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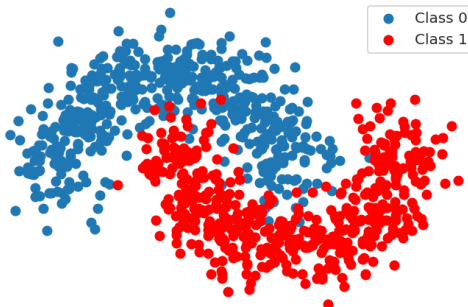
DATA SCIENCE &
SCIENTIFIC COMPUTING

Predicting Smart Grid Stability with Probabilistic Machine Learning Models.

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 - 'stabf': a categorical (binary) label ('stable' or 'unstable').



- A Gaussian process (GP) for regression is a random process where any point $\mathbf{x} \in \mathbb{R}^d$ is assigned a random variable $f(\mathbf{x})$ and where the joint distribution of a finite number of these variables $p(f(\mathbf{x}_1), \dots, f(\mathbf{x}_N))$ is itself Gaussian:

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- A GP is a prior over functions whose shape (smoothness, ...) is defined by $K = \kappa(X, X)$ where κ is a parametric kernel function.
- Given observed noisy function values y at points X we want to predict a noise-free function value f_* at point x_* . The joint distribution of observed values y and prediction f_* is also a Gaussian:



$$p(y, f_* \mid X, x_*) = \mathcal{N} \left(\begin{pmatrix} y \\ f_* \end{pmatrix} \middle| 0, \begin{pmatrix} K_y & k_* \\ k_*^T & k_{**} \end{pmatrix} \right) \quad (2)$$

where $K_y = K + \sigma_y^2 I$, $k_* = \kappa(X, x_*)$ and $k_{**} = \kappa(x_*, x_*)$. σ_y^2 models noise in the observed function values y .



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- Turning the joint distribution (2) into a conditional distribution we obtain a predictive distribution:

$$p(f_* | x_*, X, y) = \mathcal{N}(f_* | \mu_*, \Sigma_*) \quad (3)$$

with

$$\begin{aligned} \mu_* &= k_*^T K_y^{-1} y \\ \Sigma_* &= k_{**} - k_*^T K_y^{-1} k_* \end{aligned} \quad (4)$$



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- The predictive distribution can be defined as:

$$p(t_* = 1 \mid \mathbf{t}, x_*, X) = \int p(t_* = 1 \mid f_*) p(f_* \mid \mathbf{t}, x_*, X) df_* \quad (5)$$

$$p(f_* \mid \mathbf{t}, x_*, X) = \int p(f_* \mid f, x_*, t) p(f \mid \mathbf{t}, X) df \quad (6)$$

Where $p(f \mid \mathbf{t}, X)$ can be approximated with a Gaussian distribution $q(f)$ using the Laplace approximation, minimising the KL divergence.



$$q(\mathbf{f}) = \mathcal{N}(\mathbf{f} \mid \hat{\mathbf{f}}, \mathbf{H}^{-1}) \quad (7)$$

where $\mathbf{H} = \mathbf{W} + \mathbf{K}_f^{-1}$. \mathbf{W} is a diagonal matrix with elements $\sigma(f_n)(1 - \sigma(f_n))$ with f_n being the elements of \mathbf{f} . Written in vector notation the diagonal is $\boldsymbol{\sigma}(1 - \boldsymbol{\sigma})$.



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- The mean $\hat{\mathbf{f}}$ can be obtained iteratively with the following update equation:

$$\mathbf{f}^{\text{new}} = \mathbf{K}_f(\mathbf{I} + \mathbf{W}\mathbf{K}_f)^{-1}(\mathbf{t} - \boldsymbol{\sigma} + \mathbf{W}\mathbf{f}) \quad (8)$$

At convergence $\hat{\mathbf{f}} = \mathbf{f}^{\text{new}}$.



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At convergence $\hat{\mathbf{f}} = \mathbf{f}^{\text{new}}$.

