

25/4/24

(After Mid)

④ Linear D.S.:

→ Array

→ Stack

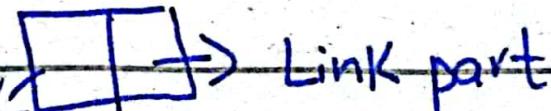
→ Queue

→ List

0	1	2	3	4
1000	1001	1002	1003	1010

→ Linked List:

Reference part



→ class Node

{ int data;

 Node * node;

 next

→ Constructor:

Node (int d)

{
 data=d

 Node* next = nullptr;

}

Node ()

{

 data=0

 next=nullptr;

}

Node (int d, Node* n)

{
 data=d;
 next=n;

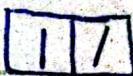
}

→ Node * Head = new Node(0);

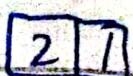
Head.next = First



First.next = second
Node First = new Node(1);



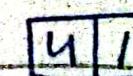
Second.next = third
Node Second = new Node(2);



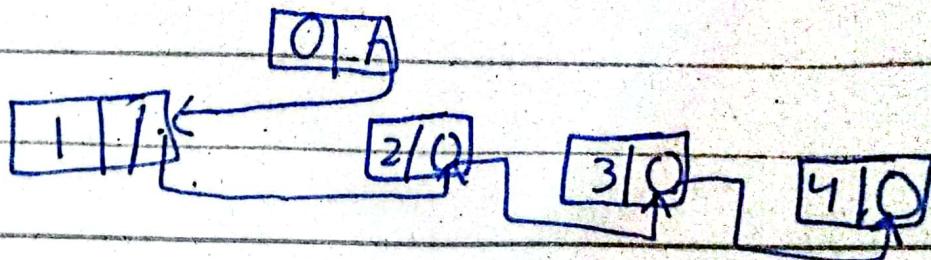
Third.next = fourth
Node Third = new Node(3);



Fourth.next = null;
Node Fourth = new Node(4);

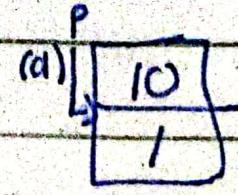
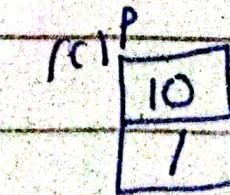
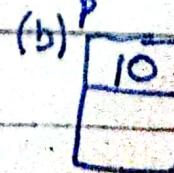


Fourth.next = null;
(Scattered Node)

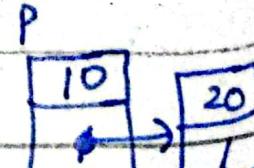
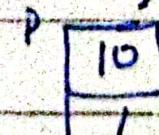
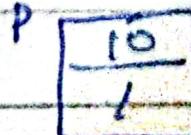


→ Node * p = new Node(10)

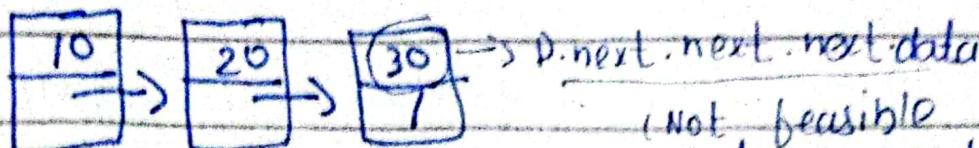
Step 3



→ p.next = new Node(20)



→ $P.\text{next}.\text{next} = \text{new Node}(30)$



(Not feasible
for 1000 nodes).

→ For proper solution, we make class List:

class List {

 Node * head;

 Node * tail;

}

→ List()

{ head=tail=nullptr;

}

→ bool isEmpty()

{ if (Head == 0)

{ return 1;

}

else

{ return 0;

}

→ For First element head and tail points to same.

→ void addToHead (int e)

{

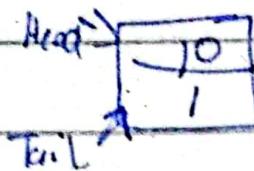
Head = new Node (e, Head);

if (Tail == 0)

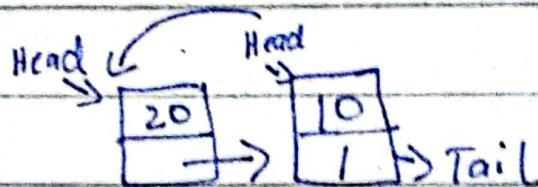
{ Tail = Head;

}

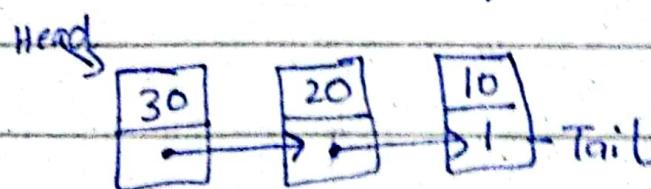
: add To Head (10)



: add To Head (20)



: add To Head (30)



→ void addToTail (int e)

{ if (Tail == 0)

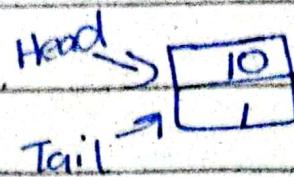
{ Head = Tail = new Node (e)

else // Tail != 0

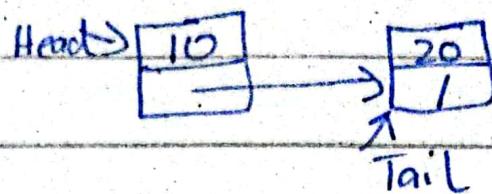
{ Tail·Next = new Node (e)

; Tail = Tail·Next;

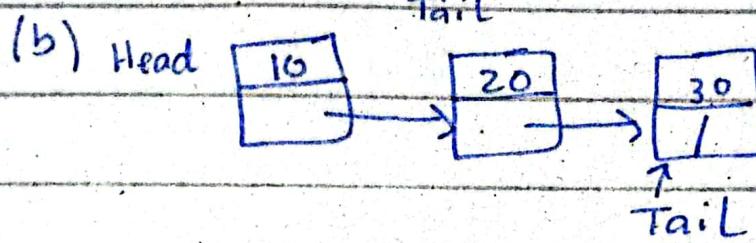
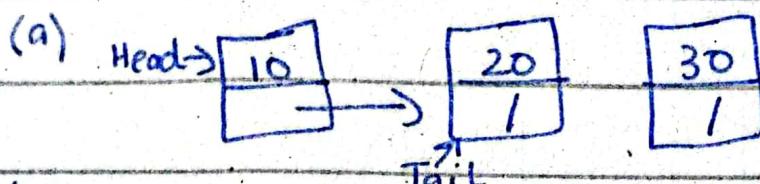
: addToTail (10)



: addToTail (20)



: addToTail (30)



→ int deleteFromHead()

```
{ int e = Head.data;
```

```
Node *temp = Head;
```

```
if (Head == Tail)
```

```
{ delete Head;
```

```
Head = Tail = 0;
```

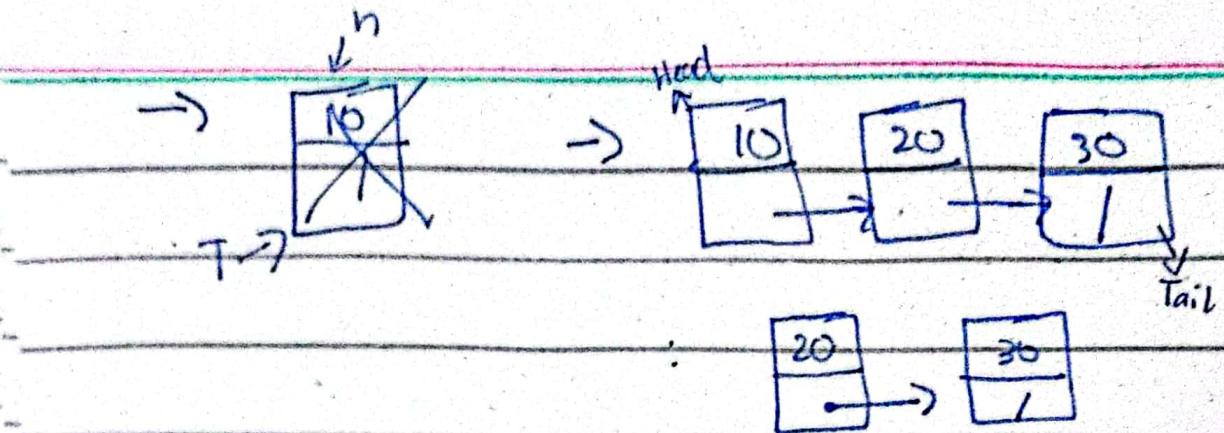
```
Head = Head.next;
```

```
Delete temp
```

```
} return e;
```

```
}
```

```
}
```

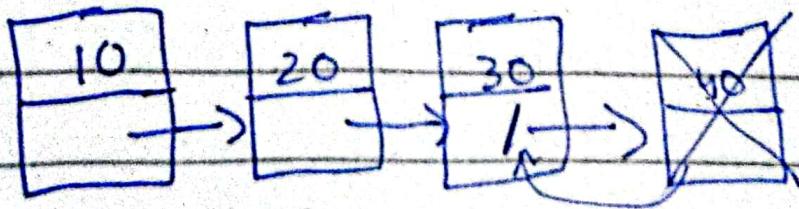


→ int deleteFromTail()

```
{
    int el = Tail.data;
    If (Head == Tail)
    {
        Delete Head;
        Head = Tail = 0;
    }
}
```

```

Node * temp;
for (temp = head; temp.next != tail;
     temp = temp.next);
delete Tail;
Tail = temp;
Tail.next = 0;
return e;
```



e=40;

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Single Linked List

→ delete Node (int e)

→ Node *pred; *temp;

for(Pred=Head; temp=Head.Next;)

{

 while (temp != '0' || !(temp.data == e))

{

 Pred = Pred.Next;

 temp = temp.next,

 if (temp == 0)

 Pred.next = temp.next

 if (temp == tail)

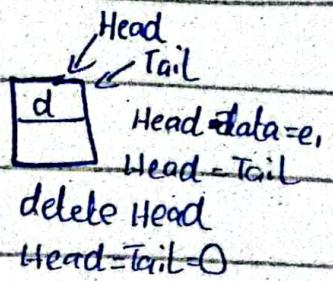
 Tail = Pred

 delete temp;

