

SYDE 556/750

Simulating Neurobiological Systems

Lecture 8: Learning

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October 27, 28 & Nov 3 2022

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**UNIVERSITY OF
WATERLOO**

**FACULTY OF
ENGINEERING**



Learning



















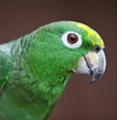
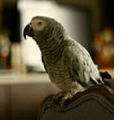


Definition

Learning is a directed change in synaptic weights \mathbf{W} while the network is active.

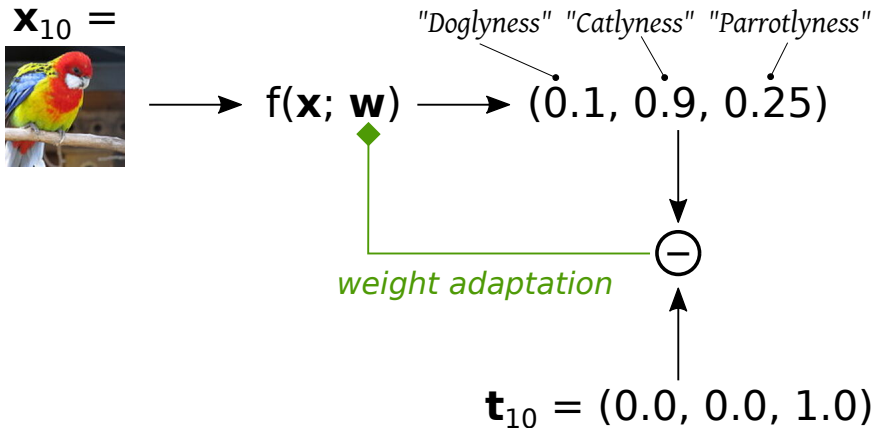
Learning is important because:

1. We might not know the function we want to compute at the beginning of a task.
2. The desired function might change over time.
3. The “optimal weights” we are solving for are not optimal.
4. Answering scientific questions about learning in nervous systems.

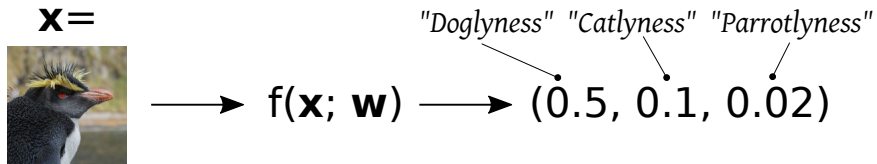
Supervised Learning

$\mathbf{x}_1 =$ 	$\mathbf{x}_2 =$ 	$\mathbf{x}_3 =$ 	$\mathbf{x}_4 =$ 	$\mathbf{x}_5 =$ 	$\mathbf{x}_6 =$ 	$\mathbf{x}_7 =$ 	$\mathbf{x}_8 =$ 
$\mathbf{t}_1 = (1, 0, 0)$	$\mathbf{t}_2 = (1, 0, 0)$	$\mathbf{t}_3 = (1, 0, 0)$	$\mathbf{t}_4 = (0, 0, 1)$	$\mathbf{t}_5 = (1, 0, 0)$	$\mathbf{t}_6 = (0, 0, 1)$	$\mathbf{t}_7 = (1, 0, 0)$	$\mathbf{t}_8 = (0, 0, 1)$
$\mathbf{x}_9 =$ 	$\mathbf{x}_{10} =$ 	$\mathbf{x}_{11} =$ 	$\mathbf{x}_{12} =$ 	$\mathbf{x}_{13} =$ 	$\mathbf{x}_{14} =$ 	$\mathbf{x}_{15} =$ 	$\mathbf{x}_{16} =$ 
$\mathbf{t}_9 = (0, 1, 0)$	$\mathbf{t}_{10} = (0, 0, 1)$	$\mathbf{t}_{11} = (1, 0, 0)$	$\mathbf{t}_{12} = (1, 0, 0)$	$\mathbf{t}_{13} = (0, 1, 0)$	$\mathbf{t}_{14} = (0, 1, 0)$	$\mathbf{t}_{15} = (0, 1, 0)$	$\mathbf{t}_{16} = (0, 1, 0)$
$\mathbf{x}_{17} =$ 	$\mathbf{x}_{18} =$ 	$\mathbf{x}_{20} =$ 	$\mathbf{x}_{21} =$ 	$\mathbf{x}_{22} =$ 	$\mathbf{x}_{23} =$ 	$\mathbf{x}_{24} =$ 	
$\mathbf{t}_{17} = (0, 0, 1)$	$\mathbf{t}_{18} = (0, 1, 0)$	$\mathbf{t}_{20} = (0, 1, 0)$	$\mathbf{t}_{21} = (0, 0, 1)$	$\mathbf{t}_{22} = (0, 0, 1)$	$\mathbf{t}_{23} = (1, 0, 0)$	$\mathbf{t}_{24} = (0, 1, 0)$	

