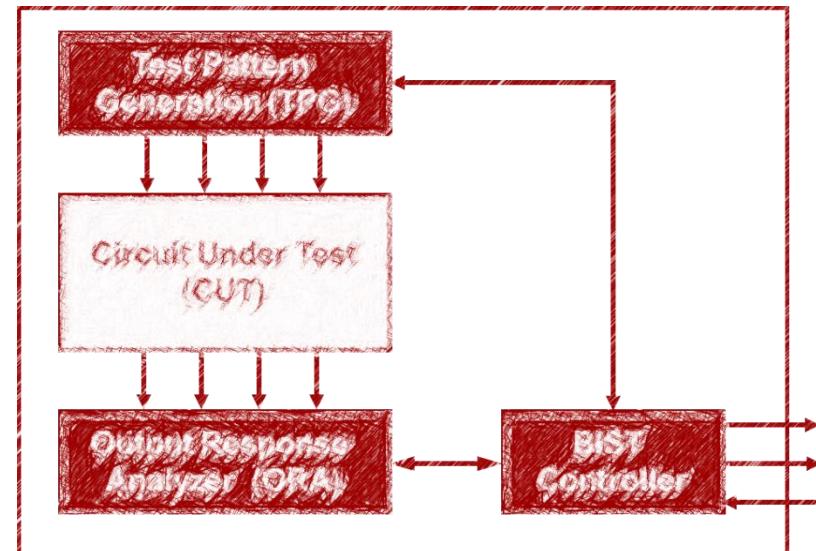


# BIST Part1 - TPG

- Introduction
- Test Pattern Generation
  - ◆ Deterministic: ROM, Algorithm, Counter
  - ◆ Pseudo Random
    - \* Linear Feedback Shift Register, LFSR (1977)
    - \* Cellular Automata, CA (1984)



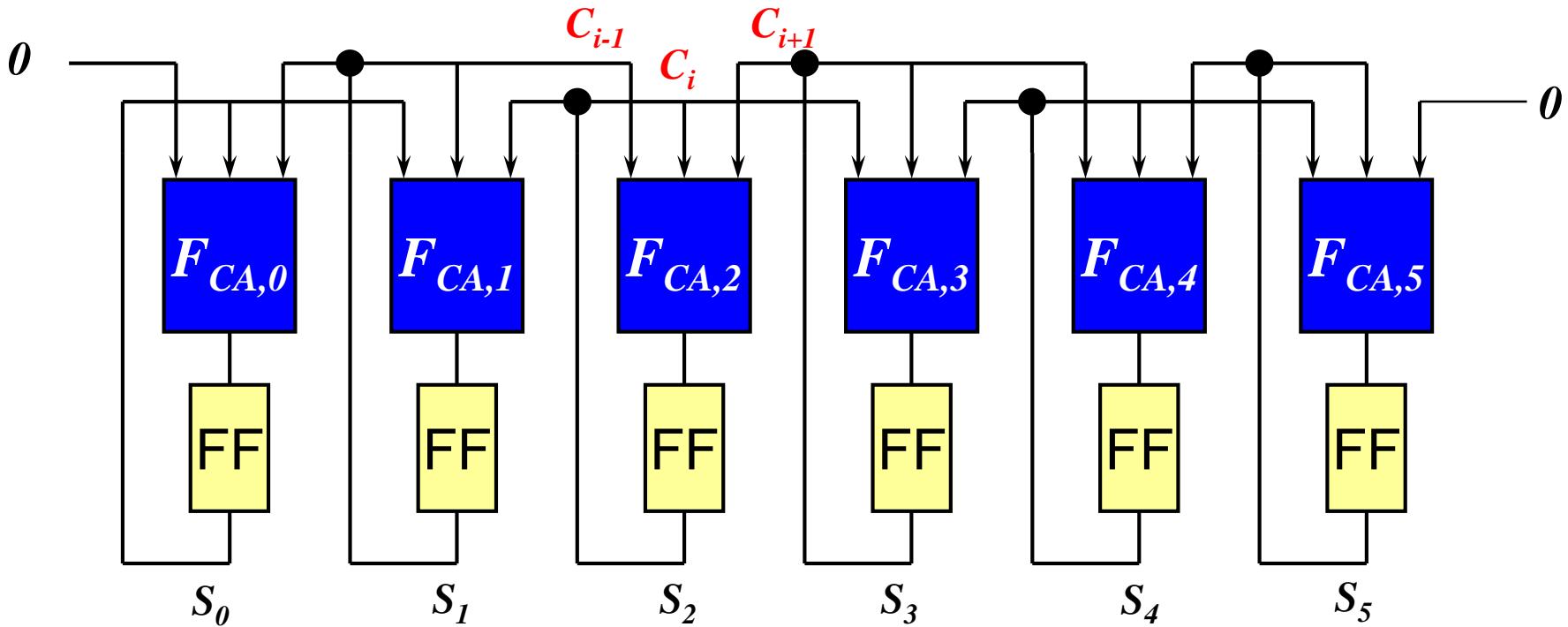
# Cellular Automata [Wolfram 84]

