# CN-Advanced L32

#### Distance Vector Routing

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## Distance Vector Routing

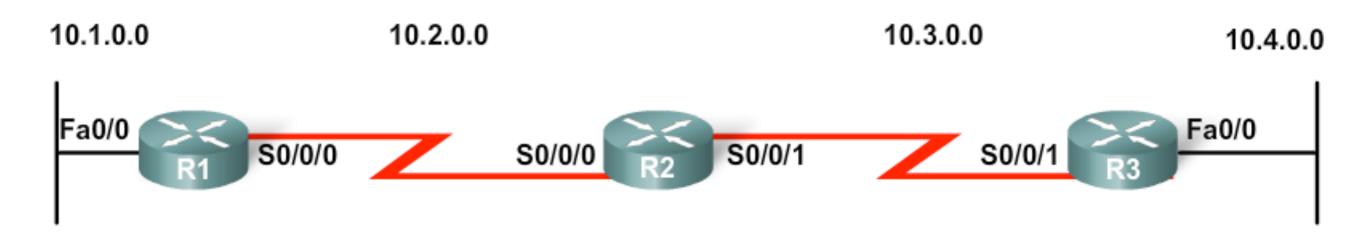
- Assumption
  - Each node knows cost of its directly connected link
  - A down (or non-existent) link cost is taken as infinity
- Distributed
  - Each node receives info from neighbors
  - Computes routing and distributes to neighbors
  - No central computation
- Iterative
  - Routing computation stops when no more info exchange
  - It is self terminating no external control
- Asynchronous
  - Each node does not work in sync with others

#### Distance Vector Routing

- Does not allows a router to know exact topology
- Uses router as signposts along the path to dst<sup>n</sup>
- Sends periodic updates
- Core of the DV protocol
  - Bellman Ford Algorithm
- Works best in following type of situations
  - Network is simple and flat
    - Does not require hierarchical design
  - Administrators do not have enough knowledge
    - Configure/troubleshoot link state protocols
  - Worst case convergence time is not a concern

# DV Routing - Example

#### **Initial Network**



Network	Interface	Нор
10.1.0.0	Fa0/0	0
10.2.0.0	S0/0/0	0

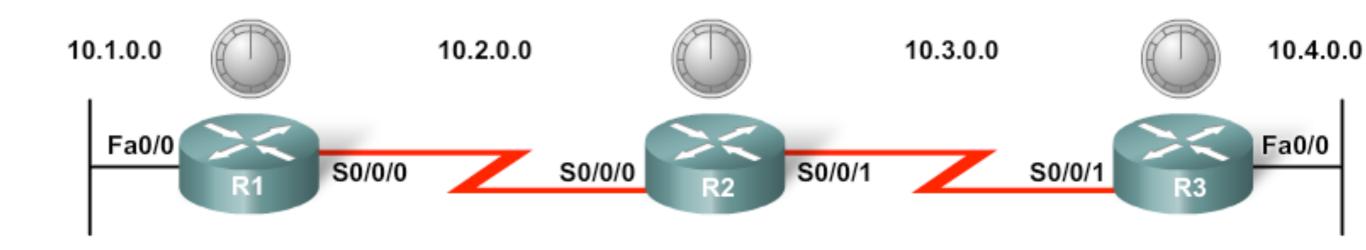
Network	Interface	Нор
10.2.0.0	\$0/0/0	0
10.3.0.0	S0/0/1	0

Network	Interface	Нор
10.3.0.0	S0/0/0	0
10.4.0.0	Fa0/0	0

Src: CCNA Module 2

#### DV Routing - Example

After the exchange of routing packets



Network	Interface	Нор
10.1.0.0	Fa0/0	0
10.2.0.0	\$0/0/0	0
10.3.0.0	\$0/0/0	1
10.4.0.0	S0/0/0	2

Network	Interface	Нор
10.2.0.0	S0/0/0	0
10.3.0.0	S0/0/1	0
10.1.0.0	S0/0/0	1
10.4.0.0	S0/0/1	1

Network	Interface	Нор
10.3.0.0	S0/0/1	0
10.4.0.0	Fa0/0	0
10.2.0.0	S0/0/1	1
10.1.0.0	S0/0/1	2

