

# CSC413: Homework 2

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## 1 Optimization

### 1.1 Stochastic Gradient Descent (SGD)

#### 1.1.1 Minimum Norm Solution

*Answer.* Recall from the previous homework that the solution found by gradient descent in the over-parameterized situation was

$$\mathbf{w}^* = X^T (X X^T)^{-1} \mathbf{t} \quad (1.1)$$

Moreover, the solution  $\mathbf{w}^*$  reached by gradient descent was in the row space of  $X$  (i.e., the span of rows of  $X$ ), and  $\mathbf{w}^*$  is a zero loss solution.

For one single updating using  $\mathbf{x}_i$  in the  $t^{th}$  iteration in the SGD process, the gradient is

$$\nabla_{\mathbf{w}_t} \mathcal{L}_i = \frac{\partial}{\partial \mathbf{w}_t} \|\mathbf{w}_t^T \mathbf{x}_i - t_i\|_2^2 \quad (1.2)$$

$$= 2 \underbrace{(\mathbf{w}_t^T \mathbf{x}_i - t_i)}_{\in \mathbb{R}} \mathbf{x}_i \quad (1.3)$$

$$\implies -\eta \nabla_{\mathbf{w}_t} \mathcal{L}_i \in \text{Row}(X) \quad (1.4)$$

Provided that the starting point  $\mathbf{w}_0 = \mathbf{0} \in \text{Row}(X)$ , for every  $t$ ,  $\mathbf{w}_t \in \text{Row}(X)$  by an inductive argument. Because  $\mathbf{w}_t \in \text{Row}(X)$ , let

$$\mathbf{w}_t = X_t^T \quad t \in \mathbb{R}^n \quad (1.5)$$

$$\hat{\mathbf{w}} = X^{T^\wedge} \quad \wedge \in \mathbb{R}^n \quad (1.6)$$

Note that, if  $\mathbf{x}_i$  is chosen for the  $t^{th}$  iteration of SGD, then only the  $i^{th}$  components of  $t$  and  $t_{+1}$  are different, and all other components are the same.

Suppose the solution  $\hat{\mathbf{w}}$  reached by SGD is a zero loss solution, that is,  $X \hat{\mathbf{w}} = \mathbf{t}$ . Then

$$X X^{T^\wedge} = \mathbf{t} \quad (1.7)$$

Because  $\hat{\mathbf{w}}$  is a global minimum and SGD converges to this point, then it must be the case that

$$\nabla_{\hat{\mathbf{w}}} \mathcal{L}_i(\mathbf{x}_i, \hat{\mathbf{w}}) = 0 \quad \forall i \in \{1, \dots, n\} \quad (1.8)$$

That is, one additional iteration of SGD does not improve performance no matter which sample is chosen. This is the same as

$$\nabla_{r_i} \|XX^{T^*} - \mathbf{t}\|_2^2 = 0 \quad \forall i \in \{1, \dots, n\} \quad (1.9)$$

$$\iff \nabla \|XX^{T^*} - \mathbf{t}\|_2^2 = 0 \quad (1.10)$$

$$\implies (XX^{T^*} - \mathbf{t})^T XX^T = 0 \quad (1.11)$$

$$\implies XX^T(XX^{T^*} - \mathbf{t}) = 0^T \quad (1.12)$$

$$\implies XX^T XX^{T^*} = XX^T \mathbf{t} \quad (1.13)$$

$$\implies \hat{\mathbf{w}} = (XX^T)^{-1} \mathbf{t} \quad (1.14)$$

$$\implies \hat{\mathbf{w}} = X^{T^*} = X^T (XX^T)^{-1} \mathbf{t} \quad (1.15)$$

