



# **Chapter 20: Database System Architectures**

**Database System Concepts, 7<sup>th</sup>  
Ed.**

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# Outline

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- Centralized Database Systems
- Server System Architectures
- Parallel Systems
- Distributed Systems
- Network Types



# Centralized Database Systems

- Run on a **single computer system** *centralized database system is that all data is stored, managed, and processed on a single centralized server or system*
- **Single-user system**
- **Multi-user systems** also known as **server systems**.
  - Service requests received from client systems
  - Multi-core systems with **coarse-grained parallelism**
    - Typically, a few to tens of processor cores
    - In contrast, **fine-grained parallelism** uses very large number of computers or nodes [*Not belong to centralized database systems, rather distributed database systems*]

|                                   |   |
|-----------------------------------|---|
| <b>coarse-grained parallelism</b> | Few big tasks across <b>few (4–64) CPU cores</b>          |
| <b>fine-grained parallelism</b>   | Many tiny tasks across <b>many machines or processors</b> |

Horizontal scaling (Scale out) : increasing the number of machines/nodes in the cluster

Vertical scaling (Scale Up): increasing the number of CPUs, RAM, Storage



# Server System Architecture

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- Server systems can be broadly categorized into two kinds:
  - **Transaction servers**
    - Widely used in relational database systems, and
    - Ensure ACID Properties: *Consistency, Atomicity, Isolation, and Durability*.
  - **Data servers**
    - Parallel data servers used to implement high-performance transaction processing systems



# Transaction Servers

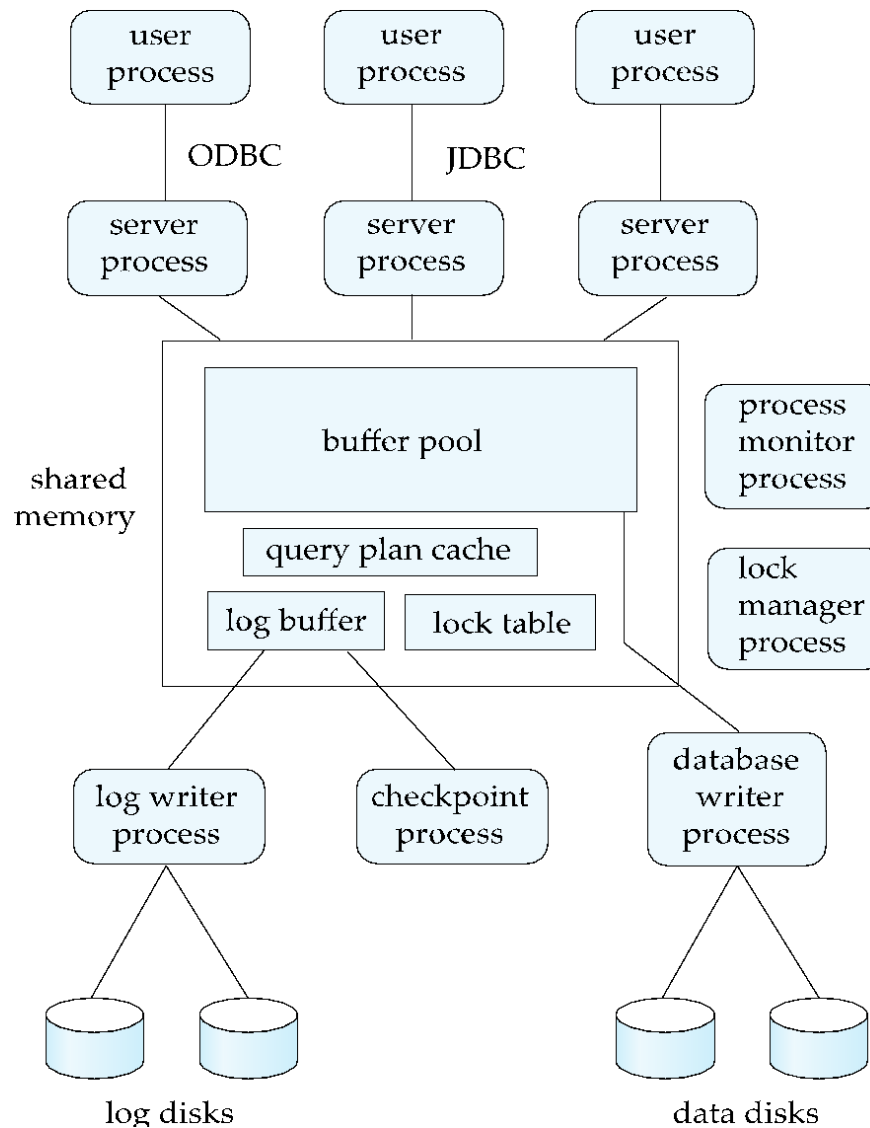
- Also called **query server** systems or SQL server systems
  - Clients send requests to the server
  - Transactions are executed at the server
  - Results are shipped back to the client.
- Requests are specified in SQL and communicated to the server through a *remote procedure call* (RPC) mechanism.
  - SQL: `SELECT * FROM Orders WHERE CustomerID = 5;`
  - RPC: Call `executeSQL("SELECT * FROM Orders WHERE CustomerID = 5")`
- Transactional RPC allows many RPC calls to form a transaction. *So any of the failing or RPC call will revert back all the previous calls.*
  1. `StartTransaction()`, 2. RPC: Insert new order, 3. RPC: Update customer balance 4. RPC: Deduct inventory, 5. `CommitTransaction()`
- Applications typically use ODBC/JDBC APIs to communicate with transaction servers

```
Connection conn = DriverManager.getConnection(url, user, pass);
conn.setAutoCommit(false);
Statement stmt = conn.createStatement();
stmt.executeUpdate("UPDATE accounts SET balance = balance - 100 WHERE id = 1");
stmt.executeUpdate("UPDATE accounts SET balance = balance + 100 WHERE id = 2");
conn.commit();
```

Example with JDBC



# Transaction System Processes (Cont.)





# Transaction Server Process Structure

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- A typical transaction server consists of **multiple processes** accessing **data in shared memory**
- **Shared memory** contains shared data
  - **Buffer pool** [For buffering]
  - **Lock table** [Lock Mechanism]
  - **Log buffer** [Activity Logging]
  - **Cached query plans** (reused if same query submitted again)
- All **database processes** can access shared memory
- **Server processes**
  - These receive user queries (transactions), execute them and send results back
  - Processes may be **multithreaded**, allowing a **single process to execute several user queries concurrently**
  - Typically, **multiple multithreaded server processes**



# Transaction Server Processes (Cont.)

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- **Database writer process**
  - Output modified buffer blocks to disks continually
- **Log writer process**
  - Server processes simply add log records to log record buffer
  - Log writer process outputs log records to stable storage.
- **Checkpoint process**
  - Performs periodic checkpoints
- Process monitor process
  - **Monitors other processes**, and takes recovery actions if any of the other processes fail
    - E.g. aborting any transactions being executed by a server process and restarting it





# Transaction System Processes (Cont.)

- **Lock manager process**

- To avoid overhead of interprocess communication for lock request/grant, each database process operates directly on the lock table
  - Instead of sending requests to lock manager process
- Lock manager process still used for deadlock detection

- **To ensure that no two processes are accessing the same data structure at the same time**, databases systems implement **mutual exclusion** using either

- Atomic instructions
  - Test-And-Set
  - Compare-And-Swap (CAS)
- Operating system semaphores
  - Higher overhead than atomic instructions
  - Important for process synchronization and mutual exclusion

a **semaphore** is a **synchronization primitive** used to **control access to shared resources** in a **concurrent system** like multitasking processes or threads.

