

Part IB NST Mathematics Tripos Suggested Solutions

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Foreword. *Many thanks to my supervisor Robert Dillion for his guidance and suggested solutions. Email (crsid: ytt26) me if there are any mistakes.*

1 2010

1.1 Paper 1

Problem 1.1 (Vector Calculus):

- (a) Using Cartesian coordinates, show that

$$(\mathbf{u} \cdot \nabla)\mathbf{u} = \frac{1}{2}\nabla(\mathbf{u} \cdot \mathbf{u}) - \mathbf{u} \times (\nabla \times \mathbf{u})$$

and hence that

$$\nabla \times (\mathbf{u} \cdot \nabla)\mathbf{u} = (\nabla \cdot \mathbf{u})(\nabla \times \mathbf{u}) + (\mathbf{u} \cdot \nabla)(\nabla \times \mathbf{u}) - ((\nabla \times \mathbf{u}) \cdot \nabla)\mathbf{u}$$

[8]

- (b) Consider a vector field $\mathbf{v}(x, y, z)$, which may be expressed in Cartesian coordinates as

$$\mathbf{v} = \left(\frac{-\kappa y}{2\pi(x^2 + y^2)}, \frac{\kappa x}{2\pi(x^2 + y^2)}, 0 \right)$$

- (i) Show that $\nabla \times \mathbf{v} = \mathbf{0}$ everywhere except at the line $x = 0, y = 0$.

[6]

- (ii) Show that the line integral

$$\oint_C \mathbf{v} \cdot d\mathbf{r} = 0 \quad (*)$$

$\forall C = \partial S$ in the x, y plane which bound open surfaces S (also in x, y plane) which do not intersect the line $x = y = 0$. What is the value of the integral (*) if the curve bounds such a surface which **does** intersect this line?

[You may find it useful to use cylindrical polar coordinates.]

[6]

Answer 1.1.

- (a) Using suffix notation, the k th component of $\mathbf{u} \times (\nabla \times \mathbf{u})$ is

$$\epsilon_{ijk}u_i\epsilon_{pqj}\frac{\partial}{\partial x_p}u_q = u_i\frac{\partial}{\partial x_k}u_i - u_i\frac{\partial}{\partial x_i}u_k = \frac{1}{2}\frac{\partial}{\partial x_k}(u_iu_i) - u_i\frac{\partial}{\partial x_i}u_k \quad (*)$$

The desired result follows by rearranging the terms. Substitute $\mathbf{v} = \nabla \times \mathbf{u}$, and take the curl of the LHS of (*). Since the curl of a gradient is zero, we have

$$-\epsilon_{ijk}\frac{\partial}{\partial x_i}\epsilon_{pqj}u_p v_q = \frac{\partial}{\partial x_i}(u_i v_k) - \frac{\partial}{\partial x_i}(u_k v_i) = u_i\frac{\partial v_k}{\partial x_i} + v_k\frac{\partial u_i}{\partial x_i} - u_k\frac{\partial v_i}{\partial x_i} - v_i\frac{\partial u_k}{\partial x_i}$$

We have the divergence of a curl to be zero and so $\mathbf{u}(\nabla \cdot \mathbf{v}) = 0$. The result follows.

- (b) (i) Observe that the only component of $\nabla \times \mathbf{v}$ needed to be evaluated is the z component

$$(\nabla \times \mathbf{v}) \cdot \hat{\mathbf{z}} = \frac{1}{x^2 + y^2} - \frac{2x^2}{(x^2 + y^2)^2} + \frac{1}{x^2 + y^2} - \frac{2y^2}{(x^2 + y^2)^2}$$

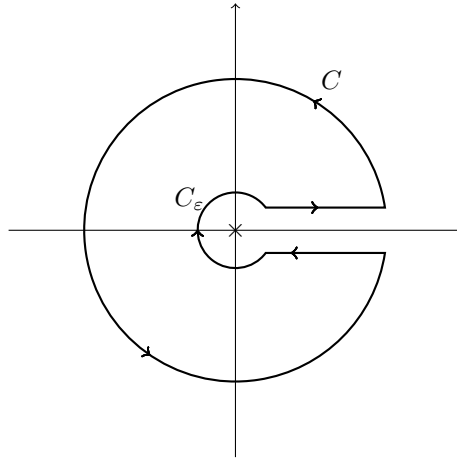
which gives 0 except when $x = 0$ and $y = 0$, since the expression $\infty - \infty$ is not defined.

- (ii) Using Stokes' Theorem, we have

$$\int_{\partial S} \mathbf{v} \cdot d\mathbf{r} = \int_S (\nabla \times \mathbf{v}) \cdot d\mathbf{S}$$

where S is an orientable surface and ∂S is a closed, rectifiable non-intersecting curve bounding S . $d\mathbf{S}$ is traversed in the same sense as ∂S , and \mathbf{v} is any differentiable vector function of position defined everywhere on S . In our case, if $\nabla \times \mathbf{v} = 0$ is true everywhere in S (as long as S does not intersect the z -axis), then the closed loop integral must be zero.

To 'avoid' the z axis, we integrate along a circular curve C_ϵ of constant arbitrary radius ϵ (with opposite fashion) centred at the origin in the x - y plane. Let the original closed loop be a circle C of radius a . Then, $C' = C \cup C_\epsilon$, as well as, two additional lines (say both along $y = 0$) together is called the keyhole contour. The resulting keyhole contour is the boundary of a closed surface that does not intersect the z -axis.



Now suppose the surface does intersect the z -axis, then the closed loop integral would be

$$\oint_{C'} \mathbf{v} \cdot d\mathbf{r} = \int_0^{2\pi} \mathbf{v} \cdot \frac{d\mathbf{r}}{d\theta} d\theta = \frac{\kappa}{2\pi} \oint \frac{xdy - ydx}{x^2 + y^2} = \frac{\kappa}{2\pi} \int_0^{2\pi} d\theta = \kappa$$

Physically, one can imagine the z -axis to be a source of strength κ , i.e. similar to Ampere's Law in magnetostatics.

Problem 1.2 (Partial Differential Equation):

- (a) Consider diffusion inside a circular tube with very small cross-section and circumference 2π . Let x denote the arc-length parameter $-\pi \leq x \leq \pi$, so that the density of the diffusing substance u satisfies (for $t > 0$)

$$\frac{\partial u}{\partial t} = \lambda \frac{\partial^2 u}{\partial x^2}$$

with specified initial conditions $u(x, 0) = f(x)$ for some function $f(x)$. What are the appropriate boundary conditions to impose on u at $x = \pm\pi$ for $t > 0$? [3]

- (b) Use separation of variables to express $u(x, t)$ in terms of an appropriate infinite series. [7]

- (c) Compute explicitly the coefficients of the above series in the case that $f(x) = (\pi - |x|)^2$ and identify the density distribution of the substance u as $t \rightarrow \infty$. [10]

Answer 1.2.

- (a) We integrate the PDE over an infinitesimal region of x ,

$$\lim_{\epsilon \rightarrow 0} \lambda \int_{x-\epsilon}^{x+\epsilon} \frac{\partial^2 u}{\partial x'^2} dx' = \lim_{\epsilon \rightarrow 0} \int_{x-\epsilon}^{x+\epsilon} \frac{\partial u}{\partial t} dx' = 0$$

We thus have $\frac{\partial}{\partial x} u$ to be continuous everywhere and hence u have to be continuous everywhere. This includes the endpoints $x = \pm\pi$. This is known as periodic boundary conditions.

- (b) Using separation of variables, $u(x, t) = X(x)T(t)$, then we have

$$\frac{T'}{T} = \lambda \frac{X''}{X} = -n^2 \lambda$$

for $\lambda > 0$ and $n^2 > 0$. Such a choice is necessary to ensure $X(x)$ satisfy the periodic boundary conditions. Hence, $X(x) = c_1 \cos(nx) + c_2 \sin(nx)$. Hence, $\frac{dT}{T} = -n^2 \lambda dt \implies T(t) = ce^{-n^2 \lambda t}$. The general solution will thus be

$$u(x, t) = C + \sum_{n=1}^{\infty} e^{-n^2 \lambda t} [A_n \cos(nx) + B_n \sin(nx)]$$

- (c) We have initial condition $u(x, 0) = f(x) = (\pi - |x|)^2$ (which is even). To find the Fourier coefficients,

$$B_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin(nx) dx = 0 \text{ since even}$$

$$C = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) dx = \frac{1}{2\pi} 2 \int_0^{\pi} (\pi - x)^2 dx = \frac{\pi^2}{3}$$

$$A_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos(nx) dx = \frac{1}{\pi} 2 \int_0^{\pi} (\pi - x)^2 \cos(nx) dx = \frac{4}{n\pi} \left(\frac{\pi}{n} - \frac{1}{n^2} [\sin(nx)]_0^{\pi} \right) = \frac{4}{n^2}$$

Hence, in large times $t \gg 1$:

$$\lim_{t \rightarrow \infty} u(x, t) = \frac{\pi^2}{3} + \lim_{t \rightarrow \infty} \sum_{n=1}^{\infty} \frac{4}{n^2} \cos(nx) e^{-\lambda n^2 t} = \frac{\pi^2}{3}$$

Problem 1.3 (Green's Functions):

- (a) Consider a linear differential operator
- \mathcal{L}
- defined by

$$\mathcal{L}y = -\frac{1}{x^2} \frac{d}{dx} \left(x^2 \frac{dy}{dx} \right) + y$$

for $0 < x < +\infty$. By writing $y = z/x$ or otherwise, find those solutions of $\mathcal{L}y = 0$ which are either (i) bounded as $x \rightarrow 0$, or (ii) bounded as $x \rightarrow +\infty$. [5]

- (b) Find the Green's function
- $G(x, \xi)$
- satisfying

$$\mathcal{L}G(x, \xi) = \delta(x - \xi)$$

such that G is bounded as $x \rightarrow 0$ and G is bounded as $x \rightarrow +\infty$. [8]

- (c) Use
- $G(x, \xi)$
- to solve

$$\mathcal{L}y = \begin{cases} 1 & 0 \leq x \leq R \\ 0 & x > R \end{cases}$$

with y bounded as $x \rightarrow 0$ and $x \rightarrow +\infty$.

[It is convenient to consider the solution for $x > R$ and $x < R$ separately.] [7]

Answer 1.3.

- (a) Upon using this substitution, we have

$$\mathcal{L}(z/x) = -\frac{1}{x} \frac{d^2 z}{dx^2} + \frac{z}{x}$$

The corresponding solution will be

$$y = \frac{1}{x} (c_1 e^x + c_2 e^{-x})$$

For (i), $c_1 = -c_2$; for (ii), $c_1 = 0$.

- (b) The corresponding Green's function satisfy
- $\mathcal{L}G(x, \xi) = \delta(x - \xi)$
- and the b.c.s. (
- G
- is bounded as
- $x \rightarrow 0$
- and
- $x \rightarrow +\infty$
-). The equation is homogeneous when
- $x \neq \xi$
- . Using the homogeneous solution in part (a),

$$G(x, \xi) = \begin{cases} A(\xi) \frac{\sinh(x)}{x} & 0 \leq x < \xi < \infty \\ B(\xi) \frac{e^{-x}}{x} & 0 \leq \xi < x < \infty \end{cases}$$

We can integrate $\mathcal{L}G(x, \xi)$ over an infinitesimal region about $x = \xi$, to obtain the jump condition $[\frac{\partial G}{\partial x}]^+_- = -1$ at $x = \xi$. Also, G has to be continuous everywhere, including $x = \xi$ (otherwise $G'' \propto \delta'(x - \xi)$ which leads to a contradiction). At $x = \xi$, we have the jump and continuity conditions to be respectively

$$\begin{aligned} -A(\xi) \frac{\cosh(\xi)}{\xi} + \frac{A(\xi)}{\xi^2} \sinh(\xi) - B(\xi) \frac{e^{-\xi}}{\xi} - \frac{B(\xi)}{\xi^2} e^{-\xi} &= -1 \\ \frac{\sinh(\xi)}{\xi} A(\xi) &= B(\xi) \frac{e^{-\xi}}{\xi} \end{aligned}$$

With both conditions, we have $A = \xi e^{-\xi}$ and $B = \xi \sinh \xi$. Hence, $G(x, \xi) = \xi e^{-\xi} \sinh(x)/x$ for $0 \leq x \leq \xi$ and $G(x, \xi) = \xi \sinh \xi e^{-x}/x$ for $0 \leq \xi \leq x$.

- (c) The solution is

$$y = \int_0^\infty G(x, \xi) f(\xi) d\xi = \frac{e^{-x}}{x} \int_0^x \xi \sinh \xi f(\xi) d\xi + \frac{\sinh(x)}{x} \int_x^\infty \xi e^{-\xi} f(\xi) d\xi$$

We first consider the case $x < R$,

$$y = \frac{e^{-x}}{x} \int_0^x \xi \sinh \xi d\xi + \frac{\sinh(x)}{x} \int_x^R \xi e^{-\xi} d\xi = \frac{\sinh(x)}{x} [(2+x)e^{-x} - (1+R)e^{-R}]$$

and then $x > R$,

$$y = \frac{e^{-x}}{x} \int_0^R \xi \sinh \xi d\xi = \frac{e^{-x}}{x} [1 - (1+R)e^{-R}]$$

Problem 1.4 (Fourier Transform):

- (a) Calculate the Fourier transform of the function

$$g(x) = e^{-\lambda|x|}$$

where λ is a positive constant, and hence or otherwise calculate the Fourier transform of the function

$$h(x) = \frac{1}{x^2 + \mu^2}$$

where μ is a positive constant. [8]

- (b) Consider Laplace's Equation for
- $\psi(x, y)$
- in the half-plane with prescribed boundary conditions at
- $y = 0$
- , i.e.

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0; \quad -\infty < x < \infty, \quad y \geq 0$$

where $\psi(x, 0) = f(x)$ is a known function with a well-defined Fourier transform, and where $\psi \rightarrow 0$ as $y \rightarrow \infty$, and $f(x) \rightarrow 0$ as $|x| \rightarrow \infty$.

By taking the Fourier transform with respect to x , and applying the convolution theorem (which may be quoted without proof), show that [8]

$$\psi(x, y) = \frac{y}{\pi} \int_{-\infty}^{\infty} \frac{f(u)}{(x-u)^2 + y^2} du$$

- (c) Find (in closed form) the solution when
- [4]

$$f(x) = \begin{cases} c = \text{constant} & |x| < a \\ 0 & \text{otherwise} \end{cases}$$

Answer 1.4.

- (a) Evaluate the Fourier transform of
- g, \tilde{g}
- :

$$\frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-\lambda|x|} e^{-ikx} dx = \frac{1}{\sqrt{2\pi}} \left(\int_{-\infty}^0 e^{x(\lambda-ik)} dx + \int_0^{\infty} e^{-x(\lambda+ik)} dx \right) = \frac{1}{\sqrt{2\pi}} \left(\frac{1}{\lambda-ik} + \frac{1}{\lambda+ik} \right)$$

which is $\frac{1}{\sqrt{2\pi}} \frac{2\lambda}{\lambda^2 + k^2}$, so by Fourier inversion theorem,

$$\mathcal{F} \left[\frac{1}{x^2 + \mu^2} \right] = \mathcal{F}[\tilde{g}(x)] \frac{\sqrt{2\pi}}{2\mu} = e^{-\mu|k|} \frac{1}{\mu} \sqrt{\frac{\pi}{2}}$$

- (b) Take the Fourier transform of the Laplace's equation w.r.t
- x
- ,

$$0 = \int_{-\infty}^{\infty} \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right) e^{-ikx} dx = \left[\frac{\partial \psi}{\partial x} e^{-ikx} \right]_{-\infty}^{\infty} + ik \int_{-\infty}^{\infty} \frac{\partial \psi}{\partial x} e^{-ikx} dx + \frac{\partial^2 \tilde{\psi}}{\partial y^2} = [ik\psi e^{-ikx}]_{-\infty}^{\infty} - k^2 \tilde{\psi} + \frac{\partial^2 \tilde{\psi}}{\partial y^2}$$

where we note that $\psi \rightarrow 0$ as $y \rightarrow \infty$. We thus have $\tilde{\psi}(k, y) = A(k)e^{-ky} + B(k)e^{ky}$. Naturally, $\tilde{\psi}$ vanish as $y \rightarrow \infty$ so $\tilde{\psi}(k, y) = D(k)e^{-y|k|}$. Using the convolution theorem,

$$\tilde{v} = \tilde{a}\tilde{b} \implies v = \frac{1}{\sqrt{2\pi}} a * b$$

and the fact that $D(k)$ obtained from the Fourier Transform of $\psi(x, 0)$,

$$\psi(x, y) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \psi(x, 0) \frac{1}{\sqrt{2\pi}} \frac{2y}{y^2 + (x-u)^2} du = \frac{y}{\pi} \int_{-\infty}^{\infty} \frac{f(x)}{y^2 + (x-u)^2} du$$

where $f(x) = \psi(x, 0)$.

- (c) Using substitution,
- $x - u = y \tan \theta$
- , we have
- $\psi(x, y)$
- to be

$$\frac{y}{\pi} \int_{\tan^{-1}((-a-x)/y)}^{\tan^{-1}((a-x)/y)} \frac{c}{y^2(1 + \tan^2 \theta)} y \sec^2 \theta d\theta = \frac{c}{\pi} \left[\tan^{-1} \left(\frac{a-x}{y} \right) - \tan^{-1} \left(\frac{-a-x}{y} \right) \right]$$

such that \tan^{-1} is consistent with $y \geq 0$.

Problem 1.5 (Linear Algebra):

- (a) What is (i) an eigenvalue, and (ii) an eigenvector, of a complex $n \times n$ matrix A ? Show that A has at least one eigenvector. [3]
- (b) Give an example of a non-diagonalizable $n \times n$ matrix for some n . [2]
- (c) What is a Hermitian matrix? Explain briefly why a Hermitian matrix can always be diagonalized. [3]
- (d) In the remainder of this question, A is a Hermitian matrix. Now assume that \mathbf{e}_i for $i = 1, \dots, n$ is a complete set of eigenvectors for A , with corresponding eigenvalues λ_i . Prove that the eigenvalues λ_i are real. [1]
- (e) Assume from now on that all the eigenvalues are negative, i.e. $\lambda_i < 0$. Obtain complete sets of eigenvectors and eigenvalues for A^{-1} and $A^n \forall n \in \mathbb{Z}^+$. [4]
- (f) Prove that [7]

$$A^{-1} = \int_0^\infty e^{tA} dt$$

You may use without proof that any complex polynomial has a complex zero. If B is a matrix, then $e^B = \sum_{n=0}^\infty \frac{B^n}{n!}$. If $B(t)$ is a matrix depending on t with entries $B_{ij}(t)$, then $\int_0^\infty B(t) dt$ means the matrix with entries $\int_0^\infty B_{ij}(t) dt$, when these integrals exist.

Answer 1.5.

- (a) If λ is an eigenvalue of the matrix A , then $\exists v \neq 0$ such that $Av = \lambda v$. The characteristic polynomial of A is $\chi_A(\lambda) = \det(A - \lambda I)$ which is complex since A is complex. By the fundamental theorem of algebra, $\chi_A(\lambda)$ has at least one root. There is thus at least one eigenvalue and therefore at least one eigenvector, which is the corresponding eigenvector to this eigenvalue.

- (b) Consider the matrix

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

Then its characteristic equation is given by

$$\det \begin{pmatrix} 1 - \lambda & 1 \\ 0 & 1 - \lambda \end{pmatrix} = 0 \implies (1 - \lambda)^2 = 0 \implies \lambda = 1$$

so if it were to be diagonalizable, then \exists an invertible matrix R such that $R^{-1}AR = \text{diag}(1, 1) \implies A = I$ which contradicts. Hence, A is not diagonalizable.

- (c) The matrix A is Hermitian if $A^\dagger = A$. Since A is Hermitian, then the eigenvectors corresponding to distinct eigenvalues must be pairwise orthogonal. If A has n distinct eigenvalues, we will have n linearly independent eigenvectors and has n linearly independent eigenvectors, which can be normalized to obtain an orthonormal basis. If not, there will be say $r < n$ distinct eigenvalues, then we can extend the basis of r eigenvectors to \mathbb{C}^n and use Gram-Schmidt procedure to obtain an orthonormal basis of n vectors. Regardless, we can always construct a unitary matrix R whose columns are the orthonormal vectors such that $R^T A R$ will be a diagonal matrix.

- (d) Let the corresponding eigenvalue for the eigenvector \mathbf{e}_i be λ_i such that $A\mathbf{e}_i = \lambda_i \mathbf{e}_i$. Multiplying \mathbf{e}_i^\dagger from the left on both sides, we have

$$\lambda_i \mathbf{e}_i^\dagger \mathbf{e}_i = \mathbf{e}_i^\dagger A \mathbf{e}_i = (A \mathbf{e}_i)^\dagger \mathbf{e}_i = \lambda_i^* \mathbf{e}_i^\dagger \mathbf{e}_i$$

This means $(\lambda_i^* - \lambda_i) \mathbf{e}_i^\dagger \mathbf{e}_i = 0$. Since $\mathbf{e}_i \neq \mathbf{0}$, then $\mathbf{e}_i^\dagger \mathbf{e}_i \neq 0$, we must have $\lambda_i = \lambda_i^* \in \mathbb{R} \forall i$.

(e) We have

$$A^n \mathbf{e}_i = A^{n-1} \lambda_i \mathbf{e}_i = \cdots = (\lambda_i)^n \mathbf{e}_i$$

as long as the eigenvalue is not zero. This also works for $n = -1$, i.e.

$$A^{-1} \mathbf{e}_i = \frac{1}{\lambda_i} \mathbf{e}_i$$

And so the eigenvectors of A are also the eigenvectors of A^n with eigenvalues λ_i^n .

(f) Consider any vector \mathbf{v} . Since the eigenvectors of A form a complete set, then they form an eigenbasis. we may decompose \mathbf{v} in terms of this eigenbasis, i.e. $\mathbf{v} = \sum_{p=1}^n \alpha_p \mathbf{e}_p$. We thus have $\int_0^\infty e^{tA} \mathbf{v} dt$ to be

$$\begin{aligned} \int_0^\infty \left(\sum_{q=0}^\infty \frac{t^q A^q}{q!} \right) \left(\sum_{p=1}^n \alpha_p \mathbf{e}_p \right) dt &= \sum_{p=1}^n \alpha_p \int_0^\infty \sum_{q=0}^\infty \frac{t^q \lambda_p^q}{q!} \mathbf{e}_p dt \\ &= \sum_{p=1}^n \alpha_p \mathbf{e}_p \int_0^\infty e^{t \lambda_p} dt \\ &= - \sum_{p=1}^n \alpha_p \mathbf{e}_p \lambda_p^{-1} \end{aligned}$$

where we handwavingly swap the infinite sum with the integral. Since all the eigenvalues are negative, the upper limit vanishes. Moreover, we have from part e,

$$A^{-1} \mathbf{v} = A^{-1} \sum_{p=1}^n \alpha_p \mathbf{e}_p = \sum_{p=1}^n \frac{\alpha_p}{\lambda_p} \mathbf{e}_p$$

so $A^{-1} = - \int_0^\infty e^{tA} dt$ as requested.

Problem 1.6 (Linear Algebra):

- Give a real linear transformation $\mathbf{x} = L\mathbf{y}$ which converts the quadratic form $Q_1(\mathbf{x}) = x_1^2 + 4x_1x_2 + 5x_2^2 + 6x_3^2$ into $\tilde{Q}_1(\mathbf{y}) = y_1^2 + y_2^2 + y_3^2$. What is the corresponding result for the quadratic form $Q_2(\mathbf{x}) = x_1^2 + 4x_1x_2 + 5x_2^2 - 6x_3^2$? [5]
- Define the trace $\text{Tr}(A)$ of a square matrix A , and prove that $\text{Tr}(AB) = \text{Tr}(BA)$. For which complex numbers c do there exist $n \times n$ matrices A, B such that

$$AB - BA = cI$$

where I is the identity matrix? For each complex number c either give an example or prove the non-existence of such matrices. [6]

- Let $A(\epsilon)$ be a symmetric $n \times n$ matrix for each real ϵ . The smallest eigenvalue of $A(\epsilon)$ is $\lambda(\epsilon)$, with corresponding real eigenvector $\mathbf{x} = \mathbf{x}(\epsilon)$ normalized so that $\mathbf{x}^T \mathbf{x} = 1 \forall \epsilon$, where T denotes transpose. Assuming that $A(\epsilon), \lambda(\epsilon), \mathbf{x}(\epsilon)$ vary smoothly with ϵ , show that [9]

$$\left. \frac{d\lambda}{d\epsilon} \right|_{\epsilon=0} = \mathbf{x}^T \left. \frac{dA}{d\epsilon} \right|_{\epsilon=0} \mathbf{x}$$

where T denotes transpose.

Answer 1.6.

(a) We write Q_1 as a quadratic form

$$Q_1(\mathbf{x}) = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}^T \begin{pmatrix} 1 & 2 & 0 \\ 2 & 5 & 0 \\ 0 & 0 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \mathbf{x}^T M \mathbf{x}$$

$$\det(M - \lambda I) = \det \begin{pmatrix} 1 - \lambda & 2 & 0 \\ 2 & 5 - \lambda & 0 \\ 0 & 0 & 6 - \lambda \end{pmatrix} = 0 \implies (6 - \lambda)(\lambda - 3 - 2\sqrt{2})(\lambda - 3 + 2\sqrt{2}) = 0$$

By inspection, the eigenvector for $\lambda = 6$ is $(0, 0, 1)^T$. For $\lambda = 3 \pm 2\sqrt{2}$, we have

$$\begin{pmatrix} -2 \mp 2\sqrt{2} & 2 & 0 \\ 2 & 2 \mp \sqrt{2} & 0 \\ 0 & 0 & 3 \pm 2\sqrt{2} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

which gives $\frac{1}{\sqrt{3}}(1, 1 \pm \sqrt{2}, 0)^T$. We can construct an orthogonal matrix R by having the normalized eigenvectors as its rows such that $M' = RMR^T$ is a diagonal matrix with diagonal entries as the corresponding eigenvalues. Further, we can write $M' = PIP$ so that we associate $\mathbf{y} = PR\mathbf{x}$, thus

$$Q_1 = \mathbf{x}^T R^T P I P R \mathbf{x} = \mathbf{y}^T I \mathbf{y} = y_1^2 + y_2^2 + y_3^2$$

The requested linear transformation is $L = PR$:

$$L = \begin{pmatrix} \sqrt{6} & 0 & 0 \\ 0 & \sqrt{3+2\sqrt{2}} & 0 \\ 0 & 0 & \sqrt{3-2\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 & 1/\sqrt{3} & 1/\sqrt{3} \\ 0 & \frac{1}{\sqrt{3}}(1+\sqrt{2}) & \frac{1}{\sqrt{3}}(1-\sqrt{2}) \\ 1 & 0 & 0 \end{pmatrix}$$

For Q_2 , we have $-y_1^2 + y_2^2 + y_3^2$ due to the eigenvalue of the x_3 direction now being -6 instead of $+6$.

(b) The trace is $\sum_{i=1}^n a_{ii}$ and so

$$\text{Tr}(AB) = \sum_{i=1}^n (AB)_{ii} = \sum_{i=1}^n \sum_{j=1}^n a_{ij} b_{ji} = \sum_{j=1}^n (BA)_{jj} = \text{Tr}(BA)$$

Taking the trace of the given expression, we have $\text{Tr}(AB - BA) = \text{Tr}(cI) = cn$. Hence, $c = 0$. One example would be $A = I$, $B = \sigma_z$ (Pauli spin matrix).

(c) Consider the Rayleigh quotient $\Lambda = \frac{\mathbf{x}^T A \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$. If \mathbf{x} is an eigenvector, then this quotient is simply the eigenvalue λ , i.e. $A\mathbf{x} = \lambda\mathbf{x}$. Differentiating both sides with respect to ϵ , we have

$$\begin{aligned} \frac{d\lambda}{d\epsilon} &= \frac{1}{\mathbf{x}^T \mathbf{x}} \left(\frac{d\mathbf{x}^T}{d\epsilon} A \mathbf{x} + \mathbf{x}^T \frac{dA}{d\epsilon} \mathbf{x} + \mathbf{x}^T A \frac{d\mathbf{x}}{d\epsilon} \right) - \frac{\mathbf{x}^T A \mathbf{x}}{(\mathbf{x}^T \mathbf{x})^2} \left(\frac{d\mathbf{x}^T}{d\epsilon} \mathbf{x} + \mathbf{x}^T \frac{d\mathbf{x}}{d\epsilon} \right) \\ &= \frac{1}{\mathbf{x}^T \mathbf{x}} \left(\frac{d\mathbf{x}^T}{d\epsilon} \lambda \mathbf{x} + \mathbf{x}^T \frac{dA}{d\epsilon} \mathbf{x} + \lambda \mathbf{x}^T \frac{d\mathbf{x}}{d\epsilon} \right) - \frac{\lambda}{\mathbf{x}^T \mathbf{x}} \left(\frac{d\mathbf{x}^T}{d\epsilon} \mathbf{x} + \mathbf{x}^T \frac{d\mathbf{x}}{d\epsilon} \right) \\ &= \mathbf{x}^T \frac{dA}{d\epsilon} \mathbf{x} \end{aligned}$$

where $\mathbf{x}^T \mathbf{x} = 1$, $A\mathbf{x} = \lambda\mathbf{x}$, $\mathbf{x}^T A = (A\mathbf{x})^T = \lambda\mathbf{x}^T$ since A is symmetric. Hence, we obtained our desired result (true $\forall \epsilon$, especially $\epsilon = 0$).

Problem 1.7 (Cauchy-Riemann):

- (a) Obtain the Cauchy-Riemann equations for the analytic function

[2]

$$f(z) = u(x, y) + iv(x, y)$$

- (b) Show that:

- (i)
- u
- and
- v
- satisfy the Laplace's equation,
- $\nabla^2 u = \nabla^2 v = 0$
- ;

[2]

- (ii) the level sets constant
- u
- and constant
- v
- are orthogonal, i.e.
- $\nabla u \cdot \nabla v = 0$
- ;

[2]

- (iii) every stationary point of
- u
- is a stationary point of
- v
- and conversely;

[2]

- (iv) stationary points for which
- $\begin{vmatrix} \partial_{xx}u & \partial_{xy}u \\ \partial_{yx}u & \partial_{yy}u \end{vmatrix} \neq 0$
- must be saddle points;

[4]

- (v) If
- $f(z) = u(x, y) + iv(x, y)$
- and
- $g(z) = s(x, y) + it(x, y)$
- are analytic functions, then so is
- $g(f(z))$
- , and hence deduce that
- $s(u(x, y), v(x, y))$
- satisfies Laplace's equation.

[8]

Answer 1.7.

- (a) The Cauchy-Riemann equations are obtained by requiring the existence of

$$f'(z) = \lim_{\delta z \rightarrow 0} \frac{f(z + \delta z) - f(z)}{\delta z}$$

This value should be independent of the direction of approach for $\delta z \rightarrow 0$. We can take any two linearly independent directions, say $\delta z = \delta x$ and $\delta z = i\delta y$.

$$\lim_{\delta x \rightarrow 0} \frac{u(x + \delta x, y) + iv(x + \delta x, y)}{\delta x} = \lim_{\delta y \rightarrow 0} \frac{u(x, y + \delta y) + iv(x, y + \delta y)}{i\delta y} \implies \frac{\partial u}{\partial x} + i \frac{\partial v}{\partial x} = -i \frac{\partial u}{\partial y} + \frac{\partial v}{\partial y}$$

This gives us the Cauchy-Riemann equations, namely $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ and $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$.

- (b) (i) We have the Laplacian of
- u
- to be

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial}{\partial y} \left(-\frac{\partial v}{\partial x} \right) = 0$$

Similar for v , hence u and v satisfy the Laplace's equation.

- (ii) Evaluating
- $\nabla u \cdot \nabla v$
- with the Cauchy-Riemann equations

$$\nabla u \cdot \nabla v = \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial y} = \frac{\partial v}{\partial y} \frac{\partial v}{\partial x} - \frac{\partial v}{\partial x} \frac{\partial v}{\partial y} = 0$$

- (iii) If we have a stationary point of
- u
- , then
- $\frac{\partial u}{\partial x} = \frac{\partial u}{\partial y} = 0$
- . By Cauchy-Riemann, then
- $\frac{\partial v}{\partial x} = \frac{\partial v}{\partial y} = 0$
- , and hence a stationary point of
- v
- .

- (iv) Evaluating the Hessian, we have

$$\frac{\partial}{\partial x} \frac{\partial u}{\partial x} \times \frac{\partial}{\partial y} \frac{\partial u}{\partial y} - \left(\frac{\partial^2 u}{\partial x \partial y} \right)^2 = - \left(\frac{\partial^2 v}{\partial x \partial y} \right)^2 - \left(\frac{\partial^2 u}{\partial x \partial y} \right)^2 < 0$$

For a function of 2 variables $u(x, y)$, if the determinant of the Hessian is negative at this point, this point is a saddle point.

- (v) We have
- $f(x + iy) = u(x, y) + iv(x, y)$
- to be analytic, then
- f
- satisfies the Cauchy-Riemann equations, i.e.
- $(\frac{\partial u}{\partial x})_y = (\frac{\partial v}{\partial y})_x$
- and
- $(\frac{\partial u}{\partial y})_x = -(\frac{\partial v}{\partial x})_y$
- . Similarly,
- $g(u + iv) = s(u, v) + it(u, v)$
- is analytic, this gives
- $(\frac{\partial s}{\partial v})_u = (\frac{\partial t}{\partial v})_u$
- and
- $(\frac{\partial s}{\partial v})_u = -(\frac{\partial t}{\partial u})_v$
- . Consider the composite function

$$g(f(z)) = s(u(x, y), v(x, y)) + it(u(x, y), v(x, y))$$

then we have by chain rule,

$$\begin{aligned} \left(\frac{\partial s}{\partial x} \right)_y &= \left(\frac{\partial u}{\partial x} \right)_y \left(\frac{\partial s}{\partial u} \right)_v + \left(\frac{\partial v}{\partial x} \right)_y \left(\frac{\partial s}{\partial v} \right)_u = \left(\frac{\partial v}{\partial y} \right)_x \left(\frac{\partial t}{\partial v} \right)_u + \left(\frac{\partial t}{\partial u} \right)_v \left(\frac{\partial u}{\partial y} \right)_x = \left(\frac{\partial t}{\partial y} \right)_x \\ \left(\frac{\partial s}{\partial y} \right)_x &= \left(\frac{\partial u}{\partial y} \right)_x \left(\frac{\partial s}{\partial u} \right)_v + \left(\frac{\partial v}{\partial y} \right)_x \left(\frac{\partial s}{\partial v} \right)_u = - \left(\frac{\partial v}{\partial x} \right)_y \left(\frac{\partial t}{\partial v} \right)_u - \left(\frac{\partial t}{\partial u} \right)_v \left(\frac{\partial u}{\partial x} \right)_y = \left(\frac{\partial t}{\partial x} \right)_y \end{aligned}$$

Hence composite functions obey the Cauchy-Riemann equations. By part (a), we can thus conclude $s(u, v)$ satisfy the Laplace's equation.

Problem 1.8 (Series Solution to ODE):

- (a) Show that the origin is an ordinary point, and that $x = 1$ and $x = -1$ are regular singular points of the equation

$$(1 - x^2) \frac{d^2 y}{dx^2} - x \frac{dy}{dx} + p^2 y = 0 \quad (*)$$

where p is a real constant.

[4]

- (b) You may assume that there are two linearly independent series solutions of the form

$$y_q = x^q \sum_{n=0}^{\infty} a_n x^n, \quad q = 0, 1$$

Find the recurrence relations for a_n for the two cases, and show that the series converges for $|x| < 1$. [6]

- (c) Show that polynomial solutions $T_m(x)$ exist for $p = m$, where m is a non-negative integer. With the condition $T_m(1) = 1$, calculate all the coefficients for the cases $m = 0, 1, 2, 3$. [6]
- (d) For $-1 \leq x \leq 1$, make the substitution $x = \cos \theta$ with $0 \leq \theta \leq \pi$, in the above differential equation (*). Hence, or otherwise, show that $T_m(x) = \cos(m \cos^{-1}(x))$ for any non-negative integer m . [4]

Answer 1.8.

- (a) Write the ordinary differential equation as $\frac{d^2 y}{dx^2} - \frac{x}{1-x^2} \frac{dy}{dx} + \frac{p^2}{1-x^2} y = 0$. We see that $-\frac{x}{1-x^2}$ and $\frac{p^2}{1-x^2}$ are analytic at $x = 0$, but not analytic at $x = \pm 1$. But, $-\frac{(x \mp 1)x}{1-x^2} = -\frac{x}{1 \pm x}$ and $-\frac{p^2(x \mp 1)^2}{1-x^2} = \frac{x(1 \mp x)}{1 \pm x}$ are analytic at $x = \pm 1$. So $x = 0$ is an ordinary point while $x = \pm 1$ are regular singular points.

- (b) Use a Frobenius series solution $y_q = \sum_{n=0}^{\infty} a_n x^{n+q}$, and so

$$\sum_{n=0}^{\infty} a_n(n+q)(n+q-1)x^{n+q-2} - \sum_{n=0}^{\infty} a_n(n+q)(n+q-1)x^{n+q} - \sum_{n=0}^{\infty} a_n(n+q)x^{n+q} + p^2 \sum_{n=0}^{\infty} a_n x^{n+q} = 0$$

Comparing coefficients for x^{q-2} , we have the indicial equation $a_0 q(q-1) = 0$. Since we are given $q = 0, 1$, we must have $a_0 \neq 0$. Comparing coefficients for x^{q-1} , we have $a_1 q(1+q) = 0$. For $q = 0$, free to choose $a_1 = 0$. For $q = 1$, we have $q(1+q) \neq 0$ and thus $a_1 = 0$ must be true. Comparing coefficients for x^{n+q} where $n \geq 0$, then we obtain the recurrence relation

$$a_{n+2}(n+q+2)(n+q+1) - a_n(n+q)(n+q-1+1-p^2) = 0 \implies \frac{a_{n+2}}{a_n} = \frac{(n+q)^2 - p^2}{(n+q+2)(n+q+1)}$$

for $q = 0, 1$. For the series to converge $\forall |x| < 1$, we require $\lim_{n \rightarrow \infty} \left| \frac{a_{n+2}}{a_n} \right| |x|^2 < 1$. We have

$$|x|^2 < \lim_{n \rightarrow \infty} \left| \frac{(n+q+2)(n+q+1)}{(n+q)^2 - p^2} \right| < 1$$

- (c) We will obtain polynomial solutions if the recurrence relation terminates for some i , where $i \in \mathbb{Z}^+ \cup \{0\}$. This requires $(i+q)^2 = p^2 \implies i+q = p$.

- $m = p = 0$: $i+q = 0 \implies q = 0 \implies T_0 = a_0 x^0$. Normalization: $T_0(1) = a_0 = 1 \forall x$;
- $m = p = 1$: $i+q = 1$. $q = 0$ give no valid solution while $q = 1$ give $i = 0$ and so $T_1(x) = a_0 x$. Normalization: $T_1(1) = a_0 = 1 \forall x$, so $T_1(x) = x$;
- $m = p = 2$: $i+q = 2$. $q = 0$ gives $\frac{a_2}{a_0} = \frac{-2^2}{2} = -2$. Series terminates at $n = 2$. Normalization: $T_2(1) = 1 \implies a_0 = -1 \forall x$, so $T_2(x) = 2x^2 - 1$;
- $m = p = 3$: $i+q = 3$. If $q = 0$, $a_1 = 0$, $\frac{a_3}{a_0} = \frac{3^2 - 3^2}{(3+0+2)(3+0+1)} = 0$, so no valid solution. If $q = 1$ and $i = 2$, $\frac{a_2}{a_0} = \frac{1-3^2}{(1+2)(1+1)} = \frac{-4}{3}$. Normalization: $T_3(1) = 1 \implies a_0 = -3 \forall x$, so $T_3(x) = -3x + 4x^3$.

(d) We have $x = \cos \theta$, and so $\frac{d}{dx} = -\frac{1}{\sin \theta} \frac{d}{d\theta}$ and $\frac{d^2}{dx^2} = -\frac{1}{\sin \theta} \frac{d}{d\theta} \left(-\frac{1}{\sin \theta} \frac{d}{d\theta} \right)$. Hence,

$$\sin^2 \theta \left(\frac{1}{\sin^2 \theta} \frac{d^2}{d\theta^2} - \frac{\cos \theta}{\sin^3 \theta} \frac{d}{d\theta} \right) y + \frac{\cos \theta}{\sin \theta} \frac{d}{d\theta} y + p^2 y = 0 \implies \frac{d^2 y}{d\theta^2} + p^2 y = 0$$

This is solved by $y_p(\theta) = A \cos(p\theta) + B \sin(p\theta)$. Imposing normalization $1 = y_p(\cos^{-1}(1)) = A$. As for $\sin(p \cos^{-1}(x)) = \text{Im}[(x \pm i\sqrt{1-x^2})^p]$ where p is a real constant. The real part of this will always contain an even power of $\pm\sqrt{1-x^2}$ and thus polynomial. But, the imaginary part will always contain an odd power of $\sqrt{1-x^2}$ and thus non-polynomial. Hence, $B = 0$. Finally, $y_p(\theta) = \cos(m \cos^{-1}(x))$ for $p = m \in \mathbb{Z}^+ \cup \{0\}$.

Problem 1.9 (Variational Principle):

(a) State the Euler equation obtained by making stationary

$$F[y] = \int_a^b f(x, y, y') dx$$

with fixed values of $y(a)$ and $y(b)$, and show that if $f = f(y, y')$ is not an explicit function of x , then [6]

$$y' \frac{\partial f}{\partial y'} - f = A$$

(b) In an optical medium occupying the region $0 < y < h$, the speed of light is

$$c(y) = \frac{c_0}{\sqrt{1 - ky}}, \quad (0 < k < 1/h)$$

Show that the paths of light rays in the medium are parabolic. [8]

(c) Show also that, if a ray enters the medium at $(-x_0, 0)$ and leaves it at $(x_0, 0)$, then

$$(kx_0)^2 = 4ky_0(1 - ky_0)$$

where $y_0 < h$ is the greatest value of y attained on the ray path. [6]

Answer 1.9.

(a) The functional is stationary if the integrand satisfies the Euler equation, which is $\frac{d}{dx} \frac{\partial f}{\partial y'} - \frac{\partial f}{\partial y} = 0$. If $f = f(y, y')$, then $\frac{\partial f}{\partial x} = 0$, and hence using chain rule,

$$\begin{aligned} \frac{df}{dx} &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' = \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' = 0 + y' \frac{d}{dx} \frac{\partial f}{\partial y'} + \frac{\partial f}{\partial y'} y'' \\ \implies 0 &= \frac{d}{dx} \left(f - y' \frac{\partial f}{\partial y'} \right) \implies y' \frac{\partial f}{\partial y'} - f = A = \text{constant} \end{aligned}$$

(b) Fermat's Principle states that the path a light ray travels in, minimizes the time it takes, T .

$$T = \int \frac{dt}{dl} dl = \int \frac{1}{c(y)} \sqrt{dx^2 + dy^2 + dz^2} = \frac{1}{c_0} \int \sqrt{1 - ky} \sqrt{1 + y'^2} dx$$

where we choose $dz = 0$ since the system is symmetric about the z -axis. Let the integrand be $f(y, y')$. Since it is not an explicit function of x , then by part (a), we have

$$\frac{y'^2 \sqrt{1 - ky}}{\sqrt{1 + y'^2}} - \sqrt{1 - ky} \sqrt{1 + y'^2} = A \implies dx = \frac{A dy}{\sqrt{1 - A^2 - ky}}$$

Then we have $\frac{k^2}{4A^2} (x - B)^2 = 1 - A^2 - ky$, i.e. parabolic paths.

(c) Imposing boundary conditions $(-x_0, 0)$ and $(x_0, 0)$ then $B = 0$. Since it is a symmetric parabola, the greatest height y_0 occurs at $x = 0$, i.e. $0 = 1 - A^2 + ky_0$. Then, at $x = \pm x_0$, $y = 0$:

$$k^2 x_0^2 = 4(1 - ky_0)k(y_0 - y) = 4(k - ky_0)ky_0$$

Problem 1.10 (Rayleigh-Ritz Method): Consider a Sturm-Liouville problem

$$-\frac{d}{dx} \left(p(x) \frac{dy}{dx} \right) + q(x)y - \lambda w(x)y = 0$$

defined for $a \leq x \leq b$, with $p > 0$ and $w > 0$ on this interval, and with boundary conditions $y(a) = y(b) = 0$. You may assume that this problem has a complete infinite set of orthonormal eigenfunctions y_i for $i = 0, 1, 2, \dots$ with associated ordered eigenvalues $\lambda_0 < \lambda_1 < \lambda_2 < \dots$

(a) Define a class of trial functions $y_{trial}(x)$ such that

$$y_{trial}(x) = A \left(y_0(x) + \sum_{i=1}^{\infty} c_i y_i \right) \quad (\dagger)$$

for some non-zero constant A . Define

$$\Lambda[y] = \frac{\int_a^b (py'^2 + qy^2) dx}{\int_a^b y^2 w dx} = \frac{F[y]}{G[y]}$$

Show that [4]

$$\lambda_{trial} := \Lambda[y_{trial}] = \frac{\lambda_0 + \sum_{i=1}^{\infty} c_i^2 \lambda_i}{1 + \sum_{i=1}^{\infty} c_i^2} \quad (*)$$

(b) By taking variations of Λ , F and G explicitly, for general y satisfying boundary conditions of the above form, show that the stationary values of $\Lambda[y]$ are the eigenvalues λ_i , and hence deduce that $\Lambda[y]$ is bounded below by λ_0 .

(Euler's equation may be quoted without proof.) [6]

(c) Consider the specific problem

$$\frac{d^2 y}{dx^2} + \lambda y = 0, \quad 0 \leq x \leq 1, \quad y(0) = y(1) = 0$$

Generate an estimate λ_{trial} for the smallest eigenvalue λ_0 by using the trial function $y_{trial}(x) = x(1-x)$. [4]

(d) Represent $y_{trial} = x(1-x)$ an infinite series of the form given in (\dagger) for this particular problem, and thus derive an expression for the ratio [6]

$$\frac{c_1^2(\lambda_1 - \lambda_0)}{\lambda_{trial} - \lambda_0}$$

Answer 1.10.

(a) The functional F can be cast into Sturm-Liouville (SL) form

$$F[y] = \int_a^b (py'^2 + qy^2)dx = [ypy']_a^b + \int_a^b -y \frac{d}{dx}(py') + yqydx = [ypy']_a^b + \int_a^b y\mathcal{L}ydx$$

where $\mathcal{L} = -\frac{d}{dx}(p\frac{d}{dx}) + q$ and $[ypy']_a^b = 0$ due to given boundary conditions $y(a) = y(b) = 0$ and assuming p is finite at end points. With the given (\dagger), the functionals become

$$F[y_{\text{trial}}] = A\langle y_0 | \mathcal{L}y_0 \rangle + A \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} c_i \langle y_j | \mathcal{L}y_i \rangle = A^2 \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} \lambda_j c_i c_j \langle y_i | y_j \rangle_w = A^2 \sum_{i=0}^{\infty} c_i^2 \lambda_i$$

$$G[y_{\text{trial}}] = A^2 \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} c_i c_j \langle y_i | y_j \rangle_w = A^2 \sum_{i=0}^{\infty} c_i^2$$

where $c_0 = 1$, and given that y_i form an orthonormal set. Hence,

$$\Lambda[y_{\text{trial}}] = \frac{F[y_{\text{trial}}]}{G[y_{\text{trial}}]} = \frac{\lambda_0 + \sum_{i=1}^{\infty} c_i^2 \lambda_i}{1 + \sum_{i=1}^{\infty} c_i^2}$$

(b) Taking first order variations,

$$\Lambda[y + \delta y] = \frac{F[y + \delta y]}{G[y + \delta y]} - \frac{F[y]}{G[y]} \implies \delta\Lambda = \frac{\delta F}{G} - \frac{F}{G^2} \delta G = \frac{1}{G}(\delta F - \Lambda \delta G)$$

So extremizing Λ , i.e. $\delta\Lambda = 0$, is equivalent to extremizing $F - \lambda G := F - \Lambda G$ with fixed $y(a)$ and $y(b)$.

$$F - \lambda G = \int_a^b py'^2 + qy^2 - \lambda wy^2 dx$$

The integrand does not explicitly depend on x , so we use the first integral to Euler equation:

$$p'y' + py'' = qy - \lambda wy \implies \lambda wy = -(py')' + qy$$

where we recover the original SL equation $\mathcal{L}y = \lambda wy$. Since the lowest possible value of Λ (where integrand of F is positive-definite) is its global minimum, and all of its stationary values are eigenvalues of \mathcal{L} , then Λ is bounded below by λ_0 .

(c) For the specific problem, we identify $w = 1$, $a = 0$, $b = 1$, $p = 1$ and $q = 0$, then

$$G[y_{\text{trial}}] = \int_0^1 x^2(1-x)^2 dx = \int_0^1 x^2 - 2x^3 + x^4 dx = \frac{1}{3} - \frac{1}{2} + \frac{1}{5} = \frac{1}{30}$$

$$F[y_{\text{trial}}] = \int_0^1 (1-2x)62dx = \frac{1}{3}$$

Hence, $\Lambda[y_{\text{trial}}] = \frac{F[y_{\text{trial}}]}{G[y_{\text{trial}}]} = \frac{1/3}{1/30} = 10$. The actual eigenfunction is $y = \sin \pi x$, and so $\lambda_0 = \pi^2$. λ_{trial} is an overestimate of the true $\lambda_0 = \pi^2$.

(d) Since the eigenfunctions form a complete basis, write y_{trial} as a linear combination of them:

$$x(1-x) = A \sum_{i=1}^{\infty} c_i \sin(i\pi x) \implies c_n = \frac{1}{2(1)} \int_0^1 x(1-x) \sin n\pi x dx = \begin{cases} \frac{2}{n^3\pi^3} & \text{odd } n \\ 0 & \text{even } n \end{cases}$$

$$\implies \frac{\lambda_1 - \lambda_0}{\lambda_{\text{trial}} - \lambda_0} c_1^2 = \frac{4}{\pi^6} \frac{4\pi^2 - \pi^2}{10 - \pi^2} = \frac{12}{\pi^4} \frac{1}{10 - \pi^2}$$

1.2 Paper 2

Problem 1.11 (Sturm-Liouville): Solutions of the equation

$$\left(1 - \frac{1}{x}\right) \frac{d^2 y}{dx^2} + \left(\frac{2}{x} - \frac{1}{x^2}\right) \frac{dy}{dx} - \frac{l(l+1)}{x^2} y = -\lambda y \quad (*)$$

with $l = 1, 2, \dots$ behave for small but positive $(x - 1)$ like

$$c_1 + c_2 \ln(x - 1)$$

where c_1 and c_2 are constants. An eigenvalue problem is defined by the condition that real valued solutions on the interval $1 \leq x \leq R$ are subject to the boundary conditions that $y(R) = 0$ and $y(x)$ and dy/dx are bounded as x tends to 1 from above.

- (i) Show that the equation (*) may be cast into self-adjoint form. [6]
- (ii) Give the self-adjoint operator and verify, subject to the boundary conditions, that it is indeed self-adjoint. [4]
- (iii) Show that the eigenvalues λ must be real and greater than zero. [5]
- (iv) Show explicitly, using the boundary conditions, that eigenfunctions y_i and y_j with different eigenvalues $\lambda_i \neq \lambda_j$ are orthogonal with respect to a suitably weighted inner product. [5]

Answer 1.11.

(i) To cast into self-adjoint form, multiply by an integration factor

$$\mathcal{L}'y = \mu \mathcal{L}y = \mu(x) \left(1 - \frac{1}{x}\right) \frac{d^2 y}{dx^2} + \mu(x) \left(\frac{2}{x} - \frac{1}{x^2}\right) \frac{dy}{dx} - \mu(x) \frac{l(l+1)}{x^2} y$$

If \mathcal{L}' is self-adjoint, then $\mathcal{L}' = p(x) \frac{d^2}{dx^2} + p'(x) \frac{d}{dx} + q(x)$. Comparing coefficients give

$$\frac{1}{p(x)} \frac{dp(x)}{dx} = \frac{2x-1}{x^2-x} \implies p(x) \propto x^2 - x \implies \mu(x) = \frac{p(x)}{1-x^{-1}} \propto x^2$$

Then, $\mathcal{L}'y = \frac{d}{dx}((x^2 - x) \frac{d}{dx})y - l(l+1)y = -\lambda x^2 y$, with x^2 being the weight function.

(ii) Let $y = u$ and $y = v$ be two arbitrary functions subjected to the boundary conditions $y(R) = 0$ and that y and $\frac{dy}{dx}$ are bounded from above as $x \rightarrow 1$ on the interval $1 \leq x \leq R$. Then,

$$\begin{aligned} \langle u | \mathcal{L}'v \rangle &= \int_1^R u^* \frac{d}{dx} \left[(x^2 - x) \frac{dv}{dx} \right] - u^* l(l+1) v dx \\ &= \left[u^* (x^2 - x) \frac{dv}{dx} \right]_1^R + \int_1^R \frac{du^*}{dx} (x^2 - x) \frac{dv}{dx} - u^* l(l+1) v dx \\ &= \left[u^* (x^2 - x) \frac{dv}{dx} - \frac{du^*}{dx} (x^2 - x) v \right]_1^R + \int_1^R v \frac{d}{dx} \left((x^2 - x) \frac{du^*}{dx} \right) - u^* l(l+1) v dx \end{aligned}$$

For $\langle u | \mathcal{L}'v \rangle = \langle \mathcal{L}'u | v \rangle$, the boundary terms $[u^* (x^2 - x) \frac{dv}{dx} - \frac{du^*}{dx} (x^2 - x) v]_1^R$ must be zero.

(iii) We have $\mathcal{L}'y = -\lambda x^2 y$, so $\Lambda = \frac{\langle y | \mathcal{L}'y \rangle}{\langle y | y \rangle_w} = \frac{\langle y | -\lambda x^2 y \rangle}{\langle y | y \rangle_w} = -\lambda$, i.e.

$$\begin{aligned} \lambda &= -\frac{1}{\langle y | y \rangle_w} \int_1^R y^* \frac{d}{dx} \left[(x^2 - x) \frac{dy}{dx} \right] - y^* l(l+1) y dx \\ &= -\frac{1}{\langle y | y \rangle_w} \left(\left[y^* (x^2 - x) \frac{dy}{dx} \right]_1^R + \int_1^R -\frac{dy^*}{dx} (x^2 - x) \frac{dy}{dx} - y^* l(l+1) y dx \right) \\ &= \frac{\int_1^R \left| \frac{dy}{dx} \right|^2 (x^2 - x) + |y|^2 l(l+1) dx}{\int_1^R |y|^2 x^2 dx} \end{aligned}$$

Both the numerator and denominator are real. Clearly, since the integrand of the integral in denominator is non-negative, the denominator is positive in the range $0 \leq x \leq R$. Moreover, since $x^2 \geq x$, the numerator is non-negative. Thus, λ is positive and real.

(iv) Suppose y_i and y_j are eigenfunctions with different eigenvalues λ_i and λ_j , then

$$\begin{aligned}\langle y_i | \mathcal{L}' y_j \rangle &= \int_1^R y_i^* \frac{d}{dx} \left[(x^2 - x) \frac{dy_j}{dx} \right] - y_i^* l(l+1) y_j dx \\ &= \left[y_i^* (x^2 - x) \frac{dy_j}{dx} - \frac{dy_i^*}{dx} (x^2 - x) y_j \right]_1^R \langle \mathcal{L}' y_i | y_j \rangle\end{aligned}$$

But from part (ii), the boundary terms must be zero. The LHS gives $\lambda_j \langle y_i | y_j \rangle_w$ but the RHS gives $\lambda_i \langle y_i | y_j \rangle_w$. Note that λ is real from part (iii). Bringing to one side,

$$(\lambda_i - \lambda_j) \int_1^R y_i^* y_j x^2 dx = 0$$

Since $\lambda_i \neq \lambda_j$, then $\langle y_i | y_j \rangle_w = 0$, i.e. the eigenfunctions y_i and y_j are orthogonal with respect to a suitably weighted inner product.

Problem 1.12 (Laplace's Equation):

(i) Show that Laplace's equation in plane polar coordinates r, θ ,

$$\nabla^2 \Phi = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \Phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \Phi}{\partial \theta^2} = 0$$

admits solutions of the form

[4]

$$\Phi = a_0 + b_0 \ln(r) + \sum_{n=1}^{\infty} \left(a_n r^n + \frac{b_n}{r^n} \right) \left(A_n \cos(n\theta) + B_n \sin(n\theta) \right)$$

(ii) Find a solution $\Phi(r, \theta)$ which is bounded inside the disc $r \leq R$ and such that

$$\Phi(R, \theta) = \begin{cases} 0 & \frac{\pi}{2} \leq \theta \leq \pi \\ C & -\frac{\pi}{2} < \theta < \frac{\pi}{2} \\ 0 & -\pi \leq \theta \leq -\frac{\pi}{2} \end{cases}$$

where C is a constant.

[6]

(iii) Show that your solution is unique subject to the stated boundary conditions by supposing to the contrary the existence of another solution $\tilde{\Phi}$ satisfying the same boundary conditions, and applying the divergence theorem to

$$\int_D (\tilde{\Phi} - \Phi) \nabla^2 (\tilde{\Phi} - \Phi) dx dy$$

where the domain D is the disc $r \leq R$.

[4]

(iv) Construct a solution bounded outside the disc, i.e. for $r \geq R$, with the same boundary data on the circle $r = R$ and which tends to a constant at infinity.

[2]

(v) Show that the constant is not freely specifiable but must take a certain value which should be specified.

[2]

(vi) Show further, using the divergence theorem, that there is no other bounded solution taking that value.

[2]

Answer 1.12.

(i) Use separation of variables $\Phi(r, \theta) = R(r)\Theta(\theta)$:

$$\frac{1}{rR} \frac{d}{dr} \left(r \frac{dR}{dr} \right) = -\frac{1}{r^2 \Theta} \frac{d^2 \Theta}{d\theta^2} = \frac{\lambda}{r^2}$$

where λ is some constant. Then, the angular part gives $\Theta(\theta) = c_1 \cos \sqrt{\lambda} \theta + c_2 \sin \sqrt{\lambda} \theta$ for $\lambda \neq 0$ and $\Theta(\theta) = c_3 \theta + c_4$ for $\lambda = 0$. $\Theta(\theta)$ is single-valued, hence $c_3 = c_4 = 0$. Moreover, Θ is periodic, i.e. $\Theta(\theta + 2\pi) = \Theta(\theta)$ and this requires $\sqrt{\lambda} \pi = n\pi$ for $n \in \mathbb{Z}^+$. Thus, $\Theta(\theta) = c_1 \cos n\theta + c_2 \sin n\theta$ for $n \in \mathbb{R}^+$.

The radial part gives $rR' + r^2 R'' = \lambda R$. For $\lambda = 0$, $R(r) = c_7 \ln r + c_8$ but for $\lambda \neq 0$, try $R = r^k$ to get $k = \pm n$ and hence $R(r) = c_5 r^n + c_6 r^{-n}$. Then,

$$\Phi(r, \theta) = c_7 \ln r + c_8 + \sum_{n=1}^{\infty} (c_5 r^n + c_6 r^{-n}) (c_1 \cos n\theta + c_2 \sin n\theta)$$

Then we have $a_n = c_5$, $b_n = c_6$, $A_n = c_1$, $B_n = c_2$, $a_0 = c_8$ and $b_0 = c_7$.

(ii) Since $\Phi(r, \theta)$ bounded in $r \leq R$, then $\Phi(r, \theta)$ is finite at $r = 0$ and thus $b_n = 0 \forall n \in [0, \infty)$.

$$\psi(R, \theta) = f(\theta) = a_0 + \sum_{n=1}^{\infty} R^n (A_n \cos(n\theta) + B_n \sin(n\theta))$$

Since $f(-\theta) = f(\theta)$, i.e. even symmetry, then $B_n = 0 \forall n$. Using Fourier series:

$$R^n A_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(\theta) \cos n\theta d\theta = \frac{2C}{\pi} \int_0^{\pi/2} \cos n\theta d\theta = \frac{2C}{n\pi} \sin \frac{n\pi}{2}$$

where $\sin \frac{n\pi}{2} = (-1)^{(n-1)/2}$ for odd n and zero otherwise.

$$a_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(\theta) d\theta = \frac{2C}{\pi} \int_0^{\pi/2} d\theta = \frac{C}{2}$$

Then relabelling the index (to factor in odd index only), the general solution is

$$\Phi(r, \theta) = \frac{C}{2} + \frac{2C}{\pi} \sum_{n=1}^{\infty} \frac{r^{2n-1} (-1)^{n+1}}{(2n-1) R^{2n-1}} \cos((2n-1)\theta)$$

(iii) Let $\Psi := \tilde{\Phi} - \Phi$. Since both Φ and $\tilde{\Phi}$ satisfy the same boundary conditions at $r = R$, then $\Psi(R, \theta) = f(\theta) - f(\theta) = 0 \forall R$. With the given hint, consider

$$\int_D \Psi \nabla^2 \Psi dA = \int_D \nabla \cdot (\Psi \nabla \Psi) - |\nabla \Psi|^2 dA = \int_{\partial D} \Psi \nabla \Psi dl - \int_D |\nabla \Psi|^2 dA$$

Since $\Psi = 0$ along ∂D , $\int_{\partial D} \Psi \nabla \Psi dl = 0$. But $\nabla^2 \Psi = \nabla^2 \tilde{\Phi} - \nabla^2 \Phi = 0$, so $\int_D \Psi \nabla^2 \Psi dA = 0 \implies \nabla \Psi = 0 \forall D$. But yet $\Psi = 0$ on $r = R$, then $\Phi = \tilde{\Phi}$ and the solution is unique.

(iv) Now we have $\lim_{r \rightarrow \infty} \Phi(r, \theta)$ to be finite, and thus $b_0 = 0$ and $a_n = 0 \forall n \geq 1$. Since the symmetry of $f(\theta)$ is unchanged, the general solution differs slightly from that in part (ii):

$$\Phi(r, \theta) = \frac{C}{2} + \frac{2C}{\pi} \sum_{n=1}^{\infty} \frac{R^{2n-1} (-1)^{n+1}}{(2n-1) r^{2n-1}} \cos((2n-1)\theta)$$

(v) The constant is $\lim_{r \rightarrow \infty} \Phi(r, \theta) = \frac{C}{2}$ and it depends on $f(\theta)$, hence not freely specifiable.

(vi) Repeat procedure in part (iii) but the boundary is now made of 2 disjoint regions - the circle at $r = R$ and the circle at $r = \infty$. Since the function is bounded, Ψ remains zero on the boundary, and the same conclusion - solution is unique, follows.

Problem 1.13 (Green's Functions):

(i) If

$$G_F(\mathbf{x}, \mathbf{y}) = \frac{1}{4\pi|\mathbf{x} - \mathbf{y}|} e^{i\omega|\mathbf{x} - \mathbf{y}|}$$

and if $\Psi(\mathbf{x})$ satisfies the equation

$$\frac{\partial^2 \Psi}{\partial x_1^2} + \frac{\partial^2 \Psi}{\partial x_2^2} + \frac{\partial^2 \Psi}{\partial x_3^2} = -\omega^2 \Psi \quad (*)$$

in a volume V , by applying Green's identity show that

$$\int_{\partial V} \left(\nabla G_F(\mathbf{x}, \mathbf{y}) \Psi(\mathbf{y}) - G_F(\mathbf{x}, \mathbf{y}) \nabla \Psi(\mathbf{y}) \right) \cdot d\mathbf{S}(\mathbf{y}) = \begin{cases} -\Psi(\mathbf{x}) & \mathbf{x} \in V \\ 0 & \mathbf{x} \notin V \end{cases} \quad (**)$$

where ∂V is a closed surface with **outward** unit normal \mathbf{n} which encloses the volume V . For surfaces we write the surface area element $d\mathbf{S} = \mathbf{n}dS$, and in (**), the gradient operator $\nabla = \mathbf{i} \frac{\partial}{\partial y_1} + \mathbf{j} \frac{\partial}{\partial y_2} + \mathbf{k} \frac{\partial}{\partial y_3}$ [4]

(ii) Now assume that Ψ satisfies (*) in the half-space $x_3 > 0$. By applying Green's identity, and taking into account the integral over a large hemisphere in the half-space $\{x_3 > 0\}$, show that if

$$\begin{aligned} \lim_{|\mathbf{y}| \rightarrow \infty} |\mathbf{y} \Psi(\mathbf{y})| &\leq \infty \\ \lim_{|\mathbf{y}| \rightarrow \infty} (\mathbf{y} \cdot \nabla - i\omega|\mathbf{y}|) \Psi(\mathbf{y}) &= 0 \end{aligned} \quad (\dagger)$$

then

[6]

$$\int_{y_3=0} \left(\Psi(\mathbf{y}) \nabla G_F(\mathbf{x}, \mathbf{y}) - G_F(\mathbf{x}, \mathbf{y}) \nabla \Psi(\mathbf{y}) \right) \cdot d\mathbf{S}(\mathbf{y}) = \begin{cases} -\Psi(\mathbf{x}) & \text{for } \mathbf{x} \text{ such that } x_3 > 0 \\ 0 & \text{for } \mathbf{x} \text{ such that } x_3 < 0 \end{cases}$$

(iii) Hence show that for $x_3 > 0$,

$$\Psi(\mathbf{x}) = -\frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{\partial \Psi}{\partial y_3}(y_1, y_2, 0) \frac{e^{i\omega R}}{R} dy_1 dy_2$$

where $R = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2 + x_3^2}$. [You may find it useful to consider also the function $G_F((x_1, x_2, -x_3), \mathbf{y})$.] [6]

(iv) Hence show that if $\Psi(\mathbf{x})$ satisfies the boundary conditions (\dagger) together with

$$\frac{\partial \Psi}{\partial x_3}(x_1, x_2, 0) = 0$$

then $\Psi(\mathbf{x}) = 0$ for all $x_3 > 0$.

[4]

Answer 1.13.

(i) Apply Green's identity:

$$\int_V u \nabla^2 v - v \nabla^2 u dV = \oint_{\partial V} (u \nabla v - v \nabla u) \cdot d\mathbf{S}$$

The corresponding Green's function G_F of (*) satisfies

$$(\nabla^2 + \omega^2)G_F(\mathbf{x}, \mathbf{y}) = -\delta(\mathbf{x} - \mathbf{y})$$

Replace u with Ψ and v with G_F , and add $0 = \omega^2 \Psi G_F - \omega^2 G_F \Psi$:

$$\begin{aligned} \oint_{\partial V} (\Psi \nabla G_F - G_F \nabla \Psi) \cdot d\mathbf{S} &= \int_V \psi \nabla^2 G_F - G_F \nabla^2 \Psi + \omega^2 \Psi G_F - \omega^2 \Psi G_F dV \\ &= \int_V \Psi (\nabla^2 + \omega^2) G_F - G_F (\nabla^2 + \omega^2) \Psi dV \end{aligned}$$

But $(\nabla^2 + \omega^2)\Psi = 0$ from (*), and

$$\int_V \Psi(\mathbf{y})(\nabla^2 + \omega^2)G_F(\mathbf{x}, \mathbf{y})dV = - \int_V \delta(\mathbf{x} - \mathbf{y})\Psi(\mathbf{y})dV = \begin{cases} -\Psi(\mathbf{x}) & \mathbf{x} \in V \\ 0 & \mathbf{x} \notin V \end{cases}$$

hence obtaining (**).

(ii) The closed surface ∂V in (**) is the boundary of the half-space $y_3 > 0$, consisting of the plane $y_3 = 0$ and the hemisphere is at $|\mathbf{y}| \rightarrow \infty$. Far away from \mathbf{x} , $dS(\mathbf{y}) \rightarrow \hat{\mathbf{y}} y^2 d\theta d\phi$. Since

$$G_F(\mathbf{x}, \mathbf{y}) = \frac{e^{i\omega|\mathbf{x}-\mathbf{y}|}}{4\pi|\mathbf{x}-\mathbf{y}|} \implies \nabla G_F(\mathbf{x}, \mathbf{y}) = \frac{1}{4\pi} \left(\frac{i\omega}{|\mathbf{x}-\mathbf{y}|} - \frac{1}{|\mathbf{x}-\mathbf{y}|^2} \right) e^{i\omega(\mathbf{x}-\mathbf{y})} (\hat{\mathbf{x}} - \hat{\mathbf{y}})$$

To evaluate the surface integral over the hemisphere, we take the limit of $|\mathbf{y}| \rightarrow \infty$ and after casually dropping off the exponential term:

$$(\Psi(\mathbf{y}) \nabla G_F(\mathbf{x}, \mathbf{y}) - G_F \nabla \Psi(\mathbf{y})) \cdot \hat{\mathbf{y}} y^2 \sim -\frac{1}{4\pi} (i\omega y - y) \Psi(\mathbf{y}) + \frac{1}{4\pi} \mathbf{y} \cdot \nabla \Psi(\mathbf{y})$$

which vanish as $|\mathbf{y}| \rightarrow \infty$ as given. We are thus left with the surface integral over the $y_3 = 0$ plane. The RHS result is obtained from (**).

(iii) The given hint suggests we need to use an image at $(x_1, x_2, -x_3)$ of equal magnitude, so after setting $r^2 = (x_1 - y_1)^2 + (x_2 - y_2)^2$, the combined Green's function is

$$G_F = \frac{1}{4\pi} \left(\frac{e^{i\omega\sqrt{r^2+(x_3-y_3)^2}}}{\sqrt{r^2+(x_3-y_3)^2}} + \frac{e^{i\omega\sqrt{r^2+(-x_3-y_3)^2}}}{\sqrt{r^2+(-x_3-y_3)^2}} \right)$$

Set $y_3 = 0$ then $R = \sqrt{r^2 + x_3^2}$, and so

$$\begin{aligned} -\Psi(\mathbf{x}) &= \frac{1}{4\pi} \int_{y_1=-\infty}^{\infty} \int_{y_2=-\infty}^{\infty} -\frac{2e^{i\omega R}}{R} \nabla \Psi \cdot (0, 0, -1) dy_2 dy_1 \\ &= \frac{1}{2\pi} \int_{y_1=-\infty}^{\infty} \int_{y_2=-\infty}^{\infty} \frac{e^{i\omega R}}{R} \frac{\partial \Psi}{\partial y_3}(y_1, y_2, 0) dy_1 dy_2 \end{aligned}$$

(iv) In this case, the integrand is zero (the given \mathbf{x} can be treated as a dummy variable) and $\Psi(\mathbf{x}) = 0 \forall x_3 > 0$.

Problem 1.14 (Contour Integration):

- (i) If a, b, c are real positive constants such that $a^2 > b^2 + c^2 > 0$, find the poles, z_1, z_2 of the analytic function [4]

$$f(z) = \frac{1}{az + 0.5b(z^2 + 1) - 0.5ic(z^2 - 1)}$$

- (ii) Show that

$$|z_1 z_2| = 1$$

and hence that one pole lies inside and one outside the unit circle. [3]

- (iii) Are the poles simple? [3]

- (iv) Hence show, using the contour $|z| = 1$ and Cauchy's Theorem, how one may evaluate the integral [5]

$$I = \int_{-\pi}^{\pi} \frac{d\theta}{a + b \cos \theta + c \sin \theta}$$

- (v) Give the value of I . [5]

Answer 1.14.

- (i) The poles occur when

$$0 = z^2 \left(\frac{c}{2i} + \frac{b}{2} \right) + az + \frac{1}{2}(b + ic) \implies z_{1/2} = \frac{(-a \pm \sqrt{a^2 - (b^2 + c^2)})(b + ic)}{b^2 + c^2}$$

Since $a^2 > b^2 + c^2$, the discriminant α is real and positive. Then, $z_{1/2} = \frac{(-a \pm \alpha)(b + ic)}{b^2 + c^2}$.

- (ii) Evaluate

$$|z_1 z_2|^2 = \frac{a^2 - \alpha^2}{b^2 + c^2} = \frac{a^2 - (a^2 - (b^2 + c^2))}{b^2 + c^2} = 1$$

For the statement to be false, we require $|z_1| = 1$ and $|z_2| = 1$. Evaluate

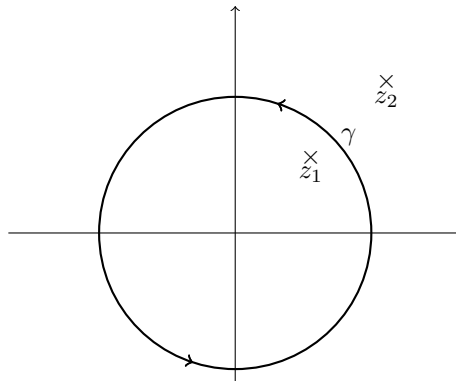
$$|z_2| = \left| \frac{-a - \alpha}{b^2 + c^2} \right| \sqrt{b^2 + c^2} = \frac{a}{\sqrt{b^2 + c^2}} + \sqrt{\frac{a^2}{b^2 + c^2} + 1} > 1$$

So, z_2 lies outside the unit circle and z_1 lies inside.

- (iii) For poles to be simple, we require the following limits to be finite.

$$\lim_{z \rightarrow z_{1,2}} (z - z_{1,2}) \frac{1}{0.5(b - ic)(z - z_1)(z - z_2)} = \begin{cases} \frac{2}{b - ic} \frac{b - ic}{2\alpha} = \frac{1}{\sqrt{a^2 - (b^2 + c^2)}} & z \rightarrow z_1 \\ \frac{2}{b - ic} \frac{-b - ic}{2\alpha} = -\frac{1}{\sqrt{a^2 - (b^2 + c^2)}} & z \rightarrow z_2 \end{cases}$$

- (iv) Using the contour $|z| = 1$, we have the pole z_1 to be in the circle and z_2 outside. Parametrize the contour $\gamma: z = e^{i\theta}$.



$$\begin{aligned}
I &= \int_{-\pi}^{\pi} \frac{d\theta}{a + b \cos \theta + c \sin \theta} \\
&= \oint_{\gamma} \frac{1}{a + \frac{b}{2}(z + z^{-1}) + \frac{c}{2i}(z - z^{-1})} \frac{dz}{iz} \\
&= \frac{1}{i} \oint_{\gamma} f(z) dz
\end{aligned}$$

Now, invoke Cauchy's theorem, i.e. $\oint_{\gamma} f(z) dz = 2\pi i \sum_i \text{res}_{z=z_i} f(z)$ where a finite number of singularities z_i are enclosed in the contour γ .

(v) The residue of z_1 is

$$\text{res}_{z=z_1} f(z) = \frac{1}{\sqrt{a^2 - (b^2 + c^2)}} \implies I = \frac{2\pi}{\sqrt{a^2 - (b^2 + c^2)}}$$

Problem 1.15 (Transform Methods):

(i) Find an ordinary differential equation satisfied by the Fourier transform

$$\tilde{\theta}(k, t) = \int_{-\infty}^{\infty} e^{-ikx} \theta(x, t) dx$$

of a solution $\theta(x, t)$ of the heat equation

$$\frac{\partial \theta}{\partial t} = \frac{\partial^2 \theta}{\partial x^2}$$

on the interval $-\infty < x < \infty$ for $t \geq 0$.

[2]

(ii) Give an expression for the solution $\theta(x, t)$ in terms of the Fourier transform of the initial distribution of temperature $\tilde{\theta}(k, 0)$.

[2]

(iii) Use the convolution theorem to express $\theta(x, t)$ as a convolution

$$\theta(x, t) = \int_{-\infty}^{\infty} \theta(y, 0) G(x - y, t) dy$$

giving an explicit form for $G(x - y, t)$.

[5]

(iv) Suppose that the initial distribution is of Gaussian form:

$$\theta(x, 0) = A_0 e^{-a_0(x-x_0)^2} \quad (*)$$

where x_0 , A_0 and $a_0 > 0$ are constants. Show that $\theta(x, t)$ is of Gaussian form and give an explicit formula for it.

[6]

(v) Find an expression for $\theta(x, t)$ in terms of the error function $\text{erf}(x)$ defined by

$$\text{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-u^2} du$$

in the case that

[5]

$$\theta(x, 0) = \begin{cases} 0 & x < a \\ B & a < x < b \\ 0 & x > b \end{cases} \quad (\dagger)$$

(vi) Hence show that at late times, in the interval $a < x < b$,

$$\theta(x, t) \approx \frac{B(b-a)}{\sqrt{4\pi t}}$$

Show in both cases (*) and (†) and that at late times the heat has spread out over a distance which is $O(\sqrt{t})$.

[2]

You may assume that

$$\int_{-\infty}^{\infty} e^{-(x+iy)^2} dx = \sqrt{\pi}$$

for x and y real.

Answer 1.15.

(i) Assume θ and $\frac{\partial \theta}{\partial x}$ vanish at $x = \pm\infty$, perform Fourier transform on the heat equation,

$$\int_{-\infty}^{\infty} e^{-ikx} \frac{\partial \theta}{\partial t} dx = \int_{-\infty}^{\infty} \frac{\partial^2 \theta}{\partial x^2} e^{-ikx} dx \implies \frac{\partial \tilde{\theta}}{\partial t} = -k^2 \tilde{\theta}$$

(ii) The solution of the differential equation is $\tilde{\theta}(k, t) = \tilde{\theta}(k, 0)e^{-k^2 t}$ and so perform inverse Fourier transform,

$$\theta(x, t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} \tilde{\theta}(k, 0) e^{-k^2 t} dk$$

(iii) By convolution theorem, $\mathcal{F}^{-1}[f\tilde{g}] = f * g$. Then

$$\theta(x, t) = \theta(x, 0) * \mathcal{F}^{-1}[e^{-k^2 t}]$$

where the inverse Fourier transform gives

$$\begin{aligned} \mathcal{F}^{-1}[e^{-k^2 t}] &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-k^2 t} e^{ikx} dk \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-t((k - \frac{ix}{2t}) + \frac{x^2}{4t^2})} dk \\ &= \frac{e^{-x^2/4t}}{2\pi} \int_{-\infty}^{\infty} e^{-t(k - \frac{ix}{2t})^2} dk \\ &= \frac{1}{\sqrt{4\pi t}} e^{-x^2/4t} \end{aligned}$$

where we used the hint. Hence,

$$\theta(x, t) = \int_{-\infty}^{\infty} \theta(y, 0) \frac{1}{\sqrt{4\pi t}} e^{-(x-y)^2/4t} dy \implies G(x-y, t) = \frac{1}{\sqrt{4\pi t}} e^{-(x-y)^2/4t}$$

This is also called the fundamental solution of the heat equation.

(iv) Given $\theta(x, 0)$ in (*),

$$\begin{aligned} \theta(x, t) &= \int_{-\infty}^{\infty} \frac{A_0}{\sqrt{4\pi t}} e^{-a_0(y-x_0)^2} e^{-(x-y)^2/4t} dy \\ &= \frac{A_0}{\sqrt{4\pi t}} \int_{-\infty}^{\infty} e^{-a_0(y-\Delta x)^2} e^{-y^2/4t} dy \\ &= \frac{A_0}{\sqrt{4\pi t}} \int_{-\infty}^{\infty} e^{-y^2(a_0/4t) + 2a_0 y \Delta x - a_0 \Delta x^2} dy \\ &= \frac{A_0}{\sqrt{4\pi t}} e^{-a_0 \Delta x^2} \int_{-\infty}^{\infty} \exp\left(-\left(a_0 + (1/4t)\right)\left(y^2 - \frac{2a_0 \Delta x}{a_0 + (1/4t)} y\right)\right) dy \\ &= \frac{A_0}{\sqrt{4\pi t}} e^{-a_0 \Delta x^2} \int_{-\infty}^{\infty} \exp\left[-\left(a_0 + \frac{1}{4t}\right)\left(y^2 - \frac{a_0 \Delta x}{a_0 + (1/4t)}\right)^2 - \left(\frac{a_0 \Delta x}{a_0 + (1/4t)}\right)^2\right] dy \\ &= \frac{A_0}{\sqrt{4\pi t}} e^{-a_0 \Delta x^2} e^{\frac{a_0^2 \Delta x^2}{a_0 + (1/4t)}} \int_{-\infty}^{\infty} e^{-(a_0 + (1/4t))y'^2} dy' \\ &= \frac{A_0}{\sqrt{4\pi t}} \exp\left[-\frac{a_0 \Delta x^2}{a_0 + (1/4t)}(a_0 + (1/4t) - a_0)\right] \sqrt{\frac{\pi}{a_0 + (1/4t)}} \\ &= \frac{A_0}{\sqrt{1 + 4a_0 t}} e^{-\frac{\Delta x^2}{4t + (1/a_0)}} \end{aligned}$$

where $\Delta x = x - x_0$ and we used the substitution $y \rightarrow y + x$. The final result is also Gaussian.

(v) Use result from (iii),

$$\begin{aligned}
 \theta(x, t) &= \int_a^b \frac{B}{\sqrt{4\pi t}} e^{-(x-y)^2/4t} dy \\
 &= \frac{B}{\sqrt{4\pi t}} \int_{\frac{a-x}{2\sqrt{t}}}^{\frac{b-x}{2\sqrt{t}}} e^{-u^2/4t} 2\sqrt{t} du \\
 &= \frac{B}{\sqrt{\pi}} \left[\operatorname{erf} \left(\frac{b-x}{2\sqrt{t}} \right) - \operatorname{erf} \left(\frac{a-x}{2\sqrt{t}} \right) \right]
 \end{aligned}$$

(vi) Given $\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-u^2} du$, then

$$\operatorname{erf}(x) \approx \operatorname{erf}(0) + xe^x + O(x^2) = \operatorname{erf}(0) + x + O(x^2)$$

which is a valid approximation as $t \rightarrow \infty$. Hence,

$$\theta(x, t) \approx \frac{B}{\sqrt{4\pi t}} (b - a)$$

For the cases:

- (*): the variance is $\frac{1}{2}(4t + (1/a_0))$ and the standard deviation is

$$\sqrt{2t} \sqrt{1 + \frac{1}{4a_0 t}} \approx \sqrt{2t}$$

as $t \rightarrow \infty$. This is of order $O(\sqrt{t})$.

- (†): $\theta(x, t) \sim O(1/\sqrt{t})$ and hence the heat spread out over \sqrt{t} .

Problem 1.16 (Tensors):

- (i) Define the terms tensor and isotropic tensor. Show that ϵ_{ijk} , the completely anti-symmetric tensor with $\epsilon_{123} = 1$, is isotropic. Let A be a rank two tensor with matrix entries A_{ij} . Using the formula

$$\det(A)\epsilon_{ijk} = \epsilon_{lmn}A_{il}A_{jm}A_{kn}$$

deduce that

$$\det(A) = \frac{1}{6}\epsilon_{ijk}\epsilon_{lmn}A_{il}A_{jm}A_{kn}$$

and hence show that the determinant is a scalar. Show also that the inverse matrix A^{-1} has entries given by the formula [6]

$$A_{ba}^{-1} = \frac{1}{2\det(A)}\epsilon_{ajk}\epsilon_{bmn}A_{jm}A_{kn}$$

- (ii) Prove that the partial derivative $\frac{\partial \det(A)}{\partial A_{ab}}$ is given by

$$\frac{\partial \det(A)}{\partial A_{ab}} = \det(A)(A^{-1})_{ab}^T$$

where T denotes matrix transpose. [8]

- (iii) Consider the case that $A_{ij}(t, \mathbf{x})$ arises as the Jacobian matrix of a smooth time-dependent transformation $x_i \rightarrow y_i = \Phi_i(t, \mathbf{x})$, i.e.

$$A_{ij}(t, \mathbf{x}) = \frac{\partial y_j}{\partial x_i} = \frac{\partial \Phi_j}{\partial x_i}(t, \mathbf{x})$$

and assume that $\Phi_i(t, \mathbf{x}) = x_i + tu_i(\mathbf{x}) + O(t^2)$ for small t . By considering $\frac{d}{dt} \det(A)(t, \mathbf{x})$, show that $\det(A)(t, \mathbf{x}) = 1 + O(t^2)$ for small t if $\nabla \cdot \mathbf{u} = 0$. [6]

The summation convention is assumed throughout this question.

Answer 1.16.

- (i) A tensor T is an object that is the same in all frames related by an orthogonal transformation. The tensor's components $T_{ijk\dots}$ with respect to two such frames related by such an orthogonal transformation (given by matrix L) must change as

$$T'_{ijk} = (\det L)^p L_{i\alpha} L_{j\beta} L_{k\gamma} \dots T_{\alpha\beta\gamma\dots}$$

where $p = 1$ for pseudotensors and $p = 0$ otherwise.

An isotropic tensor has its components to be the same in all frames, i.e. $T'_{ijk\dots} = T_{\alpha\beta\gamma\dots}$. ϵ_{ijk} is a pseudotensor and transforms as

$$\epsilon'_{ijk} = \det L L_{i\alpha} L_{j\beta} L_{k\gamma} \epsilon_{\alpha\beta\gamma} = (\det L)^2 \epsilon_{ijk}$$

Since L is orthogonal, $\det L = \pm 1 \implies (\det L)^2 = 1$. Hence, $\epsilon'_{ijk} = \epsilon_{ijk}$, i.e. is isotropic.

Evaluate $\epsilon_{ijk}\epsilon_{ijk}$:

$$\epsilon_{ijk}\epsilon_{ijk} = \delta_{jj}\delta_{kk} - \delta_{jk}\delta_{kj} = 3 \times 3 - \delta_{jj} = 9 - 3 = 6$$

so with the given formula:

$$\epsilon_{ijk}\epsilon_{lmn}A_{il}A_{jm}A_{kn} = \epsilon_{ijk}\epsilon_{ijk}\det(A) = 6\det(A)$$

Next, we show that $\det A$ indeed transforms as a scalar:

$$\begin{aligned}
 (\det A)' &= \frac{1}{6} \epsilon_{ijk} \epsilon_{lmn} A'_{il} A'_{jm} A'_{kn} \\
 &= \frac{1}{6} \epsilon_{ijk} \epsilon_{lmn} L_{i\alpha} L_{lp} A_{\alpha p} L_{j\beta} L_{mq} A_{\beta q} L_{k\gamma} L_{nr} A_{\gamma r} \\
 &= \frac{1}{6} \epsilon_{ijk} L_{i\alpha} L_{j\beta} L_{k\gamma} \epsilon_{lmn} L_{lp} L_{mq} L_{nr} A_{\alpha p} A_{\beta q} A_{\gamma r} \\
 &= \frac{1}{6} \det L \epsilon_{\alpha\beta\gamma} \epsilon_{pqr} \det L A_{\alpha p} A_{\beta q} A_{\gamma r} \\
 &= \frac{1}{6} \det(L) \det(L) \epsilon_{\alpha\beta\gamma} \epsilon_{pqr} A_{\alpha p} A_{\beta q} A_{\gamma r} \\
 &= \det A
 \end{aligned}$$

where we first invoked transformation law, rearranged the terms, used the given formula for $\det A \epsilon_{ijk}$, and finally invoke the result for $\det A$. Hence, $\det A$ transforms like a scalar. Consider the tensor $Q_{ba} := \frac{1}{2 \det A} \epsilon_{ajk} \epsilon_{bmn} A_{jm} A_{kn}$:

$$\begin{aligned}
 Q_{ba} A_{ac} &= \frac{1}{2 \det A} \epsilon_{ajk} \epsilon_{bmn} A_{jm} A_{kn} A_{ac} \\
 &= \frac{1}{2 \det A} \epsilon_{cmn} \det A \epsilon_{bmn} \\
 &= \frac{1}{2} \epsilon_{mnc} \epsilon_{mnb} \\
 &= \frac{1}{2} (\delta_{cb} \delta_{nn} - \delta_{cn} \delta_{nb}) \\
 &= \frac{1}{2} (3 - 1) \delta_{cb} \\
 &= \delta_{cb}
 \end{aligned}$$

Hence, $Q_{ba} = A_{ba}^{-1}$ is the inverse of A .

(ii) We used the result $\frac{\partial A_{il}}{\partial A_{ab}} = \delta_{ia} \delta_{lb}$ and differentiate the $\det A$ result from part (i):

$$\begin{aligned}
 \frac{\partial \det A}{\partial A_{ab}} &= \frac{1}{6} \epsilon_{ijk} \epsilon_{lmn} \left(\frac{\partial A_{il}}{\partial A_{ab}} A_{jm} A_{kn} + A_{il} \frac{\partial A_{jm}}{\partial A_{ab}} A_{kn} + A_{il} A_{jm} \frac{\partial A_{kn}}{\partial A_{ab}} \right) \\
 &= \frac{1}{6} \epsilon_{ijk} \epsilon_{lmn} (\delta_{ia} \delta_{lb} A_{jm} A_{kn} + A_{il} \delta_{ja} \delta_{mb} A_{kn} + A_{il} A_{jm} \delta_{ka} \delta_{nb}) \\
 &= \frac{1}{6} (\epsilon_{ajk} \epsilon_{bmn} A_{jm} A_{kn} + \epsilon_{ajk} \epsilon_{lbn} A_{il} A_{kn} + \epsilon_{ija} \epsilon_{lmb} A_{il} A_{jm}) \\
 &= \frac{1}{6} (2 \det A (A^{-1})_{ab}^T) + \frac{1}{6} (2 \det A (A^{-1})_{ab}^T) + \frac{1}{6} (2 \det A (A^{-1})_{ab}^T) \\
 &= \det A (A^{-1})_{ab}^T
 \end{aligned}$$

where we used the result for A_{ba}^{-1} in part (i).

(iii) We are given $A_{ij}(t, \mathbf{x}) = \frac{\partial \Phi_i}{\partial x_j}(t, \mathbf{x}) = \delta_{ij} + t \frac{\partial u_i}{\partial x_j} + O(t^2)$:

$$\begin{aligned}
 \det A &= \frac{1}{6} \epsilon_{ijk} \epsilon_{lmn} [(\delta_{il} + t \frac{\partial u_i}{\partial x_l} + O(t^2))(\delta_{jm} + t \frac{\partial u_j}{\partial x_m} + O(t^2))(\delta_{kn} + t \frac{\partial u_k}{\partial x_n} + O(t^2))] \\
 &= \frac{1}{6} \epsilon_{ijk} \epsilon_{lmn} \left[\delta_{il} \delta_{jm} \delta_{kn} + t \left(\delta_{il} \delta_{jm} \frac{\partial u_k}{\partial x_n} + \delta_{jm} \delta_{kn} \frac{\partial u_i}{\partial x_l} + \delta_{kn} \delta_{il} \frac{\partial u_j}{\partial x_m} \right) \right] + O(t^2) \\
 &= \frac{1}{6} \epsilon_{ijk} \epsilon_{ijk} + \frac{1}{6} t \left(\epsilon_{ijk} \epsilon_{ijn} \frac{\partial u_k}{\partial x_n} + \epsilon_{ijk} \epsilon_{ljk} \frac{\partial u_i}{\partial x_l} + \epsilon_{ijk} \epsilon_{imk} \frac{\partial u_j}{\partial x_m} \right) + O(t^2) \\
 &= \frac{6}{6} + \frac{t}{6} \left(\delta_{nk} \frac{\partial u_k}{\partial x_n} + \delta_{il} \frac{\partial u_i}{\partial x_l} + \delta_{jm} \frac{\partial u_j}{\partial x_m} \right) + O(t^2) \\
 &= 1 + t \nabla \cdot \mathbf{u} + O(t^2)
 \end{aligned}$$

Thus, $\frac{d}{dt} \det A = \nabla \cdot \mathbf{u} + O(t)$. If $\nabla \cdot \mathbf{u} = 0$, then $\frac{d}{dt} \det A = O(t)$, hence $\det A = \det A(t=0) + O(t^2) = 1 + O(t^2)$, where $A(t=0)$ is the identity matrix.

Problem 1.17 (Normal Modes):

- (i) A mechanical system with N degrees of freedom (q_1, \dots, q_N) described by a Lagrangian of the form

$$\mathcal{L} = \frac{1}{2} \sum_{ij} T_{ij} \dot{q}_i \dot{q}_j - V(q_1, \dots, q_N)$$

where T_{ij} is a constant symmetric positive definite matrix, is subject to small oscillations about an equilibrium point. Define the normal modes and normal frequencies. State and derive the orthogonality relation for the normal modes. [3]

- (ii) Consider three point masses of equal mass m , situated at points $\mathbf{x}_1 = (X_1, Y_1)$, $\mathbf{x}_2 = (X_2, Y_2)$ and $\mathbf{x}_3 = (X_3, Y_3)$ in the plane, and connected by springs of equal unstretched length $l = \sqrt{3}$ and spring constant k . Write down the potential and kinetic energies and show that they are unchanged by an overall translation and by an overall rigid rotation of the system. Show that configurations in which the three masses lie at the vertices of equilateral triangles whose sides have length $l = \sqrt{3}$ are equilibrium points for the system. [1]
- (iii) Write down the potential energy V for the system when the masses are located at $(X_1, Y_1) = (q_1, 1 + q_2)$, $(X_2, Y_2) = (\frac{\sqrt{3}}{2} + q_3, -\frac{1}{2} + q_4)$ and $(X_3, Y_3) = (-\frac{\sqrt{3}}{2} + q_5, -\frac{1}{2} + q_6)$. Show that for small (q_1, \dots, q_6) the potential energy V can be expanded to quadratic order as [3]

$$V = \frac{1}{2} k (q_5 - q_3)^2 + \frac{k}{2} \left[\frac{1}{2} (q_1 - q_5) + \frac{\sqrt{3}}{2} (q_2 - q_6) \right]^2 + \frac{k}{2} \left[-\frac{1}{2} (q_1 - q_3) + \frac{\sqrt{3}}{2} (q_2 - q_4) \right]^2 + \dots$$

- (iv) Set up the problem for small oscillations around the configuration in which the masses are at the vertices of an equilateral triangle centred at the origin, with the first mass situated at $(0, 1)$ and the remaining two at $(\pm \frac{\sqrt{3}}{2}, -\frac{1}{2})$. Show that the Lagrangian for this system takes the form [6]

$$\mathcal{L} = \frac{m}{2} \sum_j \dot{q}_j^2 - \frac{1}{2} \sum_{ij} V_{ij} q_i q_j$$

where

$$V_{ij} = \frac{k}{4} \begin{pmatrix} 2 & 0 & -1 & \sqrt{3} & -1 & -\sqrt{3} \\ 0 & 6 & \sqrt{3} & -3 & -\sqrt{3} & -3 \\ -1 & \sqrt{3} & 5 & -\sqrt{3} & -4 & 0 \\ \sqrt{3} & -3 & -\sqrt{3} & 3 & 0 & 0 \\ -1 & -\sqrt{3} & -4 & 0 & 5 & \sqrt{3} \\ -\sqrt{3} & -3 & 0 & 0 & \sqrt{3} & 3 \end{pmatrix}$$

- (v) Use the translations and rigid rotations that you wrote down above to show that there are three normal modes of zero frequency, giving them explicitly. [4]
- (vi) Prove that there is a normal mode in which all of the masses move radially and find its frequency. [3]

Answer 1.17.

- (i) A normal mode of an oscillating system is a pattern of motion in which all parts of the system move sinusoidally with the same frequency (termed as the normal frequency) and with a fixed phase relation. The free motion of the mechanical system described by the normal modes takes place at the normal frequencies which are fixed frequencies (can compute from the Lagrangian of the system).

The orthogonality relation of two normal modes $\mathbf{Q}^{(i)}$ and $\mathbf{Q}^{(j)}$ is

$$(\mathbf{Q}^{(i)})^T \mathcal{T} \mathbf{Q}^{(j)} = \delta_{ij}$$

where the orthogonal relation is with respect to the matrix with entries $(\mathcal{T})_{ij} = T_{ij}$. This can be computed from the Lagrangian.

By the least action principle, the action is stationary when the Lagrangian of the mechanical system satisfies the Euler-Lagrange equations

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} - \frac{\partial \mathcal{L}}{\partial q_i} = 0, \quad i = 1, \dots, N$$

which gives the equations of motion (N coupled second-order linear equations)

$$T_{ij}\ddot{q}_j + V_{ij}q_j = 0, \quad j = 1, \dots, N$$

Look for normal mode solutions of the form $q_i(t) = Q_i e^{i\omega(t-t_0)}$, where \mathbf{Q} is independent of t . Plug this into the equation of motion, we get

$$-\omega^2 T_{ij}Q_j + V_{ij}Q_i = 0 \implies \det(-\omega^2 \mathcal{T} + \mathcal{V}) = 0$$

Looking for the non-trivial solutions \mathbf{Q} is equivalent to finding the eigenfrequencies ω by solving $\det(-\omega^2 \mathcal{T} + \mathcal{V}) = 0$. Suppose there are two generalized eigenvectors of distinct normal frequencies, namely $\mathbf{Q}^{(i)}$ and $\mathbf{Q}^{(j)}$ with $\omega_i \neq \omega_j$. Then, they separately satisfy

$$(-\omega_i^2 \mathcal{T} + \mathcal{V})\mathbf{Q}^{(i)} = \mathbf{0}, \quad (-\omega_j^2 \mathcal{T} + \mathcal{V})\mathbf{Q}^{(j)} = \mathbf{0}$$

This gives $(\omega_i^2 - \omega_j^2)(\mathbf{Q}^{(i)})^T \mathcal{T} \mathbf{Q}^{(j)} = 0$. Since $\omega_i^2 - \omega_j^2 \neq 0$, we must have $(\mathbf{Q}^{(i)})^T \mathcal{T} \mathbf{Q}^{(j)} = 0$, i.e. the normal modes are orthogonal with respect to \mathcal{T} .

(ii) The kinetic energy is

$$T = \frac{1}{2}m(\dot{X}_1^2 + \dot{Y}_1^2 + \dot{X}_2^2 + \dot{Y}_2^2 + \dot{X}_3^2 + \dot{Y}_3^2)$$

and the potential energy is

$$V = \frac{1}{2}k[(\ell_A - \ell_0)^2 + (\ell_B - \ell_0)^2 + (\ell_C - \ell_0)^2]$$

where $\ell_0 = \sqrt{3}$, $\ell_A = \sqrt{(X_1 - X_2)^2 + (Y_1 - Y_2)^2}$, $\ell_B = \sqrt{(X_2 - X_3)^2 + (Y_2 - Y_3)^2}$ and $\ell_C = \sqrt{(X_1 - X_3)^2 + (Y_1 - Y_3)^2}$.

Suppose we do an overall translation, say $X_i \mapsto X_i + \varepsilon$ and $Y_i \mapsto Y_i + \eta$, then we merely have \dot{X}_i invariant and thus the kinetic energy T is invariant. The extent of stretching is also unchanged, hence the potential energy V is invariant. Now suppose we do a rigid rotation, then the position of the centre of mass is unchanged and the extensions of the springs are unchanged. Hence, the kinetic energy T and potential energy V are invariant.

Equilibrium: When the strings have length $\sqrt{3}$ each, they are unstretched, and the masses are stationary, hence no kinetic energy and potential energy. With zero energy, the system is trivially at equilibrium.

(iii) Let (X_i, Y_i) be the vector \mathbf{X}_i . The quadratic approximation to the potential energy for each string (of original length ℓ_0) is

$$\frac{1}{2}k(|\mathbf{X}_i - \mathbf{X}_j| - \ell_0)^2 \approx \frac{k}{2} \left(\frac{\mathbf{a} \cdot \mathbf{v}}{\ell_0} \right)^2$$

where we write $\mathbf{X}_i - \mathbf{X}_j$ as $\mathbf{v} + \mathbf{a}$ where $|\mathbf{a}| = \ell_0 \gg |\mathbf{v}|$ and thus,

$$|\mathbf{a} + \mathbf{v}| = (\mathbf{a} \cdot \mathbf{a} + 2\mathbf{a} \cdot \mathbf{v} + \mathbf{v} \cdot \mathbf{v})^{1/2} = \ell_0 \left(1 + \frac{\mathbf{a} \cdot \mathbf{v}}{\ell_0^2} + \dots \right)$$

The potential energies in each spring are

$$\begin{aligned} \mathbf{x}_1 - \mathbf{x}_2 &= \begin{pmatrix} q_1 - q_3 \\ q_2 - q_4 \end{pmatrix} + \begin{pmatrix} -\sqrt{3}/2 \\ 3/2 \end{pmatrix} \implies V_{1,2} = \frac{1}{2}k \left[\frac{-(\sqrt{3}/2)(q_1 - q_3) + (3/2)(q_2 - q_4)}{\sqrt{3}} \right]^2 \\ \mathbf{x}_2 - \mathbf{x}_3 &= \begin{pmatrix} q_3 - q_5 \\ q_4 - q_6 \end{pmatrix} + \begin{pmatrix} \sqrt{3} \\ 0 \end{pmatrix} \implies V_{3,2} = \frac{1}{2}k \left[\frac{\sqrt{3}(q_3 - q_5)}{\sqrt{3}} \right]^2 \\ \mathbf{x}_1 - \mathbf{x}_3 &= \begin{pmatrix} q_1 - q_5 \\ q_2 - q_6 \end{pmatrix} + \begin{pmatrix} \sqrt{3}/2 \\ 3/2 \end{pmatrix} \implies V_{1,3} = \frac{1}{2}k \left[\frac{(\sqrt{3}/2)(q_1 - q_5) + (3/2)(q_2 - q_6)}{\sqrt{3}} \right]^2 \end{aligned}$$

The potential energy, expanded to quadratic order, will be a sum of these 3 terms.

(iv) Expand the potential energy expression in part (iii):

$$\begin{aligned}
 V = & \frac{1}{2}k \left(\frac{q_1^2}{4} + \frac{q_1^2}{4} + \frac{3q_2^2}{4} + \frac{3q_2^2}{4} + q_3^2 + \frac{q_3^2}{4} + \frac{3q_4^2}{4} + \frac{q_5^2}{4} + q_5^2 + \frac{3q_6^2}{4} \right) \\
 & + \frac{1}{2}k \left(-\frac{1}{2}q_1q_3 + \frac{\sqrt{3}}{2}q_1q_4 - \frac{1}{2}q_1q_5 - \frac{\sqrt{3}}{2}q_1q_6 + \frac{\sqrt{3}}{2}q_2q_3 - \frac{3}{2}q_2q_4 - \frac{\sqrt{3}}{2}q_2q_5 - \frac{3}{2}q_2q_6 \right. \\
 & \left. - \frac{\sqrt{3}}{2}q_3q_4 - 2q_5q_3 + \frac{\sqrt{3}}{2}q_5q_6 \right)
 \end{aligned}$$

Write the potential energy as $V = \frac{1}{2}V_{ij}q_iq_j$. We do this by noting:

- For the cross-terms of the form $\frac{1}{2}k\frac{a}{2}q_iq_j$ for some coefficient a , take a for its V_{ij} ;
- For the quadratic terms of the form $\frac{1}{2}k\frac{b}{4}q_iq_j$ for some coefficient b , take b for its V_{ii} .

Hence, we obtain the desired V_{ij} matrix. For the kinetic energy, we have

$$T = \frac{1}{2}m \left(\sum_{i=1}^3 |\dot{\mathbf{X}}_i|^2 \right) = \frac{1}{2}m \left(\sum_{i=1}^6 \dot{q}_i^2 \right)$$

(v) Let the translations be $\mathbf{Q}_x = (1, 0, 1, 0, 1, 0)^T$ and $\mathbf{Q}_y = (0, 1, 0, 1, 0, 1)^T$ and the rotation be $\mathbf{Q}_R = (1, 0, -\cos 60^\circ, -\sin 60^\circ, -\cos 60^\circ, \sin 60^\circ)^T = (1, 0, -0.5, -\sqrt{3}/2, -1/2, \sqrt{3}/2)^T$, then

$$\begin{aligned}
 \mathcal{V}\mathbf{Q}_R &= \frac{k}{4} \begin{pmatrix} 2 - (-0.5) - \sqrt{3}\sqrt{3}/2 - (-0.5) - \sqrt{3}\sqrt{3}/2 \\ -\sqrt{3}/2 + 3\sqrt{3}/2 + \sqrt{3}/2 - 3\sqrt{3}/2 \\ -1 - 5/2 + 3/2 + 2 \\ \sqrt{3} + \sqrt{3}/2 - 3\sqrt{3}/2 \\ -1 + 2 + 3/2 - 5/2 \\ -\sqrt{3} - \sqrt{3}/2 + 3\sqrt{3}/2 \end{pmatrix} = \mathbf{0} \\
 \mathcal{V}\mathbf{Q}_x &= \frac{k}{4} \begin{pmatrix} 2 - 1 - 1 \\ \sqrt{3} - \sqrt{3} \\ -1 + 5 - 4 \\ \sqrt{3} - \sqrt{3} \\ -1 - 4 + 5 \\ -\sqrt{3} + \sqrt{3} \end{pmatrix} = \mathbf{0}, \quad \mathcal{V}\mathbf{Q}_y = \frac{k}{4} \begin{pmatrix} \sqrt{3} - \sqrt{3} \\ 6 - 3 - 3 \\ -1 + 5 - 4 \\ \sqrt{3} - \sqrt{3} \\ -3 + 3 \\ -\sqrt{3} + \sqrt{3} \end{pmatrix} = \mathbf{0}
 \end{aligned}$$

Since $\mathcal{V}\mathbf{Q} = \omega^2 T\mathbf{Q}$, then ω for $\mathbf{Q}_R, \mathbf{Q}_x, \mathbf{Q}_y$ is zero.

(vi) The (radially expanding) mode is

$$\mathbf{Q}_E = (0, 1, \sin 60^\circ, -\cos 60^\circ, -\sin 60^\circ, -\cos 60^\circ)^T = (0, 1, \sqrt{3}/2, -1/2, -\sqrt{3}/2, -1/2)^T$$

The frequency is

$$\omega^2 \mathcal{T}\mathbf{Q}_E = \mathcal{V}\mathbf{Q}_E = \frac{k}{4} \begin{pmatrix} -\sqrt{3}/2 - \sqrt{3}/2 + \sqrt{3}/2 + \sqrt{3}/2 \\ 6 + \sqrt{3}\sqrt{3}/2 - (1/2)(-3) - \sqrt{3}(-\sqrt{3}/2) - 3(-1/2) \\ \sqrt{3} + 5\sqrt{3}/2 + \sqrt{3}/2 + 4\sqrt{3}/2 \\ -3 - \sqrt{3}\sqrt{3}/2 - 3/2 \\ -\sqrt{3} - 4(\sqrt{3}/2) + 5(-\sqrt{3}/2) - \sqrt{3}/2 \\ -3 - \sqrt{3}\sqrt{3}/2 - 3/2 \end{pmatrix} = \frac{12k}{4} \begin{pmatrix} 0 \\ 1 \\ \sqrt{3}/2 \\ -1/2 \\ -\sqrt{3}/2 \\ -1/2 \end{pmatrix}$$

where $\mathcal{T} = mI_{6 \times 6}$, so the eigenfrequency is $\sqrt{3k/m}$.

Problem 1.18 (Group Theory):

- (i) Define the order of a finite group G and state Lagrange's theorem on the order of a subgroup K of G . [2]
- (ii) Prove that every order four group is either the cyclic group C_4 or is the Vierergruppe V , i.e. the order four abelian group $\{I, a, b, c\}$ in which $a^2 = b^2 = c^2 = I$ and $ab = c$. [5]
- (iii) Define a homomorphism $\Phi : G \rightarrow H$ between finite groups G and H . [1]
- (iv) Prove that K , the kernel of a homomorphism $\Phi : G \rightarrow H$, is a normal subgroup of G . Assuming that the image of Φ contains all of H , prove that the quotient group G/K is isomorphic to H . [4]

Consider the multiplicative group Q which has elements $\pm 1, \pm i, \pm j, \pm k$, where 1 is the identity, $(-1)^2 = 1$ and i, j, k satisfy

$$i^2 = j^2 = k^2 = -1$$

and

$$ij = k, jk = i, ki = j$$

- (v) Show that these relations imply that (-1) commutes with i, j, k and deduce that $N = \{\pm 1\}$ is a normal subgroup of Q . [4]
- (vi) Obtain a homomorphism $\Phi : Q \rightarrow V$ (where V is as defined above) whose kernel is N , and give a quotient group of Q which is isomorphic to V . [4]

Answer 1.18.

- (i) The order of a group is the number of elements of G . This is written as $|G|$.
Lagrange's Theorem states that if G is a finite group and $K \leq G$ is a subgroup, then $|G| = |K||G/K|$, i.e. $|K|$ divides $|G|$.
- (ii) The order of a group element of $g \in G$, denoted as $\text{ord}(g)$, then $\text{ord}(g)$ is the smallest $k \in \mathbb{N}$ s.t. $g^k = e$. Such k will exist for a finite G , otherwise the closure axiom will not be satisfied. g will generate a finite cyclic subset, called the generator.

$$\langle g \rangle := \{g, g^2, g^3, \dots, g^{k-1}, e\}$$

The generator is a subgroup, i.e. $\langle g \rangle \leq G$, since it

- is closed, i.e. $g^a g^b = g^{(a+b) \bmod p}$;
- inherits associativity from the parent group G ;
- contains the identity e ;
- contains the inverse, i.e. g^{k-a} is the inverse of $g^a \forall a \in \{1, k\}$.

These are the axioms for a group. Lagrange's theorem suggests that since $\langle g \rangle \leq G$, $|\langle g \rangle|$ divides $|G|$, i.e. the $\text{ord}(g)$ is a factor of $|G|$. Given $|G| = 4$, $\text{ord}(g) = 1, 2, 4$. Trivially, if $\text{ord}(g) = 1$, $g = e$. For $g \neq e$, we can only have

- either $\text{ord}(g) = 4$, then $G = \langle g \rangle$ is cyclic, and hence $G \cong C_4$;
- or $\text{ord}(g) = 2$, then from the form of the given group V , $G \cong V_4$.

- (iii) If H and G are groups then a function $\phi : G \rightarrow H$ is called a group homomorphism, if $\forall a, b \in G$, we have

$$\phi(a \cdot_G b) = \phi(a) \cdot_H \phi(b)$$

where $\phi(a), \phi(b) \in H$, and \cdot_H, \cdot_G are the binary operations in the groups H and G respectively. In another words, homomorphism preserves group structure.

(iv) We first check the kernel $K = \text{Ker } \Phi$ is a subgroup of G . For $\text{Ker}(\Phi)$, we have $\Phi^{-1}(e_H) = e_G \in \text{Ker}(\Phi)$, so this set is non-empty. If $a, b \in \text{Ker}(\Phi)$, then

$$\Phi(a \cdot_G b^{-1}) = \Phi(a) \cdot_H \Phi(b^{-1}) = \Phi(a) \cdot_H \Phi(b)^{-1} = e_H \cdot_H e_H^{-1} = e_H$$

so $a \cdot_G b^{-1} \in \text{Ker}(\Phi)$, hence $\text{Ker } \Phi \leq G$.

Then check $\text{Ker } \Phi$ is normal in G . Let $k \in \text{Ker } \Phi$ s.t. $\Phi(k) = e$. If $g \in G$,

$$\Phi(gkg^{-1}) = \Phi(g)\Phi(k)\Phi(g^{-1}) = \Phi(g)\Phi(g^{-1}) = \Phi(e) = e$$

hence, $gkg^{-1} \in \text{Ker } \Phi \implies g \text{Ker } \Phi g^{-1} = \text{Ker } \Phi \implies \text{Ker } \Phi \triangleleft G$.

Next, assume $\text{Im } \Phi = H$. We first check $G/\text{Ker } \Phi$ is a group. We need to show

$$(g_1 \text{Ker } \Phi) \cdot (g_2 \text{Ker } \Phi) := g_1 g_2 \text{Ker } \Phi$$

is a well-defined operation. Let $g_1 \text{Ker } \Phi = g'_1 \text{Ker } \Phi$, $g_2 \text{Ker } \Phi = g'_2 \text{Ker } \Phi$, then $g'_1 = g_1 h_1$ and $g'_2 = g_2 h_2$ for some $h_1, h_2 \in \text{Ker } \Phi$, thus

$$g'_1 g'_2 \text{Ker } \Phi = g_1 h_1 g_2 h_2 \text{Ker } \Phi = g_1 h_1 g_2 \text{Ker } \Phi = g_1 g_2 (g_2^{-1} h_1 g_2) \text{Ker } \Phi$$

which is equal to $g_1 g_2 \text{Ker } \Phi$ since $g_2^{-1} h_1 g_2 \in \text{Ker } \Phi$, i.e. $\text{Ker } \Phi \triangleleft G$. Next, check the group axioms.

- Closure: Since operation is well-defined, then $g_1 g_2 \text{Ker } \Phi \in G/\text{Ker } \Phi$
- Associativity:

$$(g_1 \text{Ker } \Phi \cdot g_2 \text{Ker } \Phi) \cdot g_3 \text{Ker } \Phi = (g_1 g_2 \text{Ker } \Phi) \cdot g_3 \text{Ker } \Phi = ((g_1 g_2) g_3) \text{Ker } \Phi = (g_1 (g_2 g_3)) \text{Ker } \Phi$$

which is equal to $g_1 \text{Ker } \Phi \cdot (g_2 \text{Ker } \Phi \cdot g_3 \text{Ker } \Phi)$.

- Identity ($e \text{Ker } \Phi$):

$$g \text{Ker } \Phi \cdot e \text{Ker } \Phi = (g \cdot e) \text{Ker } \Phi = g \text{Ker } \Phi$$

- Inverse ($g^{-1} \text{Ker } \Phi$ is inverse for $g \text{Ker } \Phi$):

$$g \text{Ker } \Phi \cdot g^{-1} \text{Ker } \Phi = (g \cdot g^{-1}) \text{Ker } \Phi = e \text{Ker } \Phi$$

To show isomorphism, we need to construct a bijective homomorphism between the quotient group $G/\text{Ker } \Phi$ and $\text{Im } \Phi$.

$$\begin{aligned} \bar{\phi} : G/\text{Ker}(\phi) &\rightarrow \text{Im}(\phi) \\ g \text{Ker}(\phi) &\mapsto \phi(g) \end{aligned}$$

Check well-defined: if $g \text{Ker}(\phi) = g' \text{Ker}(\phi)$, then $g' = gh$ for some $h \in \text{Ker}(\phi)$, thus

$$\phi(g') = \phi(g)\phi(h) = \phi(g)$$

since $h \in \text{Ker}(\phi)$, hence $\bar{\phi}(g \text{Ker}(\phi)) = \phi(g) = \phi(g') = \bar{\phi}(g' \text{Ker}(\phi))$. Thus, $\bar{\phi}$ is well-defined. Check homomorphism:

$$\bar{\phi}(a \text{Ker}(\phi) b \text{Ker}(\phi)) = \bar{\phi}(ab \text{Ker}(\phi)) = \phi(ab) = \phi(a)\phi(b) = \bar{\phi}(a \text{Ker}(\phi)) \bar{\phi}(b \text{Ker}(\phi))$$

where ϕ is a homomorphism $\implies \bar{\phi}$ is a homomorphism.

$\bar{\phi}$ is surjective, so $\text{Im}(\bar{\phi})$ consists elements of the form $\phi(g)$. If $\bar{\phi}(a \text{Ker}(\phi)) = e \implies \phi(a) = e \implies a \in \text{Ker}(\phi)$. But $a \text{Ker}(\phi) = e \text{Ker}(\phi)$, so $\text{Ker}(\bar{\phi}) = \{a \text{Ker}(\phi)\}$, so $\bar{\phi}$ is injective. Thus, $\bar{\phi}$ is a bijection, and hence a group isomorphism.

(v) This is the Quaternion group.

$$[-1, i] = (-1)i - i(-1) = jji - ijj = jk - kj = 0$$

where $k = j^{-1}i = ji$. Similarly, $[-1, j] = 0$ and $[-1, k] = 0$. Since both 1 and -1 commute with $g \forall g \in Q$, then

$$gNg^{-1} = gg^{-1}N = N \implies N \triangleleft Q$$

(vi) Since $\text{Ker } \Phi = N$, then $\Phi(1) = I$, $\Phi(-1) = I$. We can thus map

$$\Phi(i) = a = \Phi(-i), \quad \Phi(j) = b = \Phi(-j), \quad \Phi(k) = c = \Phi(-k)$$

From part (iv), $Q/\text{Ker } \Phi \cong \text{Im } \Phi$. Since $\text{Im } \Phi = V$ (we have just checked Φ is surjective), then $Q/K \cong V$. The quotient group Q/K consists of

$$\{1, -1\}, \quad \{i, -i\}, \quad \{j, -j\}, \quad \{k, -k\}$$

which individually map to I , a , b and c respectively.

Problem 1.19 (Group Theory):

- (i) If G is an arbitrary finite group, define the conjugacy classes of G and show that each element lies in a unique conjugacy class. [4]
- (ii) Show that if G is Abelian then each element lies in a conjugacy class consisting only of itself, i.e. each element forms its own conjugacy class. [2]
- (iii) If G is an arbitrary, not necessarily Abelian, finite group, its centre Z is defined to be the set of elements which each form their own conjugacy class. Prove that Z is an Abelian subgroup of G . [4]
- (iv) Describe the group D_4 of symmetry operations of the square, including a geometrical description of the action of each element and a 2×2 matrix form for each such action. Give an example, with justification, of a pair of elements which are not conjugate to each other. [6]
- (v) Find the centre of D_4 . [4]

Answer 1.19.

(i) The conjugacy class of $h \in G$ is written as $\text{ccl}(h)$ and is

$$\text{ccl}(h) := \{k \in G \text{ s.t. } k = g \cdot h \cdot g^{-1} \text{ for some } g \in G\}$$

Let's suppose the contrary. Let $g_1 = gg_2g^{-1}$ for some $g \in G$, then $g_2 \in \text{ccl}(g_1)$. Also, suppose $g_2 = g'g_3g'^{-1}$ for some $g' \in G$, then $g_2 \in \text{ccl}(g_3)$. But $g_1 = (gg')g_3(gg')^{-1} \implies g_1 \in \text{ccl}(g_3)$. Then, $g_2 \in \text{ccl}(g_1) \in \text{ccl}(g_3)$. Essentially, each element lies in a unique conjugacy class.

- (ii) If G is abelian, then $g_i g_j = g_j g_i \quad \forall g_i, g_j \in G$. Then, $g_j = g_i^{-1} g_j g_i \quad \forall g_j$, i.e. each element forms its own conjugacy class. The converse is true.
- (iii) The centre of G , written as $Z(G)$, is

$$Z(G) := \{g \in G \text{ s.t. } g \cdot h \cdot g^{-1} = h \quad \forall h \in G\}$$

From part (ii), since Z is the set of elements which each form their own conjugacy class, then Z is abelian. Check group axioms:

- Closure: $\forall g_1, g_2 \in G$,

$$g_1 g_2 = g g_1 g^{-1} g g_2 g^{-1} = g(g_1 g_2)g^{-1}$$

- Associativity is inherited from G .

- Identity $e \in Z$ since $geg^{-1} = e \in Z$. Likewise, the inverse of g_j is

$$g_j^{-1} = (gg_j g^{-1})^{-1} = gg_j^{-1} g^{-1} \in Z$$

- (iv) The elements of D_4 are r (clockwise rotation by $\frac{2\pi}{4} = \frac{\pi}{2}$ about the centre of mass) and s (reflection passing through the centre and parallel to any of the four faces). Their matrix representations are

$$s = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad r = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

There are 8 distinct elements in D_4 :

$$\text{Id}, \quad r, \quad r^2 = -\text{Id}, \quad r^3 = -r, \quad sr = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad sr^2 = -s, \quad sr^3 = -sr$$

Id and r^2 are separately self-conjugate and they are in a conjugation class each of its own. $\{\text{Id}, r\}$ is an example of a pair of elements that are not conjugate.

(v) The conjugacy classes of D_4 are

$$\{\text{Id}\}, \quad \{r^2\}, \quad \{r, r^3\}, \quad \{s, sr^2\}, \quad \{sr, sr^3\}$$

The centre of D_4 is $\{\text{Id}, r^2\}$ since s does not commute with all elements, but only with r^2 .

Problem 1.20 (Representation Theory):

(i) Define the terms representation, invariant subspace, irreducible representation and faithful representation. Define the character of a representation, and state the orthogonality relation for characters. [5]

(ii) Consider the group Σ_3 of all possible permutations of three objects with the group operation defined by composition of the permutations. Display the group multiplication table and identify the conjugacy classes. [3]

Define a faithful three-dimensional representation of Σ_3 in which each element is represented by one of the following matrices:

$$I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad A = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$C = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad D = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad E = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

(iii) Show that the one-dimensional subspace V_0 of vectors of the form (c, c, c) , for arbitrary real c , is an invariant subspace of the representation. Show that the subspace V_0^\perp consisting of real vectors (v_1, v_2, v_3) with $v_1 + v_2 + v_3 = 0$ is the space of real vectors orthogonal to V_0 , and prove that V_0^\perp is also an invariant subspace of the representation. Find the eigenvectors of A and show that A has no (real) eigenvectors in V_0^\perp . Hence show that V_0^\perp determines a two-dimensional irreducible representation of Σ_3 . Hence decompose the above three-dimensional faithful representation into irreducible representations. [8]

(iv) Prove that Σ_3 has two one-dimensional irreducible representations, and one two-dimensional irreducible representation. [2]

You may use without proof that if n_α is the dimension of the α th irreducible representation of a finite group G , then the order of G is given by $|G| = \sum_\alpha n_\alpha^2$.

Answer 1.20.

(i) The definitions are

- A representation of a group is a homomorphism from the group to a set of invertible matrices.
- An invariant subspace is a space spanned by column vectors such that any matrix in the representation acting on a vector in that subspace does not return a vector outside of that subspace.
- An irreducible representation has no non-trivial invariant subspaces (the two trivial invariant subspaces for a representation are the null vector and the entire space).
- A faithful representation of a group is an isomorphism from the group to a set of invertible matrices.
- The character of a representation is the vector of the traces of the matrices representing each group elements.

The characters of different irreducible representations are orthogonal.

(ii) Express the permutations in terms of disjoint cycles. The group multiplication table of Σ_3 is

	Id	(123)	(132)	(13)(2)	(12)(3)	(1)(23)
Id	Id	(123)	(132)	(13)(2)	(12)(3)	(1)(23)
(123)	(123)	(132)	Id	(12)(3)	(1)(23)	(1)(23)
(132)	(132)	Id	(123)	(1)(23)	(13)(2)	(12)(3)
(13)(2)	(13)(2)	(1)(23)	(12)(3)	Id	(132)	(123)
(12)(3)	(12)(3)	(13)(2)	(1)(23)	(123)	Id	(132)
(1)(23)	(1)(23)	(12)(3)	(13)(2)	(132)	(123)	Id

Writing it this way, then evidently the conjugacy classes of Σ_3 are

$$\{\text{Id}\}, \quad \{(123), (132)\}, \quad \{(13)(2), (12)(3), (1)(23)\}$$

(iii) The 6 matrices are row/column permutations of the identity matrix. Any of the 6 matrices merely shuffles the elements of the vector upon which it acts. By inspection, $(c, c, c)^T$ is a vector that is invariant after acting any of the matrices upon it. This forms a one-dimensional invariant subspace of the representation.

After acting any of the 6 matrices, $(v_1, v_2, v_3)^T$ merely gets its components shuffled and that the property $v_1 + v_2 + v_3 = 0$ is preserved. We see that any vector in the plane perpendicular to $(c, c, c)^T$ must stay in that plane. This forms a two-dimensional invariant subspace orthogonal to V_0 . Call this V_0^\perp .

$$0 = \det(A - \lambda I) = \det \begin{pmatrix} -\lambda & 0 & 1 \\ 1 & -\lambda & 0 \\ 0 & 1 & -\lambda \end{pmatrix} = -\lambda^3 + 1 \implies \lambda = 1, e^{\pm 2i\pi/3}$$

The eigenvectors will be

$$\mathbf{e}_{\lambda=1} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \quad \mathbf{e}_{\lambda=e^{\pm 2i\pi/3}} = \begin{pmatrix} 1 \\ e^{\pm i2\pi/3} \\ e^{\mp i2\pi/3} \end{pmatrix}$$

We see that $\mathbf{e}_{\lambda=1}$ is the only real eigenvector, and it is in V_0 but not in V_0^\perp . The other two eigenvectors merely rotate by $2\pi/3$. There are no further invariant subspaces, so V_0^\perp determines a two-dimensional irreducible representation of Σ_3 .