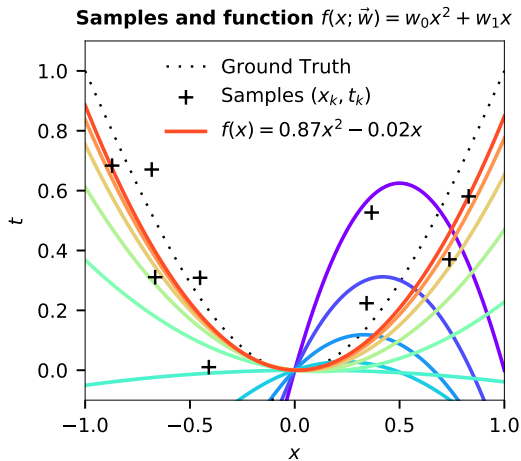
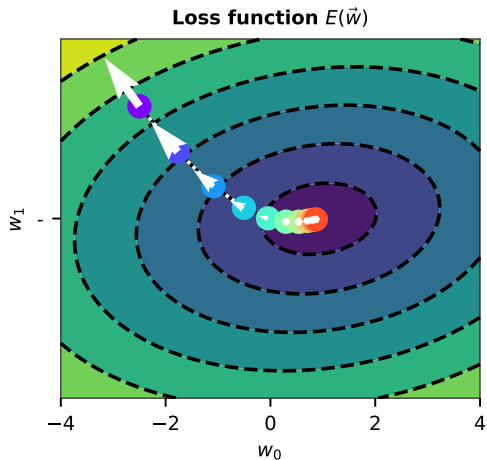
Supervised Learning – Training



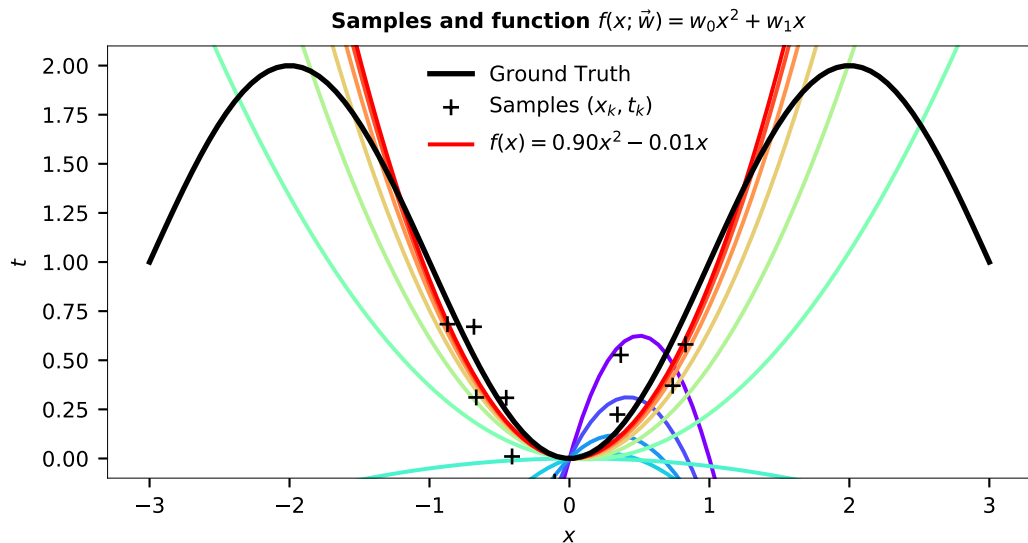
Supervised Learning – Inference



Gradient Descent – Example

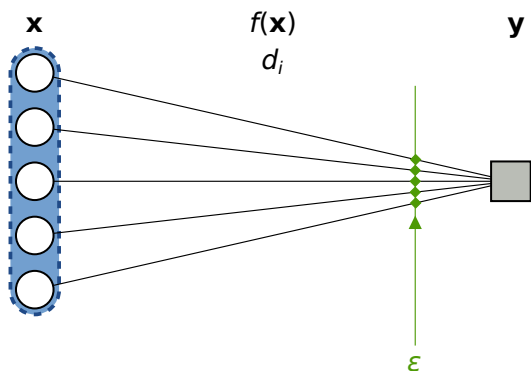


Supervised Learning – Generalisation



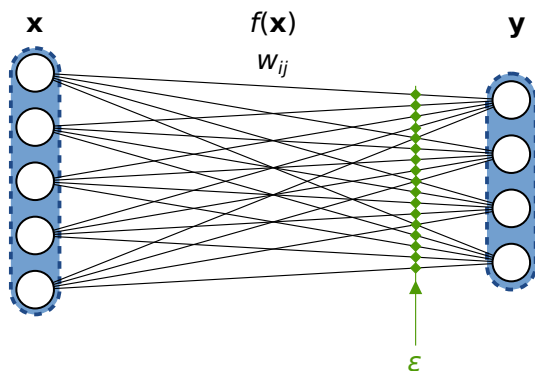
Learning Decoders and Learning Weights

Learning Decoders (Delta Rule)



