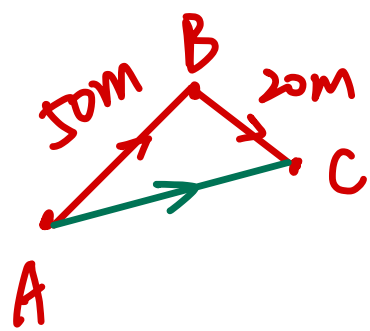


Topic 7. Vectors

Vectors



Clearly I've walked 70m in total, although it is not necessarily 70m from A to C. To get from one place to another, we need two bits of information: a direction and a length, such quantities that encode these pieces of information are called vectors.

EXAMPLE: Going from A to B can be denoted by \vec{AB} , B to C, \vec{BC} and A to C, \vec{AC} .
 direction
 start end

$$\vec{AB} + \vec{BC} = \vec{AC}$$

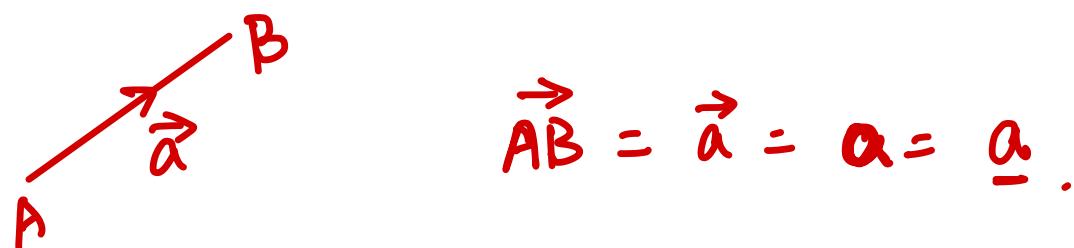
We can denote the length of a vector as $|\vec{AB}| = 50$. $|\vec{BC}| = 20$.

Note: $|\vec{AB}| + |\vec{BC}| \neq |\vec{AC}|$
 \geq

$$|\vec{AC}| \neq 70.$$

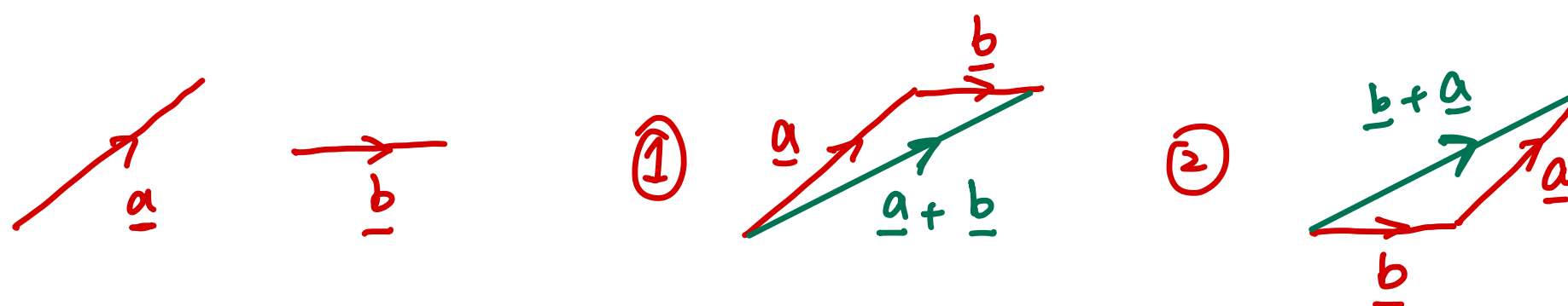
Other notation

We usually denote a vector using bold or underlined letters, or with an arrow top.