`wait()` (also called `P()` or `down()`)  
`signal()` (also called `V()` or `up()`)



# Atomic Instructions

## ▪ **Test-And-Set(M)**

- Memory location M, initially 0
- Test-and-set(M) sets M to 1, and returns old value of M
  - Return value 0 indicates process has acquired the mutex
  - Return value 1 indicates someone is already holding the mutex
    - Must try again later
  - Release of mutex done by setting M = 0

```
// Lock variable
int M = 0;

// Process trying to acquire the lock
while (TestAndSet(M) == 1) {
    // Busy-wait (spinlock)
}

// Critical section
// ...

// Release the lock
M = 0;
```



# Atomic Instructions

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- **Compare-and-swap**(M, V1, V2)
  - Atomically do following
    - If  $M = V1$ , set  $M = V2$  and return success
    - Else return failure
  - With  $M = 0$  initially,  $\text{CAS}(M, 0, 1)$  equivalent to test-and-set(M)
  - Can use  $\text{CAS}(M, 0, \text{id})$  where  $\text{id}$  = thread-id or process-id to record who has the mutex



# Data Servers/Data Storage Systems

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- Data items are shipped to clients where processing is performed.  
Instead of doing heavy computation or query processing on the **server**, the **raw data is sent to the client**, which does the necessary processing (e.g., filtering, aggregating). This system is known as client-centric system. E.g., Edge Computing.
- Updated data items written back to server. [Persistency]
- Earlier generation data servers **operated on disk pages, each potentially containing multiple data items, or occasionally at the level of individual items**. In contrast, current-generation data storage systems operate exclusively at the level of individual data items.
- Current generation commonly includes:
  - Commonly used data item formats include JSON, XML, or just uninterpreted binary strings



# Data Servers/Storage Systems (Cont.)

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- **Prefetching**
  - Prefetch items that may be used soon
- **Data caching**
  - Cache coherence
- **Lock caching**
  - Locks can be cached by client across transactions
  - Locks can be **called back** by the server
- **Adaptive lock granularity**
  - **Lock granularity escalation**
    - switch from finer granularity (e.g. tuple) lock to coarser
  - **Lock granularity de-escalation**
    - Start with coarse granularity to reduce overheads, switch to finer granularity in case of more concurrency conflict at server
    - Details in book



# Data Servers (Cont.)

## ▪ Data Caching

- **Data can be cached at client** even in between transactions
- But check that **data is up-to-date before it is used** (**cache coherency**)
- **Check can be done when requesting lock on data item**

## ▪ Lock Caching (not immediate release of the lock after transaction execution)

- Locks can be retained by client system even in between transactions
- Transactions can acquire cached locks locally, without contacting server
- Server **calls back** locks from clients when it receives conflicting lock request. If **another client** requests a lock that **conflicts** (e.g., wants to write to the same data), the server sends a **callback** to the caching client: *return the lock*
  - *If any local transaction is using it, it can not return, otherwise it returns*
  - Client returns lock once no local transaction is using it.
  - This idea is similar to lock callback on prefetch, but across transactions, keeping lock though the transaction has already



# Parallel Systems

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- Parallel database systems consist of multiple processors and multiple disks connected by a fast interconnection network.
- Motivation: handle workloads beyond what a single computer system can handle
- High performance **transaction processing**
  - E.g. handling user requests at web-scale
- **Decision support** on very large amounts of data
  - E.g. data gathered by large web sites/apps



# Parallel Systems (Cont.)

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- A **coarse-grain parallel** machine consists of a small number of powerful processors
- A **massively parallel** or **fine grain parallel** machine utilizes thousands of smaller processors.
  - Typically hosted in a **data center**
- Two main performance measures:
  - **Throughput** --- the number of tasks that can be completed in a given time interval
  - **Response time** --- the amount of time it takes to complete a single task from the time it is submitted





