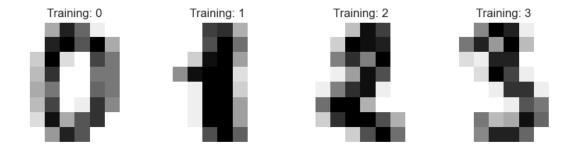
Q2 current 12

January 7, 2023

```
[]: import numpy as np
     import numpy as np
     import matplotlib.pyplot as plt
     from typing import List
     from sklearn import datasets, svm, metrics
     from sklearn.model_selection import train_test_split
     import numpy as np
     import matplotlib.pyplot as plt
     from sklearn.datasets import load_digits
     import matplotlib.pyplot as plt
     from sklearn.model_selection import train_test_split
     from sklearn.model selection import train test split
     import numpy as np
     from matplotlib import pyplot as plt
     import warnings
     warnings.filterwarnings("ignore")
     import matplotlib.pyplot as plt
     from typing import List
     import seaborn as sns
     sns.set_theme(context='notebook')
[]: # Load the digits dataset from scikit-learn
     digits = datasets.load_digits()
     # Create a figure with 1 row and 4 columns of subplots, and set the size of the
      \hookrightarrow figure
     _, axes = plt.subplots(nrows=1, ncols=4, figsize=(10, 3))
     # Iterate through the subplots and the images and labels from the digits dataset
     # and plot each image in a subplot, with the corresponding label as the title
     for ax, image, label in zip(axes, digits.images, digits.target):
         # Turn off the axis lines and labels for each subplot
         ax.set axis off()
         # Display the image in the subplot, using a grayscale color map
         ax.imshow(image, cmap=plt.cm.gray_r, interpolation="nearest")
         # Set the title of the subplot to the corresponding label
         ax.set_title("Training: %i" % label)
```



```
[]: def oneHot(x, classes):
         # Convert a 1D array of integers to a 2D one-hot encoded array
         return np.eye(classes)[x]
     def normalize(x: np.ndarray) -> np.ndarray:
         # Normalize the values in a numpy array so that they lie between 0 and 1
         return (x - np.min(x)) / (np.max(x) - np.min(x))
     # Get the number of samples in the digits dataset
     n_samples = len(digits.images)
     # Reshape the images array to a 2D array of shape (n_samples, 64)
     data = digits.images.reshape((n_samples, -1))
     # Get the labels for each image
     labels = digits.target
     # Split the data and labels into training and test sets
     split = int(0.8 * len(labels))
     x_train = data[:split].T
     y_train = labels[:split]
     # Convert the training labels to one-hot encoding
     y_train = oneHot(y_train, 10).T
     # Get the test data and labels
     x_test = data[split:].T
     y_test = labels[split:]
     # Save a copy of the test labels before they are one-hot encoded
     y_testDash = y_test
     # Convert the test labels to one-hot encoding
     y_test = oneHot(y_test, 10).T
     # Normalize the training data
```

```
x_train = normalize(x_train)
     # Print the shapes of the training and test data and labels
     print('Shapes: x_train: {}, y_train: {}, x_test: {}, y_test: {}'.format(x_train.
      ⇒shape, y_train.shape, x_test.shape, y_test.shape))
    Shapes: x_train: (64, 1437), y_train: (10, 1437), x_test: (64, 360), y_test:
    (10, 360)
[]: class NeuralNetwork(object):
         def __init__(self, x_train, y_train, activation, network):
             # Initialize the class with the training data, labels, and network _{f \sqcup}
      \rightarrow architecture
             self.epsilon = 1e-7
             self.x_train = x_train
             self.y_train = y_train
             self.network = network
             self.activation = activation
             self.paramsDict = {}
             self.layers = {}
             self.m = x_train.shape[1] # Number of training examples
             self.networkLen = len(network) # Number of layers in the network
         def getAccuracy(self, X, y):
             # Calculate the accuracy of the model on the given data and labels
             P = self.predict(X)
             return sum(np.equal(P, np.argmax(y, axis=0))) / y.shape[1]*100
         def softmax(self, z):
             # Calculate the softmax activation function
             e = np.exp(z - np.max(z))
             return e / np.sum(e, axis=0, keepdims=True)
         def activationFunction(self, z):
             # Calculate the activation function for a given input
             if self.activation == "tanh":
                 return np.tanh(z)
             elif self.activation == "relu":
                 return (z > 0) * 1
         def activationDerivative(self, z):
             # Calculate the derivative of the activation function for a given input
             if self.activation == "tanh":
                 return 1 - np.square(self.activationFunction(z))
             if self.activation == "relu":
                 v = (z > 0) * 1
```