(iv) Using the bases of the invariant subspaces, we construct the transformation matrix to block diagonalize the 6 matrix representations.

$$R = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 1 & 1 \\ 1 & e^{i2\pi/3} & e^{-i2\pi/3} \\ 1 & e^{-i2\pi/3} & e^{i2\pi/3} \end{pmatrix}$$

For each M of the 6 matrices, we take $M' = R^\dagger M R$, then

$$I' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad A' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^{i2\pi/3} & 0 \\ 0 & 0 & e^{-i2\pi/3} \end{pmatrix}, \quad B' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^{-i2\pi/3} & 0 \\ 0 & 0 & e^{i2\pi/3} \end{pmatrix}$$

$$C' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & e^{i2\pi/3} \\ 0 & e^{-i2\pi/3} & 0 \end{pmatrix}, \quad D' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & e^{-i2\pi/3} \\ 0 & e^{i2\pi/3} & 0 \end{pmatrix}, \quad E' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

(v) We have found 1 one-dimensional irreducible representation and 1 two-dimensional irreducible representation. The order of Σ_3 is $3! = 6$, and so $6 - 1^2 - 2^2 = 1$. Hence, there is one more one-dimensional irreducible representation left.

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2.1 Paper 1

Problem 2.1 (Vector Calculus):

- (a) Define the curl $\nabla \times \mathbf{v}$ and the divergence $\nabla \cdot \mathbf{v}$ of a vector field \mathbf{v} in Cartesian coordinates. Show that [6]

$$\nabla \times (\mathbf{v} \times (\nabla \times \mathbf{v})) = ((\nabla \times \mathbf{v}) \cdot \nabla) \mathbf{v} - (\mathbf{v} \cdot \nabla)(\nabla \times \mathbf{v}) - (\nabla \times \mathbf{v})(\nabla \cdot \mathbf{v})$$

- (b) Define the scale factors h_i , $i = 1, 2, 3$ for a general right-handed orthogonal curvilinear coordinate system (q_1, q_2, q_3) . Calculate the scale factors for the cylindrical polar coordinate system (ρ, ϕ, z) . Calculate and sketch the unit vectors $\mathbf{e}_\rho, \mathbf{e}_\phi, \mathbf{e}_z$ relative to Cartesian axes (x, y, z) defined about the same origin as the cylindrical polar coordinate system. [8]

The curl $\nabla \times \mathbf{v}$ and the divergence $\nabla \cdot \mathbf{v}$ in a general right-handed orthogonal curvilinear coordinate system (q_1, q_2, q_3) are given by

$$\nabla \times \mathbf{v} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \mathbf{e}_1 & h_2 \mathbf{e}_2 & h_3 \mathbf{e}_3 \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial q_3} \\ h_1 v_1 & h_2 v_2 & h_3 v_3 \end{vmatrix}$$

$$\nabla \cdot \mathbf{v} = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial q_1} (h_2 h_3 v_1) + \frac{\partial}{\partial q_2} (h_3 h_1 v_2) + \frac{\partial}{\partial q_3} (h_1 h_2 v_3) \right]$$

- (c) Consider the specific example $\mathbf{u} = u_0(1 - \rho^2)\mathbf{e}_z$ in the cylindrical polar coordinates, where u_0 is a positive constant, defined in the cylindrical region $\rho \leq 1$. Using the above formulae, compute $\nabla \times \mathbf{u}$, $\mathbf{u} \times (\nabla \times \mathbf{u})$ and $\nabla \times (\mathbf{u} \times (\nabla \times \mathbf{u}))$, and hence deduce that [6]

$$((\nabla \times \mathbf{u}) \cdot \nabla) \mathbf{u} = (\mathbf{u} \cdot \nabla)(\nabla \times \mathbf{u})$$

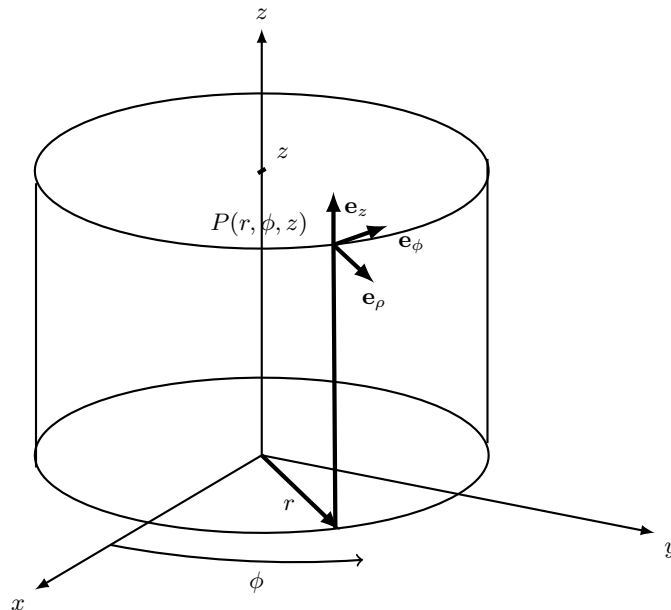
Answer 2.1.

- (a) In Cartesian coordinates, the curl is $\epsilon_{ijk} \partial_i v_j \hat{\mathbf{k}}$, the divergence is $\partial_i v_i$. Let $\mathbf{w} = \nabla \times \mathbf{v}$, then using suffix notation, the k -th component of $\nabla \times (\mathbf{v} \times \mathbf{w})$ is

$$\partial_i v_k w_i - \partial_i v_i w_k = v_k \partial_i w_i + w_i \partial_i v_k - w_k \partial_i v_i - v_i \partial_i w_k$$

but the divergence of a curl is zero and so the result follows.

- (b) For $\mathbf{r}(q_1, q_2, q_3)$, the scale factors are defined to be $h_i = |\partial_{q_i} \mathbf{r}|$ for $i = 1, 2, 3$. For cylindrical polars, $\mathbf{r} = (\rho \cos \phi, \rho \sin \phi, z)^T$. We have $\mathbf{h}_\rho = (\cos \phi, \sin \phi, 0)^T \Rightarrow |\mathbf{h}_\rho| = 1$, $\mathbf{h}_\phi = (-\rho \sin \phi, \rho \cos \phi, 0)^T \Rightarrow |\mathbf{h}_\phi| = \rho$ and $\mathbf{h}_z = (0, 0, 1)^T \Rightarrow |\mathbf{h}_z| = 1$.



(c) We have $\nabla \cdot \mathbf{u} = \frac{1}{\rho} \frac{\partial}{\partial z} u_0(1 - \rho^2) = 0$, and

$$\nabla \times \mathbf{u} = \frac{1}{\rho} \begin{vmatrix} \mathbf{e}_\rho & \mathbf{e}_\phi \rho & \mathbf{e}_z \\ \partial_\rho & \partial_\phi & \partial_z \\ 0 & 0 & u_0(1 - \rho^2) \end{vmatrix} = 2\rho u_0 \mathbf{e}_\phi$$

$$\mathbf{u} \times \nabla \times \mathbf{u} = \frac{1}{\rho} \begin{vmatrix} \mathbf{e}_\rho & \mathbf{e}_\phi \rho & \mathbf{e}_z \\ 0 & 0 & u_0(1 - \rho^2) \\ 0 & 2\rho u_0 & 0 \end{vmatrix} = -u_0^2 2(1 - \rho^2) \mathbf{e}_\rho$$

$$\nabla \times (\mathbf{u} \times \nabla \times \mathbf{u}) = \frac{1}{\rho} \begin{vmatrix} \mathbf{e}_\rho & \mathbf{e}_\phi \rho & \mathbf{e}_z \\ \partial_\rho & \partial_\phi & \partial_z \\ -u_0^2 2(1 - \rho^2) & 0 & 0 \end{vmatrix} = \mathbf{0}$$

Using the result from part (a),

$$\mathbf{0} = \nabla \times (\mathbf{u} \times (\nabla \times \mathbf{u})) = ((\nabla \times \mathbf{u}) \cdot \nabla) \mathbf{u} - (\mathbf{u} \cdot \nabla)(\nabla \times \mathbf{u}) - (\nabla \times \mathbf{u}) 0$$

and the desired result follows.

Problem 2.2 (Partial Differential Equations):

- (a) Consider the problem for
- $u(x, t)$
- defined on
- $[0, \pi]$
- for
- $t \geq 0$
- .

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial u}{\partial t} + \beta(u - u_0); \quad u(x, 0) = f(x), \quad u(0, t) = u_1, \quad u(\pi, t) = u_2$$

where $\beta > 0$, u_0 , u_1 and u_2 are constants. By means of the substitution $u(x, t) = u_0 + v(x, t)e^{-\beta t}$, show that $v(x, t)$ satisfies the diffusion equation on $[0, \pi]$ for $t \geq 0$:

$$\frac{\partial^2 v}{\partial x^2} = \frac{\partial v}{\partial t}$$

with boundary conditions and initial conditions given by [6]

$$v(0, t) = e^{\beta t}(u_1 - u_0), \quad v(\pi, t) = e^{\beta t}(u_2 - u_0), \quad v(x, 0) = f(x) - u_0$$

- (b) Now consider the specific situation where $u_0 = u_1 = u_2 \neq 2$ and $f(x) = x(\pi - x)$. Use the method of separation of variables to construct the solution for $v(x, t)$. [10]

- (c) Hence show that as $t \rightarrow \infty$, $u(x, t)$ may be approximated as [4]

$$u(x, t) \approx u_0 - \frac{4}{\pi}[u_0 - 2]e^{-(\beta+1)t} \sin x$$

Answer 2.2.

- (a) Try the given substitution $u(x, t) = u_0 + v(x, t)e^{-\beta t}$. The LHS of the PDE gives $\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 v}{\partial x^2}$ while RHS gives $\frac{\partial v}{\partial t}e^{-\beta t} - \beta ve^{-\beta t} + \beta ve^{-\beta t} = \frac{\partial v}{\partial t}$. We have $v(x, t) = e^{\beta t}(u - u_0)$ and so the corresponding boundary and initial conditions are $v(x, 0) = f(x) - u_0$, $v(0, t) = e^{\beta t}(u_1 - u_0)$ and $v(\pi, t) = e^{\beta t}(u_2 - u_0)$ as desired.

- (b) After considering $u_1 = u_2 = u_0 \neq 2$, our boundary conditions for $v(x, t)$ become homogeneous. We can now use separation of variables, $v(x, t) = X(x)T(t)$,

$$\frac{X''}{X} = \frac{T'}{T} = -na^2$$

This gives $X(x) = C \sin(nx)$, where $n \in \mathbb{Z}^+$ and $T(t) = De^{-n^2 t}$ for some constants C, D . Our initial condition is now $v(x, 0) = x(\pi - x) - u_0$. Hence,

$$x(\pi - x) - u_0 = \sum_{n=1}^{\infty} C_n \sin(nx) \implies C_n = \frac{2}{\pi} \int_0^{\pi} x(\pi - x) \sin(nx) dx - \frac{2u_0}{\pi} \int_0^{\pi} \sin(nx) dx$$

$$\begin{aligned} C_n &= 2 \int_0^{\pi} x \sin(nx) dx - \frac{2}{\pi} \int_0^{\pi} x^2 \sin(nx) dx + \frac{2u_0}{n\pi} [\cos(nx)]_0^{\pi} \\ &= 2 \left[-\frac{x \cos(nx)}{n} \right]_0^{\pi} + \frac{2}{n^2} [\sin(nx)]_0^{\pi} - \frac{2}{\pi} \left[-x^2 \frac{\cos(nx)}{n} \right]_0^{\pi} - \frac{4}{n\pi} \int_0^{\pi} x \cos(nx) dx + \frac{2u_0}{\pi n} [1 - (-1)^n] \\ &= -\frac{8}{\pi(2r-1)^3} + \frac{4u_0}{\pi(2r-1)} \end{aligned}$$

where relabel $n = 2r - 1$ since only odd n values give $C_n \neq 0$. Thus,

$$v(x, t) = \sum_{r=1}^{\infty} \left(\left(\frac{4u_0}{(2r-1)\pi} - \frac{8}{\pi(2r-1)^3} \right) \sin(rx) \right) e^{-r^2 t}$$

- (c) Given $u(x, t) = u_0 + v(x, t)e^{-\beta t}$ and taking the slowest decaying exponential, i.e. $r = 1$,

$$\lim_{t \rightarrow \infty} u(x, t) = u_0 + e^{-(1+\beta)t} \left(\frac{4u_0}{\pi} - \frac{8}{\pi} \right) \sin(x)$$

as desired.

Problem 2.3 (Green's Functions):

- (a) Find the general solution
- $y(x)$
- to the homogeneous second order linear differential equation.

[4]

$$y'' + 4x^{-1}y' - 4x^{-2}y = 0$$

- (b) Using a Green's function, find an integral representation for the solution of the following inhomogeneous problem:

[10]

$$u'' + 4x^{-1}u' - 4x^{-2}u = f(x), \quad 0 < x < 1, \quad u(0) = u(1) = 0$$

- (c) Using this representation to find an explicit solution in the case that

[6]

$$f(x) = \begin{cases} x & 0 < x < 0.5 \\ 0 & 0.5 < x < 1 \end{cases}$$

[Hints: It may be useful to consider solutions of the form $y = x^n$, and to evaluate $u(x)$ for $x < 0.5$ and $x > 0.5$ separately.]

Answer 2.3.

- (a) The general solution is
- $y = c_1x + c_2x^{-4}$
- , which is obtained by guessing a solution of the form
- $y = x^r$
- for
- $r \in \mathbb{R}$
- , where we eventually get a quadratic equation of
- r
- , i.e.
- $r^2 + 3r - 4 = 0$
- .

- (b) The corresponding Green's function satisfies

$$\frac{\partial^2 G}{\partial x^2} + \frac{4}{x} \frac{\partial G}{\partial x} - \frac{4}{x^2} G = \delta(x - \xi), \quad G(0) = G(1) = 0$$

From the homogeneous solution in part (a), our guess for $G(x, \xi)$ is

$$G(x, \xi) = \begin{cases} A(\xi)x + B(\xi)x^{-4} & 0 \leq x < \xi < 1 \\ C(\xi)x + D(\xi)x^{-4} & 0 \leq \xi < x < 1 \end{cases}$$

We thus have $B(\xi) = 0$ (otherwise singular) and $C(\xi) = -D(\xi)$. Now, if we were to integrate the differential equation in the infinitesimal range $[\xi, \xi + \epsilon]$ for $\epsilon \rightarrow 0$, we see that G must be continuous everywhere otherwise $G'' \propto \delta'(x - \xi)$ which is a contradiction. G' is also continuous everywhere but at $x = \xi$, we have the jump condition $[\frac{\partial G}{\partial x}]^+_- = 1$ at $x = \xi$. Imposing the continuity of G and discontinuity of G' at $x = \xi$ give respectively

$$A(\xi)\xi = C(\xi)(\xi - \xi^{-4})$$

$$C(\xi)(1 + 4\xi^5) - A(\xi) = 1$$

We thus have $C(\xi) = \frac{1}{5}\xi^5$ and $A(\xi) = \frac{1}{5}(\xi^5 - 1)$. We have

$$G(x, \xi) = \begin{cases} \frac{1}{5}(\xi^5 - 1)x & 0 \leq x < \xi < 1 \\ \frac{1}{5}\xi^5(x - x^{-4}) & 0 \leq \xi < x < 1 \end{cases}$$

Hence,

$$u = \frac{x}{5} \int_x^1 (\xi^5 - 1)f(\xi)d\xi + \frac{1}{5}(x - x^{-4}) \int_0^x \xi^5 f(\xi)d\xi$$

- (c) We have
- $f(\xi) = \xi$
- and hence

$$u = \frac{x}{5} \int_x^1 (\xi^6 - \xi)d\xi + \frac{1}{5}(x - x^{-4}) \int_0^x \xi^6 d\xi = \frac{1}{14}x^3 - \frac{111}{4480}x$$

Problem 2.4 (Fourier Transform): The Fourier transform $\tilde{f}(k)$ of a function $f(x)$ is defined by

$$\tilde{f}(k) = \int_{-\infty}^{\infty} e^{-ikx} f(x) dx$$

(a) For an appropriately well-behaved function $f(x)$ such that all the relevant integrals exist, define the inverse Fourier transform and the autocorrelation $h(x) = f \otimes f$. [4]

(b) Using the definition of $h(x)$, prove Parseval's theorem for Fourier transforms: [6]

$$\int_{-\infty}^{\infty} |f(x)|^2 dx = \frac{1}{2\pi} \int_{-\infty}^{\infty} |\tilde{f}(k)|^2 dk$$

(c) Now consider the specific function

$$f(x) = \begin{cases} \cos(x) & |x| \leq \pi/2 \\ 0 & \text{otherwise} \end{cases}$$

Show that

$$\tilde{f}(k) = \frac{2 \cos(0.5k\pi)}{1 - k^2}$$

and hence evaluate the integral [10]

$$\int_0^{\infty} \frac{\cos^2 t}{(0.25\pi^2 - t^2)^2} dt$$

Answer 2.4.

(a) The inverse Fourier transform is

$$f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} \tilde{f}(k) dk$$

and the autocorrelation is

$$h(x) = \int_{-\infty}^{\infty} f(y) f^*(y - x) dy$$

(b) Using the definition of h , the Fourier transformation will be

$$\tilde{h}(k) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(y) f^*(x - y) e^{-ikx} dy dx$$

First, we substitute $x - y = \epsilon$,

$$\tilde{h}(k) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(y) f^*(\epsilon) e^{-iky} e^{-ik\epsilon} dy d\epsilon = \int_{-\infty}^{\infty} f(y) e^{-iky} dy \int_{-\infty}^{\infty} f^*(\epsilon) e^{-ik\epsilon} d\epsilon = \tilde{f}(k) \tilde{f}^*(k) = |\tilde{f}(k)|^2$$

Next, we invert it

$$h(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{h}(k) e^{ikx} dk \implies \int_{-\infty}^{\infty} f(y) f^*(y) dy = \frac{1}{2\pi} \int_{-\infty}^{\infty} |\tilde{f}(k)|^2 dk$$

where we set $x = 0$.

(c) Take the Fourier Transform of $f(x)$,

$$\tilde{f}(k) = \int_{-0.5\pi}^{0.5\pi} \cos(x) e^{-ikx} dx = \frac{1}{2} \left[\frac{e^{ix(1-k)}}{i(1-k)} - \frac{e^{-ix(1+k)}}{i(1+k)} \right]_{-0.5\pi}^{0.5\pi} = \frac{2 \cos(0.5k\pi)}{1 - k^2}$$

Taking Parseval's Theorem, we have

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{4 \cos^2(0.5k\pi)}{(1 - k^2)^2} dk = \int_{-\pi/2}^{\pi/2} \cos^2(x) dx$$

Make the substitution $t = 0.5k\pi$ on the left and note that the integrands are even on both sides, so we just take half the integral.

$$\frac{1}{2\pi} 2 \int_0^{\infty} \frac{4 \cos^2 t}{(1 - (4/\pi^2)t^2)^2} \frac{2}{\pi} dt = 2 \int_0^{0.5\pi} \frac{1}{2} (1 + \cos(2x)) dx \implies \frac{\pi^2}{2} \int_0^{\infty} \frac{\cos^2 t}{(0.25\pi^2 - t^2)^2} dt = \frac{\pi}{2}$$

and the result follows.

Problem 2.5 (Linear Algebra):

(a) State the condition(s) for a square $n \times n$ matrix to be invertible. [1]

(b) Let A be a square $n \times n$ complex matrix such that $A_{ij} = 0$ if $i < j$, i.e. a lower triangular matrix. Prove by induction or otherwise, that the determinant of the matrix is [8]

$$\det A = A_{11}A_{22}\dots A_{nn}$$

(c) Let B be an $n \times n$ dimensional invertible complex diagonal matrix with diagonal elements $\{b, b^2, \dots, b^n\}$ where b is a complex number. Find the condition on b such that the determinant of B is pure imaginary. [5]

(d) Let C and D be two anti-Hermitian matrices, i.e. $C^\dagger = -C$ and $D^\dagger = -D$. Show that CD is anti-Hermitian iff $CD + DC = 0$. Find a number α (real or complex) such that $CD + \alpha DC$ is anti-Hermitian. [6]

Answer 2.5.

(a) To be an invertible $n \times n$ matrix, we must have n linearly independent columns or rows.

(b) We denote an $n \times n$ matrix by $A^{(n)}$. The base case $n = 1$ is trivial, i.e. determinant is itself. Assume that the statement is true for $n = k$, then we consider a $(k+1) \times (k+1)$ matrix

$$A^{(k+1)} = \begin{pmatrix} A_{11} & \dots \\ 0 & A^{(k)} \end{pmatrix}$$

Expanding the determinant down the first column, we have $\det(A^{k+1}) = A_{11} \det(A^{(k)})$. Hence, by induction, the statement is true.

(c) We have

$$\det(B) = b \times b^2 \times \dots \times b^n = b^{0.5n(n+1)} = (|b|e^{i \arg(b)})^{0.5n(n+1)}$$

And so to be purely imaginary, we require $i \arg(b) \frac{1}{2}n(n+1) = i \frac{\pi}{2} + ip\pi$ for some $p \in \mathbb{Z}$, so $\arg(b) = \frac{\pi}{n} \frac{1+2p}{n+1}$.

(d) Assume that CD is anti-Hermitian, i.e. $(CD)^\dagger = -CD$. We have

$$-CD = D^\dagger C^\dagger = (-D)(-C) = DC \implies DC + CD = 0$$

Conversely, assume $CD + DC = 0$, then

$$-CD = DC = (-D)(-C) = D^\dagger C^\dagger = (CD)^\dagger$$

and so CD is indeed anti-Hermitian. If we require $CD + \alpha DC$ to be anti-Hermitian, then

$$(CD + \alpha DC)^\dagger = -CD - \alpha DC \implies DC + \alpha^\dagger CD = -CD - \alpha DC$$

so $\alpha = -1$.

Problem 2.6 (Linear Algebra):(a) What is the condition on a square matrix A for it to be diagonalizable? [2](b) Given the following real 2×2 matrix

$$A = \begin{pmatrix} 4 & 5 \\ 1 & 0 \end{pmatrix}$$

find its eigenvalues λ_1, λ_2 , and their corresponding eigenvectors $\mathbf{V}_1, \mathbf{V}_2$, and then construct the matrix P that diagonalizes A . [6]

(c) Show that [4]

$$P^{-1}A^nP = \begin{pmatrix} \lambda_1^n & 0 \\ 0 & \lambda_2^n \end{pmatrix} \quad (*)$$

(d) By assuming that $A^n = \alpha_n A + \beta_n I$ for some scalars α_n and β_n , or otherwise, use $(*)$ to prove that [8]

$$A^n = \left(\frac{5^n + (-1)^{n+1}}{6} \right) A + \left(\frac{5^n + 5(-1)^n}{6} \right) I$$

Answer 2.6.(a) For an $n \times n$ matrix A to be diagonalizable, it must have n linearly independent eigenvectors.

(b) The characteristic equation is

$$0 = \det \begin{pmatrix} 4 & 5 \\ 1 & 0 \end{pmatrix} = \lambda^2 - 4\lambda - 5 \implies \lambda = 5, -1$$

The corresponding eigenvectors are $(5, 1)^T$ and $(-1, 1)^T$. The appropriate matrix P is $\begin{pmatrix} 5 & -1 \\ 1 & 1 \end{pmatrix}$ such that

$$P^{-1}AP = \frac{1}{6} \begin{pmatrix} 1 & 1 \\ -1 & 5 \end{pmatrix} \begin{pmatrix} 4 & 5 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 5 & -1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 5 & 0 \\ 0 & -1 \end{pmatrix}$$

(c) Given $P^{-1}AP = \text{diag}(\lambda_1, \lambda_2)$. Raising both sides to the power n gives

$$(P^{-1}AP)^n = P^{-1}APP^{-1}AP \dots P^{-1}AP = P^{-1}A^nP = \begin{pmatrix} \lambda_1^n & 0 \\ 0 & \lambda_2^n \end{pmatrix}$$

(d) We have $A^n = \alpha_n A + \beta_n I$ and also

$$A^n = P \begin{pmatrix} 5^n & 0 \\ 0 & (-1)^n \end{pmatrix} P^{-1} = \frac{1}{6} \begin{pmatrix} 5^{n+1} + (-1)^n & 5^{n+1} + 5(-1)^{n+1} \\ 5^n + (-1)^{n+1} & 5^n + 5(-1)^n \end{pmatrix}$$

Since the element in the lower left-hand corner of A is 1 and the lower right-hand corner is 0, we can see that α_n is the entry in the lower left-hand corner of A^n , and β_n is the entry in the lower right-hand corner, i.e.

$$\alpha_n = \frac{1}{6}(5^n + (-1)^{n+1}), \quad \beta_n = \frac{1}{6}(5^n + 5(-1)^n)$$

Problem 2.7 (Cauchy-Riemann):

- (a) State the Cauchy-Riemann equations of an analytic function

$$f(z) = u(x, y) + iv(x, y)$$

where $z = x + iy$ and x, y are real numbers. Show that $u(x, y)$ and $v(x, y)$ satisfy Laplace's equation. [4]

- (b) What is an entire function? Prove that
- $f(z) = \sinh(z)$
- is an entire function. By induction, prove that
- $f(z) = z^n$
- , where
- n
- is a positive integer, is also an entire function. [10]

- (c) What are the conditions on the function
- $f(z)$
- to have a pole of order
- n
- at
- z_0
- ? What does it mean for the function
- $f(z)$
- to have an essential singularity at
- z_0
- ? Show that
- $f(z) = e^{1/z}$
- has an essential singularity at
- $z = 0$
- . For the function

$$f_N(z) = z^N e^{1/z}$$

where N is a positive integer, calculate the Laurent series about the point at infinity. Deduce that $f_N(z)$ has a pole at $z = \infty$, and identify its order. [6]

Answer 2.7.

- (a) For a function
- $f(z) = u(x, y) + iv(x, y)$
- to be analytic, it must satisfy the Cauchy-Riemann equations, i.e.
- $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$
- and
- $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$
- . We evaluate
- $\nabla^2 u$
- :

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial}{\partial y} \left(-\frac{\partial v}{\partial x} \right) = 0$$

which means u satisfy the Laplace's equation. Similar for v .

- (b) An entire function is analytic for the whole complex plane (except
- $z = \infty$
-). We have

$$f = \sinh(z) = \sinh(x) \cosh(iy) + \cosh(x) \sinh(iy) = \sinh(x) \cos(y) + i \sin(y) \cosh(x)$$

Check: $\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} = \cosh(x) \cos(y) - \cos(y) \cosh(x) = 0$ and $\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = \sin(y) \sinh(x) - \sinh(x) \sin(y) = 0$, so f satisfy Cauchy-Riemann equations at all points on the complex plane and is thus entire.

We prove by induction that $f(z) = z^n$ is entire. The base case $n = 1$ $z = x + iy$ is trivially true. Assume $f(z) = z^n := u + iv$ is entire, i.e. $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ and $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$ are both true.

We want to show $g(z) = z^{n+1} = zf(z)$ is entire. We have $g(z) = (x + iy)(u + iv) = (xu - yv) + i(xv + yu)$. We have

$$\begin{aligned} \frac{\partial}{\partial x} \Big|_y (xu - yv) - \frac{\partial}{\partial y} \Big|_x (xv + yu) &= x \left(\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right) - y \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \\ \frac{\partial}{\partial x} \Big|_y (xu + yu) + \frac{\partial}{\partial y} \Big|_x (xu - yv) &= x \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) - y \left(\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right) \end{aligned}$$

So if $f(z)$ is entire, $zf(z)$ is entire by induction.

- (c) If
- $f(z)$
- has a pole of order
- n
- at
- $z = z_0$
- , then
- $\lim_{z \rightarrow z_0} (z - z_0)^n f(z)$
- is not zero or infinity. If no such finite
- n
- can be found, then the pole is an essential singularity.

For $f(z) = e^{1/z} = \sum_{p=0}^{\infty} \frac{1}{p!} z^{-p}$, where $\lim_{z \rightarrow 0} z^n f(z)$ does not exist for any finite n and so $f(z)$ has an essential singularity at the origin.

For $f_N(z) = z^N e^{1/z}$. Let $w = 1/z$, then

$$f_N(w = 1/z) = \frac{1}{w^N} \sum_{p=0}^{\infty} \frac{w^p}{p!}$$

We have $\lim_{w \rightarrow 0} w^N f_N(w)$ to be finite and so $f_N(z)$ has an N th order pole at $z = \infty$.

Problem 2.8 (Series Solution to ODE):

(a) Define ordinary point, a regular singular point and an irregular singular point of a second order linear ordinary differential equation. [3]

(b) Laguerre's equation for $y(x)$ is defined as

$$x \frac{d^2 y}{dx^2} + (1-x) \frac{dy}{dx} + \nu y = 0$$

where ν is a real constant. Show that $x = 0$ is a regular singular point, and $x = \infty$ is an irregular singular point. [4]

(c) Search for solutions of the form

$$y(x) = \sum_{k=0}^{\infty} a_k x^{k+\sigma}$$

where σ is a (not necessarily integer) constant to be determined, and $a_0 \neq 0$. Show that the indicial equation has a double root $\sigma^2 = 0$, and hence derive the recursion relation for the coefficients of the power series solution to Laguerre's equation. Briefly comment on the convergence properties of the series. [6]

(d) Assume that $a_0 = 1$, and that $\nu = n \in \mathbb{Z}^+$. Show that the recursion relation terminates, thus defining the n th Laguerre polynomial $L_n(x)$. Compute $L_0(x)$, $L_1(x)$, $L_2(x)$ and $L_3(x)$. [7]

Answer 2.8.

(a) For $\frac{d^2 y}{dx^2} + p(x) \frac{dy}{dx} + q(x)y = 0$, the point $x = x_0$ is

- an ordinary point if neither $p(x_0)$ nor $q(x_0)$ are singular;
- a singular point if either $p(x_0)$ or $q(x_0)$ are singular;
- a regular singular point: a singular point where $(x - x_0)p(x_0)$ and $(x - x_0)^2 q(x_0)$ are not singular as well;
- an irregular singular point: a singular point where $(x - x_0)p(x_0)$ and $(x - x_0)^2 q(x_0)$ are singular;

(b) We have $\frac{1-x}{x}$ and $\frac{\nu}{x}$ to be both singular at $x = 0$ but $1-x$ and νx are not singular at $x = 0$, so $x = 0$ is a regular singular point. To check the behaviour at $x = \infty$, define $w = \frac{1}{x}$ then

$$\frac{dw}{dx} = \frac{-1}{x^2} \implies \frac{dy}{dx} = -w^2 \frac{dy}{dw}, \quad \frac{d^2 y}{dx^2} = 2w^3 \frac{dy}{dw} + w^4 \frac{d^2 y}{dw^2} \implies \frac{d^2 y}{dw^2} + \frac{w+1}{w^2} \frac{dy}{dw} + \frac{\nu}{w^3} y = 0$$

$\frac{w+1}{w^2}$ and $\frac{\nu}{w^3}$ are both singular at $x = \infty$, i.e. $w = 0$. Similarly, $\frac{w+1}{w}$ and $\frac{\nu}{w}$ are both singular at this point, hence $x = \infty$ is an irregular singular point.

(c) Trying solutions of the suggested form, we have

$$\sum_{k=0}^{\infty} a_k (k+\sigma)(k+\sigma-1)x^{k+\sigma-2} + \sum_{k=0}^{\infty} a_k (k+\sigma)x^{k+\sigma-2} - \sum_{k=0}^{\infty} a_k (k+\sigma)x^{k+\sigma-1} + \nu \sum_{k=0}^{\infty} a_k x^{k+\sigma-1} = 0$$

Compare coefficients for $x^{\sigma-2}$: We obtain the indicial equation $a_0 \sigma^2 = 0$. But $a_0 \neq 0$ and so $\sigma = 0$. Compare coefficients for $x^{k+\sigma-1}$ where $\sigma = 0$ and $k \geq 1$: We have the recurrence relation

$$a_{k+1}(k+1+\sigma)^2 + a_k(\nu - k - \sigma) \implies a_{k+1} = \frac{k - \nu}{(k+1)^2} a_k$$

For series to converge $\forall |x| < 1$, we require $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| |x| < 1 \implies |x| < \lim_{n \rightarrow \infty} \left| \frac{a_n}{a_{n+1}} \right| = R < 1$. The radius of convergence R is $R = \lim_{k \rightarrow \infty} \left| \frac{a_k}{a_{k+1}} \right| = \lim_{k \rightarrow \infty} |k| = \infty$, which is no smaller than the distance to the next nearest singular point of the equation, which we found to be $x = \infty$.

(d) Assume $a_0 = 1$ and $\nu = n$. To obtain a polynomial solution, the recurrence relation must terminate, i.e. $a_{k+1} = 0$ for $k \geq 1$. This gives $k = \nu \in \mathbb{Z}^+$. If

- $\nu = 0$: $L_0(x) = a_0 = 1$;
- $\nu = 1$: $a_1 = a_0(-1/1^2) = -a_0 = -1$ and so $L_1(x) = 1 - x$;
- $\nu = 2$: $a_1 = a_0(-2/1^2) = -2a_0 = -2$ and $a_2 = a_1((1-2)/(1+1)^2) = -a_1/4 = 0.5$, and hence $L_2(x) = 1 - 2x + 0.5x^2$;
- $\nu = 3$: $a_1 = a_0(-3/1^2) = -3$, $a_2 = -a_1((1-3)/(1+1)^2) = -a_1/2 = 1.5$ and $a_3 = -a_2 \frac{2-3}{(2+1)^2} = -\frac{a_2}{9} = -\frac{1}{6}$ and hence $L_3(x) = 1 - 3x + 1.5x^2 - \frac{x^3}{6}$.

Problem 2.9 (Variational Principle):

(a) State Euler's equation for determining stationary values of functionals $I[y]$ of the form

$$I[y] = \int_{x_s}^{x_e} F(x, y, y') dx$$

along paths $y(x)$ between fixed points (x_s, y_s) and (x_e, y_e) and hence show that if $F(y, y')$ does not depend explicitly on x , then the Euler's equation reduces to $F - y' \frac{\partial F}{\partial y'} = A$, where A is a constant, and a prime denotes differentiation with respect to x . [4]

(b) One particular form of Fermat's principle states that the path taken by a ray of light between two points in a medium is the path which makes the elapsed time stationary. Consider a medium where the speed of light $c(y)$ is a function of y alone. By taking a first integral of the Euler equation or otherwise, show that the rays of light follow paths defined implicitly by the equation

$$\int^y \frac{Ac(\hat{y})d\hat{y}}{(1 - A^2[c(\hat{y})]^2)^{1/2}} = \pm(x + B)$$

where A and B are constants to be determined by requiring the path to pass through the start and end points. [8]

(c) Now consider a specific medium filling the upper half-plane $y > 0$ where $c(y) = 1/y$ and the start and end points of interest are $(-1, \cosh[1])$ and $(1, \cosh[1])$ respectively. Calculate the path followed by a ray of light travelling between the start and end points, the minimal value of y along this path, and the time taken to travel between the start and end points. [8]

[Hint: It may be convenient to use the addition formulae for hyperbolic functions.]

Answer 2.9.

(a) For the functional I to be the stationary, the integrand F must satisfy the Euler's equation which is $\frac{d}{dx} \frac{\partial F}{\partial y'} - \frac{\partial F}{\partial y} = 0$. Since $F = F(y, y')$ does not depend explicitly on x , then $\frac{\partial F}{\partial x} = 0$. Then by the chain rule,

$$\frac{dF}{dx} = \frac{\partial F}{\partial x} + \frac{\partial F}{\partial y} y' + \frac{\partial F}{\partial y'} y'' = 0 + \frac{d}{dx} y' \frac{\partial F}{\partial y'} \implies F - \frac{\partial F}{\partial y'} y' = \text{constant}$$

(b) The functional for the time taken is $I[y] = \int \frac{dt}{dl} dl = \int \frac{1}{c(y)} \sqrt{1 + y'^2} dx$. Since the integrand does not explicitly depend on x , then by part (a),

$$A = \frac{1}{c(y)} \sqrt{1 + y'^2} - y' \frac{y'}{c(y) \sqrt{1 + y'^2}} = \frac{1}{c(y) \sqrt{1 + y'^2}} [1 + y'^2 - y'^2] \implies \frac{dy}{dx} = \pm \sqrt{\frac{1 - A^2 c^2(y)}{A^2 c^2(y)}}$$

(c) The integral is $\int^y \frac{A(1/y)dy}{\sqrt{1 - (A/y)^2}} = \pm(x + B)$. Substitute $y = A \cosh u$, then $y = A \cosh(x + B)$. The boundary conditions are $x = \pm 1$, $y = \cosh(1)$, and so $B = 0$ and $A = 1$. Using the suggested hint, the functional I will be

$$I[y] = \int_{-1}^1 \cosh^2 x dx = \frac{1}{2} \int_{-1}^1 (1 + \cosh 2x) dx = 1 + 0.5 \sinh(2)$$

Problem 2.10 (Rayleigh-Ritz Method): Consider the self-adjoint problem for $y(x)$:

$$\frac{d^2 y}{dx^2} + (\lambda_\epsilon - \epsilon x)y = 0, \quad 0 < x < \pi, \quad y(0) = y(\pi) = 0 \quad (*)$$

where $\epsilon \geq 0$ and λ_ϵ is a real constant.

(a) Consider the functional

$$F[u] = \int_0^\pi [(u')^2 + \epsilon x u^2] dx \quad (\dagger)$$

where $u(x)$ are members of the class of functions such that $u(0) = u(\pi) = 0$ and

$$G[u] = \int_0^\pi u^2 dx = 1$$

while a prime denotes differentiation with respect to x . Show that stationary values of F correspond to eigenvalues λ_ϵ of the ODE, and the functions which make F stationary correspond to the associated eigenfunctions of the eigenvalues λ_ϵ . [8]

(b) When $\epsilon = 0$, show that the smallest eigenvalue for the problem is $\lambda_0 = 1$ with associated normalized eigenfunction [4]

$$Y_1(x) = \sqrt{2/\pi} \sin(x)$$

(c) Using $Y_1(x)$ as a trial function for $u(x)$ in (\dagger) , calculate an upper bound for the smallest eigenvalue λ_ϵ of the full problem $(*)$ for non-zero ϵ . [8]

[Hints: The Euler equation can be used without proof, and it may be convenient to express $\sin^2 x$ using a double angle formula.]

Answer 2.10.

(a) Extremizing F subjected to the constraint G is akin to extremizing $F - \lambda(G - 1)$.

$$\phi[u] = F - \lambda(G - 1) = \int_0^\pi (u'^2 + \epsilon x u^2 - \lambda u^2) dx + \lambda$$

In order to make the integrand $f(u, u'; x)$ stationary, it must satisfy the Euler equation.

$$0 = \frac{\partial f}{\partial u} - \frac{d}{dx} \frac{\partial f}{\partial u'} = -2(\lambda - \epsilon x)u - \frac{d}{dx}(2u') = -2u(\lambda - \epsilon x) - 2u''$$

We then have $-u'' + \epsilon x u = \lambda u$, hence recover the SL problem with $\mathcal{L} = -\frac{d^2}{dx^2} + \epsilon x$, and λ is the eigenvalue of the associated eigenfunction u .

(b) When $\epsilon = 0$, the ODE becomes $y'' = -\lambda y \implies y = A \sin \sqrt{\lambda} x + B \cos \sqrt{\lambda} x$. Then $y(0) = 0 \implies B = 0$ and $y(\pi) = 0 \implies \lambda = n^2$, with $n \in \mathbb{Z}^+ \cup \{0\}$. A ensures normalization.

$$1 = \int_0^\pi |A|^2 \sin^2 n x dx \implies A = \sqrt{\frac{2}{\pi}}$$

For the smallest λ_0 , we must have $n = 1$ and so $Y_1(x) = \sqrt{2/\pi} \sin(x)$.

(c) With $Y_1(x)$ as the trial function,

$$F[Y_1] = \int_0^\pi \frac{2}{\pi} \cos^2 x + \epsilon x \frac{2}{\pi} \sin^2 x dx = \frac{1}{\pi} \int_0^\pi 1 + \cos 2x dx + \frac{\epsilon}{\pi} \int_0^\pi x - x \cos 2x dx = 1 + \epsilon 0.5\pi^2$$

Trivially, $G[Y_1] = 1$ (also because Y_1 is normalized). Then let

$$\Lambda[Y_1] = \frac{F[Y_1]}{G[Y_1]} \implies \delta \Lambda = \frac{\delta F}{G} - \frac{F}{G^2} \delta G = \frac{1}{G} [\delta F - \Lambda \delta G]$$

Extremizing Λ is equivalent to extremizing $F - \Lambda G$. The stationary value of Λ is also the smallest eigenvalue of the problem.

$$\lambda_{min} \leq \frac{F[Y_1]}{G[Y_1]} = 1 + \frac{\epsilon \pi^2}{2}$$

This is the upper bound for the smallest eigenvalue of the problem.

2.2 Paper 2

Problem 2.11 (Sturm-Liouville): Consider the eigenvalue problem

$$\frac{d}{dx} \left(p(x) \frac{dy}{dx} \right) + q(x)y + \lambda r(x)y = 0, \quad 0 \leq x \leq \infty \quad (*)$$

where $p(x) \rightarrow 0$ as $x \rightarrow 0$ and as $x \rightarrow \infty$, and $r(x) > 0$ such that $r(x) \rightarrow 0$ as $x \rightarrow \infty$.

- (i) Show that eigenfunctions y_m and y_n , associated respectively with distinct eigenvalues λ_m and λ_n , satisfy the orthogonality property

$$\int_0^\infty r(x)y_m y_n dx = 0 \quad (\dagger)$$

making it clear where you have to make assumptions about the behaviour of y_m and y_n as $x \rightarrow 0$ and $x \rightarrow \infty$. [6]

- (ii) Show that the equation

$$x \frac{d^2 y}{dx^2} + (1-x) \frac{dy}{dx} + \lambda y = 0 \quad (\ddagger)$$

may be written in the form (*) and find the corresponding functions $p(x)$ and $r(x)$. Write down the orthogonality property satisfied by y_m and y_n in this case. [6]

You are given that (\ddagger) has eigenvalues $\lambda_0, \lambda_1, \lambda_2, \dots$, where $\lambda_n = n$, and corresponding eigenfunctions y_0, y_1, y_2, \dots where each y_n is a polynomial of degree n .

- (iii) Find the functions y_1 and y_2 , respectively linear and quadratic polynomials, and show explicitly that they satisfy the orthogonality property (\dagger) . [8]

Answer 2.11.

- (i) Let $\mathcal{L} := \frac{d}{dx} \left(p(x) \frac{d}{dx} \right) + q(x)$ such that $\mathcal{L}y_n = -\lambda_n r(x)y_n$, then

$$\begin{aligned} \langle y_n | \mathcal{L}y_m \rangle &= \int_0^\infty y_n \frac{d}{dx} \left(p(x) \frac{dy_m}{dx} \right) + y_n q(x)y_m dx \\ &= \left[y_n p(x) \frac{dy_m}{dx} \right]_0^\infty - \int_0^\infty y'_n p y'_m dx + \int_0^\infty y_n q y_m dx \\ &= \left[y_n p(x) \frac{dy_m}{dx} - y_m \frac{dy_n}{dx} p(x) \right]_0^\infty + \int_0^\infty y_m \frac{d}{dx} \left(p(x) \frac{dy_n}{dx} \right) + y_n q(x)y_m dx \end{aligned}$$

Assuming y and $\frac{dy}{dx}$ do not diverge as $x \rightarrow 0$ and $x \rightarrow \infty$, the boundary terms vanish. We thus have $\langle y_n | \mathcal{L}y_m \rangle = \langle \mathcal{L}y_n | y_m \rangle$. LHS gives $-\lambda_n \langle y_n | y_m \rangle$ while RHS gives $-\lambda_m \langle y_n | y_m \rangle_r = \int_0^\infty y_n r(x)y_m dx$, where $\langle y_n | y_m \rangle_r$ is the weighted inner product (recover (\dagger)). Then

$$\lambda_m \neq \lambda_n, \quad \langle y_n | y_m \rangle_r (\lambda_m - \lambda_n) = 0 \implies \langle y_n | y_m \rangle_r = 0$$

- (ii) Multiply (\ddagger) by an integration factor $\mu(x)$ such that we can recover (*).

$$\frac{dp(x)}{dx} \frac{1}{p(x)} = \frac{1-x}{x} \implies p(x) \propto x e^{-x} \implies \mu(x) \propto e^{-x}$$

$$(\ddagger) \implies \frac{d}{dx} \left(x e^{-x} \frac{dy}{dx} \right) = -\lambda e^{-x} y, \quad (\dagger) \implies \int_0^\infty y_m e^{-x} y_n dx \propto \delta_{n,m}$$

where $p(x) = x e^{-x}$, $q(x) = 0$ and $r(x) = e^{-x}$.

- (iii) Since y_1 is a polynomial of degree 1, it must have the form $y_1 = c_1 x + c_2$, so

$$\frac{d}{dx} (x e^{-x} c_1) = -e^{-x} (c_1 x + c_2) \implies c_2 = -c_1$$

Since y_2 is a polynomial of degree 2, it must have the form $y_2 = c_3 x^2 + c_4 x + c_5$, so

$$\frac{d}{dx} (x e^{-x} (2c_3 x + c_4)) = -2e^{-x} (c_3 x^2 + c_4 x + c_5) \implies c_4 = -2c_5, \quad 4c_3 = -c_4$$

Then, $y_1(x) = c_1(x-1)$ and $y_2(x) = c_3(x^2-4x+2)$. Check (\dagger) :

$$\int_0^\infty c_1 c_3 (x^2-4x+2)(x-1)e^{-x} dx = c_1 c_3 \int_0^\infty (x^3-5x^2+6x-2)e^{-x} dx = 3!-5(2!)+6-2 = 6-10+6-2 = 0$$

Problem 2.12 (Laplace's Equation):

- (i) The temperature
- $T(x)$
- in a volume
- \mathcal{V}
- of a solid satisfies the steady-state diffusion equation

$$\nabla^2 T = 0 \quad (*)$$

in \mathcal{V} . T is specified to be a given function $T_b(x)$ on the boundary of \mathcal{V} , the surface \mathcal{S} . Show that the solution of $(*)$ with the boundary condition $T = T_b(\mathbf{x})$ on \mathcal{S} is unique. [7]

A solid body consists of one substance in the volume \mathcal{V}_1 entirely enclosed within a second substance occupying the volume \mathcal{V}_2 . The outer surface of \mathcal{V}_2 is \mathcal{S}_2 . The outer surface of \mathcal{V}_1 and also the inner surface of \mathcal{V}_2 is \mathcal{S}_1 . In this case the temperature T satisfies the equations

$$\nabla^2 T = 0 \text{ in } \mathcal{V}_1$$

$$\nabla^2 T = 0 \text{ in } \mathcal{V}_2$$

with T a given function $T_b(\mathbf{x})$ on \mathcal{S}_2 , T continuous across \mathcal{S}_1 and $\alpha \nabla T \cdot \mathbf{n}|_{\mathcal{S}_1^+} = \beta \nabla T \cdot \mathbf{n}|_{\mathcal{S}_1^-}$, where the unit vector \mathbf{n} is the outward normal to \mathcal{S}_1 , $|_{\mathcal{S}_1^+}$ denotes the limit as \mathcal{S}_1 is approached from \mathcal{V}_2 and $|_{\mathcal{S}_1^-}$ denotes the limit as \mathcal{S}_1 is approached from \mathcal{V}_1 . α and β are positive constants.

- (ii) Show that the above equations and boundary conditions have a unique solution in
- \mathcal{V}_1
- and
- \mathcal{V}_2
- . [13]

Hint: Start by applying the approach you used in the first part of the question to \mathcal{V}_1 and \mathcal{V}_2 separately.

Answer 2.12.

- (i) Assume
- T_1
- and
- T_2
- are solutions that satisfy
- $(*)$
- and the boundary conditions. Let
- $T := T_1 - T_2$
- , then
- $\nabla^2 T = \nabla^2 T_1 - \nabla^2 T_2 = 0$
- , which implies
- T
- is also a solution that satisfies the same boundary condition. Consider the Green's identity

$$\int_{\partial V} u \nabla v \cdot d\mathbf{S} = \int_V \nabla \cdot (u \nabla v) dV = \int_V u \nabla^2 v + \nabla u \cdot \nabla v dV$$

Let $u = v = T$, and since $T = T_b - T_b = 0$ on \mathcal{S} and $\nabla^2 T = 0$ in \mathcal{V} , then

$$\int_{\mathcal{S}} T \nabla T \cdot d\mathbf{S} = \int_{\mathcal{V}} T \nabla^2 T + \nabla T \cdot \nabla T dV \implies 0 = 0 + \int_{\mathcal{V}} |\nabla T|^2 dV$$

hence, $|\nabla T| = 0$ on $\mathcal{V} \cup \mathcal{S}$. And since $T = 0$ on the domain, we must have $T_1 = T_2$ everywhere, and thus the solutions of $(*)$ with the given boundary conditions are unique.

- (ii) Let
- T'
- and
- T''
- be solutions, then define
- $T := T' - T''$
- such that
- $\nabla^2 T = 0$
- in
- $\mathcal{V}_1 \cup \mathcal{V}_2$
- . The boundary condition for
- T
- is
- $T = T' - T'' = T_b(\mathbf{x}) - T_b(\mathbf{x}) = 0$
- for
- \mathbf{x}
- on
- \mathcal{S}_2
- . Let
- $T_{i,j}(\mathbf{x})$
- be the
- T_i
- solution (
- $i = a, b$
-) in region
- \mathcal{V}_j
- . Invoke the continuity conditions:

- Continuity of T across \mathcal{S}_1 :

$$T'_1 = T'_2; \quad T''_1 = T''_2$$

- Discontinuity of $\nabla T \cdot \mathbf{n}$ across \mathcal{S}_1 :

$$\nabla T'_1 \cdot \mathbf{n} = \frac{\alpha}{\beta} \nabla T'_2 \cdot \mathbf{n}; \quad \nabla T''_1 \cdot \mathbf{n} = \frac{\alpha}{\beta} \nabla T''_2 \cdot \mathbf{n}$$

Consider from earlier using Divergence Theorem:

$$\int_V |\nabla T|^2 dV = \int_V \nabla \cdot (T \nabla T) - T \nabla^2 T dV = \int_{\partial V} T \nabla T \cdot d\mathbf{S} - \int_V T \nabla^2 T dV$$

for an arbitrary volume V . But $\nabla^2 T = 0$ for \mathcal{V}_1 and \mathcal{V}_2 , so

$$\int_{\mathcal{V}_2} |\nabla T|^2 dV = \int_{\mathcal{S}_2} T \nabla T \cdot d\mathbf{S} - \int_{\mathcal{S}_1} T \nabla T \cdot d\mathbf{S} - \int_{\mathcal{V}_2} T \nabla^2 T dV = 0 - \int_{\mathcal{S}_2} (T'_2 - T''_2) \nabla (T'_2 - T''_2) \cdot d\mathbf{S} + 0$$

where $\partial\mathcal{V}_2 = \mathcal{S}_2 - \mathcal{S}_1$. Separately,

$$\begin{aligned}\int_{\mathcal{V}_1} |\nabla T|^2 dV &= \int_{\mathcal{S}_1} T \nabla T \cdot d\mathbf{S} - \int_{\mathcal{V}_1} T \nabla^2 T dV \\ &= 0 - \int_{\mathcal{S}_1} (T'_1 - T''_1) \nabla (T'_1 - T''_1) \cdot d\mathbf{S} + 0 \\ &= \frac{\alpha}{\beta} \int_{\mathcal{S}_1} (T'_2 - T''_2) \nabla (T'_2 - T''_2) \cdot d\mathbf{S}\end{aligned}$$

where we used the discontinuity condition for $\nabla^2 T$ across \mathcal{S}_1 . The conclusion is

$$\int_{\mathcal{V}_2} |\nabla T|^2 dV = -\frac{\beta}{\alpha} \int_{\mathcal{V}_1} |\nabla T|^2 dV$$

A positive semi-definite integrand is equal to a negative semi-definite integrand, would mean both of them are actually zero in both regions. So, $|\nabla T| = 0$ everywhere. But $T = 0$ for \mathbf{x} on \mathcal{S}_2 , so T must be zero everywhere. Hence, the solution is unique.

Problem 2.13 (Green's Functions):

- (a) Derive the fundamental solution

$$G(\mathbf{x}, \mathbf{y}) = -\frac{1}{2\pi} \log |\mathbf{x} - \mathbf{y}|$$

to the Poisson equation

$$-\nabla^2 G = \delta(\mathbf{x} - \mathbf{y})$$

in two-dimensional space.

[4]

- (b) A point charge q is placed at the origin in the presence of a boundary along the line $x = b$, with $b > 0$. The electrostatic potential $V(\mathbf{x})$ satisfies

$$\nabla^2 V = q\delta(\mathbf{x})$$

Using the method of images, construct an expression for $V(\mathbf{x})$ in $x < b$ for the cases:

- (i) where the boundary is an earthed conductor, i.e. $V = 0$ on the boundary;
- (ii) where the boundary is an insulator, i.e. $\mathbf{n} \cdot \nabla V = \frac{\partial V}{\partial x} = 0$ on the boundary. (\mathbf{n} is the unit normal to the boundary.)

In each case show explicitly that your solution satisfies the required boundary conditions. [8]

- (c) Now consider the case where there are two insulating boundaries at $x = b$ and at $x = -b$. Construct the corresponding image system which gives an appropriate solution for V in $-b < x < b$. Write down expressions for V and for $\frac{\partial V}{\partial y}$ as series. [6]

- (d) Deduce that for $y > 0$,

[2]

$$\int_{-b}^b \frac{\partial V}{\partial y} dx = \frac{q}{2\pi} \sum_{n=-\infty}^{\infty} \left\{ \tan^{-1} \left[\frac{(2n+1)b}{y} \right] - \tan^{-1} \left[\frac{(2n-1)b}{y} \right] \right\} = \frac{q}{2}$$

Answer 2.13.

(a) Set $\mathbf{r} = \mathbf{x} - \mathbf{y}$, and integrate over a circle D centred at the origin of radius R :

$$1 = \int_D \delta(r) dA = - \int_D \nabla^2 G dA = - \int_{\partial D} \frac{\partial G}{\partial r} dl = - \int_0^{2\pi} \frac{\partial G}{\partial r} R d\theta$$

where we used 2D Divergence theorem. The system is circularly symmetric about $r = 0$, then $G = G(r)$:

$$-\frac{dG}{dr} \Big|_{r=R} \int_0^{2\pi} R d\theta = 1 \implies G = -\frac{1}{2\pi} \ln R + B = -\frac{1}{2\pi} \ln |\mathbf{x} - \mathbf{y}| + B$$

where B is some constant, that depends on the problem.

(b) (i) Add an image $-q$ at $(2b, 0)$, then

$$V(x < b, y) = \frac{q}{2\pi} (\ln \sqrt{(x-2b)^2 + y^2} - \ln \sqrt{x^2 + y^2}) = \frac{q}{4\pi} \ln \frac{(x-2b)^2 + y^2}{x^2 + y^2}$$

where the potential is zero on the boundary, i.e. $V(b, y) = \frac{q}{4\pi} \ln \frac{b^2 + y^2}{b^2 + y^2} = 0$.

(ii) Add an image $+q$ at $(2b, 0)$, then

$$V(x < b, y) = -\frac{q}{2\pi} (\ln \sqrt{(x-2b)^2 + y^2} + \ln \sqrt{x^2 + y^2})$$

where the electric field (gradient of potential) is zero on the boundary, i.e.

$$\frac{\partial V}{\partial x}(b, y) = -\frac{q}{4\pi} \left(\frac{2(b-2b)}{(b-2b)^2 + y^2} + \frac{2b}{b^2 + y^2} \right) = 0$$

(c) We now need an infinite number of image charges, all with charge $+q$ at positions $(2nb, 0)$ for $n \in \mathbb{Z} \setminus \{0\}$.

$$V(x, y) = \sum_{n=-\infty}^{\infty} \frac{-q}{4\pi} \ln |(x-2nb)^2 + y^2| \implies \frac{\partial V}{\partial y} = \frac{-q}{4\pi} \sum_{n=-\infty}^{\infty} \frac{2y}{(x-2nb)^2 + y^2}$$

(d) Substitute $x = 2nb + y \tan \theta$ in evaluating $\int_{-b}^b \frac{\partial V}{\partial y} dx$

$$-\frac{q2y}{4\pi} \int_{n=-\infty}^{\infty} \int_{-\tan^{-1}(b(1+2n)/y)}^{\tan^{-1}(b(1-2n)/y)} \frac{y \sec^2 \theta d\theta}{y^2 + y^2 \tan^2 \theta} = -\frac{q}{2\pi} \sum_{n=-\infty}^{\infty} \left\{ \tan^{-1} \left[\frac{(2n+1)b}{y} \right] - \tan^{-1} \left[\frac{(2n-1)b}{y} \right] \right\}$$

To get the second equality, we construct a closed loop consisting of the lines $x = \pm b$, $y = 0$ and $y = \infty$. Since this closed loop encloses an area A which only has half of the actual charge, at the origin, hence $\int_A \nabla^2 V dA = -\frac{q}{2}$. Invoke the 2-dimensional Divergence Theorem:

$$\frac{-q}{2} = \int_A \nabla^2 V dA = \oint_{\partial A} \nabla V \cdot d\mathbf{l}$$

But from part (b) (ii), $\frac{\partial V}{\partial x}(\pm b, y) = 0$, and that $\frac{\partial V}{\partial y}$ (from part (c)) scales like y^{-1} as $y \rightarrow \infty$. Hence, the only contribution is on the line $y = 0$. Thus,

$$-\frac{q}{2} = \oint_{\partial A} \nabla V \cdot d\mathbf{l} = \int_{-b}^b -\frac{\partial V}{\partial y}(x, 0) dx$$

Problem 2.14 (Contour Integration):

- (i) State the residue theorem for the integral

$$\oint_{\mathcal{C}} f(z) dz$$

where \mathcal{C} is a closed contour and $f(z)$ is analytic within \mathcal{C} except for a finite number of poles at z_1, z_2, \dots, z_N . [4]

- (ii) Consider the function $f(z) = \frac{\log(z)}{1+z^\beta}$ where $\beta > 1$. Show that a branch cut can be chosen so that, apart from isolated poles, $f(z)$ is analytic in the region $|z| > 0, 0 \leq \arg(z) < \pi$. Identify all poles of $f(z)$ in this region and calculate the corresponding residues. [8]

- (iii) Now, by considering the integral of $f(z)$ around a suitable closed contour which includes the real axis from $z = \epsilon$ ($\epsilon \ll 1$) to $z = R$ ($R \gg 1$) and which encloses a single pole of $f(z)$, show that [8]

$$\int_0^\infty \frac{\log(x)}{1+x^\beta} dx = -\frac{\pi^2 \cos(\pi/\beta)}{\beta^2 \sin^2(\pi/\beta)}$$

and

$$\int_0^\infty \frac{1}{1+x^\beta} dx = \frac{\pi}{\beta \sin(\pi/\beta)}$$

Answer 2.14.

- (i) Suppose f is analytic in a simply-connected domain except at a finite number of isolated singularities $\{z_1, \dots, z_N\}$. Suppose a simple closed contour \mathcal{C} encircles the origin anticlockwise, then the residue theorem states

$$\oint_{\mathcal{C}} f(z) dz = 2\pi i \sum_{k=1}^N \text{res}_{z=z_k} f(z)$$

- (ii) We have essential branch singularities at $z = 0$ and $z = \infty$ (due to $\log z$). The first order poles are at $z^\beta = -1 \implies z = e^{i\pi(1+2m)/\beta}$ for $m \in \mathbb{Z}^+$. To prevent encircling either branch points, we choose a branch cut from 0 to ∞ . Since $\beta > 1$, the first order poles are dense on the unit circle. This choice of branch cut resolves this problem. Hence, the only isolated singularities that contributes to the residue theorem are the first order poles $z_j = e^{(2j+1)i\pi/\beta}$ for $j = 1, \dots, q$ where q is the largest integer such that $\frac{(2q+1)}{\beta} < 2$. The corresponding residue will be

$$\begin{aligned} \text{res}_{z=z_j} f(z) &= \lim_{z \rightarrow z_j} (z - z_j) f(z) \\ &= \lim_{z \rightarrow z_j} \frac{\log z}{\beta z^{\beta-1}} \\ &= \frac{\ln e^{(2s+1)i\pi/\beta}}{\beta e^{(2s+1)i\pi \frac{\beta-1}{\beta}}} \\ &= i \frac{\pi(2s+1)}{\beta^2} e^{-(2s+1)i\pi} e^{(2s+1)i\pi/\beta} \\ &= -i\pi \frac{2s+1}{\beta^2} e^{(2s+1)i\pi/\beta} \end{aligned}$$

- (iii) Choose the contour $\gamma = \gamma_1 \cup \gamma_2 \cup \gamma_3 \cup \gamma_4$ to be a sector of a circle such that only one of the isolated pole, say z_1 without loss of generality, is enclosed. The parametrization of the sub-contours will be

$$\gamma_1 : z = r, \quad \gamma_2 : z = Re^{i\theta}, \quad \gamma_3 : z = re^{i\phi}, \quad \gamma_4 : z = \epsilon e^{i\theta}$$

We define the integrals

$$I := \lim_{\varepsilon \rightarrow 0, R \rightarrow \infty} \int_{\varepsilon}^R \frac{\ln x}{1+x^{\beta}} dx, \quad J := \lim_{\varepsilon \rightarrow 0, R \rightarrow \infty} \int_{\varepsilon}^R \frac{dx}{1+x^{\beta}}$$

The contour integrals are

$$\begin{aligned} \int_{\gamma_1} f(z) dz &= \lim_{\varepsilon \rightarrow 0, R \rightarrow \infty} \int_{\varepsilon}^R \frac{\ln r}{1+r^{\beta}} dr = I \\ \int_{\gamma_2} f(z) dz &= \lim_{R \rightarrow \infty} \int_0^{\phi} \frac{\ln R + i\theta}{1+R^{\beta} e^{i\theta\beta}} i R e^{i\theta} d\theta = \lim_{R \rightarrow \infty} O(R^{1-\beta} \ln R) = 0 \\ \int_{\gamma_3} f(z) dz &= \lim_{R \rightarrow \infty, \varepsilon \rightarrow 0} \int_R^{\varepsilon} \frac{\ln r + i\phi}{1+r^{\beta} e^{i\phi\beta}} e^{i\phi} dr \\ &= - \lim_{\varepsilon \rightarrow 0, R \rightarrow \infty} \int_{\varepsilon}^R \frac{\ln r + i(2\pi/\beta)}{1+r^{\beta} e^{i(2\pi/\beta)}} dr \\ &= -e^{+i2\pi/\beta} I - i \frac{2\pi}{\beta} e^{i2\pi/\beta} J \\ \int_{\gamma_4} f(z) dz &= \lim_{\varepsilon \rightarrow 0} \int_{\phi}^0 \frac{\ln \varepsilon + i\phi}{1+\varepsilon^{\beta} e^{i\theta\beta}} i \varepsilon e^{i\theta} d\theta = \lim_{\varepsilon \rightarrow 0} O(\varepsilon \ln \varepsilon) = 0 \end{aligned}$$

Hence, invoke residue theorem from part (i):

$$2\pi i \operatorname{res}_{z=e^{i\pi/\beta}} f(z) = \oint_{\gamma} f(z) dz = I(1 - e^{i2\pi/\beta}) - i \frac{2\pi}{\beta} e^{i2\pi/\beta} J$$

LHS is $-i\pi \frac{1}{\beta^2} e^{i\pi/\beta}$ from part (ii). So,

$$\frac{2\pi^2}{\beta^2} = -2i \sin \frac{\pi}{\beta} I - i \frac{2\pi}{\beta} (\cos \frac{\pi}{\beta} + i \sin \frac{\pi}{\beta}) J$$

Comparing the real and imaginary parts,

$$\begin{aligned} \frac{2\pi^2}{\beta^2} &= \frac{2\pi}{\beta} \sin \frac{\pi}{\beta} J \implies J = \frac{\pi}{\beta \sin \frac{\pi}{\beta}} \\ -2I \sin \frac{\pi}{\beta} - \frac{2\pi}{\beta} \cos \frac{\pi}{\beta} J &= 0 \implies I = -\frac{\pi^2}{\beta^2} \frac{\cos(\pi/\beta)}{\sin^2(\pi/\beta)} \end{aligned}$$

Problem 2.15 (Transform Method): The Fourier transform $\tilde{f}(k)$ of a function $f(t)$ and the corresponding inverse transform are defined by

$$\tilde{f}(k) = \int_{-\infty}^{\infty} e^{-ikt} f(t) dt, \quad f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikt} \tilde{f}(k) dk$$

(i) Show that if

$$h(t) = \int_{-\infty}^{\infty} f(s)g(t-s)ds$$

then $\tilde{h}(k) = \tilde{f}(k)\tilde{g}(k)$.

[6]

Consider the differential equation

$$\frac{d^2 y}{dt^2} + (a+b)\frac{dy}{dt} + aby = f(t)$$

with the constants a and b such that $a > b > 0$. The solution $y(t)$ and its derivatives may be assumed to tend to zero as $t \rightarrow \pm\infty$.

(ii) Derive an equation relating \tilde{y} to \tilde{f} , carefully justifying all steps in your calculation. Deduce that

$$y(t) = \int_{-\infty}^{\infty} f(s)G(t-s)ds$$

and find the function $G(t)$ by inverting $\tilde{G}(k)$.

[7]

(iii) In the case $f(t) = e^{-|t|}$ evaluate $\tilde{f}(k)$. Assuming that $a \neq 1$ and $b \neq 1$, deduce an expression for $\tilde{y}(k)$ and invert to deduce $y(t)$.

[7]

Answer 2.15.

(i) Compute the Fourier transform of $h(t)$:

$$\begin{aligned} \tilde{h}(k) &= \int_{-\infty}^{\infty} e^{-ikt} \int_{-\infty}^{\infty} f(s)g(t-s)ds dt \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-ikt} f(s)g(t-s)ds dt \\ &= \int_{-\infty}^{\infty} f(s) \left[\int_{-\infty}^{\infty} e^{-ikt} g(t-s)dt \right] ds \\ &= \int_{-\infty}^{\infty} f(s) \left[\int_{-\infty}^{\infty} e^{ik(s+q)} g(q)dq \right] ds \\ &= \int_{-\infty}^{\infty} e^{-iks} f(s)ds \int_{-\infty}^{\infty} e^{-ikq} g(q)dq \\ &= \tilde{f}(k)\tilde{g}(k) \end{aligned}$$

where we substituted $q = t - s$. This proves convolution theorem.

(ii) Assume $y(t)$ and $\frac{dy}{dt}$ both approach 0 as $t \rightarrow \pm\infty$, then

$$\mathcal{F}[y'] = [ye^{-ikt}]_{-\infty}^{\infty} + ik\tilde{y} = 0 + ik\tilde{y}$$

$$\mathcal{F}[y''] = [y'e^{-ikt}]_{-\infty}^{\infty} + ik\tilde{y}' = 0 + ik\tilde{y}' = -k^2\tilde{y}$$

Perform Fourier transform on the given ODE, then

$$-k^2\tilde{y} + (a+b)ik\tilde{y} + ab\tilde{y} = \tilde{f}(k) \implies \tilde{y} = \frac{-\tilde{f}}{(k-ia)(k-ib)}$$

By convolution theorem in part (i), $y = f * G$ where $\tilde{G} = \frac{1}{(k-ia)(k-ib)}$ and hence using inverse Fourier transform,

$$G(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{-e^{ikt}}{(k-ia)(k-ib)} dk$$

The integrand has first order poles at $k = ia$ and $k = ib$. An essential singularity on the upper half-plane at $k = \infty$ for $t < 0$ and on the lower half-plane at $k = -\infty$ for $t > 0$. Jordan's Lemma allows us to close the upper half-plane for $t > 0$ and add zero from the arc at ∞ . The total integral, by the residue theorem, is $2\pi i$ times the sum of residues from the isolated singularities. For $t < 0$, we close the lower half-plane, which does not enclose any poles, and thus the integral is 0. This is consistent with causality. For $t > 0$, we close the upper half-plane which encloses the poles $k = ia$ and $k = ib$. The residues will be

$$\begin{aligned} \text{res}_{k=ia} \frac{-e^{ikt}}{(k-ia)(k-ib)} &= \lim_{k \rightarrow ia} \frac{-e^{ikt}}{2\pi(k-ib)} = \frac{-e^{-at}}{2\pi(ia-ib)} \\ \text{res}_{k=ib} \frac{-e^{ikt}}{(k-ia)(k-ib)} &= \lim_{k \rightarrow ib} \frac{-e^{ikt}}{2\pi(k-ia)} = \frac{-e^{-bt}}{2\pi(ib-ia)} \end{aligned}$$

So the Green's function $G(t)$ is

$$G(t) = \begin{cases} 0 & t < 0 \\ \frac{e^{-at} - e^{-bt}}{b-a} & t > 0 \end{cases}$$

(iii) Now $f(t) = e^{-|t|}$. Perform Fourier transform,

$$\begin{aligned} \tilde{f}(k) &= \int_{-\infty}^{\infty} e^{-|t|} e^{-ikt} dt \\ &= \int_{-\infty}^0 e^{t-ikt} dt + \int_0^{\infty} e^{-t-ikt} dt \\ &= \frac{1}{1-ik} + \frac{1}{1+ik} \\ &= \frac{2}{1+k^2} \end{aligned}$$

Hence, we have

$$y(t) = -\frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{2e^{ikt}}{(k-ia)(k-ib)(k-i)(k+i)} dk$$

For $a \neq 1$, $b \neq 1$, the integrand (let this be $J(k)$) has four first-order poles: 3 in the upper half-plane and 1 in the lower half-plane. The corresponding residues are

$$\begin{aligned} \text{res}_{k=ia} J(k) &= \lim_{k \rightarrow ia} \frac{1}{2\pi} \frac{2e^{ikt}}{(k-ib)(k-i)(k+i)} = \frac{e^{-at}}{i\pi(a-b)(a^2-1)} \\ \text{res}_{k=ib} J(k) &= \lim_{k \rightarrow ib} \frac{1}{2\pi} \frac{2e^{ikt}}{(k-ia)(k-i)(k+i)} = \frac{e^{-bt}}{i\pi(b-a)(b^2-1)} \\ \text{res}_{k=i} J(k) &= \lim_{k \rightarrow i} \frac{1}{2\pi} \frac{2e^{ikt}}{(k-ia)(k-ib)(k+i)} = \frac{e^{-t}}{2i\pi(1-a)(1-b)} \\ \text{res}_{k=-i} J(k) &= \lim_{k \rightarrow -i} \frac{1}{2\pi} \frac{2e^{ikt}}{(k-ia)(k-ib)(k-i)} = \frac{-e^t}{2i\pi(1+a)(1+b)} \end{aligned}$$

For $t > 0$, close the upper half-plane and invoke residue theorem to yield

$$y(t) = 2\pi i \left[\frac{e^{-at}}{i\pi(a-b)(a^2-1)} + \frac{e^{-bt}}{i\pi(b-a)(b^2-1)} + \frac{e^{-t}}{2i\pi(1-a)(1-b)} \right]$$

For $t < 0$, close the lower half-plane and invoke residue theorem (now the contour traverse clockwise) to yield

$$y(t) = -2\pi i \left[\frac{-e^t}{2i\pi(1+a)(1+b)} \right] = \frac{e^t}{(1+a)(1+b)}$$

The solution is

$$y(t) = \begin{cases} \frac{e^t}{(1+a)(1+b)} & t < 0 \\ \frac{2}{a-b} \left[\frac{e^{-at}}{a^2-1} - \frac{e^{-bt}}{b^2-1} \right] + \frac{e^{-t}}{(1-a)(1-b)} & t > 0 \end{cases}$$

Problem 2.16 (Tensors): [In this question you should assume three dimensions.]

- (i) Write down the transformation law for the components t_{ij} of a tensor of rank 2 and the components u_{ijkl} of a tensor of rank 4 under rotation of the coordinate axes. [2]
- (ii) What is an isotropic tensor? Show that $a\delta_{ij}$ and $b\delta_{ij}\delta_{kl} + c\delta_{ik}\delta_{jl} + d\delta_{il}\delta_{jk}$, with a, b, c and d constants and δ_{ij} the Kronecker delta, are isotropic tensors. [4]
- (iii) By considering rotations by $\pi/2$ about two different coordinate axes show that $a\delta_{ij}$ is the most general form of an isotropic tensor of rank 2. [4]
(You may henceforth assume that $b\delta_{ij}\delta_{kl} + c\delta_{ik}\delta_{jl} + d\delta_{il}\delta_{jk}$ is the most general form for an isotropic tensor of rank 4.)

- (iv) Consider the tensors

$$A_{ij} = \int_{\mathcal{V}_R} x_i x_j |\mathbf{x}|^2 dV$$

and

$$B_{ijkl} = \int_{\mathcal{V}_R} x_i x_j x_k x_l dV$$

where the volume \mathcal{V}_R is a sphere of radius R centred on the origin. Show that A_{ij} and B_{ijkl} are isotropic tensors and determine their components. [6]

- (v) Consider the tensor

$$C_{ij} = \int_{\mathcal{V}_R} \{x_i x_j |\mathbf{x}|^2 + x_i x_j (\mathbf{x} \cdot \mathbf{n})^2\} dV$$

where \mathbf{n} is a fixed unit vector. What are the eigenvectors and corresponding eigenvalues of this tensor? [4]

Answer 2.16.

(i) The transformation laws are

$$t_{ij} = L_{i\alpha} L_{j\beta} t_{\alpha\beta}, \quad u'_{ijkl} = L_{i\alpha} L_{j\beta} L_{k\gamma} L_{l\eta} u_{\alpha\beta\gamma\eta}$$

where L_{ij} are elements of orthogonal matrix representing the rotation of coordinate system.

(ii) Isotropic tensor has the property $s'_{ijkl\dots} = s_{ijkl\dots}$. Using $LL^T = I$,

$$(a\delta_{ij})' = aL_{i\alpha} L_{j\beta} \delta_{\alpha\beta} = aL_{i\alpha} L_{\alpha j}^T = a\delta_{ij}$$

$$\begin{aligned} (b\delta_{ij}\delta_{kl} + c\delta_{ik}\delta_{jl} + d\delta_{il}\delta_{jk})' &= bL_{i\alpha} L_{j\beta} L_{k\gamma} L_{l\eta} \delta_{\alpha\beta} \delta_{\gamma\eta} + cL_{i\alpha} L_{j\beta} L_{k\gamma} L_{l\eta} \delta_{\alpha\gamma} \delta_{\beta\eta} + dL_{i\alpha} L_{j\beta} L_{k\gamma} L_{l\eta} \delta_{\alpha\eta} \delta_{\beta\gamma} \\ &= bL_{i\beta} L_{j\beta} + L_{k\eta} L_{l\eta} + cL_{i\gamma} L_{k\gamma} L_{j\eta} L_{l\eta} + dL_{i\eta} L_{j\gamma} L_{k\gamma} L_{l\eta} \\ &= b\delta_{ij}\delta_{kl} + c\delta_{ik}\delta_{jl} + d\delta_{il}\delta_{jk} \end{aligned}$$

Hence, both $a\delta_{ij}$ and $b\delta_{ij}\delta_{kl} + c\delta_{ik}\delta_{jl} + d\delta_{il}\delta_{jk}$ are isotropic tensors.

(iii) If T_{ij} is isotropic then $T_{ij} = R_{ip} R_{jq} T_{pq}$ for any R . We will use rotations by $\frac{\pi}{2}$ about each axis. First, we take about x_3 -axis

$$(R_{ij}) = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Then

$$T_{13} = R_{1p} R_{3q} T_{pq} = R_{12} R_{33} T_{23} = T_{23}$$

$$T_{23} = R_{2p} R_{3q} T_{pq} = R_{21} R_{33} T_{13} = -T_{13}$$

so $T_{13} = T_{23} = 0$. We also have

$$T_{11} = R_{1p} R_{1q} T_{pq} = R_{12} R_{12} T_{22} = T_{22}$$

Next we rotate by $\pi/2$ about x_1 -axis

$$(R_{ij}) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$

Then

$$T_{32} = R_{3p} R_{2q} T_{pq} = R_{32} R_{23} T_{23} = -T_{23} = 0$$

$$T_{12} = R_{1p} R_{2q} T_{pq} = R_{11} R_{23} T_{13} = -T_{13} = 0$$

$$T_{31} = R_{3p} R_{1q} T_{pq} = R_{32} R_{11} T_{21} = -T_{21}$$

$$T_{21} = R_{2p} R_{1q} T_{pq} = R_{23} R_{11} T_{31} = T_{31}$$

so $T_{31} = T_{21} = 0$. We also have

$$T_{22} = R_{2p} R_{2q} T_{pq} = R_{23} R_{23} T_{33} = T_{33}$$

Combining the result from the two rotations, we conclude that all the off-diagonal elements of T are zero, i.e. $T_{ij} = 0$ if $i \neq j$ and all diagonal elements are equal, i.e. $T_{11} = T_{22} = T_{33}$. Hence $T_{ij} = \alpha\delta_{ij}$ for scalar α .

(iv) First evaluate the transformation law for A_{ij} :

$$\begin{aligned} A'_{ij} &= \int_{V_R} x'_i x'_j |\mathbf{x}'|^2 dx' dy' dz' \\ &= \int_{V_R} L_{i\alpha} x_\alpha L_{j\beta} x_\beta |\mathbf{x}|^2 dx dy dz \\ &= L_{i\alpha} L_{j\beta} A_{\alpha\beta} \end{aligned}$$

where $|\mathbf{x}|^2$ is a scalar and $dV' = dV$. But A'_{ij} is actually A_{ij} by just relabelling. Hence, $A'_{ij} = A_{ij}$ and thus isotropic. From part (iii), $A_{ij} = a\delta_{ij} \implies A_{ii} = 3a$. Hence

$$a = \frac{1}{3} \int_{V_R} |\mathbf{x}|^4 dV = \frac{1}{3} \int_{V_R} r^4 r^2 \sin \theta d\theta d\phi = \frac{4\pi}{21} R^7 \implies A_{ij} = \frac{4}{21} \pi R^7 \delta_{ij}$$

Next, evaluate the transformation law for B_{ijkl} :

$$\begin{aligned} B'_{ijkl} &= \int_{V_R} x'_i x'_j x'_k x'_l dx' dy' dz' \\ &= \int_{V_R} L_{i\alpha} x_\alpha L_{j\beta} x_\beta L_{k\gamma} x_\gamma L_{l\eta} x_\eta dx dy dz \\ &= L_{i\alpha} L_{j\beta} L_{k\gamma} L_{l\eta} B_{\alpha\beta\gamma\eta} \end{aligned}$$

Using a similar labelling argument, we conclude $B'_{ijkl} = B_{ijkl}$. Now, we relate B with the previous result for A by tracing out any two pair indices:

$$B_{ijkk} = A_{ij}, \quad B_{ijki} = A_{jk}, \quad B_{jjkl} = A_{kl}$$

Then, we get $\frac{4}{21} \pi R^7 = 3b + c + d = 3d + c + b = 3c + b + d$ and thus $b = c = d = \frac{4}{21} \frac{1}{5} \pi R^7$. Hence,

$$B_{ijkl} = \frac{4}{105} \pi R^7 (\delta_{ij} \delta_{kl} + \delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk})$$

(v) From the definition of C_{ij} , observe that

$$(C_{ij} - A_{ij})n_j = \int_{V_R} x_i (\mathbf{x} \cdot \mathbf{n})^3 dV$$

Without loss of generality, choose $\mathbf{n} = \hat{\mathbf{z}}$, then it becomes $\int_{V_R} x_i z^3 dV$. The integrand is odd for $x_i = x, y$, hence

$$(C_{3j} - A_{3j})n_j = \int_{V_R} z^4 dV = \int_0^{2\pi} d\phi \int_0^R \int_0^\pi r^4 \cos^4 \theta r^2 \sin \theta d\theta dr = \frac{4\pi}{35} R^7$$

Now for any $\mathbf{b} \perp \mathbf{n}$,

$$(C_{ij} - A_{ij})b_j = \int_{V_R} x_i (\mathbf{x} \cdot \mathbf{n})^2 \mathbf{b} \cdot \mathbf{x} dV = \int_{V_R} x_i z^2 x dV$$

Again, choosing $\mathbf{n} \parallel \hat{\mathbf{z}}$, then \mathbf{b} can either be parallel to $\hat{\mathbf{x}}$ or $\hat{\mathbf{y}}$, say choose the former:

$$(C_{1j} - A_{1j})b_j = \int_{V_R} x^2 z^2 dV = \int_0^{2\pi} \int_0^R \int_0^\pi r^2 \sin^2 \theta \cos^2 \phi r^2 \cos^2 \theta r^2 \sin \theta d\theta dr d\phi = \frac{4\pi R^7}{105}$$

For the last integral, just replace $\cos^2 \phi$ with $\sin^2 \phi$, and we will get a similar result. Hence, the eigenvalues of C are one copy of

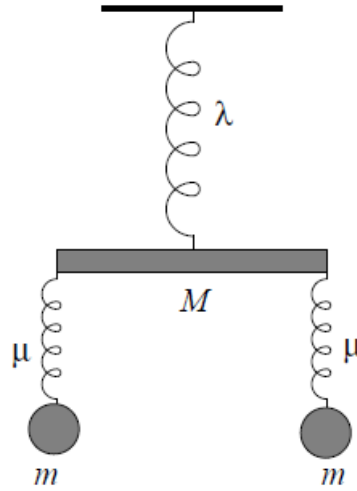
$$\left(\frac{4}{21} + \frac{4}{35} \right) \pi R^7 = \frac{32}{105} \pi R^7$$

and two copies of

$$\left(\frac{4}{21} + \frac{4}{105} \right) \pi R^7 = \frac{8}{35} \pi R^7$$

Problem 2.17 (Normal Modes): A mechanical system has three degrees of freedom and is described by coordinates q_1 , q_2 and q_3 , where $q_1 = q_2 = q_3 = 0$ corresponds to a position of equilibrium of the system. The kinetic energy $\mathcal{T} = \frac{1}{2} \sum_{i=1}^3 \sum_{j=1}^3 T_{ij}(\mathbf{q}) \dot{q}_i \dot{q}_j = \frac{1}{2} \dot{\mathbf{q}}^T \mathbf{T} \dot{\mathbf{q}}$, defining a matrix \mathbf{T} . The potential energy is given by the function $\mathcal{V}(\mathbf{q})$.

- (i) Define the Lagrangian \mathcal{L} of the system and write down the corresponding Euler-Lagrange equations. What conditions must apply at the equilibrium position $q_1 = q_2 = q_3 = 0$? Calculate the leading-order non-constant terms in a Taylor expansion of $\mathcal{V}(\mathbf{q})$ about this position, and hence show that these leading-order non-constant terms can be written as $\frac{1}{2} \mathbf{q}^T \mathbf{V} \mathbf{q}$ for some constant matrix \mathbf{V} . Deduce the form of the Lagrangian and the corresponding Euler-Lagrange equations for small disturbances from equilibrium. With reference to this set of equations define the terms normal frequencies and normal modes. [5]



- (ii) Consider a system consisting of a heavy horizontal bar of mass M , from the ends of which two masses m hang on identical vertical springs, each with spring constant μ and equilibrium length l . The bar itself is suspended from a fixed point by a spring with spring constant λ and equilibrium length L . (The bar is constrained to remain horizontal.) Define q_1 , q_2 and q_3 to be the vertical displacements of, respectively, the bar and the two masses away from their equilibrium positions. Show that the relevant matrices \mathbf{T} and \mathbf{V} (as defined above) take the form

$$\mathbf{T} = \begin{pmatrix} M & 0 & 0 \\ 0 & m & 0 \\ 0 & 0 & m \end{pmatrix}, \quad \mathbf{V} = \begin{pmatrix} \frac{\lambda}{L} + \frac{2\mu}{l} & -\frac{\mu}{l} & -\frac{\mu}{l} \\ -\frac{\mu}{l} & \frac{\mu}{l} & 0 \\ -\frac{\mu}{l} & 0 & \frac{\mu}{l} \end{pmatrix}$$

and hence construct the Lagrangian for this system. [6]

- (iii) Hence for the case $M = 2$, $m = 1$, $\lambda = 4$, $\mu = 1$, $L = 1$ and $l = 1$, derive the corresponding normal frequencies and normal modes. [6]
- (iv) Give a brief geometrical description of each normal mode. [3]

Answer 2.17.

- (i) The Lagrangian of the system is the difference between the kinetic energy and the potential energy, i.e. $\mathcal{L} = \mathcal{T} - \mathcal{V} = \frac{1}{2}\dot{\mathbf{q}}^T \mathbf{T} \dot{\mathbf{q}} - \mathcal{V}(\mathbf{q})$. To extremize the Lagrangian, it has to satisfy the Euler-Lagrange equation

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\mathbf{q}}} = \frac{\partial \mathcal{L}}{\partial \mathbf{q}}$$

At equilibrium, $\frac{\partial \mathcal{L}}{\partial \mathbf{q}} = \frac{\partial \mathcal{T}}{\partial \mathbf{q}} - \frac{\partial \mathcal{V}}{\partial \mathbf{q}} = 0 - 0 = 0$. When we have a deviation $\Delta \mathbf{q} = (q_1, q_2, q_3)$ from $\mathbf{q}_0 = \mathbf{0}$, then the Taylor expansion of \mathcal{V} is

$$\mathcal{V}(\Delta \mathbf{q}) = \mathcal{V}(\mathbf{0}) + 0 + \frac{1}{2}(\Delta \mathbf{q} \cdot \nabla)^2 \mathcal{V} + O(\Delta \mathbf{q})^3 = \mathcal{V}(\mathbf{0}) + \frac{1}{2} \begin{pmatrix} q_1 & q_2 & q_3 \end{pmatrix} \begin{pmatrix} \frac{\partial^2 \mathcal{V}}{\partial q_1^2} & \frac{\partial^2 \mathcal{V}}{\partial q_1 \partial q_2} & \frac{\partial^2 \mathcal{V}}{\partial q_1 \partial q_3} \\ \frac{\partial^2 \mathcal{V}}{\partial q_1 \partial q_2} & \frac{\partial^2 \mathcal{V}}{\partial q_2^2} & \frac{\partial^2 \mathcal{V}}{\partial q_2 \partial q_3} \\ \frac{\partial^2 \mathcal{V}}{\partial q_1 \partial q_3} & \frac{\partial^2 \mathcal{V}}{\partial q_2 \partial q_3} & \frac{\partial^2 \mathcal{V}}{\partial q_3^2} \end{pmatrix} \begin{pmatrix} q_1 \\ q_2 \\ q_3 \end{pmatrix} + O(\Delta \mathbf{q}^2)$$

Then for small disturbances, we have $\mathcal{L} = \frac{1}{2}\dot{\mathbf{q}}^T \mathbf{T} \dot{\mathbf{q}} - \frac{1}{2}\mathbf{q}^T \mathbf{V} \mathbf{q}$, and so by the Euler-Lagrange equation, we have $\frac{d}{dt}(\mathbf{T} \dot{\mathbf{q}}) = -\mathbf{V} \mathbf{q}$. Let's assume \mathbf{T} is independent of time. We look for solutions of the form $\mathbf{q} = \mathbf{a}_n e^{i\omega_n t}$ where \mathbf{a}_n are the normal modes and ω_n are the normal frequencies, then we find the normal frequencies

$$-\omega^2 \mathbf{T} \mathbf{a}_n = -\mathbf{V} \mathbf{a}_n \implies \det |\mathbf{V} - \omega^2 \mathbf{T}| = 0$$

the normal modes are thus the corresponding eigenvectors for each normal frequency.

- (ii) Define the q_i coordinates relative to the equilibrium, then the kinetic energy is

$$\mathcal{T} = \frac{1}{2}M|\dot{\mathbf{q}}_1|^2 + \frac{1}{2}m(|\dot{\mathbf{q}}_2|^2 + |\dot{\mathbf{q}}_3|^2) = \frac{1}{2} \begin{pmatrix} \dot{q}_1 & \dot{q}_2 & \dot{q}_3 \end{pmatrix} \begin{pmatrix} M & 0 & 0 \\ 0 & m & 0 \\ 0 & 0 & m \end{pmatrix} \begin{pmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \dot{q}_3 \end{pmatrix}$$

The potential energy is

$$\mathcal{V} = \frac{1}{2}\lambda q_1^2 + \frac{1}{2}\mu(q_1 - q_2)^2 + \frac{1}{2}\mu(q_1 - q_3)^2 = \frac{1}{2} \begin{pmatrix} q_1 & q_2 & q_3 \end{pmatrix} \begin{pmatrix} \lambda + 2\mu & -\mu & -\mu \\ -\mu & \mu & 0 \\ -\mu & 0 & \mu \end{pmatrix} \begin{pmatrix} q_1 \\ q_2 \\ q_3 \end{pmatrix}$$

We neglect gravity contributions to \mathcal{V} since it merely redefines the equilibrium positions. The Lagrangian is thus

$$\mathcal{L} = \frac{1}{2} \begin{pmatrix} \dot{q}_1 & \dot{q}_2 & \dot{q}_3 \end{pmatrix} \begin{pmatrix} M & 0 & 0 \\ 0 & m & 0 \\ 0 & 0 & m \end{pmatrix} \begin{pmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \dot{q}_3 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} q_1 & q_2 & q_3 \end{pmatrix} \begin{pmatrix} \lambda + 2\mu & -\mu & -\mu \\ -\mu & \mu & 0 \\ -\mu & 0 & \mu \end{pmatrix} \begin{pmatrix} q_1 \\ q_2 \\ q_3 \end{pmatrix}$$

- (iii) With $M = 2$, $m = 1$, $\lambda = 4$, $\mu = 1$, $L = 1$, $l = 1$, solve for

$$0 = \det |\mathbf{V} - \omega^2 \mathbf{T}| = \det \begin{pmatrix} 6 - 2\omega^2 & -1 & -1 \\ -1 & 1 - \omega^2 & 0 \\ -1 & 0 & 1 - \omega^2 \end{pmatrix} = (1 - \omega^2)((6 - 2\omega^2)(1 - \omega^2) - 2) = 2(1 - \omega^2)(\omega^4 - 4\omega^2 + 2)$$

with solutions $\omega^2 = 1$, $\omega^2 = 2 \pm \sqrt{2}$, with respective normalized eigenvectors $\frac{1}{\sqrt{2}}(0, 1, -1)^T$ and $\frac{1}{\sqrt{5 \pm 2\sqrt{2}}}(\mp\sqrt{2} - 1, 1, 1)^T$.

- (iv)
- $\omega^2 = 1$: the bar is stationary and the two masses are oscillating in anti-phase with equal amplitudes;
 - $\omega^2 = 2 + \sqrt{2}$: the two masses oscillate in phase, but the bar oscillate in anti-phase with relative amplitude $-\sqrt{2} - 1$;
 - $\omega^2 = 2 - \sqrt{2}$: the two masses and the bar all oscillate in phase with relative amplitude $\sqrt{2} - 1$;

Problem 2.18 (Group Theory):

- (i) Define the order
- $|G|$
- of a finite group
- G
- and the order of an element
- $g \in G$
- . [2]

Consider the Cartesian product of two groups G_1 and G_2 . This is the set $G_1 \times G_2$ of all pairs (g_1, g_2) with the composition law

$$(g_1, g_2)(g'_1, g'_2) \equiv (g_1g'_1, g_2g'_2)$$

- (ii) Show that
- $G_1 \times G_2$
- is a group. What is the order of the group? [6]

- (iii) Consider the order 2 group
- $Z_2 = \{e, w\}$
- . Construct the multiplication table for the order 4 group
- $Z_2 \times Z_2$
- . [4]

- (iv) Now consider the order 4 cyclic group
- $Z_4 = \{e, a, a^2, a^3\}$
- . Show that the order 2 cyclic group
- $Z_2 = \{e, a^2\}$
- is a proper subgroup for
- Z_4
- . Prove there are no other proper subgroups for
- Z_4
- . Hence, show that
- $Z_2 \times Z_2$
- is not isomorphic to
- Z_4
- . [8]

Answer 2.18.

- (i) The order of a group
- G
- is the number of elements of
- G
- . If
- G
- is a group and
- $g \in G$
- , the order of
- g
- (denoted as
- $\text{ord}(g)$
-) is the smallest
- $k \in \mathbb{N}$
- s.t.
- $g^k = e$
- where
- e
- is the identity of
- G
- .

- (ii) • Closure: For
- $g_1, g'_1 \in G_1$
- ,
- $g_2, g'_2 \in G_2$
- ,
- $\implies (g_1, g_2), (g'_1, g'_2) \in G_1 \times G_2$
- . Since
- G_1
- and
- G_2
- are groups,
- $g_1, g'_1 \in G_1 \implies g_1g'_1 \in G_1$
- ,
- $g_2, g'_2 \in G_2 \implies g_2g'_2 \in G_2$
- , then we must have
- $(g_1g_1', g_2g'_2) \in G_1 \times G_2$
- .

- Identity: Let
- $e_1 \in G_1$
- ,
- $e_2 \in G_2$
- be identities, then

$$(e_1, e_2)(g_1, g_2) = (e_1g_1, e_2g_2) = (g_1, g_2) \in G_1 \times G_2 \implies (e_1, e_2) \in G_1 \times G_2$$

- Associative: For
- $g_1, g'_1, g''_1 \in G_1$
- ,
- $g_2, g'_2, g''_2 \in G_2$
- , then consider

$$\begin{aligned} [(g_1, g_2)(g'_1, g'_2)](g''_1, g''_2) &= (g_1g'_1, g_2g'_2)(g''_1, g''_2) \\ &= (g_1g'_1g''_1, g_2g'_2g''_2) \\ &= (g_1, g_2)(g'_1g''_1, g'_2g''_2) \\ &= (g_1, g_2)[(g'_1, g'_2)(g''_1, g''_2)] \end{aligned}$$

- Inverse: Since
- G_1
- and
- G_2
- are groups,
- $g_1 \in G_1 \implies g_1^{-1} \in G_1$
- ,
- $g_2 \in G_2 \implies g_2^{-1} \in G_2$
- , so

$$(g_1^{-1}, g_2^{-1})(g_1, g_2) = (g_1^{-1}g_1, g_2^{-1}g_2) = (e_1, e_2) \in G_1 \times G_2 \implies (g_1^{-1}, g_2^{-1}) \in G_1 \times G_2$$

which is inverse for some $(g_1, g_2) \in G_1 \times G_2$.

All the group axioms are satisfied. The order of $G_1 \times G_2$ is $|G_1| \times |G_2|$.

- (iii) Since the group
- Z_2
- is order 2, then
- $w^2 = e$
- . The group table of
- $Z_2 \times Z_2$
- is

	(e, e)	(e, w)	(w, e)	(w, w)
(e, e)	(e, e)	(e, w)	(w, e)	(w, w)
(e, w)	(e, w)	(e, e)	(w, w)	(w, e)
(w, e)	(w, e)	(w, w)	(e, e)	(e, w)
(w, w)	(w, w)	(w, e)	(e, w)	(e, e)

- (iv) The generators are
- $\langle e \rangle = \{e\} \implies \text{ord}(e) = 1$
- ,
- $\langle a \rangle = \{a, a^2, a^3, e\} \implies \text{ord}(a) = 4$
- ,
- $\langle a^2 \rangle = \{a^2, e\} \implies \text{ord}(a^2) = 2$
- ,
- $\langle a^3 \rangle = \{a^3, a^2, a, e\} \implies \text{ord}(a^3) = 4$
- . The only order 2 group is the group
- $\langle a^2 \rangle$
- . This is the cyclic group
- $Z_2 = \{e, a^2\}$
- with group table

	e	a^2
e	e	a^2
a^2	a^2	e

The group table illustrates closure. Z_2 inherits associativity from the parent group Z_4 and share the same identity e . For any $g \in Z_2$, the inverse is g itself. Z_2 thus satisfies the axioms of a subgroup. Since $|Z_2| < |Z_4|$, Z_2 is a proper subgroup. But $\text{ord}(a), \text{ord}(a^3) = |Z_4|$ so $\langle a \rangle, \langle a^3 \rangle$ are not proper subgroups. $\langle e \rangle$ is a trivial subgroup and by definition is not a proper subgroup.

$Z_2 \times Z_2$ has three order-two subgroups, namely

$$\langle (w, w) \rangle, \quad \langle (e, w) \rangle, \quad \langle (w, e) \rangle$$

Hence the group $Z_2 \times Z_2$ is not isomorphic to Z_4 . For any isomorphism $\Phi : G \rightarrow H$, elements must map to elements of the same order as if $g \mapsto h$, then

$$h^{\text{ord}(g)} = \Phi(g^{\text{ord}(g)}) = \Phi(e) = e$$

where we used the fact that Φ is a homomorphism. $\text{ord}(h)$ must thus be a factor of $\text{ord}(g)$. But Φ is also an isomorphism and hence invertible. By symmetry, $\text{ord}(g)$ must also be a factor of $\text{ord}(h)$. Thus, $\text{ord}(g) = \text{ord}(h)$. But, $\forall g \in Z_4$, the list of possible orders are $\{1, 4, 2, 4\}$, whereas $\forall h \in Z_2 \times Z_2$, the list of possible orders are $\{1, 2, 2, 2\}$. The two groups are thus not isomorphic.

Problem 2.19 (Group Theory):

- (i) If H and K are subgroups of G , show that the intersection $H \cap K$ is also a group. [6]
- (ii) Consider D_3 , the group of symmetries of the equilateral triangle. D_3 has six elements: the identity (I); two rotations (A, B); and three reflections (C, D, E). Explain their geometrical action on the equilateral triangle. Construct the multiplication table for D_3 . Is this group abelian? [9]
- (iii) How many order 2 subgroups are there in D_3 ? List them. Are they normal subgroups of D_3 ? Justify your conclusion. Finally, show by explicit construction that the union of two order 2 subgroups of D_3 does not form a group. [5]

Answer 2.19.

(i) Check axioms of a group:

- Closure: If $g_1, g_2 \in H \cap K$, $g_1 g_2 \in H \cap K$.
- Identity: $H, K \leq G \implies e \in H, e \in K \implies e \in H \cap K$.
- Associativity: $H \cap K$ inherits associativity from H, K .
- Inverse: $H, K \leq G, g_2, g_1 \in H \cap K \implies g_1^{-1}, g_2^{-1} \in H \cap K$.

(ii) Let the 3 vertices of a triangle be (a, b, c) , then the mappings are:

$$I : (a, b, c) \mapsto (a, b, c), \quad A : (a, b, c) \mapsto (b, c, a), \quad B : (a, b, c) \mapsto (c, a, b)$$

$$C : (a, b, c) \mapsto (a, c, b), \quad D : (a, b, c) \mapsto (c, b, a), \quad E : (a, b, c) \mapsto (b, a, c)$$

Since A, B are rotations, $A^3 = B^3 = I$. Also, A and B are rotations in the opposite directions and so $A^{-1} = B$ and $B^{-1} = A$. Since C, D and E are reflections, then $C^2 = D^2 = E^2 = I$. We can thus work out $AC = D, AD = E, AE = C$ and similar relations. The group table of D_3 is thus

	I	A	B	C	D	E
I	I	A	B	C	D	E
A	A	B	I	D	E	C
B	B	I	A	E	C	D
C	C	E	D	I	B	A
D	D	C	E	A	I	B
E	E	D	C	B	A	I

The group table is not symmetric on the main diagonal, hence D_3 is not abelian (it is also the smallest non-abelian subgroup).

(iii) Since the reflections have order 2, the order 2 subgroups in D_3 are

$$\{I, C\}, \quad \{I, D\}, \quad \{I, E\}$$

All 3 subgroups are not normal in D_3 as $\{C, D, E\}$ form a conjugacy class. None of the above are constructed from the union of entire conjugacy classes. $\{I, C\} \cup \{I, D\} = \{I, C, D\}$ is not a group as it is not closed. For instance, $CD = B \notin \{I, C, D\}$.

Problem 2.20 (Representation Theory): [In this question, you may state without proof any theorems you use.]

- (i) Suppose G_1 and G_2 are groups, and D is a mapping $D : G_1 \rightarrow G_2$. Give the definition for the map D to be a homomorphism. What is the kernel of D , $\ker(D)$? [2]

Let $S_3 = \{e, x, y, y^2, xy, xy^2\}$ be the $n = 3$ symmetric group with

$$x^2 = y^3 = e, \quad yx = xy^2, \quad y^2x = xy$$

- (ii) Verify by explicit calculation that, with $z = e^{2\pi i/3}$,

$$\begin{aligned} R(x) &= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad R(y) = \begin{pmatrix} z & 0 \\ 0 & z^2 \end{pmatrix}, \quad R(y^2) = \begin{pmatrix} z^2 & 0 \\ 0 & z \end{pmatrix} \\ R(xy) &= \begin{pmatrix} 0 & z^2 \\ z & 0 \end{pmatrix}, \quad R(xy^2) = \begin{pmatrix} 0 & z \\ z^2 & 0 \end{pmatrix} \end{aligned} \quad (*)$$

is a two-dimensional complex representation of S_3 . You can assume without proof that (*) is an irreducible representation. [7]

- (iii) Given that the trivial representation of S_3 is the one-dimensional complex representation $T(s) = 1$ where $s \in S_3$, find the non-trivial one-dimensional complex representation $U : S_3 \rightarrow \mathbb{C}^1$. What is $\text{Ker}(U)$? Is U a faithful representation? [8]

- (iv) Finally, given these results, deduce the number of conjugacy classes in S_3 . [3]

Answer 2.20.

- (i) If G_1 and G_2 are groups then a function $D : G_1 \rightarrow G_2$ is called a group homomorphism, if $\forall a, b \in G_1$, we have $D(a \cdot_{G_1} b) = D(a) \cdot_{G_2} D(b)$. For the group homomorphism $D : G_1 \rightarrow G_2$, the kernel of D is $\text{Ker}(D) := \{h \in G_1 | D(h) = e_{G_2} \text{ for some } h \in G_1\}$.

- (ii) Since $z = e^{2\pi i/3}$, then $z^3 = 1$. Define $R(e) := \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$. Then, since R is a representation, R is a homomorphism. Verify the group table of S_3 .

$$R(x^2) = R(x)R(x) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = R(e) \implies x^2 = e$$

$$R(y^3) = R(y)R(y)R(y) = \begin{pmatrix} z & 0 \\ 0 & z^2 \end{pmatrix} \begin{pmatrix} z & 0 \\ 0 & z^2 \end{pmatrix} \begin{pmatrix} z & 0 \\ 0 & z^2 \end{pmatrix} = \begin{pmatrix} z^3 & 0 \\ 0 & z^6 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = R(e) \implies y^3 = e$$

$$R(yx) = R(y)R(x) = \begin{pmatrix} z & 0 \\ 0 & z^2 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & z \\ z^2 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} z^2 & 0 \\ 0 & z \end{pmatrix} = R(x)R(y^2) = R(xy^2)$$

$$R(y^2x) = R(y^2)R(x) = \begin{pmatrix} z^2 & 0 \\ 0 & z \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & z^2 \\ z & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} z & 0 \\ 0 & z^2 \end{pmatrix} = R(x)R(y) = R(xy)$$

The last two implies $yx = xy^2$ and $y^2x = xy$ respectively.

- (iii) Let $x = a \in \mathbb{C}^1$, $y = b \in \mathbb{C}^1$, then the group table of S^3 gives $a = -1$, $b = 1$. So the character of U is the list of trace of $U(s)$ for $s \in S_3$. Since \mathbb{C}^1 is a number, its trace is itself, so

$$\chi(U) = \{e = 1, x = -1, y = 1, y^2 = 1, xy = -1, xy^2 = -1\}$$

which is orthogonal to $\chi(T) = \{1, 1, 1, 1, 1, 1\}$ (trivial rep) and

$$\chi(D) = \{\text{Tr}(R(e)), \text{Tr}(R(x)), \text{Tr}(R(y)), \text{Tr}(R(y^2)), \text{Tr}(R(xy)), \text{Tr}(R(xy^2))\} = \{2, 0, -1, -1, 0, 0\}$$

where we used the roots identity $1 + z + z^2 = 0$, for $z = e^{i2\pi/3}$. From part (i), $\text{Ker}(U) = \{s \in S_3 | U(s) = 1\} = \{e, y, y^2\} \neq \{0\}$, which is non-trivial, hence not a faithful representation

- (iv) Since the number of irreducible representations is the number of conjugacy classes and the sum of squares of irreducible representations is the order of the group, we have

$$|S_3| = 3! = 6 = 1^2 + 1^2 + 2^2$$

where we have two one-dimensional representations T, U and one two-dimensional representation D . Hence, there is exactly 3 conjugacy classes.

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3.1 Paper 1

Problem 3.1 (Vector Calculus):

- (a) Let \mathbf{F} be a vector field and \mathbf{a} be an arbitrary constant vector. Show that [4]

$$\nabla \times (\mathbf{a} \times \mathbf{F}) = \mathbf{a}(\nabla \cdot \mathbf{F}) - (\mathbf{a} \cdot \nabla)\mathbf{F}$$

- (b) State Stokes' Theorem. [2]

- (c) By applying it to the above identity, show that

$$\int_C d\mathbf{l} \times \mathbf{F} = \int_S (d\mathbf{S} \times \nabla) \times \mathbf{F}$$

for any closed curve C that bounds a surface S . [8]

- (d) Verify this identity for the case where C is a square path starting at $(0,0,0)$, then progressing in a straight line to $(0,1,0)$, then to $(1,1,0)$, then to $(1,0,0)$ and finally back to the origin with $\mathbf{F} = \mathbf{r}$, where $\mathbf{r} = (x, y, z)$. [6]

Answer 3.1.

- (a) Use suffix notation. LHS is $\epsilon_{kij}\epsilon_{pqj}\partial_i a_p F_q = \partial_i a_k F_i - \partial_i a_i F_k = a_k(\nabla \cdot \mathbf{F}) - (\mathbf{a} \cdot \nabla)F_k$, as desired.

- (b) Let $\mathbf{F} = \mathbf{F}(\mathbf{x})$ be a continuously differentiable vector field, and let surface S be orientable, piecewise regular with piecewise smooth boundary ∂S , then Stokes' theorem states that

$$\int_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S} = \oint_{\partial S} \mathbf{F} \cdot d\mathbf{x}$$

- (c) Apply Stokes' theorem to part (a)'s result:

$$\oint_C (\mathbf{a} \times \mathbf{F}) \cdot d\mathbf{l} = \int_S (\nabla \times (\mathbf{a} \times \mathbf{F})) \cdot d\mathbf{S} = \int_S (d\mathbf{S} \times \nabla) \cdot (\mathbf{a} \times \mathbf{F}) = - \int_S ((d\mathbf{S} \times \nabla) \times \mathbf{F}) \cdot \mathbf{a}$$

where we used $\epsilon_{ijk}\partial_i(\epsilon_{pqj}a_p F_q)dS_k = (\epsilon_{kij}dS_k\partial_i)\epsilon_{pqj}a_p F_q = -\epsilon_{jqp}(\epsilon_{kij}dS_k\partial_i)F_q a_p$, but the LHS is also $-\oint_C (d\mathbf{l} \times \mathbf{F}) \cdot \mathbf{a}$. Putting everything to one side

$$\mathbf{a} \cdot \left(\oint_C (d\mathbf{l} \times \mathbf{F}) - \int_S (d\mathbf{S} \times \nabla) \times \mathbf{F} \right) = 0$$

where \mathbf{a} is a constant vector and can be pulled out of the integral. \mathbf{a} is also arbitrary, so whatever is dotted with \mathbf{a} must be a zero vector. The result follows.

- (d) Let $d\mathbf{S} = (0, 0, -dxdy)$, then $d\mathbf{S} \times \nabla = (-\partial_y, \partial_x, 0)dxdy$ and so $\int_S (d\mathbf{S} \times \nabla) \times \mathbf{F} = (0, 0, 2)$. For C , we segment into four segments:

- C_1 where $d\mathbf{l} = (0, dt, 0)$ with $y = t$, $0 \leq t \leq 1$;
- C_2 where $d\mathbf{l} = (dt, 0, 0)$ with $x = t$, $0 \leq t \leq 1$ and $y = 1$;
- C_3 where $d\mathbf{l} = (0, -dt, 0)$ with $x = 1$, $y = 1 - t$, $0 \leq t \leq 1$;
- C_4 where $d\mathbf{l} = (-dt, 0, 0)$ with $x = 1 - t$.

The line integral gives the same result, with only the term from C_2 and C_3 contributes.

$$\int_C d\mathbf{l} \times \mathbf{F} = \left(\int_0^1 dt + \int_0^1 dt \right) \hat{\mathbf{z}} = 2\hat{\mathbf{z}}$$

$$\int_S (d\mathbf{S} \times \nabla) \times \mathbf{F} = \int_0^1 \int_0^1 2\hat{\mathbf{z}}dxdy = 2\hat{\mathbf{z}}$$

Problem 3.2 (Laplace's Equation): The number density of neutrons $n(\mathbf{r}, t)$ in a lump of Uranium is determined by the PDE

$$\nabla^2 n = \frac{\partial n}{\partial t} - \lambda n$$

where ∇^2 is the Laplacian operator, \mathbf{r} is the position vector, t is the time and λ is a constant.

- (a) Suppose the lump of Uranium is a sphere of radius a , and the density of the neutrons is spherically symmetric. Furthermore, suppose this equation can be solved by the method of separation of variables so that

$$n = R(r)T(t)$$

where r is the distance from the centre of the sphere. Find two ordinary differential equations for $R(r)$ and $T(t)$. [4]

- (b) Suppose that the density of neutrons is never zero, except at the surface of the sphere, and finite everywhere inside. Find $n(\mathbf{r}, t)$. [8]

- (c) Show that the concentration of neutrons will grow as a function of time provided that [8]

$$\lambda > \pi^2/a^2$$

[Hint: To find $R(r)$, substitute $R(r) = r^p f(r)$ for some p .]

Answer 3.2.

- (a) Use separation of variables $n(r, t) = R(r)T(t)$, then

$$\frac{1}{r^2 R} \frac{d}{dr} r^2 \frac{dR}{dr} = \frac{1}{T} \frac{dT}{dt} - \lambda = -b$$

which gives two ODE

$$\frac{dT}{dt} = (\lambda - b)T \quad (\text{time})$$

$$\frac{d}{dr} r^2 \frac{dR}{dr} = -br^2 R \quad (\text{radial})$$

- (b) Guessing the form $R(r) = r^p f(r)$, we have

$$r^{p+2} f''(r) + (r^{p+1} + (p+2)r^{p+1}) f'(r) + p(p+1)r^p - br^{2+p} f(r) = 0$$

Choosing $p = -1$, we have $f''(r)r = -brf(r)$ and so

$$R(r) = \frac{1}{r} (Ae^{\sqrt{-b}r} + Be^{-\sqrt{-b}r})$$

For R to be finite everywhere inside, we require $A = -B$. $r = a$ is also the first zero where $R(r = a) = 0$. This requires $e^{2\sqrt{-b}a} = 1$ and so

$$R(r) = \frac{A \sin(\pi r/a)}{r}$$

for $n = 1$ to be the first zero and that $n = \frac{\pi}{a}$. Similarly, $T(t) = e^{(\lambda - \pi^2/a^2)t}$. Finally,

$$n(r, t) = \frac{A}{r} \sin \frac{\pi r}{a} e^{(\lambda - \frac{\pi^2}{a^2})t}$$

- (c) $T(t) = e^{(\lambda - \pi^2/a^2)t}$ diverges if $\lambda > \pi^2/a^2$

Problem 3.3 (Green's Functions):

- (a) Find the general solution $y(x)$ to the homogeneous second-order linear differential equation [6]

$$\frac{d^2 y}{dx^2} + \frac{3}{x} \frac{dy}{dx} + \frac{y}{x^2} = 0$$

- (b) Construct the Green's function for this equation in the region $0 \leq x < \infty$, which satisfies

$$\frac{d^2}{dx^2} G(x, \xi) + \frac{3}{x} \frac{d}{dx} G(x, \xi) + \frac{1}{x^2} G(x, \xi) = \delta(x - \xi)$$

subject to the boundary conditions $G(0, \xi) = \frac{d}{dx} G(0, \xi) = 0$, where $\delta(x - \xi)$ is the Dirac delta function. [8]

- (c) Use your Green's function to solve the differential equation

$$\frac{d^2 y}{dx^2} + \frac{3}{x} \frac{dy}{dx} + \frac{y}{x^2} = x$$

for $x \geq 0$, subject to the boundary conditions $y(0) = y'(0) = 0$. [6]

Answer 3.3.

- (a) The general solution to the homogeneous equation is $y = c_1 x^{-1} + c_2 x^{-1} \ln(x)$, where we substitute $y = x^r$ for $r \in \mathbb{R}$ to obtain quadratic equation, i.e. $r^2 + 2r + 1 = 0$.
- (b) The corresponding Green's function must satisfy the given DE and the b.c.s $G(0, \xi) = G'(0, \xi) = 0$. Using the homogeneous solutions in part (a), we guess the Green's function $G(x, \xi)$ to be

$$G(x, \xi) = \begin{cases} (A(\xi) + B(\xi) \ln(x))x^{-1} & 0 \leq x < \xi < \infty \\ (C(\xi) + D(\xi) \ln(x))x^{-1} & 0 \leq \xi < x < \infty \end{cases}$$

Since $G(0, \xi) = \frac{\partial G}{\partial x}(0, \xi) = 0$, we must have $A = B = 0$. Integrating the DE over a small infinitesimal region at $x = \xi$, one obtains the jump condition $[\frac{\partial G}{\partial x}]_{-}^{+} = 1$. G must be continuous everywhere, including $x = \xi$. Otherwise, $G'' \propto \delta'(x - \xi)$ which is a contradiction. Imposing the jump and continuity condition respectively gives

$$\frac{\partial G}{\partial x} = -x^{-2}(C(\xi) + D(\xi) \ln(x)) + D(\xi)x^{-2} \implies D - C - D \ln \xi = \xi$$

$$C(\xi) + D(\xi) \ln(\xi) = 0$$

Both requires $D = \xi^2$ and $C = -\xi^2 \ln \xi$. Hence,

$$G(x, \xi) = \begin{cases} 0 & 0 \leq x < \xi < \infty \\ -\frac{\xi^2}{x} \ln(\xi/x) & 0 \leq \xi < x < \infty \end{cases}$$

- (c) The solution for the differential equation will be

$$y = \int_0^\xi G(x, \xi) f(\xi) d\xi = - \int_0^\xi \frac{\xi^2}{x} \ln(\xi/x) \xi d\xi = -x^3 \int_0^1 u^3 \ln(u) du = \frac{1}{16} x^3$$

where we used the substitution $u = \xi/x$ and integrated by parts. By construction, y obeys the desired boundary conditions.

Problem 3.4 (Fourier Transform):

- (a) Calculate the Fourier transform of the function

$$f(x) = e^{-\lambda x^2}$$

where λ is a positive constant.

[5]

- (b) Consider the partial differential equation for
- $\psi(x, t)$

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{\partial \psi}{\partial t}$$

Find the ordinary differential equation that

$$\tilde{\psi}(k, t) = \int_{-\infty}^{\infty} \psi(x, t) e^{-ikx} dx$$

obeys.

[5]

- (c) Find
- $\tilde{\psi}(k, t)$
- given
- $\psi(x, 0) = e^{-\lambda x^2}$
- .

[5]

- (d) Hence find
- $\psi(x, t)$
- for
- $t > 0$
- .

[5]

Hint: You may find the following relation

$$\int_{-\infty}^{\infty} e^{-\lambda(x+i\alpha)^2} dx = \sqrt{\frac{\pi}{\lambda}}$$

for α and λ real constants and $\lambda < 0$.

Answer 3.4. (a) Evaluate the Fourier Transform

$$\tilde{f}(k) = \int_{-\infty}^{\infty} e^{-\lambda x^2} e^{-ikx} dx = \int_{-\infty}^{\infty} e^{-\lambda(x^2 + (ikx/\lambda))} dx = \int_{-\infty}^{\infty} e^{-\lambda(x + \frac{ik}{2\lambda})^2} e^{-\lambda \frac{k^2}{4\lambda^2}} dx = e^{-\frac{k^2}{4\lambda}} \sqrt{\frac{\pi}{\lambda}}$$

- (b) Taking the Fourier Transform for the PDE w.r.t
- x
- ,

$$\int_{-\infty}^{\infty} \frac{\partial^2 \psi}{\partial x^2} e^{-ikx} dx = \frac{\partial}{\partial t} \int_{-\infty}^{\infty} \psi e^{-ikx} dx$$

Integrating the LHS twice such that $[\frac{\partial \psi}{\partial x} e^{-ikx}]_{-\infty}^{\infty}$, $[ik\psi e^{-ikx}]_{-\infty}^{\infty}$ to be both zero, we have $\frac{\partial \tilde{\psi}}{\partial t} = -k^2 \tilde{\psi}$.

- (c)
- $\tilde{\psi}(k, t) = \tilde{\psi}(k, 0) e^{-k^2 t}$
- will be the solution. We have

$$\tilde{\psi}(k, t) = \tilde{\psi}(k, 0) e^{-k^2 t} = \mathcal{F}[\psi(x, 0)] e^{-k^2 t} = \sqrt{\frac{\pi}{\lambda}} e^{-k^2/4\lambda} e^{-k^2 t}$$

- (d) Invert the answer from part (c),

$$\psi(x, t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{\psi}(k, t) e^{ikx} dk = \frac{1}{2\pi} \int_{-\infty}^{\infty} \sqrt{\frac{\pi}{\lambda}} e^{-k^2/4\lambda} e^{-k^2 t} e^{ikx} dk$$

We substitute $\beta = t + \frac{1}{4\lambda}$ such that we can complete the square.

$$\psi(x, t) = \frac{1}{2\sqrt{\pi\lambda}} \int_{-\infty}^{\infty} \exp\left(-\beta \left[\left(k - \frac{ix}{2\beta}\right)^2 + \frac{x^2}{4\beta^2}\right]\right) dk = \frac{1}{2\sqrt{\pi\lambda}} e^{-x^2/4\beta} \sqrt{\frac{\pi}{\beta}} = \frac{1}{2\sqrt{\lambda t + 0.25}} e^{-x^2/(4t + \lambda^{-1})}$$

Problem 3.5 (Linear Algebra):

- (i) Show that an $n \times n$ matrix A is diagonalisable if it has n linearly independent eigenvectors. Show that if A is diagonalisable, then so is $B = P^{-1}AP$, where P is an $n \times n$ matrix and P^{-1} is its inverse. [6]

- (ii) Let λ_i (with $i = 1, 2, \dots, n$) be the eigenvalues of an $n \times n$ Hermitian matrix A .

- (a) Show that [6]

$$\text{Tr}(A^k) = \sum_{i=1}^n \lambda_i^k \text{ and } \det(A^k) = \prod_{i=1}^n \lambda_i^k$$

for all positive integers k .

- (b) Show that [4]

$$\det(\exp(A)) = \exp(\text{Tr}(A))$$

- (c) If $A^2 = A$, prove that either (i) $\det(A) = 1$ and $\text{Tr}(A) = n$ or (ii) $\det(A) = 0$ and $\text{Tr}(A) = m < n$, where m is an integer. [4]

Answer 3.5.

- (i) Let the normalized eigenvectors of A be $\{\mathbf{e}_i\}$, then $R = (\mathbf{e}_1, \mathbf{e}_2, \dots)$ such that $R^{-1} = (\mathbf{b}_1^T, \mathbf{b}_2^T, \dots)^T$ where $\mathbf{b}_i \cdot \mathbf{e}_j = \delta_{ij}$, then

$$R^{-1}AR = (\mathbf{b}_1^T, \mathbf{b}_2^T, \dots)^T (\lambda_1 \mathbf{e}_1, \lambda_2 \mathbf{e}_2, \dots)^T = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$$

Indeed, R diagonalizes A . Now if A is diagonalizable, then to diagonalize $B = P^{-1}AP$, we require the matrix $Q = P^{-1}R$:

$$Q^{-1}BQ = (P^{-1}R)^{-1}(P^{-1}AP)(P^{-1}R) = R^{-1}PP^{-1}APP^{-1}R = R^{-1}AR = \text{diag}(\lambda_1, \dots, \lambda_n)$$

so Q diagonalizes B .

- (ii) (a) To show $\text{Tr}(A^k) = \sum_{i=1}^n \lambda_i^k$, we require $\text{Tr}(A^k) = \text{Tr}((\text{diag}(\lambda_1, \dots, \lambda_n))^k)$. From part (i), in order to diagonalize A , it must have n linearly independent eigenvectors. This is true since the eigenvectors of a Hermitian matrix are orthogonal, i.e. consider $A\mathbf{e}_i = \lambda_i \mathbf{e}_i$, then

$$\lambda_i \mathbf{e}_j^\dagger \mathbf{e}_i = \mathbf{e}_j^\dagger A \mathbf{e}_i = (A^\dagger \mathbf{e}_j)^\dagger \mathbf{e}_i = (A \mathbf{e}_j)^\dagger \mathbf{e}_i = (\lambda_j \mathbf{e}_j)^\dagger \mathbf{e}_i = \lambda_j^* \mathbf{e}_j^\dagger \mathbf{e}_i$$

For $\lambda_j^* \neq \lambda_i$, then $\mathbf{e}_j^\dagger \mathbf{e}_i = 0$ and hence eigenvectors of different eigenvalues are pairwise orthogonal.

We can thus find a unitary matrix R that diagonalizes A , i.e. $\Lambda := \text{diag}(\lambda_1, \dots, \lambda_n) = R^\dagger A R$. Then,

$$\text{Tr}(A^k) = \text{Tr}((R\Lambda R^\dagger)^k) = \text{Tr}(R\Lambda^k R^\dagger) = \text{Tr}(\Lambda^k R R^\dagger) = \text{Tr}(\Lambda^k) = \sum_{i=1}^n \lambda_i^k$$

$$\det(A^k) = \det((R\Lambda R^\dagger)^k) = \det(R\Lambda^k R^\dagger) = \det(\Lambda^k) \det(R R^\dagger) = \det(\text{diag}(\lambda_1^k, \dots, \lambda_n^k)) = \prod_{i=1}^n \lambda_i^k$$

- (b) By definition of exponential of a matrix, we have $\exp^B = \sum_{n=0}^{\infty} \frac{1}{n!} B^n$. Then, $\det(\exp(A))$ is

$$\det\left(\sum_{n=0}^{\infty} \frac{1}{n!} (R^\dagger \Lambda R)^n\right) = \det\left(R^\dagger \sum_{n=0}^{\infty} \frac{1}{n!} \Lambda^n R\right) = \det\left(\sum_{n=0}^{\infty} \frac{1}{n!} \Lambda^n\right) = \prod_{i=1}^n e^{\lambda_i} = e^{\sum_{i=1}^n \lambda_i} = e^{\text{Tr}(A)}$$

- (c) If $A^2 = A$, each eigenvalue must be a square of itself, and hence can only be zero or 1. Also, $A^2 = A \implies \det(A) = \det(A^2) = \det(A) \det(A) \implies \det(A)(\det(A) - 1) = 0$. If $\det(A) = 1$, then $\text{Tr}(A) = n$. Similarly, if $\det(A) = 0$, then $\text{Tr}(A) < n$.

Problem 3.6 (Linear Algebra):

- (i) Let
- A
- be a complex
- $n \times n$
- matrix, and define

$$H = \frac{1}{2}(A + A^\dagger) \text{ and } S = \frac{1}{2i}(A - A^\dagger)$$

Let λ be an eigenvalue of A , and x be the corresponding unit-normalized eigenvector.

- (a) Show that $\lambda = x^\dagger Hx + ix^\dagger Sx$. [4]
 (b) Show that the real part of λ is given by $\text{Re}(\lambda) = x^\dagger Hx$ and the imaginary part is given by $\text{Im}(\lambda) = x^\dagger Sx$. [4]

- (ii) Let
- B
- be a Hermitian
- $n \times n$
- matrix with
- n
- distinct (real) eigenvalues
- λ_i
- .