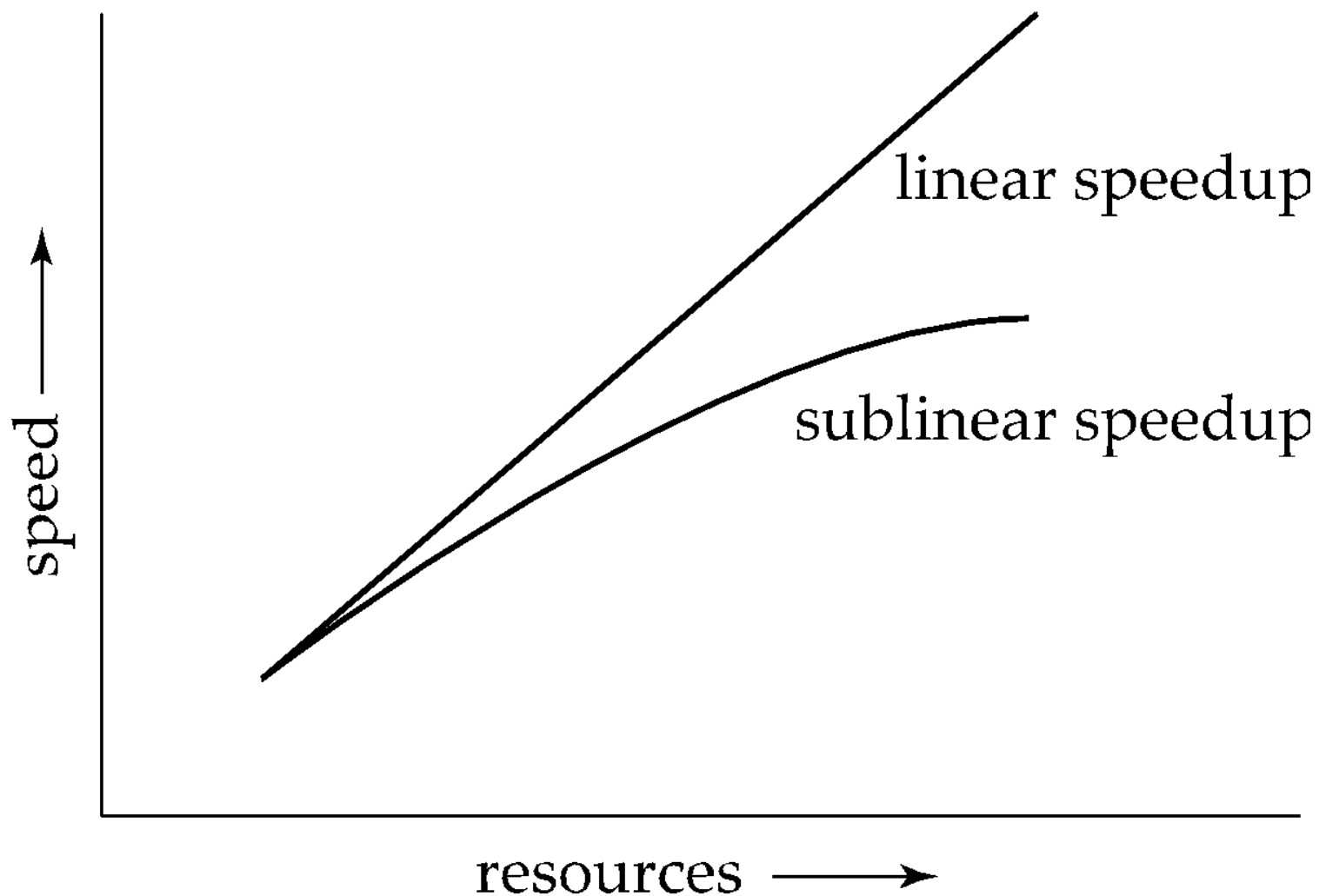
# Speed-Up and Scale-Up

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- **Speedup**: a fixed-sized problem executing on a small system is given to a system which is  $N$ -times larger.
  - Measured by:
$$\text{speedup} = \frac{\text{small system elapsed time}}{\text{large system elapsed time}}$$
  - Speedup is **linear** if equation equals  $N$ .
- **Scaleup**: increase the size of both the problem and the system
  - $N$ -times larger system used to perform  $N$ -times larger job
  - Measured by:
$$\text{scaleup} = \frac{\text{small system small problem elapsed time}}{\text{big system big problem elapsed time}}$$
  - Scale up is **linear** if equation equals 1.

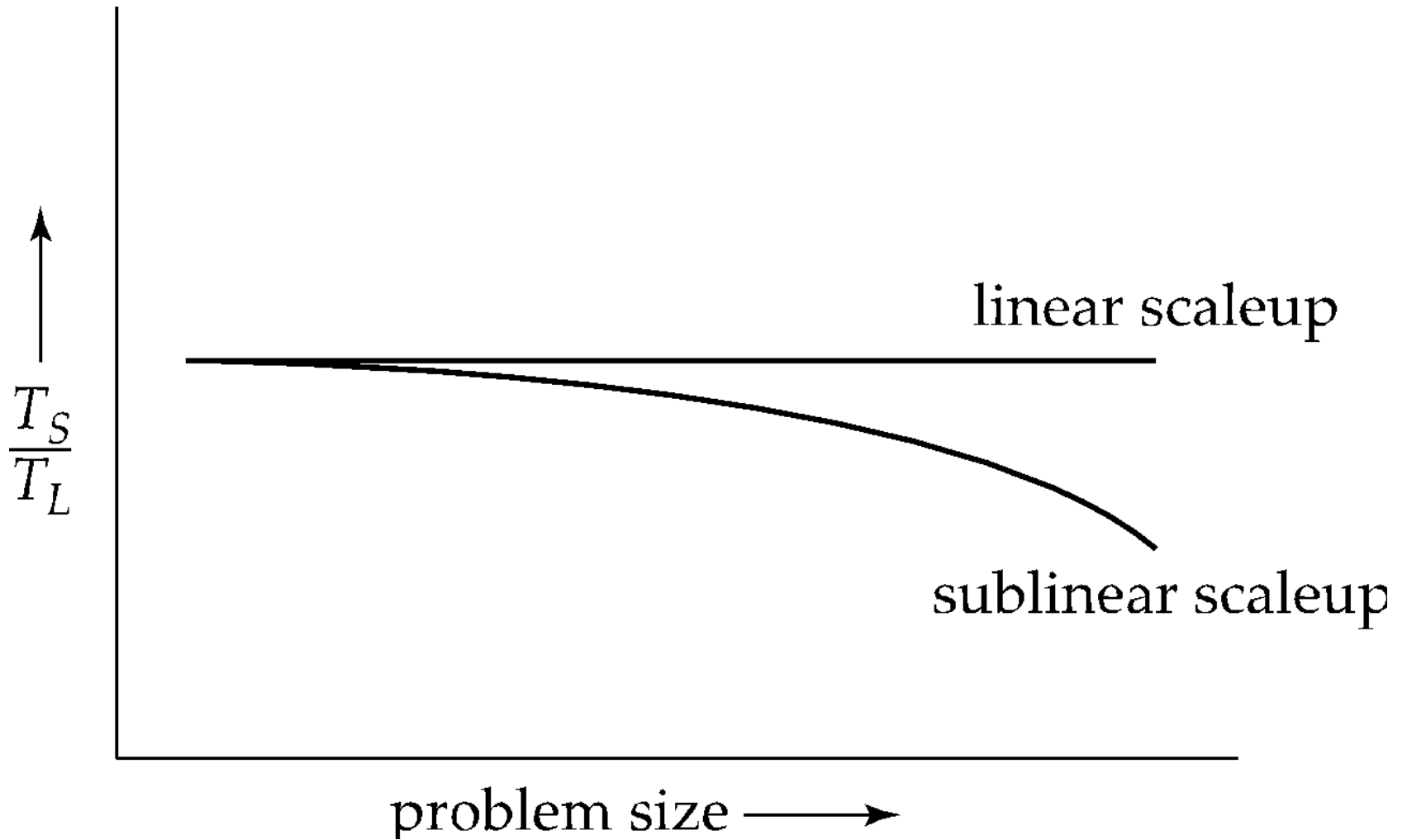


# Speedup





# Scaleup





# Batch and Transaction Scaleup

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- **Batch scaleup:**

- A single large job; typical of most decision support queries and scientific simulation.
- Use an  $N$ -times larger computer on  $N$ -times larger problem.

- **Transaction scaleup:**

- Numerous small queries submitted by independent users to a shared database; typical transaction processing and timesharing systems.
- $N$ -times as many users submitting requests (hence,  $N$ -times as many requests) to an  $N$ -times larger database, on an  $N$ -times larger computer.
- Well-suited to parallel execution.



# Factors Limiting Speedup and Scaleup

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Speedup and scaleup are often sublinear due to:

- **Startup/sequential costs:** Cost of starting up multiple processes, and sequential computation before/after parallel computation
  - May dominate computation time, if the degree of parallelism is high
  - Suppose  $p$  fraction of computation is sequential
  - **Amdahl's law:** speedup limited to:  $1 / [(1-p) + (p/n)]$
  - **Gustafson's law:** scaleup limited to:  $1 / [n(1-p) + p]$
- **Interference:** Processes accessing shared resources (e.g., system bus, disks, or locks) compete with each other, thus spending time waiting on other processes, rather than performing useful work.
- **Skew:** Increasing the degree of parallelism increases the variance in service times of parallelly executing tasks. Overall execution time determined by **slowest** of parallelly executing tasks.