}

}

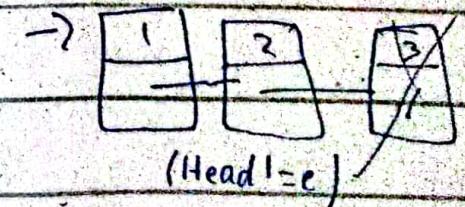
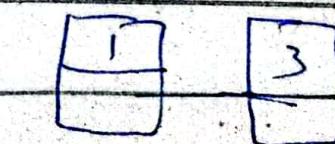
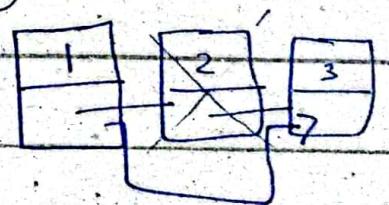
①



②



③



→ bool: isINList(int e)

{ Node *temp = Head;

 while(temp.Next != NULL)

```
{ if( temp.data == e )
```

```
{ return true;
```

```
}
```

```
temp = temp.next;
```

```
}
```

```
return false;
```

```
}
```

→ for(temp = head ; temp != 0 && !(temp.data
= e))

```
{ temp = temp.next;
```

```
if( temp == 0 )
```

```
{ return 0;
```

: (other way)

```
} else
```

```
} { return 1;
```

→ Destructor:

① ~List()

```
{ Node * temp = Head.next;
```

```
while( temp != NULL )
```

```
{ delete Head;
```

```
Head = temp;
```

```
} temp = temp.next;
```

```
    delete Tail;  
}
```

④ ~LinkedList()

```
{  
    while (!head)
```

```
{  
    Node *temp = head;
```

```
    head = head->next
```

```
}  
    delete temp;
```

```
};  
    head = tail = 0;
```

⑤ for (temp = head ; head != 0 ; head = head->next)

```
{  
    delete temp;  
}
```

⑥ ~List()

```
for (Node *p = head ; !Head())
```

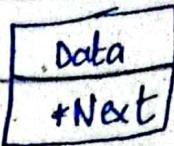
```
{  
    p = p->next;
```

```
    delete Head
```

```
}  
    Head = p;
```

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* SLLIST
(Single linked)



* DLLIST
(Double linked)



→ DLLIST Node

```
{ int data;  
    DLLIST Node * Next;  
    DLLIST Node * Prev;  
}
```

: DLLIST Node()

```
{  
    *Next = 0;  
    *Prev = 0;  
}
```

: DLLIST Node (int d, DLLIST Node * n,
 DLLIST Node * p)

```
{  
    data = d;  
    Next = n;  
    Prev = p  
}
```

(*)

DLLIST

{

DLLISTNode * Head;

DLLISTNode * Tail;

DLLIST()

{

Head = Tail = 0;

}

}

: add To DLLIST Tail (int e₁)

{ if (Head == 0)

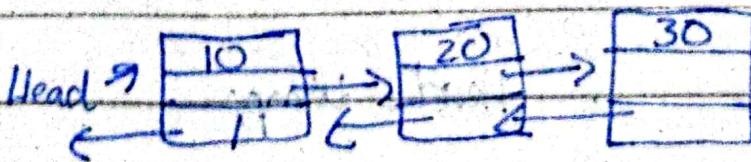
{ Head = tail = new DLLIST^{de}(e₁, 0, 0);

}

else

{ Tail = new DLLIST Node(e₁, 0, tail)

Tail. Prev. Next = Tail;



: delete from DLLIST Tail()

{

e₁ = Tail. data();

if (Head == Tail)

{ delete Head;

Tail = Head = 0;

else

```
{ Tail = Tail · Prev;  
    delete Tail · next  
    Tail · Next = 0;  
}
```

: add to DLLIST Head (int e_i)

{

if (Head == 0)

```
{ Head · data = ei;
```

```
Head · prev = 0;
```

```
Head · Next = 0;
```

} Head = Tail = new DLLIST (e_i, 0, 0)

else

```
{ DLLIST Node *temp = new
```

DLLISTNode (e_i)

temp · next = Head;

temp · prev = 0;

Head · prev = temp;

Head = temp;

:

{

Head · prev = new DLLIST

Node (e_i, head);

} Head = Head · prev;

: { 'if' (Head == 0)

{ Head = new Node(n, 0);

}

else

{ Head = new Node(n, Head, 0);

Head → next → prev = Head;

}

: delete from DLLIST Head()

④ { 'if' (Head == 0)

{ return;

}

else

{ Head = Head · next;

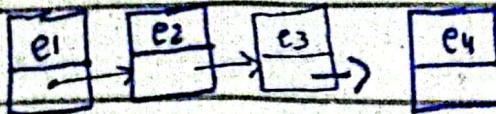
delete Head · prev;

Head · prev = 0;

}

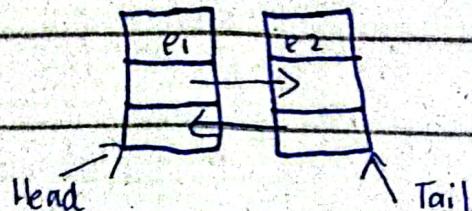
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④ Single Linked List:

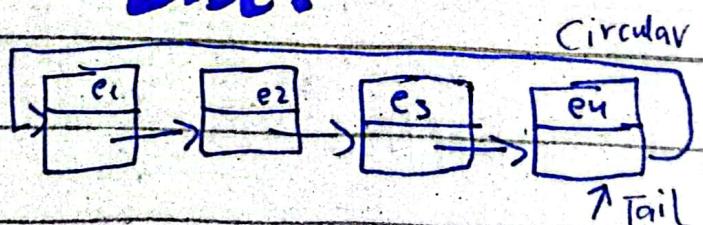


(Deleting tail problems)

④ Double Linked List:



⑤ Circular Single Linked List:



→ addToTail (int e1)

```
{ if (Tail == Tail.next) { e1 }
```

```
    { Tail.next = new Node(e1, Tail); }
```



: addToTail (int e1)

```
{ if (Tail == 0) { }
```

```
    [ Tail = new Node(e1, 0); ]
```

```
    } Tail.next = Tail;
```

else

{ Tail → next = new Node (e₁, Tail.next);

Tail = Tail.next;

}

}

→ add to Head (int e₁)

{

if (Tail == 0)

{ Tail = new Node (e₁, 0);

Tail.next = Tail;

}

else

{ Tail.next = new Node (e₁, Tail.next);

}

→ delete from Head ()

{

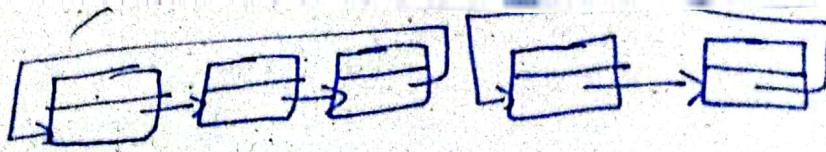
int e₁ = tail.data;

if (tail == tail.next)

{ delete tail;

} Tail = 0;

exit(0);



else

```
{ int e = tail.next.data;
    delete tail.next; }
```

✓: else

```
{ Node *temp = Tail.next;
    Tail.next = Tail.next.next;
    delete temp; }
```

→ delete from Tail()

```
{ if (tail.next == tail)
    { delete tail;
        tail = 0; }
```

else

```
{ Node *temp = Tail;
    while (temp.next != Tail)
```

```
{ temp = temp.next; }
```

$\text{temp.next} = \text{Tail.next}$
delete Tail;

Tail = temp;

```
}
```

else

: for (temp=tail.next; temp.next!=
tail;

temp=temp->next)

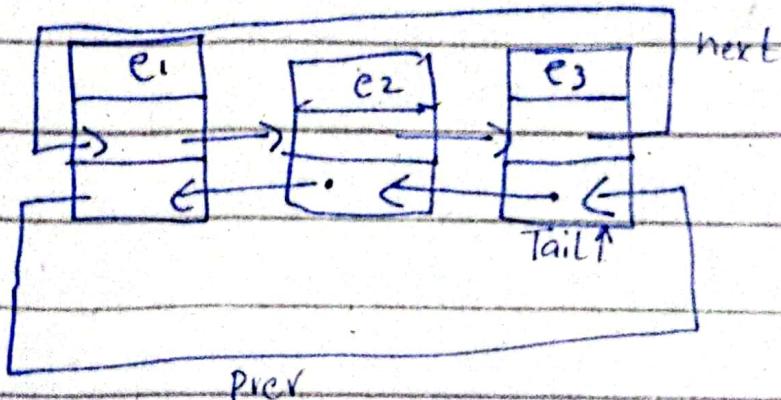
temp.next=tail.next;

delete tail;

} tail=temp;

}

* Circular Double Linked List:

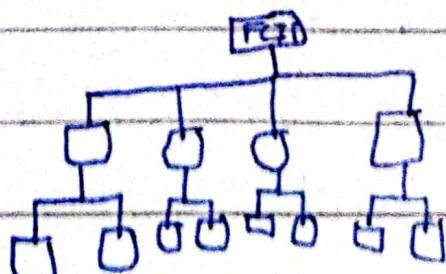


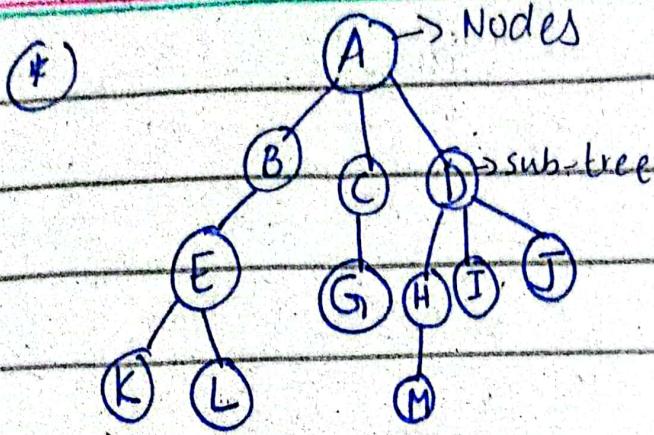
* ④ Assignment ^{circular} Double Linked List
(4 Operations) (Hand Written).