- (a) Show that the corresponding normalised eigenvectors
- x_i
- satisfy

$$x_i^\dagger x_j = \delta_{ij}$$

and therefore form an orthonormal basis, $\{x_i : i = 1, 2, \dots, n\}$. [6]

- (b) Now, consider

$$\beta = (Bv - av)^\dagger (Bv - bv)$$

where v is an arbitrary vector, while a and b are real constants with $a < b$. By expanding v in terms of the eigenvectors x_i , show that $\beta > 0$ if no eigenvalue lies in the interval $[a, b]$. [6]

Answer 3.6.

- (i) (a) We have
- $Ax = \lambda x$
- and
- $x^\dagger x = 1$
- , so

$$x^\dagger Hx + ix^\dagger Sx = \frac{1}{2}[x^\dagger Ax + x^\dagger A^\dagger x] + \frac{1}{2}[x^\dagger Ax - x^\dagger A^\dagger x] = x^\dagger Ax = \lambda$$

- (b) Take the conjugate transpose,

$$\lambda^* = (x^\dagger Hx + ix^\dagger Sx)^\dagger = x^\dagger Hx - ix^\dagger Sx$$

Add and subtract gives

$$2x^\dagger Hx = \lambda + \lambda^* = 2\text{Re}[\lambda], \quad 2ix^\dagger Sx = \lambda - \lambda^* = 2i\text{Im}[\lambda] \implies \text{Re}[\lambda] = x^\dagger Hx, \quad \text{Im}[\lambda] = x^\dagger Sx$$

- (ii) (a) Consider

$$\lambda_j x_i^\dagger x_j = x_i^\dagger Bx_j = (Bx_i)^\dagger x_j = \lambda_i^* x_i^\dagger x_j$$

where B is Hermitian. If $i \neq j$, then we are given $\lambda_i \neq \lambda_j = \lambda_j^*$, and hence $x_i^\dagger x_j = 0$.

Further, given $x_i^\dagger x_i = 1 \forall i$, then $x_i^\dagger x_j = \delta_{ij}$.

- (b) Write
- $v = \sum_i \alpha_i x_i$
- , then

$$\begin{aligned} \beta &= (Bv - av)^\dagger (Bv - bv) = \sum_i (\lambda_i - a)^\dagger (\alpha_i x_i)^\dagger \sum_j (\lambda_j - b) \alpha_j x_j \\ &= \sum_i \sum_j \alpha_i^* \alpha_j (\lambda_i - a)(\lambda_j - b) \delta_{ij} \\ &= \sum_i |\alpha_i|^2 (\lambda_i - a)(\lambda_i - b) \end{aligned}$$

If $\lambda_i \in [a, b]$, then $(\lambda_i - a) > 0$ and $(\lambda_i - b) < 0$ and so $\beta < 0$. For $\beta > 0$ to be true, $\lambda_i \notin [a, b]$.

Problem 3.7 (Cauchy-Riemann):

- (i) Two-dimensional fluid flow can be described by a complex potential

$$f(z) = u(x, y) + iv(x, y)$$

where $z = x + iy$. Let the fluid velocity be $\mathbf{V} = \nabla u$. If $f(z)$ is analytic, show that

$$(a) \quad \nabla \cdot \mathbf{V} = 0, \quad [4]$$

$$(b) \quad \frac{df}{dz} = V_x - iV_y. \quad [4]$$

[You may assume the Cauchy-Riemann equations without proof.]

- (ii) Consider the Gamma function

$$\Gamma(z) = \int_0^\infty t^{z-1} e^{-t} dt, \text{ for } \operatorname{Re}(z) > 0$$

- (a) Using integration by parts, derive the recursion relation

$$\Gamma(z+1) = z\Gamma(z) \quad (*)$$

Also show that $\Gamma(1) = 1$. [4]

- (b) Assuming that $(*)$ holds $\forall z \in \mathbb{C}$, show that $\Gamma(z)$ has simple poles at all non-positive integers. Compute their residues. [8]

Answer 3.7.

- (i) (a) If $f(z)$ is analytic, then $f(z)$ satisfies the Cauchy-Riemann equations $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ and $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$. Let $\mathbf{V} = \nabla u$, then

$$\nabla \cdot \mathbf{V} = \frac{\partial}{\partial x} \frac{\partial u}{\partial x} + \frac{\partial}{\partial y} \frac{\partial u}{\partial y} = \frac{\partial}{\partial x} \frac{\partial v}{\partial y} - \frac{\partial}{\partial y} \frac{\partial v}{\partial x} = 0$$

- (b) We define $\frac{df}{dz} := \lim_{\Delta z \rightarrow 0} \frac{f(z+\Delta z) - f(z)}{\Delta z}$. Since f is analytic, we can take Δz to be any two linearly independent directions, say $\Delta z = \Delta x$ and $\Delta z = i\Delta y$. We will just evaluate the case for $\Delta z = \Delta x$, then after using the Cauchy-Riemann equations,

$$\frac{df}{dz} = \frac{\partial u}{\partial x} + i \frac{\partial v}{\partial x} = \frac{\partial u}{\partial x} - i \frac{\partial u}{\partial y} = V_x - iV_y$$

- (ii) (a) Evaluate
- $\Gamma(z+1)$
- ,

$$\Gamma(z+1) = \int_0^\infty t^z e^{-t} dt = [-t^z e^{-t}]_0^\infty + z \int_0^\infty t^{z-1} e^{-t} dt = z\Gamma(z)$$

We have $\Gamma(1) = \int_0^\infty e^{-t} dt = [-e^{-t}]_0^\infty = 1$.

- (b) Rewrite $\Gamma(z+1) = z\Gamma(z)$ as $\Gamma(z) = \frac{\Gamma(1+z)}{z}$, then consider the case where $z = 0$: $\lim_{z \rightarrow 0} (z-0)\Gamma(z) = 1$, then we have a first order pole at $z = 0$. Then the residue is

$$\lim_{z \rightarrow 0} (z-0)\Gamma(z) = \lim_{z \rightarrow 0} \Gamma(z+1) = \Gamma(1) = 1$$

Next, we consider the case $z = -p$, where $p \in \mathbb{Z}^+$, then $\lim_{z \rightarrow -p} (z - (-p))\Gamma(z)$ is

$$\lim_{z \rightarrow -p} \frac{z+p}{\prod_{i=1}^p (z+i)} \Gamma(z+p+1) = \lim_{z \rightarrow -p} \frac{\Gamma(z+p+1)}{\prod_{i=0}^{p-1} (z+i)} = \frac{\Gamma(1)}{-p(-p+1)\dots(-2)(-1)} = \frac{(-1)^p}{p!}$$

Hence, this is a first-order pole and the value is the residue.

Problem 3.8 (Series Solution to ODE): Legendre's equation

$$(1 - x^2)y'' - 2xy' + l(l + 1)y = 0$$

admits series solutions of the form $y = \sum_{n=0}^{\infty} a_n x^n$.

- (a) Derive the recurrence relation for a_n . [4]
- (b) Show that for integer l , one of the solutions, P_l , is a polynomial of order l ; while the other solution is an infinite series Q_l . [2]
- (c) Find the first four polynomials $P_l(x)$, i.e. $l = 0, 1, 2, 3$, given the normalization $P_l(1) = 1$. [4]
- (d) Show that the Wronskian of P_l and Q_l is given by

$$P_l Q'_l - P'_l Q_l = \frac{A_l}{1 - x^2}$$

for A_l independent of x . [6]

- (e) Derive $Q_0(x)$ in closed form, assuming $Q_0(0) = 0$. [4]

Answer 3.8.

- (a) Admitting the given series solution, we obtain the recurrence relation

$$\sum_{n=0}^{\infty} a_n n(n-1)x^{n-2} + \sum_{n=0}^{\infty} (l(l+1) - n(n-1) - 2n)a_n x^n = 0 \implies a_{n+2} = \frac{n(n+1) - l(l+1)}{(n+2)(n+1)} a_n$$

- (b) Since the recurrence is a double jump, we have two independent sets of coefficients anchored on a_0 (even) and a_1 (odd), hence two linearly independent series for each possible solution.

For the series to terminate, $n(n+1) - l(l+1) = 0 \implies n = -\frac{1}{2} \pm \frac{\sqrt{4l^2 + 4l + 1}}{2} = -l - 1, l$.

For $n = l$, we have $P_l = \sum_{n=0}^{\infty} a_n x^n$ with $a_i = 0 \forall i > l$, i.e. polynomial of degree l .

For $n = -l - 1$, we have $a_{-l+1} = 0$ but $a_{-l+2} = a_l \frac{-l(-l+1) - l(l+1)}{(-l+2)(-l+1)} = -\frac{2l}{(l-2)(l-1)} a_l$. So $a_i = 0$ for $i \leq -l + 1$. This series is an infinite series, $Q_l = \sum_{n=-l-1}^{\infty} a_n x^n$.

- (c) For P_0 and P_2 , the terms are multiples of a_0 . For P_1 and P_3 , the terms are multiples of a_1 . Imposing the normalization condition:

- $P_0(x) = a_0 \implies P_0(1) = 1 \implies P_0(x) = 1$;
- $P_1(x) = a_1 x \implies P_1(1) = 1 \implies P_1(x) = x$;
- $P_2(x) = a_0 + a_2 x^2$ but we have $a_2 = -\frac{2}{2}(2+1)a_0 = -3a_0$, and so $P_2(1) = 1 \implies a_0 = -\frac{1}{2} \implies P_2(x) = \frac{1}{2}(3x^2 - 1)$;
- $P_3(x) = a_1 x + a_3 x^3$ with $a_3 = -a_1 \frac{3(3+1) - 1(1+1)}{(1+1)(1+2)} = -\frac{10}{6}a_1 = -\frac{5}{3}a_1 \implies P_3(x) = a_1 x - \frac{5}{3}a_1 x^3$. Hence, $P_3(1) = 1 \implies a_1 = -\frac{3}{2} \implies P_3(x) = -\frac{3}{2}x + \frac{5}{2}x^3$.

- (d) The Wronskian is defined as $W_l(x) := P_l(x)Q'_l(x) - P'_l(x)Q_l(x)$, then its derivative is

$$\begin{aligned} \frac{dW_l}{dx} &= P_l Q''_l + P'_l Q'_l - P'_l Q'_l - P''_l Q_l = P_l Q''_l - P''_l Q_l \\ &= P_l [-l(l+1)Q_l + 2xQ'_l] \frac{1}{1-x^2} - Q_l [-l(l+1)P_l + 2xP'_l] \frac{1}{1-x^2} \end{aligned}$$

where we recall P_l and Q_l being solution to the Legendre's equation. Integrating $\frac{dW_l}{dx} = \frac{2x}{1-x^2} W_l$, we have $W_l = \frac{A_l}{1-x^2}$ for A_l being independent of x , as desired.

- (e) Dividing the Wronskian by P_l^2 , observe that $\frac{W_l}{P_l^2} = \frac{d}{dx} \frac{Q_l}{P_l}$, then

$$Q_0(x) = P_0(x) \int^x \frac{A_0}{1-t^2} \frac{1}{P_0(t)^2} dt = \frac{A_0}{2} \ln \left| \frac{1+x}{1-x} \right| + C$$

but $Q_0(0) = 0 \implies C = 0$. Hence, $Q_0(x) = \frac{A_0}{2} \ln \left| \frac{1+x}{1-x} \right|$.

Problem 3.9 (Variational Principle):

- (i) (a) State the Euler-Lagrange equation corresponding to stationary values of the functional

$$I[y(x)] = \int_a^b f(x, y(x), y'(x)) dx$$

for fixed $y(a)$ and $y(b)$.**[2]**

- (b) Derive the first integral of the Euler-Lagrange equation for the case where
- f
- is independent of
- $y(x)$
- .

[3]

- (ii) Driving on a hot asphalt road, you may see the road in the distance appear to be covered by what looks like water. This mirage effect arises because the refractive index of air depends on temperature and is smaller near the surface of the hot road.

- (a) Let
- x
- be the height above the road and
- y
- be a coordinate along the road. The travel time of light is the following functional of the path taken

$$\int n(x) \sqrt{1 + (y')^2} dx$$

where $n(x)$ is the refractive index. Show that the path of least time satisfies

$$y' = \frac{dy}{dx} = \frac{c}{\sqrt{n(x)^2 - c^2}} \quad (*)$$

where c is a real constant.**[4]**

- (b) Now let
- $n(x) = 1 + \beta x$
- , where
- $\beta > 0$
- is a real constant. By integrating (*), show that

$$x = -\frac{1}{\beta} + \frac{c}{\beta} \cosh(\beta(y - y_0)/c)$$

where the integration constant is defined such that $y_0 = y(x_0)$ at $x_0 = (-1 + c)/\beta$.**[8]**

- (c) For
- $c > 1$
- , sketch the path of the light
- $x(y)$
- .

[3]**Answer 3.9.**

- (i) (a) For the functional
- I
- to be stationary, the integrand
- f
- must satisfy the Euler-Lagrange's equation
- $\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} = 0$
- .

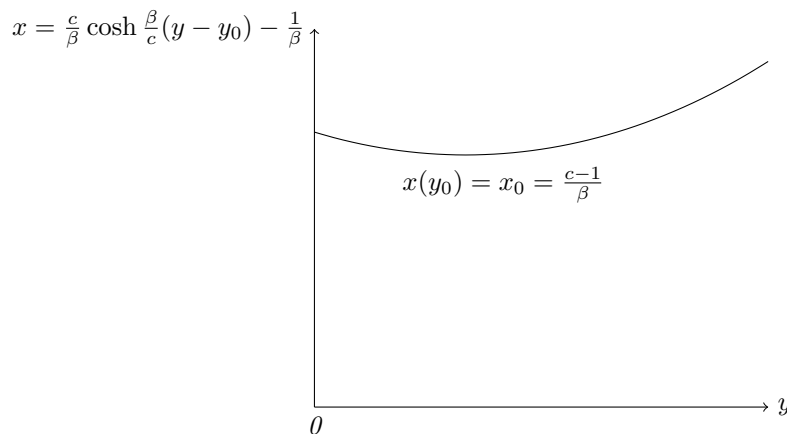
- (b) Suppose
- f
- is independent of
- $y(x)$
- , then
- $\frac{\partial f}{\partial y} = 0$
- . By part (i)(a), we have
- $\frac{d}{dx} \frac{\partial f}{\partial y'} = 0$
- , and so
- $\frac{\partial f}{\partial y'}$
- is a constant.

- (ii) (a) We see that the integrand is independent of
- $y(x)$
- , then by part (i)(b), we have
- $\frac{\partial f}{\partial y'} = \frac{ny'}{\sqrt{1+y'^2}} = c$
- , where
- c
- is some real constant. then,
- $\frac{dy}{dx} = \frac{c}{\sqrt{n^2 - c^2}}$
- .

- (b) Let
- $n = 1 + \beta x$
- and substitute
- $1 + \beta x = c \cosh t$
- .

$$y - y_0 = \int_{x_0}^x \frac{cdx}{\sqrt{(1 + \beta x)^2 - c^2}} = \int_0^t \frac{c}{\sqrt{c^2 \cosh^2 t - c^2}} \frac{c}{\beta} \cosh t dt = \frac{c}{\beta} \cosh^{-1} \frac{1 + \beta x}{c}$$

- (c) Sketch
- $x = \frac{c}{\beta} \cosh \frac{\beta(y - y_0)}{c} - \frac{1}{\beta}$
- .



Problem 3.10 (Rayleigh-Ritz Method):

- (i) Consider the Sturm-Liouville Equation

$$-\frac{d}{dx}\left(p(x)\frac{d\psi}{dx}\right) + q(x)\psi = \lambda w(x)\psi$$

where $p(x) > 0$ and $w(x) > 0$ for $\alpha < x < \beta$.

- (a) Show that finding the eigenvalues
- λ
- is equivalent to finding the stationary values of the functional

$$\Lambda[\psi(x)] = \int_{\alpha}^{\beta} (p\psi'^2 + q\psi^2)dx$$

subject to the constraint

$$\int_{\alpha}^{\beta} w\psi^2 dx = 1$$

You may assume that $\psi(x)$ satisfies suitable boundary conditions at $x = \alpha$ and $x = \beta$ (which should be stated). [6]

- (b) Explain briefly the Rayleigh-Ritz method for estimating the lowest eigenvalue
- λ_0
- .
- [4]

- (ii) The wavefunction
- $\psi(x)$
- for a quantum harmonic oscillator satisfies

$$\left(-\frac{d^2}{dx^2} + x^2\right)\psi = \lambda\psi \quad (*)$$

- (a) Use the trial function

$$\psi(x) = \begin{cases} \sqrt{\frac{15}{16a^5}}(a^2 - x^2) & |x| \leq a \\ 0 & |x| > a \end{cases}$$

to estimate the lowest eigenvalue λ_0 . [8]

- (b) The exact ground state wavefunction is

$$\psi_0(x) = \frac{1}{\sqrt{2\pi}} e^{-0.5x^2}$$

Find the corresponding eigenvalue and compare it to the previous estimate. [2]

Answer 3.10.

(i) (a) Let the functional be

$$\phi[\psi] = \int_{\alpha}^{\beta} (p\psi'^2 + q\psi^2 - w\lambda\psi^2)dx - \lambda$$

Let the integrand be f . To make ϕ stationary, f must satisfy the Euler-Lagrange equation. The first order variation of F is zero if stationary.

$$f[\psi + \epsilon y] = \int_{\alpha}^{\beta} f + \epsilon y \frac{\partial f}{\partial \psi} + \epsilon y' \frac{\partial f}{\partial \psi'} dx \implies \delta F = \epsilon \left[y \frac{\partial f}{\partial \psi} \right]_{\alpha}^{\beta} + \int_{\alpha}^{\beta} \epsilon \left(\frac{\partial f}{\partial \psi} - \frac{d}{dx} \left(\frac{\partial f}{\partial \psi'} \right) \right) dx$$

- We need $y(\alpha) = y(\beta) = 0$, i.e. boundary terms is zero,
- and integrand on the right be zero to recover Euler-Lagrange equations.

The Euler-Lagrange equations will give

$$0 = \frac{\partial f}{\partial \psi} - \frac{d}{dx} \left(\frac{\partial f}{\partial \psi'} \right) = 2q\psi - 2w\lambda\psi - 2(p\psi')' \implies -(p\psi')' + q\psi = w\lambda\psi$$

We thus recover the Sturm-Liouville problem. We see that the functional $\Lambda[\psi]$ is

$$\Lambda[\psi(x)] = \int_{\alpha}^{\beta} (p\psi'^2 + q\psi^2)dx = [p\psi'\psi]_{\alpha}^{\beta} + \int_{\alpha}^{\beta} -(p\psi')' + q\psi\psi dx$$

Since $\psi(\alpha) = \psi(\beta) = 0$, the boundary terms is zero. Then,

$$\Lambda[\psi] = \int_{\alpha}^{\beta} \lambda w \psi^2 dx = \lambda G = \lambda$$

(b) The Rayleigh-Ritz method uses a trial function constructed from a linearly independent set of basis functions such that they all satisfy the boundary conditions, i.e. $y_{\text{trial}} = \sum_i c_i y_i$ such that y_i satisfy the boundary conditions. $\frac{\Lambda}{G}[\psi]$ is minimized with respect to c_i and the minimum value is an overestimate for the lowest true eigenvalue λ_0 .

$$\delta(\Lambda/G) = \frac{\delta\Lambda}{G} - \frac{\delta G}{G^2} F = \frac{1}{G} \left(\delta F - \frac{\Lambda}{G} \delta G \right)$$

From part (i)(a), since the stationary value of Λ is λ , then if $F - \lambda G$ is stationary, Λ is stationary.

(ii) (a) For the quantum harmonic oscillator, we identify $p(x) = 1$, $q(x) = x^2$, $w(x) = 1$ and $\psi'_{\text{trial}} = -2\sqrt{15/16a^5}x$. Then, $\Lambda[\psi_{\text{trial}}(x)]$ is

$$\int_{-a}^a \frac{4 \times 15}{16a^5} x^2 + x^2 \frac{15}{16a^5} (a^2 - x^2)^2 dx = \frac{15}{4a^5} \int_{-a}^a x^2 dx + \frac{15}{16a} \int_{-a}^a x^2 dx - \frac{15}{8a^3} \int_{-a}^a x^4 dx + \frac{15}{16a^5} \int_{-a}^a x^6 dx$$

which is $\frac{1}{56}(140a^{-2} + 8a^2)$. Extremize Λ with respect to a gives $a^4 = 35/2$. Then the lowest eigenvalue λ_0 is

$$\lambda_0 = \Lambda[\psi_{\text{trial}}] = \frac{1}{56}(140\sqrt{2/35} + 8\sqrt{35/2}) \approx 1.195$$

(b) Take ψ_0 :

$$\left(-\frac{d^2}{dx^2} + x^2 \right) \psi_0 = \psi_0$$

and so $\lambda = 1 < \lambda_0$, as expected since the minimum eigenvalue λ obtained from the trial function is always an overestimate for the lowest true eigenvalue λ_0 .

3.2 Paper 2

Problem 3.11 (Sturm-Liouville):

- (i) Define a scalar product between two scalar functions $y_1(x)$ and $y_2(x)$ with weight function $w(x)$. [2]
 (ii) Express the following equation for the function $y(x)$ in Sturm-Liouville form

$$y'' + \left(\frac{1}{x} - 1\right)y' + \frac{n}{x}y = 0$$

where $n > 0$ is an integer. Find the required boundary conditions for the linear operator on $y(x)$ to be self-adjoint over the interval $[0, \infty]$. Show that as long as the eigenfunctions of the operator are polynomials, the boundary conditions are always satisfied. What is the orthogonality condition for this linear operator? [6]

- (iii) Show that

$$u(x) = -x + 1 \quad \text{and} \quad v(x) = \frac{1}{6}(-x^3 + 9x^2 - 18x + 6)$$

are eigenfunctions of the linear operator, and find the corresponding eigenvalues. By assuming that the eigenfunction $h(x)$ associated with $n = 2$ is a polynomial of order 2, find $h(x)$ given $h(1) = 1$. [6]

- (iv) Find two solutions for the case $n = 0$, given the boundary condition $y(x_0) = 1$ for $0 < x_0 < \infty$. You may leave the solutions in integral form. Show that one of the solution diverges at $x = \infty$. [6]

Answer 3.11.

(i) $\int y_1^*(x)w(x)y_2(x)dx$

- (ii) Multiply $\mathcal{L} := \frac{d^2}{dx^2} + (x^{-1} - 1)\frac{d}{dx} + \frac{n}{x}$ by integration factor $\mu(x)$ to cast into Sturm-Liouville form

$$\mathcal{L}' = \mu\mathcal{L} = \frac{d}{dx}\left(p(x)\frac{d}{dx}\right), \quad \frac{1}{p(x)}\frac{dp(x)}{dx} = \frac{1}{x} - 1 \implies p(x) \propto xe^{-x} \implies \mu(x) = p(x)$$

So, $\mathcal{L}'y = -\frac{d}{dx}(xe^{-x}\frac{dy}{dx}) = ne^{-x}y$. For it to be self-adjoint:

$$\begin{aligned} \langle y_n | \mathcal{L}' y_m \rangle &= - \int_0^\infty y_n^* \frac{d}{dx} \left(xe^{-x} \frac{dy_m}{dx} \right) dx \\ &= \left[-y_n^* xe^{-x} \frac{dy_m}{dx} \right]_0^1 - \int_0^\infty \frac{dy_n^*}{dx} xe^{-x} \frac{dy_m}{dx} dx \\ &= \left[y_n^* xe^{-x} \frac{dy_m}{dx} - y_m \frac{dy_n^*}{dx} xe^{-x} \right]_0^\infty + \int_0^\infty y_m \frac{d}{dx} \left(xe^{-x} \frac{dy_n^*}{dx} \right) dx \end{aligned}$$

For $\langle y_n | \mathcal{L}' y_m \rangle = \langle \mathcal{L}' y_n | y_m \rangle$, we require the boundary term to be zero. Surely it must be satisfied if y_1 and y_2 are polynomial. The orthogonality condition is $\int_0^1 y_1^* e^{-x} y_2 dx = 0$ where y_1 and y_2 have distinct eigenvalues.

- (iii) Check $u(x)$ and $v(x)$ respectively:

$$-\frac{d}{dx} \left(xe^{-x} \frac{du}{dx} \right) = \frac{d}{dx} xe^{-x} = (-x + 1)e^{-x}$$

$$-\frac{d}{dx} \left(xe^{-x} \frac{dv}{dx} \right) = \frac{d}{dx} (xe^{-x}(-x^2 + 6x - 6)) \frac{1}{2} = 3e^{-x} \frac{1}{6}(-x^3 + 9x^2 - 18x + 6)$$

u and v have eigenvalue 1 and 3 respectively. Since $h(x)$ is of order 2, it has the form $h(x) = c_1 x^2 + c_2 x + c_3$:

$$-\frac{d}{dx} \left(xe^{-x} \frac{dh(x)}{dx} \right) = -\frac{d}{dx} (xe^{-x}(2c_1 x + c_2)) = 2e^{-x}(c_1 x^2 + \frac{1}{2}(c_2 - 4c_1)x - \frac{1}{2}c_2)$$

Comparing coefficients we have $c_2 - 4c_1 = 2c_2$ and $c_3 = -0.5c_2 = 2c_1$. Hence, $h(x) = c_1(x^2 - 4x - 2)$. For $h(1) = 1$, we must have $c_1 = -1$. Hence, $h(x) = -x^2 + 4x - 2$.

(iv) For $n = 0$,

$$\frac{dy'}{dx} = \left(1 - \frac{1}{x}\right)y' \implies y' \propto \frac{e^x}{x} \implies y = A \int_{x_0}^x \frac{e^t}{t} dt + B$$

But $y(x_0)1 = 1 \implies B = 1$. Hence, $y(x) = A \int_{x_0}^x \frac{e^t}{t} dt + 1$. Only two solutions generated for two different values of $x_0 \in [0, \infty]$. For $A \neq 0$, it diverges for $x \rightarrow \infty$.

Problem 3.12 (Partial Differential Equations): Consider the diffusion equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

with $t \geq 0$ on the interval $x \in [0, 1]$ with boundary conditions

$$\frac{\partial u}{\partial x}(0, t) = -u(0, t), \quad \frac{\partial u}{\partial x}(1, t) = -u(1, t)$$

- (i) Using the method of separation of variables $u(x, t) = W(x)T(t)$, with the separation constant k , show that $k = 0$ yields the trivial solution $u(x, t) = 0$. [4]
- (ii) By separately considering solutions for $k > 0$ and $k < 0$, show that the general solution to the diffusion equation with the given boundary conditions can be written as

$$u(x, t) = c_0 e^{-x} e^t + \sum_{n=1}^{\infty} c_n e^{-n^2 \pi^2 t} W_n(x)$$

where

$$W_n(x) = n\pi \cos(n\pi x) - \sin(n\pi x)$$

and c_0 and c_n are constants of integration. [10]

- (iii) Given the initial condition $u(x, 0) = f(x)$ where $f(x)$ is an arbitrary function, find the coefficients c_0 and c_n as integrals involving $f(x)$. You may assume without proof that the functions W_n are orthogonal to each other and to e^{-x} in the interval $x \in [0, 1]$ [6].

Answer 3.12.

(i) Use separation of variables $u(x, t) = W(x)T(t)$, then

$$\frac{\dot{T}(t)}{T(t)} = \frac{W''(x)}{W(x)} = k$$

for some given separation constant k . The b.c.s have separable form $W'(0) = -W(0)$, $W'(1) = -W(1)$. When $k = 0$, we must have $W(x) = ax + b$. The b.c.s. give $a = -b$ and $a = -a - b$, hence $a = b = 0$. This gives the trivial solution $u(x, t) = 0$.

- (ii) When $k \neq 0$, then $W_k(x) = A_k e^{\sqrt{k}x} + B_k e^{-\sqrt{k}x}$. The b.c.s. give $\sqrt{k}(A_k - B_k) = -(A_k + B_k)$ and $\sqrt{k}(A_k e^{\sqrt{k}} - B_k e^{-\sqrt{k}}) = -(A_k e^{\sqrt{k}} + B_k e^{-\sqrt{k}})$. Both give

$$A_k = B_k \frac{\sqrt{k} - 1}{\sqrt{k} + 1}, \quad B_k = e^{2\sqrt{k}} \frac{\sqrt{k} + 1}{\sqrt{k} - 1} A_k$$

Either $k = 1$ or $e^{2\sqrt{k}} = 1$. Former gives $A_k = 0$, $W(x) = B_k e^{-x}$, $T(t) \propto e^t$ and hence $u \propto e^{-x+t}$. Latter gives $k = -\pi^2 n^2$ where $n \in \mathbb{Z}^+$, and so $T_k(t) \propto e^{-n^2 \pi^2 t}$ and $W_k(x)$ to be

$$A_k \left(e^{in\pi x} + \frac{in\pi + 1}{in\pi - 1} e^{-in\pi x} \right) = \frac{A_k}{in\pi - 1} [(in\pi - 1)e^{in\pi x} + (in\pi + 1)e^{-in\pi x}] := c_n (n\pi \cos(n\pi x) - \sin(n\pi x))$$

The general solution is a superposition of the $k = 1$ solution (e^{-x+t}) and $k = -\pi^2 n^2$ solutions ($e^{-n^2 \pi^2 t} W_n(x)$).

(iii) Using the initial condition, we have

$$u(x, 0) = f(x) = c_0 e^{-x} + \sum_{n=1}^{\infty} c_n (n\pi \cos(n\pi x) - \sin(n\pi x))$$

Using Fourier series and exploit orthogonality,

$$\int_0^1 f(x) e^{-x} dx = c_0 \int_0^1 e^{-2x} dx + \sum_{n=1}^{\infty} 0 = c_0 \frac{1}{2} (1 - e^{-2})$$

$$\int_0^1 f(x) W_n(x) dx = 0 + c_n \int_0^1 (n\pi \cos(n\pi x) - \sin(n\pi x))^2 dx = c_n \frac{n^2 \pi^2 - 1}{2}$$

Then we have $c_0 = \frac{2}{1-e^{-2}} \int_0^1 f(x) e^{-x} dx$ and $c_n = \frac{2}{n^2 \pi^2 - 1} \int_0^1 f(x) W_n(x) dx$.

Problem 3.13 (Green's Functions):

- (i) Let $u(\mathbf{r})$ and $v(\mathbf{r})$ be scalar fields that tend to zero as $|\mathbf{r}| \rightarrow \infty$, with the coordinates $\mathbf{r} = (x, y, z)$. Use the divergence theorem to show that

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (u \mathcal{L}_H v - v \mathcal{L}_H u) dx dy dz = 0$$

where $\mathcal{L}_H = \nabla^2 + k_0^2$ is the Helmholtz operator and $k_0 > 0$ is a real constant. [4]

- (ii) The eigenfunctions for the following equation

$$\nabla^2 \psi_{\mathbf{k}}(\mathbf{r}) = -k^2 \psi_{\mathbf{k}}(\mathbf{r})$$

are given by

$$\psi_{\mathbf{k}}(\mathbf{r}) = \frac{1}{(2\pi)^{3/2}} e^{i\mathbf{k} \cdot \mathbf{r}} \quad (*)$$

with eigenvalues $-k^2$ where $k = |\mathbf{k}|$. Show that these eigenfunctions satisfy the orthogonality condition [2]

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \psi_{\mathbf{k}_1}^*(\mathbf{r}) \psi_{\mathbf{k}_2}(\mathbf{r}) dx dy dz = \delta^3(\mathbf{k}_1 - \mathbf{k}_2)$$

- (iii) Consider the Helmholtz equation with a source

$$(\nabla^2 + k_0^2) \Phi(\mathbf{r}) = V(\mathbf{r})$$

By expanding the solution $\Phi(\mathbf{r})$ using the eigenfunctions (*),

$$\Phi(\mathbf{r}) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} A_{\mathbf{k}} \psi_{\mathbf{k}}(\mathbf{r}) dk_x dk_y dk_z$$

where $A_{\mathbf{k}}$ are complex coefficients and (k_x, k_y, k_z) are components of \mathbf{k} , show that [8]

$$\Phi(\mathbf{r}) = \frac{1}{(2\pi)^3} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{e^{i\mathbf{k} \cdot (\mathbf{r} - \mathbf{r}')}}{k_0^2 - k^2} V(\mathbf{r}') dk_x dk_y dk_z dx' dy' dz'$$

- (iv) Hence show that the Green's Function for the Helmholtz operator \mathcal{L}_H is

$$G(\mathbf{r}, \mathbf{r}') = \frac{1}{2\pi^2 l} \int_0^{\infty} \frac{\sin(kl)}{k^2 - k_0^2} k dk$$

where $l = |\mathbf{r} - \mathbf{r}'|$. [6]

Answer 3.13.

(i) Invoke Divergence Theorem to $u\nabla v$ and $v\nabla u$ separately:

$$\int_{\partial V} u \nabla v \cdot d\mathbf{S} = \int_V \nabla \cdot (u \nabla v) dV = \int_V u \nabla^2 v + \nabla u \cdot \nabla v dV$$

$$\int_{\partial V} v \nabla u \cdot d\mathbf{S} = \int_V \nabla \cdot (v \nabla u) dV = \int_V v \nabla^2 u + \nabla v \cdot \nabla u dV$$

Take the difference and add $k_0^2 vu - vk_0^2 u$:

$$\int_V u(\nabla^2 v + k_0^2)v - v(\nabla^2 u + k_0^2)u dV = \int_{\partial V} (u \nabla v - v \nabla u) \cdot d\mathbf{S}$$

The RHS is zero from the boundary conditions $u(\mathbf{r}), v(\mathbf{r}) \rightarrow 0$ as $|\mathbf{r}| \rightarrow \infty$. The integrand in the LHS is basically $u\mathcal{L}_H v - v\mathcal{L}_H u$.

(ii) We see that

$$\begin{aligned} \int_V \psi_{\mathbf{k}_1}^*(\mathbf{r}) \psi_{\mathbf{k}_2}(\mathbf{r}) dV &= \frac{1}{(2\pi)^3} \int_{-\infty}^{\infty} e^{ix(k_{2x}-k_{1x})} dx \int_{-\infty}^{\infty} e^{iy(k_{2y}-k_{1y})} dy \int_{-\infty}^{\infty} e^{iz(k_{2z}-k_{1z})} dz \\ &= \frac{(2\pi)^3}{(2\pi)^3} \delta^{(3)}(\mathbf{k}_1 - \mathbf{k}_2) \end{aligned}$$

where $\int e^{ikx(k_{2x}-k_{1x})} dx = 2\pi \delta(k_{2x} - k_{1x})$.

(iii) Exploit orthogonality

$$\begin{aligned} \int_V \psi_{\mathbf{k}}^*(\mathbf{r}) V(\mathbf{r}) dV &= \int_V \psi_{\mathbf{k}}^*(\mathbf{r}) \mathcal{L}_H \Phi(\mathbf{r}) dV \\ &= \int_V \Phi(\mathbf{r}) \mathcal{L}_H \psi_{\mathbf{k}}^*(\mathbf{r}) dV \\ &= \int_V \Phi(\mathbf{r}) (k_0^2 - k^2) \psi_{\mathbf{k}}^*(\mathbf{r}) dV \\ &= (k_0^2 - k^2) A_{\mathbf{k}} \end{aligned}$$

Plugging it back into the eigenfunction expansion,

$$\begin{aligned} \Phi(\mathbf{r}) &= \int_{\mathbf{k} \in \mathbb{R}^3} \psi_{\mathbf{k}}(\mathbf{r}) \int_{\mathbf{r}' \in \mathbb{R}^3} \frac{V(\mathbf{r}') \psi_{\mathbf{k}}^*(\mathbf{r}')}{k_0^2 - k^2} d^3 \mathbf{r}' d^3 \mathbf{k} \\ &= \frac{1}{(2\pi)^3} \int_{\mathbf{k} \in \mathbb{R}^3} \int_{\mathbf{r}' \in \mathbb{R}^3} \frac{V(\mathbf{r}') e^{i\mathbf{k} \cdot (\mathbf{r} - \mathbf{r}')}}{k_0^2 - k^2} d^3 \mathbf{r}' d^3 \mathbf{k} \end{aligned}$$

(iv) Switch the order of integration and integrate over the \mathbf{k} -sphere for $\Phi(\mathbf{r})$

$$\begin{aligned} \Phi(\mathbf{r}) &= \int_{\mathbf{r}' \in \mathbb{R}^3} V(\mathbf{r}') \left[\int_0^\infty \int_0^{2\pi} \int_0^\pi \frac{1}{(2\pi)^3} \frac{e^{ik \cos \theta |\mathbf{r} - \mathbf{r}'|}}{k_0^2 - k^2} k^2 \sin \theta d\theta d\phi dk \right] d^3 \mathbf{r}' \\ &= \int_{\mathbf{r}' \in \mathbb{R}^3} V(\mathbf{r}') \int_0^\infty \frac{1}{(2\pi)^2 |\mathbf{r} - \mathbf{r}'|} \frac{k \sin(k|\mathbf{r} - \mathbf{r}'|)}{k^2 - k_0^2} dk d^3 \mathbf{r}' \end{aligned}$$

We identify the Green's function by letting $\Phi(\mathbf{r}) = \int_{\mathbf{r}' \in \mathbb{R}^3} V(\mathbf{r}') G(\mathbf{r}, \mathbf{r}') d^3 \mathbf{r}'$.

Problem 3.14 (Contour Integration):

- (i) (a) State the Cauchy integral formula for a function $f(z)$ which is analytic on a closed contour C and within the interior region bounded by C . [2]
 (b) Use the Cauchy integral formula to calculate

$$\oint_C \frac{dz}{z^2 - 1}$$

where C is the circle $|z| = 2$.

[4]

- (ii) (a) The Laurent expansion of a complex function $f(z)$ about a point z_0 is given by

$$f(z) = \sum_{n=-\infty}^{\infty} a_n (z - z_0)^n$$

Write the expression for the coefficients a_n as a contour integral, with the contour C within the annular region $r < |z - z_0| < R$ encircling z_0 once in a counterclockwise sense, assuming that such an annular region of convergence of $f(z)$ exists. [2]

- (b) For the complex function

$$f(z) = \frac{1}{z(z-1)}$$

show that the Laurent expansion about $z_0 = 0$ is given by

[12]

$$f(z) = - \sum_{n=-1}^{\infty} z^n$$

Answer 3.14.

- (i) (a) Suppose $f(z)$ is analytic in a simply-connected domain D and $z \in D$, then for any simple closed contour C in D encircling z anti-clockwise, then Cauchy integral formula:

$$f(z) = \frac{1}{2\pi i} \oint_C \frac{f(w)}{w - z} dw$$

- (b) We identify C as $\{z : |z| = 2\}$, and the enclosed z values are ± 1 .

$$\oint_C \frac{dz}{z^2 - 1} = \frac{1}{2} \oint_C \left[\frac{1}{z-1} - \frac{1}{z+1} \right] dz$$

where we used part (a)(i), $\oint_C \frac{\pm 1/2}{z \mp 1} dz = \pm 2\pi i 0.5 = \pm \pi i$. Hence, $\oint_C \frac{dz}{z^2 - 1} = \pi i - \pi i = 0$.

- (ii) (a) We have $C = \{z : r < |z - z_0| < R\}$ and perform contour integral,

$$\oint_C f(z)(z-z_0)^p dz = \sum_{n=-\infty}^{\infty} a_n \oint_C (z-z_0)^{n+p} dz = 2\pi i a_{-(p+1)} \implies a_p = \frac{1}{2\pi i} \oint_C f(z)(z-z_0)^{-p-1} dz$$

- (b) $f(z)$ has poles at $z = 0, 1$. Choose $C = \{z : |z| = \varepsilon, 0 < \varepsilon < 1\}$. From part (ii)(a),

$$a_n = \frac{1}{2\pi i} \oint_C \frac{z^{-1-n}}{z(z-1)} dz = \frac{1}{2\pi i} \oint_C \frac{1}{z^{n+2}(z-1)} dz$$

If $n+2 \leq 0$, the function is analytic at the origin, so $a_n = 0 \forall n < -1$. Integrate by parts,

$$\begin{aligned} a_n &= 0 - \frac{1}{2\pi i} \oint_C \frac{-1}{n+1} \frac{1}{z^{n+1}} \frac{-1}{(z-1)^2} dz = \dots \\ &= \frac{1}{2\pi i} \oint_C \frac{(-1)^{n+1}}{(n+1)!} \frac{1}{z} \frac{(n+1)!}{(z-1)^{n+2}} dz \end{aligned}$$

Use part(a)(i) with $f(z) = \frac{1}{(z-1)^{n+2}}$, then $a_n = (-1)^{n+1} \frac{1}{(0-1)^{n+2}} = -1$. Then the Laurent series is

$$f(z) = \sum_{n=-\infty}^{\infty} a_n (z - z_0)^n = \sum_{n=-1}^{\infty} (-1)(z-0)^n$$

Problem 3.15 (Transform Methods): The Fourier transform $\tilde{f}(k)$ of a function $f(x)$ is defined by

$$\tilde{f}(k) = \int_{-\infty}^{\infty} e^{-ikx} f(x) dx$$

(i) Prove the convolution theorem; namely that if [6]

$$\tilde{h}(k) = \tilde{f}(k)\tilde{g}(k)$$

then

$$h(x) = \int_{-\infty}^{\infty} f(y)g(x-y)dy$$

(ii) Suppose that $f(x) = e^{-|x|}$. Show that the convolution of $f(x)$ with itself is given by [10]

$$h(x) = \begin{cases} (1-x)e^x & x < 0 \\ (1+x)e^{-x} & x > 0 \end{cases}$$

(iii) Hence, use the convolution theorem to show that [4]

$$h(x) = \frac{2}{\pi} \int_{-\infty}^{\infty} \frac{e^{ikx}}{(1+k^2)^2} dk$$

Answer 3.15.

(i) *Prove convolution theorem:*

$$\begin{aligned} h(x) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{f}(k)\tilde{g}(k)e^{ikx} dk \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\varepsilon)e^{-ik\varepsilon} d\varepsilon \int_{-\infty}^{\infty} g(\xi)e^{-ik\xi} d\xi e^{ikx} dk \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\varepsilon)g(\xi) \int_{-\infty}^{\infty} \frac{e^{ik(x-(\varepsilon+\xi))}}{2\pi} dk d\xi d\varepsilon \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\varepsilon)g(\xi)\delta(x-\varepsilon-\xi) d\xi d\varepsilon \\ &= \int_{-\infty}^{\infty} f(\varepsilon)g(x-\varepsilon) d\varepsilon \\ &= f * g \end{aligned}$$

(ii) *The autoconvolution of f gives*

$$\begin{aligned} h(x) &= \int_{-\infty}^{\infty} e^{-|y|} e^{-|x-y|} dy \\ &= \begin{cases} \int_{-\infty}^x e^y e^{y-x} dy + \int_x^0 e^y e^{x-y} dy + \int_0^{\infty} e^{-y} e^{-y+x} dy & x < 0 \\ \int_{-\infty}^0 e^y e^{y-x} dy + \int_0^x e^{-y} e^{y-x} dy + \int_x^{\infty} e^{-y} e^{-y+x} dy & x > 0 \end{cases} \\ &= \begin{cases} e^x(1-x) & x < 0 \\ e^{-x}(1+x) & x > 0 \end{cases} \end{aligned}$$

(iii) *The Fourier transform of f is*

$$\begin{aligned} \tilde{f}(k) &= \int_{-\infty}^{\infty} e^{-|x|} e^{-ikx} dx \\ &= \int_{-\infty}^0 e^{x(1-ik)} dx + \int_0^{\infty} e^{x(-1-ik)} dx \\ &= \frac{1}{1-ik} + \frac{1}{1+ik} \\ &= \frac{2}{1+k^2} \end{aligned}$$

but by part (i),

$$h(x) = \mathcal{F}^{-1} \left[\frac{4}{(1+k^2)^2} \right] = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{4}{(1+k^2)^2} e^{ikx} dk$$

Problem 3.16 (Tensors):

- (i) Define the terms tensor and isotropic tensor.

Show that the Kronecker delta δ_{ij} is an isotropic tensor. [2]

Let A and B be a pair of rank two tensors. The determinant of a rank two tensor whose components are A_{ij} is given by

$$\det A = \frac{1}{6} \epsilon_{ijk} \epsilon_{lmn} A_{il} A_{jm} A_{kn}$$

- (ii) Show that
- [10]

$$\det(AB) = \det A \det B$$

- (iii) Suppose that
- A
- depends on a parameter
- t
- and is invertible. Show that
- [8]

$$\frac{d}{dt} \det(A) = \left(\text{Tr} \left[A^{-1} \frac{dA}{dt} \right] \right) \det A$$

Answer 3.16.

- (i) A tensor T is an object that is the same in all frames related by an orthogonal transformation. The tensor's components $T_{ijk\dots}$ with respect to two such frames related by such an orthogonal transformation (given by matrix L) must change as

$$T'_{ijk\dots} = (\det L)^p L_{i\alpha} L_{j\beta} L_{k\gamma} \dots T_{\alpha\beta\gamma\dots}$$

where $p = 1$ for pseudotensors and $p = 0$ otherwise.

An isotropic tensor has its components to be the same in all frames, i.e. $T'_{ijk\dots} = T_{\alpha\beta\gamma\dots}$.

Kronecker delta transforms like

$$\delta'_{pq} = L_{ip} L_{jq} \delta_{ij} = L_{ip} L_{iq} = \delta_{pq}$$

where L is orthogonal, $LL^T = I$, hence isotropic.

- (ii) Evaluate
- $\epsilon_{ijk}\epsilon_{ijk}$
- :

$$\epsilon_{ijk}\epsilon_{ijk} = \delta_{jj}\delta_{kk} - \delta_{jk}\delta_{kj} = 3 \times 3 - \delta_{jj} = 9 - 3 = 6$$

so with the given formula:

$$\begin{aligned} \det(AB) &= \frac{1}{6} \epsilon_{\alpha\beta\gamma} \epsilon_{ijk} (AB)_{i\alpha} (AB)_{j\beta} (AB)_{k\gamma} \\ &= \frac{1}{6} \epsilon_{\alpha\beta\gamma} \epsilon_{ijk} A_{il} B_{l\alpha} A_{jm} B_{m\beta} A_{kn} B_{n\gamma} \\ &= \frac{1}{6} \epsilon_{ijk} A_{il} A_{jm} A_{kn} \epsilon_{\alpha\beta\gamma} B_{l\alpha} B_{m\beta} B_{n\gamma} \\ &= \frac{1}{6} \epsilon_{lmn} \det A \epsilon_{lmn} \det(B^T) \\ &= \frac{6}{6} \det(A) \det(B) \end{aligned}$$

where we used $\epsilon_{lmn} \det A = \epsilon_{ijk} A_{il} A_{jm} A_{kn}$, which is the generalized expansion for determinant. For $(\alpha, \beta, \gamma) = (1, 2, 3)$, we recover the Laplace expansion for determinant: $\det A = \epsilon_{ijk} A_{i1} A_{j2} A_{k3}$. If any pair of the three indices are identical, both sides vanish. If we swap any pair of the three indices, then both sides change sign.

(iii) Starting from first principles, we have

$$\begin{aligned}
 \frac{d}{dt} \det[A(t)] &= \lim_{\Delta t \rightarrow 0} \frac{1}{\Delta t} \left\{ \det[A(t + \Delta t) - A(t)] - \det[A(t)] \right\} \\
 &= \lim_{\Delta t \rightarrow 0} \frac{1}{\Delta t} (\det[A(t) + \Delta t A'(t) + O(\Delta t^2)] - \det[A(t)]) \\
 &= \det[A(t)] \lim_{\Delta t \rightarrow 0} \frac{1}{\Delta t} (\det[I + \Delta t A^{-1}(t) A'(t)] - 1)
 \end{aligned}$$

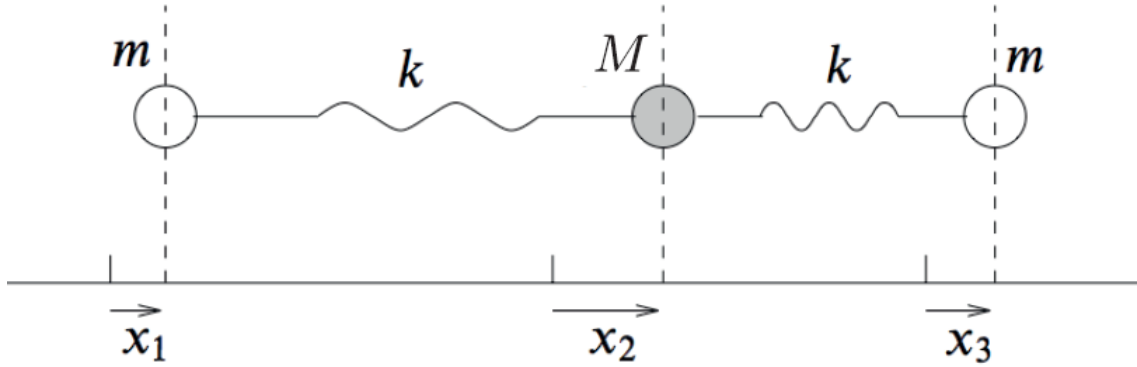
Set $B(t) := A^{-1}(t)A'(t)$, then using the given formula again and expand up to the first order of Δt ,

$$\begin{aligned}
 \det(I + \Delta t B) &= \frac{1}{6} \epsilon_{ijk} \epsilon_{ilm} (\delta_{il} + B_{il} \Delta t) (\delta_{jm} + B_{jm} \Delta t) (\delta_{kn} + B_{kn} \Delta t) \\
 &= \frac{1}{6} \epsilon_{ijk} \epsilon_{lmn} (\delta_{il} \delta_{jm} \delta_{kn} + \Delta t (\delta_{jm} \delta_{kn} B_{il} + \delta_{il} \delta_{kn} B_{jm} + \delta_{il} \delta_{jm} B_{kn}) + O(\Delta t^2)) \\
 &= \frac{1}{6} (\epsilon_{ijk} \epsilon_{ijk} + \Delta t (\epsilon_{ijk} \epsilon_{ljk} B_{il} + \epsilon_{ijk} \epsilon_{imk} B_{jm} + \epsilon_{ijk} \epsilon_{ijn} B_{kn})) \\
 &= \frac{1}{6} (6 + \Delta t (2\delta_{il} B_{il} + 2\delta_{jm} B_{jm} + 2\delta_{kn} B_{kn})) \\
 &= 1 + \Delta t \text{Tr}(B)
 \end{aligned}$$

Hence,

$$\frac{d}{dt} \det[A(t)] = \det[A(t)] \lim_{\Delta t \rightarrow 0} \frac{1}{\Delta t} (\text{Tr } A^{-1}(t) A'(t) \Delta t) = \det(A) \text{Tr}(A^{-1} A')$$

Problem 3.17 (Normal Modes): A model of the carbon dioxide molecule is sketched below



where the central atom is carbon which has mass M and the two oxygen atoms have mass m . The vibrational motion in the x -direction can be modelled by springs joining the carbon atom with the oxygen atoms. Let the springs have spring constant k .

- (i) For vibrations in the x -direction, find the normal modes and their eigenfrequencies. [6]
- (ii) Give a brief explanation for the occurrence of any zero modes. [4]
- (iii) Suppose that initially the molecule is in equilibrium and the left-hand oxygen atom starts to move with speed u in the positive x -direction whilst the other two atoms are stationary. Describe the subsequent motion in terms of the normal modes you have found. [10]

Answer 3.17.

(i) The potential energy and the kinetic energy are respectively

$$\mathcal{V} = \frac{1}{2}k(x_1 - x_2)^2 + \frac{1}{2}k(x_2 - x_3)^2 = \frac{1}{2} \begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} \begin{pmatrix} k & -k & 0 \\ -k & 2k & -k \\ 0 & -k & k \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} := \frac{1}{2} \mathbf{x}^T \mathbf{V} \mathbf{x}$$

$$\mathcal{T} = \frac{1}{2}m\dot{x}_1^2 + \frac{1}{2}M\dot{x}_2^2 + \frac{1}{2}m\dot{x}_3^2 = \frac{1}{2} \begin{pmatrix} \dot{x}_1 & \dot{x}_2 & \dot{x}_3 \end{pmatrix} \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix} \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{pmatrix} = \frac{1}{2} \dot{\mathbf{x}}^T \mathbf{T} \dot{\mathbf{x}}$$

Extremize the Lagrangian functional $\mathcal{L}[\mathbf{x}, \dot{\mathbf{x}}, t] = \mathcal{T} - \mathcal{V}$ and it thus must satisfy the Euler-Lagrange equation $\frac{d}{dt}(\mathbf{T}\dot{\mathbf{x}}) = -\mathbf{V}\mathbf{x}$. Since \mathbf{T} is not time-dependent, we look for solutions of the form $\mathbf{x} = \mathbf{x}_0 e^{i\omega t}$. Solve for $\mathbf{0} = (\mathbf{V} - \omega^2 \mathbf{T})\mathbf{x}_0$ would be equivalent to solving

$$0 = \det(\mathbf{V} - \omega^2 \mathbf{T}) = \det \begin{pmatrix} k - \omega^2 m & -k & 0 \\ -k & 2k - \omega^2 M & -k \\ 0 & -k & k - \omega^2 m \end{pmatrix} = (k - \omega^2 m)(-2km - kM + \omega^2 M^2)\omega^2$$

which has solutions $\omega^2 = 0$, $\omega^2 = \frac{k}{m}$ and $\omega^2 = \frac{k}{mM}(2m + M)$. Their corresponding eigenvectors are $(1, 1, 1)^T$, $(1, 0, -1)^T$ and $(1, -\frac{2m}{M}, 1)^T$.

(ii) By symmetry, the carbon dioxide molecule may translate along the x -direction. This translation of its centre of mass corresponds to the zero mode.

(iii) The general displacement is thus

$$\mathbf{x} = (c_1 + c_2 t) \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \operatorname{Re} \left[c_3 e^{i\sqrt{k/mt}} \right] \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \operatorname{Re} \left[c_4 e^{i\sqrt{k/Mm}\sqrt{2m+M}t} \right] \begin{pmatrix} 1 \\ -2m/M \\ 1 \end{pmatrix}$$

where $c_1, c_2 \in \mathbb{R}$ and $c_3, c_4 \in \mathbb{C}$. The initial conditions are

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \mathbf{x}(t=0) = c_1 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \operatorname{Re}[c_3] \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \operatorname{Re}[c_4] \begin{pmatrix} 1 \\ -2m/M \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} u \\ 0 \\ 0 \end{pmatrix} = \dot{\mathbf{x}}(t=0) = c_2 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \operatorname{Re} \left[i\sqrt{\frac{k}{m}} c_3 \right] \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \operatorname{Re} \left[i\sqrt{\frac{k}{Mm}(2m+M)} c_4 \right] \begin{pmatrix} 1 \\ -2m/M \\ 1 \end{pmatrix}$$

Now notice that the eigenvectors are mutually orthogonal with respect to \mathbf{T} , i.e.

$$\begin{pmatrix} 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = m - m = 0$$

$$\begin{pmatrix} 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix} \begin{pmatrix} 1 \\ -2m/M \\ 1 \end{pmatrix} = 2m - \frac{2m}{M}M = 0$$

$$\begin{pmatrix} 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix} \begin{pmatrix} 1 \\ -2m/M \\ 1 \end{pmatrix} = m - m = 0$$

We exploit this orthogonality to find c_1, c_2, c_3, c_4 . Denote the inner product with respect to \mathbf{T} to be $\langle \cdot | \cdot \rangle_T$.

$$c_1 \langle (1, 1, 1)^T | (1, 1, 1)^T \rangle_T = \langle (0, 0, 0)^T | (1, 1, 1)^T \rangle_T \implies c_1 = 0$$

Similarly, $\operatorname{Re}[c_3] = \operatorname{Re}[c_4] = 0$. Finally,

$$c_2 \langle (1, 1, 1)^T | (1, 1, 1)^T \rangle_T = \langle (u, 0, 0)^T | (1, 1, 1)^T \rangle_T \implies c_2(2m+M) = mu \implies c_2 = \frac{mu}{2m+M}$$

$$-Im\left[\sqrt{\frac{k}{m}}c_3\right]\langle(1,0,-1)^T|(1,0,-1)^T\rangle_T = \langle(u,0,0)^T|(1,0,-1)^T\rangle_T \implies -Im[c_3]2m\sqrt{\frac{k}{m}} = mu$$

$$-Im\left[\sqrt{\frac{k(2m+M)}{mM}}c_4\right]\langle(1,-2m/M,1)^T|(1,-2m/M,1)^T\rangle_T = \langle(u,0,0)^T|(1,-2m/M,1)^T\rangle_T$$

which gives $Im[c_3] = -\frac{u}{2}\sqrt{\frac{k}{m}}$ and $-\sqrt{\frac{k(2m+M)}{mM}}Im[c_4](2m + \frac{4m^2}{M}) = mu \implies Im[c_4] = \frac{-u}{2+4(m/M)}\sqrt{\frac{mM}{k(2m+M)}}$. Thus, the solution will be

$$\mathbf{x} = \frac{mut}{2m+M} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \frac{u}{2}\sqrt{\frac{k}{m}} \sin \sqrt{\frac{k}{m}}t \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \frac{u}{2+4(m/M)}\sqrt{\frac{mM}{k(2m+M)}} \sin \sqrt{\frac{k(2m+M)}{mM}}t \begin{pmatrix} 1 \\ -2m/M \\ 1 \end{pmatrix}$$

Problem 3.18 (Group Theory):

- (i) Define the order of a finite group G . What is meant by a normal subgroup H of G ? [2]
- (ii) Consider D_4 , the symmetry group of a square. Identify the elements of this group, and explain their geometrical action on the square. List all 8 proper subgroups. Hence identify the order 2 normal subgroup of D_4 . [8]
- (iii) Consider now the D_n group, the symmetry group of an n -gon for $n > 3$. Prove that when n is even, there exists only one order 2 normal subgroup while when n is odd, there exists no order 2 normal subgroup. [10]

Answer 3.18.

- (i) The order of a group G is the number of elements in G . A subgroup $H \leq G$ is normal if for every $h \in H$ and $g \in G$, we have $ghg^{-1} \in H$.
- (ii) The symmetry group contains r (rotation by $\pi/2$) and reflection s (about x -axis). The commutation relation is

$$sr = r^{-1}s \implies r^n = sr^{-n}s \implies sr^p = r^{n-p}s$$

where $n = 4$. The group thus contains

$$\{\text{Id}, r, r^2, r^3, s, sr, sr^2, sr^3\}$$

The proper subgroups are (don't count the group itself and the trivial subgroup):

$$\{\text{Id}, r, r^2, r^3\}, \quad \{\text{Id}, r^2\}, \quad \{\text{Id}, s\}, \quad \{\text{Id}, sr\}$$

$$\{\text{Id}, sr^2\}, \quad \{\text{Id}, sr^3\}, \quad \{\text{Id}, r^2, s, sr^2\}, \quad \{\text{Id}, r^2, sr, sr^3\}$$

To have an order 2 normal subgroup, it must contain the identity and one element that squares to the identity. This other element needs to be in a conjugacy class of its own (the identity is also in a conjugacy class of its own). We only have $\{\text{Id}, r^2\}$.

- (iii) The only rotation that commutes with all mirrors is the one for which $p = n-p \implies p = n/2$. When n is even, we only have one order 2 normal subgroup $\{\text{Id}, r^{n/2}\}$, but there is no solution for n odd. This also follows from Lagrange's theorem, which suggests that G has no order 2 subgroups when $|G|$ is odd.

Problem 3.19 (Group Theory):

- (i) Define a homomorphism and an isomorphism between two groups
- G_1
- and
- G_2
- . [2]

Let $M(n)$ be the set of all real $n \times n$ matrices.

- (ii) Show that the subset of
- M
- ,

$$GL(n) = \{A \in M \text{ such that } \det(A) \neq 0\}$$

forms a group under the usual law of matrix multiplication. [2]

- (iii) Show that the following two subsets of
- $GL(n)$

$$SO(n) = \{A \in M \text{ such that } \det(A) = 1 \text{ and } AA^T = \text{Id}\}$$

and

$$GL^+(n) = \{A \in M \text{ such that } \det(A) > 0\}$$

are subgroups of $GL(n)$. [4]

- (iv) Now consider
- $SO(2)$
- , the set of all real
- 2×2
- matrices

$$M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

such that $MM^T = \text{Id}$ and $\det M = 1$. By finding a suitable parametrization for (a, b, c, d) , prove that $SO(2)$ is isomorphic to $U(1)$, the group of all complex numbers of modulus one under the usual multiplication of complex numbers. [12]**Answer 3.19.**

- (i) If
- G_1
- and
- G_2
- are groups, then a function
- $\phi : G_1 \rightarrow G_2$
- is a group homomorphism if
- $a, b \in G_1$
- , then

$$\phi(a \cdot_{G_1} b) = \phi(a) \cdot_{G_2} \phi(b)$$

If this homomorphism ϕ is invertible, then it is a group isomorphism.

- (ii) Check
- $GL(n)$
- satisfy the group axioms:

- Closure: Consider $M_1, M_2 \in GL(n)$, then $\det M_1 \neq 0$, $\det M_2 \neq 0$. We must have

$$\det M_1 M_2 = \det M_1 \det M_2 \neq 0 \implies M_1 M_2 \in GL(n)$$

- Associative: matrix multiplication is associative.
- Identity: $I_n \in GL(n)$ since $\det I_n = 1 \neq 0$.
- Inverse: $\forall M \in GL(n)$, then $\det M \neq 0$ and so M is invertible.

- (iii) Check the subgroup axioms: for
- $SO(n)$
- ,

- Closure: Consider $A, B \in SO(n)$, then $\det AB = \det A \det B = 1 \implies AB \in SO(n)$.
- Associative: Inherit from parent group.
- Identity: $I_n \in SO(n)$ since $\det I_n = 1$.
- Inverse: $\forall A \in SO(n)$, $\exists A^{-1} \in SO(n)$ since $\det A^{-1} = \frac{1}{\det A} = 1$.

for $GL^+(n)$:

- Closure: Consider $A, B \in GL^+(n)$, then $\det AB = \det A \det B > 0 \implies AB \in GL^+(n)$.
- Associative: Inherit from parent group.
- Identity: $I_n \in GL^+(n)$ since $\det I_n = 1 > 0$.
- Inverse: $\forall A \in GL^+(n)$, $\exists A^{-1} \in GL^+(n)$ since $\det A^{-1} = \frac{1}{\det A} > 0$.

(iv) We need to construct an isomorphism between $g_p := e^{i\theta_p} \in U(1)$ (which is also $\in \mathbb{C}$ with modulus 1) and the matrix

$$A := \begin{pmatrix} \cos \theta_p & \sin \theta_p \\ -\sin \theta_p & \cos \theta_p \end{pmatrix} \in SO(2)$$

since $\det A = \cos^2 \theta_p + \sin^2 \theta_p = 1$. Let this map be Φ . This is a homomorphism.

$$\begin{aligned} \Phi(g_p)\Phi(g_q) &= \begin{pmatrix} \cos \theta_p & \sin \theta_p \\ -\sin \theta_p & \cos \theta_p \end{pmatrix} \begin{pmatrix} \cos \theta_q & \sin \theta_q \\ -\sin \theta_q & \cos \theta_q \end{pmatrix} \\ &= \begin{pmatrix} \cos \theta_p \cos \theta_q - \sin \theta_p \sin \theta_q & \cos \theta_p \sin \theta_q + \cos \theta_q \sin \theta_p \\ -\sin \theta_p \cos \theta_q - \cos \theta_p \sin \theta_q & \cos \theta_p \cos \theta_q - \sin \theta_p \sin \theta_q \end{pmatrix} \\ &= \begin{pmatrix} \cos(\theta_p + \theta_q) & \sin(\theta_p + \theta_q) \\ -\sin(\theta_p + \theta_q) & \cos(\theta_p + \theta_q) \end{pmatrix} \\ &= \Phi(g_p g_q) \end{aligned}$$

The inverse mapping exists, defined by

$$\Phi^{-1} \left(\begin{pmatrix} \cos \theta_p & \sin \theta_p \\ -\sin \theta_p & \cos \theta_p \end{pmatrix} \right) = e^{i\theta_p}$$

and it too is a homomorphism.

$$\begin{aligned} \Phi^{-1} \left(\begin{pmatrix} \cos \theta_p & \sin \theta_p \\ -\sin \theta_p & \cos \theta_p \end{pmatrix} \right) \Phi^{-1} \left(\begin{pmatrix} \cos \theta_q & \sin \theta_q \\ -\sin \theta_q & \cos \theta_q \end{pmatrix} \right) &= e^{i(\theta_p + \theta_q)} \\ &= \Phi^{-1} \left(\begin{pmatrix} \cos(\theta_p + \theta_q) & \sin(\theta_p + \theta_q) \\ -\sin(\theta_p + \theta_q) & \cos(\theta_p + \theta_q) \end{pmatrix} \right) \end{aligned}$$

Since Φ is a homomorphism and is bijective, then it is an isomorphism. Hence, $SO(2) \simeq U(1)$.

Problem 3.20 (Representation Theory): Any theorems you use should be stated, but need not be proven in this question.

- (i) (a) State the definition of a conjugacy class of a group. State the definition of an irreducible representation. [1]

Consider the quaternion group $\mathcal{Q} = \{\pm 1, \pm i, \pm j, \pm k\}$ with the defining relations

$$-1 = i^2 = j^2 = k^2 = ijk$$

- (b) Find all conjugacy classes of \mathcal{Q} . Hence deduce the number of irreducible representations of \mathcal{Q} and state their dimensions. [8]
- (ii) (a) Consider the 3-dimensional real matrix representation T of the order 4 cyclic group $Z_4 = \{I, a, a^2, a^3\}$ given by

$$T(a) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & b \\ 0 & c & 0 \end{pmatrix}$$

What are the conditions on the real constants b and c such that T is (i) a faithful representation, and (ii) an unfaithful representation? [7]

- (b) Finally, construct a 2-dimensional representation of Z_4 with kernel $\{I, a^2\}$. [3]

Answer 3.20.

- (i) (a) The conjugacy class of $h \in G$ is the set of possible outputs to the process $gg_i g^{-1}$ by systematically conjugating h with each element of G in turn (written as $\text{ccl}(h)$), and is

$$\text{ccl}(h) := \{k \in G \text{ s.t. } k = g \cdot h \cdot g^{-1} \text{ for some } g \in G\}$$

A representation D of a group G is a homomorphic mapping from the group elements to the set of invertible matrices, i.e. $D(g_i)$ is an invertible matrix for $g_i \in G$. A representation is said to be reducible if \exists an invertible matrix S s.t. $SD(g_i)S^{-1}$ has the same block-diagonal form (the entire space being the invariant subspace does not count) $\forall M(g_i)$. If no such matrix can be found, then the representation is said to be irreducible.

- (b) ± 1 are respectively in their conjugate classes of their own. Other conjugacy classes are

$$\{i, -i\}, \quad \{j, -j\}, \quad \{k, -k\}$$

Since the number of irreducible representations is the number of conjugacy classes, there are thus 5 irreducible representations. Furthermore, since the sum of the squares of the dimensions of the matrices of the distinct irreducible representations is the order of the group, we require 5 positive integers whose squares sum to 8. They must be

$$\{2, 1, 1, 1, 1\}$$

- (ii) (a) Since T is a representation, it must be a homomorphic mapping. We have

$$T(a) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & b \\ 0 & c & 0 \end{pmatrix}, \quad T(a)^2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & bc & 0 \\ 0 & 0 & bc \end{pmatrix}, \quad T(a)^3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & b^2c \\ 0 & bc^2 & 0 \end{pmatrix}, \quad T(a)^4 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & b^2c^2 & 0 \\ 0 & 0 & b^2c^2 \end{pmatrix}$$

We require $T(I) = T(a^4) = T(a)^4$, so $b^2c^2 = 1$. We either have $bc = -1$ (then $T(a)$, $T(a)^2 = T(a^2)$, $T(a)^3 = T(a^3)$ and $T(a)^4 = T(a^4)$ are distinct matrices, hence faithful representation) or $bc = +1$ (unfaithful representation with kernel $\{I, a^2\}$ since $T(a^2) = T(a)^2 = I$).

- (b) The two-dimensional representation with kernel $\{I, a^2\}$ is the two-dimensional sub-block in the unfaithful representation T . Since $bc = 1$, we choose $b = c = 1$ for convenience. Then, let this representation be U

$$U(a) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = U(a^3), \quad U(a^2) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = U(a^4)$$

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4.1 Paper 1

Problem 4.1 (Vector Calculus):

- (i) Using Cartesian coordinates, show that for arbitrary vector fields $\mathbf{A}(x, y, z)$ and $\mathbf{B}(x, y, z)$ [6]

$$\nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot (\nabla \times \mathbf{A}) - \mathbf{A} \cdot (\nabla \times \mathbf{B})$$

- (ii) State the divergence theorem, and use it to show that for a scalar field $a(x, y, z)$ and a vector field $\mathbf{B}(x, y, z)$,

$$\int_V \nabla a \cdot (\nabla \times \mathbf{B}) dV = - \int_S (\nabla a \times \mathbf{B}) \cdot \hat{\mathbf{n}} dS \quad (*)$$

where V is a given volume, and $\hat{\mathbf{n}}$ is the unit vector outward normal to its surface S . [6]

- (iii) Consider the particular case $a = xy + z^2$ and $\mathbf{B} = (y, -yz, x)$.

Verify both sides of (*), where V is a circular cylinder of height h and radius 1 with base $x^2 + y^2 = 1$ at $z = 0$. [8]

Answer 4.1.

- (i) Using suffix notation in Cartesian coordinates, then evaluating the LHS:

$$\frac{\partial}{\partial x_k} \epsilon_{ijk} A_i B_j = \epsilon_{ijk} B_j \frac{\partial}{\partial x_k} A_i + \epsilon_{ijk} A_i \frac{\partial B_j}{\partial x_k} = B_j \epsilon_{kij} \frac{\partial A_i}{\partial x_k} - A_i \epsilon_{kji} \frac{\partial B_j}{\partial x_k}$$

where $\epsilon_{jki} = -\epsilon_{kji}$.

- (ii) If $\mathbf{F} = \mathbf{F}(\mathbf{x})$ be a continuously differentiable vector field and $D \subset \mathbb{R}^2$ a region with piecewise smooth boundary ∂D , then the divergence theorem states

$$\int_D \nabla \cdot \mathbf{F} dA = \oint_{\partial D} \mathbf{F} \cdot \mathbf{n} ds$$

where the normal to ∂V points outwards from V . Invoke divergence theorem to part (i)'s result, and let $\mathbf{A} = \nabla a$, $V = D$, $\partial V = S$,

$$\int_S (\nabla a \times \mathbf{B}) \cdot \hat{\mathbf{n}} dS = \int_V \nabla \cdot (\nabla a \times \mathbf{B}) dV = \int_V \mathbf{B} \cdot (\nabla \times \nabla a) - \nabla a \cdot (\nabla \times \mathbf{B}) dV$$

Since the curl of a gradient is zero, the result trivially follows.

- (iii) We have $\nabla a = (y, x, 2z)^T$ and $\nabla \times \mathbf{B} = (y, -1, -1)^T$. So, $\nabla a \cdot (\nabla \times \mathbf{B}) = y^2 - x - 2z$ and $\nabla a \times \mathbf{B} = (x^2 + 2yz^2, 2zy - xy, -y^2z - xy)^T$. We parametrize $S = S_1 \cup S_2 \cup S_3$ with $S_1 : z = 0$ and $\hat{\mathbf{n}} = -\hat{\mathbf{z}}$; $S_2 : z = h$ and $\hat{\mathbf{n}} = \hat{\mathbf{z}}$; $S_3 : \hat{\mathbf{n}} = \hat{\mathbf{r}}$. We note for all 3 surfaces, $x^2 + y^2 = 1$. Then, the surface integral gives

$$\begin{aligned} & \int_{S_1} xy dx dy + \int_{S_2} -y^2 h - xy dx dy + \int_0^h \int_0^{2\pi} \begin{pmatrix} \cos^2 \theta + 2 \sin \theta z^2 \\ 2z \sin \theta - \sin \theta \cos \theta \\ -\sin^2 \theta z - \cos \theta \sin \theta \end{pmatrix} \cdot \begin{pmatrix} \cos \theta \\ \sin \theta \\ 0 \end{pmatrix} d\theta dz \\ &= -\frac{h}{4} \int_0^{2\pi} \sin^2 \theta d\theta + \int_0^{2\pi} h \cos^3 \theta + \frac{2}{3} h^3 \sin \theta \cos \theta + h^2 \sin^2 \theta - h \sin^2 \theta \cos \theta d\theta \\ &= -\frac{h}{4} \int_0^{2\pi} \sin^2 \theta d\theta + \int_0^{2\pi} h \cos \theta \cos 2\theta d\theta + h^2 \int_0^{2\pi} \frac{2}{3} h \sin \theta \cos \theta + \sin^2 \theta d\theta \\ &= \left(h^2 - \frac{h}{4} \right) \pi \end{aligned}$$

where we cancel the first term with part of the second term, since the two regions have the same integration limits for x, y . We also used $\int_0^{2\pi} \sin \theta \cos \theta d\theta = 0$, $\int_0^{2\pi} \cos 2\theta \cos \theta d\theta = 0$ and $\int_0^{2\pi} \sin^2 \theta d\theta = \pi$. This is indeed the negative of the volume integral:

$$\int_0^h \int_0^1 \int_0^{2\pi} r^3 \sin^2 \theta - r^2 \cos \theta - 2rz d\theta dr dz = \frac{1}{4} \pi h - \pi h^2$$

Hence, the identity in part (ii) was verified.

Problem 4.2 (Partial Differential Equation): A damped wave on a string can be described by the equation

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} - \alpha \frac{\partial u}{\partial t}$$

where subscripts denote partial derivatives and α and c are constants.

- (i) Use the method of separation of variables to find two ordinary differential equations. [4]
- (ii) Consider a string between $-L \leq x \leq L$ with fixed endpoints $u(x = -L) = u(x = L) = 0$. If the string is plucked in the centre, we might expect the solutions to be symmetric about $x = 0$. Show that the general solution for symmetric disturbances to be written in the following form

$$u(x, t) = \sum_{n=1}^{\infty} e^{-\alpha t/2} \cos\left(\frac{n\pi x}{2L}\right) \operatorname{Re}[A_n e^{i\omega_n t} + B_n e^{-i\omega_n t}] \quad (*)$$

where n is an odd integer and Re denotes real part. [6]

- (iii) Give an expression for ω_n as a function of α , n , L and c . How small must the damping coefficient, α , be for oscillatory solutions to exist? Describe what happens if $\alpha < 0$. [3]
- (iv) If the string is plucked so that at $t = 0$,

$$\frac{\partial u}{\partial t} = 0, \quad u(x, t = 0) = e^{-|x|/l}$$

find the coefficients A_n and B_n in (*). How do the coefficients simplify in the limit when $l \ll L$, as required to impose $u(x = -L) = u(x = L) = 0$. [7]

Answer 4.2.

- (i) Use separation of variables $u(x, t) = X(x)T(t)$ such that

$$\frac{T''(t)}{T(t)} = c^2 \frac{X''(x)}{X(x)} - \alpha \frac{T'(t)}{T(t)} = -\lambda^2$$

to obtain two ordinary differential equations

$$\frac{d^2 T(t)}{dt^2} + \alpha \frac{dT(t)}{dt} + \lambda^2 T(t) = 0 \quad (\text{time})$$

$$\frac{d^2 X(x)}{dx^2} = -\frac{\lambda^2}{c^2} X(x) \quad (\text{position})$$

- (ii) The corresponding solutions are

$$X(x) = c_1 \sin \frac{\lambda}{c} x + c_2 \cos \frac{\lambda}{c} x$$

$$T(t) = e^{-\alpha t/2} (c_3 e^{0.5\sqrt{\alpha^2 - 4\lambda^2}t} + c_4 e^{-0.5\sqrt{\alpha^2 - 4\lambda^2}t})$$

Since $u(x = -L) = u(x = L) = 0$, only the term $\cos \frac{n\pi x}{2L}$ for odd n matters (since symmetric about $x = 0$) for $X(x)$. We have $\lambda = \frac{n\pi c}{2L}$ and $\omega_n = 0.5\sqrt{4\lambda^2 - \alpha^2} = \sqrt{\frac{c^2 n^2 \pi^2}{4L^2} - \frac{\alpha^2}{4}}$. Hence, we obtain the desired form for $u(x, t)$.

$$u(x, t) = \sum_{n=1}^{\infty} X_n(x) T_n(t) = \sum_{n=1}^{\infty} e^{-\alpha t/2} \cos\left(\frac{n\pi x}{2L}\right) \operatorname{Re}[A_n e^{i\omega_n t} + B_n e^{-i\omega_n t}]$$

- (iii) Since n can be arbitrarily high, oscillatory solutions will always exist. For $\alpha < 0$, the system is unstable.

(iv) The time derivative at for u at $t = 0$ is

$$0 = \frac{\partial u(x, t)}{\partial t} \Big|_{t=0} = \sum_{n=1}^{\infty} \cos \frac{n\pi x}{2L} \left(\omega_n \operatorname{Im}[B_n - A_n] - \frac{\alpha}{2} \operatorname{Re}[A_n + B_n] \right) \implies \operatorname{Im}[B_n - A_n] = \frac{\alpha}{2\omega_n} \operatorname{Re}[A_n + B_n]$$

We have $e^{-|x|/l} = u(x, 0) = \sum_{n=1}^{\infty} \cos(\frac{n\pi x}{2L}) \operatorname{Re}[A_n + B_n]$ and so

$$\begin{aligned} \int_{-L}^L e^{-|x|/l} \operatorname{Re}[e^{im\pi x/2L}] dx &= \sum_{n=1}^{\infty} \operatorname{Re}[A_n + B_n] \int_{-L}^L \cos \frac{m\pi x}{2L} \cos \frac{n\pi x}{2L} dx \\ 2 \int_0^L e^{-l^{-1}(1 - \frac{im\pi l}{2L}x)} dx &= \sum_{n=1}^{\infty} \operatorname{Re}[A_n + B_n] \delta_{nm} L \\ 2 \operatorname{Re} \left[\frac{-l}{1 - \frac{im\pi l}{2L}} \left(e^{-Ll^{-1}(1 - \frac{im\pi l}{2L})} - 1 \right) \right] &= L \operatorname{Re}[A_m + B_m] \end{aligned}$$

To write $u(x, t)$ in terms of $\cos(\omega_n t)$ and $\sin(\omega_n t)$, we require $A_n = B_n^*$. This means

$$\begin{aligned} B_n &= \frac{1}{L} \operatorname{Re} \left[\frac{-l}{1 - \frac{in\pi l}{2L}} \left(e^{-Ll^{-1}(1 - \frac{in\pi l}{2L})} - 1 \right) \right] \left(1 + i \frac{\alpha}{2\omega_n} \right) \\ A_n &= \frac{1}{L} \operatorname{Re} \left[\frac{-l}{1 - \frac{in\pi l}{2L}} \left(e^{-Ll^{-1}(1 - \frac{in\pi l}{2L})} - 1 \right) \right] \left(1 - i \frac{\alpha}{2\omega_n} \right) \end{aligned}$$

Further, we note that due to symmetry we have to take odd n only such that $e^{in\pi/2} = i(-1)^n$. In the limit $l \ll L$, we have

$$\begin{aligned} A_n &\approx \frac{l}{L} \operatorname{Re} \left[l \left(1 + \frac{in\pi l}{2L} \right) \right] \left(1 - i \frac{\alpha}{2\omega_n} \right) = \frac{l}{L} \left(1 - i \frac{\alpha}{2\omega_n} \right) \\ B_n &\approx \frac{1}{L} \operatorname{Re} \left[l \left(1 + \frac{in\pi l}{2L} \right) \right] \left(1 + i \frac{\alpha}{2\omega_n} \right) = \frac{l}{L} \left(1 + i \frac{\alpha}{2\omega_n} \right) \end{aligned}$$

Problem 4.3 (Green's Functions):

- (i) Find the general solution $y(x)$ to the homogeneous second-order linear differential equation [6]

$$\frac{d^2y}{dx^2} - \frac{1+x}{x} \frac{dy}{dx} + \frac{y}{x} = 0$$

[Hint: Look for a particular solution of the form $y_p(x) = g(x)e^x$.]

- (ii) Find the Green's function for this equation in the region $-1 \leq x \leq 1$, subject to the homogeneous boundary conditions $y(-1) = 0$ and $y(1) = 0$. [8]
- (iii) Use the Green's function found above to solve the inhomogeneous differential equation

$$\frac{d^2y}{dx^2} - \frac{1+x}{x} \frac{dy}{dx} + \frac{y}{x} = x$$

subject to the same boundary conditions. [6]

Answer 4.3.

- (i) We try their suggested form of y_p . We then have

$$\left(g'' + 2g' + g - \frac{1}{x}g' - \frac{1}{x}g - g' - g + \frac{1}{x}g \right) e^x = 0 \implies g'' = g' \frac{1-x}{x}$$

This means the solution is $\frac{dg}{dx} = e^{\ln(x)-x+C} = Axe^{-x} \implies g(x) = -Ae^{-x}(1+x) + B \implies y(x) = -A(1+x) + Be^x$.

- (ii) The corresponding Green's function satisfy

$$\frac{\partial^2 G(x, \xi)}{\partial x^2} - \frac{1+x}{x} \frac{\partial G(x, \xi)}{\partial x} + \frac{G(x, \xi)}{x} = \delta(x - \xi), \quad -1 \leq x \leq 1, \quad G(-1, \xi) = 0 = G(1, \xi)$$

Integrate this over an infinitesimal region about $x = \xi$, we deduce that G' satisfy the jump condition $[G']_{\xi-}^{\xi+} = 1$ at $x = \xi$ and G to be continuous everywhere (otherwise $G'' \propto \delta'(x - \xi)$ which is a contradiction), including $x = \xi$. Using the homogeneous solution in part (i), our Green's function will have the form

$$G(x, \xi) = \begin{cases} A(\xi)(1+x) & -1 \leq x < \xi \leq 1 \\ C(\xi)[(1+x) - 2e^{x-1}] & -1 \leq \xi < x \leq 1 \end{cases}$$

We have $\frac{\partial G}{\partial x} = A$ for $-1 \leq x < \xi < 1$ and $C(\xi)[1 - 2e^{x-1}]$ for $-1 \leq \xi < x \leq 1$. Jump condition and continuity condition respectively give

$$C(\xi)[1 - 2e^{x-1}] - A(\xi) = 1$$

$$A(\xi)(1+\xi) = C(\xi)((1+\xi) - 2e^{\xi-1})$$

We thus have $C(\xi) = -(\frac{1+\xi}{2\xi})e^{1-\xi}$ and $A(\xi) = -\frac{1}{2\xi}[(1+\xi)e^{1-\xi} - 2]$. The Green's function is

$$G(x, \xi) = \begin{cases} \frac{1}{2\xi}(1+x)[2 - (1+\xi)e^{1-\xi}] & -1 \leq x < \xi \leq 1 \\ \frac{1}{2\xi}(1+\xi)e^{-\xi}[2e^x - (1+x)e] & -1 \leq \xi < x \leq 1 \end{cases}$$

- (iii) The solution is $y = \int_{-1}^1 G(x, \xi) f(\xi) d\xi$, where $f(x) = x$.

$$y = [2e^x - (1+x)e] \int_{-1}^x \frac{1}{2\xi}(1+\xi)e^{-\xi}\xi d\xi + (1+x) \int_x^1 \frac{1}{2\xi}[2 - (1+\xi)e^{1-\xi}]\xi d\xi$$

Since $\int (1+\xi)e^{-\xi} d\xi = -(2+\xi)e^{-\xi}$, we have

$$y(x) = \frac{1}{2}[2e^{x+1} - 2x^2 + (1+e^2)(x+1)]$$

Problem 4.4 (Fourier Transform): The Fourier transform $\tilde{f}(k)$ of a function $f(x)$ is defined by

$$\tilde{f}(k) = \int_{-\infty}^{\infty} e^{-ikx} f(x) dx$$

and the correlation $h(x)$ between two functions $f(x)$ and $g(x)$ is defined by

$$h(x) = \int_{-\infty}^{\infty} (f(y))^* g(x+y) dy$$

where $*$ denotes a complex conjugate.

(i) Prove that [6]

$$\tilde{h}(k) = (\tilde{f}(k))^* \tilde{g}(k)$$

(ii) Use this result to prove Parseval's Theorem [6]

$$\int_{-\infty}^{\infty} |f(x)|^2 dx = \frac{1}{2\pi} \int_{-\infty}^{\infty} |\tilde{f}(k)|^2 dk$$

(iii) Verify Parseval's theorem for the following function [8]

$$f(x) = \begin{cases} 1 & |x| \leq 1 \\ 0 & |x| > 1 \end{cases}$$

Hint: $\int_0^{\infty} x^{-1} \sin(x) \cos(x) dx = \frac{\pi}{4}$

Answer 4.4.

(i) The standard proof for convolution theorem: set $x = u - y$ and separate the integrals.

$$\tilde{h}(k) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f^*(y) g(x+y) dy e^{-ikx} dx = \int_{-\infty}^{\infty} f^*(y) e^{iky} dy \int_{-\infty}^{\infty} g(u) e^{-iku} du = (\tilde{f}(k))^* \tilde{g}(k)$$

(ii) Another standard proof. From the previous result, set $f = g$, and integrate over k

$$\int_{-\infty}^{\infty} \tilde{h}(k) dk = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f^*(y) f(x+y) e^{-ikx} dy dx dk$$

Rearranging, we have

$$\begin{aligned} \int_{-\infty}^{\infty} |\tilde{f}(k)|^2 dk &= \int_{-\infty}^{\infty} f^*(y) \int_{-\infty}^{\infty} f(x+y) \int_{-\infty}^{\infty} e^{-ikx} dk dx dy \\ &= \int_{-\infty}^{\infty} f^*(y) \int_{-\infty}^{\infty} f(x+y) 2\pi \delta(x) dx dy \\ &= 2\pi \int_{-\infty}^{\infty} |f(y)|^2 dy \end{aligned}$$

(iii) The norm is trivially $\int_{-\infty}^{\infty} |f(x)|^2 dx = \int_{-1}^1 dx = 2$. Also, the Fourier transform is $\tilde{f}(k) = \int_{-1}^1 e^{-ikx} dx = \frac{2 \sin(k)}{k}$. We then have

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} |\tilde{f}(k)|^2 dk = \frac{4}{2\pi} \int_0^{\infty} \frac{\sin^2 k}{k^2} dk = \frac{4}{\pi} \left([-k^{-1} \sin^2 k]_0^{\infty} + \int_0^{\infty} \frac{2 \sin(k) \cos(k)}{k} dk \right) = \frac{4}{\pi} 2 \frac{\pi}{4} = 2$$

which is consistent with Parseval's theorem.

Problem 4.5 (Linear Algebra):

- (i) If M is an invertible complex matrix with Hermitian conjugate M^\dagger and inverse M^{-1} , show that [2]

$$(M^\dagger)^{-1} = (M^{-1})^\dagger$$

- (ii) If A is an anti-Hermitian matrix, i.e. one such that $A^\dagger = -A$, show, by diagonalizing iA , that

$$|\det(1 + A)|^2 \geq 1$$

and hence that $1 + A$ is always invertible. [6]

- (iii) If A is an anti-Hermitian matrix, show that

$$U = (1 - A)(1 + A)^{-1} \quad (*)$$

is a unitary matrix, that is $U^\dagger = U^{-1}$. [6]

- (iv) If U is a unitary matrix such that $1 + U$ is invertible, show that there is a unique matrix A satisfying (*). Show that the matrix A is indeed anti-Hermitian. Give an example of a unitary matrix for which $1 + U$ is not invertible. [6]

Answer 4.5.

- (i) Take conjugate transpose of $MM^{-1} = I$ gives $(M^{-1})^\dagger M^\dagger = I \implies (M^{-1})^\dagger = (M^\dagger)^{-1}$.

- (ii) If A is anti-Hermitian, then iA is Hermitian, i.e. $A^\dagger = -A \implies (iA)^\dagger = -iA^\dagger = iA$. To show iA is diagonalizable, it must have n linearly independent eigenvectors. Being Hermitian, its eigenvalues are real and the eigenvectors corresponding to different eigenvalues are orthogonal:

$$(iA)x_q = \lambda_q x_q \implies x_p^\dagger (iA)x_q = \lambda_q x_p^\dagger x_q \implies (\lambda_p x_p)^\dagger x_q = \lambda_q x_p^\dagger x_q \implies (\lambda_p^* - \lambda_q)x_p^\dagger x_q = 0$$

$x_p^\dagger x_q = 1$ iff $p = q$, then $\lambda_p^* = \lambda_p \in \mathbb{R} \forall p$. $x_p^\dagger x_q = 0$ iff $\lambda_p^* - \lambda_q \neq 0$. If iA has n distinct eigenvalues, we get a basis of n pairwise orthogonal vectors. Otherwise, say we have $r < n$ distinct eigenvalues, then by Gram-Schmidt, we can extend the r orthogonal eigenvectors into a basis for \mathbb{C}^n . Thus, iA is guaranteed to have n linearly independent eigenvectors.

Having established that iA is diagonalizable, one can construct a matrix R whose columns are the normalized eigenvectors of iA such that $R^\dagger iA R$ is diagonal with real eigenvalues. Then,

$$\det(I + A) = \det((R R^\dagger)(I + A)) = \det(R^\dagger(I + A)R) = \det(I + \Lambda) = \prod_{i=1}^n (1 + \lambda_i)$$

where $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$ and λ_i is imaginary, since A is anti-Hermitian. Hence

$$|\det(1 + A)|^2 = \prod_{i=1}^n (1 + \lambda_i)(1 + \lambda_i^*) = 1 + |\lambda_i|^2 \geq 1$$

Since the $\det \neq 0$, $1 + A$ is always invertible.

- (iii) We have $A^\dagger = -A$ and from part (ii), $1 + A$ is invertible so by part (i), $((1 + A)^{-1})^\dagger = ((1 + A)^\dagger)^{-1} = (1 - A)^{-1}$.

$$U^\dagger = [(1 - A)(1 + A)^{-1}]^\dagger = [(1 + A)^{-1}]^\dagger (1 - A)^\dagger = (1 - A)^{-1}(1 + A)$$

To show U is unitary, we need to further show that $1 + A$ and $1 - A$ commute, i.e.

$$\begin{aligned} [1 + A, 1 - A] &= (1 + A)(1 - A) - (1 - A)(1 + A) = 1 - A + A - A^2 - 1 - A + A - A^2 = 0 \\ \implies U^\dagger U &= (1 - A)^{-1}(1 + A)(1 - A)(1 + A)^{-1} = (1 - A)^{-1}(1 - A)(1 + A)(1 + A)^{-1} = I \end{aligned}$$

so U is unitary, i.e. $U^\dagger = U^{-1}$.

- (iv) Since $U = (1 - A)(1 + A)^{-1}$, we naturally have $U(1 + A) = 1 - A$. Taking conjugate transpose on both sides, $(1 + A)^\dagger U^\dagger = (1 - A)^\dagger = (1 - A^\dagger)$ and hence

$$(1 - A^\dagger)(1 - A) = (1 + A^\dagger)U^\dagger U(1 + A) = (1 + A^\dagger)(1 + A) \implies A^\dagger = -A$$

where we used the fact that U is unitary to show A is anti-Hermitian.

One example of $1 + U$ being non-invertible is $U = -I$.

Problem 4.6 (Linear Algebra):

- (i) If
- M
- is an anti-symmetric
- $n \times n$
- matrix show that

$$\det(M) = (-1)^n \det(M)$$

and hence if n is odd, $\det(M)$ must vanish. [2]

- (ii) If
- M
- is a real anti-symmetric
- $n \times n$
- matrix show that
- M^2
- is a real symmetric non-positive matrix, i.e.

$$x^T M^2 x \leq 0$$

for all vectors x , where T denotes transpose. Hence show that if n is odd then M^2 must have at least one vanishing eigenvalue. [3]

- (iii) If
- e_1
- is an eigenvector of
- M^2
- with non-vanishing eigenvalue
- $\lambda_1 = -\mu_1^2$
- , with
- $\mu_1 > 0$
- , show that
- $e_2 = M e_1$
- is also an eigenvector of
- M^2
- , orthogonal to
- e_1
- with the same eigenvalue.
- [5]

- (iv) By considering the remaining eigenvectors,
- $\{e_3, \dots, e_n\}$
- , conclude that the non-vanishing eigenvalues of
- M^2
- occur in, not necessarily distinct, pairs.
- [4]

- (v) Hence show, using the basis of eigenvectors of
- M^2
- , that the original matrix
- M
- may be cast in block diagonal form with each block being either
- 2×2
- anti-symmetric with entries
- $\pm\mu_1, \pm\mu_2, \dots$
- or a block with zero entries.
- [6]

Answer 4.6.

- (i) If
- M
- is anti-symmetric,
- $M^T = -M$
- , then
- $\det M = \det(M^T) = \det(-M) = (-1)^n \det(M)$
- . For odd
- n
- ,
- $\det(M) = -\det(M) \implies \det(M) = 0$
- .

- (ii) Consider
- $y = Mx$
- . We have
- $|y|^2 \geq 0 \forall x$
- . So

$$0 \leq |y|^2 = (Mx)^T Mx = x^T M^T Mx = -x^T M Mx \implies x^T M^2 x \leq 0$$

If n is odd, $\det M = 0$ from earlier, then at least one of the eigenvalues of M is 0, since $\det M = \prod_{i=1}^n \lambda_i = 0$. Then, $0x = Mx = M^2x$, M^2 has at least one vanishing eigenvalue.

- (iii) Given
- $M^2 e_1 = -\mu_1^2 e_1$
- ,
- $M^2 e_2 = M^2 M e_1 = M M^2 e_1 = -\mu_1^2 M e_1 = -\mu_1^2 e_2$
- , and so
- e_2
- is an eigenvector of
- M^2
- with eigenvalue
- $-\mu_1^2$
- as well.

Consider $e_1 \cdot e_2 = (e_1 \cdot e_2)^T$, which is a scalar.

$$0 = e_1 \cdot e_2 - (e_1 \cdot e_2)^T = e_1^T M e_1 - e_2^T e_1 = e_1^T M e_1 - e_1^T M^T e_1 = e_1^T M e_1 + e_1^T M e_1$$

where M is anti-symmetric. So, $0 = e_1^T M e_1 = e_1 \cdot e_2$, i.e. e_1 and e_2 are orthogonal.

- (iv) From part (iii), each eigenvector corresponding to a non-zero eigenvalue will generate a 2D subspace under the action of arbitrary powers of
- M
- , each vector within each subspace having the same eigenvalue.

Eigenvalues may be repeated within different subspaces. 2D subspaces with different eigenvalues are disjoint, whilst those subspaces with repeated eigenvalues can be chosen to be disjoint.

- (v) Assume
- \hat{e}_1
- is an eigenvector of
- M^2
- with eigenvalue of
- $\lambda = -\mu_1^2$
- , then
- $e_2 = M \hat{e}_1$
- will not, in general, be properly normalized.

$$e_2 \cdot e_2 = (M \hat{e}_1)^T M \hat{e}_1 = -\hat{e}_1^T M^2 \hat{e}_1 = \mu_1^2$$

since M is anti-symmetric. So, we can construct the normalized version $\hat{e}_2 = \frac{1}{\mu_1} M \hat{e}_1$. Then, $\hat{e}_1^T M \hat{e}_2 = \hat{e}_1^T \frac{1}{\mu_1} M^2 \hat{e}_1 = \mu_1$. Consider orthogonal matrix R , whose columns are the normalized eigenvectors of M^2 , then $R^T M R$ has diagonal entries to be zero. In particular, the absolute values of (1,2) and (2,1) entries are μ_1 and $-\mu_1$ respectively such that M is anti-symmetric..

Problem 4.7 (Cauchy-Riemann):

- (i) Write down the Cauchy Riemann equations for the real and imaginary parts, u , v of the analytic function $f(z) = u(x, y) + iv(x, y)$, where $z = x + iy$ and hence show that the level sets, $u = \text{constant}$ and $v = \text{constant}$, are orthogonal, and that $|\nabla u| = |\nabla v|$. [3]
- (ii) Show that u satisfies Laplace's equation $\nabla^2 u = (\partial_x^2 + \partial_y^2)u$, where $\partial_x = \frac{\partial}{\partial x}$, $\partial_y = \frac{\partial}{\partial y}$. [2]
- (iii) Using the analytic function $f(z) = \cosh^{-1} z$, show that the level sets $u = \text{constant}$ and $v = \text{constant}$ form an orthogonal system of ellipses and hyperbolae. [5]
- (iv) Hence show that $\phi = u - \cosh^{-1}(\sqrt{2})$ is a solution of Laplace's equation which vanishes on the ellipse

$$\frac{1}{2}x^2 + y^2 = 1$$

How does ϕ behave as $x, y \rightarrow \infty$?

[5]

- (v) If

$$F(z, \bar{z}) = \bar{z}H(z) + G(z) = U(x, y) + iV(x, y)$$

where $H(z)$ and $G(z)$ are analytic functions of z and $\bar{z} = x - iy$, show that U and V satisfy the fourth order partial differential equations

[5]

$$\nabla^4 U = (\partial_x^2 + \partial_y^2)(\partial_x^2 + \partial_y^2)U = 0$$

$$\nabla^4 V = (\partial_x^2 + \partial_y^2)(\partial_x^2 + \partial_y^2)V = 0$$

Answer 4.7.

- (i) For $f(z) = u(x, y) + iv(x, y)$ to be analytic, $f(z)$ must satisfy the Cauchy-Riemann equations $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ and $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$. Then, we use them to evaluate

$$\nabla u \cdot \nabla v = \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial y} = \frac{\partial v}{\partial x} \frac{\partial v}{\partial y} - \frac{\partial v}{\partial x} \frac{\partial v}{\partial y}, \quad |\nabla u| |\nabla v| = \sqrt{\left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2} - \sqrt{\left(\frac{\partial v}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial y}\right)^2}$$

Both evaluate to 0. Hence, $\nabla u \perp \nabla v$, showing that contours of constant u and v are orthogonal.

- (ii) Use Cauchy Riemann equations to show u satisfy Laplace's equation.

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial}{\partial y} \left(-\frac{\partial v}{\partial x} \right) = 0$$

- (iii) We have $f(z) = \cosh^{-1}(z) := u + iv$ given that it is analytic. So,

$$x + iy = \cosh(u + iv) = \cosh(u) \cosh(iv) + \sinh(u) \sinh(iv) = \cosh(u) \cos(v) + i \sinh(u) \sin(v)$$

We conclude $x = \cosh(u) \cos(v)$ and $y = \sinh(u) \sin(v)$. Recalling the key identities

$$\left(\frac{x}{\cosh(u)} \right)^2 + \left(\frac{y}{\sinh(u)} \right)^2 = 1, \quad \left(\frac{x}{\cos(v)} \right)^2 - \left(\frac{y}{\sin(v)} \right)^2 = 1$$

Surfaces of constant u and constant v are thus ellipses and hyperbolae respectively.

- (iv) Take $\cosh(u) = \sqrt{2}$, then $\sinh(u) = 1$, the ellipse becomes $\frac{1}{2}x^2 + y^2 = 1$. So $\phi = u - \cosh^{-1}(\sqrt{2}) = 0$ everywhere on the ellipse. Since u satisfies Laplace's equation, $\phi = u - \cosh^{-1}(\sqrt{2})$ must also satisfy Laplace's equation. We have $\lim_{x, y \rightarrow \infty} \phi = \lim_{x, y \rightarrow \infty} u = \infty$.

- (v) Using change of variables. $z = x + iy$ and $\bar{z} = x - iy$, then by chain rule,

$$\frac{\partial}{\partial z} = \frac{\partial}{\partial x} \frac{\partial x}{\partial z} + \frac{\partial}{\partial y} \frac{\partial y}{\partial z} = \frac{\partial}{\partial x} - i \frac{\partial}{\partial y}, \quad \frac{\partial}{\partial \bar{z}} = \frac{\partial}{\partial x} \frac{\partial x}{\partial \bar{z}} + \frac{\partial}{\partial y} \frac{\partial y}{\partial \bar{z}} = \frac{\partial}{\partial x} + i \frac{\partial}{\partial y}$$

And so $\frac{\partial}{\partial z} \frac{\partial}{\partial \bar{z}} = \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right) \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right) = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} = \nabla^2$. We take

$$\left(\frac{\partial}{\partial z} \frac{\partial}{\partial \bar{z}} \right)^2 F(z, \bar{z}) = \frac{\partial}{\partial z} \frac{\partial}{\partial \bar{z}} \frac{\partial}{\partial z} \frac{\partial}{\partial \bar{z}} \bar{z} H(z) = \frac{\partial}{\partial z} \frac{\partial H(z)}{\partial \bar{z}} = 0 \implies 0 = \nabla^4 F = \nabla^4 (U + iV)$$

Hence, $\nabla^4 U = 0$ and $\nabla^4 V = 0$.

Problem 4.8 (Series Solution to ODE):

- (i) Find a series solution of the differential equation

$$(1 - x^3)y'' - 6x^2y' - 6xy = 0$$

subject to the boundary conditions $y(0) = 1$, $y'(0) = 0$. [5]

- (ii) Sum the series and verify that the sum satisfies the differential equation.
- [5]

- (iii) If
- $P_n(x)$
- is a Legendre Polynomial, that is a polynomial of degree
- n
- satisfying Legendre's equation

$$\frac{d}{dx} \left((1 - x^2) \frac{dy}{dx} \right) + n(n+1)y = 0$$

find the equation satisfied by $v(x)$ if $y = v(x)P_n(x)$ is a solution of Legendre's equation. [3]

- (iv) Give the general solution of your equation in terms of an explicit integral.
- [2]

- (v) Hence show that any solution of Legendre's equation which is linearly independent of
- $P_n(x)$
- must behave like a logarithm of
- $1 \pm x$
- near
- $x = \mp 1$
- .
- [3]

- (vi) How do those solutions of Legendre's equation which are bounded as
- $|x| \rightarrow \infty$
- behave as
- $|x| \rightarrow \infty$
- ?
- [2]

Answer 4.8.

- (i)
- $-\frac{6x^2}{1-x^3}$
- and
- $\frac{-6x}{1-x^3}$
- are analytic at
- $x = 0$
- and so
- $x = 0$
- is an ordinary point, so try series solution of the form
- $y = \sum_{n=0}^{\infty} a_n x^n$
- about
- $x = 0$
- .

$$\sum_{n=0}^{\infty} a_n n(n-1)x^{n-2} - \sum_{n=0}^{\infty} a_n n(n-1)x^{n+1} - 6 \sum_{n=0}^{\infty} a_n n x^{n+1} - 6 \sum_{n=0}^{\infty} a_n x^{n+1} = 0 \implies a_{n+3} = a_n$$

Then $y = a_0(1 + x^3 + x^6 + \dots) + a_1(x + x^4 + x^7 + \dots)$. Since $y(0) = 1$ and $y'(0) = 0$, we have $a_0 = 1$ and $a_1 = 0$. We have

$$y = a_0 + a_3x^3 + a_6x^6 + a_9x^9 + \dots = a_0(1 + x^3 + x^6 + x^9 + \dots) = \frac{a_0}{1 - x^3}$$

- (ii) We can then explicitly demonstrate it is a solution:

$$(1 - x^3) \frac{6a_0x(1 - x^3) + 18a_0x^4}{(1 - x^3)^3} - 6x^2 \frac{3a_0x^2}{(1 - x^3)^2} - 6x \frac{a_0}{1 - x^3} = 0$$

- (iii) Since
- $y = v(x)P_n(x)$
- is a solution of Legendre's equation,

$$0 = \frac{d}{dx} \left((1 - x^2) \frac{d}{dx} v(x)P_n(x) \right) + n(n+1)v(x)P_n(x) = -2xv'P_n + (1 - x^2)v''P_n + 2(1 - x^2)v'P'_n - 2xvP'_n$$

- (iv) But
- P_n
- is a solution, i.e.
- $0 = \frac{d}{dx}((1 - x^2)P'_n) + n(n+1)P_n = -2xP'_n + (1 - x^2)P''_n + n(n+1)P_n$
- . We thus have

$$\frac{v''}{v'} = \frac{2x}{1 - x^2} - \frac{2P'_n}{P_n} \implies v(x) = A \int^x \frac{1}{(1 - t^2)P_n^2(t)} dt \implies y(x) = AP_n(x) \int^x \frac{1}{(1 - t^2)P_n^2(t)} dt$$

- (v) Assume
- $P_n(x)$
- 's have no zeroes at
- $x = \pm 1$
- , the integrand can be expanded as partial fractions, two of whom will be of the form
- $\frac{1}{1 \pm x}$
- , which will integrate to
- $\ln(1 \pm x)$
- .

- (vi) These solutions tend to zero as
- $|x| \rightarrow \infty$
- .

Problem 4.9 (Variational Principle):

- (i) Write down the Euler-Lagrange equations governing the stationary values of the functional

$$I[y(x)] = \int_a^b F(y, y', x) dx$$

among functions whose endpoint values where $y(a)$ and $y(b)$ are fixed. [2]

- (ii) Derive first integrals of the Euler-Lagrange equations in the cases

(a) the integrand F has no explicit dependence on y , $F = F(y', x)$, [1]

(b) the integrand F has no explicit dependence on x , $F = F(y, y')$. [3]

- (iii) Suppose

$$F = y\sqrt{1 + (y')^2} - \lambda y$$

obtain a first integral. [2]

- (iv) If $y' = \tan \psi$, and assuming that a solution exists for $y > 0$ with a maximum at which $\psi = 0$, $y = y_0$ and $y_0 > 0$, find an expression for λ in terms of ψ , y , y_0 with $y_0 > y$. [4]

Hence show that for solutions of this type $\lambda > 1$. [2]

- (v) Show that if $\psi = \alpha$ at $y = y_1$, where $y_0 > y_1$, then for $y_0 > y > y_1$, [6]

$$\sin^2(\psi/2) = \frac{y_1}{y} \frac{y_0 - y}{y_0 - y_1} \sin^2(\alpha/2)$$

Answer 4.9.

- (i) The functional I is stationary if the integrand f satisfies the Euler-Lagrange equations is $\frac{\partial F}{\partial y} - \frac{d}{dx} \frac{\partial F}{\partial y'} = 0$.

- (ii) (a) If $F = F(y', x)$, $\frac{\partial F}{\partial y} = 0$, then $\frac{d}{dx} \frac{\partial F}{\partial y'} = 0$ from Euler-Lagrange, and so $\frac{\partial F}{\partial y'}$ is a constant.

- (b) If $F = F(y, y')$, then $\frac{\partial F}{\partial x} = 0$. By chain rule,

$$\frac{dF}{dx} = \frac{\partial F}{\partial x} + \frac{\partial F}{\partial y} y' + \frac{\partial F}{\partial y'} y'' = 0 + \frac{d}{dx} \frac{\partial F}{\partial y'} y' \implies \frac{d}{dx} \left(F - \frac{\partial F}{\partial y'} y' \right) = 0$$

Hence, $F - \frac{\partial F}{\partial y'} y'$ is a constant.

- (iii) F has no explicit dependence on x , so by part (ii)(b), for some constant A , we have

$$A = \frac{yy'^2}{\sqrt{1 + y'^2}} + y\sqrt{1 + y'^2} - \lambda y = \frac{y}{\sqrt{1 + y'^2}} - \lambda y$$

- (iv) If $y' = \tan \psi$, then $y(\cos \psi - \lambda) = A$. But $y(\psi = 0) = y_0$, and so $A = y_0(1 - \lambda)$, then

$$\lambda = 1 + \frac{y(1 - \cos \psi)}{y_0 - y} > 1$$

where $y_0 - y > 0$ and $y > 0$ given, and that $\cos \psi \leq 1$.

- (v) $\psi(y = y_1) = \alpha$. We have

$$\lambda = 1 + \frac{y(1 - \cos \psi)}{y_0 - y} = 1 + \frac{y_1(1 - \cos \alpha)}{y_0 - y_1} \implies \frac{y_1}{y} \frac{y_0 - y}{y_0 - y_1} (1 - \cos \alpha) = 1 - \cos \psi = \sin^2(\psi/2)$$

Then use half-angle trick to get desired result.

Problem 4.10 (Rayleigh-Ritz Method): The vertical displacement of the skin of a drum with circular cross section and radius a satisfies

$$\nabla^2 u - \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} = 0$$

- (i) If $u = e^{i\omega t} R(r)$, where r, θ are plane polar coordinates, find an ordinary differential equation satisfied by $R(r)$ and show that it is in self-adjoint form with a certain weight function which should be specified. You may assume that in plane polar coordinates [4]

$$\nabla^2 u = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2}$$

- (ii) Show that the boundary condition $u = 0$ at $r = a$ defines an eigenfunction problem, with real and positive eigenvalues λ such that the frequencies $\nu = \frac{\omega}{2\pi}$ are real. [4]
- (iii) Show that the eigenfunctions with distinct eigenvalues are orthogonal with respect to a suitable inner product which should be specified. [4]
- (iv) Obtain an upper bound for the lowest non-vanishing frequency ν , using the trial function $f(r) = (1 - (r/a)^p)$ and picking the constant p so as to give the best possible bound. [8]

Answer 4.10.

- (i) Use the suggested substitution to get the ODE $-(rR')' = \frac{\omega^2}{c^2} rR$. This is of Sturm-Liouville (SL) equation form with weight function r .

$$-\frac{d}{dr} \left(r \frac{dR}{dr} \right) + 0 = \frac{\omega^2}{c^2} rR$$

To show self-adjoint for some eigenfunctions u and v that remain finite $\forall r \in [0, a]$:

$$\langle u | \mathcal{L} v \rangle = \int_0^a -u^* \frac{d}{dr} \left(r \frac{dv}{dr} \right) dr = \left[-u^* r \frac{dv}{dr} \right]_0^a + \int_0^a \frac{du^*}{dr} r \frac{dv}{dr} dr = \left[r \left(\frac{du^*}{dr} v - \frac{dv}{dr} u^* \right) \right]_0^a + \int_0^a \frac{d}{dr} \left(r \frac{du^*}{dr} \right) v dr$$

Since the boundary condition is $v, u = 0$ at $r = a$, the boundary term is zero. Hence, $\langle u | \mathcal{L} v \rangle = \langle \mathcal{L} u | v \rangle$.

- (ii) The LHS gives $\lambda_v \langle u | v \rangle_r$ (where this is an inner product with respect to the weight function r) while the RHS gives $\lambda_u^* \langle u | v \rangle_r$. The eigenvalue, as found in part (i) is $\frac{\omega^2}{c^2} = \frac{4\pi^2 \nu^2}{c^2}$. Then,

$$\frac{4\pi^2}{c^2} ((\nu_u^*)^2 - (\nu_v)^2) \int_0^a y_n^* r y_m dr = 0$$

For $n = m$, $\langle y_n | y_n \rangle_r \neq 0$, hence $\nu_n = \nu_n^*$, i.e. the frequencies are real.

- (iii) But for $n \neq m$, $\nu_n \neq \nu_m$, and so $\langle y_n | y_m \rangle_r = 0$, thus orthogonal (with respect to the weight function r) functions have distinct eigenvalues.

- (iv) The eigenfunctions of \mathcal{L} are complete, so we can write $y(x) = \sum_{n=0}^{\infty} c_n y_n(x)$. The Rayleigh quotient will be

$$\Lambda[y(x)] = \frac{\langle y | \mathcal{L} y \rangle}{\langle y | y \rangle_w} = \frac{\sum_{n=0}^{\infty} |c_n|^2 \lambda_n}{\sum_{n=0}^{\infty} |c_n|^2}$$

For Λ to be stationary, we require $\frac{\partial \Lambda}{\partial c_p} = 0 \forall p$. Then the minimum value is the lowest eigenvalue. With the trial function f :

$$\langle f | \mathcal{L} f \rangle = \int_0^a \left(1 - \left(\frac{r}{a} \right)^p \right) \left(-\frac{d}{dr} r \frac{d}{dr} \left(1 - \frac{r^p}{a^p} \right) \right) dr = \frac{p^2}{a^p} \int_0^a r^{p-1} \left(1 - \frac{r^p}{a^p} \right) dr = \frac{p}{2}$$

$$\langle f | f \rangle_r = \int_0^a r \left(1 - \left(\frac{r}{a} \right)^p \right)^2 dr = \int_0^a r dr - \frac{2}{a^p} \int_0^a r^{p+1} dr + \frac{1}{a^{2p}} \int_0^a r^{2p+1} dr = \frac{p^2 a^2}{2(p+2)(p+1)}$$

hence, $\Lambda[y_{\text{trial}}] = \frac{(p+2)(p+1)2p}{2p^2 a^2} > 0 \forall p$. Extremizing gives $\frac{\partial \Lambda}{\partial p} = 0 \implies p = \sqrt{2}$.

$$\Lambda[y_{\text{trial}}(p = \sqrt{2})] = \frac{1}{a^2} \left(1 + \frac{2}{\sqrt{2}} \right) \left(1 + \frac{1}{\sqrt{2}} \right) \implies \nu = \frac{c}{a} \frac{1}{2\pi} \sqrt{2 + \frac{3}{\sqrt{2}}}$$

Any possible value of Λ is an overestimate of the minimum value.

4.2 Paper 2

Problem 4.11 (Sturm-Liouville): Consider the equation

$$(1-x^2)\frac{d^2y}{dx^2} - x\frac{dy}{dx} + n^2y = 0 \quad (*)$$

on the domain $-1 \leq x \leq 1$ with n an integer. We require y and its derivative to be bounded at $x = \pm 1$.

(i) Put this equation into Sturm-Liouville form and identify the weight function. [3]

Let y_n and y_m be two eigenfunctions of (*) with associated eigenvalues n^2 and m^2 .

(ii) (a) State and prove the orthogonality property for these eigenfunctions, assuming $n \neq m$. [4]

(b) Go on to prove that [3]

$$\int_{-1}^1 \frac{dy_n}{dx} \frac{dy_m}{dx} \sqrt{1-x^2} dx = 0$$

(iii) (a) Demonstrate that $y_n = \cos[n \cos^{-1} x]$ is an eigenfunction of the DE. [3]

(b) Show, using de Moivre's theorem or otherwise, that y_n is a polynomial in x of degree n . [4]

(c) Compute the first three polynomials, y_0 , y_1 , and y_2 , and verify that they are orthogonal. [3]

Answer 4.11.

(i) Multiply (*) by an integration factor $\mu(x)$ to cast to Sturm-Liouville form

$$\mathcal{L}' = \frac{d}{dx} \left(p(x) \frac{d}{dx} \right), \quad \frac{1}{p(x)} \frac{dp(x)}{dx} = \frac{-x}{1-x^2} \implies p(x) \propto (1-x^2)^{1/2} \implies \mu(x) = \frac{1}{\sqrt{1-x^2}}$$

This is also the weight function. Hence, $-\frac{d}{dx}(\sqrt{1-x^2} \frac{dy}{dx}) = \frac{1}{\sqrt{1-x^2}} n^2 y$.

(a) The orthogonality property should be $\langle y_n | y_m \rangle_w = 0$ for $n \neq m$ and the weight function $w(x)$ found in part (i). Given that y and y' are bounded at $x = \pm 1$, the boundary terms vanish:

$$\begin{aligned} \langle y_n | \mathcal{L}' y_m \rangle &= - \int_{-1}^1 y_n^* \frac{d}{dx} \left(\sqrt{1-x^2} \frac{dy_m}{dx} \right) \\ &= \left[-y_n^* \sqrt{1-x^2} \frac{dy_m}{dx} \right]_{-1}^1 + \int_{-1}^1 \frac{dy_n^*}{dx} \sqrt{1-x^2} \frac{dy_m}{dx} dx \\ &= \left[y_n^* \sqrt{1-x^2} \frac{dy_m}{dx} - y_m \frac{dy_n^*}{dx} \sqrt{1-x^2} \right]_{-1}^1 - \int_{-1}^1 y_m \frac{d}{dx} \left(\sqrt{1-x^2} \frac{dy_n^*}{dx} \right) dx \end{aligned}$$

So, $\langle y_n | \mathcal{L}' y_m \rangle = \langle \mathcal{L}' y_n | y_m \rangle$. LHS and RHS respectively give $m^2 \langle y_n | y_m \rangle_w$, $n^2 \langle y_n | y_m \rangle_w$, so $(m^2 - n^2) \langle y_n | y_m \rangle_w = 0$. So for $m \neq n$, y_m , y_n are orthogonal w.r.t. the inner product.

(b) Using integration by parts for $\langle \mathcal{L}' y_n | y_m \rangle$ and use the boundary condition.

$$0 = n^2 \langle y_n | y_m \rangle = \langle \mathcal{L}' y_n | y_m \rangle = \left[y_m \frac{dy_n}{dx} \sqrt{1-x^2} \right]_{-1}^1 - \int_{-1}^1 \sqrt{1-x^2} \frac{dy_n}{dx} \frac{dy_m}{dx} dx$$

(c) (a) To show $(1-x^2) \frac{d^2 y_n}{dx^2} - x \frac{dy_n}{dx} = -n^2 y_n$, where

$$\frac{dy_n}{dx} = -\sin(n \cos^{-1} x) \frac{n}{\sqrt{1-x^2}}, \quad \frac{d^2 y_n}{dx^2} = -\frac{n^2}{1-x^2} \cos(n \cos^{-1} x) - \frac{nx}{(1-x^2)^{3/2}} \sin(n \cos^{-1} x)$$

(b) By de Moivre's theorem, we have $y_n = \cos(n \cos^{-1}(x)) = \operatorname{Re}[e^{in \cos^{-1}(x)}] = \operatorname{Re}[(x \pm i\sqrt{1-x^2})^n]$. Evaluate this by binomial expansion. Since we are only taking the real part, $\sqrt{1-x^2}$ must be raised to an even power, hence we will only get positive integer power, and hence y_n is indeed a polynomial of degree n .

(c) $y_0 = 1$, $y_1 = x$, $y_2 = \cos(2 \cos^{-1} x) = \operatorname{Re}[x^2 \pm 2i\sqrt{1-x^2} - 1 + x^2] = 2x^2 - 1$.

$$\langle y_0 | y_1 \rangle_w = \int_{-1}^1 x dx = 0, \quad \langle y_1 | y_2 \rangle_w = \int_{-1}^1 \frac{x(2x^2 - 1)}{\sqrt{1-x^2}} dx = 0$$

since for both of them, the integrands are odd, and the integration limits is symmetric.

$$\langle y_0 | y_2 \rangle_w = \int_{-1}^1 \frac{2x^2 - 1}{\sqrt{1-x^2}} dx = \int_0^\pi \frac{2 \cos^2 \theta - 1}{\sin \theta} (-\sin \theta) d\theta = \int_0^\pi \cos 2\theta d\theta = 0$$

where we used the substitution $x = \cos \theta$. Hence, $\{y_0, y_1, y_2\}$ are orthogonal.

Problem 4.12 (Laplace's Equations): The free decay of the Earth's axisymmetric magnetic field can be modelled by the equations

$$\nabla^2 B + sB = 0 \text{ when } r < R$$

$$\nabla^2 B = 0 \text{ when } r > R$$

Here R is the radius of the Earth's spherical core and s is the decay rate. We require that $B \rightarrow 0$ as $r \rightarrow \infty$, and that B and $\frac{\partial B}{\partial r}$ are continuous at $r = R$.

Hint: The axisymmetric spherical Laplacian is

$$\nabla^2 B = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial B}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial B}{\partial \theta} \right)$$

(i) Using separation of variables, find an expression for B as an expansion in Legendre polynomials $P_l(\cos \theta)$ when $r > R$. [6]

Hint: Recall that

$$\frac{d}{d\mu} \left[(1 - \mu^2) \frac{dy}{d\mu} \right] + \lambda y = 0$$

only admits regular solutions at $\mu = \pm 1$ when $\lambda = l(l+1)$ and these are the $P_l(\mu)$.

(ii) Show that when $r < R$, B can be expressed as

$$B(r, \theta) = \sum_{l=0}^{\infty} B_l f_l(s^{1/2} r) P_l(\cos \theta)$$

where B_l is a constant and $f_l(s^{1/2} r)$ satisfies the equation [6]

$$r^2 \frac{d^2 f_l}{dr^2} + 2r \frac{df_l}{dr} + (sr^2 - l(l+1)) f_l = 0$$

Hint: Note that the second solution to this equation is singular at $r = 0$ but f_l is bounded at $r = 0$.

(iii) Impose the two boundary conditions at $r = R$ to obtain the following eigenvalue equation

$$f_l(s^{1/2} R) = 0$$

using the identity $xf'_{\nu+1}(x) + (\nu+2)f_{\nu+1}(x) = xf_{\nu}(x)$. [6]

- (iv) The smallest zero of $f_l(x)$ is π . Hence write down an expression for the smallest value of s in terms of R . [2]

Answer 4.12.

- (i) Use separation of variables: $B(r > R, \theta) = R(r > R)\Theta(\theta)$:

$$\frac{1}{R} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = - \frac{1}{r^2 \sin \theta} \frac{1}{\Theta} \frac{d}{d\theta} \sin \theta \frac{d\Theta}{d\theta} = \frac{\lambda}{r^2}$$

for some constant λ . The angular part gives

$$\lambda \Theta = - \frac{1}{\sin \theta} \frac{d\Theta}{d\theta} = - \frac{1}{\sqrt{1-x^2}} (-\sqrt{1-x^2}) \frac{d}{dx} \left(-(\sqrt{1-x^2})^2 \frac{d\Theta}{dx} \right)$$

where we substitute $x = \cos \theta$. This result is identical to the hint with $x = \mu$ and $y = \Theta$. So at $x = \pm 1 \implies \theta = 0, \pi$, $\Theta(x) = P_l(x)$ with $\lambda = l(l+1)$. The radial part gives

$$\lambda R = \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = 2rR' + r^2 R''$$

Try $R = r^k$, then $k(k+1) = \lambda = l(l+1) \implies k = l, -(l+1)$. Hence, $R(r) = d_l r^l + c_l r^{-(l+1)}$. Fitting them together

$$B(r, \theta) = \sum_{l=0}^{\infty} (c_l r^{-(l+1)} + d_l r^l) P_l(\cos \theta)$$

But $\lim_{r \rightarrow \infty} B(r, \theta) = 0 \implies d_l = 0 \forall l$. Hence, $B(r > R, \theta) = \sum_{l=0}^{\infty} \frac{c_l}{r^{-(l+1)}} P_l(\cos \theta)$.

- (ii) With the given solution $B(r < R, \theta) = \sum_{l=0}^{\infty} B_l f_l(s^{1/2}r) P_l(\cos \theta) \implies \frac{dB(r < R, \theta)}{dr} = \sum_{l=0}^{\infty} B_l P_l(\cos \theta) \frac{df_l}{dr}$, then we proceed to verify that it is indeed a solution:

$$\begin{aligned} 0 &= \nabla^2 B + sB \\ &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial B}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial B}{\partial \theta} \right) + sB \\ &= \sum_{l=0}^{\infty} \frac{B_l}{r^2} P_l(\cos \theta) \left[2r \frac{df_l}{dr} + r^2 \frac{d^2 f_l}{dr^2} + -\lambda f_l + r^2 s f_l \right] \end{aligned}$$

where we used again the hint in part (i). Hence this requires $f_l(s^{1/2}r)$ to satisfy the given equation.

- (iii) The piecewise solutions are

$$\begin{aligned} B(r < R, \theta) &= \sum_{l=0}^{\infty} B_l f_l(s^{1/2}r) P_l(\cos \theta) \implies \frac{dB}{dr}(r < R, \theta) = \sum_{l=0}^{\infty} B_l s^{1/2} f'_l(s^{1/2}r) P_l(\cos \theta) \\ B(r > R, \theta) &= \sum_{l=0}^{\infty} \frac{c_l}{r^{l+1}} P_l(\cos \theta) \implies \frac{dB}{dr}(r > R, \theta) = - \sum_{l=0}^{\infty} \frac{c_l(l+1)}{r^{l+2}} P_l(\cos \theta) \end{aligned}$$

where $f'_l = \frac{df_l}{d(s^{1/2}r)}$. The boundary conditions are

- B continuous at $r = R$: $c_l = B_l R^{l+2} f_l \forall l$
- $\frac{\partial B}{\partial r}$ continuous at $r = R$: $c_l(l+1) = -B_l R^{l+2} s^{1/2} f'_l$.

