

## Task1: Install Ros and Ubuntu

-go to the safari

-First to you need to install Virtual Box:

To install it go to <https://www.virtualbox.org/>

And selection VirtualBox platform packages

-Second to install ubuntu go to <https://ubuntu.com/download/desktop>

-Third to install ROS on virtual box using ubuntu commands on this website

<http://wiki.ros.org/noetic/Installation/Ubuntu>

## Task 2: installing ROS2

-First install ROS2-foxy from this website

<https://docs.ros.org/en/foxy/Installation/Ubuntu-Install-Debians.html#id8>

-Enter the commands in ubuntu

-Finally download Balena for jetson nano

<https://www.balena.io/etcher/>