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* TREE :

→ Non-Linear Data Structure





Root
: 1 Root Node
(A)

Recursive
Structure
(Tree)

→ Number of sub-trees of a
^{up to}
internal node is called its degree . From Node
A, 3 degree

→ Nodes that have degree zero
are called as leaf nodes or
terminal nodes . (K, L, G, I, J)

Non-terminal nodes (A, B, C, D, ...)

→ The roots of a sub-tree
of a node x are called
children of x and x is
parent of it .

→ Children of the same parents
are called siblings . (B, C, D, ...)

→ The terminology can be
extended so we can ask
for grandparent n (e.g.: GP
of M is D) .

→ The degree of tree is the

maximum of the degree of nodes in the tree. (maximum 3).

→ The Ancestors of the node along the path from the root to that node ($L \rightarrow (A, B, E)$)

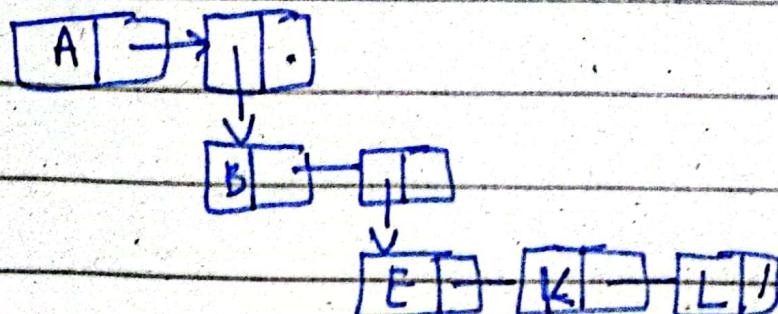
→ The level of the node is defined by mapping netting the root letting Be at Level 1. If a node is at level 1, then its children are on n+1.

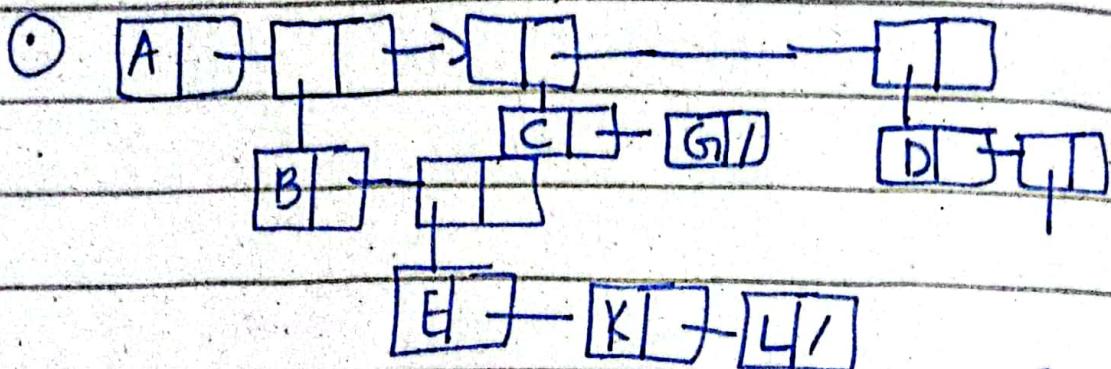
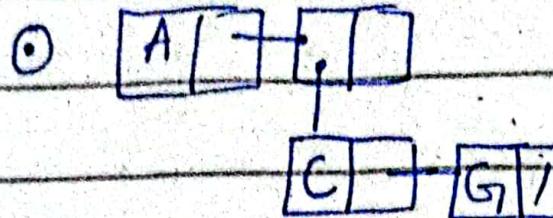
→ The height or depth of a tree is defined to be the maximum level of any node in the tree. (height: 4).

④ List representation:

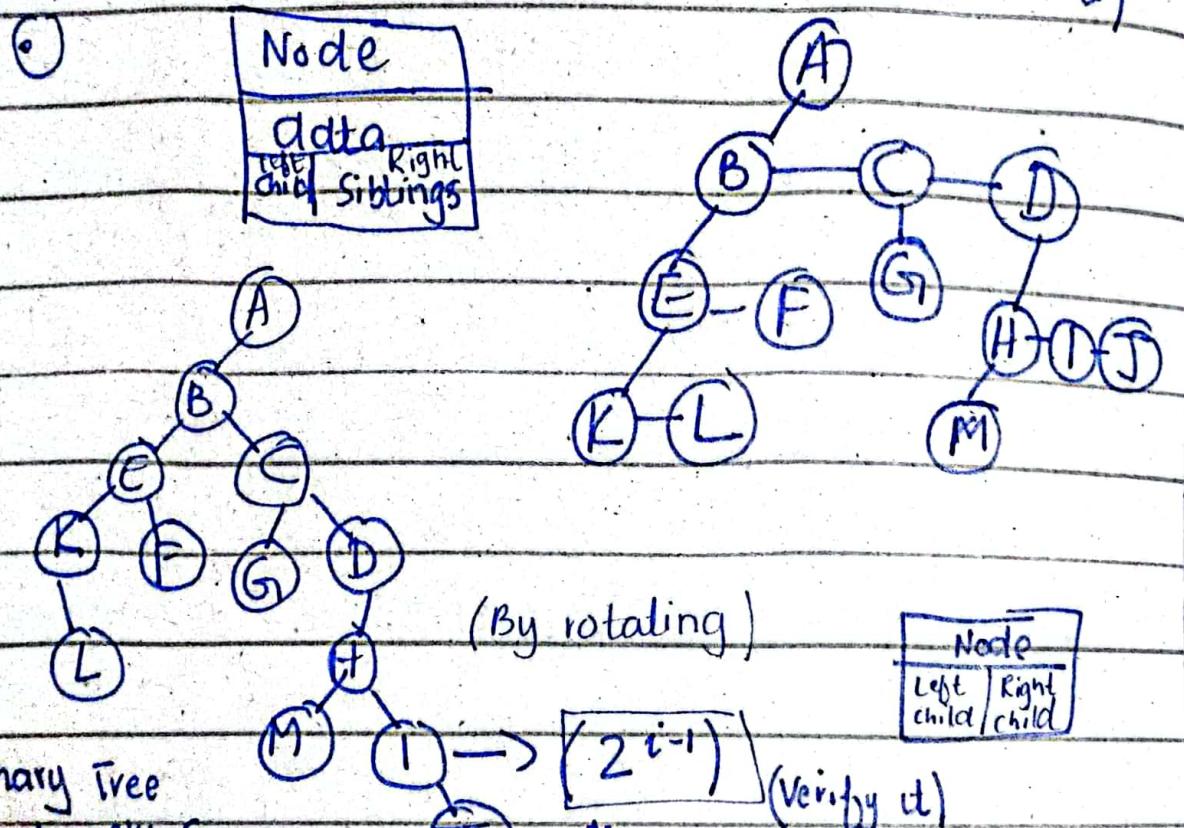
: $(A(B(E(K,L)), C(G), D(H(M), I, J)))$

Data | child | child | ...





(Practice it)



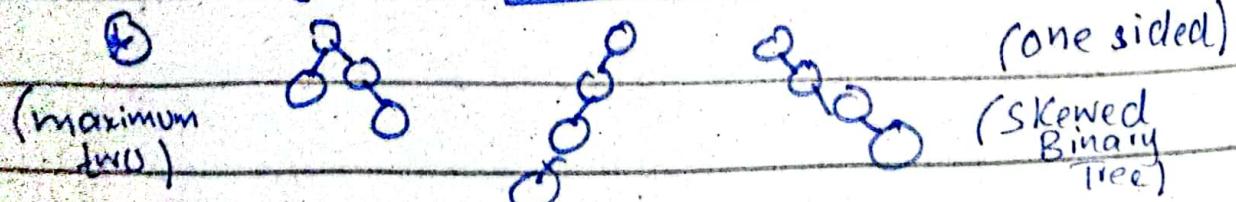
(By rotating)

Node		
Left child	Right child	

Binary Tree
(start only 8 maximum two child).

Number of nodes at particular Level

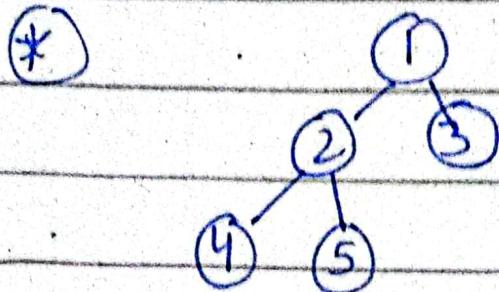
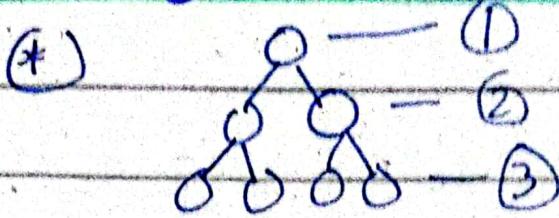
$$\text{Height} = [2^k - 1] : k = \text{maximum}$$



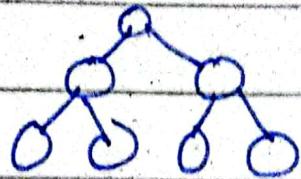
(maximum two)

(one sided)
(Skewed Binary Tree)

: Binary Tree

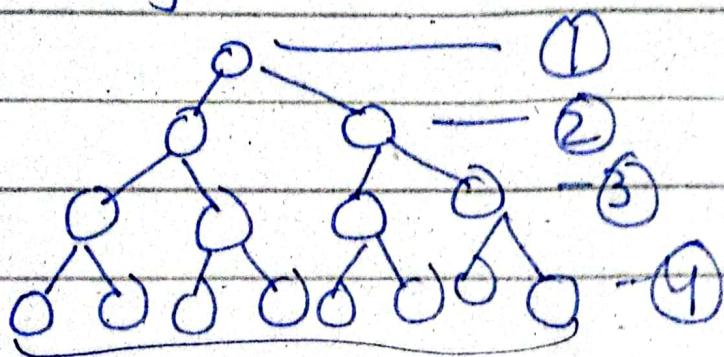


: filled from
left to right
complete Binary
Tree



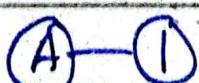
: Full Binary
Tree

(*) Height = 4



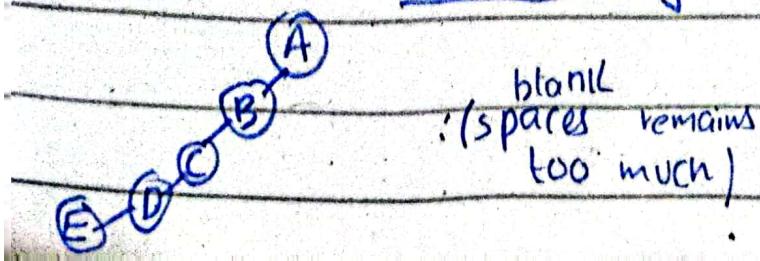
$$2^{n-1} = 8$$

(*)

