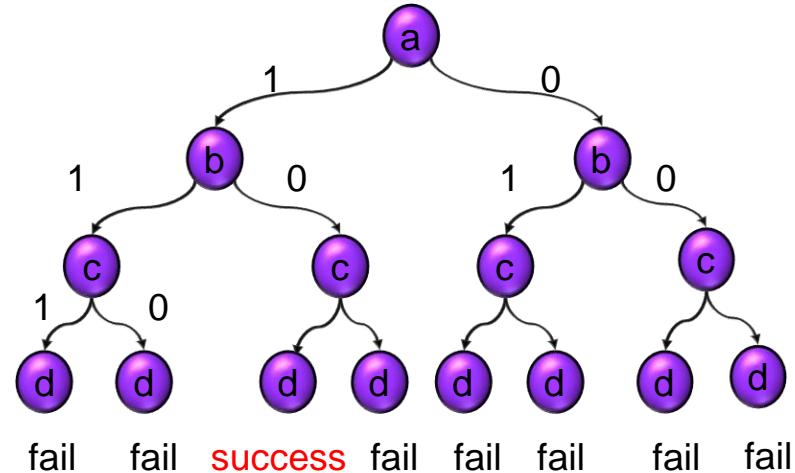


Combinational ATPG

- Introduction
- Deterministic Test Pattern Generation
 - ◆ Boolean difference approach*
 - ◆ Path sensitization method**
 - ◆ D-Algorithm [Roth 1966] **
 - ◆ PODEM [Goel 1981] **
 - ◆ FAN [Fujiwara 1983]**
 - ◆ SAT-based [Larrabee 1992] *
- Acceleration Techniques
- Concluding Remarks

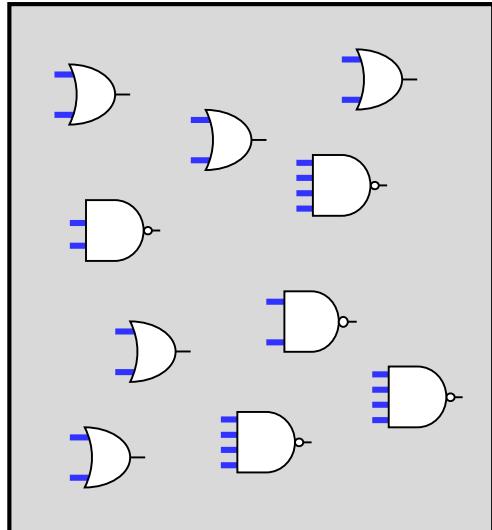
*Boolean-based methods

**path-based methods

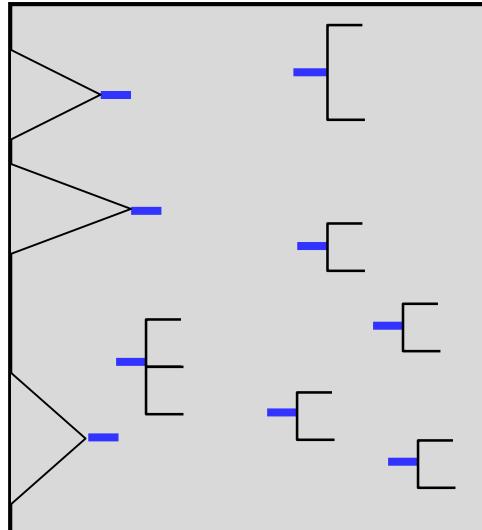


D→PODEM →FAN

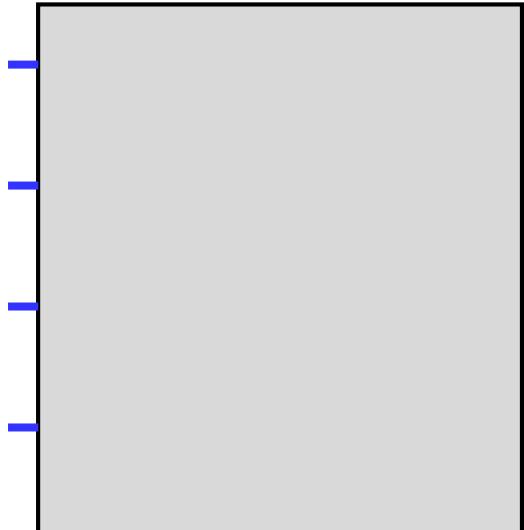
- D-algorithm decision at **internal nodes** → too many decisions, slow!
- PODEM decision at **PI** → too little information, mistake-prone!
- FAN decision at **head lines** and **fanout stems** → good trade-off



D-alg.
too many decisions



FAN
good trade-off



PODEM
too little information

— decision points

FAN [Fujiwara 1983]

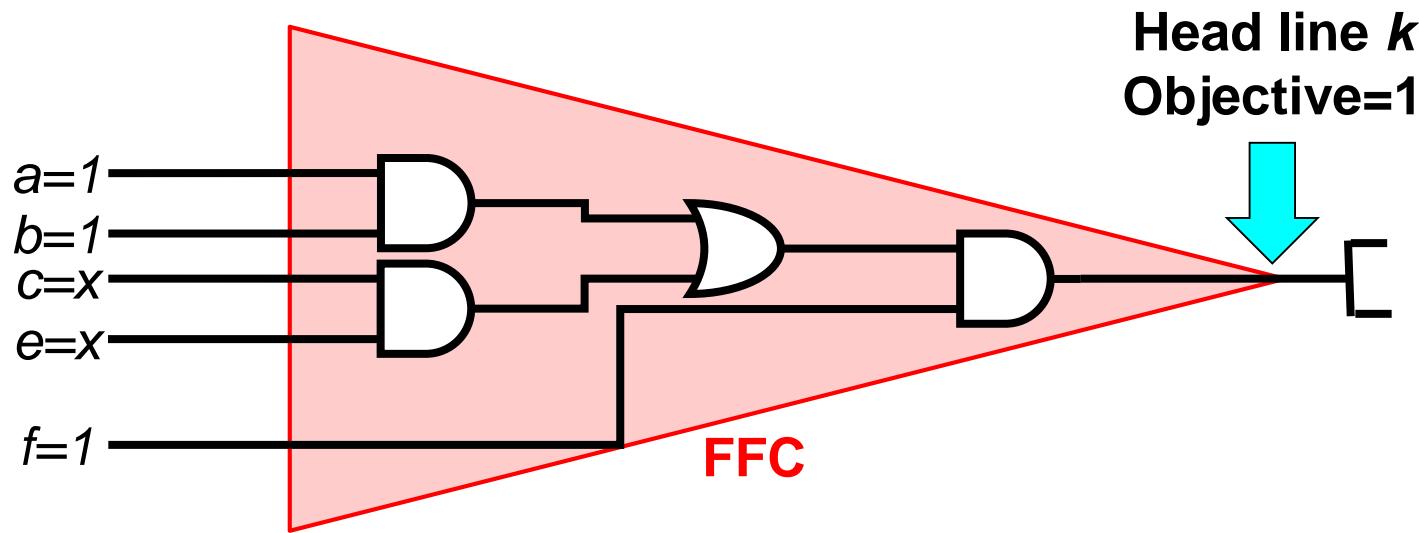
- ***FANout-oriented test generation***
- Four improvements over PODEM
 - ◆ #1. Make decision at head lines or fanout stem
 - ◆ #2. Forward/backward Implications
 - ◆ #3. Unique sensitization
 - ◆ #4. Multiple backtraces