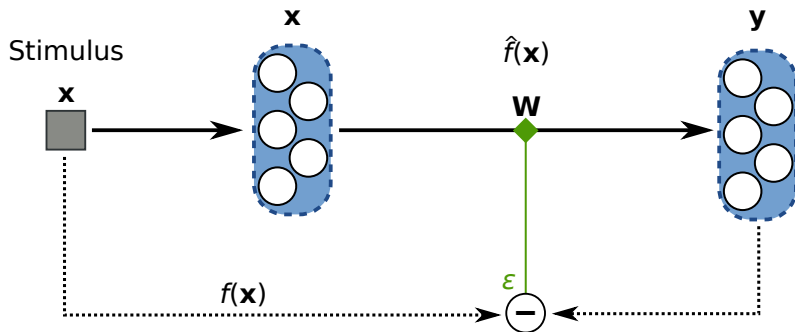
$$\Delta d_i = -\eta a_i(\mathbf{x}) \underbrace{(y(t) - y^d(t))}_{\varepsilon(t)}$$

Learning Weights (PES Rule)



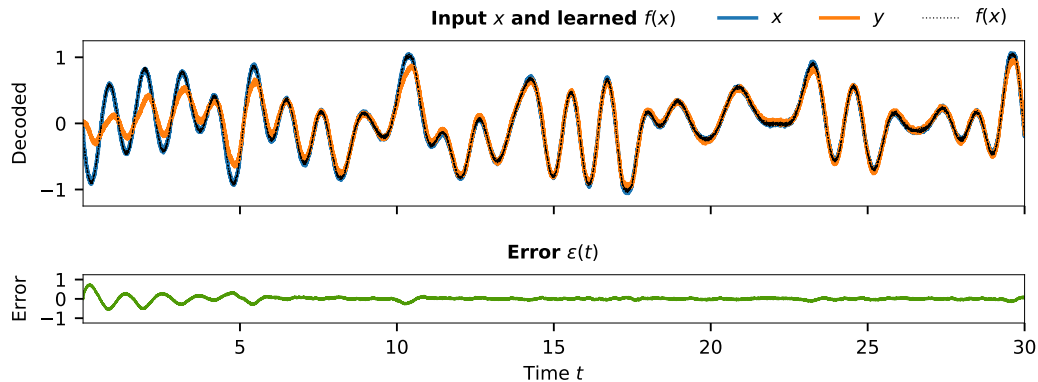
$$\Delta w_{ij} = -\eta a_i(\mathbf{x}) \left(\alpha_j \langle \mathbf{e}_j, \varepsilon(t) \rangle \right)$$

Example: Learning Functions (I)



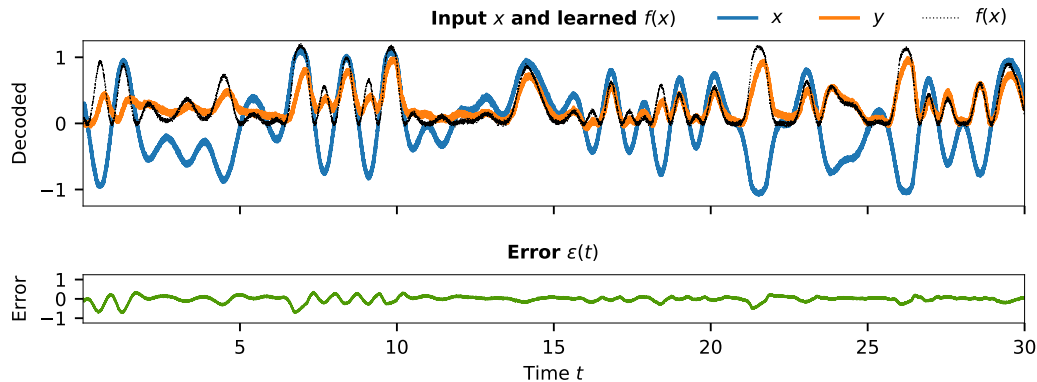
Example: Learning Functions (II)

Communication Channel $f(x) = x$



Example: Learning Functions (III)

Square $f(x) = x^2$

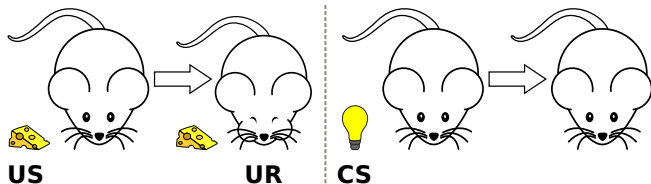


Works, but learns more slowly!