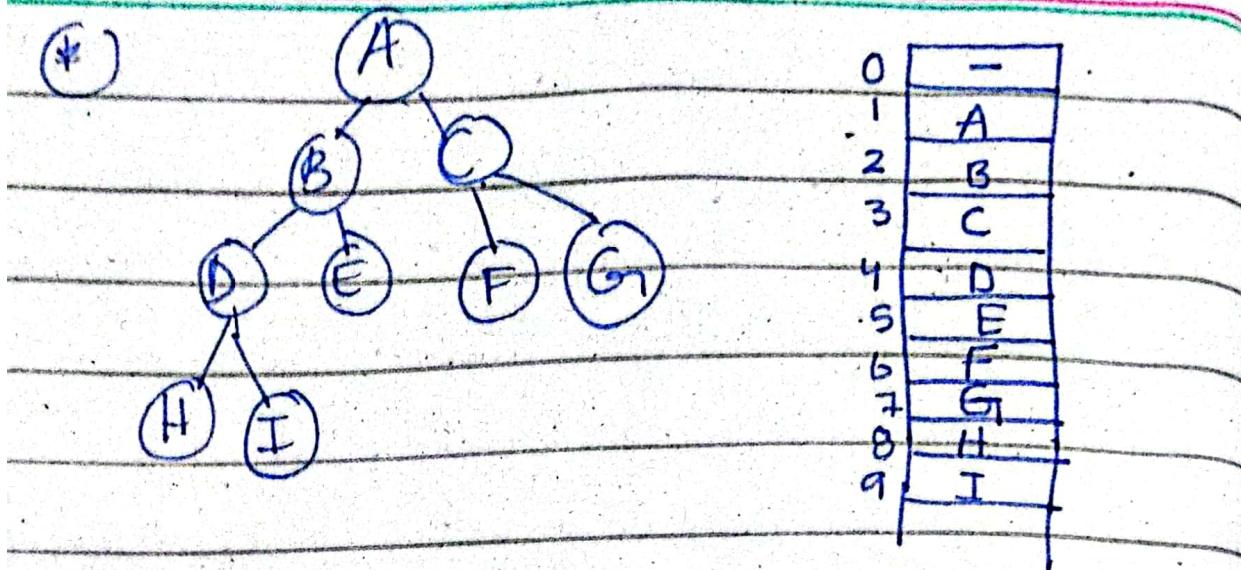


$2i$: left	$\leq n$	condition
$2i+1$: right	$\leq n$	
Parent : $i/2$ condition			

(*) Skewed Binary Tree
By Array:



0	-
1	A
2	B
3	-
4	C
	-



(*) Tree ADT :

→ TreeNode()

{ int data;

TreeNode * leftChild;

TreeNode * rightChild;

}

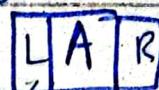
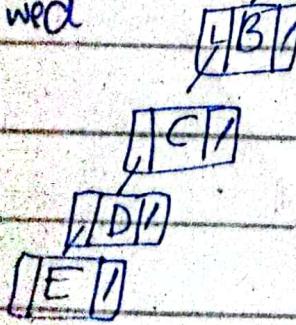
→ Tree

{ TreeNode * root;

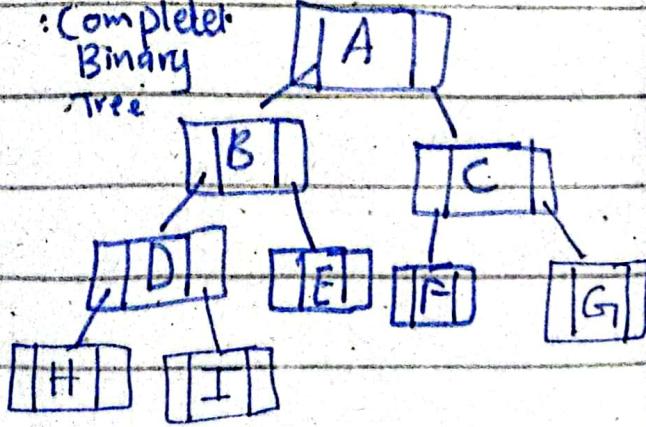
}

(*)

Skewed



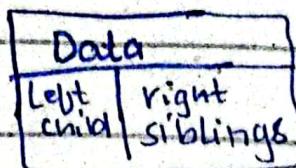
: Complete
Binary
Tree



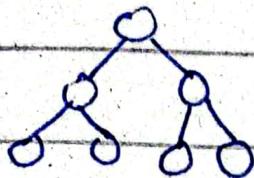
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① Tree and Graph have bit difference.

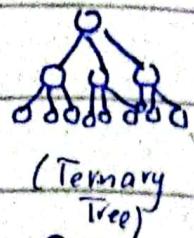
② Tree:



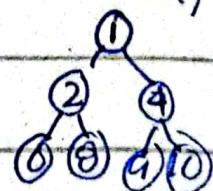
③ Binary Tree:



Data	
Left child	Right child



(BST) ④ Binary Search Tree:

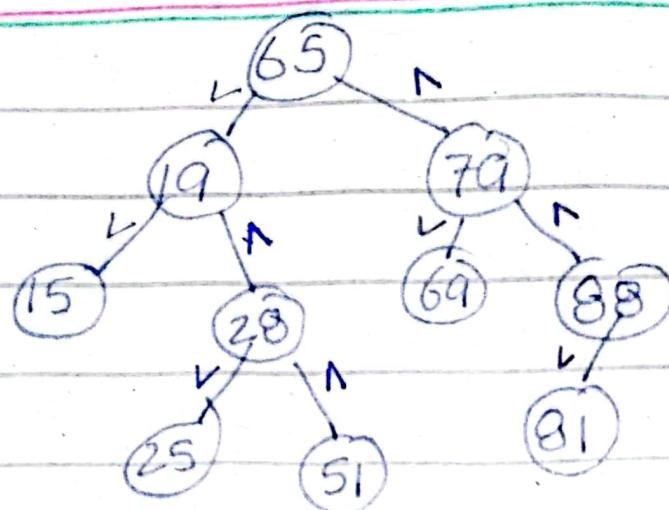


→ Binary Tree is said to be Binary Search Tree when it satisfy the following properties:

(i) The value of each Node 'N' is greater than every value in the ^{left} sub-tree of N and is less than every value in right sub-tree of N.

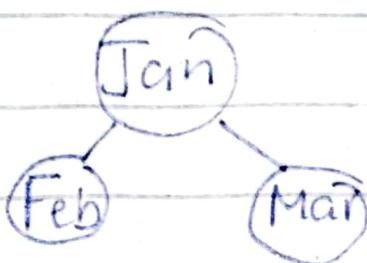


E.g: There is a binary search tree which satisfy it:



• BST
should
satisfy
this
property

① For months:



: Compare
alphabetical
order
(ASCII
value)

② Operations:

- Searching
- Insertion
- Deletion
- Traversing (Search or move through tree)

③ Tree Node

```

{   int data;
    TreeNode * left;
    " " * right;
}
  
```

Tree

```

{
    TreeNode * Root;
}
  
```

→ Search (ITEM)

{
 PTR = Root;
 if (ITEM < PTR.data)
 { left subtree;
 if (ITEM < PTR.data)
 { right subtree;
 if (ITEM == PTR.data)
 { Return true;
 }
 }
 }
 }

: { PTR = Root, Flag = False }
while (PTR != Null & Flag = False)
{

 if (ITEM < PTR.data)

 : Code { PTR = PTR.left;

 if { ITEM > PTR.data)

 { PTR = PTR.right; }

 if { ITEM == PTR.data)

 { Flag = true; }

} }

if (flag == true)

{
 } return true;
}

→ Insertion (ITEM)

{ PTR = Root, flag = false; : Search
 PTR1 = Root; bring
 (For Parent where
 data) new
 node to bp

while((PTR1 == NULL) && (flag == false)) inserted

{ if (ITEM < PTR.data)

{ PTR1 = PTR;
 PTR = PTR.left;

} else if (ITEM > PTR.data)

{ PTR1 = PTR;
 PTR = PTR.right;

else if (ITEM == PTR.data)

{ Flag = True;
 return true;

} if (flag != True)

{ N = new NodeTree(ITEM);
 { return;

if (PTR.data > ITEM)

{ PTR.Left = N;

}

else

{ PTR.Right = N;

}

}

→ Deletion(ITEM)

(null pointer) (i) N is Leaf Node (27)

(Parent points to child) (ii) N has 1 child (45)

(iii) N has 2 child (20)

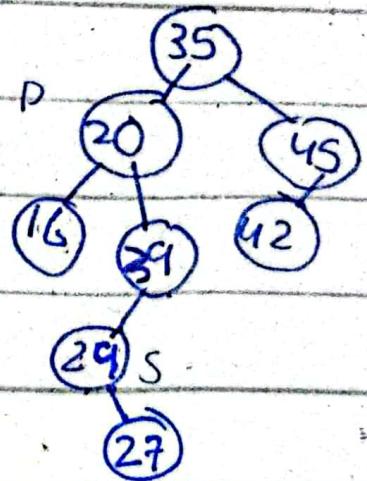
(Parent node will be assigned successor)
then check for successor
node for leaf or 1 child
and apply again
Case-I and Case-II)

N

Parent(N) →

Succ(N) →

Inorder



16 - 20 - 24 - 27
Pd P S

In-order traversal
can be done using
inorder.