Vector properties

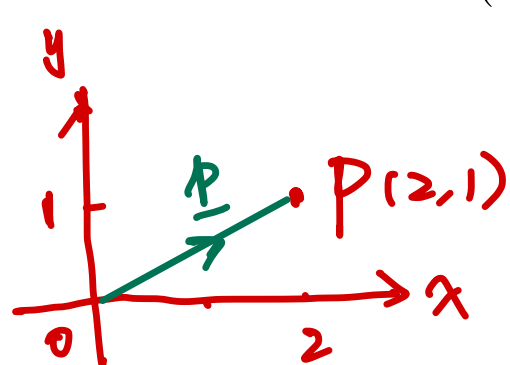
Addition (geometrically):



Commutative law: $\underline{a} + \underline{b} = \underline{b} + \underline{a}$

Associative law: $(\underline{a} + \underline{b}) + \underline{c} = \underline{a} + (\underline{b} + \underline{c})$

Position vector: Any point in space can be represented by a coordinate. We can also denote a coordinate (P) by a vector, this is called its position vector.



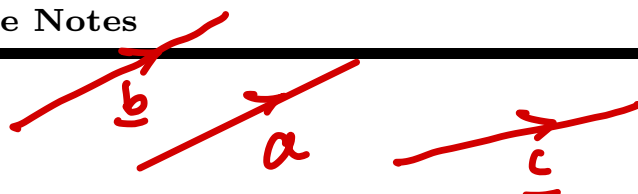
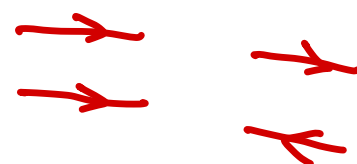
P

$$\begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

A position vector tells us how to get to a point in space when starting at the origin (0, 0).

NOTE:

- A coordinate tells us where we are in space.
- A position vector tells us how to get to a coordinate from the origin
- In general, a vector tells us in which direction and how far we should move from a starting coordinate.



Parallel vector: two vectors are parallel if they are scalar multiples of each other.

EXAMPLE: Let \underline{a} and \underline{b} be vectors then if $\underline{a}\lambda = \underline{b}$, where λ is a constant, \underline{a} and \underline{b} are parallel. Let $\underline{a} = \begin{pmatrix} 2 \\ -4 \end{pmatrix}$ and $\underline{b} = \begin{pmatrix} 4 \\ -8 \end{pmatrix}$, are \underline{a} and \underline{b} parallel? ✓

$$\lambda \underline{a} = \lambda \begin{pmatrix} 2 \\ -4 \end{pmatrix} = \begin{pmatrix} 2\lambda \\ -4\lambda \end{pmatrix} \quad \underline{b} = \begin{pmatrix} 4 \\ -8 \end{pmatrix} \quad \lambda=2. \text{ i.e. } 2\underline{a} = \underline{b}$$

We can add and subtract vectors quite nicely:

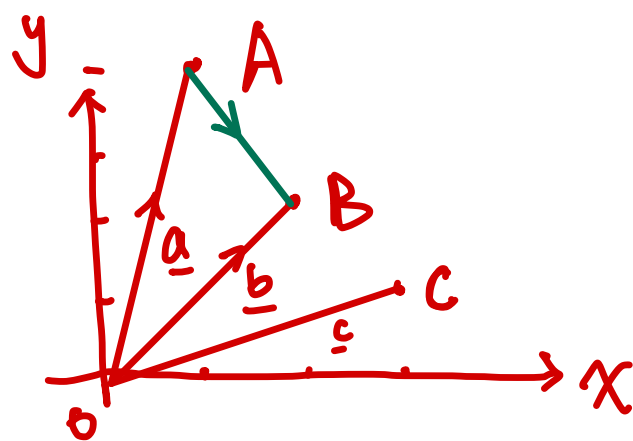
EXAMPLE: $\underline{a} = \begin{pmatrix} 2 \\ 3 \\ 5 \end{pmatrix}, \underline{b} = \begin{pmatrix} -1 \\ -3 \\ 4 \end{pmatrix}$

$$\underline{a} = \begin{pmatrix} 2 \\ 3 \\ 5 \end{pmatrix} \quad \underline{c} = \begin{pmatrix} 1 \\ 0 \\ 9 \end{pmatrix}$$

$$\underline{a} + \underline{b} = \begin{pmatrix} 2-1 \\ 3-3 \\ 5+4 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 9 \end{pmatrix}$$

