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# **Assignment 4: Multivariable Calculus & Optimization**

**Math4AI Program: Calculus Foundations**

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# 1 Introduction

This assignment focuses on the fundamental tools of Multivariable Calculus—the Gradient ( $\nabla f$ ), the Hessian Matrix ( $\mathbf{H}$ ), and Numerical Double Integration—which are essential for navigating and optimizing high-dimensional loss functions in Machine Learning and AI. The goal is to implement these tools from scratch using numerical approximation techniques.

## 2 Mathematical Foundations

### 2.1 The Gradient Vector ( $\nabla f$ )

The gradient points in the direction of the steepest ascent of a function  $f(\mathbf{x})$ . It is approximated using the Forward Difference finite approximation:

$$\frac{\partial f}{\partial x_i}(\mathbf{a}) \approx \frac{f(\mathbf{a} + h\mathbf{e}_i) - f(\mathbf{a})}{h}$$

The resulting vector is:

$$\nabla f(\mathbf{a}) = \left[ \frac{\partial f}{\partial x_1}(\mathbf{a}), \dots, \frac{\partial f}{\partial x_n}(\mathbf{a}) \right]$$

### 2.2 The Hessian Matrix ( $\mathbf{H}$ )

The Hessian matrix describes the local curvature of the function's landscape, which is crucial for determining if a critical point is a minimum, maximum, or a saddle point. Its elements are the second-order partial derivatives:

$$H_{ij} = \frac{\partial^2 f}{\partial x_i \partial x_j}$$

The numerical implementation approximates this by applying the partial derivative function iteratively.

### 2.3 Numerical Double Integration

The double integral of  $f(x, y)$  over a rectangular region  $R = [a, b] \times [c, d]$  is approximated using a nested Midpoint Riemann Sum (Double Riemann Sum):

$$\iint_R f(x, y) dx dy \approx \sum_{j=0}^{n_y-1} \sum_{i=0}^{n_x-1} f(x_i^*, y_j^*) \Delta x \Delta y$$

This technique is vital for calculating probabilities from Joint Probability Density Functions in AI models.

## 3 Implementation and Methodology

### 3.1 Objective

The main objective was to implement four core functions from scratch: `partial_derivative`, `compute_gradient`, `compute_hessian`, and `double_integral`.

### 3.2 Methodology Details

- **Gradient:** `partial_derivative` was defined first using the Forward Difference. `compute_gradient` iteratively called this function for every dimension.
- **Hessian:** `compute_hessian` utilized the implemented `partial_derivative` function in a nested manner to approximate the second-order mixed partial derivatives, ensuring the resulting matrix is numerically symmetric.
- **Double Integral:** `double_integral` implemented a nested loop structure to calculate the sum of function values at the midpoints of  $n_x \times n_y$  sub-rectangles, then scaled the result by the area of the differential element  $\Delta x \Delta y$ .

## 4 Results and Verification

### 4.1 Problem 1.1: Gradient Vector Verification

The gradient was computed for the function  $f(x, y) = x^2 + 2y^2$  at the test point  $\mathbf{a} = [1.0, 1.0]$ . The analytical gradient is  $\nabla f(1, 1) = [2.0, 4.0]$ .

Table 1: Gradient Calculation Results (Problem 1.1)

Method	Gradient Vector $\nabla f(1, 1)$
Scratch Implementation	2.0000000000, 4.0000000000

#### 4.1.1 Contour and Gradient Vector Plot

The plot below shows the contour lines of the function and the computed gradient vectors.

