

# CS498: Algorithmic Engineering

## Lecture 6: Modeling Patterns for Integer Programs

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# Outline

- 1 Formulation Strength
- 2 Setup and Motivation
- 3 Core Binary Modeling Patterns
- 4 Disjunctions and Big-M
- 5 SOS1 and SOS2
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# 0–1 Knapsack and Its LP Relaxation

General 0–1 knapsack:  $\max \sum_{i=1}^n v_i x_i$

$$\text{s.t. } \sum_{i=1}^n w_i x_i \leq C, \quad x_i \in \{0, 1\} \text{ for all } i.$$

LP relaxation:

$$0 \leq x_i \leq 1 \quad \text{instead of } x_i \in \{0, 1\}.$$

Now the LP is allowed to take *fractions* of items:

$$x_1 = 1, \quad x_2 = 0.4, \quad x_3 = 0.6, \dots$$

At the root node of B&B:

- LP value at root becomes the upper bound  $UB_{\text{root}}^{(0)}$ .
- Any integer solution has value  $\leq z_{\text{ILP}}^*$ .

Typically:  $UB_{\text{root}}^{(0)} > z_{\text{ILP}}^*$ , so the solver *must* branch to prove there is nothing better than  $z_{\text{ILP}}^*$ .

# Strengthening with Cover Inequalities

A **cover**  $S \subseteq \{1, \dots, n\}$  is any set of items with  $\sum_{i \in S} w_i > C$ .

These items **do not all fit** in the knapsack. We can build stronger and stronger LP relaxations:

- **Model  $M_0$  (weak):** only the knapsack constraint,  $\sum_{i=1}^n w_i x_i \leq C$ .
- **Model  $M_1$  (pairs):**  $M_0$  + all 2-item covers

$$x_i + x_j \leq 1 \quad \text{for every pair } \{i, j\} \text{ with } w_i + w_j > C.$$

- **Model  $M_2$  (triples):**  $M_1$  + all 3-item covers

$$x_i + x_j + x_k \leq 2 \quad \text{for every triple with } w_i + w_j + w_k > C.$$

- ... and so on, adding covers of size 4, 5, ...,  $k$ .

Each step: same integer problem, but LP relaxation gets tighter.

# How the Number of Inequalities Blows Up

For each cover  $S$  we add

$$\sum_{i \in S} x_i \leq |S| - 1.$$

## Counting them:

- All 2-item covers: up to  $\binom{n}{2} = O(n^2)$  inequalities.
- All 3-item covers: up to  $\binom{n}{3} = O(n^3)$  inequalities.
- All covers with  $|S| \leq k$ : up to  $O(n^k)$  inequalities.
- All covers of any size: potentially exponentially many.

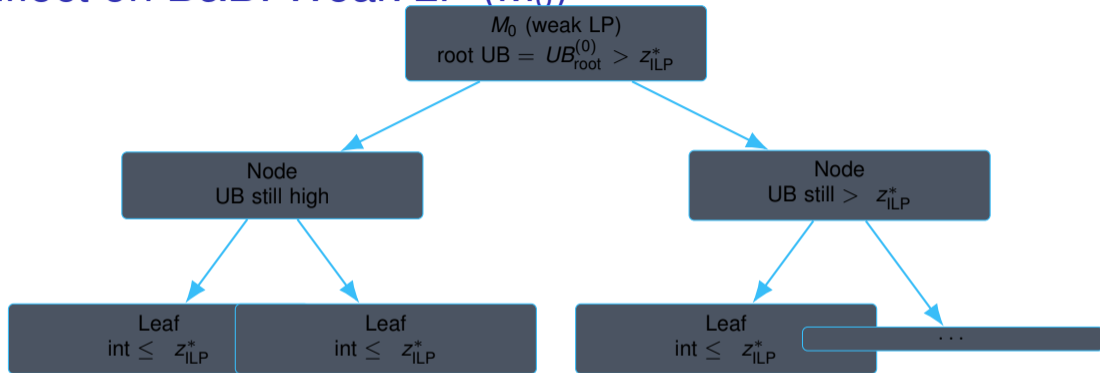
As we move from  $M_0$  to  $M_1$  to  $M_2$  to  $\dots$ :

$$z_{\text{LP}(M_0)}^* \geq z_{\text{LP}(M_1)}^* \geq z_{\text{LP}(M_2)}^* \geq \dots \geq z_{\text{ILP}}^*.$$

LP bounds get closer to the true integer optimum,

But the LP itself gets larger and more expensive to solve (more rows, denser constraint matrix).