Finding vectors between points

What is the vector \overrightarrow{AB} ? $\underline{a} = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$, $\underline{b} = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$, $\underline{c} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$

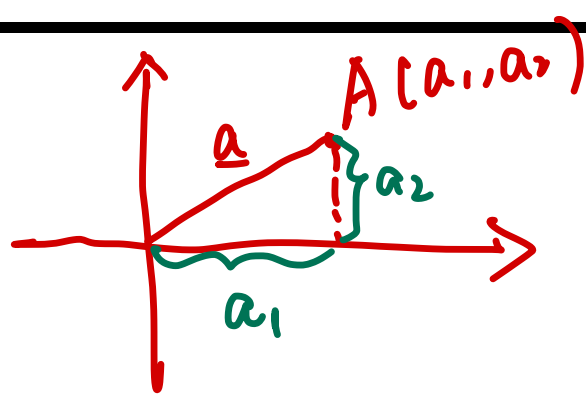


$$\begin{aligned} \vec{OA} + \vec{AB} &= \vec{OB} \\ \Rightarrow \vec{AB} &= \vec{OB} - \vec{OA} \\ &= \underline{b} - \underline{a} \\ &= \begin{pmatrix} 2 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 \\ 4 \end{pmatrix} = \begin{pmatrix} 2-1 \\ 2-4 \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \end{pmatrix} \end{aligned}$$

What is the length of vector \underline{a} , i.e., $|\underline{a}|$?

EXAMPLE: Let $\underline{a} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$. Find $|\underline{a}|$

$$|\vec{AB}| = \sqrt{1^2 + (-2)^2} = \sqrt{5}.$$



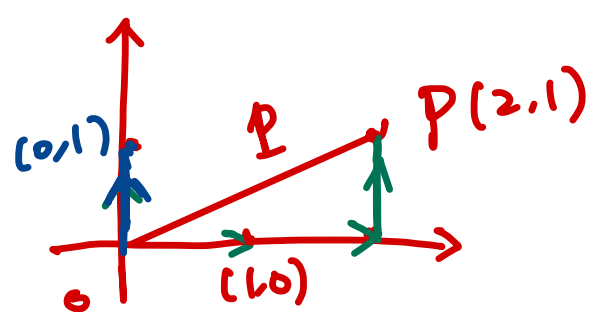
$$|\underline{a}| = \sqrt{a_1^2 + a_2^2}.$$

In general, for an n -dimensional vector $\underline{p} = \begin{pmatrix} p_1 \\ p_2 \\ \vdots \\ p_n \end{pmatrix} \in \mathbb{R}^n$, $\underline{p} = (p_1, p_2, \dots, p_n)^T$, \rightarrow transpose.

$$|\underline{p}| = \sqrt{p_1^2 + p_2^2 + \dots + p_n^2} = \sqrt{\sum_{i=1}^n p_i^2}$$

Component form

We can split the vector into ‘moves’ across space, usually moves ‘across’ and ‘up’ for 2 vectors.



$$\begin{pmatrix} 2 \\ 1 \end{pmatrix} = \underline{p} = 2 \text{ across} + 1 \text{ up.} \\ = 2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

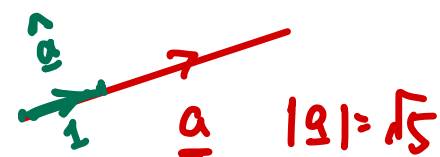
$$:= 2 \underline{i} + 1 \underline{j}.$$

Unit vectorsa s.t. $|\underline{a}| = 1$.

These are vectors with length 1, and are useful when comparing between directions. We can make any vector a unit vector simply by dividing it by its length.

