



Modern day monitoring and control challenges outlined on an industrial-scale benchmark fermentation process

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ABSTRACT

This paper outlines real-world control challenges faced by modern-day biopharmaceutical facilities through the extension of a previously developed industrial-scale penicillin fermentation simulation (*IndPenSim*). The extensions include the addition of a simulated Raman spectroscopy device for the purpose of developing, evaluating and implementation of advanced and innovative control solutions applicable to biotechnology facilities. *IndPenSim* can be operated in fixed or operator controlled mode and generates all the available on-line, off-line and Raman spectra for each batch. The capabilities of *IndPenSim* were initially demonstrated through the implementation of a QbD methodology utilising the three stages of the PAT framework. Furthermore, *IndPenSim* evaluated a fault detection algorithm to detect process faults occurring on different batches recorded throughout a yearly campaign. The simulator and all data presented here are available to download at www.industrialpenicillinsimulation.com and acts as a benchmark for researchers to analyse, improve and optimise the current control strategy implemented on this facility. Additionally, a highly valuable data resource containing 100 batches with all available process and Raman spectroscopy measurements is freely available to download. This data is highly suitable for the development of big data analytics, machine learning (ML) or artificial intelligence (AI) algorithms applicable to the biopharmaceutical industry.

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1. Introduction

Penicillin fermentation monitoring and control has been carried for the last three decades (Mou and Cooney, 1983; Min et al., 1995 and Lee et al., 2004a; Luo and Bao, 2018). However the biopharmaceutical sector as a whole is still significantly lagging behind other sectors in their adoption of advanced process control (APC), particularly in their use of innovative process analytical technology (PAT) solutions (Tomba et al., 2013). This is more evident in comparison to other highly sophisticated industries such as oil & gas, semi-conductor and automotive where automation and lean manufacturing are better engrained into company practice and culture. A major push from industrial regulators to rectify this has been the implementation of the Quality by Design (QbD)

and PAT initiatives set out by the FDA in 2004 and 2009, respectively (FDA 2004, FDA 2009). However, a major challenge remaining is the expertise and confidence required to adopt and implement these novel control solutions throughout industrial biopharmaceutical processes. Over the last 25 years the development of first principles mathematical models mimicking complex industrial processes have aided in the development and deployment of APC solutions (Downs and Vogel, 1993; Lyman and Georgakis, 1995; Birol et al., 2002; Jeppsson et al., 2007; Kontoravdi et al., 2010; Kiparissides et al., 2011; Benyahia et al., 2012; Gernaey and Gani, 2010; Goldrick et al., 2014; Papadakis et al., 2018). The ability to test and validate a novel control strategy on a simulation subsequent to implementation on a real process has the potential to revolutionise control theory and applications of advanced controllers throughout the biopharmaceutical sector (Randek and Mandenius, 2018; Yuan et al., 2009). A limitation of current biopharmaceutical mathematical models is their inability to address the current control challenges of a modern-day biopharmaceutical facility. In

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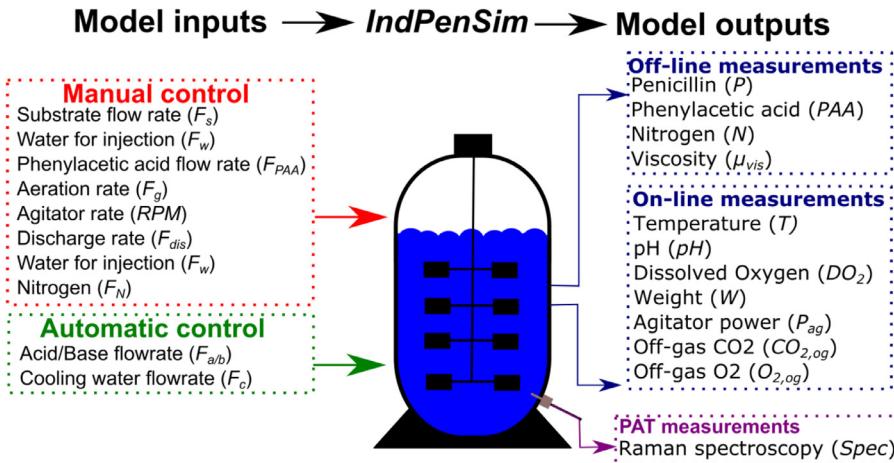


Fig. 1. Summary of all model inputs and outputs recorded by *IndPenSim*. Automatic control is dependent on PID control loops whereas manual control is a recipe-driven approach maintaining a fixed profile throughout the batch which can be manually adjusted by operator intervention.

the future era of Industry 4.0, which envisions a highly intelligent data-driven manufacturing environment incorporating a multitude of advanced on-line process analytics (Sami Sivri and Oztaysi 2018), the need for a modern-day biopharmaceutical simulation is paramount.

The simulation described in this paper aims to address the current and future challenges of biopharmaceutical process manufacturing through the extension of a highly complex industrial-scale penicillin fermentation, referred to as *IndPenSim*. The simulation was developed using the historical batch records of a 100,000 litre penicillin fermentation utilising a high-yielding industrial strain of *Penicillium chrysogenum* and accurately simulates all the available process inputs and outputs (Goldrick et al. 2015). *IndPenSim* can be operated in multiple modes enabling the generation of large volumes of realistic fermentation data. The simulation mimics a real process through its ability to include delays in off-line assay measurements, manual operator intervention of feeding strategies, inaccurate sensor readings and random deviations in growth and production levels. Furthermore, a realistic Raman spectroscopy device has been integrated within *IndPenSim*. The inclusion of this device aims to support the current and future development of innovative and advanced control strategies on biopharmaceutical facilities. Furthermore, a data set containing 100 batches (~ 2.5 GB) is available to download at www.industrialpenicillinsimulation.com which aims to act as a valuable resource for big-data analytics, machine learning (ML) and artificial intelligence (AI) approaches.

1.1. Overview of IndPenSim

IndPenSim acts as a standalone application (freely available to download at www.industrialpenicillinsimulation.com). A summary of all the process inputs and outputs recorded by *IndPenSim* are shown in Fig. 1. Table 1 outlines the measurement frequency and primary control strategy of these main process variables in addition to the functional relationship between each variable. Automatically controlled variables; i.e. temperature (T) and pH (pH), are regulated using a feed-back proportional integral derivative (PID) loop. Manually controlled variables; i.e. substrate flowrate (F_s) and phenylacetic acid flowrate (F_{PAA}), are manipulated using a recipe driven approach which follows a fixed profile throughout the batch (Recipe driven) or are controlled by an operator that manipulates this fixed profile throughout the batch (Operator dependant). This mode of control replicates the observed control actions of the operators manually adjusting F_s and F_{paa} throughout the batch as described in Goldrick et al. (2015). The batch length can be fixed

to a constant value (Fixed), typically 230 h or dependent on delays in downstream process operation (Variable). A summary of a five-year campaign outlining the annual production metrics generated by *IndPenSim* is summarised in Table 2. Each campaign was operated in a different mode and no advanced control algorithms were implemented during any campaign. *IndPenSim* calculates the annual production metrics using the assumption that the facility has a 24-hour operating period and operates 336 days per year. The remaining 29 days are used for an annual shut-down period, allowing for routine maintenance activities to be carried out. A three-day turn around period for bioreactor cleaning and re-inoculation is required following each batch. A target production yield of 2000 kg of penicillin is required in each batch. Any batches achieving yields below this specification are considered below target batches and an investigation into their poor performance is required.

1.2. IndPenSim control objectives

IndPenSim considers the growth, morphology, metabolic production and degeneration of a large-scale *Penicillium chrysogenum* fermentation in addition to modelling all the required on-line and off-line variables. The details regarding the mathematical structure of the model have been previously described in Goldrick et al. (2015). The primary focus of this paper is to demonstrate the ability of this simulation to act as a benchmark for the development and validation of novel control solutions applicable to biopharmaceutical processes. Currently this fermentation process has no advanced process control strategies in place and therefore presents significant process improvement opportunities. The primary goal of any control strategy is to ensure an economically viable process through increased product yields and reduced operating costs (Montague et al., 1989), therefore the following control objectives have been defined:

- Develop a control strategy to maximise annual penicillin production and reduce variation in batch yields in comparison to the five campaigns outlined in Table 2.
- Identify the critical process parameters (CPPs) and critical quality attributes (CQAs) influencing penicillin production.
- Develop an enhanced control strategy for pH and temperature variables to minimise their fluctuations in comparison to the existing PID control loops.
- Develop a control strategy that manipulates one or more of the following flowrates: substrate, nitrogen or phenylacetic acid, to

Table 1

Summary of measurement frequency, primary control variables, functional relationships and control strategies for recorded process variables.

Variable reference	Measurement frequency	Primary control variables	Functional relationship	Control strategy
Dissolved oxygen (DO_2 - mg L $^{-1}$)	12 min	F_g, RPM	$P, O_{2,og}, Viscosity, T, V, F_{oil}$	>10% of saturation
Weight (W - kg)	12 min	$F_{water}, F_s, F_{a/b}, F_{PAA}, F_{dis}$	P, X, V	Maintain between 7×10^4 and 11×10^4 kg
pH (pH)	12 min	$F_{a/b}$	P, X, V	PID control algorithm
Temperature (T - K)	12 min	F_c	P, X, V	PID control algorithm
Off-gas measurements ($CO_{2,og}$ & $O_{2,og}$ - %)	12 min	F_g, RPM	O_2, CO_2	Not controlled
Penicillin (P - g L $^{-1}$)	12 h (+ 4 delay)	$F_s, F_{oil}, F_{PAA}, F_N$	X, PAA, DO_2, S	Maximise production
Biomass (X - g L $^{-1}$)	12 h (+ 4 delay)	$F_s, F_{oil}, F_{PAA}, F_N$	$P, PAA, N, S, pH, T, CO_2$	Maximise production
Phenylacetic acid (PAA - mg L $^{-1}$)	12 h (+ 4 delay)	F_{PAA}	P, X, V	Maintain between 600 and 1800 mg L $^{-1}$
Nitrogen (N - mg L $^{-1}$)	12 h (+ 4 delay)	$N_{shots}, F_{oil}, F_{PAA}$	P, X, V	Maintain above 300 mg L $^{-1}$
Viscosity (μ - cP)	12 h (+ 4 delay)	F_{water}	P, X, V	Maintain below 100 cP
Substrate (S - g L $^{-1}$)	No off-line measurements available	F_s, F_{oil}	P, X, V	Maintain between 5×10^{-3} and 1×10^{-3} g L $^{-1}$

Table 2

A summary of the annual production metrics recorded by *IndPenSim* operated using different control strategies throughout a five-year production period.