:successor:
sub-right → left
most data

21/5/24

Searching }
Insertion } → BST
Deletion }

Traversing → Recursive Functions

* Traversing:

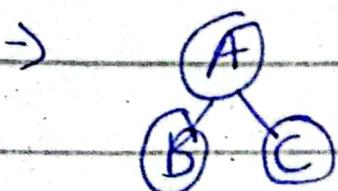
L → Move Left : LVR

V → Visit LRV

R → Move Right VLR

VRL

RLV



: Left node is visited first

Inorder : BAC

Inorder ↗ LVR

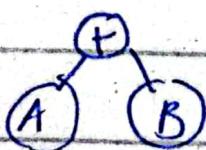
Preorder : ABC

Postorder ↗ LRV

Postorder : BCA

Pre-order ↗ VLR

(Three methods of traversing)



Inorder : A+B

Preorder : +AB

Postorder : AB+

Points of expression Tree:

(i) Convert to postfix expression

(ii) Create stack of TreeNode type

```
TreeNode  
{ data;  
left;  
right; }
```

(iii) Read the expression from left to right until end of expression reached.

(iv) If the character is operand, create new node of that character and push to the stack.

```
: n1 = new TreeNode(ch);
```

```
st.push(n1)
```

: Else

ch == operator

```
t = new TreeNode(ch);
```

```
t1 = s.pop();
```

: Takes two nodes and put it into tree

```
t2 = s.pop();
```

t->Right = t₁, t->left = t₂:

```
st.push(t);
```

: Last element:

```
st.pop();
```

: At last elements parent node present

* A + B - E * F * G

AB+ - E * FG* *

AB+ E FG* * -

: AB+ EF * G * -
Correct

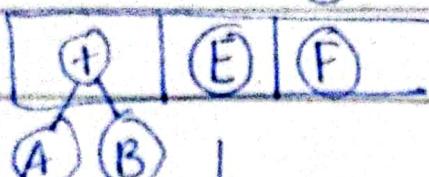
$$AB + EF * G_1 * -$$

Tree Node

$$: Ch = A \beta_1 \\ \beta_2 *$$

(A) (B)

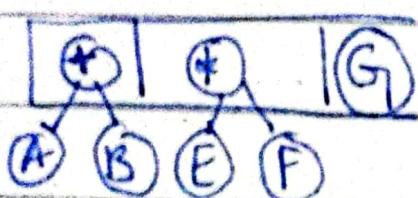
$\downarrow +$



$$t_1 = B$$

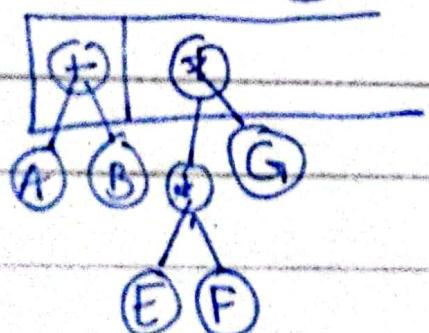
$$t_2 = A$$

$\downarrow *$

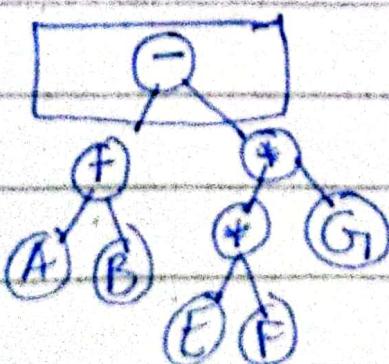


$\downarrow +$

$\downarrow +$



$\downarrow -$



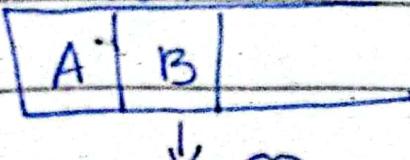
$$* A | B * C * D + E$$

Postfix: AB \ * CD * E *
AB \ CD

: AB | C * D * E *
(correct)

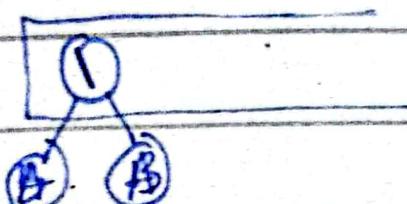
$A \oplus B | C + D + E +$

Tree Node



↓

(1)



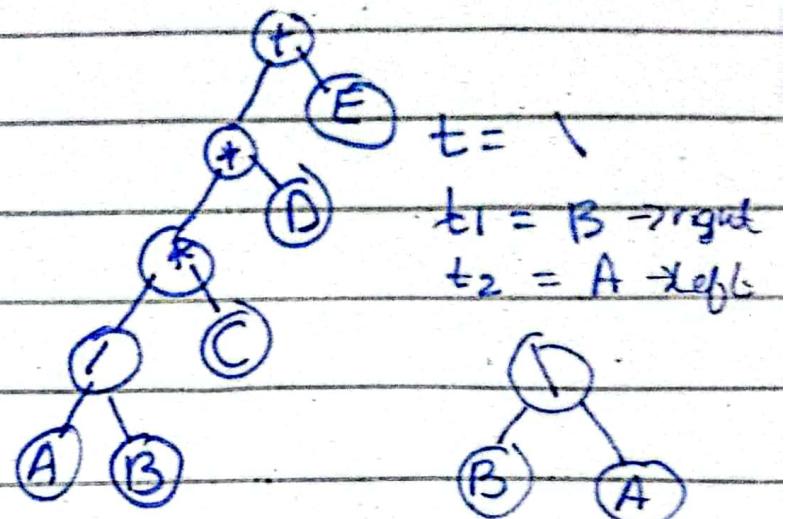
(A) (B)

Ch = A B |

t = 1

t1 = B → right

t2 = A → left



* Inorder(Tree Node * currNode)

{ Ibf(currNode)

}

Inorder(currNode → left);
(print) visit(currNode),

Inorder(currNode → Right);

) }

* Preorder(Tree Node * currNode)

{ Ibf(currNode)

{

visit(currNode);

Inorder(currNode → left);

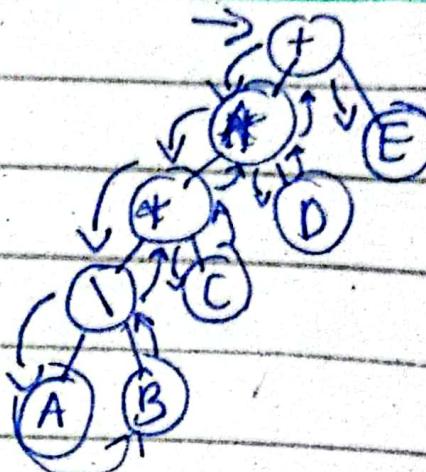
Inorder(currNode → right);

) }

: VLR

④ Prefix:

$+ * \backslash A B C D E$



(LRV)

* Postfix (currNode)

{ If (currNode)

Inorder (currNode->left);

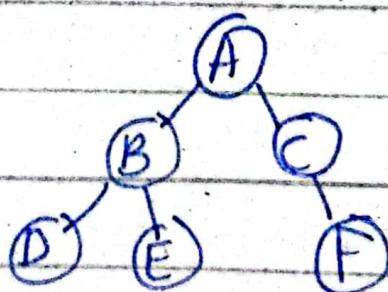
Inorder (currNode->right);

visit (currNode);

}

Postfix: A B \ C * D * E +

Without expression:



↑ short cut
(Preorder-right hanger)

LVR

○ Inorder : B E D B E F C A

(VLR)

Inorder-Center hanger
Postorder-left hanger

○ Preorder : B D E A A B D E C F

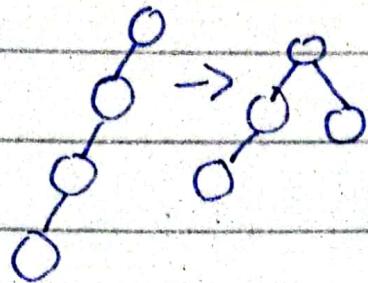
(LRV)

○ Postorder: D B E F C A

↑ # * Next Class Quiz
on Traversal.

23/5/24

- * In-order of BST is sorted data.
(Faster algorithm for sorting).
- * Skewed form (Problem)
(Balancing of Tree)



④ Heap:

Tree data structure.

(Removing data in constant time).

→ The element to be removed
should be root element for heap.

○ → Root
(Highest priority element)

→ Root data should be greater
than all other data.

Heap ○ → Max Heap

→ Root data smaller than other.

Heap ○ → Min Heap

④ All the data to be made a heap data.

* If left data is smaller than swap with greater (Max heap) and vice versa.

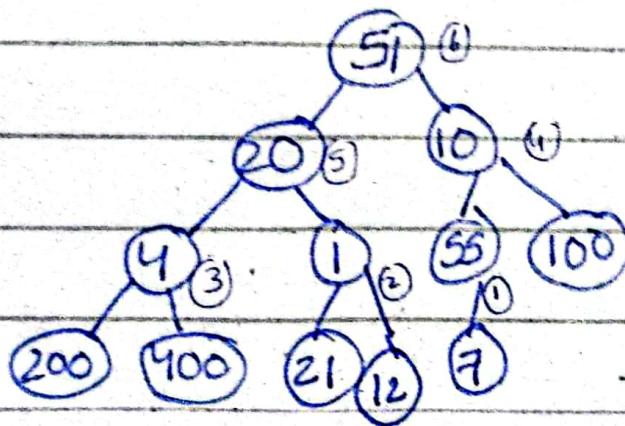
○ 51, 20, 10, 4, 1, 55, 100, 200, 400, 24, 17

: Heapify

Process

Greates element
on top)

(then it
will deleted)

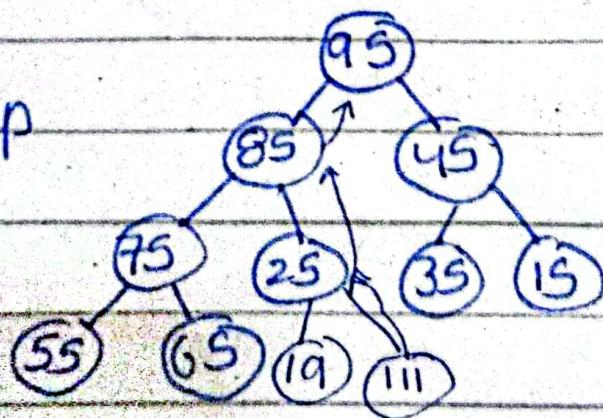


: Internal
(which has
no leaf)