EXAMPLE: $\underline{a} = \begin{pmatrix} 2 \\ -1 \end{pmatrix} = 2\mathbf{i} - \mathbf{j}$, where \mathbf{i}, \mathbf{j} are unit vectors in the directions of the x, y axes respectively.

$$\underline{a} = \begin{pmatrix} 2 \\ -1 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} - 1 \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 2\underline{i} - \underline{j}.$$



$$|\underline{a}| = \sqrt{2^2 + (-1)^2} = \sqrt{5}.$$

$$\underline{\hat{a}} = \frac{1}{|\underline{a}|} \times \underline{a} = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ -1 \end{pmatrix} = \begin{pmatrix} \frac{2}{\sqrt{5}} \\ -\frac{1}{\sqrt{5}} \end{pmatrix} \quad |\underline{\hat{a}}| = 1.$$

Base vector and change of basis

Using the vectors $\mathbf{i} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $\mathbf{j} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$, we can reach any point in space.

$$\begin{pmatrix} x \\ y \end{pmatrix} = x \begin{pmatrix} 1 \\ 0 \end{pmatrix} + y \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad \begin{matrix} \mathbf{i} \uparrow \\ \mathbf{j} \rightarrow \end{matrix} \quad \begin{matrix} \underline{e}_1 \nearrow \\ \underline{e}_2 \rightarrow \end{matrix}$$

In fact, any pair of non-parallel vectors give a base pair in 2D space. We usually denote base vectors in 2D as e_1 and e_2 .

EXAMPLE: Express $\begin{pmatrix} 7 \\ 6 \end{pmatrix}$ as a vector using base vectors $e_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ and

$$e_2 = \begin{pmatrix} 1 \\ 3 \end{pmatrix}.$$

① base: $\underline{i} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ & $\underline{j} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$\begin{pmatrix} 7 \\ 6 \end{pmatrix} = 7 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 6 \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 7\underline{i} + 6\underline{j}.$$

② base: $\underline{e}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ & $\underline{e}_2 = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$, i.e. $\begin{pmatrix} 7 \\ 6 \end{pmatrix} = 3\underline{e}_1 + 1 \cdot \underline{e}_2$

$$\begin{pmatrix} 7 \\ 6 \end{pmatrix} = \lambda_1 \underline{e}_1 + \lambda_2 \underline{e}_2 = \lambda_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} + \lambda_2 \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$= \begin{pmatrix} 2\lambda_1 \\ \lambda_1 \end{pmatrix} + \begin{pmatrix} \lambda_2 \\ 3\lambda_2 \end{pmatrix}$$

$$= \begin{pmatrix} 2\lambda_1 + \lambda_2 \\ \lambda_1 + 3\lambda_2 \end{pmatrix}$$

$$\Rightarrow \begin{cases} 7 = 2\lambda_1 + \lambda_2 \\ 6 = \lambda_1 + 3\lambda_2 \end{cases}$$

$$\text{i.e. } \lambda_1 = 3 ; \lambda_2 = 1.$$

3D: base: $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$

Vector dot product/scalar product/inner product

Let \underline{a} and \underline{b} be two n -dimensional vectors with $\underline{a} = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}$, $\underline{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$.

Dot product of \underline{a} and \underline{b} :

$$\underline{a} \cdot \underline{b} = (a_1 \times b_1) + (a_2 \times b_2) + (a_3 \times b_3) + \dots + (a_n \times b_n) = \sum_{i=1}^n a_i b_i$$

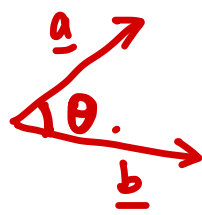
EXAMPLE: $\underline{a} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$, $\underline{b} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$ $\underline{a} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $\underline{b} = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$ ✗.

Note: dot product gives a number (scalar) not a vector.

$$\underline{a} \cdot \underline{b} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 2 \end{pmatrix} = 3 \times (-1) + 1 \times 2 = -3 + 2 = -1.$$

Geometrically, the dot product has a very nice (and helpful) property as it tells us the angle between two vectors.

$$\underline{a} \cdot \underline{b} = |\underline{a}| |\underline{b}| \cos(\theta).$$



$$\Rightarrow \cos(\theta) = \frac{\underline{a} \cdot \underline{b}}{|\underline{a}| |\underline{b}|}$$

EXAMPLE: $\underline{a} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$, $\underline{b} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$ What is the angle between \underline{a} and \underline{b} ?