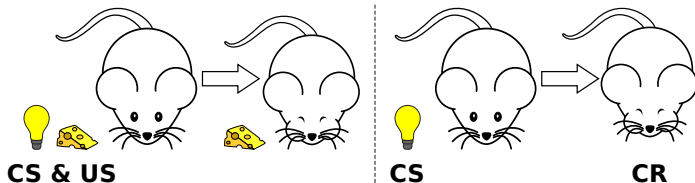
Where is the error signal $\varepsilon(t)$ coming from?

Example: Classical Conditioning (I)

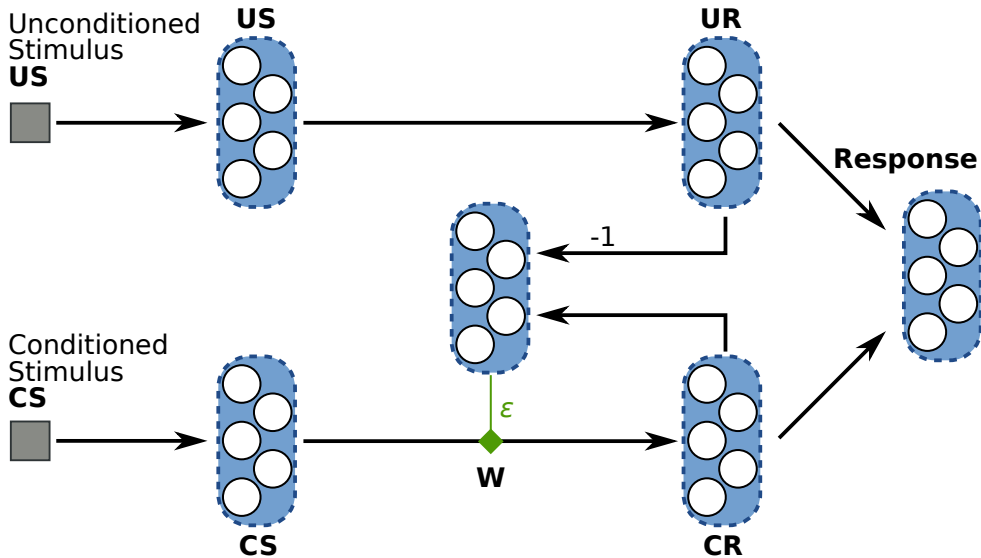
Before conditioning:



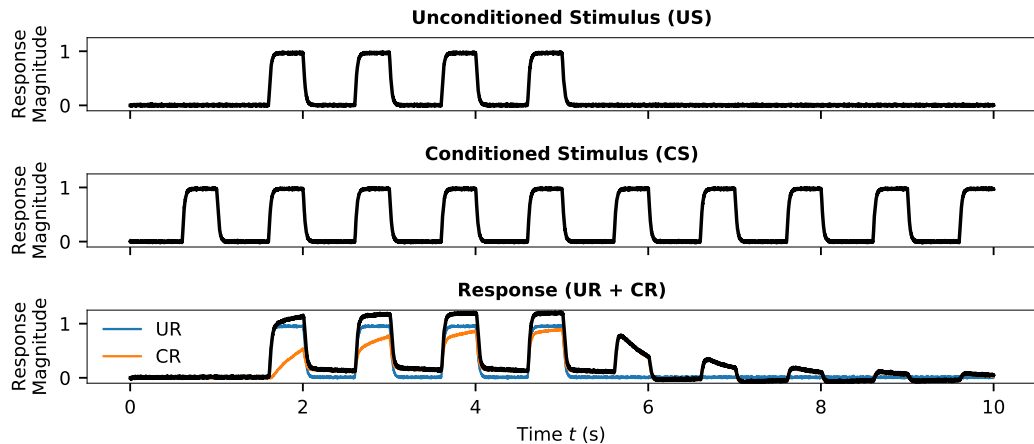
After conditioning:



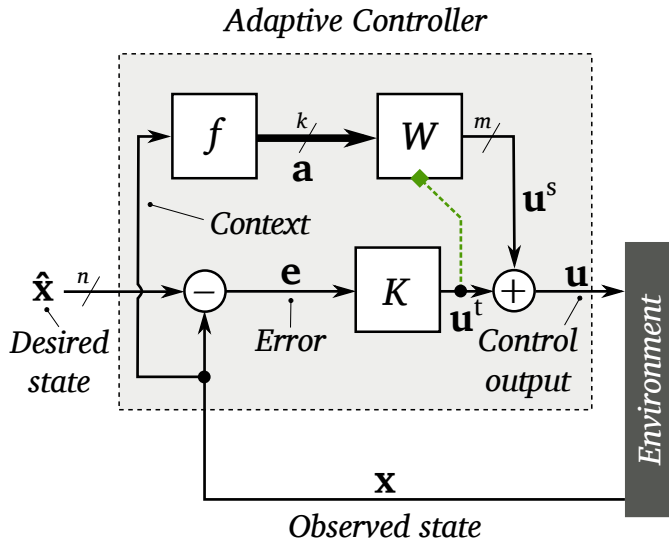
Example: Classical Conditioning (II)