Campaign summary	Campaign 1 (Year 1)	Campaign 2 (Year 2)	Campaign 3 (Year 3)	Campaign 4 (Year 4)	Campaign 5 (Year 5)
Control strategy	Operator dependant	Recipe driven	Operator dependant	Recipe driven	Operator dependant
Fixed or variable batch length	Fixed	Variable	Variable	Fixed	Fixed
Average batch length (hours)	230 ± 0	239 ± 27	239 ± 32	230 ± 0	230 ± 0
Number of batches	26	25	26	26	26
Number of below target batches	2	8	6	2	5
Average Penicillin yield per batch (kg)	2882 ± 745	2578 ± 769	2950 ± 888	2912 ± 786	2816 ± 796
Annual production (kg $\times 10^3$)	74,939	64,458	76,690	75,716	73,228

maintain these variables within their acceptable ranges defined in Table 1.

- Utilise the spectra recorded by the Raman spectroscopy device to develop a soft-sensor enabling an on-line prediction of phenylacetic acid, biomass or penicillin concentration in real-time.
- Develop a control strategy that calculates the optimum harvest time for each batch to maximise annual penicillin yields generated throughout a yearly campaign.

2. Material and materials

2.1. Simulation software

IndPenSim was written in Matlab R2018b and is freely available to download at www.industrialpenicillinsimulation.com where the historical batch records of campaigns 1–5 outlined in Table 2 are also available. *IndPenSim* has the following capabilities and functionality:

- Batch to batch variation of both the biomass and penicillin concentration as well as in-batch fluctuations
- Option to add disturbances on inlet concentrations of the substrate (c_s), oil (c_{oil}), acid/base molar concentration ($c_{a/b}$) and Phenylacetic acid concentration (c_{PAA}).
- Ability to adjust the current sequential batch control strategy for F_s , F_{oil} , F_g , RPM , F_{dis} and F_{PAA} .
- Option to include inhibition effects on the growth rates during DO_2 , N and PAA limitation as well as during excessive PAA and CO_2 concentrations and sub-optimal T and pH operation.
- Includes a pre-defined delay (4 h) in the off-line measurements of P , N , PAA and μ_{app} .
- Option to include process faults including agitator trip, aeration faults, substrate faults and sensor errors.
- Option to record Raman spectra throughout the batch, enabling real-time predictions of the critical quality attributes and criti-

cal process parameters provided an accurate calibration model is developed and the spectra is pre-processed correctly.

2.2. Raman spectroscopy simulation development

This section describes the development of an empirical mathematical model to simulate a realistic PAT analyser, specifically a Raman spectroscopy device. The simulated spectra were generated and validated through a detailed analysis of experimental Raman spectra recorded on a 5 litre fungal fermentation producing a commercially available antibiotic. Further details describing the materials and methods of this fermentation are outlined in Goldrick et al. (2018). The Raman spectroscopy device used was a Kaiser 1000 RXN system implementing an indium gallium arsenide (InGaAs) detector array with a spectral range of 200–2400 cm $^{-1}$ and a resolution of 3 cm $^{-1}$. The Raman spectroscopy analyser was set-up to record a spectrum every 30 min based on 9 averages using an integration time of 180 s. In total 540 spectra were recorded throughout the 260-hour fermentation, highlighted in Fig. 2A. The simulated PAT analyser described here aims to mimic the three main characteristics that define this experimentally recorded Raman spectra. These are outlined by Bocklitz et al. (2011) as fluorescence baseline increase, Raman spectrum peaks and noise. The modelling of random cosmic spikes on Raman spectroscopy was not considered in this work.

2.2.1. Non-linear spectra profile and baseline increase

Raman spectra recorded on fermentation systems contain characteristic peaks related to media components and cell culture in addition to the characteristic non-linear shape associated with the background signal of the Raman spectroscopy device. This was modelled by taking the first spectrum of the experimental Raman data set and using this as a template for all spectra generated by this simulated PAT analyser, the reference spectrum is shown in Fig. 2B. The fluorescence increase shown in the experimental Ra-

Experimental Raman Spectra

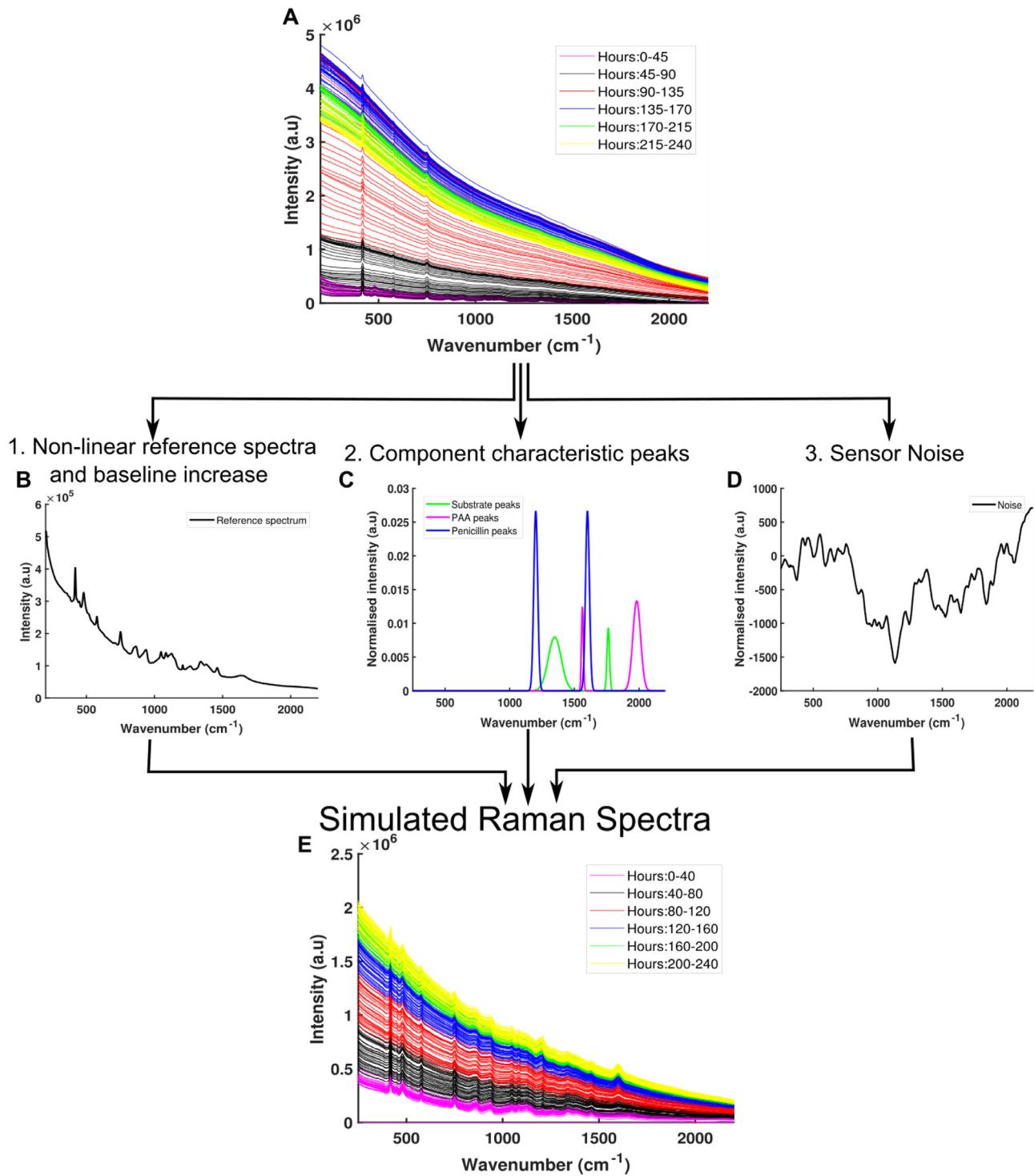


Fig. 2. A summary outlining the development of the Raman spectroscopy simulation. A) Highlights the experimental spectra recorded by a 993 nm Raman spectroscopy. B) Highlights the non-linear reference spectrum implemented as the starting spectrum in this simulation. C) Highlights the non-linear characteristic peak increase related to fermentation compositional changes in penicillin, substrate and phenylacetic acid. D) Highlights an example of the typical noise added to each simulated spectrum. E) Shows an example of the simulated spectra developed in this work.

man spectra is visible in Fig. 2A where the baseline intensity of the spectra collected during the start (0–45 h) can be compared with that collected at the end of the fermentation (215–240 h). To model this fluorescence increase ($\Delta_{\text{Fluorescence}_{\text{Exp}}}$) in the experimental spectra the average change in intensity from one spectrum to the next was calculated as:

$$\Delta_{\text{Fluorescence}_{\text{Exp}}}(n) = \sum_{v=250}^{v=2250} \frac{(\text{Spectra}(n+1) - \text{Spectra}(n))}{2000} \quad (1)$$

