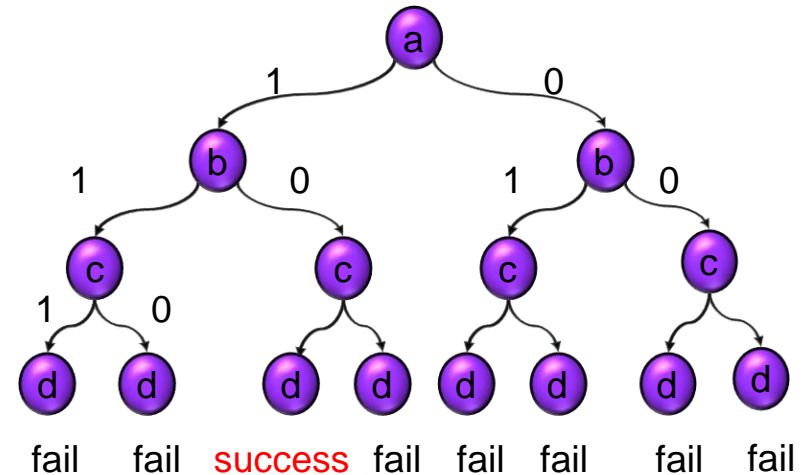


Combinational ATPG

- Introduction
- **Deterministic Test Pattern Generation**
 - ◆ Boolean difference approach*
 - ◆ Path sensitization method**
 - ◆ D-Algorithm [Roth 1966] **
 - ◆ PODEM [Goel 1981] **
 - ◆ **FAN [Fujiwara 1983]****
 - ◆ SAT-based [Larrabee 1992] *
- Acceleration Techniques
- Concluding Remarks

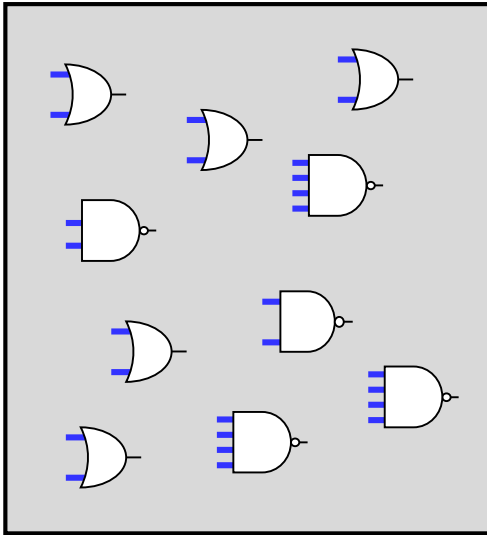
*Boolean-based methods

**path-based methods

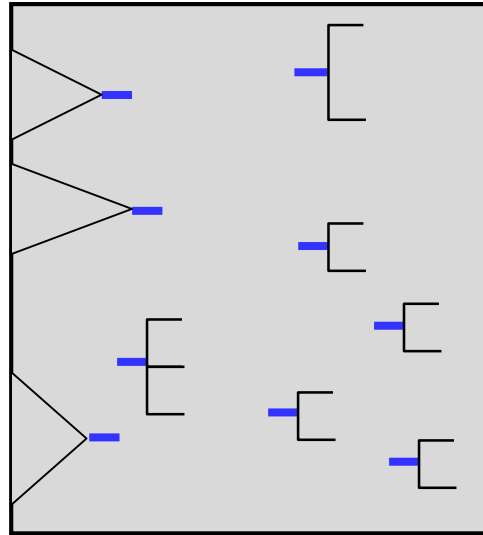


D → PODEM → FAN

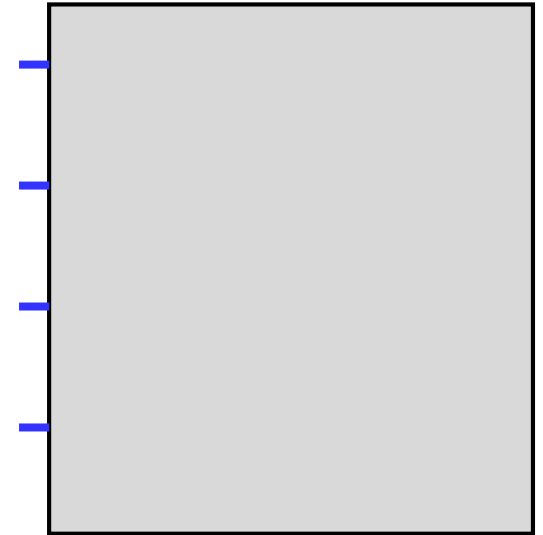
- D-algorithm decision at **internal nodes** → too many decisions, slow!
- PODEM decision at **PI** → too little information, mistake-prone!
- FAN decision at **head lines** and **fanout stems** → good trade-off



D-alg.
too many decisions



FAN
good trade-off



PODEM
too little information

— decision points

FAN [Fujiwara 1983]

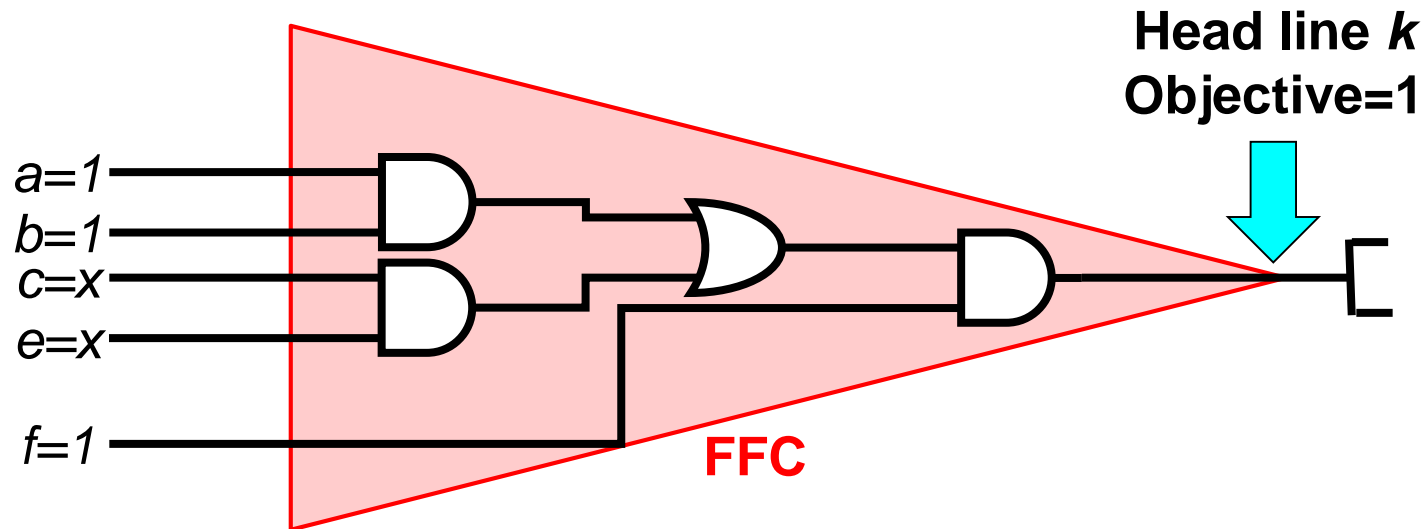
- ***FANout-oriented test generation***
- **Four improvements over PODEM**
 - ◆ #1. Make decision at head lines or fanout stem
 - ◆ #2. Forward/backward Implications
 - ◆ #3. Unique sensitization
 - ◆ #4. Multiple backtraces