<https://insights.ubuntu.com>

Justify Head Line Is Easy

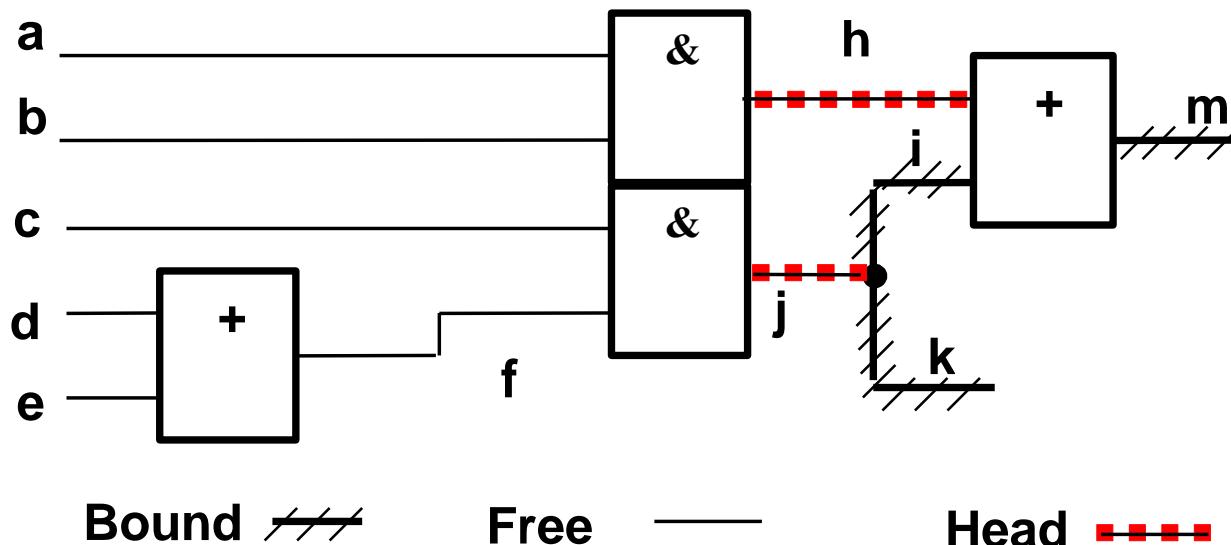
- Justification inside FFC (*fanout-free cone*) is linear time
 - ◆ Guaranteed to find an answer
- Example: a,b,c,e,f are PI, k is *head line*
 - ◆ objective $k=1$



Can Make Decision at Head Line
Instead of PI

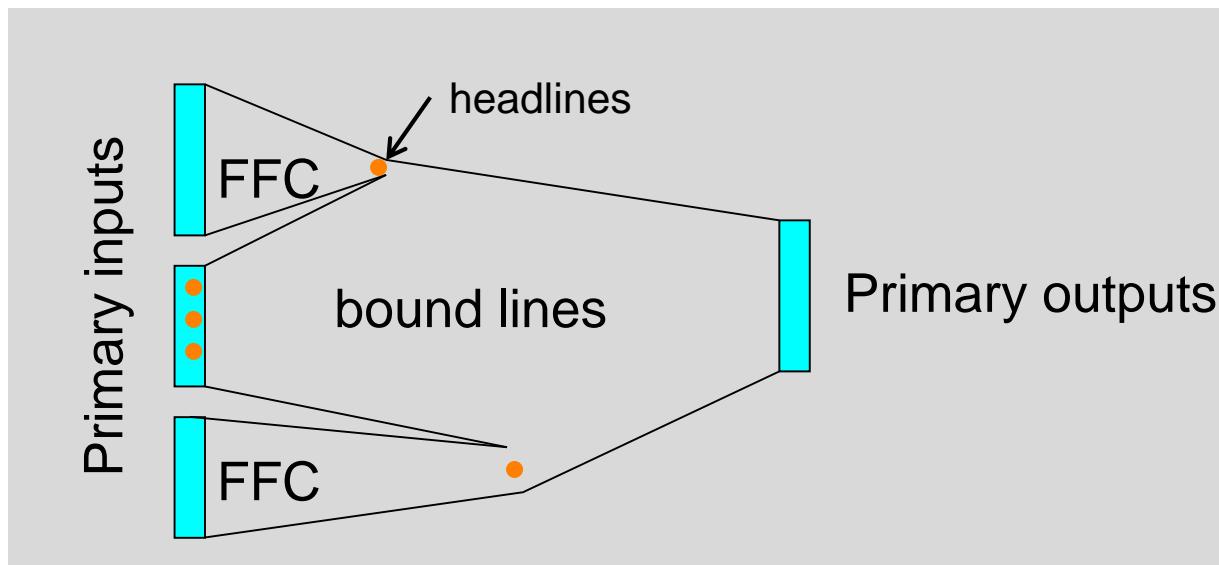
Head Line

- **Bound line:** line fed directly (*i*, *k*) or indirectly (*m*) by fanout stem
- **Free Line:** line that is not Bound (*a~f, h, j*)
- **Head Line:** free line that is either
 - ♦ Fanout stem (*j*), or
 - ♦ Input to a gate with bound output (*h*)



#1. Make Decision at Head Lines

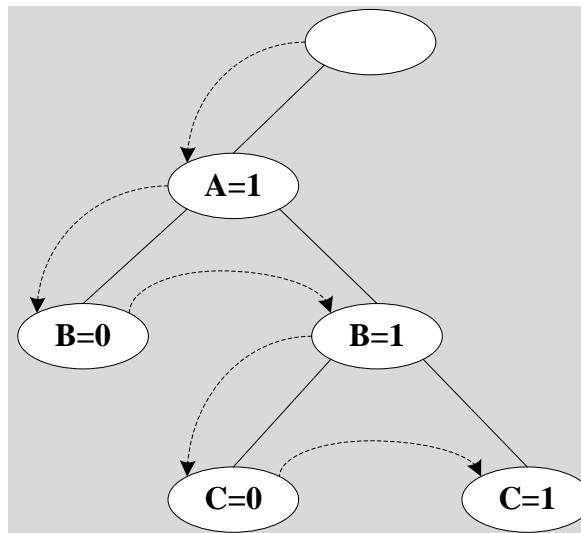
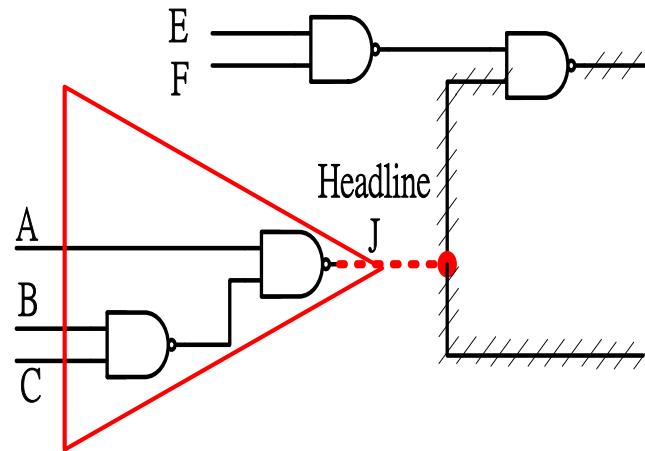
- FFC can be isolated from rest of circuit by cutting head lines
- Assignment of PI's that feed head lines are
 - ◆ deferred until other objectives have been achieved
 - * Reduce search space



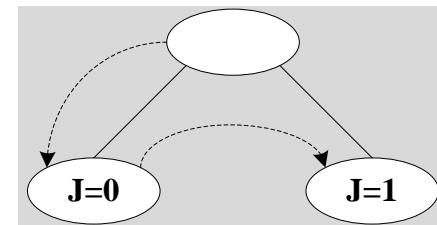
Head Lines Reduces Search Space

Example

- PODEM decision tree is **big**
 - ◆ A=1, B=0
 - * No test, backtrack
 - ◆ B=1, C=0
 - * No test, backtrack
 - ◆ C=1
- FAN decision tree is **small**
 - ◆ J=0
 - * No test, backtrack
 - ◆ J=1



