## Gradient Descent Example

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```
GradientDescent

M: int
function: Callable[ndarray(M,), float]
gradient: Callable[ndarray(M,), ndarray(M,)]
epsilon: float
gamma: float
run(x0: ndarray(M,)): Dict[str: float]
```

Figure 1: Gradient descent class that optimizes a scalar function using its gradient with tolerance epsilon.

```
Data: Starting Point of Gradient Descent x_0: ndarray(M,), Maximum iteration K
Result: Dictionary with keys:values {"success" : bool, "value" : float, "pt" : ndarray(M,)}
Raise TypeError if x_0 is not of type np.ndarray;
Raise ValueError if x_0 is not of length M;
Raise ValueError if gamma is not inbetween zero and one;
x_{n-1} := x_0;
x_n := x_0 + \operatorname{epsilon} \cdot M;
i := 0;
while ||x_n - x_{n-1}||_2 < epsilon and i < K do
   temp := x_n;
   x_n = x_{n-1} - \gamma \cdot \operatorname{gradient}(x_{n-1});
   x_{n-1} := \text{temp};
   i := i + 1;
If i == K then success := False, Else success := True;
value := function(x_n);
pt := x_n
```

Algorithm 1: GradientDescent.run (Gradient Descent Algorithm)