<https://insights.ubuntu.com>

Justify Head Line Is Easy

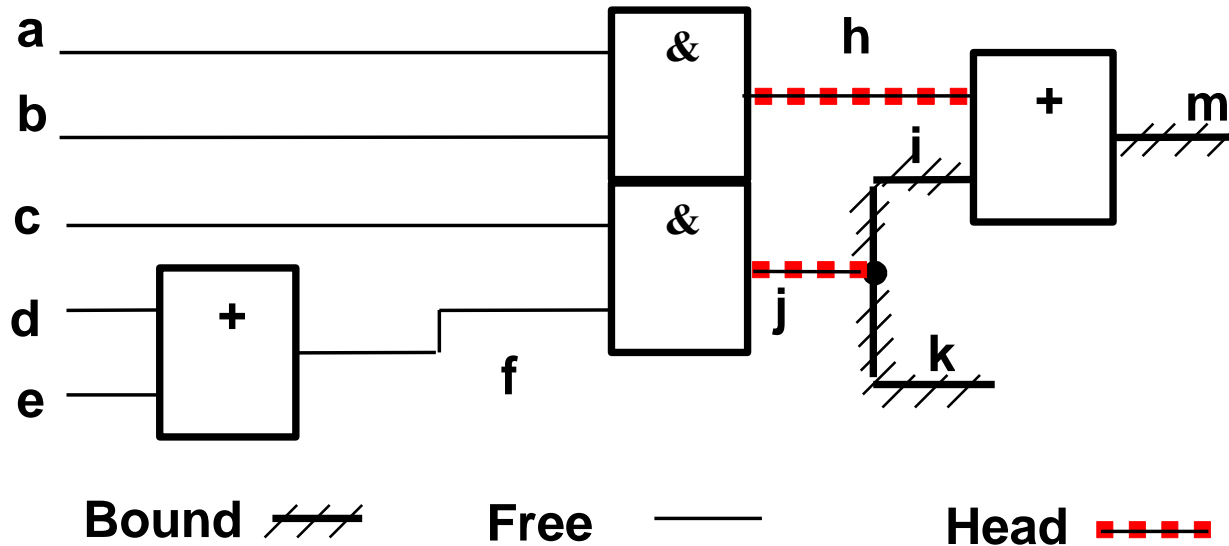
- Justification inside FFC (*fanout-free cone*) is **linear time**
 - ♦ Guaranteed to find an answer
- Example: a, b, c, e, f are PI, *k is head line*
 - ♦ objective $k=1$



**Can Make Decision at Head Line
Instead of PI**

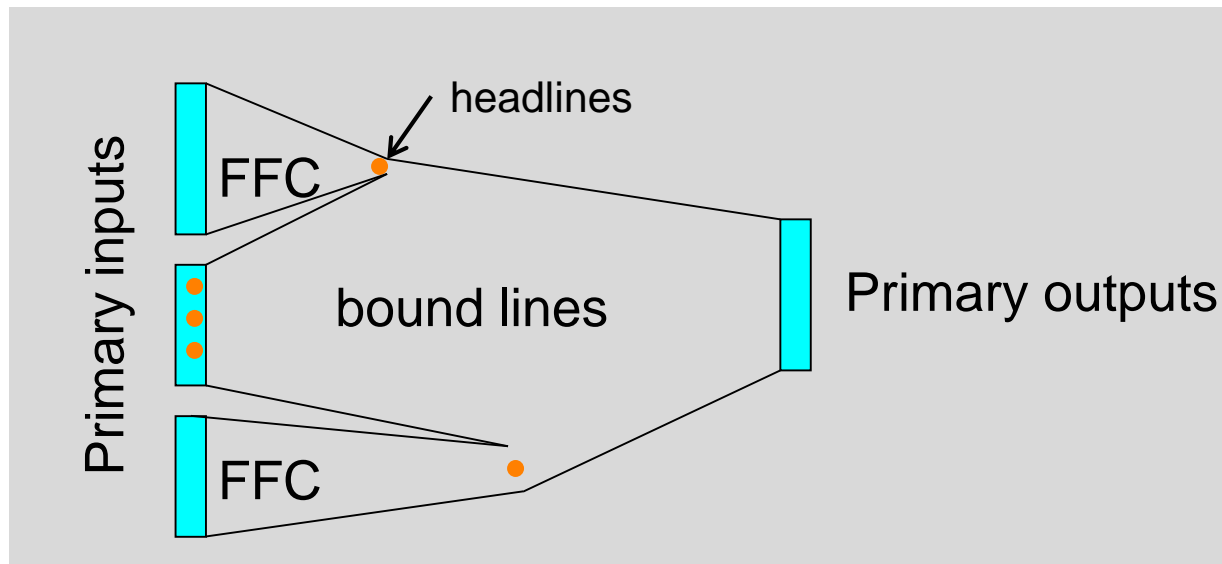
Head Line

- **Bound line**: line fed directly (*i, k*) or indirectly (*m*) by fanout stem
- **Free Line**: line that is not Bound (*a~f, h, j*)
- **Head Line**: free line that is either
 - ♦ Fanout stem (*j*), or
 - ♦ Input to a gate with bound output (*h*)



#1. Make Decision at Head Lines

- FFC can be isolated from rest of circuit by cutting head lines
- Assignment of PI's that feed head lines are
 - ◆ deferred until other objectives have been achieved
 - * Reduce search space

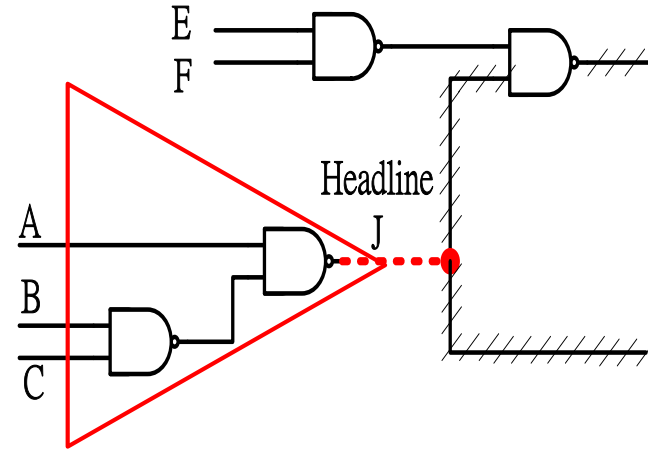


Head Lines Reduces Search Space

Example

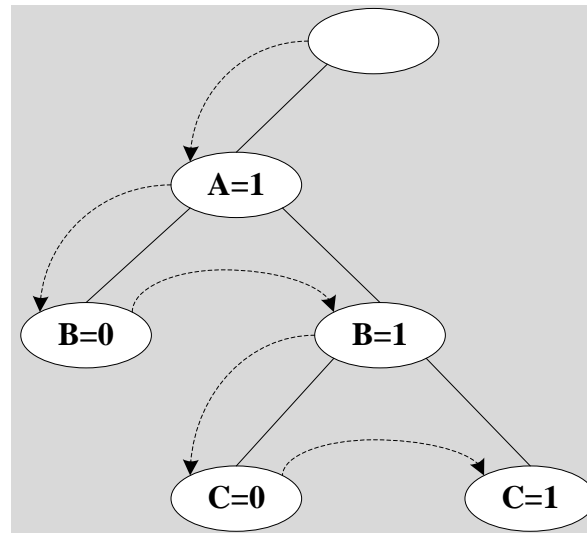
- PODEM decision tree is **big**

- ♦ $A=1, B=0$
 - * No test, backtrack
- ♦ $B=1, C=0$
 - * No test, backtrack
- ♦ $C=1$