Where $\Delta_{\text{Fluorescence}_{\text{Exp}}}$ represents the average change in baseline intensity of two consecutive spectra between the wavelengths (v) 250–2250 cm^{-1} . Taking the cumulative sum of the calculated fluorescence increase results in an average fluorescence profile of the

fermentation. In these empirically simulated Raman spectra, the fluorescence increase ($\Delta_{\text{Fluorescence}_{\text{Sim}}}$) was assumed to be the result of compositional changes to the fermentation broth. The compositional changes assumed to have the largest influences were the biomass (X), penicillin (P), viscosity (μ) and batch time (t), which are defined as:

$$\sum_{t=0}^{t=240} \Delta_{\text{Fluorescence}_{\text{Sim}}} = \alpha_1 X + \alpha_2 P + \alpha_3 \mu + \alpha_4 t \quad (2)$$

The coefficients ($\alpha_{1, 2, 3, 4}$) were calculated using a step-wise linear regression function that minimised the error between the calculated experimental fluorescence increase and the simulated fluorescence. The fluorescence increase was found to be accurately modelled by these four variables with the product concentration identified as having the largest influence on the experimentally recorded fluorescence. The finalised coefficients ($\alpha_{1, 2, 3, 4}$) were equal to -0.002 (X), 1.05 (P), -0.07 (μ) and -0.2 (t). It was observed in Fig. 2A that fluorescence had a greater influence on the lower wavelengths in comparison to the higher wavelengths. To account for this nonlinearity an exponential function was multiplied by each spectrum to mimic this as shown in Eq. (5). This exponential function is defined in this work as β , further details can be found in Goldrick (2015).

2.2.2. Non-linear characteristic peak increase related to fermentation composition

The simulated Raman spectra needs to take into account the characteristic peaks related to changes in component concentrations throughout the batch. Previous work on the use of Raman spectroscopy for on-line monitoring of biological processes has simulated these characteristic peaks as Gaussian functions (Oh et al., 2012). Furthermore, Gaussian functions have also been demonstrated to represent specific molecules in chemical analysis utilising Raman spectroscopy (Kneipp et al., 1999). Therefore, Gaussian functions were used to represent the substrate (S), penicillin (P) and phenylacetic acid (PAA) concentrations in this simulation. The position of the substrate and phenylacetic acid peaks were selected based on analysis of the Raman spectra containing media spiked with high concentrations of phenylacetic acid and substrate as outlined in Goldrick (2015). The penicillin peak positions were chosen based on Raman spectra of Penicillin G samples shown in Clarke et al. (2005). These peaks were represented by a Gaussian distribution function defined as:

$$f(\text{Peak}_{(P/S/PAA)}) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(\text{peak}(P/S/PAA) - \mu_{P/S/PAA})^2}{2\sigma^2}} \quad (3)$$

Where $\text{Peak}_{(P/S/PAA)}$ is the specific wavelength related to either changes in penicillin (P), substrate (S) or phenylacetic acid (PAA), σ is the standard deviation of either $\text{Peak}(P)$ or $\text{Peak}(S)$ or $\text{Peak}(PAA)$ and μ represents the peak mean. These component peaks are shown in Fig. 2C.

2.2.3. Signal-to-noise ratio

Noise is an inherent disturbance to any sensor. For Raman spectroscopy noise generally results from thermal effects, instrument read-out errors or random cosmic rays. The magnitude of the noise was modelled by calculating the signal-to-noise ratio (SNR) of the spectra. The SNR assumes the Raman spectra collected in close succession to each other should be almost identical with the main difference between these two signals being the result of noise within the signals (Grimbergen et al., 2010). By calculating the mean and standard deviation of each consecutive spectra the SNR is calculated as follows:

$$\text{SNR} = \frac{\bar{S}}{\sigma_{\text{diff}}} \quad (4)$$

Where \bar{S} is the mean Raman intensity and σ_{diff} is the standard deviation of spectrum divided by $\sqrt{2}$. The SNR was calculated for 10 spectra and equalled 50 counts (intensity). The magnitude of this was used to add noise to each individual spectrum based on a random walk noise generation. A typical example of the noise added to each spectra is shown in Fig. 2D.

The final simulated spectrum (Sim. Spectra) is summarised as:

Sim. Spectra = Reference Spectra

$$+ (\delta_1 \Delta_{\text{Fluorescence}} + \delta_2 \text{Peaks}(S, P, PAA) + \delta_3 \text{Noise}) \times \beta \quad (5)$$

Where the $\delta_{1, 2, 3}$ are coefficients related to the intensity of each characteristic component of the simulated spectra. δ_1 is the fluorescence increase due compositional changes in biomass, penicillin, viscosity and also batch time. δ_2 is related to the intensity increase based off current concentrations of penicillin (P), substrate (S) and phenylacetic acid (PAA) in the bioreactor and δ_3 is the intensity associated with the noise added to each spectrum. β relates to the exponential function to account for non-linear increase of the lower wavelengths of the spectra.

A demonstration of the robustness of the simulated Raman spectra to accurately predict the penicillin concentration during routine and abnormal operation is demonstrated in Fig. 3. In total, four batches were simulated that contained a low filtered pseudo random binary signal (PRBS) added to the substrate feed rate (F_s) to mimic realistic process deviations as shown in Fig. 3A. The first batch was used to build the PLS model taking the interpolated off-line penicillin concentration as the response. The spectra was pre-processed as described in Section 4. The PLS model selected four latent variables as optimum, accounting for 99% of the variance in the X-data (spectral data) and the 98% of variance in the Y-data matrix (interpolated penicillin concentration). A calibration batch was simulated and resulted in highly comparable predictions of the off-line penicillin concentration with the root mean square error (RMSE) equal to $+/- 0.1 \text{ g L}^{-1}$. Two addition batches were simulated containing a process disturbance in the substrate flow rate (F_s) as demonstrated in Fig. 3A. The resultant drop in penicillin concentration as a result of these process disturbances is evident from Fig. 3B. The PLS predictions of penicillin during these process disturbances is highly comparable with the off-line penicillin concentration measurements shown in Fig. 3B. The ability of the spectra to be utilised as a real-time measurement of penicillin during normal and abnormal operation represents a significant opportunity to develop and implement advanced process control algorithms on this benchmark simulation. However, it must be noted that the simulated Raman spectroscopy was built using spectra collected at the 5 L scale and does not account for any potential process heterogeneities or additional process issues that may be present at the 100,000 scale.

3. Theoretical section

The following section outlines the multivariate data analysis (MVDA) techniques applied in this manuscript. A batch-wise unfolding algorithm was initially implemented to decompose the data set into a structured format enabling the main sources of variation between each batch to be highlighted (Nomikos and Macgregor 1995). Both principal component analysis (PCA) and partial least squares (PLS) were implemented to reduce the high dimensionality of this large unfolded data allowing for easier data interpretation and better visualisation of hidden correlations. These two techniques have been demonstrated extensively in the monitoring and control of industrial fermentation systems (Lennox et al., 2001; Ündey et al., 2003; Kourtis et al. 2005; Chiang et al., 2006; Goldrick et al., 2017).

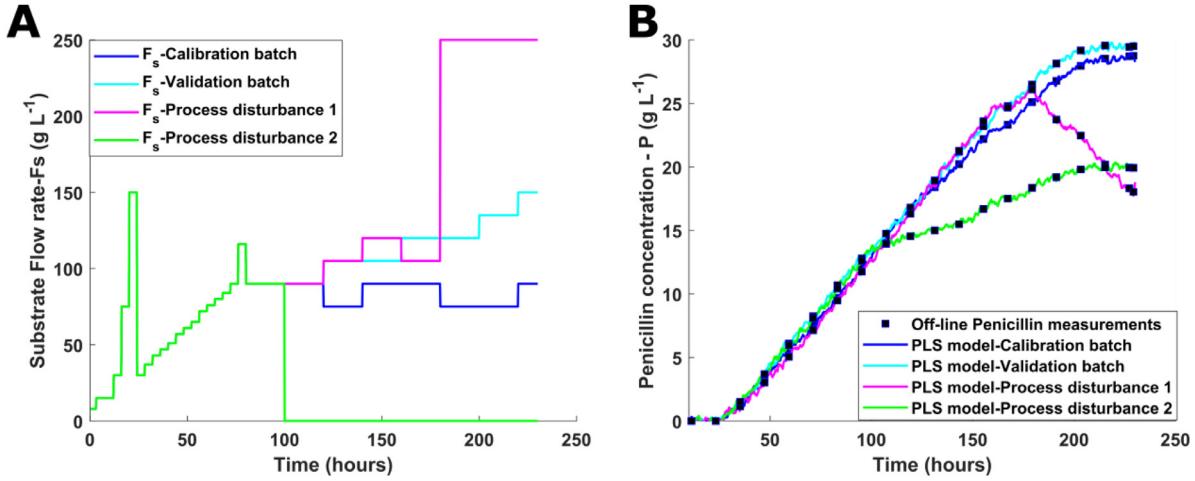


Fig. 3. A) Outlines the substrate flow rate (F_s) for the calibration and validation batches used to generate the PLS model for predicting the penicillin in addition to two batches containing process disturbances. B) Represents the off-line penicillin concentration of the four batches compared to the on-line PLS penicillin predictions.

