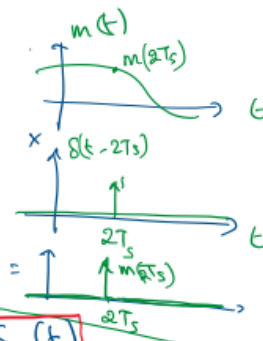


Monday, April 6, 2020
8:50 AM

Diagram illustrating the sampling process:

A continuous-time signal $m(t)$ is input to a "Sampling" block. The output is a sampled signal $m_s(t)$, which is a continuous-time signal that only keeps on discrete values of $m(t)$.


$$\delta_{T_s}(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

train of impulses

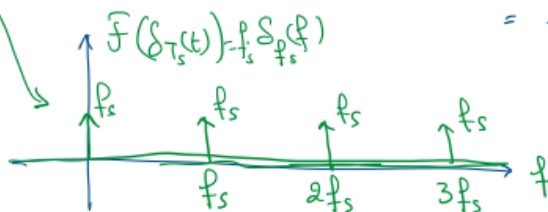
$$m_s(t) = m(t) \cdot \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

$$m_s(t) = \sum_{n=-\infty}^{\infty} m(t) \cdot \delta(t - nT_s)$$

$$m_s(t) = \sum_{n=-\infty}^{\infty} m(nT_s) \cdot \delta(t - nT_s)$$

$$M_s(f) = M(f) * \mathcal{F}(\delta_{T_s}(t))$$

We have : $\mathbb{F}(S_{T_s+}) = p_s \cdot \delta_{p_s}(F)$ with $p_s = \frac{1}{T_s}$
 $= p_s \cdot \sum_{p=-\infty}^{\infty} \delta(F - n p_s)$

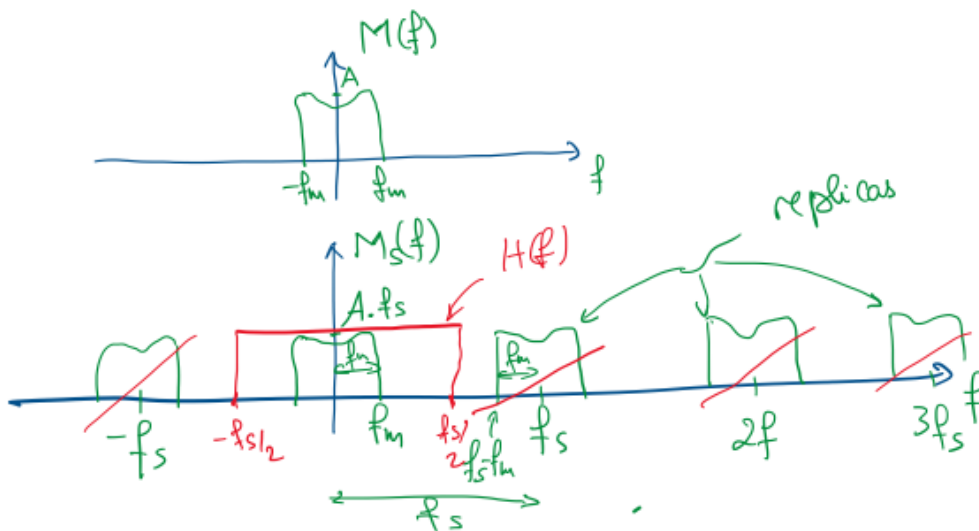


$$M_s(f) = M(f) * f_s \sum_{n=-\infty}^{\infty} \delta(f - n f_s)$$

$$M_s(f) = f_s \sum_{n=-\infty}^{\infty} \underbrace{M(f) * \delta(f - n f_s)}_{\text{a shift of } M(f) \text{ by } n f_s}$$

$$M_s(f) = f_s \sum_{n=-\infty}^{\infty} M(f - n f_s)$$

For example if :



If $f_s > 2f_m$, there is no overlap between the replicas (no aliasing).

In this case we can get back to $M(f)$ and therefore $m(t)$ using a low-pass filter.

In this case the sampling operation did not result in a loss of information.

* Reconstruction of sampled signal :

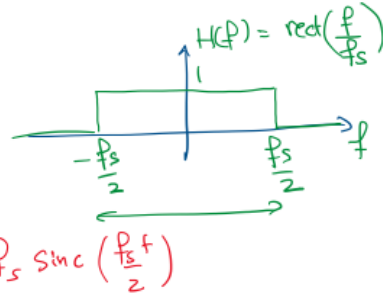
if $f_s > 2f_m$:



In frequency domain:

$$\boxed{f_s \cdot M(f) = M_s(f) \cdot H(f)}$$

$$= M_s(f) \cdot \text{rect}\left(\frac{f}{f_s}\right) \xrightarrow{F^{-1}} f_s \text{sinc}\left(\frac{f_s t}{2}\right)$$



In time domain:

$$\underbrace{f_s \cdot m(t)} = \underbrace{m_s(t)} * f_s \text{sinc}\left(\frac{f_s t}{2}\right)$$

$$= \sum_{n=-\infty}^{\infty} \underbrace{m(nT_s) \delta(t - nT_s)} * f_s \text{sinc}\left(\frac{f_s t}{2}\right)$$

$$\boxed{f_s m(t) = \sum_{n=-\infty}^{\infty} f_s m(nT_s) \cdot \text{sinc}\left(\frac{f_s}{2}(t - nT_s)\right)}$$