



Sri Chaitanya IIT Academy, India

A.P, TELANGANA, KARNATAKA, TAMILNADU, MAHARASHTRA, DELHI, RANCHI

A right Choice for the Real Aspirant

ICON CENTRAL OFFICE, MADHAPUR-HYD

Sec: Sr. IPLCO

Time: 9:00 AM to 12:00 Noon

RPTM-5

Date: 05-09-15

Max.Marks: 360

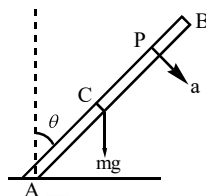
KEY SHEET

PHYSICS		MATHS		CHEMISTRY	
Q.NO	ANSWER	Q.NO	ANSWER	Q.NO	ANSWER
1	2	31	3	61	4
2	1	32	1	62	2
3	1	33	4	63	1
4	2	34	3	64	4
5	3	35	3	65	4
6	2	36	1	66	4
7	1	37	4	67	2
8	1	38	1	68	4
9	3	39	1	69	3
10	1	40	3	70	2
11	2	41	2	71	3
12	3	42	1	72	4
13	2	43	4	73	1
14	2	44	1	74	2
15	2	45	4	75	3
16	2	46	4	76	3
17	4	47	2	77	3
18	1	48	3	78	3
19	3	49	3	79	4
20	3	50	1	80	4
21	2	51	4	81	4
22	3	52	4	82	4
23	3	53	1	83	3
24	4	54	3	84	3
25	2	55	2	85	2
26	2	56	3	86	2
27	1	57	1	87	2
28	4	58	3	88	2
29	2	59	2	89	4
30	1	60	2	90	2

PHYSICS

1. Conceptual
2. Taking torque about A. when the rod has fallen through an angle θ

$$\tau = mg \frac{l}{2} \sin \theta = I \alpha = \left(\frac{1}{3} ml^2 \right) \alpha$$



$$\text{Or } \alpha = \frac{3g}{2l} \sin \theta$$

For any point P on the rod, at a distance r from A, the linear acceleration is $a = r\alpha = \frac{3gr}{2l} \sin \theta$. P will also have centripetal acceleration.

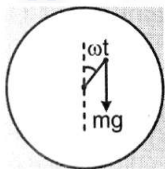
3.

$$\vec{\tau}_o = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & 3 & 6 \\ 2 & -4 & 1 \end{vmatrix}$$

$$= 27\hat{i} + 10\hat{j} - 14\hat{k}$$

4.

Opposing couple is $-mgR \sin \omega t$



5.

$$F \left(\frac{a+b}{2} \right) = 2F \left(\frac{b-a}{2} \right)$$

$$\therefore \frac{a}{b} = \frac{1}{3}$$

6.

Time at which centre of mass is at highest point is

$$= \frac{u}{g} = \frac{10}{10} = 2 \text{ sec}$$

Rotation of the rod

$$= \omega t = \frac{\pi}{2} \Rightarrow a_A = \omega^2 R \hat{j} - g \hat{j}$$

7.

$$3\hat{i} + 8\hat{j} = \vec{V}_{CM} + \frac{4}{\sqrt{3}} \left(\frac{\hat{i}}{2} + \frac{\sqrt{3}\hat{j}}{2} \right)$$

$$\vec{V}_A = \vec{V}_{CM} + \frac{4}{\sqrt{3}} \left(\frac{\hat{i}}{2} - \frac{\sqrt{3}\hat{j}}{2} \right)$$

$$\Rightarrow \vec{V}_A = 3\hat{i} + 4\hat{j}$$

$$\therefore V_A = 5 \text{ m/s}$$

$$8. \quad \frac{1}{2}(1+1)mv^2 + \frac{1}{2}m(2v)^2 + \frac{1}{2}m(v\sqrt{2})^2 + \frac{1}{2}m(v\sqrt{2})^2 = 5mv^2$$

9. **Conceptual**

10.

$$k = (1 + 2/3) \times \frac{1}{2}MV^2 + \frac{1}{2}(2M)V^2$$

$$= \frac{11}{6}MV^2$$

$$11. \quad f_{\max} = \frac{kx_{\max}}{1 + \frac{mR^2}{I}} = 10N$$

12.