○ 95, 85, 45, 75, 25, 35, 15, 55, 65

: MaxHeap

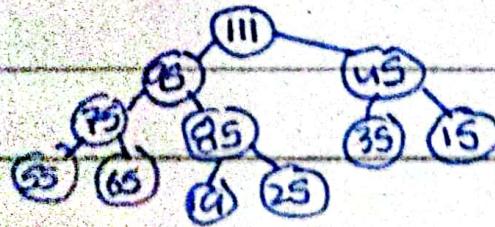
: Already heap
satisfying



: Insert(19)

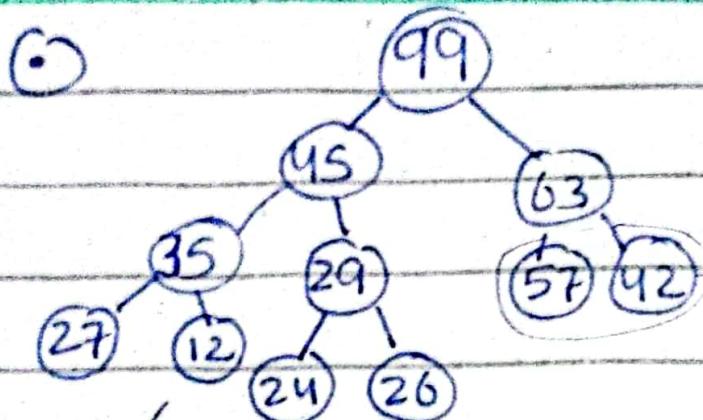
: Insert(111)

: Inserted(111)

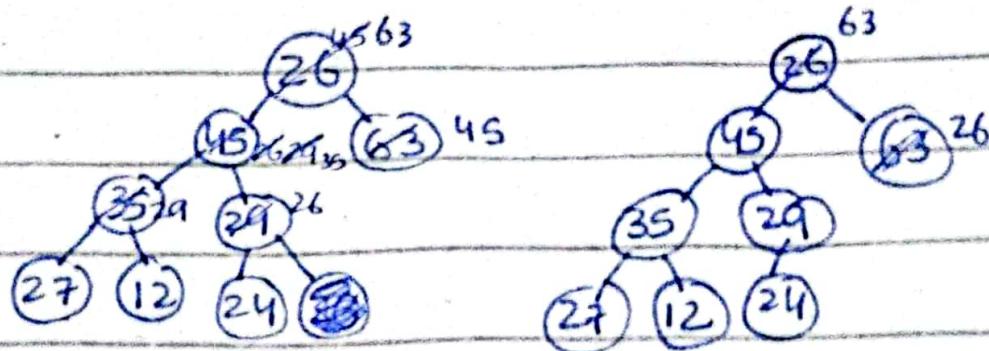


: Delete()
in replace root
with last node
and delete last node
and then again
follow heapify process

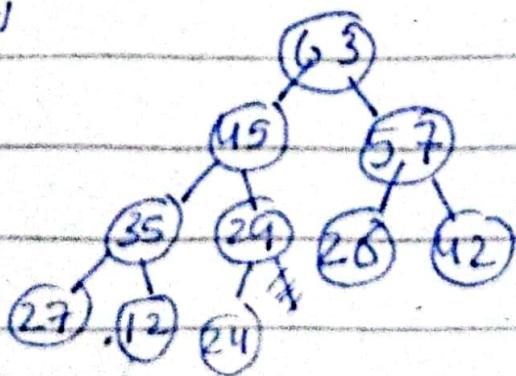
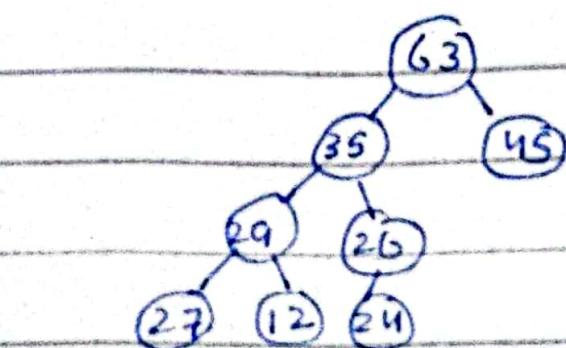
: Insert: Leaf \rightarrow Root
Delete: Root \rightarrow Leaf



: Delete():



Dekletion

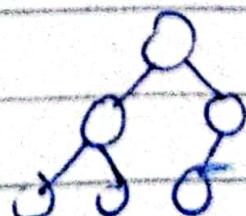


30/5/24

① Height Balance Tree

$$B.F = R_H - R_L$$

{ -1, 0, 1 }



: Avial

• Tree: Generalized tree

< 0 : Left heavy

> 0 : Right heavy

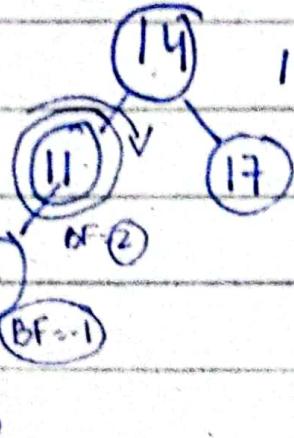
• Binary

Heap

: Balance Factor
 $\{ -1, 0, 1 \}$

$\rightarrow 14, 17, 11, 7, 5, 3, 4, 13$

Rotate
opposite
side



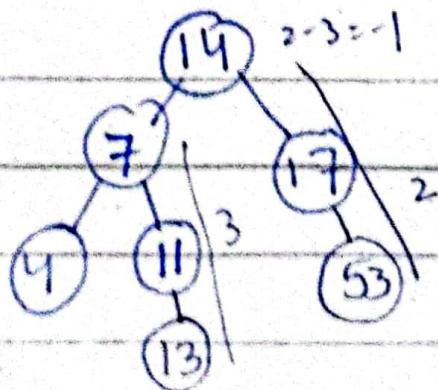
1 - 0 : $BF = -1$

: Checking
Node
Parent
if balance
factor is
out or not.

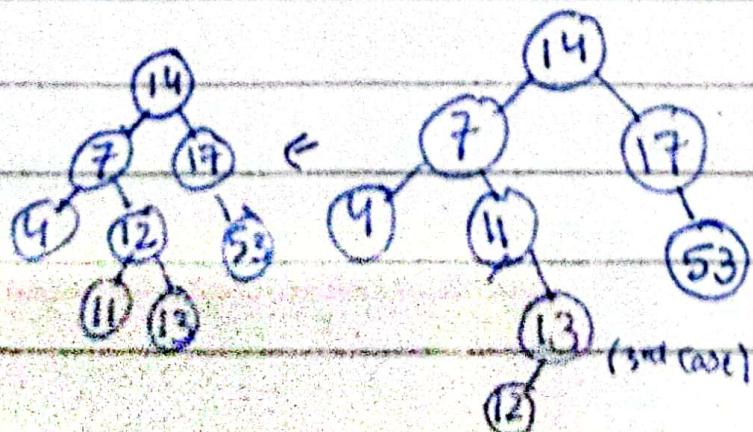
: (Right sub-tree) -

(Left sub-tree)

\rightarrow Rotating



: Rotation
cases (4)



(3rd case)

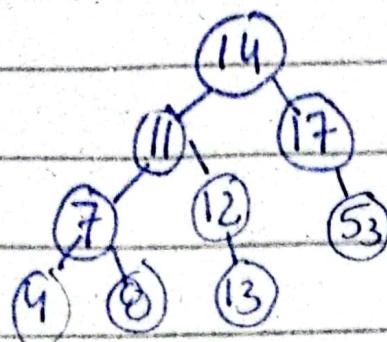
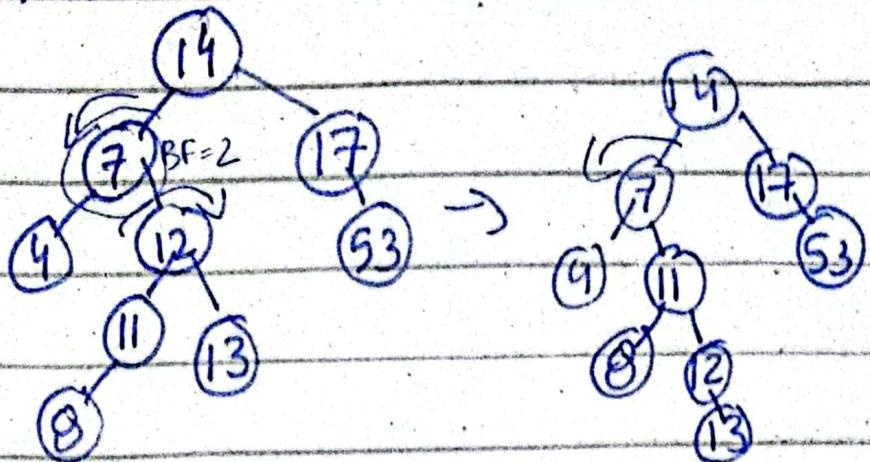
1. BST (Important)

7:45

(Lecture

on Monday)

→ 12, 8 :