PODEM

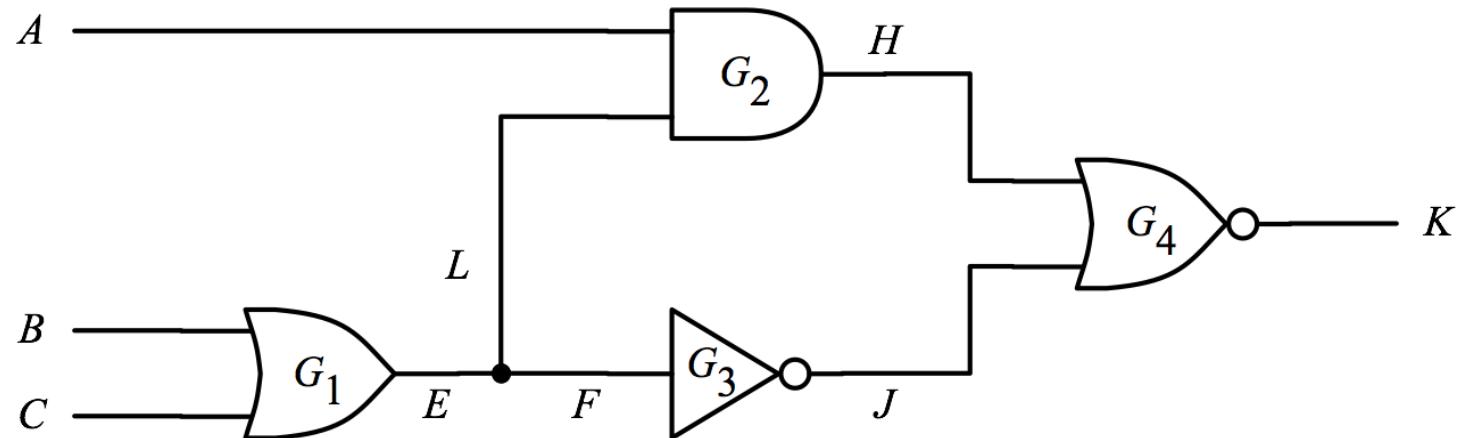


FAN

Quiz

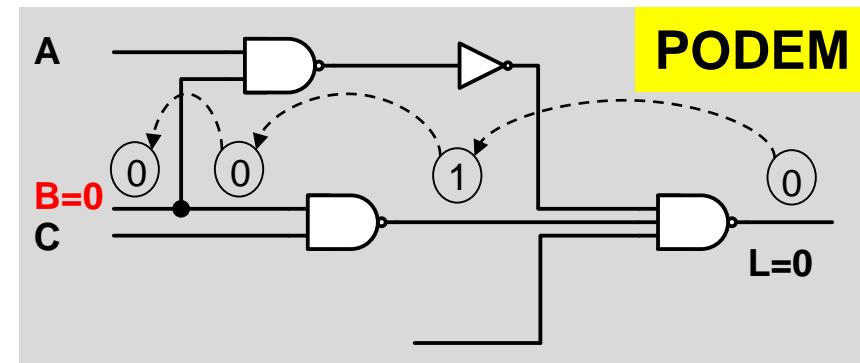
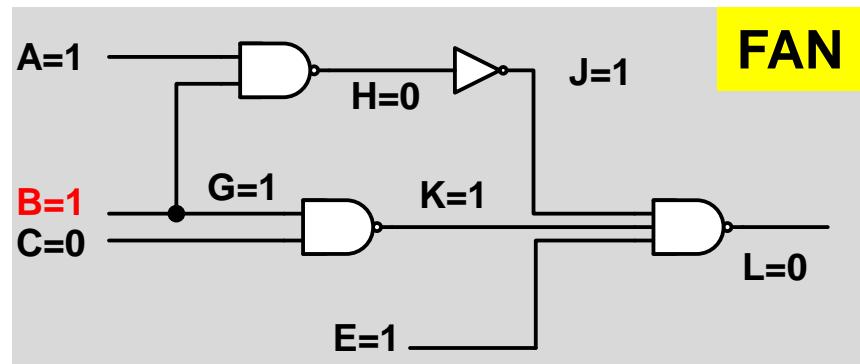
Q: Which are bound lines? free lines? head lines?

A:

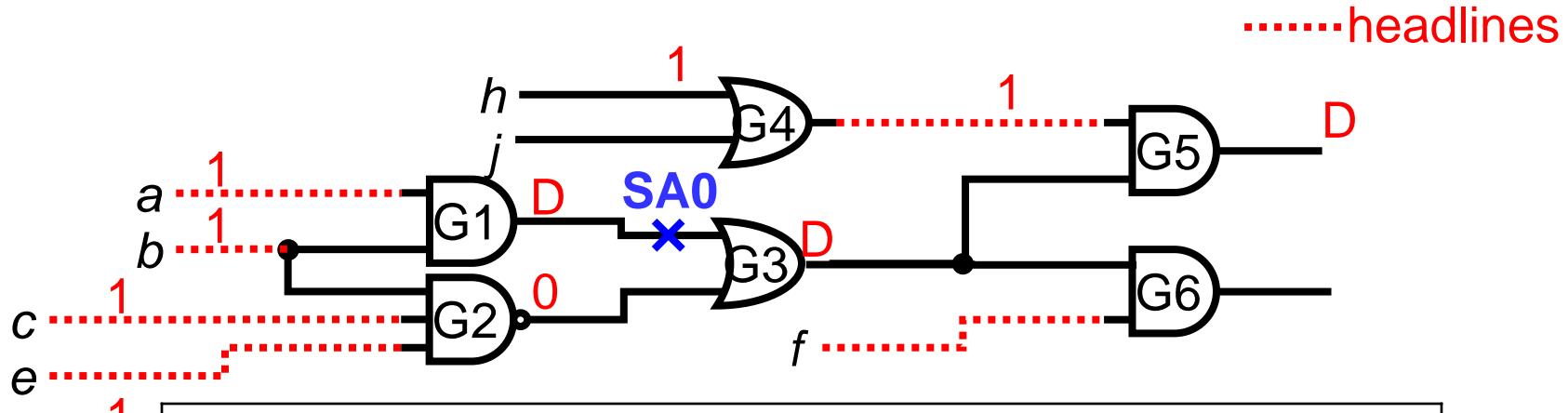


#2. Forward/backward Implication

- PODEM does not assign internal values
 - ◆ Only forward implication, no backward implication
- FAN assigns internal values when they are uniquely implied
 - ◆ Both forward and backward implication
- Example: L SA1 fault
- FAN
 - ◆ Bwd: $JKE=1, H=0, A=1, B=1$
 - ◆ Fwd: $G=1$
 - ◆ Bwd: $K=1, C=0$
 - ◆ no backtrack needed
- PODEM
 - ◆ Backtrace to $B=0$
 - ◆ Forward implication
 - ◆ Wrong! backtrack