return y

```
def init_params(self):
       for i in range(1, self.networkLen):
           self.paramsDict["W"+str(i)] = np.random.randn(self.network[i], self.
\rightarrownetwork[i-1]) * 0.01
           self.paramsDict["b"+str(i)] = np.zeros((self.network[i], 1))
  def forwardProp(self):
       # Calculate the forward propagation of the network
      params = self.paramsDict # Dictionary of model parameters
       self.layers["a0"] = self.x_train # Input layer
       for 1 in range(1, self.networkLen): # Loop through each layer in the
\rightarrownetwork
           # Calculate the weighted sum of the inputs and biases for the
⇔current layer
           self.layers["z" + str(1)] = np.dot(params["W" + str(1)], self.
\hookrightarrowlayers["a" + str(l-1)]) + params["b" + str(l)]
           # Calculate the activation of the current layer
           self.layers["a" + str(1)] = self.activationFunction(self.layers["z"
→+ str(1)])
       self.output = self.layers["a" + str(self.networkLen-1)] # Output of_
⇔the network
       # Calculate the cost of the model using the cross-entropy loss function
       # with a small constant added to the output to prevent taking the log_{\sqcup}
of 0
       cost = - np.sum(self.y_train * np.log(self.output + self.epsilon))
       return cost
  def backProp(self):
       # Initialize a dictionary to store the gradients for each layer
       derivatives = {}
       # Calculate the difference between the output and the labels
       dZ = self.output - self.y train
       # Calculate the gradient of the weights for the final layer using the
→difference and activations of the second-to-last layer
       dW = np.dot(dZ, self.layers["a" + str(self.networkLen-2)].T) / self.m
       # Calculate the gradient of the biases for the final layer using the
\hookrightarrow difference
       db = np.sum(dZ, axis=1, keepdims=True) / self.m
       # Calculate the gradient of the activations for the final layer using \Box
→ the weights and difference
       dA_prev = np.dot(self.paramsDict["W" + str(self.networkLen-1)].T, dZ)
       # Store the gradients for the final layer
       derivatives["dW" + str(self.networkLen-1)] = dW
       derivatives["db" + str(self.networkLen-1)] = db
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for l in range(self.networkLen-2, 0, -1):
           dZ = dA_prev * self.activationDerivative(self.layers["z" + str(1)])
→# Propagate derivatives after computing using the function
           dW = 1. / self.m * np.dot(dZ, self.layers["a" + str(l-1)].T) #_L
⇔Weights derivative
           db = 1. / self.m * np.sum(dZ, axis=1, keepdims=True) # Bias_
           dA_prev = np.dot(self.paramsDict["W" + str(1)].T, dZ) # Compute_
→previous dA using the paramsDict
           derivatives["dW" + str(1)] = dW # Save derivatives of weights
           derivatives["db" + str(1)] = db # Save derivatives of bias
      return derivatives
  def fit(self, lr, epochs):
      self.costList = □
      self.accList = []
      self.init params()
      for epoch in range(epochs): # forward propagate to calculate cost
           cost = self.forwardProp() # forward propagation to compute last_
→ layer activations
           self.costList.append(cost) # backward propagate to calculate_
\rightarrow qradients
           derivatives = self.backProp() # backward propagation to compute_
\hookrightarrow gradients
           for layer in range(1, self.networkLen): # update parameters based_
→on the update rule using derivatives
               self.paramsDict["W"+str(layer)] = self.
paramsDict["W"+str(layer)] - lr * derivatives["dW" + str(layer)]
               self.paramsDict["b"+str(layer)] = self.
paramsDict["b"+str(layer)] - lr * derivatives["db" + str(layer)]
           train_accuracy = self.getAccuracy(self.x_train, self.y_train)
           self.accList.append(train_accuracy) # capture training accuracy
           if epoch\%40 == 0:
               print('Train Accuracy for epoch: {} is: {}%'.format(epoch, np.
→round(train_accuracy, 3)))
      return self.costList, self.accList
  def predict(self, x):
      z = x
      for l in range(1, self.networkLen):
       # Activation function is applied to the dot product of the weights and \Box
⇔inputs, plus the bias
           a = self.activationFunction(np.dot(self.paramsDict["W" + str(1)],
→z) + self.paramsDict["b" + str(1)])
           z = a
```

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# Final output is passed through the softmax function to give_
probabilities for each label

output = self.softmax(z)

# If there is more than one input, return a list of the predicted_
plabels (index of highest probability)

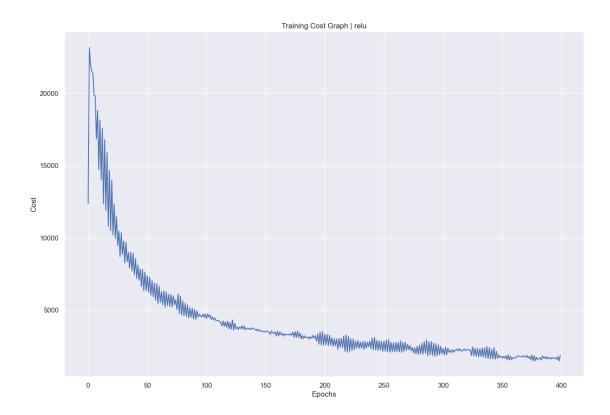
# Otherwise, return a single predicted label
return np.argmax(output, axis=0) if x.shape[1] > 1 else np.