Let P = external force F = force of friction between A and B.

$$P - F = ma_1 \text{ and } P = ma_2 \therefore a_2 > a_1.$$

Let α = angular acceleration between A and B. For one rotation,

$$\theta = 2\pi = \frac{1}{2}\alpha T^2 \text{ or}$$

$$T = (4\pi / \alpha)^{1/2} = \text{time of travel from A to B.}$$

Angular velocity at B = $\omega_B = \alpha T$.

For one rotation to the right to B,

$$\theta = 2\pi = \omega_B t \quad \text{or } t = \frac{2\pi}{\alpha T} = \frac{\frac{1}{2}T^2}{T} = \frac{T}{2}$$

13. **Conceptual**

14.

$$Mg.R = \frac{MR^2}{2}\alpha \Rightarrow \alpha = \frac{2g}{R} = \frac{w}{t}$$

$$v = 2RW \Rightarrow 4gt = \frac{ds}{dt}$$

$$\int_0^s ds = \int_0^{WR/2g} 4gt dt \Rightarrow s = \frac{R^2W^2}{2g}$$

15

$$T + f = mg \sin \theta$$

$$T \cdot R = f \cdot R \Rightarrow T = f$$

$$\therefore f = \frac{mg \sin \theta}{2} = T$$

16. Conceptual

17.

$$U_1 = MgR$$

$$U_2 = \frac{M}{4} g \left(\frac{R}{2} \right)$$

18.

$$mg \frac{L}{2} = \frac{mL^2}{3} \alpha$$

$$\Rightarrow \alpha = \frac{3g}{2L}$$

19. Conceptual

20.

$$Mgx = \left(\frac{Ma^2 \times 4}{12 \times 4} + \frac{Ma^2}{48} + \frac{3Ma^2}{16 \times 3} + \frac{Mx^2 \times 48}{48} \right) \alpha$$

$$\Rightarrow \alpha = \frac{48gx}{8a^2 + 48x^2} \alpha \frac{x}{a^2 + 6x^2}$$

$$\frac{d\alpha}{dx} = 0 \Rightarrow x = \frac{a}{\sqrt{6}}$$

21.

$$|\tau_A| = |\tau_B| = (F \sin \theta) \frac{L}{2} = I\alpha$$

$$\therefore \alpha \propto \frac{1}{I}$$

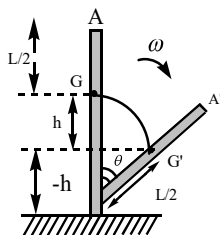
22. The distance of mass is the nearest to axis xx, hence moment of inertia is least about xx-axis.

23.

$$\frac{2}{3} ML^2 \omega^2 = \frac{3}{2} MgL \quad \therefore \quad \omega = \frac{3}{2} \sqrt{\frac{g}{L}}$$

24. Conceptual

25.



$$Mg \frac{L}{2} (1 - \cos \theta) = \frac{ML^2}{6} \omega^2$$

$$\therefore \omega = \sqrt{6g/L} \sin\left(\frac{\theta}{2}\right)$$

26.

$$2\pi = \frac{1}{2} \times \frac{\pi}{4} \times t^2$$

$$\therefore t = 4$$

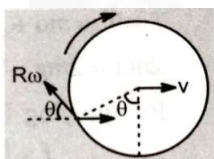
27.

$$\frac{I_1}{I_2} = \frac{1}{8} = \frac{mR^2}{m_2(nR)^2} = \frac{mR^2}{mn(nR)^2}$$

$$\text{or } \frac{1}{8} = \frac{1}{n^3} \quad \text{or } n = 2$$

28. Torque is always perpendicular to \vec{F} as well as $\vec{r} \therefore \vec{r} \cdot \vec{\tau} = 0$ as well as $\vec{F} \cdot \vec{\tau} = 0$

29.



$$v = R\omega \cos \theta$$

$$\cos \theta = \frac{v}{R\omega}$$

$$h = R - R \cos \theta$$

30.

$$V_p = 2V \cos \frac{\theta}{2}$$

$$\begin{aligned} K_{ABC} &= \int_{-\pi/2}^{\pi/2} \frac{1}{2} \lambda R d\theta V_p^2 \\ &= \int_{-\pi/2}^{\pi/2} 2\lambda V^2 R \cos^2 \frac{\theta}{2} d\theta \\ &= MV^2 \left(\frac{\pi + 2}{2\pi} \right) \end{aligned}$$