- The Gaussian approximation of $p(\mathbf{f}_* \mid \mathbf{t})$ is therefore given by

$$p(\mathbf{f}_* \mid \mathbf{t}) \approx \mathcal{N}(\mathbf{f}_* \mid \mu_{\mathbf{f}_*}, \sigma_{\mathbf{f}_*}^2) \quad (9)$$



with

$$\begin{aligned}\mu_{f_*} &= \mathbf{k}_*^T (\mathbf{t} - \boldsymbol{\sigma}) \\ \sigma_{f_*}^2 &= k_{**} - \mathbf{k}_*^T (\mathbf{W}^{-1} + \mathbf{K}_f)^{-1} \mathbf{k}_*\end{aligned}\tag{10}$$

Finally, $p(t_* = 1 \mid f_*)$ in Equation (4) is approximate with the inverse probit function $\Phi(f_*)$ so that the predictive distribution can be approximated with:

$$p(t_* = 1 \mid \mathbf{t}) \approx \sigma(\mu_{f_*} (1 + \pi \sigma_{f_*}^2 / 8)^{-1/2})\tag{11}$$



- It is a Naive Bayes classifier with the likelihood of the features is assumed to be Gaussian:

$$P(x_i | C) = \frac{1}{\sqrt{2\pi\sigma_C^2}} \exp\left(-\frac{(x_i - \mu_C)^2}{2\sigma_C^2}\right) \quad (12)$$



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- The parameters σ_C and μ_C are estimated using maximum likelihood



- In logistic regression, parameters (weight and bias) are learned by maximum likelihood



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- Prior on parameters w and b



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- Family of distributions
- Find an approximate posterior distribution from this family that has the lowest KL divergence from the true posterior.

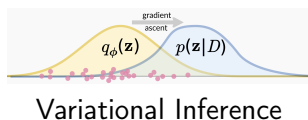


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- Objective: minimize the KL-divergence from the approximate posterior to the true posterior



$$\begin{aligned} \text{KL}[q_\phi(z) \| p(z|D)] &= \int q_\phi(z) \log \frac{q_\phi(z)}{p(z|D)} \\ &= \mathbb{E}_{q_\phi(z)} [\log q_\phi(z) - \log p(z|D)] \end{aligned} \quad (13)$$



- We can't directly optimize (minimize) the KL divergence, instead we optimize (maximize) the ELBO: Evidence Lower Bound with respect to the variational parameters

$$\text{ELBO} \equiv \mathbb{E}_{q_{\phi}(z)} [\log p_{\theta}(z, D) - \log q_{\phi}(z)] \quad (14)$$

$$\mathbb{E}_{q_{\phi}(z)} [\log q_{\phi}(z) - \log p(z|D)] = \mathbb{E}_{q_{\phi}(z)} [\log p_{\theta}(z, D) - \log q_{\phi}(z)] + [\log p(D)] \quad (15)$$

$$\text{KL divergence} = -\text{ELBO} + \text{Evidence} \quad (16)$$



- Artificial Neural Network: train network parameters as point estimates



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- Bayesian Neural Network:



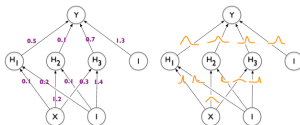
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Bayesian Neural Networks

- Artificial Neural Network: train network parameters as point estimates
- Bayesian Neural Network:
 - Model uncertainty in network parameters
 - Prior over parameters represented with probability distribution
 - Posterior of parameters given dataset is approximated using the stochastic variational inference



Weights in ANN Vs. BNN



- we split the data into test data, training data, and validation data to train the BNN method and others. The validation data will be used to track the bias-variance tradeoff in our models.

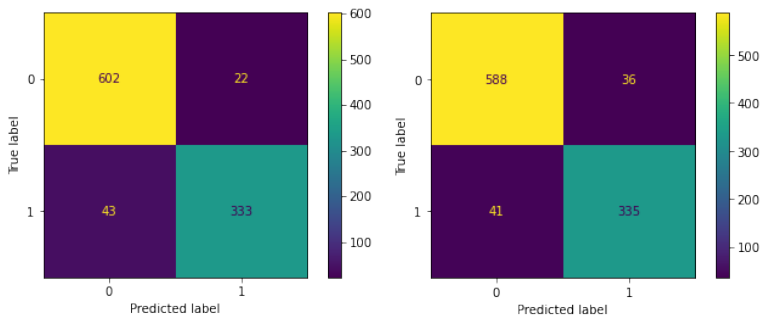


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- To train the Gaussian Process classifier, we select the first 1000 samples and the last 1000 samples for the test. the same test data will be used to evaluate all of our models.



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- To train the Gaussian Process classifier, we select the first 1000 samples and the last 1000 samples for the test. the same test data will be used to evaluate all of our models.
- We perform Cross-Validation to choose the best kernel for the Gaussian process classification.