- $F_{CA}$  is a linear function of Its two immediate neighbors and itself

$$F_{CA,i} = C_{i-1}S_{i-1} \oplus C_iS_i \oplus C_{i+1}S_{i+1}$$

$C_i=1$  means connection exists

- **Null Boundary Condition** = both ends tied to zero
- **Degree** = number of FF = 6



CA Has No Long Global Wires

# Name of CA Cell

- CA cell is named by  $F_{CA}$  function

K map of  $F_{CA}$

		00	01	11	10	
		$S_i S_{i-1}$	$S_i$	$S_{i-1}$	$S_{i+1}$	
		0	$A_0$	$A_1$	$A_3$	$A_2$
		1	$A_4$	$A_5$	$A_7$	$A_6$

$$Name = \sum_{i=0}^7 A_i 2^i$$

- Example:  $F_{CA,i} = S_{i-1} \oplus S_i$

		00	01	11	10	
		$S_i S_{i-1}$	$S_i$	$S_{i-1}$	$S_{i+1}$	
		0	0	1	0	1
		1	0	1	0	1

Name =  $2^6 + 2^5 + 2^2 + 2^1 = 102$   
This is called a **rule-102 cell**

# Quiz

Q1: Given a CA cell  $F_{CA,i} = S_{i-1} \oplus S_{i+1}$ . What is rule number?

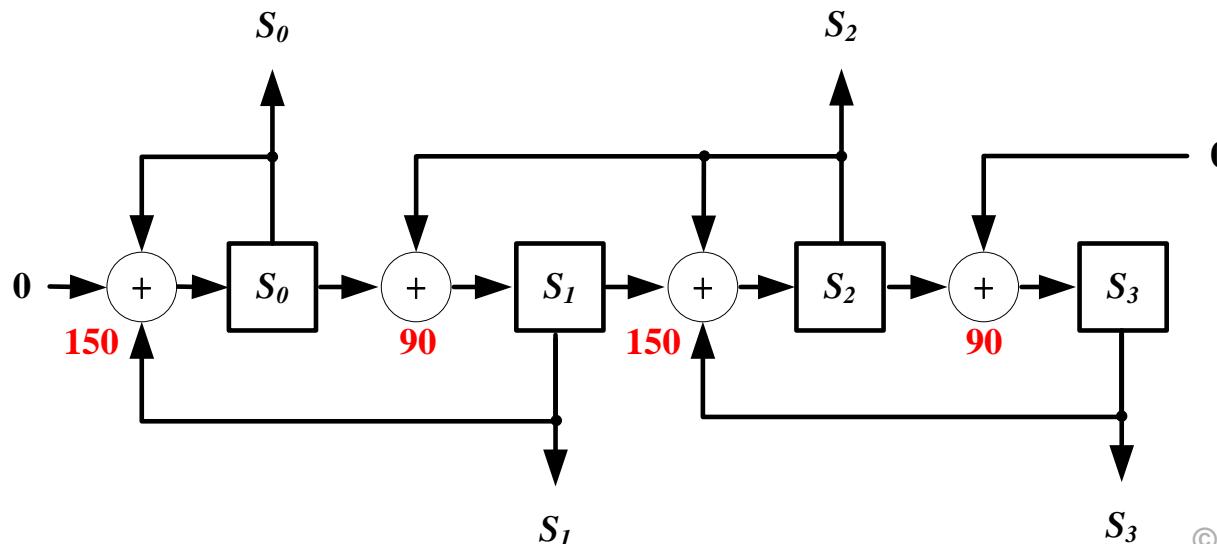
ANS:

K map of  $F_{CA}$

		00	01	11	10
		S <sub>i</sub>	S <sub>i-1</sub>	S <sub>i+1</sub>	
S <sub>i+1</sub>	0	A <sub>0</sub>	A <sub>1</sub>	A <sub>3</sub>	A <sub>2</sub>
	1	A <sub>4</sub>	A <sub>5</sub>	A <sub>7</sub>	A <sub>6</sub>

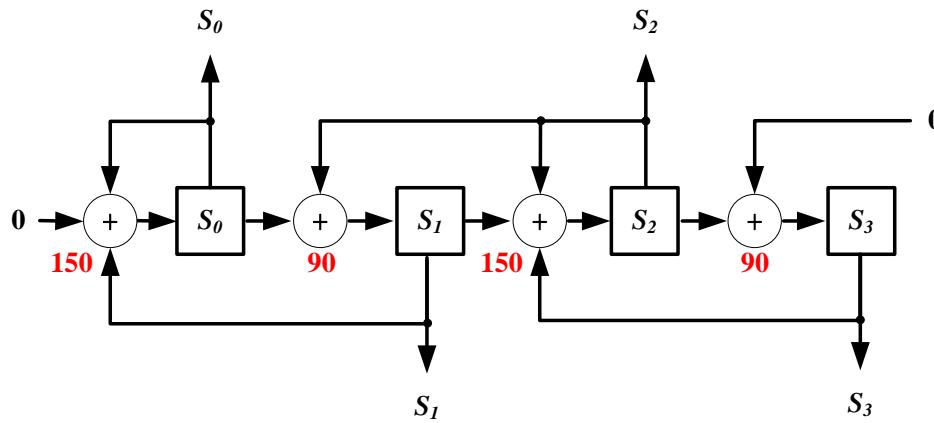
# Linear Hybrid CA, LHCA

- Rule-90 CA cell
  - ◆  $F_{CA,i} = S_{i-1} \oplus S_{i+1}$
- Rule-150 CA cell
  - ◆  $F_{CA,i} = S_{i-1} \oplus S_i \oplus S_{i+1}$
- 90/150 LHCA with null boundary condition
  - ◆ Consist of only rule-90 and rule-150 cells
  - ◆ Very popular CA, math model well studied
- Example: 4-degree 90/150 LHCA



# State Transition

- Given seed = 1000
- CA generates pseudo random patterns
  - m-sequence of phase difference
  - Periodic
- Why this CA generates m-sequence?
  - to be proved later



state	$S_0$	$S_1$	$S_2$	$S_3$
0	1	0	0	0
1	1	1	0	0
2	0	1	1	0
3	1	1	0	1
4	0	1	0	0
5	1	0	1	0
6	1	0	1	1
7	1	0	0	1
8	1	1	1	0
9	0	0	0	1
10	0	0	1	0
11	0	1	1	1
12	1	1	1	1
13	0	0	1	1
14	0	1	0	1
15				