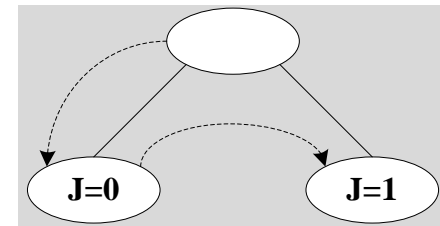


- FAN decision tree is **small**

- ♦ $J=0$
 - * No test, backtrack
- ♦ $J=1$



PODEM

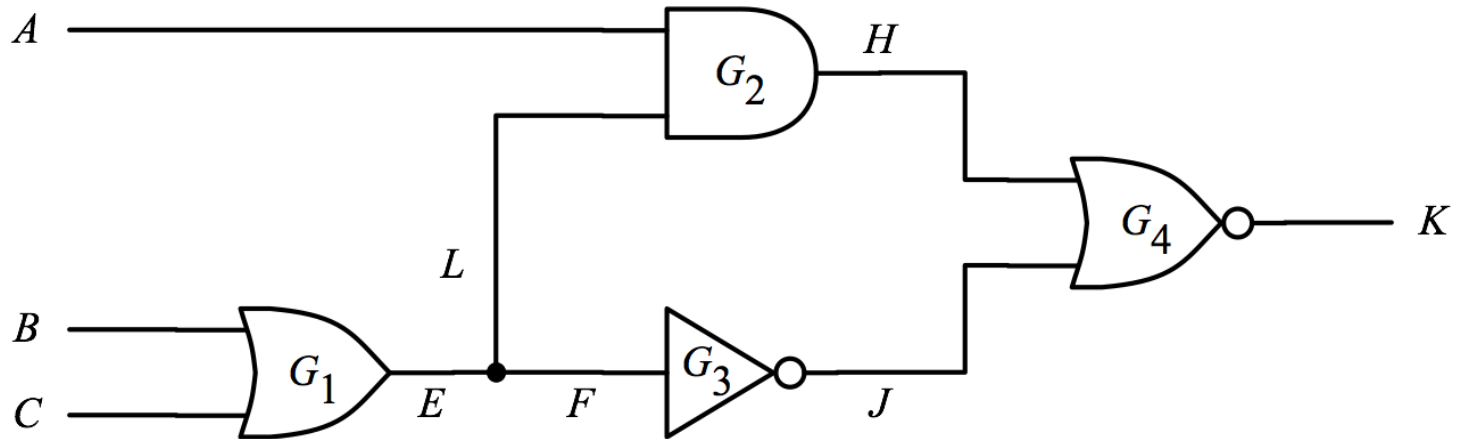


FAN

Quiz

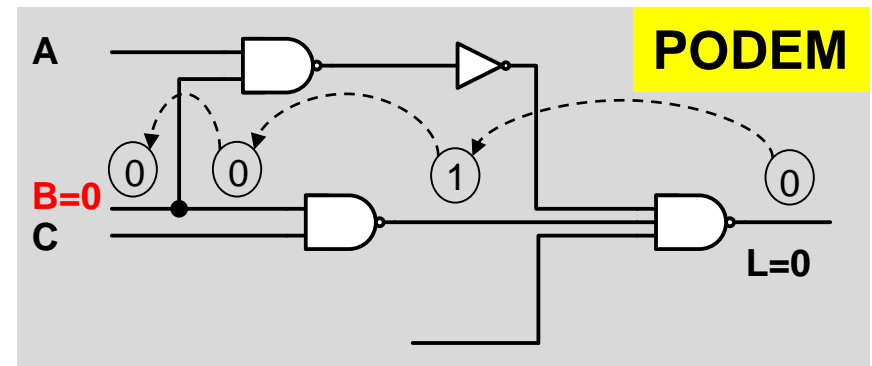
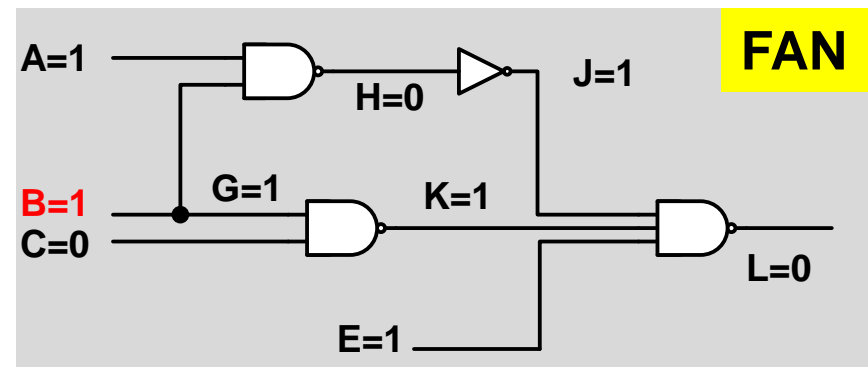
Q: Which are bound lines? free lines? head lines?

A:



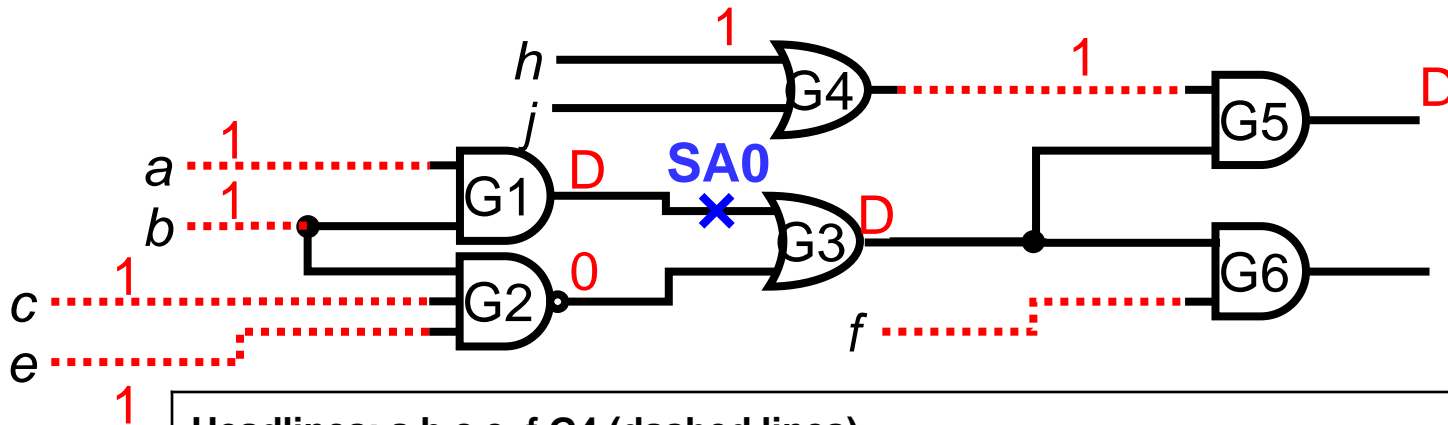
#2. Forward/backward Implication

- PODEM does not assign internal values
 - ♦ Only forward implication, no backward implication
- FAN assigns internal values when they are uniquely implied
 - ♦ Both forward and backward implication
- Example: *L* SA1 fault
- FAN
 - ♦ Bwd: $JKE=1, H=0, A=1, B=1$
 - ♦ Fwd: $G=1$
 - ♦ Bwd: $K=1, C=0$
 - ♦ no backtrack needed
- PODEM
 - ♦ Backtrace to $B=0$
 - ♦ Forward implication
 - ♦ Wrong! backtrack



FAN Example

.....headlines



Headlines: a b c e f G4 (dashed lines)

Initial objective: G1 output =1

Implication: assign a = 1; b=1

Implication

Objective: propagate through G3, objective G2=0

Implication: assign c = 1; e=1

Propagate through G5, objective G4=1

Assign headline G4 = 1

Make decision
at head line

G5=D, Objective achieved.