FAN Example

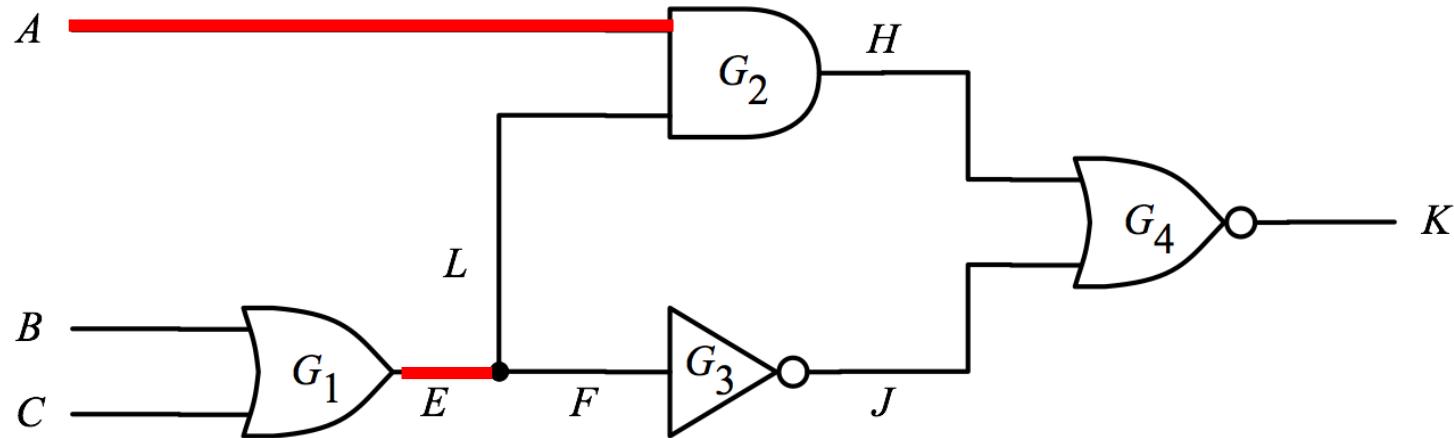


1	Headlines: a b c e f G4 (dashed lines)
	Initial objective: G1 output =1
	Implication: assign a = 1; b=1
	Objective: propagate through G3, objective G2=0
	Implication: assign c = 1; e=1
	Propagate through G5, objective G4=1
	Assign headline G4 = 1
	G5=D, Objective achieved.
	Justify head line G4 = 1 → h=1
	Test generated abcehfj = 11111xx
	Justify head lines at end

Quiz

Q: If we want $K=1$, apply implication to determine head lines
 $A=? E=?$

ANS:



FAN

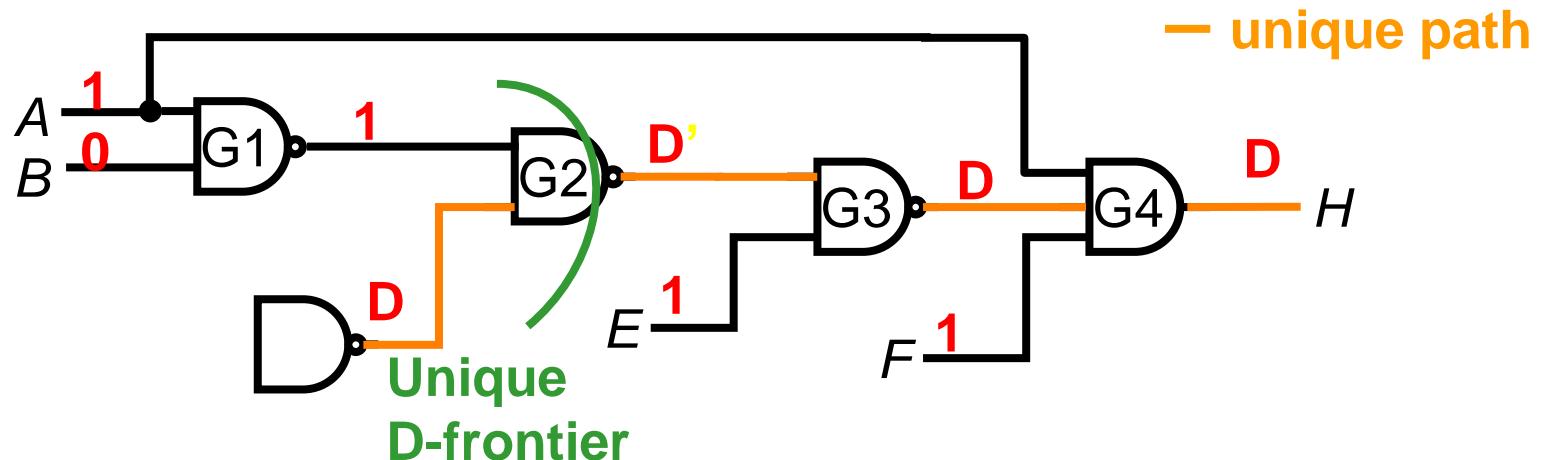
- **Four improvements over PODEM**
 - ◆ #1. Make decision at head lines or fanout stem
 - ◆ #2. Forward/backward Implications
 - ◆ #3. Unique sensitization
 - ◆ #4. Multiple backtraces



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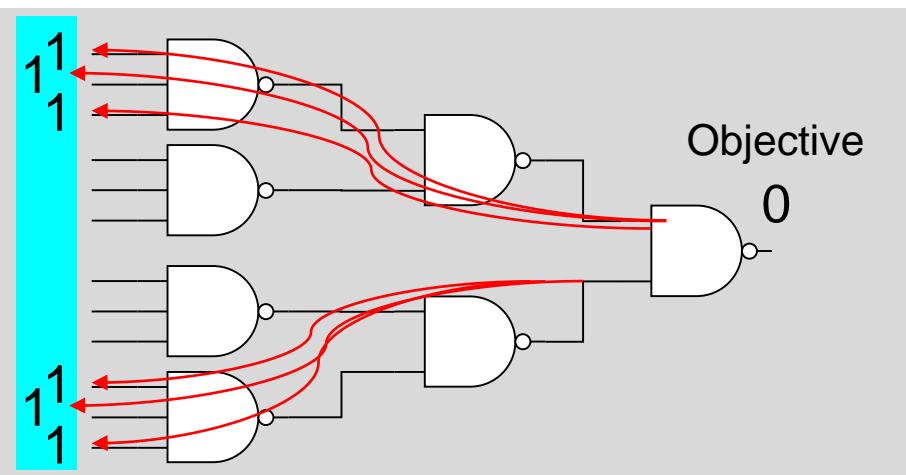
#3. Unique Sensitization

- When there is **only one gate** in D-frontier
 - ◆ if unique path exists, set side inputs to non-controlling values
- Example:
 - ◆ FAN
 - * **G2** is unique D-frontier, only one path to **H**
 - * $G1 = 1, E = 1, F = 1, A = 1 \rightarrow B = 0 \rightarrow \text{success!}$
 - ◆ PODEM
 - * Initial objective: $G1 = 1 \rightarrow$
 - * backtrace to $A = 0 \rightarrow$ X-path disappear!

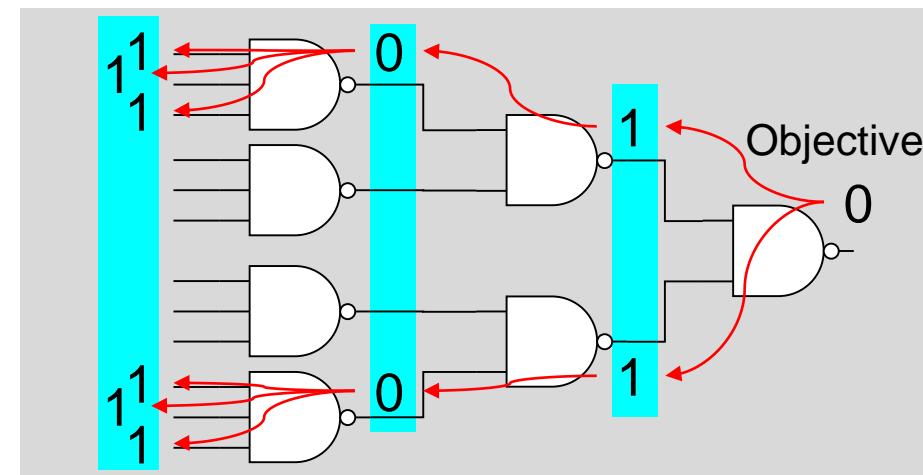


#4. Multiple Backtraces

- PODEM uses **depth-first search (DFS)**
 - ◆ One single backtrace at a time
- FAN uses **breadth first search (BFS)**
 - ◆ Multiple parallel search at a time
- Example
 - ◆ PODEM needs **6 backtraces**
 - ◆ FAN needs only **1 multiple backtrace**