Phase diff.      11      9      1

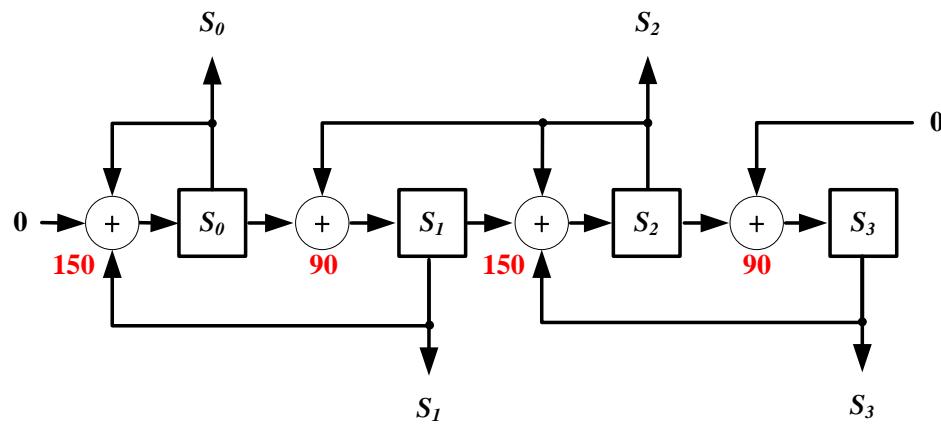
# Quiz

**Q1: What is state 15?**

**ANS:**

**Q2: What is cycle length of this CA?**

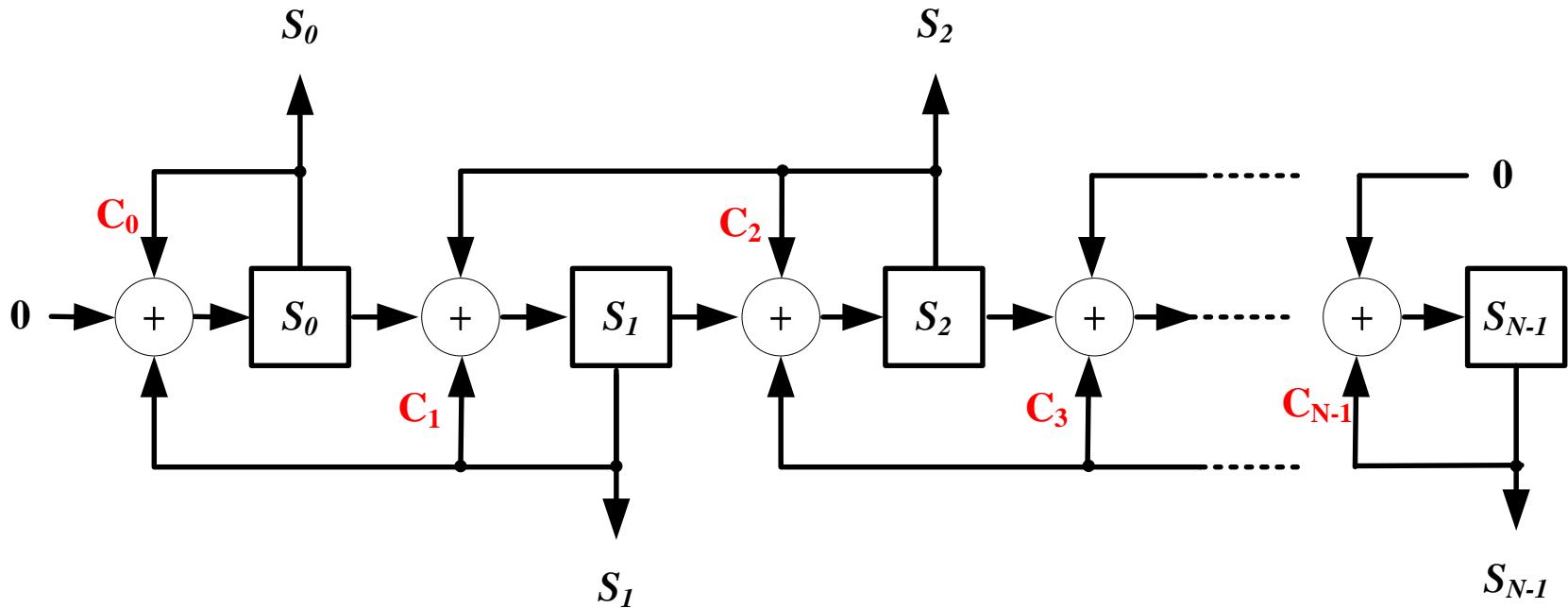
**ANS:**



state	$S_0$	$S_1$	$S_2$	$S_3$
0	1	0	0	0
1	1	1	0	0
2	0	1	1	0
3	1	1	0	1
4	0	1	0	0
5	1	0	1	0
6	1	0	1	1
7	1	0	0	1
8	1	1	1	0
9	0	0	0	1
10	0	0	1	0
11	0	1	1	1
12	1	1	1	1
13	0	0	1	1
14	0	1	0	1
15				

# N-degree 90/150 LHCA

- $C_i$  are coefficients
  - ◆ 1 = feedback exists; rule-150 cell
  - ◆ 0 = no feedback; rule-90 cell



$$F_{CA,i} = S_{i-1} \oplus C_i S_i \oplus S_{i+1}$$

