# **Practice Lab: Decision Trees**

In this exercise, you will implement a decision tree from scratch and apply it to the task of classifying whether a mushroom is edible or poisonous.

# Outline

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**NOTE:** To prevent errors from the autograder, you are not allowed to edit or delete non-graded cells in this notebook. Please also refrain from adding any new cells. **Once you have passed this assignment** and want to experiment with any of the non-graded code, you may follow the instructions at the bottom of this notebook.

# 1 - Packages

First, let's run the cell below to import all the packages that you will need during this assignment.

- numpy is the fundamental package for working with matrices in Python.
- matplotlib is a famous library to plot graphs in Python.
- utils.py contains helper functions for this assignment. You do not need to modify code in this file.

## 2 - Problem Statement

Suppose you are starting a company that grows and sells wild mushrooms.

- Since not all mushrooms are edible, you'd like to be able to tell whether a given mushroom is edible or poisonous based on it's physical attributes
- You have some existing data that you can use for this task.

Can you use the data to help you identify which mushrooms can be sold safely?

Note: The dataset used is for illustrative purposes only. It is not meant to be a guide on identifying edible mushrooms.

## 3 - Dataset

You will start by loading the dataset for this task. The dataset you have collected is as follows:

	Cap Color	Stalk Shape	Solitary	Edible
drav drav	Brown	Tapering	Yes	1
drav drav	Brown	Enlarging	Yes	1
drav drav	Brown	Enlarging	No	0
drav drav	Brown	Enlarging	No	0
drav drav	Brown	Tapering	Yes	1
drav drav	Red	Tapering	Yes	0

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	Cap Color	Stalk Shape	Solitary	Edible
drav drav	Red	Enlarging	No	0
drav drav	Brown	Enlarging	Yes	1
drav drav	Red	Tapering	No	1
drav drav	Brown	Enlarging	No	0

- You have 10 examples of mushrooms. For each example, you have
  - Three features
    - Cap Color (Brown or Red),
    - $\circ$  Stalk Shape ( Tapering (as in \/) or Enlarging (as in /\) ), and
    - Solitary ( Yes or No )
  - Label
    - Edible (1 indicating yes or 0 indicating poisonous)

## 3.1 One hot encoded dataset

For ease of implementation, we have one-hot encoded the features (turned them into 0 or 1 valued features)

	<b>Brown Cap</b>	<b>Tapering Stalk Shape</b>	Solitary	Edible
drav drav	1	1	1	1
drav	1	0	1	1
drav	1	0	0	0
drav	1	0	0	0
drav drav	1	1	1	1
drav drav	0	1	1	0

	Brown Cap	<b>Tapering Stalk Shape</b>	Solitary	Edible
☑ drav	0	0	0	0
🚨 drav	1	0	1	1
drav drav	0	1	0	1
🗟 drav	1	0	0	0

#### Therefore,

- X\_train contains three features for each example
  - Brown Color (A value of 1 indicates "Brown" cap color and 0 indicates "Red" cap color)
  - Tapering Shape (A value of 1 indicates "Tapering Stalk Shape" and 0 indicates "Enlarging" stalk shape)
  - Solitary (A value of 1 indicates "Yes" and 0 indicates "No")
- y\_train is whether the mushroom is edible
  - y = 1 indicates edible
  - y = 0 indicates poisonous

```
In [ ]: X_train = np.array([[1,1,1],[1,0,1],[1,0,0],[1,0,0],[1,1,1],[0,1,1],[0,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,0],[1,0,
```

#### View the variables

Let's get more familiar with your dataset.

• A good place to start is to just print out each variable and see what it contains.

The code below prints the first few elements of X\_train and the type of the variable.

```
In [ ]: print("First few elements of X_train:\n", X_train[:5])
    print("Type of X_train:",type(X_train))

First few elements of X_train:
    [[1 1 1]
    [1 0 1]
    [1 0 0]
    [1 0 0]
    [1 1 1]]
Type of X_train: <class 'numpy.ndarray'>
```

Now, let's do the same for y\_train

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```
In [ ]: print("First few elements of y_train:", y_train[:5])
    print("Type of y_train:",type(y_train))

First few elements of y_train: [1 1 0 0 1]
    Type of y_train: <class 'numpy.ndarray'>
```

### Check the dimensions of your variables

Another useful way to get familiar with your data is to view its dimensions.

Please print the shape of X\_train and y\_train and see how many training examples you have in your dataset.