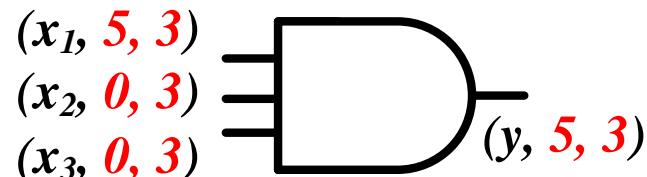
PODEM



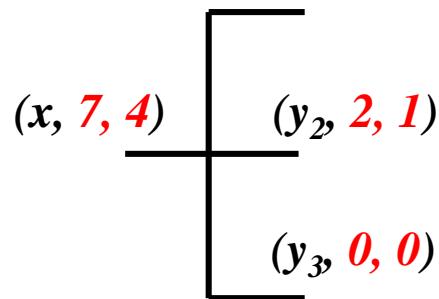
FAN

Rules for Multiple Backtraces

- **Objective:** (x, n_0, n_1)
 - ◆ number of backtraced zeros (n_0) and ones (n_1) on signal x
- **For AND gate**
 - ◆ Easiest unspecified input x_1
 - * $(x_1, n_0, n_1) = (y, n_0, n_1)$
 - ◆ Other inputs x_2, x_3
 - * $(x_2, n_0) = 0$
 - * $(x_2, n_1) = (y, n_1)$
- **For fanout Stem**
 - * $(x, n_0) = \text{sum of } (y_i, n_0)$
 - * $(x, n_1) = \text{sum of } (y_i, n_1)$

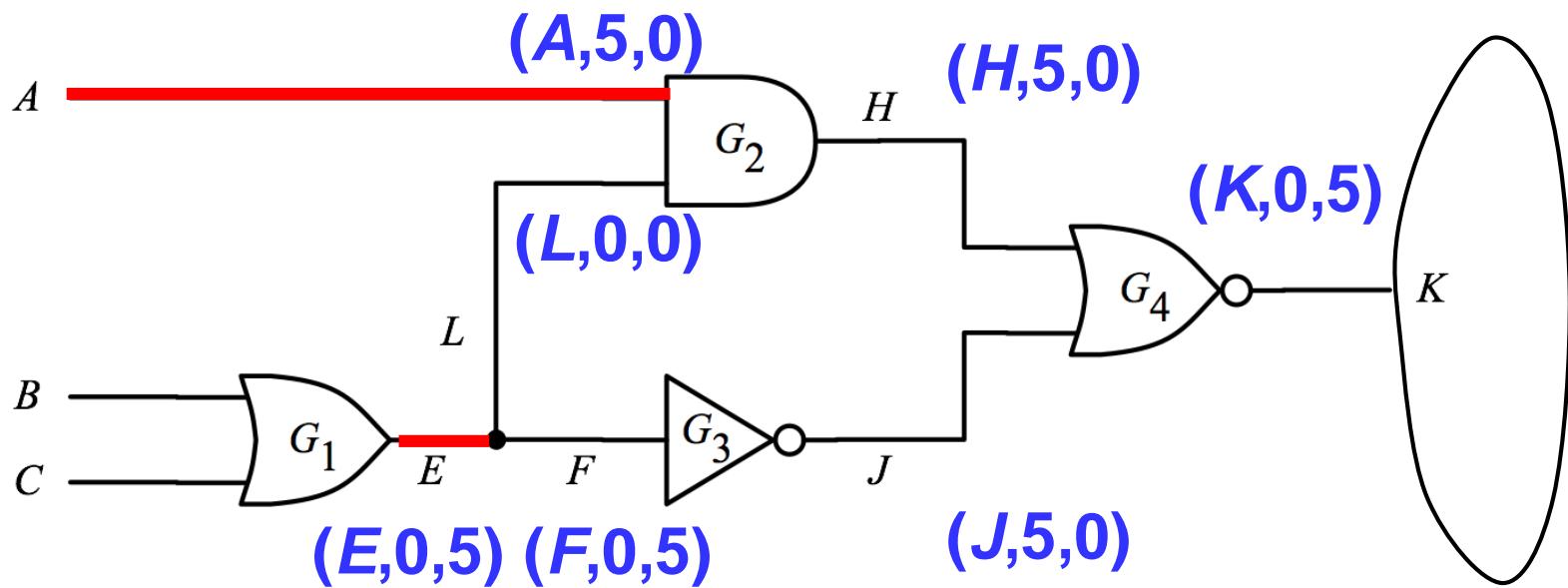


$(y_1, 5, 3)$



Example

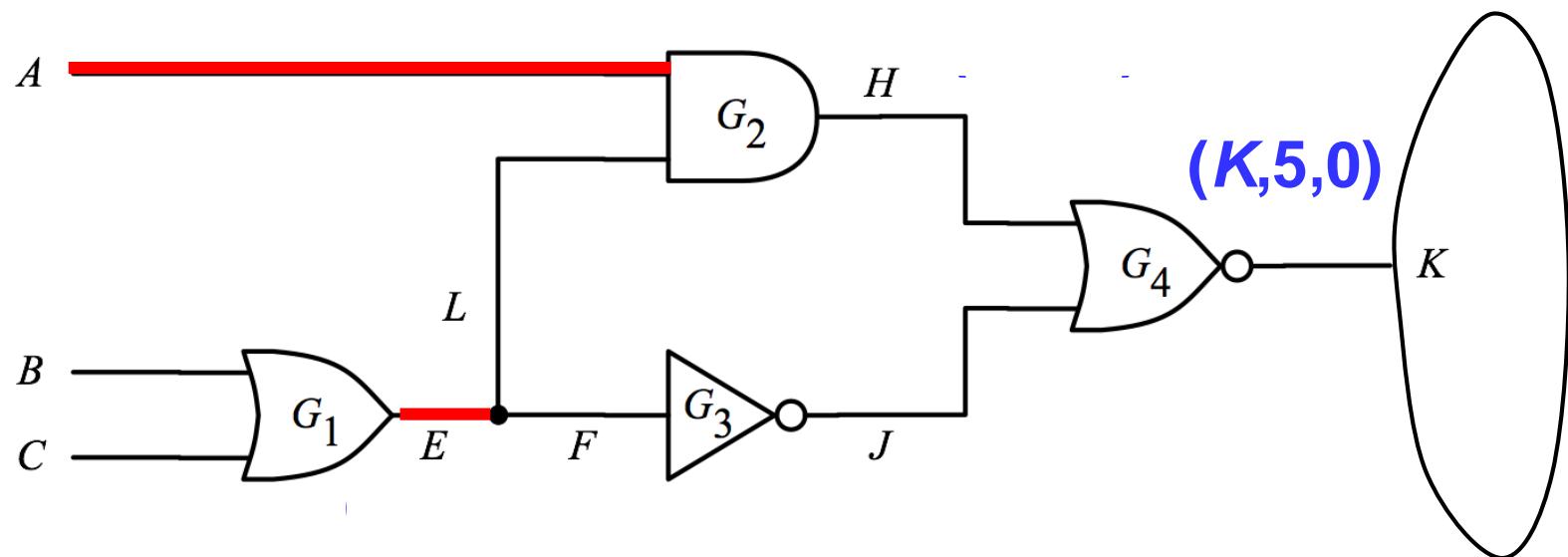
- Starting from $(K,0,5)$, multiple backtrace to head lines A and E
 - So we get two assignments $A=0, E=1$