argmax(output)
```

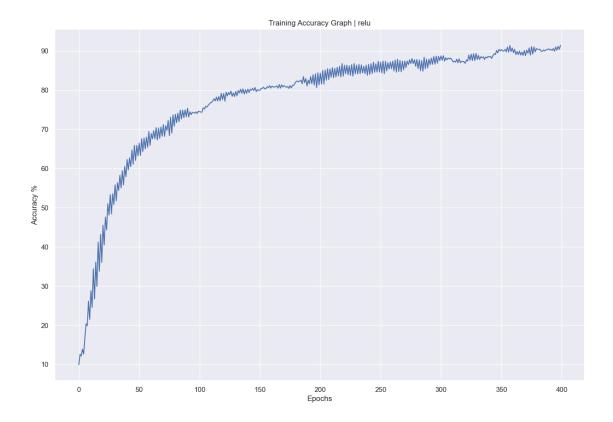
Network can be adjusted as required, for this case I have set the architecture to be "[x_train.shape[0], 700, 200, 10]". Note: The first layer has contain x_train.shape[0] and the last one has to contain 10, to match the input features and the output classes respectively.

Relu

```
[]: obj1 = NeuralNetwork(x_train, y_train, "relu",[x_train.shape[0], 700, 200, 10])
     costList, accList = obj1.fit(0.01, 400)
     testAcc = obj1.getAccuracy(x test, y test)
     print('Test Accuracy is: ', np.round(testAcc,3), '%')
    Train Accuracy for epoch: 0 is: 9.951%
    Train Accuracy for epoch: 40 is: 62.283%
    Train Accuracy for epoch: 80 is: 73.834%
    Train Accuracy for epoch: 120 is: 79.123%
    Train Accuracy for epoch: 160 is: 81.002%
    Train Accuracy for epoch: 200 is: 84.342%
    Train Accuracy for epoch: 240 is: 86.569%
    Train Accuracy for epoch: 280 is: 87.822%
    Train Accuracy for epoch: 320 is: 86.848%
    Train Accuracy for epoch: 360 is: 89.562%
    Test Accuracy is: 69.444 %
[]: plt.figure(figsize=(15,10))
    plt.plot(costList)
     plt.title('Training Cost Graph | relu')
     plt.xlabel('Epochs')
     plt.ylabel('Cost')
     plt.show()
```



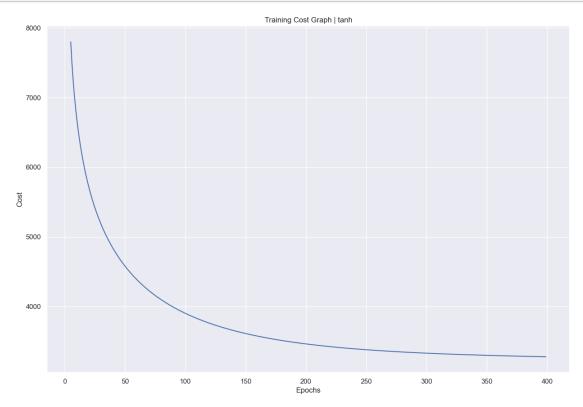
```
[]: plt.figure(figsize=(15,10))
  plt.plot(accList)
  plt.title('Training Accuracy Graph | relu')
  plt.xlabel('Epochs')
  plt.ylabel('Accuracy %')
  plt.show()
```



Tanh

```
[]: obj1 = NeuralNetwork(x_train, y_train, "tanh",[x_train.shape[0], 700, 200, 10])
     costList, accList = obj1.fit(0.01, 400)
     testAcc = obj1.getAccuracy(x_test, y_test)
     print('Test Accuracy is: ', np.round(testAcc, 3), '%')
    Train Accuracy for epoch: 0 is: 12.317%
    Train Accuracy for epoch: 40 is: 15.936%
    Train Accuracy for epoch: 80 is: 23.104%
    Train Accuracy for epoch: 120 is: 29.367%
    Train Accuracy for epoch: 160 is: 35.56%
    Train Accuracy for epoch: 200 is: 44.468%
    Train Accuracy for epoch: 240 is: 52.679%
    Train Accuracy for epoch: 280 is: 59.708%
    Train Accuracy for epoch: 320 is: 65.901%
    Train Accuracy for epoch: 360 is: 70.912%
    Test Accuracy is: 60.278 %
[]: plt.figure(figsize=(15,10))
     plt.plot(costList)
     plt.title('Training Cost Graph | tanh')
     plt.xlabel('Epochs')
```

```
plt.ylabel('Cost')
plt.show()
```



```
[]: plt.figure(figsize=(15,10))
  plt.plot(accList)
  plt.title('Training Accuracy Graph | tanh')
  plt.xlabel('Epochs')
  plt.ylabel('Accuracy %')
  plt.show()
```