```
In [ ]: print ('The shape of X_train is:', X_train.shape)
    print ('The shape of y_train is: ', y_train.shape)
    print ('Number of training examples (m):', len(X_train))

The shape of X_train is: (10, 3)
    The shape of y_train is: (10,)
    Number of training examples (m): 10
```

## 4 - Decision Tree Refresher

In this practice lab, you will build a decision tree based on the dataset provided.

- Recall that the steps for building a decision tree are as follows:
  - Start with all examples at the root node
  - Calculate information gain for splitting on all possible features, and pick the one with the highest information gain
  - Split dataset according to the selected feature, and create left and right branches of the tree
  - Keep repeating splitting process until stopping criteria is met
- In this lab, you'll implement the following functions, which will let you split a node into left and right branches using the feature with the highest information gain
  - Calculate the entropy at a node
  - Split the dataset at a node into left and right branches based on a given feature
  - Calculate the information gain from splitting on a given feature
  - Choose the feature that maximizes information gain
- We'll then use the helper functions you've implemented to build a decision tree by repeating the splitting process until the stopping criteria is met
  - For this lab, the stopping criteria we've chosen is setting a maximum depth of 2

# 4.1 Calculate entropy

First, you'll write a helper function called compute\_entropy that computes the entropy (measure of impurity) at a node.

• The function takes in a numpy array ( y ) that indicates whether the examples in that node are edible ( 1 ) or poisonous( 0 )

Complete the compute\_entropy() function below to:

- ullet Compute  $p_1$ , which is the fraction of examples that are edible (i.e. have value =  $\, {f 1} \,$  in  $\, {f y} \,$  )
- The entropy is then calculated as

$$H(p_1) = -p_1 \log_2(p_1) - (1-p_1) \log_2(1-p_1)$$

- Note
  - The log is calculated with base 2
  - $\blacksquare$  For implementation purposes,  $0\log_2(0)=0.$  That is, if <code>p\_1 = 0</code> or <code>p\_1 = 1</code> , set the entropy to <code>0</code>
  - Make sure to check that the data at a node is not empty (i.e. len(y) != 0).
     Return 0 if it is

### Exercise 1

Please complete the compute\_entropy() function using the previous instructions.

If you get stuck, you can check out the hints presented after the cell below to help you with the implementation.

```
In [ ]: # UNQ C1
        # GRADED FUNCTION: compute_entropy
        def compute_entropy(y):
            Computes the entropy for
            Args:
               y (ndarray): Numpy array indicating whether each example at a node is
                   edible (`1`) or poisonous (`0`)
                entropy (float): Entropy at that node
            # You need to return the following variables correctly
            entropy = 0.
            ### START CODE HERE ###
            if len(y) !=0:
                p1 = len(y[y==1]) / len(y)
                if p1 != 0 and p1 != 1:
                    entropy = -p1 * np.log2(p1) - (1 - p1) * np.log2(1-p1)
            ### END CODE HERE ###
            return entropy
```

### **▶** Click for hints

You can check if your implementation was correct by running the following test code:

```
In [ ]: # Compute entropy at the root node (i.e. with all examples)
# Since we have 5 edible and 5 non-edible mushrooms, the entropy should be 1"

print("Entropy at root node: ", compute_entropy(y_train))
# UNIT TESTS
compute_entropy_test(compute_entropy)
```

Entropy at root node: 1.0 All tests passed.

#### **Expected Output:**

#### Entropy at root node: 1.0

# 4.2 Split dataset

Next, you'll write a helper function called split\_dataset that takes in the data at a node and a feature to split on and splits it into left and right branches. Later in the lab, you'll implement code to calculate how good the split is.

- The function takes in the training data, the list of indices of data points at that node, along with the feature to split on.
- It splits the data and returns the subset of indices at the left and the right branch.
- For example, say we're starting at the root node (so node\_indices =
   [0,1,2,3,4,5,6,7,8,9] ), and we chose to split on feature 0, which is whether or not the example has a brown cap.
  - The output of the function is then, left\_indices = [0,1,2,3,4,7,9] (data points with brown cap) and right\_indices = [5,6,8] (data points without a brown cap)

		<b>Brown Cap</b>	<b>Tapering Stalk Shape</b>	Solitary	Edible
0	drav drav	1	1	1	1
1	drav drav	1	0	1	1
2	drav drav	1	0	0	0
3	drav drav	1	0	0	0
4	drav drav	1	1	1	1

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		Brown Cap	<b>Tapering Stalk Shape</b>	Solitary	Edible
5	☑ drav	0	1	1	0
6	drav drav	0	0	0	0
7	🗟 drav	1	0	1	1
8	🗟 drav	0	1	0	1
9	drav drav	1	0	0	0

### Exercise 2

Please complete the split\_dataset() function shown below

- For each index in node\_indices
  - If the value of X at that index for that feature is 1, add the index to left\_indices
  - If the value of X at that index for that feature is 0, add the index to right\_indices

If you get stuck, you can check out the hints presented after the cell below to help you with the implementation.