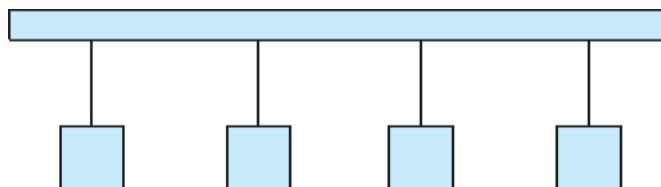
# Interconnection Network Architectures

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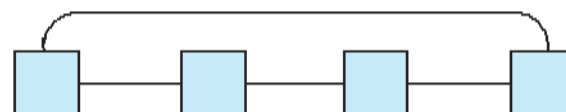
- **Bus.** System components send data on and receive data from a single communication bus;
  - Does not scale well with increasing parallelism.
- **Mesh.** Components are arranged as nodes in a grid, and each component is connected to all adjacent components
  - Communication links grow with growing number of components, and so scales better.
  - But may require  $2\sqrt{n}$  hops to send message to a node (or  $\sqrt{n}$  with wraparound connections at edge of grid).
- **Hypercube.** Components are numbered in binary; components are connected to one another if their binary representations differ in exactly one bit.
  - $n$  components are connected to  $\log(n)$  other components and can reach each other via at most  $\log(n)$  links; reduces communication delays.
- **Tree-like Topology.** Widely used in data centers today



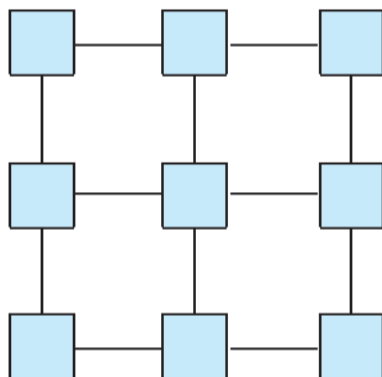
# Interconnection Architectures



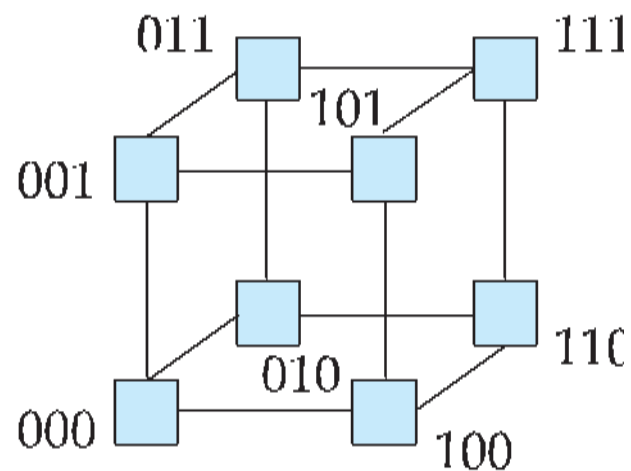
(a) bus



(b) ring



(c) mesh

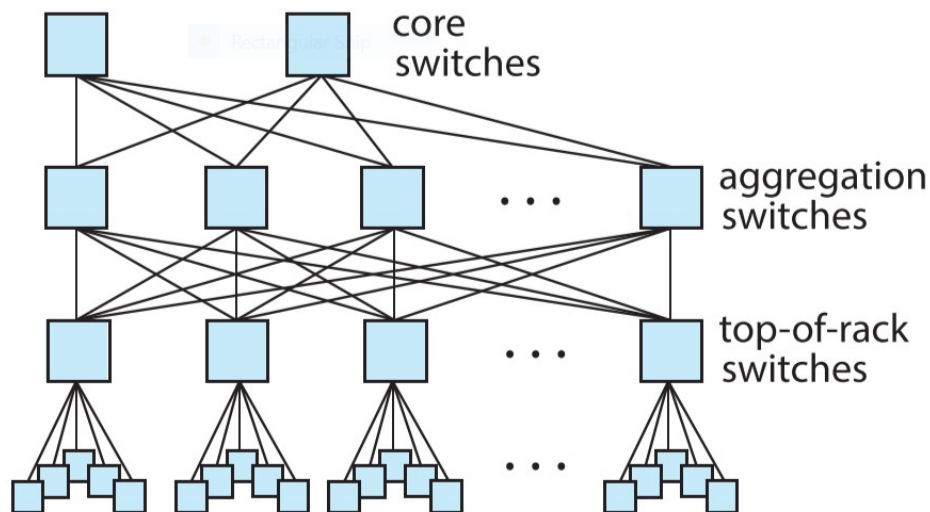


(d) hypercube



# Interconnection Network Architectures

- **Tree-like or Fat-Tree Topology:** widely used in data centers today
  - Top of rack switch for approx 40 machines in rack
  - Each top of rack switch connected to multiple aggregation switches.
  - Aggregation switches connect to multiple core switches.
- **Data center fabric**



(e) tree-like topology





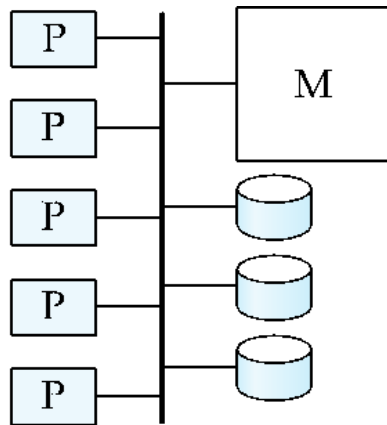
# Network Technologies

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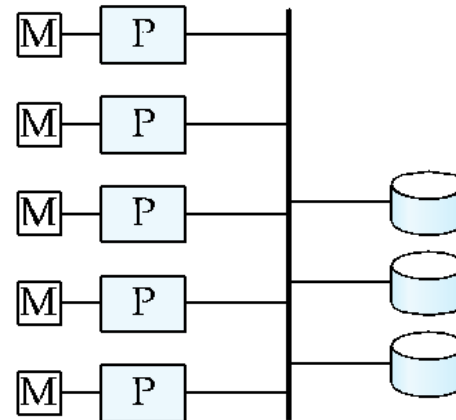
- Ethernet
  - 1 Gbps and 10 Gbps common, 40 Gbps and 100 Gbps are available at higher cost
- Fiber Channel
  - 32-138 Gbps available
- **Infiniband**
  - A very-low-latency networking technology
    - 0.5 to 0.7 microseconds, compared to a few microseconds for optimized ethernet



