

# Assignment 4 Solution

**6.18**  $x^3 + 8x^2 + 2x - 40 = 0$

$$x(0) = 1$$

$$J(i) = \left. \frac{df}{dx} \right|_{x=x(i)} = [3x^2 + 16x + 2]_{x=x(i)}$$

In the general form:

$$x(i+1) = x(i) + \frac{1}{3x(i)^2 + 16x(i) + 2} \times (-x(i)^3 - 8x(i)^2 - 2x(i) + 40)$$

Using  $x(0) = 1$ , we arrive at

$i$	0	1	2	3	4
$x$	1	2.381	1.9675	1.9116	1.9106
$\varepsilon$	1.381	0.1737	0.0284	5.19E-4	

After 4 iterations,  $\varepsilon < 0.001$ .

$$\therefore x = 1.9106$$

The textbook uses  $\frac{x(i+1) - x(i)}{x(i)} < \varepsilon$  as the stopping criterion. You can also use  $x(i+1) - x(i) < \varepsilon$  or  $f(x(i+1)) < \varepsilon$  as discussed in class.

$$x^0 = \begin{bmatrix} 1.0 \\ 0.5 \end{bmatrix}$$





stopping condition:  $\varepsilon = 0.005$

$$F(x) = \begin{bmatrix} e^{x_1 x_2} - 1.2 \\ \cos(x_1 + x_2) - 0.5 \end{bmatrix}$$



$$J(x) = \begin{bmatrix} x_2 e^{x_1 x_2} & x_1 e^{x_1 x_2} \\ -\sin(x_1 + x_2) & -\sin(x_1 + x_2) \end{bmatrix}$$

Find the next value of  $X$  using:

- $J(X^{(K)}) \cdot (X^{(K+1)} - X^{(K)}) = -F(X^{(K)})$ . Solve the system of linear equations to get  $(X^{(K+1)} - X^{(K)})$ . Then, using values of  $X^{(K)}$ , you can calculate  $X^{(K+1)}$
- Alternatively, you can find the inverse of the Jacobian, and use:  $X^{(K+1)} = X^{(K)} - J(X^{(K)})^{-1} F(X^{(K)})$  to calculate  $X^{(K+1)}$  directly.

K	$X^{(k)}$	$F(X^{(k)})$	$J(X^{(k)})$	$X^{(k+1)}$	$\ F(X^{(k)})\ $	Another iteration?
1	$\begin{bmatrix} 1 \\ 0.5 \end{bmatrix}$	$\begin{bmatrix} 0.4487 \\ -0.4293 \end{bmatrix}$	$\begin{bmatrix} 0.8244 & 1.6487 \\ -0.9975 & -0.9975 \end{bmatrix}$	$\begin{bmatrix} 0.6836 \\ 0.386 \end{bmatrix}$	0.4487	
2	$\begin{bmatrix} 0.6836 \\ 0.386 \end{bmatrix}$	$\begin{bmatrix} 0.102 \\ -0.0196 \end{bmatrix}$	$\begin{bmatrix} 0.5026 & 0.8901 \\ -0.877 & -0.877 \end{bmatrix}$	$\begin{bmatrix} 0.8956 \\ 0.1518 \end{bmatrix}$	0.102	
3	$\begin{bmatrix} 0.8956 \\ 0.1518 \end{bmatrix}$	$\begin{bmatrix} -0.0544 \\ -0.0001 \end{bmatrix}$	$\begin{bmatrix} 0.1739 & 1.026 \\ -0.8661 & -0.8661 \end{bmatrix}$	$\begin{bmatrix} 0.8315 \\ 0.2157 \end{bmatrix}$	0.054	
4	$\begin{bmatrix} 0.8315 \\ 0.2157 \end{bmatrix}$	$\begin{bmatrix} -0.0036 \\ 0 \end{bmatrix}$	$\begin{bmatrix} 0.2580 & 0.9949 \\ -0.866 & -0.866 \end{bmatrix}$	$\begin{bmatrix} 0.8267 \\ 0.2205 \end{bmatrix}$	0.0036	
5	$\begin{bmatrix} 0.8267 \\ 0.2205 \end{bmatrix}$	$\begin{bmatrix} 0 \\ 0 \end{bmatrix}$	$\begin{bmatrix} 0.2646 & 0.992 \\ -0.866 & -0.866 \end{bmatrix}$	$\begin{bmatrix} 0.8267 \\ 0.2206 \end{bmatrix}$	0.000	Nope!