Justify head line G4 = 1 → h=1

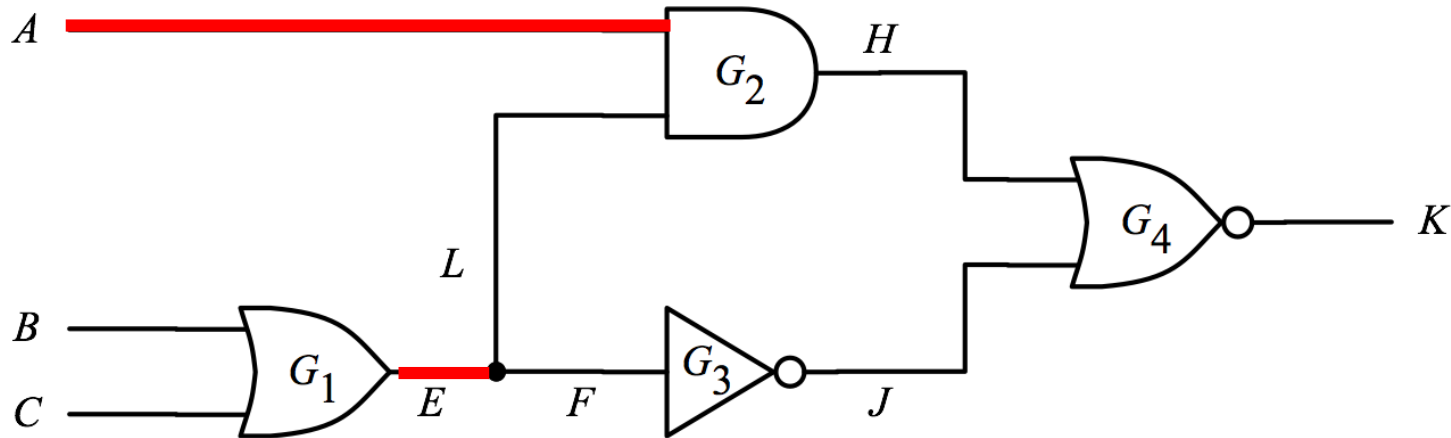
Justify head
lines at end

Test generated abcehjf = 11111xx

Quiz

Q: If we want $K=1$, apply implication to determine head lines
 $A=?$ $E=?$

ANS:



FAN

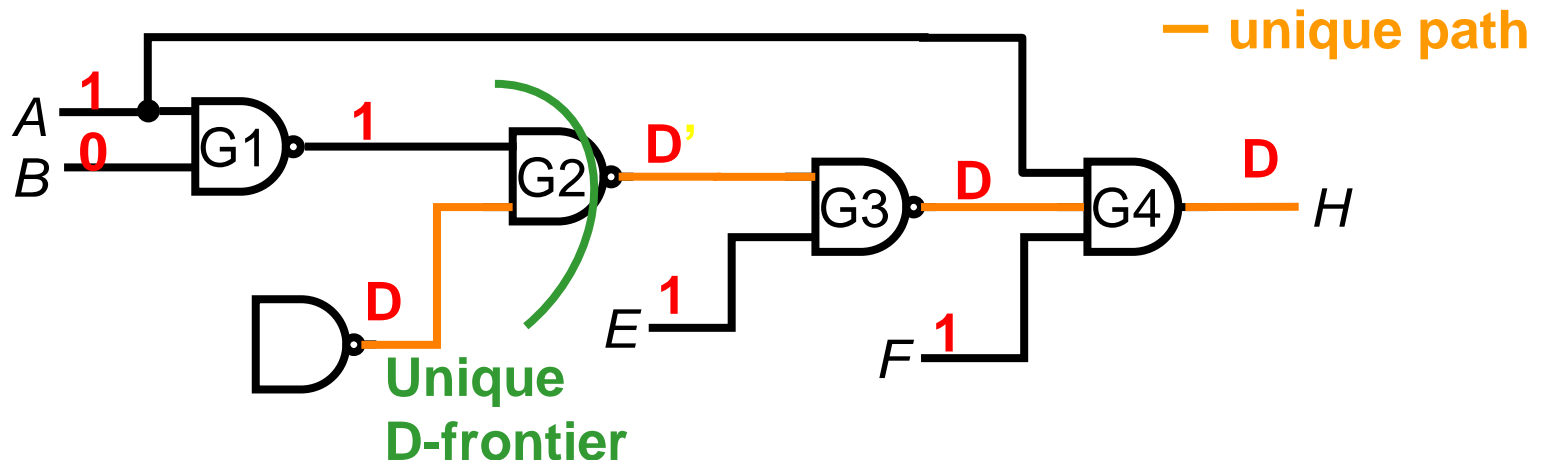
- **Four improvements over PODEM**
 - ◆ #1. Make decision at head lines or fanout stem
 - ◆ #2. Forward/backward Implications
 - ◆ #3. Unique sensitization
 - ◆ #4. Multiple backtraces



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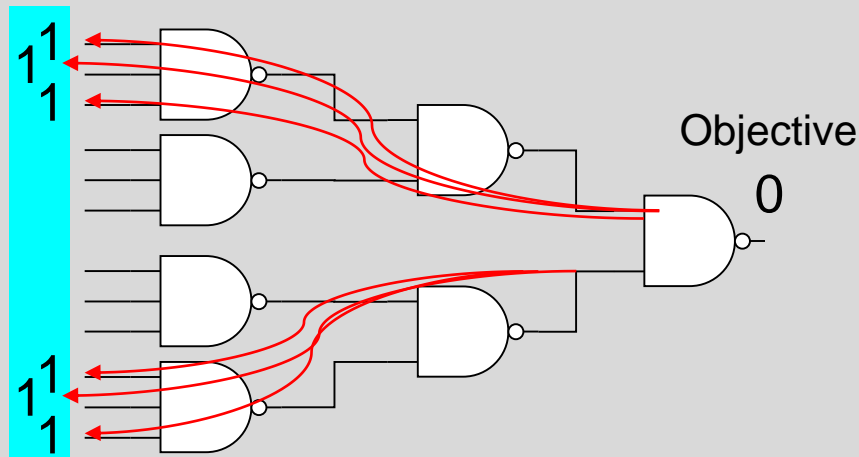
#3. Unique Sensitization

- When there is **only one gate in D-frontier**
 - ♦ if unique path exists, set side inputs to non-controlling values
- Example:
 - ♦ FAN
 - * **G2** is unique D-frontier, only one path to *H*
 - * $G1 = 1, E = 1, F = 1, A = 1 \rightarrow B = 0 \rightarrow \text{success!}$
 - ♦ PODEM
 - * Initial objective: $G1 = 1 \rightarrow$
 - * backtrace to $A = 0 \rightarrow$ X-path disappear!