# Matrix Representation (90/150 LHCA)

$$\begin{bmatrix} S_0^+ \\ S_1^+ \\ \vdots \\ S_{N-3}^+ \\ S_{N-2}^+ \\ S_{N-1}^+ \end{bmatrix} = \begin{bmatrix} C_0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & C_1 & 1 & \dots & 0 & 0 & 0 \\ \vdots & \vdots & C_2 & 1 & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & C_{n-3} & 1 & 0 \\ 0 & 0 & 0 & \dots & 1 & C_{n-2} & 1 \\ 0 & 0 & 0 & \dots & 0 & 1 & C_{n-1} \end{bmatrix} \begin{bmatrix} S_0 \\ S_1 \\ \vdots \\ S_{N-3} \\ S_{N-2} \\ S_{N-1} \end{bmatrix}$$

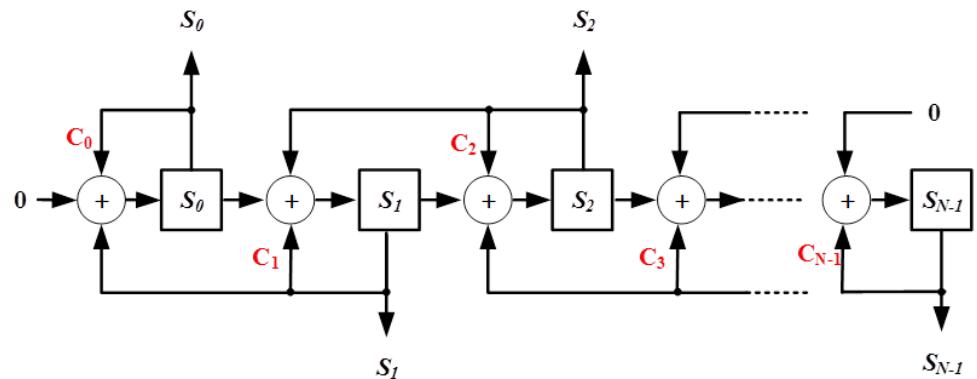
$S^+ = CS$  (mod-2 addition)