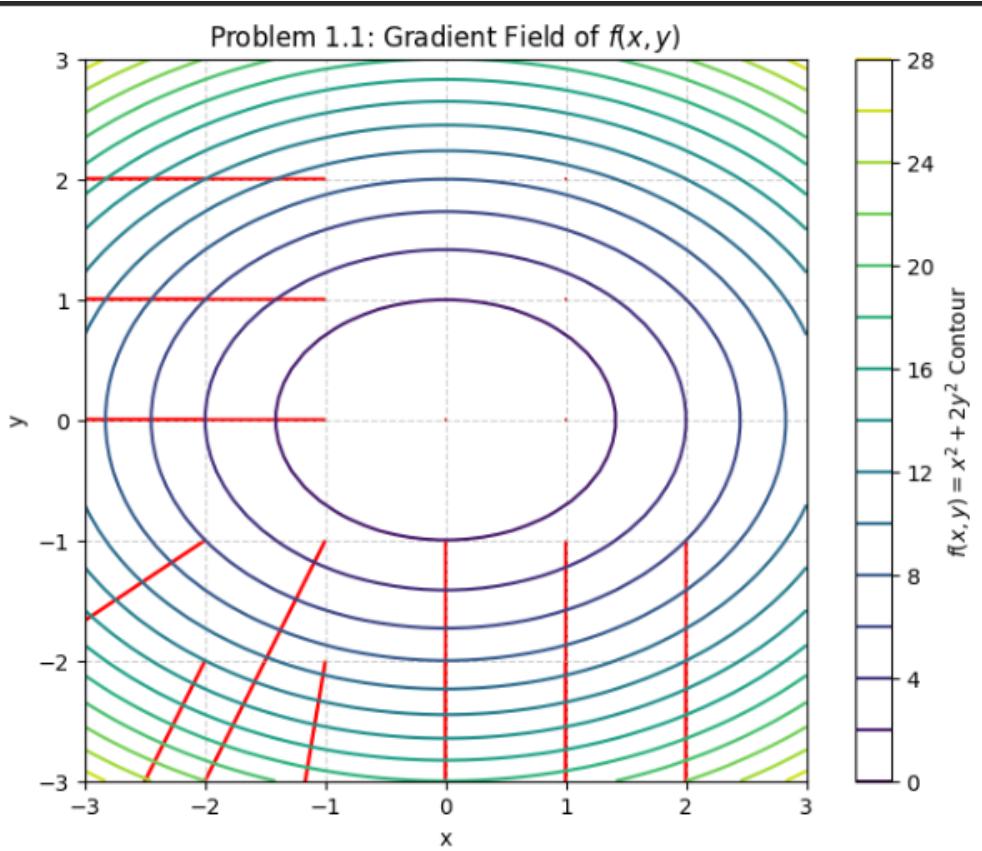


Figure 1: Contour Plot and Gradient Field for  $f(x, y) = x^2 + 2y^2$

**Discussion (1.1):** The numerical result matches the analytical expectation. The plot confirms that the gradient vectors are perpendicular to the contour lines, pointing towards the steepest ascent.

## 4.2 Problem 1.2: Hessian Matrix Verification

The Hessian was computed for the function  $f(x, y) = x^2 - y^2$  at  $\mathbf{a} = [5.0, -3.0]$ .

Table 2: Hessian Matrix Comparison (Problem 1.2)

Method	Hessian Matrix $\mathbf{H}$
Scratch Implementation	$\begin{pmatrix} 2.00000000000 & 0.00000000000 \\ 0.00000000000 & -2.00000000000 \end{pmatrix}$
SymPy Verification (Analytical)	$\begin{pmatrix} 2 & 0 \\ 0 & -2 \end{pmatrix}$

**Discussion (1.2):** The numerical and symbolic results match exactly. The indefinite nature of the Hessian (mixed eigenvalues) confirms a Saddle Point.

### 4.3 Problem 1.3: Double Integration Verification

The double integral of  $f(x, y) = x \cdot \sin(y)$  was computed over  $x \in [0.0, 1.0]$  and  $y \in [0.0, \pi]$ , using  $n_x = n_y = 100$ .

Table 3: Double Integral Comparison (Problem 1.3)

Method	Integral Value
Scratch Implementation	1.0000000000
SciPy Verification	1.0000000000

**Discussion (1.3):** The result from the scratch implementation agrees exactly with the SciPy reference, validating the accuracy of the numerical Midpoint Rule.

## 5 Conclusion

The assignment successfully implemented the core numerical tools of multivariable calculus. The high precision achieved across all verification steps confirms a strong foundational understanding of how these mathematical concepts are translated into computational algorithms essential for AI.