Quiz

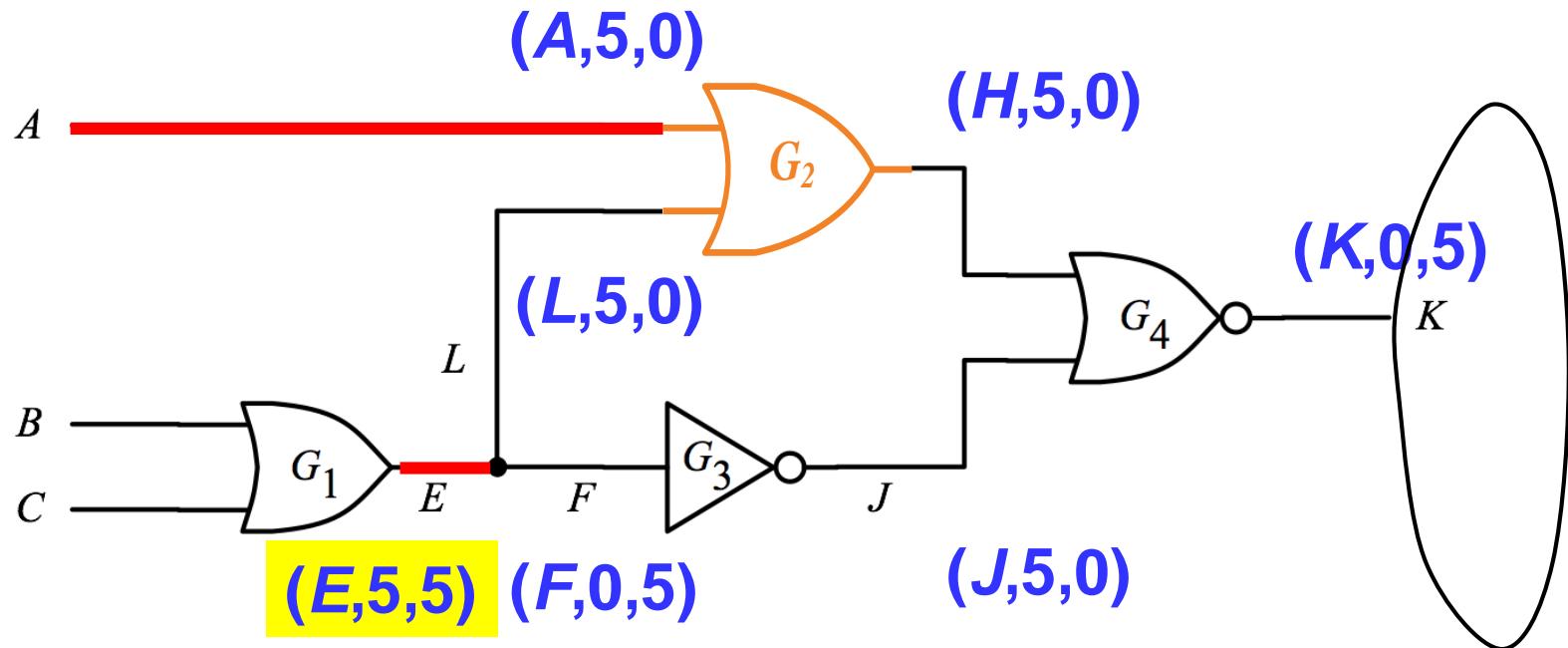
Q: Starting from $(K, 5, 0)$, multiple backtrace to head lines
 $(E, n_0, n_1) = ?$ $(A, n_0, n_1) = ?$ Suppose H is chosen over J

A:



Multiple Backtrace Conflict

- What if change G_2 to OR gate?
- Want $K=1$, perform multiple backtrace to headlines A and E
 - ◆ conflicting values at E !



- How to handle a conflict ?
 - ◆ assign a value **most requested**, then start next backtrace
 - ◆ will backtrack if it is wrong

Multiple Backtrace (1/2)

```
MultipleBacktrace (Initial_objectives, Fanout_objectives) {  
    Current_objectives = Initial_objectives  
    while (Current_objectives ≠ φ or Fanout_objectives ≠ φ) {  
        dequeue entry (k, vk) from Current or Fanout_objectives  
        switch (type of entry) { // (k, vk) = want vk on signal k  
            1. HEAD_LINE:  
                add (k, vk) to Headline_objectives  
            2. FANOUT_BRANCH:  
                j = stem(k);  
                increment n0 or n1 at j for vk; //sum of n0, n1  
                add j to Fanout_objectives  
            3. GATE: //page 15  
                i = inversion of k; c = controlling value of k;  
                if ((vk ⊕ i) == c) {  
                    select easiest input j with unknown value  
                    add( j, c) to Current_objectives;  
                }  
                else {  
                    for every input j of k with value  
                    add(j, c') to Current_objectives;  
                }  
        } // switch
```

Multiple Backtrace (2/2)

(cont'd from previous page)

*simplified from Fig. 8 of FAN paper

```
if(Fanout_objectives ≠ φ) {  
    dequeue highest-level stem (k) from Fanout_Objectives  
    vk = 0 or 1, depends on which of (n0, n1) is larger  
    if there is no conflict on k {  
        add (k, vk) to Current_objectives // continue backtrace  
        else { return (k, vk) as the Final_objective} } // stop backtrace  
    else { // no fanout objective  
        dequeue (k, vk) from Headline_objectives  
        return (k, vk) as the Final_objective }  
    } // while  
} // MultipleBacktrace
```

MultipleBacktrace

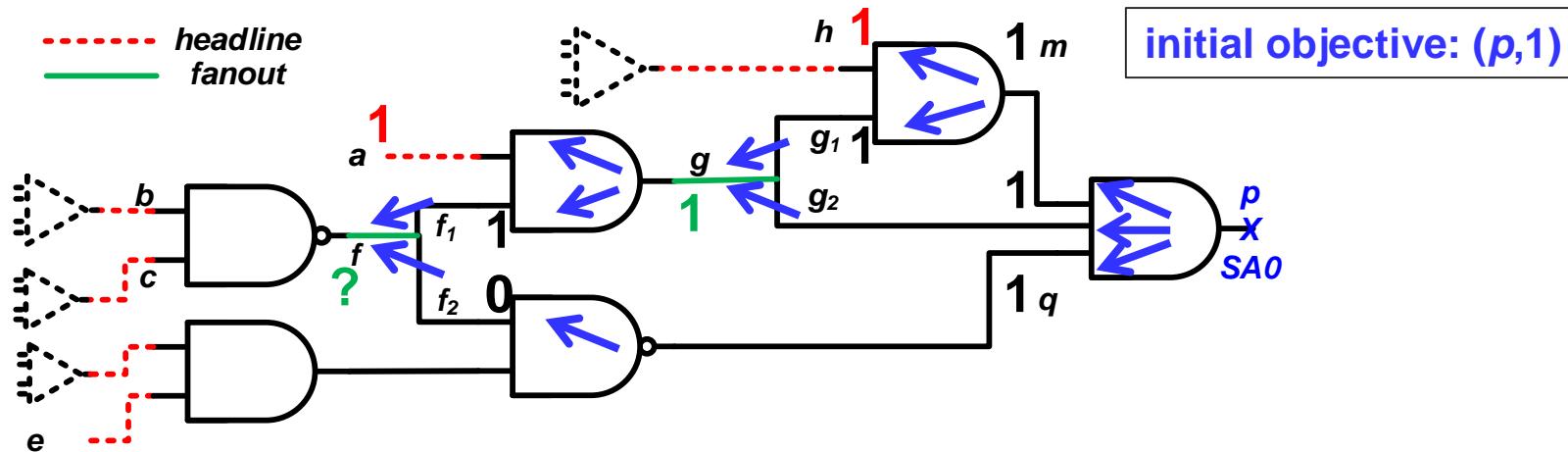
final_objective

(either a fanout or a headline)