$S$  = current state

$S^+$  = next state

Characteristic polynomial:

$$f(\lambda) = \det(C - \lambda I)$$



# Quiz

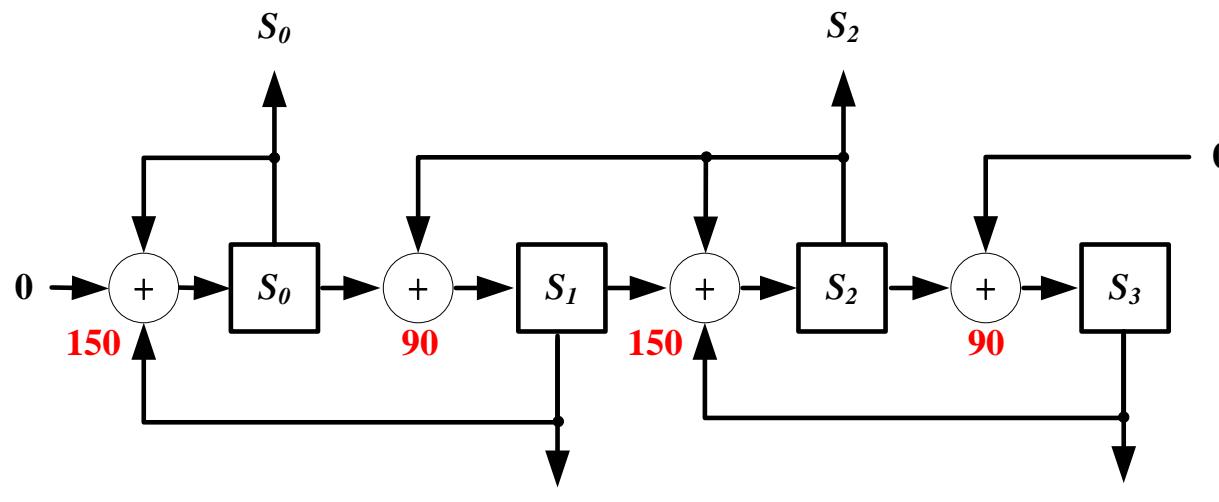
**Q1: Given this LHCA, what is matrix C ?**

**ANS:**

**Q2: What is characteristic polynomial?**

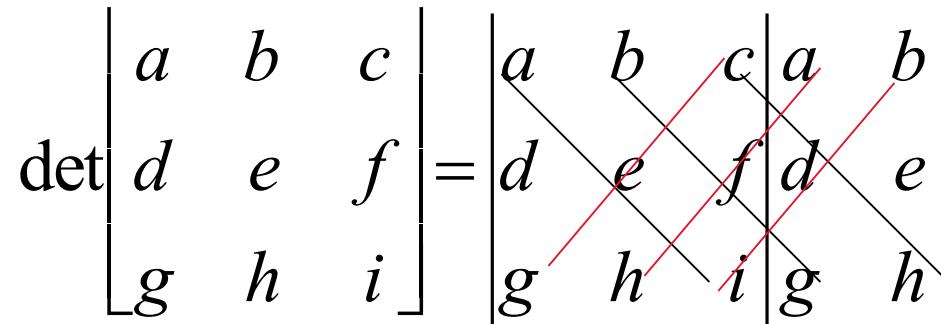
**NOTE : please use mod-2 addition**

**ANS:**



# Determinant

$$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$$

$$\det \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = \begin{vmatrix} a & b & c & a & b \\ d & e & f & d & e \\ g & h & i & g & h \end{vmatrix}$$


**Determinant =  $[aei + bfg + cdh] - [gec + hfa + idb]$**

# Determinant (column expansion)

- **Column expansion** (with respect to the  $j^{th}$  column)

$$\det(A) = |A| = \sum_{i=1}^n a_{ij} C_{ij} = a_{1j} C_{1j} + a_{2j} C_{2j} + \cdots + a_{nj} C_{nj}$$