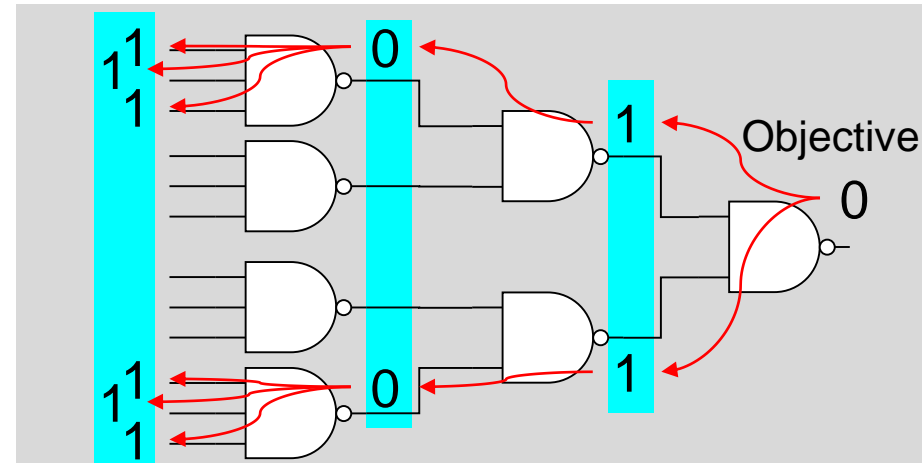


#4. Multiple Backtraces

- PODEM uses **depth-first search (DFS)**
 - ♦ One single backtrace at a time
- FAN uses **breadth first search (BFS)**
 - ♦ Multiple parallel search at a time
- Example
 - ♦ PODEM needs **6 backtraces**
 - ♦ FAN needs only **1 multiple backtrace**



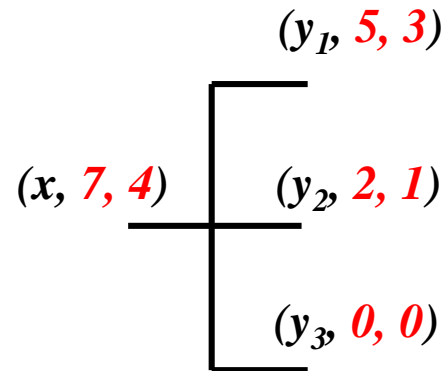
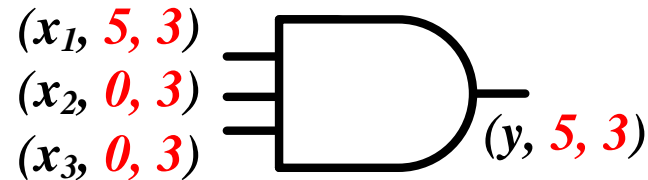
PODEM



FAN

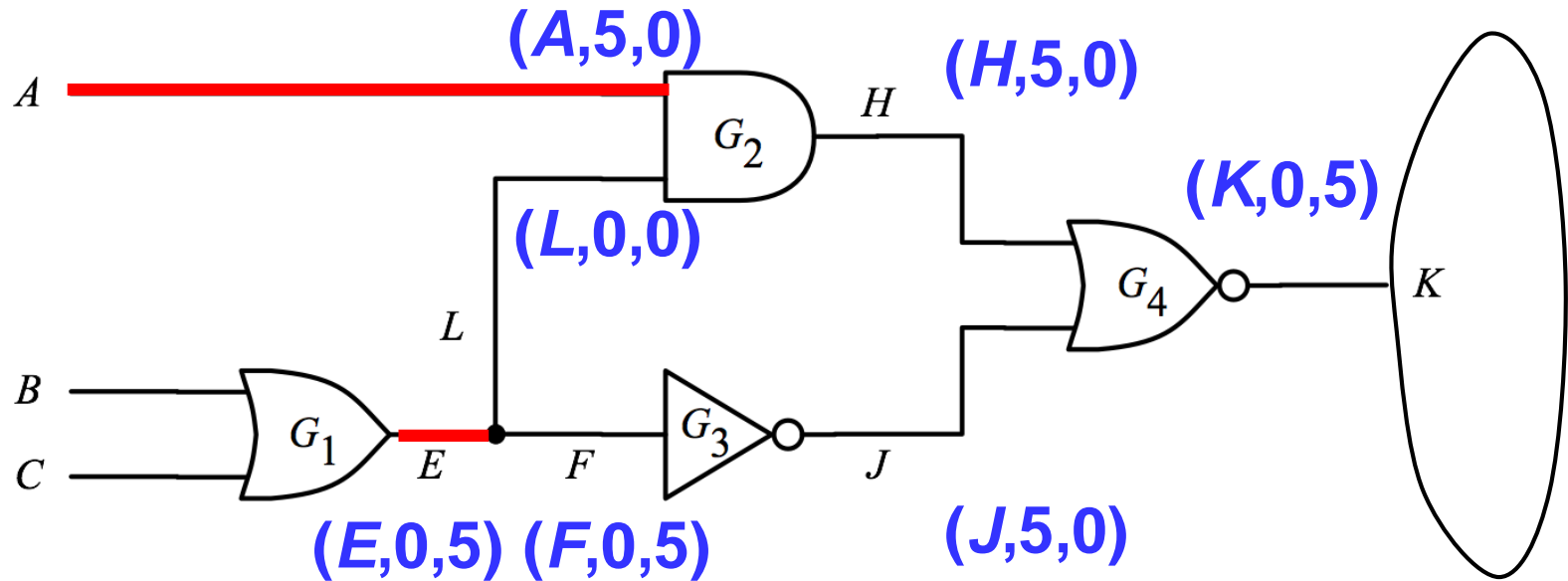
Rules for Multiple Backtraces

- **Objective:** (x, n_0, n_1)
 - ◆ number of backtraced zeros (n_0) and ones (n_1) on signal x
- **For AND gate**
 - ◆ Easiest unspecified input x_1
 - * $(x_1, n_0, n_1) = (y, n_0, n_1)$
 - ◆ Other inputs x_2, x_3
 - * $(x_2, n_0) = 0$
 - * $(x_2, n_1) = (y, n_1)$
- **For fanout Stem**
 - * $(x, n_0) = \text{sum of } (y_i, n_0)$
 - * $(x, n_1) = \text{sum of } (y_i, n_1)$



Example

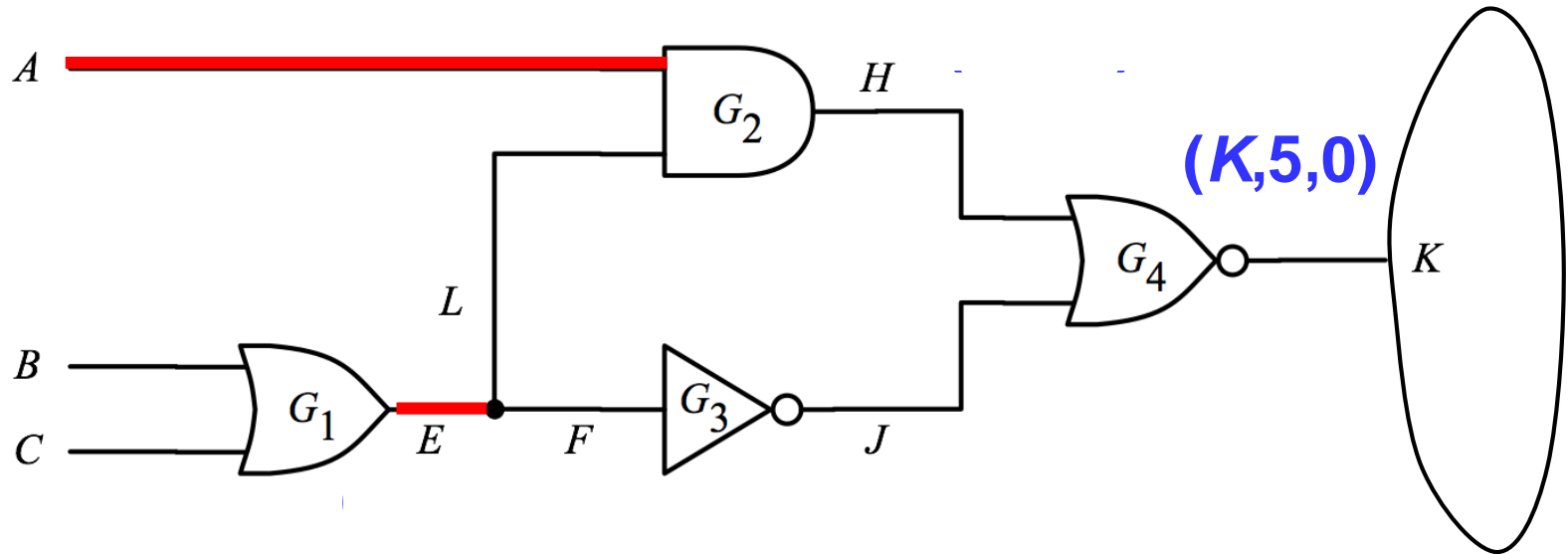
- Starting from $(K,0,5)$, multiple backtrace to head lines A and E
 - So we get two assignments $A=0, E=1$



