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Report on Implementation of DFS, UCS, and A\* Algorithms

## Introduction:

In this project the main goal was to use several tree-search algorithms and heuristic functions to discover optimal or nearly optimal solutions for the routing problem.

## Depth First Search (DFS):

Implementation - >

- 1. It starts with a depote node and stack is used to manage the path.
- 2. After, nodes are marked as visited once they're included in a path.
- 3. As the path grows, the cumulative load is checked to ensure it doesn't exceed the capacity.
- 4. If a path returns to the depot and visits all store nodes, it is returned as the solution.
- 5. Else, it will explore furthermore, by using neighboring nodes.

Here is the Pseucode for better understanding:

#### Pseudo-Code:

- 1. Initialize a stack with the depot node and a set to track visited nodes.
- 2. While the stack is not empty:
  - ->Pop the latest path and get the current node.
  - -> Calculate cumulative load along the path.
  - ->If the path is complete (returns to the depot with all store nodes visited), return it.
  - ->Otherwise, explore neighboring nodes that haven't been visited and meet load constraints.
- 3. Return the last valid path or an empty solution.

## Uniform Cost Search (UCS):

The main point of the UCS is to explore path's based on the total cost by always choosing the lowest one.

## Implementation - >

- 1. A priority queue is used to keep track of paths by their cost.
- 2. The algorithm avoids revisiting nodes and checks that the total load doesn't go over capacity.
- 3. If a path goes back to the depot and visits all store nodes, it gives the outcome.

#### Pseucode:

- 1. Add the depot node to the priority queue and keep track of the lowest cost to each node.
- 2. While the queue has path's left:
  - ->Get the path with the lowest cost.
  - ->If the path completes by returning to the depot and visiting all stores, return it.
  - ->If not, keep exploring nearby nodes that don't exceed capacity.
- 3. Return the last path or return nothing at all.

#### Astar (A\*):

Heuristic Function: The heuristic is the estimated cost from a node to the depot.

# Implementation ->

- 1. A queue keeps track of paths based on their total cost, including the heuristic.
- 2. If a path goes back to the depot and visits all store nodes, then comes the outcome.
- 3. The algorithm tries not to exceed the capacity and revisitation.

### Pseucode:

- 1. Add the depot node to the queue, by also tracking the lowest costs and heuristics.
- 2. While the queue has paths:
  - a. Get the path with the lowest cost.

- b. If the path completes by returning to the depot and visiting all nodes, return the outcome.
- c. If not, keep exploring neighboring nodes, by checking it does not exceed the capacity and get nodes reviseted.
- 3. Return the last valid path or nothing at all.

## Runtime:

DFS has longer runtimes because of deeper exploration before backtracking. However, UCS and A\* have shorter runtimes because they use cost-based exploration.

# Memory Usage:

DFS uses less memory because it doesn't maintain a complete tree structure.

UCS and A\* require more memory due to their priority queues and heuristic calculations.