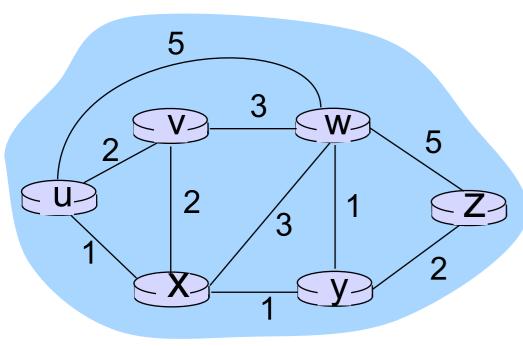
Src: CCNA Module 2

Bellman-Ford equation (dynamic programming)

```
let
  d_{x}(y) := cost of least-cost path from x to y
then
  d_{x}(y) = min_{v} \{c(x,v) + d_{v}(y)\}
                          cost from neighbor v to destination y
                    cost to neighbor v
               min taken over all neighbors v of x
```

#### Bellman-Ford example

#### Compute D<sub>u</sub>(z):



For u's neighbors: v, x, w, we have

$$d_v(z) = ?, d_x(z) = ?, d_w(z) = ?$$

$$d_v(z) = 5$$
,  $d_x(z) = 3$ ,  $d_w(z) = 3$ 

B-F equation says:

equation says:  

$$d_{u}(z) = \min \{ c(u,v) + d_{v}(z), c(u,x) + d_{x}(z), c(u,w) + d_{w}(z) \}$$

$$= \min \{ 2 + 5, 1 + 3, 5 + 3 \}$$

$$= 4$$

node achieving minimum is next hop in shortest path, used in forwarding table

- $D_{x}(y) = estimate of least cost from x to y$ 
  - actual least cost from x to y is represented as d<sub>x</sub>(y)
  - node x maintains distance vector
    - $\mathbf{D}_{\mathsf{x}} = [\mathsf{D}_{\mathsf{x}}(\mathsf{y}): \mathsf{y} \in \mathsf{N}]$
- Node x:
  - knows cost to each neighbor v: c(x,v)
  - maintains its neighbors' distance vectors.
  - For each neighbor v, it maintains

$$\mathbf{D}_{\mathsf{v}} = [\mathsf{D}_{\mathsf{v}}(\mathsf{y}): \mathsf{y} \in \mathsf{N}]$$

#### key idea:

- From time-to-time, each node sends its own distance vector estimate to neighbors
- When x receives new DV estimate from neighbor v, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow min_v\{c(x,v) + D_v(y)\}\$$
for each node  $y \in N$ 

• Under minor, natural conditions, the estimate  $D_x(y)$  converges to the actual least cost  $d_x(y)$ 

# iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

#### distributed:

- each node notifies neighbors only when its DV changes
  - neighbors then notify their neighbors if necessary

#### each node:

initialize  $D_x(y) = c(x,y)$ 

wait for (change in local link cost or msg from neighbor)

recompute estimates

if DV to any dest has changed, *notify* neighbors

## DV Algorithm

/\* Initialisation - for each node x \*/
for all destinations y in N:  $D_x(y) = c(x,y) / * c(x,y) = \infty \text{ for non neighbour */}$ for each neighbor w  $D_w(y) = ? \text{ for all destinations y in N}$ for each neighbour w  $\text{send distance vector } D_x = [D_x(y): y \text{ in N}] \text{ to w}$ 

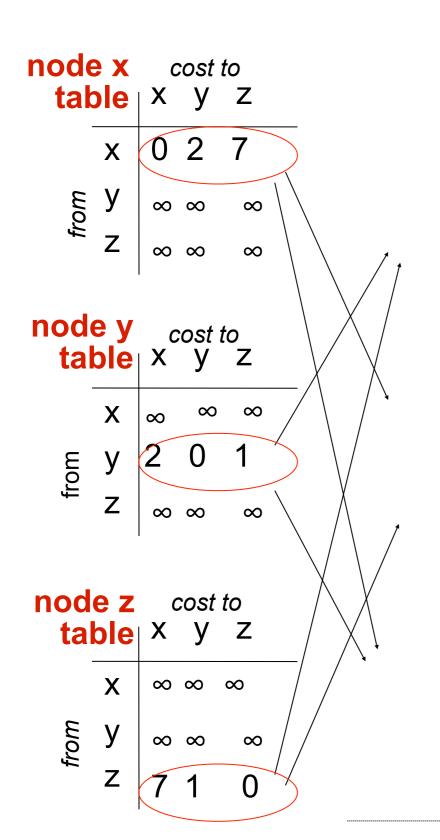
#### DV Algorithm

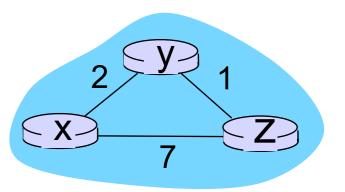
Loop /\* for each node x \*/
wait for (change in local link cost
or msg from neighbor)

```
for each y in N:

D_x(y) = \min_v\{c(x,v) + D_v(y)\}
```

if Dx(y) changed for any destination y send  $D_x = [D_x(y): y \text{ in } N]$  to all neighbour Forever