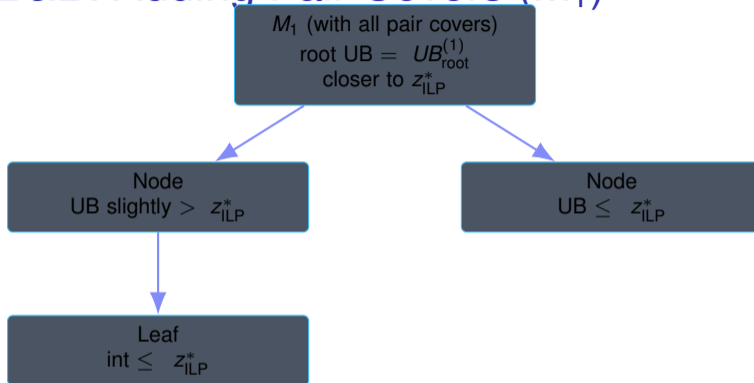
# Effect on B&B: Weak LP ( $M_0$ )



## Behavior:

- Root UB far above the best integer value.
- LP relaxation gives weak guidance.
- Solver must explore many nodes before pruning.

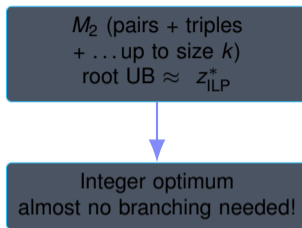
# Effect on B&B: Adding Pair Covers ( $M_1$ )



## Behavior:

- Pair-cover inequalities tighten the relaxation.
- Root UB moves closer to the true integer optimum.
- Some nodes are pruned much earlier than in  $M_0$ .

# Effect on B&B: Adding Higher-Order Covers ( $M_2$ )



## Behavior:

- Root LP bound is very close to, or equal to,  $z_{ILP}^*$ .
- The B&B tree essentially collapses to the root.
- But the LP now has  $O(n^k)$  extra inequalities. Solving the LP takes as much as brute forcing!

# Formulation Strength vs Search Effort

- Starting from the basic knapsack LP ( $M_0$ ), bounds are loose, and the solver has to explore many nodes.
- Adding all pair covers ( $M_1$ ) and then all triples, etc. ( $M_2$ ) makes the LP bounds tighter and the B&B tree smaller.

But:

- The number of cover inequalities grows as  $O(n^2)$ ,  $O(n^3)$ ,  $\dots$ ,  $O(n^k)$ .
- Solving the LP at each node becomes more and more expensive.

**Big picture:**

Stronger LP  $\Rightarrow$  fewer nodes but bigger LPs.

Good models strike a balance:

- LP strong enough to give meaningful bounds,
- but not so huge that the LP solve itself dominates the running time.

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# Why Modeling Patterns Matter

- In practice, the hard part is rarely “solving” the IP.
- The hard part is **formulating** the problem so that:
  - ▶ it captures the real-world constraints, and
  - ▶ it is solver-friendly (strong LP relaxation).
- Instead of reinventing the wheel every time, we reuse patterns:
  - ▶ selection / knapsack,
  - ▶ fixed-charge on/off,
  - ▶ logical implications,
  - ▶ cardinality and “at most  $k$ ”,
  - ▶ either–or and disjunctions,
  - ▶ SOS1/SOS2 for piecewise-linear functions.

Today’s lecture = “design patterns” for integer programming.

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# Pattern 1: Subset Selection / 0–1 Knapsack

Basic 0–1 knapsack:

$$\max \sum_{i=1}^n v_i x_i \quad \text{s.t.} \quad \sum_{i=1}^n w_i x_i \leq C, \quad x_i \in \{0, 1\}.$$

Interpretation:

- $x_i = 1 \Rightarrow$  choose item  $i$ .
- $x_i = 0 \Rightarrow$  do not choose item  $i$ .