Quiz

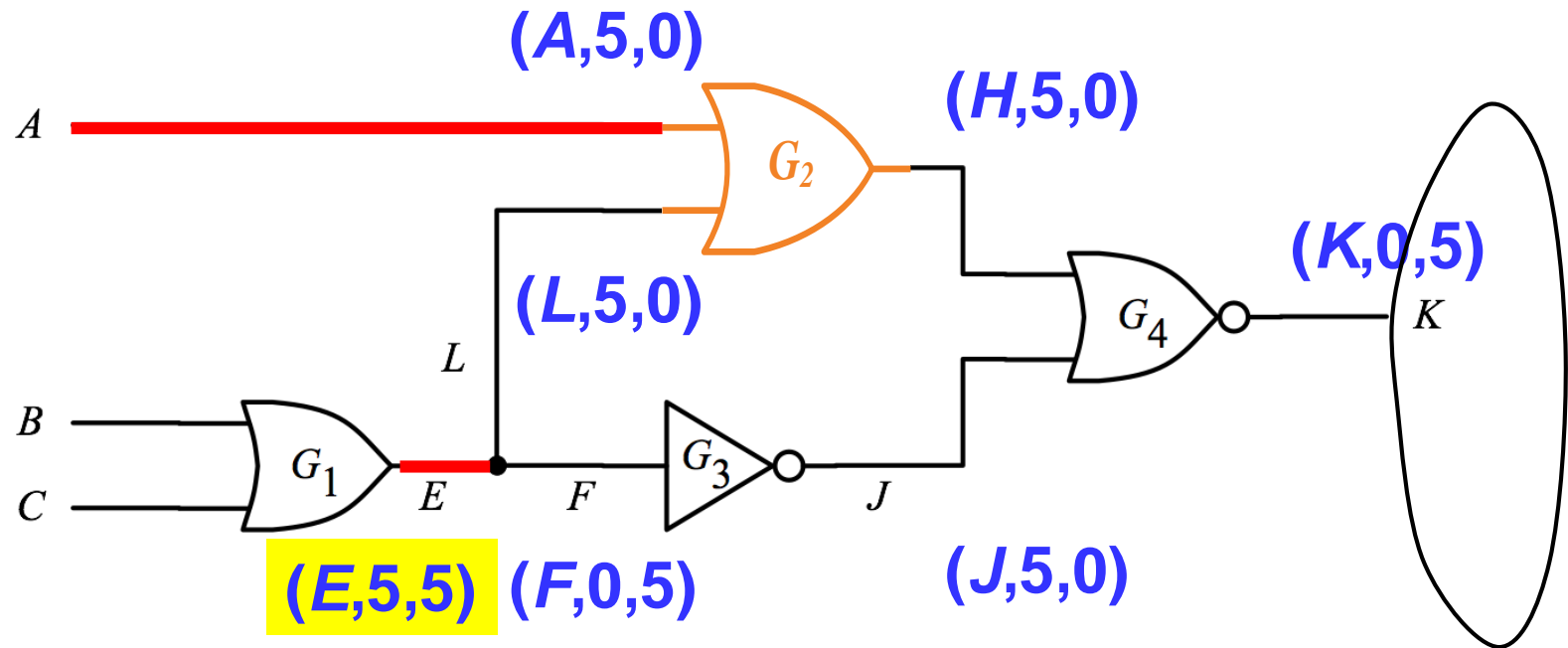
Q: Starting from $(K, 5, 0)$, multiple backtrace to head lines $(E, n_0, n_1)=?$ $(A, n_0, n_1)=?$ Suppose H is chosen over J

A:



Multiple Backtrace Conflict

- What if change G_2 to OR gate?
- Want $K=1$, perform multiple backtrace to headlines A and E
 - ♦ conflicting values at E !



- How to handle a conflict ?
 - ♦ assign a value **most requested**, then start next backtrace
 - ♦ will backtrack if it is wrong

Multiple Backtrace (1/2)

```
MultipleBacktrace (Initial_objectives, Fanout_objectives) {  
    Current_objectives = Initial_objectives  
    while (Current_objectives  $\neq \phi$  or Fanout_objectives  $\neq \phi$ ) {  
        dequeue entry  $(k, v_k)$  from Current or Fanout_objectives  
        switch (type of entry) { //  $(k, v_k)$  = want  $v_k$  on signal  $k$   
            1. HEAD_LINE:  
                add  $(k, v_k)$  to Headline_objectives  
            2. FANOUT_BRANCH:  
                 $j = \text{stem}(k)$ ;  
                increment  $n_0$  or  $n_1$  at  $j$  for  $v_k$ ; //sum of  $n_0, n_1$   
                add  $j$  to Fanout_objectives  
            3. GATE: //page 15  
                 $i = \text{inversion of } k$ ;  $c = \text{controlling value of } k$ ;  
                if  $((v_k \oplus i) == c)$  {  
                    select easiest input  $j$  with unknown value  
                    add  $(j, c)$  to Current_objectives;  
                }  
                else {  
                    for every input  $j$  of  $k$  with value  
                    add  $(j, c')$  to Current_objectives; }  
        } // switch  
    }  
}
```

Multiple Backtrace (2/2)

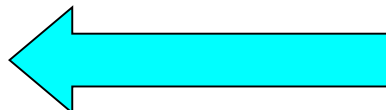
(cont'd from previous page)

*simplified from Fig. 8 of FAN paper

```
if(Fanout_objectives  $\neq \phi$ ) {  
    dequeue highest-level stem ( $k$ ) from Fanout_Objectives  
     $v_k = 0$  or  $1$ , depends on which of ( $n_0, n_1$ ) is larger  
    if there is no conflict on  $k$  {  
        add ( $k, v_k$ ) to Current_objectives } // continue backtrace  
    else { return ( $k, v_k$ ) as the Final_objective } } // stop backtrace  
else { // no fanout objective  
    dequeue ( $k, v_k$ ) from Headline_objectives  
    return ( $k, v_k$ ) as the Final_objective }  
} // while  
} // MultipleBacktrace
```