Example: Classical Conditioning (III)



Example: Adaptive Controller



Unsupervised Learning

$\mathbf{x}_1 =$



$\mathbf{x}_2 =$



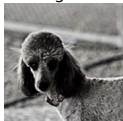
$\mathbf{x}_3 =$



$\mathbf{x}_4 =$



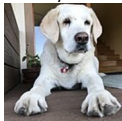
$\mathbf{x}_5 =$



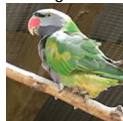
$\mathbf{x}_6 =$



$\mathbf{x}_7 =$



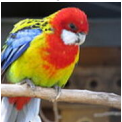
$\mathbf{x}_8 =$



$\mathbf{x}_9 =$



$\mathbf{x}_{10} =$



$\mathbf{x}_{11} =$



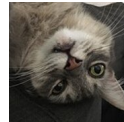
$\mathbf{x}_{12} =$



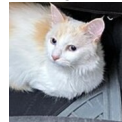
$\mathbf{x}_{13} =$



$\mathbf{x}_{14} =$



$\mathbf{x}_{15} =$



$\mathbf{x}_{16} =$



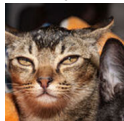
$\mathbf{x}_{17} =$



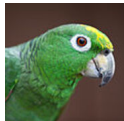
$\mathbf{x}_{18} =$



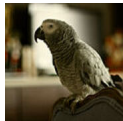
$\mathbf{x}_{20} =$



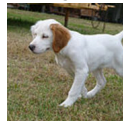