3.1. Principal component analysis (PCA): On-line and off-line monitoring

The application of PCA for the on-line and off-line monitoring of industrial biopharmaceutical data is well described by [Gunther et al. \(2007\)](#). In summary, prior to applying PCA the data was mean centred and scaled to unit variance. PCA is described mathematically as:

$$\mathbf{X} = \sum_{r=1}^R \mathbf{t}_r \mathbf{p}_r' + \mathbf{E} \quad (6)$$

Where \mathbf{X} represents the two-dimensional data set and \mathbf{t}_r , \mathbf{p}_r and \mathbf{E} represent scores, loadings and residuals, when R principal components are retained. The scores (\mathbf{t} vector) represents a single batch and can quantify the overall variability of each batch analysed by the PCA model. The loadings (\mathbf{p} vector) represents the time-series variance of each variable in comparison to the average trajectory of each variable considering all batches in the PCA model. PCA is a well suited and established method to compare new batches to previously recorded normal operating conditions (NOC) batches. The comparability is defined by calculating the new batch scores (\mathbf{t}_{new}) by projecting the new batch data (\mathbf{x}_{new}) onto the previously generated PCA model generated using the NOC batches:

$$\mathbf{t}_{new} = \mathbf{x}_{new} \mathbf{P} (\mathbf{P}' \mathbf{P})^{-1} \quad (7)$$

This generated score enables off-line monitoring of the newly generated batches. To help identify any abnormal operation two statistical metrics are typically used. The first is the Hotelling T^2 statistic that captures the difference in the systematic part of the model and is calculated as:

$$T_{new}^2 = \mathbf{t}_{new}' \left(\frac{\mathbf{T}' \mathbf{T}}{I-1} \right) \mathbf{t}_{new} \quad (8)$$

Where I is the number of NOC batches used to generate the PCA model. Any batches that behave abnormally can be detected through analysis of the confidence limit of the T_{α}^2 defined by [Lee et al. \(2004b\)](#) as:

$$T_{\alpha}^2 = \left(\frac{R(I-1)}{I-R} \right) F_{R,I-R,\alpha} \quad (9)$$

Where $F_{R,I-R,\alpha}$ is the F -distribution assuming a confidence limit equal to α taking R principal components and using I batches to build the model. A second method to detect abnormal behaviour

is to analyse the residual error of the PCA model, this is quantified by the sum of squared residuals (SPE) or Q statistic:

$$Q_{new} = \mathbf{e}_{new} \mathbf{e}_{new}' \quad (10)$$

$$e_{new} = \mathbf{x}_{new} - \mathbf{t}_{new} \mathbf{P}' \quad (11)$$

Typically these residuals follow a chi squared distribution (χ^2) with a confidence limit approximated by [Jackson and Mudholkar \(1979\)](#) as:

$$Q_{\alpha} = \theta_1 \left(\frac{z_{\alpha} (2\theta_2 h_0^2)^{0.5}}{\theta_1} + 1 + \frac{\theta_2 h_0 (h_0 - 1)}{\theta_1^2} \right)^{\frac{1}{h_0}} \quad (12)$$

$$V = \frac{\mathbf{E} \mathbf{E}'}{I-1} \quad (11a)$$

$$\theta_i = \text{trace}(V^i) \text{ for } i = 1, 2, 3 \quad (13)$$

$$h_0 = 1 - \frac{2\theta_1 \theta_2}{3\theta_2^2} \quad (14)$$

With V representing the covariance matrix of \mathbf{E} , z_{α} is standardised normal variable with confidence limit equal to α . A major benefit of applying PCA to analyse biopharmaceutical data is its ability to be used for on-line monitoring. The PCA model generated from the NOC batches can be used to evaluate batch progression in real-time and utilise this information to alleviate faults and enhance control operations. This PCA projection method utilises a portion of the loading matrix corresponding to the current lapsed time of the current batch until current sampling time k to calculate the new score vector $\mathbf{t}_{new}(k)$ for the selected number of principal components of the model.

$$\mathbf{t}_{new}(k) = \mathbf{x}_{new,1:jk} \mathbf{P}_{1:jk} (\mathbf{P}'_{1:jk} \mathbf{P}_{1:jk})^{-1} \quad (15)$$

Where $\mathbf{x}_{new,1:jk}$ is the available batch data up until current time point k and $\mathbf{P}_{1:jk}$ is the loadings matrix of the NOC batches calculated using data up to time point k . Both the $T_{new}^2(k)$ and $\mathbf{e}_{new}(k)$ are calculated from Eqs. (8) and (11), respectively, using the time varying covariance matrix $\mathbf{S}(k)$ and the loadings matrix $\mathbf{P}_{1:jk}$. The on-line SPE enables the distance between the PCA model generated by the NOC batches and the progression of the new batch and is calculated as:

$$SPE_{new}(k) = \sum_{j=1}^J \mathbf{e}_{new,jk}^2(k) \quad (16)$$

The SPE and T^2 can act as an on-line indicator of overall system performance. High SPE or T^2 indicates that the process is behaving abnormally enabling real-time fault detection. To localise the root cause of any abnormal behaviour the variable contributions towards the SPE and T^2 can be evaluated at any time point k as follows:

$$C_{T_{jk}^2} = \sum_{a=1}^A S_{aa}^{-1}(k) \mathbf{t}_{new,a}(k) \mathbf{x}_{new,jk} \mathbf{P}_{jk,a} \quad (17)$$

$$C_{SPE_{jk}} = \mathbf{e}_{new,jk}^2(k) \quad (18)$$

Where $S_{aa}(k)$ is the a^{th} diagonal element of the time-varying covariance matrix at time point k .

3.2. Partial least squares (PLS) model development

Partial least squares modelling is similar to PCA in its ability to reduce large data sets into low-dimensional vector spaces. However, this technique enables the prediction of a response variable, \mathbf{Y} , using the predictor variables contained within \mathbf{X} . The PLS model is generated from a set of regression vectors maximising the covariance between the \mathbf{X} and \mathbf{Y} data. Similar to PCA the initial step in building a PLS model was to construct the \mathbf{X} data by unfolding all the available variables within each batch using a batch-wise unfolding algorithm ensuring the \mathbf{X} and \mathbf{Y} data have an equal number of rows. The PLS model was generated through a non-linear iterative partial least squares (NIPALS) algorithm (Wold et al., 1987). This algorithm generates an outer-relationship that identifies the main sources of variance within each of the data and links them together through an inner-relationship. The outer relationships are generated by decomposing the newly unfolded \mathbf{X} and \mathbf{Y} data into R latent score variables [\mathbf{t} , \mathbf{u}], loading vectors [\mathbf{p} , \mathbf{q}], weights \mathbf{W} and the model residual matrices \mathbf{E} and \mathbf{F} . \mathbf{t} , \mathbf{u} , \mathbf{p} , and \mathbf{q} can be combined into \mathbf{T} , \mathbf{U} , \mathbf{P} , \mathbf{Q} and \mathbf{W} as defined below (Wold et al., 1987):

$$\mathbf{X} = \sum_{r=1}^R \mathbf{t}_r \mathbf{p}'_r + \mathbf{E} \dots \mathbf{X} = \mathbf{T} \mathbf{P}' + \mathbf{E} \quad (19)$$

$$\mathbf{Y} = \sum_{r=1}^R \mathbf{u}_r \mathbf{q}'_r + \mathbf{F} \dots \mathbf{Y} = \mathbf{U} \mathbf{Q}' + \mathbf{F} \quad (20)$$

A vector of inner-relationships (\mathbf{B}) is generated that relates the scores of the \mathbf{X} data to the \mathbf{Y} data, which is defined as:

$$\mathbf{B} = \mathbf{U}' \mathbf{T} (\mathbf{T}' \mathbf{T})^{-1} \quad (21)$$

The PLS model implements an iterative procedure for each latent variable to reach convergence and once the procedure is complete, a matrix of regression coefficients (β) can be generated as follows:

$$\beta = \mathbf{W} (\mathbf{P}' \mathbf{W})^{-1} \text{diag}(\mathbf{B}) \quad (22)$$

Where, $\mathbf{W} = (\mathbf{U}^{-1} \mathbf{X})'$. The cumulative sum of the regression coefficients predicts the response variable ($\hat{\mathbf{Y}}$) from the \mathbf{X} data taking R latent variables, which was equal to:

$$\hat{\mathbf{Y}} = \mathbf{X} \sum_{r=1}^R \beta \quad (22a)$$

4. Soft-sensor development

The generation of the PAA soft-sensor involves generating a PLS model as described in Section 3.2 taking the Raman spectra and off-line phenylacetic acid (PAA) concentration as the \mathbf{X} and \mathbf{Y} data, respectively. The Raman spectra recorded by *IndPenSim* was generated every 12 min and recorded data along the wavenumber 250–2250 cm⁻¹ resulting in a large two dimensional matrix. The wavenumbers of interest that contain information related to

the PAA concentration in the bioreactor were equal to 1540:1580 and 1950:2050 cm⁻¹, identified through analysis of Raman spectra recorded from fermentation media spiked with various concentrations of PAA (Goldrick 2015). The selected wavenumbers of the Raman spectra were pre-processed using a standard Savitzky-Golay smoothing technique using a 15-point average and taking the first derivative, this pre-processed data was taken as the \mathbf{X} data. The PAA off-line concentrations were taken as the \mathbf{Y} data in the PLS model and were interpolated using a cubic-spline function to ensure an equal number of rows as the \mathbf{X} data. The selection of the optimum number of latent variables was based on a cross-validation operation employing a leave-one-out protocol (Martens and Naes 1992).