- **Cofactor of  $a_{ij}$**  =  $C_{ij}$  =  $(-1)^{i+j} \times M_{ij}$ 
  - ◆  $M_{ij}$  is determinant of A by removing  $i^{th}$  row and  $j^{th}$  column
- Example:  $j=1$



$$\begin{aligned}\det(A) &= \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11}C_{11} + a_{21}C_{21} + a_{31}C_{31} = a_{11}(-1)^{1+1}M_{11} + a_{21}(-1)^{2+1}M_{21} + a_{31}(-1)^{3+1}M_{31} \\ &= a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{21} \begin{vmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{vmatrix} + a_{31} \begin{vmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{vmatrix}\end{aligned}$$

# Characteristic Polynomial of CA

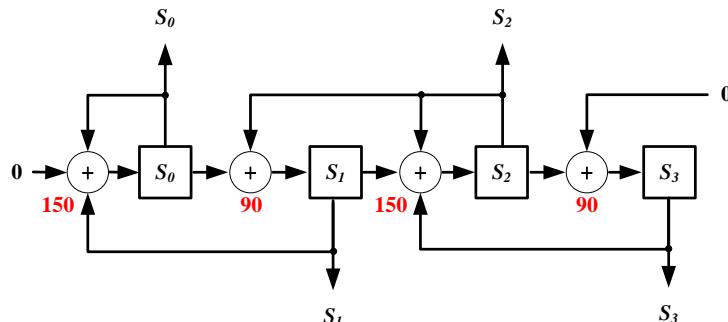
$$\det(C - \lambda I) = \det \begin{pmatrix} 1-\lambda & 1 & 0 & 0 \\ 1 & -\lambda & 1 & 0 \\ 0 & 1 & 1-\lambda & 1 \\ 0 & 0 & 1 & -\lambda \end{pmatrix}$$
$$C = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$
$$= (-1)^{1+1}(1-\lambda) \begin{vmatrix} -\lambda & 1 & 0 \\ 1 & 1-\lambda & 1 \\ 0 & 1 & -\lambda \end{vmatrix} + (-1)^{1+2}(1) \begin{vmatrix} 1 & 0 & 0 \\ 1 & 1-\lambda & 1 \\ 0 & 1 & -\lambda \end{vmatrix}$$
$$= (1-\lambda)[\lambda^2(1-\lambda) + \lambda + \lambda] + (-1)[- \lambda(1-\lambda) - 1]$$
$$= \lambda^2(1-\lambda)^2 + 2\lambda(1-\lambda) + \lambda(1-\lambda) + 1$$
$$= \lambda^4 - 2\lambda^3 - 2\lambda^2 + 3\lambda + 1$$
$$= \lambda^4 + \lambda + 1 \quad (\text{mod-2 arithmetic})$$

**This CA has a primitive polynomial**

# LFSR $\leftrightarrow$ CA \*not in exam

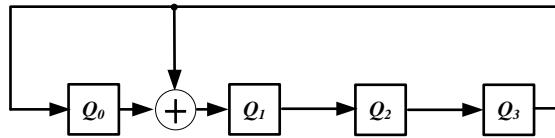
- If irreducible characteristic polynomial are equal:  $f_{CA}(x) = f_{LFSR}(x)$ 
  - ◆ Then their matrices are *similar*:  $T_{CA} \leftrightarrow T_{LFSR}$
  - ◆ i.e.  $T_{CA} = V^{-1}T_{LFSR}V$  (aka. *isomorphism transformation*)
  - ◆ [Serra 88][Bardell 90]

- Implications:
- 1. If characteristic polynomial  $f_{CA}(x)$  is primitive polynomial
  - ◆ It generates *m-sequence* of length  $2^N-1$
- 2. CA and LFSR of same polynomial generate same sequence
  - ◆ Just phase difference



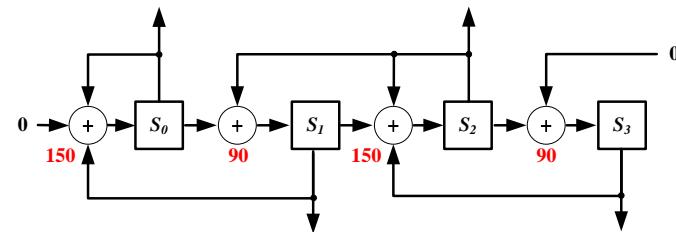
$f_{CA}(x) = x^4 + x + 1$   
is primitive polynomial  
so it generates m-sequence