$\mathbf{x}_{21} =$



$\mathbf{x}_{22} =$



$\mathbf{x}_{23} =$



$\mathbf{x}_{24} =$



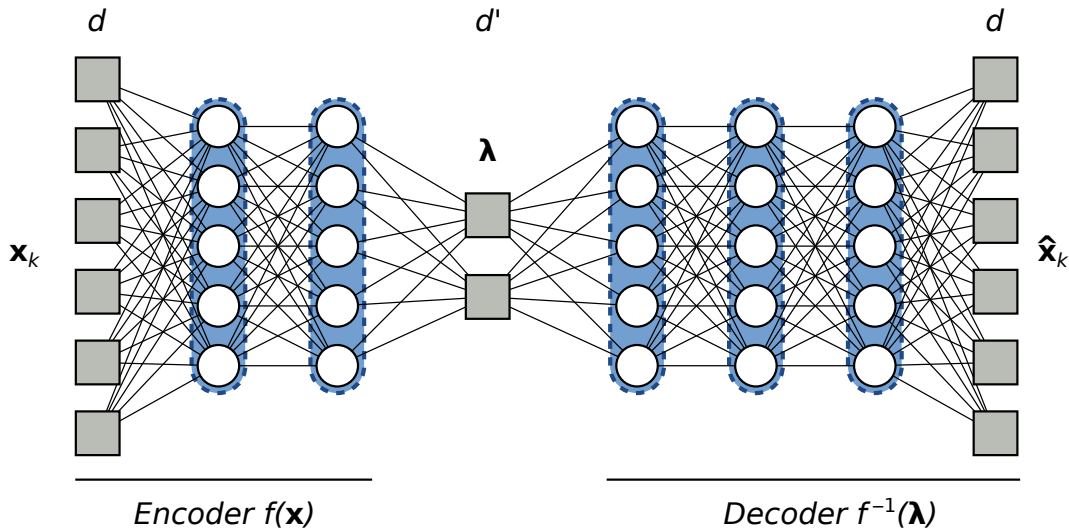
Unsupervised Learning – Training

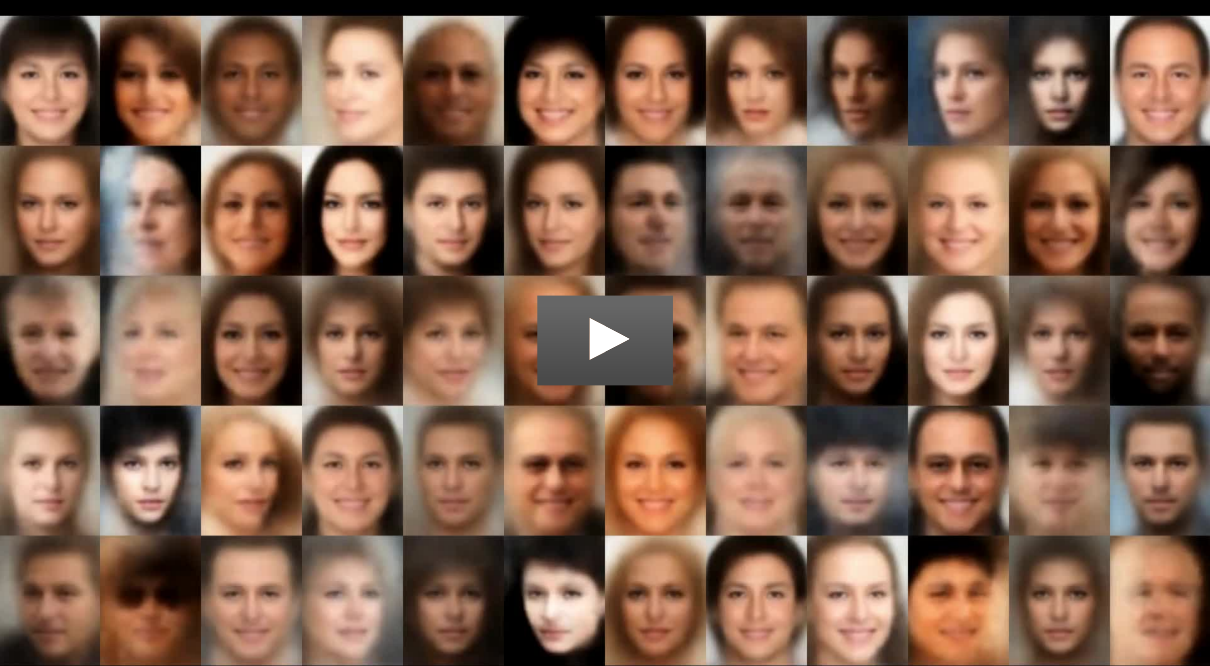


Unsupervised Learning – Inference



Autoencoder





PCA in Python



```
def PCA(X): # X: N x d matrix
    N, d = X.shape
    X_cen = X - np.mean(X, axis=0)
    C = (X_cen.T @ X_cen) / (N - 1)
    L, V = np.linalg.eigh(C) # "eigh" faster than "eig" for symmetric matrices
    return V.T[::-1, :] # d x d matrix
```

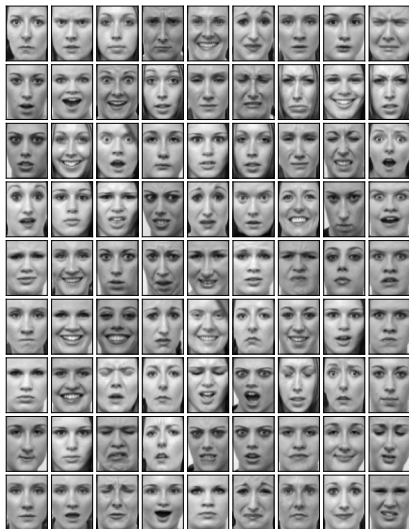


```
def PCA_SVD(X): # X: N x d matrix
    return np.linalg.svd(X - np.mean(X, axis=0))[2]
```

PCA Example: Source Images

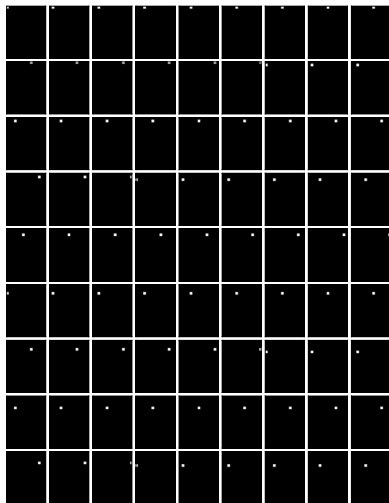
Face Database

- ▶ 84 images of 12 women with 7 different expressions
- ▶ Normalised eye location
- ▶ 45×60 pixels (2700 dimensions)
- ▶ Greyscale

