

Tube adjustments:

0.998  $\alpha_u$

1.0  $\alpha_L$

0.98  $\beta_u$

1.0  $\beta_l$

On state T and Inputs  $V_{in}$

$W_x$  for  $k:N-1=0$  on all dual controllers  
Violation penalty=10 for soft constraint