5. Results and discussion

5.1. Quality by Design and PAT application

Monitoring and control of penicillin fermentation processes has been around for decades and essential to ensure the production of high yields and product quality remains within specification (Mou and Cooney, 1983; Min et al., 1995 and Lee et al., 2004a; Luo and Bao, 2018). The recent Quality by Design (QbD) initiative represents a paradigm shift in biopharmaceutical manufacturing involving a systematic approach to process optimisation enabled through enhanced process understanding and innovative control strategies. The primary focus of this approach is to ensure a predefined product quality target is confidently and consistently achieved for all batches regardless of inherent process disturbances and batch-to-batch fluctuations. To accelerate the adoption of this systematic approach the regulatory bodies have launched the process analytical technology (PAT) framework (FDA 2004) to promote the application of advanced sensors integrated through innovative control solutions. Table 2 highlights the need for an improved control strategy for *IndPenSim* as both the recipe driven and operator dependent control strategies resulted in significant deviations in annual penicillin production for each of the five campaigns. To demonstrate how a QbD methodology can be correctly implemented for process improvements the three different stages of the PAT framework were implemented using *IndPenSim*:

Design stage: To identify the critical process parameters (CPPs) and subsequent critical quality attributes (CQAs), all the process data recorded in campaign 5 were analysed using multivariate data analysis (MVDA). This campaign is summarised in Table 2 and resulted in 26 batches with 5 of those batches failing to meet the required target penicillin production yield of 2000 kg. All batches implemented an operator dependant control strategy and had a fixed batch length equal to 230 h. The operator controlled flowrates of substrate (F_S) and phenylacetic acid (F_{PAA}) for this campaign are shown in Fig. 4A and B. The significant deviations in these primary control variables results in highly varied penicillin and biomass profiles, as shown in Fig. 4C and D, respectively. The need to improve the control strategy implemented on this process is highlighted by the five batches that failed to meet the penicillin demand at harvest shown in Fig. 4C and D. To fully exploit the available information recorded throughout this campaign and identify the CPPs influencing the observed deviation in penicillin yields a partial least square (PLS) regression model was implemented to analyse the data. This PLS model was identified using the selected variables shown in Fig. 5B taking the final penicillin yield at harvest as the response variable. The development of the PLS model required the data to be restructured using a batch-wise unfolding algorithm enabling the main sources of variation between the variables to be identified. The PLS model was generated using three latent variables that captured 47.7% of the total variance in the X-data and 98.7% of the total variance in the Y-data. All 26 batches

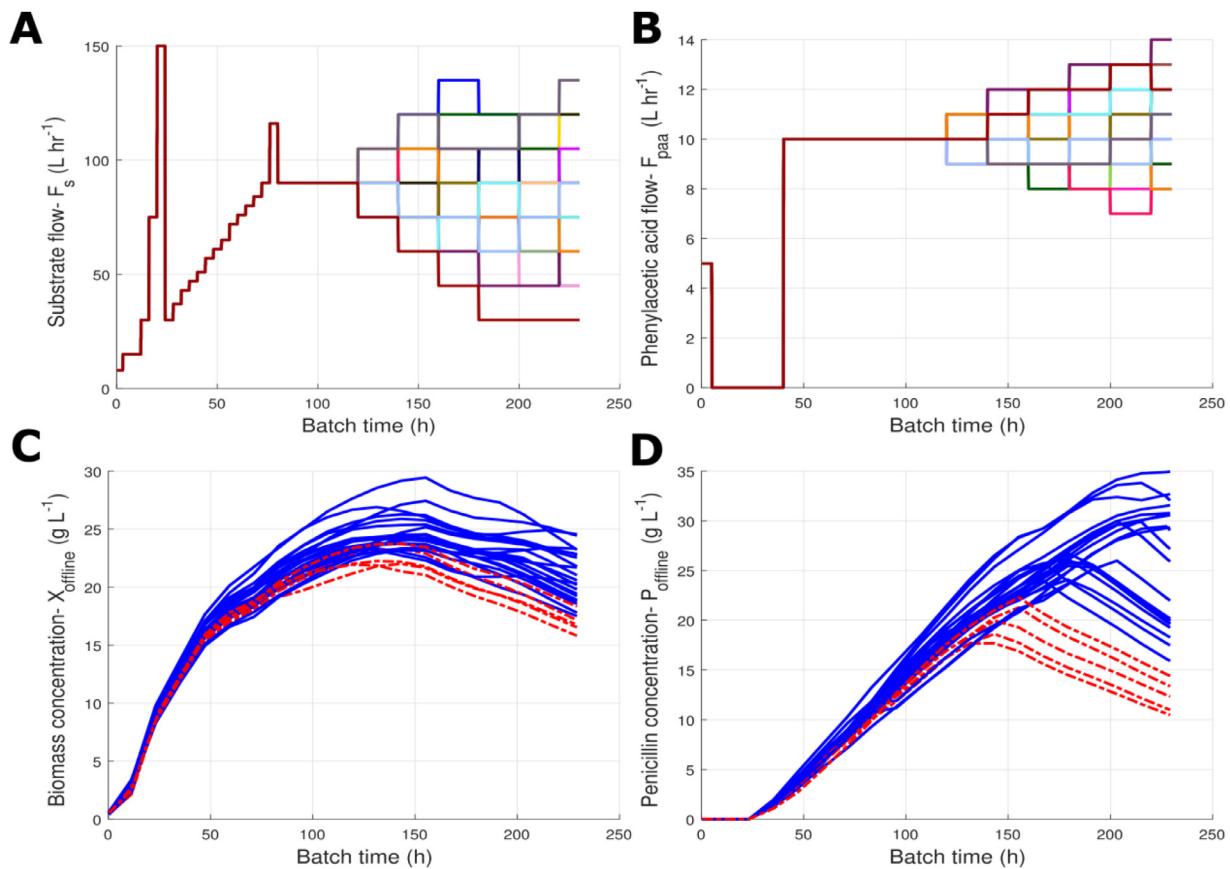


Fig. 4. Summary of variable profiles for campaign 5 with A highlighting the substrate flow rate (F_s), B: Phenylacetic acid flow (F_{paa}), C: Biomass (X) and D: Penicillin (P). The failed batches shown in C and D are highlighted by red dashed lines.

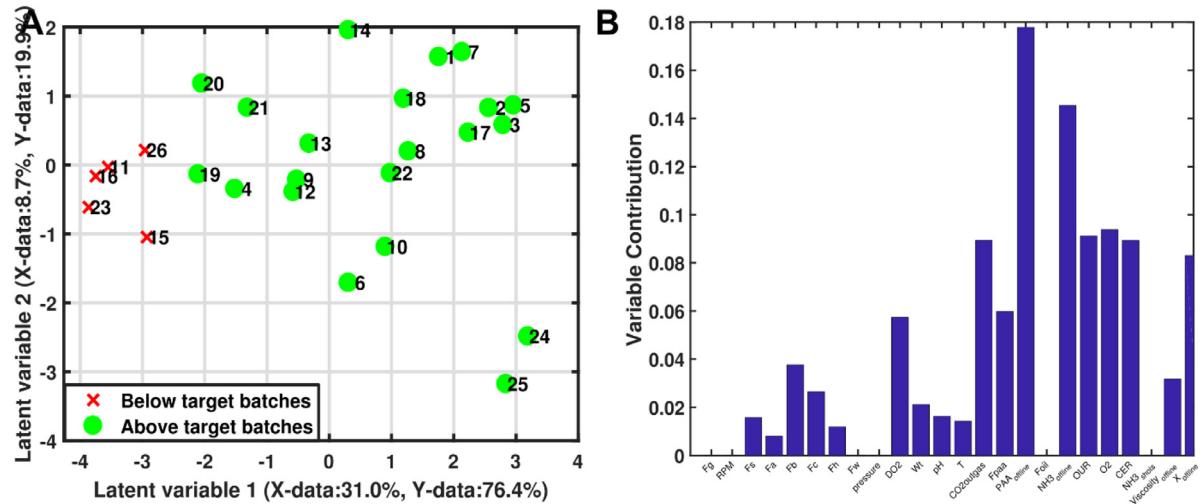


Fig. 5. A The scores generated from a PLS model of the above target batches (Penicillin yield > 2000 kg) are represented by green circles and the below target batches (Penicillin yield < 2000 kg) are represented by red crosses. The 1st latent variable represents 31.0% and 76.4% of the variance of the \mathbf{X} and \mathbf{Y} data, respectively, similarly the 2nd latent represents 8.7% and 19.9% of these data. B represents the variable contribution plot showing the normalised weight of each variable calculated using the 1st latent variable.

were used to build the PLS model with cross validation implemented to determine the appropriate number of latent variables to retain. Fig. 5A shows the first and second latent variables of this PLS model and highlights a clustering between the “below” and “above” target batches. This clustering indicates that the below target batches have similar characteristics in the data. To investigate the primary variables influencing these differences in penicillin

yields the summed contribution ($\sum_{k=1}^K \beta_{jk}^2$) of each process variable is shown in Fig. 5B for the first latent variable. The large contribution of the off-line concentrations of phenylacetic acid ($\text{PAA}_{\text{offline}}$) indicates this variable is highly influential in the final penicillin yields. Therefore, this variable was selected as the primary CPP to be considered for the Analyse Stage.