**Pattern name:** binary **subset selection**.

## Pattern 2: Fixed-Charge / On–Off Decisions

Many problems have a **fixed cost** to “turn something on” before you use it:

- Opening a facility.
- Starting up a machine for the day.
- Using a particular shipping route (e.g. Suez Canal registration fees).

### Variables:

- $y \in \{0, 1\}$ : on/off decision.
- $q \geq 0$ : flow / production / quantity.

**Model:**  $0 \leq q \leq Q_{\max}y$  and  $y \in \{0, 1\}$ .

If  $y = 0 \Rightarrow q = 0$

if  $y = 1 \Rightarrow 0 \leq q \leq Q_{\max}$

# Fixed-Charge Example: Mini Factory Startup

Simple factory:

- Revenue: \$6 per unit produced.
- Fixed startup cost: \$200 if we open.
- Capacity: at most 50 units.

$$\begin{aligned} \max \quad & 6q - 200y \\ \text{s.t.} \quad & 0 \leq q \leq 50y, \\ & y \in \{0, 1\}. \end{aligned}$$

## Observations:

- If  $y = 0$ : we get  $q = 0$ , profit = 0.
- If  $y = 1$ : we choose  $q = 50$ .

**Pattern name:** *fixed-charge on/off*.

## Pattern 3: Logical Implications (If A then B)

Suppose we have 2 options:

$$A, B \in \{0, 1\}.$$

Requirements:

- If  $A$  is chosen,  $B$  must be chosen.

**Encoding:**

$$A \leq B.$$

- If  $A = 1$  then  $B = 1$ .
- If  $A = 0$  then  $B \in \{0, 1\}$ .

**Pattern name:** *binary implication / precedence constraints.*

# Pattern 3 in Gurobi: Logical Implication with >>

**Goal:** If  $A = 1$ , then enforce constraint  $a^\top x \leq b$ .

```
import gurobipy as gp
from gurobipy import GRB

m = gp.Model("implication_demo")

# Binary "trigger" variable A
A = m.addVar(vtype=GRB.BINARY, name="A")

# Some continuous variables x
x1 = m.addVar(lb=0.0, name="x1")
x2 = m.addVar(lb=0.0, name="x2")

# If A == 1, then x1 + 2*x2 <= 5
m.addConstr((A == 1) >> (x1 + 2*x2 <= 5), name="A_implies_constr") #Only new thing here.
m.setObjective(x1 + x2 - 10*A, GRB.MINIMIZE)
m.optimize()
```

**Notes:** The constraint only *activates* when  $A = 1$ .

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## Pattern 4: Either–Or Constraints

Many decisions are mutually exclusive:

- Route A or Route B (but not both).
- Use technology 1 or technology 2.
- Choose one of several pricing schemes.

Basic idea: introduce binaries  $z_A, z_B$ :

$$z_A + z_B = 1, \quad z_A, z_B \in \{0, 1\}.$$

Then “gate” each option:

- If Route A: constraints for Route A active when  $z_A = 1$ .
- If Route B: constraints for Route B active when  $z_B = 1$ .

# Either–Or Example: Two Shipping Routes

Demand:  $D$  units, must ship all of it. Two routes:

- Route 1: cost  $c_1$  per unit, capacity  $U_1$ .
- Route 2: cost  $c_2$  per unit, capacity  $U_2$ .

Variables:

$$f_1, f_2 \geq 0, \quad z_1, z_2 \in \{0, 1\}.$$

Constraints:

$$\begin{aligned} f_1 + f_2 &= D, \\ f_1 &\leq U_1 z_1, \quad f_2 \leq U_2 z_2, \\ z_1 + z_2 &= 1. \end{aligned}$$

Objective:

$$\min c_1 f_1 + c_2 f_2.$$

**Pattern name:** *either–or / disjunctive constraints.*

## Pattern 5: Big- $M$

We often need a binary variable  $z$  to indicate if a linear inequality is satisfied.

$$z = 1 \implies a^\top x \leq b$$

Using Big- $M$ , we can encode this logic linearly:

$$a^\top x \leq b + M(1 - z) \quad z \in \{0, 1\}$$

- If  $z = 1$ : constraint is enforced  $\Rightarrow a^\top x \leq b$ .
- If  $z = 0$ : constraint relaxed  $\Rightarrow a^\top x \leq b + M$  (always true if  $M$  large enough).