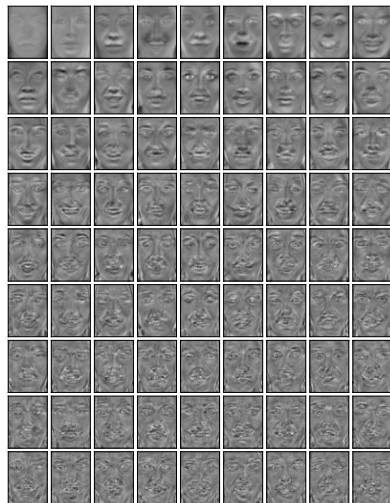


PCA Example: Eigenfaces

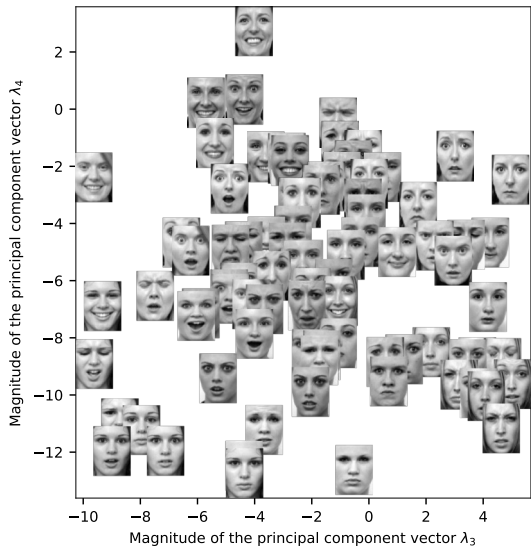
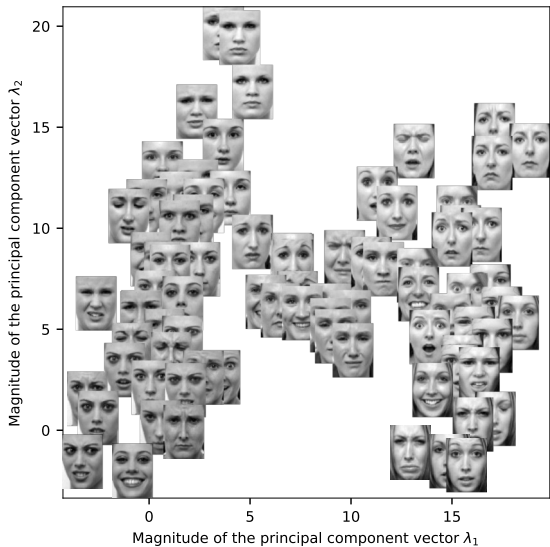
Identity Basis



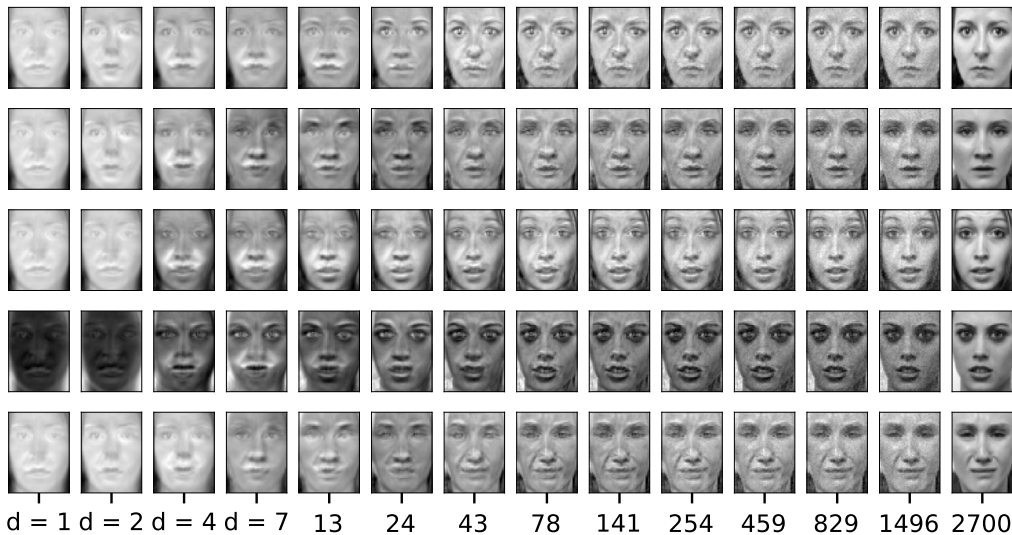
Principal Components



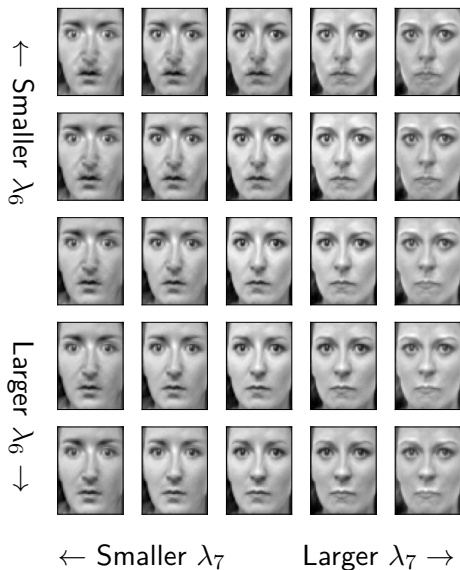
PCA Example: Face Spaces



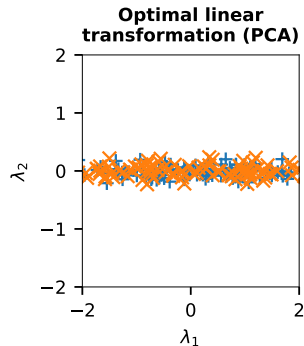
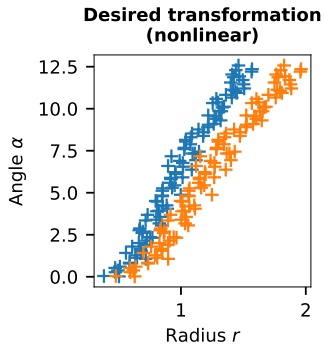
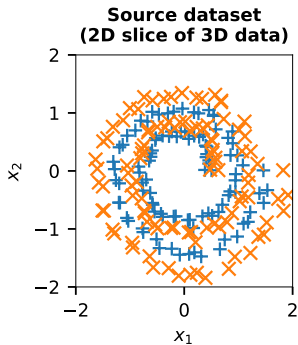
PCA Example: Sparse Vectors