# LFSR $\leftrightarrow$ CA, same $f(x)=x^4+x+1$



state	$Q_0$	$Q_1$	$Q_2$	$Q_3$
0	1	0	0	0
1	0	1	0	0
2	0	0	1	0
3	0	0	0	1
4	1	1	0	0
5	0	1	1	0
6	0	0	1	1
7	1	1	0	1
8	1	0	1	0
9	0	1	0	1
10	1	1	1	0
11	0	1	1	1
12	1	1	1	1
13	1	0	1	1
14	1	0	0	1

Phase diff.       $\leftrightarrow$       12       $\leftrightarrow$       1       $\leftrightarrow$       1



state	$S_0$	$S_1$	$S_2$	$S_3$
0	1	0	0	0
1	1	1	0	0
2	0	1	1	0
3	1	1	0	1
4	0	1	0	0
5	1	0	1	0
6	1	0	1	1
7	1	0	0	1
8	1	1	1	0
9	0	0	0	1
10	0	0	1	0
11	0	1	1	1
12	1	1	1	1
13	0	0	1	1
14	0	1	0	1

Phase diff.       $\leftrightarrow$       11       $\leftrightarrow$       9       $\leftrightarrow$       1

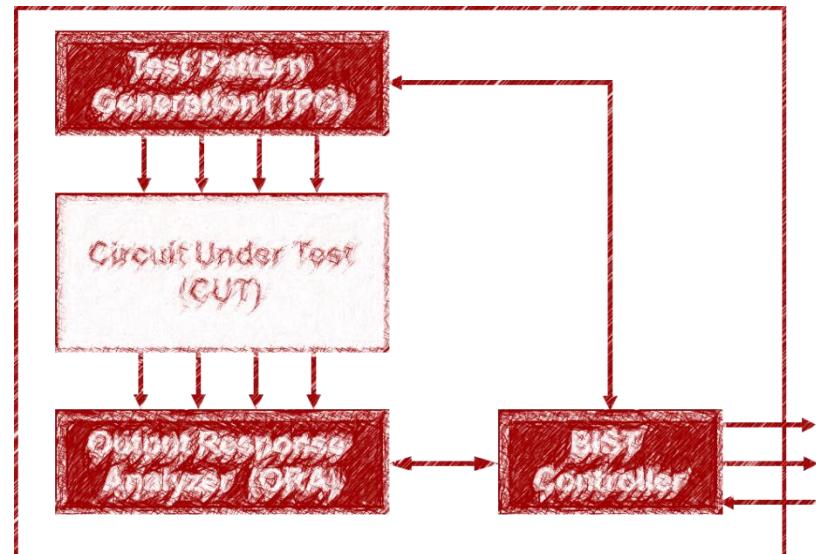
# Pros and Cons of CA

- Advantages of CA (over LFSR)
  - + More randomness than LFSR
    - ⇒ Large phase shift
  - + Potentially faster than LFSR
    - ⇒ short feedback loop
  - + Small XOR
    - ⇒ no more than 3-input XOR
- Disadvantages of CA (over LFSR)
  - No easy design methodology
    - ⇒ No good method to construct LHCA from polynomial



# Summary - CA

- CA are named by its **function**
- **90/150 LHCA** very popular
- Polynomial of CA is  $f(\lambda) = \det(C - \lambda I)$
- CA are good but hard to design



# Reference

- **(BMS 87) P.H. Bardell, W.H. McAnney, J. Savior, *Built-in Test for VLSI: Pseudorandom Techniques*, Wiley Interscience, 1987.**
- **[Könemann 91] B Könemann, “LFSR-coded test patterns for scan designs,” European Test Conference, 1991**