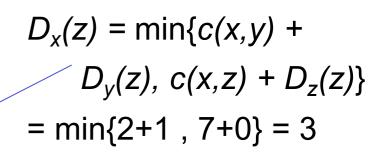


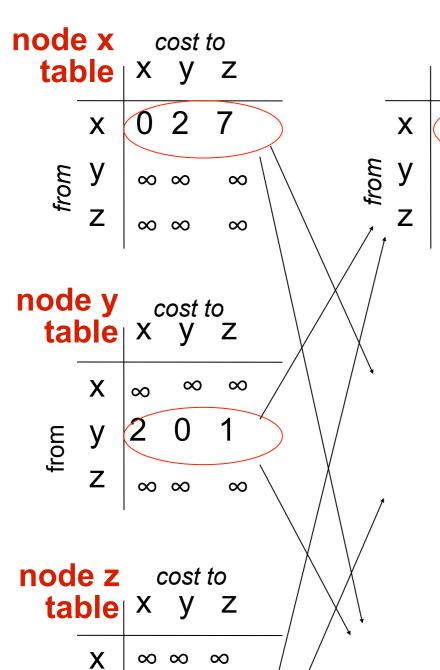


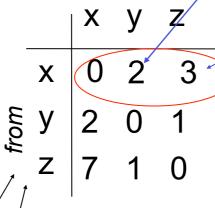
time -

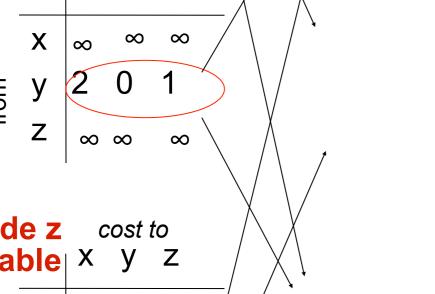
$$D_x(y) = min\{c(x,y) + D_y(y), c(x,z) + D_z(y)\}$$
  
=  $min\{2+0, 7+1\} = 2$ 

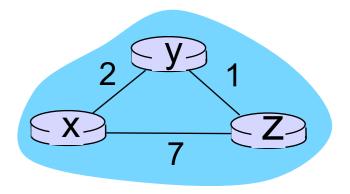
cost to











time

 $\infty$   $\infty$ 

 $\infty$ 

0

from

У

Z

$$D_{x}(y) = \min\{c(x,y) + D_{y}(y), c(x,z) + D_{z}(y)\}$$

$$= \min\{2+0, 7+1\} = 2$$

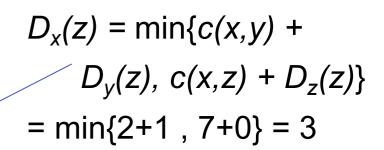
$$\begin{array}{c|cccc} node & x & cost to \\ \hline table & x & y & z \\ \hline x & 0 & 2 & 7 \\ \hline x & 0 & 2 & 3 \\ \hline y & x & 0 & 2 & 3 \\ \hline y & x & 0 & 2 & 3 \\ \hline y & 2 & 0 & 1 \\ \hline z & 7 & 1 & 0 \\ \hline \end{array}$$

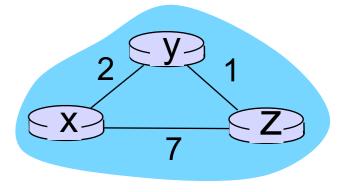
$$\begin{array}{c|ccccc} node & x & cost to \\ \hline x & y & z \\ \hline \hline x & 0 & 2 & 3 \\ \hline y & 2 & 0 & 1 \\ \hline z & 7 & 1 & 0 \\ \hline \end{array}$$

$$\begin{array}{c|ccccc} node & x & y & z \\ \hline x & 0 & 2 & 7 \\ \hline y & 2 & 0 & 1 \\ \hline z & 7 & 1 & 0 \\ \hline \end{array}$$