b) Same problem but setting  $x^0 = \begin{bmatrix} 1.0 \\ 2.0 \end{bmatrix}$

K	$X^{(k)}$	$F(X^{(k)})$	$J(X^{(k)})$	$X^{(k+1)}$	$\ F(X^{(k)})\ $	Another iteration?
1	$\begin{bmatrix} 1 \\ 2 \end{bmatrix}$	$\begin{bmatrix} 6.1891 \\ -1.49 \end{bmatrix}$	$\begin{bmatrix} 14.7781 & 7.3891 \\ -0.1411 & -0.1411 \end{bmatrix}$	$\begin{bmatrix} 10.7207 \\ -18.2791 \end{bmatrix}$	6.189	
2	$\begin{bmatrix} 10.7207 \\ -18.2791 \end{bmatrix}$	$\begin{bmatrix} -1.2 \\ -0.2087 \end{bmatrix}$	$\begin{bmatrix} 0 & 0 \\ 0.9566 & 0.9566 \end{bmatrix}$			

Cannot proceed anymore since  $J(x)$  is not invertible.

6.28

a)  $Y_{[1,1]} = 2 - j4 + 3 - j6 = 5 - j10 = 11.18 \angle -63.43^\circ$

$Y_{[2,2]} = 2 - j4 = 4.47 \angle -63.43^\circ$

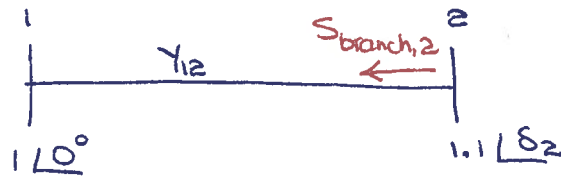
$Y_{[3,3]} = 3 - j6 = 6.71 \angle -63.43^\circ$

$Y_{[2,1]} = Y_{[1,2]} = -2 + j4 = 4.47 \angle 116.57^\circ$

$Y_{[1,3]} = Y_{[3,1]} = -3 + j6 = 6.71 \angle 116.57^\circ$

$Y_{[2,3]} = Y_{[3,2]} = 0$

b) at bus 2,  $P_{gen,2} - P_{load,2} - P_{branch,2} = 0$   
 $1.5 - 0 - P_{branch,2} = 0$



$$\begin{aligned} S_{branch,2} &= \bar{V}_2 \cdot \bar{I}_{12}^* \\ &= \bar{V}_2 \cdot [(\bar{V}_2 - \bar{V}_1) \cdot Y_{12}]^* \\ &= \bar{V}_2 \cdot Y_{12}^* \cdot (\bar{V}_2 - \bar{V}_1)^* \\ &= \bar{V}_2 \cdot Y_{12}^* \cdot \bar{V}_2^* - \bar{V}_2 \cdot Y_{12}^* \bar{V}_1^* \\ &= (\bar{V}_2)^2 \cdot Y_{12} \angle -\theta_{12} - \bar{V}_2 \angle \delta_2 \cdot Y_{12} \angle -\theta_{12} \cdot \bar{V}_1 \angle -\delta_1 \\ &= (\bar{V}_2)^2 \cdot Y_{12} \angle -\theta_{12} - \bar{V}_1 \cdot \bar{V}_2 \cdot Y_{12} \angle \delta_2 - \delta_1 - \theta_{12} \end{aligned}$$

This is the Pbranch equation with Y expressed in polar coordinates.