Together they give $B_l R^{l+2}(l+1) f_l = -B_l R^{l+2} s^{1/2} f'_l \forall l$. For the given identity, substitute $x = s^{1/2}R$ and $l = \nu + 1$, then we have

$$s^{1/2} R f'_l(x) + (l+1) f_l(x) = s^{1/2} R f_{l-1}(x) \implies s^{1/2} R f_{l-1}(s^{1/2}R) = 0$$

- (iv) We must have $s^{1/2}R = \pi \implies s = \frac{\pi^2}{R^2}$.

Problem 4.13 (Green's Functions):

- (i) (a) Verify that

$$H(\mathbf{r}, \mathbf{r}') = -\frac{1}{4\pi|\mathbf{r} - \mathbf{r}'|}$$

is a solution to the equation

$$\nabla^2 H = \delta(\mathbf{r} - \mathbf{r}')$$

in three-dimensions. [7]

- (b) Hence write down the general solution for the gravitational potential
- Φ
- satisfying Poisson's equation

$$\nabla^2 \Phi = 4\pi G\rho$$

where G is the gravitational constant and $\rho = \rho(\mathbf{r})$ is a general mass distribution. What is the potential Φ associated with the point mass $\rho = M\delta(\mathbf{r})$? [3]

- (ii) Consider the gravitational potential associated with a spherical planet of radius
- R
- and constant mass density
- ρ
- .

- (a) Show that the Green's function of the Laplacian may be written as

$$H(\mathbf{r}, \mathbf{r}') = -\frac{1}{4\pi\sqrt{r'^2 - 2r'r\cos\theta' + r^2}}$$

where θ' is the angle between \mathbf{r} and \mathbf{r}' , $r = |\mathbf{r}|$; $r' = |\mathbf{r}'|$. [3]

- (b) Insert this expression in the Green's function solution for
- Φ
- to obtain
- [4]

$$\Phi = -2\pi G\rho \int_0^R \frac{r'}{r} (r' + r - |r' - r|) dr'$$

Hint: Use spherical coordinates where the z' axis points in the same direction as \mathbf{r} .

- (c) Perform the final
- r'
- integration to obtain the gravitational potential for
- $r < R$
- .
- [3]

Answer 4.13.

- (i) (a) Let
- $\mathbf{l} = \mathbf{r} - \mathbf{r}'$
- , then
- $H = H(l)$
- is spherically symmetric in 3D. Integrate over a sphere of radius
- l
- centred on
- \mathbf{r}
- , i.e.
- $S = \{|\mathbf{r}| \leq l\}$
- , and use Divergence Theorem:

$$1 = \int_S \delta(\mathbf{l}) dV = \int_S \nabla^2 H dV = \int_{\partial S} \nabla H \cdot d\mathbf{S} = \int_0^{2\pi} d\phi \int_0^\pi \frac{dH}{dl} \sin\theta l^2 d\theta = 4\pi l^2 \frac{dH}{dl}$$

This gives $H(l) = -\frac{1}{4\pi l} + C$, where C is a constant of integration, which we will set to zero.

- (b)
- $\frac{\Phi}{4\pi GM} = -\frac{1}{4\pi|\mathbf{r}-\mathbf{r}'|} \implies \Phi(\mathbf{r}-\mathbf{r}') = -\frac{GM}{|\mathbf{r}-\mathbf{r}'|}$
- .

- (ii) (a)
- $l = \sqrt{(\mathbf{r} - \mathbf{r}') \cdot (\mathbf{r} - \mathbf{r}')} = \sqrt{r^2 + r'^2 - 2rr'\cos\theta}$
- .

- (b) The potential
- Φ
- is

$$-G\rho \int_0^{2\pi} d\phi \int_0^{\pi/2} \int_0^R \frac{r^2 dr \sin\theta d\theta}{\sqrt{r^2 + r'^2 - 2rr'\cos\theta'}} = -2\pi G\rho \int_0^R [r^{-1}r'^{-1}\sqrt{r^2 + r'^2 - 2rr'\cos\theta'}]_0^\pi r'^2 dr'$$

where the integrand becomes $\frac{r'}{r}[\sqrt{r^2 + r'^2 + 2rr'} - \sqrt{r^2 + r'^2 - 2rr'}]dr'$. In the brackets, the first term is trivially $r + r'$ but the second is $|r - r'|$.

- (c) We have to split the integration into two regimes:

$$\frac{\Phi}{-2\pi G\rho} = \int_{r'=0}^r \frac{r'}{r} (r+r'-|r-r'|) dr' + \int_{r'=r}^R \frac{r'}{r} (r+r'-|r-r'|) dr' = \int_{r_0}^r \frac{2r'^2}{r} dr' + \int_r^R 2r' dr' = \frac{3R^2 - r^2}{3}$$

Problem 4.14 (Contour Integration):

- (i) Use Cauchy's residue theorem to evaluate the complex integral

$$\int_C \frac{f(z)}{z - z_0} dz$$

where C is a closed contour in the complex plane, the point z_0 lies within the region enclosed by C , and f is analytic in this region. [2]

- (ii) (a) Consider the contour integral

$$\int_C \frac{e^{iz}}{a^2 + z^2} dz \quad (*)$$

where $a > 0$ and C is the closed contour consisting of the real axis between $-R$ and R and a semicircle in the upper half plane of radius R connecting the two points $(-R, 0)$ and $(R, 0)$. The sense of the integration path is counterclockwise and $R > a$.

Locate the integrand's singularities and then evaluate the integral with the residue theorem. [5]

- (b) By considering the real part of (*) deduce that
- [3]

$$\int_{-\infty}^{\infty} \frac{\cos x}{a^2 + x^2} dx = \frac{\pi}{a} e^{-a}$$

- (iii) Consider the real integral

$$\int_0^{2\pi} \frac{1}{1 + \epsilon \cos \theta} d\theta \quad (**)$$

for $-1 < \epsilon < 1$.

- (a) Turn this integral into a closed contour integral and specify the integration path. [2]
 (b) Show that the integrand possesses two simple poles in the complex z plane

$$z_{\pm} = \frac{-1 \pm \sqrt{1 - \epsilon^2}}{\epsilon}$$

and that one is enclosed by the integration path. [5]

- (c) Use the residue theorem to calculate (**).
- [3]

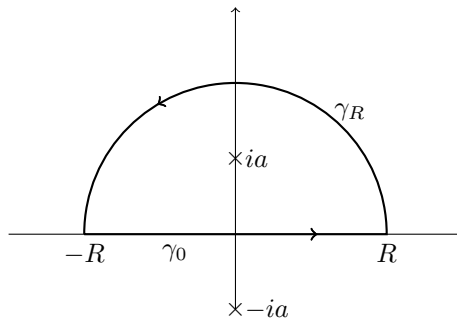
Answer 4.14.

- (i) The residue of a function at a point $z = z_0$ is the coefficient of $\frac{1}{z - z_0}$ in the Laurent expansion about $z = z_0$, then by Cauchy's residue theorem, we have

$$\int_C \frac{f(z)}{z - z_0} dz = 2\pi i \operatorname{res}_{z=z_0} f(z)$$

- (ii) (a) The integrand has first order poles at $z = \pm ia$ and an essential pole at $z = -\infty$. Only the pole $z = +ia$ is enclosed, so by part (i),

$$\int_C \frac{e^{iz}}{a^2 + z^2} dz = 2\pi i \operatorname{res}_{z=ia} \frac{e^{iz}}{z^2 + a^2} = 2\pi i \frac{e^{-a}}{2ia} = \frac{\pi}{a} e^{-a}$$



(b) We have

$$\int_{\gamma_R} \frac{e^{iz}}{a^2 + z^2} dz = \int_0^\pi \frac{e^{iR \cos \theta - R \sin \theta}}{a^2 + R^2 e^{2i\theta}} iR e^{i\theta} d\theta$$

which $\rightarrow 0$ as $R \rightarrow \infty$. Hence, $\int_C \frac{e^{iz}}{a^2 + z^2} dz \rightarrow \int_{-\infty}^\infty \frac{e^{ix}}{a^2 + x^2} dx$. Hence, looking at the real part,

$$\int_{-\infty}^\infty \frac{\cos x}{a^2 + x^2} dx = \frac{\pi}{a} e^{-a}$$

(iii) (a) Write (**) as

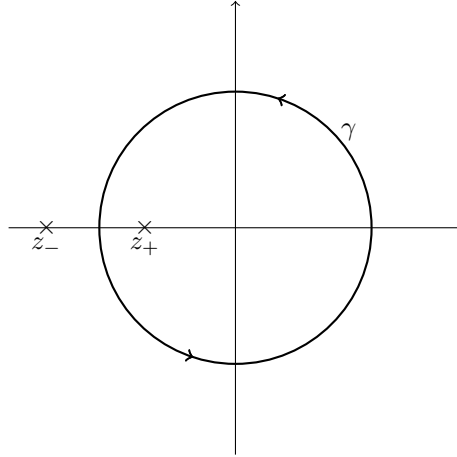
$$\int_C \frac{1}{1 + \epsilon(0.5)(z + z^{-1})} \frac{dz}{iz} = \int_C \frac{-2idz}{\epsilon z^2 + 2z + \epsilon}$$

where C is a unit circle in the complex plane, traversing in the clockwise sense.

(b) The poles of the integrand are

$$\epsilon z^2 + 2z + \epsilon = 0 \implies z_{\pm} = \frac{-1 \pm \sqrt{1 - \epsilon^2}}{\epsilon^2}$$

These are first order zeros for the denominator, hence first order poles of the integrand. We have $\epsilon^2 < 1$, so $\sqrt{1 - \epsilon^2} \in \mathbb{R}$ and hence $z_- < -1$ and $z_+ < 0$. z_+ is enclosed in the unit circle even as $\epsilon \rightarrow 0$.



(c) The residue of z_+ is

$$\text{res}_{z=z_+} \frac{-2i}{\epsilon(z - z_+)(z - z_-)} = \lim_{z \rightarrow z_+} \frac{-2i}{\epsilon(z - z_-)} = \frac{-2i}{\epsilon(z_+ - z_-)}$$

By residue theorem,

$$\int_0^{2\pi} \frac{1}{1 + \epsilon \cos \theta} d\theta = 2\pi i \frac{-2i}{\epsilon(z_+ - z_-)} = \frac{2\pi}{\sqrt{1 - \epsilon^2}}$$

Problem 4.15 (Transform Methods):

- (i) Calculate the Fourier transform of the triangle function [5]

$$f(x) = \begin{cases} 1 - |x| & |x| < 1 \\ 0 & \text{otherwise} \end{cases} \quad (*)$$

The Fourier transform with respect to x of a function $u(x, t)$ is given by

$$\tilde{u}(k, t) = \int_{-\infty}^{\infty} u(x, t) e^{-ikx} dx$$

- (ii) Using the formal limit definition of a derivative, derive expressions for the Fourier transforms with respect to x of $\frac{\partial u}{\partial t}$ and $\frac{\partial u}{\partial x}$. [Hint: You may assume that $u \rightarrow 0$ as $|x| \rightarrow \infty$.] [5]
- (iii) If $u(x, t)$ satisfies

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$$

write down the ordinary differential equation obeyed by the Fourier transform $\tilde{u}(k, t)$ of $u(x, t)$. [4]

- (iv) Find $u(x, t)$ subject to the following initial conditions at $t = 0$

$$u = f(x), \quad \frac{\partial u}{\partial t} = 0$$

where $f(x)$ is the triangle function. Assume again that $u \rightarrow 0$ as $|x| \rightarrow \infty$. [6]

Answer 4.15.

- (i) The Fourier transform of $(*)$ is

$$\tilde{f} = \int_{-1}^1 (1 - |x|) e^{-ikx} dx = 2 \int_0^1 (1 - x) \cos kx dx = \text{sinc}^2(k/2)$$

- (ii) Using limits,

$$\mathcal{F} \left[\frac{\partial u}{\partial t} \right] = \int_{-\infty}^{\infty} \lim_{\Delta t \rightarrow 0} \frac{u(x, t + \Delta t) - u(x, t)}{\Delta t} e^{-ikx} dx = \lim_{\Delta t \rightarrow 0} \frac{\tilde{u}(k, t + \Delta t) - \tilde{u}(k, t)}{\Delta t} = \frac{\partial \tilde{u}}{\partial t}$$

$$\mathcal{F} \left[\frac{\partial u}{\partial x} \right] = \int_{-\infty}^{\infty} \lim_{\Delta x \rightarrow 0} \frac{u(x + \Delta x, t) - u(x, t)}{\Delta x} e^{-ikx} dx = [u e^{-ikx}]_{-\infty}^{\infty} + ik \int_{-\infty}^{\infty} u e^{-ikx} dx$$

which is $ik\tilde{u}$ if we assume $u \rightarrow 0$ as $|x| \rightarrow \infty$.

- (iii) The ODE is $\frac{\partial^2 \tilde{u}}{\partial t^2} = -k^2 c^2 \tilde{u}$ for constant u .
- (iv) The solution is $\tilde{u}(k, t) = A(k) e^{ikct} + B(k) e^{-ikct}$. From $\frac{\partial \tilde{u}}{\partial t} = 0 \implies A(k) = B(k)$ and $\tilde{u} = \tilde{f}(x) = A + B = 2A \implies \mathcal{F}^{-1}[A] = \frac{1}{2} f(x)$. Writing the solution u using inverse Fourier transform,

$$u(x, t) = \int_{-\infty}^{\infty} A(k) e^{i(ct+x)k} + B(k) e^{i(-ct+x)k} dk = \mathcal{F}^{-1}[A] + \mathcal{F}^{-1}[B] = \frac{1}{2} f(x+ct) + \frac{1}{2} f(x-ct)$$

From part (i), $f(x)$ is a triangle function, so the solution $u(x, t)$ consist of two triangular functions with half the height, one displaced to the left by a distance ct and the another to the right by ct .

Problem 4.16 (Tensors):

- (i) State the transformation rules for tensors of rank one and two. [2]
- (ii) If u_i and v_j are rank one tensors (i.e. vectors), show that $u_i v_j$ is a rank two tensor. [2]
- (iii) Consider a rank two tensor B_{ij} . Let S_{ij} and A_{ij} be symmetric and anti-symmetric rank two tensors where $B_{ij} = S_{ij} + A_{ij}$. Write S_{ij} and A_{ij} in terms of the components of B_{ij} . [2]
- (iv) Show that if R_{ij} is a symmetric rank two tensor, then

$$R_{ij}B_{ij} = R_{ij}S_{ij}$$

where S_{ij} is the symmetric part of B_{ij} defined above. [2]

- (v) Show that the tensor product of a rank two tensor with a vector is a rank three tensor. [2]
- (vi) Let S_{ijk} be a rank three tensor. A contraction of S_{ijk} is defined as

$$C_k = \sum_i S_{iik}$$

Show that C_k is a vector. [4]

- (vii) Using suffix notation and the Levi-Civita pseudo-tensor, ϵ_{ijk} , prove the following vector identity [6]

$$\nabla \times (\mathbf{A} \times \mathbf{B}) = \mathbf{A} \nabla \cdot \mathbf{B} + (\mathbf{B} \cdot \nabla) \mathbf{A} - \mathbf{B} \nabla \cdot \mathbf{A} - (\mathbf{A} \cdot \nabla) \mathbf{B}$$

Answer 4.16.

- (i) Transformation rule for tensor of rank one: $u'_i = L_{ij}u_j$ where L_{ij} is an element of an orthogonal transformation ($LL^T = I$), relating two bases systems.

Transformation rule for tensor of rank two: $B'_{ij} = L_{ia}L_{jb}B_{ab}$.

- (ii) $(u_i v_j)' = L_{i\alpha}u_\alpha L_{j\beta}v_\beta = L_{i\alpha}L_{j\beta}(u_\alpha v_\beta)$, so it is rank-two tensor.
- (iii) $S_{ij} = \frac{1}{2}(B_{ij} + B_{ji})$ and $A_{ij} = \frac{1}{2}(B_{ij} - B_{ji})$.
- (iv) We note the contraction of a symmetric and anti-symmetric tensor gives:

$$R_{ij}A_{ij} = -R_{ij}A_{ji} = -R_{ij}A_{ij} \implies R_{ij}A_{ij} = 0$$

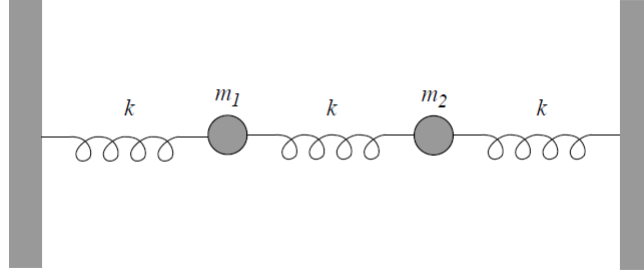
where we used the definition of anti-symmetric tensor, followed by relabelling the dummy index.

- (v) $(A_{ij}v_k)' = L_{i\alpha}L_{j\beta}A_{\alpha\beta}L_{k\gamma}v_\gamma$, so it is rank-three tensor.
- (vi) $C'_k = S_{iik} = L_{ia}L_{ib}L_{kc}S_{abc} = \delta_{ab}L_{kc}S_{abc} = L_{kc}S_{aac}$, where L is orthogonal, i.e. $LL^T = I$, hence rank-one tensor, i.e. vector.
- (vii) It is obvious both sides is a rank-one tensor.

$$\nabla \times (\mathbf{A} \times \mathbf{B}) = \epsilon_{ijk} \frac{\partial}{\partial x_i} \epsilon_{pqj} A_p B_q \hat{\mathbf{k}} = (\delta_{kp}\delta_{iq} - \delta_{kq}\delta_{ip}) \frac{\partial}{\partial x_i} (A_p B_q) \hat{\mathbf{k}}$$

Expand the derivative by chain rule and expand everything. Finally, realize that $\nabla \cdot \mathbf{V} = \frac{\partial V_i}{\partial x_i}$ and $\mathbf{V} \cdot \nabla = V_i \frac{\partial}{\partial x_i}$ for an arbitrary vector field $\mathbf{V}(\mathbf{x})$.

Problem 4.17 (Normal Modes): Two objects with masses m_1 and m_2 are connected to two rigid walls by three springs with identical spring constants k , as sketched below. Let x_1 and x_2 be the displacements of m_1 and m_2 from their equilibrium positions, respectively. The motion of the objects is confined to the horizontal (x) direction.



- (i) Find the normal modes of oscillation and their associated frequencies. [10]
- (ii) At $t = 0$, the masses are each displaced from their equilibrium position by a distance x_0 and away from each other, then released from a state of rest. Solve for x_1 and x_2 and express them as linear combinations of the normal modes. [5]
- (iii) If the masses are initially at the equilibrium position, but m_2 is given an initial velocity u_0 , while m_1 is initially at rest, solve for x_1 and x_2 . Describe this motion in terms of the normal modes. [5]

Answer 4.17.

(i) The kinetic energy is

$$T = \frac{1}{2}m_1\dot{x}_1^2 + \frac{1}{2}m_2\dot{x}_2^2 = \frac{1}{2} \begin{pmatrix} \dot{x}_1 & \dot{x}_2 \end{pmatrix} \begin{pmatrix} m_1 & 0 \\ 0 & m_2 \end{pmatrix} \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} := \frac{1}{2}\dot{\mathbf{x}}^T \mathcal{T} \dot{\mathbf{x}}$$

and the potential energy is

$$V = \frac{1}{2}kx_1^2 + \frac{1}{2}k(x_1 - x_2)^2 + \frac{1}{2}kx_2^2 = \frac{1}{2} \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} 2k & -k \\ -k & 2k \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} := \frac{1}{2}\mathbf{x}^T \mathcal{V} \mathbf{x}$$

The Lagrangian is $\mathcal{L} = T - V = \frac{1}{2}\dot{\mathbf{x}}^T \mathcal{T} \dot{\mathbf{x}} - \frac{1}{2}\mathbf{x}^T \mathcal{V} \mathbf{x}$ and thus the Euler-Lagrange equation extremizes the Lagrangian to give $0 = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\mathbf{x}}} - \frac{\partial \mathcal{L}}{\partial \mathbf{x}} = \frac{d}{dt} (\mathcal{T} \dot{\mathbf{x}}) + \mathcal{V} \mathbf{x}$. Since T is time-independent, we can look for solutions of the form $\mathbf{x}(t) = \mathbf{A}e^{i\omega t}$:

$$0 = \det(\mathcal{V} - \omega^2 \mathcal{T}) = \det \begin{pmatrix} 2k - \omega^2 m_1 & -k \\ -k & 2k - \omega^2 m_2 \end{pmatrix} = 3k^2 - 2k\omega^2(m_2 + m_1) + \omega^4 m_1 m_2$$

Rearranging gives

$$\omega_{\pm}^2 = k \frac{m_1 + m_2}{m_1 m_2} \pm \frac{k}{m_1 m_2} \sqrt{m_1^2 + m_2^2 - m_1 m_2}$$

Let the ratio of masses be $\alpha = \frac{m_1}{m_2}$, then

$$\frac{m_1}{k} \omega^2 = (\alpha + 1) \pm \sqrt{\alpha^2 - \alpha + 1}, \quad \frac{m_2}{k} \omega^2 = 1 + \alpha^{-1} \pm \sqrt{\alpha^{-2} - \alpha^{-1} + 1}$$

Let the eigenvector be $(a, b)^T$, then the first line of $(\mathcal{V} - \omega^2 \mathcal{T})$ gives

$$(2k - m_1 \omega_+^2)a - kb = 0 \implies b = a(1 - \alpha \pm \sqrt{\alpha^2 - \alpha + 1})$$

The normal modes are the unnormalized eigenvectors are $\mathbf{A}_{\pm} = (1, 1 - \alpha \pm \sqrt{\alpha^2 - \alpha + 1})^T$. Verify that these eigenvectors are orthogonal with respect to \mathcal{T} :

$$\begin{aligned} \langle \mathbf{A}_- | \mathbf{A}_+ \rangle_{\mathcal{T}} &= \begin{pmatrix} 1 & 1 - \alpha - \sqrt{\alpha^2 - \alpha + 1} \end{pmatrix} \begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 - \alpha + \sqrt{\alpha^2 - \alpha + 1} \end{pmatrix} \\ &= \alpha + (1 - \alpha)^2 - (\alpha^2 - \alpha + 1) \\ &= 0 \end{aligned}$$

(ii) The general solution is

$$\mathbf{x}(t) = \operatorname{Re}[c_+ e^{i\omega_+ t}] \left(1 - \alpha - \frac{1}{\sqrt{\alpha^2 - \alpha + 1}}\right) + \operatorname{Re}[c_- e^{i\omega_- t}] \left(1 - \alpha + \frac{1}{\sqrt{\alpha^2 - \alpha + 1}}\right)$$

The initial conditions are $\mathbf{x}(t = 0) = (x_0, -x_0)^T$ and $\dot{\mathbf{x}}(t = 0) = (0, 0)^T$. We exploit orthogonality:

$$\operatorname{Re}[c_{\pm}] = \frac{\langle \mathbf{x}(0) | \mathbf{A}_{\pm} \rangle_{\mathcal{T}}}{\langle \mathbf{A}_{\pm} | \mathbf{A}_{\pm} \rangle_{\mathcal{T}}}, \quad \operatorname{Im}[-\omega_{\pm} c_{\pm}] = \frac{\langle \dot{\mathbf{x}}(0) | \mathbf{A}_{\pm} \rangle_{\mathcal{T}}}{\langle \mathbf{A}_{\pm} | \mathbf{A}_{\pm} \rangle_{\mathcal{T}}}$$

We have $\langle \mathbf{A}_{\pm} | \mathbf{A}_{\pm} \rangle_{\mathcal{T}} = 2m_2(1 - \alpha + \alpha^2 \pm (1 - \alpha)\sqrt{1 - \alpha + \alpha^2})$. From $\dot{\mathbf{x}}(t = 0) = (0, 0)^T$, it is obvious that $c_{\pm} \in \mathbb{R}$, and so

$$c_{\pm} = \frac{x_0(-1 + 2\alpha \mp \sqrt{\alpha^2 - \alpha + 1})}{2(1 - \alpha + \alpha^2 \pm (1 - \alpha)\sqrt{1 - \alpha + \alpha^2})}$$

Hence, the solution is

$$\mathbf{x}(t) = c_+ \cos(\omega_+ t) \left(1 - \alpha - \frac{1}{\sqrt{\alpha^2 - \alpha + 1}}\right) + c_- \cos(\omega_- t) \left(1 - \alpha + \frac{1}{\sqrt{\alpha^2 - \alpha + 1}}\right)$$

(iii) Now, the initial conditions are $\mathbf{x}(t = 0) = (0, 0)^T$ and $\dot{\mathbf{x}}(0) = (0, u_0)^T$. This time, c_{\pm} is purely imaginary.

$$c_{\pm} = \frac{-1}{\omega_{\pm}} \frac{u_0(1 - \alpha \pm \sqrt{\alpha^2 - \alpha + 1})}{2(1 - \alpha + \alpha^2 \pm (1 - \alpha)\sqrt{1 - \alpha + \alpha^2})}$$

Hence the solution is

$$\mathbf{x}(t) = -c_+ \sin(\omega_+ t) \left(1 - \alpha - \frac{1}{\sqrt{\alpha^2 - \alpha + 1}}\right) - c_- \sin(\omega_- t) \left(1 - \alpha + \frac{1}{\sqrt{\alpha^2 - \alpha + 1}}\right)$$

Problem 4.18 (Group Theory):

(i) Consider the set of functions of x

$$\mathcal{F} = \left\{ x, -x, \frac{1}{x}, -\frac{1}{x} \right\}$$

endowed with the operation of functional composition, i.e. if $f, g \in \mathcal{F}$ then $f * g = f(g(x))$.

- (a) Prove that \mathcal{F} is a group. Construct a ‘multiplication’ table as part of your answer. [6]
- (b) What are the subgroups of \mathcal{F} ? [2]
- (c) Prove that \mathcal{F} is isomorphic to the dihedral group D_2 . [2]
- (ii) State Lagrange’s theorem. Subsequently show that if the order of a group is prime then that group has no proper subgroups. [3]
- (iii) Define the order of a group element. Prove that the order of any group element is a factor of the group’s order. [3]
- (iv) Show that if the order of a group is prime then that group is cyclic. [2]
- (v) Suppose \mathcal{G} is a cyclic group but not of prime order. Demonstrate that \mathcal{G} contains a proper cyclic subgroup. [2]

Answer 4.18.

(i) (a) The multiplication table of \mathcal{F} is

	x	$-x$	$1/x$	$-1/x$
x	x	$-x$	$1/x$	$-1/x$
$-x$	$-x$	x	$-1/x$	$1/x$
$1/x$	$1/x$	$-1/x$	x	$-x$
$-1/x$	$-1/x$	$1/x$	$-x$	x

Check the group axioms:

- Closure: yes, see the group table.
- Associativity: functional composition is associative

$$(f * g) * h = (f * g)(h(x)) = f(g)(h(x)) = f((g * h)(x)) = f * (g * h)$$

- Identity: x is the identity;
- Inverse: each element in \mathcal{F} is its own inverse.

(b) The trivial subgroup and \mathcal{F} itself are subgroups of \mathcal{F} . The remaining subgroups are proper: $\{x, -x\}$, $\{x, 1/x\}$.

(c) The dihedral group of a rectangle contains r (rotations by π) and s (reflection) where $r^2 = \text{Id} = s^2$. It also contains rs where $rsrs = rssr^{-1} = \text{Id}$. The map $\Phi : \mathcal{F} \rightarrow D_2$ thus

$$x \mapsto \text{Id}, \quad -x \mapsto r, \quad 1/x \mapsto s, \quad -1/x \mapsto rs$$

This map is bijective (easy to check). It is also a homomorphism, for instance $\Phi(-1/x) = \Phi(-x)\Phi(1/x) = rs$. Thus, it is an isomorphism.

(ii) Lagrange's theorem states that the order of $H \leq G$ is such that $\frac{|G|}{|H|} \in \mathbb{N}$. Since the only divisors of a prime number are itself and one, and the subgroups of these orders are the entire group and the trivial subgroup (contains just the identity). hence, the group has no proper subgroup.

(iii) The order of a group element $g \in G$ is the smallest $k \in \mathbb{N}$ such that $g^k = e$. Write as $\text{ord}(g) = k$. The resultant group generated is $\langle g \rangle = \{g, g^2, \dots, g^{k-1}, e\}$. $\langle g \rangle \leq G$ because

- Closure: $g^s g^r = g^p$ where $p = (s + r) \bmod k$.
- Associativity: inherited;
- Identity: the same as that of G ;
- Inverse: g^{k-r} is the inverse of g^r .

By Lagrange's theorem, $\text{ord}(g)$ divides $|G|$.

(iv) $|G| = p$ prime. Take $g \in G$ but $g \neq e$, so $\text{ord}(g) = p$. Hence, $\langle g \rangle = G$, i.e. cyclic.

(v) If \mathcal{G} is cyclic s.t. $|\mathcal{G}| = nm$ with $n, m \in \mathbb{Z}$ but $n, m \neq 1$. Take $g \in \mathcal{G}$ s.t. $|g| = nm$, then $\exists h \in \mathcal{G}$ s.t. $g^n = h$ where $|h| = m$ which generates a cyclic subgroup of order $m < p$, i.e. a proper cyclic subgroup.

Problem 4.19 (Group Theory):

- (i) What is meant by the terms normal subgroup and group homomorphism? [2]
- (ii) Consider the group homomorphism $\phi : \mathcal{G}_1 \rightarrow \mathcal{G}_2$.
- (a) Prove that the image of ϕ is a subgroup of \mathcal{G}_2 . [2]
- (b) Prove that the kernel K of ϕ is a normal subgroup of \mathcal{G}_1 . [3]
- (c) Demonstrate that if K consists only of the identity element then ϕ is injective (i.e. one-to-one). [3]
- (iii) (a) If D_3 is the symmetry group of the equilateral triangle, describe the geometrical action of the six members of D_3 and give the minimal generating set of the group. Express the members of D_3 in terms of the generators. [6]
- (b) Identify the members of D_3 with the permutation group Σ_3 . Hence show that the two groups are isomorphic. [4]

Answer 4.19.

- (i) $H \leq G$ is a normal subgroup if for every $h \in H$ and $g \in G$, we have $ghg^{-1} \in H$.
 ϕ is a group homomorphism if $\forall a, b \in H$, then

$$\phi(a \cdot_H b) = \phi(a) \cdot_G \phi(b)$$

- (ii) (a) Check subgroup axioms:

- Closure: $\forall g_1, g_2 \in \mathcal{G}_1 \implies g_1 g_2 \in \mathcal{G}_1$ (since \mathcal{G}_1 is a group), then

$$\phi(g_1)\phi(g_2) = \phi(g_1 g_2) \in \mathcal{G}_2$$

- Associativity: inherits from \mathcal{G}_2 ;
- Identity: same as that of \mathcal{G}_2 ;
- Inverse: $\forall g \in \mathcal{G}_1, \exists g^{-1} \in \mathcal{G}_1$ such that

$$\phi(e) = \phi(g^{-1}g) = \phi(g^{-1})\phi(g) \implies (\phi(g))^{-1} = \phi(g^{-1}) \in \mathcal{G}_2$$

- (b) First check subgroup axioms for K :

- Closure: $\forall g_1, g_2 \in K, e = \phi(g_1)\phi(g_2) = \phi(g_1 g_2) \implies g_1 g_2 \in K$;
- Associativity: inherited from \mathcal{G}_1 ;
- Identity: Same identity as that of \mathcal{G}_1

$$\phi(e_{\mathcal{G}_1}) = e_{\mathcal{G}_2} \implies e_{\mathcal{G}_1} \in K$$

- Inverse: For $g \in K$,

$$e = \phi(e) = \phi(g^{-1}g) = \phi(g^{-1})\phi(g) = e\phi(g^{-1}) \implies \phi(g^{-1}) = e \implies g^{-1} \in K$$

Let $k \in K$, then $\phi(k) = e$. If $g \in \mathcal{G}_1$,

$$\phi(gkg^{-1}) = \phi(g)\phi(k)\phi(g^{-1}) = \phi(e) = e \implies gkg^{-1} \in K \implies K \triangleleft \mathcal{G}_1$$

- (c) Suppose the contrary. If $g \neq e_{\mathcal{G}_1}$ and $g \in K$, then $\phi(g) = e_{\mathcal{G}_2}$, so both $e_{\mathcal{G}_1}$ and g map to $e_{\mathcal{G}_2}$, i.e. not one-to-one.

- (iii) (a) D_3 contains r (rotation by $2\pi/3$) and s (reflection about a line passing through one vertex and the centre), then

$$D_3 = \{\text{Id}, r, r^2, s, sr, sr^2\}, \quad sr = r^2s$$

The generators are $\langle r \rangle = \{r, r^2, \text{Id}\} = \langle r^2 \rangle \implies \text{ord}(r) = \text{ord}(r^2) = 3$, $\langle s \rangle = \{s, \text{Id}\}$, $\langle sr \rangle = \{sr, sr^2s = srr^2s = \text{Id}\}$ and $\langle sr^2 \rangle = \{sr^2, sr^2sr^2 = sr^2rs = \text{Id}\}$. Hence, $\text{ord}(s) = \text{ord}(sr) = \text{ord}(sr^2) = 2$. Trivially, $\langle \text{Id} \rangle = \{\text{Id}\}$ so $\text{ord}(\text{Id}) = 1$.

- (b) We can construct the mapping Φ such that

$$\text{Id} \mapsto (1)(2)(3), \quad r \mapsto (123), \quad r^2 \mapsto (321), \quad s \mapsto (12), \quad sr \mapsto (13), \quad sr^2 \mapsto (23)$$

We can easily check that it is a homomorphism. Also check commutation: $srs = (12)(123)(12) = (12)(13) = (321) = r^2$, i.e. preserved. Φ is one-to-one and onto. Thus, Φ is an isomorphism, i.e. $D_3 \simeq \Sigma_3$.

Problem 4.20 (Representation Theory):

(i) Define faithful representation, equivalent representations, irreducible representation, and the character of a representation. [4]

(ii) Let \mathcal{G} be the following set of real 4×4 matrices

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \quad \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}, \quad \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}, \quad \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

(a) Show that \mathcal{G} is a group under the operation of matrix multiplication. Go on to show that it is a faithful representation of the dihedral group D_2 . [5]

(b) By finding an invariant subspace of the representation, prove that \mathcal{G} is reducible. [3]

(iii) (a) What are the conjugacy classes of Z_n , the cyclic group of order n ? What can you say about the number and dimensions of its irreducible representations? [4]

Hint: You may need the result $|\mathcal{G}| = \sum_{k=1}^{n_p} d_k^2$, where n_p is the number of irreducible representations of any group \mathcal{G} and d_k is the dimension of the k 'th representation.

(b) Give the irreducible representations of Z_n . Write down the associated character table for the special case $n = 3$. [4]

Answer 4.20.

(i) The definitions:

- A faithful representation is one where each element in the representation only has one pre-image.
- Two representations $D_1(G)$ and $D_2(G)$ are equivalent if \exists some matrix S s.t. $SD_1(g_i)S^{-1} = D_2(g_i) \forall g_i \in G$.
- An irreducible representation is one where a single similarity transformation S cannot be found such that $SD(g_i)S^{-1}$ is a diagonal matrix $\forall g_i \in G$ simultaneously.
- The character of a representation is the vector of the traces of the matrices representing the individual elements.

(ii) (a) Check group axioms:

- Closure:

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

- Associativity: matrix multiplication is associative;
- Identity: $I_{4 \times 4}$;
- Inverse: Each matrix is its own inverse.

The faithful representation of D_2 is $\{\text{Id}, r, s, rs\}$ since each of the 3 non-identity matrix can be mapped bijectively to r , s and rs .

- (b) By inspection, the invariant subspace is $(1, 1, 1, 1)^T$ since the matrix are formed by permutating the rows/columns of the identity. Hence, \exists a similarity transformation which will put all four matrix into the form $1 \oplus A_{3 \times 3}$.
- (iii) (a) For an element $g_i \in Z_n$ to be conjugate to another element g_j , then $\exists z \in Z_n$ s.t. $zg_jz^{-1} = g_i$, but all elements of a cyclic group can be expressed as a single generator $f \in Z_n$ to some power $p \leq n$, i.e. $z = f^r$, $z^{-1} = f^q$, then

$$zg_iz^{-1} = f^r f^i f^q = f^{r+q} f^i = f^i \quad \forall i$$

Each element is thus a conjugate class of its own.

Since we are given that the number of distinct irreducible representations is equal to the number of conjugate classes, then there are a total of n one-dimensional irreducible representations of Z_n since each of the n elements form a distinct conjugate class of its own.

- (b) The irreducible representations of Z_n are generated by $e^{i2\pi n/p} \in \mathbb{C}$ (one-dimensional) where $p \in \{1, \dots, n\}$. For $n = 3$ and recalling for one-dimensional representations, the trace is just itself, then the associated character table is

Rep 1	1	1	1
Rep 2	1	$e^{2\pi i/3}$	$e^{4\pi i/3}$
Rep 3	1	$e^{4\pi i/3}$	$e^{2\pi i/3}$

which does satisfy the character orthogonality theorem, by noting $1 + e^{2\pi i/3} + e^{4\pi i/3} = 0$ since they are roots of a quadratic equation $x^2 + x + 1 = 0$.

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5.1 Paper 1

Problem 5.1 (Vector Calculus):

- (i) Using Cartesian coordinates show that

$$\nabla \times (\nabla \times \mathbf{u}) = \nabla(\nabla \cdot \mathbf{u}) - \nabla^2 \mathbf{u}$$

and that

$$\nabla \times (\mathbf{u} \times \mathbf{v}) = \mathbf{u}(\nabla \cdot \mathbf{v}) - \mathbf{v}(\nabla \cdot \mathbf{u}) + (\mathbf{v} \cdot \nabla)\mathbf{u} - (\mathbf{u} \cdot \nabla)\mathbf{v}$$

where \mathbf{u} and \mathbf{v} are three-dimensional vector fields.

[6]

- (ii) State the divergence theorem and use it to show that

$$\int_V [\mathbf{G} \cdot (\nabla \times \mathbf{F}) - \mathbf{F} \cdot (\nabla \times \mathbf{G})] dV = \int_S (\mathbf{F} \times \mathbf{G}) \cdot \hat{\mathbf{n}} dS$$

where \mathbf{F} and \mathbf{G} are three-dimensional vector fields, V is a given volume with surface S , and $\hat{\mathbf{n}}$ is the outward unit vector normal to S .

[6]

- (iii) Let V be the volume bounded by the plane $z = 0$ and the paraboloid $z = 4 - x^2 - y^2$ with surface S and outward unit normal vector $\hat{\mathbf{n}}$. If

$$\mathbf{F} = \begin{pmatrix} xz \sin(yz) + x^3 \\ \cos(yz) \\ 3zy^2 - e^{x^2+y^2} \end{pmatrix}$$

find $\int_S \mathbf{F} \cdot \hat{\mathbf{n}} dS$.

[8]

Answer 5.1.

- (i) Use suffix notation in Cartesian coordinates for LHS of both identities:

$$\begin{aligned} \epsilon_{ijk} \frac{\partial}{\partial x_i} (\nabla \times \mathbf{u})_j &= \epsilon_{kij} \epsilon_{pqj} \frac{\partial}{\partial x_i} \frac{\partial}{\partial x_p} u_q = \frac{\partial^2 u_i}{\partial x_k \partial x_i} - \frac{\partial^2 u_k}{\partial x_i \partial x_i} \\ \epsilon_{ijk} \frac{\partial}{\partial x_i} (\mathbf{u} \times \mathbf{v})_j &= \epsilon_{kij} \epsilon_{pqj} \frac{\partial}{\partial x_i} u_p v_q = \frac{\partial}{\partial x_i} (u_k v_i) - \frac{\partial}{\partial x_i} (u_i v_k) = u_k \frac{\partial v_i}{\partial x_i} + v_i \frac{\partial u_k}{\partial x_i} - v_k \frac{\partial u_i}{\partial x_i} - u_i \frac{\partial v_k}{\partial x_i} \end{aligned}$$

- (ii) If $\mathbf{F} = \mathbf{F}(\mathbf{x})$ be a continuously differentiable vector field and V is a volume with a piecewise regular boundary ∂V , then the divergence theorem states

$$\int_V \nabla \cdot \mathbf{F} dV = \int_{\partial V} \mathbf{F} \cdot d\mathbf{S}$$

where the normal to ∂V points outwards from V . RHS of our desired result is $\int_V \nabla \cdot (\mathbf{F} \times \mathbf{G}) dV$ after invoking divergence theorem. Then, using suffix notation again. The result follows after a volume integral.

$$\frac{\partial}{\partial x_k} \epsilon_{ijk} F_i G_j = -\epsilon_{kji} \frac{\partial G_j}{\partial x_k} F_i + \epsilon_{kij} \frac{\partial F_i}{\partial x_k} G_j \implies \nabla \cdot (\mathbf{F} \times \mathbf{G}) = -(\nabla \times \mathbf{G}) \cdot \mathbf{F} + (\nabla \times \mathbf{F}) \cdot \mathbf{G}$$

- (iii) We invoke Divergence Theorem again and evaluate $\nabla \cdot \mathbf{F} = 3(x^2 + y^2)$. We change to cylindrical coordinates, $z \in [0, 4 - r^2]$ and $r \in [0, 2]$ such that

$$\int_S \mathbf{F} \cdot \mathbf{n} dS = \int_{S \cup C} \mathbf{F} \cdot \mathbf{n} dS - \int_C \mathbf{F} \cdot \mathbf{n} dS = \int_V (\nabla \cdot \mathbf{F}) dV - \int_C \mathbf{F} \cdot \mathbf{n} dS$$

where C is a circular disc at $z = 0$ plane, oriented such that $\mathbf{n} = (0, 0, -1)^T$. In that case, $\int_C \mathbf{F} \cdot \mathbf{n} dS = \int_0^{2\pi} \int_0^2 r(e^{r^2} - 3zr^2 \sin^2 \theta) dr d\theta = \pi(e^4 - 1)$. We thus have

$$\int_S \mathbf{F} \cdot \mathbf{n} dS = 32\pi - \pi(e^4 - 1) = (33 - e^4)\pi$$

Problem 5.2 (Partial Differential Equation): The velocity, $u(x, t)$, of a viscous fluid satisfies

$$\frac{\partial u}{\partial t} = \nu \frac{\partial^2 u}{\partial x^2} \quad (*)$$

where ν is a positive constant.

- (i) Consider the flow of a semi-infinite viscous fluid above a flat oscillating plate with boundary conditions $u(0, t) = U_0 \cos(\omega t)$ and $\lim_{x \rightarrow \infty} u(x, t) = 0$. Using the method of separation of variables, solve for $u(x, t)$. [10]

[Hint: Consider the complex velocity, v , such that $u = \Re(v)$ where \Re denotes the real part.]

- (ii) A viscous fluid satisfying (*) is confined between two stationary parallel plates, separated by a distance L . At $t = 0$, the fluid velocity is

$$u(x, 0) = U_0 \left(\frac{x}{L} - \frac{x^2}{L^2} \right)$$

and the fluid remains at rest at each plate with boundary conditions $u(0, t) = 0$ and $u(L, t) = 0$ for $t \geq 0$. Using the method of separation of variables, find a series solution for the velocity $u(x, t)$ for $t \geq 0$. Write down an expression for the series coefficients. What is the velocity in the limit as $t \rightarrow \infty$? [10]

Answer 5.2.

- (i) We solve by separation of variables, $v(x, t) = X(x)T(t)$ where $u = \Re(v)$. Then

$$\frac{T'}{T} = \nu \frac{X''}{X} = \alpha \in \mathbb{C}$$

Given the form of $u(0, t) = U_0 \cos(\omega t)$, T has the form $e^{\alpha t}$. This boundary condition suggests α is a purely imaginary term, i.e. $\alpha = \pm ia^2\nu$, such that $\sqrt{\alpha/\nu} = \pm\sqrt{\pm ia} = \pm a\frac{1}{\sqrt{2}}(1 \pm i)$.

With $\lim_{x \rightarrow \infty} u(x, t) = 0$, we can only have the following form for $u(x, t)$:

$$\begin{aligned} u(x, t) &= \operatorname{Re} \left[\int_0^\infty \left(A e^{-a(1+i)x/\sqrt{2}} + B e^{-a(1-i)x/\sqrt{2}} \right) e^{\pm ia^2\nu t} da \right] \\ &= \int_0^\infty e^{-ax/\sqrt{2}} \left[A \cos(a^2\nu t - (ax/\sqrt{2})) + B \sin(a^2\nu t - (ax/\sqrt{2})) \right] da \end{aligned}$$

Imposing the boundary condition $U_0 \cos(\omega t) = u(0, t) = \int_0^\infty A \cos(a^2\nu t) + B \sin(a^2\nu t) da$, then $a^2\nu = \omega$ and hence the general solution is

$$u(x, t) = U_0 e^{-x\sqrt{\omega/2\nu}} \cos(\omega t - x\sqrt{\omega/2\nu})$$

- (ii) The fluid is constrained between $x = 0$ and $x = L$ such that $u(0, t) = u(L, t) = 0$, then

$$\frac{X''}{X} \nu = \frac{T'}{T} = -\lambda^2\nu, \lambda \in \mathbb{R}$$

such that $X = c_1 \sin(\lambda x) + c_2 \cos(\lambda x)$ where $\lambda = \frac{n\pi}{L}$ and $T \sim e^{-\nu n^2 \pi^2 t/L^2}$. From the boundary conditions, $c_2 = 0$. The general form of $u(x, t)$ is thus $\sum_{n=1}^\infty A_n \sin(\frac{n\pi x}{L}) e^{-\nu n^2 \pi^2 t/L^2}$. We have

$$A_n = \frac{2}{L} \int_0^L U_0 \left(\frac{x}{L} - \frac{x^2}{L^2} \right) \sin \frac{n\pi x}{L} dx = \frac{2}{L} \left[U_0 \left(\frac{x}{L} - \frac{x^2}{L^2} \right) \frac{-L \cos(n\pi x/L)}{n\pi} \right]_0^L + \frac{2U_0}{n\pi} \int_0^L \left(\frac{1}{L} - \frac{2x}{L^2} \right) \cos \frac{n\pi x}{L} dx$$

which further simplifies to $A_n = \frac{4U_0 L}{n^3 \pi^3}$ for odd n and 0 for even n . Hence,

$$u(x, t) = \sum_{p=0}^\infty \frac{4U_0 L}{(2p+1)^3 \pi^3} \sin \frac{(2p+1)\pi x}{L} e^{-\nu \pi^2 (2p+1)^2 t/L^2}$$

As $t \rightarrow \infty$, the slowest decaying exponential dominates.

$$u(x, t) \approx \frac{4U_0 L}{\pi^3} \sin \frac{\pi x}{L} e^{-\nu \pi^2 t/L^2}$$

Problem 5.3 (Green's Functions): A beam lies along the x -axis with its ends at $x = 0$ and $x = 1$. The transverse displacement $y(x)$ of the beam when a force per length $f(x)$ is applied satisfies

$$\frac{d^4 y}{dx^4} = f(x)$$

The boundary conditions are $y = 0$ and $\frac{dy}{dx} = 0$ at both $x = 0$ and $x = 1$. The displacement can be written in terms of a Green's function $G(x, \xi)$ as

$$y(x) = \int_0^1 G(x, \xi) f(\xi) d\xi$$

(i) What conditions must the Green's function satisfy at $x = 0$ and $x = 1$ and at $x = \xi$? [4]

(ii) Construct the Green's function to show that [12]

$$G(x, \xi) = \begin{cases} -\frac{1}{6}x^2(\xi - 1)^2(x + 2x\xi - 3\xi) & \text{for } x < \xi \\ -\frac{1}{6}\xi^2(x - 1)^2(\xi + 2x\xi - 3x) & \text{for } x > \xi \end{cases}$$

(iii) Consider two points x_1 and x_2 along the beam. A force $f(x) = \delta(x - x_1)$ causes a displacement $y_1(x_2)$ at x_2 . If the force is instead $f(x) = \delta(x - x_2)$, the displacement at x_1 is $y_2(x_1)$. Show that $y_1(x_2) = y_2(x_1)$. [4]

Answer 5.3.

(i) The corresponding Green's function satisfy

$$\frac{\partial^4 G(x, \xi)}{\partial x^4} = \delta(x - \xi), \quad G(0, \xi) = G(1, \xi) = 0, \quad G'(0, \xi) = G'(1, \xi) = 0$$

Integrate this over an infinitesimal region around $x = \xi$, then G, G', G'' must all be continuous everywhere including $x = \xi$ (otherwise $G''' \propto$ higher derivatives of $\delta(x - \xi)$, which is a contradiction). G''' is continuous everywhere except at $x = \xi$ (unit jump discontinuity).

(ii) We propose a polynomial solution (of order 3) for the Green's function

$$\begin{aligned} G(x, \xi) &= \begin{cases} c_1 x^3 + c_2 x^2 + c_3 x + c_4 & 0 \leq x < \xi \leq 1 \\ c_5 x^3 + c_6 x^2 + c_7 x + c_8 & 0 \leq \xi < x \leq 1 \end{cases} \\ \implies \frac{\partial G(x, \xi)}{\partial x} &= \begin{cases} 3c_1 x^2 + 2c_2 x + c_3 & 0 \leq x < \xi \leq 1 \\ 3c_5 x^2 + 2c_6 x + c_7 & 0 \leq \xi < x \leq 1 \end{cases} \\ \implies \frac{\partial^2 G(x, \xi)}{\partial x^2} &= \begin{cases} 6c_1 x + 2c_2 & 0 \leq x < \xi \leq 1 \\ 6c_5 x + 2c_6 & 0 \leq \xi < x \leq 1 \end{cases} \\ \implies \frac{\partial^3 G(x, \xi)}{\partial x^3} &= \begin{cases} 6c_1 & 0 \leq x < \xi \leq 1 \\ 6c_5 & 0 \leq \xi < x \leq 1 \end{cases} \end{aligned}$$

We require 8 equations for 8 unknowns. The first two is obtained from boundary conditions $G = 0$ and $\frac{\partial G}{\partial x} = 0$ at $x = 0$ and $x = 1$:

$$c_4 = 0; \quad c_5 + c_6 + c_7 + c_8 = 0$$

$$c_3 = 0; \quad 3c_5 + 2c_6 + c_7 = 0$$

The next six is obtained from continuity conditions and discontinuity condition at $x = \xi$:

$$3\xi(c_5 - c_1) = c_2 - c_6; \quad 6(c_5 - c_1) = 1$$

$$3(c_5 - c_1)\xi^2 + 2(c_6 - c_2)\xi + c_7 - c_3 = 0; \quad (c_5 - c_1)\xi^3 + (c_6 - c_2)\xi^2 + (c_7 - c_3)\xi + (c_8 - c_4) = 0$$

This gives the matrix equation:

$$\begin{pmatrix} -1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 3 & 2 & 1 & 0 \\ 0 & 1 & 0 & -1 & 0 & 0 \\ -\xi^3 & -\xi^2 & \xi^3 & \xi^2 & \xi & 1 \\ -3\xi^2 & -2\xi & 3\xi^2 & 2\xi & 1 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_5 \\ c_6 \\ c_7 \\ c_8 \end{pmatrix} = \begin{pmatrix} 1/6 \\ 0 \\ 0 \\ \xi/2 \\ 0 \\ 0 \end{pmatrix} \implies \begin{pmatrix} c_1 \\ c_2 \\ c_5 \\ c_6 \\ c_7 \\ c_8 \end{pmatrix} = \begin{pmatrix} \frac{1}{6}(-1 + 3\xi^2 - 2\xi^3) \\ \frac{1}{2}(\xi - 2\xi^2 + \xi^3) \\ \frac{1}{6}(3\xi^2 - 2\xi^3) \\ \frac{1}{2}(-2\xi^2 + \xi^3) \\ \xi^2/2 \\ -\xi^3/6 \end{pmatrix}$$

hence

$$G(x, \xi) = \begin{cases} \frac{1}{6}(-1 + 3\xi^2 - 2\xi^3)x^3 + \frac{1}{2}(\xi - 2\xi^2 + \xi^3)x^2 & 0 \leq x < \xi \leq 1 \\ \frac{1}{6}(3\xi^2 - 2\xi^3)x^3 + \frac{1}{2}(-2\xi^2 + \xi^3)x^2 + \frac{1}{2}\xi^2x - \frac{1}{6}\xi^3 & 0 \leq \xi < x \leq 1 \end{cases}$$

which simplifies to their desired result.

- (iii) To show $y_1(x_2) = y_2(x_1)$, we need to show the associated Green's functions for a self-adjoint operator \mathcal{L} (in this case $\mathcal{L} = y^{(4)}$) are symmetric.

$$G(y, x) = \int_a^b G(y, \xi)\delta(x - \xi)d\xi = \int_a^b G(y, \xi)\mathcal{L}G(x, \xi)d\xi = \int_a^b \delta(y - \xi)G(x, \xi)d\xi = G(x, y)$$

where $\mathcal{L}^\dagger = \mathcal{L}$ for a self-adjoint operator, and since $y_1(x_2) = \int_0^1 G(x_2, \xi)\delta(\xi - x_1)d\xi = G(x_2, x_1)$ and then $y_2(x_1) = \int_0^1 G(x_1, \xi)\delta(\xi - x_2)d\xi = G(x_1, x_2)$ and hence $y_1(x_2) = y_2(x_1)$.

Problem 5.4 (Fourier Transform):

- (i) The Fourier transform of a function
- $f(x)$
- is given by

$$\tilde{f}(k) = \int_{-\infty}^{\infty} f(x)e^{-ikx} dx$$

Write down the corresponding expression for the inverse Fourier transform. [2]

- (ii) Let
- $g(x) = x^n f(x)$
- , where
- n
- is a positive integer. Derive an expression for
- $\tilde{g}(k)$
- , written in terms of derivatives of
- $\tilde{f}(k)$
- with respect to
- k
- . [4]

- (iii) Using the result from part (ii), or otherwise, find the Fourier transform of the following function: [6]

$$f(x) = xe^{-x^2} \quad (*)$$

[Hint: $\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$.]

- (iv) Derive Parseval's Theorem: [4]

$$\int_{-\infty}^{\infty} [f(x)]^* g(x) dx = \frac{1}{2\pi} \int_{-\infty}^{\infty} [\tilde{f}(k)]^* \tilde{g}(k) dk$$

- (v) The energy,
- E
- , of a function
- $f(x)$
- is defined as

$$E = \int_{-\infty}^{\infty} |f(x)|^2 dx$$

Find the energy of the function defined in (*) and verify that the result is consistent with the Parseval's Theorem. [4]

Answer 5.4.

- (i) The inverse is
- $f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{f}(k)e^{ikx} dk$

- (ii) The Fourier transform of
- g
- is
- $\tilde{g}(k) = \int_{-\infty}^{\infty} x^n f(x)e^{-ikx} dx$
- , but
- $\frac{d}{dk} \int_{-\infty}^{\infty} f(x)e^{-ikx} dx = \int_{-\infty}^{\infty} (-ix)f(x)e^{-ikx} dx$
- , and so

$$\frac{d^n \tilde{f}}{dk^n} = \int_{-\infty}^{\infty} (-ix)^n f(x)e^{-ikx} dx = e^{-in\pi/2} \tilde{g} \implies \tilde{g}(k) = e^{i\pi n/2} \tilde{f}^{(n)}(k)$$

- (iii) The Fourier transform of
- e^{-x^2}
- is
- $\int_0^{\infty} e^{-(x^2+ikx)} dx = \int_0^{\infty} e^{-((x-i(k/2))^2 + (k^2/4))} dx = e^{-k^2/4} \sqrt{\pi}$
- and so the Fourier transform of
- $f(x)$
- is
- $e^{-k^2/4} (ik/2) \sqrt{\pi}$
- .

- (iv) Using inverse Fourier transform, write
- $\int_{-\infty}^{\infty} f^*(x)g(x)dx$
- as

$$\frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} \left[\int_{-\infty}^{\infty} \tilde{f}^*(k)e^{-ikx} dk \int_{-\infty}^{\infty} \tilde{g}(q)e^{iqx} dq \right] dx = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} \tilde{f}^*(k) \int_{-\infty}^{\infty} \tilde{g}(q) \int_{-\infty}^{\infty} e^{ix(q-k)} dx dq dk$$

which is $\frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{f}^*(k) \tilde{g}(k) dk$ where $\int_{-\infty}^{\infty} e^{ix(q-k)} dx = 2\pi \delta(k-q)$.

- (v) By direct computation,
- $E = \int_{-\infty}^{\infty} x^2 e^{-2x^2} dx = [x(-e^{-x^2}/4)]_{-\infty}^{\infty} + \frac{1}{4} \int_{-\infty}^{\infty} e^{-2x^2} dx = \frac{1}{2} \sqrt{\frac{\pi}{2}}$
- . From previous results and together with Parseval's Theorem,

$$E = \frac{1}{2\pi} \int_{-\infty}^{\infty} |(ik/2)| e^{-k^2/2} \pi dk = \frac{1}{8} \left([-ke^{-k^2/2}]_{-\infty}^{\infty} + \int_{-\infty}^{\infty} e^{-k^2/2} dk \right) = \frac{1}{2} \sqrt{\frac{\pi}{2}}$$

Hence we have shown that it is consistent with Parseval's Theorem.

Problem 5.5 (Linear Algebra):

(i) Define a Hermitian matrix and show that its eigenvalues are real. Define a unitary matrix and show that its eigenvalues have unit modulus. [7]

(ii) Consider two $n \times n$ matrices U and H that are related by

$$U = e^{iH} \equiv \sum_{m=0}^{\infty} \frac{(iH)^m}{m!}$$

If H is Hermitian, show that U is unitary. [5]

(iii) Suppose that a $n \times n$ unitary matrix can be written as $U = M + iN$, where M and N are Hermitian matrices. You may assume that M and N have n distinct eigenvalues.

Show that M and N have the same eigenvectors and determine the eigenvalues of M and N in terms of the eigenvalues of U . [8]

Answer 5.5.

(i) A matrix is Hermitian if it is equal to its transposed complex conjugate, i.e. Hermitian conjugate.

$$H = (H^*)^T := H^\dagger$$

A matrix is unitary if it is equal to its Hermitian conjugate.

$$U^\dagger = U^{-1}$$

For a Hermitian matrix with eigenvectors x and y with corresponding eigenvalues λ and μ , then $Hx = \lambda x$, $Hy = \mu y$. We have

$$0 = y^\dagger Hx - y^\dagger x \lambda = (H^\dagger y)^\dagger x - y^\dagger x \lambda = (\mu y)^\dagger x - y^\dagger x \lambda = (\mu^* - \lambda) y^\dagger x$$

For $x - y \neq 0$, then $y^\dagger x > 0$ and so $\lambda^* = \lambda$ hence $\lambda \in \mathbb{R}$. For unitary matrix,

$$x^\dagger x = x^\dagger U^\dagger U x = (Ux)^\dagger Ux = (\nu x)^\dagger \nu x = |\nu|^2 x^\dagger x \implies (|\nu|^2 - 1)x^\dagger x = 0$$

For $x \neq 0$, $x^\dagger x > 0$, and so $|\nu| = 1$.

(ii) H commutes with itself and is Hermitian, so

$$U^\dagger U = e^{-iH^\dagger} e^{iH} = e^{-iH} e^{iH} = 1$$

U is unitary.

(iii) Let e_n be eigenvector of U , then $Ue_n = \nu_n e_n$ and so $U^\dagger e_n = \nu_n^{-1} e_n$. We have $U = M + iN$ and $U^\dagger = M - iN$, hence

$$Me_n = \frac{1}{2}(\nu_n + \nu_n^{-1})e_n$$

$$Ne_n = \frac{1}{2i}(\nu_n - \nu_n^{-1})e_n$$

M and N have eigenvalues $\frac{1}{2}(\nu_n + \nu_n^{-1})$ and $\frac{1}{2i}(\nu_n - \nu_n^{-1})$ respectively.

Problem 5.6 (Linear Algebra):

- (i) Let M be a $n \times n$ real symmetric matrix. Explain how to construct an orthogonal matrix O such that $O^T M O = D$, where D is a real diagonal matrix. [4]
- (ii) The quadratic form associated with a 3×3 real symmetric matrix M is

$$Q(x) = x^T M x = \sum_{i=1}^3 \sum_{j=1}^3 x_i M_{ij} x_j$$

where $x^T = [x_1, x_2, x_3]$. Let Σ be the surface in \mathbb{R}^3 defined by

$$Q(x) = k = \text{constant} \quad (*)$$

Define the change in coordinates that brings $(*)$ into the form

$$\lambda_1 x_1'^2 + \lambda_2 x_2'^2 + \lambda_3 x_3'^2 = k$$

For $k > 0$, describe Σ for the following cases: [4]

- (a) $\lambda_1 = \lambda_2 = \lambda_3 > 0$;
 (b) $\lambda_1 = \lambda_2 > 0, \lambda_3 < 0$;
 (c) $\lambda_1 = 0, \lambda_2 > 0, \lambda_3 > 0$.
- (iii) Consider the quadratic surface Σ defined by

$$x_1^2 + x_2^2 + x_3^2 - 2x_1x_2 - 2x_1x_3 - 2x_2x_3 = 3$$

Show that Σ has an axis of rotational symmetry and find its direction. [10]

Answer 5.6.

- (i) Find the eigenvalues and their corresponding eigenvectors of M . If there are n distinct real eigenvalues, then the corresponding n eigenvectors can be normalized to form a normalized eigenbasis. Otherwise, if there are only $r < n$ distinct eigenvalues, then we can always extend the normalized basis of r normalized eigenvectors to a basis of \mathbb{R}^n . The normalized vectors in the basis form the columns of an orthogonal matrix O such that $O^T M O$ is a diagonal matrix.
- (ii) (a) Surface is a sphere centred at the origin and has radius $\sqrt{k/\lambda_1}$.
 (b) Surface is a hyperboloid of revolution of one sheet, with y_3 being its axis, and circle of intersection in the y_1 - y_2 plane with centre at origin and of radius $\sqrt{k/\lambda_1}$.
 (c) Surface is an elliptical cylinder with y_1 being the axis, and with principal axes $\sqrt{k/\lambda_2}$ and $\sqrt{k/\lambda_3}$ in y_2 and y_3 directions respectively.
- (iii) To show Σ has an axis of rotational symmetry, we need to show 2 of its eigenvalues are degenerate and find the eigenvector corresponding to the non-degenerate case. This eigenvector is parallel to the rotational axis.

$$3 = x_1^2 + x_2^2 + x_3^2 - 2x_1x_2 - 2x_2x_3 - 2x_3x_1 = \begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} \begin{pmatrix} 1 & -1 & -1 \\ -1 & 1 & -1 \\ -1 & -1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

The characteristic equation of this quadratic surface is

$$\det \begin{pmatrix} 1-\lambda & -1 & -1 \\ -1 & 1-\lambda & -1 \\ -1 & -1 & 1-\lambda \end{pmatrix} = (1-\lambda)(1-2\lambda+\lambda^2) + (-1+\lambda-1) - (1+1-\lambda) = (\lambda-2)^2(\lambda+1)$$

The degenerate and non-degenerate eigenvalues are 2 and -1 respectively. When $\lambda = -1$, the eigenvector is $(1, 1, 1)^T$. This surface corresponds to a hyperboloid of revolution of one sheet, with rotational symmetry along $(1, 1, 1)^T$ direction. In the perpendicular plane, we have a circle of intersection, centred at origin and radius $\sqrt{3/2}$.

Problem 5.7 (Cauchy-Riemann):

- (i) Derive the Cauchy–Riemann conditions satisfied by the real part $u(x, y)$ and the imaginary part $v(x, y)$ of an analytic function $f(z)$ of the complex variable $z = x + iy$, and show that u and v each satisfy Laplace’s equation in two dimensions, i.e., $\nabla^2 u = 0$ and $\nabla^2 v = 0$. [4]
- (ii) Show that the equation

$$\left| \frac{z - a}{z + a} \right| = \lambda$$

defines a family of circles in the complex plane and find their centres and radii in terms of the real and positive parameters a and λ . [6]

- (iii) A real function $V(x, y)$ satisfies $\nabla^2 V = 0$ in two dimensions in the half-plane $x > 0$ outside a circle of radius R centred on $x = d$ and $y = 0$ (with $d > R$). The function takes values $V = 0$ on $x = 0$ and $V = -V_0$ on the circle. By considering the real part of the complex function

$$f(z) = \ln \left(\frac{z - a}{z + a} \right)$$

or otherwise, show that

$$V = \frac{V_0}{\cosh^{-1}(d/R)} \ln \left| \frac{z - a}{z + a} \right|$$

for a suitable constant a that should be determined. [10]

Answer 5.7.

- (i) $f(z) = u(x, y) + iv(x, y)$ is analytic if its complex derivative

$$\frac{df}{dz} = \lim_{\Delta z \rightarrow 0} \frac{f(z + \Delta z) - f(z)}{\Delta z}$$

exists and is independent of the direction of approach $\Delta z \rightarrow 0$ in the complex plane. We choose two linearly independent direction $\Delta z = \Delta x$ and $\Delta z = i\Delta y$, then

$$\begin{aligned} & \lim_{\Delta x \rightarrow 0} \frac{u(x + \Delta x, y) + iv(x + \Delta x, y) - u(x, y) - iv(x, y)}{\Delta x} \\ & - \lim_{i\Delta y \rightarrow 0} \frac{u(x, y + i\Delta y) + iv(x, y + i\Delta y) - u(x, y) - iv(x, y)}{i\Delta y} \\ & = \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} + i \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) = 0 \end{aligned}$$

The real and imaginary parts together give the Cauchy-Riemann conditions. Evaluate $\nabla^2 u$ gives

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial}{\partial y} \left(-\frac{\partial v}{\partial x} \right) = 0$$

since the partial derivatives of v are symmetric, hence u satisfies Laplace’s equation. By symmetry, v also satisfies Laplace’s equation.

- (ii) Given

$$\begin{aligned} \lambda &= \left| \frac{z - a}{z + a} \right| = \sqrt{\frac{(x - a)^2 + y^2}{(x + a)^2 + y^2}} \\ \implies x^2(\lambda^2 - 1) + 2ax(\lambda^2 + 1) + (a^2 + y^2)(\lambda^2 - 1) &= 0 \\ \implies \left(x - a \frac{1 + \lambda^2}{1 - \lambda^2} \right)^2 + y^2 &= a^2 \left(\left(\frac{1 + \lambda^2}{1 - \lambda^2} \right)^2 - 1 \right) = \frac{4a^2 \lambda^2}{(1 - \lambda^2)^2} \end{aligned}$$

This is the equation of a circle with centre $(a \frac{1 + \lambda^2}{1 - \lambda^2}, 0)$ and radius $\frac{2a\lambda}{1 - \lambda^2}$.

(iii) Rewriting $f(z)$,

$$\begin{aligned} f(z) &= \ln \left(\frac{z-a}{z+a} \right) \\ &= \ln \left(\frac{\sqrt{(x-a)^2 + y^2} e^{i \tan^{-1}(y/(x-a))}}{\sqrt{(x+a)^2 + y^2} e^{i \tan^{-1}(y/(x+a))}} \right) \\ &= \ln \left| \frac{z-a}{z+a} \right| + i \left(\tan^{-1} \left(\frac{y}{x-a} \right) - \tan^{-1} \left(\frac{y}{x+a} \right) \right) \end{aligned}$$

We have $\operatorname{Re}[f] = \ln \left| \frac{z-a}{z+a} \right|$ which satisfies $\nabla^2 V = 0$ with $V = \alpha \operatorname{Re}[f]$ for some real constant α . By the uniqueness theorem, any solution of the Laplace's equation that satisfies the given boundary conditions ($V = 0$ at $x = 0$ and $V = -V_0$ on circle) is the only solution. From the previous result, the given circle has

$$d = a \frac{1 + \lambda^2}{1 - \lambda^2}, \quad R = \frac{2a\lambda}{1 - \lambda^2}$$

Thus, eliminating a gives $\frac{d}{R} = \frac{1+\lambda^2}{2\lambda}$ and hence

$$R\lambda^2 - 2d\lambda + R = 0 \implies \lambda = \frac{d}{R} \pm \frac{\sqrt{d^2 - R^2}}{R} \implies \ln(\lambda) = \pm \ln \left(\frac{d}{R} + \sqrt{\left(\frac{d}{R} \right)^2 - 1} \right) = \pm \cosh^{-1} \left(\frac{d}{R} \right)$$

Since $\alpha \operatorname{Re}[f] = V \in [-V_0, 0]$, then $\ln(\lambda) = \operatorname{Re}[f] < 0$ and so $\ln(\lambda) = -\cosh^{-1}(d/R)$ and $\lambda = \frac{d}{R} - \frac{\sqrt{d^2 - R^2}}{R}$. On the circle, $V = -V_0$, and so $V_0 = \alpha \cosh^{-1}(d/R)$. We have

$$V = \frac{V_0}{\cosh^{-1}(d/R)} \ln \left| \frac{z-a}{z+a} \right|$$

where a is

$$a = \frac{1 - \lambda^2}{2\lambda} R = \frac{R}{2} \left(\frac{1}{\lambda} - \lambda \right) = R \sqrt{\left(\frac{d}{R} \right)^2 - 1}$$

Problem 5.8 (Series Solution to ODE):

- (i) Consider the ordinary differential equation

$$x^2 \frac{d^2 y}{dx^2} + 2x \frac{dy}{dx} + [x^2 - l(l+1)]y = 0$$

where l is a non-negative integer. Find and classify the singular points of the equation. [4]

- (ii) The differential equation admits two linearly-independent solutions of the form [10]

$$y(x) = x^\sigma \sum_{n=0}^{\infty} a_n x^n, \quad (a_0 \neq 0)$$

Determine the two possible values of σ and the recursion relations satisfied by the a_n in each case.

- (iii) Using these recursion relations, verify that, for a suitable choice of
- a_0
- , the solution that is regular at
- $x = 0$
- is

$$y(x) = 2^l x^l \sum_{s=0}^{\infty} \frac{(-1)^s (s+l)!}{s!(2s+2l+1)!} x^{2s}$$

Express this series for $l = 0$ in terms of elementary functions and verify directly that your result satisfies the differential equation. [6]

Answer 5.8.

- (i)
- $x = 0$
- is a singularity since
- $\frac{2}{x}$
- and
- $1 - \frac{l(l+1)}{x^2}$
- are not analytic at
- $x = 0$
- . But
- 2
- and
- $x^2 - l(l+1)$
- are analytic at
- $x = 0$
- , so
- $x = 0$
- is a regular singular point.

- (ii) With the suggested series solution, we have

$$\sum_{n=0}^{\infty} (n+\sigma)(n+\sigma-1)a_n x^{n+\sigma} + 2 \sum_{n=0}^{\infty} a_n (n+\sigma)x^{n+\sigma} - l(l+1) \sum_{n=0}^{\infty} a_n x^{n+\sigma} + \sum_{n=0}^{\infty} a_n x^{n+\sigma+2} = 0$$

Comparing coefficients for x^σ , we have the indicial equation $a_0[\sigma(\sigma+1) - l(l+1)] = 0$. Since $a_0 \neq 0$ given, then $\sigma^2 + \sigma - l(l+1) = 0 \implies \sigma = l, -(l+1)$. Comparing coefficients for $x^{\sigma+1}$, we have

$$a_1[(1+\sigma)\sigma + 2(\sigma+1) - l(l+1)] = 0$$

which give $a_1 = 0$ and $\sigma = l, -(l+1)$ consistent with $a_0 \neq 0$. We either have $a_1 \neq 0$ and $a_0 = 0$, or $a_1 = 0$ and $a_0 \neq 0 \implies \sigma = l, -(l+1)$. Comparing coefficients for $x^{\sigma+r} \forall r > 1$, we obtain the recurrence relation

$$a_{n+2} = -\frac{a_n}{(n+\sigma+2)(n+\sigma+3) - l(l+1)}$$

When $\sigma = l$, we have $a_{n+2} = -\frac{a_n}{(n+2)(n+3+2l)}$ and $a_{n+2} = \frac{-a_n}{(n+2)(n+1-2l)}$.

- (iii) Given the suggested form
- $y(x)$
- , we have
- $\sigma = l$
- , and since it is a double jump, we can write as

$$a_{2(s+1)} = -\frac{a_{2s}}{(2s+2)(2s+3+2l)}$$

With the suggested series solution, we can verify that the ratio is indeed

$$\frac{a_{2(s+1)}}{a_{2s}} = -\frac{s+l+1}{(s+1)(2s+2l+2)(2s+2l+3)} = \frac{-1}{2(s+1)(2s+2l+3)}$$

For $l = 0$,

$$y(x) = \sum_{s=0}^{\infty} \frac{(-1)^s s!}{(2s+1)! s!} x^{2s} = \frac{\sin(x)}{x}$$

We have $x^2 y'' + 2xy' + x^2 y = -2\cos(x) + \frac{2}{x}\sin(x) - \frac{2}{x}\sin(x) + 2\cos(x) = 0$ as desired.

Problem 5.9 (Variational Principle):

- (i) Derive the Euler–Lagrange equation for the function $q(t)$ corresponding to stationary values of the functional

$$S[q(t)] = \int_{t_0}^{t_1} L(t, q(t), \dot{q}(t)) dt, \quad \dot{q} = dq/dt$$

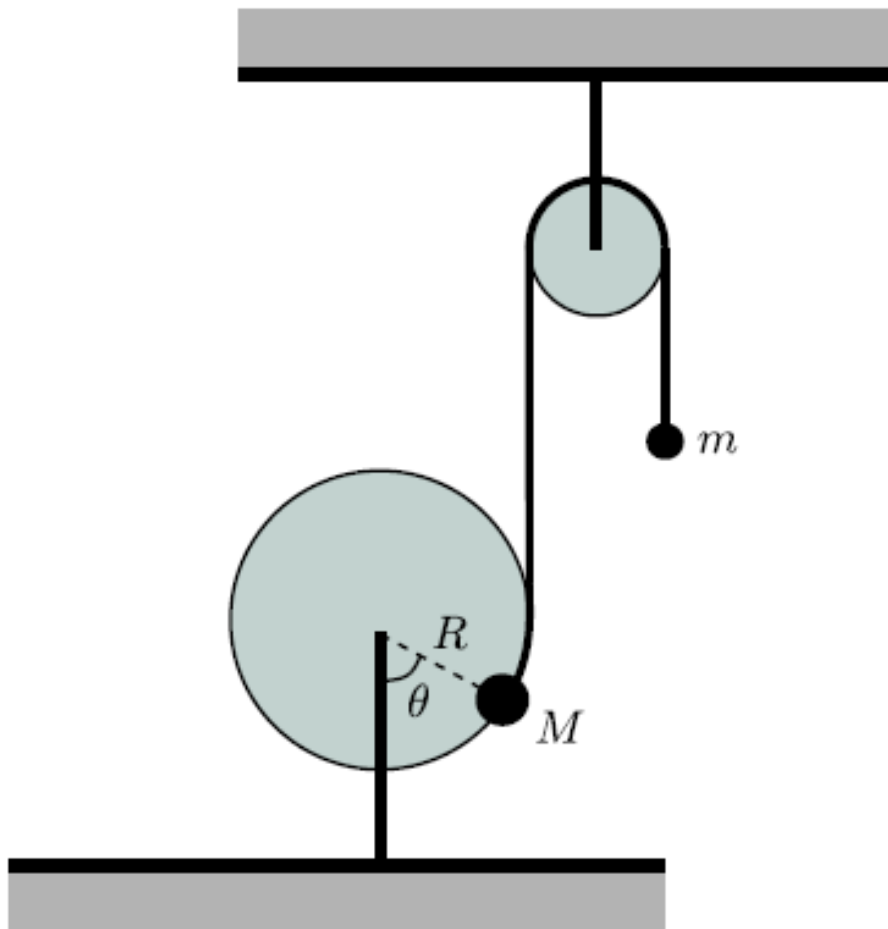
for fixed $q(t_0)$ and $q(t_1)$.

[5]

What is the first integral of the Euler–Lagrange equation if L is independent of t ?

[5]

- (ii) A mass M is attached to a massless hoop of radius R . The hoop lies in a vertical plane and is free to rotate about its fixed center. A massless, inextensible string connects M to a second mass $m < M$ as shown in the figure (i.e., the string winds part way around the hoop, then rises vertically up and over a massless pulley). Assume that m moves only vertically in a uniform gravitational field (with gravitational acceleration g). You may ignore friction.



The Lagrangian \mathcal{L} is the difference of the kinetic and potential energies of the system. From the Euler–Lagrange equation find the equation of motion for the angle of rotation of the hoop, $0 \leq \theta(t) \leq \pi/2$.

Derive the equilibrium angle θ_0 . Consider small oscillations around θ_0 , i.e., let $\theta(t) = \theta_0 + \delta(t)$, where $|\delta| \ll \theta_0$. Show that the angular frequency of oscillations is

$$\omega = \left(\frac{M - m}{M + m} \right)^{1/4} \sqrt{\frac{g}{R}}$$

Comment on the limit $M \gg m$.

[10]

Answer 5.9.

(i) The first order variation of the action S is

$$\delta S = S[q + \delta q] - S[q] = \int_{t_0}^{t_1} \delta q \frac{\partial L}{\partial q} + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} dt = \int_{t_0}^{t_1} \delta q \left(\frac{\partial L}{\partial q} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} \right) dq + \left[\frac{\partial L}{\partial \dot{q}} \delta q \right]_{t_0}^{t_1}$$

The boundary term is zero since q is fixed at t_0 and t_1 . To find the stationary value of the functional, $\frac{\partial S}{\partial q} = 0 \implies \frac{\partial L}{\partial q} = \frac{d}{dt} \frac{\partial L}{\partial \dot{q}}$, which is the Euler-Lagrange equation.

If $L = (q(t), \dot{q}(t))$, then $\frac{\partial L}{\partial t} = 0$, and so by the chain rule,

$$\frac{dL}{dt} = \frac{\partial L}{\partial t} + \frac{\partial L}{\partial q} \dot{q} + \frac{\partial L}{\partial \dot{q}} \ddot{q} = 0 + \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \dot{q} \right)$$

which implies $L - \frac{\partial L}{\partial \dot{q}} \dot{q}$ is a constant.

(ii) The Lagrangian is given to be the difference between kinetic and potential energies

$$\mathcal{L}(\theta, \dot{\theta}, t) = \frac{1}{2}(m + M)R^2 \dot{\theta}^2 - gR[-m\theta + M(1 - \cos \theta)]$$

We define the action to be the functional $\mathcal{S}[\theta(t)] = \int \mathcal{L} dt$. We wish to extremize the action, then by the Euler-Lagrange equation in part (i),

$$0 = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\theta}} - \frac{\partial \mathcal{L}}{\partial \theta} = \ddot{\theta}(M + m)R^2 - gR(-m + M \sin \theta)$$

This gives the equation of motion

$$\ddot{\theta} + g \frac{M \sin \theta}{R(m + M)} = \frac{gm}{(M + m)R}$$

Note the first integral of motion (since \mathcal{L} is independent of t) gives the conservation of energy. At equilibrium, $\ddot{\theta} = 0$, and so $\theta_0 = \sin^{-1} \frac{m}{M}$. Now perturb θ about θ_0 with $|\delta(t)| \ll \theta_0$, then

$$\ddot{\delta} + \frac{gM}{R(m + M)} \sin(\theta_0 + \delta) = \frac{gm}{R(M + m)} = \frac{gM}{R(m + M)} \sin \theta_0$$

Then we have $\ddot{\delta} + \frac{gM\delta}{R(m+M)} \sqrt{1 - (m/M)^2}$. This is an equation of simple harmonic motion $\ddot{\delta} = -\omega^2 \delta = 0$, and hence the angular frequency is

$$\omega = \sqrt{\frac{gM}{R(M + m)} \left(1 - \frac{m^2}{M^2} \right)^{1/4}} = \sqrt{\frac{g}{R} \left(\frac{M - m}{M + m} \right)^{1/4}}$$

In the limit $M \gg m$, $\omega \approx \sqrt{\frac{g}{R}}$, where M just oscillates about θ_0 without the influence of m .

Problem 5.10 (Rayleigh-Ritz Method): The Sturm–Liouville equation is

$$[-p(x)\psi']' + q(x)\psi = \lambda w(x)\psi \quad (*)$$

where $p(x) > 0$ and $w(x) > 0$ for $a \leq x \leq b$, and primes denote differentiation with respect to x .

- (i) Show that finding the eigenvalues λ is equivalent to finding the stationary values of the functional

$$\Lambda[\psi(x)] = \frac{\int_a^b (p\psi'^2 + q\psi^2)dx}{\int_a^b w\psi^2 dx}$$

if suitable boundary conditions are satisfied at $x = a$ and $x = b$ (which should be stated). [6]

- (ii) Let λ_0 be the lowest eigenvalue and ψ_0 be the associated eigenfunction. A general function $\tilde{\psi}$ can be written as

$$\tilde{\psi}(x) = c_0\psi_0(x) + \sum_{i=1}^{\infty} c_i\psi_i(x)$$

where c_0 and c_i are constants, and ψ_i ($i = 0, 1, 2, \dots$) are orthonormal eigenfunctions of (*) with eigenvalues $\lambda_i \geq \lambda_0$. Show that

$$\tilde{\lambda} = \Lambda[\tilde{\lambda}(x)] = \frac{\lambda_0 + \sum_{i=1}^{\infty} |a_i|^2 \lambda_i}{1 + \sum_{i=1}^{\infty} |a_i|^2}$$

where $a_i = \frac{c_i}{c_0}$. Explain how this result allows you to estimate the lowest eigenvalue λ_0 . [6]

- (iii) Consider the Schrodinger equation

$$-\psi'' + x^2\psi = \lambda\psi$$

for $0 \leq x < \infty$ and with the boundary conditions $\psi(0) = 0$, $\lim_{x \rightarrow \infty} \psi(x) = 0$. Using the trial function $\tilde{\psi} = xe^{-\alpha x}$ with α a real positive constant, estimate the lowest eigenvalue λ_0 .

[8]

Answer 5.10.

- (i) We define the functionals $F[\psi] := \int_a^b p\psi'^2 + q\psi^2 dx$ and $G[\psi] := \int_a^b w\psi^2 dx$ such that $\Lambda = \frac{F}{G}$. Its first order variation is

$$\delta\Lambda = \frac{\delta F + F}{\delta G + G} - \frac{F}{G} = \frac{1}{G} \left(\delta F - \frac{F}{G} \delta G \right)$$

Then, $0 = \frac{\delta\Lambda}{\delta\psi} = \frac{1}{G} \left[\frac{\delta F}{\delta\psi} - \Lambda \frac{\delta G}{\delta\psi} \right]$. The value of Λ at the stationary point is λ , and hence to extremize Λ , it is equivalent to extremizing $F - \lambda G = \int_a^b p\psi'^2 + q\psi^2 - \lambda w\psi^2 dx$. Euler-Lagrange gives us

$$(2p\psi')' - 2q\psi + 2\lambda w\psi = 0$$

which is the SL equation (*) multiplied by 2. The stationary values of the functional

$$\Lambda = \frac{[p\psi\psi']_a^b + \int_a^b -\psi(p\psi')' + \psi q\psi dx}{\int_a^b \psi w\psi dx} = \frac{[p\psi\psi']_a^b + \langle \psi | \mathcal{L}\psi \rangle}{\langle \psi | \psi \rangle_w} = \lambda$$

if $[p\psi\psi']_a^b = 0$ (boundary terms). For this to be true, we choose $\psi(a) = \psi(b) = 0$.

- (ii) Firstly, we need to show the eigenfunctions ψ_i and ψ_j are orthogonal. ψ_i and ψ_j satisfy $\mathcal{L}\psi_i = \lambda_i w\psi_i$ and $\mathcal{L}\psi_j = \lambda_j w\psi_j$ as long as certain boundary conditions are satisfied. In part (i), we have established $\langle \psi_i | \mathcal{L}\psi_j \rangle = \langle \mathcal{L}\psi_i | \psi_j \rangle$, then the LHS gives $\lambda_j \langle \psi_i | \psi_j \rangle_w$ while the RHS gives $\lambda_i^* \langle \psi_i | \psi_j \rangle_w$. Bringing to one side, we have

$$(\lambda_i^* - \lambda_j) \langle \psi_i | \psi_j \rangle_w = 0$$

If $i = j$, since $\langle \psi_i | \psi_i \rangle_w > 0$ then $\lambda_i^* = \lambda_i \in \mathbb{R}$, i.e. the eigenvalues are real. If $i \neq j$, $\lambda_i^* = \lambda_i \neq \lambda_j$, then we have $\langle \psi_i | \psi_j \rangle_w = 0$, i.e. eigenfunctions corresponding to distinct eigenvalues are orthogonal with respect to the inner product with weight w . The eigenfunctions of a SL operator are complete. Assuming the eigenfunctions are also properly normalized, then we can expand a general function ψ in terms of the orthonormal eigenfunctions, i.e. $\tilde{\psi}(x) = \sum_{n=0}^{\infty} c_n \psi_n$.

$$F[\tilde{\psi}] = \left\langle \sum_{p=0}^{\infty} c_p \psi_p | \mathcal{L} \sum_{n=0}^{\infty} c_n \psi_n \right\rangle = \sum_{p=0}^{\infty} \sum_{n=0}^{\infty} c_p^* \lambda_n c_n \langle \psi_p | \psi_n \rangle = \sum_{n=0}^{\infty} \lambda_n |c_n|^2$$

where $\langle \psi_p | \psi_n \rangle = \delta_{p,n}$. And

$$G\tilde{\psi} = \sum_{n=0}^{\infty} |c_n|^2$$

Hence,

$$\Lambda[\tilde{\psi}] = \frac{\sum_{n=0}^{\infty} \lambda_n |c_n|^2}{\sum_{n=0}^{\infty} |c_n|^2} = \frac{\lambda_0 + \sum_{n=1}^{\infty} \lambda_n \frac{|c_n|^2}{|c_0|^2}}{1 + \sum_{n=1}^{\infty} \frac{|c_n|^2}{|c_0|^2}}$$

We thus obtained our desired result with $|a_n|^2 = \frac{|c_n|^2}{|c_0|^2}$. One can use this obtained result to estimate the lowest eigenvalue by guessing a trial function that obeys the boundary conditions. Afterwhich, we extremize Λ with respect to all the parameters it contains.

- (iii) For the Schrodinger equation, we identify $p(x) = 1$, $q(x) = x^2$ and $w(x) = 1$. The trial function is $\tilde{\psi} = xe^{-\alpha x} \implies \tilde{\psi}' = e^{-\alpha x}(1 - \alpha x)$. The following identity will be helpful:

$$I_n(a) = \int_0^{\infty} x^n e^{-ax} dx = \frac{n!}{a^{n+1}}$$

$$F[\tilde{\psi}] = \int_0^{\infty} e^{-2\alpha x} (1 - 2\alpha x + \alpha^2 x^2) + x^4 e^{-2\alpha x} dx = \frac{1}{2\alpha} - 2\alpha \frac{1}{(2\alpha)^2} + \alpha^2 \frac{2!}{(2\alpha)^3} + \frac{4!}{(2\alpha)^5} = \frac{1}{4\alpha} + \frac{3}{4\alpha^5}$$

$$G[\tilde{\psi}] = \int_0^{\infty} x^2 e^{-2\alpha x} dx = \frac{2!}{(2\alpha)^3} = \frac{1}{4\alpha^3}$$

$$\Lambda[\tilde{\psi}] = \frac{F[\tilde{\psi}]}{G[\tilde{\psi}]} = 4\alpha^3 \left(\frac{1}{4\alpha} + \frac{3}{4\alpha^5} \right) = \alpha^2 + \frac{3}{\alpha^2}$$

Then, $0 = \frac{\partial \Lambda}{\partial \alpha} = 2\alpha - 6\alpha^{-3} \implies \alpha = 3^{1/4}$. Thus, the lowest eigenvalue is $\lambda_0 = \sqrt{3} + \frac{3}{\sqrt{3}} = 2\sqrt{3}$.

5.2 Paper 2

Problem 5.11 (Sturm-Liouville):

- (i) The inner product of two functions $f(x)$ and $g(x)$, defined on the closed interval $[a, b]$, is

$$\langle f|g \rangle = \int_a^b f^* g w dx$$

where $w(x) > 0$. Consider the operator

$$\mathcal{L} = -\frac{1}{w(x)} \left[\frac{d}{dx} \left(p(x) \frac{d}{dx} \right) - q(x) \right], \quad a \leq x \leq b$$

where $p(x) > 0$.

- (a) Derive the boundary conditions under which \mathcal{L} is self-adjoint over the range $[a, b]$, with respect to the inner product defined above. [3]
 (b) Show that any two eigenfunctions of \mathcal{L} with distinct eigenvalues are orthogonal. [3]

- (ii) Consider the eigenvalue problem

$$\mathcal{L}y = -x^2 y'' - xy' - y = \lambda y \quad (*)$$

with boundary conditions $y(1) = y(e) = 0$.

- (a) Show that $(*)$ can be written in Sturm-Liouville form and identify the functions $p(x)$, $q(x)$ and $w(x)$. [2]
 (b) Find the eigenvalues and orthonormal eigenfunctions of \mathcal{L} . [6]
 (c) Derive the solution to the inhomogeneous equation $\mathcal{L}y = 1$ as an eigenfunction expansion. [6]

Answer 5.11.

- (i) (a) For \mathcal{L} to be self-adjoint, we require $\langle y_m | \mathcal{L}y_n \rangle = \langle \mathcal{L}y_m | y_n \rangle$.

$$\begin{aligned} \langle y_n | \mathcal{L}y_m \rangle &= - \left[\int_a^b y_n^* \frac{d}{dx} \left(p(x) \frac{dy_m}{dx} \right) - y_n^* q(x) y_m \right] dx \\ &= - \left[- y_n^* p(x) \frac{dy_m}{dx} \right]_a^b + \int_a^b \frac{dy_n^*}{dx} p(x) \frac{dy_m}{dx} dx + \int_a^b y_n^* q(x) y_m dx \\ &= \left[y_n^* p(x) \frac{dy_m}{dx} - y_m \frac{dy_n^*}{dx} p(x) \right]_a^b - \int_a^b y_m \frac{d}{dx} \left(p(x) \frac{dy_n^*}{dx} \right) + y_n^* y_m q(x) dx \end{aligned}$$

We require $p > 0$ at the boundaries $x = a$, $x = b$, as well as, some combination of Neumann, Dirichlet or Cauchy boundary condition to set the boundary terms zero.

- (b) LHS gives $\langle y_j | \lambda_i y_i \rangle$ and RHS gives $\langle \lambda_j^* y_j | y_i \rangle$, then $(\lambda_j^* - \lambda_i) \langle y_j | y_i \rangle = 0$. If $i \neq j$ (distinct eigenvalues), then $\lambda_j \neq \lambda_i \implies \langle y_j | y_i \rangle = 0$, i.e. orthogonal w.r.t inner product.

- (ii) (a) Multiply $(*)$ with an integration factor μ to cast to Sturm-Liouville form

$$\mathcal{L}y = -\frac{1}{\mu(x)} (\mu(x)x^2 y'' + \mu(x)xy' + \mu(x)y) = -\frac{1}{\mu} ((\mu(x)x^2 y')' + \mu(x)y)$$

where we require $\mu'x^2 = -\mu x \implies \mu(x) \propto \frac{1}{x}$. Then, we have $\mathcal{L}y = -x((xy')^2 + \frac{y}{x})$, such that $w(x) = \frac{1}{x}$, $p(x) = x$ and $q(x) = \frac{1}{x}$.

- (b) This is an equidimensional differential equation. We substitute $x = e^t$, such that $\frac{d}{dx} \frac{d}{dx} = e^{-2t}(-\frac{d}{dt} + \frac{d^2}{dt^2})$ and $\frac{d}{dx} = e^{-t} \frac{d}{dt}$, thus we get $\mathcal{L}y = -\frac{d^2 y}{dt^2} - y$, hence

$$\frac{d^2 y}{dt^2} = -(\lambda + 1)y \implies y(x) = A \sin(\sqrt{\lambda + 1} \ln x) + B \cos(\sqrt{\lambda + 1} \ln x)$$

With the boundary conditions $y(1) = 0 \implies B = 0$ and $y(e) = 0 \implies \lambda = n^2 \pi^2 - 1$ for $n \in \mathbb{Z}^+$, i.e. discrete eigenvalues. Hence, to find A , we need to ensure normalization:

$$1 = \langle y | y \rangle_w = \int_1^e |y|^2 \frac{1}{x} dx = |A|^2 \int_0^1 \sin^2(n\pi t) dt = \frac{1}{2} |A|^2 \implies y_n(x) = \sqrt{2} \sin(n\pi \ln x)$$

- (c) Since the eigenfunctions of the Sturm-Liouville operator are complete, write $y = \sum_{n=0}^{\infty} a_n y_n$ such that $1 = \mathcal{L}y = \sum_{n=0}^{\infty} a_n \lambda_n y_n$. Then,

$$\int_1^e w(x) y_p dx = \sum_{n=0}^{\infty} a_n \lambda_n \int_1^e y_p^* y_n w(x) dx \implies \int_0^1 \sqrt{2} \sin(p\pi t) dt = a_p (p^2 \pi^2 - 1)$$

This gives $a_p = 0$ for p even, and $\frac{2\sqrt{2}}{(-1+p^2\pi^2)^{p\pi}}$ for p odd. Hence,

$$y(x) = \frac{4}{\pi} \sum_{n=1}^{\infty} \frac{1}{(2n-1)((2n-1)^2\pi^2 - 1)} \sin((2n-1) \ln x)$$

Problem 5.12 (Laplace's Equation):

- (i) Let $\Psi(r, \theta)$ be an axisymmetric solution of Laplace's equation in spherical polar coordinates,

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \Psi}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \Psi}{\partial \theta} \right) = 0$$

By the method of separation of variables, derive the general solution

$$\Psi(r, \theta) = \sum_{l=0}^{\infty} \left(a_l r^l + \frac{b_l}{r^{l+1}} \right) P_l(\cos \theta)$$

Here, $P_l(\cos \theta)$ is the l th Legendre polynomial, i.e., the solution of the differential equation

$$\frac{d}{dx} \left((1-x^2) \frac{dP_l}{dx} \right) + l(l+1)P_l = 0$$

with $x = \cos \theta$, which is regular at $x = \pm 1$. [8]

- (ii) A surface charge density $\sigma(\theta) = A \sin^2 \theta$ lies on the surface of a sphere of radius R centred on the origin. The electrostatic potential $\Psi(r, \theta)$ satisfies Laplace's equation for $r \neq R$, is continuous and regular everywhere, and tends to zero as $r \rightarrow \infty$. The surface charge causes a discontinuity in the radial gradient of Ψ across $r = R$ given by

$$\lim_{\epsilon \rightarrow 0} \left(\frac{\partial \Psi}{\partial r} \Big|_{R+\epsilon} - \frac{\partial \Psi}{\partial r} \Big|_{R-\epsilon} \right) = -\sigma$$

Determine Ψ for $r < R$ and $r > R$. [12]

[Note: $P_0(x) = 1$ and $P_2(x) = (3x^2 - 1)/2$.]

Answer 5.12.

(i) Use separation of variables: $\Psi(r > R, \theta) = R(r > R)\Theta(\theta)$:

$$\frac{1}{R} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = -\frac{1}{r^2 \sin \theta} \frac{1}{\Theta} \frac{d}{d\theta} \sin \theta \frac{d\Theta}{d\theta} = \frac{\lambda}{r^2}$$

for some constant λ . The angular part gives

$$\lambda \Theta = -\frac{1}{\sin \theta} \frac{d\Theta}{d\theta} = -\frac{1}{\sqrt{1-x^2}} (-\sqrt{1-x^2}) \frac{d}{dx} \left(-(\sqrt{1-x^2})^2 \frac{d\Theta}{dx} \right)$$

where we substitute $x = \cos \theta$. This result is identical to the hint. At $x = \pm 1$, $\Theta(x) = P_l(x)$ with $\lambda = l(l+1)$. The radial part gives

$$\lambda R = \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = 2rR' + r^2 R''$$

Try $R = r^k$, then $k(k+1) = \lambda = l(l+1) \implies k = l, -(l+1)$. Hence,

$$R(r) = a_l r^l + b_l r^{-(l+1)}$$

Fitting them together gives the desired $\Psi(r, \theta)$.

$$\Psi(r, \theta) = \sum_{l=0}^{\infty} \left(a_l r^l + \frac{b_l}{r^{l+1}} \right) P_l(\cos \theta)$$

(ii) For $r < R$: $b_l = 0 \forall l$ since $R(r=0)$ finite. For $r > R$: $a_l = 0 \forall l$ since $\lim_{r \rightarrow \infty} R(r) = 0$. Imposing boundary conditions: Ψ continuous at $r = R$ gives $b_l = a_l R^l R^{l+1} \forall l$, while the discontinuity at $r = R$ for $\frac{\partial \Psi}{\partial r}$ gives

$$-\sum_{l=0}^{\infty} \left(\frac{(l+1)b_l}{R^{l+2}} + a_l R^{l-1} \right) P_l(\cos \theta) = -\sigma = -A(1 - \cos^2 \theta) = \frac{-2A}{3}(P_0 + P_2)$$

Comparing coefficients give

$$\frac{2A}{3} = \frac{b_0}{R^2}, \quad \frac{2A}{3} \frac{3b_2}{R^4} + \frac{2a_2}{R}, \quad (l+1) \frac{b_l}{R^{l+2}} = -la_l R^{l-1} \forall l \neq 0, 2$$

Solving for the coefficients give $b_0 = \frac{2}{3}AR^2$, $b_2 = \frac{2}{15}AR^4$, $a_0 = \frac{2}{3}AR$, $a_2 = \frac{2A}{15R}$ and $a_l = b_l = 0 \forall l \neq 0, 2$.

$$\Psi(r < R, \theta) = \frac{2}{3}ARP_0(\cos \theta) + r^2 \frac{2A}{15R}P_2(\cos \theta) = 2A \left(\frac{R}{3} + \frac{r^2}{15R}(3\cos^2 \theta - 1) \right)$$

$$\Psi(r > R, \theta) = \frac{2AR^2}{3r}P_0(\cos \theta) + \frac{2AR^4}{15r^3}P_2(\cos \theta) = 2A \left(\frac{R^2}{3r} + \frac{R^4}{15r^3}(3\cos^2 \theta - 1) \right)$$

Problem 5.13 (Green's Functions):

- (i) Two scalar functions $\phi(\mathbf{r})$ and $\psi(\mathbf{r})$ are defined in a volume V of three-dimensional space with boundary S . Show that

$$\int_V [\phi \nabla^2 \psi - \psi \nabla^2 \phi] dV = \int_S [\phi \hat{\mathbf{n}} \cdot \nabla \psi - \psi \hat{\mathbf{n}} \cdot \nabla \phi] dS$$

where $\hat{\mathbf{n}}$ is the outward-directed unit normal to S .

[3]

- (ii) Suppose that $\phi(\mathbf{r})$ satisfies

$$\nabla^2 \phi + k^2 \phi = 0$$

for some real and positive k .

- (a) Introducing the Green's function $G(\mathbf{r}, \mathbf{r}')$ that satisfies

$$\nabla^2 G(\mathbf{r}, \mathbf{r}') + k^2 G(\mathbf{r}, \mathbf{r}') = \delta^{(3)}(\mathbf{r} - \mathbf{r}')$$

show that

$$\phi(\mathbf{r}') = \int_S \phi(\mathbf{r}) \hat{\mathbf{n}} \cdot \nabla G(\mathbf{r}, \mathbf{r}') dS$$

for \mathbf{r}' in V and a suitable boundary condition for \mathbf{r} on S that you should specify. For the case that V is all space, show that a suitable Green's function is

$$G(\mathbf{r}, \mathbf{r}') = A \frac{e^{ik|\mathbf{r}-\mathbf{r}'|}}{|\mathbf{r}-\mathbf{r}'|}$$

where the constant A should be determined.

[10]

- (b) Determine the Green's function for the case that V is the half-space $z \geq 0$.

Assuming that ϕ falls to zero sufficiently rapidly as $|\mathbf{r}| \rightarrow \infty$, show that

$$\phi(\mathbf{r}') = -\frac{ik}{2\pi} \int_{z=0} \frac{e^{ikR}}{R} \left(1 + \frac{i}{kR}\right) \cos \theta \phi(\mathbf{r}) dS$$

where R is the magnitude of $\mathbf{R} = \mathbf{r}' - \mathbf{r}$, which makes an angle θ with the positive z -direction, and the integral is over the plane $z = 0$.

[7]

Answer 5.13.

(i) Invoke Divergence Theorem to $\phi \nabla \psi$ and $\psi \nabla \phi$ separately:

$$\begin{aligned}\int_{\partial V} \phi \nabla \psi \cdot d\mathbf{S} &= \int_V \nabla \cdot (\phi \nabla \psi) dV = \int_V \phi \nabla^2 \psi + \nabla \phi \cdot \nabla \psi dV \\ \int_{\partial V} \psi \nabla \phi \cdot d\mathbf{S} &= \int_V \nabla \cdot (\psi \nabla \phi) dV = \int_V \psi \nabla^2 \phi + \nabla \psi \cdot \nabla \phi dV\end{aligned}$$

Take the difference :

$$\int_V \phi \nabla^2 \psi - \psi \nabla^2 \phi dV = \int_{\partial V} (\phi \nabla \psi - \psi \nabla \phi) \cdot d\mathbf{S}$$

(ii) (a) We set $G \rightarrow 0$ on S as $|\mathbf{r}| \rightarrow \infty$. From the result in part (i), let $\psi = G$, then adding $k^2 G \psi - k^2 \psi G$:

$$\int_V \phi (\nabla^2 + k^2) G - G (\nabla^2 + k^2) \phi dV = \int_{\partial V} (\phi \nabla G - \psi \nabla G) \cdot d\mathbf{S}$$

where LHS is $\int_V \phi(\mathbf{r}) \delta^{(3)}(\mathbf{r} - \mathbf{r}') - 0 dV$ and RHS is $\int_V (\phi(\mathbf{r}) \nabla G - 0) \cdot d\mathbf{S}$

$$\phi(\mathbf{r}') = \int_S \phi(\mathbf{r}) \nabla G(\mathbf{r}, \mathbf{r}') \cdot d\mathbf{S}$$

Since the problem has spherical symmetry (V is all space), then $G(\mathbf{r}, \mathbf{r}') = G(|\mathbf{r} - \mathbf{r}'|) = G(r)$. We check the suggested solution is indeed a solution:

$$\nabla_{\mathbf{r}}^2 G = \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dG}{dr} \right) = \frac{A}{r^2} e^{ikr} \frac{d}{dr} (-1 + ikr) = -k^2 G$$

To find A , we use Divergence Theorem for a sphere of radius ϵ centred on the origin, $V = \{|\mathbf{r}| = \epsilon\}$.

$$\int_V \nabla^2 G dV + k^2 \int_V G dV = \int_V \delta(r) dV \implies \lim_{\epsilon \rightarrow 0} \frac{dG}{dr} \Big|_{r=\epsilon} 4\pi \epsilon^2 = 1 \implies 1 = - \lim_{\epsilon \rightarrow 0} A e^{-k\epsilon} (\epsilon^{-1} + k) 4\pi \epsilon$$

Then after taking $\epsilon \rightarrow 0$, we have $A = -\frac{1}{4\pi}$.

(b) For V being the half-space, we have a further condition $G(z=0) = 0$ and $G \rightarrow 0$ as $|\mathbf{r}| \rightarrow \infty$. By Uniqueness Theorem, we use the method of images. We replace the original problem with one involving images. This is valid as long as the boundary condition is still satisfied and (*) is still satisfied everywhere on V (i.e. add images outside of V). Since the solution is unique, this must be the solution to the original problem.

To preserve the mirror symmetry of the problem (about $z=0$ plane), we place an image of opposing strength at \mathbf{r}' where \mathbf{r}' and \mathbf{r} are related to each other with the z -component flipped. Then, the corresponding G of this modified problem satisfies

$$(\nabla^2 - k^2)G = \delta^{(3)}(\mathbf{r} - \mathbf{r}_0) - \delta^{(3)}(\mathbf{r} - \mathbf{r}')$$

Since the PDE is linear, the solution will be a linear combination of that found earlier:

$$G = \frac{1}{4\pi} \left(\frac{e^{ik|\mathbf{r} - \mathbf{r}_0|}}{|\mathbf{r} - \mathbf{r}_0|} - \frac{e^{ik|\mathbf{r} - \mathbf{r}'|}}{|\mathbf{r} - \mathbf{r}'|} \right)$$

Then we have

$$\frac{\partial G}{\partial z} \Big|_{z=0} = \frac{1}{4\pi} \left[\left(\frac{ike^{ikR}}{R} - \frac{e^{ikR}}{R^2} \right) (-\cos\theta) - \left(\frac{ike^{ikR}}{R} - \frac{e^{ikR}}{R^2} \right) \cos\theta \right] = -\frac{e^{ikR \cos\theta}}{2\pi} \left(\frac{ik}{R} - \frac{1}{R^2} \right)$$

where $R = \sqrt{(x-x')^2 + (y-y')^2 + z'^2}$. Plugging it back to a previous result, we get our desired result.

$$\phi(\mathbf{r}') = - \int_S \phi(\mathbf{r}) \frac{e^{ikR \cos\theta}}{2\pi} \left(\frac{ik}{R} - \frac{1}{R^2} \right) dS = \frac{-ik}{2\pi} \int_S \phi(\mathbf{r}) e^{ikR \cos\theta} \left(\frac{1}{R} + \frac{i}{kR^2} \right) dS$$

Problem 5.14 (Contour Integration):

- (i) (a) For real
- a
- and
- b
- , with
- $a > b > 0$
- , show that

$$z^2 + 2i(a/b)z - 1 = 0$$

has a single solution within the unit circle $|z| = 1$ in the complex plane. [4]

- (b) By evaluating a suitable contour integral, show that

$$\int_0^{2\pi} \frac{d\theta}{a + b \sin \theta} = \frac{2\pi}{\sqrt{a^2 - b^2}}$$

for real a and b , with $a > b > 0$. [6]

- (ii) By integrating the complex function

$$f(z) = \frac{\ln(z+i)}{z^2+1}$$

along the real axis, evaluate the real integral [10]

$$\int_0^\infty \frac{\ln(x^2+1)}{x^2+1} dx$$

Answer 5.14.

- (i) (a) The solution to the quadratic equation is

$$z_{\pm} = \frac{-2ia/b \pm \sqrt{-4(a^2/b^2) + 4}}{2} = -i\frac{a}{b} \pm \sqrt{1 - \frac{a^2}{b^2}} = -i\frac{a}{b} \left[-1 \pm \sqrt{1 - (b/a)^2} \right]$$

Since $a > b > 0$, we must have $|z_+| < 1$ and $|z_-| > 1$, hence z_+ lies inside the unit circle $|z| = 1$.

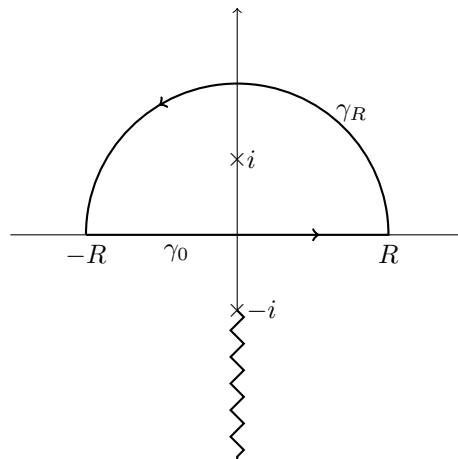
- (b) Parametrize the contour
- $\gamma = \{z : |z| = 1\}$
- (chosen to be a unit circle) as
- $z = e^{i\theta}$
- , then the integral becomes

$$\int_0^{2\pi} \frac{d\theta}{a + b \sin \theta} = \oint_{\gamma} \frac{1}{a + \frac{b}{2i}(z - z^{-1})} \frac{dz}{iz} = \frac{2}{b} \oint_{\gamma} \frac{1}{-2i\frac{a}{b}z + z^2 - 1} dz$$

Use residue theorem to evaluate the contour integral:

$$\frac{2}{b} 2\pi i \operatorname{res}_{z=z_+} \frac{1}{(z - z_+)(z - z_-)} = \frac{4\pi i}{b(z_+ - z_-)} = \frac{2\pi}{\sqrt{a^2 - b^2}}$$

- (ii)
- $f(z)$
- has simple pole at
- $z = i$
- and essential branch singularity at
- $z = -i$
- . Take the branch cut from
- $z = -i$
- to
- $-\infty$
- along the imaginary axis. Then, close the upper-half plane.



The contour $\gamma = \gamma_R \cup \gamma_0$ encloses the simple pole. Parametrize the contours as $\gamma_0 : z = x$ and $\gamma_R : z = Re^{i\theta}$. The contour integrals are

$$\int_{\gamma_0} f(z)dz = \int_{-\infty}^{\infty} \frac{1}{2} \frac{\ln[(x^2+1)e^{i \tan^{-1}(1/x)}]}{2(x^2+1)} dx = \int_0^{\infty} \frac{\ln(x^2+1)}{x^2+1} dx + \int_{-\infty}^0 \frac{i \tan^{-1}(1/x)}{2(1+x^2)} dx$$

$$\begin{aligned} \int_{\gamma_R} f(z)dz &= \int_0^{\pi} \frac{\ln(Re^{i\theta} + i)}{R^2 e^{2i\theta} + 1} iRe^{i\theta} d\theta \\ &= \int_0^{\pi} \ln \left[Re^{i\theta} \left(1 + \frac{ie^{-i\theta}}{R} \right) \right] \frac{i}{Re^{i\theta}} \left(1 + R^{-1}e^{-i\theta} \right)^{-1} d\theta \\ &= \int_0^{\pi} \left[\ln(Re^{i\theta}) + \frac{ie^{-i\theta}}{R} + O(R^{-2}) \right] \left[\frac{i}{Re^{i\theta}} + O(R^{-2}) \right] d\theta \\ &= O(\ln(R)/R) \rightarrow 0 \end{aligned}$$

as $R \rightarrow \infty$. The residue of the enclosed pole is

$$\text{res}_{z=i} f(z) = \lim_{z \rightarrow i} \frac{\ln(z+i)}{z^2+1} (z-i) = \frac{\ln 2 + i(\pi/2)}{2i} = \frac{\ln 2}{2i} + \frac{\pi}{4}$$

Hence, by residue theorem,

$$2\pi i \text{res}_{z=i} f(z) = \int_{\gamma_0 \cup \gamma_R} f(z)dz = \int_{\gamma_0} f(z)dz$$

LHS is $\pi \ln 2 + \frac{\pi^2}{2}i$ and RHS is $\int_0^{\infty} \frac{\ln(x^2+1)dx}{x^2+1} + \int_{-\infty}^0 \frac{i \tan^{-1}(1/x)}{2(1+x^2)} dx$. Comparing the real parts, we get

$$\int_0^{\infty} \frac{\ln(x^2+1)dx}{x^2+1} = \pi \ln 2$$

Problem 5.15 (Fourier Transform): The Fourier transform in x of a function $u(x, t)$ is given by

$$\tilde{u}(k, t) = \int_{-\infty}^{\infty} u(x, t) e^{-ikx} dx \quad (*)$$

(i) Consider the following partial differential equation for $u(x, t)$:

$$\frac{\partial^2 u}{\partial t^2} + 2\gamma \frac{\partial u}{\partial t} + \gamma^2 u = c^2 \frac{\partial^2 u}{\partial x^2} \quad (**)$$

where γ and c are real constants. Write down the corresponding ordinary differential equation for $\tilde{u}(k, t)$ defined in (*). You may assume that u and its derivatives vanish as $|x| \rightarrow \infty$. [2]

(ii) Seeking solutions of the form e^{rt} for constant r , find the general solution to the Fourier transform of (**) for $\tilde{u}(k, t)$, and hence find the general solution for $u(x, t)$. [8]

(iii) Solve (**) for $u(x, t)$ subject to the following initial conditions at $t = 0$: [10]

$$u = e^{-|x|} \text{ and } \frac{\partial u}{\partial t} = 0$$

Answer 5.15.

- (i) Assume u , $\frac{\partial u}{\partial x}$ and $\frac{\partial u}{\partial t}$ all vanish as $|x| \rightarrow \infty$, then $\mathcal{F}[\frac{\partial^2 u}{\partial t^2}] = \frac{\partial^2 \tilde{u}}{\partial t^2}$, $\mathcal{F}[\frac{\partial^2 u}{\partial x^2}] = -k^2 \tilde{u}$ and $\mathcal{F}[\frac{\partial u}{\partial t}] = \frac{\partial \tilde{u}}{\partial t}$. Hence, perform Fourier transform on $(**)$ gives

$$\frac{d^2 \tilde{u}}{dt^2} + 2\gamma \frac{d\tilde{u}}{dt} + (\gamma^2 + (ck)^2) \tilde{u} = 0$$

- (ii) Try $\tilde{u} = e^{rt}$, then we have $r = -\gamma \pm ick$. The solution to the Fourier transform of $(**)$ is

$$\tilde{u}(k, t) = A(k)e^{(-\gamma - ick)t} + B(k)e^{(-\gamma + ick)t}$$

Perform inverse Fourier transform,

$$u(x, t) = \frac{e^{-\gamma t}}{2\pi} \int_{-\infty}^{\infty} [A(k)e^{ik(x-ct)} + B(k)e^{ik(x+ct)}] dk$$

- (iii) Fourier transform the initial conditions

$$\begin{aligned} \tilde{u}(k, 0) &= \int_{-\infty}^{\infty} e^{-|x|} e^{-ikx} dx \\ &= \int_{-\infty}^0 e^{-x(ik-1)} dx + \int_0^{\infty} e^{-x(ik+1)} dx \\ &= \frac{1}{1+ik} + \frac{1}{1-ik} \\ &= \frac{2}{1+k^2} \end{aligned}$$

So, $\tilde{u}(k, 0) = A(k) + B(k) = \frac{2}{1+k^2}$. Similarly,

$$A(k)(-\gamma - ick) + (-\gamma + ick)B(k) = \frac{\partial \tilde{u}(k, 0)}{\partial t} = 0$$

We must have

$$A(k) = \frac{1}{1+k^2} \left(1 - \frac{\gamma}{ick}\right), \quad B(k) = \frac{1}{1+k^2} \left(1 + \frac{\gamma}{ick}\right)$$

Let $u(x, 0) = f(x) = e^{-|x|}$, then the general solution would then be

$$\begin{aligned} u(x, t) &= \frac{e^{-\gamma t}}{2\pi} \int_{-\infty}^{\infty} \frac{1}{2} \mathcal{F}[f(x)] (e^{ik(x-ct)} + e^{ik(x+ct)}) + \frac{\gamma}{c} \frac{\mathcal{F}[f(x)]}{2ik} (e^{ik(x+ct)} - e^{ik(x-ct)}) dk \\ &= e^{-\gamma t} \left[\frac{1}{2} f(x-ct) + \frac{1}{2} f(x+ct) + \frac{\gamma}{2c} (F(x+ct) - F(x-ct)) \right] \end{aligned}$$

where $\frac{\mathcal{F}[f(x)]}{ik} = \mathcal{F}[F]$ such that $F' = f$, and using inverse Fourier transform:

$$\begin{aligned} \frac{1}{2\pi} \int_{-\infty}^{\infty} \mathcal{F}[f(x)] e^{ik(x \pm ct)} dk &= f(x \pm ct) = e^{-|x \pm ct|} \\ \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{\mathcal{F}[f(x)]}{ik} e^{ik(x \pm ct)} dk &= F(x \pm ct) \end{aligned}$$

The integral of $f(x) = e^{-|x|}$ is

$$F(x) = \frac{|x|}{x} (1 - e^{-|x|})$$

One can check by differentiating back, taking note of the two regimes $x > 0$ and $x < 0$. Also, check

$$\mathcal{F}[F] = \mathcal{F}[|x|/x] - \mathcal{F}[|x|e^{-|x|}/x] = \frac{2}{ik} - \frac{2ik}{1+k^2} = \frac{2}{ik(1+k^2)} = \frac{1}{ik} \mathcal{F}[f]$$

hence, the general solution is

$$u(x, t) = \frac{e^{-\gamma t}}{2} \left[e^{-|x-ct|} + e^{-|x+ct|} + \frac{\gamma}{c} \left(\frac{|x+ct|}{x+ct} (1 - e^{-|x+ct|}) - \frac{|x-ct|}{x-ct} (1 - e^{-|x-ct|}) \right) \right]$$

Problem 5.16 (Tensors):

- (i) Write down the transformation law for a tensor of order n . Use this to define an isotropic tensor. [2]
- (ii) Consider a three-dimensional vector field with Cartesian components u_i . Show that $\frac{\partial u_i}{\partial x_j}$ is an order 2 tensor. [4]
- (iii) Write down the transformation law for an axial vector. Under what conditions does an axial vector obey the same transformation law as a vector? Show that the curl of u_i is an axial vector field. [6]
- (iv) Show that $\frac{\partial u_i}{\partial x_j}$ can be decomposed into the following terms

$$\frac{\partial u_i}{\partial x_j} = p\delta_{ij} + s_{ij} + \epsilon_{ijk}\omega_k \quad (*)$$

where s_{ij} is a symmetric, traceless tensor, ω_k is an axial vector field, ϵ_{ijk} is the Levi-Civita symbol, and δ_{ij} is the Kronecker delta. Find p , s_{ij} , and ω_k , expressed in terms of u_i . [4]

- (v) Consider the three-dimensional vector field

$$u_i = (ax_2, bx_1, 0)$$

where a and b are constants. Find ω_k and the principal values and principal axes of s_{ij} , where ω_k and s_{ij} are defined in (*). [4]

Answer 5.16.

- (i) The transformation law for a tensor of order n :

$$T'_{i_1 i_2 \dots i_n} = (\det L)^p L_{i_1 j_1} L_{i_2 j_2} \dots L_{i_n j_n} T_{j_1 j_2 \dots j_n}$$

where $p = 1$ for pseudotensors and $p = 0$ otherwise.

An isotropic tensor has its components to be the same in all frames, i.e. $T'_{i_1 i_2 \dots i_n} = T_{i_1 i_2 \dots i_n}$.

- (ii) $\frac{\partial u_i}{\partial x_j}$ transform like

$$\left(\frac{\partial u_i}{\partial x_j} \right)' = \frac{\partial L_{i\alpha} u_\alpha}{\partial x_\beta} L_{j\beta}$$

hence a rank-two tensor.

- (iii) The transformation law for an axial vector is $u'_i = \det L L_{i\alpha} u_\alpha$. When the transformation involves an even number of reflections (recall any rotation can be constructed out of an even number of reflections), then $\det L = 1$, so $u'_i = L_{i\alpha} u_\alpha$ and thus transforms like a normal vector.

The curl of u_i transforms like

$$[\nabla \times \mathbf{u}]'_i = \epsilon_{ijk} \nabla'_j u'_k = \epsilon'_{ijk} L_{j\alpha} L_{k\beta} \nabla_\alpha u_\beta$$

Now how does the Levi-Civita tensor transforms? ϵ_{ijk} is a pseudotensor and transforms like

$$\epsilon'_{ijk} = \det L \epsilon_{\alpha\beta\gamma} L_{i\alpha} L_{j\beta} L_{k\gamma}$$

Then by the general definition of determinant:

$$\epsilon_{\alpha\beta\gamma} \det L = \epsilon_{ijk} L_{i\alpha} L_{j\beta} L_{k\gamma}$$

Hence,

$$\epsilon'_{ijk} = \det(L) \epsilon_{\alpha\beta\gamma} L_{i\alpha} L_{j\beta} L_{k\gamma} = (\det L)^2 \epsilon_{ijk}$$

Since L is orthogonol, $\det L = \pm 1 \implies \det(L)^2 = 1 \implies \epsilon'_{ijk} = \epsilon_{ijk}$. Now, we have

$$\epsilon_{\alpha\beta\gamma} \det L L_{i\gamma} = \epsilon_{jks} L_{j\alpha} L_{k\beta} L_{s\gamma} L_{i\gamma} = \epsilon_{jki} L_{j\alpha} L_{k\beta} = \epsilon'_{ijk} L_{j\alpha} L_{k\beta} \implies [\nabla \times \mathbf{u}]'_i = L_{i\gamma} \det L \epsilon_{\alpha\beta\gamma} \nabla_\alpha u_\beta$$

Hence, $\nabla \times \mathbf{u}$ transforms like an axial-vector.

(iv) We decompose a general rank-two matrix T :

$$T_{ij} = S_{ij} - \frac{\text{Tr}(S)}{\text{Tr}(I)}\delta_{ij} + \frac{\text{Tr}(S)}{\text{Tr}(I)}\delta_{ij} + A_{ij}$$

where $S = \frac{1}{2}(T + T^T)$ is a symmetric tensor (further decomposed to extract a traceless tensor and an isotropic tensor) and $A = \frac{1}{2}(T - T^T)$ is an anti-symmetric tensor. But an anti-symmetric rank-two tensor is also equivalent to an axial-vector, i.e. $A_{ij} = \epsilon_{ijk}\omega_k$. Then

$$\epsilon_{ijl}A_{ij} = \epsilon_{ijl}\epsilon_{ijk}\omega_k = (\delta_{jj}\delta_{lk} - \delta_{jk}\delta_{lj})\omega_k = (3\delta_{lk} - \delta_{kl})\omega_k = 2\delta_{lk}\omega_k \implies \omega_k = \frac{1}{2}\epsilon_{ijk}A_{ij}$$

By inspection, we see that

$$s_{ij} = \frac{1}{2}\left(\frac{\partial u_i}{\partial x_j} - \frac{\text{Tr}(\nabla \mathbf{u})}{\text{Tr}(I_{2 \times 2})}\delta_{ij}\right), \quad p = \frac{\text{Tr}(\nabla \mathbf{u})}{\text{Tr}(I_{2 \times 2})}, \quad \omega_k = \frac{1}{2}\epsilon_{ijk}\frac{1}{2}\left(\frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i}\right)$$

(v) We have

$$\nabla \mathbf{u} = \begin{pmatrix} 0 & a & 0 \\ b & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \implies \text{Tr}[\nabla \mathbf{u}] = 0 \implies p = 0$$

$$s = \frac{a+b}{2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

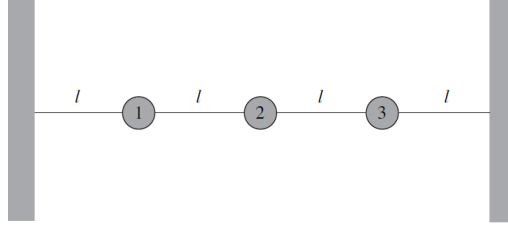
$$\omega = \frac{a-b}{2} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

The principal values and axes of s_{ij} are the eigenvalues and the eigenvectors respectively.

$$0 = \det[s_{ij} - \lambda I] = \det \begin{pmatrix} -\lambda & (a+b)0.5 & 0 \\ 0.5(a+b) & -\lambda & 0 \\ 0 & 0 & -\lambda \end{pmatrix} \implies \lambda = 0, \pm \frac{1}{2}(a+b)$$

By inspection, the eigenvectors are respectively $(0, 0, 1)^T$ and $(\pm 1, 1, 0)^T$. Observe that one of the eigenvector is parallel to ω .

Problem 5.17 (Normal Modes): A loaded string, sketched below, consists of a string stretched tightly between two vertical walls with three beads of equal mass m , numbered 1, 2, and 3 as shown, attached at regular intervals with spacing l . Assume the beads are constrained to move vertically and that the tension in the string, τ , is positive and constant. Let z_i be the upward displacement of the i th bead



- (i) For small displacements, $|z_i| \ll l$, the potential energy, V , stored in the string is

$$V = \frac{\tau}{2l}(z_1^2 + (z_1 - z_2)^2 + (z_2 - z_3)^2 + z_3^2)$$

Find the normal modes of oscillation and their associated frequencies. Sketch the displacements associated with each normal mode. [12]

- (ii) At time $t = 0$, bead 2 is displaced upwards by a distance a , so that $z_2 = a$, while the other beads are at their equilibrium positions ($z_1 = z_3 = 0$), and all beads are initially at rest. Find the subsequent time evolution of the displacement of each bead, and describe the motion in terms of the normal modes. [8]

Answer 5.17.