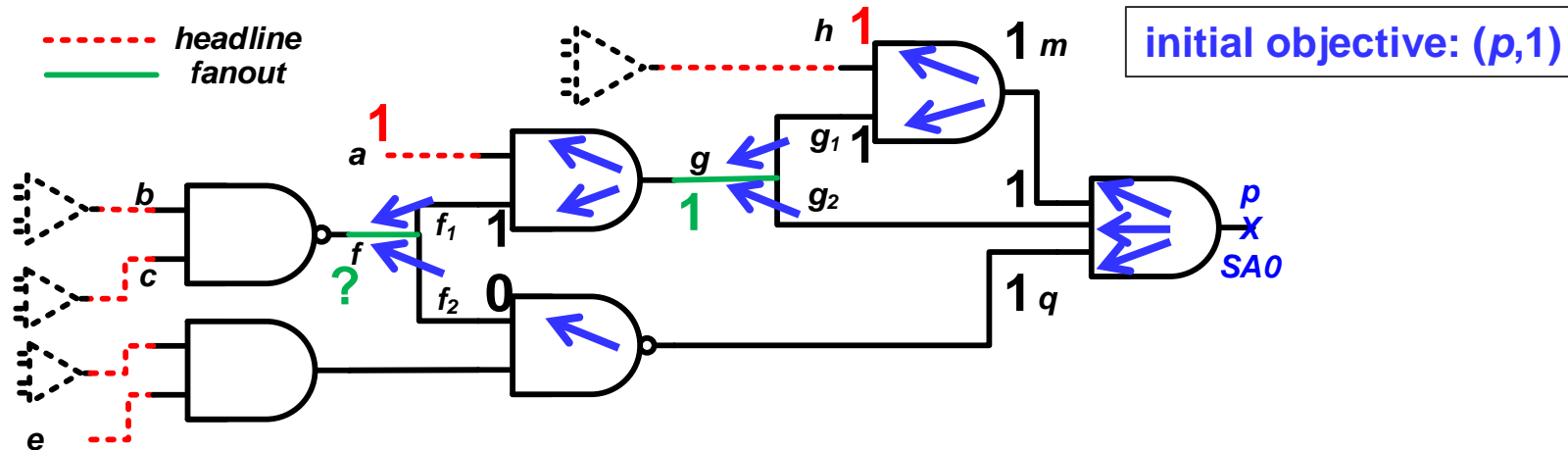
final_objective
(either a fanout or a headline)

MultipleBacktrace



initial_objectives
fanout_objectives

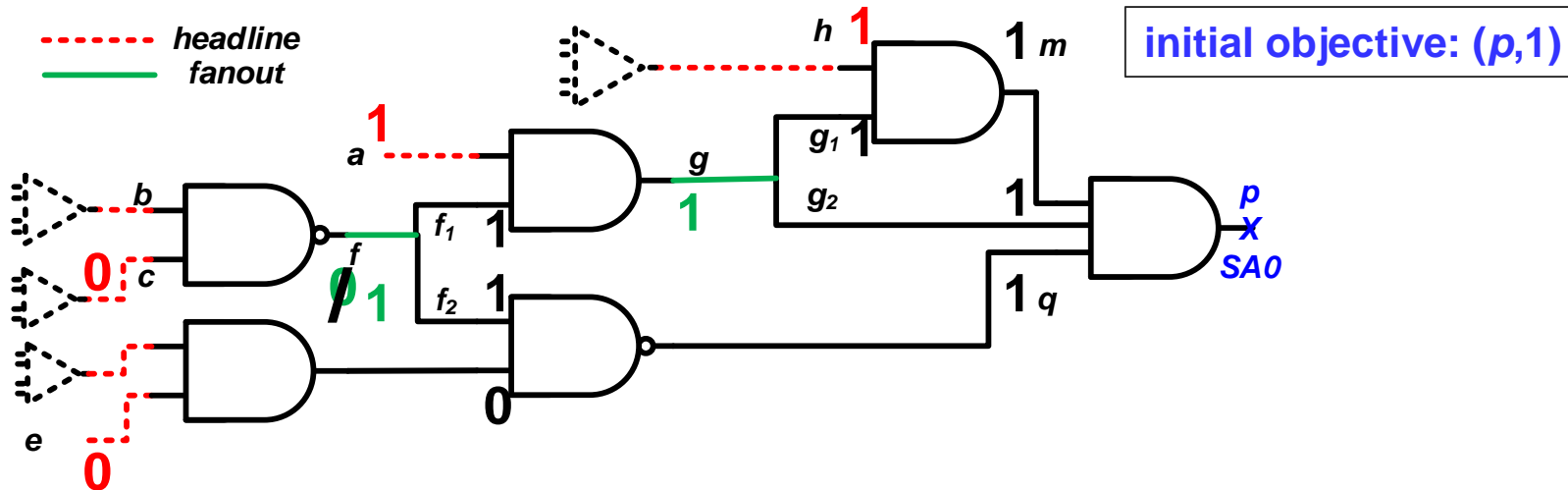
Multiple Backtrace Example (1/3)



Current Obj.	processed entry	Fanout Obj.	Headline Obj.
$(m,1)(g_2,1)(q,1)$	$(m,1)$	-	$(h,1)$
$(g_2,1)(q,1)(g_1,1)$	$(g_2,1)$	$(g, n_i=1)$	$(h,1)$
$(q,1)(g_1,1)$	$(q,1)$	$(g, n_i=1)$	$(h,1)$
$(g_1,1)(f_2,0)$	$(g_1,1)$	$(g, n_i=2)$	$(h,1)$
$(f_2,0)$	$(f_2,0)$	$(g, n_i=2) (f, n_o=1)$	$(h,1)$
-	$(g,1)$ consistent	$(f, n_o=1)$	$(h,1)$
$(g,1)$	$(g,1)$	$(f, n_o=1)$	$(h,1)(a,1)$
$(f_1,1)$	$(f_1,1)$	$(f, n_o=1 n_i=1)$	$(h,1)(a,1)$
-	f conflict!	-	$(h,1)(a,1)$

Decision at Fanout Stem Detects Inconsistency Earlier

Multiple Backtrace Example (3/3)



Assign $f=1$

Forward implication, consistent.

Multiple_Backtrace again

This time, headline objectives: $h=1, a=1, e=0, c=0$

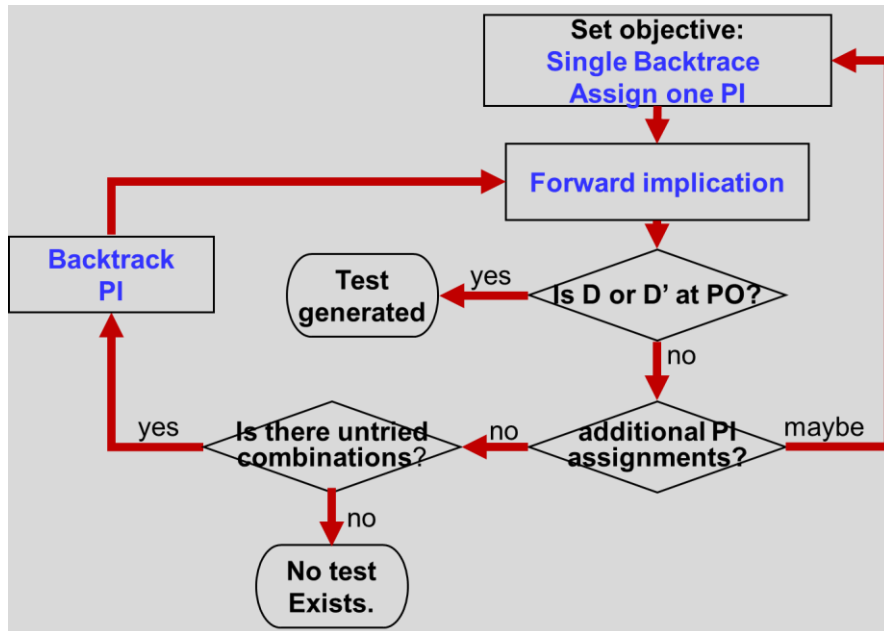
Forward implication

Initial objective achieved!

