np.dot(diff_on_omega_matrix, np.transpose(Y))
214
215
                  # Scaled gradient
```

```
216
                 scale = linalg.solve(np.dot(Y, np.transpose(Y)), identity)
217
                 dx = np.dot(grad_X, scale)
218
                 delta_XY = np.dot(dx, Y)
219
                 tx = np.trace(np.dot(np.transpose(dx),grad_X))/linalg.norm(
220
        delta_XY [Omega]) **2
221
                 # Update X
222
223
                 X = X + tx*dx
224
                 diff_on_omega = diff_on_omega-tx*delta_XY [Omega]
225
                 # Gradient for Y
226
227
                 diff_on_omega_matrix = np.zeros((m,n))
228
                 diff_on_omega_matrix [Omega] = diff_on_omega
229
                 Xt = np.transpose(X)
230
                 grad_Y = np.dot(Xt, diff_on_omega_matrix)
231
232
                 # Scaled gradient
233
                 scale = linalg.solve(np.dot(Xt, X), identity)
                 dy = np.dot(scale, grad_Y)
234
235
                 # Stepsize for Y
236
                 delta_XY = np.dot(X, dy)
237
238
                 ty = np.trace(np.dot(dy,np.transpose(grad_Y)))/linalg.norm(
        delta_XY[Omega])**2
239
                 # Update Y
240
                 Y = Y + tv*dv
241
242
                 diff_on_omega = diff_on_omega-ty*delta_XY [Omega]
243
                 # Update iteration information
244
245
                 res = linalg.norm(diff_on_omega)
                 iter = iter + 1
246
247
                 itres [iter] = res/frob_norm_data
248
249
             M_{\text{-}}out = np.dot(X, Y)
250
             out_info = [iter, itres]
251
252
253
             return M_out, out_info
254
255
        def complete_it(self, algo_name, r = None, reltol=1e-5, maxiter=5000):
256
             """ Function to solve the optimization with the choosen algorithm
257
258
259
                 Input:
                  1) algo_name: Algorithm name (ASD, sASD, ect)
260
261
                  2) r: rank of the matrix if performing alternating algorithm
262
263
             if algo_name == "ASD":
264
                 self._X, self._out_info = self._ASD(self._M, r, reltol, maxiter)
```

```
265
             elif algo_name == "sASD":
266
                 self._X, self._out_info = self._sASD(self._M, r, reltol, maxiter)
267
             else:
                 raise NameError("Algorithm name not recognized")
268
269
    class MatrixCompletionBD:
270
271
272
        A general class for matrix factorization via stochastic gradient descent
273
        Class members
274
275
        file: three column file of user, item, and value to build models
276
277
278
279
        Class methods
280
281
        train_sgd():= method to complete the matrix via sgd
282
        shuffle_file():= method to 'psuedo' shuffle input file in chunks
283
         file_split():= method to split input file into training and test set
        save_model():= save user and items parameters to text file
284
        validate_sgd():= validate sgd model on test set
285
        build_matrix():= for smaller data build complete matrix in pandas df or
286
        numpy matrix?
        ,, ,, ,,
287
288
289
290
        def __init__(self, file_path, delimitter='\t',*args, **kwargs):
291
292
                  Object constructor
293
                  Initialize Matrix Completion BD object
294
295
              self._file = file_path
296
              self._delimitter = '\t'
297
              self._users = dict()
              self._items = dict()
298
299
        def shuffle_file(self,batch_size=50000):
300
301
302
303
             Shuffle line of file for sgd method, improves performance/convergence
304
305
             data = open(self._file)
306
307
             temp_file=open('temp_shuffled.txt', 'w')
308
             try:
309
                 temp=open('backup_data_file.txt')
                 temp.close()
310
311
             except:
                 os.system('cp' +self._file + ' backup_data_file.txt')
312
313
314
             temp_array = []
```