- (i) Expressing the potential and kinetic energies in quadratic form:

$$V = \frac{\tau}{2l} \begin{pmatrix} z_1 & z_2 & z_3 \end{pmatrix} \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \\ z_3 \end{pmatrix} := \frac{\tau}{2l} \mathbf{z}^T \mathcal{V} \mathbf{z}$$

$$T = \frac{m}{2} \begin{pmatrix} \dot{z}_1 & \dot{z}_2 & \dot{z}_3 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \dot{z}_1 \\ \dot{z}_2 \\ \dot{z}_3 \end{pmatrix} := \frac{1}{2} m \dot{\mathbf{z}}^T \mathcal{T} \dot{\mathbf{z}}$$

The Lagrangian is $\mathcal{L} = T - V$ and is extremized by the Euler-Lagrange equation $\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\mathbf{z}}} = \frac{\partial \mathcal{L}}{\partial \mathbf{z}}$, then the equation of motion is $\mathcal{T} \ddot{\mathbf{z}} = -\mathcal{V} \mathbf{z}$, where T is time-independent. We look for solutions of the form $\mathbf{z}(t) = \mathbf{e} e^{i\omega t}$:

$$\begin{aligned} 0 &= \det(\mathcal{V} - \omega^2 \mathcal{T}) \\ &= \det \begin{pmatrix} 2(\tau/l) - \omega^2 m & -(\tau/l) & 0 \\ -(\tau/l) & 2(\tau/l) - \omega^2 m & -(\tau/l) \\ 0 & -(\tau/l) & 2(\tau/l) - \omega^2 m \end{pmatrix} \\ &= (2(\tau/l)u - \omega^2 m)(2(\tau/l)^2 - 4(\tau/l)\omega^2 m + m^2\omega^4) \end{aligned}$$

The solutions are $\omega_0^2 = \frac{2\tau}{ml}$, $\omega_{\pm}^2 = \frac{\tau}{ml}(2 \pm \sqrt{2})$ with their corresponding normalized eigenvectors $\mathbf{e}_0 = \frac{1}{\sqrt{2m}}(1, 0, -1)^T$ and $\mathbf{e}_{\pm} = \frac{1}{2\sqrt{m}}(1, \mp\sqrt{2}, 1)^T$. For the mode with frequency ω_0 , the centre mass is stationary and the outer masses are in anti-phase (one up, one down). For the mode with frequency ω_{\pm} , the outer masses are in phase, with the centre mass either in-phase or anti-phase, with a relative amplitude of $\sqrt{2}$.

- (ii) The general solution is

$$\mathbf{z}(t) = \text{Re}[c_0 \mathbf{e}_0 e^{i\omega_0 t} + c_+ \mathbf{e}_+ e^{i\omega_+ t} + c_- \mathbf{e}_- e^{i\omega_- t}]$$

The initial conditions are $\mathbf{z}(0) = (0, a, 0)^T$ and $\dot{\mathbf{z}}(0) = \mathbf{0} \implies c_0, c_{\pm} \in \mathbb{R}$. We exploit orthogonality:

$$c_0 = \mathbf{e}_0 \cdot \mathbf{z}(t=0) = 0, \quad c_{\pm} = \mathbf{e}_{\pm} \cdot \mathbf{z}(t=0) = \pm a \sqrt{\frac{m}{2}}$$

Hence,

$$\mathbf{z}(t) = \frac{a}{\sqrt{2}} \cos \frac{\tau}{ml} (2 - \sqrt{2})t \begin{pmatrix} 1 \\ \sqrt{2} \\ 1 \end{pmatrix} - \frac{a}{\sqrt{2}} \cos \frac{\tau}{ml} (2 + \sqrt{2})t \begin{pmatrix} 1 \\ -\sqrt{2} \\ 1 \end{pmatrix}$$

Problem 5.18 (Group Theory):

- (i) Let G be a finite group. The centre $Z(G)$ of G is the set of elements $z \in G$ that commute with every element $g \in G$, i.e.,

$$Z(G) = \{z \in G | gz = zg, \forall g \in G\}$$

Prove that $Z(G)$ is a subgroup of G .

[8]

- (ii) Let C_n be the order n cyclic group.

- (a) Determine whether the product group $C_2 \times C_3$ is isomorphic to the group C_6 . Do the same for $C_2 \times C_4$ and C_8 .

[8]

- (b) What condition do the integers n and m have to satisfy in order for $C_n \times C_m$ to be isomorphic to $C_{n \times m}$?

[4]

Answer 5.18.

- (i) Check subgroup axioms:

- Closure: For any $z_1, z_2 \in Z$, then $gz_1z_2g^{-1} = gz_1g^{-1}gz_2g^{-1} = z_1z_2 \implies z_1z_2 \in Z$.
- Associativity: Inherited from G .
- Identity: For $e \in G$, $geg^{-1} = gg^{-1} = e \implies e \in Z$.
- Inverse: For any $z \in Z$, $gz^{-1}g^{-1} = (gzg^{-1})^{-1} = z^{-1} \implies z^{-1} \in Z$.

- (ii) (a) Let $C_2 = \{e, a\}$, $C_3 = \{e, b, b^2\}$, then

$$C_2 \times C_3 = \{(e, e), (e, b), (e, b^2), (a, e), (a, b), (a, b^2)\}$$

where (e, e) is the identity. The generator of (a, b) is

$$\langle (a, b) \rangle = \{(a, b), (e, b^2), (a, e), (e, b), (a, b^2), (a^2, e)\}$$

so $\text{ord}((a, b)) = 6$ and hence $C_2 \times C_3 \simeq C_6$. Closure is satisfied. The inverse of (e, b) , (a, e) and (a, b) respectively are (e, b^2) , (a, e) and (a, b^2) . Associativity is inherited from C_2 and C_3 .

Again, let $C_4 = \{e, c, c^2, c^3\}$ and so

$$C_2 \times C_4 = \{(e, e), (e, c), (e, c^2), (e, c^3), (a, e), (a, c), (a, c^2), (a, c^3)\}$$

Then, $\langle (a, c) \rangle = \{(a, c), (e, c^2), (a, c^3), (e, e)\}$ and so $\text{ord}((a, c)) = 4$, which happens to be $\text{lcm}(2, 4)$. Thus, $C_2 \times C_4$ is not isomorphic to C_8 .

- (b) For $(a^p, b^q) \in C_n \times C_m$, say $\text{ord}((a^p, b^q)) = r$, then

$$(e, e) = (a^p, b^q)^r = (a^{pr}, b^{qr})$$

we require $pr = 0$ and $qr = 0 \pmod n$ and m respectively. Thus, $r = \text{lcm}(n, m)$.

Problem 5.19 (Group Theory):

- (i) State Lagrange's theorem relating the order of a group to the orders of its subgroups. [2]
- (ii) The symmetry group D_N of a regular N -sided polygon is generated by elements R and m , with $R^N = I$, $m^2 = I$ and $Rm = mR^{-1}$.
 - (a) List the distinct group elements of D_5 and indicate the geometric action of all order 2 elements on a sketch. [5]
 - (b) Find all proper subgroups of D_5 . [4]
 - (c) Explain the notion of a conjugacy class of a finite group and determine the conjugacy classes of D_5 . Determine which of the proper subgroups of D_5 are normal. [9]

Answer 5.19.

(i) Lagrange's theorem states that for $H \leq G$, $\frac{|G|}{|H|} \in \mathbb{N}$.

(a) The group D_5 is

$$D_5 = \{I, R, R^2, R^3, R^4, m, mR, mR^2, mR^3, mR^4\}$$

The order 2 groups are $\{I, m\}$, $\{I, mR\}$, $\{I, mR^2\}$, $\{I, mR^3\}$ and $\{I, mR^4\}$ since $(mR^n)^2 = \text{Id} \ \forall n \in \mathbb{N}$. The generator $\langle m \rangle$ flips the pentagon about an axis passing through the centre, while the generators $\langle mR^n \rangle$ flips the pentagon followed by a rotation of $\frac{n2\pi}{5}$ radians about the centre, in the plane of the pentagon.

(b) The proper subgroups of D_5 are

$$\{I, m\}, \quad \{I, mR\}, \quad \{I, mR^2\}, \quad \{I, mR^3\}, \quad \{I, mR^4\}$$

(c) The conjugacy class of $h \in G$ (written as $\text{ccl}(h)$) is

$$\text{ccl}(h) := \{k \in G \text{ such that } k = ghg^{-1} \text{ for some } g \in G\}$$

$g * h = ghg^{-1}$ is said to be the conjugate action. If g_i is conjugate to g_j , write $g_i \sim g_j$, where $hg_ih^{-1} = g_j$ for some $h \in G$. This action is transitive, i.e. $g_1 \sim g_2, g_2 \sim g_3 \implies g_1 \sim g_3$:

$$h_1g_1h_1^{-1} = g_2 = h_2g_2h_2^{-1} = (h_2^{-1}h_1)g_1(h_2^{-1}h_1)^{-1} = g_3 \implies g_1 \sim g_3$$

Furthermore, if two elements are conjugate to each other, they must be of the same order. Let $|g_1| = p$, $|g_2| = q$, then

$$e = g_2^q = (h_1g_1h_1^{-1})^q = h_1g_1^qh_1^{-1} \implies h_1^{-1}eh_1 = g_1^q \implies e = g_1^q$$

Hence, $q = np$ for $n \in \mathbb{Z}^+$. Similarly, $p = mq$ for $m \in \mathbb{Z}^+$. Hence, $p = q$.

Lastly, any element that commutes with all other elements is in a conjugacy class of its own.

$$g_ihg_i^{-1} = hg_ih_i^{-1} = he = h \ \forall i$$

The conjugacy classes of D_5 are

$$\{I\}, \quad \{R, R^4\}, \quad \{R^2, R^3\}, \quad \{m, mR, mR^2, mR^3, mR^4\}$$

A normal subgroup H has the property that its left and right cosets are the same, i.e. $g_iH = Hg_i \ \forall g_i$, so $g_iHg_i^{-1} = H$, which means that H is built out of the union of complete conjugacy classes. In general, it can be shown that if $H \leq G$ such that $|H| = \frac{1}{2}|G|$, then $H \triangleleft G$, so

$$\{I, R, R^2, R^3, R^4\}$$

is a normal subgroup of D_5 . This is the only proper normal subgroup.

Problem 5.20 (Representation Theory):

- (i) Explain what is meant by a representation D of a group G . Define the terms faithful representation, equivalent representation, and the character of a representation. [4]
- (ii) Construct the group table for the order 4 cyclic group $C_4 = \{I, a, a^2, a^3\}$. [4]
- (iii) Consider the following faithful representations of C_4 :

$$D_1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad D_2 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad D_3 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \quad D_4 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

and

$$E_1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad E_2 = \begin{pmatrix} i & 0 \\ 0 & i \end{pmatrix}, \quad E_3 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \quad E_4 = \begin{pmatrix} -i & 0 \\ 0 & -i \end{pmatrix}$$

Determine whether the representations D and E are equivalent or inequivalent, clearly justifying your answer. Find the characters of each representation. [4]

- (iv) Consider a three-dimensional representation, T , of C_4 for which the element a is represented by

$$T(a) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & b \\ 0 & c & 0 \end{pmatrix}$$

What are the conditions on the real constants b and c such that T is: (1) a faithful representation; and (2) an unfaithful representation of C_4 ? [8]

Answer 5.20.

- (i) A representation D of a group G is a homomorphism between elements of the group and a set of invertible matrices. The definitions are:

- A faithful representation is an injective homomorphism, i.e. the identity matrix only has one pre-image (trivial kernel).
- Two representations D and D' are equivalent if \exists a similarity transformation S such that $D'(g_i) = SD(g_i)S^{-1} \forall i$.
- The character of a representation is the vector of the traces of the matrices used to represent the elements.

- (ii) The group table of C_4 is

	I	a	a^2	a^3
I	I	a	a^2	a^3
a	a	a^2	a^3	I
a^2	a^2	a^3	I	a
a^3	a^3	I	a	a^2

- (iii) Equivalent representations must have the same characters as the trace is invariant under cyclic permutations: $\forall g_i$, we have

$$\text{Tr}(D'(g_i)) = \text{Tr}(SD(g_i)S^{-1}) = \text{Tr}(S^{-1}SD(g_i)) = \text{Tr}(D(g_i))$$

Since $\text{Tr}(E_2), \text{Tr}(E_4) \in \mathbb{C}$, while $\text{Tr}(D_i) \in \mathbb{R} \forall i$, then no similarity transformation can be found. The characters are $\chi_D = \{2, 0, -2, 0\}$ and $\chi_E = \{2, -2, 2i, -2i\}$.

- (iv) Since T is a representation, it must be a homomorphic mapping. We have

$$T(a) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & b \\ 0 & c & 0 \end{pmatrix}, \quad T(a)^2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & bc & 0 \\ 0 & 0 & bc \end{pmatrix}, \quad T(a)^3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & b^2c \\ 0 & bc^2 & 0 \end{pmatrix}, \quad T(a)^4 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & b^2c^2 & 0 \\ 0 & 0 & b^2c^2 \end{pmatrix}$$

We require $T(I) = T(a^4) = T(a)^4$, so $b^2c^2 = 1$. We either have $bc = -1$ (then $T(a), T(a)^2 = T(a^2), T(a)^3 = T(a^3)$ and $T(a)^4 = T(a^4)$ are distinct matrices, hence faithful representation) or $bc = +1$ (unfaithful representation with kernel $\{I, a^2\}$ since $T(a^2) = T(a)^2 = I$).

6 2015

6.1 Paper 1

Problem 6.1 (Vector Calculus): Consider a toroidal body defined parametrically in the Cartesian coordinate system $x = (x, y, z)$ as the region satisfying

$$\begin{aligned}x &= (1 + r \sin \alpha) \cos \beta \\y &= (1 + r \sin \alpha) \sin \beta, \\z &= r \cos \alpha\end{aligned}$$

with $0 \leq r \leq R$, $-\pi \leq \alpha < \pi$ and $0 \leq \beta < 2\pi$ for constant $0 < R < 1$.

- (a) For a toroidal coordinate system (r, α, β) , determine the Cartesian components of the vectors \mathbf{h}_r , \mathbf{h}_α , \mathbf{h}_β such that the Cartesian differential $d\mathbf{x}$ is given by

$$d\mathbf{x} = \mathbf{h}_r dr + \mathbf{h}_\alpha d\alpha + \mathbf{h}_\beta d\beta,$$

and hence establish whether or not the toroidal coordinate system is orthogonal. Determine the Jacobian for the coordinate transformation. [8]

- (b) Suppose the toroidal body is immersed in a vector field $\mathbf{F}(\mathbf{x}) = \nabla\Omega + \nabla \times \mathbf{U}$, where Ω is a scalar field and \mathbf{U} is a vector field. Consider the integral

$$I = \int_S \mathbf{F} \cdot d\mathbf{S},$$

where S is the surface of the body and $d\mathbf{S}$ is an element of vector area. Why does I not depend on \mathbf{U} ? [3]

- (c) Determine I for the case $\Omega = z^4 - xyz + e^{-3y} \cos(3x) + e^{2x} \sin(2y)$. [9]

Answer 6.1.

- (a) We have

$$\mathbf{h}_r = \begin{pmatrix} \sin \alpha \cos \beta \\ \sin \alpha \sin \beta \\ \cos \alpha \end{pmatrix}; \quad \mathbf{h}_\alpha = \begin{pmatrix} r \cos \alpha \cos \beta \\ r \cos \alpha \sin \beta \\ -r \sin \alpha \end{pmatrix}; \quad \mathbf{h}_\beta = \begin{pmatrix} -(1 + r \sin \alpha) \sin \beta \\ (1 + r \sin \alpha) \cos \beta \\ 0 \end{pmatrix}$$

One can show that they are mutually orthogonal, i.e. $\mathbf{h}_r \cdot \mathbf{h}_\alpha = \mathbf{h}_\beta \cdot \mathbf{h}_\alpha = \mathbf{h}_r \cdot \mathbf{h}_\beta = 0$, hence the toroidal coordinate system is orthogonal. The Jacobian will simply be

$$J = \begin{vmatrix} \sin \alpha \cos \beta & r \cos \alpha \cos \beta & -(1 + r \sin \alpha) \sin \beta \\ \sin \alpha \sin \beta & r \cos \alpha \sin \beta & (1 + r \sin \alpha) \cos \beta \\ \cos \alpha & -r \sin \alpha & 0 \end{vmatrix} = r(1 + r \sin \alpha)$$

which is zero only for $r = 0$ as $0 \leq r \leq R < 1$.

- (b) The toroidal body has a closed surface (no boundary), so the closed loop integral is zero, so the integral is

$$I = \int_S (\nabla\Omega + \nabla \times \mathbf{U}) \cdot d\mathbf{S} = \int_S \nabla\Omega \cdot d\mathbf{S} + \int_{\partial S} \mathbf{U} \cdot d\mathbf{l} = \int_S \nabla\Omega \cdot d\mathbf{S}$$

- (c) We evaluate I by using divergence theorem.

$$\begin{aligned}I &= \int_S \nabla\Omega \cdot d\mathbf{S} = \int_V \nabla \cdot \nabla\Omega dV = \int_V \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} -yz - 3e^{-3y} \sin(3x) + 2e^{2x} \sin(2y) \\ -xz - 3e^{-3y} \cos(3x) + 2e^{2x} \cos(2y) \\ 4z^3 - xy \end{pmatrix} dV \\ &= \int_0^R \int_{-\pi}^{\pi} \int_0^{2\pi} 12r^2 \cos^2 \alpha r (1 + r \sin \alpha) d\beta d\alpha dr = 6\pi^2 R^4\end{aligned}$$

where $\int_{-\pi}^{\pi} \cos^2 \alpha \sin \alpha d\alpha = 0$ and $\int_{-\pi}^{\pi} \cos^2 \alpha d\alpha = \pi$.

Problem 6.2 (Partial Differential Equation): In two spatial dimensions the time evolution of a scalar field $u(x, y, t)$ is given by

$$\frac{\partial u}{\partial t} = \nabla^2 u + \beta \frac{\partial u}{\partial x} \quad (*)$$

for constant β .

- (a) Consider the domain $0 \leq x \leq 1$, $0 \leq y \leq 1$ with boundary conditions $\frac{\partial u}{\partial y} = 0$ on $y = 0$ and $u = 0$ on the other three boundaries. Use separation of variables to determine the general solution of (*) satisfying the boundary conditions and show that at $t = 0$ this reduces to

$$u(x, y, 0) = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} A_{mn} e^{-\frac{\beta}{2}x} \sin(m\pi x) \cos\left(\frac{2n-1}{2}\pi y\right),$$

for some set of constants A_{mn} . [14]

- (b) Determine the constants A_{mn} required for u to satisfy the initial condition [6]

$$u(x, y, 0) = x(1-x)e^{-\frac{\beta}{2}x} \cos \frac{3}{2}\pi y$$

Answer 6.2.

- (a) Since the boundary conditions are homogeneous, we use separation of variables, $u(x, y, t) = X(x)T(t)Y(y)$. Then,

$$\frac{T'}{T} = \frac{X''}{X} + \beta \frac{X'}{X} + \frac{Y''}{Y}$$

the boundary conditions suggest the form $Y \sim \cos y$. So, let

$$\frac{T'}{T} = -\mu; \quad \frac{X''}{X} + \beta \frac{X'}{X} = -\lambda; \quad \frac{Y''}{Y} = -\mu + \lambda$$

We thus obtain a 2nd order differential equation for X , i.e. $X'' + \beta X' + \lambda X = 0$ such that we get

$$X(x) = P e^{-\beta/2x} \sin(\sqrt{4\lambda - \beta^2}x)$$

where $\beta^2 - 4\lambda < 0$. Similarly, we have $Y = Q \cos(\sqrt{\mu - \lambda}y)$ and $T = R e^{-\mu t}$, where P , Q and R are constants. The general solution is thus

$$u(x, y, t) = C e^{-\beta x/2} \sin(\sqrt{4\lambda - \beta^2}x) \cos(\sqrt{\mu - \lambda}y) e^{-\mu t}$$

We thus impose the boundary conditions. $u(0, y, t) = 0 \implies \sqrt{4\lambda - \beta^2} = m\pi$ where $m \in \mathbb{Z}$; $u(x, 1, t) = 0 \implies \sqrt{\mu - \lambda} = \frac{2n-1}{2}\pi$ for $n \in \mathbb{Z}$. Hence,

$$\mu = \lambda + \frac{(2n-1)^2}{2^2}\pi^2 = \frac{m^2\pi^2 + \beta^2}{4} + \frac{(2n-1)^2}{2^2}\pi^2$$

By relabelling the constant as A_{mn} and trivially set $t = 0 \implies e^{-\mu t} = 1$, we get the desired form for $u(x, y, t)$.

- (b) Let $f(x) = x(1-x)$, then using Fourier series,

$$\begin{aligned} f(x)e^{-\beta x/2} \cos(1.5\pi y) &= \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} A_{mn} \cos\left(\frac{2n-1}{2}\pi y\right) \sin(m\pi x) e^{-\beta x/2} \\ f(x) \int_0^1 \cos(1.5\pi q - y) \cos\left(\frac{2p-1}{2}\pi y\right) dy &= \int_0^1 \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} A_{mn} \cos\left(\frac{2n-1}{2}\pi y\right) \cos\left(\frac{2p-1}{2}\pi y\right) dy \sin(m\pi x) \\ \int_0^1 x(1-x) \frac{1}{2} \delta_{2,p} \sin(\gamma\pi x) dx &= \frac{1}{2} \int_0^1 \sum_{m=1}^{\infty} A_{m2} \sin(\gamma\pi x) \sin(m\pi x) dx \\ \implies A_{k,2} &= \frac{8}{(2k+1)^3\pi^2} \end{aligned}$$

where $2k+1 = \gamma$.

Problem 6.3 (Green's Functions):

- (a) Use the method of Green's functions to solve

$$\frac{d^2 y}{dx^2} - y = f(x)$$

for $0 \leq x \leq 1$, with the boundary conditions $y(0) = y(1) = 0$.

[9]

[You may use the identity $\sinh a \cosh b - \cosh a \sinh b = \sinh(a - b)$.]

- (b) A forced damped harmonic oscillator satisfies the equation

$$\frac{d^2 x}{dt^2} + 2\frac{dx}{dt} + (1 + \mu^2)x = g(t),$$

where μ is a positive constant.

- (i) Solve this equation for
- $t \geq 0$
- with initial conditions
- $x = \frac{dx}{dt} = 0$
- at
- $t = 0$
- .

[7]

- (ii) Assume that
- $|g(t)| < Ce^{-at}$
- where
- C
- and
- a
- are constants with
- $a > 0$
- . Prove that
- $x(t) \rightarrow 0$
- as
- $t \rightarrow \infty$
- .

[4]

Answer 6.3.

- (a) The homogeneous ODE has the solution
- $y_a = \cosh(x)$
- and
- $y_b = \sinh(x)$
- . The corresponding Green's function satisfy

$$\frac{\partial^2 G}{\partial x^2} - G = \delta(x - \xi), \quad G(0, \xi) = G(1, \xi) = 0$$

Integrate around an infinitesimal region around $x = \xi$, we obtain the jump condition $[G']_{\xi-}^{\xi+} = 1$. G is continuous everywhere including $x = \xi$ (otherwise, $G'' \propto \delta'(x - \xi)$, which is a contradiction). Using the homogeneous solutions and the boundary conditions,

$$G(x, \xi) = \begin{cases} A \sinh(x) & 0 \leq x < \xi \leq 1 \\ C \sinh(x - 1) & 0 \leq \xi < x \leq 1 \end{cases}$$

At $x = \xi$, the continuity condition and jump condition give respectively

$$A \sinh \xi = C \sinh(\xi - 1)$$

$$-A \cosh \xi + C \cosh(\xi - 1) = 1$$

$$\begin{pmatrix} C \\ A \end{pmatrix} = \frac{1}{\cosh(\xi - 1) \sinh \xi + \cosh \xi \sinh(\xi - 1)} \begin{pmatrix} \sinh \xi & \cosh \xi \\ \sinh(\xi - 1) & \cosh(\xi - 1) \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{\sinh(1)} \begin{pmatrix} \sinh(\xi) \\ \sinh(\xi - 1) \end{pmatrix}$$

$$\Rightarrow G(x, \xi) = \begin{cases} \sinh(x) \frac{\sinh(\xi - 1)}{\sinh(1)} & 0 \leq x < \xi \leq 1 \\ \frac{\sinh \xi}{\sinh(1)} \sinh(x - 1) & 0 \leq \xi < x \leq 1 \end{cases}$$

The general solution will thus be

$$y(x) = \int_0^1 G(x, \xi) f(\xi) d\xi = \frac{\sinh(x)}{\sinh(1)} \int_x^1 f(\xi) \sinh(\xi - 1) d\xi + \frac{\sinh(x - 1)}{\sinh(1)} \int_0^x f(\xi) \sinh(\xi) d\xi$$

- (b) (i) For the homogeneous second order ODE, we try the ansatz $x = e^{\lambda t}$, then we obtain the characteristic equation $\lambda^2 + 2\lambda + (1 + \mu^2) = 0$ which has solutions $\lambda = -1 \pm i\mu$, hence the homogeneous solutions are $x = e^{-t} e^{\pm i\mu t}$. Then, our corresponding Green's function will be

$$G(t, \tau) = \begin{cases} Ae^{-t} \sin(\mu t + \phi) & 0 \leq t < \tau < \infty \\ Be^{-\tau} \sin(\mu \tau + \theta) & 0 \leq \tau < t < \infty \end{cases}$$

where θ , ϕ , A and B are constants to be found. This Green's function satisfy

$$\frac{\partial^2 G(t, \tau)}{\partial t^2} + 2\frac{\partial G(t, \tau)}{\partial t} + (1 + \mu^2)G(t, \tau) = \delta(t - \tau), \quad G(0, \tau) = G'(0, \tau) = 0$$

Integrate this around an infinitesimal region around $t = \tau$ again, we obtain the jump condition at $t = \tau$ to be $[G']_{\tau^-}^{\tau^+} = 1$. Similarly, G is continuous $\forall t$. At $t = \tau$, the continuity and jump condition give respectively

$$0 = Be^{-\tau} \sin(\mu\tau + \theta) \implies \mu\tau = -\theta$$

$$Be^{-\tau} e^{-(\tau-\tau)} (\mu \cos(\mu(\tau-\tau)) - \sin(\mu(\tau-\tau))) = 1 \implies Be^{-\tau} \mu = 1$$

Hence,

$$G(t, \tau) = \begin{cases} 0 & 0 \leq t < \tau < \infty \\ \frac{1}{\mu} e^{-(t-\tau)} \sin(\mu(t-\tau)) & 0 \leq \tau < t < \infty \end{cases}$$

The general solution is thus

$$x(t) = \int_0^t \frac{1}{\mu} e^{-(t-\tau)} \sin(\mu(t-\tau)) g(\tau) d\tau$$

(ii) We have $|g(t)| < Ce^{-at}$, and so

$$\begin{aligned} |x(t)| &\leq \int_0^t \frac{C}{\mu} e^{-(t-\tau)} \sin(\mu(t-\tau)) e^{-a\tau} d\tau \\ &\leq \frac{C}{\mu} e^{-t} \operatorname{Im} \left[\int_0^t e^{\tau(1-a)+i\mu(t-\tau)} d\tau \right] \\ &= \frac{C}{\mu} e^{-t} \operatorname{Im} \left[e^{i\mu t} \left[\frac{e^{\tau(1-a-i\mu)}}{1-a+i\mu} \right]_0^t \right] \end{aligned}$$

which approaches zero as $t \rightarrow \infty$.

Problem 6.4 (Fourier Transform): A radio station wishes to analyse its broadcast of the signal $a(t)$ using Fourier analysis. As a test signal, the radio station chooses a single pulse given by

$$a(t) = \begin{cases} 1 & |t| < 1 \\ 0 & \text{otherwise} \end{cases}$$

(a) Determine $\tilde{a}(\omega)$, the Fourier transform of $a(t)$. [3]

(b) Due to bandwidth limitations, the radio station decides to filter the signal so that it broadcasts

$$b(t) = \int_{-\infty}^{\infty} a(s)f(t-s)ds,$$

where the filter $f(t)$ is defined as

$$f(t) = \begin{cases} 1 - |t| & |t| < 1 \\ 0 & \text{otherwise} \end{cases}$$

Determine $\tilde{f}(\omega)$, the Fourier transform of $f(t)$, and hence use the convolution theorem to derive an expression for $\tilde{b}(\omega)$, the Fourier transform of $b(t)$. [7]

(c) Due to reflections from a mountain range, the signal received by the listeners can be modelled by

$$r(t) = b(t) + \alpha b(t - \tau),$$

where α is the relative strength of the reflected signal and τ is the delay in receiving the reflection. Determine $\tilde{r}(\omega)$, the Fourier transform of $r(t)$. [4]

(d) Measurements of the received signal suggest it is well approximated by $s(t)$ with Fourier transform

$$\tilde{s}(\omega) = 2(1 + \epsilon\omega^2)e^{-\omega^2/4}$$

for some constant ϵ . Determine $s(t)$. [6]

[You may assume $\int_{-\infty}^{\infty} e^{-(z-ia)^2} dz = \sqrt{\pi}$ for real a .]

Answer 6.4.

(a) The Fourier transform of $a(t)$ is

$$\tilde{a}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-1}^1 e^{-i\omega t} dt = \sqrt{\frac{2}{\pi}} \text{sinc}(\omega)$$

(b) The Fourier transform of $f(t)$ is

$$\tilde{f}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-1}^1 (1-|t|)e^{-i\omega t} dt = \frac{1}{\sqrt{2\pi}} \int_{-1}^1 (1-|t|) \cos(\omega t) dt = \frac{2}{\sqrt{2\pi}} \int_0^1 (1-t) \cos \omega t dt = \sqrt{\frac{2}{\pi}} \frac{2 \sin^2(\omega/2)}{\omega^2}$$

By the Convolution Theorem, if $b(t) = a(t) * f(t)$, then

$$\tilde{b}(\omega) = \tilde{a}(\omega) \tilde{f}(\omega) \sqrt{2\pi} = \sqrt{\frac{2}{\pi}} \frac{4}{\omega^3} \sin(\omega) \sin^2(\omega/2)$$

(c) The Fourier transform of $r(t)$ is

$$\tilde{r}(\omega) = \tilde{b}(\omega) + \alpha \int_{-\infty}^{\infty} b(t-\tau)e^{-i\omega t} d\omega \frac{1}{\sqrt{2\pi}} = \tilde{b}(\omega) + \alpha \int_{-\infty}^{\infty} b(s)e^{-i\omega(s+\tau)} ds \frac{1}{\sqrt{2\pi}} = \tilde{b} + \alpha \tilde{b} e^{-i\omega\tau}$$

(d) The inverse Fourier transform of s is

$$s(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \tilde{s}(\omega) e^{i\omega t} d\omega = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} 2(1+\epsilon\omega^2)e^{-\omega^2/4} e^{i\omega t} d\omega = \sqrt{\frac{2}{\pi}} \int_{-\infty}^{\infty} (1+\epsilon\omega^2) e^{-(\omega-2it)^2/4} e^{-t^2} d\omega$$

$$\implies = \sqrt{\frac{2}{\pi}} e^{-t^2} \left[(1-4\epsilon t^2) \int_{-\infty}^{\infty} e^{-\omega'^2/4} d\omega' + \epsilon \int_{-\infty}^{\infty} \omega'^2 e^{-\omega'^2/4} d\omega' \right] = 2\sqrt{2} e^{-t^2} [(1-4\epsilon t^2) + 2\epsilon]$$

where we labelled $\omega' = \omega - 2it$ and used $-(\omega - 2it)^2/4 = -(\omega^2/4) + i\omega t + t^2$.

Problem 6.5 (Linear Algebra):

- (a) Let A and B be $n \times n$ Hermitian matrices that commute, i.e., $AB = BA$. Assuming that the eigenvalues of A and B are non-degenerate, show that the eigenvectors of A and B are the same so that A and B may be written as $A = U\Lambda_A U^\dagger$ and $B = U\Lambda_B U^\dagger$, where Λ_A and Λ_B are diagonal matrices and U is unitary. [4]

- (b) For such matrices A and B , using this result, or otherwise, show that

$$\exp(A)\exp(B) = \exp(A+B)$$

where the exponential of a square matrix A is defined by the series

$$\exp(A) = I + A + \frac{1}{2!}A^2 + \frac{1}{3!}A^3 + \dots$$

with I the identity matrix. [4]

- (c) For general $n \times n$ matrices X and Y , verify that

$$\exp(\epsilon X)\exp(\epsilon Y) = \exp(\epsilon X + \epsilon Y + \frac{1}{2}\epsilon^2[X, Y]) + O(\epsilon^3)$$

where ϵ is an arbitrary parameter and [5]

$$[X, Y] = XY - YX$$

- (d) For the matrix

$$M = \begin{pmatrix} 0 & a & 0 & 0 \\ a & 0 & 0 & 0 \\ 0 & 0 & 0 & b \\ 0 & 0 & -b & 0 \end{pmatrix}$$

where a and b are real, show that [7]

$$\exp(M) = \begin{pmatrix} \cosh(a) & \sinh(a) & 0 & 0 \\ \sinh(a) & \cosh(a) & 0 & 0 \\ 0 & 0 & \cos(b) & \sin(b) \\ 0 & 0 & -\sin(b) & \cos(b) \end{pmatrix}$$

Answer 6.5.

- (a) Let the set of eigenvectors of A be $\{e_i\}$, then $Ae_i = \lambda_i e_i$.

$$0 = BAe_i - B\lambda_i e_i = AB e_i - \lambda_i B e_i$$

so Be_i is an eigenvector of A with eigenvalue λ_i . But the eigenvalues of A are non-degenerate, so Be_i can only be a rescaling of e_i , i.e. $Be_i = \mu e_i$, with $\mu \neq 1$. Hence, the eigenvectors of A and B are the same, unique up to a scaling factor.

The eigenvectors corresponding to distinct eigenvalues of a Hermitian matrix are orthogonal. From the Hermiticity property,

$$0 = \langle e_i | Ae_j \rangle - \langle A^\dagger e_i | e_j \rangle = (\lambda_j - \lambda_i^*) \langle e_i | e_j \rangle$$

If $i = j$, the norm $\langle e_i | e_i \rangle > 0$ as long as $\mathbf{e}_i \neq \mathbf{0}$, and so their eigenvalues are real, i.e. $\lambda_i = \lambda_i^* \in \mathbb{R}$. Now if $i \neq j$, $\lambda_i \neq \lambda_j$ (given to be distinct), so their eigenvectors must be orthogonal, i.e. $\langle e_i | e_j \rangle = 0$. We may therefore construct a unitary matrix U whose columns are the normalized vectors of either A or B , so that

$$(U^\dagger AU)_{jk} = (U^\dagger)_{jk}(AU)_{pk} = (e_j)_p(Ae_k)_p = \lambda_k(e_j)_p(e_k)_p = \lambda_k e_j^\dagger e_k = \lambda_k \delta_{jk}$$

where the rows of U^\dagger is e_j and columns of AU is Ae_k . Hence, $U^\dagger AU$ is a diagonal matrix with entries being the eigenvalues of A . We denote this as Λ_A . A similar result for B , i.e. $B = U\Lambda_B U^\dagger$.

(b) We have

$$e^A e^B = \sum_{n=0}^{\infty} \frac{A^n}{n!} \sum_{p=0}^{\infty} \frac{B^p}{p!} = \sum_{n=0}^{\infty} \frac{(U\Lambda_A U^\dagger)^n}{n!} \sum_{p=0}^{\infty} \frac{(U\Lambda_B U^\dagger)^p}{p!} = \sum_{n=0}^{\infty} \sum_{p=0}^{\infty} \frac{U\Lambda_A^n \Lambda_B^p U^\dagger}{n!p!} = U \sum_{r=0}^{\infty} \sum_{s=0}^r \frac{\Lambda_A^r \Lambda_B^{r-s}}{(r-s)!s!} U^\dagger$$

where we used the variables $n + p = r$ and $s = p$. Now using $(U\Lambda_A U^\dagger)^r (U\Lambda_B U^\dagger)^{r-s} = U\Lambda_A^r \Lambda_B^{r-s} U^\dagger$

$$e^A e^B = \sum_{r=0}^{\infty} \frac{1}{r!} \sum_{s=0}^r \frac{r!}{(r-s)!s!} (U\Lambda_A U^\dagger)^r (U\Lambda_B U^\dagger)^{r-s} = \sum_{r=0}^{\infty} \frac{(A+B)^r}{r!} = e^{A+B}$$

where $\frac{r!}{(r-s)!s!}$ is actually ${}^r C_s$.

(c) We have

$$e^{\epsilon X} e^{\epsilon Y} = (I + \epsilon X + \frac{1}{2}\epsilon^2 X^2 + O(\epsilon^3))(I + \epsilon Y + \frac{1}{2}\epsilon^2 Y^2 + O(\epsilon^3)) = I + \epsilon(X+Y) + \epsilon^2(XY + \frac{1}{2}X^2 + \frac{1}{2}Y^2) + O(\epsilon^3)$$

as well as

$$\begin{aligned} e^{\epsilon X + \epsilon Y + \frac{1}{2}\epsilon^2[X,Y] + O(\epsilon^3)} &= I + \epsilon X + \epsilon Y + \frac{1}{2}\epsilon^2(XY - YX) + O(\epsilon^3) + \frac{1}{2}(\epsilon X + \epsilon Y + O(\epsilon^3))^2 + O(\epsilon^3) \\ &= I + \epsilon(X+Y) + \frac{1}{2}\epsilon^2(XY - YX) + \frac{1}{2}\epsilon^2(X^2 + Y^2 + XY + YX) + O(\epsilon^3) \\ &= I + \epsilon(X+Y) + \epsilon^2(XY + \frac{1}{2}X^2 + \frac{1}{2}Y^2) + O(\epsilon^3) \end{aligned}$$

(d) Observe that M can be written as a direct sum, i.e. $M = aA \oplus bB$, with

$$A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

such that $A^2 = I$ and $B^4 = I$. Taking the matrix exponential,

$$\begin{aligned} e^M &= \sum_{n=0}^{\infty} \frac{1}{n!} (aA \oplus bB)^n \\ &= \sum_{n=0}^{\infty} \frac{a^n A^n}{n!} \oplus \sum_{p=0}^{\infty} \frac{b^p B^p}{p!} \\ &= (I + aA + \frac{a^2 A^2}{2!} + \frac{a^3 A^3}{3!} + \frac{a^4 A^4}{4!} + \dots) \oplus (I + bB + \frac{b^2 B^2}{2!} + \frac{b^3 B^3}{3!} + \frac{b^4 B^4}{4!} + \dots) \\ &= (I + aA + \frac{a^2 I}{2!} + \frac{a^3 A}{3!} + \frac{a^4 I}{4!}) \oplus (I + bB - \frac{b^2 I}{2!} - \frac{b^3 B}{3!} + \frac{b^4 I}{4!} + \dots) \\ &= (I \cosh a + A \sinh a) \oplus (I \cos b + B \sinh B) \end{aligned}$$

where matrices act in disjoint subspaces. We have also used the Taylor series of \sinh and \cosh . The result is our desired matrix.

Problem 6.6 (Linear Algebra):

- (a) Explain how to diagonalize a real symmetric matrix A . [4]
 (b) Describe the quadratic surface Σ in \mathbb{R}^3 defined by

$$5x_1^2 - 8x_1x_2 + 5x_2^2 + 9x_3^2 = 9$$

specifying the principal axes and, where appropriate, the semi-axis lengths. [6]

Show that Σ intersects the surface defined by

$$x_1^2 + x_2^2 + x_3^2 = 4$$

in a pair of circles, and find their orientations, radii, and centres. [5]

- (c) On a general quadratic surface defined by $x^T A x = 1$, with A a real symmetric matrix, show that the squared distance from the origin, $x^T x$, is extremised for x an eigenvector of A . [5]

Answer 6.6.

- (a) We first show the eigenvectors e_i of a real symmetric matrix, corresponding to distinct eigenvalues, are orthogonal.

$$0 = \langle e_i | A e_j \rangle - \langle A e_i | e_j \rangle = (\lambda_j - \lambda_i) \langle e_i | e_j \rangle$$

where $A = A^T$. If the eigenvalues are distinct, $i \neq j$, $\lambda_i \neq \lambda_j$, then we have $\langle e_i | e_j \rangle = 0$.

Let A be $n \times N$. If A has n distinct eigenvalues, then we automatically have n pairwise orthogonal eigenvectors, which are linearly independent and form a basis. But suppose there are only $r < n$ distinct eigenvalues. There will always be at least one eigenvector e_1 corresponding to one of the repeated eigenvalues, say λ . Consider a change of basis to $\{e_1\} \cup \{e_2, e_3, \dots\}$ such that $\langle e_i | e_1 \rangle = 0 \forall i > 1$. Then, in this basis, A has the form

$$A = \begin{pmatrix} \lambda & 0 & 0 & \dots \\ 0 & \langle e_2 | A e_2 \rangle & \langle e_2 | A e_3 \rangle & \dots \\ 0 & \langle e_3 | A e_2 \rangle & \langle e_3 | A e_3 \rangle & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

which is the direct sum of the space e_1 and its orthogonal complement. This reduced $(n - 1) \times (n - 1)$ matrix will have one fewer copy of the degenerate eigenvalue as the roots of its characteristic polynomial. Keep repeating the procedure until we obtain a basis set of orthogonal eigenvectors.

So it is always possible to find an orthogonal basis (and hence orthonormal basis) for A . If we place the orthonormal eigenvectors, which we now denote $\{f_i\}$, and place them in the columns of a matrix U , then that matrix will be unitary and

$$(U^\dagger A U)_{jk} = (U^\dagger)_{jp} (A U)_{pk} = (f_j)_p (\lambda_j f_j)_p = \lambda_j \delta_{jk}$$

hence $U^\dagger A U$ is a diagonal matrix, i.e. $\text{diag}(\lambda_1, \lambda_2, \dots)$.

- (b) Write the quadratic form as

$$x^\dagger A x = 9 \implies A = \begin{pmatrix} 5 & -8/2 & 0 \\ -8/2 & 5 & 0 \\ 0 & 0 & 9 \end{pmatrix}$$

Thus, $9 = x^\dagger U U^\dagger A U U^\dagger x = (U^\dagger x)^\dagger \Lambda_A U^\dagger x$, where $U^\dagger x = \alpha$ such that $\alpha = (\alpha_1, \alpha_2, \alpha_3)^T$ are the coordinates of the eigenbasis of A , and Λ_A is a diagonal matrix containing the eigenvalues of A , i.e. $\Lambda_A = \text{diag}(\lambda_1, \lambda_2, \lambda_3)$. By inspection, $\lambda = 9$ is an eigenvalue with corresponding eigenvector $\mathbf{e}_{\lambda=9} = (0, 0, 1)^T$. To find the remaining eigenvalues, we find the determinant of the reduced 2 by 2 subspace

$$0 = \det \begin{pmatrix} 5 - \lambda & -4 \\ -4 & 5 - \lambda \end{pmatrix} = (5 - \lambda)^2 - 16 \implies \lambda = 9, 1$$

For $\lambda = 1$, we have $\mathbf{e}_{\lambda=1} = (1, 1, 0)^T \frac{1}{\sqrt{2}}$. For $\lambda = 9$ (again), we have $\mathbf{e}'_{\lambda=9} = \frac{1}{\sqrt{2}}(1, -1, 0)^T$. There is two linearly independent eigenvectors for the eigenvalue $\lambda = 9$, i.e. degeneracy. The matrix U is thus

$$U = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & \sqrt{2} \end{pmatrix}$$

The quadratic surface is thus

$$\Sigma : \alpha_1^2 + 9\alpha_2^2 + 9\alpha_3^2 = 9$$

This is an ellipsoid of revolution with rotational axis $\mathbf{e}_{\lambda=1} = \frac{1}{\sqrt{2}}(1, 1, 0)^T$, semi-major axis length 3 and semi-minor axis length 1. This rotational symmetry is the reason for the degeneracy.

0 The sphere $x_1^2 + x_2^2 + x_3^2 = 4$ with respect to the new coordinates is $\alpha_1^2 + \alpha_2^2 + \alpha_3^2 = 4$. Then, we have

$$\alpha_1^2 + (1 - (\alpha_1/3)^2) = 4 \implies \alpha_1 = \pm \frac{3\sqrt{3}}{2\sqrt{2}}, \quad \alpha_2^2 + \alpha_3^2 = 4 - \frac{27}{8} = \frac{5}{8}$$

The centres are at $\pm \frac{3\sqrt{3}}{2\sqrt{2}} \frac{1}{\sqrt{2}}(1, 1, 0)^T$, in a plane perpendicular to $\frac{1}{\sqrt{2}}(1, 1, 0)^T$ with radius $r = \sqrt{\frac{5}{8}}$.

(c) Use the method of Lagrange multipliers, i.e. extremize $|x| = x^T x$ with the constraint $x^T A x = 1$:

$$\mathcal{L} = x^T x - \mu(x^T A x - 1) \implies \frac{\partial \mathcal{L}}{\partial x_q} = 2 \frac{\partial x_i}{\partial x_q} x_i - 2\mu \frac{\partial x_i}{\partial x_q} A_{ij} x_j \implies x_q = \mu A_{qi} x_i$$

where A is symmetric. The result suggests that x is indeed an eigenvector of A .

Problem 6.7 (Cauchy-Riemann):

- (a) Derive the Cauchy–Riemann equations for the analytic function

$$f(z) = u(x, y) + iv(x, y),$$

where $z = x + iy$. [2]

- (b) Determine the analytic function
- $f(z)$
- if
- $u(x, y) = x \cos x \cosh y + y \sin x \sinh y$
- .
- [7]

- (c) Assume that
- $g(z)$
- is analytic and
- $|g(z)|$
- is constant. Prove that
- $g(z)$
- is constant.
- [6]

- (d) Calculate the Taylor series of the function

$$h(z) = \frac{2z}{z^2 + 1}$$

about $z = 1$ and state its radius of convergence. [5]

[Hint: use partial fractions.]

Answer 6.7.

- (a) A function is analytic if its complex derivative

$$\frac{df}{dz} := \lim_{\Delta z \rightarrow 0} \frac{f(z + \Delta z) - f(z)}{\Delta z}$$

exists and is independent of the direction of approach of $\Delta z \rightarrow 0$ in the complex plane. So, take any two orthogonal directions Δx and $i\Delta y$.

$$\lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x + iy) - f(x + iy)}{\Delta x} = \lim_{\Delta y \rightarrow 0} \frac{f(x + i(y + \Delta y)) - f(x + iy)}{i\Delta y} \implies \frac{\partial u}{\partial x} + i \frac{\partial v}{\partial x} = -i \frac{\partial u}{\partial y} + \frac{\partial v}{\partial y}$$

This is the Cauchy-Riemann equations.

- (b)
- $\frac{\partial u}{\partial x} = \cos(x) \cosh(y) - x \sin(x) \cosh(y) + y \cos(x) \sinh(y)$
- ,
- $\frac{\partial u}{\partial y} = x \cos(x) \sinh(y) + \sin(x) \sinh(y) + y \sin(x) \cosh(y)$
- . Using Cauchy-Riemann relations, we must have
- $v = y \sin(x) \sinh(y) + c$
- , where
- c
- is an integration constant. Hence,
- $f(x, y) = z \cos(z) + ic$
- .

- (c) Since
- g
- is analytic,
- g
- satisfies Cauchy-Riemann Equations. If
- $|g(z)|$
- is constant,

$$0 = \frac{\partial}{\partial x} |g|^2 = 2u \frac{\partial u}{\partial x} + 2v \frac{\partial v}{\partial x}$$

where we recover one of the Cauchy Riemann equations. Doing this for y yields the other. Hence, either $u = v = 0$ (which also naturally satisfies g being a constant) or

$$u \frac{\partial u}{\partial x} = v \left(-\frac{v}{u} \right) \frac{\partial u}{\partial x} \implies \frac{\partial u}{\partial x} \frac{u^2 + v^2}{u} = 0$$

which gives $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} = 0$ and $\frac{\partial u}{\partial y} = \frac{\partial v}{\partial x} = 0$. Hence, u and v are constants and thus $g(z) = u + iv$ is a constant.

- (d) We have
- $h(z) = \frac{2z}{(z+i)(z-i)}$
- . The poles are at
- $z = \pm i$
- . Using partial fractions, we have
- $h(z) = \frac{(z-i)}{z^2+1} + \frac{(z+i)}{z^2+1}$
- . Expand about
- $z = 1$
- ,

$$f_{\pm}(z) = \frac{1}{z \pm i}, \quad f'_{\pm}(z) = -\frac{1}{(z \pm i)^2} \implies f_{\pm}(1) = (1 \pm i)^{-1} = \frac{1}{\sqrt{2}} e^{\mp i\pi/4}, \quad f'_{\pm}(1) = -\frac{1}{2} e^{\mp i\pi/2}$$

We have $f_{\pm}^{(n)} = (-1)^n n! 2^{-n/2} e^{\mp i n \pi/4}$, and so

$$h(w = z-1) = \sum_{n=0}^{\infty} \left(-\frac{1}{\sqrt{2}} \right)^n (w e^{-i\pi/4})^n + \sum_{n=0}^{\infty} \left(\frac{1}{\sqrt{2}} \right)^n (w e^{+i\pi/4})^n = \sum_{n=0}^{\infty} \left(-\frac{1}{\sqrt{2}} \right)^n 2 \cos \frac{n\pi}{4} w^n$$

We perform the ratio test for $u_n(w) = 2^{-n/2} \cos(n\pi/4) w^n$. The radius of convergence R is also the distance from the expansion point $z = 1$ to the nearest pole $z = \pm i$, which is $\sqrt{1^2 + 1^2} = \sqrt{2}$.

$$1 = \lim_{n \rightarrow \infty} \left| \frac{u_{n+1}(R)}{u_n(R)} \right| = \lim_{n \rightarrow \infty} \left| \frac{2^{-(n+1)/2} \cos((n+1)\pi/4) R^{n+1}}{2^{-n/2} \cos(n\pi/4) R^n} \right| = \frac{R}{\sqrt{2}}$$

Problem 6.8 (Series Solution to ODE): Consider the equation

$$(1-x^2)\frac{d^2y}{dx^2} - x\frac{dy}{dx} + n^2y = 0 \quad (*)$$

- Show that $x = 0$ is an ordinary point, and determine the nature of the points $x = \pm 1$ and $x = \infty$. [6]
- Explain how to construct two independent solutions of $(*)$ as power series about $x = 0$. What is the recurrence relation for the coefficients of these series? [6]
- Use the ratio test to determine the radius of convergence of each series. How are these related to the location of the singular points of $(*)$? [3]
- Show that polynomial solutions of $(*)$ exist when n is an integer. With the condition $y(1) = 1$, determine these solutions for the cases $n = 0, 1, 2$, and 3 . [5]

Answer 6.8.

- (a) $-\frac{x}{1-x^2}$ and $\frac{n^2}{1-x^2}$ are analytic at $x = 0$ and so $x = 0$ is an ordinary point. Also, $-\frac{x}{1-x^2}$ and $\frac{n^2}{1-x^2}$ are not analytic at $x = \pm 1$, but $-\frac{x}{1\pm x}$ and $\frac{-xp^2(1\mp x)}{1\pm x}$ are analytic at $x = \pm 1$. Hence, $x = \pm 1$ is a regular singular point. To determine the behaviour at $x = \infty$, we substitute $w = \frac{1}{x}$,

$$(1-w^{-2})w^2\left(2w\frac{dy}{dw} + w^2\frac{d^2y}{dw^2}\right) - w^2\frac{dy}{dw} + n^2y = 0$$

So, $\frac{2w^2-2-w}{w^2(w^2-1)}$ and $\frac{n^2}{w^2(w^2-1)}$ diverge as $w \rightarrow 0$. But, $\frac{ww(2w^2-2-w)}{w^2(w^2-1)}$ and $\frac{n^2w^2}{w^2(w^2-1)}$ are analytic at $w = 0$. Hence, $x = \infty$ is a regular singular point.

- (b) Since $x = 0$ is an ordinary point, we try a power series solution $y = \sum_{n=0}^{\infty} a_n x^n$, and so the recurrence relation is

$$\sum_{n=0}^{\infty} n(n-1)a_n x^{n-2} - n(n-1)a_n x^n - na_n x^n + p^2 a_n x^n = 0 \implies (n+2)(n+1)a_{n+2} = (n^2 - p^2)a_n$$

We have two linearly independent solutions each anchored on a_0 and a_1 respectively.

- (c) Use ratio test:

$$1 > \lim_{p \rightarrow \infty} \left| \frac{a_{p+2}x^{p+2}}{a_p x^p} \right| = |x|^2 \lim_{p \rightarrow \infty} \left| \frac{(p+1)(p+2)}{n^2 - p^2} \right| \implies |x| < 1$$

which is the distance to the nearest singular point at $x = \pm 1$.

- (d) For $n \in \mathbb{Z}$, the series terminates as the numerator vanishes for each of the series individually.

- $n = 0 \implies y = 1$, trivially normalized;
- $n = 1 \implies y = x$, trivially normalized;
- $n = 2 \implies a_2 = -a_0 \frac{2^2}{1 \times 2} = -2a_0 \implies y = a_0(1 - 2x^2)$. But since $y(1) = 1 = -a_0$, then $y = 2x^2 - 1$;
- $n = 3 \implies a_3 = \frac{1-9}{(1+1)(1+2)}a_0 = -\frac{4}{3}a_0$. But since $y(1) = 1 = a_1(1 - (4/3)) \implies y = 4x^3 - 3x$.

Problem 6.9 (Variational Principle):

- (a) (i) State the Euler–Lagrange equation that determines the extrema of the functional $F[z]$ of the function $z(x)$, where

$$F[z] = \int_{\alpha}^{\beta} f(z, z'; x) dx$$

with primes denoting differentiation with respect to x . [2]

- (ii) If f does not depend explicitly on x , show that

$$f - z' \frac{\partial f}{\partial z'} = \text{constant}$$

when $z(x)$ extremises $F[z]$. [4]

- (iii) Explain how to determine the extrema of F subject to the constraint that a further functional $G[z]$ is constant. [2]

- (b) (i) An inextensible string of total length $\pi a/2$ hangs under its own weight in the x – z plane, with its endpoints fixed at $z = 0$ and $x = \pm a/\sqrt{2}$. The mass per unit length of the string, μ , is uniform. The gravitational potential $\Phi(z)$ varies with z , and is defined such that the potential energy of an element of the string of mass δm is $\delta m \Phi$. Parameterising the path of the string as $z(x)$, show that the total gravitational potential energy is [2]

$$V[z] = \mu \int_{-a/\sqrt{2}}^{a/\sqrt{2}} \Phi(x) \sqrt{1 + z'^2} dx$$

- (ii) The shape adopted by the string is such as to minimise V subject to the constraint of a fixed length. Show that $z(x)$ satisfies

$$\frac{\mu \Phi(z) - \lambda}{\sqrt{1 + z'^2}} = \text{constant}$$

where λ is a constant. [5]

- (iii) Determine a suitable $\Phi(z)$ if the string is to hang along an arc of a circle of radius a . [5]

Answer 6.9.

- (a) (i) The Euler–Lagrange equation is $\frac{d}{dx} \frac{\partial f}{\partial z'} = \frac{\partial f}{\partial z}$.

- (ii) Given that $f = f(z, z')$, then $\frac{\partial f}{\partial x} = 0$. By chain rule,

$$\frac{df}{dx} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial x} + \frac{\partial f}{\partial z'} \frac{\partial z'}{\partial x} = 0 + \frac{\partial z}{\partial x} \frac{d}{dx} \frac{\partial f}{\partial z'} + \frac{\partial f}{\partial z'} \frac{\partial z'}{\partial x} = \frac{d}{dx} z' \frac{\partial f}{\partial z'}$$

where we used the Euler–Lagrange equation. Hence, $f - z' \frac{\partial f}{\partial z'}$ is a constant.

- (iii) Extremize $\mathcal{L} = F - \lambda G$ with λ being the Lagrange multiplier.

- (b) (i) The potential energy is $V = \int \Phi dm = \int \Phi \frac{dm}{dl} dl$, then the functional is $V[z] = \mu \int_{-a/\sqrt{2}}^{a/\sqrt{2}} \Phi \sqrt{1 + (z')^2} dx$.

- (ii) We extremize $\mathcal{L} = V[z] - \lambda \int dl = \int_{-a/\sqrt{2}}^{a/\sqrt{2}} (\mu \Phi - \lambda) \sqrt{1 + z'^2} dx$. Since the integrand does not depend on x , then by part (a)(ii), for some constant A we have

$$A = (\mu \Phi - \lambda) \sqrt{1 + z'^2} - z' (\mu \Phi - \lambda) \frac{z'}{\sqrt{1 + z'^2}} = \frac{\mu \Phi - \lambda}{\sqrt{1 + z'^2}}$$

- (iii) Given that the ends are along $x = \pm a/\sqrt{2}$ and $z = 0$, then by symmetry, the centre of the circle must be at $(0, z_0)$ and the equation of the circle is

$$x^2 + (z - z_0)^2 = a^2 \implies z' = -\frac{x}{z - z_0} = -\frac{x}{\sqrt{a^2 - x^2}}$$

Then from part (b)(ii), we have

$$\Phi = \frac{\lambda}{\mu} + \frac{A}{\mu} \frac{a}{\sqrt{a^2 - x^2}}$$

Problem 6.10 (Rayleigh-Ritz Method):

(a) Consider the functionals

$$F[y] = \int_{\alpha}^{\beta} [p(x)(y')^2 + q(x)y^2]dx, \quad G[y] = \int_{\alpha}^{\beta} w(x)y^2dx$$

where $p(x) > 0$, $q(x) > 0$, and $w(x) > 0$ for $\alpha < x < \beta$, and primes denote differentiation with respect to x . Show that if suitable boundary conditions are imposed at $x = \alpha$ and $x = \beta$, the ratio $F[y]/G[y]$ is extremised when y satisfies the Sturm–Liouville eigenvalue equation

$$-[p(x)y']' + q(x)y = \lambda w(x)y \quad (*)$$

(i) How do the eigenvalues $(*)$ relate to the extremal values of $F[y]/G[y]$? **[4]**(ii) Hence explain the Rayleigh–Ritz method for estimating the lowest eigenvalue of $(*)$. **[3]**(b) Pressure waves in a spherical cavity of radius a satisfy

$$\nabla^2 \psi + k^2 \psi = 0 \quad (\dagger)$$

with k a real constant. The function ψ is bounded everywhere and vanishes on $r = a$.

(i) For spherically-symmetric solutions $\psi(r)$, show that (\dagger) reduces to an ordinary differential equation that can be written in Sturm–Liouville form with $p(r) = r^2$, $q(r) = 0$, and $w(r) = r^2$. **[3]**(ii) By considering a trial function $\psi_{\text{trial}}(r) = 1 - (r/a)^2$, calculate an approximation to the lowest eigenvalue k_0^2 . **[5]**(iii) Using the substitution $\psi(r) = u(r)/r$, determine the spherically-symmetric solutions of (\dagger) and show that the exact lowest eigenvalue is $k_0^2 = \pi^2/a^2$. Comment on the relation of this value with the approximate eigenvalue determined in (ii). **[5]****Answer 6.10.**(a) (i) Let the Rayleigh quotient be $\Lambda[y] = \frac{F[y]}{G[y]}$, then the first order variation is

$$\delta\Lambda = \frac{\delta F}{G} - \frac{F}{G^2}\delta G = \frac{1}{G}\delta(F - \Lambda G)$$

where we replace $\frac{F}{G}$ with the stationary value of Λ , λ . The stationary values of $\frac{F}{G}$ thus correspond to the stationary values of $F - \lambda G$. Extremizing it gives

$$0 = \frac{\delta}{\delta y}(F - \lambda G) = \frac{\delta}{\delta y} \int_{\alpha}^{\beta} py'^2 + qy^2 - \lambda wy^2 dx = 2qy - 2\lambda wy - (2py')'$$

where we used the Euler-Lagrange equations $\frac{d}{dx} \frac{\partial f}{\partial y'} = \frac{\partial f}{\partial y}$ for the integrand $f(y, y'; x)$. The result is the SL equation, with a factor of 2. Hence, the stationary value of $\frac{F}{G}$ is the eigenvalue and the Lagrange multiplier of the problem.

(ii) If there exists a lowest eigenvalue for the problem, then any trial function that obeys the boundary conditions cannot return an underestimate of the lowest eigenvalue. By superposing a linearly independent set of functions that satisfy the boundary conditions, and minimizing the resulting quotient $\frac{F}{G}$ with respect to these parameters, we will get an upper bound on the lowest eigenvalue.(b) (i) For spherical symmetry, $\nabla^2 = \frac{1}{r^2} \frac{d}{dr} r^2 \frac{d}{dr}$, then we convert (\dagger) to SL form:

$$-(r^2 \psi')' = r^2 k^2 \psi$$

where $p = r^2$, $q = 0$ and $w = r^2$.

(ii) With ψ_{trial} ,

$$\Lambda = \frac{\int_0^a r^2 (-2r/a^2)^2 dr}{\int_0^a r^2 (1 - (r/a)^2)^2 dr} = \frac{\frac{4}{a^4} \int_0^a r^4 dr}{\frac{1}{a^4} \int_0^a a^4 r^2 - 2a^2 r^4 + r^6 dr} = \frac{1}{a^2} \frac{1/5}{(1/3) - (2/5) + (1/7)} = \frac{21}{2a^2}$$

(iii) With the suggested substitution, $\psi(r) = \frac{u(r)}{r} \implies \nabla^2 \psi = \frac{1}{r} \frac{d^2 u}{dr^2}$, then we convert (\dagger) to $\frac{1}{r}(u'' + k^2 u) = 0 \implies u(r) = A \sin(kr) + B \cos(kr)$. Since $\frac{u}{r}$ bounded everywhere, then $B = 0$. Also, $u(r = a) = 0 \implies ka = n\pi$, hence the smallest value is $k_0^2 = \frac{\pi^2}{a^2} < \frac{21}{2a^2}$. Hence, this estimate is an overestimate of the true value, as expected.

6.2 Paper 2

Problem 6.11 (Sturm-Liouville):

- (a) (i) Explain what it means for the differential operator \mathcal{L} to be self-adjoint on the interval $a \leq x \leq b$. [2]
 (ii) The eigenfunctions $y_n(x)$ of a self-adjoint operator \mathcal{L} satisfy

$$\mathcal{L}y_n = \lambda_n w y_n$$

for some weight function $w(x) > 0$. Show that for appropriate boundary conditions, eigenfunctions with distinct eigenvalues are orthogonal, i.e.,

$$\int_a^b w(x) y_m^*(x) y_n(x) dx = 0$$

for $\lambda_m \neq \lambda_n$.

[4]

- (b) Consider the eigenvalue problem

$$-(1-x^2) \frac{d^2 y_n}{dx^2} + x \frac{dy_n}{dx} = n^2 y_n \quad (*)$$

on the interval $-1 \leq x \leq 1$, with the boundary conditions $y_n(-1) = 0$ and $y_n(1) = 0$.

- (i) Express (*) in Sturm-Liouville form, and hence determine the weight function $w(x)$. [5]
 (ii) By using the substitution $x = \cos \theta$, solve (*) with the given boundary conditions to show that n must be an integer, and construct the normalised eigenfunctions for $n > 0$. [6]
 (iii) Verify explicitly the orthogonality of your eigenfunctions for $n \neq m$. [3]

Answer 6.11.

- (a) (i) For \mathcal{L} to be self-adjoint on the interval $[a, b]$, \mathcal{L} must satisfy $\langle u | \mathcal{L}v \rangle = \int_a^b u^* \mathcal{L}v dx = \int_a^b (\mathcal{L}u)^* v dx = \langle \mathcal{L}u | v \rangle$, where u and v are solutions of \mathcal{L} on this interval. Here, $\mathcal{L}^\dagger = \mathcal{L}$.
 (ii) For $\mathcal{L} = \frac{d}{dx}(p(x) \frac{d}{dx}) - q(x)$ to be self-adjoint, we require the boundary terms below to be zero.

$$\begin{aligned} \langle u | \mathcal{L}v \rangle &= \int_a^b u^* \frac{d}{dx} \left[p(x) \frac{dv}{dx} \right] - u^* q(x) v dx \\ &= \left[u^* p(x) \frac{dv}{dx} \right]_a^b + \int_a^b \frac{du^*}{dx} p(x) \frac{dv}{dx} - u^* q(x) v dx \\ &= \left[u^* p(x) \frac{dv}{dx} - \frac{du^*}{dx} p(x) v \right]_a^b + \int_a^b v \frac{d}{dx} \left(p(x) \frac{du^*}{dx} \right) - u^* q(x) v dx \end{aligned}$$

For $u = y_m$, $v = y_n$, we have LHS to give $\lambda_n \langle y_m | y_n \rangle_w$ while the RHS give $\lambda_m^* \langle y_m | y_n \rangle_w$ since $\mathcal{L}y_n = \lambda_n w y_n$. We thus have $(\lambda_n^* - \lambda_m) \langle y_m | y_n \rangle_w = 0$. For $y_n = y_m$, $\lambda_n^* = \lambda_n \in \mathbb{R}$. For $y_n \neq y_m$, we have $\lambda_n \neq \lambda_m$, and so $\langle y_n | y_m \rangle_w = 0$.

- (b) (i) Multiply $\mathcal{L} = -(1-x^2) \frac{d^2}{dx^2} + x \frac{d}{dx}$ by an integration factor $\mu(x)$ such that $\mu \mathcal{L}$ is of Sturm-Liouville form $\frac{d}{dx}(p \frac{d}{dx})$:

$$\frac{1}{p(x)} \frac{dp(x)}{dx} = \frac{-x}{1-x^2} \implies p(x) \propto \sqrt{1-x^2} \implies \mu(x) \propto \frac{1}{\sqrt{1-x^2}}$$

. Then the weight function is $\frac{1}{\sqrt{1-x^2}}$ since $\mu \mathcal{L}y_n = \mu n^2 y_n$.

(ii) $x = \cos \theta \implies \frac{d}{dx} = -\sin \theta \frac{d}{d\theta}$ and $\frac{d^2}{dx^2} = -\cot \theta \frac{d}{d\theta} + \frac{d^2}{d\theta^2}$, then (*) becomes $\frac{d^2 y_n}{d\theta^2} = n^2 y_n \implies y_n = c_1 \cos(n\theta) + c_2 \sin(n\theta)$. The boundary conditions becomes $y_n(0) = y_n(\pi) = 0$, so $n \in \mathbb{Z}$ with $c_1 = 0$. Thus, $y_n = c_2 \sin(n \cos^{-1}(x))$. Since y_n must be normalized,

$$\int_{-1}^1 |c_2|^2 \sin^2(n \cos^{-1} x) dx = 1 \implies |c_2| = \sqrt{\frac{2}{\pi}}$$

(iii) $\int_{-1}^1 \sqrt{\frac{2}{\pi}} \sqrt{\frac{2}{\pi}} \sin(m \cos^{-1} x) (\sin(n \cos^{-1} x)) dx = 0$ for $n \neq m$, due to orthogonality of sines.

Problem 6.12 (Laplace's Equation): In plane-polar coordinates (r, θ) , Laplace's equation is

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \Phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \Phi}{\partial \theta^2} = 0 \quad (*)$$

(a) Use separation of variables to show that the general solution of (*) that is continuous and single-valued for $r > 0$ can be written as

$$\Phi(r, \theta) = A_0 + B_0 \ln(r) + \sum_{n=1}^{\infty} [(A_n r^n + B_n r^{-n}) \cos(n\theta) + (C_n r^n + D_n r^{-n}) \sin(n\theta)]$$

where A_n, B_n, C_n , and D_n are constants. [10]

(b) The surface of an infinite cylinder is given by $r = R$ in cylindrical polar coordinates (r, θ, z) . The cylinder has a surface charge density $\sigma(\theta)$ so the electrostatic potential Φ is continuous at $r = R$, but its normal derivative has a discontinuity:

$$\left(\frac{\partial \Phi}{\partial r} \right)_{r=R^+} - \left(\frac{\partial \Phi}{\partial r} \right)_{r=R^-} = -\sigma(\theta)$$

where R^+ denotes the limit as $r \rightarrow R$ from above and R^- the limit as $r \rightarrow R$ from below. The surface charge density has Fourier series

$$\sigma(\theta) = \sum_{n=1}^{\infty} (a_n \cos(n\theta) + b_n \sin(n\theta))$$

Assume that Φ is independent of z and therefore satisfies (*) for $r < R$ and $r > R$. Determine Φ for all r , assuming that $\Phi \rightarrow 0$ as $r \rightarrow \infty$ and that Φ is finite at $r = 0$. [10]

Answer 6.12.

(a) Use separation of variables $\Phi(r, \theta) = R(r)\Theta(\theta)$:

$$\frac{1}{rR} \frac{d}{dr} \left(r \frac{dR}{dr} \right) = -\frac{1}{r^2 \Theta} \frac{d^2 \Theta}{d\theta^2} = \frac{\lambda}{r^2}$$

where λ is some constant. Then, the angular part gives $\Theta(\theta) = c_1 \cos \sqrt{\lambda} \theta + c_2 \sin \sqrt{\lambda} \theta$ for $\lambda \neq 0$ and $\Theta(\theta) = c_3 \theta + c_4$ for $\lambda = 0$. $\Theta(\theta)$ is single-valued, hence $c_3 = c_4 = 0$. Moreover, Θ is periodic, i.e. $\Theta(\theta + 2\pi) = \Theta(\theta)$ and this requires $\sqrt{\lambda} \pi = n\pi$ for $n \in \mathbb{Z}^+$. Thus,

$$\Theta(\theta) = c_1 \cos n\theta + c_2 \sin n\theta, \quad n \in \mathbb{R}^+$$

The radial part gives $rR' + r^2 R'' = \lambda R$. For $\lambda = 0$, $R(r) = c_7 \ln r + c_8$ but for $\lambda \neq 0$, try $R = r^k$ to get $k = \pm n$ and hence $R(r) = c_5 r^n + c_6 r^{-n}$. Then,

$$\Phi(r, \theta) = c_7 \ln r + c_8 + \sum_{n=1}^{\infty} (c_5 r^n + c_6 r^{-n}) (c_1 \cos n\theta + c_2 \sin n\theta)$$

Then we have $A_n = c_1 c_5$, $B_n = c_1 c_6$, $A_0 = c_8$ and $B_0 = c_7$.

(b) The boundary conditions on $\Phi(r, \theta)$:

- for $r > R$: $\lim_{r \rightarrow \infty} \Phi = 0 \implies A_n = C_n = A_0 = 0 \forall n$;
- for $r < R$: $R(r=0)$ is finite, so $B_n = D_n = B_0 = 0 \forall n$;
- continuity of Φ for $r = R \forall \theta$: $B_n = A_n R^{2n}$ and $D_n = C_n R^{2n}$;
- jump discontinuity of $\frac{\partial \Phi}{\partial r}$ at $r = R \forall \theta$:

$$-\sum_{n=1}^{\infty} a_n \cos n\theta + b_n \sin n\theta = -\sum_{n=1}^{\infty} (A_n \cos n\theta + C_n \sin n\theta)(nR^{-n-1}R^{2n} + nR^{-n-1}R^{2n})$$

Comparing coefficients give $A_n = \frac{a_n}{2nR^{n-1}}$, $B_n = \frac{a_n R^{n+1}}{2n}$, $C_n = \frac{b_n}{2nR^{n-1}}$ and $D_n = \frac{b_n R^{n+1}}{2n}$.

$$\Phi(r, \theta) = \begin{cases} \sum_{n=1}^{\infty} \frac{R^{n+1}}{2nr^n} (a_n \cos n\theta + b_n \sin n\theta) & r > R \\ \sum_{n=1}^{\infty} \frac{r^n}{2nR^{n-1}} (a_n \cos n\theta + b_n \sin n\theta) & r < R \end{cases}$$

Problem 6.13 (Green's Functions): Let V be a region of three-dimensional space with boundary S .

(a) Prove that

$$\int_V (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dV = \int_S (\phi \mathbf{n} \cdot \nabla \psi - \psi \mathbf{n} \cdot \nabla \phi) dS$$

where ϕ and ψ are scalar fields and \mathbf{n} is the outward-directed unit normal to S . [3]

(b) Let ϕ satisfy Laplace's equation $\nabla^2 \phi = 0$ in V , and let $G(\mathbf{x}, \mathbf{x}')$ obey

$$-\nabla_{\mathbf{x}}^2 G = \delta^{(3)}(\mathbf{x} - \mathbf{x}')$$

where $\nabla_{\mathbf{x}}$ is the gradient with respect to \mathbf{x} . Prove that [2]

$$\phi(\mathbf{x}') = \int_S [G(\mathbf{x}, \mathbf{x}') \mathbf{n} \cdot \nabla_{\mathbf{x}} \phi(\mathbf{x}) - \phi(\mathbf{x}) \mathbf{n} \cdot \nabla_{\mathbf{x}} G(\mathbf{x}, \mathbf{x}')] dS$$

(c) State the boundary condition that should be imposed on $G(\mathbf{x}, \mathbf{x}')$ for it to be a Green's function for Laplace's equation with Dirichlet boundary conditions (i.e., $\phi(\mathbf{x}) = f(\mathbf{x})$ on S). [2]

(d) Let V be the half-space $z > 0$ and let ϕ satisfy Laplace's equation in V with boundary conditions $\phi(x, y, 0) = f(x, y)$ and $\phi(\mathbf{x}) \rightarrow 0$ as $|\mathbf{x}| \rightarrow \infty$. Use the method of images to determine $G(\mathbf{x}, \mathbf{x}')$ and hence show that, for $z > 0$, [9]

$$\phi(x, y, z) = \frac{z}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{f(\xi, \eta)}{[(x - \xi)^2 + (y - \eta)^2 + z^2]^{3/2}} d\xi d\eta$$

[You may assume that $H(\mathbf{x}) = \frac{1}{4\pi|\mathbf{x}|}$ satisfies $-\nabla^2 H = \delta^{(3)}(\mathbf{x})$.]

(e) Determine $\phi(0, 0, z)$ explicitly for the case [4]

$$f(x, y) = \begin{cases} 0 & x^2 + y^2 > a^2 \\ 1 & x^2 + y^2 < a^2 \end{cases}$$

where $a > 0$.

Answer 6.13.

(a) Take the Divergence Theorem separately to $\phi \nabla \psi$ and $\psi \nabla \phi$:

$$\begin{aligned}\int_S \phi \nabla \psi \cdot d\mathbf{S} &= \int_V \nabla \cdot (\phi \nabla \psi) dV = \int_V \phi \nabla^2 \psi + \nabla \phi \cdot \nabla \psi dV \\ \int_S \psi \nabla \phi \cdot d\mathbf{S} &= \int_V \nabla \cdot (\psi \nabla \phi) dV = \int_V \psi \nabla^2 \phi + \nabla \psi \cdot \nabla \phi dV\end{aligned}$$

Now take the difference between the two results:

$$\int_S (\phi \nabla \psi - \psi \nabla \phi) \cdot d\mathbf{S} = \int_V (\phi \nabla^2 \psi + \nabla \phi \cdot \nabla \psi - \nabla \psi \cdot \nabla \phi - \psi \nabla^2 \phi) dV = \int_V (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dV$$

(b) Using $\nabla^2 \phi = 0$ and the result from part (a):

$$\int_S (\phi \nabla G - G \nabla \phi) \cdot d\mathbf{S} = \int_V \phi \nabla^2 G - G \nabla^2 \phi dV = \int_V \phi(\mathbf{r}) \delta^{(3)}(\mathbf{r} - \mathbf{r}') dV$$

(c) We require $G(\mathbf{x}, \mathbf{x}') = 0$ on S , then $\phi(\mathbf{x}') = - \int f(x, y) \nabla_{\mathbf{x}} G \cdot d\mathbf{S}$.

(d) Due to Uniqueness Theorem, we can replace the problem with one with images. This is valid as long as the Laplace's equation is still satisfied in V and the boundary conditions are still satisfied. In this case, we can add the image outside of V , then the corresponding G will be

$$G(\mathbf{x}, \mathbf{x}') = \frac{1}{4\pi} \left[\frac{1}{\sqrt{(x-x')^2 + (y-y')^2 + (z-z')^2}} - \frac{1}{\sqrt{(x-x')^2 + (y-y')^2 + (z+z')^2}} \right]$$

Then, taking gradient gives

$$\nabla_{\mathbf{x}} G(\mathbf{x}, \mathbf{x}') = \frac{2}{4\pi} \left[\frac{-1}{2} \frac{\mathbf{x} - \mathbf{x}'}{|\mathbf{x} - \mathbf{x}'|^{3/2}} + \frac{1}{2} \frac{\mathbf{x} - \mathbf{x}''}{|\mathbf{x} - \mathbf{x}''|^{3/2}} \right]$$

where $\mathbf{x}'' = \mathbf{x}' - (0, 0, 2z)$. At $z = 0$:

$$\begin{aligned}\phi(\mathbf{x}') &= \int_S \frac{f(x, y)}{4\pi} \left[\frac{\mathbf{x} - \mathbf{x}'}{|\mathbf{x} - \mathbf{x}'|^{3/2}} - \frac{\mathbf{x} - \mathbf{x}''}{|\mathbf{x} - \mathbf{x}''|^{3/2}} \right] dS \\ &= \frac{1}{4\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{f(x, y) z'}{((x-x')^2 + (y-y')^2 + z'^2)^{3/2}} - \frac{f(x, y) z'}{((x-x')^2 + (y-y')^2 + z'^2)^{3/2}} dx dy \\ &= \frac{z'}{4\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{f(x, y)}{((x-x')^2 + (y-y')^2 + z'^2)^{3/2}} dx dy\end{aligned}$$

Identify \mathbf{x}' with their \mathbf{x} , x with their ξ , y with their η .

(e) Switch to plane polars:

$$\phi(0, 0, z) = \frac{z}{2\pi} \int_0^a \int_0^{2\pi} \frac{r dr d\theta}{(\rho^2 + z^2)^{3/2}} = z \left[\frac{1}{z} - \frac{1}{\sqrt{a^2 + z^2}} \right] = 1 - \frac{z}{\sqrt{a^2 + z^2}}$$

Problem 6.14 (Contour Integration):

- (a) (i) State the residue theorem of complex analysis. [2]
 (ii) Consider the function

$$f(z) = \frac{z^2}{1 + z^4}$$

State the location of any singularities of $f(z)$ and calculate the residues of $f(z)$ at these singularities, simplifying your answers as much as possible. [7]

- (iii) By considering the integral of $f(z)$ around a large semicircle, evaluate the integral [3]

$$\int_{-\infty}^{\infty} \frac{x^2}{1 + x^4} dx$$

- (b) Use contour integration to determine the value of

$$\int_0^{\infty} \frac{\ln(x)}{x^2 + a^2} dx$$

where a is real and positive. State clearly the location of any branch cut required. [8]

Answer 6.14.

- (a) (i) Suppose f is analytic in a simply-connected domain except at a finite number of isolated singularities $\{z_1, \dots, z_n\}$. Suppose a simple closed contour γ encircles the origin anticlockwise, then the residue theorem states that

$$\oint_{\gamma} f(z) dz = 2\pi i \sum_{k=1}^n \text{res}_{z=z_k} f(z)$$

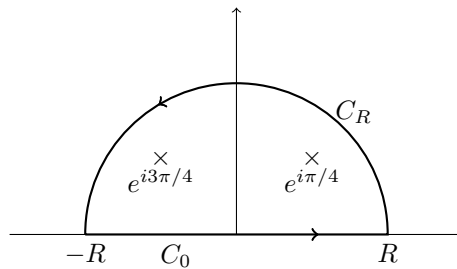
where the residue of an N th order isolated pole is

$$\text{res}_{z=z_0} f(z) = \lim_{z \rightarrow z_0} \frac{1}{(N-1)!} \frac{d^{N-1}}{dz^{N-1}} [(z - z_0)^N f(z)]$$

- (ii) The integrand has singularities at $z^4 = -1 \implies z = e^{i(\pi/4 + p\pi/2)}$ where $p = -2, -1, 0, 1$. Using L'Hopital rule, the residue is

$$\text{res}_{z=z_p} f(z) = \lim_{z \rightarrow z_p} (z - z_p) \frac{z^2}{z^4 + 1} = \lim_{z \rightarrow z_p} \frac{z^2}{4z^3} = \frac{1}{4} z_p^{-1} = \frac{1}{4} e^{-i(\pi/4 + p\pi/2)}$$

- (iii) The semicircle $C = C_0 \cup C_R$ encloses two poles $z = e^{i\pi/4}$ and $z = e^{i3\pi/4}$ for $R > 1$.



The residue theorem gives

$$\oint_C \frac{z^2}{1 + z^4} dz = 2\pi i (0.25e^{-i\pi/4} + 0.25e^{-i3\pi/4}) = \pi \cos \frac{\pi}{4}$$

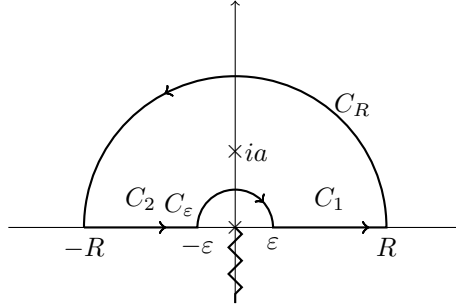
The integration along $\gamma_R : z = Re^{i\theta}$ gives

$$\begin{aligned} \int_{\gamma_R} \frac{z^2}{1 + z^4} dz &= \int_0^{\pi} \frac{R^2 e^{2i\theta}}{1 + R^4 e^{i4\theta}} i R e^{i\theta} d\theta \\ &= \frac{iR^3}{R^4} \int_0^{\pi} e^{-i\theta} \left(1 - \frac{1}{R^4} e^{-4i\theta}\right)^{-1} d\theta \\ &= \frac{i}{R} \int_0^{\pi} 1 + O(R^{-4}) d\theta \rightarrow 0 \text{ as } R \rightarrow \infty \end{aligned}$$

The contour integration would then be

$$\oint_C \frac{z^2}{1+z^4} dz \rightarrow \int_{\gamma_0} \frac{z^2}{1+z^4} dz = \int_{-\infty}^{\infty} \frac{x^2}{1+x^4} dx = \frac{\pi}{\sqrt{2}}$$

(b) Consider $\int_C \frac{\ln z}{z^2+a^2} dz$, then the integrand has branch point singularity at 0 and ∞ , as well as, first order poles at $x = \pm ia$. We need to choose a branch cut - say along the negative imaginary axis. We thus choose C to be an indentation contour.



The residue at the pole $z = +ia$ (enclosed by C) is

$$\text{res}_{z=ia} \frac{\ln z}{z^2+a^2} dz = \lim_{z \rightarrow ia} \frac{\ln z}{z+ia} d\theta = \frac{\ln a + i(\pi/2)}{2ai}$$

The corresponding contributions are:

$$\int_{C_1} \frac{\ln z}{z^2+a^2} dz \rightarrow \int_0^\infty \frac{\ln x}{a^2+x^2} dx, \text{ as } \varepsilon \rightarrow 0, R \rightarrow \infty$$

$$\int_{C_R} \frac{\ln z}{z^2+a^2} dz = \int_0^\pi \frac{\ln R + i\theta}{R^2 e^{2i\theta} + a^2} iR e^{i\theta} d\theta = \int_0^\pi O\left(\frac{\ln R}{R}\right) + O\left(\frac{1}{R}\right) d\theta \rightarrow 0, \text{ as } R \rightarrow \infty$$

$$\int_{C_2} \frac{\ln z}{z^2+a^2} dz = - \int_R^\varepsilon \frac{\ln r + i\pi}{r^2+a^2} dr \rightarrow \int_0^\infty \frac{\ln r}{r^2+a^2} dr + i\pi \int_0^\infty \frac{1}{r^2+a^2} dr, \text{ as } \varepsilon \rightarrow 0, R \rightarrow \infty$$

$$\int_{C_\varepsilon} \frac{\ln z}{z^2+a^2} dz = \int_\pi^0 \frac{\ln \varepsilon + i\theta}{\varepsilon^2 e^{2i\theta} + a^2} i\varepsilon e^{i\theta} d\theta = O(\varepsilon \ln \varepsilon) + O(\varepsilon) \rightarrow 0, \text{ as } \varepsilon \rightarrow 0$$

We thus have by residue theorem,

$$2\pi i \text{res}_{z=ia} \frac{\ln z}{z^2+a^2} dz = \oint_\gamma \frac{\ln z}{z^2+a^2} dz \rightarrow 2 \int_0^\infty \frac{\ln x}{x^2+a^2} dx + i\pi \int_0^\infty \frac{1}{r^2+a^2} dr$$

The real part gives

$$\int_0^\infty \frac{\ln x}{x^2+a^2} dx = \frac{\pi}{2a} \ln a$$

Problem 6.15 (Transform Methods): The response $y(t)$ of a system to a forcing function $f(t)$ is described by the second-order linear equation

$$\ddot{y} + 2\dot{y} + 5y = f(t) \quad (*)$$

You may assume that $f(t)$ vanishes as $t \rightarrow \pm\infty$.

- (a) By multiplying $(*)$ by $e^{-i\omega t}$ and integrating, or otherwise, show that the solution to $(*)$ can be written as

$$\tilde{y}(\omega) = -\frac{\tilde{f}(\omega)}{\omega^2 - 2i\omega - 5}$$

where $\tilde{y}(\omega)$ and $\tilde{f}(\omega)$ are the Fourier transforms of $y(t)$ and $f(t)$, respectively. [5]

- (b) Consider the forcing function described by $\tilde{f}(\omega) = \frac{i}{\omega - 2i}$.

- (i) Use contour integration in the complex ω plane to determine the solution $y(t)$ for both positive and negative t . [12]
- (ii) What does this solution imply about $f(t)$ for $t < 0$? (You need not determine $f(t)$ itself.) [3]

Answer 6.15.

- (a) We are essentially Fourier transforming $(*)$ by doing integration by parts, and assert $y, \dot{y} \rightarrow 0$ as $|t| \rightarrow \infty$.

$$\int_{-\infty}^{\infty} (\ddot{y} + 2\dot{y} + 5y)e^{-i\omega t} dt = \int_{-\infty}^{\infty} f(t)e^{-i\omega t} dt \implies -\omega^2 \tilde{y} + 2i\omega \tilde{y} + 5\tilde{y} = \tilde{f}(\omega)$$

The result follows.

- (b) (i) Perform inverse Fourier transform to find the solution

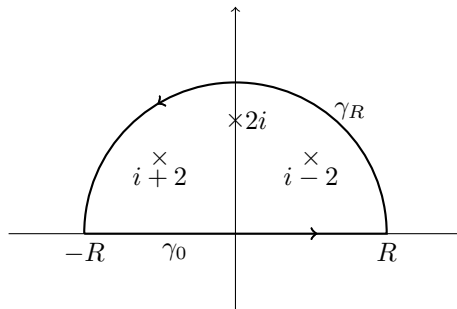
$$y(t) = -\frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{i}{\omega - 2i} \frac{1}{\omega^2 - 2i\omega - 5} e^{i\omega t} d\omega$$

The integrand has poles that satisfy

$$\omega^2 - 2i\omega - 5 = 0 \implies \omega = i \pm 2$$

as well as, $\omega = 2i$. To perform inverse Fourier transform, close the contour in the upper half-plane for $t > 0$ and lower half-plane for $t < 0$ (in order to invoke Jordan's Lemma). Close the upper half-plane ($t > 0$):

$$\lim_{|\omega| \rightarrow \infty} \frac{i}{(\omega^2 - 2i\omega - 5)(\omega - 2i)} = 0 \implies \int_{\gamma_R} \frac{ie^{i\omega t}}{(\omega - (i+2))(\omega - (i-2))(\omega - 2i)} dz \rightarrow 0, \text{ as } R \rightarrow \infty$$



All 3 poles are enclosed when we close the upper half-plane. The residues are

$$\text{res}_{\omega=2i} \frac{-i}{2\pi} \frac{e^{i\omega t}}{(\omega - (i+2))(\omega - (i-2))(\omega - 2i)} = \lim_{\omega \rightarrow 2i} \frac{-i}{2\pi} \frac{e^{i\omega t}}{(\omega - (i+2))(\omega - (i-2))} = \frac{i}{10\pi} e^{-2t}$$

$$\begin{aligned} \text{res}_{\omega=i\pm 2} \frac{-i}{2\pi} \frac{e^{i\omega t}}{(\omega - (i+2))(\omega - (i-2))(\omega - 2i)} &= \lim_{\omega \rightarrow i\pm 2} \frac{-i}{2\pi} \frac{e^{i\omega t}}{(\omega - 2i)(\omega - (i \mp 2))} \\ &= \frac{-i}{40\pi} (2 \pm i) e^{-t} e^{\pm 2it} \end{aligned}$$

Hence, by residue theorem,

$$-\frac{1}{2\pi} \oint_C \frac{i}{\omega - 2i} \frac{1}{\omega^2 - 2i\omega - 5} e^{i\omega t} dt = 2\pi i \left(\frac{i}{10\pi} e^{-2t} - \frac{i}{40\pi} (2+i) e^{-t} e^{2it} - \frac{i}{40\pi} (2-i) e^{-t} e^{-2it} \right)$$

But as $R \rightarrow \infty$, then LHS $\rightarrow y(t > 0)$.

Next, close the lower half-plane for $t < 0$ (in order to invoke Jordan's Lemma again). But since no poles are enclosed, we expect the contour integral to be zero after invoking residue theorem. Hence, the solution is

$$\begin{aligned} y(t) &= \begin{cases} -\frac{1}{5}e^{-2t} + \frac{1}{20}e^{-t}[(2+i)e^{2it} + (2-i)e^{-2it}] & t > 0 \\ 0 & t < 0 \end{cases} \\ &= \begin{cases} -\frac{1}{5}e^{-2t} + \frac{1}{10}e^{-t}(2 \cos 2t + \sin 2t) & t > 0 \\ 0 & t < 0 \end{cases} \end{aligned}$$

(ii) Given that the Green's function is causal and since $y(t) = 0$ for $t < 0$, we expect $f(t) = 0$ for $t < 0$.

Problem 6.16 (Tensors): Let T be a second-order tensor with components T_{ij} with respect to a Cartesian coordinate system (x_1, x_2, x_3) . An alternative Cartesian coordinate system (x'_1, x'_2, x'_3) is defined by $x'_i = M_{ij}x_j$.

- What restriction is placed on the transformation matrix M_{ij} ? How can one determine whether (x'_1, x'_2, x'_3) is a left- or right-handed coordinate system? Write down expressions for the components of T in the x'_i coordinate system in terms of T_{ij} . [3]
- Show that the symmetric and antisymmetric parts of T are second-order tensors. [3]
- Consider the second-order tensor field F , with position-dependent components

$$F_{ij} = \begin{pmatrix} x_1^2 & -x_1^2 + x_2x_1 - x_2^2 & x_1 - x_2 \\ x_1^2 + x_1x_2 + x_2^2 & x_2^2 & -x_1 - x_2 \\ -x_1 + x_2 & x_1 + x_2 & 3(x_1^2 + x_2^2) \end{pmatrix}$$

with respect to the x_i coordinates. Write down the components of the symmetric part of F . Determine the principal axes and corresponding principal values of the symmetric part of F , and describe the orientation of the principal axes geometrically.

Write down the transformation matrix M_{ij} that is needed to transform from the original axes to these principal axes. [10]

- Decompose the tensor field F introduced above as $F_{ij} = P\delta_{ij} + \hat{S}_{ij} + \hat{A}_{ij}$, where P is a scalar field, \hat{S}_{ij} is symmetric and trace-free, and \hat{A}_{ij} is antisymmetric. Determine whether the principal axes of \hat{S}_{ij} are the same as those found in (c). [4]

Answer 6.16.

- M must be orthogonal. With respect to the primed frame, if $(1, 0, 0) \times (0, 1, 0)$

- $= (0, 0, 1)$, the system is right-handed;
- $= (0, 0, -1)$, the system is left-handed.

$$T'_{ij} = M_{i\alpha}M_{j\beta}T_{\alpha\beta}$$

- Any second-order tensor may be decomposed into a symmetric part and an anti-symmetric part:

$$T_{ij} = \frac{1}{2}(T_{ij} + T_{ji}) + \frac{1}{2}(T_{ij} - T_{ji})$$

Now each part transforms like a second-order tensor:

$$\frac{1}{2}(T_{ij} \pm T_{ji})' = \frac{1}{2}(M_{i\alpha}M_{j\beta}T_{\alpha\beta} \pm M_{i\alpha}M_{j\beta}T_{\beta\alpha}) = M_{i\alpha}M_{j\beta}\frac{1}{2}(T_{\alpha\beta} \pm T_{\beta\alpha})$$

- The symmetric part of F is

$$S = \begin{pmatrix} x_1^2 & x_1x_2 & 0 \\ x_1x_2 & x_2^2 & 0 \\ 0 & 0 & 3(x_1^2 + x_2^2) \end{pmatrix}$$

By inspection, $3(x_1^2 + x_2^2)$ is an eigenvalue of S with eigenvector $(0, 0, 1)^T$. For the remaining:

$$0 = \det \begin{pmatrix} x_1^2 - \lambda & x_1x_2 \\ x_1x_2 & x_2^2 - \lambda \end{pmatrix} = (x_1^2 - \lambda)(x_2^2 - \lambda) - x_1^2x_2^2 = -\lambda(x_1^2 + x_2^2) + \lambda^2$$

The eigenvalues are thus $x_1^2 + x_2^2$ and 0 with respective eigenvectors $(x_1, x_2, 0)^T$ and $(x_2, -x_1, 0)^T$. The transformation matrix is

$$M = \frac{1}{\sqrt{x_1^2 + x_2^2}} \begin{pmatrix} x_1 & x_2 & 0 \\ x_2 & -x_1 & 0 \\ 0 & 0 & \sqrt{x_1^2 + x_2^2} \end{pmatrix}$$

(d) $P = \frac{\text{Tr}(S)}{3} = \frac{4(x_1^2 + x_2^2)}{3}$, and

$$\hat{S} = \begin{pmatrix} -(x_1^2 + 4x_2^2)/3 & x_1x_2 & 0 \\ x_1x_2 & -(4x_1^2 + x_2^2)/3 & 0 \\ 0 & 0 & -(5x_1^2 + 5x_2^2)/3 \end{pmatrix}, \quad \hat{A} = \begin{pmatrix} 0 & -x_1^2 - x_2^2 & x_1 - x_2 \\ x_1^2 + x_2^2 & 0 & -x_1 - x_2 \\ x_2 - x_1 & x_1 + x_2 & 0 \end{pmatrix}$$

Let \mathbf{e}_i be one of the eigenvectors along the principal axes, then

$$\hat{S}\mathbf{e}_i = S\mathbf{e}_i - P\mathbf{e}_i = (\lambda_i - P)\mathbf{e}_i$$

Problem 6.17 (Normal Modes): Three climbers have fallen from an overhanging cliff and are now suspended by their identical elastic safety ropes. The tension in each rope is given by $T(L) = k(L - L_0)$, for $L > L_0$, where k is a constant and L_0 is the unstretched length of each rope. Climber 1 is suspended from the cliff top by rope 1 with stretched length $L_1(t)$. The other two climbers are suspended directly from climber 1. Climber 2 is suspended from climber 1 by rope 2 with stretched length $L_2(t)$, while climber 3 is suspended from climber 1 by rope 3 with stretched length $L_3(t)$. The climbers have masses m_1 , m_2 , and m_3 , respectively. The mass of the ropes is negligible.

- (a) Write down expressions for the potential and kinetic energies of the system and hence determine its Lagrangian. (Take the gravitational acceleration to be g and remember to include the elastic potential energy.) [4]
- (b) Use the Euler–Lagrange equations to derive the equations of motion for L_i . Show that, at equilibrium, the lengths of the ropes are given by $L_i = \hat{L}_i$ where [5]

$$\hat{L}_1 = L_0 + \frac{g}{k}(m_1 + m_2 + m_3)$$

$$\hat{L}_2 = L_0 + \frac{g}{k}m_2$$

$$\hat{L}_3 = L_0 + \frac{g}{k}m_3$$

- (c) Let $y_i = L_i - \hat{L}_i$ be a small departure from equilibrium. Show that [2]

$$\begin{pmatrix} m_1 + m_2 + m_3 & m_2 & m_3 \\ m_2 & m_2 & 0 \\ m_3 & 0 & m_3 \end{pmatrix} \begin{pmatrix} \ddot{y}_1 \\ \ddot{y}_2 \\ \ddot{y}_3 \end{pmatrix} + \begin{pmatrix} k & 0 & 0 \\ 0 & k & 0 \\ 0 & 0 & k \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

- (d) Assume, now, that all climbers have equal mass m . Show that one normal mode of oscillation has frequency $\omega = \sqrt{k/m}$ and that climber 1 is stationary in this mode. For this case, describe the motion of the other two climbers. Determine also the frequencies of the other two modes of oscillation. [9]

Answer 6.17.

- (a) We define the positions of the 3 climbers relative to the top of the cliff are $z_1 = -L_1$, $z_2 = -L_2 - L_1$, $z_3 = -L_1 - L_3$. The Lagrangian is $\mathcal{L} = T - V$. The kinetic energy is

$$T = \frac{1}{2}m_1\dot{z}_1^2 + \frac{1}{2}m_2\dot{z}_2^2 + \frac{1}{2}m_3\dot{z}_3^2$$

The potential energy is

$$V = g(m_1z_1 + m_2z_2 + m_3z_3) + \frac{k}{2}[(L_1 - L_0)^2 + (L_2 - L_0)^2 + (L_3 - L_0)^2]$$

Then the Lagrangian is $\mathcal{L}[L_i, \dot{L}_i; t]$:

$$\begin{aligned} & \frac{1}{2}(m_1\dot{L}_1^2 + m_2(\dot{L}_2 + \dot{L}_1)^2 + m_3(\dot{L}_3 + \dot{L}_1)^2) \\ & + g(m_1L_1 + m_2(L_2 + L_1) + m_3(L_1 + L_3)) - \frac{1}{2}k((L_1 - L_0)^2 + (L_2 - L_0)^2 + (L_3 - L_0)^2) \end{aligned}$$

- (b) To extremize the Lagrangian, it must satisfy the Euler-Lagrange equation $\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{L}_i} = \frac{\partial \mathcal{L}}{\partial L_i} \quad \forall i = 1, 2, 3$:

$$\frac{d}{dt}(m_1\dot{L}_1 + m_2(\dot{L}_1 + \dot{L}_2) + m_3(\dot{L}_1 + \dot{L}_3)) = g(m_1 + m_2 + m_3) - k(L_1 - L_0)$$

$$\frac{d}{dt}(m_2(\dot{L}_2 + \dot{L}_1)) = gm_2 - k(L_2 - L_0)$$

$$\frac{d}{dt}(m_3(\dot{L}_3 + \dot{L}_1)) = gm_3 - k(L_3 - L_0)$$

In equilibrium, $\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{L}_i} = 0$, so $k(\hat{L}_1 - L_0) = g(m_1 + m_2 + m_3)$, $k(\hat{L}_2 - L_0) = gm_2$ and $k(\hat{L}_3 - L_0) = gm_3$, which is the desired result.

- (c) Let $y_i = L_i - \hat{L}_i$ and $\dot{y}_i = \dot{L}_i \quad \forall i$, so rearranging gives

$$\ddot{y}_1(m_1 + m_2 + m_3) + \ddot{y}_2 + \ddot{y}_3m_3 = -ky_1$$

$$\ddot{y}_1m_2 + \ddot{y}_2m_2 = 0 + ky_2$$

$$\ddot{y}_3m_3 + \ddot{y}_3m_3 = 0 + ky_3$$

This is equivalent to the desired matrix.

- (d) We look for solutions of the form $y_i = \text{Re}[a_ie^{i\omega t}]$, then we need solve the following equation to obtain ω^2 :

$$0 = \det \begin{pmatrix} 3 - \frac{k}{m\omega^2} & 1 & 1 \\ 1 & 1 - \frac{k}{m\omega^2} & 0 \\ 1 & 0 & 1 - \frac{k}{m\omega^2} \end{pmatrix} = \left(1 - \frac{k}{m\omega^2}\right) \left(\frac{k^2}{m^2\omega^4} - 4\frac{k}{m\omega^2} + 1\right)$$

The solutions are $\frac{k}{m\omega^2} = 1, 2 \pm \sqrt{3}$ and hence $\omega_0 := \sqrt{\frac{k}{m}}$ and $\omega_{\pm} = \sqrt{\frac{k}{m} \frac{1}{2 \pm \sqrt{3}}}$. For the ω_0 mode, let the eigenvector be $(a, b, c)^T$, then

$$0 = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \implies a = 0, b = -c$$

The other two climbers oscillate in anti-phase with equal amplitude, while the first climber is stationary.

Problem 6.18 (Group Theory):

(a) Let H be a subgroup of a finite group G . Define the left coset gH of H for an element $g \in G$. Prove that the left cosets of H partition G . [6]

(b) Show that the set of all real 3×3 matrices with elements

$$\begin{pmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{pmatrix} \quad (*)$$

forms a group under matrix multiplication. Show further that the subset of matrices with $x = z = 0$ forms a normal subgroup. [6]

(c) (i) Now suppose that x, y , and z are integers mod 4 (e.g., $5 \bmod 4 = 1$). Show that the set of matrices of the form in $(*)$ is a finite group G under matrix multiplication with arithmetic modulo 4, and determine the order of G . [4]

(ii) Show that the subset of such matrices given by $x = z$ defines an Abelian subgroup H . Determine the order of H . How many distinct left cosets of H are there in G ? [4]

Answer 6.18.

(a) A left coset of $H \leq G$ is

$$gH := \{g' \in G \mid g' = g * h \text{ for some } h \in H\}$$

for some $g \in G$. The set of left cosets is G/H . These cosets are either disjoint or identical. Let g_1H and g_2H only share a single element but $g_1 \neq g_2$, then

$$g_1h_i = g_2h_j \implies g_1 = g_2h_jh_i^{-1} = g_2h_k$$

where $h_i, h_j \in H$, $h_k = h_jh_i^{-1} \in H$. So, $g_1H = g_2h_kH = g_2H$. Take each element in G in turn and pre-multiply H by that element, then at least one coset contains each element in G . Each element is thus in one coset and this coset is the only one as shown earlier, then the cosets partition the group.

(b) We let the set of this matrix is G . Check group axioms:

- closure: Let $A, A' \in G$,

$$AA' = \begin{pmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & x' & y' \\ 0 & 1 & z' \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & x+x' & y'+xz'+y \\ 0 & 1 & z+z' \\ 0 & 0 & 1 \end{pmatrix} \in G$$

- associativity: matrix multiplication is associative.
- identity: $x = 0 = y = z \in \mathbb{R}$, so $I \in G$.
- Inverse: For $A \in G$, we have $x + x' = 0$, $z + z' = 0$, $x' + y' + xz = 0$. So,

$$A^{-1} = \begin{pmatrix} 1 & -x & -y+xz \\ 0 & 1 & -z \\ 0 & 0 & 1 \end{pmatrix} \in G$$

Let H to be the set of all real 3×3 matrices of the form ($x = z = 0$):

$$\begin{pmatrix} 1 & 0 & y \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

For H , trivial to show it inherits associativity and identity ($y = 0 \in \mathbb{R}$) and has an inverse ($y \in \mathbb{R} \implies -y \in \mathbb{R}$). This satisfies subgroup axioms, so $H \leq G$.

To check this form a normal subgroup in G , we need to show each element in H commutes with every element in G (so each element in H is in their conjugacy classes, hence H is built from the entire conjugacy classes, and hence normal in G):

$$\begin{pmatrix} 1 & 0 & y' \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & x & y+y' \\ 0 & 1 & z \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & y' \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

(c) Let $\mathbb{Z}_4 = \{0, 1, 2, 3\}$ be the set of integers modulo 4. The groups G and $H \leq G$ are of the same forms but this time over \mathbb{Z}_4 and not \mathbb{R} .

(i) Check the group axioms (all binary operations are defined modulo 4):

- closure: closed since $x, x' \in \mathbb{Z}_4 \implies x + x' \in \mathbb{Z}_4$; $x, y, y', z, z' \in \mathbb{Z}_4 \implies y + xz' + y' \in \mathbb{Z}_4$ and $z + z' \in \mathbb{Z}_4$.
- associativity: matrix multiplication is still associative over \mathbb{Z}_4 .
- identity: the same identity exists since $0 \in \mathbb{Z}_4$.
- inverse: when $x + x' = 0$, $y' + xz' + y = 0$ and $z + z' = 0$, we can find solutions $x', y', z' \in \mathbb{Z}_4$, so we have an inverse.

There are 4 possibilities for x, y, z and so 4^3 distinct matrices. The order of G is $4^3 = 64$.

(ii) Again, similar to part (b) and (ci), H will satisfy the subgroup axioms over \mathbb{Z}_4 . The order is now $4^2 = 16$. By Lagrange's theorem, the number of distinct cosets of H in G is $\frac{|G|}{|H|} = 4$.

Problem 6.19 (Group Theory): Let G and G_0 be finite groups.

- Let $\Phi : G \rightarrow G'$ be a homomorphism. Define the kernel K of Φ . Prove that K is a normal subgroup of G . [5]
- Define the conjugacy class of $g \in G$. Prove that any normal subgroup of G is a union of conjugacy classes. [3]
- What is meant by the cycle structure of a permutation? List the possible cycle structures for elements of Σ_3 (the permutation group for three objects). [3]
- Assume that $\Phi : \Sigma_3 \rightarrow G'$ is a homomorphism that is onto, i.e., any element of G' can be written as $\Phi(g)$ for some $g \in \Sigma_3$. Determine the possible forms of K (the kernel of Φ) and hence, or otherwise, prove that G' must be isomorphic to one of Σ_3 , C_2 (the cyclic group of order 2), or the trivial group $\{I\}$. [9]

[You may assume that two elements of Σ_3 belong to the same conjugacy class if, and only if, they have the same cycle structure.]

Answer 6.19.

(a) The kernel of a homomorphism $\Phi : G \rightarrow G'$ is

$$K = \{h \in G \mid \Phi(h) = e_{G'} \text{ for some } h \in G\}$$

First check $K \leq G$ (subgroup axioms):

- closed: let $k_1, k_2 \in K$, then $\Phi(k_1) = e_{G'} = \Phi(k_2)$. We have

$$e_{G'} = \Phi(k_1)\Phi(k_2) = \Phi(k_1k_2) \implies k_1k_2 \in K$$

- associativity: inherited from G .
- identity: $e_G \in K$ since $\Phi(e_G) = e_{G'}$.
- inverse: for $k \in K$,

$$e_{G'} = \Phi(e_G)\Phi(k^{-1}k) = \Phi(k^{-1}k) = \Phi(k^{-1})\Phi(k) = \Phi(k^{-1})e_{G'} \implies k^{-1} \in K$$

next, check K is a normal subgroup of G , i.e. $K \triangleleft G$. Let $k \in K$ and if $g \in G$,

$$\Phi(gkg^{-1}) = \Phi(g)\Phi(k)\Phi(g^{-1}) = \Phi(g)e_{G'}\Phi(g^{-1}) = e_{G'} \implies gkg^{-1} \in K$$

(b) The conjugacy class of $g \in G$, written as $\text{ccl}(g)$ is

$$\text{ccl}(g) = \{k \in G \text{ such that } k = hgh^{-1} \text{ for some } h \in G\}$$

H is a normal subgroup of G if for every $h \in H$ and $g \in G$, we have $ghg^{-1} \in H$. As a result, $Hg_i = g_iH \forall g_i \in G$, then $g_iHg_i^{-1} = H$. If $h_i \in H$ but does not contain every element to which h_i was conjugate, then the above will not be true. But it is, so H does contain every element to which h_i was conjugate to. Hence, H is a union of conjugacy classes.

- (c) Given a list $a_1, a_2, \dots, a_k \in \{1, 2, \dots, n\}$ of distinct elements, then the k -cycle $(a_1 a_2 \dots a_k) \in \Sigma_n$ is the permutation given by

$$(a_1 a_2 \dots a_k)(i) = \begin{cases} a_{j+1} & i = a_j \text{ for } j < k \\ a_1 & i = a_k \\ i & i \neq a_j \text{ for any } j \end{cases}$$

i.e. the k -cycle moves every element in the subset $\{a_1, a_2, \dots, a_k\} \subset \{1, 2, \dots, n\}$ and fixes every element outside of this subset. Every permutation $\sigma \in \Sigma_n$ can be written as a composition of disjoint cycles. The possible cycle structures of Σ_3 are $(\cdot)(\cdot)(\cdot)$, $(\cdot\cdot)(\cdot)$ and (\dots) .

- (d) Σ_3 consists of

$$\Sigma_3 = \{\text{Id} = (1)(2)(3), (12)(3), (23)(1), (13)(2), (123), (132)\}$$

Id has order 1, $(12)(3), (23)(1), (13)(2)$ have order 2 each, $(123), (132)$ have order 3 each. The group table of Σ_3 is

	Id	(12)(3)	(23)(1)	(13)(2)	(123)	(132)
Id	Id	(12)(3)	(23)(1)	(13)(2)	(123)	(132)
(12)(3)	(12)(3)	Id	(123)	(132)	(23)(1)	(13)(2)
(23)(1)	(23)(1)	(132)	Id	(123)	(13)(2)	(12)(3)
(13)(2)	(13)(2)	(123)	(132)	Id	(12)(3)	(23)(1)
(123)	(123)	(13)(2)	(12)(3)	(23)(1)	(132)	Id
(132)	(132)	(23)(1)	(13)(2)	(12)(3)	Id	(123)

The subgroups of Σ_3 are the trivial subgroup, Σ_3 itself, $\{\text{Id}, (12)(3)\}$, $\{\text{Id}, (23)(1)\}$, $\{\text{Id}, (13)(2)\}$, $\{\text{Id}, (123), (132)\}$. None of the order 2 subgroups are normal in Σ_3 , for instance:

$$(132)(12)(3)(132)^{-1} = (13)(2) \neq (12)(3)$$

so order 2 subgroups can't be $\text{Ker } \Phi$. In fact, only elements of the same order may be conjugate to each other (hence same cycle structure), say g_1, g_2 where $\text{ord}(g_1) = p$ and $\text{ord}(g_2) = q$, then

$$g_1 = hg_2h^{-1} \implies e = g_1^p = hg_2^ph^{-1} \implies g_2^p = h^{-1}eh = e$$

so q is a factor of p . Similarly, can show p is a factor of q . Hence, $p = q$. In conclusion, the only normal subgroups are $\{e\}$, Σ_3 and $\{\text{Id}, (12), (132)\}$. These are possible forms of $\text{Ker } \Phi$ by part (a).

Each coset of K in G can be put into one-to-one correspondence to the elements in G , which means the number of cosets of K is the number of elements in G . We can show this: suppose two cosets map to the same elements in G' , then

$$\Phi(g_i K) = \Phi(g_j K) \implies \Phi(g_j^{-1} g_i K) = \Phi(g_j^{-1}) \Phi(g_i K) = \Phi(g_j^{-1}) \Phi(g_j K) = \Phi(K) = I$$

Hence, $g_j^{-1} g_i K = K \implies g_i K = g_j K$, i.e. the two cosets are the same. Hence, the order of the image of an element must be a factor of the order of the pre-image.

- For the mapping whose kernel is Σ_3 , everything is mapped to the identity so This corresponds to $G' = \{\text{Id}\}$.
- For the mapping whose kernel is $\{\text{Id}\}$, this is an one-to-one onto mapping, so G and G' are isomorphic, i.e. $G \simeq G'$.
- For the mapping whose kernel is $\{\text{Id}, (123), (132)\}$. The above shows that there are only two elements in G' , hence $G' = C_2$ (cyclic).

Problem 6.20 (Representation Theory): Consider the D_6 dihedral group

$$G = \{I, R, R^2, R^3, R^4, R^5, m_1, m_2, m_3, m_4, m_5, m_6\}$$

with structure defined by the group table

	I	R	R^2	R^3	R^4	R^5	m_1	m_2	m_3	m_4	m_5	m_6
I	I	R	R^2	R^3	R^4	R^5	m_1	m_2	m_3	m_4	m_5	m_6
R	R	R^2	R^3	R^4	R^5	I	m_2	m_3	m_4	m_5	m_6	m_1
R^2	R^2	R^3	R^4	R^5	I	R	m_3	m_4	m_5	m_6	m_1	m_2
R^3	R^3	R^4	R^5	I	R	R^2	m_4	m_5	m_6	m_1	m_2	m_3
R^4	R^4	R^5	I	R	R^2	R^3	m_5	m_6	m_1	m_2	m_3	m_4
R^5	R^5	I	R	R^2	R^3	R^4	m_6	m_1	m_2	m_3	m_4	m_5
m_1	m_1	m_6	m_5	m_4	m_3	m_2	I	R^5	R^4	R^3	R^2	R
m_2	m_2	m_1	m_6	m_5	m_4	m_3	R	I	R^5	R^4	R^3	R^2
m_3	m_3	m_2	m_1	m_6	m_5	m_4	R^2	R	I	R^5	R^4	R^3
m_4	m_4	m_3	m_2	m_1	m_6	m_5	R^3	R^2	R	I	R^5	R^4
m_5	m_5	m_4	m_3	m_2	m_1	m_6	R^4	R^3	R^2	R	I	R^5
m_6	m_6	m_5	m_4	m_3	m_2	m_1	R^5	R^4	R^3	R^2	R	I

- (a) What do the generators R and m_1 represent geometrically? Give an expression for each of the group members in terms of the generators $\{R, m_1\}$. [2]
- (b) Identify all the subgroups of order 2 and 3. Are any of these subgroups cyclic? [5]
- (c) Explain how to construct a faithful representation of G using 2×2 orthogonal matrices. Give matrices corresponding to R , m_1 , and m_2 in such a representation. [4]
- (d) Write down the regular representation $D(g)$ for $g = m_4$ and hence or otherwise derive an expression for $[D(m_4)]^n$ for any integer n . [5]
- [Reminder: the regular representation is a set of $|G| \times |G|$ permutation matrices each with $|G|$ non-zero elements.]
- (e) State the characters of the representations used above in (c) and (d). [4]

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7.1 Paper 1

Problem 7.1 (Vector Calculus):

- (a) State the divergence theorem for a vector field $\mathbf{F}(x, y, z)$. [2]
 (b) Let the surface S be defined as $S = S_1 \cup S_2 \cup S_3$, where

$$S_1 = \{(x, y, z) : x^2 + y^2 = 2 - z, 1 \leq z \leq 2\}$$

$$S_2 = \{(x, y, z) : x^2 + y^2 = 1, 0 \leq z \leq 1\},$$

$$S_3 = \{(x, y, z) : z = 0, x^2 + y^2 \leq 1\}$$

Sketch all four surfaces. [4]

- (c) Given that $\mathbf{F}(x, y, z) = (2xy + x^6, -y^2 + y^4, z)$, find $\oint_S \mathbf{F} \cdot d\mathbf{S}$, where $d\mathbf{S}$ is an element of vector area pointing in the direction of the outward normal to S . [14]

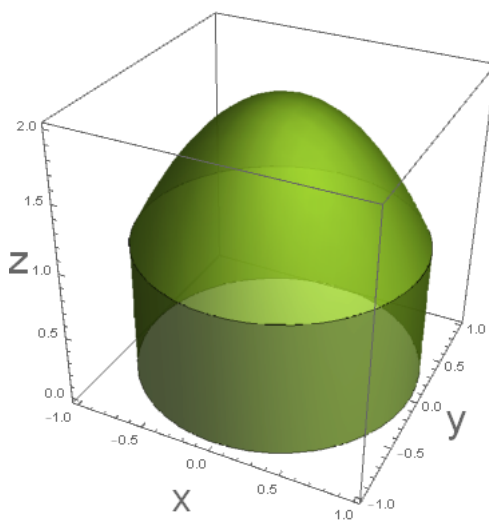
Answer 7.1.

- (a) If $\mathbf{F} = \mathbf{F}(\mathbf{x})$ be a continuously differentiable vector field and V is a volume with a piecewise regular boundary ∂V , then divergence theorem states

$$\int_V \nabla \cdot \mathbf{F} dV = \int_{\partial V} \mathbf{F} \cdot d\mathbf{S}$$

where the normal to ∂V points outwards from V .

- (b) S_3 is the bottom circular base of the cylindrical curved surface S_2 . S_1 is a parabolic cap on top of S_2 .



- (c) The divergence of \mathbf{F} is

$$\nabla \cdot \mathbf{F} = 2y + 6x^5 - 2y + 4y^3 + 1 = 6r^5 \cos^5 \theta + 4r^3 \sin^3 \theta + 1$$

We then invoke divergence theorem:

$$\oint_S \mathbf{F} \cdot d\mathbf{S} = \int_V \nabla \cdot \mathbf{F} dV = \int_0^1 \int_0^{2-r^2} \int_{-\pi}^{\pi} (6r^5 \cos^5 \theta + 4r^3 \sin^3 \theta + 1) r d\theta dz dr = 2\pi \int_0^1 r(2-r^2) dr = \frac{3}{2}\pi$$

where integrate odd power of trigonometric functions over integer number of cycles gives zero.

Problem 7.2 (Partial Differential Equation): A string of uniform density per unit length ρ is stretched under tension along the x -axis and undergoes small transverse oscillations in the (x, y) plane with amplitude $y(x, t)$. The waves in the string travel with velocity c and the equation of motion satisfied by $y(x, t)$ is

$$\frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{\partial^2 y}{\partial x^2}$$

(a) If the string is fixed at $x = 0$ and $x = L$, derive the general separable solution for the amplitude $y(x, t)$. [9]

(b) For $t < 0$ the string is at rest. At $t = 0$ the string is struck by a hammer in the interval $[\ell - a/2, \ell + a/2]$, the distance being measured from one end. The effect of the hammer is to impart a constant velocity v to the string inside the interval and zero velocity outside the interval. Calculate the proportion of the total energy given to the string in each mode.

[You may assume the kinetic energy formula $K.E. = \int_0^L \frac{\rho}{2} (\partial y / \partial t)^2 dx$.] [9]

(c) If $\ell = L/5$ and $a = L/7$, identify all the modes of the string which are not excited by the hammer. [2]

Answer 7.2.

(a) Since the boundary condition is homogeneous, we can use separation of variables $y = X(x)T(t)$.

$$\frac{T''}{T} = c^2 \frac{X''}{X} = -\lambda^2$$

where the minus sign was chosen and $\lambda \neq 0$ due to the boundary conditions $y(0, t) = y(L, t) = 0 \forall t$. We have $X \sim \sin \frac{\lambda}{c} x$ and $T(t) \sim c_3 \sin \lambda t + c_4 \cos \lambda t$. We require $\lambda = \frac{n\pi c}{L}$ such that $n \in \mathbb{N}$. Then, we have the general solution to be

$$y(x, t) = \sum_{n=1}^{\infty} \sin \frac{n\pi x}{L} \left(A_n \cos \frac{n\pi ct}{L} + B_n \sin \frac{n\pi ct}{L} \right)$$

(b) For $t < 0$, the string is at rest, so $A_n = 0 \forall n$. The initial velocity $g(x) = v$ for $x \in [\ell - 0.5a, \ell + 0.5a]$ and zero elsewhere. We have $g(x) = \frac{\partial y}{\partial t} \Big|_{t=0} = \sum_{n=1}^{\infty} \sin \frac{n\pi x}{L} B_n \frac{n\pi c}{L}$. Then, the Fourier coefficients will be

$$B_n \frac{n\pi c}{L} = \frac{2}{L} \int_0^L g(x) dx \implies B_n = \frac{L}{n\pi c} \frac{2}{L} \int_{\ell-0.5a}^{\ell+0.5a} v \sin \frac{n\pi x}{L} dx = -\frac{4vL}{n^2\pi^2 c} \sin \frac{n\pi a}{2L} \sin \frac{n\pi \ell}{L}$$

The kinetic energy for the n th mode is

$$\begin{aligned} K_n &= \frac{1}{2} \rho \int_0^L g(x)^2 \sin^2 \frac{n\pi ct}{L} dx \\ &= \frac{1}{2} \rho \int_0^L \left(B_n \frac{n\pi c}{L} \right)^2 \sin^2 \frac{n\pi x}{L} \sin^2 \frac{n\pi ct}{L} dx \\ &= \frac{4\rho v^2}{n^2\pi^2} \sin^2 \frac{n\pi ct}{L} \sin^2 \frac{n\pi a}{2L} \sin^2 \frac{n\pi \ell}{L} \left[x - \frac{L}{2\pi n} \sin^2 \frac{n\pi x}{L} \right]_0^L \\ &= \frac{4\rho L v^2}{n^2\pi^2} \sin^2 \frac{n\pi ct}{L} \sin^2 \frac{n\pi a}{2L} \sin^2 \frac{n\pi \ell}{L} \end{aligned}$$

The total energy is the maximum of kinetic energy which is $\frac{4\rho L v^2}{n^2\pi^2} \sin^2 \frac{n\pi a}{2L} \sin^2 \frac{n\pi \ell}{L}$. The total energy imparted is $\int_0^L \frac{1}{2} \rho v^2 dx = \frac{1}{2} \rho v^2 \int_{\ell-a/2}^{\ell+a/2} dx = \frac{1}{2} \rho a v^2$. The ratio will be $\frac{8L}{a n^2\pi^2} \sin^2 \frac{n\pi a}{2L} \sin^2 \frac{n\pi \ell}{L}$.

(c) If the coefficient B_n is zero, that mode is not excited. For $\ell = \frac{L}{5}$, $a = \frac{L}{7}$,

$$B_n = -\frac{4vL}{n^2\pi^2 c^2} \sin \frac{n\pi}{14} \sin \frac{n\pi}{5}$$

We thus require to be $n = 0 \pmod{5}$ or $\pmod{14}$, i.e. a multiple of either 5 or 14.

Problem 7.3 (Green's Functions): Consider the linear differential operator \mathcal{L} defined by

$$\mathcal{L}y = -\frac{d^2y}{dx^2} + y$$

on the interval $0 \leq x < \infty$. The boundary conditions are given by $y(0) = 0$ and $\lim_{x \rightarrow \infty} y(x) = 0$.

- (a) Find the Green's function $G(x, \xi)$ for \mathcal{L} satisfying these boundary conditions. Hence, or otherwise, obtain the solution of

$$\mathcal{L}y = \begin{cases} 1 & 0 \leq x < \mu \\ 0 & \mu < x < \infty \end{cases}$$

subject to the above boundary conditions, where μ is a positive constant. [14]

- (b) Show that your piecewise solution is continuous at $x = \mu$ and has the value [6]

$$y(\mu) = \frac{1}{2}(1 + e^{-2\mu} - 2e^{-\mu})$$

Answer 7.3.

- (a) The homogeneous solutions are e^x and e^{-x} . The corresponding Green's function satisfy

$$\mathcal{L}G = -\frac{\partial^2 G(x, \xi)}{\partial x^2} + G(x, \xi) = \delta(x - \xi), \quad G(0, \xi) = 0, \quad \lim_{x \rightarrow \infty} G(x, \xi) = 0$$

Integrate around an infinitesimal region about $x = \xi$, we obtain the jump condition $[G']_{\xi-}^{\xi+} = 1$. G is continuous everywhere, including $x = \xi$ (otherwise, $G'' \propto \delta'(x - \xi)$ which is a contradiction). Using the homogeneous solutions and the b.c.s,

$$G(x, \xi) = \begin{cases} A \sinh x & 0 \leq x < \xi < \infty \\ B e^{-x} & 0 \leq \xi < x < \infty \end{cases}$$

At $x = \xi$, the continuity and jump conditions give respectively

$$A \sinh \xi = B e^{-\xi}$$

$$B e^{-\xi} + A \cosh \xi = +1$$

These give $A = e^{-\xi}$ and $B = \sinh \xi$. The solution is thus

$$y(x) = \int_0^\infty G(x, \xi) f(\xi) d\xi = \int_x^\infty e^{-\xi} \sinh(x) f(\xi) d\xi + \int_0^x e^{-x} \sinh \xi f(\xi) d\xi$$

For $x < \mu$,

$$y(x) = \sinh x \int_x^\mu e^{-\xi} d\xi + \int_0^x \sinh \xi e^{-x} d\xi = e^{2x} - e^x - \frac{1}{2}e^\mu(e^x - e^{-x})$$

For $x > \mu$,

$$y(x) = e^{-x} \int_0^\mu \sinh \xi d\xi = -e^x + \frac{1}{2}e^x(e^\mu + e^{-\mu})$$

- (b) At $x = \mu$, both sides give $y(\mu) = e^{2\mu} - e^\mu - \frac{1}{2}e^{2\mu} + 0.5$ and $y(\mu) = -e^\mu + 0.5e^{2\mu} + 0.5$, which are equal and hence continuous.