Gaussian Process result



a) RBF kernel b) Rational Quadratic kernel

Figure: Confusion matrix

Gaussian Process Performance Metrics



	precision	recall	f1-score	support
unstable	0.93	0.96	0.95	624
stable	0.94	0.89	0.91	376
Best Mean Accuracy: 0.937				
Best Config: {'kernel': 1**2 * RationalQuadratic(alpha=1, length_scale=1)}				
>0.628 with: {'kernel': 1**2 * RBF(length_scale=1)}				
>nan with: {'kernel': 1**2 * DotProduct(sigma_0=1)}	accuracy		0.94	1000
>0.905 with: {'kernel': 1**2 * Matern(length_scale=1, nu=1.5)}	macro avg	0.94	0.93	1000
>0.937 with: {'kernel': 1**2 * RationalQuadratic(alpha=1, length_scale=1)}	weighted avg	0.94	0.93	1000
>0.628 with: {'kernel': 1**2 * WhiteKernel(noise_level=1)}				

a) Cross-Validation b) Classification report using RBF kernel

	precision	recall	f1-score	support
unstable	0.93	0.94	0.94	624
stable	0.90	0.89	0.90	376
accuracy			0.92	1000
macro avg	0.92	0.92	0.92	1000
weighted avg	0.92	0.92	0.92	1000

c) Classification report using RQ kernel

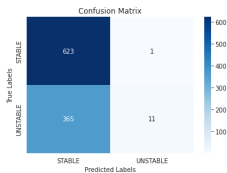
Bayesian Logistic Regression Result

Classification Report:

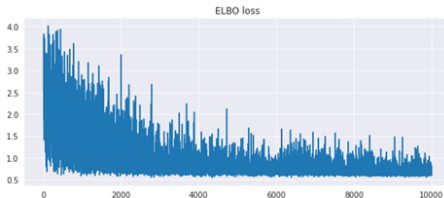
	precision	recall	f1-score	support
1	0.9167	0.0293	0.0567	376
0	0.6306	0.9984	0.7730	624
accuracy			0.6340	1000
macro avg	0.7736	0.5138	0.4148	1000
weighted avg	0.7381	0.6340	0.5036	1000

Activate Windows

a) Classification Report



b) Confusion Matrix

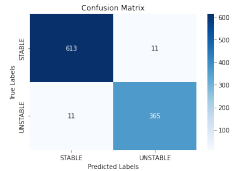


c) ELBO loss

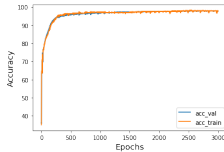
Artificial Neural Network Result

Classification Report:

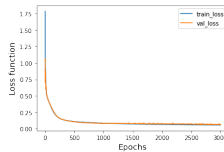
	precision	recall	f1-score	support
1	0.9707	0.9707	0.9707	376
0	0.9824	0.9824	0.9824	624
accuracy			0.9780	1000
macro avg	0.9766	0.9766	0.9766	1000
weighted avg	0.9780	0.9780	0.9780	1000



a) Classification Report b) Confusion Matrix



c) Accuracy



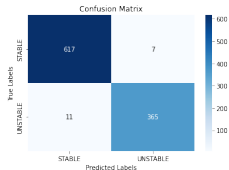
d) Loss function

Figure: 1 hidden layer

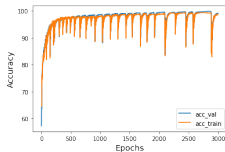
Artificial Neural Network Result

Classification Report:

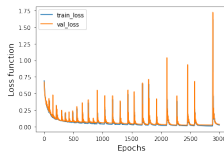
	precision	recall	f1-score	support
1	0.9812	0.9707	0.9759	376
0	0.9825	0.9888	0.9856	624
accuracy			0.9820	1000
macro avg	0.9818	0.9798	0.9808	1000
weighted avg	0.9820	0.9820	0.9820	1000



a) Classification Report b) Confusion Matrix



c) Accuracy



d) Loss function

Figure: 3 hidden layers

Parameters of Bayesian Neural Network

```
[191] model = nn.Sequential(  
    bnn.BayesLinear(prior_mu=0, prior_sigma=0.1, in_features=12, out_features=100),  
    nn.ReLU(),  
    bnn.BayesLinear(prior_mu=0, prior_sigma=0.1, in_features=100, out_features=2),  
)  
  
[192] ce_loss = nn.CrossEntropyLoss()  
kl_loss = bnn.BKLLoss(reduction='mean', last_layer_only=False)  
kl_weight = 0.01  
  
optimizer = optim.Adam(model.parameters(), lr=0.005)
```