initial_objectives
fanout_objectives

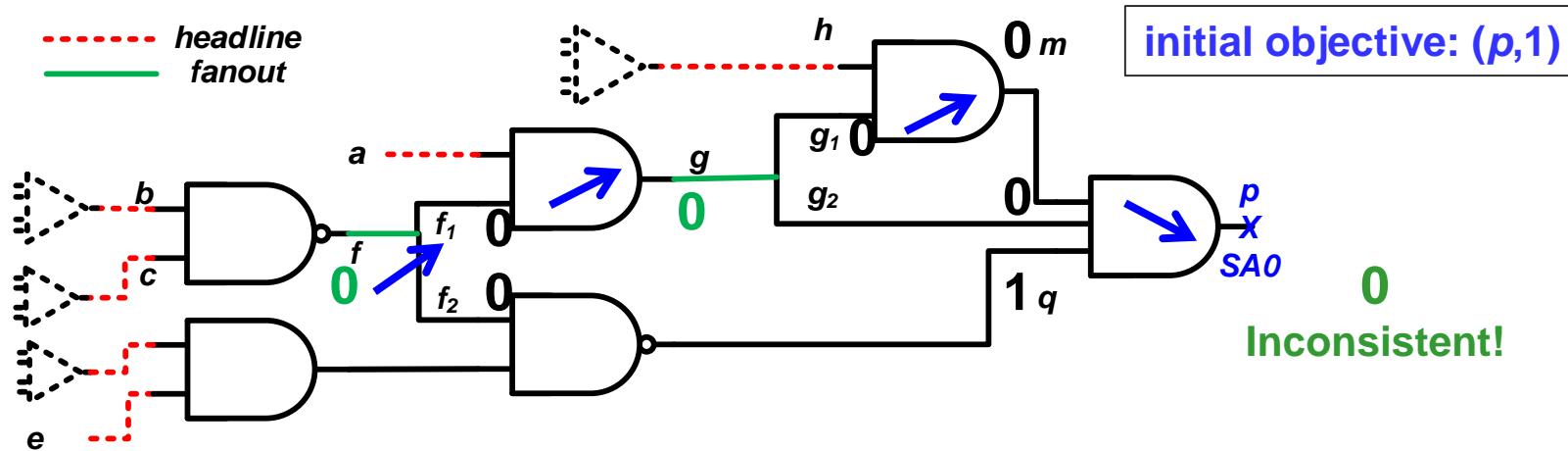
Multiple Backtrace Example (1/3)



Current Obj.	processed entry	Fanout Obj.	Headline Obj.
$(m, 1)(g_2, 1)(q, 1)$	$(m, 1)$	-	$(h, 1)$
$(g_2, 1)(q, 1)(g_1, 1)$	$(g_2, 1)$	$(g, n_f=1)$	$(h, 1)$
$(q, 1)(g_1, 1)$	$(q, 1)$	$(g, n_f=1)$	$(h, 1)$
$(g_1, 1)(f_2, 0)$	$(g_1, 1)$	$(g, n_f=2)$	$(h, 1)$
$(f_2, 0)$	$(f_2, 0)$	$(g, n_f=2) (f, n_o=1)$	$(h, 1)$
-	$(g, 1)$ consistent	$(f, n_o=1)$	$(h, 1)$
$(g, 1)$	$(g, 1)$	$(f, n_o=1)$	$(h, 1)(a, 1)$
$(f_1, 1)$	$(f_1, 1)$	$(f, n_o=1 n_f=1)$	$(h, 1)(a, 1)$
-	f conflict!	-	$(h, 1)(a, 1)$

Final Objective: $f=?$

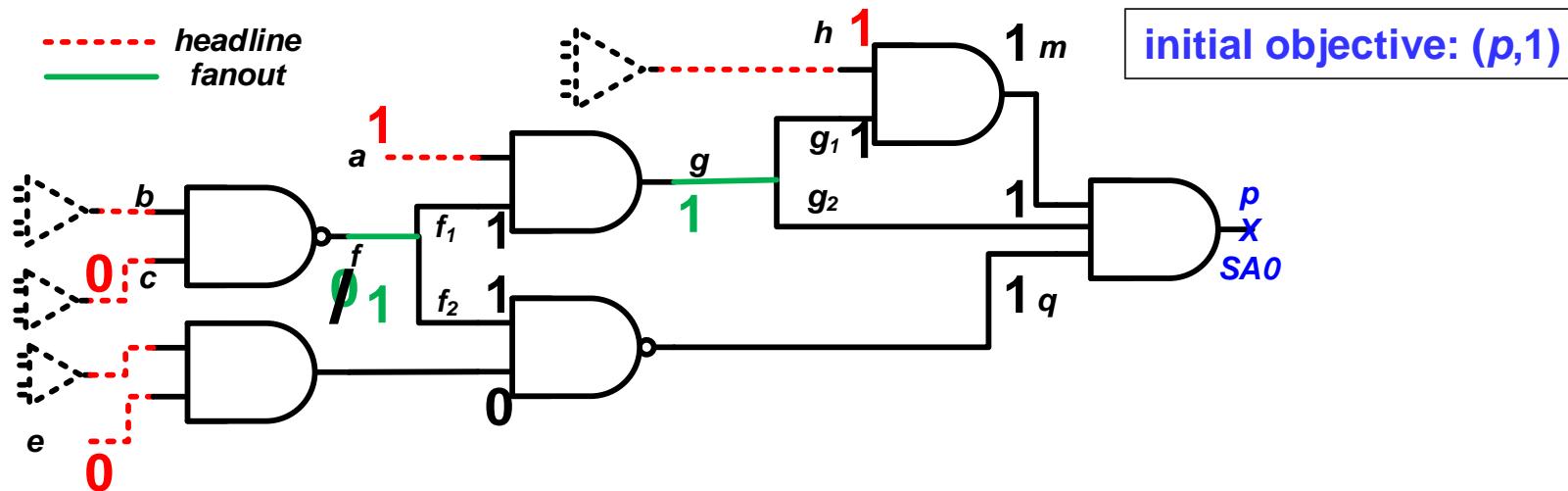
Multiple Backtrace Example (2/3)



because $n_0=n_1=1$, just choose randomly
suppose we assign $f=0$
forward implication
inconsistent with initial objectives!
backtrack to $f=1$

**Decision at Fanout Stem
Detects Inconsistency Earlier**

Multiple Backtrace Example (3/3)



Assign $f=1$

Forward implication, consistent.
Multiple_Backtrace again

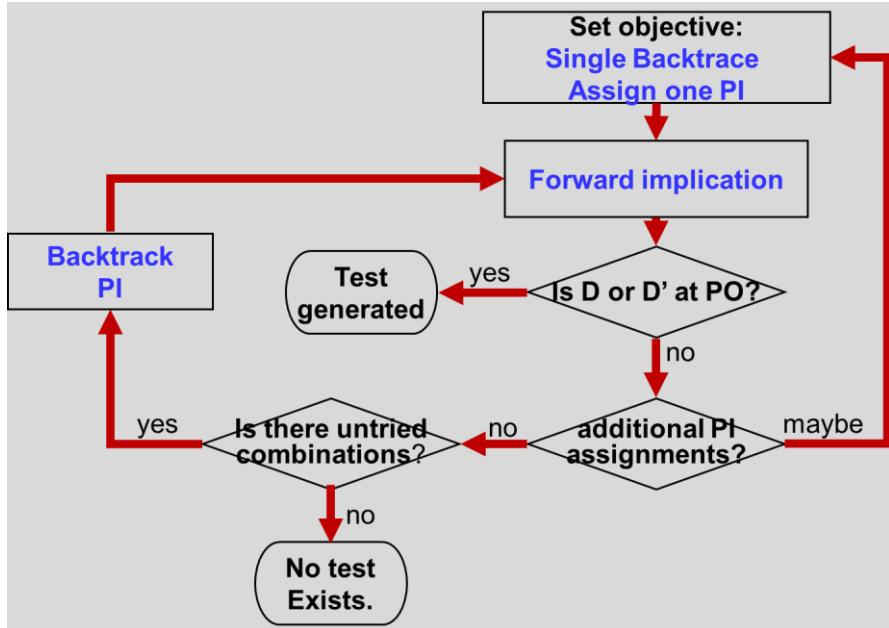
This time, headline objectives: $h=1, a=1, e=0, c=0$

Forward implication
Initial objective achieved!