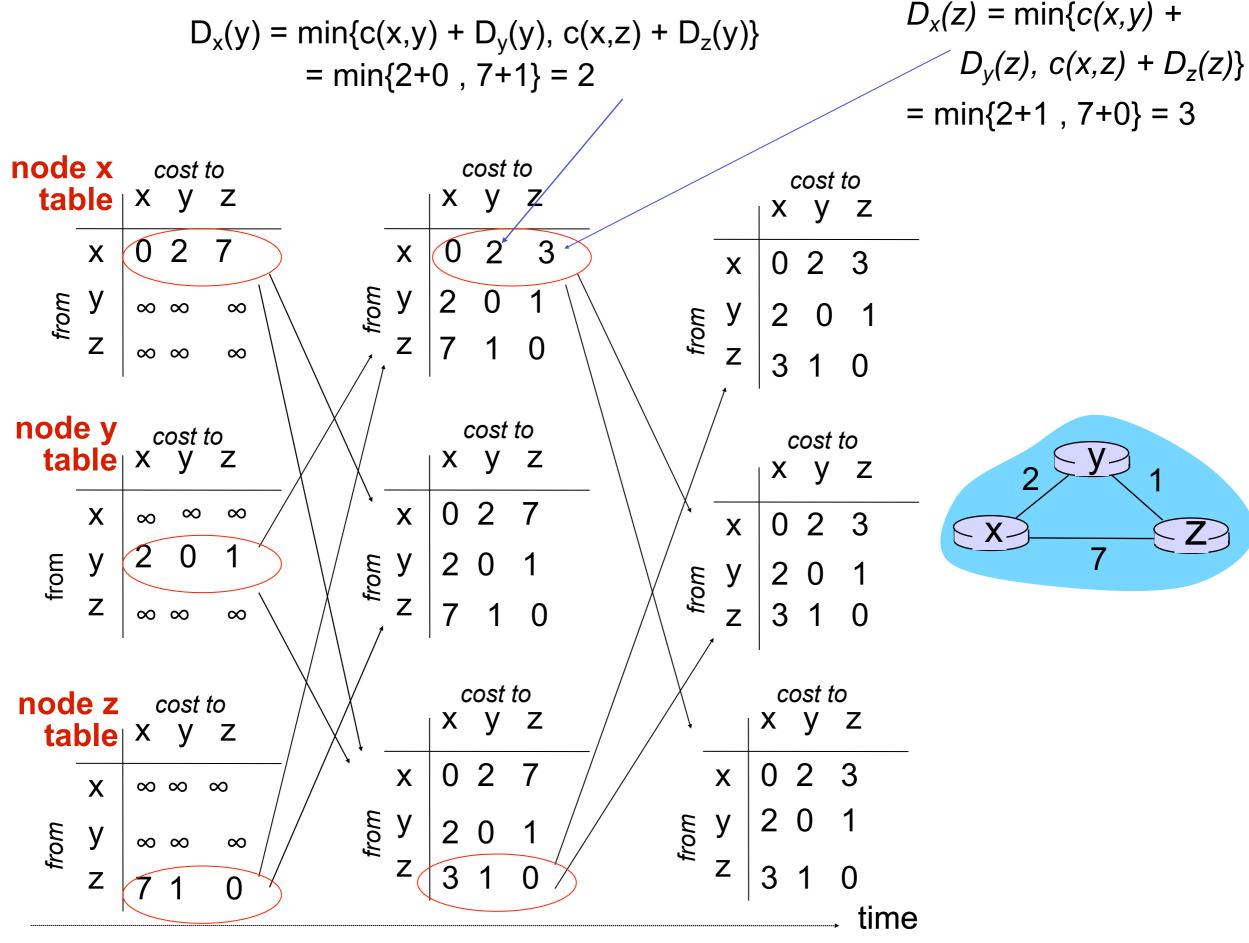
$$\begin{array}{c|ccccc} node & x & y & z \\ \hline x & 0 & 2 & 7 \\ \hline y & 2 & 0 & 1 \\ \hline z & 7 & 1 & 0 \\ \hline \end{array}$$

$$\begin{array}{c|ccccc} node & x & y & z \\ \hline x & 0 & 2 & 7 \\ \hline y & 2 & 0 & 1 \\ \hline z & 7 & 1 & 0 \\ \hline \end{array}$$





\_time



## **DV** Routing

- Issues
  - Routing Loop
  - Count to Infinity
  - Slow Convergence
    - link cost changes (increases)

## Summary

- Each node knows only its neighbours
- Each node knows cost to all nodes
  - A node does not know the topology of the network
- A node receives cost of all nodes from its neighbours