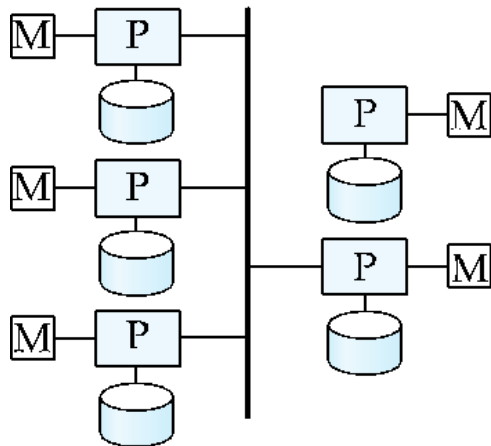
# Parallel Database Architectures



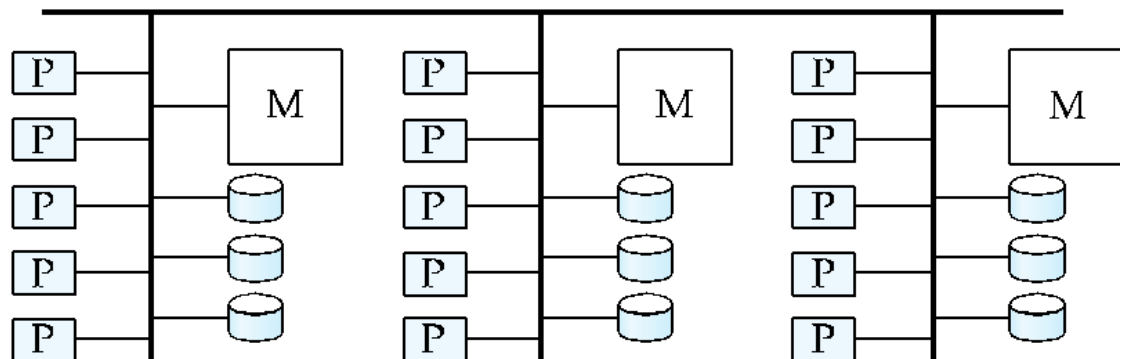
(a) shared memory



(b) shared disk



(c) shared nothing

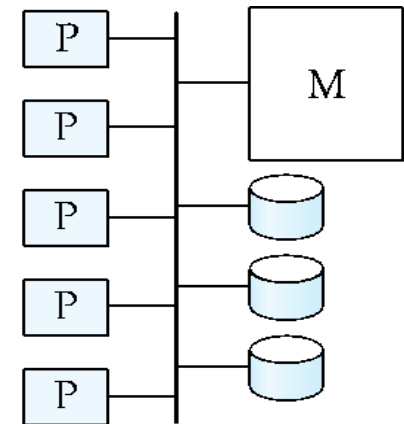


(d) hierarchical



# Shared Memory

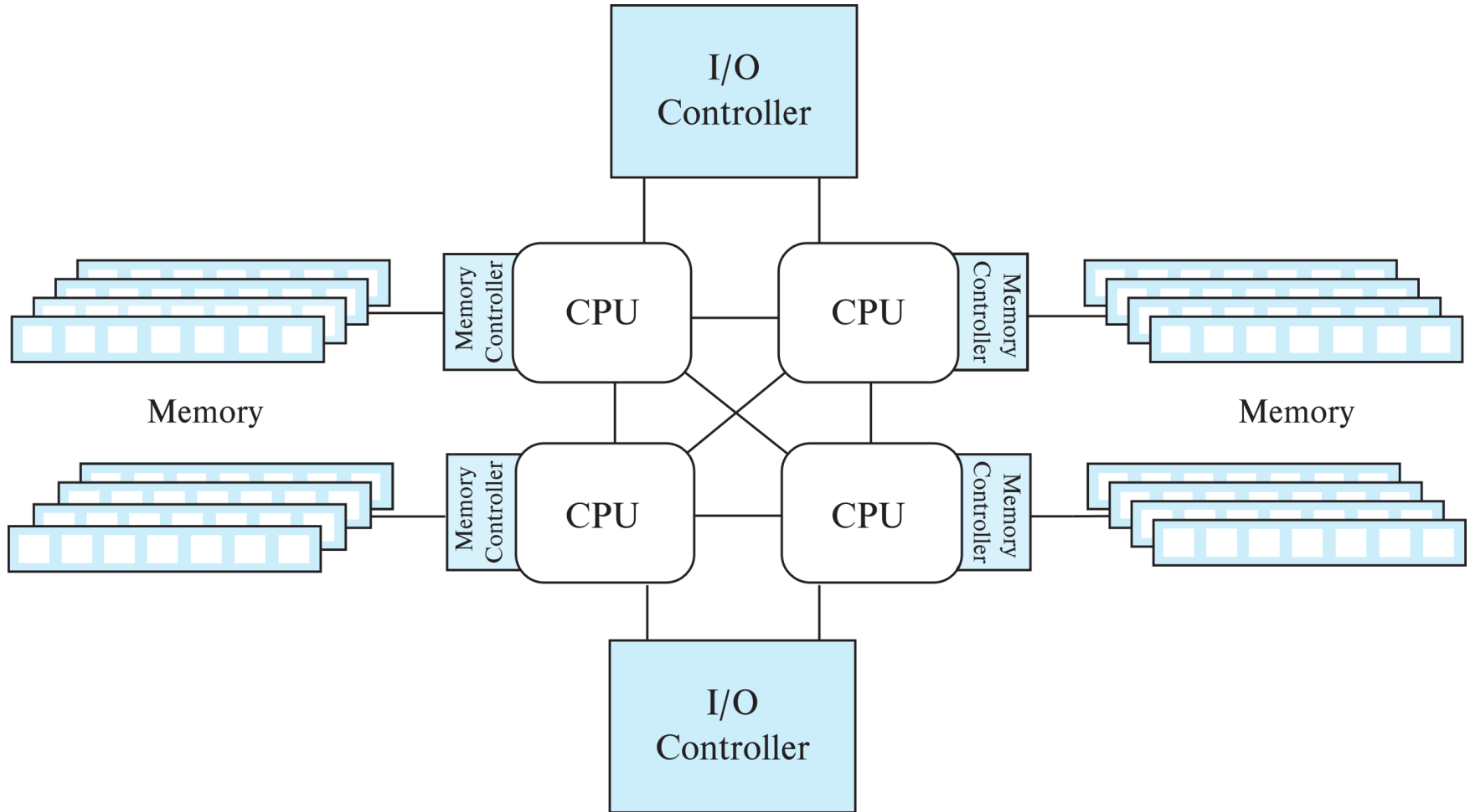
- Processors (or processor cores) and disks have access to a common memory
  - Via a bus in earlier days, through an interconnection network today
- Extremely efficient communication between processors
- Downside: shared-memory architecture is not scalable beyond 64 to 128 processor cores
  - Memory interconnection network becomes a bottleneck



(a) shared memory



# Modern Shared Memory Architecture





# Cache Levels

- Cache line: typically 64 bytes in today's processors
- Cache levels within a single multi-core processor

| Core 0          | Core 1   | Core 2   | Core 3   |
|-----------------|----------|----------|----------|
| L1 Cache        | L1 Cache | L1 Cache | L1 Cache |
| L2 Cache        | L2 Cache | L2 Cache | L2 Cache |
| Shared L3 Cache |          |          |          |