$$= \mathbf{w}^* \quad (1.16)$$

■

### 1.1.2 Mini-batch SGD (Optional)

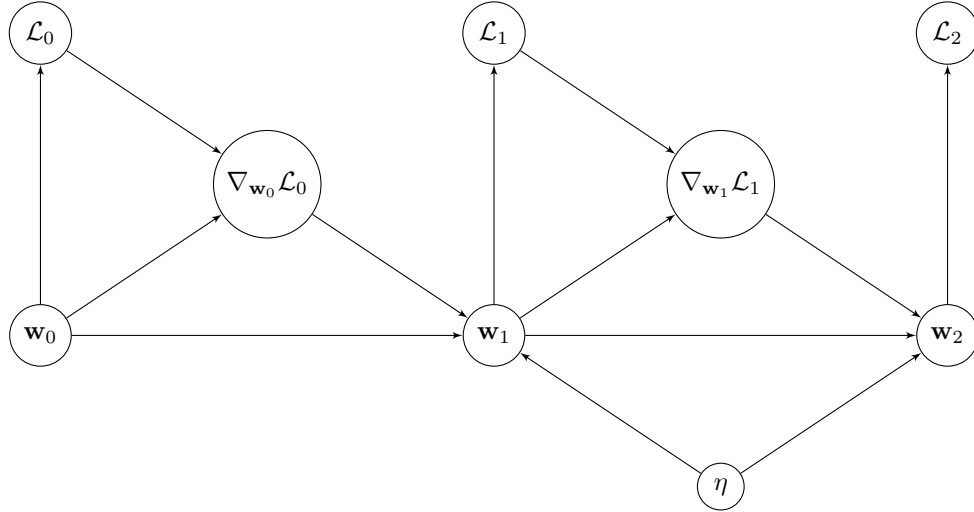
*Answer.*

■

## 2 Gradient-Based Hyper-Parameter Optimization

### 2.1 Computation Graph of Learning Rates

#### 2.1.1



#### 2.1.2

*Answer.*

**(Forward-Propagation)** For each iteration  $t$ , the prediction  $X\hat{\mathbf{w}} \in \mathbb{R}^n$  and label  $\mathbf{t}$  take memory of size  $2t$ , the loss takes 1 unit of memory. Therefore, the overall memory complexity is  $\mathcal{O}(d)$ .

**(Back-Propagation)**  $\nabla_{\eta} \mathcal{L}_t$  needs to be computed using chain rule through  $\mathbf{w}_{\tau}$  for every  $\tau \leq t$ . Note that for every  $\tau$ ,  $\nabla_{\mathbf{w}_{\tau}} \mathcal{L}_{\tau} \in \mathbb{R}^d$  and  $\frac{d}{d\eta} \mathbf{w}_{\tau} \in \mathbb{R}^d$ . The memory complexity is  $\mathcal{O}(dt)$ .

■

### 2.1.3

*Answer.* The memory complexity analysis in the previous question suggests the required memory of tracing gradient with respect to  $\eta$  grows linearly in the number of iterations, the memory cost can be prohibitive. ■

## 2.2 Learning Learning Rates

### 2.2.1

*Answer.*

$$\mathbf{w}_1 = \mathbf{w}_0 - \eta \nabla_{\mathbf{w}_0} \mathcal{L}_0 \quad (2.1)$$

$$= \mathbf{w}_0 - \frac{2\eta}{n} X^T (X \mathbf{w}_0 - \mathbf{t}) \quad (2.2)$$

$$\mathcal{L}_1 = \frac{1}{n} \|X \left[ \mathbf{w}_0 - \frac{2\eta}{n} X^T (X \mathbf{w}_0 - \mathbf{t}) \right] - \mathbf{t}\|_2^2 \quad (2.3)$$

$$= \frac{1}{n} \|X \left[ \mathbf{w}_0 - \frac{2\eta}{n} X^T \mathbf{a} \right] - \mathbf{t}\|_2^2 \quad (2.4)$$

$$= \frac{1}{n} \|X \mathbf{w}_0 - \frac{2\eta}{n} X X^T \mathbf{a} - \mathbf{t}\|_2^2 \quad (2.5)$$

$$= \frac{1}{n} \|\mathbf{a} - \frac{2\eta}{n} X X^T \mathbf{a}\|_2^2 \quad (2.6)$$