```
In [ ]: # UNQ_C2
       # GRADED FUNCTION: split_dataset
       def split_dataset(X, node_indices, feature):
          Splits the data at the given node into
          left and right branches
          Args:
              X (ndarray):
                                   Data matrix of shape(n_samples, n_features)
              node_indices (list): List containing the active indices. I.e, the sa
              feature (int):
                                    Index of feature to split on
          Returns:
              # You need to return the following variables correctly
           left_indices = []
           right_indices = []
```

```
### START CODE HERE ###
for i in node_indices:
    if X[i][feature] == 1:
        left_indices.append(i)
    else:
        right_indices.append(i)

### END CODE HERE ##

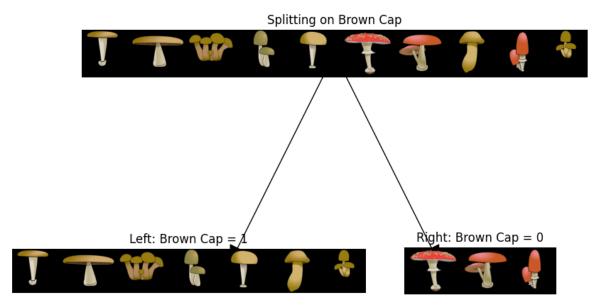
return left_indices, right_indices
```

#### Click for hints

Now, let's check your implementation using the code blocks below. Let's try splitting the dataset at the root node, which contains all examples at feature 0 (Brown Cap) as we'd discussed above. We've also provided a helper function to visualize the output of the split.

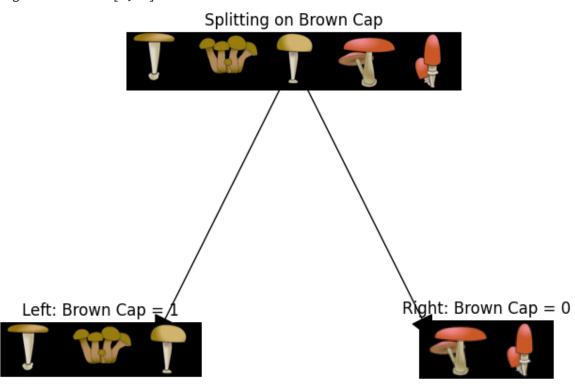
```
In [ ]: # Case 1
        root_indices = [0, 1, 2, 3, 4, 5, 6, 7, 8, 9]
        # Feel free to play around with these variables
        # The dataset only has three features, so this value can be 0 (Brown Cap), 1 (Ta
        feature = 0
        left_indices, right_indices = split_dataset(X_train, root_indices, feature)
        print("CASE 1:")
        print("Left indices: ", left_indices)
        print("Right indices: ", right_indices)
        # Visualize the split
        generate_split_viz(root_indices, left_indices, right_indices, feature)
        print()
        # Case 2
        root_indices_subset = [0, 2, 4, 6, 8]
        left_indices, right_indices = split_dataset(X_train, root_indices_subset, featur
        print("CASE 2:")
        print("Left indices: ", left_indices)
        print("Right indices: ", right_indices)
        # Visualize the split
        generate_split_viz(root_indices_subset, left_indices, right_indices, feature)
        # UNIT TESTS
        split_dataset_test(split_dataset)
       CASE 1:
```

Left indices: [0, 1, 2, 3, 4, 7, 9] Right indices: [5, 6, 8]



CASE 2:

Left indices: [0, 2, 4] Right indices: [6, 8]



All tests passed.

### **Expected Output:**

CASE 1:

Left indices: [0, 1, 2, 3, 4, 7, 9]

Right indices: [5, 6, 8]

CASE 2:

Left indices: [0, 2, 4] Right indices: [6, 8]

# 4.3 Calculate information gain

Next, you'll write a function called information\_gain that takes in the training data, the indices at a node and a feature to split on and returns the information gain from the split.

### Exercise 3

Please complete the compute\_information\_gain() function shown below to compute

$$ext{Information Gain} = H(p_1^{ ext{node}}) - (w^{ ext{left}}H(p_1^{ ext{left}}) + w^{ ext{right}}H(p_1^{ ext{right}}))$$

where

- ullet  $H(p_1^{
  m node})$  is entropy at the node
- ullet  $H(p_1^{
  m left})$  and  $H(p_1^{
  m right})$  are the entropies at the left and the right branches resulting from the split
- ullet  $w^{
  m left}$  and  $w^{
  m right}$  are the proportion of examples at the left and right branch, respectively

#### Note:

- You can use the compute\_entropy() function that you implemented above to calculate the entropy
- We've provided some starter code that uses the split\_dataset() function you implemented above to split the dataset

If you get stuck, you can check out the hints presented after the cell below to help you with the implementation.