PCA Example: Modifying the Latent Space



Limitations of PCA: Classifying Two Groups



Limitations of PCA: Metaphorical Illustration

Optimally extracted
manifold X'



Dataset X



PCA X'



PCA

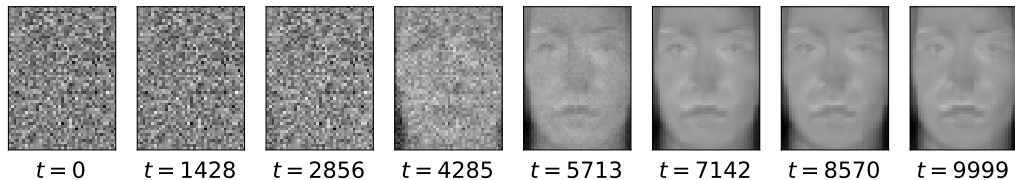
Projects ("squashes") data
onto a hyperplane

Hebbian Learning

When an axon of cell A is near enough to excite a cell B and repeatedly or persistently takes part in firing it, some growth process or metabolic change takes place in one or both cells such that A 's efficiency, as one of the cells firing B , is increased.

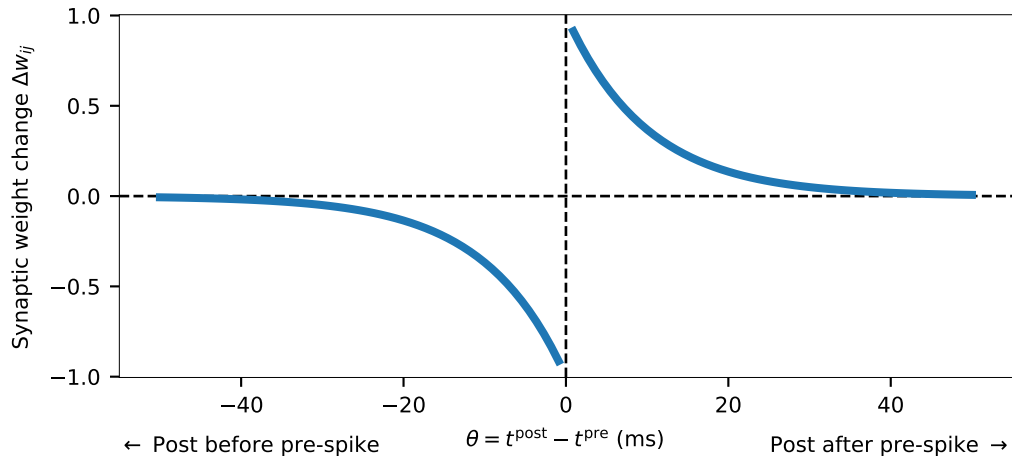
— Donald O. Hebb, “The Organization of Behaviour”, 1949

Example: Normalised Hebbian Learning



Learning an encoder \mathbf{e} , with $\|\mathbf{e}\| = 1$, 10000 steps, $\eta = 0.2 \times 10^{-4}$, $\Delta \mathbf{e} = \eta(\mathbf{x} \circ \mathbf{e})$

Spike-Time Dependent Plasticity



Conclusion

Supervised Learning

- ▶ Find \mathbf{w} such that $f(\mathbf{x}_k; \mathbf{w}) \approx \mathbf{t}_k$
- ▶ *Hope:* $f(\mathbf{x}_k; \mathbf{w}) \approx f_{\text{GT}}(\mathbf{x}_k)$
- ▶ Use gradient descent to find \mathbf{w}
- ▶ Delta, PES learning rules
- ▶ Modulatory synapses in the brain

Unsupervised Learning

- ▶ Dimensionality reduction $f(\mathbf{x}_k) = \lambda_k$
- ▶ *Hope:* latent dimensions λ are “meaningful”
- ▶ Autoencoders (nonlinear), PCA (linear)
- ▶ Hebbian learning \Rightarrow learns PCA

Image sources

Title slide

Page from “Liber ethicorum des Henricus de Alemannia”. Title: “Henricus de Alemannia con i suoi studenti” (Henricus of Germany with his students), second half of 14th century.
From Wikimedia.