Problem 7.4 (Fourier Transform): The waveform $\phi(t)$ transmitted by an analogue radio is produced by modulating a carrier wave $c(t) = \cos(\Omega t)$ of frequency Ω by the signal $s(t)$ to be broadcast such that

$$\phi(t) = (1 + s(t))c(t)$$

The Fourier transform of $s(t)$ is $\tilde{s}(\omega)$ and the maximum amplitude of $s(t)$ does not exceed unity.

- (a) What is the Fourier transform $\tilde{c}(\omega)$ of the carrier wave? What is $\tilde{\phi}(\omega)$, the Fourier transform of $\phi(t)$, in terms of $\tilde{s}(\omega)$? [4]

- (b) For the case

$$s(t) = \frac{1 - \cos t}{t^2},$$

compute the Fourier transform to show that

$$\tilde{s}(\omega) = \begin{cases} \pi(1 - |\omega|) & |\omega| < 1 \\ 0 & |\omega| \geq 1 \end{cases}$$

Sketch $|\tilde{s}(\omega)|$ and hence $|\tilde{\phi}(\omega)|$ for $\Omega > 1$. [Hint: The Fourier transform of $1/t^2$ is $-\pi|\omega|$.] [6]

- (c) To reduce the bandwidth requirements for the radio, a ‘single side-band’ design was adopted such that the new transmitted signal $\rho(t)$ has a Fourier transform given by

$$\tilde{\rho}(\omega) = \begin{cases} \tilde{\phi}(\omega) & |\omega| < \Omega \\ 0 & |\omega| \geq \Omega \end{cases}$$

For the case $\Omega = \frac{3}{4}$ and using the form of $\tilde{\phi}(\omega)$ determined in (b), sketch $|\tilde{\phi}(\omega)|$ and $|\tilde{\rho}(\omega)|$. Determine $\rho(t)$. [10]

Answer 7.4.

- (a) The Fourier transform of the carrier wave is

$$\tilde{c}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \cos(\Omega t) e^{-i\omega t} dt = \frac{\sqrt{2\pi}}{2} (\delta(\Omega - \omega) + \delta(\Omega + \omega))$$

By convolution theorem,

$$\phi(t) = c(t) + s(t)c(t) \implies \tilde{\phi}(\omega) = \tilde{c}(\omega) + \tilde{s}(\omega) * \tilde{c}(\omega) = \sqrt{\frac{\pi}{2}} (\delta(\Omega - \omega) + \delta(\Omega + \omega)) + \sqrt{\frac{\pi}{2}} (\tilde{s}(\Omega - \omega) + \tilde{s}(\Omega + \omega))$$

- (b) The Fourier transform of $s(t)$ is

$$\tilde{s}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} (t^{-2} - t^{-2} \cos t) e^{-i\omega t} dt = \frac{1}{\sqrt{2\pi}} (-\pi|\omega| - \frac{1}{2}(-\pi|\omega - 1|) - \frac{1}{2}(-\pi|\omega + 1|))$$

where we used $\cos(t) = \frac{1}{2}(e^{it} + e^{-it})$. Turns out $\tilde{s}(\omega)$ is a triangle function,

$$\tilde{s}(\omega) = \begin{cases} 0 & |\omega| > 1 \\ \sqrt{\frac{\pi}{2}}(|\omega| - 1) & |\omega| < 1 \end{cases}$$

$\tilde{\phi}(\omega)$ is thus two triangle functions centred at $\omega = \pm\Omega$ such that a delta peak occurs at this value as well, with the base at the tip of the triangle ($|\tilde{\phi}| = \sqrt{\frac{\pi}{2}}$).

- (c) For $\Omega = \frac{3}{4}$, the two triangles will definitely overlap, resulting in a straight line (add up) from $\omega = -\frac{1}{4}$ to $\omega = +\frac{1}{4}$. In addition, select the part within $[-\Omega, +\Omega]$ and so an inverse Fourier transform is needed to find $\rho(t)$:

$$\begin{aligned} & \frac{1}{\sqrt{2\pi}} \sqrt{\frac{\pi}{2}} \left[\int_{-3/4}^{-1/4} \left(\frac{1}{4} - \omega \right) e^{i\omega t} d\omega + \int_{-1/4}^{1/4} \frac{1}{2} e^{i\omega t} d\omega + \int_{1/4}^{3/4} \left(\frac{1}{4} + \omega \right) e^{i\omega t} d\omega \right] \\ &= \frac{1}{2} \left(\left[\left(\frac{1}{4} - \omega \right) \frac{e^{i\omega t}}{it} \right]_{-3/4}^{-1/4} + \frac{1}{it} \int_{-3/4}^{-1/4} e^{i\omega t} d\omega \right) + \frac{1}{4it} [e^{i\omega t}]_{-1/4}^{1/4} + \frac{1}{2} \left(\left[\left(\frac{1}{4} + \omega \right) \frac{e^{i\omega t}}{it} \right]_{-3/4}^{-1/4} - \frac{1}{it} \int_{1/4}^{3/4} e^{i\omega t} d\omega \right) \\ &= \frac{\sin 0.75t}{t} + \frac{1}{t^2} [-e^{-it/4} + e^{-i3t/4} + e^{i3t/4} - e^{it/4}] \\ &= \frac{1}{t} \sin \frac{3t}{4} + \frac{1}{t^2} (2 \cos 0.75t - 2 \cos 0.25t) \end{aligned}$$

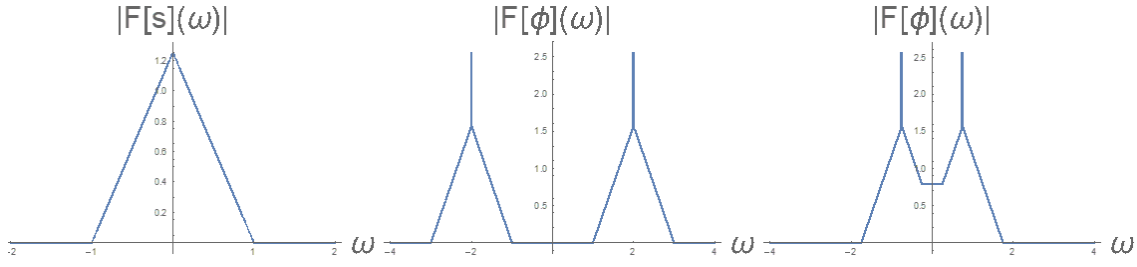


Figure 1: (Left) $F[s](\omega) := \tilde{s}(\omega)$; $F[\phi](\omega) := \tilde{s}(\omega)$ for arbitrarily $\Omega = 2$ where as long as $\Omega - 1 > -\Omega + 1$ is satisfied (centre) and $\Omega = 0.75$ (right).

Problem 7.5 (Linear Algebra):

- Given an $n \times n$ matrix M and the identity I , show that the matrices $I + M$ and $(I - M)^{-1}$ commute. [4]
- Show that the three eigenvalues of a real orthogonal 3×3 matrix are $e^{+i\alpha}$, $e^{-i\alpha}$ and $+1$ or -1 , where α is real. [4]
- For a real antisymmetric matrix A , the matrix N is defined by

$$N = (I + A)(I - A)^{-1}$$

- Show that N is orthogonal. [3]
- Show that eigenvectors of A are also eigenvectors of N . What is the relation between the eigenvalues of A and the eigenvalues of N ? [4]
- Show that when A and N are 3×3 matrices, $\det N = 1$ and that there exists a direction x in which $Ax = 0$, with $x \neq 0$. [5]

Answer 7.5.

- Expand and regroup

$$(I + M)(I - M) = I - M + M - M^2 = I + M - M - M^2 = (I - M)(I + M)$$

Then, multiply $(I - M)^{-1}$ on the left and right for both sides,

$$(I - M)^{-1}(I + M)(I - M)(I - M)^{-1} = (I - M)^{-1}(I - M)(I + M)(I - M)^{-1}$$

to show $(I - M)^{-1}(I + M) = (I + M)(I - M)^{-1}$.

- We have $Ae = \lambda e$, then

$$\lambda|e|^2 = e^\dagger Ae = (Ae)^\dagger e = e^\dagger A^\dagger e = A^{-1}e^\dagger e = \lambda^{-1}|e|^2 \implies \left(\frac{1}{\lambda^*} - \lambda\right)|e|^2 = 0$$

where A is real and orthogonal, so $A^\dagger = A^T = A^{-1}$. Since $|e| \neq 0$, we must have $|\lambda|^2 = 1$. Then the eigenvalues are either ± 1 or come in complex conjugate pairs $e^{\pm i\alpha}$.

- (i) Before showing $N^T N = I$, we first show $(B^{-1})^T = (B^T)^{-1}$ for any B .

$$I = BB^{-1} = (B^{-1})^T B^T \implies (B^T)^{-1} = (B^{-1})^T$$

Then, using $[I + M, (I - M)^{-1}] = 0$ from part (a), and that $A^T = -A$:

$$\begin{aligned} N^T N &= [(I + A)(I - A)^{-1}]^T (I + A)(I - A)^{-1} = [(I - A)^{-1}]^T (I + A)^T (I + A)(I - A)^{-1} \\ &= [(I - A)^{-1}]^T (I - A)(I + A)(I - A)^{-1} \\ &= [(I - A)^{-1}]^T (I - A)(I - A)^{-1} (I + A) \\ &= [(I - A)^{-1}]^T (I + A) \\ &= (I + A)^{-1} (I + A) = I \end{aligned}$$

- (ii) Let x be eigenvectors of A such that $Ax = \lambda x$. Then, $(I - A)^{-1} = (1 - \lambda)^{-1}x$, provided $\lambda \neq 1$. This is true since the eigenvalues of an anti-symmetric matrix must be imaginary: We have $Ae = \lambda e$, then

$$\lambda|e|^2 = e^\dagger Ae = (Ae)^\dagger e = e^\dagger A^\dagger e = e^\dagger (-A)e = -\lambda^*|e|^2 \implies (\lambda + \lambda^*)|e|^2 = 0$$

where A is real and anti-symmetric, i.e. $A^\dagger = A^T = -A$. So, $\lambda = -\lambda^*$ must be imaginary. Then,

$$Nx = (I + A)(I - A)^{-1}x = \frac{1 + \lambda}{1 - \lambda}x$$

x is indeed an eigenvector of N with eigenvalue $\frac{1+\lambda}{1-\lambda}$.

- (iii) Since A is antisymmetric, $A = -A^T$. But

$$\det A = (-1)^n \det(A^T), \quad \det A = \det A^T$$

This means for $n = 3$, $\det A = 0$. So $\det A = \prod_j \lambda_j = 0$, so at least one of the eigenvalues of A must be zero. \exists an eigenvector that A sends to zero. Take $\lambda = 0$, then one of the three eigenvalues of N is $+1$. Since $\det N = 1$, the other 2 eigenvalues must be complex conjugate pairs.

Problem 7.6 (Linear Algebra):

- (a) What does it mean for an $n \times n$ square matrix to be diagonalisable? [2]
- (b) Suppose that A is a complex $n \times n$ matrix such that $A^p = 0$ for some positive integer p . Show that A has 0 as an eigenvalue. Show that A is not diagonalisable unless $A = 0$. [6]
- (c) Let B and C be the matrices

$$B = \begin{pmatrix} 4+2\alpha & -2 & -2-4\alpha \\ 3\alpha & -3 & 9-6\alpha \\ 2+\alpha & -1 & -1-2\alpha \end{pmatrix} \text{ and } C = \begin{pmatrix} 0 & 2 & 6 \\ 3 & 3 & 3 \\ 3 & 1 & -3 \end{pmatrix}$$

By considering the characteristic polynomials of B and C , determine whether B and C are diagonalizable. [12]

Answer 7.6.

- (a) A square matrix A is diagonalizable if there exists a matrix S such that $S^{-1}AS$ is a diagonal matrix. S is constructed from n linearly independent vectors. This is easily found if A possesses n distinct eigenvalues, and thus each eigenvalue will have a separate eigenvector.
- (b) If $A^p = 0$ and $Ae = \lambda e$, then $0 = A^p e = \lambda^p e \implies \lambda^p = 0 \implies \lambda = 0$.
If A were diagonalizable, $\exists S$ such that $S^{-1}AS = \text{diag}(a_1, a_2, \dots)$. Hence, $(S^{-1}AS)^p = \text{diag}(a_1^p, a_2^p, \dots)$. But $(S^{-1}AS)^p = S^{-1}A^p S = 0$, so $S^{-1}AS = 0$ and thus $A = 0$.
- (c) For B , we evaluate the determinant along the second row for ease.

$$\begin{aligned} & \det(B - \lambda I) \\ &= \det \begin{pmatrix} 4+2\alpha-\lambda & -2 & -2-4\alpha \\ 3\alpha & -3-\lambda & 9-6\alpha \\ 2+\alpha & -1 & -1-2\alpha-\lambda \end{pmatrix} \\ &= -3\alpha \begin{vmatrix} -2 & -2-4\alpha \\ -1 & -1-2\alpha-\lambda \end{vmatrix} + (-3-\lambda) \begin{vmatrix} 4+2\alpha-\lambda & -2-4\alpha \\ 2+\alpha & -1-2\alpha-\lambda \end{vmatrix} - (9-6\alpha) \begin{vmatrix} 4+2\alpha-\lambda & -2 \\ 2+\alpha & -1 \end{vmatrix} \\ &= -3\alpha(2(1+2\alpha+\lambda) - (2+4\alpha)) - (3+\lambda)[(2+4\alpha)(2+\alpha) - (4+2\alpha-\lambda)(1+2\alpha+\lambda)] \\ &\quad - (9-6\alpha)[2(2+\alpha) - (4+2\alpha-\lambda)] \\ &= -\lambda^3 \end{aligned}$$

All three eigenvalues are zero. From (b), B is not diagonalizable since it is not the null matrix. For C , we evaluate the determinant along the first row.

$$\begin{aligned} \det(C - \lambda I) &= \det \begin{pmatrix} -\lambda & 2 & 6 \\ 3 & 3-\lambda & 3 \\ 3 & 1 & -3-\lambda \end{pmatrix} \\ &= -\lambda \begin{vmatrix} 3-\lambda & 3 \\ 1 & -3-\lambda \end{vmatrix} - 2 \begin{vmatrix} 3 & 3 \\ 3 & -3-\lambda \end{vmatrix} + 6 \begin{vmatrix} 3 & 3-\lambda \\ 3 & 1 \end{vmatrix} \\ &= -\lambda[-(3-\lambda)^2(3+\lambda) - 3] - 2[-3(3+\lambda) - 9] + 6[3 - 3(3-\lambda)] \\ &= 36\lambda - \lambda^3 \end{aligned}$$

The eigenvalues are 0 and ± 6 . Since there are 3 distinct eigenvalues, from part (a), the matrix is diagonalizable.

Problem 7.7 (Cauchy-Riemann): Consider the mapping $z = f(\zeta)$ such that $G(z) = G(f(\zeta)) = \psi(\zeta)$, where f, G, ψ are complex functions and z, ζ are complex variables.

(a) What condition(s) must be satisfied for $\psi(\zeta)$ to be analytic? [3]

(b) Suppose that $\psi(\zeta) = \ln(\zeta + 2)$ and $f(\zeta)$ is defined by

$$\frac{df}{d\zeta} = \frac{i}{\sqrt{(\zeta + 1)(\zeta - 1)}} \quad (*)$$

where $\zeta = 0$ maps to $z = 0$.

(i) By integrating, show that the upper half of the ζ plane maps onto the region R defined by $|\operatorname{Re}(z)| \leq \frac{\pi}{2}$, $\operatorname{Im}(z) \geq 0$. Determine the location of any points in the region R where $G(z)$ is not analytic. How do these relate to points in the ζ plane? [Hint: $\sin(x + iy) = \sin(x) \cosh(y) + i \cos(x) \sinh(y)$.] [7]

(ii) The vector field $\mathbf{u} = (u, v)$ in the ζ plane is given by $u - iv = \frac{d\psi}{d\zeta}$. How does the magnitude of \mathbf{u} vary across the upper half of the ζ plane? In what direction is \mathbf{u} oriented? [3]

(iii) The vector field $\mathbf{U} = (U, V)$ is defined in the region R of the z plane by $U - iV = \frac{dG}{dz}$. Determine this field and use a sketch to illustrate the orientation of the vector field in this region. [7]

Answer 7.7.

(a) A function $\psi = u + iv$ is analytic in $\zeta = a + ib$ if its complex derivative

$$\frac{d\psi}{d\zeta} := \lim_{\Delta\zeta \rightarrow 0} \frac{\psi(\zeta + \Delta\zeta) - \psi(\zeta)}{\Delta\zeta}$$

exists and is independent of the direction of approach of $\Delta\zeta \rightarrow 0$ in the complex plane. So, take any two orthogonal directions Δa and $i\Delta b$.

$$\lim_{\Delta a \rightarrow 0} \frac{\psi(a + \Delta a + ib) - \psi(a + ib)}{\Delta a} = \lim_{\Delta b \rightarrow 0} \frac{\psi(a + i(b + \Delta b)) - \psi(a + ib)}{i\Delta b} \implies \frac{\partial u}{\partial a} + i \frac{\partial v}{\partial a} = -i \frac{\partial u}{\partial b} + \frac{\partial v}{\partial b}$$

This is the Cauchy-Riemann equations that $\psi(\zeta)$ need to satisfy in order to be analytic.

(b) f is a mapping from the ξ plane to the z plane, while G is a mapping

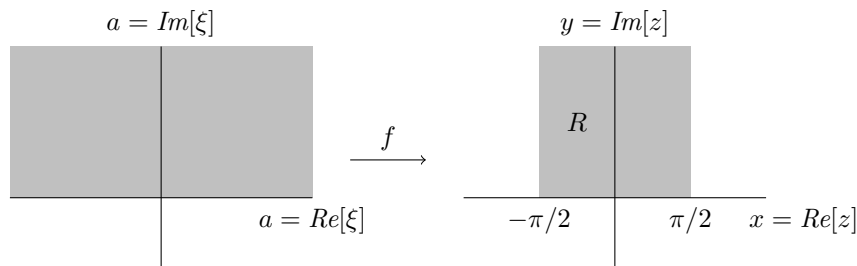
$$G: x + iy = z = f(\xi = a + ib) \rightarrow \psi(\xi)$$

(i) We have $df = \frac{d\zeta}{\sqrt{1-\zeta^2}} = \frac{\cos u du}{\sqrt{1-\sin^2 u}} \implies f = \sin^{-1} \zeta + C$ where we used $\zeta = \sin u$.

As \sin is periodic in its real argument, we must restrict the range of \sin^{-1} . Since $\zeta = 0 \mapsto f(\zeta) = 0 \implies C = 0$. ζ in terms of x and y is

$$a + ib = \zeta = \sin f(\zeta) = \sin z = \sin x \cosh y + i \cos x \sinh y$$

For Region R , $\frac{\pi}{2} \geq |\operatorname{Re}[z]| = |x| \implies \cos x \geq 0$ and together with $\operatorname{Im}[z] = y \geq 0 \implies \sinh y \geq 0$. Hence, $b = \cos x \sinh y \geq 0$ which is the upper half-plane of ξ .



Now, we want to find the point(s) in R where G is not analytic.

$$G(z) = \psi(\zeta) = \ln(\zeta + 2) = \ln(\sin z + 2)$$

G is not analytic at either $\sin z = \infty$ or

$$\sin z = \sin x \cosh y + i \cos x \sinh y = -2 \implies y = 0, x = \pm \frac{\pi}{2}$$

but $\sin x \cosh 0 = -2$ has no solution, so only $x = \pm \frac{\pi}{2}$. There is only one solution to $\sin(\pm \frac{\pi}{2}) \cosh(y) = -2$, which is $x = -\pi/2$, $y = \cosh^{-1}(2) = \pm \ln(2 + \sqrt{2^2 - 1}) = \pm \ln(2 + \sqrt{3})$. But $y \geq 0$ in region R , so $y = \ln(2 + \sqrt{3})$. There is thus only one finite point in region R where G is not analytic: $z = -\frac{\pi}{2} + i \ln(2 + \sqrt{3})$.

(ii) We have

$$u - iv = \frac{d\psi}{d\zeta} = \frac{d}{d\zeta} \ln(\zeta + 2) = \frac{1}{\zeta + 2} = \frac{a + 2 - ib}{(a + 2)^2 + b^2}$$

Hence, $\mathbf{u} = (a + 2, b)^T \frac{1}{(a+2)^2 + b^2}$ which implies $|\mathbf{u}| = \frac{1}{\sqrt{(a+2)^2 + b^2}}$, and \mathbf{u} is directed radially away from the point $(-2, 0)$ in the ξ -plane towards the origin.

(iii) We have

$$U - iV = \frac{dG}{dz} = \frac{d}{dz} \ln|2 + \sin z| = \frac{\cos z}{2 + \sin z} = \frac{\cos x \cosh y - i \sin x \sinh y}{\sin x \cosh y + 2 + i \cos x \sinh y}$$

This requires

$$U = \operatorname{Re} \left[\frac{dG}{dz} \right] = \frac{\cos x (2 \cosh y + \sin x)}{(2 + \sin x \cosh y)^2 + \cos^2 x \sinh^2 y}$$

$$V = \operatorname{Im} \left[\frac{dG}{dz} \right] = \frac{\sinh y (\cosh y + 2 \sin x)}{(2 + \sin x \cosh y)^2 + \cos^2 x \sinh^2 y}$$

We have $dG = (U - iV)dz = (U + iV)^*(dx + idy) = \mathbf{U} \cdot d\mathbf{l}$. \mathbf{U} is thus orthogonal to the contours of constant G , i.e. $G = c \in \mathbb{C} \implies z = \sin^{-1}(e^c - 2)$. Plotting \mathbf{U} and $G = c$ in region R ($|\operatorname{Re}[z]| \leq 0.5\pi$, $\operatorname{Im}[z] \geq 0$):

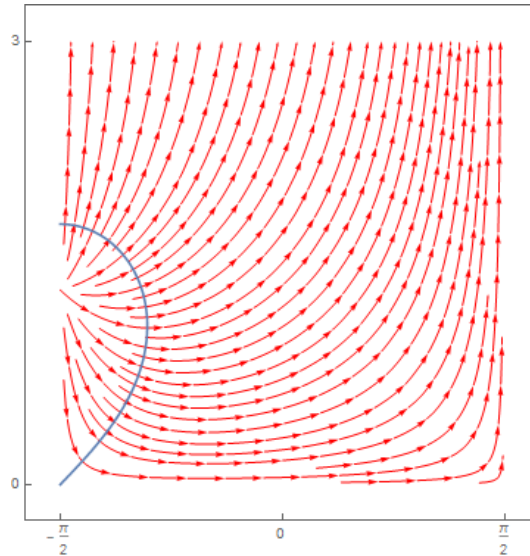


Figure 2: \mathbf{U} in red and $G = c$ in blue, in region R

Important points of the plot: singularity at $(x = -\pi/2, y = \ln(2 + \sqrt{3}))$ which has non-zero divergence (This must be true since $\nabla \cdot \mathbf{U} = \frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} = \frac{\partial U}{\partial x} - \frac{\partial U}{\partial x} = 0$ everywhere else by Cauchy-Riemann equations since G is analytic $\implies \frac{\partial G}{\partial z}$ is analytic). Near vertical vector field lines at $x = \pm \frac{\pi}{2}$ since $U = 0$ for $x = \pm \frac{\pi}{2}$ (numerator has $\cos x$). Near horizontal vector field lines at $y = 0$ since $V = 0$ for $y = 0$ (numerator has $\sinh y$).

Problem 7.8 (Series Solution to ODE):

- (a) Define the terms ordinary point and regular singular point for a second order linear differential equation of the form

$$\frac{d^2y}{dx^2} + p(x)\frac{dy}{dx} + q(x)y = 0$$

and explain briefly the reason for distinguishing between them. [4]

- (b) Let $f(x)$ and $g(x)$ be two differentiable functions on $x \in [a, b]$. Define the Wronskian $W(f, g)(x)$ and show that if $W(f, g)(x_0) \neq 0$ for $x_0 \in [a, b]$ then f and g are linearly independent on $[a, b]$. [6]

- (c) Find power series solutions of the equation

$$(1 - x^2)\frac{d^2y}{dx^2} - x\frac{dy}{dx} + k^2y = 0$$

about the point $x = 0$, giving the recurrence relation for the coefficients. Determine the radius of convergence of the solutions about $x = 0$. [10]

Answer 7.8.

- (a) For the given ordinary differential equation, an ordinary point x_0 is where both $p(x)$ and $q(x)$ are analytic at $x = x_0$. A regular singular point x_1 is where either $p(x)$ and $q(x)$ are not analytic at $x = x_1$, but both $(x - x_1)p(x)$ and $(x - x_1)^2q(x)$ are analytic at $x = x_1$.

For a regular singular point, there will always be at least one series expansion of the solution to the differential equation in its neighbourhood. For an ordinary point, there will always exist two linearly independent series solution in its neighbourhood.

- (b) The Wronskian is defined to be $W(f, g)(x) := fg' - gf'$. For f and g to be linearly dependent in the interval $[a, b]$, there must exist some scalar α such that $f = \alpha g$ everywhere in this interval. Equivalently, $W = 0$ everywhere in this interval. Hence, the existence of a single point where $W \neq 0$ is sufficient to guarantee linear independence on every point in the domain within which the functions are differentiable.

- (c) Since $\frac{-x}{1-x^2}$ and $\frac{k^2}{1-x^2}$ are both analytic at $x = 0$, $x = 0$ is an ordinary point. We can thus try a series solution of the form $y = \sum_{n=0}^{\infty} a_n x^n$.

$$\sum_{n=0}^{\infty} n(n-1)a_n x^{n-2} - \sum_{n=0}^{\infty} n(n-1)a_n x^n - \sum_{n=0}^{\infty} na_n x^2 + k^2 \sum_{n=0}^{\infty} a_n x^n \implies a_{n+2} = a_n \frac{n^2 - k^2}{(n+2)(n+1)}$$

So the series solution is

$$y = \sum_{n=0}^{\infty} a_n x^n, \quad a_{n+2} = a_n \frac{n^2 - k^2}{(n+2)(n+1)}$$

For the series to converge, we require $\lim_{n \rightarrow \infty} \left| \frac{a_{n+2}}{a_n} \right| |x|^2 < 1 \quad \forall |x| < 1$, then the radius of convergence will be

$$R = \lim_{n \rightarrow \infty} \sqrt{\left| \frac{a_n}{a_{n+2}} \right|} = \lim_{n \rightarrow \infty} \sqrt{\frac{(n+2)(n+1)}{n^2 - k^2}} = 1$$

Problem 7.9 (Variational Principle):

- (a) Suppose that the speed of light $c(y)$ varies continuously through a medium and is a function of the distance from the boundary $y = 0$. Use Fermat's principle to show that the path $y(x)$ of the light ray is given by the solution of [4]

$$c(y)y'' + c'(y)(1 + y'^2) = 0$$

- (b) The curve assumed by a uniform chain, which is suspended between two points $(-a, b)$ and (a, b) minimises the potential energy,

$$\int_{-a}^a y(1 + y'^2)^{1/2} dx$$

subject to the constraint that its length remains fixed,

$$\int_{-a}^a (1 + y'^2)^{1/2} dx = 2L$$

where $L > a$.

- (i) Show that the curve is the catenary

$$y - y_0 = k \cosh \frac{x - x_0}{k}$$

where k , x_0 and y_0 are constants. [8]

- (ii) Find an equation for k and show, using a graphical method, that it has a unique positive solution. [8]

Answer 7.9.

- (a) *Fermat's Principle states that the path adopted by a light ray is one where its time of flight is minimized. The time functional is*

$$T[y] = \int \frac{dt}{dl} dl = \int \frac{1}{c(y)} \sqrt{1 + y'^2} dx$$

with end points at $x = a, b$. To find stationary T , the integral f must satisfy the Euler-Lagrange equation

$$\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} = 0$$

where $f(y, y'; x) = \frac{1}{c(y)} \sqrt{1 + y'^2}$. By Euler-Lagrange,

$$0 = -\frac{1}{c^2} c' \sqrt{1 + y'^2} - \frac{d}{dx} \frac{1}{c} \frac{y'}{\sqrt{1 + y'^2}} \implies c'(1 + y'^2) + cy'' = 0$$

- (b) (i) Extremize

$$F = \int_{-a}^a y(1 + y'^2)^{1/2} dx + y_0 \left(\int_{-a}^a (1 + y'^2)^{1/2} dx - 2L \right)$$

where y_0 is the Lagrange multiplier (reason to be made obvious later). But since the integrand $f = (y - y_0) \sqrt{1 + y'^2}$ is not explicitly dependent on x , then $\frac{\partial f}{\partial x} = 0$. By chain rule,

$$\frac{df}{dx} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' = 0 + y \frac{d}{dx} \frac{\partial f}{\partial y'} + \frac{\partial f}{\partial y'} y'' = \frac{d}{dx} y' \frac{\partial f}{\partial y'}$$

where we used the Euler-Lagrange equation. So, $f - y' \frac{\partial f}{\partial y'}$ is a constant, say k :

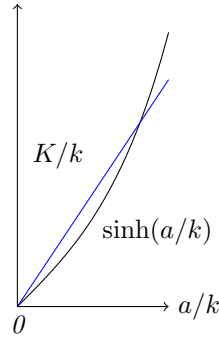
$$k = (y - \lambda) \sqrt{1 + y'^2} - \frac{y'(y - y_0)y'}{\sqrt{1 + y'^2}} \implies y' = \frac{1}{k} \sqrt{(y - y_0)^2 - k^2}$$

We substitute $y - \lambda = k \cosh u$ to get $y - y_0 = A \cosh \frac{x - x_0}{k}$.

(ii) The boundary conditions are $y = b$ for $x = \pm a$, this gives $x_0 = 0$. Also,

$$2L = \int_{-a}^a \sqrt{1 + \sinh^2 \frac{x}{k}} dx = 2k \sinh \frac{a}{k}$$

We see that graphically, $\sinh(a/k) = L/k$ gives a unique positive solution at $a/k > 0$ since $L/a > 1$.



Problem 7.10 (Rayleigh-Ritz Method):

- (a) Let E_n be the eigenvalues of the self-adjoint operator H , and ψ_n be the corresponding orthonormal eigenfunctions. Let $F[\phi]$ be the functional

$$F[\phi] = \frac{\int \phi^* H \phi d\tau}{\int \phi^* \phi d\tau}$$

(for finite, non-zero $\int \phi^* \phi d\tau$) where $\phi(\tau)$ is a finite arbitrary function and the integration extends from $-\infty$ to $+\infty$.

- (i) If ψ_n is an eigenfunction of H , show that [2]

$$F[\psi_n] = E_n$$

- (ii) Show that if $\phi = \psi_n + \delta\phi$, where $\delta\phi$ is an arbitrary infinitesimal variation, the functional $F[\psi_n]$ is stationary and that

$$(H - F[\psi_n])\phi = 0$$

State any assumptions made. [6]

- (iii) Show that $F[\phi]$ gives an upper bound to the exact ground state eigenvalue E_0 by expanding ϕ as

$$\phi = \sum_n a_n \psi_n$$

where $\int \phi^* \phi d\tau = \sum_n |a_n|^2$. [2]

- (b) Consider a particle of mass m moving in one dimension. For the operator $H = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2}$ for $-a < x < a$, with $H = 0$ elsewhere, the exact ground state eigenvalue E_0 is given by

$$E_0 = \frac{6\hbar^2}{5ma^2}$$

where a and \hbar are constants. Use the Rayleigh-Ritz method to obtain the lowest upper bound of the value of E_0 by choosing a trial function

$$\phi_{trial}(\lambda, x) = \begin{cases} (a^2 - x^2)(1 + \lambda x^2) & -a \leq x \leq a \\ 0 & |x| > a \end{cases}$$

where λ is a real variational parameter. [10]

[You may assume that the roots to the quadratic equation $13a^4\lambda^2 + 98a^2\lambda + 21$ are approximately $-1/5a^2$ and $-7/a^2$.]

Answer 7.10.

(a) (i) Since $H\psi_n = E\psi_n$,

$$F[\psi_n] = \frac{\int_{-\infty}^{\infty} \psi_n^* H \psi_n d\tau}{\int_{-\infty}^{\infty} \psi_n^* \psi_n d\tau} = E_n$$

(ii) With $\phi = \psi_n + \delta\phi$, and discarding higher orders of $\delta\phi$:

$$\begin{aligned} F[\psi_n + \delta\phi] &= \frac{\langle \psi_n | H | \psi_n \rangle + \langle \psi_n | H | \delta\phi \rangle + \langle \delta\phi | H | \psi_n \rangle + \langle \delta\phi | H | \delta\phi \rangle}{\langle \psi_n | \psi_n \rangle + \langle \psi_n | \delta\phi \rangle + \langle \delta\phi | \psi_n \rangle + \langle \delta\phi | \delta\phi \rangle} \\ &= \frac{E_n + E_n(\langle \psi_n | \delta\phi \rangle + \langle \delta\phi | \psi_n \rangle) + O(\delta\phi^2)}{1 + (\langle \psi_n | \delta\phi \rangle + \langle \delta\phi | \psi_n \rangle) + O(\delta\phi^2)} \\ &= E_n + O(\delta\phi^2) \end{aligned}$$

We see that there is no first order of $\delta\phi$, hence the functional is stationary, i.e. $\frac{\delta F}{\delta\phi} = 0$. Consider the state

$$|\Phi\rangle = (H - F[\psi_n])|\phi\rangle = (H - E_n)|\psi_n + \delta\phi\rangle = (E_n - E_n)|\psi_n\rangle + (H - E_n)|\delta\phi\rangle = (H - E_n)|\delta\phi\rangle$$

then the norm of this state is $O(\delta\phi^2)$, which is zero up to the first order. For the norm to be zero, it means the state is zero.

(iii) The exact ground state is by definition the global minimum eigenvalue. Since the stationary points of F are eigenvalues, $F[\phi]$ must bound E_0 from above.

(b) With $\phi_{\text{trial}} = -\lambda x^4 + x^2(-1 + a^2\lambda) + a^2 \implies \frac{d^2\phi_{\text{trial}}}{dx^2} = -12\lambda x^2 + 2(-1 + a^2\lambda)$, then $\int \phi^* \phi dx$ and $\int \phi^* H \phi dx$ respectively gives

$$2 \int_0^a \lambda^2 x^8 + 2\lambda x^6(1 - a^2\lambda) + x^4(-2\lambda a^2 + (-1 + a^2\lambda)^2) + 2a^2 x^2(-1 + a^2\lambda) + a^4 dx = \frac{16a^5}{315}(\lambda^2 a^4 + 6\lambda a^2 + 21)$$

$$\begin{aligned} \int \phi^* H \phi dx &= -\frac{\hbar^2}{2m} \int \phi^* \frac{d^2}{dx^2} \phi dx \\ &= -\frac{\hbar^2}{2m} \int_{-a}^a (-\lambda x^4 + x^2(-1 + a^2\lambda) + a^2)(-12\lambda x^2 + 2(-1 + a^2\lambda)) dx \\ &= \frac{\hbar^2}{m} \int_0^a -12\lambda^2 x^6 + x^4(2\lambda(-1 + a^2\lambda) - 12\lambda + 12a^2\lambda^2) \\ &\quad + x^2(12\lambda a^2 + 2(1 - a^2\lambda)(-1 + a^2\lambda)) - 2a^2(-1 + a^2\lambda) dx \\ &= \frac{4\hbar^2 a^3}{105m} (11\lambda^2 a^4 + 14\lambda a^2 + 35) \end{aligned}$$

Then, we must have

$$F[\phi] = \frac{\int \phi^* H \phi dx}{\int \phi^* \phi dx} = \frac{12\hbar^2}{16ma^2} \frac{11\lambda^2 a^4 + 14\lambda a^2 + 35}{a^4\lambda^2 + 6\lambda a^2 + 21}$$

Differentiating with respect to λ , then

$$0 = \frac{\partial F}{\partial \lambda} \implies 13\lambda^2 a^4 + 98\lambda a^2 + 21 = 0$$

We are given that the roots to this quadratic equation is $-\frac{1}{5a^2}$ and $-\frac{7}{a^2}$, then

$$F[-0.2a^{-2}] = \frac{153}{124} \frac{\hbar^2}{ma^2}, \quad F[-7a^{-2}] = \frac{51}{4} \frac{\hbar^2}{ma^2}$$

Our lowest upper bound is the lowest of the two, which is the former. Since $\frac{153\hbar^2}{124ma^2} > E_0 = \frac{6\hbar^2}{5ma^2}$, then it is indeed an overestimate of the lowest eigenvalue.

7.2 Paper 2

Problem 7.11 (Sturm-Liouville): Consider the Sturm-Liouville system

$$\mathcal{L}y(x) - \lambda\omega(x)y(x) = 0, a \leq x \leq b$$

where

$$\mathcal{L}y(x) = -[p(x)y'(x)]' + q(x)y(x)$$

with $\omega(x) > 0$ and $p(x) > 0$ for all x in $[a, b]$. The boundary conditions on y are

$$A_1y(a) + A_2y'(a) = 0$$

$$B_1y(b) + B_2y'(b) = 0$$

where A_1, A_2, B_1 and B_2 are constants and all functions are real.

(a) Show that with these boundary conditions, \mathcal{L} is self-adjoint. [4]

(b) By considering $y\mathcal{L}y$, or otherwise, show that the eigenvalue λ can be written as [4]

$$\lambda = \frac{\int_a^b [py'^2 + qy^2]dx - [pyy']_a^b}{\int_a^b \omega y^2 dx}$$

(c) Now suppose that $a = 0$ and $b = \ell$, that $p(x) = 1$, $q(x) \geq 0$ and $\omega(x) = 1$ for all x in $[0, \ell]$, and that $A_1 = 1$, $A_2 = 0$, $B_1 = k > 0$ and $B_2 = 1$. Show that the eigenvalues of this Sturm-Liouville system are strictly positive. [4]

(d) Assume further that $q(x) = 0$ and solve the system explicitly. With the aid of a sketch, show that there exist infinitely many eigenvalues $\lambda_1 < \lambda_2 < \dots < \lambda_n < \dots$ [6]

(e) Describe the behaviour of λ_n as $n \rightarrow \infty$. [2]

Answer 7.11.

(a) To be self-adjoint, we require $\langle u|\mathcal{L}v \rangle = \langle \mathcal{L}u|v \rangle$ for any pair of functions u, v that satisfy the given boundary conditions.

$$\langle u|\mathcal{L}v \rangle = \int_a^b -u(pv')' + uqv dx = [-puv']_a^b + \int_a^b u'pv' + uqv dx = [p(u'v - uv')]_a^b + \int_a^b -(pu')'v + uqv dx$$

The boundary condition term is $p(b)(u'(b)v(b) - u(b)v'(b)) - p(a)(u'(a)v(a) - u(a)v'(a))$ with each term vanishing on its own, given $A_1u(a) + A_2u'(a) = 0 \implies A_1u(a)v'(a) + A_2u'(a)v(a) = 0$ and $A_1v(a) + A_2v'(a) = 0 \implies A_1u'(a)v(a) + A_2v'(a)u'(a)$.

(b) We have $\langle y|\mathcal{L}y \rangle = \lambda\langle y|y \rangle_\omega$, with the LHS being

$$\int_a^b -y(py')' + yqy dx = [-pyy']_a^b + \int_a^b py'^2 + qy^2 dx \implies \lambda = \frac{\int_a^b [py'^2 + qy^2]dx - [pyy']_a^b}{\int_a^b \omega y^2 dx}$$

(c) The boundary conditions are $y(0) = 0$ and $ky(\ell) + y'(\ell) = 0$ with $k > 0$

$$\lambda = \frac{\int_0^\ell [y'^2 + qy^2]dx - [yy']_0^\ell}{\int_0^\ell y^2 dx} = \frac{\int_0^\ell [y'^2 + qy^2]dx + ky(\ell)^2}{\int_0^\ell y^2 dx}$$

Since the ratio of integrals above is strictly positive, all the eigenvalues will be positive.

(d) With $q(x) = 0$, then $\frac{d^2y}{dx^2} = -\lambda y$ with the same boundary conditions. We thus have $y = \sin tx$ such that $\tan(t\ell) = -\frac{t}{k}$. Plot $f(t) := \tan(t\ell)$ and $g(t) := -\frac{t}{k}$, then we can see that there are infinitely many different solutions, each spaced out so that the solutions are never dense on the t -axis, and that they increase without limit.

(e) As $n \rightarrow \infty$, the intersection point approaches the asymptote at $(2n+1)\frac{\pi}{2}$ and so

$$\lim_{n \rightarrow \infty} \frac{\lambda_n}{(2n+1)0.5\pi} = 1$$

Problem 7.12 (Laplace's Equation): Consider the Laplace equation in bipolar coordinates

$$\frac{\partial^2 \Phi}{\partial \sigma^2} + \frac{\partial^2 \Phi}{\partial \tau^2} = 0 \quad (*)$$

where $0 \leq \sigma < 2\pi$ is a periodic coordinate and $\tau > 0$.

- (a) Use separation of variables to show that the general solution of (*), which is continuous and single valued for $\tau > 0$, can be written as

$$\Phi = A_0 + B_0 \tau + \sum_{n=1}^{+\infty} \left\{ \left[A_n \cosh(n\tau) + B_n \sinh(n\tau) \right] \cos(n\sigma) + \left[C_n \cosh(n\tau) + D_n \sinh(n\tau) \right] \sin(n\sigma) \right\}$$

where A_n , B_n , C_n and D_n are constants. [10]

- (b) A line of constant τ is a circle of radius $1/\sinh \tau$ that can be defined in terms of Cartesian coordinates as

$$y^2 + (x - \coth \tau)^2 = \frac{1}{\sinh^2 \tau}$$

Suppose Φ satisfies (*) in the region defined by $a < \tau < b$. The inner circle, defined by $\tau = a$, is held at $\Phi = 0$ and the outer circle, defined by $\tau = b$, is held at $\Phi = \cos(2\sigma)$. Use separation of variables to find Φ in the region $a < \tau < b$. [10]

Answer 7.12.

- (a) Use separation of variables $\Phi(\tau, \sigma) = T(\tau)\Theta(\sigma)$:

$$\frac{1}{\Theta} \frac{d^2 \Theta}{d\sigma^2} = -\frac{d^2 T}{d\tau^2} = -\lambda^2$$

where λ is some constant, then $\Theta(\sigma) = c_1 \cos \lambda \sigma + c_2 \sin \lambda \sigma$ for $\lambda \neq 0$ and $c_3 \sigma + c_4$ for $\lambda = 0$. But $\Theta(\sigma + 2\pi) = \Theta(\sigma) \implies c_3 = c_4 = 0$ and $\lambda = n \in \mathbb{Z}^+$. Also, $T(\tau) = c_7 \tau + c_8$ for $\lambda = 0$ and $T(\tau) = c_5 \sinh \lambda \tau + c_6 \cosh \lambda \tau$ for $\lambda \neq 0$. Thus,

$$\Phi(\tau, \sigma) = c_7 \tau + c_8 + \sum_{n=1}^{\infty} (c_5 \sinh n\tau + c_6 \cosh n\tau)(c_1 \cos n\sigma + c_2 \sin n\sigma)$$

where we identify $c_7 = A_0$, $c_8 = B_0$, $c_5 c_1 = B_n$, $c_6 c_1 = A_n$, $c_2 c_6 = C_n$, $c_2 c_5 = D_n$.

- (b) Plugging into boundary conditions and comparing coefficients for $\Phi(\tau, \sigma)$:

$$0 = \Phi(a, \sigma) = A_0 + B_0 a + \sum_{n=1}^{+\infty} \left\{ \left[A_n \cosh(na) + B_n \sinh(na) \right] \cos(n\sigma) + \left[C_n \cosh(na) + D_n \sinh(na) \right] \sin(n\sigma) \right\}$$

which gives $A_0 = -B_0 a$, $A_n \cosh(na) + B_n \sinh(na) = 0$, $C_n \cosh(na) + D_n \sinh(na) = 0$ $\forall n \geq 1$.

$$\cos 2\sigma = \Phi(b, \sigma) = A_0 + B_0 b + \sum_{n=1}^{+\infty} \left\{ \left[A_n \cosh(nb) + B_n \sinh(nb) \right] \cos(n\sigma) + \left[C_n \cosh(nb) + D_n \sinh(nb) \right] \sin(n\sigma) \right\}$$

which gives $A_2 \cosh(2b) + B_2 \sinh(2b) = 1$, $A_0 + B_0 b = 0$, $C_n \cosh(nb) + D_n \sinh(nb) = 0$ $\forall n \geq 1$ and $A_n \cosh(nb) + B_n \sinh(nb) = 0$ $\forall n \geq 1$ and $n \neq 2$. This gives $A_n = B_n = 0$ $\forall n \neq 2$ and $C_n = D_n = 0$ $\forall n$, as well as,

$$\begin{pmatrix} A_2 \\ B_2 \end{pmatrix} = \frac{1}{\cosh(2a) \sinh(2b) - \cosh(2b) \sinh(2a)} \begin{pmatrix} \sinh 2b & -\sinh 2a \\ -\cosh 2b & \cosh 2a \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{\sinh(2(b-a))} \begin{pmatrix} -\sinh(2a) \\ \cosh(2a) \end{pmatrix}$$

Hence,

$$\Phi(\tau, \sigma) = \frac{\sinh(2(\tau-a))}{\sinh(2(b-a))} \cos 2\sigma$$

Problem 7.13 (Green's Functions): Let V be a region of three-dimensional space with boundary S .

(a) Prove that

$$\int_V (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dV = \int_S (\phi \mathbf{n} \cdot \nabla \psi - \psi \mathbf{n} \cdot \nabla \phi) dS$$

where ϕ and ψ are scalar fields and \mathbf{n} is the outwards directed unit normal to S . [3]

(b) Let ϕ be a scalar field that tends to zero as $|\mathbf{r}| \rightarrow +\infty$ and satisfies the Poisson equation

$$\nabla^2 \phi = -\rho$$

where $\rho(\mathbf{r})$ tends to zero rapidly as $|\mathbf{r}| \rightarrow +\infty$.

(i) Show that

$$\phi(\mathbf{r}) = \int_{\mathbb{R}^3} G(\mathbf{r}, \bar{\mathbf{r}}) \rho(\bar{\mathbf{r}}) d\bar{V}$$

where $G(\mathbf{r}, \bar{\mathbf{r}})$ satisfies [3]

$$\nabla_{\bar{\mathbf{r}}}^2 G(\mathbf{r}, \bar{\mathbf{r}}) = -\delta^{(3)}(\mathbf{r} - \bar{\mathbf{r}})$$

(ii) Determine $G(\mathbf{r}, \bar{\mathbf{r}})$. [4]

(iii) Show that

$$\phi(\mathbf{r}) = \frac{e^{-\beta|\mathbf{r}|} - 1}{|\mathbf{r}|^2}$$

for the case

$$\rho(\mathbf{r}) = -\frac{e^{-\beta|\mathbf{r}|}}{|\mathbf{r}|}$$

where $\beta > 0$. [10]

Answer 7.13.

(a) Take the Divergence Theorem separately to $\phi \nabla \psi$ and $\psi \nabla \phi$:

$$\int_S \phi \nabla \psi \cdot d\mathbf{S} = \int_V \nabla \cdot (\phi \nabla \psi) dV = \int_V \phi \nabla^2 \psi + \nabla \phi \cdot \nabla \psi dV$$

$$\int_S \psi \nabla \phi \cdot d\mathbf{S} = \int_V \nabla \cdot (\psi \nabla \phi) dV = \int_V \psi \nabla^2 \phi + \nabla \psi \cdot \nabla \phi dV$$

Now take the difference between the two results:

$$\int_S (\phi \nabla \psi - \psi \nabla \phi) \cdot d\mathbf{S} = \int_V (\phi \nabla^2 \psi + \nabla \phi \cdot \nabla \psi - \nabla \psi \cdot \nabla \phi - \psi \nabla^2 \phi) dV = \int_V (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dV$$

(b) (i) The corresponding G satisfies

$$\nabla_{\mathbf{r}}^2 G(\mathbf{r}, \mathbf{r}') = -\delta^{(3)}(\mathbf{r} - \mathbf{r}')$$

with $\lim_{|\mathbf{r}| \rightarrow \infty} G(\mathbf{r}, \mathbf{r}') = 0$. Using result from part (a):

$$\int_S (\phi \nabla G - G \nabla \phi) \cdot d\mathbf{S} = \int_V \phi \nabla^2 G - G \nabla^2 \phi dV = - \int_V \phi(\mathbf{r}) \delta^{(3)}(\mathbf{r} - \mathbf{r}') + G(\mathbf{r}, \mathbf{r}') \rho(\mathbf{r}) dV$$

where the LHS evaluates to zero due to our boundary conditions. The result follows.

(ii) Integrate $\nabla_{\mathbf{r}}^2 G(\mathbf{r}, \mathbf{r}') = -\delta^{(3)}(\mathbf{r} - \mathbf{r}')$ over a sphere of radius $r = |\mathbf{r} - \mathbf{r}'|$ centred on the origin, then

$$\frac{dG}{dr} 4\pi r^2 = -1 \implies G = \frac{1}{4\pi r} + C = \frac{1}{4\pi |\mathbf{r} - \mathbf{r}'|}$$

where C is some constant. But $\lim_{|\mathbf{r}| \rightarrow \infty} G(\mathbf{r}, \mathbf{r}') = 0$ so $C = 0$.

(iii) From part (b)(i) and (ii),

$$\begin{aligned}
 \phi(\mathbf{r}) &= -\frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{1}{|\mathbf{r} - \mathbf{r}'|} \frac{e^{-\beta|\mathbf{r}'|}}{|\mathbf{r}'|} dV' \\
 &= -\frac{1}{4\pi} \int_0^{2\pi} d\phi \int_0^\pi \int_0^\infty \frac{r' e^{-\beta r'}}{\sqrt{r^2 + r'^2 - 2rr' \cos \theta}} dr' d\theta' \\
 &= -\frac{1}{2} \int_0^\infty \frac{e^{-\beta r'}}{r} [\sqrt{r^2 + r'^2 - 2rr' \cos \theta}]_0^\pi dr' \\
 &= -\frac{1}{2r} \int_0^\infty e^{-\beta r'} (|r + r'| - |r - r'|) dr'
 \end{aligned}$$

but

$$|r - r'| = \begin{cases} r - r' & r > r' \\ -r + r' & r < r' \end{cases}$$

Then, the integral is done piecewise.

$$\begin{aligned}
 \phi(r) &= -\frac{2}{2r} \left(\int_0^r r' e^{-\beta r'} dr' + r \int_r^\infty e^{-\beta r'} dr' \right) \\
 &= -\frac{1}{r} \left(-\frac{r}{\beta} e^{-\beta r} - \frac{1}{\beta^2} (e^{-\beta r} - 1) + \frac{r}{\beta} e^{-\beta r} \right) \\
 &= \frac{1}{\beta^2 r} (e^{-\beta r} - 1)
 \end{aligned}$$

Problem 7.14 (Contour Integration):

(a) Consider the integral

$$I = \int_C \frac{f(z)}{\sqrt{z}} dz$$

along some contour C , where $z = re^{i\theta}$ is complex, $f(z)$ is analytic and nonzero along the real axis, and the branch cut associated with the integrand is taken along the positive real axis.

- (i) Determine the integral I for the contour C given by $r = R$, followed in a clockwise direction from $\theta = \frac{3}{2}\pi$ to $\theta = \frac{1}{2}\pi$, in the limit $R \rightarrow 0$. If $f(z)$ is analytic in the limit $r \rightarrow \infty$, then what constraint needs to be placed on the behaviour of $f(z)$ for the integral to vanish in the limit $R \rightarrow \infty$? [3]
- (ii) Determine how the value of the integrand just below the branch cut at some $z = x - i\epsilon$ is related to the integrand just above the branch cut at $z = x + i\epsilon$ in the limit $\epsilon \rightarrow 0$. [2]

(b) Consider now the function

$$g(z) = \frac{z(z^2 + 3)}{(z^2 + 1)(z^2 + 4)\sqrt{z^2 - 1}}$$

- (i) Identify the point(s) or region(s) in the complex plane where $g(z)$ is not analytic, stating the nature of the features identified. [3]
- (ii) Evaluate the integral

$$J = \int_1^\infty g(x) dx$$

using contour integration around a closed contour. Identify contributions from different parts of the contour. [12]

Answer 7.14.

(a) (i) Parametrize the contour as $z = re^{i\theta}$ with $\theta \in [3\pi/2, \pi/2]$. The integral is:

$$I = \int_C \frac{f(z)}{\sqrt{z}} dz = \int_{3\pi/2}^{\pi/2} \frac{f(Re^{i\theta})}{R^{1/2}e^{i\theta/2}} iRe^{i\theta} d\theta$$

Since $f(z)$ is analytic at $z = 0$, $I = O(R^{1/2}) \rightarrow 0$ as $R \rightarrow 0$ to vanish as $R \rightarrow \infty$, we require $|f(z)| \rightarrow 0$ faster than $R^{1/2}$.

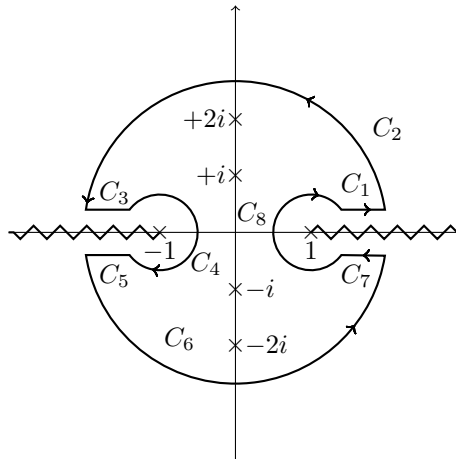
(ii) Since $f(z)$ is analytic, only \sqrt{z} changes sign. We have $z^{-1/2} = r^{-1/2}e^{-i\theta/2}$, then $\theta \rightarrow \theta + 2\pi$, $z^{-1/2}$ acquires a negative sign ($e^{i\pi}$ phase), i.e. $z^{-1/2} \rightarrow -z^{-1/2}$.

(b) (i) $g(z)$ has

- first-order poles at $\pm i$ and $\pm 2i$,
- first-order zeros at $0, \pm i\sqrt{3}$,
- second-order zero at ∞ ,
- branch point singularities at ± 1 .

We choose branch cuts along $[+1, \infty)$ and $(-\infty, -1]$.

(ii) We need to choose a contour that avoids the branch point singularities and both branch cuts. A dual keyhole contour of the following form $C = C_1 \cup C_2 \cup C_3 \cup C_4 \cup C_5 \cup C_6 \cup C_7 \cup C_8$ would be appropriate:



Since $g(z) = O(R^{-2}) \rightarrow 0$ as $R \rightarrow \infty$, then the contributions along γ_2 and γ_2 vanish. But $g(z)(z \mp 1)^{1/2}$ is analytic at $z = \mp 1$ so the contributions from C_4 and C_8 vanish as well. Thus, we see that

$$\oint_C g(z) dz \rightarrow \int_{-\infty}^{\infty} g(x) dx = 4J, \text{ as } R \rightarrow \infty$$

The poles enclosed are $\pm i$ and $\pm 2i$ with residues

$$\text{res}_{z=\pm i} g(z) = \lim_{z \rightarrow \pm i} \frac{(z \mp i)z(z^2 + 3)}{(z^2 + 1)(z^2 + 4)\sqrt{z^2 - 1}} = \frac{\pm i(-1 + 3)}{\pm 2i(-1 + 4)\sqrt{-2}} = \frac{1}{3\sqrt{2}i}$$

$$\text{res}_{z=\pm 2i} g(z) = \lim_{z \rightarrow \pm 2i} \frac{(z \mp 2i)z(z^2 + 3)}{(z^2 + 1)(z^2 + 4)\sqrt{z^2 - 1}} = \frac{\pm 2i(-4 + 3)}{\pm 4i(-4 + 1)\sqrt{-4 - 1}} = \frac{1}{6\sqrt{5}i}$$

By residue theorem, we must have

$$J = \frac{1}{4} \oint_C g(z) dz = \frac{1}{4} 2\pi i \left(\frac{2}{3\sqrt{2}i} + \frac{2}{6\sqrt{5}i} \right) = \frac{\pi}{3\sqrt{2}} + \frac{\pi}{6\sqrt{5}}$$

Problem 7.15 (Transform Methods): The Fourier transform of $y(t)$ is given by

$$\tilde{y}(\omega) = \frac{-\omega \tilde{f}(\omega)}{\omega^3 - i\omega^2 + 4\omega - 4i} \quad (*)$$

where $\tilde{f}(\omega)$ is the Fourier transform of the function $f(t)$, and both $y(t)$ and $f(t)$ vanish as $t \rightarrow \pm\infty$.

(a) Determine the third order differential equation that governs $y(t)$. [3]

(b) Find $f(t)$, valid for all t , for the case [5]

$$\tilde{f}(\omega) = \frac{-i}{\omega - i} \quad (\dagger)$$

(c) Substitute (\dagger) into $(*)$ and use an inverse Fourier transform to determine $y(t)$, valid for all t . Sketch the behaviour of $y(t)$. [12]

Answer 7.15.

(a) Rearrange $(*)$:

$$\omega^3 \tilde{y}(\omega) - i\omega^2 \tilde{y}(\omega) + 4\omega \tilde{y}(\omega) - 4i \tilde{y}(\omega) = -\omega \tilde{f}(\omega)$$

Since $y(t)$ and $f(t)$ vanish as $|t| \rightarrow \infty$, then further assume $\frac{dy}{dt}$ and $\frac{d^2y}{dt^2}$ have similar asymptotic behaviours, then taking the inverse Fourier transform of $(*)$ gives $\tilde{y}^{(n)} = (i\omega)^n \tilde{y}$. So multiply $-i$ across.

$$i\omega \tilde{f}(\omega) = -i\omega^3 \tilde{y}(\omega) - \omega^2 \tilde{y}(\omega) - 4i\omega \tilde{y}(\omega) - 4\tilde{y}(\omega) = \tilde{y}''' + \tilde{y}'' - 4\tilde{y}' - 4\tilde{y}$$

Perform inverse FT, the ODE is

$$\frac{df}{dt} = y''' + y'' - 4y' - 4y$$

(b) The inverse Fourier transform is

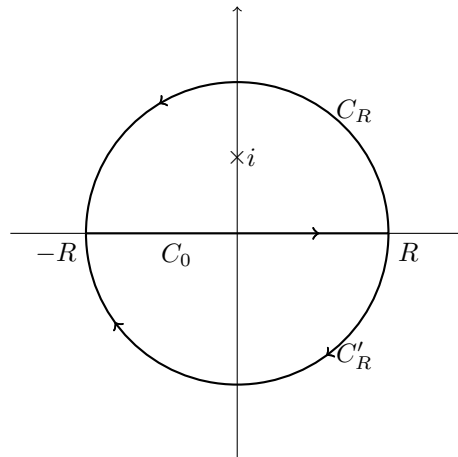
$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{-i}{\omega - i} e^{i\omega t} d\omega$$

The integrand has first order pole at $\omega = i$ with residue

$$\text{res}_{\omega=i} \frac{-i}{\omega - i} \frac{e^{i\omega t}}{2\pi} = \frac{-ie^{-t}}{2\pi}$$

For $t > 0$, we close the contour in upper half-plane to invoke Jordan's Lemma:

$$\oint_{C:=C_R \cup C_0} \frac{-i}{\omega - i} e^{i\omega t} d\omega = \int_{C_R} \frac{-i}{\omega - i} e^{i\omega t} d\omega + \int_{-R}^R \frac{-i}{\omega - i} e^{i\omega t} d\omega \rightarrow 0 + 2\pi f(t > 0)$$



By residue theorem, we have

$$\oint_{C:=C_R \cup C_0} \frac{-i}{\omega - i} e^{i\omega t} d\omega = 2\pi i \frac{-ie^{-t}}{2\pi} = e^{-t}$$

For $t < 0$, we close the lower half-plane and again invoke Jordan's Lemma:

$$\oint_{C':=C'_R \cup C_0} \frac{-i}{\omega - i} e^{i\omega t} d\omega = \int_{C'_R} \frac{-i}{\omega - i} e^{i\omega t} d\omega + \int_{-R}^R \frac{-i}{\omega - i} e^{i\omega t} d\omega \rightarrow 0 + 2\pi f(t < 0)$$

But no pole is enclosed so by residue theorem, $f(t < 0) = 0$. Similarly, for $t = 0$, we just have

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} -\frac{i}{\omega - i} d\omega = 0$$

Hence, the solution is

$$f(t) = \begin{cases} e^{-t} & t > 0 \\ 0 & t \leq 0 \end{cases}$$

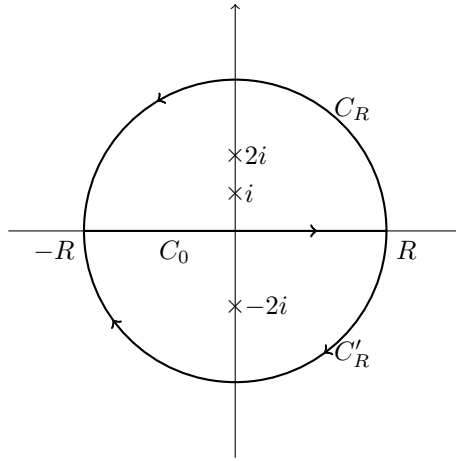
(c) (*) becomes

$$\tilde{y}(\omega) = \frac{-\omega}{\omega^3 - i\omega^2 + 4\omega - 4i} \frac{-i}{\omega - i} = \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)}$$

which has a second order pole at $\omega = i$ and simple poles at $\omega = \pm 2i$. By inverse Fourier transform, the solution would be

$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} e^{i\omega t} d\omega$$

Repeat a similar computation using the same contour:



The residues at the three poles are

$$\begin{aligned} \text{res}_{\omega=i} \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} \frac{e^{i\omega t}}{2\pi} &= \frac{1}{2\pi} \lim_{\omega \rightarrow i} \frac{d}{d\omega} \frac{\omega i}{(\omega + 2i)(\omega - 2i)} e^{i\omega t} \\ &= \frac{1}{2\pi} \lim_{\omega \rightarrow i} \frac{i(1 + i\omega t)e^{i\omega t}(\omega^2 + 4) - i\omega e^{i\omega t}2\omega}{(\omega^2 + 4)^2} \\ &= \frac{3i(1 - t)e^{-t} + 2ie^{-t}}{18\pi} \\ &= \frac{5 - 3t}{18\pi} ie^{-t} \\ \text{res}_{\omega=\pm 2i} \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} \frac{e^{i\omega t}}{2\pi} &= \frac{1}{2\pi} \lim_{\omega \rightarrow \pm 2i} \frac{i\omega e^{i\omega t}}{(\omega - i)^2(\omega \pm 2i)} \end{aligned}$$

which gives $\frac{-i}{4\pi}e^{-2t}$ for $\omega = 2i$ and $\frac{-i}{36\pi}e^{2t}$ for $\omega = -2i$. For $t > 0$, again we close the upper half-plane in order to invoke Jordan's Lemma:

$$\begin{aligned} & \oint_{C:=C_R \cup C_0} \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} e^{i\omega t} d\omega \\ &= \int_{C_R} \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} e^{i\omega t} d\omega + \int_{-R}^R \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} e^{i\omega t} d\omega \\ &\rightarrow 0 + 2\pi y(t > 0) \end{aligned}$$

The two poles enclosed are $2i$ and i , so by residue theorem,

$$y(t > 0) = \frac{1}{2\pi} \oint_{C:=C_R \cup C_0} \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} e^{i\omega t} d\omega = 2\pi i \left(\frac{-i}{4\pi} e^{-2t} + \frac{5-3t}{18\pi} i e^{-t} \right)$$

Again, for $t < 0$, we close the lower half-plane and invoke Jordan's Lemma:

$$\begin{aligned} & \oint_{C':=C'_R \cup C_0} \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} e^{i\omega t} d\omega \\ &= \int_{C_R} \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} e^{i\omega t} d\omega + \int_{-R}^R \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} e^{i\omega t} d\omega \\ &\rightarrow 0 + 2\pi y(t < 0) \end{aligned}$$

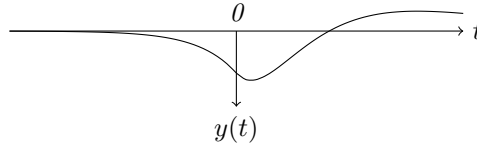
again by residue theorem,

$$\frac{1}{2\pi} \oint_{C':=C'_R \cup C_0} \frac{\omega i}{(\omega - i)^2(\omega + 2i)(\omega - 2i)} e^{i\omega t} d\omega = 2\pi i \left(\frac{-i}{36\pi} e^{2t} \right)$$

The solution is thus

$$y(t) = \begin{cases} -\frac{1}{18}e^{2t} & t < 0 \\ \frac{1}{2}e^{-2t} + \frac{3t-5}{9}e^{-t} & t > 0 \end{cases}$$

Since f is discontinuous at $t = 0$ and $\dot{f} = \infty$ at $t = 0$, we must have \ddot{y} to have a unit discontinuity while both y and \dot{y} are continuous.



Problem 7.16 (Tensors):

- Define an order two tensor. [2]
- The quantity C_{ij} has the property that for every order two tensor A_{ij} , the quantity $C_{ij}A_{ij}$ is a scalar. Prove that C_{ij} is necessarily an order two tensor. [4]
- Show that if a tensor T_{ij} is invariant under a rotation of $\pi/2$ about the x_3 -axis then it has the form

$$\begin{pmatrix} \alpha & \omega & 0 \\ -\omega & \alpha & 0 \\ 0 & 0 & \beta \end{pmatrix}$$

Also show that T_{ij} is invariant under a general rotation about the x_3 -axis. [6]

- The inertia tensor about the origin of a rigid body occupying volume V with mass density $\rho(\mathbf{x})$ is defined as

$$I_{ij} = \int_V \rho(\mathbf{x})(x_k x_k \delta_{ij} - x_i x_j) dV$$

The rigid body B has uniform density ρ and occupies the cylinder

$$\{(x_1, x_2, x_3) : -2 \leq x_3 \leq 2, x_1^2 + x_2^2 \leq 1\}$$

Show that the inertia tensor of B about the origin is diagonal in the (x_1, x_2, x_3) coordinate system and calculate its diagonal elements. [8]

Answer 7.16.

- (a) An order-2 tensor has components D_{ij} such that under any orthogonal transformation of the coordinates, it remains invariant. Hence, the components must transform as

$$D'_{ij} = L_{i\alpha} L_{j\beta} D_{\alpha\beta}$$

where L is the orthogonal transformation matrix.

- (b) $(C_{ij}A_{ij})' = C'_{ij}A'_{ij} = C'_{ij}L_{i\alpha}L_{j\beta}A_{\alpha\beta}$.

$$C'_{ij}L_{i\alpha}L_{j\beta} = C_{\alpha\beta} \implies C'_{ij}\delta_{ip}\delta_{jq} = L_{p\alpha}L_{q\beta}C_{\alpha\beta} \implies C'_{pq} = L_{p\alpha}L_{q\beta}C_{\alpha\beta}$$

Indeed, a rank-two tensor.

- (c) Assume T is three-dimensional. Let's rotate around x_1 - x_2 plane by $\frac{\pi}{2}$:

$$L = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Then,

$$T'_{ij} = L_{ip}T_{pq}L_{jq} = (LTL^T)_{ij} = \begin{pmatrix} T_{22} & -T_{21} & T_{23} \\ -T_{12} & T_{11} & -T_{13} \\ T_{32} & -T_{31} & T_{33} \end{pmatrix}$$

Then, for $T' = T$, we have $T_{11} = T_{22}$ with T_{33} unconstrained. Call the former α and latter β . $-T_{21} = T_{12}$, $-T_{12} = T_{21}$, and must be the same value. Call this ω . Now, $T_{23} = T_{13}$, $-T_{13} = T_{23}$, $T_{32} = T_{31}$, $-T_{31} = T_{32}$, all zero.

Now apply generic rotation about the x_3 -axis to T_{ij} , i.e show

$$L'TL'T = T, \quad L' = \begin{pmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

- (d) The cylindrical axis is x_3 . The system is symmetric under arbitrary rotations in the x_1 - x_2 plane, hence I_{ij} has the form T_{ij} in part (c). We proceed to compute the individual elements:

$$I_{12} - I_{21} = \rho \int_V (x_k x_k (\delta_{12} - \delta_{21}) - x_1 x_2 + x_2 x_1) dV = 0$$

but $T_{12} - T_{21} = 2\omega$, hence the off-diagonal elements of I_{ij} must be zero.

$$I_{11} = I_{22} = \int_{-2}^2 \int_0^1 \int_{-\pi}^{\pi} \rho(r^2 + x_3^2 - (r \cos \theta)^2) r d\theta dr dx_3 = \frac{19}{3} \pi \rho$$

$$I_{33} = \rho \int_{-2}^2 \int_0^1 \int_{-\pi}^{\pi} r^2 r d\theta dr dx_3 = 2\pi \rho$$

Thus,

$$I = \pi \rho \begin{pmatrix} 19/3 & 0 & 0 \\ 0 & 19/3 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

Problem 7.17 (Normal Coordinates): A mass m_1 is suspended from the origin by a spring with spring constant k_1 . A second mass m_2 is suspended from the first by a spring with spring constant k_2 . Both springs are of a type that has zero length when not extended. The motion of the masses is restricted to the (x, y) plane such that m_1 is located at $(X_1(t), Y_1(t))$ and m_2 is located at $(X_2(t), Y_2(t))$. Gravity acts in the $-y$ direction.

- (a) Write down the Lagrangian for the system and hence use the Euler-Lagrange equation to determine the equations of motion for the system. [6]
- (b) Determine the equilibrium position $(\hat{X}_1, \hat{Y}_1, \hat{X}_2, \hat{Y}_2)$. Suppose the setup is altered so that $X_2(t) = \hat{X}_2$. Show that small perturbations $(x_1(t), y_1(t), y_2(t))$ about the equilibrium are governed by [3]

$$\begin{pmatrix} m_1 & 0 & 0 \\ 0 & m_1 & 0 \\ 0 & 0 & m_2 \end{pmatrix} \begin{pmatrix} \ddot{x}_1 \\ \dot{y}_1 \\ \dot{y}_2 \end{pmatrix} + \begin{pmatrix} k_1 + k_2 & 0 & 0 \\ 0 & k_1 + k_2 & -k_2 \\ 0 & -k_2 & k_2 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

- (c) Determine the frequency and structure of each of the modes for the case $m_1 = m_2 = m$ and $k_1 = k_2 = k$. [11]

Answer 7.17.

- (a) The Lagrangian for the system is

$$\mathcal{L} = \frac{1}{2}m_1(\dot{X}_1^2 + \dot{Y}_1^2) + \frac{1}{2}m_2(\dot{X}_2^2 + \dot{Y}_2^2) - \frac{1}{2}k_1(X_1^2 + Y_1^2) - \frac{1}{2}k_2((X_1 - X_2)^2 + (Y_1 - Y_2)^2) + m_1gY_1 + m_2gY_2$$

where we define the zero-position for the GPE is at $y = 0$. When the Lagrangian is extremized, it satisfies the Euler-Lagrange equations for each independent variable q_i :

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} = \frac{\partial \mathcal{L}}{\partial q_i}$$

Then, the equations of motion are

$$\begin{aligned} m_1 \ddot{X}_1 &= -k_1 X_1 - k_2 (X_1 - X_2) \\ m_1 \ddot{Y}_1 &= -k_1 Y_1 - k_2 (Y_1 - Y_2) + m_1 g \\ m_2 \ddot{X}_2 &= -k_2 (X_2 - X_1) \\ m_2 \ddot{Y}_2 &= -k_2 (Y_2 - Y_1) + m_2 g \end{aligned}$$

- (b) Equilibrium position is attained when the acceleration is zero. So, writing in matrix form:

$$\begin{pmatrix} -k_1 - k_2 & k_2 \\ k_2 & -k_1 \end{pmatrix} \begin{pmatrix} \hat{X}_1 \\ \hat{X}_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \implies \hat{X}_1 = \hat{X}_2 = 0$$

$$\begin{pmatrix} -k_1 - k_2 & k_2 \\ k_2 & -k_1 \end{pmatrix} \begin{pmatrix} \hat{Y}_1 \\ \hat{Y}_2 \end{pmatrix} = \begin{pmatrix} m_1 g \\ m_2 g \end{pmatrix} \implies \hat{Y}_1 = -\frac{(m_1 + m_2)g}{k_1}, \quad \hat{Y}_2 = -\frac{(m_1 + m_2)g}{k_1} - \frac{m_2 g}{k_2}$$

Now we alter the setup such that $x_2(t) = X_2 - \hat{X}_2 = 0$, $x_1(t) = X_1 - \hat{X}_1$, $y_i(t) = Y_i - \hat{Y}_i$ for $i = 1, 2$, then from the equations of motion, we obtained the desired relation.

- (c) Set $m_1 = m_2 = m$, $k_1 = k_2 = k$, and seek solutions of the form $(x_1, y_1, y_2)^T = (a, b, c)^T e^{i\omega t}$, then this is equivalent to solving

$$0 = \det \begin{pmatrix} 2k - m\omega^2 & 0 & 0 \\ 0 & 2k - m\omega^2 & -k \\ 0 & -k & k - m\omega^2 \end{pmatrix} = (k - 2m\omega^2)((2k - m\omega^2)(k - m\omega^2) - k^2)$$

Then we have $\omega_0^2 = \frac{2k}{m}$, $\omega_{\pm}^2 = \frac{k}{2m}(3 \pm \sqrt{5})$. By inspection, the corresponding eigenvector for ω_0 is $(1, 0, 0)^T$. And we can work out the remaining eigenvectors to be $(0, 1, 3 \pm \sqrt{5})^T$. The modes thus look like $(1, 0, 0)^T e^{i\sqrt{2k/m}t}$ and $(0, 1, 3 \pm \sqrt{5})^T e^{i\sqrt{k(3 \pm \sqrt{5})/m}t}$.

Problem 7.18 (Group Theory):

- (a) Given a finite group G of order $|G|$ and a normal subgroup N of order $|N|$, define the quotient group G/N and show that it is indeed a group. State Lagrange's theorem relating the order of a group and those of its subgroups. [2]
- (b) Show that the Pauli matrices together with the identity matrix

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

do not constitute a group under matrix multiplication. Show that these matrices can be multiplied by ± 1 and $\pm i$, to generate a set of 16 matrices, which meet the conditions to form a group. [9]

- (c) Prove that in any group, an element and its inverse have the same order. [9]

Answer 7.18.

- (a) G/N is the set of left cosets of $N \leq G$, i.e.

$$gN = \{g \in G \mid g' = g * n \text{ for some } n \in N\}$$

Check group axioms:

- closure: For $g_1N, g_2N \in G/N$, $g_1Ng_2N = g_1g_2N \in G/N$ since $g_1, g_2 \in G \implies g_1, g_2 \in G$.
- associativity: inherit from parent group G .
- identity: $eN \in G/N$.
- inverse: $g^{-1}NgN = eN \implies g^{-1}N \in G/N$.

Lagrange's theorem states that for $H \leq G$, then $\frac{|G|}{|H|} \in \mathbb{N}$.

- (b) Take for instance,

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \notin \{\sigma_x, \sigma_y, \sigma_z, \text{Id}\}$$

The set $\{\sigma_x, \sigma_y, \sigma_z, \text{Id}\}$ is not closed. Essentially,

$$\sigma_x\sigma_y = i\sigma_z = -\sigma_y\sigma_x, \quad \sigma_y\sigma_z = i\sigma_x = -\sigma_z\sigma_y, \quad \sigma_z\sigma_x = i\sigma_y = -\sigma_x\sigma_z$$

Any arbitrary element can be written as $(-1)^n \sigma_x^a \sigma_y^b \sigma_z^c$. So, check closure again:

$$(-1)^n \sigma_x^a \sigma_y^b \sigma_z^c (-1)^p \sigma_x^\alpha \sigma_y^\beta \sigma_z^\gamma = (-1)^{n+p} \sigma_x^{a+\alpha} \sigma_y^{b+\beta} \sigma_z^{c+\gamma}$$

The powers are only meaningful if they are either 0 or 1 since $\sigma_p^2 = \text{Id} \forall p = x, y, z$. So the new set is closed. The set contains the identity Id (raise to zero power for all). The binary operation (matrix multiplication) is associative. The inverse is $(-1)^n \sigma_x^{-a} \sigma_y^{-b} \sigma_z^{-c}$ if $a, b, c \neq 0$ and $(-1)^n \sigma_x^a \sigma_y^b \sigma_z^c$ if only one of a, b, c is not zero. All the group axioms are satisfied, so this new set of $2^4 = 16$ distinct elements is a group.

- (c) Let $g, h \in G$ such that $hg = e$ where e is the identity in G . Let $\text{ord}(g) = p$, $\text{ord}(h) = q$, i.e. $g^p = e = h^q$, then

$$e = e^p = (gh)^p = g^p h^p = eh^p$$

so q is a factor of p . Similarly, we can show p is a factor of q . Hence, $q = p$ and thus g and $h = g^{-1}$ has the same order.

Problem 7.19 (Group Theory):

- (a) Let G be a finite subgroup. The centre $Z(G)$ of G is the set of elements $z \in G$ that commute with every element $g \in G$, that is to say

$$Z(G) = \{z \in G : gz = zg, \forall g \in G\}$$

Prove that if H is a normal subgroup of G with order $|H| = 2$, then $H \subseteq Z(G)$. [7]

- (b) Define a homomorphism between two groups H and G . Define the kernel of a homomorphism. [3]

- (c) Suppose that G is a group of order $|G| = 21$. Show that every proper subgroup of G is cyclic. [10]

Answer 7.19.

- (a) A normal subgroup is the union of complete conjugacy classes. The conjugacy classes are

$$\text{ccl}(g) = \{g' \in G \mid g' = lgl^{-1} \text{ for some } l \in G\}$$

Elements that commute with all other elements are thus in a class of their own, as $lgl^{-1} = ll^{-1}g = g \forall l \in G$. The identity trivially commutes with every element in the group. The centre thus consists of complete conjugacy classes, so $Z(G) \triangleleft G$.

Since $H \triangleleft G$ and $|H| = 2$. Let $H = \{e, h\}$, then h is a conjugacy class of its own.

$$hlh^{-1} = h \forall l \in G \implies hl = lh \implies h \in Z \implies H \subseteq Z(G)$$

- (b) If H and G are groups, then a function $\Phi: H \rightarrow G$ is a group homomorphism, if $\forall a, b \in H$, $\Phi(a \cdot_H b) = \Phi(a) \cdot_G \Phi(b)$. The kernel of Φ is

$$\text{Ker } \Phi = \{h \in H \mid \Phi(h) = e_G \text{ for some } h \in H\}$$

- (c) Consider $H \leq G$, the cosets of H in G are $g_i H \forall g_i \in G$. $H \leq G \implies e \in H \implies g_i \in g_i H$, so each element in G is in at least one coset. Now suppose two cosets generated by distinct $g_i, g_j \in G$ share an element, then for some $h_i, h_j \in H$,

$$g_i h_i = g_j h_j \implies g_i h_i h_j^{-1} = g_j \implies g_j H = g_i h_i h_j^{-1} H = g_i h_i H = g_i H$$

The cosets are either disjoint or identical, so every element $g_i \in G$ is in at most one coset. The cosets thus partition the group into blocks of size equal to the size of the generating subgroup. The order of the group is thus the order of the subgroups times the number of cosets.

Consider the generator of any $g \in G$, $\langle g \rangle = \{g, g^2, g^3, \dots, e\}$ has $\text{ord}(g)$ elements and is a group since it

- is closed, i.e. $g^p g^q = g^r$ where $r = p + q \text{ mod } \text{ord}(g)$.
- inherit associativity from G .
- contains the identity.
- for $g^p \in \langle g \rangle$, it has an inverse in $\langle g \rangle$. $(g^p)^{-1} = g^{\text{ord}(g)-p} \in \langle g \rangle$.

Hence, the order of any element $g \in G$ must be a factor of $|G|$. This is Lagrange's theorem. If $|G| = 21$ and $H \leq G$ is proper, then $|H| = 3$ or 7 prime. Since prime order groups ($h \in H$ where $h \neq e$ and $\text{ord}(h) = p$, then $\langle h \rangle = H$) are cyclic, H is cyclic. So only proper subgroups are cyclic.

Problem 7.20 (Representation Theory): Let $G = \{I, g_1, g_2, \dots, g_{n-1}\}$ be a group with a faithful representation by multiplication of 2×2 real orthogonal matrices of the form

$$D(g_i) = \begin{pmatrix} \alpha & \gamma \\ \delta & \beta \end{pmatrix}$$

in the vector space \mathbb{R}^2 . Suppose $A = \{I, a\}$ and $B_p = \{I, g_1, g_2, \dots, g_{p-1}\}$ are cyclic subgroups of G such that $g_i = g_1^i$ for $i < p$ for some $2 < p < n$.

- Show that $D(a)$ is symmetric. Obtain relationships between α , β , γ and δ and hence determine the most general form(s) for $D(a)$. What geometric operations do these form(s) correspond to in the vector space \mathbb{R}^2 ? [Hint: consider $\alpha = \cos \theta$.] [5]
- What restriction must be placed on p for B_p to have a cyclic subgroup $C = \{I, c\}$? Give the representation $D(c)$ and hence the representation $D(g_i)$ for $i < p$. What is the character of B_p for this representation? [6]
- Suppose G has generators $\{g_1, s\}$ where $\det(D(s)) = -1$ and $\{I, s\}$ is a subgroup of G , and B_p is of the form given in (b). What is the order of G ? How many cyclic subgroups of order 2 does G have? For the case $p = 4$, give suitable representations for $D(g_1)$ and $D(s)$, and use these representations to demonstrate that $sg_1s = g_3$. Determine the group table (for $p = 4$) and identify this group. [9]

Answer 7.20.

- (a) Since D is a representation, it is a homomorphism.

$$D(a)D(a) = D(a^2) = D(I) = I \implies D(a) = [D(a)]^{-1}$$

but all the matrices are given to be orthogonal ($DD^T = I$), so $D^T = D^{-1} = D$, i.e. D is symmetric. Since every $D(g_i)$ is orthogonal, we have

$$I = D(g_i)D^T(g_i) = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \begin{pmatrix} \alpha^2 + \beta^2 & \alpha\gamma + \beta\delta \\ \alpha\gamma + \beta\delta & \gamma^2 + \delta^2 \end{pmatrix}$$

We choose $\alpha = \pm \cos \theta$, $\beta = -\gamma = \pm \sin \theta$. Hence, the most general form of $D(g_m)$ is

$$D(g_m) = \begin{pmatrix} \cos \theta_m & \sin \theta_m \\ -\sin \theta_m & \cos \theta_m \end{pmatrix}$$

is rotations of $\theta_m = \frac{2\pi m}{n}$ possibly coupled with inversions through the origin.

- (b) For B_p to have a cyclic subgroup of the form given, p must be even.

$$D(c) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$D(g_m) = \begin{pmatrix} \cos \frac{2\pi m}{p} & \sin \frac{2\pi m}{p} \\ -\sin \frac{2\pi m}{p} & \cos \frac{2\pi m}{p} \end{pmatrix}, \quad m < p$$

The character of this representation is

$$\chi_{B_p} = \left\{ 2, 2 \cos \frac{2\pi}{p}, 2 \cos \frac{4\pi}{p}, \dots, -2, \dots, 2 \cos \frac{(2p-1)\pi}{p} \right\}$$

(c) Since $s^2 = I$ and $\det[D(s)] = -1$, we must have

$$D(s) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \quad D(g_m) = \begin{pmatrix} \cos \frac{2\pi m}{p} & \sin \frac{2\pi m}{p} \\ -\sin \frac{2\pi m}{p} & \cos \frac{2\pi m}{p} \end{pmatrix}, \quad m < p$$

or any similarity transforms of that set. The order of G is thus $2p$. For $p = 4$:

$$D(I) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad D(g_1) = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}, \quad D(g_2) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \quad D(g_3) = \frac{1}{2\sqrt{3}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

$$D(s) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \quad D(g_1s) = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 & -1 \\ -1 & 1 \end{pmatrix}, \quad D(g_3s) = \frac{1}{2\sqrt{2}} \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix}$$

G has 5 subgroups of order 2 (order 2 groups are necessarily cyclic). They are $\{I, s\}$, $\{I, g_1s\}$, $\{I, g_2\}$ where $i = 1, 2, 3$. With $g_1s = sg_1^{-1}$, we can work out the group table.

	I	g_1	g_2	g_3	s	g_1s	g_2s	g_3s
I	I	g_1	g_2	g_3	s	g_1s	g_2s	g_3s
I	I	g_1	g_2	g_3	s	g_1s	g_2s	g_3s
g_1	g_1	g_2	g_3	I	g_1s	g_2s	g_3s	s
g_2	g_2	g_3	I	g_1	g_2s	g_3s	s	g_1s
g_3	g_3	I	g_1	g_2	g_3s	s	g_1s	g_2s
s	s	g_3s	g_2s	g_1s	I	g_3	g_2	g_1
g_1s	g_1s	s	g_3s	g_2s	g_1	I	g_3	g_2
g_2s	g_2s	g_1s	s	g_3s	g_2	g_1	I	g_3
g_3s	g_3s	g_2s	g_1s	s	g_3	g_2	g_1	I

This is the symmetry group of a square, sometimes notated as D_4 .

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8.1 Paper 1

Problem 8.1 (Vector Calculus):

(a) State the divergence theorem for a vector field \mathbf{G} . [2]

(b) Let A denote the open surface

$$x^2 + y^2 = 2z^2, \quad 0 \leq z < h$$

Sketch the surface A . [3]

(c) By applying the divergence theorem to a suitable closed surface, or otherwise, calculate

$$\int_A \mathbf{G} \cdot d\mathbf{A}$$

where $d\mathbf{A}$ is the unit area element pointing out of A , and [15]

$$\mathbf{G} = \begin{pmatrix} x^3 + 2xy \\ y^3 + \sin x \\ z \end{pmatrix}$$

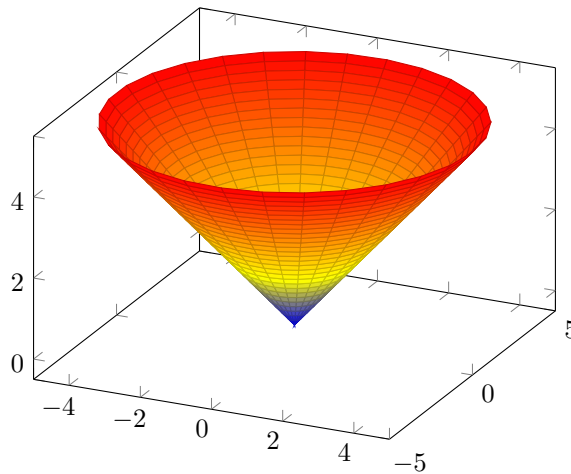
Answer 8.1.

(a) If $\mathbf{F} = \mathbf{F}(\mathbf{x})$ be a continuously differentiable vector field and V is a volume with a piecewise regular boundary ∂V , then the divergence theorem states that

$$\int_V \nabla \cdot \mathbf{F} dV = \int_{\partial V} \mathbf{F} \cdot d\mathbf{S}$$

where the normal to ∂V points outwards from V .

(b) A cone, with a circular top at $z = h$ (arbitrarily set to 5 in the plot) and vertex at the origin, where A is the curved surface.



(c) Let $S_1 = \{x^2 + y^2 \leq 2h^2\}$. This describes a circular region at height $z = h$. The closed surface is $S = A \cup S_1$. Then \mathbf{G} satisfy the divergence theorem,

$$\int_V \nabla \cdot \mathbf{G} dV = \int_{\partial V=S} \mathbf{G} \cdot \mathbf{n} dS = \int_A \mathbf{G} \cdot \mathbf{n} dS + \int_{S_1} \mathbf{G} \cdot \mathbf{n} dS$$

We have $\nabla \cdot \mathbf{G} = 3x^2 + 3y^2 = 1$ and \mathbf{n} for S_1 to be $\hat{\mathbf{z}}$, so

$$\int_{S_1} \mathbf{G} \cdot \mathbf{n} dS = \int_0^{2\pi} \int_0^{\sqrt{2}h} hr dr d\theta = 2\pi h^3$$

We thus have

$$\int_A \mathbf{G} \cdot \mathbf{n} dS = \int_V \nabla \cdot \mathbf{G} dV - \int_{S_1} \mathbf{G} \cdot \mathbf{n} dS = \int_0^h \int_0^{\sqrt{2}z} r(3r^2 + 1) dr dz 2\pi - 2\pi h^3 = \pi h^2$$

Problem 8.2 (Partial Differential Equation): Consider the equation

$$\frac{\partial v}{\partial t} = \frac{\partial^2 v}{\partial x^2} + \frac{2v}{t+1}$$

where $v(x, t)$ is defined on $0 \leq x \leq \pi$ and is subject to the initial and boundary conditions

$$v(0, t) = 0, \quad v(\pi, t) = f(t), \quad v(x, 0) = h(x)$$

for some functions $f(t)$ and $h(x)$.

- (a) Using the substitution $v = (t+1)^2 u$, show that u satisfies the diffusion equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

and state the boundary and initial conditions satisfied by u .

[5]

- (b) Now consider the specific case when the functions f and h are given by

$$f(t) = 3(t+1)^2, \quad h(x) = \frac{\sin(2x) + 3x}{\pi}$$

Using the method of separation of variables, construct the solution $v(x, t)$.

[13]

[Hint: You may find it helpful to use the substitution $u(x, t) = w(x, t) + \gamma x$, for a suitably chosen constant γ .]

- (c) For $t \gg 1$, show that

[2]

$$v \sim \frac{3xt^2}{\pi}$$

Answer 8.2.

- (a) With $v = (t+1)^2 u$, then $\frac{\partial v}{\partial t} = 2(t+1)u + (t+1)^2 \frac{\partial u}{\partial t}$, $\frac{\partial^2 v}{\partial x^2} = (t+1)^2 \frac{\partial^2 u}{\partial x^2}$ and so u satisfy the diffusion equation. The boundary and initial conditions become

$$0 = v(0, t) = (t+1)^2 u(0, t) \implies u(0, t) = 0$$

$$f(t) = v(\pi, t) = (t+1)^2 u(\pi, t) \implies u(\pi, t) = \frac{f(t)}{(t+1)^2}$$

$$h(x) = v(x, 0) = u(x, 0)$$

- (b) We first substitute $u(x, t) = w(x, t) + \gamma(x)$. Then,

$$\frac{\sin 2x + 3x}{\pi} = h(x) = w(x, 0) + \gamma x \implies w(x, 0) = \frac{1}{\pi} \sin 2x$$

and $\gamma = \frac{3}{\pi}$. $u(0, t) = w(0, t) = 0$ and $3 = w(\pi, t) + 3 \implies w(\pi, t) = 0$. We now have homogeneous boundary conditions and may use separation of variables, i.e. $w(x, t) = X(x)T(t)$. Note, $w(x, t)$ satisfies the same diffusion equation as $u(x, t)$.

$$\frac{T'(t)}{T(t)} = \frac{X''(x)}{X(x)} = -\lambda^2$$

The boundary condition for w suggests $X(x) \sim \sin \lambda x$ and so $T(t) \sim e^{-\lambda^2 t}$ with $\lambda \in \mathbb{N}$. Imposing the initial condition $\frac{1}{\pi} \sin 2x = w(x, 0) = \sum_{\lambda=1}^{\infty} A_{\lambda} \sin \lambda x$ would give $A_2 = \frac{1}{\pi}$ and $A_{\lambda} = 0 \forall \lambda \neq 2$. We thus have

$$v(x, t) = (t+1)^2 u(x, t) = \frac{(t+1)^2}{\pi} (3x + \sin 2xe^{-4t})$$

- (c) For $t \gg 1$, $e^{-4t} \approx 0$, so $v(x, t) \approx \frac{3xt^2}{\pi}$, as desired.

Problem 8.3 (Green's Function): An amplifier outputs a signal $x(t)$ given by the initial-value problem

$$\frac{d^2x}{dt^2} + 2q\frac{dx}{dt} + (q^2 + 4)x = f(t), \quad x(0) = \frac{dx}{dt}(0) = 0 \quad (*)$$

for some constant $q > 0$ and input function $f(t)$.

(a) Show that the Green's function $G(t, \tau)$ for this problem is [7]

$$G(t, \tau) = \begin{cases} 0 & 0 \leq t < \tau \\ \frac{1}{2}e^{-q(t-\tau)} \sin[2(t-\tau)] & \tau \leq t \end{cases}$$

Write down the general solution $x(t)$ of equation $(*)$ in terms of an integral. [2]

(b) Now consider the specific case $q = 0$ and

$$f(t) = \begin{cases} t_0 & 0 \leq t < t_0 \\ 0 & t_0 \leq t \end{cases}$$

where $t_0 > 0$ is a constant. Calculate the solution of equation $(*)$ in this case. [8]

Find all values of t_0 for which $x(t) = 0 \forall t \geq t_0$. [3]

Answer 8.3.

(a) The homogeneous solution to $(*)$ is $x(t) = e^{-qt}(c_1 \cos(2t) + c_2 \sin(2t))$. The corresponding Green's function $G(t, \tau)$ satisfies

$$\frac{\partial^2 G(t, \tau)}{\partial t^2} + 2q\frac{\partial G(t, \tau)}{\partial t} + (q^2 + 4)G(t, \tau) = \delta(t - \tau), \quad G(0, \tau) = G'(0, \tau) = 0$$

Integrate this around an infinitesimal region about $t = \tau$, we obtain the jump condition at $t = \tau$, i.e. $[G']_{\tau^-}^{\tau^+} = 1$. G is continuous everywhere, including $t = \tau$ (otherwise, $G'' \propto \delta'(t - \tau)$ which is a contradiction). Using the two linearly independent homogeneous solutions, we construct the Green's function

$$G(t, \tau) = \begin{cases} A(\tau)e^{-qt} \sin(2t) + B(\tau)e^{-qt} \cos(2t) & 0 \leq t < \tau < \infty \\ C(\tau)e^{-q(t-\tau)} \sin 2(t-\tau) + D(\tau)e^{-q(t-\tau)} \cos 2(t-\tau) & 0 \leq \tau < t < \infty \end{cases}$$

The initial conditions for $G(t, \tau)$ are $G(0, \tau) = 0 \implies B(\tau) = 0$ and $\frac{dG}{dt}|_{t=0} = 0 \implies 2A(\tau) - qB(\tau)e^{-qt} = 0$. Hence, $A(\tau) = B(\tau) = 0$. The continuity and jump conditions at $t = \tau$ are respectively

$$A(\tau)e^{-q\tau} \sin 2\tau + B(\tau)e^{-q\tau} \cos 2\tau = D(\tau) \implies D(\tau) = 0$$

$$2C(\tau) - qD(\tau) - 2A(\tau) + qB(\tau) = 1 \implies C(\tau) = 0.5$$

Hence, we have our desired $G(t, \tau)$. The general solution would be

$$x(t) = \int_0^\infty f(\tau)G(t, \tau)d\tau = \int_0^t \frac{1}{2}e^{-q(t-\tau)} \sin[2(t-\tau)]f(\tau)d\tau$$

(b) Consider $q = 0$. For $t \leq t_0$,

$$x(t) = \int_0^t t_0 \frac{1}{2} \sin[2(t-\tau)]d\tau = \frac{t_0}{4}(1 - \cos 2t)$$

For $t > t_0$,

$$x(t) = \int_0^{t_0} t_0 \frac{1}{2} \sin[2(t-\tau)]d\tau = \frac{t_0}{4}[\cos[2(t_0-t)] - \cos(2t)] = \frac{t_0}{4}[\cos(2t)(\cos(2t_0)-1) - \sin 2t_0 \sin 2t]$$

For $x(t) = 0 \forall t > t_0$, $\sin 2t_0 = 0$ and $\cos 2t_0 = 1$, and so $t_0 = n\pi$ for $n \in \mathbb{Z}$.

Problem 8.4 (Fourier Transform):

- (a) The Fourier transform of a function
- $f(t)$
- is given by

$$\tilde{f}(\omega) = \int_{-\infty}^{\infty} f(t)e^{-i\omega t} dt$$

Write down the corresponding expression for the inverse Fourier transform.

[2]

- (b) Consider the convolution of the functions
- f
- and
- g

$$h(z) = \int_{-\infty}^{\infty} f(t)g(z-t)dt$$

Prove that the Fourier transform of h is given by the product of the Fourier transforms of f and g .**[5]**

- (c) Find the Fourier transform of

$$f(\gamma, p, t) = \begin{cases} e^{-\gamma t} \sin(pt) & t > 0 \\ 0 & t \leq 0 \end{cases}$$

where $\gamma > 0$ and p are fixed parameters.**[6]**[Hint: Write $\sin(pt)$ in terms of exponential functions.]

- (d) The current
- $I(t)$
- flowing through a system is related to the applied voltage
- $V(t)$
- by the equation

$$I(t) = \int_{-\infty}^{\infty} K(t-u)V(u)du$$

where

$$K(\tau) = a_1 f(\gamma_1, p_1, \tau) + a_2 f(\gamma_2, p_2, \tau)$$

Here the function $f(\gamma, p, t)$ is as given in part (c), and all the a_i , $\gamma_i > 0$ and p_i are fixed parameters. By considering the Fourier transform of $I(t)$, find the relationship that must hold between a_1 and a_2 if the net charge Q , defined by

$$Q = \int_{-\infty}^{\infty} I(t')dt'$$

is to be zero for an arbitrary applied voltage.

[7][Hint: $\int_{-\infty}^{\infty} e^{i\omega t'} dt' = 2\pi\delta(\omega)$.]**Answer 8.4.**

- (a) The inverse Fourier transform will be
- $f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{f}(\omega)e^{+i\omega t} d\omega$
- .

- (b) Evaluate the Fourier transform of
- $h(z)$
- ,
- $\tilde{h}(\omega)$
- :

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(t)g(z-t) dt e^{-i\omega z} dz = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(t)g(u)e^{-i\omega(u+t)} du dt = \int_{-\infty}^{\infty} f(t)e^{-i\omega t} dt \int_{-\infty}^{\infty} g(u)e^{-i\omega u} du$$

which is $\tilde{f}(\omega)\tilde{g}(\omega)$, where we swap integration order, substitute $u = z - t$ and finally separate the integral.

- (c) Write
- $f(\gamma, p, t > 0) = e^{-\gamma t} \frac{1}{2i}(e^{ipt} - e^{-ipt})$
- , so the Fourier transform is

$$\tilde{f}(\gamma, p, \omega) = \frac{1}{2i} \int_0^{\infty} e^{(-\gamma+i(p-\omega))t} + e^{(-\gamma-i(p+\omega))t} dt = \frac{1}{2i} \left[\frac{1}{\gamma+i(\omega-p)} - \frac{1}{\gamma+i(\omega+p)} \right]$$

- (d) By the convolution theorem, the Fourier transform is
- $\tilde{I}(\omega) = \tilde{K}(\omega)\tilde{V}(\omega) = \tilde{V}(\omega)[a_1\tilde{f}(\gamma_1, p_1, \omega) + a_2\tilde{f}(\gamma_2, p_2, \omega)]$
- . Given
- $Q = \int_{-\infty}^{\infty} I(t')dt' = 0$
- for any arbitrary
- $V(u)$
- . We thus have
- $\frac{dQ}{dt} = I(t) = 0 \implies i\omega Q = \tilde{I}(\omega) = 0 \implies \tilde{K}(\omega) = 0 \forall \omega$
- . For convenience, let
- $\omega = 0$
- , then
- $\tilde{K}(0) = 0$
- .

$$0 = a_1 \left(\frac{p_1}{-p_1^2 - \gamma_1^2} \right) + a_2 \left(\frac{p_2}{-p_2^2 - \gamma_2^2} \right) \implies \frac{a_1}{a_2} = -\frac{p_2}{p_1} \frac{p_1^2 + \gamma_1^2}{p_2^2 + \gamma_2^2}$$

Problem 8.5 (Linear Algebra):

- (a) When is an $n \times n$ matrix A diagonalisable? Give an example of a non-diagonalizable $n \times n$ matrix (for some n). What is a Hermitian matrix? Show that the eigenvalues of a Hermitian matrix are real, and that the corresponding eigenvectors are orthogonal. [5]

- (b) Diagonalize the matrix

$$A = \begin{pmatrix} 2 & -a & 0 \\ -a & 2 & 0 \\ 0 & 0 & c \end{pmatrix}$$

where $a > 0$ and $c > 0$ are real numbers and finds its eigenvectors. [6]

- (c) Sketch the surface

$$\mathbf{x}^T A \mathbf{x} = 1$$

where $\mathbf{x} = (x, y, z)$, specifying the principal axes and, where appropriate, the semi-axis lengths. Note that different values of a may correspond to different surfaces. [9]

Answer 8.5.

- (a) An $n \times n$ matrix A is diagonalizable if it has n linearly independent eigenvectors. We can then place the n linearly independent eigenvectors into the columns of $n \times n$ matrix P such that $P^T A P$ is a diagonal matrix.

An example is $M = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$. Since M is block diagonal, then the eigenvalues are easily determined to be 1 and 1. If M were diagonalizable, there exists a transformation such that $RMR^{-1} = I$, which imply $M = R^{-1}IR = I$. A contradiction, so M is not diagonalizable.

A Hermitian matrix H has the property that for all the vectors \mathbf{a} , \mathbf{b} , we have $\langle \mathbf{a} | H \mathbf{b} \rangle = \langle H \mathbf{a} | \mathbf{b} \rangle$. This is equivalent to stating $H = H^\dagger = (H^T)^*$.

Let the eigenvectors \mathbf{e}_n and eigenvalues λ_n of H satisfy $H \mathbf{e}_n = \lambda_n \mathbf{e}_n$. Then,

$$0 = \langle e_p | H e_n \rangle - \langle H e_p | e_n \rangle = (\lambda_n - \lambda_p^*) \langle e_p | e_n \rangle$$

If we choose $n = p$, then since $\langle e_n | e_n \rangle > 0$, we have $\lambda_n = \lambda_p^* = \lambda_n^* \in \mathbb{R}$. If the eigenvalues are distinct, $n \neq p$ and $\lambda_n \neq \lambda_p^* = \lambda_p$, and so $\langle e_n | e_p \rangle = 0$, i.e. the eigenvectors corresponding to distinct eigenvalues are orthogonal.

Suppose there are n distinct eigenvalues for the $n \times n$ Hermitian matrix, then we can automatically find n linearly independent orthogonal eigenvectors.

But suppose there are only $r < n$ distinct eigenvalues, i.e. the eigenvalues are degenerate, then there must exist at least one direction which possesses one of the degenerate eigenvalues, say λ , and is the corresponding eigenvector. Construct an orthonormal basis for the n -dimensional space consisting of that direction and any orthonormal basis in the orthogonal complement. In this basis $\{\mathbf{e}_n\}$ (where \mathbf{e}_1 is the known direction with eigenvalue λ), then in this basis, H has the form

$$H = \begin{pmatrix} \langle e_1 | H e_1 \rangle & \langle e_1 | H e_2 \rangle & \dots \\ \langle e_2 | H e_1 \rangle & \langle e_2 | H e_2 \rangle & \dots \\ \vdots & \vdots & \ddots \end{pmatrix} = \begin{pmatrix} \lambda_1 & 0 & \dots \\ 0 & \langle e_2 | H e_2 \rangle & \dots \\ \vdots & \vdots & \ddots \end{pmatrix}$$

where $\langle e_1 | e_2 \rangle = 0$. e_2 is not assumed to be an eigenvector. Having to decompose the space into the direct sum of \mathbf{e}_1 and its orthogonal complement, we restrict ourselves to the $(n-1) \times (n-1)$ subspace where a copy of the degenerate eigenvalue λ has been removed from the characteristic equation. We repeat the above process until each copy of the degenerate eigenvalue has been given an orthogonal eigenvector. This set of orthogonal eigenvectors is not unique. With this orthogonal basis, we can construct a matrix P to diagonalize H .

- (b) The determinant is

$$0 = \det(A - \lambda I) = \det \begin{pmatrix} 2 - \lambda & -a & 0 \\ -a & 2 - \lambda & 0 \\ 0 & 0 & c - \lambda \end{pmatrix} = (c - \lambda) \begin{vmatrix} 2 - \lambda & -a \\ -a & 2 - \lambda \end{vmatrix} = (c - \lambda) [(2 - \lambda)^2 - a^2]$$

$\lambda = c, 2 \pm a$. By inspection, the eigenvector is found to be $\mathbf{e}_{\lambda=c} = (0, 0, 1)^T$. For $\lambda = 2 + a$, we evaluate $(A - (2 + a)I)x = 0$ and show that $\mathbf{e}_{\lambda=2+a} = \frac{1}{\sqrt{2}}(1, -1, 0)^T$. Since A is Hermitian, the set of eigenvectors must be mutually orthogonal. So the last eigenvector is $\mathbf{e}_{\lambda=2-a} = \frac{1}{\sqrt{2}}(1, 1, 0)^T$. Hence, $A = R\Lambda R^T$:

$$A = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ -1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2+a & 0 & 0 \\ 0 & 2-a & 0 \\ 0 & 0 & c \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

(c) The quadratic surface is

$$1 = x^T A x = x^T R \Lambda R^T x = U^T \Lambda U, \quad U = R^T x = \begin{pmatrix} \frac{1}{\sqrt{2}}(x - y) \\ \frac{1}{\sqrt{2}}(x + y) \\ z \end{pmatrix}$$

In u coordinates,

$$1 = u_1^2(2 + a) + u_2^2(2 - a) + u_3^2 c$$

where the u_3 -axis coincide with the z -axis.

- $a = 0, c = 2$: $1 = 2(u_1^2 + u_2^2 + u_3^2)$ is a sphere of radius $\frac{1}{\sqrt{2}}$;
- $a = 0, c < 2$: $1 = 2u_1^2 + 2u_2^2 + u_3^2 c$ is a prolate ellipsoid of revolution about the z -axis with major axis length $\frac{1}{\sqrt{c}}$ and minor axis length $\frac{1}{\sqrt{2}}$;
- $a = 0, c > 2$: $1 = 2u_1^2 + 2u_2^2 + u_3^2 c$ is an oblate ellipsoid of revolution about the z -axis with major axis length $\frac{1}{\sqrt{2}}$ and minor axis length $\frac{1}{\sqrt{c}}$;
- $a < 2$: triaxial ellipsoid with principal axes being eigenvectors and semi-axes lengths being $\frac{1}{\sqrt{2+a}}$, $\frac{1}{\sqrt{2-a}}$ and $\frac{1}{\sqrt{c}}$;
- $a = 2$: $1 = 4u_1^2 + cu_3^2$ is an ellipsoidal cylinder with cylindrical axis in \mathbf{e}_2 and elliptical cross-section in e_1 - e_3 plane with semi-axes of lengths $\frac{1}{\sqrt{2+a}}$ and $\frac{1}{\sqrt{c}}$;
- $a > 2$: hyperboloid of one sheet, with elliptical cross-section in e_1 - e_3 plane and e_2 being the symmetry axis.

Problem 8.6 (Linear Algebra):

- (a) Let A and B be $n \times n$ Hermitian matrices, each with n distinct eigenvalues. Show that:
- (i) the matrix $H = i(AB - BA)$ is Hermitian; [4]
 - (ii) the eigenvectors of A and B are identical if and only if $AB = BA$; [6]
 - (iii) the matrix $N = A + iB$ is diagonalisable. [5]
- (b) Suppose C is a unitary matrix, A is a Hermitian matrix, and p is a positive integer. Show that $(C^{-1}AC)^p$ has real eigenvalues. [5]

Answer 8.6.

- (a) (i) This is true. Since A and B are Hermitian, i.e. $A^\dagger = A$ and $B^\dagger = B$,

$$H^\dagger = -i(AB - BA)^\dagger = -i(B^\dagger A^\dagger - A^\dagger B^\dagger) = -i(BA - AB) = i(AB - BA) = H$$

- (ii) Assume the eigenbasis of A is also the eigenbasis of B . Let this be $\{\mathbf{e}_n\}$ such that $A\mathbf{e}_n = a_n\mathbf{e}_n$ and $B\mathbf{e}_n = b_n\mathbf{e}_n$. Since each eigenvalue is distinct, the eigenvectors are linearly independent, i.e. the only solution to $\mathbf{q} = \sum_{p=1}^n \alpha_p \mathbf{e}_p = \mathbf{0}$ is $\alpha_p = 0 \forall p$. Consider

$$\mathbf{0} = \prod_{p=1, p \neq s}^n (A - a_p I) \mathbf{q} = \prod_{p=1, p \neq s}^n (a_s - a_p) \alpha_s \mathbf{e}_s$$

which implies $\alpha_s = 0 \forall \mathbf{e}_s$, so the eigenvectors form a basis. Apply $AB - BA$ to an arbitrary vector $\mathbf{v} = \sum_{p=1}^n \beta_p \mathbf{e}_p$ written as a linear combination of the basis vectors:

$$(AB - BA)\mathbf{v} = \sum_{p=1}^n (a_p b_p - b_p a_p) \beta_p \mathbf{e}_p = \mathbf{0} \implies AB = BA$$

Conversely, if $AB = BA$, then $a_n B\mathbf{e}_n = AB\mathbf{e}_n = BA\mathbf{e}_n$, and so $B\mathbf{e}_n$ is an eigenvector of A with eigenvalue a_n . But all the eigenvalues of A are given to be distinct, so $B\mathbf{e}_n$ is parallel to \mathbf{e}_n , $\exists b_n$ such that $B\mathbf{e}_n = b_n \mathbf{e}_n$. Hence, the eigenvectors of A are also the eigenvectors of B .

- (iii) This is not true! We can rewrite N as

$$N = \frac{1}{2}(N + N) + \frac{1}{2}(N^\dagger - N^\dagger) = \frac{1}{2}(N + N^\dagger) + i\frac{1}{2i}(N - N^\dagger)$$

We label $A = \frac{1}{2}(N + N^\dagger)$ and $B = \frac{1}{2i}(N - N^\dagger)$. We give a quick example of a non-diagonalizable matrix. Let $N = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}$. The eigenvalues are 1 and 1. If the matrix were diagonalizable, $\exists U$ such that $U^\dagger N U = I$. But, $N = U I U^\dagger = I$, which is a contradiction. For this choice of N , we choose $A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$. Indeed, both are Hermitian matrices and have 2 distinct eigenvalues, namely $\{2, 0\}$ and $\{+1, -1\}$ respectively. But yet, N is not diagonalizable.

- (b) A is Hermitian and must have real eigenvalues. Take $A\mathbf{e}_n = a_n \mathbf{e}_n$.

$$0 = \langle \mathbf{e}_n | A \mathbf{e}_n \rangle - \langle A \mathbf{e}_n | \mathbf{e}_n \rangle = (a_n - a_n^*) \langle \mathbf{e}_n | \mathbf{e}_n \rangle$$

Since $\langle \mathbf{e}_n | \mathbf{e}_n \rangle \neq 0$, $a_n = a_n^* \in \mathbb{R}$. So consider $v_n = C^\dagger \mathbf{e}_n$, then

$$(C^{-1}AC)^p C^\dagger \mathbf{e}_n = C^{-1}AC C^\dagger \mathbf{e}_n = C^{-1}A^p \mathbf{e}_n = a_n^p C^{-1} \mathbf{e}_n = a_n^p C^\dagger \mathbf{e}_n$$

where C is unitary. So, $C^\dagger \mathbf{e}_n$ is an eigenvector of $(C^{-1}AC)^p$. Since $a_n \in \mathbb{R} \implies a_n^p \in \mathbb{R}$, then $(C^{-1}AC)^p$ have real eigenvalues.

Problem 8.7 (Cauchy-Riemann):

- (a) Use the Cauchy-Riemann relations to show that, for any analytic function $f(x, y) = u(x, y) + iv(x, y)$, the relation $|\nabla u| = |\nabla v|$ must hold. [2]

- (b) Find the most general analytic function $f(z)$ of the variable $z = x + iy$ whose imaginary part is

$$(y \cos y + x \sin y)e^x$$

(Your final expression for $f(z)$ should be in terms of z , not x and y .) [10]

- (c) Find the radii of convergence of the following Taylor series:

- (i) [3]

$$\sum_{n=2}^{\infty} \frac{z^n}{\ln n}$$

- (ii) [5]

$$\sum_{n=1}^{\infty} \left(\frac{n+p}{n} \right)^{n^2} z^n, \text{ with } p \in \mathbb{R}$$

Hint: You may want to use the following result:

$$a^n = e^{n \ln a}$$

for some real a .

Answer 8.7.

- (a) The Cauchy-Riemann relations are $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ and $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$. If f is analytic, then

$$|\nabla u| = \sqrt{\left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2} = \sqrt{\left(\frac{\partial v}{\partial y}\right)^2 + \left(-\frac{\partial v}{\partial x}\right)^2} = |\nabla v|$$

- (b) $\text{Im}[f] = (y \cos y + x \sin y)e^x$. For $f = u + iv$ to be analytic, it must be complex differentiable and obeys the Cauchy-Riemann relations. So

$$-\frac{\partial u}{\partial y} = \frac{\partial v}{\partial x} = e^x \sin y + e^x (y \cos y + x \sin y) \implies u(x, y) = \cos y e^x - \int y \cos y dy e^x + e^x x \cos y + g(x)$$

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} = \cos y e^x - y \sin y e^x + x \cos y e^x \implies u(x, y) = e^x (\cos y - y \sin y) + \cos y \int x e^x dx + h(y)$$

But $\int y \cos y dy = y \sin y + \cos y$ and $\int x e^x dx = e^x (x - 1)$ and so comparing both expressions, $u(x, y) = (x \cos y - y \sin y)e^x + C$ where C is some constant. Thus,

$$f(x, y) = u(x, y) + iv(x, y) = (x \cos y - y \sin y)e^x + i(y \cos y + x \sin y)e^x + C = z e^x e^{iy} + C = z e^z + C$$

- (c) (i) Try ratio test with $u_n(z) = \frac{z^n}{\ln n}$ for $n \geq 2$:

$$1 = \lim_{n \rightarrow \infty} \left| \frac{u_{n+1}(R)}{u_n(R)} \right| = \lim_{n \rightarrow \infty} \frac{R^{n+1}}{R^n} \frac{\ln n}{\ln n + 1} = R \lim_{n \rightarrow \infty} \frac{1/n}{1/(n+1)} = R$$

where we used L'Hopital Rule.

- (ii) Try ratio test with $u_n(z) = \left(\frac{n+p}{n}\right)^{n^2} z^n$ for $n \geq 1$:

$$1 = \lim_{n \rightarrow \infty} \left| \frac{u_{n+1}(R)}{u_n(R)} \right| = \lim_{n \rightarrow \infty} \left| \frac{R^{n+1}}{R^n} \left(\frac{n+1+p}{n+1}\right)^{(n+1)^2} \left(\frac{n}{n+p}\right)^{n^2} \right| = R \lim_{n \rightarrow \infty} e^{(n+1)p - np} = R e^p$$

where we used the given hint, as well as, the approximation $\ln(1 + \frac{p}{n+1}) \approx \frac{p}{n+1}$ for large n . Hence, $R = e^{-p}$.

Problem 8.8 (Series Solution to ODE):

- (a) Find the power series solution of the equation

$$\frac{d^2y}{dx^2} - 2x\frac{dy}{dx} + \lambda y = 0 \quad (*)$$

where λ is a real parameter, about the point $x = 0$, and find suitable recurrence relations for the coefficients. For what values of λ does (*) have a polynomial solution? Find the solutions corresponding to two eigenvalues λ of your choice. [10]

- (b) Consider the hypergeometric equation

$$x(1-x)\frac{d^2y}{dx^2} + [\gamma - (1 + \alpha + \beta)x]\frac{dy}{dx} - \alpha\beta y = 0$$

where α, β and γ are real constants. Assuming a solution of the form

$$y(x) = \sum_{n=0}^{\infty} a_n x^{n+\sigma} \text{ with } a_0 \neq 0$$

show that

$$\sigma = 0 \text{ or } \sigma = 1 - \gamma$$

and that

$$a_n = \frac{(n + \sigma + \alpha - 1)(n + \sigma + \beta - 1)}{(n + \sigma)(n + \sigma + \gamma - 1)} a_{n-1}$$

for all $n \geq 1$. [10]

Answer 8.8.

- (a) $-2x$ and λ are analytic at $x = 0$, so $x = 0$ is an ordinary point. We can try a series solution of the form $y = \sum_{n=1}^{\infty} a_n x^n$. The recurrence relation will be

$$\sum_{n=1}^{\infty} a_n n(n-1)x^{n-2} - 2 \sum_{n=1}^{\infty} a_n n x^n + \lambda \sum_{n=1}^{\infty} a_n x^n = 0 \implies a_{n+2} = \frac{2n - \lambda}{(n+2)(n+1)} a_n$$

To have a polynomial solution, the series must terminate. This means $\lambda = 2n$, i.e. λ is even. We have $a_2 = -\frac{\lambda}{2}a_0$ and $a_3 = \frac{2-\lambda}{3 \times 2}a_1$. We choose $\lambda = 0 \implies y = a_0$ and $\lambda = 2 \implies y = a_1 x$.

- (b) With the suggested series solution and comparing the $x^{n+\sigma}$ terms with $n \geq 1$ will give the recurrence relation

$$\begin{aligned} 0 &= \sum_{n=0}^{\infty} a_n (n + \sigma)(n + \sigma - 1)x^{n+\sigma-1} - \sum_{n=0}^{\infty} a_n (n + \sigma)(n + \sigma - 1)x^{n+\sigma} \\ &\quad + \gamma \sum_{n=0}^{\infty} a_n (n + \sigma)x^{n+\sigma-1} - \sum_{n=0}^{\infty} [(1 + \alpha + \beta)(n + \sigma) - \alpha\beta] a_n x^{n+\sigma} \\ \implies a_{n+1} &= \frac{(n + \sigma + \alpha)(n + \sigma + \beta)}{(n + 1 + \sigma)(n + \sigma + \gamma)} a_n \end{aligned}$$

Reindexing give the desired relation. Comparing the $x^{\sigma-1}$ terms give $a_0\sigma(\gamma + \sigma - 1) = 0$. Since $a_0 \neq 0$, $\sigma = 0$ or $\sigma = 1 - \gamma$.

Problem 8.9 (Variational Principle):

- (a) The Euler–Lagrange equation for extrema of the functional

$$D[y] = \int_a^b f(x, y, y') dx$$

where $y' = \frac{dy}{dx}$ is

$$\frac{\partial f}{\partial y} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) = 0 \quad (*)$$

If $f = f(y, y')$ does not depend explicitly on x show that $(*)$ can be written as

$$\frac{dh}{dx} = 0$$

for some h , which you should determine. [3]

- (b) A forest lies in the (x, y) plane. A new path through the forest is proposed, starting at $(x, y) = (-1, 1)$ and ending at $(x, y) = (1, 1)$. The density of undergrowth in the forest is given by $g(y)$, such that the total undergrowth D to be destroyed by the new path is

$$D = \int_{\mathcal{P}} g(y) ds$$

where ds is the arc-length element along the path \mathcal{P} .

- (i) Given that the path always travels in the positive x direction, show that the path $y(x)$ that minimises the destruction of undergrowth satisfies [4]

$$\frac{d}{dx} \left(\frac{g}{\sqrt{1 + y'^2}} \right) = 0$$

- (ii) In the specific case when $g = y^{-1}$, calculate the path $y(x)$. [9]

- (iii) Sketch the path, and determine its length. [4]

Answer 8.9.

- (a) By chain rule and invoke Euler-Lagrange equation $(*)$:

$$\frac{df}{dx} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial x} + \frac{\partial f}{\partial y'} \frac{\partial y'}{\partial x} = \frac{\partial f}{\partial x} + y' \frac{d}{dx} \frac{\partial f}{\partial y'} + y'' \frac{\partial f}{\partial y'} = \frac{\partial f}{\partial x} + \frac{d}{dx} y' \frac{\partial f}{\partial y'}$$

Since $f = f(y, y')$ does not explicitly depend on x , then $h := y' \frac{\partial f}{\partial y'} - f$ is a constant.

- (b) (i) $D = \int_{\mathcal{P}} g(y) \sqrt{dx^2 + dy^2} = \int_{x>0} g(y) \sqrt{1 + y'^2} dx$. The integrand is independent of x and hence by part (a),

$$0 = \frac{d}{dx} \left(g(y) \sqrt{1 + y'^2} - \frac{y' g}{\sqrt{1 + y'^2}} \right) = \frac{d}{dx} \frac{g}{\sqrt{1 + y'^2}}$$

- (ii) With $g(y) = y^{-1}$, then $y^{-1} = k \sqrt{1 + y'^2}$ for some constant k . This simplifies to

$$y^{-2} = k^2(1 + y'^2) \implies dx = \frac{ky}{\sqrt{1 - k^2 y^2}} dy \implies (x - x_0)^2 + y^2 = \frac{1}{k^2}$$

which describes an arc of a circle. The boundary conditions $y(x = \pm 1) = 1$ gives $x_0 = 0$ and $\frac{1}{k^2} = 2$. This describes an arc of a circle of radius $\sqrt{2}$.

- (iii) The path will be a circular arc traversed clockwise from $(-1, 1)$ to $(+1, 1)$. The arc length will be $\frac{\pi}{2} \sqrt{2}$ (where we notice that the line from the origin to $(1, 1)$ subtends an angle of $\pi/4$ and by symmetry, the angle subtended by the arc is $\pi/2$).

Problem 8.10 (Rayleigh-Ritz Method):

(i) Consider the problem

$$\frac{d^2 u}{dx^2} + \epsilon \left[x \frac{d^2 u}{dx^2} + \frac{du}{dx} - u \right] = -\lambda u, \quad 0 \leq x \leq \pi, \quad u'(0) = u(\pi) = 0 \quad (*)$$

where $\epsilon \geq 0$ is a parameter, λ is a real constant, and $u' = \frac{du}{dx}$. Express (*) in the form

$$\mathcal{L}u = \lambda u \quad (**)$$

where \mathcal{L} is an operator in Sturm-Liouville form. [2]

(ii) Now consider the functional

$$I[v] = \int_0^\pi (pv'^2 + qv^2) dx$$

where $v(x)$ satisfies $v'(0) = v(\pi) = 0$, and is subject to the constraint

$$\int_0^\pi wv^2 dx = 1$$

for smooth functions $p(x) > 0$, $q(x) > 0$ and $w(x) > 0$. Show that, for a particular choice of the functions p , q and w , which should be specified, finding extrema of I is equivalent to finding solutions of (*). Explain why the stationary values of I are the eigenvalues λ of equation (**). You may use the Euler-Lagrange equation without proof. [8]

(iii) When $\epsilon = 0$, show that the smallest eigenvalue of (**) is $\lambda_0 = 1/4$, and the associated normalised eigenfunction is

$$U_0(x) = \sqrt{\frac{2}{\pi}} \cos \frac{x}{2}$$

Using $U_0(x)$ as a trial function, find an upper bound for the lowest eigenvalue λ of equation (**) when $\epsilon > 0$. [10]**Answer 8.10.**(i) Rearranging gives $\mathcal{L} = -\frac{d}{dx}[(1 + \epsilon x)\frac{d}{dx}] + \epsilon$.(ii) We have to extremize $\int_0^\pi pv'^2 + qv^2 - \mu wv^2 dx$. The integrand $f(v, v'; x) = pv'^2 + qv^2 - \mu wv^2$ must satisfy Euler-Lagrange equation whenever the functional is stationary. Hence,

$$0 = \frac{d}{dx} \frac{\partial f}{\partial v'} - \frac{\partial f}{\partial v} = \frac{d}{dx}(2pv') - 2qv + 2\mu wv \implies \frac{1}{w} \left(-\frac{d}{dx} \left(p \frac{dv}{dx} \right) + qv \right) = \mu v$$

This is equivalent to the original SL problem, where $p(x) = 1 + \epsilon x$, $q = \epsilon$, $\mu = \lambda$ and $w = 1$. So finding extrema of I (subject to the constraint) will be equivalent to finding the solutions of (**).

$$I[v] = \int_0^\pi pv'^2 + qv^2 dx = [vpv']_0^\pi + \int_0^\pi -v(pv')' + vqv dx = \int_0^\pi v \left(-\frac{d}{dx} \left(p \frac{dv}{dx} \right) + qv \right) dx = \int_0^\pi vw \mathcal{L}v dx$$

where we are given $v'(0) = v(\pi) = 0$, hence the boundary terms is zero. The result is just $\int_0^\pi vw \lambda v dx = \lambda$. The stationary values of I is indeed the corresponding eigenvalues of (**).