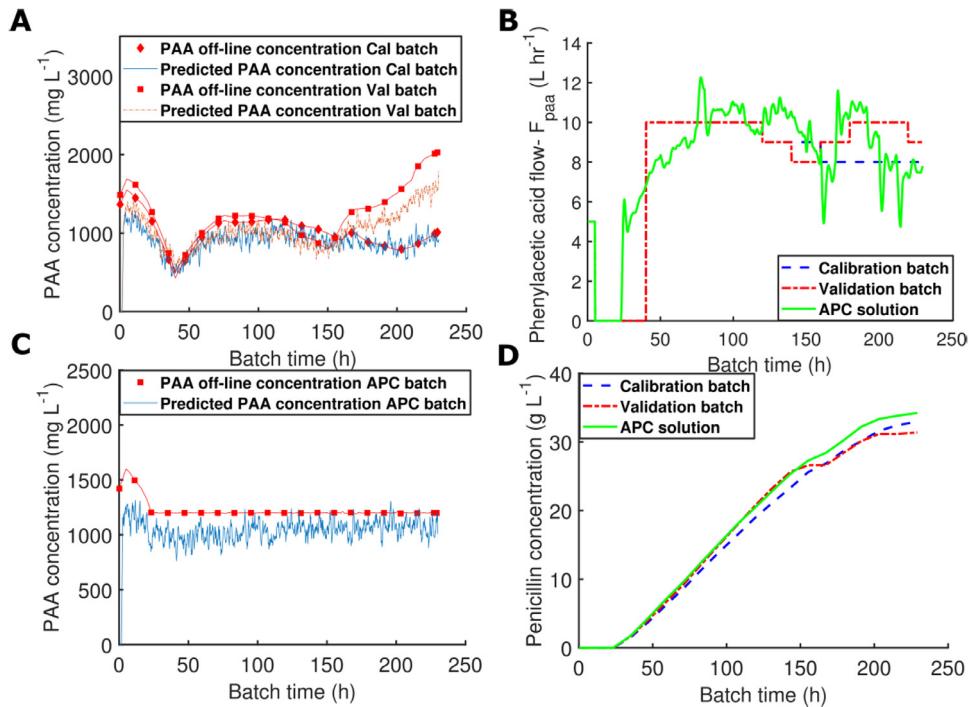


Fig. 6. A Calibration and validation batches of the off-line PAA samples and the corresponding predictions using a PLS model combined with the Raman spectroscopy analyser. B Summary of F_{PAA} for the calibration and validation batches and the APC batch with F_{PAA} controlled using the soft-sensor developed here. C Outline of PAA controlled using the APC strategy implemented here where the set-point for PAA was equal to 1250 mg L⁻¹. D Profile of Penicillin concentrations during the calibration, validation and APC controlled batches.

Analyse stage: The current control strategy for PAA concentration is to maintain this variable between 600 and 1800 mg L⁻¹ through manipulation of the phenylacetic flow rate (F_{PAA}). However, due to the infrequent nature of the off-line measurements of PAA combined with a timely 4-hour delay period for this assay, the control of this CPP remains suboptimal. The challenge of controlling this variable within these limits is highlighted through analysis of the annual production records recorded for each campaign. The Analyse stage therefore confirmed a real-time measurement could significantly improve the control of this key process variable. To address this, the inclusion of a Raman spectroscopy analyser within *IndPenSim* was implemented to investigate whether a soft-sensor could be developed to enable real-time predictions of PAA. To facilitate the Analyse stage a calibration batch was performed on *IndPenSim* that included the simulated PAT analyser recording a Raman spectrum every 12 min as described in Section 2.2. The routinely measured off-line PAA concentrations were also recorded every 12 h and used to develop the soft-sensor. The soft-sensor was built using a PLS model as described in Section 3.2. The subsequent predictions of PAA generated by the soft-sensor are highly comparable to the off-line concentrations of PAA for the calibration batch shown in Fig. 6A. To demonstrate these predictions in real-time a validation batch was ran using the soft-sensor built from data recorded in the calibration batch. The validation batch enabled on-line predictions of the PAA concentration and was shown to be comparable to the off-line PAA samples as shown in Fig. 6A. The ability to measure the PAA in real-time on *IndPenSim* therefore enables the Control stage to be implemented which is the final and most important step in the PAT framework.

Control stage: The final stage of the PAT framework involved the implementation of a proportional integral (PI) control loop that manipulated the F_{PAA} to maintain PAA at its set-point. The raw soft-sensor signal, shown in Fig. 6A, contains some high frequency fluctuations that may be problematic for the controller. To account for this, the signal was initially filtered using a three point moving av-

erage thus minimising any unnecessary control actions. Fig. 6B and C highlights this APC solution in operation, where the PI controller was switched on after 25 h and manipulates the F_{PAA} to maintain the PAA concentration at its set-point of 1250 mg L⁻¹. This APC solution was implemented on the *IndPenSim* for a year and the annual penicillin yield was compared against the previous campaigns, which implemented recipe driven and operator dependant control strategies. Implementing this APC strategy resulted in significant improvements in the annual production yields of penicillin. In total 26 batches were operated through the year and there were no batches that failed to meet the production targets of 2000 kg. The average penicillin yield per batch was 3517 ± 315 kg which represents a 20% overall increase in annual penicillin yields compared to the average of the previous five campaigns. The significant increase in penicillin production demonstrates the benefits of following the QbD methodology and implementing an APC solution utilising the Raman spectroscopy analyser.

5.2. Fault detection

Faults are an inherent hindrance to every manufacturing facility with early detection and subsequent isolation essential to minimise any significant process deviations (Venkatasubramanian et al., 2003). Early detection of faults during biopharmaceutical processes are necessary to ensure all process variables remain within a tight operating window ensuring strict target product requirements are maintained. Monitoring all available measurements is significantly challenging due to the increasing number of on-line and off-line variables recorded on industrial manufacturing facilities. Many biopharmaceutical companies rely on MVDA to help efficiently monitor the multitude of available process measurements enabling faster detection of process faults (Nomikos and Macgregor 1995). This approach was applied here to provide a benchmark for detecting abnormal processing conditions within *IndPenSim*.

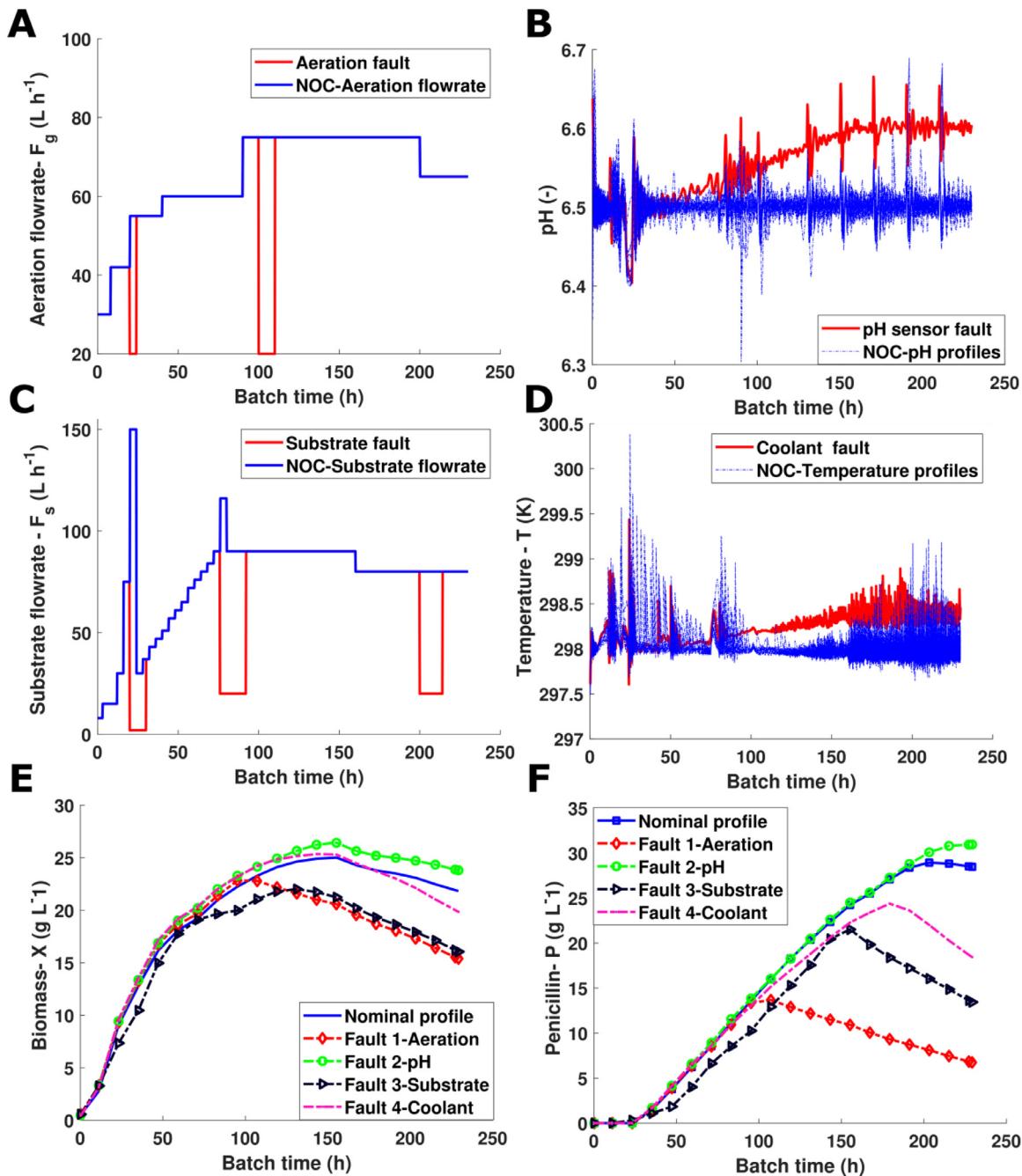


Fig. 7. Outline of the nominal trajectories of representative batches (Batches 1–17) from Campaign 4 in addition to time-series profiles of batches 18–21 containing known faults. A: Aeration fault (Batch 18), B: pH sensor drift fault (Batch 19), C: Substrate fault (Batch 20) and D: Coolant fault (Batch 21). The nominal Biomass (X) and Penicillin (P) profiles are shown in E and D, respectively with the profiles shown for each of the four batches containing faults.