: Hardcode

to add

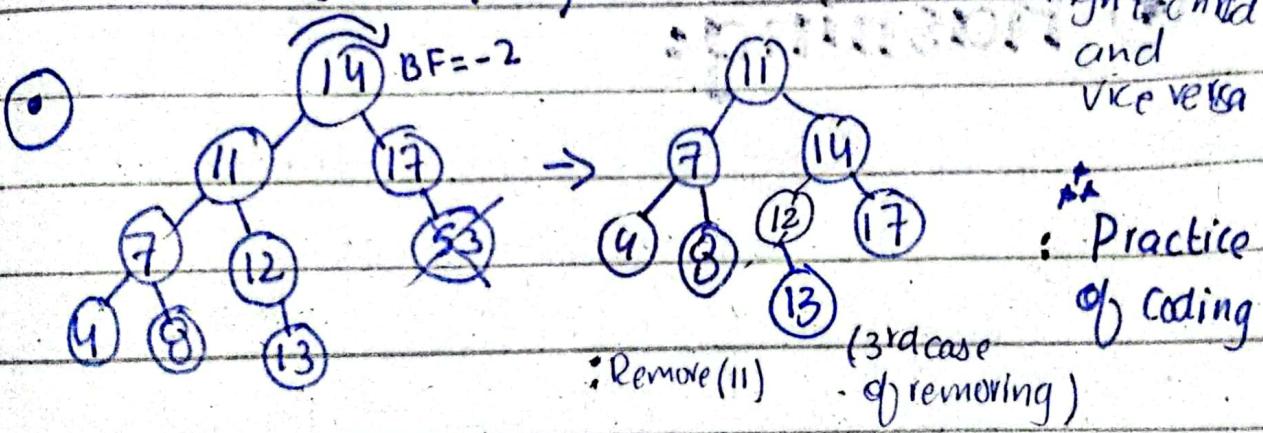
left child

on previous

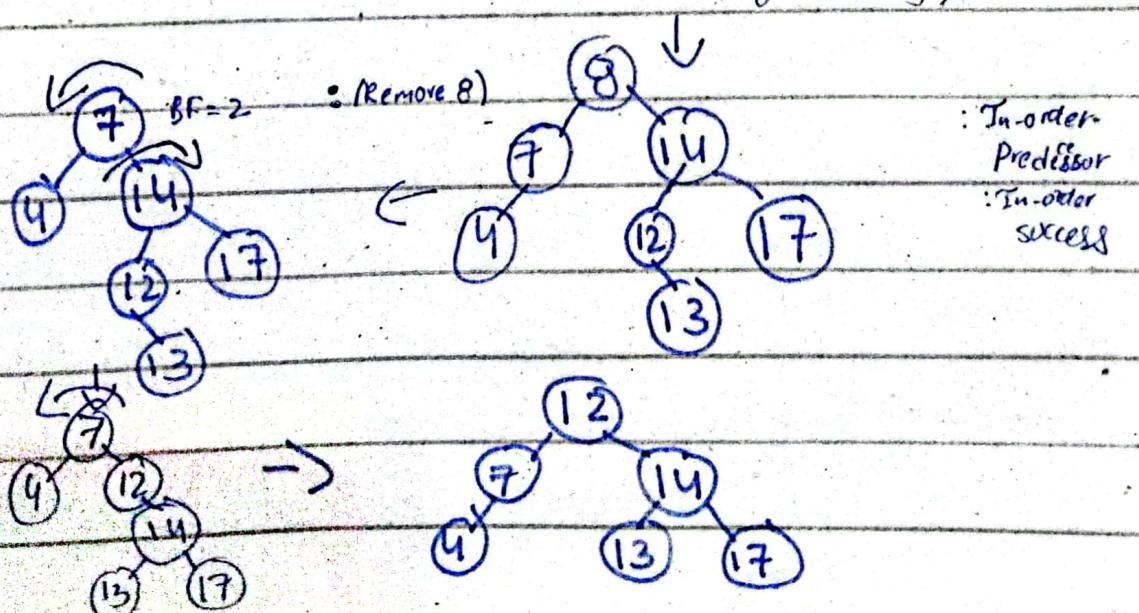
right child

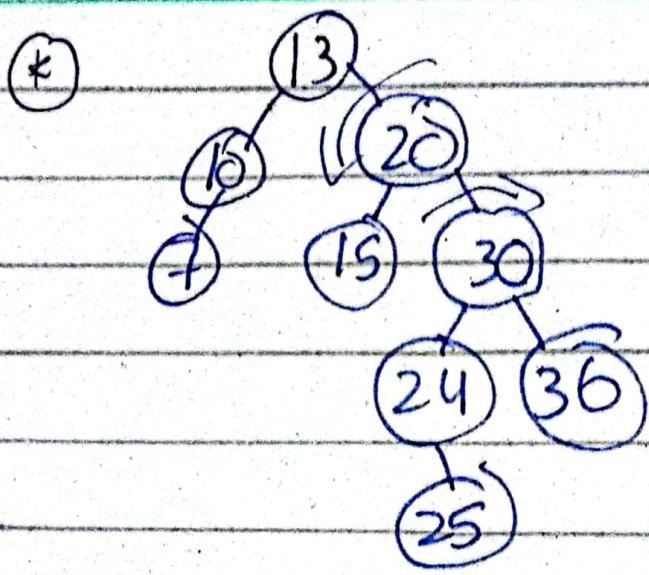
and vice versa

: remove (53)



: Practice
of Coding





3|5|24

④ Trees → Graphs → Hashing

④ Hashing:

Concept from Hash table
(An Array)

⑤ Use to store key values.

$(K = i, i+1, \dots, n)$ →

→ Save and Retrieve data
in constant time

→ Generate mapping between key
values and index.

$$: H(K) \rightarrow I$$

→ Implementation is important
and easy of all Data structures

* 12, 13, 14, 15
↑↑

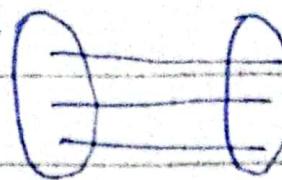
$$H(12) = 1+2 = 3$$

Multiples have index same

$$H(13) = 1+3 = 4$$

$$3+1 = 4 \\ 1+3 = 4$$

*



Hashing.

→ Hash Table:

- We have to place a key value into a location in the hash table. The location will be calculated from the key value itself.

→ Hashing:

- To find the one-to-one correspondence between a key value and index in hash table where the key value will be placed.

○ Properties:

- Easy to use → Unique ID

* : AVL, Graph, Hash,
Linked List (paper questions)

E.g:

Hash Table = 10

0 9

10, 19, 35, 43, 62, 59, 31, 49, 77, 33

- Add the digit
- Take the unit place digit as index and ignore the decimal place digit.

	K	I	
0	19	10	1
1	10	19	0
2	-	35	8
3	49	43	7
4	59, 31, 77	62	8
5	- (1) (2)	59	4
6	33	31	4
7	43	49	3
8	35, 62	77	4
9	(3)	33	6

(3 collisions).
(1st data no collision)

: Same
Index
(Collision)

① Division Method

(Circular
Function).

$K \bmod h \rightarrow$ size of
(solve collisions). (h: Normally taking
prime number)

②

Mid Square Method:

$$(321^2 \rightarrow 7862)$$

* 1234 2345 3456
↓ ↓ ↓ ↓ ↓ ↓
1 3 2 4 3 5

$$K_1 = 1234$$

$$K_2 = 2345$$

$$K_3 = 3456$$

$$K_1 = 1234 \rightarrow 525$$

$$K_2 = 2345 \rightarrow 492$$

$$K_3 = 3456 \rightarrow 933$$

: chances
of collision
is there

→ Collision Resolution

Techniques:

- ① Closed Hashing (Linear Probing)
- ② Open Hashing (Chaining)

① Closed Hashing:

Element at index

already exist, then place element
at $i+1$. If again already exist
then $i+2$ till size and then $(i-1)$.
→ If we again come at the same
place then no space for it.

① Example:

0 9 (10 index)

$$K \bmod(h) + 1$$

: function

For
Quadratic
Probing ($H(K)=i^2$)

$$h=7$$

15, 11, 25, 16, 9, 8, 12, 8

Solve by Linear Probing.

K	15	11	25	16	9	8	12
I	2	5	6	3	4	7	8

(Primary clustering) (collection of data at one place) (iii)

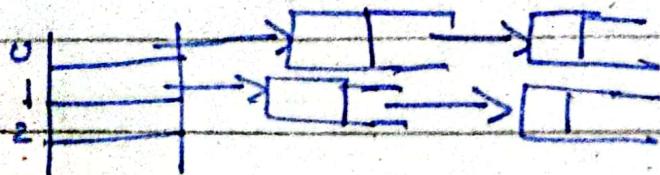
→ Solution of Primary Clustering
is quadratic probing :

: $i+1^2, i+2^2, i+3^2 \dots \dots$

- * ① Do it with quadratic probing
- * Overflowing is still an error.

→ Open-Hashing:

Linked List on
each index

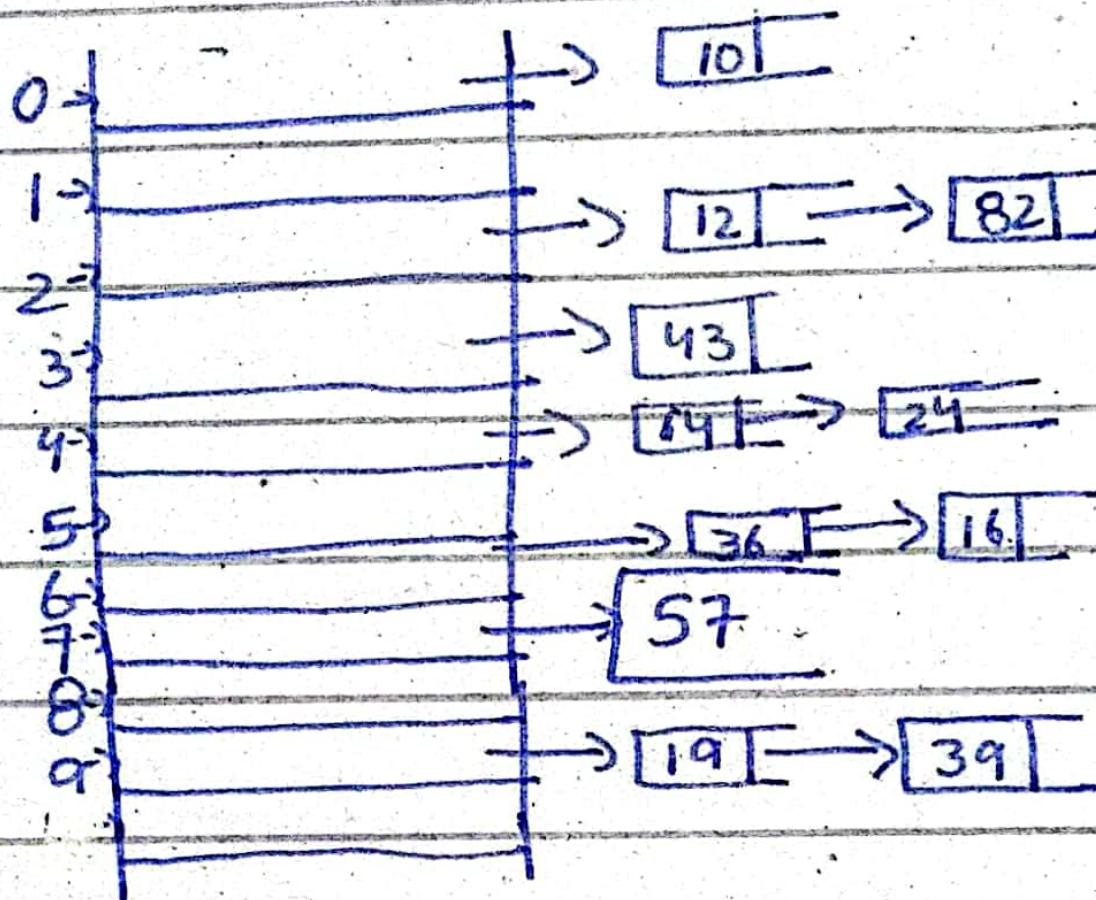


Eg:

Data : 57, 36, 19, 39, 16, 10, 43, 64
12, 82, 24

Table Size = 10

: Right
Side
Index
(Function)



: Collision
and
Overflowing
fixed.