$\therefore P_{branch,2} = (\bar{V}_2)^2 (Y_{12}) \cdot \cos(-\theta_{12}) - \bar{V}_1 \cdot \bar{V}_2 \cdot Y_{12} \cos(\delta_2 - \delta_1 - \theta_{12})$

Please note the difference between  $Y_{12}$  and  $Y_{[1,2]}$

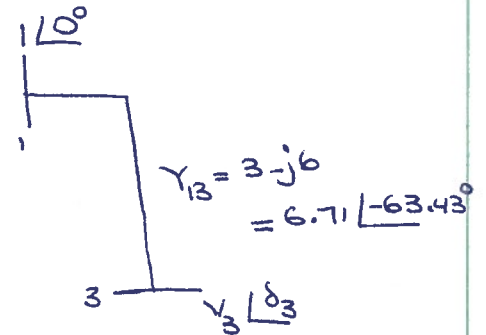
reminder  $Y_{12} = 2 - j4 = 4.47 \angle -63.43^\circ$

$$\therefore 0 = 1.5 - 0 - (1.1)^2 (4.47) \cos(+63.43^\circ) + (1)(1.1)(4.47) \cos(\delta_2 + 63.43^\circ)$$

$$\text{solve for } \delta_2 : \delta_2 = 15.795^\circ$$

c) Similar to part b),

$$P_{\text{branch},3} = (V_3)^2 (Y_{13}) \cos(-\theta_{13}) - V_1 V_3 Y_{13} \cos(\delta_3 - \delta_1 - \theta_{13})$$



$$\therefore -1.5 - 0 - (V_3)^2 (6.71) \cos(63.43^\circ) + (1) V_3 (6.71) \cos(\delta_3 + 63.43^\circ) = 0 \quad (i)$$

$$Q_{\text{branch},3} = (V_3)^2 (Y_{13}) \sin(-\theta_{13}) - V_1 V_3 Y_{13} \sin(\delta_3 - \delta_1 - \theta_{13})$$

$$\therefore 0.8 - 0 - (V_3)^2 (6.71) \sin(63.43^\circ) + (1) V_3 (6.71) \sin(\delta_3 + 63.43^\circ) = 0 \quad (ii)$$

Solve (i) & (ii) to get  $V_3$  &  $\delta_3$ , painfully!

$$V_3 = 0.9723 \text{ pu}$$

$$\delta_3 = -15.1^\circ$$

$$d) P_{\text{branch},1} = (V_1)^2 (Y_{12}) \cos(-\theta_{12}) - V_1 V_2 Y_{12} \cos(\delta_1 - \delta_2 - \theta_{12}) + (V_1)^2 (Y_{13}) \cos(-\theta_{13}) - V_1 V_3 Y_{13} \cos(\delta_1 - \delta_3 - \theta_{13})$$

plug in all values,

$$P_{\text{branch},1} = 0.39 \text{ pu}$$

$$P_{\text{gen},1} - P_{\text{load},1} - P_{\text{branch},1} = 0$$

$$\therefore P_{\text{gen},1} = 0.39 \text{ pu}$$

$$e) P_{\text{loss}} = P_{\text{gen}} - P_{\text{load}}$$

$$= P_{\text{gen},1} + P_{\text{gen},2} - P_{\text{load},3}$$

$$= 0.39 + 1.5 - 1.5$$

$$= 0.39 \text{ pu}$$

**6.30**

$6.25 - j18.695$	$-5.00 + j15.00$	$-1.25 + j3.75$	0	0
$-5.00 + j15.00$	$12.9167 - j38.665$	$-1.6667 + j5.00$	$-1.25 + j3.75$	$-5.00 + j15.00$
$-1.25 + j3.75$	$-1.6667 + j5.00$	$8.7990 - j32.2294$	$-5.8824 + j23.5294$	0
0	$-1.25 + j3.75$	$-5.8824 + j23.5294$	$9.8846 - j36.4037$	$-2.7523 + j9.1743$
0	$-5.00 + j15.00$	0	$-2.7523 + j9.1743$	$7.7523 - j24.1443$

**6.31** First, we need to find the per-unit shunt admittance of the added capacitor.

$$75 \text{ Mvar} = 0.75 \text{ p.u.}$$

To find  $Y$ , we use the relation

$$S = V^2 Y$$

$$Y = \frac{S}{V^2} = \frac{0.75}{1^2} = 0.75 \text{ p.u.}$$

Now, we can find  $Y_{44}$ 

$$\begin{aligned}
 Y_{44} &= \frac{1}{0.08 + j0.24} + \frac{1}{0.01 + j0.04} + \frac{1}{0.03 + j0.10} \\
 &\quad + j \frac{0.05 + 0.01 + 0.04}{2} + j0.75 \\
 &= 9.8846 - j35.6537
 \end{aligned}$$