Question: How do we choose  $M$ ?

# Tiny Big- $M$ Demo: Tight vs Loose $M$

Consider relaxation (i.e.  $0 \leq y \leq 1$ ) of:

$$\min y \text{ s.t. } x \geq 1, \quad x \leq My, \quad y \in \{0, 1\}.$$

## Case 1: Tight $M = 1$ .

- Constraints:  $x \geq 1, x \leq y \Rightarrow y \geq 1$ .
- Feasible LP region: only  $x = 1, y = 1$ .
- LP relaxation = integer solution  $\Rightarrow$  **strong LP**.

## Case 2: Loose $M = 1000$ .

- Constraints:  $x \geq 1, x \leq 1000y$ .
- LP can pick  $y = 0.001, x = 1$ .
- Objective  $y$  becomes tiny  $\Rightarrow$  large integrality gap.
- Branch-and-bound must search many nodes.

## Takeaway:

- $M$  must be just large enough to model the logic correctly.
- Too-large  $M$  weakens the LP relaxation and slows the solver.

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# Special Ordered Sets: SOS1 and SOS2

Solvers support **Special Ordered Sets** patterns:

**SOS1:** At most one variable in the set can be non-zero.

**SOS2:** At most two adjacent variables (in a specified order) can be non-zero.

## Usage:

- SOS1: choose exactly one option / segment / pattern.
- SOS2: piecewise-linear functions with convex hull interpolation.

## Benefit:

- 1 Solver can internally use clever heuristics designed for either SOS1/SOS2.

# Gurobi: Using SOS1 for Choice Modeling

## Example: choose exactly one option

```
import gurobipy as gp
from gurobipy import GRB

m = gp.Model("inventory_complementarity")
demand = 50

# Continuous decision variables
produced = m.addVar(lb=0, ub=supply, name="produced")
leftover = m.addVar(lb=0, name="leftover_stock")
backorder = m.addVar(lb=0, name="unmet_demand")

# produced - leftover + backorder = demand
m.addConstr(produced - leftover + backorder == demand)

# Complementarity: cannot have leftover AND backorder
m.addSOS(GRB.SOS_TYPE1, [leftover, backorder]) #New

# Penalties
m.setObjective(1*leftover + 100*backorder, GRB.MINIMIZE)
m.optimize()
```

## Interpretation:

- SOS1 enforces mutual exclusivity. Exactly one of leftover or demand is non-zero.

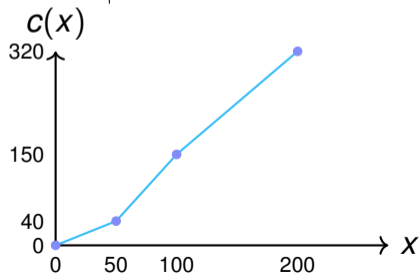
# Motivating SOS2: What Is a Piecewise-Linear Function?

A **piecewise-linear (PWL)** function is made of straight segments between known **breakpoints**:

$$(x_0, c_0), (x_1, c_1), \dots, (x_K, c_K).$$

**Example:**

$k$	0	1	2	3
$x_k$	0	50	100	200
$c_k$	0	40	150	320



# Representing a Point on the Curve

We want to represent an arbitrary point  $(x, c)$  on this broken line.

Idea: write it as a **convex combination** of the breakpoints.

$$(x, c) = \sum_{k=0}^K \lambda_k (x_k, c_k), \quad \sum_{k=0}^K \lambda_k = 1, \quad \lambda_k \geq 0.$$

**Example:** Suppose the true point is halfway between  $(x_1, c_1) = (50, 40)$  and  $(x_2, c_2) = (100, 150)$ .

$$\lambda_1 = 0.5, \quad \lambda_2 = 0.5, \quad \text{others} = 0.$$

Then

$$x = 50(0.5) + 100(0.5) = 75, \quad c = 40(0.5) + 150(0.5) = 95.$$

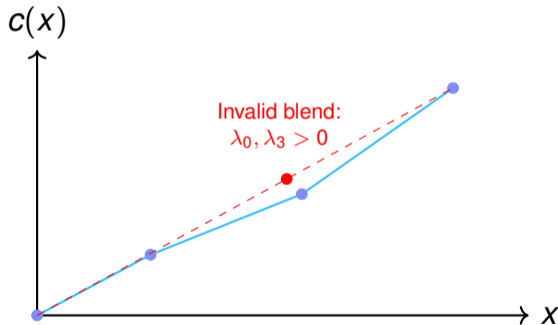
$(x, c) = (75, 95)$  lies exactly on the line segment between breakpoints 1 and 2.

