view_frames Result Recorded at time: 3216.324 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (3216.324 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (3216.324 sec old) Most recent transform: 3216.288 (0.036 sec old) Buffer length: 0.000 sec Buffer length: 4.940 sec shoulder_link base Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 3216.288 (0.036 sec old) Buffer length: 4.940 sec upper_arm_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 3216.288 (0.036 sec old) Buffer length: 4.940 sec forearm_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 3216.288 (0.036 sec old) Buffer length: 4.940 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 3216.288 (0.036 sec old) Buffer length: 4.940 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 3216.288 (0.036 sec old) Buffer length: 4.940 sec wrist_3_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (3216.324 sec old) Most recent transform: 0.000 (3216.324 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec ee_link tool0 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (3216.324 sec old) Buffer length: 0.000 sec robotiq_85_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 3216.288 (0.036 sec old) Most recent transform: 3216.288 (0.036 sec old) Most recent transform: 3216.288 (0.036 sec old) Most recent transform: 3216.288 (0.036 sec old) Buffer length: 4.940 sec Buffer length: 4.940 sec Buffer length: 4.940 sec Buffer length: 4.940 sec robotiq_85_left_knuckle_link robotiq_85_right_knuckle_link robotiq_85_left_inner_knuckle_link robotiq_85_right_inner_knuckle_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 0.000 (3216.324 sec old) Most recent transform: 0.000 (3216.324 sec old) Most recent transform: 3216.288 (0.036 sec old) Most recent transform: 3216.288 (0.036 sec old) Buffer length: 0.000 sec Buffer length: 4.940 sec Buffer length: 4.940 sec Buffer length: 0.000 sec robotiq_85_right_finger_link robotiq_85_left_finger_link robotiq_85_left_finger_tip_link robotiq_85_right_finger_tip_link