$$\underline{a} \cdot \underline{b} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 2 \end{pmatrix} = 3 \times (-1) + 1 \times 2 = -1.$$

$$|\underline{a}| = \sqrt{3^2 + 1^2} = \sqrt{10}, \quad |\underline{b}| = \sqrt{(-1)^2 + 2^2} = \sqrt{5}.$$

$$\Rightarrow \cos(\theta) = \frac{\underline{a} \cdot \underline{b}}{|\underline{a}| |\underline{b}|} = -\frac{1}{\sqrt{50}}.$$

$$\Rightarrow \theta = \cos^{-1}\left(-\frac{1}{\sqrt{50}}\right) \approx 98^\circ.$$

Important properties

$$\underline{a} \cdot \underline{a} = |\underline{a}| |\underline{a}| \cos(\hat{0}) = |\underline{a}| |\underline{a}| = |\underline{a}|^2 = \sum_{i=1}^n a_i^2$$

$$\underline{a} \cdot \underline{b} = \underline{b} \cdot \underline{a}$$

$$(k\underline{a}) \cdot \underline{b} = \underline{a} \cdot (k\underline{b}) = k(\underline{a} \cdot \underline{b}), \quad k = \text{constant}$$

$$\underline{a} \cdot (\underline{b} + \underline{c}) = \underline{a} \cdot \underline{b} + \underline{a} \cdot \underline{c}$$

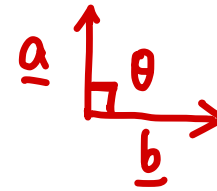
If two vectors are perpendicular. i.e. normal, then $\underline{a} \cdot \underline{b} = 0$.

$$\underline{a} \cdot \underline{b} = |\underline{a}| |\underline{b}| \cos(90^\circ)$$

$$= |\underline{a}| |\underline{b}| \times 0$$

$$= 0.$$

$$\begin{aligned} \underline{a} \cdot \underline{b} &= a_1 \times b_1 + a_2 \times b_2 + \dots + a_n \times b_n \\ &= b_1 \times a_1 + b_2 \times a_2 + \dots + b_n \times a_n \\ &= \underline{b} \cdot \underline{a}. \end{aligned}$$

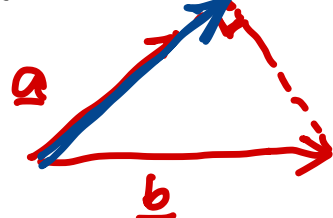


Projections

Formula for finding the projection of \underline{a} onto \underline{b} is given by

$$\text{proj}_{\underline{b}} \underline{a} = \frac{\underline{a} \cdot \underline{b}}{|\underline{b}|^2} \underline{b} = \frac{\underline{a} \cdot \underline{b}}{|\underline{b}|} \times \frac{\underline{b}}{|\underline{b}|}$$

The projection of \underline{b} onto \underline{a} is given by



$$\text{proj}_{\underline{a}} \underline{b} = \frac{\underline{b} \cdot \underline{a}}{|\underline{a}|^2} \underline{a} = \frac{\underline{a} \cdot \underline{b}}{|\underline{a}|^2} \underline{a}$$

$\frac{|\underline{a}||\underline{b}|\cos\theta}{|\underline{b}|} = |\underline{a}|\cos\theta$ unit vector.

Note: the projection $\text{proj}_{\underline{b}} \underline{a}$ and $\text{proj}_{\underline{a}} \underline{b}$ must give a vector.

EXAMPLE: Find the projection of $\underline{b} = \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}$ onto $\underline{a} = \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix}$

$$\underline{a} \cdot \underline{b} = \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix} = 2 \times 1 + 1 \times 0 + (-1) \times (-2) = 4.$$

$$|\underline{a}| = \sqrt{1^2 + 0^2 + (-2)^2} = \sqrt{5}$$

$$\text{proj}_{\underline{a}} \underline{b} = \frac{\underline{a} \cdot \underline{b}}{|\underline{a}|^2} \underline{a} = \frac{4}{5} \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix} = \begin{pmatrix} \frac{4}{5} \\ 0 \\ -\frac{8}{5} \end{pmatrix}.$$