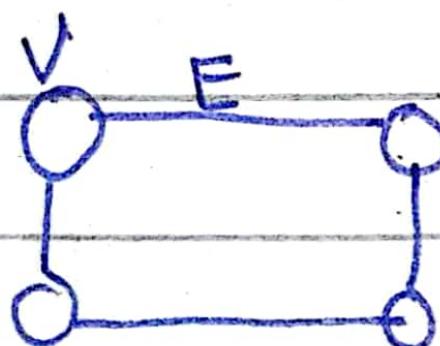
4|6|24

① Graph:

Parent and child
have relation between them.

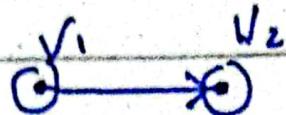
: Vertices or Nodes

: Edges or Arcs



: used for
shortest
path

④ Digraph : Directed graph



$$(v_1, v_2) \neq (v_2, v_1)$$

* Weighted graph:

Labelled edges or paths



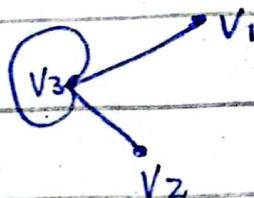
* Adjacent Vertices:

Source and Destination



* Self loop:

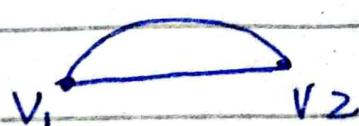
Reaches same vertex



* Parallel edges:

Multiple ways or vertices

of edges.



: Multi-
Graph

→ If loop and parallel exist,

it is multi graph.

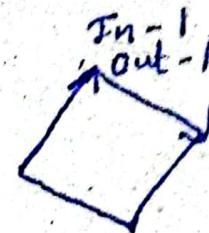
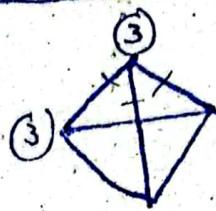
→ If no loop and not parallel

it is simple graph.

① Acyclic Graph:

If transversing, reaches same node or vertex. Other is isolated (one edge not connected)

② Degree of vertex:



③ Complete Graph:

Every Node is connected adjacent.

④ Connected Graph:

Every vertex not directly connected.

⑤ Path:

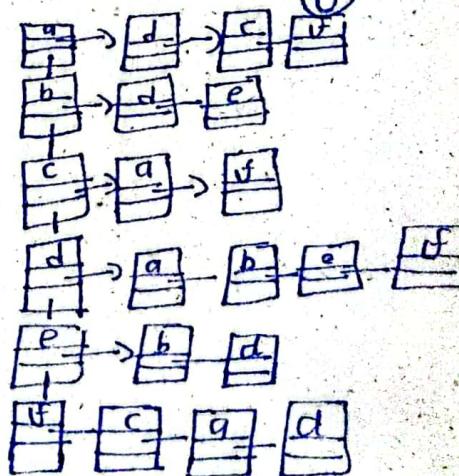
In a sequence of edges, to go from one edges to other

⑥ Adjacency List:

Table

a	d c f
b	d e
c	a f
d	a b e f
e	b d
f	c a d

Linked List:



: Stack
Trees
Graphs
Hashing

Linked List
(Sudhansu
Questions)

Q Adjacency Matrix

	a	b	c	d	e	f	g
a	0	0	1	1	0	1	0
b	0	0	0	1	1	0	0
c	1	0	0	0	0	1	0
d	1	1	0	0	1	1	0
e	0	1	0	1	0	0	0
f	1	0	1	1	0	0	0
g	0	0	0	0	0	0	0

① Incidence Matrix

	oc	af	ad	df	cf	db	be	ed
a	1							
b		0						
c			1					
d				1				
e					1			
f						1		
g							1	

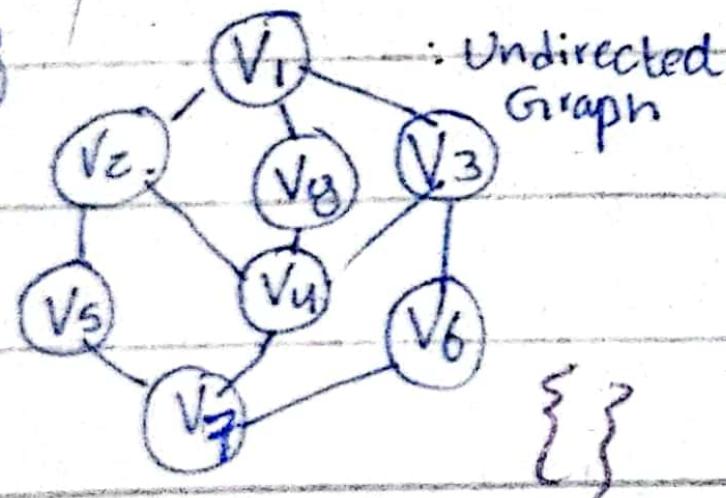
* Graph Most
Portion of
Paper

Traversal
Technique
of Graph

② Depth First Search

③ Breadth First Search

DFS



• $V_1 \rightarrow V_2 \rightarrow V_5 \rightarrow V_7 \rightarrow V_4 \rightarrow V_8$ Visited-1
 $V_4 \leftarrow V_6 \leftarrow V_3 \leftarrow$ Unvisited-0

Forward-
Traversed

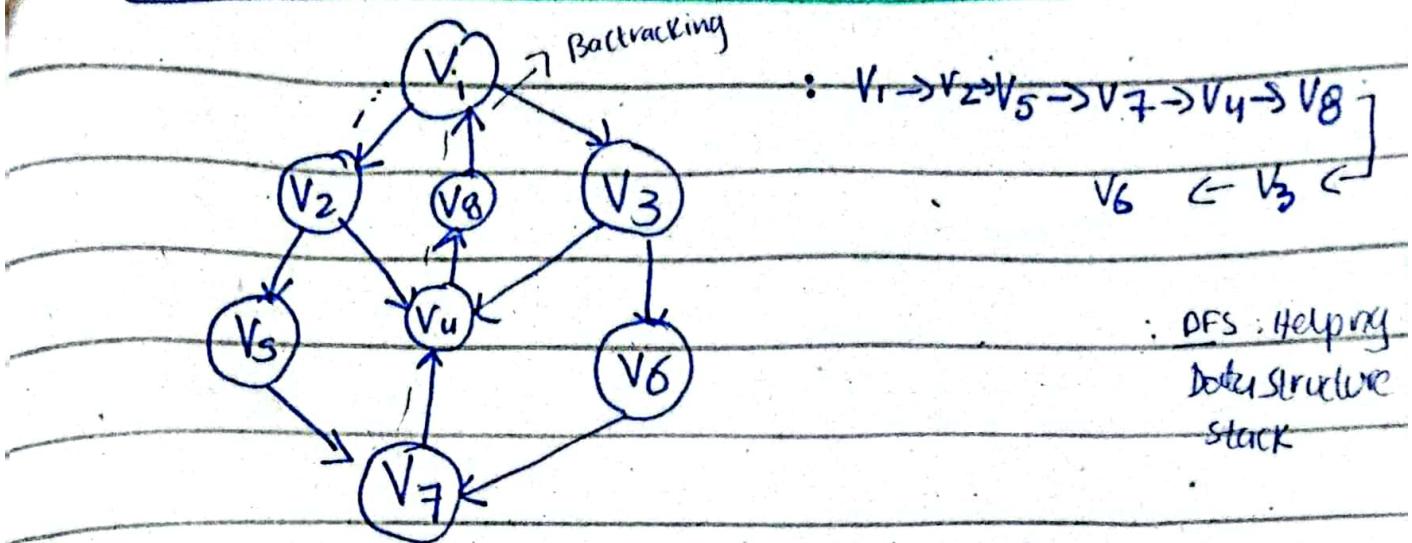
Backward-
Remaining

Tree form
after d. is
Spanning

algo

Learn

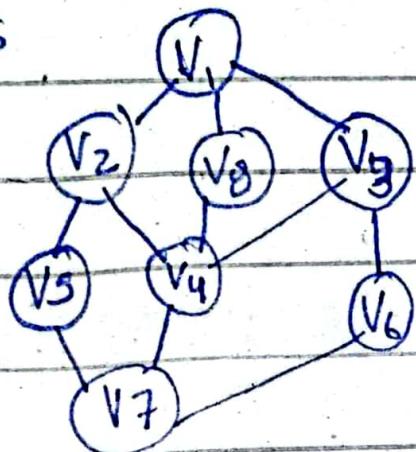
4/6/24



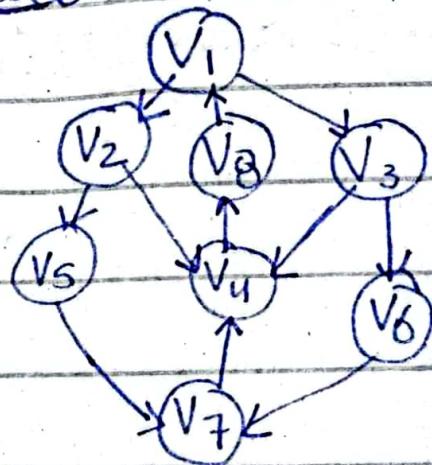
O BFS :

: All levels

: First Node
first on
each level



Directed :



$: V_1 \rightarrow V_2 - V_3 - V_5 - V_4$

$V_8 - V_7 - V_6$