- Shared memory system can have multiple processors, each with its own cache levels



# Cache Coherency

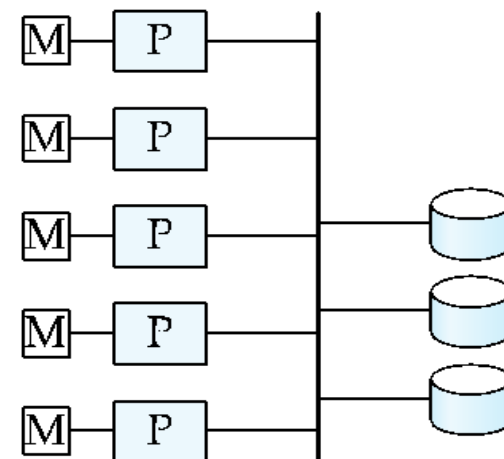
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- Cache coherency:
  - Local cache may have out of date value
  - Strong vs weak consistency models
  - With weak consistency, need special instructions to ensure cache is up to date
- Memory barrier instructions
  - **Store barrier (sfence)**
    - Instruction returns after forcing cached data to be written to memory and invalidations sent to all caches
  - **Load barrier (lfence)**
    - Returns after ensuring all pending cache invalidations are processed
  - mfence instruction does both of above
- Locking code usually takes care of barrier instructions
  - Lfence done after lock acquisition and sfence done before lock release



# Shared Disk

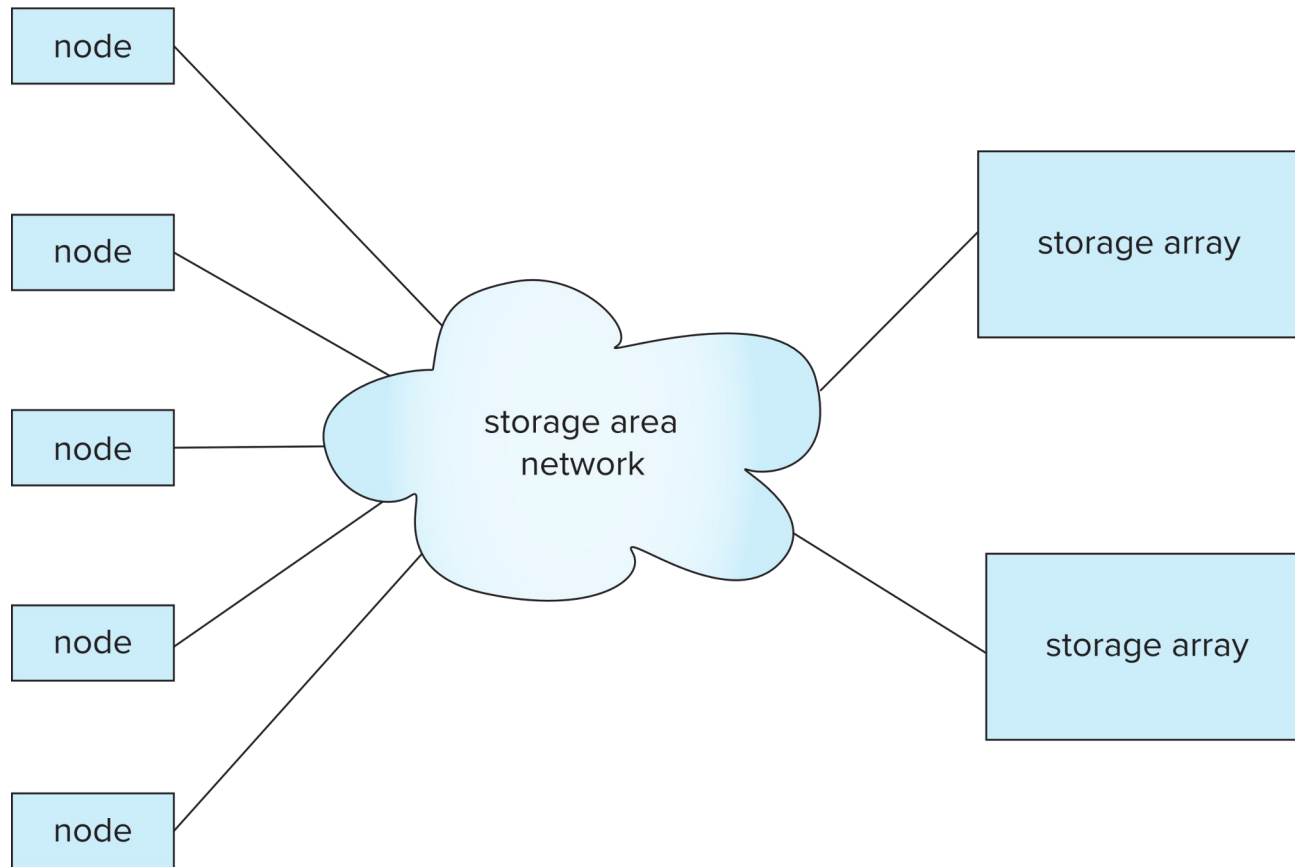
- All processors can directly access all disks via an interconnection network, but the processors have private memories.
  - Architecture provides a degree of **fault-tolerance** — if a processor fails, the other processors can take over its tasks
    - the data of the failed processor is resident on disks that are accessible from all processors.
- Downside: bottleneck now occurs at interconnection to the disk subsystem.



(b) shared disk



# Storage Area Network (SAN)

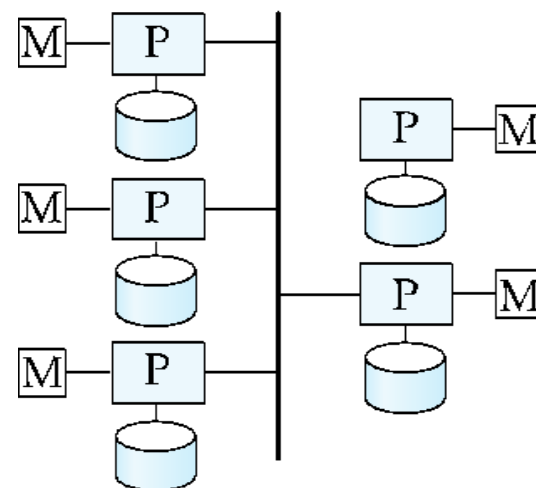






# Shared Nothing

- Node consists of a processor, memory, and one or more disks
- All communication via interconnection network
- Can be scaled up to thousands of processors without interference.
- Main drawback: cost of communication and non-local disk access; sending data involves software interaction at both ends.