```
315
             counter=0
316
             for line in data:
317
                 counter+=1
                 temp_array.append(line)
318
                 if counter=batch_size :
319
                     random. shuffle (temp_array)
320
321
                      for entry in temp_array:
                          temp_file.write(entry)
322
323
                      temp_array = []
324
                      counter=0
325
326
             if len(temp_array) > 0:
327
                 random.shuffle(temp_array)
328
                 for entry in temp_array:
329
                      temp_file.write(entry)
330
331
             data.close()
332
             temp_file.close()
333
             system_string='mv temp_shuffled.txt ' + self._file
             os.system(system_string)
334
335
        def file_split(self, percent_train = .80, train_file='data_train.csv',
336
        test_file='data_test.csv'):
337
338
339
             split input file randomly into training and test set for cross
        validation
340
341
342
             train=open(train_file, 'w')
343
             test=open(test_file, 'w')
             temp_file=open(self._file)
344
             for line in temp_file:
345
                 if np.random.rand()<percent_train:</pre>
346
347
                      train.write(line)
348
                 else:
349
                      test.write(line)
350
             train.close()
351
             test.close()
352
             print('test file written as ' + train_file)
353
354
             print('test file written as ' + test_file)
             temp_file.close()
355
356
357
        def train_sgd(self,dimension=6,init_step_size=.01,min_step=1e-5,reltol
        =.05, rand_init_scalar=1, maxiter=100, batch_size_sgd=50000, shuffle=True,
        print_output=False):
358
359
             init_time=time.time()
             alpha=init_step_size
360
361
             iteration=0
```

```
362
             delta_err=1
363
             new_mse=reltol+10
364
             counter=0
365
             ratings = []
366
             while iteration != maxiter and delta_err > reltol :
367
368
369
                 data=open(self._file)
                 total_err = [0]
370
371
                 if alpha>=min_step: alpha*=.3
372
                 else: alpha=min_step
373
374
                 for line in data:
375
376
                      record=line [0:len(line)-1].split(self._delimitter)
                      record[2] = float(record[2])
377
378
                     # format : user, movie,5-point-ratings
                      ratings.append(record[2])
379
380
                     #if record[0] in self.users and record[1] in self.items:
381
382
                          # do some updating
                          # updates
383
                          error=record[2]-np.dot(self._users[record[0]],self._items[
384
        record [1]])
385
                          self.users[record[0]] = self.users[record[0]] + alpha*2*
        error * self._items [record [1]]
                          self._items[record[1]] = self._items[record[1]] + alpha*2*
386
        error * self._users [record [0]]
387
                          total_err.append(error**2)
388
                      except:
389
                          #else:
390
                          counter+=1
391
                          if record [0] not in self._users:
392
                              self._users[record[0]] = np.random.rand(dimension)*
        rand_init_scalar
                          if record[1] not in self._items:
393
                              self._items[record[1]] = np.random.rand(dimension)*
394
        rand_init_scalar
395
396
                 data.close()
397
                 if shuffle:
398
                      self.shuffle_file(batch_size=batch_size_sgd)
                 iteration+=1
399
                 old_mse=new_mse
400
401
                 new_mse=sum(total_err)*1.0/len(total_err)
402
                 delta_err=abs(old_mse-new_mse)
                 if print_output and iteration %10==0:
403
404
                      print ('Delta Error: %f ' % delta_err)
405
             #Printing Final Output
406
407
             if print_output:
```

```
408
                 print ('Iterations: %f ' % iteration)
409
                 print ('MSE: %f ' % new_mse)
410
                 minutes=(time.time()-init_time)/60
                 print ('Total Minutes to Run: %f' % minutes)
411
412
413
414
        def save_model(self, user_out='user_params.txt', item_out='item_params.txt')
             22 22 22
415
416
             save model user and item parameters to text file
417
             user_key, user_vector entries
418
             item_key, item_vector entries
419
420
             users=open(user_out, 'w')
             items=open(item_out, 'w')
421
422
             for key in self._users:
423
                 user_string= key+ self._delimitter + self._delimitter.join(map(str
        , list(self.\_users[key]))) + '\n'
424
                 users.write(user_string)
425
426
             for key in self._items:
                 item_string=key+ self._delimitter + self._delimitter.join(map(str,
427
        list(self._items[key]))) + '\n'
428
                 items.write(item_string)
429
430
             users.close()
             items.close()
431
432
433
        ## read saved model, particularly useful for fitting very large files!
434
        def read_model(self, dimension=6, saved_user_params='user_params.txt',
        saved_item_params='item_params.txt'):
435
436
437
             Read the saved user and item parameters from text files to the item
        and user dictionaries
438
             ,, ,, ,,
439
            #populate users:
440
             user_data=open(saved_user_params)
441
442
             for line in user_data:
                 record=line [0:len(line)-1].split(self._delimitter)
443
                 key = record.pop(0)
444
                 params=np.array(map(float, record))
445
                 self._users[key]=params
446
447
448
             user_data.close()
449
450
            #populate items:
             item_data=open(saved_item_params)
451
             for line in item_data:
452
453
                 record=line [0:len(line)-1].split(self._delimitter)
```

