

FAN0		FAN1		FAN2		JUMPER FAN		
GND	PB0	GND	PB1	GND	PB2	24V	VCC	12V

RGB				JUMPER RGB			UART1	
B PB7 B	R PB6 R	G PB5 G	VCC VCC	24V	VCC	12V	GND	VCC

X-		Y-		Z-		X+		Y+		Z+		UART1	
PB14	PB13	PA0	PA1	PA2	PA3	GND	GND	GND	GND	GND	GND	PA9/TX	PA10/RX
GND	GND	GND	GND	GND	GND	VCC	VCC	VCC	VCC	VCC	VCC		

MOTOR				SWD			
2B	2A	1A	1B	3.3V	GND	PA13	PA14

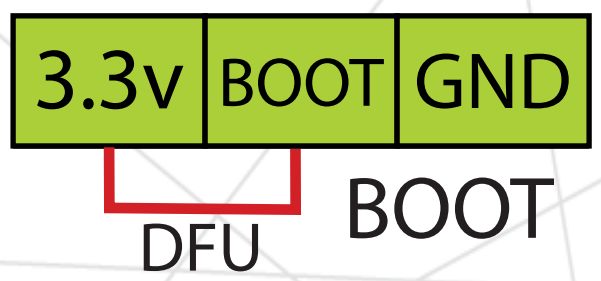
H0	H1	H2	HB
GND PB3	GND PB4	GND PB15	GND PC8

TB	T0	T1	T2
PB14 PC3	GND PC0 3.3V	GND PC1 3.3V	GND PC1 3.3V

EXP1					SPI			
GND	PD0	PC10/TX3	PC11/RX3	PC9	CD	MOSI	CS	RST
5V	PD1	PC12	PD2	PA8	5V	MISO	SCK	GND

EXP2					I2C			
GND	PB10	PC7	PC6	MISO/PA6	VCC	GND	SDA	SCL
5V	RST	MOSI/PA7	SS/PA4	SCK/PA5				

Diag Pin = Endstop  
Es. X- = DiagX = PB14



if you see differences between the silkscreen and the pins and why the drawing on the board is wrong.  
In particular the Heater and UART1