This section demonstrates the application of *IndPenSim* to generate known faults during batches. Two standardised MVDA based fault detection algorithms were implemented to identify these faults. The data set generated from Campaign 4 excluding the 2 below target batches and an additional 5 batches that were considered to be sub-optimal. Campaign 4 represents a typical campaign controlled through a **recipe driven control strategy** with a fixed batch length and yielded a highly diverse data set. In total there were 17 batches taken as normal operating conditions (NOC) batches with batches 18–21 containing known faults. A comparison between the nominal trajectories and the batches with faults are shown in Fig. 7 with A highlighting the aeration fault, B the pH sensor drift fault, C the substrate fault and D the coolant fault.

The nominal biomass (X) and penicillin (P) profiles calculated by averaging all 17 batches are shown in Fig. 7E and F, respectively in addition to highlighting the effect of the process faults on these two CPPs. PCA was selected here based on its ability to compress the large volume of data to a much smaller set of linearly uncorrelated principal components (PCs) enabling direct visualisation of all variables suitable for process monitoring fault detection (Lee et al., 2004b). The 17 NOC batches from Campaign 4 were unfolded to form the X data structure and generate the PCA model retaining three principal components as defined in Section 3.1. All 22 of the on-line variables recorded by *IndPenSim* were used in the PCA model, the utilisation of only on-line variables enables faults to be detected in real-time.

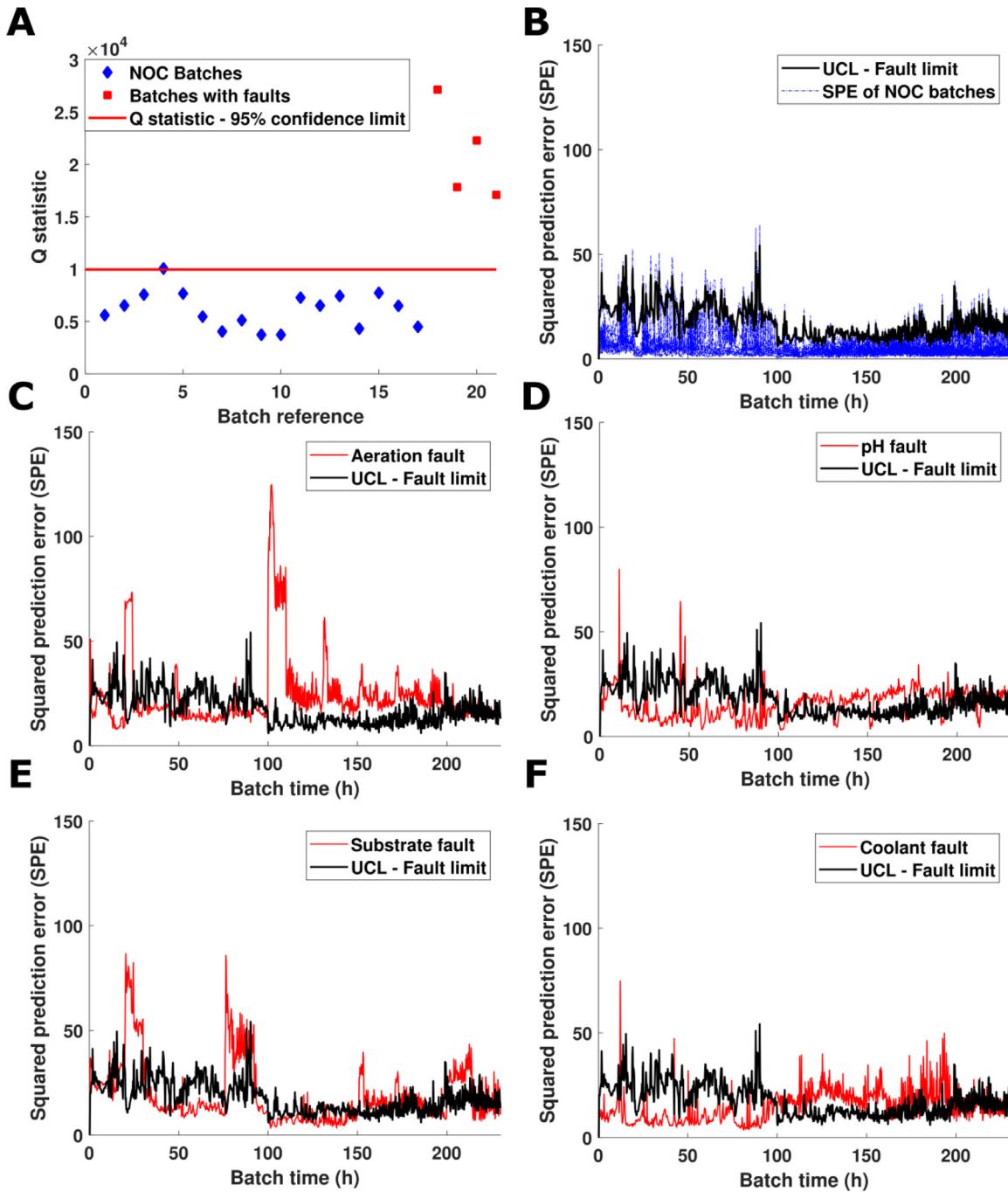


Fig. 8. A Plot of Q statistic for each of the 21 batches with the NOC batches represented by diamonds and the batches with faults represented by squares. B A summary of the SPE recorded for each of the 17 nominal batches with the UCL highlighted. C-F A summary of the SPE_k for each of the four batches with faults with the UCL highlighted.

To evaluate the comparability of the NOC batches with those containing faults the T^2 (Eq. (8)) and Q (Eq. (10)) statistic were calculated. The Q statistic is shown in Fig. 8A and highlights a clear distinction between the NOC batches and batches with faults. Each of the batches containing faults are above the Q statistic 95% confidence limit calculated from Eq. (12)–(14) indicating abnormal behaviour. The highest Q statistic is batch 17 which contains the aeration fault shown in Fig. 7E and F to have largest deviation in penicillin and biomass concentrations in comparison to the nominal trajectories. In contrast the T^2 statistic, shown in Fig. 9A, indicates all batches to be within the 95% confidence limit calculated using Eq. (8). Gunther et al. (2007) described similar results with the off-line Q statistic outperforming the T^2 statistic in its ability to

successfully identify the batches with faults in comparison to NOC batches. Typically, the T^2 is better at identifying systematic errors between batches whereas the Q statistic is better at identifying a new event that the previous PCA model has not seen which is the case for the faults described in this work. However, both the T^2 and Q statistics have successfully identified abnormal process behaviour on various different industrial processes (Westerhuis et al., 2000; Birol et al., 2002).

A second major advantage of generating these PCA models is their ability to monitor and detect the root cause of any abnormal process behaviour in real-time by analysing the SPE and T^2 using Eqs. (8) and (16). These are shown for the NOC batches in Fig. 8B and 9B respectively with the 95% upper control limit (UCL) shown.

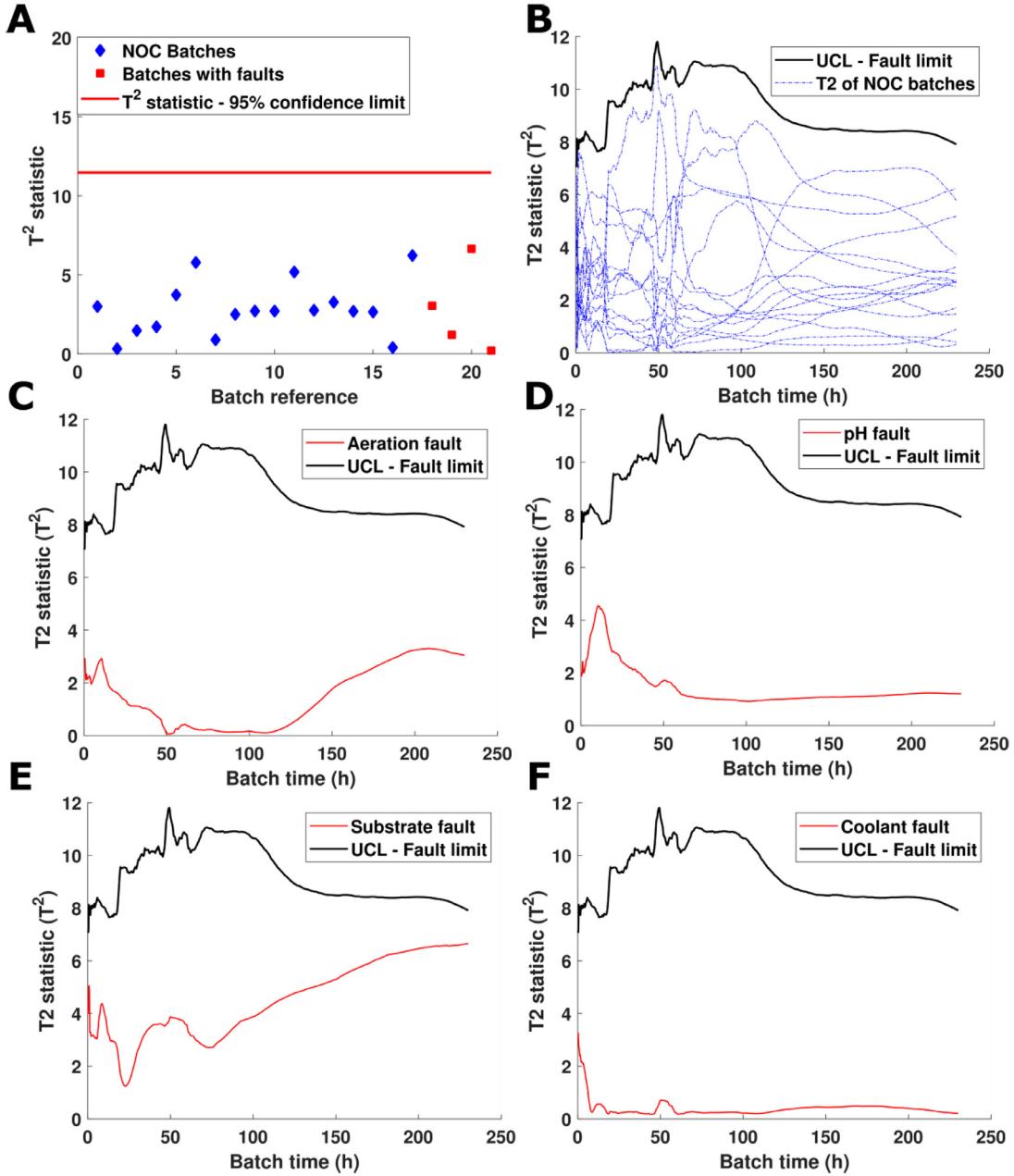


Fig. 9. A Plot of T^2 statistic for each of the 21 batches with the NOC batches represented by diamonds and the batches with faults represented by squares B A summary of the T^2 recorded for each of the 17 nominal batches with the UCL highlighted. C–F A summary of the time-series T^2 for each of the four batches with faults with the UCL highlighted.