```
454
                  key = record.pop(0)
                 params=np.array(map(float, record))
455
456
                  self._items[key]=params
457
             item_data.close()
458
459
460
         def clear_model(self):
461
462
463
             clear the user and item parameters
464
465
466
             del self._items, self._users
467
             self._items=dict()
468
             self._users=dict()
469
470
         def validate_sgd(self, test_file_path):
471
472
473
             run model on test/validation set, returns MSE
474
             22 22 22
475
476
             mse = []
477
             counter=0
478
             test_set=open(test_file_path)
479
             for line in test_set:
                  record=line [0:len(line)-1].split(self._delimitter)
480
481
                  record[2] = float(record[2])
482
                  try:
483
                      error=record[2]-np.dot(self._users[record[0]],self._items[
        record [1]])
484
                      mse.append(error**2)
485
                  except:
486
                      counter += 1
487
488
             if counter >0: print ('Items/Users Key Errors: %f' % counter')
             # returns Mean Squared Error
489
             return sum(mse)/len(mse)
490
491
492
         def build_matrix(self):
493
             pass
```

$complete that/matrix_init_.py$

```
1 """ CompleteThat is a python package that solves the low rank matrix completion \,
```

² problem. Given a low rank matrix with partial entries the package solves an 3 optimization problem to estimate the missing entries.

```
4
   Mathematically, the package solves a relaxation (using the nuclear norm or the
6
   Frobenius norm of the objective matrix) of the following problem:
7
        minimize_{-}\{X\} ||X||
        st. X(i,j) = M(i,j) \setminus forall (i,j) \setminus in \setminus Omega,
8
9
10
   Where, M represents the data matrix and Omega represents the set of p
       observed entries of M
11
12
       Usage:
       # MatrixCompletion
13
       >>> from completethat import MatrixCompletion
14
15
       >>> problem = MatrixCompletion (M)
16
       >>> problem.complete_it(algo_name)
17
       >>> X = problem.get_matrix()
       >>> out_info = problem.get_out() #Extra info (iterations, ect)
18
19
20
       # MatrixCompletionBD
21
       >>> from completethat import MatrixCompletionBD
22
       >>> temp=MatrixCompletionBD('input_data.txt')
23
       >>> temp.train_sgd(dimension=6,init_step_size=.01,min_step=.000001, reltol
       =.001, rand_init_scale=10,
                                    maxiter=1000, batch_size_sgd=50000, shuffle=True
       ):
24
       >>> temp.validate_sgd('test_data.txt')
25
       >>> temp.save_model()
26
   ,, ,, ,,
27
28 from matrix_completion import MatrixCompletion
   from matrix_completion import MatrixCompletionBD
```

$complete that/matrix_init__.py$

```
from setuptools import setup
1
2
3
   def readme():
        with open ('README.rst') as f:
4
5
            return f.read()
6
7
   setup (
8
          name='completethat',
9
          version='0.1 dev',
10
          description='A package to solve low rank matrix completion problems',
          long_description=readme(),
11
          author='Joshua Edgerton, Esteban Fajardo',
12
          author_email='ef2451@columbia.edu, jae2154@columbia.edu',
13
14
          license='BSD',
          packages = ['complete that'],
15
16
          install_requires=[
```

```
17
               'scipy', 'numpy'
          ],
18
          classifiers=[
19
             'Development Status :: 3 - Alpha',
20
              'License :: OSI Approved :: BSD License',
21
              'Programming Language :: Python :: 2.7',
22
             'Topic :: Scientific/Engineering :: Mathematics',
'Topic :: Utilities'
23
24
25
          ],
26
          include_package_data=True,
27
          zip_safe=False
28 )
```