■

### 2.2.2

*Answer.* Note that the an arbitrary norm is convex: let  $\lambda \in [0, 1]$

$$\|\lambda x + (1 - \lambda)y\|_p \leq \|\lambda x\|_p + \|(1 - \lambda)y\|_p \text{ (triangle inequality)} \quad (2.7)$$

$$= |\lambda| \|x\|_p + |1 - \lambda| \|y\|_p \quad (2.8)$$

$$= \lambda \|x\|_p + (1 - \lambda) \|y\|_p \quad (2.9)$$

And  $f(x) = x^2$  is strictly convex as well. Moreover,  $\mathbf{a} - \frac{2\eta}{n} X X^T \mathbf{a}$  is linear in  $\eta$ .  $\mathcal{L}_1(\eta)$  is a composite of linear, convex and strictly convex functions. Therefore,  $\mathcal{L}_1(\eta)$  is strictly convex with respect to  $\eta$ . ■

### 2.2.3

*Answer.* The derivative of  $\mathcal{L}_1$  w.r.t.  $\eta$  is

$$\nabla_{\eta} \mathcal{L}_1 = \nabla_{\eta} \frac{1}{n} \|\mathbf{a} - \frac{2\eta}{n} X X^T \mathbf{a}\|_2^2 \quad (2.10)$$

$$= \frac{2}{n} \left( \mathbf{a} - \frac{2\eta}{n} X X^T \mathbf{a} \right)^T X X^T \mathbf{a} \quad (2.11)$$

$$= \frac{2}{n} \left( \mathbf{a}^T - \frac{2\eta}{n} \mathbf{a}^T X X^T \right) X X^T \mathbf{a} \quad (2.12)$$

$$= \frac{2}{n} \left( \mathbf{a}^T X X^T \mathbf{a} - \frac{2\eta}{n} \mathbf{a}^T X X^T X X^T \mathbf{a} \right) \quad (2.13)$$

Set derivative to zero and solve for the optimal learning rate  $\eta^*$ :

$$\nabla_{\eta} \mathcal{L}_1 = 0 \quad (2.14)$$

$$\Rightarrow \frac{2}{n} \left( \mathbf{a}^T X X^T \mathbf{a} - \frac{2\eta}{n} \mathbf{a}^T X X^T X X^T \mathbf{a} \right) = 0 \quad (2.15)$$

$$\Rightarrow \|X^T \mathbf{a}\|_2^2 = \frac{2\eta^*}{n} \|X X^T \mathbf{a}\|_2^2 \quad (2.16)$$

$$\Rightarrow \eta^* = \frac{n \|X^T \mathbf{a}\|_2^2}{2 \|X X^T \mathbf{a}\|_2^2} \quad (2.17)$$

■

### 3 Convolutional Neural Networks

#### 3.1 Convolutional Filters

*Answer.*

$$\mathbf{I} * \mathbf{J} = \begin{bmatrix} -1 & 2 & 2 & -2 & 0 \\ -2 & 1 & 0 & 2 & -1 \\ 3 & 0 & 0 & 1 & -1 \\ -2 & 2 & 0 & 2 & -1 \\ 0 & -2 & 3 & -2 & 0 \end{bmatrix} \quad (3.1)$$

This convolutional filter detect edges.

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#### 3.2 Size of ConvNets

*Answer.* The table below presents numbers of parameters in all layers.

Layer	Dim. In	Dim. Out	Num. Weights	Num. Bias	Total Params.
Conv3-64	112*112*3	112*112*64	3*3*3*64	64	1,792
Max Pool	112*112*64	56*56*64	0	0	0
Conv3-128	56*56*64	56*56*128	3*3*64*128	128	73,856
Max Pool	56*56*128	28*28*128	0	0	0
Conv3-256	28*28*128	28*28*256	3*3*128*256	256	295,168
Conv3-256	28*28*256	28*28*256	3*3*256*256	256	590,080
Max Pool	28*28*256	14*14*256	0	0	0
FC-1024	14*14*256	1024	14*14*256*1024	1024	51,381,248
FC-100	1024	100	1024*100	100	102,500
Softmax	100	100	0	0	0
Total					52,444,644

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