Note on the induction equation

1 Generalities

We want to solve the radial induction equation at the core-mantle boundary (CMB) which reads

$$\frac{\partial B_r}{\partial t} = -\nabla_H \cdot (\boldsymbol{u}_H B_r) \tag{1.1}$$

where B_r is the radial magnetic field, $\nabla_H \cdot$ the horizontal divergence operator and u_H the tangential flow. We can distribute the divergence operator over the whole product and get

$$\frac{\partial B_r}{\partial t} = -B_r \, \nabla_H \cdot \boldsymbol{u}_H - \boldsymbol{u}_H \cdot \nabla_H B_r \tag{1.2}$$

Generally, we assume the mantle to be insulating. As a result, no currents are circulating and $\nabla \times \mathbf{B} = \mathbf{0}$ as well as $\nabla \cdot \mathbf{B} = 0$. Then, the magnetic field derives from a potential and one may write

$$\boldsymbol{B} = -\boldsymbol{\nabla}V\tag{1.3}$$

with V the magnetic potential.

At the CMB, the core flow is constrained radially by the mantle. As a consequence, its radial component vanishes (ie. $u_r = 0$). Likewise, as it is incompressible, it is also divergence-free (ie. $\nabla \cdot \boldsymbol{u} = 0$). Then, it admits a unique poloidal-toroidal decomposition.

$$\boldsymbol{u} = \nabla \times (\boldsymbol{r}\,\mathcal{T}) + \nabla \times (\nabla \times (\boldsymbol{r}\,\mathcal{S})) \tag{1.4}$$

where \mathcal{T} and \mathcal{S} are the toroidal and poloidal scalar fields, respectively. At the CMB, the expression is further simplified and the tangential flow reads

$$\boldsymbol{u}_{H} = \nabla \times (\boldsymbol{r}\,T) + \nabla_{H}\,r\,\mathcal{S} \tag{1.5}$$

In this context, the condition $\nabla \cdot \boldsymbol{u} = 0$ is directly encoded into that of \boldsymbol{u}_H .

2 Decomposition in spherical coordinates

2.1 Expression for \mathbf{u}_H

$$u_{H} = \nabla \times (rT) + \nabla_{H}rS$$

$$= -r \times \nabla T + r\nabla_{H}S$$

$$= \begin{pmatrix} -\frac{\partial_{\phi}}{\sin(\theta)} \\ \partial_{\theta} \end{pmatrix} T + \begin{pmatrix} \frac{\partial_{\theta}}{\sin(\theta)} \\ \partial_{\phi} \end{pmatrix} S$$
(2.1)

2.2 Expression for $\nabla_H \cdot \boldsymbol{u}_H$

$$\nabla_{H} \cdot \boldsymbol{u}_{H} = \frac{1}{r \sin(\theta)} \partial_{\theta}(u_{\theta} \sin(\theta)) + \frac{1}{r \sin(\theta)} \partial_{\phi}(u_{\phi})$$

$$= \frac{1}{r \sin(\theta)} (\partial_{\theta\theta} + \partial_{\phi\phi}) \mathcal{S}$$
(2.2)

2.3 Expression for $\nabla_H B_r$

$$\nabla_{H}B_{r} = \begin{pmatrix} \frac{1}{r}\partial_{\theta} \\ \frac{1}{r\sin(\theta)}\partial_{\phi} \end{pmatrix} B_{r}$$
 (2.3)

3 Equation in spherical coordinates

$$\frac{\partial B_r}{\partial t} = -\frac{B_r}{r\sin(\theta)} (\partial_{\theta\theta} + \partial_{\phi\phi}) \mathcal{S}
- \frac{1}{r\sin(\theta)} [(-\partial_{\phi}\mathcal{T} + \partial_{\theta}\mathcal{S}) \partial_{\theta} B_r + (\partial_{\theta}\mathcal{T} + \partial_{\phi}\mathcal{S}) \partial_{\phi} B_r]$$
(3.1)

4 Condition on the flow

We are adding a supplementary constraint on the flow, given by the relation

$$\nabla_{H} \cdot (\boldsymbol{u}_{H} \cos(\theta)) = 0 \tag{4.1}$$

which in spherical coordinates reads

$$\nabla_{H} \cdot (\boldsymbol{u}_{H} \cos(\theta)) = \frac{1}{r \tan(\theta)} (\partial_{\theta\theta} + \partial_{\phi\phi}) \mathcal{S} + \frac{1}{r} (\partial_{\phi} \mathcal{T} - \partial_{\theta} \mathcal{S})$$

$$(4.2)$$