(iii) When $\epsilon = 0$, $\frac{d^2 u}{dx^2} = -\lambda u$. For $\lambda \neq 0$, we have $u(x) = A(\lambda) \sin \sqrt{\lambda} x + B(\lambda) \cos \sqrt{\lambda} x$. The boundary conditions give $A(\lambda) = 0 \forall \lambda$ and $\sqrt{\lambda} \pi = \frac{\pi}{2}(2n + 1)$. Hence, $\lambda_0 = \frac{1}{4}$ ($n = 0$). To find B_0 , we normalize:

$$1 = \int_0^\pi |B_0|^2 \cos^2 \frac{x}{2} dx \implies B_0 = \sqrt{\frac{2}{\pi}}$$

Since $w = 1$, $U_0(x) = \sqrt{\frac{2}{\pi}} \cos \frac{x}{2}$ is automatically normalized. Then

$$\Lambda[U_0] = I[U_0] = \frac{2}{\pi} \int_0^\pi (1 + \epsilon x) \frac{1}{4} \sin^2 \frac{x}{2} + \epsilon \cos^2 \frac{x}{2} dx = \frac{1}{4} + \epsilon + 0 - \frac{\epsilon}{4\pi} \int_0^\pi x \cos x dx = \frac{1}{4} + \epsilon \left(1 - \frac{1}{2\pi} \right)$$

which is larger than $\frac{1}{4}$ for $\epsilon > 0$. Thus, an upper bound for the lowest eigenvalue $\lambda_0 = \frac{1}{4}$.

8.2 Paper 2

Problem 8.11 (Sturm-Liouville): Let $y_n(x)$ and λ_n , $n = 0, 1, 2, \dots$, be the real normalised eigenfunctions and corresponding eigenvalues for the Sturm-Liouville eigenvalue problem

$$\mathcal{L}y_n(x) = -\frac{d}{dx} \left[p(x) \frac{dy_n(x)}{dx} \right] + q(x)y_n(x) = \lambda_n w(x)y_n(x), \quad 0 \leq x \leq 1, \quad y_n(0) = y_n(1) = 0$$

with $p(x) > 0$ and $w(x) > 0$.

- (a) State, without proof, the orthonormality property for two eigenfunctions $y_n(x)$ and $y_m(x)$. [2]

- (b) Given the completeness of the eigenfunctions, any real function $f(x)$ satisfying the same boundary conditions as $y_n(x)$ can be written as

$$f(x) = \sum_{n=0}^{\infty} a_n y_n(x)$$

for some real constants a_n . Show that [5]

$$\int_0^1 w(x) f(x)^2 dx = \sum_{n=0}^{\infty} a_n^2$$

- (c) Now consider the equation $\mathcal{L}Y(x) = w(x)[\alpha Y(x) + f(x)]$, where α is a constant, $\alpha \neq \lambda_n$ for any n , and $Y(x)$ satisfies the same boundary conditions as $y_n(x)$.

- (i) Show that the solution of this equation can be written as [6]

$$Y(x) = \sum_{n=0}^{\infty} \frac{a_n}{\lambda_n - \alpha} y_n(x)$$

- (ii) Suppose that $\lambda_0 = 1$, $\lambda_1 = 2$, and $f = 2[y_0(x) + y_1(x)] - \alpha y_1(x)$. Given that

$$\int_0^1 w(x) Y(x)^2 dx = 2$$

and that $\alpha > 0$, find α and express $Y(x)$ in terms of the eigenfunctions $y_n(x)$. [7]

Answer 8.11.

(a) $\int_0^1 y_n(x) w(x) y_m(x) dx = \delta_{mn}$.

(b) Using the result of part (a):

$$\int_0^1 w(x) f(x)^2 dx = \int_0^1 w(x) \sum_{p=0}^{\infty} a_p y_p(x) \sum_{q=0}^{\infty} a_q y_q(x) dx = \sum_{p=0}^{\infty} \sum_{q=0}^{\infty} a_p a_q \delta_{pq} = \sum_{n=0}^{\infty} a_n^2$$

- (c) (i) By part (b) and since the eigenfunctions $y_i(x)$ are complete, and that $Y(x)$ satisfy the same boundary conditions as $y_i(x)$, can write $Y(x) = \sum_{n=0}^{\infty} b_n y_n(x)$. Then,

$$\sum_{n=0}^{\infty} b_n w(x) \lambda_n y_n(x) = w(x) \left[\alpha \sum_{n=0}^{\infty} b_n y_n(x) + \sum_{n=0}^{\infty} a_n y_n(x) \right]$$

Multiply both sides by $y_p(x)$ and integrate from 0 to 1, gives $b_p \lambda_p = \alpha b_p + a_p \implies Y(x) = \sum_{n=0}^{\infty} \frac{a_n}{\lambda_n - \alpha} y_n(x)$.

- (ii) $2 = \int_0^1 w(x) Y(x)^2 dx = \sum_{n=0}^{\infty} \frac{a_n^2}{(\lambda_n - \alpha)^2} = \frac{2^2}{(1 - \alpha)^2} + \frac{(2 - \alpha)^2}{(2 - \alpha)^2} \implies \alpha = 3$ since $\alpha > 0$. Thus,

$$Y(x) = \frac{2}{1 - 3} y_0(x) + \frac{2 - \alpha}{2 - \alpha} y_1(x) = -y_0(x) + y_1(x)$$

Problem 8.12 (Laplace's Equation): Consider the Laplace equation in elliptic coordinates

$$\frac{\partial^2 \Phi}{\partial \mu^2} + \frac{\partial^2 \Phi}{\partial \nu^2} = 0 \quad (*)$$

where $\mu > 0$, $0 \leq \nu < 2\pi$ is a periodic coordinate and Φ is single valued, so $\Phi(\mu, \nu) = \Phi(\mu, \nu + 2\pi)$.

- (a) Use separation of variables to show that the general solution of (*) that is continuous and single valued for $\mu > 0$ can be written as

$$\Phi = A_0 + B_0\mu + \sum_{n=1}^{+\infty} \left\{ \left[A_n \cosh(n\mu) + B_n \sinh(n\mu) \right] \cos(n\nu) + \left[C_n \cosh(n\mu) + D_n \sinh(n\mu) \right] \sin(n\nu) \right\}$$

where A_n , B_n , C_n and D_n are constants. [10]

- (b) A line of constant μ is an ellipse with semi-major axis $\cosh \mu$ and semi-minor axis $\sinh \mu$. Such an ellipse can be defined in terms of Cartesian coordinates as

$$\frac{x^2}{\cosh^2 \mu} + \frac{y^2}{\sinh^2 \mu} = 1$$

The function Φ satisfies (*) in the region defined by $a < \mu < b$. At the inner ellipse, defined by $\mu = a$, Φ has normal derivative

$$\left. \frac{\partial \Phi}{\partial \mu} \right|_{\mu=a} = -\cos(2\nu)$$

The outer ellipse, defined by $\mu = b$, is held at $\Phi(b, \nu) = \cos(\nu)$. Use separation of variables to find Φ in the region $a < \mu < b$. [10]

Answer 8.12.

- (a) Use separation of variables $\Phi(\mu, \nu) = T(\mu)\Theta(\nu)$:

$$\frac{1}{\Theta} \frac{d^2 \Theta}{d\nu^2} = -\frac{d^2 T}{d\mu^2} = -\lambda^2$$

where λ is some constant, then $\Theta(\nu) = c_1 \cos \lambda \nu + c_2 \sin \lambda \nu$ for $\lambda \neq 0$ and $c_3 \nu + c_4$ for $\lambda = 0$. But Θ is periodic, i.e. $\Theta(\nu + 2\pi) = \Theta(\nu) \implies c_3 = c_4 = 0$ and $\lambda = n \in \mathbb{Z}^+$. Also, $T(\mu) = c_7 \mu + c_8$ for $\lambda = 0$ and $T(\mu) = c_5 \sinh \lambda \mu + c_6 \cosh \lambda \mu$ for $\lambda \neq 0$. Thus,

$$\Phi(\mu, \nu) = c_7 \mu + c_8 + \sum_{n=1}^{\infty} (c_5 \sinh n\mu + c_6 \cosh n\mu) (c_1 \cos n\nu + c_2 \sin n\nu)$$

where we identify $c_7 = A_0$, $c_8 = B_0$, $c_5 c_1 = B_n$, $c_6 c_1 = A_n$, $c_2 c_6 = C_n$, $c_2 c_5 = D_n$.

- (b) Plugging into boundary conditions and comparing coefficients:

$$\begin{aligned} -\cos 2\nu &= \left. \frac{\partial \Phi}{\partial \mu} \right|_{\mu=a} \\ &= B_0 + \sum_{n=1}^{+\infty} \left\{ n \left[A_n \sinh(na) + B_n \cosh(na) \right] \cos(n\nu) + n \left[C_n \sinh(na) + D_n \cosh(na) \right] \sin(n\nu) \right\} \end{aligned}$$

which gives $B_0 = 0$, $2A_2 \sinh(2a) + 2B_2 \cosh(na) = -1$, $n(A_n \sinh(na) + B_n \cosh(na)) = 0$ $\forall n \neq 2$, $n(D_n \cosh(na) + C_n \sinh(na)) = 0 \forall n \geq 1$.

$\cos \nu = \Phi(b, \nu)$

$$= A_0 + B_0 b + \sum_{n=1}^{+\infty} \left\{ \left[A_n \cosh(nb) + B_n \sinh(nb) \right] \cos(n\nu) + \left[C_n \cosh(nb) + D_n \sinh(nb) \right] \sin(n\nu) \right\}$$

which gives $A_1 \cosh(b) + B_1 \sinh(b) = 1$, $A_0 + B_0 b = 0$, $C_n \cosh(nb) + D_n \sinh(nb) = 0$ $\forall n \geq 1$ and $A_n \cosh(nb) + B_n \sinh(nb) = 0$ $\forall n \geq 2$. This gives $A_n = B_n = 0$ $\forall n \neq 1, 2$ and $C_n = D_n = 0$ $\forall n$, as well as,

$$\begin{pmatrix} A_1 \\ B_1 \end{pmatrix} = \frac{1}{\cosh(a) \cosh(b) - \sinh(b) \sinh(a)} \begin{pmatrix} \cosh a & -\sinh b \\ -\sinh a & \cosh b \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{\cosh(a-b)} \begin{pmatrix} \cosh(a) \\ -\sinh(a) \end{pmatrix}$$

$$\begin{aligned} \begin{pmatrix} A_2 \\ B_2 \end{pmatrix} &= \frac{1}{2 \cosh(2a) \cosh(2b) - \sinh(2b) \sinh(2a)} \begin{pmatrix} 2 \cosh 2a & -\sinh 2b \\ -2 \sinh 2a & \cosh 2b \end{pmatrix} \begin{pmatrix} 0 \\ -1 \end{pmatrix} \\ &= \frac{1}{2 \cosh(2(b-a))} \begin{pmatrix} \sinh(2b) \\ -\cosh(2b) \end{pmatrix} \end{aligned}$$

where we used hyperbolic trigonometric identities. Hence,

$$\Phi = \frac{\cosh(a-\mu)}{\cosh(a-b)} \cos \nu + \frac{\sinh 2(b-\mu)}{2 \cosh 2(b-a)} \cos 2\nu$$

Problem 8.13 (Green's Functions):

(a) Let ϕ be a scalar field that tends to zero as $|\mathbf{r}| \rightarrow +\infty$ and satisfies the Klein-Gordon equation

$$(\nabla^2 - k^2)\phi = \rho$$

where $\rho(\mathbf{r})$ tends to zero rapidly as $|\mathbf{r}| \rightarrow +\infty$ and k is a real constant.

(i) Verify that

$$\phi(\mathbf{r}) = \int_{\mathbb{R}^3} G(\mathbf{r}, \bar{\mathbf{r}}) \rho(\bar{\mathbf{r}}) d^3 \bar{\mathbf{r}}$$

where $G(\mathbf{r}, \bar{\mathbf{r}})$ satisfies

$$(\nabla_r^2 - k^2)G(\mathbf{r}, \bar{\mathbf{r}}) = \delta^{(3)}(\mathbf{r} - \bar{\mathbf{r}}) \quad (*)$$

(ii) Show that

$$G(\mathbf{r}, \bar{\mathbf{r}}) = A \frac{e^{-k|\mathbf{r}-\bar{\mathbf{r}}|}}{|\mathbf{r}-\bar{\mathbf{r}}|}$$

and determine A .

[6]

(iii) Let V be the half plane of \mathbb{R}^3 with $z > 0$. Use the method of images to determine $G(\mathbf{r}, \bar{\mathbf{r}})$ satisfying (*) everywhere on V , subject to $G(z=0) = 0$, and $G \rightarrow 0$ as $|\mathbf{r}| \rightarrow +\infty$. [2]

(b) Let V be a region of three-dimensional space with boundary S . The scalar function $\psi(\mathbf{r})$ satisfies Laplace's equation in V

$$\nabla^2 \psi = 0$$

and $\psi(\mathbf{r}) = w(\mathbf{r})$ on S , where $w(\mathbf{r})$ is an arbitrary scalar function defined throughout V .

Show that

[8]

$$\int_V (\nabla w) \cdot (\nabla w) d^3 \mathbf{r} \geq \int_V (\nabla \psi) \cdot (\nabla \psi) d^3 \mathbf{r}$$

[Hint: Consider the inequality $\int_V \nabla(\psi - w) \cdot \nabla(\psi - w) d^3 \mathbf{r} \geq 0$.]

Answer 8.13.

(a) (i) The corresponding Green's function satisfy

$$(\nabla^2 - k^2)G(\mathbf{r}, \mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}')$$

and $G \rightarrow 0$ as $|\mathbf{r}| \rightarrow \infty$. By the Green's second identity

$$\int_V u \nabla^2 v - v \nabla^2 u dV = \int_{\partial V} (u \nabla v - v \nabla u) \cdot d\mathbf{S}$$

Let $u = \phi$ and $v = G$, then

$$\int_V \phi \nabla^2 G - G \nabla^2 \phi dV = 0$$

where RHS is zero since $\phi \rightarrow 0$ as $|\mathbf{r}| \rightarrow \infty$. But LHS is $\int_V \delta^{(3)}(\mathbf{r} - \mathbf{r}') \phi(\mathbf{r}) - G(\mathbf{r}, \mathbf{r}') \rho(\mathbf{r}) dV$, and so:

$$\phi(\mathbf{r}') = \int_V G(\mathbf{r}, \mathbf{r}') \rho(\mathbf{r}) dV$$

(ii) Since the problem has spherical symmetry, then $G(\mathbf{r}, \mathbf{r}') = G(|\mathbf{r} - \mathbf{r}'|) = G(r)$. We check the suggested solution is indeed a solution:

$$\nabla_{\mathbf{r}}^2 G = \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dG}{dr} \right) = \frac{A}{r^2} e^{-kr} \frac{d}{dr} (-1 - kr) = k^2 G$$

To find A , we use Divergence Theorem for a sphere of radius ϵ centred on the origin, $V = \{|\mathbf{r}| \leq \epsilon\}$.

$$\int_V \nabla^2 G dV - k^2 \int_V G dV = \int_V \delta(r) dV \implies \lim_{\epsilon \rightarrow 0} \frac{dG}{dr} \Big|_{r=\epsilon} 4\pi \epsilon^2 = 1 \implies 1 = -\lim_{\epsilon \rightarrow 0} A e^{-k\epsilon} (\epsilon^{-1} + k) 4\pi \epsilon$$

Then after taking $\epsilon \rightarrow 0$, we have $A = -\frac{1}{4\pi}$.

(iii) We have a further condition $G(z=0) = 0$ and $G \rightarrow 0$ as $|\mathbf{r}| \rightarrow \infty$. By Uniqueness Theorem, we use the method of images. We replace the original problem with one involving images. This is valid as long as the boundary condition is still satisfied and (*) is still satisfied everywhere on V (i.e. add images outside of V). Since the solution is unique, this must be the solution to the original problem.

To preserve the mirror symmetry of the problem (about $z=0$ plane), we place an image of opposing strength at \mathbf{r}' where \mathbf{r}' and \mathbf{r} are related to each other with the z -component flipped. Then, the corresponding G of this modified problem satisfies

$$(\nabla^2 - k^2)G = \delta^{(3)}(\mathbf{r} - \mathbf{r}_0) - \delta^{(3)}(\mathbf{r} - \mathbf{r}')$$

Since the Klein's Gordon equation is linear, the solution will be a linear combination of the fundamental solutions:

$$G = \frac{1}{4\pi} \left(\frac{e^{-k|\mathbf{r} - \mathbf{r}_0|}}{|\mathbf{r} - \mathbf{r}_0|} - \frac{e^{-k|\mathbf{r} - \mathbf{r}'|}}{|\mathbf{r} - \mathbf{r}'|} \right)$$

(b) Invoke Divergence Theorem to $(\psi - w) \nabla \psi$:

$$\int_V \nabla \cdot ((\psi - w) \nabla \psi) dV = \int_S (\psi - w) \nabla \psi \cdot d\mathbf{S}$$

The RHS vanishes as $\psi = w$ on S . The LHS evaluates to

$$\int_V \nabla(\psi - w) \cdot \nabla \psi + \nabla^2 \psi (\psi - w) dV = \int_V \nabla \psi \cdot \nabla \psi + \nabla \psi \cdot \nabla w dV + 0$$

This gives $\int_V \nabla \psi \cdot \nabla \psi dV = \int_V \nabla \psi \cdot \nabla w dV$. Now, use the given hint:

$$0 \leq \int_V \nabla(\psi - w) \cdot \nabla(\psi - w) dV = \int_V \nabla \psi \cdot \nabla \psi dV + \int_V \nabla w \cdot \nabla w dV - 2 \int_V \nabla \psi \cdot \nabla w dV$$

The desired result follows from the previous result.

Problem 8.14 (Contour Integration):

- (a) Prove that if $f(z)$ is analytic and has a simple zero at $z = z_0$ then $1/f(z)$ has a simple pole with residue $1/f'(z_0)$ there. What is the residue of $g(z)/f(z)$ at $z = z_0$ if $g(z)$ is analytic at z_0 and $g(z_0) \neq 0$? [6]
- (b) Consider the function

$$H(z) = \frac{1}{a - \frac{1}{2i}(z - z^{-1})}$$

where $a > 1$ and real. State the location of any singularities of $h(z)$ and calculate the residue of $h(z)$ for the singularity that lies inside the unit circle. [6]

- (c) Use the result of part (b) and contour integration to evaluate

$$\int_{-\pi}^{\pi} \frac{\sin \theta}{a - \sin \theta} d\theta$$

where $a > 1$ and real. [8]

Answer 8.14.

- (a) A function $g(z)$ have first order pole at $z = z_0$ if $\lim_{z \rightarrow z_0} (z - z_0)g(z)$ exists and is finite. $g(z) = \frac{1}{f(z)}$ has a first order pole by considering

$$\lim_{z \rightarrow z_0} \frac{z - z_0}{f(z)} = \lim_{z \rightarrow z_0} \frac{1}{f'(z)}$$

where we used L'Hopital rule. Since $f(z)$ has a simple zero at z_0 , then $f'(z_0) \neq 0$ because $\lim_{z \rightarrow z_0} \frac{1}{f'(z)}$ is finite. The residue is $1/f'(z_0)$.

A function with N th order pole has Laurent expansion of the form $f(z) = \sum_{n=-N}^{\infty} a_n(z - z_0)^n$ with coefficient of $(z - z_0)^{-1}$ being known as the residue.

$$a_{-1} = \lim_{z \rightarrow z_0} \frac{z - z_0}{f(z)} = \frac{1}{f'(z)}$$

For $\frac{g(z)}{f(z)}$, the residue is $\frac{g(z_0)}{f'(z_0)}$ since g is analytic at z_0 and $g(z_0) \neq 0$.

- (b) The pole of $H(z)$ occurs at $2iaz - z^2 + 1 = 0 \implies z_{\pm} = i(a \pm \sqrt{a^2 - 1})$. Since $a > 1$, z_{\pm} is purely imaginary. Evaluate $z_- z_+$:

$$z_+ z_- = i(a + \sqrt{a^2 - 1})(i(a - \sqrt{a^2 - 1})) = -(a^2 - (a^2 - 1)) = -1$$

So $|z_+| = a + \sqrt{a^2 - 1} > 1$ lies outside the unit circle while z_- lies inside the unit circle. The residue of z_- is

$$\text{res}_{z=z_-} H(z) = \lim_{z \rightarrow z_-} \frac{1}{-(1/2i)(1 + z^{-2})} = -\frac{2i}{1 + z_-^2} = \frac{i}{a} (a - \sqrt{a^2 - 1})$$

- (c) The integral desired is

$$\begin{aligned} I &= \int_{-\pi}^{\pi} \frac{\sin \theta}{a - \sin \theta} d\theta \\ &= \text{Im} \left[\int_{-\pi}^{\pi} \frac{e^{i\theta}}{a - \sin \theta} d\theta \right] \\ &= \text{Im} \left[\oint_{\gamma} \frac{-idz}{a - (1/2i)(z - z^{-1})} \right] \\ &= \text{Im} [-i(2\pi i)ia^{-1}(a - \sqrt{a^2 - 1})] \\ &= 1 - \sqrt{1 - a^{-2}} \end{aligned}$$

Problem 8.15 (Transform Methods): The Fourier transform of a function $g(t)$ is given by

$$\tilde{g}(\omega) = \int_{-\infty}^{\infty} g(t)e^{-i\omega t} dt$$

- (a) Given the Fourier transform $\tilde{f}(\omega)$ of the function $f(t)$ derive Fourier transforms of $f'(t)$, $f''(t)$ and $tf(t)$, assuming that $f(t)$, $f'(t) \rightarrow 0$ as $|t| \rightarrow +\infty$. [6]
- (b) Show that the Fourier transform of $f(t) = e^{-t^2/2}$ satisfies

$$\frac{d\tilde{f}}{d\omega} = h(\omega)\tilde{f}$$

for some $h(\omega)$ which you should find explicitly. Solve this equation to determine \tilde{f} up to a multiplicative constant. [8]

- (c) Let $y(t)$ satisfy Bessel's equation of order zero, so that

$$ty''(t) + y'(t) + ty(t) = 0$$

Show that the Fourier transform of $y(t)$ satisfies a first-order differential equation. Solve this equation up to an arbitrary multiplicative constant. Using the inverse Fourier transform, express the Bessel function $y(t)$ in terms of an integral. [8]

Answer 8.15.

- (a) Using integration by parts, the Fourier transform of $f'(t)$ is

$$\mathcal{F}[f'(t)] = [fe^{-i\omega t}]_{-\infty}^{\infty} + i\omega \int_{-\infty}^{\infty} fe^{-i\omega t} dt$$

which is $i\omega\mathcal{F}[f]$ since $f \rightarrow 0$ as $|t| \rightarrow \infty$. Similarly, $\mathcal{F}[f''] = -\omega^2\tilde{f}(\omega)$. Lastly,

$$\mathcal{F}[tf(t)] = \int_{-\infty}^{\infty} f(t) \frac{-1}{i} \frac{d}{d\omega} e^{-i\omega t} dt = i \frac{d\tilde{f}}{d\omega}$$

- (b) Evaluate

$$\begin{aligned} \frac{d\tilde{f}}{d\omega} &= \int_{-\infty}^{\infty} \frac{\partial}{\partial \omega} e^{-t^2/2} e^{-i\omega t} dt \\ &= [e^{-t^2/2} e^{-i\omega t}]_{-\infty}^{\infty} + i\omega \int_{-\infty}^{\infty} e^{-t^2/2} e^{-i\omega t} dt \\ &= -\omega\tilde{f} \end{aligned}$$

which is solved by $\tilde{f}(\omega) \propto e^{-\omega^2/2}$. Hence, $h(\omega) = \omega$.

- (c) Take Fourier transform of the Bessel's equation:

$$0 = i \frac{d}{d\omega} \mathcal{F}^{-1}[y''] + i\omega\tilde{y} + i \frac{d\tilde{y}}{d\omega} = i \frac{d}{d\omega} (-\omega^2\tilde{y}) + i\omega\tilde{y} + i \frac{d\tilde{y}}{d\omega}$$

which is solved by $\tilde{y} \propto \frac{1}{\sqrt{1-\omega^2}}$. Using inverse Fourier transform, the solution is

$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{A}{\sqrt{1-\omega^2}} e^{i\omega t} d\omega$$

Problem 8.16 (Tensors):

- (a) State the transformation law for a tensor of order n . Given vectors \mathbf{u} and $\boldsymbol{\Omega}$, show that the quantity

$$\mathbf{W} = \mathbf{u} \times (\boldsymbol{\Omega} \times \mathbf{u})$$

also transforms as a vector. [5]

- (b) (i) Let V denote the volume inside a sphere of radius a . Explain briefly why the integral

$$\int_V x_{t_1} x_{t_2} \dots x_{t_n} dV$$

is an isotropic tensor for any positive integer n . [2]

- (ii) Hence show that

$$\int_V x_i dV = 0, \quad \int_V x_i x_j dV = \alpha \delta_{ij}, \quad \text{and} \quad \int_V x_i x_j x_k dV = 0$$

for some constant α to be determined. You may state without proof the form of the general isotropic tensors of order 1, 2 and 3. [5]

- (c) Suppose now that $\boldsymbol{\Omega}$ is a constant vector and $u_i = \Omega_i + \beta x_i$ for a constant scalar β . Determine $\mathbf{W}(\mathbf{x})$ and calculate [8]

$$\int_V W_i dV$$

Answer 8.16.

- (a) The transformation law for n -th order tensor:

$$T'_{i_1 i_2 \dots i_n} = L_{i_1 j_1} L_{i_2 j_2} \dots L_{i_n j_n} T_{j_1 j_2 \dots j_n}$$

where L is an orthogonal transformation linking the two frames. We have \mathbf{W} to be:

$$W_k = \epsilon_{ijk} u_i \epsilon_{pqj} \Omega_p u_q = (\delta_{kp} \delta_{iq} - \delta_{kq} \delta_{ip}) u_i \Omega_p u_q = u_i \Omega_k u_i - u_i \Omega_i u_k$$

Applying the transformation law:

$$\begin{aligned} W'_k &= L_{i\alpha} u_\alpha L_{i\beta} u_\beta L_{k\gamma} \Omega_\gamma - L_{i\alpha} u_\alpha L_{i\beta} \Omega_\beta L_{k\gamma} u_\gamma \\ &= \delta_{\alpha\beta} u_\alpha u_\beta L_{k\gamma} \Omega_\gamma - u_\alpha \Omega_\alpha u_\gamma L_{k\gamma} \\ &= L_{k\gamma} W_\gamma \end{aligned}$$

Thus, W transforms like a first-order tensor, i.e. vector.

- (b) (i) V is a sphere of radius a , and since the domain is spherically symmetric, the final integral result is unchanged under an arbitrary orthogonal transformation, and thus an isotropic tensor.
- (ii) $\int_V x_i dV = 0$ since there is no isotropic vector; $\int_V x_i x_j dV = \alpha \delta_{ij}$ since $\alpha \delta_{ij}$ is the most general isotropic tensor of order 2. Then,

$$\int_V r^2 r^2 \sin \theta d\theta dr = 3\alpha \implies \alpha = \frac{4\pi a^5}{15}$$

There is no third order isotropic tensor, so the result should be zero. Although ϵ_{ijk} is isotropic and third-order, it is a pseudotensor. Suppose the result is $\lambda \epsilon_{ijk}$, then

$$\lambda \epsilon_{ijk} = \int_V x_i x_j x_k dV = L_{i\alpha} L_{j\beta} L_{k\gamma} \int_V x_\alpha x_\beta x_\gamma dV = \lambda \det(L) \epsilon_{ijk}$$

but $\det(L) = -1$, hence $\lambda = 0$.

(c) We have $W_i = (\Omega_j \Omega_j + 2\beta x_j \Omega_j + \beta^2 x_j x_j) \Omega_i - (\Omega_j \Omega_j + \beta \Omega_j x_j)(\Omega_i + \beta x_i)$, then

$$\begin{aligned} \int_V W_i dV &= |\Omega|^2 \Omega_i \int_V dV + 2\beta \Omega_i \Omega \cdot \int_V \mathbf{x} dV + \beta^2 \Omega_i \int_V |\mathbf{x}|^2 dV \\ &\quad - |\Omega|^2 \Omega_i \int_V dV - \beta |\Omega|^2 \int_V x_i dV - \beta \Omega_i \Omega \cdot \int_V \mathbf{x} dV - \beta^2 \Omega_j \int_V x_i x_j dV \\ &= \beta^2 \Omega_i - \beta^2 \Omega_j \frac{4\pi a^5}{15} \delta_{ij} \\ &= \frac{8\pi}{15} a^5 \Omega_i \end{aligned}$$

Problem 8.17 (Normal Modes): Consider a system consisting of three particles of masses $m_1 = m$, $m_2 = \mu m$ and $m_3 = m$, connected in that order in a straight line by two equal light springs of force constant k .

- (a) (i) Write down the kinetic and potential energies of the system in terms of the coordinates of the particles $x_1(t)$, $x_2(t)$, $x_3(t)$. Write down the corresponding symmetric matrices for the kinetic and potential energies. [6]
(ii) Find the normal frequencies of the system and the corresponding normalised eigenvectors. Describe the physical motions associated with these normal modes. [7]
(b) Consider the particular case in which $\mu = 2$. Show that the three normal (angular) frequencies are 0, Ω , and $\sqrt{2}\Omega$ where you should specify Ω in terms of k and m . Show that the corresponding (unnormalised) eigenvectors are

$$\mathbf{x}^1 = (1, 1, 1)^T, \quad \mathbf{x}^2 = (1, 0, -1)^T, \quad \mathbf{x}^3 = (1, -1, 1)^T$$

Write down the orthogonality property of these eigenvectors with respect to the kinetic matrix. [3]

- (c) The masses are released from rest with initial displacements relative to their equilibrium positions of $x_1 = 2\epsilon$, $x_2 = -\epsilon$ and $x_3 = 0$, for some real constant ϵ . Determine their subsequent motions. [4]

Answer 8.17.

- (a) (i) The kinetic energy T and potential energy V are respectively

$$\begin{aligned} T &= \frac{1}{2} m \dot{x}_1^2 + \frac{1}{2} \mu m \dot{x}_2^2 + \frac{1}{2} m \dot{x}_3^2 = \frac{1}{2} \begin{pmatrix} \dot{x}_1 & \dot{x}_2 & \dot{x}_3 \end{pmatrix} \begin{pmatrix} m & 0 & 0 \\ 0 & \mu m & 0 \\ 0 & 0 & m \end{pmatrix} \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{pmatrix} := \frac{1}{2} \dot{\mathbf{x}}^T \mathcal{T} \dot{\mathbf{x}} \\ V &= \frac{1}{2} k (x_1 - x_2)^2 + \frac{1}{2} k (x_2 - x_3)^2 = \frac{1}{2} \begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} \begin{pmatrix} k & -k & 0 \\ -k & 2k & -k \\ 0 & -k & k \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} := \frac{1}{2} \mathbf{x}^T \mathcal{V} \mathbf{x} \end{aligned}$$

\mathcal{T} and \mathcal{V} are the desired symmetric matrices.

- (ii) We look for solutions of the form $\mathbf{x} = (x_1, x_2, x_3)^T e^{i\omega t}$, and this is equivalent to solving

$$\begin{aligned} 0 &= \det(\mathcal{V} - \omega^2 \mathcal{T}) \\ &= \det \begin{pmatrix} k - m\omega^2 & -k & 0 \\ -k & 2k - \mu m\omega^2 & -k \\ 0 & -k & k - m\omega^2 \end{pmatrix} \\ &= (k - m\omega^2)((2k - \mu m\omega^2)(k - m\omega^2) - 2k^2) \end{aligned}$$

which has solutions $\omega^2 = 0$, $\omega^2 = \frac{k}{m}$ and $\omega^2 = \frac{k}{m}(1 + \frac{2}{\mu})$. By inspection, the eigenvectors respectively are $(1, 1, 1)^T$, $(1, 0, -1)^T$ and $(1, -2/\mu, 1)^T$. Normalization is taken with an inner product with respect to the kinetic energy matrix $\text{diag}(m, \mu m, m)$. Thus, the modes are

- $\omega^2 = 0$: normalized eigenvector is $\frac{1}{\sqrt{m(2+\mu)}}(1, 1, 1)^T$, which correspond to a linear translation of the system at some constant velocity;
- $\omega^2 = \frac{k}{m}$: normalized eigenvector is $\frac{1}{\sqrt{2m}}(1, 0, -1)^T$, which correspond to the central mass being stationary and the outer two to oscillate in phase but with equal amplitudes;
- $\omega^2 = \frac{k}{m}(1 + \frac{2}{\mu})$: normalized eigenvector is $\frac{1}{\sqrt{m(2+\frac{4}{\mu})}}(1, -2/\mu, 1)^T$, which correspond to the outer two mass to oscillate in phase with equal amplitudes and central mass to oscillate in anti-phase with a relative amplitude of $\frac{2}{\mu}$.

(b) When $\mu = 2$:

- $\omega^2 = 0$: unnormalized eigenvector is $(1, 1, 1)^T$;
- $\omega^2 = \frac{k}{m}$: unnormalized eigenvector is $(1, 0, -1)^T$;
- $\omega^2 = \frac{2k}{m}$: unnormalized eigenvector is $(1, -1, 1)^T$.

where $\Omega = \sqrt{\frac{k}{m}}$. As mentioned, $\langle \mathbf{x}^i | \mathbf{x}^j \rangle_{\mathcal{T}}$, where $\mathcal{T} = m \text{diag}(1, 2, 1)$.

(c) The general displacement from equilibrium is

$$\mathbf{x}(t) = \begin{pmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{pmatrix} = (c_1 + c_2 t) \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \text{Re}[c_3 e^{i\Omega t}] \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \text{Re}[c_4 e^{i\sqrt{2}\Omega t}] \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

with initial conditions $\mathbf{x}(t=0) = (2\epsilon, -\epsilon, 0)^T$ and $\dot{\mathbf{x}}(t=0) = (0, 0, 0)^T$.

$$\begin{pmatrix} 2\epsilon \\ -\epsilon \\ 0 \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \text{Re}[c_3] \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \text{Re}[c_4] \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

Exploiting the orthogonality of the eigenvectors with respect to the matrix $\mathcal{T} = m \text{diag}(1, 2, 1)$,

$$c_1 \langle (1, 1, 1)^T | (1, 1, 1)^T \rangle_{\mathcal{T}} = \epsilon \langle (2, -1, 0)^T | (1, 1, 1)^T \rangle_{\mathcal{T}} \implies c_1 = 0$$

$$\text{Re}[c_3] \langle (1, 0, -1)^T | (1, 0, -1)^T \rangle_{\mathcal{T}} = \epsilon \langle (2, -1, 0)^T | (1, 0, -1)^T \rangle_{\mathcal{T}} \implies \text{Re}[c_3] 2 = 2\epsilon$$

$$\text{Re}[c_4] \langle (1, -1, 1)^T | (1, -1, 1)^T \rangle_{\mathcal{T}} = \epsilon \langle (2, -1, 0)^T | (1, -1, 1)^T \rangle_{\mathcal{T}} \implies \text{Re}[c_4] 4 = 4\epsilon$$

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = c_2 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \text{Re}[i\Omega c_3] \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \text{Re}[i\sqrt{2}\Omega c_4] \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

which gives $c_2 = 0$ and $c_3, c_4 \in \mathbb{R}$. Hence,

$$\mathbf{x}(t) = \epsilon \cos \Omega t \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \epsilon \cos \sqrt{2}\Omega t \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

Problem 8.18 (Group Theory):

- (a) Determine the elements of the cyclic group generated by the matrix

$$P = \begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix}$$

explicitly.

[6]

- (b) Construct the multiplication table of the following set of matrices, and verify that they form a group under matrix multiplication:

[6]

$$I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad A = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}$$

- (c) Prove that the set of elements of finite order in an Abelian group is a subgroup.

[8]**Answer 8.18.**

- (a) Evaluate
- P^2
- and
- P^3
- :

$$P^2 = \begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & -1 \end{pmatrix}, \quad P^3 = \begin{pmatrix} 0 & 1 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix} = -I$$

Hence, $P^6 = I$ and the group has order 6.

- (b) We see that
- $B^2 = C^2$
- ,
- $A = -I$
- ,
- $B = -C = AC = CA$
- and
- $C = -B = AB = BA$
- . We thus have
- $BC = BBA = BB(-I) = ABB = CB$
- and hence the group is abelian. The group table is

	I	A	B	C
I	I	A	B	C
A	A	I	C	B
B	B	C	I	A
C	C	B	A	I

Check the axioms of group for the set $\{I, A, B, C\}$:

- Closure: see group table.
- Associative: matrix multiplication is associative.
- Identity: I is the identity.
- Inverse: elements are its own inverse.

- (c) Let this proposed subgroup be
- H
- and the parent group be
- G
- . Check subgroup axioms:

- Closure: consider $h_i, h_j \in H$, then

$$h_i h_j = h_i h_j g = h_j h_i g = h_j g h_i = g h_i h_j$$

so $h_i h_j$ commutes with $g \in G$.

- Associativity: inherit from G .
- Identity: obviously commutes, i.e. $eg = ge \forall g \in H$, so $e \in H$.
- Inverse: for $h_i \in H$, $h_i g = g h_i \implies g h_i^{-1} = h_i^{-1} g$, and hence $h_i^{-1} \in H$. Of course, we need to check the order of h_i^{-1} . Say $\text{ord}(h_i) = p$ and $\text{ord}(h_i^{-1}) = q$, then compute $(h_i h_j)^{\text{lcm}(\text{ord}(h_i), \text{ord}(h_j))} = ee = e$, so p is a factor of q . Similarly, q is a factor of p . Hence, $p = q$, finite.

Problem 8.19 (Group Theory): Consider the set of matrices of the form

$$A = \begin{pmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{pmatrix}$$

where a, b, c are integers modulo 5 (for example $7 \bmod 5 = 2$).

- (a) Show they form a finite group G under matrix multiplication. Show that G has 125 elements. [7]
- (b) Show that the subset given by $a = c$ defines an Abelian subgroup H . Find the order of H and verify Lagrange's theorem. How many distinct left cosets of H are in G ? [7]
- (c) Find the set of all the elements of G whose square is the 3×3 identity matrix. Is the subset of G defined by $b \neq 0$ a subgroup of G ? [6]

Answer 8.19. Let \mathbb{Z}_5 be the set of integers modulo 5, i.e. $\{0, 1, 2, 3, 4\}$.

(a) Check axioms for group:

- Closure: For $A, A' \in G$, then

$$AA' = \begin{pmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & a' & b' \\ 0 & 1 & c' \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & a' + a & b' + ac' + b \\ 0 & 1 & c' + c \\ 0 & 0 & 1 \end{pmatrix}$$

- Associativity: matrix multiplication is associative.
- Identity: $a = b = c = 0 \in \mathbb{Z}_5 \implies A = I$.
- Inverse: We require $a' + a = 0$, $b' + ac' + b = 0$, $c' + c = 0$ where the operations are modulo 5. Such integers are in \mathbb{Z}_5 since \mathbb{Z}_5 is closed.

There are 5 possibilities for a , b and c each. There are thus 5^3 possibilities in total, so $|G| = 125$.

(b) When $a = c$,

$$AA' = \begin{pmatrix} 1 & a' + a & b' + aa' + b \\ 0 & 1 & a' + a \\ 0 & 0 & 1 \end{pmatrix}$$

Since $+$ and \times modulo 5 are symmetric, $AA' = A'A$, hence H is abelian. Check axioms for subgroup: largely unchanged since $a = c$ relaxes the restrictions of the form of the matrices. There are $5^2 = 25$ possibilities for the form of matrix, hence $|H| = 25$. Lagrange's theorem is satisfied since $\frac{|G|}{|H|} = 5 \in \mathbb{N}$, so there are 5 distinct cosets of H in G .

- (c) If $\exists g \in G$ such that $\text{ord}(g) = 2$, then $\langle g \rangle = \{I, g\}$. But Lagrange's theorem states that the size of a subgroup is a factor of the order of the parent group. As 2 is not a factor of 125, there are no elements of order 2 in G .

When $b \neq 0$, take for instance:

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{pmatrix}$$

which is not in the restricted set where $b \neq 0$, hence this is not closed and thus not a subgroup.

Problem 8.20 (Representation Theory):

- (a) Define a representation $D = \{D(X)\}$ of a group G and use the definition to prove that the matrix associated with the inverse of X is the inverse of the matrix associated with X . [4]
- (b) A group \mathcal{G} has four elements I, X, Y and Z , which satisfy $X^2 = Y^2 = Z^2 = XYZ = I$. Show that all elements commute with other elements. Deduce the form of the character table of the group \mathcal{G} . [9]
- (c) For which real numbers p do the matrices

$$D(I) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad D(X) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \quad D(Y) = \begin{pmatrix} -1 & p \\ 0 & 1 \end{pmatrix}, \quad D(Z) = \begin{pmatrix} 1 & p \\ 0 & -1 \end{pmatrix}$$

form a representation D of \mathcal{G} ? Find its characters. [7]

Answer 8.20.

- (a) A representation of G is a homomorphic map of the elements $g \in G$ to the set of invertible $n \times n$ matrices. $\forall g_i, g_j \in G$, we have the corresponding matrices $D(g_i)$ and $D(g_j)$ such that $D(g_i)D(g_j) = D(g_i g_j)$.

$$D(g_i)D(e) = D(g_i e) = D(g_i) \implies D(e) = I$$

Also, $D(g_i g_i^{-1}) = D(e)$ while LHS is $D(g_i)D(g_i)^{-1} = D(g_i)D(g_i^{-1})$ since D is a homomorphism.

- (b) Obviously, the identity I commutes with all elements. Check the rest:

$$I = X^2 = XYZ \implies X = YZ \implies YZYZ = I \implies ZY = YZ$$

$$XYZ = I \implies XYZXYZ = I \implies XYXY = I \implies XY = YX$$

Hence, the group is abelian. We thus see that every element must be in a conjugacy class of its own. Since the number of irreducible representation is equal to the number of conjugacy classes (4) and the sum of the squares of the dimensions of the irreducible representations is the size of the group (4), there will be four one-dimensional irreducible representations of \mathcal{G} .

The characters of the irreducible representations must be orthogonal and have mod-squared equal to the order of the group. For one-dimensional irreducible representations, the trace thus obey the group properties of the elements. We thus deduce the character table of \mathcal{G} to be:

	I	X	Y	Z
χ_1	1	1	1	1
χ_2	1	1	-1	-1
χ_3	1	-1	1	-1
χ_4	1	-1	-1	1

- (c) Evaluate:

$$D(X^2) = D(X)^2 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} = D(I) \implies X^2 = I$$

$$D(Y^2) = D(Y)^2 = \begin{pmatrix} -1 & p \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & p \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = D(I) \implies Y^2 = I$$

$$D(Z^2) = D(Z)^2 = \begin{pmatrix} 1 & p \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & p \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = D(I) \implies Z^2 = I$$

$$D(X)D(Y)D(Z) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} -1 & p \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & p \\ 0 & -1 \end{pmatrix} = D(I) = D(XYZ) \implies XYZ = I$$

All the properties of \mathcal{G} are preserved $\forall p$. This set of a matrices form a representation fo \mathcal{G} $\forall p$. The character of D is $\chi_D = \{2, -2, 0, 0\}$, which is a direct sum of χ_4 and χ_3 in part (b).

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9.1 Paper 1

Problem 9.1 (Vector Calculus):

- (a) Show that, for vector fields \mathbf{a} and \mathbf{b} in three dimensions, [4]

$$\mathbf{a} \cdot (\nabla \times \mathbf{b}) = \mathbf{b} \cdot (\nabla \times \mathbf{a}) - \nabla \cdot (\mathbf{a} \times \mathbf{b})$$

- (b) By applying the divergence theorem to a vector field $\mathbf{a} \times \mathbf{F}$, where \mathbf{a} is an arbitrary constant vector, show that

$$\int_V \nabla \times \mathbf{F} dV = - \int_S \mathbf{F} \times d\mathbf{S} \quad (*)$$

when S is the surface of a closed volume V . [4]

- (c) Suppose now that V is the hemisphere $\{|\mathbf{x}| \leq R, z \geq 0\}$ with $R > 0$, and $\mathbf{F} = (z, x^2 + y^2, 0)$ in Cartesian coordinates. Verify the equality in (*) by calculating both integrals and showing that they take the form

$$\begin{pmatrix} 0 \\ \alpha \\ 0 \end{pmatrix}$$

in Cartesian coordinates, for some constant α that you should determine. [12]

Answer 9.1.

- (a) Using suffix notation in Cartesian coordinates, $\nabla \cdot (\mathbf{a} \times \mathbf{b})$:

$$\frac{\partial}{\partial x_k} \epsilon_{ijk} a_i b_j = b_j \epsilon_{kij} \frac{\partial a_i}{\partial x_k} - a_i \epsilon_{kji} \frac{\partial b_j}{\partial x_k} \implies \nabla \cdot (\mathbf{a} \times \mathbf{b}) = (\nabla \times \mathbf{a}) \cdot \mathbf{b} - (\nabla \times \mathbf{b}) \cdot \mathbf{a}$$

- (b) Invoke divergence theorem to $\mathbf{a} \times \mathbf{F}$,

$$\int_S (\mathbf{a} \times \mathbf{F}) \cdot \hat{\mathbf{n}} dS = \int_V \nabla \cdot (\mathbf{a} \times \mathbf{F}) dV$$

But from part (a), $\nabla \cdot (\mathbf{a} \times \mathbf{F}) = \mathbf{F} \cdot (\nabla \times \mathbf{a}) - \mathbf{a} \cdot (\nabla \times \mathbf{F})$. Combine both results and rearrange the LHS of the resulting expression using suffix notation:

$$\epsilon_{ijk} a_i F_j dS_k = \epsilon_{jki} F_j dS_k a_i \implies (\mathbf{a} \times \mathbf{F}) \cdot d\mathbf{S} = (\mathbf{F} \times d\mathbf{S}) \cdot \mathbf{a}$$

But \mathbf{a} is a constant vector, so $\nabla \times \mathbf{a} = \mathbf{0}$ and can be pulled out of the integral. Also, since \mathbf{a} is arbitrary,

$$\int_S \mathbf{F} \times d\mathbf{S} = \mathbf{0} - \int_V \nabla \times \mathbf{F} dV$$

- (c) We have $\nabla \times \mathbf{F} = (0, 1, 2x)^T$. Take V to be $\{|\mathbf{x}| \leq R < z \leq 0\}$, then S is a union of the curved surface S' and the circular base S_0 . We have $S_0 = \{x^2 + y^2 \leq R^2, z = 0\}$. We have $\int_{S_0} \mathbf{F} \times d\mathbf{S} = \int_{S_0} (x^2 + y^2, -z, 0)^T dx dy$ and so for the equation to be consistent, only the $\hat{\mathbf{y}}$ component of the integrals are necessary. Hence,

$$\int_V (\nabla \times \mathbf{F}) \cdot \hat{\mathbf{y}} dV = - \int_{S'} (\mathbf{F} \times d\mathbf{S}) \cdot \hat{\mathbf{y}} - \int_{S_0} (\mathbf{F} \times d\mathbf{S}) \cdot \hat{\mathbf{y}} \implies \int_V dV = \frac{2}{3} \pi R^3 = \alpha$$

Problem 9.2 (Partial Differential Equation): Let $u(x, t)$ denote the displacement of a string that is stretched horizontally between $x = 0$ and $x = L > 0$, and fixed at these points such that $u(0, t) = u(L, t) = 0$. The displacement of the string is subject to a resistance that is proportional to its velocity. In terms of scaled variables, the displacement satisfies

$$\frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2} - 2\lambda \frac{\partial u}{\partial t}$$

where

$$\lambda = \frac{\pi}{L} \left(M + \frac{1}{2} \right)$$

is the resistance coefficient, and $M > 0$ is an integer.

- (a) By using separation of variables, write down ordinary differential equations for the spatial and temporal dependence of the displacement, respectively. [4]
- (b) The string is initially horizontal, and is subject to an impulsive initial velocity $\frac{\partial u}{\partial t} = f(x)$ at $t = 0$. Show that the general solution for the displacement can be written in the following form:

$$u(x, t) = e^{-\lambda t} \left[\sum_{n=1}^M A_n \sin(\alpha_n x) \sinh(\Omega_n t) + \sum_{n=M+1}^{\infty} A_n \sin(\alpha_n x) \sin(\omega_n t) \right]$$

Give expressions for each of α_n , Ω_n and ω_n , in terms of M and L . [8]

- (c) Suppose now that $L = \pi$ and $M = 3$. Calculate the coefficients A_n when $f(x) = e^{-x}$. [8]

[Hint: You may find it helpful to use integration by parts to generate a recurrence relation.]

Answer 9.2.

- (a) Since the boundary conditions are homogeneous, we use separation of variables $u(x, t) = X(x)T(t)$:

$$\frac{T''(t)}{T(t)} + 2\lambda \frac{T'(t)}{T(t)} = \frac{X''(x)}{X(x)} = -\mu^2$$

This gives two ordinary differential equations.

$$X''(x) = -\mu^2 X(x) \quad (\text{position})$$

$$T''(t) + 2\lambda T'(t) + \mu^2 T(t) = 0 \quad (\text{time})$$

- (b) Given $u(0, t) = u(L, t) = 0$, then $X(x) \sim \sin \frac{n\pi x}{L}$. We also have $T = -\lambda \pm \sqrt{\lambda^2 - \mu^2}$. The form of $T(t)$ depends on the value of $\lambda^2 - \mu^2 = \frac{\pi^2}{L^2} [(M + 0.5)^2 - n^2]$. The distinction between the two regimes is $n = M$, so we have

$$u(x, t) = e^{-\lambda t} \left[\sum_{n=1}^M A_n \sin \frac{n\pi x}{L} \sinh \sqrt{(M + 0.5)^2 - n^2} \frac{\pi t}{L} + \sum_{n=M+1}^{\infty} A_n \sin \frac{n\pi x}{L} \sin \sqrt{n^2 - (M + 0.5)^2} \frac{\pi t}{L} \right]$$

- (c) We have the initial condition to be $\frac{\partial u}{\partial t}|_{t=0} = f(x)$. We have

$$\frac{\partial u}{\partial t} = -\lambda u + e^{-\lambda t} \left[\sum_{n=1}^3 \Omega_n A_n \sin(nx) \cosh(\Omega_n t) + \sum_{n=4}^{\infty} A_n \omega_n \sin(nx) \cos(\omega_n t) \right]$$

where $M = 3$, $L = \pi$. The initial condition is

$$e^{-x} = \frac{\partial u}{\partial t} \Big|_{t=0} = -\lambda u(x, 0) + \sum_{n=1}^3 A_n \sin(nx) \Omega_n + \sum_{n=4}^{\infty} A_n \omega_n \sin(nx)$$

and so $A_{n \leq 3} = \frac{2}{\Omega_n L} \int_0^L e^{-x} \sin(nx) dx$ and $A_{n > 3} = \frac{2}{\omega_n L} \int_0^L e^{-x} \sin(nx) dx$. We define the following recurrence relation and evaluate it by integration of parts.

$$I_n = \int_0^\pi e^{-x} \sin(nx) dx = [-e^{-x} \frac{1}{n} \cos(nx)]_0^\pi - \frac{1}{n} \int_0^\pi e^{-x} \cos(nx) dx \implies (n^2 + 1)I_n = n[-e^{-\pi} \cos(n\pi) + 1]$$

We thus have

$$A_n = \frac{n}{1 + n^2} (1 + e^{-\pi} (-1)^{n+1}) \frac{4}{\pi \sqrt{49 - 4n^2}}$$

Problem 9.3 (Green's Functions):

- (a) Calculate the Green's function
- $G(x, \xi)$
- that satisfies

$$\frac{d^2 G}{dx^2} - G = \delta(x - \xi)$$

on the interval $0 \leq x < \infty$, subject to the boundary condition $G(0, \xi) = 0$, with G remaining bounded as $x \rightarrow \infty$. Hence write down, in integral form, the bounded solution $y(x)$ of [8]

$$\frac{d^2 y}{dx^2} - y = f(x), \quad 0 \leq x < \infty, \quad y(0) = 0 \quad (\dagger)$$

- (b) Consider now the problem

$$\frac{d^2 u}{dx^2} + \frac{2}{x} \frac{du}{dx} - u = g(x), \quad 0 \leq x < \infty \quad (*)$$

where $u(x)$ remains bounded throughout the domain.

- (i) Show, by means of the substitution $u = y/x$, that $(*)$ reduces to the form of (\dagger) . [2]
 (ii) Show further, using the Green's function calculated in part (a), or otherwise, that the solution of $(*)$ in the case

$$g(x) = \begin{cases} 0 & 0 \leq x < 1 \\ 1 & x \geq 1 \end{cases}$$

is

$$u(x) = \begin{cases} a(x) & 0 \leq x < 1 \\ -1 + Ae^{-x}/x & x \geq 1 \end{cases}$$

where the function $a(x)$ and constant A should be specified. [10]

Answer 9.3.

- (a) Away from $x = \xi$, $\frac{d^2 G(x, \xi)}{dx^2} = G(x, \xi)$, so $G(x, \xi)$ is either exponential or hyperbolic, i.e.

$$G(x, \xi) = \begin{cases} A(\xi) \sinh(x) + B(\xi) \cosh(x) & 0 \leq x < \xi < \infty \\ C(\xi)e^x + D(\xi)e^{-x} & 0 \leq \xi < x < \infty \end{cases}$$

We have $G(0, \xi) = 0 \implies B = 0$ and G bounded as $x \rightarrow \infty \implies C = 0$. Integrate over an infinitesimal region centred at $x = \xi$,

$$\lim_{\epsilon \rightarrow 0} \left(\left[\frac{\partial G(x, \xi)}{\partial x} \right]_{\xi-\epsilon}^{\xi+\epsilon} + [G]_{\xi-\epsilon}^{\xi+\epsilon} + 2\epsilon G \right) = \delta(\xi - x)$$

G has to be continuous everywhere, otherwise $G'' \propto \delta'(x - \xi)$ which is a contradiction. At $\mu = \xi$, we obtain the jump condition $[\frac{\partial G(x, \xi)}{\partial x}]_{-}^{+} = 1$. At ξ , the continuity and jump conditions respectively give

$$A(\xi) \sinh \xi = D(\xi)e^{-\xi}$$

$$-D(\xi)e^{-\xi} - A(\xi) \cosh \xi = 1$$

$$\begin{pmatrix} e^{-\xi} & -\sinh \xi \\ -e^{-\xi} & -\cosh \xi \end{pmatrix} \begin{pmatrix} D(\xi) \\ A(\xi) \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \implies \begin{pmatrix} D(\xi) \\ A(\xi) \end{pmatrix} = \frac{1}{-e^{-\xi}(\cosh \xi + \sinh \xi)} \begin{pmatrix} -\cosh \xi & \sinh \xi \\ e^{-\xi} & e^{-\xi} \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

We thus have

$$G(x, \xi) = \begin{cases} -e^{-\xi} \sinh(x) & 0 \leq x < \xi < \infty \\ -e^{-x} \sinh \xi & 0 \leq \xi < x < \infty \end{cases}$$

The general solution will be

$$y(x) = \int_0^\infty f(\xi) G(x, \xi) d\xi = -e^{-x} \int_0^x f(\xi) \sinh \xi d\xi - \sinh x \int_x^\infty e^{-\xi} f(\xi) d\xi$$

(b) (i) $u = \frac{y}{x}$ will mean

$$g(x) = \frac{d^2 u}{dx^2} + \frac{2}{x} \frac{du}{dx} - u = -\frac{2}{x^2} \frac{dy}{dx} + \frac{1}{x} \frac{d^2 y}{dx^2} + \frac{2}{x^3} y + \frac{2}{x} \left(\frac{1}{x} \frac{dy}{dx} - \frac{1}{x^2} y \right) - \frac{y}{x} \implies \frac{d^2 y}{dx^2} - y = xg(x)$$

where $f(x) = xg(x)$.

(ii) We have from part (a):

$$u(x) = -\frac{e^{-x}}{x} \int_0^x f(\xi) \sinh \xi d\xi - \frac{\sinh x}{x} \int_x^\infty e^{-\xi} f(\xi) d\xi$$

We will consider the two different ranges of x separately. For $0 \leq x < 1$, $0 < \xi < x < 1 \implies f(\xi) = 0$, $x < 1 < \xi < \infty \implies f(\xi) = \xi$ and $x < \xi < 1 \implies f(\xi) = 0$, so

$$u(x) = -\frac{\sinh x}{x} \int_1^\infty \xi e^{-\xi} d\xi = \frac{1}{x} \sinh x [e^{-\xi}(\xi + 1)]_1^\infty = -\frac{2}{xe} \sinh x$$

For $x \geq 1$, $0 < \xi < 1 < x \implies f(\xi) = 0$, $0 < 1 < \xi < x \implies f(\xi) = \xi$ and $1 \leq x < \xi < \infty \implies f(\xi) = \xi$, so

$$\begin{aligned} u(x) &= -\frac{e^{-x}}{x} \int_1^x \xi \sinh \xi d\xi - \frac{\sinh x}{x} \int_x^\infty e^{-\xi} \xi d\xi \\ &= \frac{\sinh x}{x} [e^{-\xi}(\xi + 1)]_x^\infty - \frac{e^{-x}}{x} [\xi \cosh \xi - \sinh \xi]_1^x \\ &= -1 + \frac{e^{-x}}{xe} \end{aligned}$$

Hence, $a(x) = -\frac{2}{xe} \sinh x$ and $A = e^{-1}$.

Problem 9.4 (Fourier Transform): The Fourier transform of a function $f(t)$ is given by

$$\tilde{f}(\omega) = \int_{-\infty}^{\infty} f(t)e^{-i\omega t} dt$$

- (a) What is the Fourier transform of $\tilde{f}(t)$ in terms of f (the duality property)? [2]
- (b) What is the Fourier transform of $f(bt)$ in terms of \tilde{f} , where b is a constant (the scaling property)? [2]
- (c) Derive the Fourier transform of $g(t) = e^{-\alpha t}u(t)$, where $u(t) = 0$ for $t < 0$ and $u(t) = 1$ for $t \geq 0$, and α is a constant. [3]
- (d) Using the linearity property of the Fourier transform, together with parts (b) and (c), determine the Fourier transform of $h(t) = e^{-\alpha|t|}$. [3]
- (e) Use parts (a) and (d) to determine the Fourier transform of $s(t) = (1 + t^2)^{-1}$. [3]
- (f) Find the Fourier transform of $v(t, T) = \frac{1}{2}(u(t + T) - u(t - T))$, where u is defined in part (c) and T is a constant. [3]
- (g) A signal $z(t)$ is given by

$$z(t) = \frac{\sin(t)}{\pi t} + \frac{\sin(2t)}{\pi t}$$

Plot the graph of $|\tilde{z}(\omega)|^2$ versus ω and use Parseval's theorem to find the energy E of the signal $z(t)$ defined as [4]

$$E = \int_{-\infty}^{\infty} |z(t)|^2 dt$$

Answer 9.4.

(a) $f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{f}(\omega)e^{i\omega t} d\omega$

(b) Substitute $u = bt$ for $b > 0$,

$$\tilde{f}(\omega) = \int_{-\infty}^{\infty} f(bt)e^{-i\omega t} dt = \int_{-\infty}^{\infty} f(u)e^{-i\omega u/b} b^{-1} du = \frac{1}{b} \tilde{f}(\omega/b)$$

Repeat for $b < 0$, and we get a negative sign. So, $\tilde{f}(\omega) = \frac{1}{|b|} \tilde{f}(\omega/b)$.

(c) As long as $\text{Re}[\alpha] > 0$, the integral will converge and the Fourier transform exists, and is

$$\tilde{g}(\omega) = \int_0^{\infty} e^{-\alpha t} e^{-i\omega t} dt = \left[\frac{e^{-(\alpha + i\omega)t}}{-(\alpha + i\omega)} \right]_0^{\infty} = \frac{1}{\alpha + i\omega}$$

(d) The Fourier transform of $h(t)$ is $\tilde{h}(t) = \mathcal{F}[g(t)] + \mathcal{F}[g(-t)] = \frac{1}{\alpha + i\omega} + \frac{1}{\alpha - i\omega} = \frac{2\alpha}{\alpha^2 + \omega^2}$.

(e) Let $v(\omega) = \mathcal{F}[s(t)]$, we have $s(t) = \frac{1}{1+t^2} = \frac{1}{2} \tilde{h}(t)$ and so

$$v(\omega) = \frac{1}{2} \mathcal{F}[\tilde{h}(t)] = \frac{2}{2} \pi e^{-|\omega|} = \pi e^{-|\omega|}$$

(f) $v(t, T) = \frac{1}{2}(u(t + T) + u(T - t)) = \text{rect}(t/T)$. So,

$$\tilde{v}(\omega, T) = \int_{-\infty}^{\infty} v(t) e^{-i\omega t} dt = \int_{-T}^T e^{-i\omega t} dt = \frac{2 \sin \omega T}{\omega}$$

(g) The Fourier transform of $z(t)$ is

$$\tilde{z}(\omega) = \int_{-\infty}^{\infty} \left[\frac{\sin t}{\pi t} + \frac{\sin 2t}{\pi t} \right] e^{-i\omega t} dt = \int_{-\infty}^{\infty} [\tilde{v}(t, 1) + \tilde{v}(t, 2)] \frac{e^{-i\omega t}}{2\pi} dt = v(\omega, 1) + v(\omega, 2)$$

which is 1 for $1 \leq |t| < 2$ and 2 for $|t| \leq 1$ and zero otherwise. The energy is computed using Parseval's theorem:

$$E = \int_{-\infty}^{\infty} |z(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |\tilde{z}(\omega)|^2 d\omega = \frac{1}{2\pi} (1^2 + 2 \times 4 + 1^2) = \frac{5}{\pi}$$

where the integration was computed by finding the area under the curve.

Problem 9.5 (Linear Algebra): Given a square matrix A we define the matrix exponential via the formula:

$$e^A = I + \sum_{k=1}^{\infty} \frac{1}{k!} A^k$$

where I is the identity matrix.

- (a) Show that for any invertible matrix P , $e^{(PAP^{-1})} = Pe^AP^{-1}$. [6]
- (b) Show that if A is skew-Hermitian, then $e^A = QCQ^\dagger$ where Q is a unitary matrix, and C is a diagonal matrix with complex numbers of unit modulus on the diagonal. Deduce that e^A is unitary. [7]
- (c) Show that if A is Hermitian, then e^A is a Hermitian matrix with positive eigenvalues. [7]

Answer 9.5.

- (a) Using the definition of matrix exponential:

$$e^{PAP^{-1}} = I + \sum_{k=1}^{\infty} \frac{1}{k!} (PAP^{-1})^k = I + \sum_{k=1}^{\infty} \frac{1}{k!} PA^k P^{-1} = P \left(I + \sum_{k=1}^{\infty} \frac{A^k}{k!} \right) P^{-1} = Pe^AP^{-1}$$

- (b) Firstly, we show the eigenvalues of A are purely imaginary and eigenvectors corresponding to distinct eigenvalues are orthogonal. Let $\{e_i\}$ be the eigenvectors of A .

$$0 = \langle e_j | e_i \rangle - (A|e_j\rangle)^\dagger |e_i\rangle = \langle e_j | Ae_i \rangle - \langle (-A)e_j | e_i \rangle = (\lambda_i + \lambda_j^*) \langle e_j | e_i \rangle$$

where $A = -A^\dagger$ is skew-Hermitian. If $j = i$, and since the norm $\langle e_i | e_i \rangle > 0$, so $\lambda_i = -\lambda_i^*$ and hence purely imaginary. If $j \neq i$, and since the eigenvalues are distinct $\lambda_j^* \neq -\lambda_i$, we have $\langle e_j | e_i \rangle = 0$.

Now, consider the action of e^A on an arbitrary vector $\mathbf{v} = \sum_{p=1}^n \alpha_p \mathbf{e}_p$ (the eigenvectors form a basis for the vector space). Then

$$e^A \mathbf{e}_i = \left(1 + \sum_{k=1}^{\infty} \frac{\lambda_i^k}{k!} \right) \mathbf{e}_i = e^{\lambda_i} \mathbf{e}_i \implies e^A \mathbf{v} = \sum_{p=1}^n \alpha_p e^{\lambda_p} \mathbf{e}_p = \sum_{p=1}^n \mathbf{e}_p^\dagger \mathbf{e}_p e^{\lambda_p} \mathbf{v}$$

In this frame, $e^A = \sum_{p=1}^n \mathbf{e}_p e^{\lambda_p} \mathbf{e}_p^\dagger$ with entries e^{λ_p} on the diagonal entries. To view a matrix in any other frame, say $\{\mathbf{e}'_j\}$, we need the transformation matrix $M' = QMQ^\dagger$ where $Q_{ij} = \mathbf{e}_i^\dagger \mathbf{e}'_j$, so $e^A = QCQ^\dagger$. Finally,

$$e^A (e^A)^\dagger = \sum_{p=1}^n \mathbf{e}_p e^{\lambda_p} \mathbf{e}_p^\dagger \sum_{q=1}^n (\mathbf{e}_q^\dagger)^\dagger e^{\lambda_q^*} \mathbf{e}_q^\dagger = \sum_{p,q} e^{\lambda_p + \lambda_q^*} \mathbf{e}_p \mathbf{e}_p^\dagger \mathbf{e}_q^\dagger \mathbf{e}_q = \sum_{p,q} e^{\lambda_p + \lambda_q^*} \mathbf{e}_p \delta_{pq} \mathbf{e}_q^\dagger = \sum_{p=1}^n \mathbf{e}_p \mathbf{e}_p^\dagger = I$$

where we established that $\lambda_p + \lambda_p^* = 0$.

- (c) With a similar approach, we show the eigenvalues of A are purely real, i.e. $\lambda_i = \lambda_i^* \in \mathbb{R}$ and eigenvectors corresponding to distinct eigenvalues are orthogonal. If A is Hermitian, then by the definition of matrix exponential, e^A is Hermitian as well, with eigenvalues e^{λ_p} . Since $\lambda_p \in \mathbb{R}$, $e^{\lambda_p} \in \mathbb{R}^+$.

Problem 9.6 (Linear Algebra):

(a) State the definition of a diagonalizable matrix. Give an example of a 2×2 diagonalizable matrix, and an example of a 2×2 non-diagonalizable matrix. [5]

(b) Find the eigenvalues of the following symmetric matrix: [6]

$$M = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \\ 3 & 1 & 2 \end{pmatrix}$$

[Hint: Consider the matrix vector product $M(1, 1, 1)^T$.

(c) Show that the set of $x = (x_1, x_2, x_3)$ that satisfy $x^T M x = 0$ and $x_1 + x_2 + x_3 = 0$ consists of two infinite lines, where M is the matrix from part (b) (you do not need to find the equations of these lines). [9]

[Hint: Write $M = PDP^T$ with D diagonal, and $P = (\mathbf{u}_1 \ \mathbf{u}_2 \ \mathbf{u}_3)$ where $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ are the eigenvectors of M .]

Answer 9.6.

(a) A matrix M is diagonalizable if there exists an invertible matrix P such that PMP^T only has non-zero entries on the diagonal.

For example, $\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$ is diagonalizable but $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ is non-diagonalizable.

(b) Since each row sum to 6, $(1, 1, 1)^T$ is clearly an eigenvector of M with eigenvalue 6. The trace and determinants of M are 6 and -18 respectively. Let the other two eigenvalues be $\pm\alpha$ (since $6 = 6 + \alpha - \alpha$), then $6\alpha^2 = 18 \implies \alpha = \pm\sqrt{3}$. The eigenvalues of M are $\{6, +\sqrt{3}, -\sqrt{3}\}$.

(c) We have

$$0 = x^T M x = x^T P D P^T x, \quad P^T x = \begin{pmatrix} p \\ q \\ r \end{pmatrix}, \quad D = \text{diag}(6, \sqrt{3}, -\sqrt{3})$$

and we must have $0 = 6p^2 + \sqrt{3}q^2 - \sqrt{3}r^2$. With the constraint $x_1 + x_2 + x_3 = 0 \implies \mathbf{x} \cdot \mathbf{u}_1 = 0$, then we must have $p = 0$ and $q = \pm r$, where $q = \mathbf{x} \cdot \hat{\mathbf{u}}_2$ and $r = \mathbf{x} \cdot \hat{\mathbf{u}}_3$. In the eigenbasis of M , we have the lines

$$p = 0, \quad q = \pm r$$

Problem 9.7 (Cauchy-Riemann):

- (a) Let
- $f(z) = u(x, y) + iv(x, y)$
- be an analytic function of
- $z = x + iy$
- for real
- x, y, u, v
- .

Prove that u and v satisfy the Cauchy-Riemann equations

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}, \quad \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$$

Define a harmonic function.

Verify that $u(x, y) = \ln(x^2 + y^2)$ defined on the complex plane with the origin removed is harmonic and find a conjugate harmonic function $v(x, y)$ (i.e. v such that $u + iv$ is analytic).**[8]**

- (b) Find a power-series expansion of the function
- $f(z) = (3 - z)^{-1}$
- about the point
- $z = 4i$
- , and calculate the radius of convergence.
- [5]**

- (c) Find a power-series expansion of the function
- $g(z) = (1 - z^2) \exp(1/z)$
- about
- $z = 0$
- . Determine whether
- $z = 0$
- is a pole or an essential singularity. Compute the residue at
- $z = 0$
- .
- [7]**

Answer 9.7.

- (a) A function is analytic if its complex derivative

$$\frac{df}{dz} := \lim_{\Delta z \rightarrow 0} \frac{f(z + \Delta z) - f(z)}{\Delta z}$$

exists and is independent of the direction of approach of $\Delta z \rightarrow 0$ in the complex plane. So, take any two orthogonal directions Δx and $i\Delta y$.

$$\lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x + iy) - f(x + iy)}{\Delta x} = \lim_{\Delta y \rightarrow 0} \frac{f(x + i(y + \Delta y)) - f(x + iy)}{i\Delta y} \implies \frac{\partial u}{\partial x} + i\frac{\partial v}{\partial x} = -i\frac{\partial u}{\partial y} + \frac{\partial v}{\partial y}$$

This is the Cauchy-Riemann equations, which must be satisfied for any analytic function f .A harmonic function f satisfies the Laplace's equation $\nabla^2 f = 0$.

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + i\frac{\partial^2 v}{\partial x^2} + i\frac{\partial^2 v}{\partial y^2} = \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial y} \right) + i \left(\frac{\partial}{\partial x} \left(\frac{\partial v}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial v}{\partial y} \right) \right)$$

which is zero after using the Cauchy-Riemann equations. Given $u = \ln(x^2 + y^2)$, we have $\frac{\partial^2 u}{\partial x^2} = \frac{-2x^2 + 2y^2}{(x^2 + y^2)^2}$ and $\frac{\partial^2 u}{\partial y^2} = \frac{2x^2 - 2y^2}{(x^2 + y^2)^2}$ and so $\nabla^2 u = 0$ indeed. To find v , we exploit Cauchy-Riemann equations. We thus have $v = \int \frac{2x}{x^2 + y^2} dy = 2 \tan^{-1}(y/x) + C$, where C is some constant.

- (b) Expand
- $f(z)$
- about
- $z = 4i$
- . Let
- $z - 4i = w$
- ,

$$f(w) = (3 - w - 4i)^{-1} = (3 - 4i)^{-1} \left(1 - \frac{w}{3 - 4i} \right)^{-1} = \frac{1}{3 - 4i} \sum_{n=0}^{\infty} (-1)^n \left(\frac{w}{3 - 4i} \right)^n$$

Using ratio test for $u_n(w) = (-1)^n \left(\frac{w}{3 - 4i} \right)^n$ for $n \geq 0$:

$$1 = \lim_{n \rightarrow \infty} \left| \frac{u_{n+1}(R)}{u_n(R)} \right| = \lim_{n \rightarrow \infty} \left| \frac{(-1)R}{3 - 4i} \right| = \frac{R}{5}$$

so the radius of convergence is 5. This is also equal to the distance to the nearest pole $z = 3$ from the expansion of point of $z = 4i$, i.e. $\sqrt{4^2 + 3^2} = 5$.

- (c) Expand
- $g(z) = (1 - z^2)e^{1/z}$
- about
- $z = 0$
- for
- $n \geq 0$
- :

$$g(z) = (1 - z^2) \sum_{n=0}^{\infty} \frac{z^{-n}}{n!} = -z^2 - z + \sum_{n=0}^{\infty} \left[\frac{1}{n!} - \frac{1}{(n+2)!} \right] z^{-n} = -z^2 - z + \sum_{n=0}^{\infty} \left(1 - \frac{1}{(n+2)(n+1)} \right) z^{-n}$$

Consider $\lim_{z \rightarrow 0} z^N g(z)$ which is not finite for any finite N value, so the point $z = 0$ is an essential singularity. The residue at $z = 0$ is the coefficient of z^{-1} , which is $1 - \frac{1}{3 \times 2} = \frac{5}{6}$.

Problem 9.8 (Series Solution to ODE): Consider the second-order differential equation:

$$2x^2y'' - xy' + (1+x)y = 0$$

(a) Show that $x = 0$ is a regular singular point. [2]

(b) Consider a solution of the form

$$y(x) = x^\sigma \sum_{n=0}^{\infty} a_n x^n, \quad (a_0 \neq 0)$$

Determine the two possible values of σ for such a solution to exist. [6]

(c) For each value of σ determine the recursion relations satisfied by the a_n . Solve the recursion relations and express a_n in terms of a_0 in each case. [8]

(d) Find the radius of convergence of the power series solutions in each case. [4]

Answer 9.8.

(a) $-\frac{1}{2x}$ and $\frac{1+x}{2x^2}$ are not analytic at $x = 0$ but $-\frac{x}{2x}$ and $\frac{1+x}{2x^2}x^2$ are analytic at $x = 0$, hence $x = 0$ is a regular singular point.

(b) With the suggested series solution, the recurrence relation is

$$0 = \sum_{n=0}^{\infty} [2(n+\sigma)(n+\sigma-1) - (n+\sigma) + 1] a_n x^{n+\sigma} + \sum_{n=0}^{\infty} a_n x^{n+\sigma+1} \implies a_n = a_{n-1} \frac{1}{(n+\sigma)(3-2(n+\sigma)) - 1}$$

Comparing the x^σ terms, gives the indicial equation $(2\sigma(\sigma-1) - \sigma + 1)a_0 = 0 \implies (2\sigma^2 - 3\sigma + 1) = 0 \implies \sigma = 1$ or $\frac{1}{2}$, since $a_0 \neq 0$.

(c) For $\sigma = 1$ and $\frac{1}{2}$ respectively,

$$\begin{aligned} a_{n+1} &= a_n \frac{1}{(n+2)(3-2(n+2)) - 1} \\ &= -\frac{a_n}{(n+1)(2n+3)} \\ &= \frac{-1}{(n+1)(2n+3)} \frac{-1}{n(2n-1)} a_{n-1} \\ &= \frac{(-1)^n a_0}{(n+1)! \frac{(2n+3)!}{(2n+2)(2n)(2n-2)\dots}} \\ &= \frac{(-2)^n}{(2n+3)!} a_0 \end{aligned}$$

$$\begin{aligned} a_{n+1} &= \frac{-a_n}{(2n+3)n+1} \\ &= \frac{-2}{(n+1)(2n+1)} a_n \\ &= \frac{-2}{(n+1)(2n+1)} \frac{-2}{n(2n-1)} a_{n-1} \\ &= \frac{(-2)^n}{(n+1)! \frac{(2n+1)!}{2n(2n-2)(2n-4)\dots}} a_0 \\ &= \frac{(-1)^n 2^{2n+1}}{(n+1)(2n+1)!} a_0 \end{aligned}$$

(d) For the series to converge, $\lim_{n \rightarrow \infty} \left| \frac{a_{n+2}}{a_n} \right| |x| < 1 \quad \forall |x| < 1$. The radius of convergence is thus

$$R = \lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| = \lim_{n \rightarrow \infty} [(n+\sigma)(3-2(n+\sigma)) - 1] = \infty$$

The radius of convergence is no smaller than the distance from $x = 0$ to the next nearest singular point.

Problem 9.9 (Variational Principle):

- (a) State the Euler–Lagrange equation for the extrema of the functional

$$T[y] = \int_a^b f(x, y, y') dx$$

Write down the integral of the Euler–Lagrange equation if $f = f(x, y')$ does not depend explicitly on $y(x)$. [3]

- (b) Light travels in a plane with refractive index
- $\mu(x)$
- , given in a piecewise manner by

$$\mu^2 = \begin{cases} 1 + (1 - x)^{2/3} & x < 0 \\ 2 + x & x \geq 0 \end{cases}$$

A light ray is fired from a point $(x, y) = (-\alpha, 0)$, where α is a positive constant, and is picked up by a receiver on the line $x = \alpha$. The travel time of the ray along a path $y(x)$ is given by the functional

$$T[y] = \int_{-\alpha}^{\alpha} \mu(x) \sqrt{1 + y'^2} dx$$

Suppose that the ray crosses $x = 0$ with a slope $y' = 1$.

- (i) Determine a piecewise expression for the slope $y'(x)$ of the path of least time for the ray. [4]
- (ii) Hence calculate the path of least time $y(x)$ in terms of α . [4]
- (iii) Suppose that the slope of the light ray at the receiver $x = \alpha$ is half of its initial slope. Determine the value of α in this case. [2]
- (iv) Suppose instead that the light ray is fired with an initial slope $y' = 1/2$. Determine the value of α in this case, and find and sketch the path of the light ray. At what value of y does the ray hit the receiver? [7]

Answer 9.9.

(a) The Euler–Lagrange equation is $\frac{d}{dx} \frac{\partial f}{\partial y'} = \frac{\partial f}{\partial y}$. The first integral is $\frac{\partial f}{\partial y'}$ is constant.

- (b) (i) Observe that the integrand in $T[y]$ is independent of y , hence by part (a), $k = \frac{\partial}{\partial y'} \mu \sqrt{1 + y'^2} = \frac{\mu y'}{\sqrt{1 + y'^2}}$. Then, we must have $y' = \frac{k}{\sqrt{\mu^2 - k^2}}$ (where the \pm sign is absorbed into the constant k). Then,

$$y'(x) = \begin{cases} \frac{k}{\sqrt{1 + (1 - x)^{2/3} - k^2}} & x < 0 \\ \frac{k}{\sqrt{2 + x - k^2}} & x \geq 0 \end{cases}$$

- (ii) We have $y'(x = 0) = 1 \implies 1 = \frac{k}{\sqrt{2 - k^2}} \implies k = 1$ and so the path of least time is

$$y(x) = \begin{cases} -\frac{3}{2}(1 - x)^{2/3} + c_1 & x < 0 \\ 2\sqrt{1 + x} + c_2 & x \geq 0 \end{cases}$$

But, $y = 0 \implies x = -\alpha$, and so $0 = -\frac{3}{2}(1 + \alpha)^{2/3} + c_1$. Also, continuity at $x = 0$ gives

$$2 + c_2 = -\frac{3}{2} + \frac{3}{2}(1 + \alpha)^{2/3} \implies c_2 = -\frac{7}{2} + \frac{3}{2}(1 + \alpha)^{2/3}$$

$$y(x) = \begin{cases} -\frac{3}{2}(1 - x)^{2/3} + \frac{3}{2}(1 + \alpha)^{2/3} & x < 0 \\ 2\sqrt{1 + x} + \frac{3}{2}(1 + \alpha)^{2/3} - \frac{7}{2} & x \geq 0 \end{cases}$$

- (iii) Given $y'(x = \alpha > 0) = \frac{1}{2}y'(x = 0)$, then $\frac{1}{2} \frac{1}{\sqrt{1 + \alpha}} = \frac{1}{\sqrt{1 + \alpha}} \implies \alpha = 3$.

- (iv) Suppose $y'(x = -\alpha) = \frac{1}{2}$ instead, then $\frac{1}{2} = \frac{1}{\sqrt{(1 + \alpha)^{2/3}}} \implies \alpha = 7$.

$$y(x) = \begin{cases} -\frac{3}{2}(1 - x)^{2/3} + 6 & x < 0 \\ 2\sqrt{1 + x} + \frac{5}{2} & x \geq 0 \end{cases}$$

At $x = \alpha = 7$, we have $y = 4\sqrt{2} + \frac{5}{2}$.

Problem 9.10 (Rayleigh-Ritz Method): A plate with thermal diffusivity $\kappa(r)$ occupies the region $r \leq 1$, where r is the radial polar co-ordinate. The temperature $T(r, t)$ of the plate is axisymmetric and satisfies

$$\frac{\partial T}{\partial t} = \frac{1}{r} \frac{\partial}{\partial r} \left(r \kappa(r) \frac{\partial T}{\partial r} \right)$$

with $T = 0$ at $r = 1$.

- (a) By looking for separable solutions of the form $T = e^{-\nu t} R(r)$, find an ordinary differential equation satisfied by $R(r)$. Write this equation in Sturm–Liouville form and identify the weight function. [3]

- (b) Assuming that $R(r)$ and $\kappa(r)$ remain finite for $r \leq 1$, show that [4]

$$\nu \int_0^1 r R^2 dr = \int_0^1 r \kappa(r) |R'|^2 dr \quad (*)$$

- (c) Explain briefly why (*) can be used to generate an upper bound for the decay rate ν of the fundamental mode. [You may quote the Euler–Lagrange equation without proof.] [4]

- (d) Suppose now that $\kappa(r) = r^n$, with $n \geq 0$.

- (i) Using the trial function $R_{\text{trial}}(r) = 1 - r^q$ with $q > 0$, find an upper bound R_{trial} for the decay rate of the fundamental mode as a function of q and n . [4]

- (ii) If $n = 0$, determine the value of q that yields the best possible bound ν_{trial} , and give the value of that bound. Given that the corresponding trial temperature profile is $T_{\text{trial}}(r, t) = e^{-\nu_{\text{trial}} t} R_{\text{trial}}(r)$, sketch $T_{\text{trial}}(r, 0)$ and $T_{\text{trial}}(0, t)$. [5]

Answer 9.10.

- (a) $-r\nu R = \frac{\partial}{\partial r}(\kappa(r)rR')$. This is of SL form with operator $\mathcal{L} = -\frac{d}{dr}(r\kappa(r)\frac{d}{dr})$ such that $\mathcal{L}R = \nu rR$, hence the weight function is $w = r$ and the eigenvalue is ν .

- (b) Using \mathcal{L} from part (a)

$$\nu \int_0^1 R^* r R dr = - \int_0^1 R^* \frac{d}{dr} (r \kappa(r) R') dr = [-\kappa(r) r R' R]_0^1 + \int_0^1 \kappa(r) r |R'|^2 dr = 0 + \int_0^1 \kappa(r) r |R'|^2 dr$$

where the boundary term vanishes since $R(r)$ finite at $r = 0$ and $T(r = 1, t) = 0 \implies R(1) = 0$.

- (c) Define the Rayleigh quotient to be $\Lambda[y] = \frac{\langle y | \mathcal{L} y \rangle}{\langle y | y \rangle_w} = \frac{F[y]}{G[y]}$. From part (b), $\Lambda[R] = \nu$. The stationary values of $\Lambda[y]$ will correspond to the eigenvalues of \mathcal{L} with the given boundary conditions. Now, since $\kappa \geq 0$ (otherwise physically not realistic), $G[y] = \int_0^1 r |y|^2 dr \geq 0$ and from part (b) $F[y] = 0 + \int_0^1 r |y'|^2 dr \geq 0$, then $\Lambda[y] \geq 0$. The global minimum of Λ corresponds to the smallest value of ν , with decay time $\tau = \frac{1}{\nu}$ of the lowest mode. Consider

$$\delta \Lambda = \frac{\delta F}{G} - \frac{F}{G^2} \delta G = \frac{1}{G} (\delta F - \Lambda \delta G)$$

where the stationary value of Λ is λ , then for Λ to be stationary, $F = \lambda G$ must be true. To extremize $F - \lambda G$, the integrand $f(y, y'; x) = y'^* r y' - \lambda y^* r y$ must satisfy the Euler–Lagrange equation

$$0 = \frac{d}{dr} \frac{\partial f}{\partial y'^*} - \frac{\partial f}{\partial y} = \frac{d}{dr} (r y') = -\lambda r y$$

which we recover the SL equation as expected. Hence, any value of $\Lambda[y]$ will be an overestimate of ν_{\min} as long as y_{trial} obeys the boundary conditions.

- (d) (i) $R_{\text{trial}} = 1 - r^q$, $R'_{\text{trial}} = -q r^{q-1}$, $\kappa(r) = r^n$:

$$\nu_{\text{trial}} = \frac{F[R_{\text{trial}}]}{G[R_{\text{trial}}]} = \frac{\int_0^1 r r^n q^2 r^{2q-2} dr}{\int_0^1 r (1 - r^q)^2 dr} = \frac{q^2}{2q+n} \frac{2(q+1)(q+2)}{q^2} = \frac{2(q^2 + 3q + 2)}{2q+n}$$

- (ii) $n = 0$: $\nu_{\text{trial}} = q + 3 + 2q^{-1}$. $\frac{d\nu_{\text{trial}}}{dq} = 0 \implies q = \sqrt{2} \implies \nu_{\text{trial}} = 2\sqrt{2} + 3$. Hence, $T_{\text{trial}}(r, 0) = 1 - r^{\sqrt{2}}$ and $T_{\text{trial}}(0, t) = e^{-(2\sqrt{2}+3)t}$.

9.2 Paper 2

Problem 9.11 (Sturm-Liouville): Consider the eigenvalue problem

$$-(1-x^2)y'' + xy' = n^2y, \quad -1 \leq x \leq 1 \quad (*)$$

where $n \geq 0$ is an integer.

- (a) Rewrite equation (*) in Sturm-Liouville form and determine the weight function $w(x)$. Show that any two eigenfunctions y_n and y_m of (*) with $n \neq m$ satisfy the orthogonality condition

$$\int_{-1}^1 w(x)y_n(x)y_m(x)dx = 0$$

provided the y_n and their derivatives are finite at $x = \pm 1$. [5]

- (b) The eigenfunctions y_n of (*) are n th-order polynomials that satisfy $y_n(1) = 1$. Calculate y_0 , y_1 and y_2 explicitly. Also calculate I_0 and I_1 , where

$$I_n = \int_{-1}^1 w y_n^2 dx$$

is the weighted norm of y_n . [5]

- (c) Consider now the equation for $Z(x)$,

$$(1-x^2)Z'' - xZ' + \gamma^2 Z = e^{\epsilon x}, \quad -1 \leq x \leq 1 \quad (\dagger)$$

where γ is a real non-integer constant and $\epsilon \ll 1$ is a positive real constant.

- (i) By looking for an expansion of $Z(x)$ in terms of the eigenfunctions y_n of (*), or otherwise, and expanding the right-hand side of (\dagger) in powers of ϵ , find an expression for $Z(x)$ of the form

$$Z(x) = A + \epsilon B + \epsilon^2 C + O(\epsilon^3)$$

You should write A , B and C in terms of γ , y_0 , y_1 and y_2 . You do not need to calculate any of the $O(\epsilon^3)$ terms. [5]

- (ii) Now suppose $\gamma^2 = 5$. Using your answers to part (b), or otherwise, show that

$$\int_{-1}^1 [(1-x^2)^{-1/2} + (1-x^2)^{1/2}] Z(x) dx = \frac{3\pi}{10} + \epsilon^2 \frac{\pi}{80} + O(\epsilon^3)$$

You may use without proof that $I_2 = \pi/2$. [5]

Answer 9.11.

- (a) Multiply (*) by an integration factor $\mu(x)$ to cast to Sturm-Liouville form

$$\mathcal{L}' = -\frac{d}{dx} \left(p(x) \frac{d}{dx} \right), \quad \frac{1}{p(x)} \frac{dp(x)}{dx} = \frac{-x}{1-x^2} \implies p(x) \propto \sqrt{1-x^2} \implies \mu(x) \propto \frac{1}{\sqrt{1-x^2}}$$

Then, $\mathcal{L}' = -\frac{d}{dx}(\sqrt{1-x^2} \frac{d}{dx})$ such that $\mathcal{L}'y = n^2wy$, where $w(x) = \frac{1}{\sqrt{1-x^2}}$.

$$\begin{aligned} \langle y_n | \mathcal{L}' y_m \rangle &= - \int_{-1}^1 y_n^* \frac{d}{dx} \left(\sqrt{1-x^2} \frac{dy_m}{dx} \right) dx \\ &= \left[-y_n^* \sqrt{1-x^2} \frac{dy_m}{dx} \right]_{-1}^1 - \int_{-1}^1 \frac{dy_n^*}{dx} \sqrt{1-x^2} \frac{dy_m}{dx} dx \\ &= \left[\sqrt{1-x^2} \left(y_n^* \frac{dy_m}{dx} - y_m \frac{dy_n^*}{dx} \right) \right]_{-1}^1 + \int_{-1}^1 y_m \frac{d}{dx} \left(\sqrt{1-x^2} \frac{dy_n^*}{dx} \right) dx \end{aligned}$$

Note $y^* = y$ since we are given that they are real. Since y and y' finite at $x = \pm 1$, the boundary term is zero, and so $\langle y_n | \mathcal{L}' y_m \rangle = \langle \mathcal{L}' y_n | y_m \rangle$. LHS gives $m^2 \langle y_n | y_m \rangle_w$ while the RHS gives $n^2 \langle y_n | y_m \rangle_w$. Bringing to one side, we have $(m^2 - n^2) \langle y_n | y_m \rangle_w = 0$. Thus, for $n \neq m$, $\int_{-1}^1 y_n(x) y_m(x) w(x) dx = 0$ as desired.

(b) $y_0(x) = 1$ and is trivially normalized. Guess $y_1 = c_1x + c_2$, then

$$-\frac{d}{dx}\sqrt{1-x^2}c_1 = 1^2 \frac{1}{\sqrt{1-x^2}}(c_1x + c_2) \implies c_2 = 0$$

Normalization gives $y_1(1) = 1 \implies c_1 = 1$. Guess $y_2 = c_3x^2 + c_4x + c_5$, then

$$-\frac{d}{dx}\left(\sqrt{1-x^2}(2c_3x + c_4)\right) = 2^2 \frac{1}{\sqrt{1-x^2}}(c_3x^2 + c_4x + c_5) \implies y_2(x) \propto -2x^2 + 1$$

Since $y_2(1) = 1 \implies y_2 = 2x^2 - 1$. The integrals will be

$$I_0 = \int_{-1}^1 \frac{1}{\sqrt{1-x^2}} dx = \int_{-\pi/2}^{\pi/2} \frac{1}{\cos \theta} \cos \theta d\theta = \pi$$

$$I_1 = \int_{-1}^1 \frac{x^2}{\sqrt{1-x^2}} dx = \int_{-\pi/2}^{\pi/2} \frac{\sin^2 \theta}{\cos \theta} \cos \theta d\theta = \frac{\pi}{2}$$

(c) (i) Write $Z = ay_0 + by_1 + cy_2$, then compare coefficients:

$$(1-x^2)(0+0+4c) - x(0+b+4cx) + \gamma^2(a+bx+c(2x^2-1)) = 1 + \epsilon x + \frac{\epsilon^2}{2}x^2 + O(\epsilon^3)$$

$$\text{gives } c = \frac{\epsilon^2}{4(\gamma^2-4)}, b = \frac{\epsilon}{\gamma^2-1} \text{ and } a = \frac{1}{\gamma^2}\left(1 + \frac{\epsilon^2}{4}\right), \text{ i.e.}$$

$$Z = \frac{1}{\gamma^2}\left(1 + \frac{\epsilon^2}{4}\right)y_0 + \frac{\epsilon}{\gamma^2-1}y_1 + \frac{\epsilon^2}{4(\gamma^2-4)}y_2 + O(\epsilon^3)$$

$$\text{with } A = \frac{1}{\gamma^2}y_0, B = \frac{y_1}{\gamma^2-1} \text{ and } C = \frac{y_0}{4\gamma^2} + \frac{y_2}{4(\gamma^2-4)}.$$

(ii) Set $\gamma^2 = 5$, then $Z(x) = \frac{1}{5} + \frac{x\epsilon}{4} + \frac{\epsilon^2(2x^2-1)}{4} + \frac{\epsilon^2}{20}$. Substitute $x = \sin \theta$:

$$J = \int_{-\pi/2}^{\pi/2} \left[\frac{1}{\cos \theta} + \cos \theta \right] \left[\frac{1}{5} + \frac{\epsilon}{4} \sin \theta + \frac{\epsilon^2}{4}(2 \sin^2 \theta - 1) + \frac{\epsilon^2}{20} \right] \cos \theta d\theta$$

The integrals are

$$\int 1 + \cos^2 x dx = \frac{3x}{2} + \frac{1}{4} \sin 2x, \quad \int \sin x + \sin x \cos^2 x dx = -\cos x - \frac{1}{3} \cos^3 x,$$

$$\int \frac{1}{2} \sin^2 x + \frac{1}{2} \sin^2 x \cos^2 x - \frac{1}{5} - \frac{1}{5} \cos^2 x dx = \frac{1}{80}x - \frac{7}{40} \sin 2x - \frac{1}{64} \sin 4x$$

Hence,

$$J = \frac{3\pi}{10} + \frac{\epsilon}{4}0 + \epsilon^2 \left(\frac{3\pi}{40} - \frac{\pi}{16} \right) = \frac{3\pi}{10} + \frac{\epsilon^2\pi}{80} + O(\epsilon^3)$$

Alternatively you can evaluate the ϵ^2 part with the help of the given result for I_2 .

Problem 9.12 (Laplace's Equation): Consider Laplace's equation in plane polar coordinates

$$\frac{\partial^2 \Psi}{\partial r^2} + \frac{1}{r} \frac{\partial \Psi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \Psi}{\partial \phi^2} = 0 \quad (*)$$

where $0 \leq \phi < 2\pi$ is a periodic coordinate, $\Psi(r, \phi)$ is single-valued and finite inside the disk of radius $R > 0$ centred at the origin.

- (a) Use separation of variables to show that the general solution can be written as: [4]

$$\Psi(r, \phi) = A_0 + \sum_{n=1}^{\infty} r^n [A_n \cos(n\phi) + B_n \sin(n\phi)]$$

- (b) Assume Ψ satisfies the boundary condition $\Psi(R, \phi) = f(\phi)$ for $0 \leq \phi < 2\pi$. Show that the value of Ψ at the centre of the disk is equal to the average value of f on the circle of radius R . [6]

- (c) Compute the values of A_0 , A_n and B_n when $R = 2$ and [6]

$$f(\phi) = \begin{cases} 1 & 0 \leq \phi < \pi \\ \cos^2(\phi) & \pi \leq \phi < 2\pi \end{cases}$$

- (d) Show that any solution Ψ of Laplace's equation (*) on the disk attains its maximum value on the boundary of the disk. [4]

[Hint: Use part (b) to show that the value of Ψ at any point in the interior of the disk is the average of Ψ on a circle surrounding that point.]

Answer 9.12.

- (a) Use separation of variables $\Psi(r, \phi) = R(r)\Phi(\phi)$:

$$\frac{R''}{R} + \frac{R'}{rR} = -\frac{\Phi''}{r^2\Phi} = \frac{\lambda^2}{r^2}$$

where λ is some constant. The angular part is $\Phi''(\phi) = -\lambda^2\Phi(\phi)$ gives $\Phi(\phi) = c_1\phi + c_2$ for $\lambda = 0$ and $\Phi(\phi) = c_3 \cos \lambda\phi + c_4 \sin \lambda\phi$ for $\lambda \neq 0$. But, Φ is periodic, i.e. $\Phi(\phi) = \Phi(\phi + 2\pi) \implies c_1 = c_2 = 0$, $\lambda = n \in \mathbb{Z}^+$.

The radial part gives $r^2 R'' + R'r - \lambda^2 R = 0$. If $\lambda^2 = 0$, then rR' is a constant, hence $R(r) = c_7 \ln r + c_8$. If $\lambda \neq 0$, then try $R(r) = r^k$, and we get $k^2 = n^2 \implies k = \pm n$ and hence $R(r) = c_5 r^n + c_6 r^{-n}$. But $R(r = 0)$ is finite, so $c_6 = c_7 = 0$. Thus,

$$\Phi(r, \phi) = c_8 + \sum_{n=1}^{\infty} c_5 r^n (c_3 \cos n\phi + c_4 \sin n\phi)$$

where we identify $c_8 = A_0$, $c_5 c_3 = A_n$ and $c_4 c_5 = B_n$.

- (b) The value of Ψ at the centre of the disk is $\Psi(0, \phi) = A_0$, while the value at the boundary is

$$\Psi(R, \phi) = f(\phi) = A_0 + \sum_{n=1}^{\infty} R^n (A_n \cos n\phi + B_n \sin n\phi) \implies A_0 = \frac{1}{2\pi} \int_0^{2\pi} f(\phi) d\phi$$

using Fourier series. And so, the value at the centre is indeed equal to the average value of f on the circle.

- (c) Using Fourier series again:

$$A_0 = \frac{1}{2\pi} \int_0^{2\pi} f(\phi) d\phi = \frac{1}{2\pi} \left[\int_0^{\pi} d\phi + \int_{\pi}^{2\pi} \frac{1}{2} (1 + \cos 2\phi) d\phi \right] = \frac{3}{4}$$

$$A_n R^n = \frac{1}{\pi} \int_0^{2\pi} f(\phi) \cos n\phi d\phi = \frac{1}{\pi} \left[\int_0^{\pi} \cos n\phi d\phi + \frac{1}{2} \int_{\pi}^{2\pi} (1 + \cos 2\phi) \cos n\phi d\phi \right]$$

Then, by orthogonality of cosines, we have $A_2 R^2 = \frac{1}{\pi} \frac{1}{2} \frac{1}{2} \pi$. Hence, $A_n = 0 \forall n \neq 0, 2$ but $A_2 = \frac{1}{4R^2}$. Finally,

$$B_n R^n = \frac{1}{\pi} \int_0^{2\pi} f(\phi) \sin n\phi d\phi = \frac{1}{\pi} \left[\int_0^\pi \sin n\phi d\phi + \frac{1}{2} \int_\pi^{2\pi} (1 + \cos 2\phi) \sin n\phi d\phi \right]$$

Again, orthogonality gives $B = 0$ for even n and $B_n = \frac{1}{\pi R^n} \left(\frac{1}{n} - \frac{n}{2(n^2-1)} \right)$ for odd n . Also, we see $B_2 = 0$. Then, the general solution is

$$\Psi(r, \theta) = \frac{3}{4} + \frac{r^2}{4R^2} \cos 2\phi + \frac{1}{\pi} \sum_{n=1}^{\infty} \left(\frac{r}{R} \right)^{2n-1} \left[\frac{1}{2n-1} - \frac{2n-1}{2((2n-1)^2-1)} \right] \cos(2n-1)\phi$$

Then for $R = 2$:

$$\Psi(r, \theta) = \frac{3}{4} + \frac{r^2}{16} \cos 2\phi + \frac{1}{\pi} \sum_{n=1}^{\infty} (r/2)^{2n-1} \cos((2n-1)\phi) \frac{4n^2 - 4n - 1}{8n(n-1)(2n-1)}$$

- (d) Suppose there was an interior maximum for Ψ , say at point \mathbf{x} . Shift our origin to \mathbf{x} , and from part (b), the value at \mathbf{x} is equal to the average value of Ψ on a circle of radius ϵ centred on \mathbf{x} . The only way a maximum value of a function is equal to the mean value, is when the function is a constant. This contradicts our construction, hence Ψ has no interior maximum. The only way Ψ can take a maximum is on the boundary.

Problem 9.13 (Green's Functions): Consider Poisson's equation on a volume V in \mathbb{R}^3 with boundary conditions specified on the surface S :

$$\nabla^2 \Phi = \rho(\mathbf{r}) \text{ on } V$$

$$\Phi = f(\mathbf{r}) \text{ on } S$$

- (a) State the definition of a Green's function for Poisson's equation with the boundary conditions on the surface S as above. [4]
- (b) Using Green's identity, show that the solution to Poisson's equation can be expressed as [4]

$$\Phi(\mathbf{r}') = \int_V \rho(\mathbf{r}) G(\mathbf{r}, \mathbf{r}') dV + \int_S f(\mathbf{r}) \frac{\partial G}{\partial n} dS$$

where G is the Green's function.

- (c) Write down the fundamental solution in \mathbb{R}^3 . Hence, find the Green's function in the case where $V = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 1\}$ is the interior of the sphere of radius 1 centred at the origin. [6]
- (d) Use the method of images to determine the Green's function when $V = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 1, z \geq 0\}$ is the interior of the half-sphere ($z \geq 0$). [6]

Answer 9.13.

(a) The Green's function G must satisfy

$$\nabla_{\mathbf{r}}^2 G(\mathbf{r}, \mathbf{r}') = \delta^{(3)}(\mathbf{r} - \mathbf{r}') \text{ on } V$$

and Dirichlet's boundary conditions:

$$G(\mathbf{r}, \mathbf{r}') = 0 \text{ on } S$$

(b) We state Green's second identity:

$$\int_V u \nabla^2 v - v \nabla^2 u dV = \int_{\partial V} (u \nabla v - v \nabla u) \cdot d\mathbf{S}$$

Set $u = \Phi(\mathbf{r})$, $v = G(\mathbf{r}, \mathbf{r}')$, we get

$$\int_V \Phi \nabla_{\mathbf{r}}^2 G - G \nabla^2 \Phi dV = \int_{\partial V} (\Phi \nabla G - G \nabla \Phi) \cdot d\mathbf{S}$$

But $\nabla^2 \Phi = \rho$ and $\Phi \nabla G \cdot d\mathbf{S} = \Phi \frac{\partial G}{\partial n} dS$, $G = 0$ on $S = \partial V$, $\Phi = f$, $\nabla_{\mathbf{r}}^2 G = \delta$.

$$\Phi(\mathbf{r}') - \int_V \rho(\mathbf{r}) G(\mathbf{r}, \mathbf{r}') dV = \int_{\partial V} f(\mathbf{r}) \frac{\partial G}{\partial n} dS$$

(c) The fundamental solution in \mathbb{R}^3 is

$$G(\mathbf{r}, \mathbf{r}') = -\frac{1}{4\pi|\mathbf{r} - \mathbf{r}'|}$$

By Uniqueness Theorem, we may use the method of images. This involves replacing the problem with a corresponding problem that involves images. This is valid as long as the Green's function satisfy the same equation in the domain of interest, with boundary conditions satisfied. Consider a sphere with two sources at position C and B , with position vectors \mathbf{r}_0 and \mathbf{r}_1 , and magnitudes 1 and s respectively. Let A be an arbitrary point on the sphere, with position vector \mathbf{r} such that $|\mathbf{r}| = 1$. Then the triangles AOC is similar to BOA , since they share a common angle $\angle AOC = \angle AOB$ and a common side OA .

$$\frac{AO}{BO} = \frac{AC}{BA} = \frac{OC}{OA} \implies |\mathbf{r}_1| = \frac{|\mathbf{r} - \mathbf{r}_1|}{|\mathbf{r} - \mathbf{r}_0|} = \frac{1}{|\mathbf{r}_0|}$$

Then the Green's function for this problem satisfy

$$\nabla^2 G = \delta^{(3)}(\mathbf{r} - \mathbf{r}_0) + s\delta^{(3)}(\mathbf{r} - \mathbf{r}_1)$$

Since the Laplacian is linear, then the general solution will be a linear combination of the fundamental solutions.

$$G = -\frac{1}{4\pi} \left(\frac{1}{|\mathbf{r} - \mathbf{r}_0|} + \frac{s}{|\mathbf{r} - \mathbf{r}_1|} \right) = -\frac{1}{4\pi|\mathbf{r} - \mathbf{r}_0|} \left[1 + \frac{|\mathbf{r} - \mathbf{r}_0|}{|\mathbf{r} - \mathbf{r}_1|} s \right] = -\frac{1}{4\pi|\mathbf{r} - \mathbf{r}_0|} (1 + |\mathbf{r}_0|s)$$

But $G = 0$ (Dirichlet's boundary condition), so $s = -\frac{1}{|\mathbf{r}_0|}$ and so $\mathbf{r}_1 = \frac{1}{|\mathbf{r}_0|^2} \mathbf{r}_0$.

(d) The modified problem further requires $G = 0$ at $z = 0$. Hence, we add an additional pair of image charges such that the mirror symmetry of the problem about the plane $z = 0$ is not broken.

$$G = -\frac{1}{4\pi} \left(\frac{1}{|\mathbf{r} - \mathbf{r}_0|} + \frac{s}{|\mathbf{r} - \mathbf{r}_1|} \right) - \frac{1}{4\pi} \left(\frac{1}{|\mathbf{r} - \mathbf{r}_2|} + \frac{s}{|\mathbf{r} - \mathbf{r}_3|} \right)$$

where \mathbf{r}_2 is \mathbf{r}_0 with the z -coordinate flipped, and \mathbf{r}_3 is \mathbf{r}_1 with the z -coordinate flipped.

Problem 9.14 (Contour Integration):

- (a) State Cauchy's theorem and Cauchy's formula, clearly stating the assumptions about the integration contour used. [4]
- (b) The extension of Cauchy's formula is

$$f^{(n)}(z_0) = \frac{n!}{2\pi i} \oint_C \frac{f(z)}{(z - z_0)^{n+1}} dz$$

where $f^{(n)}(z) = \frac{d^n f}{dz^n}$.

Use this formula to evaluate

$$\oint_C \frac{\sin z}{(z+1)^7} dz$$

where C is a circle of radius 5 with centre 0 and the contour is oriented in an anticlockwise direction. [6]

- (c) State the Residue theorem and use it to evaluate the contour integral of

$$g(z) = \frac{e^{iz}}{z^4 + z^2 + 1}$$

along the closed contour, oriented anticlockwise, consisting of $L_R = [-R, R]$ and C_R . Here L_R is the line between $-R$ and R and $C_R = \{|z| = R, \operatorname{Im}(z) \geq 0\}$ is a half-circle of radius R and centre 0, located above the real line.

Prove that

$$\lim_{R \rightarrow \infty} \int_{C_R} \frac{e^{iz}}{z^4 + z^2 + 1} dz = 0$$

Therefore, evaluate

$$\int_{-\infty}^{\infty} \frac{\cos x}{x^4 + x^2 + 1} dx$$

Answer 9.14.

- (a) If $f(z)$ is analytic in a simply-connected domain D , then for every simple closed contour γ in D , then Cauchy's theorem states

$$\oint_{\gamma} f(z) dz = 0$$

Suppose f is analytic in a simply-connected domain D and $z \in D$, then for any simple closed contour γ in D encircling z anti-clockwise, then the Cauchy integral formula is

$$f(z) = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(w)}{w - z} dw$$

- (b) Identify $n = 6$, $f(z) = \sin z$, $z_0 = -1$, then

$$\oint_C \frac{\sin z}{(z+1)^7} dz = \frac{2\pi i}{n!} f^{(n)}(z_0) = -\frac{2\pi i}{6!} \sin(-1) = \frac{\pi i}{6 \times 5 \times 4 \times 3} \sin(1)$$

- (c) Suppose f is analytic in a simply-connected domain except at a finite number of isolated singularities $\{z_1, \dots, z_n\}$. Suppose a simple closed contour γ encircles the origin anticlockwise, then the residue theorem states

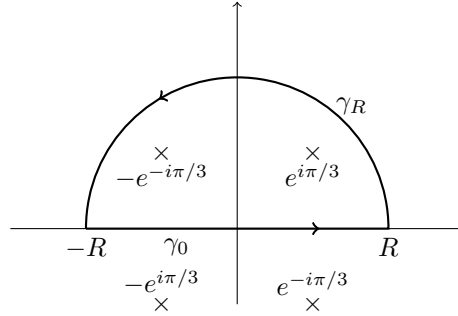
$$\oint_{\gamma} f(z) dz = 2\pi i \sum_{k=1}^n \operatorname{res}_{z=z_k} f(z)$$

where the residue of the N th order pole is

$$\operatorname{res}_{z=z_i} f(z) = \lim_{z \rightarrow z_i} \frac{1}{(N-1)!} \frac{d^{N-1}}{dz^{N-1}} (z - z_i)^N f(z)$$

Let $g(z) = \frac{e^{iz}}{z^4 + z^2 + 1}$ have simple poles at $z = \pm e^{\pm i\pi/3}$ with residues (evaluate using L'Hopital rule)

$$\begin{aligned} \operatorname{res}_{z=e^{\pm i\pi/3}} g(z) &= \lim_{z \rightarrow e^{\pm i\pi/3}} \frac{e^{iz}}{4z^3 + 2z} = \frac{e^{i/2} e^{\mp \sqrt{3}/2}}{2e^{\pm i\pi/3} - 4} \\ \operatorname{res}_{z=-e^{\pm i\pi/3}} g(z) &= \lim_{z \rightarrow -e^{\pm i\pi/3}} \frac{e^{iz}}{4z^3 + 2z} = \frac{e^{-i/2} e^{\pm \sqrt{3}/2}}{-2e^{\pm i\pi/3} + 4} \end{aligned}$$



Only the poles $e^{+i\pi/3}$ and $-e^{-i\pi/3}$ are enclosed. So by residue theorem,

$$\oint_{\gamma_0 \cup \gamma_R} g(z) dz = 2\pi i \left(\frac{e^{i/2} e^{-\sqrt{3}/2}}{-3 + i\sqrt{3}} + \frac{e^{-i/2} e^{-\sqrt{3}/2}}{3 + i\sqrt{3}} \right) = 2\pi i \frac{-ie^{-\sqrt{3}/2}}{2} (\sin 0.5 + 3^{-1/2} \cos 0.5)$$

The contribution along $\gamma_R : z = Re^{i\theta}, \theta \in [0, \pi)$ gives $O(R^{-3}e^{-R\cos\theta}) \rightarrow 0$ as $R \rightarrow \infty$. We have

$$\begin{aligned} \oint_{\gamma_0 \cup \gamma_R} g(z) dz &= \int_{-R}^R g(x) dx + \int_{\gamma_R} g(z) dz \rightarrow \int_{-\infty}^{\infty} g(x) dx + 0, \text{ as } R \rightarrow \infty \\ \Rightarrow \int_{-\infty}^{\infty} \frac{\cos(x)}{x^4 + x^2 + 1} dx &= \operatorname{Re} \left[\int_{-\infty}^{\infty} g(x) dx \right] = \pi e^{-\sqrt{3}/2} (\sin 0.5 + 3^{-1/2} \cos 0.5) \end{aligned}$$

Problem 9.15 (Transform Methods): The Fourier transform $\tilde{f}(\omega)$ of a function $f(t)$ is defined by

$$\tilde{f}(\omega) = \int_{-\infty}^{\infty} f(t)e^{-i\omega t} dt$$

- (a) Show that the Fourier transform of $f'(t)$ is given by $i\omega\tilde{f}(\omega)$. Clearly state the assumptions you made about $f(t)$. [2]
- (b) Consider the equation for forced damped harmonic motion

$$\frac{d^2 y(t)}{dt^2} + 2\kappa \frac{dy(t)}{dt} + \Omega^2 y(t) = f(t)$$

where $\kappa, \Omega > 0$ are given constants and $f(t)$ is a given function.

Show that $\tilde{y}(\omega)$ can be expressed as $\tilde{y}(\omega) = \tilde{h}(\omega)\tilde{f}(\omega)$, and write down $\tilde{h}(\omega)$. [2]

- (c) Show that your expression in (b) can be inverted to find $y(t)$ as

$$y(t) = \int_{-\infty}^{\infty} G(t - \xi)f(\xi)d\xi$$

where

$$G(t) = \int_{-\infty}^{\infty} \frac{s(\omega, t)}{(\omega - \omega_-)(\omega - \omega_+)} d\omega$$

for some ω_+, ω_- and $s(\omega, t)$ that you should determine. The convolution theorem can be used without proof. [3]

- (d) Evaluate $G(t)$ for $t > 0$ by closing the contour and using the residue theorem for: [7]

- $\Omega > \kappa$;
- $\kappa > \Omega$;
- $\kappa = \Omega$.

What is the value of $G(t)$ for $t < 0$? Describe the behaviour of $G(t)$ as $t \rightarrow \infty$. [2]

- (e) Use your results from parts (c) and (d) to determine $y(t)$ when $f(t) = \cos \kappa t$ and $\Omega = \kappa$. [4]

Answer 9.15.

- (a) Take Fourier transform of $f'(t)$ is

$$\mathcal{F}[f'] = \int_{-\infty}^{\infty} f'(t)e^{-i\omega t} dt = [fe^{-i\omega t}]_{-\infty}^{\infty} + i\omega\tilde{f}$$

For $\mathcal{F}[f'(t)] = i\omega\tilde{f}(\omega)$, then we have to assume $f(t) \rightarrow 0$ as $t \rightarrow \pm\infty$.

- (b) So take the Fourier transform of the forced damped harmonic motion

$$-\omega^2\tilde{y} + 2\kappa i\omega\tilde{y} + \Omega^2\tilde{y} = \tilde{f}$$

hence,

$$\tilde{y} = \tilde{f}\tilde{h} \implies \tilde{h}(\omega) := \frac{-1}{\omega^2 - 2i\kappa\omega - \Omega^2}$$

- (c) Convolution theorem states

$$\tilde{y}(\omega) = \tilde{f}(\omega)\tilde{h}(\omega) \implies y(t) = \int_{-\infty}^{\infty} f(\xi)h(t - \xi)d\xi$$

Use inverse Fourier transform:

$$y(t) = \int_{-\infty}^{\infty} \frac{\tilde{y}}{2\pi} e^{i\omega t} d\omega = \frac{-1}{2\pi} \int_{-\infty}^{\infty} \frac{\tilde{f} e^{i\omega t} d\omega}{\omega^2 - 2i\kappa\omega - \Omega^2} \implies h(t) = \frac{-1}{2\pi} \int_{-\infty}^{\infty} \frac{e^{i\omega t} d\omega}{\omega^2 - 2i\kappa\omega - \Omega^2}$$

This is the Green's function we are looking for with $s(\omega, t) = \frac{-e^{i\omega t}}{2\pi}$ and ω_{\pm} are the roots of $\omega^2 - 2i\kappa\omega - \Omega^2 = 0 \implies \omega_{\pm} = i\kappa \pm \sqrt{\Omega^2 - \kappa^2}$.

(d) To evaluate G , we consider

$$\oint_C \frac{s(\omega, t)}{(\omega - \omega_-)(\omega - \omega_+)} d\omega$$

over a closed loop C in complex ω -plane. The integrand has poles at ω_{\pm} with residues (depending on the regime):

- $\Omega > \kappa$: $\omega_{\pm} = i\kappa \pm \sqrt{\Omega^2 - \kappa^2}$ are simple poles.

$$\begin{aligned} \text{res}_{\omega \rightarrow \omega_{\pm}} G(t) &= \lim_{\omega \rightarrow \omega_{\pm}} \frac{1}{\omega - \omega_{\mp}} \frac{-1}{2\pi} e^{i\omega t} \\ &= \mp \frac{1}{4\pi\sqrt{\Omega^2 - \kappa^2}} e^{-\kappa t} e^{\pm i\sqrt{\Omega^2 - \kappa^2} t} \end{aligned}$$

- $\Omega < \kappa$: $\omega_{\pm} = i\kappa \pm i\sqrt{\kappa^2 - \Omega^2}$ are simple poles.

$$\begin{aligned} \text{res}_{\omega \rightarrow \omega_{\pm}} G(t) &= \lim_{\omega \rightarrow \omega_{\pm}} \frac{1}{\omega - \omega_{\mp}} \frac{-1}{2\pi} e^{i\omega t} \\ &= \mp \frac{1}{4\pi\sqrt{-\Omega^2 + \kappa^2}} e^{-\kappa t} e^{\mp \sqrt{\Omega^2 - \kappa^2} t} \end{aligned}$$

- $\Omega = \kappa$: $\omega_0 = i\kappa$ is a double pole.

$$\begin{aligned} \text{res}_{\omega \rightarrow \omega_0} G(t) &= \lim_{\omega \rightarrow \omega_0} \frac{d}{d\omega} \frac{-1}{2\pi} e^{i\omega t} \\ &= -\frac{it}{2\pi} e^{i\omega t} \end{aligned}$$

For $t > 0$, we close the upper half-plane (in order to use Jordan's Lemma). Another equivalent explanation:

$$\int_{C_R} \frac{s(\omega)}{(\omega - \omega_-)(\omega - \omega_+)} d\omega = O(R^{-2}) \rightarrow 0 \text{ as } R \rightarrow \infty$$

where $C_R: z = Re^{i\theta}$, $\theta \in [0, \pi)$ is a semi-circular arc. Then,

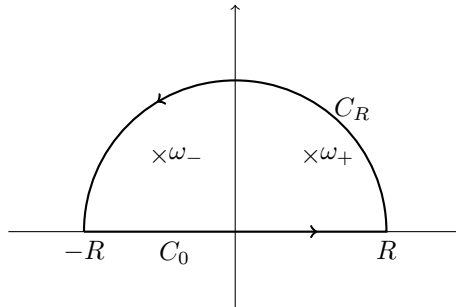
$$\oint_C \frac{s(\omega, t)}{(\omega - \omega_-)(\omega - \omega_+)} d\omega = \int_{C_R} \frac{s(\omega)}{(\omega - \omega_-)(\omega - \omega_+)} d\omega + \int_{C_0} \frac{s(\omega)}{(\omega - \omega_-)(\omega - \omega_+)} d\omega \rightarrow G(t) \text{ as } R \rightarrow \infty$$

where $C_R: z = r$, $r \in [-R, R]$. This closed contour C happens to enclose our poles, located in the upper half-plane. Then by residue theorem,

$$\oint_C f(z) dz = 2\pi i \sum_k \text{res}_{z=z_k} f(z)$$

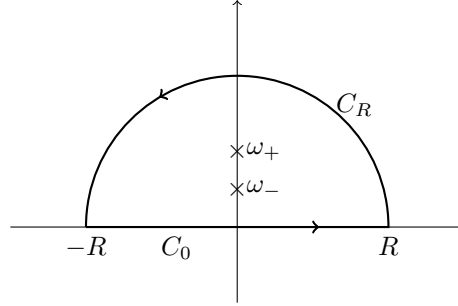
where $f(z)$ is analytic in a simply-connected domain except at a finite number of k isolated singularities, and C is a simple closed contour that traverses in an anti-clockwise fashion.

For $\Omega > \kappa$, $\sqrt{\Omega^2 - \kappa^2} \in \mathbb{R}$ and we have



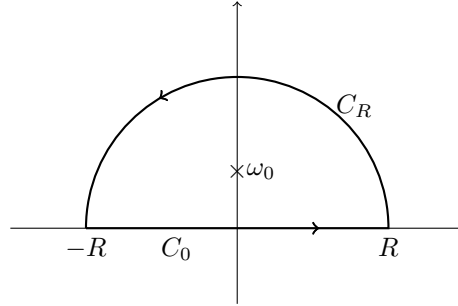
$$\begin{aligned}
G(t > 0) &= 2\pi i \frac{-e^{-\kappa t}}{4\pi\sqrt{\Omega^2 - \kappa^2}} (e^{i\sqrt{\Omega^2 - \kappa^2}t} - e^{-i\sqrt{\Omega^2 - \kappa^2}t}) \\
&= \frac{-2\pi i 2i \sin(\sqrt{\Omega^2 - \kappa^2}t) e^{-\kappa t}}{4\pi\sqrt{\Omega^2 - \kappa^2}} \\
&= \frac{e^{-\kappa t}}{\sqrt{\Omega^2 - \kappa^2}} \sin(\sqrt{\Omega^2 - \kappa^2}t)
\end{aligned}$$

For $\Omega < \kappa$, $\sqrt{\Omega^2 - \kappa^2}$ is purely imaginary, and we have



$$\begin{aligned}
G(t > 0) &= 2\pi i \frac{-e^{-\kappa t}}{4\pi\sqrt{-\Omega^2 + \kappa^2}} (e^{-\sqrt{-\Omega^2 + \kappa^2}t} - e^{\sqrt{-\Omega^2 + \kappa^2}t}) \\
&= \frac{2\pi i 2 \sinh(\sqrt{-\Omega^2 + \kappa^2}t) e^{-\kappa t}}{4\pi i \sqrt{-\Omega^2 + \kappa^2}} \\
&= \frac{e^{-\kappa t}}{\sqrt{-\Omega^2 + \kappa^2}} \sinh(\sqrt{-\Omega^2 + \kappa^2}t)
\end{aligned}$$

For $\omega = \kappa$, we only have one pole (double pole) on the imaginary axis.



$$G(t > 0) = -2\pi i \frac{it}{2\pi} e^{-\kappa t} = te^{-\kappa t}$$

When $t < 0$, we close the lower half-plane, but since there are no poles enclosed, $G(t < 0) = 0$. This is consistent with causality. As $t \rightarrow \infty$, $e^{-\kappa t} \rightarrow 0$, so $G(t) \rightarrow 0$ regardless of the regime.

(e) When $\Omega = \kappa$, $G(t) = te^{-\kappa t}H(t)$ where $H(t)$ is the heaviside function. Rewriting $y(t)$,

$$\begin{aligned}
y(t) &= \int_{-\infty}^{\infty} f(t - \xi)G(\xi)d\xi \\
&= \int_{-\infty}^{\infty} \cos(\kappa\xi)(t - \xi)e^{-\kappa(t - \xi)}H(t - \xi)d\xi \\
&= \int_{-\infty}^{\infty} \cos(\kappa(t - \xi))\xi e^{-\kappa\xi}d\xi \\
&= \frac{1}{2} \left\{ \int_0^{\infty} \xi e^{-\xi(\kappa + i\kappa)} e^{i\kappa t} d\xi + \int_0^{\infty} \xi e^{-\xi(\kappa - i\kappa)} e^{-i\kappa t} d\xi \right\} \\
&= \frac{1}{2} \left[\frac{e^{i\kappa t}}{(\kappa + i\kappa)^2} + \frac{e^{-i\kappa t}}{(\kappa - i\kappa)^2} \right] \\
&= \frac{\sin \kappa t}{2\kappa^2}
\end{aligned}$$

where $(\kappa \pm i\kappa)^2 = \kappa - \kappa \pm 2i\kappa$.

Problem 9.16 (Tensors):

- (a) Show that any second-order tensor T can be written in the form

$$T_{ij} = S_{ij} + \epsilon_{ijk}u_k$$

where S is a symmetric second-order tensor and \mathbf{u} is a vector. Find explicit expressions for S_{ij} and u_k in terms of T_{ij} . [5]

- (b) Maxwell's equations for the electric and magnetic fields $\mathbf{E}(\mathbf{x}, t)$ and $\mathbf{B}(\mathbf{x}, t)$ in a vacuum can be written as

$$\begin{aligned} \nabla \cdot \mathbf{E} &= 0, & \nabla \cdot \mathbf{B} &= 0 \\ \nabla \times \mathbf{E} + \frac{\partial \mathbf{B}}{\partial t} &= 0, & \nabla \times \mathbf{B} - \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t} &= 0 \end{aligned}$$

where c is a constant. Consider the second-order tensors $T_{ij}^E = \frac{\partial E_j}{\partial x_i}$ and $T_{ij}^B = \frac{\partial B_j}{\partial x_i}$. As in part (a), these can be written in terms of symmetric second-order tensors S^E and S^B and vectors \mathbf{u}^E and \mathbf{u}^B , respectively.

