Charging Current

The current drawn by the line capacitance is called changing current. This charging current can introduce problems when a transmission line is in operation.

for example, in underground cables, the changing current is Significant due to the fact that the distance between Conductors in underground cables is very small.

Changing current can be calculated as follows:

$$\frac{1}{2 \cos p} = \frac{\sqrt{2} an}{\sqrt{2} \cos p} = \frac{\sqrt{2}$$

The reactive power associated with the Changing current is given as

$$Q_{chg} = \frac{v_{an}^2}{v_{cap}} = \frac{v_{an}}{-L} = -\omega C_{an} v_{an}^2$$

Note: The negative Sign shows that the line is supplying reactive power to the line.

Representation of Transmission Lines

In this lecture, we will leverage the four parameters of a transmission line (resistance, Inductance, Capacitance, & Conductance) to model transmission lines.

Transmission lines can be divided into three types (namely long, medium, and short lines) based on their length.

For Short and medium lines, we consider the parameters of transmission lines we calculated earlier to be lumped at a point along the transmission line. This simplification does not introduce significant errors in calculations. However, for long lines, we do not total use the lump strategy. Rather we arrider the line parameters to be distributed along the line. The table below gives defails about Short, medium, and long transmission line models:

Table: Transmission line models

Type of Length Remarks

Short L & 80 Km R & L weed. C omitted because

It is negligible.

Medium & & < L & C weed

Medium & & < L & & C weed

Medium & & < L & & C weed

Medium & & < L & & C weed

Medium & & < L & & C weed

Medium & & < L & & C weed

Medium & & < L & & C weed

Medium & & < C weed

Medium & < C weed

Medium & & < C w

Long 17250 KM R, L& C assumed to be distributed

Note that for a linear passive, bilateral two-port return, the following equation is always satisfied:

XD-BC=1

Also, the units of the Constants are as follows.

A = D = [domensionless (no units)]

B = [ohms]

C = [Mhos or Signers].

Voltage Regulation (V.R)

It can be defined as the percentage change in the magnitude of the receiving and voltage (expressed as parent of full-load voltage) when the boad is varied from no-boad to full-boad.

Mathematically,

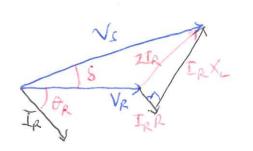
Percent V.R = $\left| V_R(NL) \right| - \left| V_R(FL) \right|_X 100$

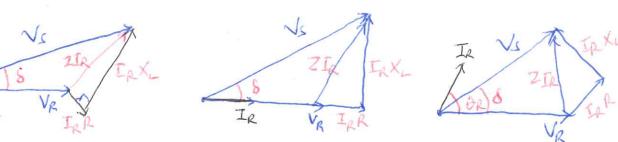
where VP(NI) = receiving end voltage at no-load; VRGFI = VR at full load. We are interested in Calculating percent V. R became we would like to keep the power quality at the consumers and Constant irrespective of load Variations. One way of satisfying the customer is by keeping the supply voltage Constant over a wide range of load anditions.

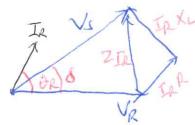
However, depending on load conditions & the Impedance of the transmission line, the required sending-end

Voltage (Vs) to satisfy the receiving-send voltage Constraint will change.

Effect of former factor on sending and voltage







(a) Lagging power factor

(b) Unity Power factor

(c) leading power factor

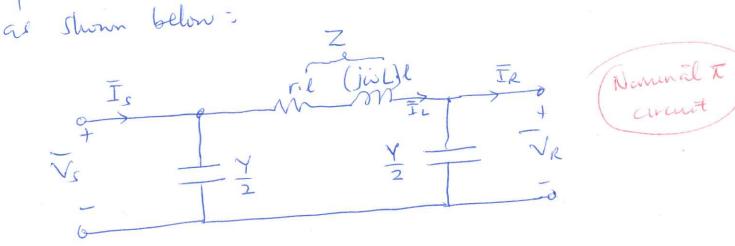
Fig Nos	Difference	Remarks
(a)	Ip is lagging Va	Required larger Vs compared to (b)
(6)	Iz is in-phase with $V_R - \theta_R = 0^\circ$	Baseline Case
(4)	IR is leading VR	Requires Lower Vs compared to

Calculating Voltage Regulation for a short-line At no-load, IR = 0; From ABCD constants band equation for a short line, VR(NL) = Vs But A = 1 for short line Percent V.A = NS |- |VR(FL)|

6 Medium length transmission bies

When the length of the line exceeds sokm, the line Changing current becomes appreciable, thui the Shunt Capacitaire cannot be reglected.

For medmen lines, we arnsider half of the Shrint Capacitance to be lumped at each end of the line



; g = 0
C = Capacitance per length

$$w = \text{fundamental frequercy in}$$

 vad/s .
 $l = \text{length-o} + \text{the line}$.