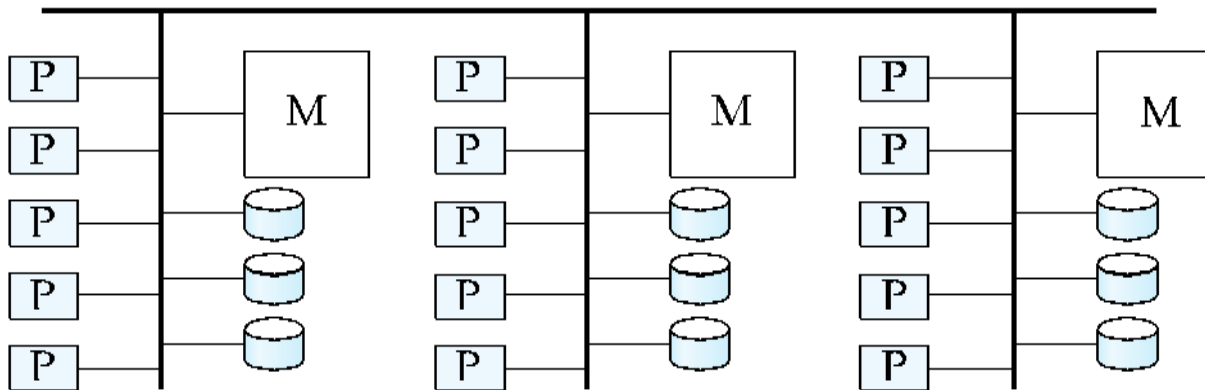


(c) shared nothing



# Hierarchical

- Combines characteristics of shared-memory, shared-disk, and shared-nothing architectures.
  - Top level is a shared-nothing architecture
    - With each node of the system being a shared-memory system
  - Alternatively, top level could be a shared-disk system
    - With each node of the system being a shared-memory system



(d) hierarchical



# Shared-Memory Vs Shared-Nothing

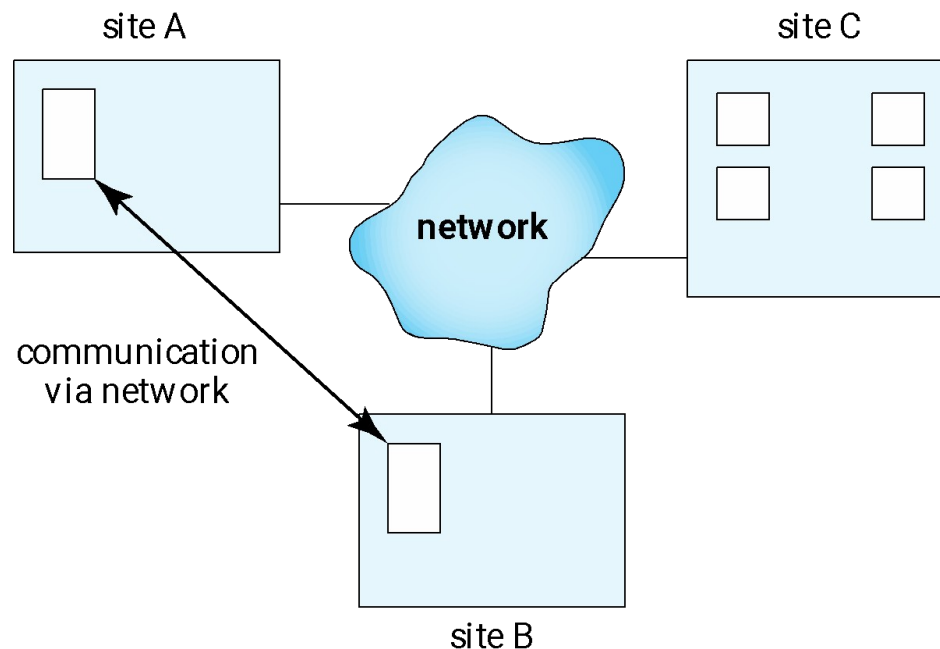
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- Shared-memory internally looks like shared-nothing!
  - Each processor has direct access to its own memory, and indirect (hardware level) access to rest of memory
  - Also called **non-uniform memory architecture (NUMA)**
- Shared-nothing can be made to look like shared memory
  - Reduce the complexity of programming such systems by **distributed virtual-memory** abstraction
  - **Remote Direct Memory Access (RDMA)** provides very low-latency shared memory abstraction on shared-nothing systems
    - Often implemented on top of **infiniband** due to its very-low-latency
  - But careless programming can lead to performance issues



# Distributed Systems

- Data spread over multiple machines (also referred to as **sites** or **nodes**).
- **Local-area networks (LANs)**
- **Wide-area networks (WANs)**
  - Higher latency





# Distributed Databases

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- **Homogeneous distributed databases**
  - Same software/schema on all sites, data may be partitioned among sites
  - Goal: provide a view of a single database, hiding details of distribution
- **Heterogeneous distributed databases**
  - Different software/schema on different sites
  - Goal: integrate existing databases to provide useful functionality
- Differentiate between **local transactions** and **global transactions**
  - A **local transaction** accesses data in the *single* site at which the transaction was initiated.
  - A **global transaction** either accesses data in a site different from the one at which the transaction was initiated or accesses data in several different sites.



# Data Integration and Distributed Databases

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- Data integration between multiple distributed databases
- Benefits:
  - Sharing data – users at one site able to access the data residing at some other sites.
  - Autonomy – each site is able to retain a degree of control over data stored locally.



# Availability

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- **Network partitioning**
- **Availability** of system
  - If all nodes are required for system to function, failure of even one node stops system functioning.
  - Higher system availability through redundancy
    - data can be replicated at remote sites, and system can function even if a site fails.



# Implementation Issues for Distributed Databases

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- Atomicity needed even for transactions that update data at multiple sites
- The **two-phase commit protocol (2PC)** is used to ensure atomicity
  - Basic idea: each site executes transaction until just before commit, and then leaves final decision to a coordinator
  - Each site must follow decision of coordinator, even if there is a failure while waiting for coordinator's decision
- 2PC is not always appropriate: other transaction models based on persistent messaging, and workflows, are also used
- Distributed concurrency control (and deadlock detection) required
- Data items may be replicated to improve data availability
- Details of all above in Chapter 24