```
In [ ]: # UNO C3
        # GRADED FUNCTION: compute_information_gain
        def compute_information_gain(X, y, node_indices, feature):
            Compute the information of splitting the node on a given feature
            Args:
                X (ndarray):
                                        Data matrix of shape(n_samples, n_features)
                y (array like):
                                        list or ndarray with n_samples containing the ta
                node_indices (ndarray): List containing the active indices. I.e, the sam
            Returns:
                cost (float): Cost computed
            # Split dataset
            left_indices, right_indices = split_dataset(X, node_indices, feature)
            # Some useful variables
            X_node, y_node = X[node_indices], y[node_indices]
            X_left, y_left = X[left_indices], y[left_indices]
            X_right, y_right = X[right_indices], y[right_indices]
```

```
# You need to return the following variables correctly
information_gain = 0

### START CODE HERE ###

node_entropy = compute_entropy(y_node)
left_entropy = compute_entropy(y_left)
right_entropy = compute_entropy(y_right)
w_left = len(X_left) / len(X_node)
w_right = len(X_right) / len(X_node)
weighted_entropy = w_left * left_entropy + w_right * right_entropy
information_gain = node_entropy - weighted_entropy
### END CODE HERE ###

return information_gain
```

#### Click for hints

You can now check your implementation using the cell below and calculate what the information gain would be from splitting on each of the features

```
In [ ]: info_gain0 = compute_information_gain(X_train, y_train, root_indices, feature=0)
    print("Information Gain from splitting the root on brown cap: ", info_gain0)

info_gain1 = compute_information_gain(X_train, y_train, root_indices, feature=1)
    print("Information Gain from splitting the root on tapering stalk shape: ", info
    info_gain2 = compute_information_gain(X_train, y_train, root_indices, feature=2)
    print("Information Gain from splitting the root on solitary: ", info_gain2)

# UNIT TESTS
    compute_information_gain_test(compute_information_gain)
```

Information Gain from splitting the root on brown cap: 0.034851554559677034

Information Gain from splitting the root on tapering stalk shape: 0.124511249783
65313

Information Gain from splitting the root on solitary: 0.2780719051126377 All tests passed.

### **Expected Output:**

```
Information Gain from splitting the root on brown cap: 0.034851554559677034

Information Gain from splitting the root on tapering stalk shape: 0.12451124978365313

Information Gain from splitting the root on solitary: 0.2780719051126377
```

Splitting on "Solitary" (feature = 2) at the root node gives the maximum information gain. Therefore, it's the best feature to split on at the root node.

# 4.4 Get best split

Now let's write a function to get the best feature to split on by computing the information gain from each feature as we did above and returning the feature that gives the maximum information gain

## Exercise 4

Please complete the get\_best\_split() function shown below.

- The function takes in the training data, along with the indices of datapoint at that node
- The output of the function is the feature that gives the maximum information gain
  - You can use the compute\_information\_gain() function to iterate through the features and calculate the information for each feature If you get stuck, you can check out the hints presented after the cell below to help you with the implementation.