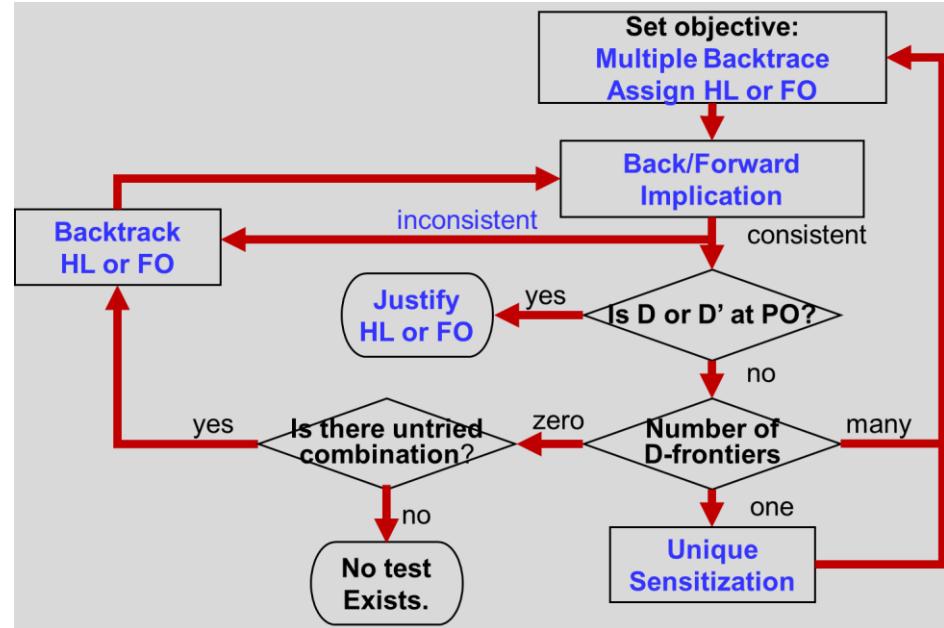
Multiple Backtrace is Fast

PODEM v.s. FAN

PODEM



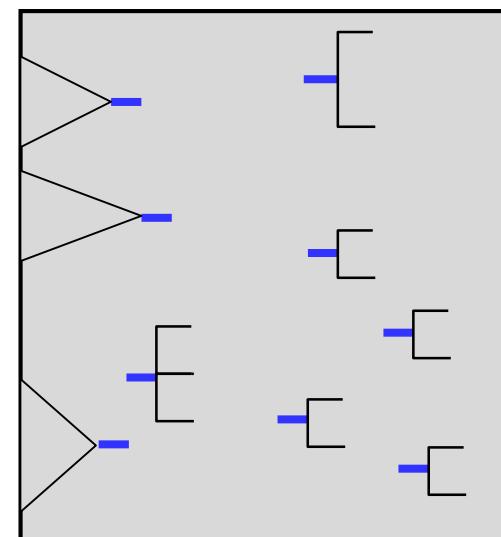
FAN



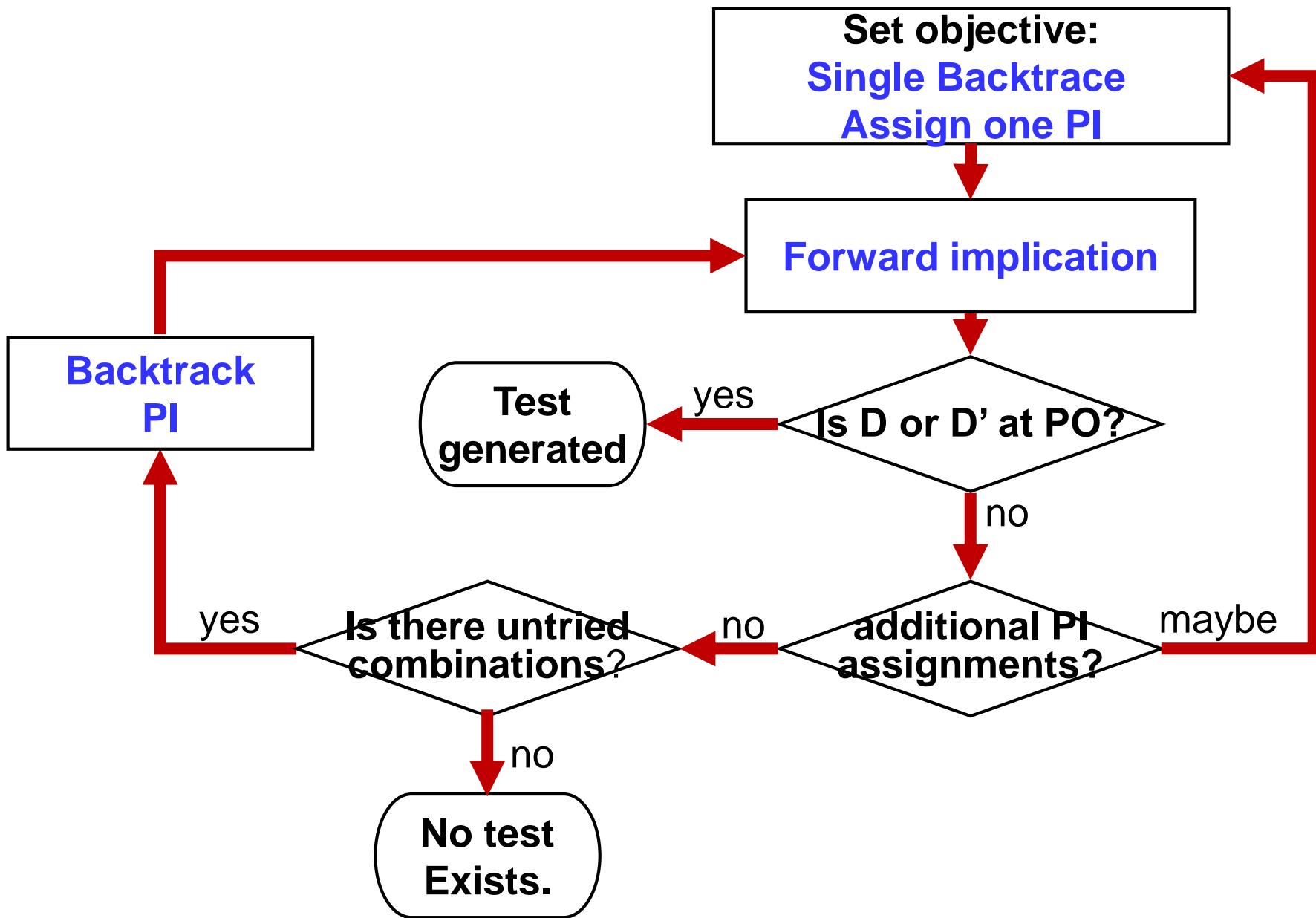
Difference highlighted in **Blue**

Summary

- 1. Make decision at **head lines** and **fanout stem**
 - ◆ Reduce search space
- 2. Forward/backward Implications
 - ◆ More information to make correct decision
- 3. Unique sensitization
 - ◆ Unique path to output
- 4. Multiple backtraces
 - ◆ BFS to search many paths together



Flowchart of PODEM



Flowchart of FAN

*simplified from Fig. 9 of FAN paper