- (i) Calculate expressions for S_{ij}^E , S_{ij}^B , \mathbf{u}^E and \mathbf{u}^B in terms of \mathbf{E} and \mathbf{B} . [2]
(ii) Show that [4]

$$\frac{\partial \mathbf{u}^E}{\partial t} = -\frac{c^2}{2} \nabla^2 \mathbf{B}$$

- (iii) Let V denote a constant closed volume with surface A . By applying the divergence theorem to a suitable integral expression, show that [4]

$$\frac{\partial}{\partial t} \int_V (u_i^E + u_i^B) dV = \oint_A (S_{ij}^E - c^2 S_{ij}^B) dA_j$$

- (iv) Show further that

$$\frac{\partial}{\partial t} \int_V \lambda dV = \oint_A (\mathbf{B} \times \mathbf{E}) \cdot d\mathbf{A}$$

for some scalar quantity λ that should be determined in terms of \mathbf{E} , \mathbf{B} and c . [5]

Answer 9.16.

- (a) We can decompose a generic second-order tensor:

$$T_{ij} = \frac{1}{2}(T_{ij} + T_{ji}) + \frac{1}{2}(T_{ij} - T_{ji})$$

with $S_{ij} = \frac{1}{2}(T_{ij} + T_{ji})$, $A_{ij} = \frac{1}{2}(T_{ij} - T_{ji}) = \epsilon_{ijk}u_k$. (anti-symmetric second-order tensor is equivalent to an axial vector). Then,

$$\epsilon_{ijl}A_{ij} = \epsilon_{ijl}\epsilon_{ijk}u_k = (\delta_{jj}\delta_{lk} - \delta_{jk}\delta_{lj})u_k = (3\delta_{lk} - \delta_{lk})u_k = 2\delta_{lk}u_k \implies u_k = \frac{1}{2}\epsilon_{ijk}\frac{1}{2}(T_{ij} - T_{ji})$$

- (b) (i)

$$S_{ij}^E = \frac{1}{2} \left(\frac{\partial E_j}{\partial x_i} + \frac{\partial E_i}{\partial x_j} \right), \quad S_{ij}^B = \frac{1}{2} \left(\frac{\partial B_j}{\partial x_i} + \frac{\partial B_i}{\partial x_j} \right), \quad u_k^E = \frac{1}{4} \epsilon_{ijk} \left(\frac{\partial E_j}{\partial x_i} - \frac{\partial E_i}{\partial x_j} \right), \quad u_k^B = \frac{1}{4} \epsilon_{ijk} \left(\frac{\partial B_j}{\partial x_i} - \frac{\partial B_i}{\partial x_j} \right)$$

- (ii) Exploit Maxwell's equations, i.e. $\nabla \cdot \mathbf{B} = 0$, $\nabla \times \mathbf{B} = \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t}$, then

$$\frac{\partial \mathbf{u}^E}{\partial t} = \frac{1}{2} \frac{\partial}{\partial t} \nabla \times \mathbf{E} = \frac{1}{2} \nabla \times c^2 (\nabla \times \mathbf{B}) = -\frac{c^2}{2} \nabla^2 \mathbf{B}$$

(iii) Apply Divergence theorem to $(S^E - c^2 S^B)\mathbf{v}$ where \mathbf{v} is an arbitrary constant vector.

$$\begin{aligned} \int_V \nabla \cdot [(S^E - c^2 S^B)\mathbf{v}] dV &= \oint_A (S^E - c^2 S^B)\mathbf{v} \cdot d\mathbf{A} \\ \Rightarrow \int_V \frac{\partial}{\partial x_j} (S_{ij}^E - c^2 S_{ij}^B) v_i dV &= \oint_A (S_{ij}^E - c^2 S_{ij}^B) v_i dA_j \end{aligned}$$

but \mathbf{v} is constant so we can pull it out of the integral. \mathbf{v} is arbitrary so we can just equate the coefficients.

$$\begin{aligned} \oint_A (S_{ij}^E - c^2 S_{ij}^B) dA_j &= \frac{1}{2} \int_V \frac{\partial^2 E_i}{\partial x_j \partial x_j} + \frac{\partial E_j}{\partial x_i \partial x_j} - c^2 \frac{\partial^2 B_i}{\partial x_j \partial x_j} - c^2 \frac{\partial^2 B_j}{\partial x_i \partial x_j} dV \\ &= \frac{1}{2} \int_V 2 \frac{\partial u^B}{\partial t} + 0 - \frac{c^2}{c^2} 2 \frac{\partial u_i^E}{\partial t} - 0 dV \\ &= \frac{\partial}{\partial t} \int_V u_i^B + u_i^E dV \end{aligned}$$

(iv) Apply Divergence theorem to $\mathbf{B} \times \mathbf{E}$, noting that

$$\nabla \cdot (\mathbf{E} \times \mathbf{B}) = \partial_i (\epsilon_{ijk} E_j B_k) = \epsilon_{ijk} (\partial_i E_j) B_k + \epsilon_{ijk} (\partial_i B_k) E_j = \mathbf{B} \cdot (\nabla \times \mathbf{E}) - \mathbf{E} \cdot (\nabla \times \mathbf{B})$$

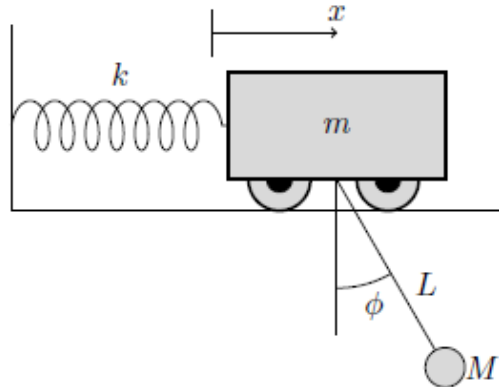
Together with the Maxwell equations $\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$ and $\frac{\partial \mathbf{E}}{\partial t} = c^2 \nabla \times \mathbf{B}$:

$$\int_V \nabla \cdot (\mathbf{E} \times \mathbf{B}) dV = \int \mathbf{E} \cdot (\nabla \times \mathbf{B}) - \mathbf{B} \cdot (\nabla \times \mathbf{E}) dV = \int \frac{\partial \mathbf{E}}{\partial t} \cdot \mathbf{E} + \frac{\partial \mathbf{B}}{\partial t} \cdot \mathbf{B} dV$$

But this is $-\frac{\partial}{\partial t} \int_V \lambda dV$ and hence $\lambda = -\frac{1}{2}(\mathbf{B} \cdot \mathbf{B} + \frac{1}{c^2} \mathbf{E} \cdot \mathbf{E})$.

Problem 9.17 (Normal Modes):

- Write down a general Lagrangian of a system with n degrees of freedom undergoing small oscillations, and state the polynomial equation for the normal frequencies. [5]
- A simple pendulum of mass M and length L is suspended from a cart of mass m that can oscillate on the end of a spring of force constant k , as shown in the figure. The cart is constrained to move in the horizontal direction only, and has a displacement $x(t)$ from its equilibrium position. The pendulum oscillates in the plane making angle $\phi(t)$ with the vertical direction.



- Assuming that the angle ϕ and displacement x remain small, write down the system's Lagrangian and the equations of motion for x and ϕ . [8]
- Assuming that $m = M = L = g = 1$ and $k = 2$ (all in appropriate units), where g is the constant acceleration due to gravity, find the normal frequencies. For each normal frequency, find and describe the motion of the corresponding normal mode.

Answer 9.17.

- (a) If the coordinates of the n degrees of freedom are q_i with corresponding velocities \dot{q}_i , and we keep only quadratic terms in the Lagrangian, we have

$$\mathcal{L} = \frac{1}{2}\dot{q}^T M \dot{q} - \frac{1}{2}q^T K q$$

where the linear terms vanish due to expanding about equilibrium, and we have dropped the irrelevant constant term. Also we have restricted to velocity-independent potentials. Here, we can just take the symmetric parts of the second-order tensors M and K . The corresponding characteristic polynomial equation for the normal frequencies ω_j is

$$\det(K - \omega^2 M) = 0$$

- (b) (i) We have $X(t) = x(t) + L \sin \phi$ and $Y(t) = L(1 - \cos \phi)$, where we let $x(t) = 0$ be vertically underneath the cart. The Lagrangian is

$$\begin{aligned} \mathcal{L} &= \frac{1}{2}m\dot{x}^2 + \frac{1}{2}M(\dot{X}^2 + \dot{Y}^2) - \frac{1}{2}kx^2 - Mgy \\ &= \frac{1}{2}m\dot{x}^2 + \frac{1}{2}M(\dot{x} + 2L \cos \phi \dot{\phi} + L^2 \cos^2 \phi \dot{\phi}^2 + L^2 \sin^2 \phi \dot{\phi}^2) - \frac{1}{2}kx^2 - MgL(1 - \cos \phi) \\ &= \frac{1}{2}(m + M)\dot{x}^2 + \frac{1}{2}m(L^2 \dot{\phi}^2 + 2L\dot{x}\dot{\phi}) - \frac{1}{2}kx^2 - \frac{1}{2}MgL\phi^2 \\ &= \frac{1}{2} \begin{pmatrix} \dot{x} & \dot{\phi} \end{pmatrix} \begin{pmatrix} m+M & ML \\ ML & L^2 \end{pmatrix} \begin{pmatrix} \dot{x} \\ \dot{\phi} \end{pmatrix} - \frac{1}{2} \begin{pmatrix} x & \phi \end{pmatrix} \begin{pmatrix} k & 0 \\ 0 & MgL \end{pmatrix} \begin{pmatrix} x \\ \phi \end{pmatrix} \end{aligned}$$

The corresponding equations of motion (use Euler-Lagrange equations to extremize the Lagrangian) is a system of ODE:

$$\begin{aligned} 0 &= \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}} - \frac{\partial \mathcal{L}}{\partial q} \\ &= \frac{d}{dt} \begin{pmatrix} m+M & ML \\ ML & L^2 \end{pmatrix} \begin{pmatrix} \dot{x} \\ \dot{\phi} \end{pmatrix} + \begin{pmatrix} k & 0 \\ 0 & MgL \end{pmatrix} \begin{pmatrix} x \\ \phi \end{pmatrix} \end{aligned}$$

- (ii) The matrix equation (equation of motion) is now

$$0 = \frac{d}{dt} \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \dot{x} \\ \dot{\phi} \end{pmatrix} + \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ \phi \end{pmatrix}$$

Hence, the characteristic polynomial gives

$$0 = \det \begin{pmatrix} 2 - 2\omega^2 & -\omega^2 \\ -\omega^2 & 1 - \omega^2 \end{pmatrix} = 2(1 - \omega^2)^2 - \omega^2 \implies \omega^2 = \frac{\sqrt{2}}{\sqrt{2} \pm 1} = 2 \mp \sqrt{2}$$

Plug these normal frequencies back to the system of linear equations:

$$\mathbf{0} = \begin{pmatrix} 2 - 2(2 \pm \sqrt{2}) & -(2 \pm \sqrt{2}) \\ -(2 \pm \sqrt{2}) & 1 - (2 \pm \sqrt{2}) \end{pmatrix} \begin{pmatrix} a_{\pm} \\ b_{\pm} \end{pmatrix}$$

which gives the eigenvectors $(\mp 1, \sqrt{2})^T$ for the normal frequencies $\sqrt{2 \pm \sqrt{2}}$ respectively (anti-phase and in-phase respectively).

Problem 9.18 (Group Theory):

- (a) Let G, G' be two finite groups and let $f : G \rightarrow G'$ be a group homomorphism. Let $a \in G$. Show that the order of $f(a)$ is at most the order of a . Show that if f is an isomorphism then a and $f(a)$ have the same order. [6]
- (b) If $a, b \in G$ show that ab and ba have the same order. [7]
- (c) Let G be a finite group where the order of each element is at most 2. Show that G is abelian. [7]

Answer 9.18.

- (a) Let the order of $a \in G$ be $\text{ord}(a)$, then $a^{\text{ord}(a)} = e$, the identity of G . Let $f : G \rightarrow G'$ be a homomorphism, then for $a_1, a_2 \in G$,

$$f(a_1)f(a_2) = f(a_1a_2)$$

Suppose $f(a)$ has order $p < \text{ord}(a)$, then $e = [f(a)]^p = f(a^p)$ where we used the fact that f is a homomorphism. This is possible since f is not specified to be injective, so e is not the unique element that maps to e .

Suppose $f(a)$ has order $\text{ord}(a) + 1$, then

$$e = (f(a))^{\text{ord}(a)+1} = f(a)(f(a))^{\text{ord}(a)} = f(a)[f(a^{\text{ord}(a)})] = f(a)f(e) = f(a)$$

This contradicts since $\text{ord}(a) + 1$ is constructed to be the smallest positive integer power for $f(a)$ to be raised to obtain the identity. But we found a smaller integer, i.e. 1. So, $f(a)$ must have order at most $\text{ord}(a)$.

If f is an isomorphism, it must be injective, so $f(a^p) = e$ is not allowed, and so for $[f(a)]^p = e$, $p = \text{ord}(a)$.

- (b) Let the order of ab be r , then

$$e = (ab)^r = (ab)^r aa^{-1} = a(ba)^r a^{-1} \implies (ba)^r = a^{-1}ea = e$$

so the order of ba is $r = \text{ord}(ab)$.

- (c) For $g \in G$ and $g \neq e$, then $\text{ord}(g)$ is specified to be 2. Consider such $g_1, g_2 \in G$ where $g_1 \neq g_2$, then

$$e = g_1^2 = g_2^2$$

Consider g_1g_2

$$g_1g_2 = g_2^2g_1g_2g_1^2 = g_2(g_2g_1)^2g_1 = g_2g_1$$

Hence, G is abelian.

Problem 9.19 (Group Theory):

- (a) Let G be a group, and H_1 and H_2 two subgroups of G . Show that the claims (I) and (II) below are equivalent. [10]

I. $H_1 \cap H_2 = \{1\}$ and any element $g \in G$ can be written as $g = h_1 h_2$, where $h_1 \in H_1$ and $h_2 \in H_2$.

II. Any element $g \in G$ can be written in a unique way as $g = h_1 h_2$ where $h_1 \in H_1$ and $h_2 \in H_2$.

- (b) Let H_1 be the group of matrices generated by $\left\{ \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right\}$ and let H_2 be the (cyclic) group generated by the single matrix $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$. Also let G be the smallest group containing H_1 and H_2 . How many elements does G have? [5]

Show that G , H_1 and H_2 satisfy the condition (I). [5]

Answer 9.19.

- (a) Consider the direct product group $H_1 \times H_2$ and the function

$$\begin{aligned} \phi : H_1 \times H_2 &\rightarrow G \\ (h_1, h_2) &\mapsto h_1 \cdot h_2 \end{aligned}$$

where $h_1 \in H_1$ and $h_2 \in H_2$. We want to show if $H_1 \cap H_2 = \{1\}$, then ϕ is an isomorphism such that (h_1, h_2) is mapped to a unique element $h_1 h_2 \in G$. Firstly, check that ϕ is a homomorphism:

$$\phi((h_1, h_2) \cdot (h'_1, h'_2)) = \phi((h_1 h'_1, h_2 h'_2)) = h_1 h'_1 h_2 h'_2 = h_1 h_2 h'_1 h'_2 = \phi((h_1, h_2)) \phi((h'_1, h'_2))$$

Given for each $g \in G$, $\exists h_1 \in H_1, h_2 \in H_2$ s.t. $g = h_1 h_2$, then ϕ is surjective. If $\phi((h_1, h_2)) = 1$, then $h_1 h_2 = 1$, and so $h_1 = h_2^{-1} \in H_1, H_2$, so if $H_1 \cap H_2 = \{1\}$, then $1 \in H_1, H_2$. Hence, $(h_1, h_2) = (1, 1) \in \text{Ker } \phi$ (this homomorphism has trivial kernel) and so ϕ is an isomorphism.

Conversely, if we can show $g = h_1 h_2$ is a unique decomposition, then there is a bijective mapping between G and $H_1 \times H_2$. Since we can construct an isomorphism, the kernel of this bijective mapping is trivial, and so $(1, 1) \in \text{Ker } \phi \implies H_1 \cap H_2 = \{1\}$.

- (b) Let the corresponding groups generated be

$$H_1 = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, -\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right\} := \{e, a, b, ab\}$$

$$H_2 = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right\} := \{e, c\}$$

where $\text{ord}(a) = \text{ord}(b) = \text{ord}(ab) = \text{ord}(c) = 2$. Note a and b commute but not a and c or b and c . The smallest group G containing H_1 and H_2 is

$$G = \{e, a, b, ab, c, ac, bc, abc\}$$

with group table:

	e	a	b	ab	c	ac	bc	abc
e	e	a	b	ab	c	ac	bc	abc
a	a	e	ab	b	ac	c	abc	bc
b	b	ab	e	a	bc	abc	c	ac
ab	ab	b	a	e	abc	bc	ac	c
c	c	ac	bc	abc	e	a	b	ab
ac	ac	c	abc	bc	a	ab	e	b
bc	bc	c	abc	ac	b	e	ab	a
abc	abc	bc	ac	c	ab	a	b	e

where we have the following identities: $ab = ba$, $ac = cb = -bc$ and $bc = ca = -ac$. Check group axioms:

- closure: the rows of the group table are identical up to permutations.
- associative: matrix multiplication is associative.
- identity: $e \in G$.
- inverse: a, b, ab, c and abc are their own self-inverse, while $(ac)^{-1} = bc$.

So G is a group and $|G| = 8$.

Obvious $H_1 \cap H_2$ is the identity matrix. For G to be closed and since G contains H_1 and H_2 , then $g = h_1 h_2$ for some $h_1 \in H_1$ and $h_2 \in H_2$, thus satisfying (I). Note that (II) is not satisfied since $h_1 h_2 \neq h_2 h_1$ (non-unique decomposition).

Problem 9.20 (Representation Theory):

- (a) Let D be a representation of G ; i.e. a homomorphism $D : G \rightarrow \text{GL}(n, \mathbb{C})$, where $\text{GL}(n, \mathbb{C})$ is the group of $n \times n$ invertible complex matrices. What does it mean for a vector subspace $W \subset \mathbb{C}^n$ to be an invariant subspace with respect to D ? What does it mean for D to be irreducible? [4]
- (b) Let $D_1 : G \rightarrow \text{GL}(n, \mathbb{C})$ be a representation, and define

$$D_2(g) = [D_1(g^{-1})]^\dagger$$

where \dagger denotes the hermitian conjugate. Show that D_2 is a representation. [6]

- (c) Suppose that W is an invariant subspace of \mathbb{C}^n with respect to D_2 . Show that W_\perp is an invariant subspace of \mathbb{C}^n with respect to D_1 , where W_\perp is the vector space of vectors orthogonal to W . Hence show that if D_1 is irreducible then D_2 must also be irreducible. [10]

Answer 9.20.

- (a) $W \subset \mathbb{C}^n$ is said to be an invariant subspace with respect to the representation D if for any vector $w \in W$,

$$D(g)(w) \in W \subset \mathbb{C}^n \quad \forall g \in G$$

If D is irreducible, then D has no non-trivial invariant subspaces (trivial subspaces are the nullspace and the entire vector space), and the matrices of D cannot be transformed into block-diagonal form.

- (b) For D_2 to be a representation, it must be a homomorphism. For $g_1, g_2 \in G$, then

$$D_2(g_1)D_2(g_2) = [D_1(g_1^{-1})]^\dagger [D_1(g_2^{-1})]^\dagger = [D_1(g_2^{-1})D_1(g_1^{-1})]^\dagger = [D_1(g_2^{-1}g_1^{-1})]^\dagger = D_2(g_1g_2)$$

- (c) Suppose W is an invariant subspace of \mathbb{C}^n with respect to D_2 , then

$$D_2(g)(w) \in W \quad \forall w \in W, \forall g \in G$$

Then $\forall y \in W_\perp$, we must have $(D_2(g)(w))^\dagger y = 0$ (inner product) since $D_2(g)(w) \in W$.

$$0 = w^\dagger D_2(g)^\dagger y = w^\dagger D_1(g^{-1})y \implies D_1(g^{-1})y \in W_\perp$$

Hence, W_\perp is an invariant subspace with respect to D_1 . If D_1 is irreducible, D_1 has no invariant subspaces. There will then be no subspaces orthogonal to them and so D_2 is irreducible.

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10.1 Paper 1

Problem 10.1 (Vector Calculus):

- (a) For vector fields
- \mathbf{A}
- and
- \mathbf{B}
- in three dimensions, show that [3]

$$\nabla \times (\mathbf{A} \times \mathbf{B}) = (\mathbf{B} \cdot \nabla)\mathbf{A} - \mathbf{B}(\nabla \cdot \mathbf{A}) - (\mathbf{A} \cdot \nabla)\mathbf{B} + \mathbf{A}(\nabla \cdot \mathbf{B})$$

- (b) State Stokes's theorem, taking care to define all the quantities which appear. [2]

- (c) Elliptic cylindrical coordinates
- (u, v, z)
- are related to Cartesian coordinates
- (x, y, z)
- by

$$x = a \cosh u \cos v, \quad y = a \sinh u \sin v, \quad z = z$$

where $u > 0$, $0 \leq v < 2\pi$, $-\infty < z < \infty$, and a is a positive real constant. Find the basis vectors \mathbf{h}_u , \mathbf{h}_v and \mathbf{h}_z defined by $d\mathbf{r} = \mathbf{h}_u du + \mathbf{h}_v dv + \mathbf{h}_z dz$, show that the coordinates are orthogonal, and find the scale factors h_u , h_v and h_z . [5]

- (d) Describe the surfaces of constant
- u
- , the surfaces of constant
- v
- and the surfaces of constant
- z
- . [3]

- (e) Consider the surface
- S
- with
- $z = c$
- and

$$\frac{x^2}{\cosh^2 1} + \frac{y^2}{\sinh^2 1} \leq a^2$$

where c is a positive constant and the normal to S points in the positive z direction. Calculate

$$\int_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S}$$

where $\mathbf{F} = (2 \sinh u \sin v, -2 \cosh u \cos v, \cosh u)$ in Cartesian coordinates. [7]

Answer 10.1.

- (a) Use suffix notation in Cartesian coordinates to evaluate
- $\nabla \times (\mathbf{A} \times \mathbf{B})$
- :

$$\epsilon_{ijk} \frac{\partial}{\partial x_i} \epsilon_{pqj} A_p B_q \hat{\mathbf{k}} = (\delta_{kp} \delta_{iq} - \delta_{kq} \delta_{ip}) \left(\frac{\partial A_p}{\partial x_i} B_q + \frac{\partial B_q}{\partial x_i} A_p \right) \hat{\mathbf{k}} = \left(\frac{\partial A_k}{\partial x_i} B_i + \frac{\partial B_i}{\partial x_i} A_k - \frac{\partial A_i}{\partial x_i} B_k - \frac{\partial B_k}{\partial x_i} A_i \right) \hat{\mathbf{k}}$$

- (b) Let
- $\mathbf{F} = \mathbf{F}(\mathbf{x})$
- be a continuously differentiable vector field, and let surface
- S
- be orientable, piecewise regular with piecewise smooth boundary
- ∂S
- , then the Stokes' theorem states that
- $\int_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S} = \oint_{\partial S} \mathbf{F} \cdot d\mathbf{x}$
- .

- (c)
- $\mathbf{h}_u = \frac{\partial \mathbf{r}}{\partial u} = (a \sinh u \cos v, a \cosh u \sin v, 0)^T$
- ,
- $\mathbf{h}_v = \frac{\partial \mathbf{r}}{\partial v} = (-a \cosh u \sin v, a \sinh u \cos v, 0)^T$
- ,
- $\mathbf{h}_z = \frac{\partial \mathbf{r}}{\partial z} = (0, 0, 1)^T$
- , where
- $d\mathbf{r} = \mathbf{h}_u du + \mathbf{h}_v dv + \mathbf{h}_z dz$
- . We have
- $h_u = a^2(\sinh^2 u \cos^2 v + \cosh^2 u \sin^2 v) = h_v$
- ,
- $h_z = 1$
- . We can show
- $\mathbf{h}_u \cdot \mathbf{h}_v = 0$
- ,
- $\mathbf{h}_u \cdot \mathbf{h}_z = \mathbf{h}_v \cdot \mathbf{h}_z = 0$
- , hence
- $\{\mathbf{h}_u, \mathbf{h}_v, \mathbf{h}_z\}$
- is an orthogonal set.

- (d) For constant
- u
- and constant
- v
- , we have

$$1 = \cos^2 v + \sin^2 v = \left(\frac{x}{a \cosh u} \right)^2 + \left(\frac{y}{a \sinh u} \right)^2, \quad 1 = \cosh^2 u - \sinh^2 u = \left(\frac{x}{a \cos v} \right)^2 - \left(\frac{y}{a \sin v} \right)^2$$

which are respectively an elliptical cylinder, centred on the z -axis of semi-axes $a \cosh u$ and $a \sinh u$ and a hyperbolic cylinder, centred on the z -axis. For constant z , we have horizontal planes at height $z = c$.

- (e) Surface
- S
- has
- $z = c$
- ,
- $\frac{x^2}{\cosh^2(1)} + \frac{y^2}{\sinh^2(1)} \leq a^2 \implies u = 1$
- . Use Stokes' Theorem,
- C
- is the cross-section in the ellipse in the
- $z = c$
- plane, then

$$\int_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S} = \oint_C \mathbf{F} \cdot d\mathbf{l} = \int_0^{2\pi} (-2 \sinh(1) \cosh(1) a) (\cos^2 v + \sin^2 v) dv = -2\pi a \sinh(2)$$

Problem 10.2 (Partial Differential Equation): The temperature, $T(x, y, t)$, in a two-dimensional bar satisfies

$$\frac{1}{\lambda} \frac{\partial T}{\partial t} = \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right)$$

where $0 \leq x \leq a$, $0 \leq y \leq b$ and λ is a positive constant. The sides $x = 0$ and $x = a$ are held at fixed temperature $T = 0$, whereas the sides $y = 0$ and $y = b$ are insulating, i.e. $\frac{\partial T}{\partial y}|_{y=0} = \frac{\partial T}{\partial y}|_{y=b} = 0$.

- (a) Using separation of variables and carefully explaining your working, show that the general solution can be written as

$$T(x, y, t) = \sum_{n,m} A_{mn} \sin\left(\frac{n\pi x}{a}\right) \cos\left(\frac{m\pi y}{b}\right) \exp\left[-\left(\frac{n^2}{a^2} + \frac{m^2}{b^2}\right)\pi^2 \lambda t\right]$$

where A_{nm} are constants and you should specify the ranges of n and m in the sum. [8]

- (b) The initial temperature is $T(x, y, 0) = x(a - x) \sin^2\left(\frac{2\pi y}{b}\right)$. What is $T(x, y, t)$? [10]

- (c) What is the leading term in $T(x, y, t)$ for large t ? [2]

Answer 10.2.

- (a) Since the boundary conditions are homogeneous, we use separation of variables $T(x, y, t) = X(x)Y(y)\tau(t)$. We have

$$\frac{1}{\lambda} \frac{\tau'}{\tau} = \frac{X''}{X} + \frac{Y''}{Y} = -\mu$$

we further define $\frac{X''}{X} = -\omega^2$. Since $T(0, y, t) = T(a, y, t) = 0$, $\omega = \frac{n\pi}{a}$ and so $X(x) \sim \sin \frac{n\pi x}{a}$. Since $\frac{\partial T}{\partial y}(x, 0, t) = \frac{\partial T}{\partial y}(x, b, t) = 0$, $Y(y) \sim \cos \frac{m\pi y}{b}$. Hence, $\mu = \pi^2\left(\frac{m^2}{b^2} + \frac{n^2}{a^2}\right)$ and so $\tau(t) \sim e^{-\mu\lambda t}$. The general solution will be

$$T(x, y, t) = \sum_{n,m} A_{mn} \sin \frac{n\pi x}{a} \cos \frac{m\pi y}{b} e^{-(\frac{n^2}{a^2} + \frac{m^2}{b^2})\pi^2 \lambda t}$$

- (b) The initial condition is

$$x(a - x) \sin^2 \frac{2\pi y}{b} = T(x, y, 0) = \sum_{n,m} A_{mn} \sin \frac{n\pi x}{a} \cos \frac{m\pi y}{b}$$

Write $\sin^2 \frac{2\pi y}{b} = \frac{1}{2}(1 - \cos \frac{4\pi y}{b})$, then using Fourier series,

$$\frac{1}{2}(1 - \cos \frac{4\pi y}{b}) \int_0^a (ax - x^2) \sin \frac{p\pi x}{a} dx = \sum_{n=1}^{\infty} \sum_{m=0}^{\infty} A_{mn} \cos \frac{m\pi y}{b} \int_0^a \sin \frac{n\pi x}{a} \sin \frac{p\pi x}{a} dx$$

We have $\int (ax - x^2) \sin \nu x dx = a(-\nu^{-1}x \cos \nu x + \nu^{-2} \sin \nu x) + \nu^{-1}x^2 \cos \nu x - 2x\nu^{-2} \sin \nu x - 2\nu^{-3} \cos \nu x$ and $\int_0^a \sin \frac{n\pi x}{a} \sin \frac{p\pi x}{a} dx = \frac{a}{2} \delta_{n,p}$, and thus

$$\frac{1}{2}(1 - \cos \frac{4\pi y}{b}) \frac{2a^3}{p^3 \pi^3} [1 - (-1)^p] = \frac{a}{2} \sum_{m=0}^{\infty} A_{mp} \cos \frac{m\pi y}{b}$$

Doing it again, but it is obvious only $A_{0p} = A_{4p} \neq 0$. Set $p = 2r - 1$, then

$$T(x, y, t) = \sum_{r=1}^{\infty} \frac{4a^3}{(2r-1)^3 \pi^3} \sin \frac{(2r-1)\pi x}{a} \left(1 - \cos \frac{4\pi y}{b} e^{-16\pi^2 \lambda t/b^2}\right) e^{-(2r-1)^2 \pi^2 \lambda t/a^2}$$

- (c) When $t \gg 1$, the $r = 1$ term dominates, and so $T(x, y, t) \approx e^{-\pi^2 \lambda t/a^2} \frac{4a^3}{\pi^3} \sin \frac{\pi x}{a}$.

Problem 10.3 (Green's Functions):

- (a) Consider an inhomogeneous ordinary differential equation of the form

$$y''(x) + p(x)y'(x) + q(x)y(x) = f(x) \quad (*)$$

for $a \leq x \leq b$ subject to homogeneous boundary conditions at $x = a$ and b . Suppose that $y_a(x)$ and $y_b(x)$ are linearly independent solutions of the homogeneous equation (where $f(x) = 0$) and satisfy the boundary conditions at $x = a$ and $x = b$ respectively. Show that the Green's function can be written as

$$G(x, z) = \begin{cases} \frac{y_a(x)y_b(z)}{W(z)} & a \leq x < z \\ \frac{y_b(x)y_a(z)}{W(z)} & z < x \leq b \end{cases}$$

where $W(z) = y_a(z)y'_b(z) - y_b(z)y'_a(z)$. [5]

- (b) Write an expression for
- $y(x)$
- , the solution of (*), in terms of an integral involving
- f
- and
- G
- .
- [1]

- (c) Find the general solution
- $y(x)$
- of

$$\frac{d^2y}{dx^2} - \frac{3}{x} \frac{dy}{dx} + 3 \frac{y}{x^2} = 0$$

[Hint: Consider $y = x^n$.] [3]

- (d) Consider the equation

$$\frac{d^2y}{dx^2} - \frac{3}{x} \frac{dy}{dx} + 3 \frac{y}{x^2} = f(x)$$

for $0 \leq x \leq 1$, with boundary conditions $y(0) = y(1) = 0$.

- (i) Find the Green's function,
- $G(x, z)$
- .
- [3]

- (ii) Find
- $y(x)$
- when
- [8]

$$f(x) = \begin{cases} 0 & 0 \leq x \leq 0.5 \\ x^2 & 0.5 \leq x \leq 1 \end{cases}$$

Answer 10.3.

- (a) The corresponding Green's function satisfy

$$\frac{\partial^2 G(x, z)}{\partial x^2} + p(x) \frac{\partial G(x, z)}{\partial x} + q(x)G(x, z) = \delta(x - z), \quad G(a, z) = G(b, z) = 0$$

We choose the linearly independent homogeneous solutions y_a and y_b such that $y_a(a) = 0$ and $y_b(b) = 0$. Whenever $x \neq z$, we can write $G(x, z)$ as a linear combination of $y_a(x)$ and $y_b(x)$, i.e.

$$G(x, z) = \begin{cases} A(z)y_a(x) + B(z)y_b(x) & a \leq x < z < b \\ C(z)y_a(x) + D(z)y_b(x) & z < x \leq b \end{cases}$$

$G(x = a, z) = 0 \implies 0 = A(z)y_a(a) + B(z)y_b(a) \implies B(z) = 0$ and $G(x = b, z) = 0 \implies 0 = C(z)y_a(b) + D(z)y_b(b) \implies C(z) = 0$. Integrate over an infinitesimal region from $x = \mu$ to $x = \mu + \epsilon$, we get

$$\left[\frac{\partial G}{\partial x} \right]_{\mu}^{\mu+\epsilon} + p(\mu)[G]_{\mu}^{\mu+\epsilon} + q(\mu)G(\mu, z)\epsilon = \delta(\mu - z)$$

Take $\epsilon \rightarrow 0$, G is continuous at $x = z$ (G should be continuous everywhere otherwise $G'' \propto \delta'(x - z)$ which is a contradiction) and $\frac{\partial G}{\partial x}$ is discontinuous at $x = z$ (unit jump). The continuity and jump conditions respectively give

$$A(z)y_a(z) = D(z)y_b(z)$$

$$D(z)y'_b(z) - A(z)y'_a(z) = 1$$

$$\begin{aligned} \begin{pmatrix} y_a(z) & -y_b(z) \\ y'_a(z) & -y'_b(z) \end{pmatrix} \begin{pmatrix} A(z) \\ D(z) \end{pmatrix} &= \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ \Rightarrow \begin{pmatrix} A(z) \\ D(z) \end{pmatrix} &= \frac{1}{-y_a(z)y'_b(z) + y_b(z)y'_a(z)} \begin{pmatrix} -y'_b(z) & y_b(z) \\ -y'_a(z) & y_a(z) \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ &= \frac{1}{W(z)} \begin{pmatrix} y_b(z) \\ y_a(z) \end{pmatrix} \end{aligned}$$

Giving us our desired $G(x, z)$.

$$(b) \quad y(x) = \int_a^b G(x, z) f(z) dz$$

(c) We have $y = x^n$ and so $n^2 - 4n + 3 = 0 \Rightarrow n = 3, 1$. Hence, $y(x) = c_1x + c_2x^3$.

(d) (i) We have $p(x) = -\frac{3}{x}$ and $q(x) = \frac{3}{x^2}$. $y(0) = y(1) = 0$. Choose $y_a(x) = x$ and $y_b(x) = x - x^3$. $W(z) = z(1 - 3z^2) - (z - z^3) = -2z^3$. Hence,

$$G(x, z) = \begin{cases} \frac{z^2-1}{2z^2}x & a \leq x < z \\ \frac{x^3-x}{2z^2} & z < x \leq b \end{cases}$$

(ii)

$$y(x) = x \int_x^1 \frac{z^2-1}{2z^2} f(z) dz + (x^3 - x) \int_0^x \frac{f(z)}{2z^2} dz$$

Consider $x \leq 0.5$, $x < z \leq 1$ which could mean $x \leq 0.5 \leq z \leq 1 \Rightarrow f(z) = z^2$ or $x < z \leq 0.5 \Rightarrow f(z) = 0$; $0 \leq z < x \leq 0.5 \Rightarrow f(z) = 0$. Hence, the solution would be

$$y(x) = \frac{x}{2} \int_{1/2}^1 z^2 - 1 dz = -\frac{5}{48}x$$

Separately, consider $x \geq 0.5$, $0.5 \leq x < z \leq 1 \Rightarrow f(z) = z^2$ and $0 \leq z < x$ either suggests $0 \leq z \leq 0.5 \leq x \Rightarrow f(z) = 0$ or $0 \leq 0.5 \leq z < x \Rightarrow f(z) = z^2$. Then the solution would be

$$\begin{aligned} y(x) &= \frac{x}{2} \int_x^1 z^2 - 1 dz + \frac{x^3 - x}{2} \int_{1/2}^x dz \\ &= \left(\frac{1}{2} - \frac{1}{6}\right)x^4 + \frac{1}{2}x^2 + \left(\frac{1}{4} - \frac{1}{3}\right)x - \frac{1}{4}x^3 - \frac{1}{2}x^2 \\ &= \frac{1}{3}x^4 - \frac{1}{4}x^3 - \frac{1}{12}x \end{aligned}$$

Problem 10.4 (Fourier Transform): The Fourier transform of a function $f(x)$ is given by

$$\tilde{f}(k) = \int_{-\infty}^{\infty} f(x)e^{-ikx} dx$$

(a) Write down the corresponding expression for the inverse Fourier transform. [1]

(b) The convolution of two functions $f(x)$ and $g(x)$ is

$$h(x) = \int_{-\infty}^{\infty} f(z)g(x-z)dz$$

Prove that $\tilde{h}(k) = \tilde{f}(k)\tilde{g}(k)$. [4]

(c) Find an expression for the Fourier transform of $x^n f(x)$ in terms of derivatives of $\tilde{f}(k)$. [4]

(d) Find the Fourier transform of the even function $q(x)$, where [5]

$$q(x) = \begin{cases} 1-x & 0 \leq x \leq 1 \\ 0 & x > 1 \end{cases}$$

(e) Find the Fourier transform of $p(x) = \int_{-1}^1 q(x-z)dz$, where $q(x)$ is as defined in part (d). [6]

Answer 10.4.

(a) $f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{f}(k)e^{ikx} dk$

(b) The convolution of $h(x)$ is

$$\begin{aligned} \tilde{h}(k) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(z)g(x-z)dz e^{-ikx} dx \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(z)g(x-z)e^{-ikx} dx dz \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(z)g(u)e^{-ik(u+z)} du dz \\ &= \int_{-\infty}^{\infty} g(u)e^{-iku} du \int_{-\infty}^{\infty} f(z)e^{0ikz} dz \\ &= \tilde{g}(k)\tilde{f}(k) \end{aligned}$$

where we first swapped the integration order and substitute $x = u + z$, and finally split the integral.

(c) To find the Fourier transform of $x^n f(x)$, evaluate the k th derivative of $\tilde{f}(k)$.

$$\frac{d^n}{dk^n} \tilde{f}(k) = \frac{d^n}{dk^n} \int_{-\infty}^{\infty} f(x)e^{-ikx} dx = (-i)^n \int_{-\infty}^{\infty} x^n f(x)e^{-ikx} dx \implies \mathcal{F}[x^n f(x)] = i^n \frac{d^n}{dk^n} \tilde{f}(k)$$

(d) We evaluate the Fourier transform of $q(x)$, $\tilde{q}(k)$. Exploit the even symmetry of $q(x)$,

$$\begin{aligned} \int_{-\infty}^{\infty} q(x)e^{ikx} dx &= 2 \int_0^{\infty} q(x) \cos(kx) dx \\ &= 2 \int_0^1 (1-x) \cos(kx) dx \\ &= 2 \left(\left[(1-x) \frac{\sin kx}{k} \right]_0^1 + \frac{1}{k} \int_0^1 \sin(kx) dx \right) \\ &= \frac{2}{k^2} (1 - \cos k) \\ &= \frac{4}{k^2} \sin^2 \frac{k}{2} \end{aligned}$$

(e) $p(x)$ is basically a convolution of the rectangular (top-hat) function $\text{rect}(x)$ and $q(x)$. By the convolution theorem,

$$\tilde{p}(k) = \mathcal{F}[\text{rect}(k)]\tilde{q}(k) = \tilde{q}(k) \int_{-1}^1 e^{-ikx} dx = \frac{2}{k} \sin k \frac{4}{k^2} \sin^2 \frac{k}{2}$$

Problem 10.5 (Linear Algebra):

- (a) State the definition of the adjoint A^\dagger of a linear operator A with respect to a general inner product $\langle \mathbf{x} | \mathbf{y} \rangle$. In the special case of the standard dot product on complex vectors, give an expression for the adjoint operator. [4]
- (b) State the definition of an invertible matrix. Assuming that the matrix A is diagonalizable, prove that A is invertible if and only if $\det(A)$ is nonzero. [5]
- (c) Let M be an $n \times n$ matrix with real entries. Show that $M^T M$ is real symmetric and that all its eigenvalues are non-negative. [5]
- (d) Let B be a diagonalizable matrix such that $B^k = 0$ for some integer k . Show that $B = 0$. Give an example of a 2×2 non-zero matrix C such that $C^2 = 0$. [6]

Answer 10.5.

- (a) If $\forall \mathbf{x}, \mathbf{y}$, the inner products $\langle \mathbf{x} | A\mathbf{y} \rangle = \langle Q\mathbf{x} | \mathbf{y} \rangle$, then we say the operator Q is said to be the adjoint of the operator A , i.e. $Q = A^\dagger$. For matrices acting on complex vector spaces, $M^\dagger = (M^T)^* = (M^*)^T$.
- (b) If a matrix is said to be invertible, $\exists P = A^{-1}$ such that $AP = PA = I$.
If a matrix is said to be diagonalizable, \exists an invertible matrix X such that XAX^{-1} is a diagonal matrix.
 $XA^{-1}X^{-1}$ is the inverse to XAX^{-1} :

$$I = AA^{-1} = XAX^{-1}XA^{-1}X^{-1} = XIX^{-1}$$

Let $XAX^{-1} = \text{diag}(\lambda_1, \lambda_2, \dots)$, then $XA^{-1}X^{-1} = \text{diag}(\lambda_1^{-1}, \lambda_2^{-1}, \dots)$ exists iff $\lambda_i \neq 0 \forall i$. Since the determinant of a diagonal matrix is simply the product of the diagonal elements, then a diagonalizable matrix is thus invertible iff $\det(A) \neq 0$.

- (c) Given M is real, $M^T M$ must be real. We evaluate $(M^T M)^T$:

$$(M^T M)^T = M^T (M^T)^T = M^T M$$

$M^T M$ is indeed symmetric. Let \mathbf{e} be an eigenvector of $M^T M$ with eigenvalue λ , then

$$\langle \mathbf{e} | M^T M \mathbf{e} \rangle = \lambda \langle \mathbf{e} | \mathbf{e} \rangle \implies \lambda = \frac{|M\mathbf{e}|^2}{|\mathbf{e}|^2} \geq 0$$

and so $\lambda \in \mathbb{R}$ since norms are real.

- (d) Let B be diagonalizable such that $B^k = 0$. $\exists X$ such that $XBX^{-1} = D$, where D is diagonal. Then,

$$0 = B^k = (X^{-1}DX)^k = X^{-1}D^kX \implies D^k = XDX^{-1} = 0$$

Since D is a diagonal matrix, its k th root consists of zeros off-diagonal, and the diagonal elements of D are diagonal elements of D^k raised to the power of $\frac{1}{k}$, which are merely zeros. So, $D = 0 \implies B = 0$.

We require C to have an eigenvalue to be 0, and its eigenvectors to not be linearly independent. An example is

$$C = \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix}$$

Problem 10.6 (Linear Algebra):

- (a) Let H be an $n \times n$ Hermitian matrix. Explain how to diagonalise H using an appropriate unitary matrix U to obtain a diagonal matrix Λ . What are the entries of Λ ? [4]
- (b) Explain how a quadratic form $\sum_{ij} A_{ij} x_i x_j$, where A_{ij} are real and $A_{ij} = A_{ji}$, can be written in the form $\sum_i a_i x'_i x'_i$. [3]
- (c) Find the eigenvalues and eigenvectors of the matrix

$$B = \begin{pmatrix} 1+c & 0 & 5-c \\ 0 & 3 & 0 \\ 5-c & 0 & 1+c \end{pmatrix}$$

where c is a real constant.

[7]

- (d) Describe the surface $x^T B x = 1$, specifying the principal axes where appropriate. [6]

[Hint: The type of surface may depend on the value of c .]

Answer 10.6.

- (a) Firstly, find the normalized eigenvectors of H , $\{\mathbf{e}_i\}$. Form the matrix U by slotting the normalized eigenvectors into the columns of U . $\Lambda = U^\dagger H U$ will be a diagonal matrix with diagonal elements to be the real eigenvalues of H in the order that the eigenvectors were chosen for the columns of U .

- (b) Let $U^\dagger x = x'$,

$$Q = \sum_{i,j} x_i A_{ij} x_j = \langle x | A x \rangle = \langle x | U U^\dagger A U U^\dagger x \rangle = \langle x' | \Lambda x' \rangle = \sum_i (x'_i)^* \lambda_i x'_i$$

since x_i are real, and the eigenvectors of a real symmetric matrix are real, then x'_i are also real. We thus have $Q = \sum_i \lambda_i x'_i x'_i$, where λ_i are the eigenvalues of the matrix with entries A_{ij} .

- (c) We evaluate the determinant by expanding in the second row:

$$\det \begin{pmatrix} 1+c-\lambda & 0 & 5-c \\ 0 & 3-\lambda & 0 \\ 5-c & 0 & 1+c-\lambda \end{pmatrix} = (3-\lambda) \begin{vmatrix} 1+c-\lambda & 5-c \\ 5-c & 1+c-\lambda \end{vmatrix} = (3-\lambda)(\lambda^2 - 2\lambda - 24 + 12c - 2c\lambda)$$

This gives $\lambda = c$ and $1+c \pm (5-c)$. By inspection, $\mathbf{e}_{\lambda=3} = (0, 1, 0)^T$. For $\lambda = 6$, we evaluate $(B - 6I)x = 0$ and get $\mathbf{e}_{\lambda=6} = \frac{1}{\sqrt{2}}(1, 0, 1)^T$. The last eigenvector must be pairwise orthogonal to the previous two since B is Hermitian. We thus have $\mathbf{e}_{\lambda=2c-4} = \frac{1}{\sqrt{2}}(1, 0, -1)^T$.

- (d) The quadratic surface is

$$1 = \lambda_1 x_1'^2 + \lambda_2 x_2'^2 + \lambda_3 x_3'^2 = 6x_1'^2 + 3x_2'^2 + (2c-4)x_3'^2$$

- $c = 3.5$: $1 = 6x_1'^2 + 3(x_2'^2 + x_3'^2)$ oblate ellipsoid of revolution about the x_1 -axis;
- $c = 5$: $1 = 6(x_1'^2 + x_3'^2) + 3x_2'^2$ prolate ellipsoid of revolution about the x_2 -axis;
- $c > 2$ but not equal to 3.5 or 5: triaxial ellipsoid aligned with the eigenvectors of B ;
- $c = 2$: $1 = 6x_1'^2 + 3x_2'^2$ elliptical cylinder about x_3 -axis;
- $c < 2$: single sheet hyperboloid of elliptical cross-section about x_3 -axis.

Problem 10.7 (Cauchy-Riemann):

(a) State the Cauchy-Riemann equations for an analytic function of $z = x + iy$, $f(z) = u(x, y) + iv(x, y)$, where x, y, u and v are real. [2]

(b) Show that curves of constant u and curves of constant v intersect at right angles. [3]

(c) Find the most general analytic function $f(z)$ with real part

$$u = e^{-x}[(x^2 - y^2) \cos y + 2xy \sin y]$$

writing your final answer in terms of z . [7]

(d) Find and classify the singularities and zeroes of the following functions (including any at the point at infinity) [4]

(i)

$$\frac{z - 4}{z^2 + iz + 6}$$

(ii)

$$\frac{e^{2z}}{\sinh z}$$

(e) Find the power series expansion of

$$g(z) = \frac{1}{z - 2i}$$

about $z = 3$. Find the radius of convergence and comment. [4]

Answer 10.7.

(a) Cauchy-Riemann equations are $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ and $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$.

(b) Using Cauchy-Riemann equations

$$\nabla u \cdot \nabla v = \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial y} = \frac{\partial u}{\partial x} \left(-\frac{\partial u}{\partial y} \right) + \frac{\partial u}{\partial y} \frac{\partial u}{\partial x} = 0$$

So, curves of constant u and v intersect at right angles.

(c) f is analytic would mean f is complex-differentiable and f satisfies the Cauchy-Riemann equations. From the form of $u(x, y) = e^{-x}[(x^2 - y^2) \cos y + 2xy \sin y]$, we guess $f = z^2 e^{-z} = (x^2 + 2ixy - y^2)e^{-x-iy}$. From u and v , we thus verify they do obey Cauchy-Riemann equations.

(d) (i) Let $h(z) = \frac{z-4}{z^2+iz+6}$, then $h(4) = 0 = h(\infty)$, i.e. first order zero. When $z = 2i$, $z = -3i$, then $\lim_{z \rightarrow 2i} h(z)(z - 2i)$ and $\lim_{z \rightarrow -3i} h(z)(z + 3i)$ are finite, so are first order poles.

(ii) Let $j(z) = \frac{e^{2z}}{\sinh(z)}$. Recall $\sinh z = \frac{1}{2}(\sum_{n=0}^{\infty} \frac{z^n}{n!} - \sum_{n=0}^{\infty} \frac{(-z)^n}{n!})$. For $\sinh z = 0$, $z = in\pi$ for $n \in \mathbb{N}$ and hence first order poles at $z = in\pi$. Now, we investigate the behaviour at $z = \infty$ by setting $1/w = z$. Then,

$$\sinh \frac{1}{w} = \frac{1}{2} \left(\sum_{n=0}^{\infty} \frac{w^{-n}}{n!} - (-1)^n \sum_{n=0}^{\infty} \frac{w^{-n}}{n!} \right)$$

which has an essential singularity at $w = 0$, since $\lim_{w \rightarrow 0} (1/w)^N j(1/w)$ is not finite for any finite N value. Thus, $z = \infty$ is an essential singularity.

(e) Expand $g(z)$ about $z = 3$. Let $z - 3 = w$,

$$g(w) = (w + 3 - 2i)^{-1} = (3 - 2i)^{-1} \left(1 + \frac{w}{3 - 2i} \right)^{-1} = \frac{1}{3 - 2i} \sum_{n=0}^{\infty} (-1)^n \left(\frac{w}{3 - 2i} \right)^n$$

Using ratio test for $u_n(w) = (-1)^n \left(\frac{w}{3 - 2i} \right)^n$ for $n \geq 0$:

$$1 = \lim_{n \rightarrow \infty} \left| \frac{u_{n+1}(R)}{u_n(R)} \right| = \lim_{n \rightarrow \infty} \left| \frac{(-1)R}{3 - 2i} \right| = \frac{R}{\sqrt{13}}$$

so the radius of convergence is $\sqrt{13}$. This is also equal to the distance to the nearest pole $z = 2i$ from the expansion of point of $z = 3$, i.e. $\sqrt{(2i)^2 + 3^2} = \sqrt{13}$.

Problem 10.8 (Series Solution to ODE):

- (a) Define an ordinary point and a regular singular point for a second-order ordinary differential equation of the form [2]

$$y''(x) + p(x)y'(x) + q(x)y(x) = 0$$

- (b) Classify the points $x = 0$ and $x = 1$ of

$$(1 - x^3)y''(x) - 6x^2y'(x) - 6xy(x) = 0$$

Find a series solution about $x = 0$ subject to the boundary conditions $y(0) = 1$ and $y'(0) = 0$. Express the solution in closed form. [8]

- (c) Find two linearly-independent series solutions about $x = 0$ of

$$4xy''(x) + 2(1 - x)y'(x) - y(x) = 0$$

In particular, you should find the indicial equation, the recurrence relation and the radius of convergence. Express one solution in closed form. [10]

Answer 10.8.

- (a) For the given ordinary differential equation, the point $x = x_0$ is an ordinary point if neither $p(x_0)$ nor $q(x_0)$ are singular. The point $x = x_1$ is a regular singular point if either $p(x_1)$ or $q(x_1)$ are singular, but both $(x - x_1)p(x_1)$ and $(x - x_1)^2q(x_1)$ are analytic at $x = x_1$.

- (b) $p(x) = -\frac{6x^2}{1-x^3}$ and $q(x) = -\frac{6x}{1-x^3}$ are analytic at $x = 0$, and so $x = 0$ is an ordinary point. $p(x)$ and $q(x)$ are not analytic at $x = 1$, but $(x-1)p(x) = \frac{6x^2}{x^2+x+1}$ and $(x-1)^2q(x) = \frac{6x(x-1)}{x^2+x+1}$ are analytic at $x = 1$, where $x^3 - 1 = (x-1)(x^2 + x + 1)$. Since $x = 0$ is an ordinary point, we try series solution of the form $y(x) = \sum_{n=0}^{\infty} a_n x^n$.

$$0 = \sum_{n=0}^{\infty} a_n n(n-1)x^{n-2} - \sum_{n=0}^{\infty} [a_n n(n-1) + 6na_n + 6a_n]x^{n+1} \implies a_{n+3} = a_n$$

This gives $y(x) = a_0(1 + x^3 + x^6 + \dots) = \frac{a_0}{1-x^3}$. But, $y(0) = 1 \implies a_0 = 1$, and so $y(x) = \frac{1}{1-x^3}$.

- (c) $\frac{2(1-x)}{4x}$ and $-\frac{1}{4x}$ are not analytic at $x = 0$, but $\frac{2(1-x)}{4x}x$ and $-\frac{1}{4x}x^2$ are analytic at $x = 0$, hence $x = 0$ is a regular singular point. Try series solution of the form $y(x) = \sum_{n=0}^{\infty} a_n x^{n+\sigma}$.

$$4 \sum_{n=0}^{\infty} a_n(n+\sigma)(n+\sigma-1)x^{n+\sigma-1} + 2 \sum_{n=0}^{\infty} a_n(n+\sigma)x^{n+\sigma-1} - 2 \sum_{n=0}^{\infty} a_n(n+\sigma)x^{n+\sigma} - \sum_{n=0}^{\infty} a_n x^{n+\sigma} = 0$$

Comparing $x^{\sigma-1}$ terms: $0 = 4a_0\sigma(\sigma-1) + 2a_0\sigma = 2a_0\sigma(2\sigma-1)$ and so if $a_0 \neq 0$, $\sigma = 0$ or $\frac{1}{2}$. Comparing $x^{\sigma+n}$ terms for $n \geq 1$, we obtain the recurrence relation $a_{n+1} = \frac{a_n(2(n+\sigma)+1)}{2(n+1+\sigma)(2(n+\sigma)+1)} = \frac{a_n}{2(n+1+\sigma)}$. For the series to converge, $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| |x| < 1 \forall |x| < 1$, then the radius of convergence is

$$R = \lim_{n \rightarrow \infty} \left| \frac{a_n}{a_{n+1}} \right| = 2 \lim_{n \rightarrow \infty} |n + \sigma + 1| = \infty$$

The radius of convergence is no smaller than the distance from $x = 0$ to the next nearest singular point. The $\sigma = 0$ solution is

$$a_{n+1} = \frac{a_n}{2(n+1)} \implies y_1(x) = a_0 \left[1 + \frac{x}{2} + \frac{1}{2} \left(\frac{x}{2} \right)^2 + \dots \right] = a_0 e^{x/2}$$

To find the other linearly independent solution, use the Wronskian

$$W(x) = e^{-\int^x \frac{2(1-x')}{4x'} dx'} = \frac{e^{x/2}}{\sqrt{x}} \implies y_2(x) = y_1(x) \int^x \frac{W(x')}{y_1(x')^2} dx' = e^{x/2} \int^x \frac{1}{\sqrt{x'}} e^{-x'/2} dx' = 2e^{x/2} \Gamma(0.5)$$

where we used the Gamma function, $\Gamma(x) := \int_0^\infty z^{x-1} e^{-z} dz$.

Problem 10.9 (Variational Principle):

- (a) Explain what is meant by Fermat's principle and the Euler-Lagrange equation. [2]
- (b) Using Fermat's principle, show that:
- (i) when light is incident on a plane mirror the angle of incidence equals the angle of reflection;
 - (ii) if light crosses a planar boundary from a medium of refractive index μ_1 to a medium of refractive index μ_2 , then

$$\sin(\theta_1)\mu_1 = \sin(\theta_2)\mu_2$$
 where θ_1 is the angle of incidence and θ_2 the angle of refraction. [8]
- (c) A thin transparent medium lies in the semi-plane $-\infty < x < \infty$, $0 < y < \infty$. Its refractive index at the point (x, y) is given by $4\sqrt{y}$. A light ray travels from a source at $(-1, 5/4)$ to an observer at $(1, 5/4)$. Show that it may follow either of two possible paths, and derive the equations for these paths. [10]

Answer 10.9.

- (a) Fermat's Principle states that light travels along a path between fixed start and end points such that it minimizes the total time of flight. For the functional $F[y_i] = \int_a^b f(y_i, y'_i; x) dx$ to be stationary, the integrand f must satisfy the Euler-Lagrange equations $\frac{d}{dx} \frac{\partial f}{\partial y'_i} = \frac{\partial f}{\partial y_i}$ for each independent y_i .

- (b) (i) Consider a mirror lying along $y = 0$ and a light beam originating from (x_0, y_0) propagating to (x_1, y_1) with $y_0, y_1 > 0$. The beam reflects off the mirror at the point $(x_r, 0)$. The total time taken is

$$T = \frac{1}{c} \sqrt{(x_r - x_0)^2 + y_0^2} + \frac{1}{c} \sqrt{(x_r - x_1)^2 + y_1^2}$$

Extremizing the time T

$$0 = \frac{dT}{dx_r} = -\frac{1}{c} \left(\frac{x_0 - x_r}{\sqrt{(x_0 - x_r)^2 + y_0^2}} + \frac{x_1 - x_r}{\sqrt{(x_1 - x_r)^2 + y_1^2}} \right) = -\frac{1}{c} (\sin \theta_i + \sin \theta_r)$$

Since $0 \leq \theta_i, \theta_r \leq \frac{\pi}{2}$, then $\theta_i = \theta_r$.

- (ii) Let the planar boundary lie along $y = 0$ and a light beam originating from (x_0, y_0) propagating to (x_1, y_1) with $y_0 y_1 < 0$. The beam touches the interface at $(x_r, 0)$. The total time taken is

$$T = \frac{\mu_1}{c} \sqrt{(x_r - x_0)^2 + y_0^2} + \frac{\mu_2}{c} \sqrt{(x_r - x_1)^2 + y_1^2}$$

Extremizing the time T

$$0 = \frac{dT}{dx_r} = -\frac{1}{c} \left(\mu_1 \frac{x_0 - x_r}{\sqrt{(x_0 - x_r)^2 + y_0^2}} + \mu_2 \frac{x_1 - x_r}{\sqrt{(x_1 - x_r)^2 + y_1^2}} \right) = -\frac{1}{c} (\mu_1 \sin \theta_i - \mu_2 \sin \theta_r)$$

where θ_i and θ_r are measured from the normal in the $y < 0$ and $y > 0$ region respectively. We thus get Snell's Law, with $\theta_i = \theta_1$ and $\theta_r = \theta_2$.

- (c) The total time taken is

$$T = \int dt = \int \frac{\mu}{c} \sqrt{dx^2 + dy^2} = \frac{1}{c} \int_a^b \sqrt{y} \sqrt{1 + y'^2} dx$$

This is extremized when the integrand satisfies the Euler-Lagrange equation. But observe that the integrand is not explicitly dependent on x . Consider $f = f(y, y')$ such that $\frac{\partial f}{\partial x} = 0$, then by chain rule,

$$\frac{df}{dx} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' = 0 + y' \frac{d}{dx} \frac{\partial f}{\partial y'} + \frac{\partial f}{\partial y'} y'' = \frac{d}{dx} y' \frac{\partial f}{\partial y'}$$

Then we immediately see that $f - y' \frac{\partial f}{\partial y'}$ is a constant. Let this be A , then $\sqrt{\frac{y}{1+y'^2}} = A \implies \frac{dy}{\sqrt{y-A^2}} = \pm \frac{dx}{A} \implies y = \left(\frac{x-x_0}{2A}\right)^2 + A^2$. For the given path to pass through $(\pm 1, 5/4)$, then $x_0 = 0$ and $A^2 = 4, 1$. Hence, $y_1 = \frac{x^2}{16} + 4$ and $y_2 = \frac{x^2}{4} + 1$.

Problem 10.10 (Rayleigh-Ritz Method):

- (a) Consider a Sturm-Liouville operator of the form

$$\mathcal{L} = -\frac{d}{dx} \left(\rho(x) \frac{d}{dx} \right) + \sigma(x)$$

The functionals $F[y]$ and $G[y]$ of real functions $y(x)$ are defined by

$$F[y] = \int_{-\infty}^{\infty} y(x) \mathcal{L}y(x) dx, \quad G[y] = \int_{-\infty}^{\infty} w(x) (y(x))^2 dx$$

Assuming that $y(x) \rightarrow 0$ as $x \rightarrow \pm\infty$, show that the ratio $\Lambda[y] = F[y]/G[y]$ is extremized by solutions of the Sturm-Liouville eigenvalue problem

$$\mathcal{L}y(x) = \lambda w(x)y(x)$$

What are the extremal values of $\Lambda[y]$? [7]

A perturbed quantum harmonic oscillator is defined so that the expectation value of the energy of a particle is

$$E[\psi] = \int_{-\infty}^{\infty} ((\psi')^2 + (x^2 + \epsilon x^4)\psi^2) dx$$

when its state is defined by a real wave function $\psi(x)$ obeying

$$\int_{-\infty}^{\infty} (\psi(x))^2 dx = 1$$

and $\psi(x) \rightarrow 0$ as $x \rightarrow \pm\infty$.

- (b) Consider the case $\epsilon = 2$, and obtain the minimum expectation value of the energy for a particle wave function of the form $\psi_{trial}(x) = Ce^{-\alpha x^2/2}$, where C and α are real and $\alpha > 0$. Define the relevant Sturm-Liouville eigenvalue problem. Explain why the calculated minimum expectation value gives an upper bound on the smallest eigenvalue for this problem. [8]

Hint: You may use the result that, for $\alpha > 0$,

$$\int_{-\infty}^{\infty} x^{2n} e^{-\alpha x^2} dx = \frac{(2n)!}{2^{2n} n!} \sqrt{\frac{\pi}{\alpha^{2n+1}}}$$

- (c) Without carrying out an explicit calculation, explain how you might improve this bound. [2]
- (d) Is there a minimum energy if $\epsilon < 0$? Justify your answer briefly. [3]

Answer 10.10.

(a) Consider the first order variation of the Rayleigh quotient $\Lambda[y] = \frac{F[y]}{G[y]}$:

$$\delta\Lambda = \frac{\delta F}{G[y_0]} - \frac{F[y_0]}{G[y_0]^2} \delta G = \frac{1}{G[y_0]} \left(\delta F - \frac{F[y_0]}{G[y_0]} \delta G \right) = \frac{1}{G[y_0]} (\delta F - \Lambda[y_0] \delta G) = \frac{1}{G} \delta(F - \Lambda G)$$

The stationary values of Λ is equivalent to the constrained stationary problem: $\delta(F - \Lambda G) = 0$.

$$\int_{-\infty}^{\infty} -y \frac{d}{dx} \left(\rho(x) \frac{d}{dx} \right) + \sigma(x)y^2 - \lambda w(x)y^2 dx = [-y\rho y']_{-\infty}^{\infty} + \int_{-\infty}^{\infty} \rho y'^2 + y^2(\sigma - \lambda w) dx$$

From the boundary condition $\lim_{x \rightarrow \pm\infty} y(x) = 0$, the boundary term is zero. Apply Euler-Lagrange to the integrand $f(y, y'; x) = \rho y'^2 + y^2(\sigma - \lambda w)$:

$$\frac{d}{dx} \frac{\partial f}{\partial y'} = \frac{\partial f}{\partial y} \implies \frac{d}{dx} 2\rho y' = 2(\sigma - \lambda w)y \implies \lambda w y = -\frac{d}{dx}(\rho y') + \sigma y = \mathcal{L}y$$

The extremal values of Λ are the highest and lowest eigenvalues of \mathcal{L} . The stationary values of Λ form the entire eigenvalue spectrum. Assuming the eigenfunctions form a complete set, then any value of Λ is a slack overestimate of the lowest eigenvalue, but a slack underestimate of the highest eigenvalue.

(b) For the problem, we identify $\rho = 1$, $\sigma = x^2 + 2x^4$, $w = 1$ and $\Lambda = E$. The integrand of E is positive semi-definite, so the eigenspectrum ψ is positive semi-definite. Hence, $E[\psi_{\text{trial}}]$ cannot be an underestimate of the lowest eigenvalue, where ψ_{trial} obeys the boundary conditions. With $\psi_{\text{trial}} = Ce^{-\alpha x^2/2}$, then

$$\begin{aligned} E[\psi] &= \frac{\int_{-\infty}^{\infty} (-\alpha x C e^{-\alpha x^2/2})^2 + (x^2 + 2x^4) C^2 e^{-\alpha x^2} dx}{\int_{-\infty}^{\infty} C^2 e^{-\alpha x^2} dx} \\ &= \frac{C^2 \alpha^2 x^2 e^{-\alpha x^2} + (x^2 + 2x^4) C^2 e^{-\alpha x^2} dx}{\int_{-\infty}^{\infty} C^2 e^{-\alpha x^2} dx} \\ &= \frac{\int_{-\infty}^{\infty} x^2 e^{-\alpha x^2} (1 + \alpha^2) + 2x^4 e^{-\alpha x^2} dx}{\int_{-\infty}^{\infty} e^{-\alpha x^2} dx} \\ &= \frac{(1 + \alpha^2) \frac{2!}{2^2} \sqrt{\frac{\pi}{\alpha^3}} + \frac{2(4!)}{2^4 2!} \sqrt{\frac{\pi}{\alpha^5}}}{\sqrt{\pi/\alpha}} \\ &= \frac{1 + \alpha^2}{2\alpha} + \frac{3}{2\alpha^2} \\ &= \frac{1}{2}\alpha^{-1} + \frac{1}{2}\alpha + \frac{3}{2}\alpha^{-2} \end{aligned}$$

Minimize E with respect to α :

$$0 = \frac{dE}{d\alpha} = -\frac{1}{2\alpha^2} + \frac{1}{2} - \frac{3}{\alpha^3} \implies \alpha^3 - \alpha - 6 = 0$$

which gives $\alpha = 2$ and $\alpha = -1 \pm \sqrt{2}i$. We reject the complex solution since $\alpha \in \mathbb{R}$, then

$$E[\psi] = \frac{1}{2 \times 2} + \frac{1}{2} \times 2 + \frac{3}{2} \times \frac{1}{2^2} = \frac{13}{8}$$

(c) To improve the bound, replace ψ_{trial} with

$$\psi_{\text{trial}} = (a_1 + a_2 x^2 + a_3 x^4 + \dots) C e^{-\alpha x^2}$$

and then minimize with respect to α and the parameters a_i . The more parameters you add, the more accurate the estimate can become.

(d) For $\epsilon < 0$, E is now no longer positive definite, and could take on arbitrarily large negative values. Hence, there is no finite minimum energy.

10.2 Paper 2

Problem 10.11 (Sturm-Liouville):

- (a) Give the general form of a second-order differential operator in Sturm-Liouville form. [2]
 (b) Consider the eigenvalue equation

$$-xy'' - (1-x)y' = ny, \quad 0 \leq x < \infty, \quad (1)$$

where n is a non-negative integer. Find a weight function $w(x)$ to put (1) into Sturm-Liouville form. The solution to (1) is a real polynomial p_n of degree n . Using the normalization $p_n(0) = 1$, compute the polynomials p_0, p_1, p_2 and verify that $\|p_0\|_w^2 = \|p_1\|_w^2 = \|p_2\|_w^2 = 1$, where $\|p\|_w^2 = \int_0^\infty w(x)p(x)^2 dx$. [8]

- (c) Let f be an arbitrary function such that $\|f\|_w^2$ is finite. We are interested in finding the best approximation of f that minimizes

$$\left\| f - \sum_{n=0}^N a_n p_n \right\|_w^2 \quad (2)$$

for a given integer N and real coefficients a_n . Give an expression for the optimal choice of a_0, \dots, a_N that minimizes (2). Compute these values for $f(x) = e^{-x}(1+x)$ and $N = 2$. [5]

- (d) Prove that the polynomials p_n satisfy $\|p_n\|_w^2 = 1$ for all n , assuming the normalization $p_n(0) = 1$. [5]

Hint: You can use the fact that any polynomial of degree d has an expansion $\sum_{n=0}^d c_n p_n$ for some coefficients c_0, \dots, c_d .

Answer 10.11.

(a) $\mathcal{L} = -\frac{d}{dx}\left(\rho(x)\frac{d}{dx}\right) + \sigma(x).$

(b) Multiply (1) by an integration factor $\mu(x)$ to cast to Sturm-Liouville form

$$\mathcal{L} = -\frac{d}{dx}\left(\rho(x)\frac{d}{dx}\right), \quad \frac{1}{\rho(x)}\frac{d\rho}{dx} = \frac{1}{x} - 1 \implies \rho \propto xe^{-x} \implies \mu(x) = e^{-x}$$

Hence, $\mathcal{L}y = -\frac{d}{dx}(xe^{-x}\frac{dy}{dx}) = ne^{-x}y$ with weight function e^{-x} . $p_0(x) = 1$ trivially satisfy normalization. For p_1 , we guess $p_1 = c_1x + c_2$,

$$-(1-x)c_1 = c_1x + c_2 \implies c_2 = -1$$

To satisfy normalization, $c_1 = 1$. For $p_2 = c_3x^2 + c_4x + c_5$, we have

$$-x(2a) - (1-x)(2ax + b) = 2(ax^2 + bx + c) \implies p_2 = ax^2 - 4ax + 2a$$

To satisfy normalization, $p_2(1) = 1 \implies a = 0.5$. Verify that they are indeed normalized, we use the identity $\int_0^\infty x^n e^{-ax} dx = \frac{n!}{a^{n+1}}$.

$$\|p_0\|_w^2 = \int_0^\infty e^{-x} dx = 1$$

$$\|p_1\|_w^2 = \int_0^\infty (1-x)^2 e^{-x} dx = 1 - 2 + 2 = 1$$

$$\|p_2\|_w^2 = \frac{1}{4} \int_0^\infty (x^2 - 4x + 2)^2 e^{-x} dx = \frac{1}{4}(4! + 16 \times 2! + 4 - 8 \times 3! + 4 \times 2! - 16 \times 1!) = 1$$

(c) Define the error to be $e := \|f - \sum_{n=0}^N a_n p_n\|_w^2$. Minimize with respect to a_i ,

$$0 = \frac{\partial E}{\partial a_i} = \frac{\partial}{\partial a_i} \int_0^\infty \left(f - \sum_{n=0}^N a_n p_n\right)^2 e^{-x} dx = \int_0^\infty \left(f - \sum_{n=0}^\infty a_n p_n\right) (-p_i) e^{-x} dx$$

This implies

$$\sum_{n=0}^\infty a_i \int_0^\infty p_i p_n e^{-x} dx = \int_0^\infty f p_i e^{-x} dx \implies a_i = \frac{\int_0^\infty f(x) p_i e^{-x} dx}{\|p_i\|_w^2} \quad \forall i$$

With $f(x) = e^{-x}(1+x)$,

$$a_0 = \int_0^\infty (1+x) e^{-2x} dx = \frac{1}{2} + \frac{1}{2^2} = \frac{3}{4}$$

$$a_1 = \int_0^\infty (1+x)(1-x) e^{-2x} dx = \frac{1}{2} - \frac{2}{2^3} = \frac{1}{4}$$

$$\begin{aligned} a_2 &= \int_0^\infty e^{-2x} (1+x) \frac{1}{4} (x^2 - 4x + 2) dx \\ &= \frac{1}{4} \int_0^\infty e^{-2x} (1+x) \frac{1}{4} (x^2 - 4x + 2) dx \\ &= \frac{1}{4} \left(\frac{3!}{2^4} - 3 \times \frac{2!}{2^3} - 2 \times \frac{1}{2} + 2 \right) \\ &= \frac{5}{8} \end{aligned}$$

(d) Evaluate, $\|p_n\|_w^2$.

$$\int_0^\infty p_n^2 e^{-x} dx = [-p_n^2 e^{-x}]_0^\infty + 2 \int_0^\infty p_n p_n' e^{-x} dx = -(-1) + 2 \int_0^\infty p_n p_n' e^{-x} dx$$

where given the hint, we can expand $p_n' = \sum_{q=0}^{n-1} c_q p_q$, to get

$$\int_0^\infty 2p_n p_n' e^{-x} dx = 2 \sum_{q=0}^{n-1} c_q \int_0^\infty p_n p_q e^{-x} dx = 0$$

since the different polynomials p_n are orthogonal with respect to the weight e^{-x} . Hence, $\|p_n\|_w^2 = 1$.

Problem 10.12 (Laplace's Equation):

- (a) Consider Laplace's equation in spherical polar coordinates when
- $\Psi(r, \theta, \phi)$
- is axisymmetric:

$$\nabla^2 \Psi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \Psi}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \Psi}{\partial \theta} \right) = 0$$

Using separation of variables show that the general solution takes the form

$$\Psi(r, \theta) = \sum_{l=0}^{\infty} \left(A_l r^l + B_l r^{-l-1} \right) P_l(\cos \theta)$$

where $P_l(u)$ is the Legendre polynomial of degree l , the solution of the Legendre equation $\frac{d}{du}[(1-u^2)\frac{dP_l}{du}] + \lambda P_l(u) = 0$ with $\lambda = l(l+1)$. [Hint: You may assume without proof that the Legendre equation has solutions which are well-behaved at $u = \pm 1$ only for such choices of λ .] [10]

- (b) Assuming the boundary condition
- $\Psi = 1 + 2 \cos \theta - 3 \sin^2 \theta$
- on the surface of a sphere of radius
- a
- , find
- Ψ
- inside and outside the sphere assuming that
- Ψ
- is finite everywhere and
- $\Psi \rightarrow 0$
- as
- $r \rightarrow \infty$
- . [Hint: You may use the fact that
- $P_0(u) = 1$
- ,
- $P_1(u) = u$
- , and
- $P_2(u) = (3u^2 - 1)/2$
- .]
- [10]

Answer 10.12.

- (a) Use separation of variables:
- $\Psi(r, \theta) = R(r)\Theta(\theta)$
- :

$$\frac{1}{R} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = -\frac{1}{r^2 \sin \theta} \frac{1}{\Theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) = \frac{\lambda}{r^2}$$

for some constant λ . The angular part gives

$$\lambda \Theta = -\frac{1}{\sin \theta} \frac{d\Theta}{d\theta} = -\frac{1}{\sqrt{1-x^2}} (-\sqrt{1-x^2}) \frac{d}{dx} \left(-(\sqrt{1-x^2})^2 \frac{d\Theta}{dx} \right)$$

where we substitute $x = \cos \theta$. This result is identical to the hint. At $x = \pm 1$, $\Theta(x) = P_l(x)$ with $\lambda = l(l+1)$. The radial part gives

$$\lambda R = \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = 2rR' + r^2 R''$$

Try $R = r^k$, then $k(k+1) = \lambda = l(l+1) \implies k = l, -(l+1)$. Hence, $R(r) = A_l r^l + B_l r^{-(l+1)}$. Fitting them together gives the desired $\Psi(r, \theta)$.

- (b) Since
- $\Psi(r=0, \theta)$
- is finite, then for
- $r < R$
- ,
- $B_l = 0 \forall l$
- . Also,
- $\lim_{r \rightarrow \infty} \Psi(r, \theta) = 0$
- , then for
- $r > R$
- ,
- $A_0 = 0 \forall l$
- . The boundary condition is

$$\Psi(a, \theta) = 1 + 2 \cos \theta - 3 \sin^2 \theta = -1 + 2 \cos \theta + 2 \frac{1}{2} (3 \cos^2 \theta - 1) = -P_0(\cos \theta) + 2P_1(\cos \theta) + 2P_2(\cos \theta)$$

$$\Psi(r=a, \theta)_{r < R} = \sum_{l=0}^{\infty} A_l a^l P_l(\cos \theta) \implies A_0 = -1, \quad A_1 a = 2, \quad A_2 a^2 = 2, \quad A_n = 0 \forall n \geq 3$$

$$\Psi(r=a, \theta)_{r > R} = \sum_{l=0}^{\infty} B_l a^{-l-1} P_l(\cos \theta) \implies B_0 a^{-1} = -1, \quad B_1 a^{-2} = 2, \quad B_2 a^{-3} = 2, \quad B_n = 0 \forall n \geq 3$$

$$\implies \Psi(r, \theta) = \begin{cases} -1 + \frac{2r}{a} \cos \theta + \frac{r^2}{a^2} (3 \cos^2 \theta - 1) & r < a \\ -\frac{a}{r} + \frac{2a^2}{r^2} \cos \theta + \frac{a^3}{r^3} (3 \cos^2 \theta - 1) & r > a \end{cases}$$

Problem 10.13 (Green's Functions):

- (a) State the definition of the fundamental solution of Laplace's equation $\nabla^2 u = 0$ in two dimensions. Show that it is given by

$$G(\mathbf{r}, \mathbf{r}') = A \ln |\mathbf{r} - \mathbf{r}'| + B$$

where A is a constant that you should specify, and B is an arbitrary constant. [5]

- (b) Define the Green's function for Laplace's equation with Dirichlet boundary conditions in a two-dimensional region D with boundary C . Using the method of images, give an expression for the Green's function when D is the unit disc $0 \leq r < 1$. [You should verify that your solution satisfies the appropriate boundary conditions.] [5]

- (c) Using Green's identity deduce that the solution to $\nabla^2 u = 0$ in the unit disc subject to the boundary condition $u = f$ on $r = 1$ is

$$u(r, \phi) = \frac{1}{2\pi} \int_0^{2\pi} f(\phi') P(r, \phi - \phi') d\phi'$$

for some function $P(r, \phi - \phi')$ that you should specify. [5]

- (d) Assuming that the function f satisfies $f(\phi') \geq 0$ for all ϕ' in the range $0 \leq \phi' < 2\pi$, show that $u(r, \phi) \leq \frac{1+r}{1-r} u(0)$ for all $0 < r < 1$, where $u(0)$ is the value of u at the origin. [5]

Answer 10.13.

- (a) The fundamental solution satisfies $\nabla^2 G(\mathbf{r}, \mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}')$ for all space. Now substitute $\mathbf{R} = \mathbf{r} - \mathbf{r}'$ and integrate both sides over a circle of radius ϵ centred on $\mathbf{R} = \mathbf{0}$ ($S = \{|\mathbf{r}| \leq \epsilon\}$):

$$\oint_{\partial S} \nabla G \cdot d\mathbf{l} = \int_S \nabla^2 G dA = \int_S \delta dA = 1$$

where we used the two-dimensional Divergence Theorem. Since there is circular symmetry about $\mathbf{R} = 0$, then $\nabla G = \frac{dG}{dr} \hat{\mathbf{r}}$ and $G = G(r)$.

$$1 = \oint_{\partial S} \frac{dG}{dr} \bigg|_{r=\epsilon} \epsilon d\theta = \frac{dG}{dr} \bigg|_{r=\epsilon} 2\pi r \implies G = \frac{1}{2\pi} \ln r + B = \frac{1}{2\pi} \ln |\mathbf{r} - \mathbf{r}'| + B$$

where B is some arbitrary integration constant and $A = \frac{1}{2\pi}$.

- (b) $D = \{|\mathbf{r}| \leq 1\}$ and thus $\nabla^2 G = \delta(\mathbf{x} - \mathbf{x}_0)$ inside D , with Dirichlet's boundary condition $G = 0$ on the boundary C . From Uniqueness Theorem, we may solve a corresponding problem with mirror images, and thus assert that this solution is the only solution. Here, we place a source on \mathbf{x}_0 and an image outside D at \mathbf{x}_1 . In that case, the Green's function of this corresponding problem satisfy

$$\nabla^2 G = \delta(\mathbf{x} - \mathbf{x}_0) - \delta(\mathbf{x} - \mathbf{x}_1)$$

If we were to restrict $\mathbf{x} \in D$, then we recover $\nabla^2 G = \delta(\mathbf{x} - \mathbf{x}_0)$ again. Since the Laplacian is linear, the solution will be a linear combination of the fundamental solution in 2D (as derived in part (a)).

$$G = \frac{1}{2\pi} \ln |\mathbf{x} - \mathbf{x}_0| - \frac{1}{2\pi} \ln |\mathbf{x} - \mathbf{x}_1| + B$$

The image problem has to satisfy the Dirichlet's boundary condition as well, $G = 0$. Consider two triangles OAC and OBA such that the position vectors of A , B and C are respectively \mathbf{x} , \mathbf{x}_1 and \mathbf{x}_0 . A is an arbitrary point on the boundary C . Since $\angle AOC = \angle AOB$ (common angle) and both triangles share one common side AO , then the triangles OAC and OBA are similar:

$$\frac{OB}{OA} = \frac{AB}{AC} = \frac{OA}{OC} \implies |\mathbf{x}_1| = \frac{|\mathbf{x} - \mathbf{x}_1|}{|\mathbf{x} - \mathbf{x}_0|} = \frac{1}{|\mathbf{x}_0|}$$

Plugging back into our solution, we have $B = \frac{-1}{2\pi} \ln |\mathbf{x}_0|$.

(c) We state the Green's identity in two-dimensions:

$$\int_D u \nabla^2 G dA = \int_D G \nabla^2 u dA + \oint_C u \nabla G \cdot d\mathbf{l} - \oint_C G \nabla u \cdot d\mathbf{l} \implies \int_D u \nabla^2 G dA = 0 + \oint_C u \nabla G \cdot d\mathbf{l} - 0$$

where we have $\nabla^2 u = 0$ in D and $G = 0$ on D (assert Dirichlet's boundary condition for G since $u = f$ on $r = 1$ is known). Next, we rewrite the solution from part (b) in terms of ϕ and ϕ' , where $\mathbf{x}_0, \mathbf{x}_1$ and \mathbf{x} respectively subtend an angle ϕ and ϕ' with respect to the x -axis.

$$G = \frac{1}{2\pi} \ln \sqrt{\frac{x^2 + x_0^2 - 2xx_0 \cos(\phi - \phi')}{x^2 + x_1^2 - 2xx_1 \cos(\phi - \phi')}} + B$$

$$\implies \frac{\partial G}{\partial x} = \frac{1}{4\pi} \left[\frac{2x - 2x_0 \cos(\phi - \phi')}{x^2 + x_0^2 - 2xx_0 \cos(\phi - \phi')} - \frac{2x - 2x_1 \cos(\phi - \phi')}{x^2 + x_1^2 - 2xx_1 \cos(\phi - \phi')} \right]$$

Recall $|\mathbf{x}_1| = \frac{1}{|\mathbf{x}_0|}$ and set $x = 1$ as given, then

$$\left. \frac{\partial G}{\partial x} \right|_{x=1} = \frac{2}{4\pi} \left[\frac{1 - x_0 \cos(\phi - \phi') - x_0^2(1 - x_0^{-1} \cos(\phi - \phi'))}{1 + x_0^2 - 2x_0 \cos(\phi - \phi')} \right]$$

Then

$$u(x_0) = \int_D u \nabla^2 G \cdot d\mathbf{A} = \oint_C u \nabla G \cdot d\mathbf{l} = \oint_C \frac{1 - x_0^2}{2\pi} \frac{f d\phi'}{1 + x_0^2 - 2x_0 \cos(\phi - \phi')}$$

where $P(r, \phi - \phi') = \frac{1 - r^2}{1 + r^2 - 2r \cos(\phi - \phi')}$.

(d) Observe that $(1 - r)^2 \leq 1 + r^2 - 2r \cos(\phi - \phi')$ since $\cos x \leq 1 \forall x$. Then,

$$u(r, \phi) = \frac{1 - r^2}{2\pi} \int_0^{2\pi} \frac{f d\phi'}{1 + r^2 - 2r \cos(\phi - \phi')} \leq \frac{1 - r^2}{2\pi} \int_0^{2\pi} \frac{f d\phi}{(1 - r)^2} = \frac{1 + r}{1 - r} \frac{1}{2\pi} \int_0^{2\pi} f d\phi$$

But, $u(0)$ is exactly $\frac{1}{2\pi} \int_0^{2\pi} f d\phi'$ at the origin.

Problem 10.14 (Contour Integration):

- (a) Define the residue of a complex function $f(z)$ at a pole $z = z_0$, assuming f is analytic in a region $0 < |z - z_0| < R$ around z_0 , where R is a positive real number. [2]
- (b) Assuming $g(z)$ is analytic everywhere in the complex plane, what is the residue of $\frac{g(z)}{z - z_0}$ at $z = z_0$? [2]
- (c) State the residue theorem, clearly including all the assumptions. Use it to show that $\frac{1}{2\pi i} \oint_C \frac{f(z)}{z - z_0} dz = f'(z_0)$, where C is a contour encircling z_0 anticlockwise and f is analytic in the region enclosed by C . [6]
- (d) Using contour integration methods compute the following integrals: [10]
- (i) $\int_{-\infty}^{\infty} \frac{1}{(x^2+1)(x^2+4)} dx$;
- (ii) $\int_0^{2\pi} \frac{d\theta}{5-3\sin\theta}$

Answer 10.14.

- (a) If $f(z)$ has a pole at $z = z_0$, then the residue is the coefficient of $(z - z_0)^{-1}$ in the Laurent expansion about that point. If the pole is of order N , it is equal to

$$a_{-1} = \frac{1}{(N-1)!} \lim_{z \rightarrow z_0} \frac{d^{N-1}}{dz^{N-1}} [(z - z_0)^N f(z)]$$

In general, it is equal to $\frac{1}{2\pi i} \oint_C f(z) dz$, where C is a closed curve entirely within the annulus, $0 < |z - z_0| < R$ such that it winds once only around the point z_0 in the anti-clockwise manner.

- (b) The residue of $\frac{g(z)}{z - z_0}$ is $g(z_0)$.
- (c) Suppose f is analytic in a simply-connected domain except at a finite number of isolated singularities $\{z_1, \dots, z_n\}$. Suppose a simple closed contour γ encircles the origin anticlockwise, then the residue theorem states

$$\oint_{\gamma} f(z) dz = 2\pi i \sum_{k=1}^n \text{res}_{z=z_k} f(z)$$

If the curve γ was self-intersecting, we need to modify the theorem by accounting for the winding number (which could be positive or negative) around each pole individually.

Since f is analytic, so is f' . Write

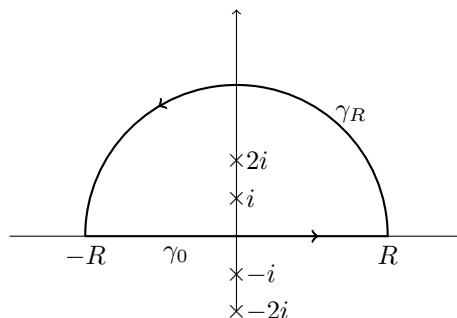
$$f'(z_0) = \frac{1}{2\pi i} \oint_C \frac{f'(z)}{z - z_0} dz = \oint_C \frac{f(z)}{(z - z_0)^2} dz \frac{1}{2\pi i}$$

where we integrate by parts and C is closed.

- (d) (i) Consider

$$\oint_C \frac{1}{(z^2+1)(z^2+4)} dz$$

The integrand has simple poles at $\pm i$ and $\pm 2i$. Choose C to be a semicircle of radius R , then



The individual contour contributions are

$$\lim_{R \rightarrow \infty} \int_{\gamma_0} \frac{1}{(z^2 + 1)(z^2 + 4)} dz = \lim_{R \rightarrow \infty} \int_{-R}^R \frac{1}{(x^2 + 1)(x^2 + 4)} dx = \int_{-\infty}^{\infty} \frac{1}{(x^2 + 1)(x^2 + 4)} dx$$

$$\lim_{R \rightarrow \infty} \int_{\gamma_R} \frac{1}{(z^2 + 1)(z^2 + 4)} dz = \lim_{R \rightarrow \infty} \int_0^{\pi/2} \frac{iRe^{i\theta} d\theta}{(R^2 e^{2i\theta} + 1)(R^2 e^{i2\theta} + 4)} = \lim_{R \rightarrow \infty} O(R^{-3}) = 0$$

So as $R \rightarrow \infty$,

$$\oint_C \frac{1}{(z^2 + 1)(z^2 + 4)} dz = \int_{\gamma_0} \frac{1}{(z^2 + 1)(z^2 + 4)} dz + \int_{\gamma_R} \frac{1}{(z^2 + 1)(z^2 + 4)} dz \rightarrow \int_{-\infty}^{\infty} \frac{dx}{(x^2 + 1)(x^2 + 4)}$$

The poles enclosed are $z = 2i$ and $z = i$ with residues

$$\text{res}_{z=i} \frac{1}{(z^2 + 1)(z^2 + 4)} = \lim_{z \rightarrow i} \frac{z - i}{(z^2 + 1)(z^2 + 4)} = \lim_{z \rightarrow i} \frac{1}{2z(z^2 + 4)} = -\frac{i}{6}$$

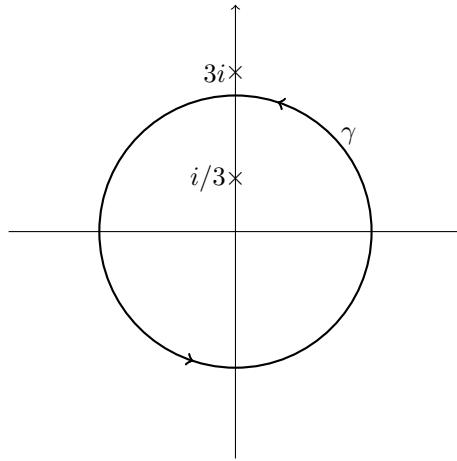
$$\text{res}_{z=2i} \frac{1}{(z^2 + 1)(z^2 + 4)} = \lim_{z \rightarrow 2i} \frac{z - 2i}{(z^2 + 1)(z^2 + 4)} = \lim_{z \rightarrow 2i} \frac{1}{2z(z^2 + 1)} = \frac{i}{12}$$

Hence, by residue theorem,

$$\int_{-\infty}^{\infty} \frac{1}{(x^2 + 1)(x^2 + 4)} dx = 2\pi i(-i/6 + i/12) = \frac{\pi}{6}$$

(ii) Consider integrating along the unit circle $\gamma: z = e^{i\theta}$, $\theta \in [0, 2\pi)$.

$$\int_0^{2\pi} \frac{d\theta}{5 - 3\sin\theta} = \oint_{\gamma} \frac{dz}{iz} \frac{1}{5 - 3(1/2i)(z - z^{-1})} = \frac{1}{i} \oint_{\gamma} \frac{dz}{5z - (3/2i)(z^2 - 1)} = \frac{-2}{3} \oint_{\gamma} \frac{dz}{(z - 3i)(z - (i/3))}$$



The integrand has poles at $z = 3i$ and $z = i/3$, but only the latter is enclosed in the unit circle. The residue is

$$\text{res}_{z=i/3} \frac{-2}{3(z - 3i)(z - (i/3))} = \lim_{z \rightarrow i/3} \frac{-2}{3(z - 3i)} = \frac{-i}{4}$$

Using residue theorem,

$$\int_0^{2\pi} \frac{d\theta}{5 - 3\sin\theta} = 2\pi i \frac{-i}{4} = \frac{\pi}{2}$$

Problem 10.15 (Transform Methods):

- (a) Using contour integration methods, show that for any complex number
- a

$$\int_{-\infty}^{\infty} e^{-(u+a)^2} du = \sqrt{\pi}$$

[Hint: You may use the fact that $\int_{-\infty}^{\infty} e^{-u^2} du = \sqrt{\pi}$.] [6]

- (b) The Fourier transform of a function
- $f(x)$
- that satisfies
- $f(x) \rightarrow 0$
- as
- $|x| \rightarrow \infty$
- is defined as

$$\tilde{f}(k) = \int_{-\infty}^{\infty} f(x) e^{-ikx} dx$$

Consider a function $u(x, t)$ that satisfies

$$\frac{\partial u}{\partial t} = \lambda \frac{\partial^2 u}{\partial x^2}$$

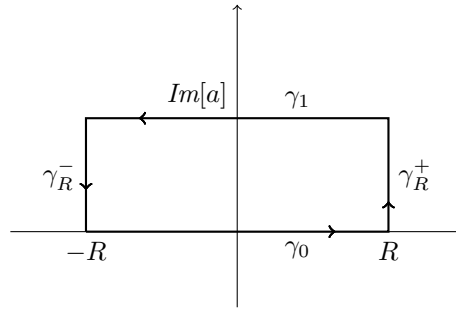
Using Fourier transform methods, assuming that $u(x, t) \rightarrow 0$ as $|x| \rightarrow \infty$, show that the solution is given by [8]

$$u(x, t) = \frac{1}{\sqrt{4\pi\lambda t}} \int_{-\infty}^{\infty} e^{-\frac{(x-y)^2}{4\lambda t}} u(y, 0) dy$$

- (c) When $u(y, 0) = \frac{a}{\sqrt{\pi}} e^{-\alpha^2 y^2}$, with $\alpha > 0$, show that $u(x, t) = \frac{\beta}{\sqrt{\pi}} e^{-\beta^2 x^2}$ for a β that you should specify in terms of α , λ and t . What happens to $u(y, 0)$ and $u(x, t)$ when $\alpha \rightarrow +\infty$? [6]

Answer 10.15.

- (a) e^z has essential pole at $z = \infty$. Construct a rectangular contour γ with vertices at $z = \pm R, \pm R + i\text{Im}[a]$. No poles are enclosed here.



The contributions along γ_R^\pm is

$$\int_{\pm R}^{\pm R + i\text{Im}[a]} e^{-R^2 - 2iy + y^2} dy = O(e^{-R^2}) \rightarrow 0, \text{ as } R \rightarrow \infty$$

Let $u = R + iy$, then

$$\int_{-\infty}^{\infty + i\text{Im}[a]} e^{-z^2} dz = \int_{-\infty}^{\infty} e^{-(u + i\text{Im}[a])^2} du = \int_{-\infty}^{\infty} e^{-(u+a)^2} du$$

The contributions along γ_0 gives

$$\int_{-R}^R e^{-x^2} dx \rightarrow \sqrt{\pi}, \text{ as } R \rightarrow \infty$$

Hence, by residue theorem, we must have

$$\int_{-\infty}^{\infty} e^{-(u+a)^2} du = \sqrt{\pi}$$

(b) Assuming $u(x, t), \frac{\partial u}{\partial x} \rightarrow 0$ as $|x| \rightarrow \infty$, then the Fourier transforms of $\frac{\partial u}{\partial t}$, $\frac{\partial u}{\partial x}$ and $\frac{\partial^2 u}{\partial x^2}$ give $\frac{\partial \tilde{u}}{\partial t}$, $ik\tilde{u}$, $-k^2\tilde{u}$ respectively. Hence, the Fourier transform of the PDE is

$$\frac{\partial \tilde{u}}{\partial t} = -k^2\lambda\tilde{u} \implies \tilde{u}(k, t) = A(k)e^{-\lambda k^2 t}$$

where $A(k) = \tilde{u}(k, 0) = \int_{-\infty}^{\infty} u(y, 0)e^{-iky}dy$. The solution after inverse Fourier transform gives

$$u(x, t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} A(k)e^{-\lambda k^2 t} e^{ikx} dk = \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} u(y, 0)e^{-iky} e^{-\lambda k^2 t} e^{ikx} dk dy$$

but $-\lambda k^2 t + ik(x - y) = -\lambda t[(k - \frac{i}{2\lambda t}(x - y))^2 + \frac{(x - y)^2}{4\lambda^2 t^2}]$, hence we could have written

$$\int_{-\infty}^{\infty} e^{ik(x - y) - \lambda k^2 t} dk = e^{-\frac{(x - y)^2}{4\lambda t}} \int_{-\infty}^{\infty} e^{-\lambda t(k - k_0)^2} dk = e^{-\frac{(x - y)^2}{4\lambda t}} \sqrt{\frac{\pi}{\lambda t}}$$

This is also the Green's function (fundamental solution for the PDE) $G(x - y, \lambda, t)$. Hence, the solution is

$$u(x, t) = \frac{1}{2\sqrt{\pi\lambda t}} \int_{-\infty}^{\infty} e^{-\frac{(x - y)^2}{4\lambda t}} u(y, 0) dy$$

(c) Now we have

$$u(x, t) = \frac{1}{\sqrt{4\pi\lambda t}} \frac{\alpha}{\sqrt{\pi}} \int_{-\infty}^{\infty} e^{-\frac{(x - y)^2}{4\lambda t} - \alpha^2 y^2} dy$$

but

$$-\alpha^2 y^2 - \frac{(x - y)^2}{4\lambda t} = -\frac{1 + 4\alpha\lambda t}{4\lambda t} (y - y_0)^2 - \frac{\alpha}{1 + 4\alpha\lambda t} x^2$$

where $y_0 = \frac{x}{1 + 4\alpha\lambda t}$. Evaluating the solution:

$$\begin{aligned} u(x, t) &= \frac{\alpha}{2\pi\sqrt{\lambda t}} \int_{-\infty}^{\infty} e^{-\frac{1 + 4\alpha\lambda t}{4\lambda t} (y - y_0)^2} dy e^{-\frac{\alpha}{1 + 4\alpha\lambda t} x^2} \\ &= \frac{\alpha}{2\pi\sqrt{\lambda t}} \sqrt{\frac{4\lambda t\pi}{1 + 4\alpha\lambda t}} e^{-\alpha x^2 / (1 + 4\alpha\lambda t)} \\ &= \frac{\alpha}{\sqrt{\pi}(1 + 4\alpha\lambda t)} e^{-\alpha x^2 / (1 + 4\alpha\lambda t)} \end{aligned}$$

where $\beta = \frac{\alpha}{1 + 4\alpha\lambda t}$. As $\alpha \rightarrow \infty$, $u(y, 0)$ behaves like a delta function. $u(x, t)$ is a spreading Gaussian with variance $2\lambda t$. This is expected for the solutions of this type of PDE, known as the heat equation.

Problem 10.16 (Tensors):

- (a) Explain what is meant by an order n Cartesian tensor and what it means for such a tensor to be isotropic.

Show that the only isotropic tensors of order 2 are of the form $a\delta_{ij}$, where a is a scalar. State (without proof) the most general form of an isotropic tensor of order 3. [9]

- (b) Let $\mathbf{n}_1, \mathbf{n}_2, \mathbf{n}_3, \mathbf{n}_4$ be unit vectors in \mathbb{R}^3 . Let V be the volume between two spheres with centres at the origin and radii R_1 and R_2 , where $R_1 < R_2$.

Justifying your answers carefully, obtain expressions for:

- (i) $\int_V (\mathbf{x} \cdot \mathbf{n}_1)(\mathbf{x} \cdot \mathbf{n}_2) d^3x$;
- (ii) $\int_V (\mathbf{x} \cdot \mathbf{n}_1)(\mathbf{x} \cdot \mathbf{n}_2)(\mathbf{x} \cdot \mathbf{n}_3) d^3x$;
- (iii) $\int_V (\mathbf{x} \cdot \mathbf{n}_1)(\mathbf{x} \cdot \mathbf{n}_2)(\mathbf{x} \cdot \mathbf{n}_3)(\mathbf{x} \cdot \mathbf{n}_4) d^3x$;

[Hint: You may assume that the only isotropic tensors of order 4 are of the form $c\delta_{ij}\delta_{kl} + d\delta_{ik}\delta_{jl} + e\delta_{il}\delta_{jk}$, where c, d and e are scalars.] [11]

Answer 10.16.

- (a) An n th-order Cartesian tensor T is an object that is the same in all frames related by an orthogonal transformation. The tensor's components $T_{i_1 i_2 \dots i_n}$ with respect to two such frames related by such an orthogonal transformation (given by matrix L) must change as

$$T'_{i_1 i_2 \dots i_n} = (\det L)^p L_{i_1 j_1} L_{i_2 j_2} L_{i_3 j_3} \dots L_{i_n j_n} T_{j_1 j_2 \dots j_n}$$

where $p = 1$ for pseudotensors and $p = 0$ otherwise.

An isotropic tensor has its components to be the same in all frames, i.e. $T'_{ijk\dots} = T_{\alpha\beta\gamma\dots}$.

Consider the n -dimensional second-order tensor. Let's rotate around x_1 - x_2 plane by $\frac{\pi}{2}$:

$$L^{(12)} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \oplus I_{(n-2) \times (n-2)}$$

Then,

$$T'_{ij} = L^{(12)}_{ip} T_{pq} L^{(12)}_{jq} = (L T L^T)_{ij} = \begin{pmatrix} T_{22} & -T_{21} & T_{23} & \dots \\ -T_{12} & T_{11} & -T_{13} & \dots \\ T_{32} & -T_{31} & T_{33} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

Then, for $T' = T$, we have $T_{11} = T_{22}$, $T'_{12} = -T_{21} = T'_{21} = -T_{12} \implies T_{12} = T_{21} = 0$. Similar for T_{1i} , T_{2i} , T_{i1} and T_{i2} . In general, use $L^{(mn)}$ rotate in the x_m - x_n plane, all diagonal elements are identical and all off-diagonal elements must be zero, i.e. $T_{ij} = \lambda\delta_{ij}$ for some scalar λ .

- (b) Note that V is spherically symmetric.

- (i) $(\mathbf{n}_1)_i (\mathbf{n}_2)_j \int_V x_i x_j d^3x$ is an isotropic second-order tensor, which is $\lambda\delta_{ij}$. Contracting this, we have

$$\lambda\delta_{ii} = 3\lambda = \int_V x_i x_i d^3x = \int_{R_1}^{R_2} \int_0^\pi \int_0^{2\pi} r^2 r^2 \sin\theta d\phi d\theta dr = \frac{4\pi}{5} (R_2^5 - R_1^5)$$

Then we must have

$$\int_V (\mathbf{x} \cdot \mathbf{n}_1)(\mathbf{x} \cdot \mathbf{n}_2) d^3x = \frac{4\pi}{15} (R_2^5 - R_1^5) \mathbf{n}_1 \cdot \mathbf{n}_2$$

- (ii) $(\mathbf{n}_1)_i (\mathbf{n}_2)_j (\mathbf{n}_3)_k \int_V x_i x_j x_k d^3x$ is an isotropic third-order tensor. But, there is no such thing, hence the integral is just zero. Note, ϵ_{ijk} may be third-order and isotropic, but it is a pseudo-tensor.

- (iii) $(\mathbf{n}_1)_i(\mathbf{n}_2)_j(\mathbf{n}_3)_k(\mathbf{n}_4)_l \int_V x_i x_j x_k x_l d^3x$ is an isotropic fourth-order tensor, which is $c\delta_{ij}\delta_{kl} + d\delta_{ik}\delta_{jl} + e\delta_{il}\delta_{jk}$, as given. Contracting this pairwise, either by $(j = i, k = l)$, $(j = l, i = k)$ or $(j = k, i = l)$, then for the first possibility, we have

$$9c + 3d + 3e = \int_V |\mathbf{x}|^2 |\mathbf{x}|^2 d^3x = \int_{R_1}^{R_2} \int_0^\pi \int_0^{2\pi} r^4 r^2 \sin\theta d\phi d\theta dr = \frac{4\pi}{7}(R_2^7 - R_1^7)$$

For the other permutations, we have $3c + 9d + 3e$ and $3c + 3d + 9e$. Hence, $c = d = e$, then we must have

$$\int_V (\mathbf{x} \cdot \mathbf{n}_1)(\mathbf{x} \cdot \mathbf{n}_2)(\mathbf{x} \cdot \mathbf{n}_3)(\mathbf{x} \cdot \mathbf{n}_4) d^3x = \frac{4\pi}{105}(R_2^7 - R_1^7)[(\mathbf{n}_1 \cdot \mathbf{n}_2)(\mathbf{n}_3 \cdot \mathbf{n}_4) + (\mathbf{n}_1 \cdot \mathbf{n}_3)(\mathbf{n}_2 \cdot \mathbf{n}_4) + (\mathbf{n}_1 \cdot \mathbf{n}_4)(\mathbf{n}_3 \cdot \mathbf{n}_2)]$$

Problem 10.17 (Normal Modes):

- (a) A system has n degrees of freedom and undergoes small oscillations about an equilibrium point. Write down the general form of its Lagrangian in generalised coordinates, explaining any approximations used. Give the equations of motion, and explain what is meant by a normal mode, a normal frequency and a zero mode of the system. [4]
- (b) Three beads of mass m , m and $2m$ are joined pairwise by identical ideal springs of spring constant k , with the masses and springs constrained to lie on a frictionless circular hoop of radius 1. The hoop is fixed and lies in a horizontal plane. Obtain the kinetic and potential energies of the system in terms of suitable generalized coordinates. Obtain the normal modes and normal frequencies. Briefly describe each normal mode physically. [9]
- (c) At time $t = 0$ the masses are equally spaced around the hoop. The beads of mass m are at rest, and the bead of mass $2m$ is given a small initial angular velocity Ω . Obtain an equation for the state of the system at later times $t > 0$. [7]

Answer 10.17.

- (a) If each particle can be described by a generalized coordinate q_i , then assuming there are no velocity-dependent potentials and the kinetic energies are quadratic in the speeds, the Lagrangian is the kinetic energy minus the potential energy $\mathcal{L} = T - V$, and has the form

$$\mathcal{L}(\mathbf{q}, \dot{\mathbf{q}}, t) = \sum_{i=1}^n \frac{1}{2} T_{ij}(t) \dot{q}_i \dot{q}_j - V(\mathbf{q}, t)$$

If we further assume \mathcal{L} to be time-independent and expand the potential around equilibrium positions (minima) to get

$$\mathcal{L} \approx \sum_{i=1}^n \frac{1}{2} T_{ij} \dot{q}_i \dot{q}_j - \sum_{i=1}^n \frac{1}{2} \frac{\partial^2 V}{\partial q_i \partial q_j} q_i q_j$$

unique up to an additive constant (potential at the equilibrium position), which we can set to zero without loss of generality. Also, we assumed for any principal directions for which V_{ij} has a zero eigenvalue, all subsequent derivatives are also zero. When the Lagrangian \mathcal{L} is extremized, it satisfies the Euler-Lagrange equations $\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} = \frac{\partial \mathcal{L}}{\partial q_i}$ to give the equations of motion

$$\frac{d}{dt} T_{ij} \dot{q}_j = -V_{ij} q_j$$

A normal mode is a solution to this generalized eigenvalue of the form $\mathbf{q} = \mathbf{q}_0 e^{i\omega t}$ or $\mathbf{q} = \mathbf{a} + t\mathbf{b}$, where latter is known as the zero mode. To find the normal mode frequencies, we solve the matrix equation

$$\omega^2 T \mathbf{q} = -V \mathbf{q}$$

and for each $\omega = 0$, we need a linearly independent zero mode.

- (b) Our coordinates will be the angles that the bead make from their equilibrium positions. If the natural lengths of the springs happen to be not $\frac{2\pi}{3}$, then at equilibrium, this merely adds a constant term to the potential energy, which will not affect the equations of motion. The potential energy and kinetic energy are thus respectively

$$V = \frac{1}{2}k(\theta_1 - \theta_2)^2 + \frac{1}{2}k(\theta_2 - \theta_3)^2 + \frac{1}{2}k(\theta_3 - \theta_1)^2 = \frac{1}{2}k \begin{pmatrix} \theta_1 & \theta_2 & \theta_3 \end{pmatrix} \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix} \begin{pmatrix} \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix}$$

$$T = \frac{1}{2}m\dot{\theta}^2 + \frac{1}{2}m\dot{\theta}_2^2 + \frac{1}{2}2m\dot{\theta}_3^2 = \frac{1}{2}m \begin{pmatrix} \dot{\theta}_1 & \dot{\theta}_2 & \dot{\theta}_3 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} \dot{\theta}_1 \\ \dot{\theta}_2 \\ \dot{\theta}_3 \end{pmatrix}$$

Let $V = 0.5k\boldsymbol{\theta}^T \mathcal{V} \boldsymbol{\theta}$ and $T = 0.5m\dot{\boldsymbol{\theta}}^T \mathcal{T} \dot{\boldsymbol{\theta}}$. We thus solve for $0 = \det(\mathcal{V} - m\omega^2 \mathcal{T})$:

$$0 = \det \begin{pmatrix} 2k - m\omega^2 & -k & -k \\ -k & 2k - m\omega^2 & -k \\ -k & -k & 2k - 2m\omega^2 \end{pmatrix} = (2k - m\omega^2)((2k - m\omega^2)(2k - 2m\omega^2) - k^2) - 2k^2(3k - 2m\omega^2)$$

which have solutions $\omega^2 = 0$, $\omega^2 = \frac{k}{m}$ and $\omega^2 = \frac{2k}{m}$. By inspection, the eigenvector for the zero mode is $(1, 1, 1)^T$, i.e. rotation with constant angular velocity. For $\omega^2 = \frac{k}{m}$, the eigenvector is $(1, -1, 0)^T$, with the lighter masses moving in anti-phase with respect to each other, but the heavier mass stationary. For $\omega^2 = \frac{2k}{m}$, the eigenvector is $(1, 1, -1)^T$, with the lighter masses moving in phase, but in anti-phase with the heavier mass.

- (c) The general solution is

$$\boldsymbol{\theta}(t) = \begin{pmatrix} \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix} = (c_1 + c_2 t) \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \text{Re}[c_3 e^{i\omega_0 t}] \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + \text{Re}[c_4 e^{i\sqrt{2}\omega_0 t}] \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$$

where $\omega_0 = \sqrt{\frac{k}{m}}$. The initial conditions are $\boldsymbol{\theta}(t=0) = (\theta_0, \theta_0, \theta_0)^T$ and $\dot{\boldsymbol{\theta}}(t=0) = (0, 0, \Omega)^T$. By inspection, we see that $c_1 = \theta_0$ and c_3, c_4 to be purely imaginary.

$$\dot{\boldsymbol{\theta}}(t=0) = \begin{pmatrix} 0 \\ 0 \\ \Omega \end{pmatrix} = c_2 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \text{Re}[i\omega_0 c_3] \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + \text{Re}[i\sqrt{2}\omega_0 c_4] \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$$

Exploiting the orthogonality of the eigenvectors with respect to $\mathcal{T} = m \text{diag}(1, 1, 2)$,

$$c_2 \langle (1, 1, 1)^T | (1, 1, 1)^T \rangle_{\mathcal{T}} = \langle (0, 0, \Omega)^T | (1, 1, 1)^T \rangle_{\mathcal{T}} \implies 2\Omega = 4c_2$$

$$-\omega_0 \text{Im}[c_3] \langle (1, -1, 0)^T | (1, -1, 0)^T \rangle_{\mathcal{T}} = \langle (0, 0, \Omega)^T | (1, -1, 0)^T \rangle_{\mathcal{T}} \implies c_3 = 0$$

$$-\sqrt{2}\omega_0 \text{Im}[c_4] \langle (1, 1, -1)^T | (1, 1, -1)^T \rangle_{\mathcal{T}} = \langle (0, 0, \Omega)^T | (1, 1, -1)^T \rangle_{\mathcal{T}} \implies 4\sqrt{2}\omega_0 c_4 = -2\Omega$$

Hence,

$$\boldsymbol{\theta}(t) = (\theta_0 + 0.5\Omega t) \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \frac{\Omega}{2\sqrt{2k/m}} \sin \sqrt{2k/m} t \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$$

Problem 10.18 (Group Theory):

- (a) Give the axioms for a group G . Explain what is meant by saying that H is a subgroup of G and that $\{g_1, \dots, g_n\}$ is a set of generators for G . Explain what is meant by the order of G and the order of an element g of G , and state Lagrange's theorem. Explain what is meant by a cyclic group and an isomorphism between groups. [6]
- (b) Now suppose G is a group of order 8. What are the possible orders of its elements? Show that if G has no elements of order greater than 2 then it is a direct product of cyclic groups. [Hint: The direct product of groups G_1, G_2, \dots, G_n is the group with elements (g_1, g_2, \dots, g_n) (where $g_i \in G_i$), with identity $(I_{G_1}, \dots, I_{G_n})$, where I_{G_i} is the identity of G_i . The group multiplication is defined by $(g_1, \dots, g_n)(g'_1, \dots, g'_n) = (g_1g'_1, \dots, g_ng'_n)$ and the inverse by $(g_1, \dots, g_n)^{-1} = (g_1^{-1}, \dots, g_n^{-1})$.] [5]
- (c) Now suppose that G has order 8 and is generated by elements a and b which have orders 4 and 2 respectively. Show that either (i) $ab = ba$ or (ii) $ab = ba^3$. Show that in case (i) G is uniquely defined up to isomorphism. Show that in case (ii) G is also uniquely defined up to isomorphism, and give a geometric representation of G and the generators a and b in this case. [7]
- (d) Is the group identified in part (c)(ii) the only non-abelian group of order 8? Justify your answer carefully. [2]

Answer 10.18.

- (a) A group G is a set of elements with a binary operation defined for $g_1, g_2 \in G$ such that $g_1 * g_2$ and the resultant group elements satisfy

- closure: $g_i * g_j \in G \forall g_i, g_j \in G$.
- associative: $(g_i * g_j) * g_k = g_i * (g_j * g_k) \forall g_i, g_j, g_k \in G$.
- identity: $\exists e \in G$ such that $e * g_i = g_i \forall g_i \in G$.
- inverse: for every $g_i \in G$, $\exists g'_i \in G$ such that $g_i * g'_i = e$.

H is a subgroup, i.e. $H \leq G$ if it is a subset that also obeys the above axioms.

A set of generators for a group G is a (not necessarily unique) set of elements in G such that every element in G can be found by combining the generators with each other to various powers. All non-identical sets of generators contain the same number of elements, and the set is minimal in that if you removed any one generator, then the set would not generate all of G .

The order of a group G is $|G|$, the number of elements it contains. The order of an element $g \in G$ is the minimum positive integer number of times you need to combine it with itself to return the identity, i.e. if $\text{ord}(g) = k$, then $g^k = e$.

Lagrange's theorem states that the order of a subgroup is a factor of the order of the parent group.

A cyclic group has a single generator (not necessarily unique).

A homomorphism between two groups G and H is a mapping $\Phi: G \rightarrow H$ such that the group structure is preserved, i.e. $\Phi(g_i)\Phi(g_j) = \Phi(g_i * g_j) \forall g_i, g_j \in G$.

- (b) If $g \in G$, then by Lagrange's theorem, $\text{ord}(g)$ (order of the resultant generator) are factors of 8: 1, 2, 4, 8. If every element other than the identity is of order 2, then it can be written as a direct product of $C_2 = \{e, a\}$, say $C_2 \times C_2 \times C_2$. Let the elements be

$$I = (e_1, e_2, e_3), \quad A = (e_1, e_2, a_3), \quad B = (e_1, a_2, e_3), \quad C = (a_1, e_2, e_3)$$

where $A^2 = B^2 = C^2 = I$, A, B and C act as generators for this group. We have $AB = BA = (e_1, a_2, a_3)$, $AC = CA = (a_1, e_2, a_3)$, $BC = CB = (a_1, a_2, e_3)$, $ABC = (a_1, a_2, a_3)$, which are all (8 of them) in $C_2 \times C_2 \times C_2$. Also, we have established that this is an abelian group.

- (c) We have $\text{ord}(a) = 2$, $\text{ord}(b) = 4$. Consider $g = a^p b^q$, with p only meaningful modulo 2 and q only meaningful modulo 4. Is ab distinct from a , b and I ?

If $ab = I$, then $b = a^{-1}$. But $\text{ord}(a) = 2$, so $a = a^{-1} = b$, but a set of generators has distinct elements, so contradict. Hence, $ab \neq I$.

No generator is the identity as a set of elements that generated the entire group which contains the identity would still generate entire group after removing the identity. Such a set would not be minimal, so contradict. $ab \neq a$, $ab \neq b$.

We could thus generate more elements, namely ab^2 , b^2 , b^3 and ab^3 . An alternative generator is $\{I, a, b, ba, b^2a, b^3, b^3a\}$ and this must be the same set, so $\{ab, ab^2, ab^3\}$ and $\{ba, b^2a, b^3a\}$ must be the same set (just reordered). The order is not 8 since the group will have a generating set of size 1. Also, these elements are not identity and again must have order 2 or 4. Consider the following combinations:

- $ab = ba \implies ab^2 = b^2a$, $ab^3 = b^3a$ no contradiction.
- $ab = b^2a \implies (ab)^2 = ab^3a$, $(ab)^4 = ab^2a$, a contradiction since $\text{ord}(ab)$ is neither 2 nor 4.
- $ab = b^3a \implies (ab)^2 = I$, this is of order 2 and no contradiction.
- $ab^2 = ba \implies (ab^2)^2 = ab^2ab^2 = ab^2ba = ab^3a$, $(ab^2)^4 = ab^2a$. A contradiction again since $\text{ord}(ab^2)$ is neither 2 nor 4.

Both allowed case: map $b \rightarrow b^3$. This is isomorphic to the symmetry group of a square, i.e. D_4 . a is geometrically a reflection about the diagonal and b is the rotation of magnitude $\frac{\pi}{2}$ about the centre of the square in the plane of the square.

- (d) No. The quaternion group has two order four generators and has eight elements. But this was not considered in part (c) as it is non-abelian.

Problem 10.19 (Group Theory):

- (a) Define a homomorphism between groups G and G' . Define what is meant by the kernel of a homomorphism and by a normal subgroup H of a group G . [4]
- (b) Consider the set of matrices of the form

$$M = \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix}$$

where a and b are complex and $a \neq 0$. Show that this set forms a group G under matrix multiplication. Let G' be the subset of G such that $b = 0$. Show that G' is a subgroup of G and that the map

$$f : \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} a & 0 \\ 0 & 1 \end{pmatrix}$$

defines a homomorphism. [8]

- (c) Hence, or otherwise, identify a non-trivial normal subgroup of G and show that it is a normal subgroup. [8]

Answer 10.19.

(a) If G and G' are groups, then the mapping $\Phi : G \rightarrow G'$ is a group homomorphism if $\forall a, b \in G$,

$$\phi(a \cdot_G b) = \phi(a) \cdot_{G'} \phi(b)$$

The kernel of the homomorphism is

$$\text{Ker } \phi = \{h \in G \mid \phi(h) = e_{G'} \text{ for some } h \in G\}$$

H is a normal subgroup of G if $g_i H = H g_i \forall g_i \in G$.

(b) Check axioms of a group G :

- closure: Consider $M, M' \in G$

$$MM' = \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a' & b' \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} aa' & ab' + b \\ 0 & 1 \end{pmatrix} \in G$$

which is true since $a, a' \neq 0 \implies aa' \neq 0$.

- associative: matrix multiplication is associative.
- identity: in G if $a = 1 \neq 0$ and $b = 0$.
- inverse: $M^{-1} = \begin{pmatrix} a^{-1} & -ba^{-1} \\ 0 & 1 \end{pmatrix} \in G$ since $a \neq 0 \implies a^{-1} \neq 0$.

When $b = 0$, check the subgroup axioms for G' :

- closure: $\begin{pmatrix} a'a & 0 \\ 0 & 1 \end{pmatrix} \in G'$ obviously.
- associativity: inherited from G .
- identity: inherited as well.
- inverse: $\begin{pmatrix} a^{-1} & 0 \\ 0 & 1 \end{pmatrix} \in G'$.

Check f is a homomorphism:

$$\begin{aligned} f\left(\begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a' & b' \\ 0 & 1 \end{pmatrix}\right) &= f\left(\begin{pmatrix} aa' & ab'b \\ 0 & 1 \end{pmatrix}\right) \\ &= \begin{pmatrix} aa' & 0 \\ 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} a & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a' & 0 \\ 0 & 1 \end{pmatrix} \\ &= f\left(\begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix}\right) f\left(\begin{pmatrix} a' & b' \\ 0 & 1 \end{pmatrix}\right) \end{aligned}$$

(c) Consider the cyclic group $G' := C_2 = \{g, e\}$ s.t. $a = e^{i\pi} = -1$, $b = 0$, then $g \in C_2$ s.t. $g^2 = e$. Check subgroup axioms of $G' \subseteq G$:

- closure: $g^p \text{ mod } 2 \in G'$.
- associativity: inherited from G .
- identity: $g^2 = e \in G$.
- inverse: self-inverse.

The identity commutes with itself, so trivially it is in a conjugacy class of its own.

$$gM_i - M_i g = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a_i & b_i \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} a_i & b_i \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -a_i & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} -a_i & 0 \\ 0 & 1 \end{pmatrix} = 0$$

g commutes with all $M_i \in G$, so it is in a conjugacy class of its own. Hence, $G' = \{g, e\} \triangleleft G$ is a normal subgroup and it is constructed from a union of entire conjugacy classes.

Problem 10.20 (Representation Theory):

- (a) Define the permutation group S_n of n elements. Explain what is meant by an m -dimensional representation of a group G , by an irreducible representation of G , and by inequivalent representations of G . [4]
- (b) Describe the conjugacy classes of S_4 , stating the number of elements in each. [You need not prove these are the conjugacy classes.] [4]
- (c) Describe two inequivalent one-dimensional representations of S_4 , showing that they are representations. What are their kernels? Are the kernels subgroups? Justify your answers. What are the characters of the two representations? Verify that they are orthogonal. [6]
- (d) Obtain the dimensions of the inequivalent irreducible finite-dimensional representations of S_4 , justifying your answer carefully. [You may quote without proof any relevant theorems, provided they are clearly stated.] [6]

Answer 10.20.

- (a) The permutation group S_n consists of the set of shufflings of n elements.

$$\sigma = \begin{pmatrix} a & b & c & d & e \\ \sigma(a) & \sigma(b) & \sigma(c) & \sigma(d) & \sigma(e) \end{pmatrix}$$

can be written in terms of cycles. It is conventional to omit single entry cycles in our notation.

An m -dimensional representation of a group is a homomorphism to a set of m -dimensional invertible matrices. If \exists a single similarity transform applied to all the matrices in the representation simultaneously that renders them all block diagonal, then the representation is reducible. Otherwise, the representation is irreducible. Equivalently, an irreducible representation has no non-trivial invariant subspaces. Two representations are equivalent if \exists a single similarity transform that maps one set of matrices to the other. Otherwise, the two representations are not equivalent.

- (b) Permutation cycles of the same type are in the same conjugacy classes of S_4 . Id is in a conjugacy class of its own. (..) have 6 elements in its conjugacy class, all of them are their own inverse. (...) have 8 elements in its conjugacy class. (..)(..) have 3 elements in its conjugacy class, all of them are their own inverse. (....) have 3 elements in its conjugacy class. The total number is $1 + 6 + 8 + 3 + 6 = 24 = 4! = |S_4|$.
- (c) Consider the trivial representation I . $\text{Ker}(I(S_4)) = S_4 \leq S_4$. χ_I contains 24 copies of +1.

Consider another one-dimensional representation T where all elements containing an even number of pairwise swaps (Id, (...), (..)(..)) maps to 1, while an odd number of pairwise swaps ((..), (....)) maps to -1. $\text{Ker } T$ is thus the set of permutations decomposable into an even number of pairwise swaps. Trivially, this is closed, inherits associativity, contains Id and all appropriate inverses. So $T \leq S_4$. There is exactly 12 (half of $|S_4|$) elements that map to +1 and another 12 map to -1, so χ_T has 12 copies of +1 and 12 copies of -1. Hence, the characters are orthogonal:

$$\chi_T \cdot \chi_I = 12(+1) + 12(-1) = 0$$

- (d) The number of inequivalent irreducible representations is the number of conjugacy classes which is 5. The sum of squares of dimensions of the irreducible representations is the order of the group which is 24. We thus look for 5 natural numbers that sum and square to 24. In part (c), we identified two distinct one-dimensional representations, so solve

$$l^2 + m^2 + n^2 = 22 \implies l = 2 = m, n = 3$$

Hence, the dimensions of the irreducible representations are 1, 1, 2, 3, 3.