# Why We Need an Additional Rule

The convex combination equations alone allow mixtures of *non-adjacent* breakpoints:

$$\lambda_0 = 0.3, \lambda_3 = 0.7 \Rightarrow x = 140, c = 224.$$

But that point is **not on the curve**—it “cuts across” segments.



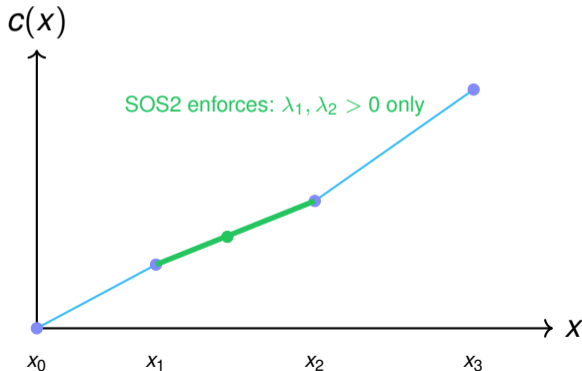
We must ensure that at most **two adjacent**  $\lambda_k$  are positive.

# Special Ordered Sets Type 2 (SOS2)

The adjacency rule is enforced by declaring the  $(\lambda_0, \dots, \lambda_K)$  as an **SOS2 set** ordered by  $x_k$ .

## SOS2 definition:

- At most two  $\lambda_k$  can be nonzero, and **adjacent in the order of  $x_k$** .



# Gurobi: Declaring an SOS2 Set

Example code for a piecewise-linear cost:

```
import gurobipy as gp
from gurobipy import GRB

xs = [0, 50, 100, 200]
cs = [0, 40, 150, 320]    # cost at breakpoints

m = gp.Model("piecewise_cost")

lam = m.addVars(len(xs), lb=0.0, name="lam")
x    = m.addVar(lb=0.0, name="x")
c    = m.addVar(lb=0.0, name="cost")

# Convex combination for x
m.addConstr(gp.quicksum(lam[k] for k in range(len(xs))) == 1)
m.addConstr(x == gp.quicksum(xs[k] * lam[k] for k in range(len(xs))))

# SOS2 declaration: at most two adjacent lambdas > 0
m.addSOS(GRB.SOS_TYPE2, [lam[k] for k in range(len(xs))], xs) #New!!

# Final convex combination for cost
m.addConstr(c == gp.quicksum(cs[k] * lam[k] for k in range(len(xs))))
```

# Homework: Building SOS1 and SOS2 from Scratch

In this week's HW, you'll **implement the same ideas manually** using big- $M$  and binary variables. For SOS2:

**Step 1:** Start from the breakpoints

$$(x_k, c_k) = (0, 0), (50, 40), (100, 150), (200, 320)$$

and define binary variables  $z_k \in \{0, 1\}$  that pick which segment is active.

**Step 2:** Use Big- $M$  or indicator constraints to:

- enforce that exactly one segment is active,
- interpolate  $x$  and  $c$  correctly within that segment.

**Goal:** understand how SOS1/SOS2 encapsulates the same logic you'd otherwise build with Big- $M$  + binaries.

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# Summary of Lecture 6

- We saw core **binary modeling patterns**:
  - ▶ selection / knapsack,
  - ▶ fixed-charge on/off and linking constraints,
  - ▶ logical implications and precedence,
  - ▶ either–or disjunctions via binaries.
- We discussed **Big- $M$** :
  - ▶ too-large  $M \Rightarrow$  weak LP, big B&B tree,
  - ▶ use data/context to tighten  $M$  and strengthen the formulation.
- We introduced **SOS1/SOS2**:
  - ▶ solver-native constructs for at-most-one and piecewise-linear modeling,
  - ▶ avoid manual Big- $M$  and get stronger relaxations.