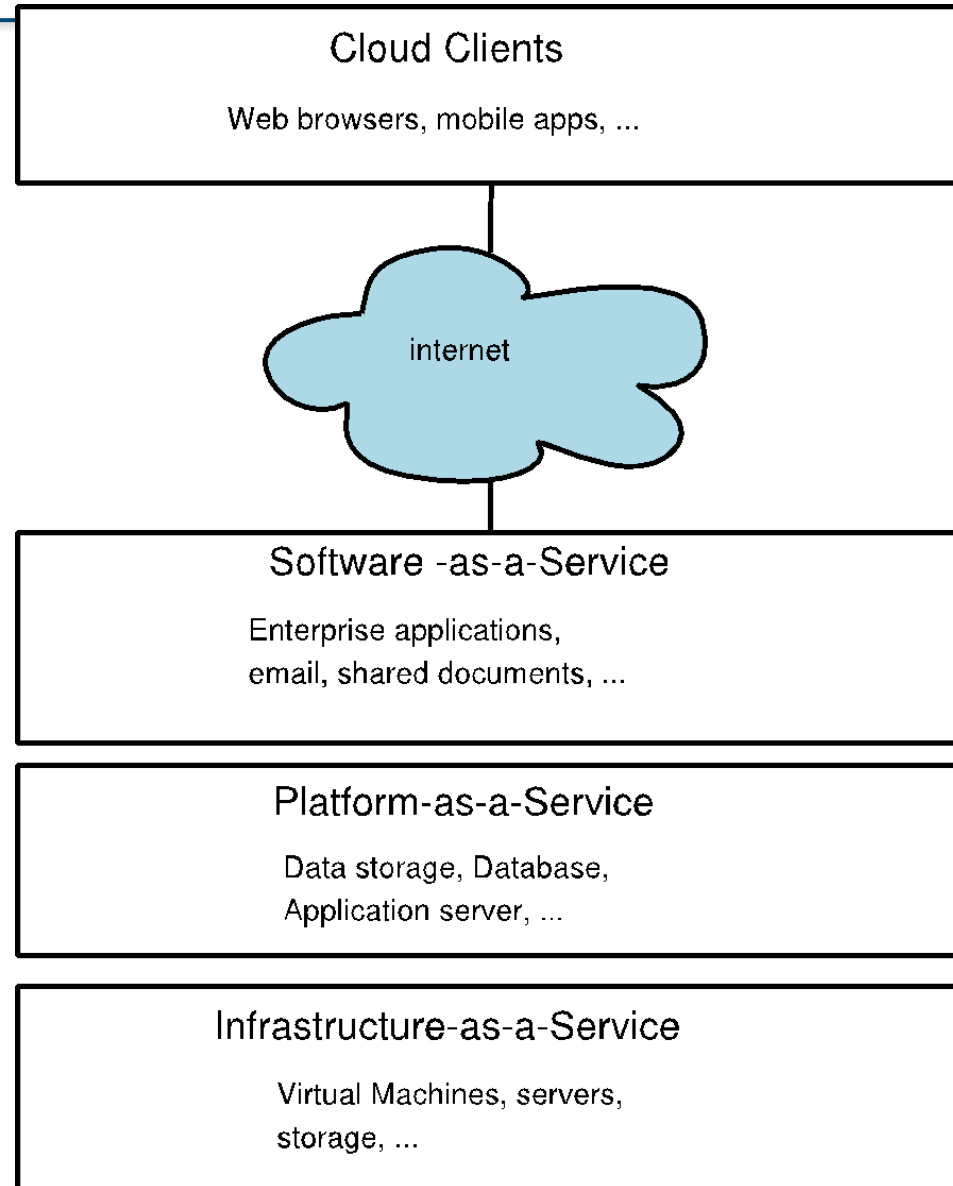
# Cloud Based Services

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- Cloud computing widely adopted today
  - On-demand provisioning and **elasticity**
    - ability to scale up at short notice and to release of unused resources for use by others
- Infrastructure as a service
  - Virtual machines/real machines
- Platform as a service
  - Storage, databases, application server
- Software as a service
  - Enterprise applications, emails, shared documents, etc,
- Potential drawbacks
  - Security
  - Network bandwidth

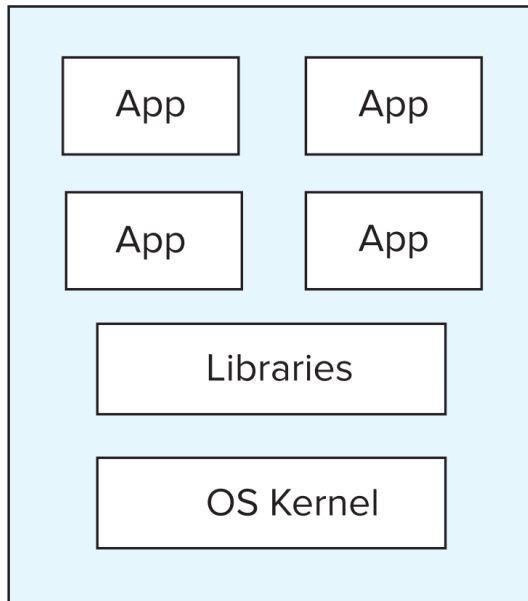


# Cloud Service Models

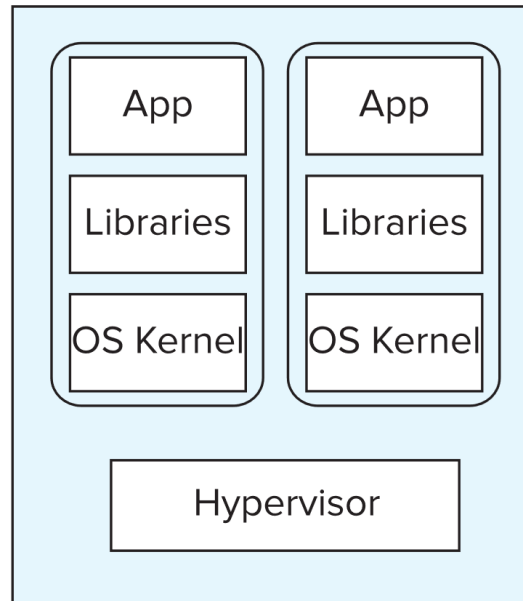




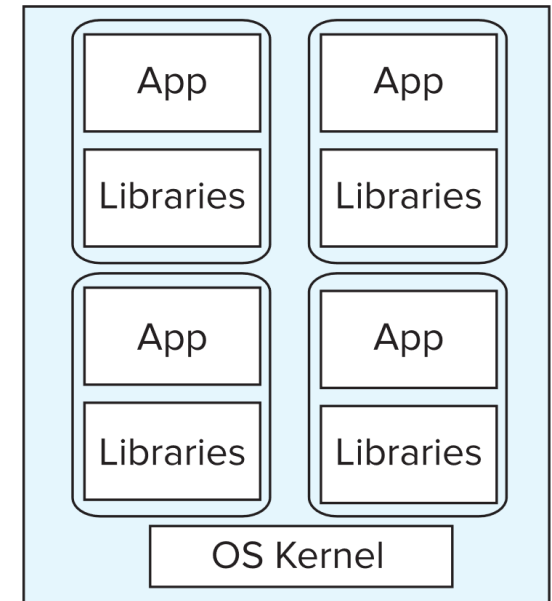
# Application Deployment Alternatives



a) Multiple applications on a single machine



b) Each application running on its own VM, with multiple VMs running in a machine



c) Each application running in its own container, with multiple containers running in a machine

Individual Machines  
Containers

Virtual Machines

(e.g. VMWare, KVM, ..)

(e.g.

Docker)



# Application Deployment Architectures

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- Services
- Microservice Architecture
  - Application uses a variety of services
  - Service can add or remove instances as required
- Kubernetes supports containers, and microservices



# End of Chapter 20

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