```
In [ ]: # UNQ C4
        # GRADED FUNCTION: get_best_split
        def get_best_split(X, y, node_indices):
            Returns the optimal feature and threshold value
            to split the node data
            Args:
                X (ndarray):
                                       Data matrix of shape(n_samples, n_features)
                                        list or ndarray with n samples containing the ta
                y (array like):
                node_indices (ndarray): List containing the active indices. I.e, the sam
            Returns:
                best_feature (int): The index of the best feature to split
            # Some useful variables
            num_features = X.shape[1]
            # You need to return the following variables correctly
            best_feature = -1
            ### START CODE HERE ###
            max_info_gain = 0
            for feature in range (num_features):
                info_gain = compute_information_gain(X, y, node_indices, feature)
                if info gain > max info gain:
                    max_info_gain = info_gain
                    best feature = feature
            ### END CODE HERE ##
            return best_feature
```

#### **▶** Click for hints

Now, let's check the implementation of your function using the cell below.

```
In [ ]: best_feature = get_best_split(X_train, y_train, root_indices)
print("Best feature to split on: %d" % best_feature)
```

```
# UNIT TESTS
get_best_split_test(get_best_split)
```

```
Best feature to split on: 2 All tests passed.
```

As we saw above, the function returns that the best feature to split on at the root node is feature 2 ("Solitary")

# 5 - Building the tree

In this section, we use the functions you implemented above to generate a decision tree by successively picking the best feature to split on until we reach the stopping criteria (maximum depth is 2).

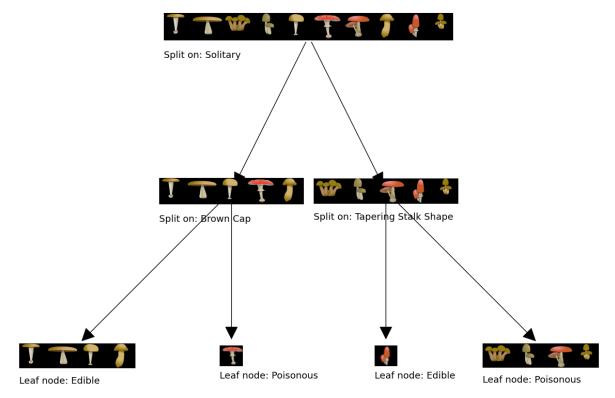
You do not need to implement anything for this part.

```
In [ ]: # Not graded
         tree = []
         def build_tree_recursive(X, y, node_indices, branch_name, max_depth, current_dep
             Build a tree using the recursive algorithm that split the dataset into 2 sub
             This function just prints the tree.
             Args:
                 X (ndarray):
                                           Data matrix of shape(n_samples, n_features)
                 y (array like):
                                           list or ndarray with n_samples containing the ta
                 node_indices (ndarray): List containing the active indices. I.e, the sam
                 branch_name (string): Name of the branch. ['Root', 'Left', 'Right']
max_depth (int): Max depth of the resulting tree.
current_depth (int): Current depth. Parameter used during recursive c
             # Maximum depth reached - stop splitting
             if current depth == max depth:
                 formatting = " "*current_depth + "-"*current_depth
                 print(formatting, "%s leaf node with indices" % branch_name, node_indice
                 return
             # Otherwise, get best split and split the data
             # Get the best feature and threshold at this node
             best_feature = get_best_split(X, y, node_indices)
             formatting = "-"*current_depth
             print("%s Depth %d, %s: Split on feature: %d" % (formatting, current_depth,
             # Split the dataset at the best feature
             left_indices, right_indices = split_dataset(X, node_indices, best_feature)
             tree.append((left_indices, right_indices, best_feature))
             # continue splitting the left and the right child. Increment current depth
             build_tree_recursive(X, y, left_indices, "Left", max_depth, current_depth+1)
             build_tree_recursive(X, y, right_indices, "Right", max_depth, current_depth+
```

```
In [ ]: build_tree_recursive(X_train, y_train, root_indices, "Root", max_depth=2, curren
        generate_tree_viz(root_indices, y_train, tree)
        Depth 0, Root: Split on feature: 2
       - Depth 1, Left: Split on feature: 0
```

- -- Right leaf node with indices [5]
- Depth 1, Right: Split on feature: 1
  - -- Left leaf node with indices [8]
  - -- Right leaf node with indices [2, 3, 6, 9]

-- Left leaf node with indices [0, 1, 4, 7]



▶ Please click here if you want to experiment with any of the non-graded code.