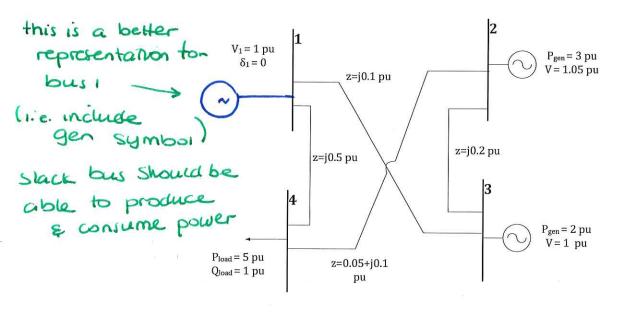
Tutorial 7

Consider the following system. The impedances (branches) between busses could represent lines or transformers in per unit.



- Identify bus types in this system
- Set up the X vector
- Set up Y_{bus}
- Write the equation f₁ (Real power flow equation at bus 1)

Power flow equations with Y_{bus} expressed in rectangular coordinates:

$$f_i = P_{gen,i} - P_{load,i} - \sum_{k=1}^{N} V_i V_k G[i, k] \cos(\delta_i - \delta_k)$$
$$- \sum_{k=1}^{N} V_i V_k B[i, k] \sin(\delta_i - \delta_k)$$

$$f_{N+i} = Q_{gen,i} - Q_{load,i} - \sum_{k=1}^{N} V_i V_k G[i, k] \sin(\delta_i - \delta_k) + \sum_{k=1}^{N} V_i V_k B[i, k] \cos(\delta_i - \delta_k)$$

. We organize power flow equations as:

$$F(x) = \begin{bmatrix} f_i \\ f_{n+i} \end{bmatrix} \begin{cases} N \\ N \end{cases} = \begin{bmatrix} Pean, i \\ Qean, i \end{bmatrix}$$

· Bus type :

Bus #	type	unknown		
1	Slack	Pgen,1	E	Ogen, 1
2	Genlar	83	8	agen, 2
3	Genlav	83	4	Qgen3
4	Non-gen	84	8	V4

- · Pload, z = Qload, z = 0. Bus 2 would still be a gen bus even if Pload, z or Qload, z #0. Same applies for bus 3.
- Bus 4 would still be a non-gen (load) bus even it $P_{load,4} = Q_{load,4} = 0 \quad las long as there is no gen connected to it).$

. The X vector is organized as follows:

· Setting up Yous :

$$Y_{1,3} = \frac{1}{Z_{1,3}} = \frac{1}{j_{0.1}} = j_{10}$$

$$Y_{i,4} = \frac{1}{Z_{i,4}} = \frac{1}{j_{0.5}} = -j^2$$

$$Y_{2,3} = \frac{1}{Z_{2,3}} = \frac{1}{j_{0,2}} = -j_{5}$$

$$Y_{2,4} = \frac{1}{Z_{2,4}} = \frac{1}{0.05 + j0.1} = 4 - j8$$

$$T_{bus} = \begin{bmatrix} -512 & 0.05 + 10.1 \\ -512 & 0 & +10 & +12 \\ 0 & 4-513 & 55 & -4+58 \\ 0 & 55 & -55 & 0 \\ 12 & -4+58 & 0 & 4-510 \end{bmatrix}$$

$$G_{bus} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 4 & 0 & -4 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$$

$$\begin{cases} B_{bus} = \begin{bmatrix} -12 & 0 & 10 & 2 \\ 0 & -13 & 5 & 8 \\ 10 & 5 & -15 & 0 \\ 2 & 8 & 0 & -10 \\ \end{bmatrix}$$

no j in the matrix! Y = G + 1B

fi : real power flow eq at bus 1

$$f_1 = P_{eqn,1} = P_{gen,1} - P_{spa,1} - V_1V_1 G_1V_1 T_1 \cos(S_1 - S_1)$$

$$-V_1V_2 G_1V_2 T_1 \cos(S_1 - S_2) - V_1V_3 G_1V_1 T_2 \cos(S_1 - S_3)$$

$$-V_1V_4 G_1V_1 T_1 \cos(S_1 - S_2) - V_1V_3 G_1V_1 T_3 \sin(S_1 - S_1)$$

$$-V_1V_2 G_1V_2 T_3 \sin(S_1 - S_2) - V_1V_3 G_1V_1 T_3 \sin(S_1 - S_3)$$

$$-V_1V_4 G_1V_1 T_3 \sin(S_1 - S_2) - V_1V_3 G_1V_1 T_3 \sin(S_1 - S_3)$$

$$-V_1V_4 G_1V_1 T_3 \sin(S_1 - S_2) - V_1V_3 G_1V_1 T_3 \sin(S_1 - S_3)$$

$$-V_1V_4 G_1V_1 T_3 \sin(S_1 - S_2) - V_1V_3 G_1V_1 T_3 \sin(S_1 - S_3)$$

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$$-V_1V_4 G_1V_1 T_3 \cos(S_1 - S_2) - V_1V_3 G_1V_1 T_3 \cos(S_1 - S_3)$$

$$-V_1V_4 G_1V_1 T_3 \cos(S_1 - S_1 - S_1 - V_1 T_3 \cos(S_1 - S_1 \cos(S_1 - S_1 - S_1$$

then, - Calculate F(x°). Likely 11F(x°) || #0

- improve x° by using the update term from NR come up with new vector x'.

- Repeat until we find optimal solution x*