Monitoring both the SPE and T^2 chart in real-time enables any process deviations from nominal trajectories to be subsequently identified. The current monitoring system signals an alarm after the SPE or T^2 exceeds an upper control limit (UCL). The SPE UCL assumes a χ^2 distribution calculated using Eqs. (12)–(14) taking the confidence limit α equal to 95%. The χ^2 distribution is the most widely implemented for monitoring the mean vector of a process (Rakitzis and Antzoulakos, 2011). The SPE of the four batches with faults are shown in Figs. 8C to 8F. These figures highlight the ability of SPE to quickly identify abnormal process behaviour for the aeration faults which occur at hours 20–24 and 100–110. Calculating the variable contribution to the SPE at time 20.2 using Eq. (18) highlights a significant contribution from the aeration rate (F_g), as shown in Fig. 10A. Additional variable contributions are shown for the carbon dioxide off-gas (CO_2_{offgas}), the dissolved

oxygen (O_2) and the carbon evolution rate (CER). The drop in the aeration during this time period shown in Fig. 7A, results in a significant drop in the dissolved oxygen and effects the mass balance recorded by the CO_2_{offgas} and CER measurements explaining their contribution to the SPE during this fault. The pH sensor fault occurs on batch 19 at approximate hour 50, however the on-line SPE only violates the UCL at hour 104. The variables contributions at this time are shown in Fig. 10B indicating the error is primarily due to deviations in pH. The relative delay in detecting this error is most likely due to the high frequency noise associated to the pH process variables highlighted in Fig. 7B. Furthermore, the penicillin and biomass concentrations were not directly influenced by the pH sensor drift as shown in Fig. 7E and F. The substrate fault behaves in a similar fashion to the aeration fault and is easily detected by the SPE in Fig. 8C. The subsequent analysis of the

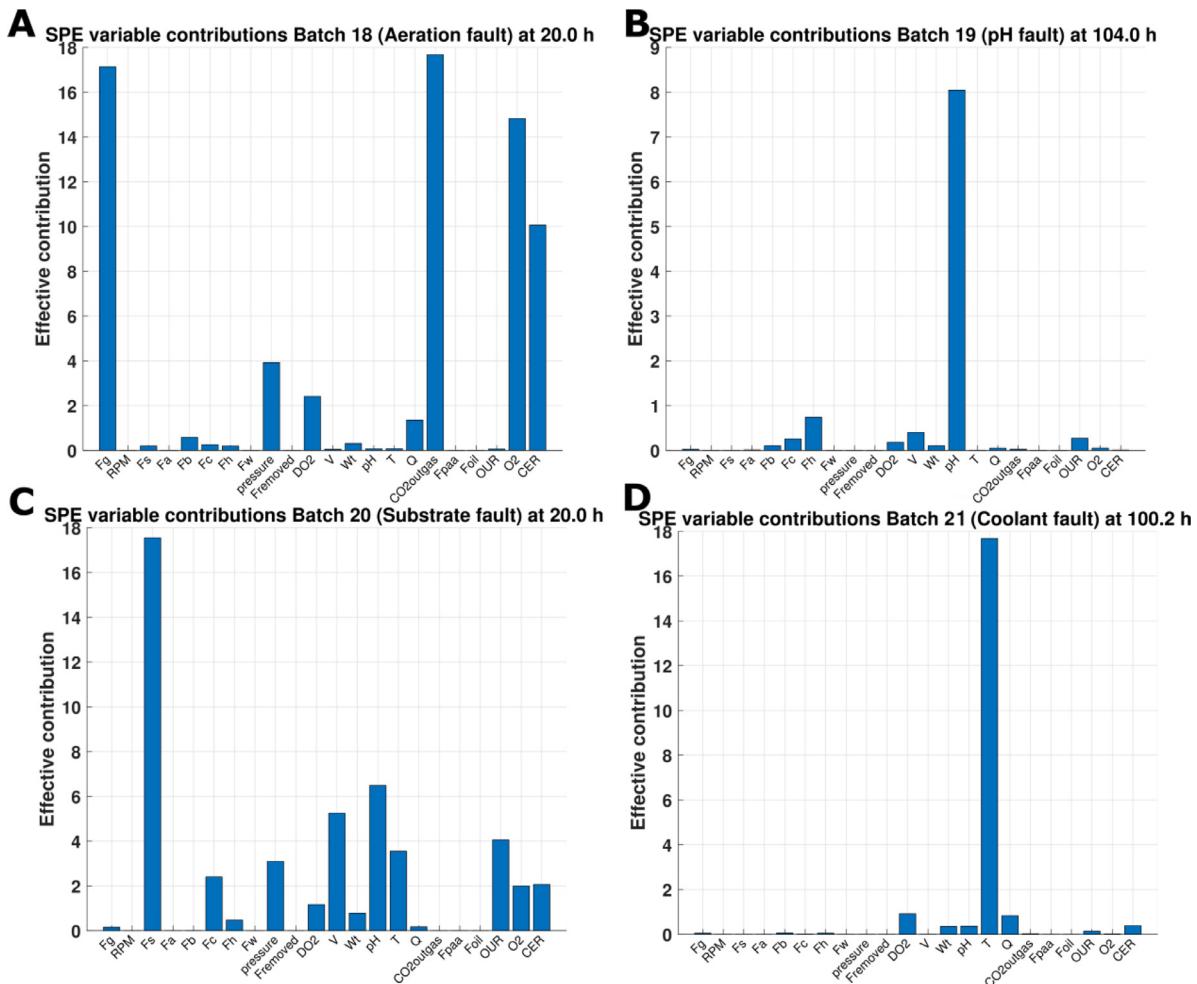


Fig. 10. Variable contribution plot of SPE statistic for A recorded at time point 20 h for batch 18 (aeration fault), B recorded at time point 104 h for batch 19 (pH fault), C recorded at time point 20 h for batch 20 (substrate fault), D recorded at time point 100.2 h for batch 21 (coolant fault).

contributions shown in Fig. 10C indicates a problem with substrate flow rate (F_S). The coolant fault results in a temperature shift highlighted in Fig. 7D and behaves similarly to the pH fault with a delay in the UCL violation as shown in Fig. 8D. The variable contributions for this time point are shown in Fig. 10D and clearly highlight an error with the temperature. This UCL violation occurs approximately when the temperature is 298.25 K which is 0.25 K above its set-point. This enables significant time for corrective action as it is only when the temperature increases to 298.5 K that a drop in penicillin production is observed as shown in Fig. 7F. The on-line T^2 are shown in Fig. 9B–F and do not highlight any process deviations with all the T^2 remaining below 95% confidence limit. The process faults in this work are better captured through the analysis of the SPE which summarised the variation not captured by PCA in contrast to the T^2 statistic which is better suited to describing deviations described by the PCA model.

6. Conclusion

The industrial-scale penicillin simulation (*IndPenSim*) developed in this paper aims to act as a benchmark simulator to develop, evaluate and validate novel and advanced control strategies, applicable to real-world biopharmaceutical manufacturing facilities. The paper outlines a number of highly challenging control objectives to enhance overall yield and productivity requiring the devel-

opment of adaptive and innovative control solutions. Furthermore, using the simulator all process improvements or modifications can be effectively compared and evaluated against the annual production yields generated by the previous five campaigns implementing operator dependant and recipe driven control strategies. The modifications to *IndPenSim* that are introduced in this paper represent the first bioprocess simulation to include a PAT device that accurately mimics the spectra recorded by a Raman spectroscopy device. The inclusion of this device represents a significant opportunity to help drive FDA's goal of enhancing process understanding and supporting innovative control solutions utilising real-time sensors. The capabilities and functionality of *IndPenSim* were demonstrated through two case studies. The first involves implementing all three stages of the PAT initiative using the Raman spectroscopy probe to enhance control of phenylacetic acid, previously identified as a CPP. The application of this control strategy resulted in a significant increase in yield improvements, increasing the annual penicillin yields to 3517 kg representing a 20% increase when compared to the previous five campaigns. Furthermore, this control strategy reduced the number of below target batches to zero emphasising the importance of implementing advanced controllers on biopharmaceutical processes. The second case study involved the evaluation of two benchmark fault detection algorithms to identify the occurrence of known faults. The SPE statistic significantly outperformed the T^2 statistic in its ability to identify and locate

the root cause of process faults during abnormal process operation. *IndPenSim* and all data presented here are available to download at www.industrialpenicillinsimulation.com and acts as an open resource for researchers to analyse, improve and optimise the current control strategy implemented on this facility.

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