Applying KCL at the sending end and at the receiving end,

$$\overline{I}_{S} = \overline{I}_{L} + \frac{\sqrt{2}}{\sqrt{2}} \overline{V}_{S}$$

$$\overline{I}_{L} = \overline{I}_{R} + \frac{\sqrt{2}}{\sqrt{2}} \overline{V}_{R}$$

Applying KVL grelds

Solving for
$$\nabla_s$$
 and \vec{I}_s yield

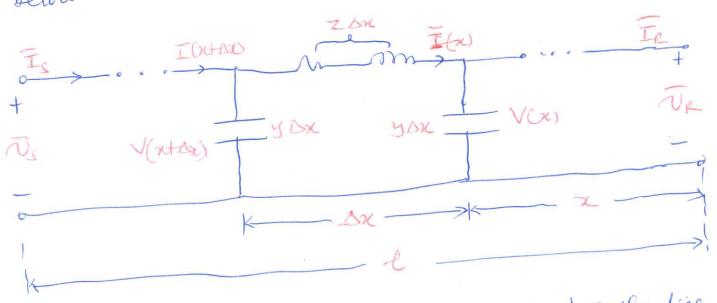
$$\begin{pmatrix} \nabla_s \\ = \\ 1 \end{pmatrix} = \begin{pmatrix} 1 + \frac{YZ}{2} \\ Y (1 + \frac{YZ}{4}) \end{pmatrix} = \begin{pmatrix} \nabla_R \\ -\frac{1}{2} \\ 1 \end{pmatrix}$$
Where $A = 1 + \frac{YZ}{2}$; $B = Z$

$$C = Y(1 + \frac{YZ}{4}); D = 1 + \frac{YZ}{2}$$

Quick question: Check if the ABCD Constants for a medium line satisfies the equation: AD-BC=1.

(c) The long transmission line

transmission lines, we will consider the line parameters to be distributed across the line. With the long transmission line model, we can calculate the voltage, current and power at any point on the transmission line provided we know the voltage, current and power at one point along the line. Consider the diagram below.



where x: distance from the receiving end of the line dx: differential element of length.

Zon: Series impedance of the Infinitely small section of length In.

y In: Shunt admittance of the Infinitely Small Section of length In.

V: Voltage phasor that varies with x.

I: Current Phasor that varies with x.

From
$$EVL$$
,

 $V(x+\Delta x) - V(x) = 2I(x)$
 Δx

Taking limit as $\Delta x - 20$,

 $dV(x) = 2I(x)$

From ECL ,

 $I(x+\Delta x) - I(x) = gV(x+\Delta x)$
 Δx

Taking limit as $\Delta x \to 0$,

 $dI(x) = gV(x)$
 Δx

Taking limit as $\Delta x \to 0$,

 $dI(x) = gV(x)$
 dx

Differentiating (x) and substituting from (x), yields

 $d^2V(x) = 2dI(x) = 2gV(x)$

Let $g^2 = 2g$ where $g^2 = 2gV(x)$

Then $d^2V(x) = 2dI(x) = 2gV(x)$
 $dx^2 = 2gV(x) = 2dI(x)$

Then $d^2V(x) = 2dI(x) = 2gV(x)$

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Then $d^2V(x) = 2dI(x) = 2gV(x)$

Then $d^2V(x) = 2dI(x) = 2gV(x)$
 $dx^2 = 2gV(x) = 2dI(x)$

After manipulating the equation, we get $\overline{V(n)} = \overline{V_R} \cdot Cosh(\pi n) + \overline{I_R}Z_C Sinh(\pi n)$ $\overline{I(n)} = \overline{V_R} \cdot Sich(\pi n) + \overline{I_R} \cdot Cosh(\pi n)$ $\overline{I(n)} = \overline{V_R} \cdot Sich(\pi n) + \overline{I_R} \cdot Cosh(\pi n)$

Where $Z_c = \sqrt{\frac{2}{y}}$ and it is Known as the characteristic Impedance $V_R = V(x=0)$

 $V_R = V(x=0)$ $\overline{I}_R = \overline{\mathbf{T}}(x=0)$

At the sending end, x=l: $\overline{V(x=l)} = \overline{V_s} = \overline{V_e} \cosh(\gamma l) + \overline{I_r} Z_c \sin h(\gamma l)$

 $\overline{I}(x=1) = \overline{I}_s = \frac{\overline{J}_R}{Z_c} \cdot \sin h(\gamma_1) + \overline{I}_R \cdot \cosh(\gamma_1)$

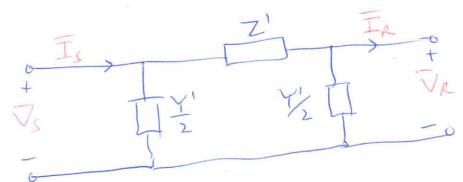
where $A = \begin{bmatrix} Co_3 h(\chi l) & Z_c, Sii h(\chi l) \\ \frac{1}{Z_c} Sii h(\chi l) & Co_3 h(\chi l) \end{bmatrix}$

Quiek græstion: Venty if A = D and AD - BC = 1in the long transmission line equation presented above.

Equivalent T- model

For circuit modeling and analysis purposes, It is more convenient to represent the long transmission line model Using the nominal at-representation as it was done for the medium transmission line.

Consider the figure below



The prime in the series impedance and shunt admittance denote the quantities are equivalent of the ones obtained for the medium length lines.

For the equivalent To-model, we can write

$$\overline{I}_{S} = \left(1 + \frac{Z'Y'}{2}\right)\overline{U}_{R} + \frac{Z'}{2}\overline{I}_{R}$$

$$\overline{I}_{S} = Y'\left(1 + \frac{Z'Y'}{4}\right)V_{R} + \left(1 + \frac{Z'Y'}{2}\right)\overline{I}_{R}$$

compening the ABCD constants in the equation above with the ABCD constants obtained for the long line, we get

$$Z' = Z \cdot \frac{\sinh(\chi l)}{\chi l}$$

where Z = Z.l Total distributed Impedance impedance Y' = Y tanh (242)

Total

Total

admittance

admittance

Thus, we can redraw the long transmirmi line model to be

Z' = Z Such(xl) Z' = Z Such(xl) V_{s} V_{s}