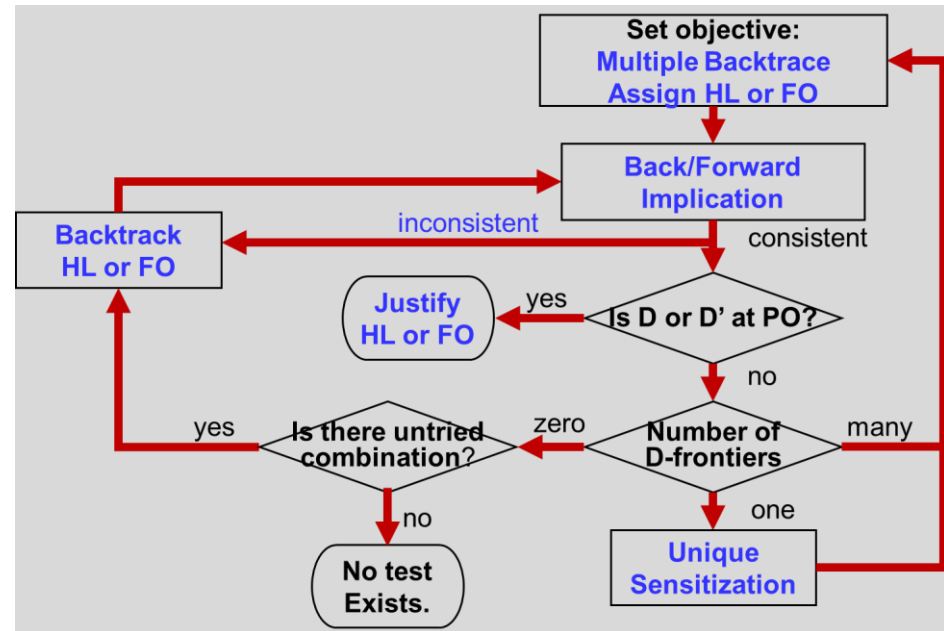
Multiple Backtrace is Fast

PODEM v.s. FAN

PODEM



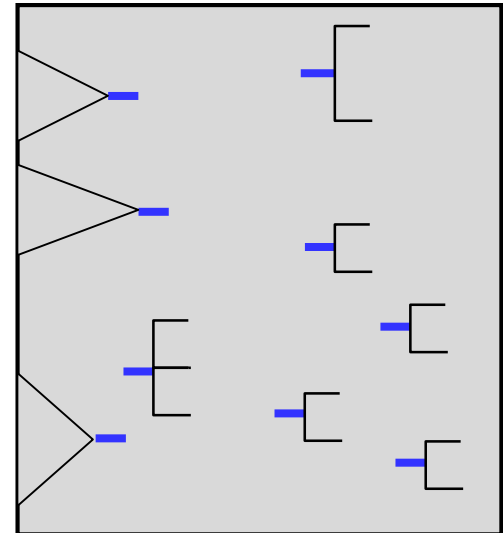
FAN



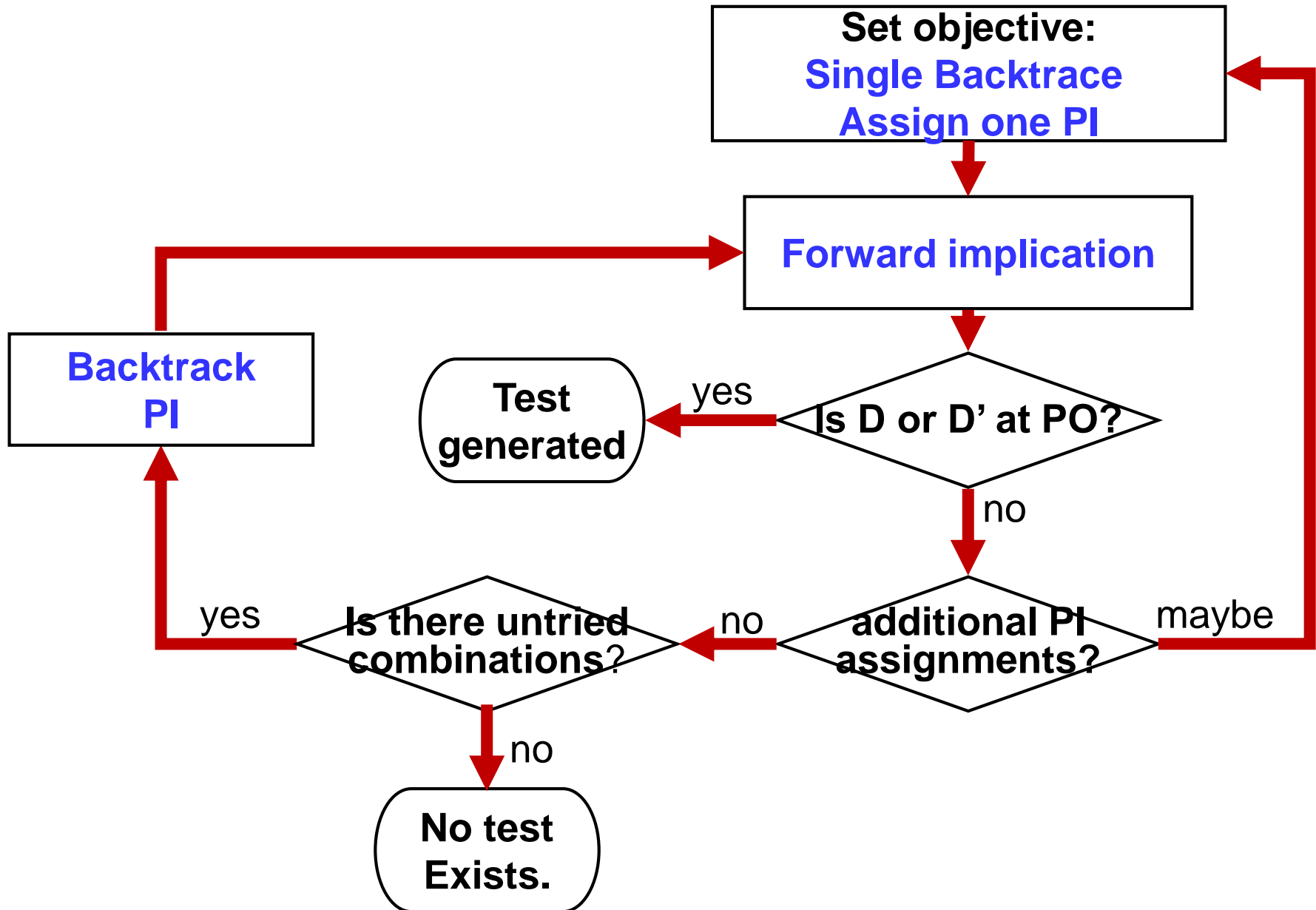
Difference highlighted in Blue

Summary

- 1. Make decision at **head lines** and **fanout stem**
 - ♦ Reduce search space
- 2. Forward/**backward Implications**
 - ♦ More information to make correct decision
- 3. **Unique sensitization**
 - ♦ Unique path to output
- 4. **Multiple backtraces**
 - ♦ BFS to search many paths together



Flowchart of PODEM



Flowchart of FAN

*simplified from Fig. 9 of FAN paper