a) 1 hidden layer

```
6) model = nn.Sequential(  
    bnn.BayesLinear(prior_mu=0, prior_sigma=0.1, in_features=12, out_features=200),  
    nn.ReLU(),  
    bnn.BayesLinear(prior_mu=0, prior_sigma=0.1, in_features=200, out_features=100),  
    nn.ReLU(),  
    bnn.BayesLinear(prior_mu=0, prior_sigma=0.1, in_features=100, out_features=50),  
    nn.ReLU(),  
    bnn.BayesLinear(prior_mu=0, prior_sigma=0.1, in_features=50, out_features=2),  
)  
  
7) ce_loss = nn.CrossEntropyLoss()  
kl_loss = bnn.BKLLoss(reduction='mean', last_layer_only=False)  
kl_weight = 0.01  
  
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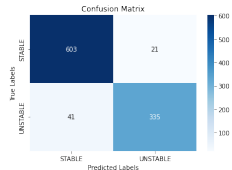
b) 3 hidden layers

Figure: BNN parameters

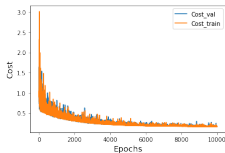
Bayesian Neural Network Result

Classification Report:

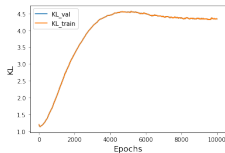
	precision	recall	f1-score	support
1	0.9410	0.8910	0.9153	376
0	0.9363	0.9663	0.9511	624
accuracy			0.9380	1000
macro avg	0.9387	0.9287	0.9332	1000
weighted avg	0.9381	0.9380	0.9376	1000



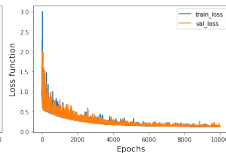
a) Classification Report b) Confusion Matrix



c) Cost function



d) KL



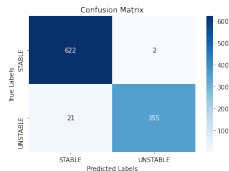
e) Loss function

Figure: 1 hidden layer

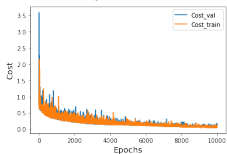
Bayesian Neural Network Result

Classification Report:

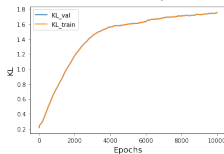
	precision	recall	f1-score	support
1	0.9944	0.9441	0.9686	376
0	0.9673	0.9968	0.9818	624
accuracy			0.9770	1000
macro avg	0.9809	0.9705	0.9752	1000
weighted avg	0.9775	0.9770	0.9769	1000



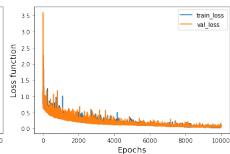
a) Classification Report b) Confusion Matrix



c) Cost function



d) KL



e) Loss function

Figure: 3 hidden layers

Comparison of Predictive Accuracy using Different Techniques

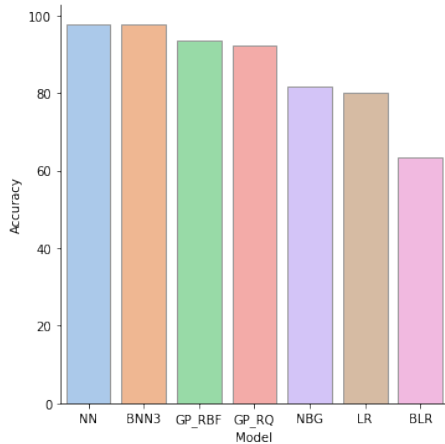


Figure: Comparison of Predictive Accuracy using Different Techniques

Comparison of Predictive Accuracy using Different Techniques



Table: Comparison of Predictive Accuracy using Different Techniques

Prediction model	Test accuracy %
GP RBF	93.5
GP RQ	92.3
NN with one hidden layer	97.8
NN with 3 hidden layer	98.2
BNN with one hidden layer	(90.5, 95.3)
BNN with 3 hidden layer	(95.2, 98.6)
NB Gaussian	81.7
LR	80
BLR	63.4

Comparison of Predictive Accuracy using Different KL weight



Table: Comparison of predictive accuracy for different KL weight (inspire from Bowman et al. 2016 work) using BNN with 1 hidden layers.

KL weight	Test accuracy %	epoch
1	(37.6, 74.7)	3000
0.5	(58.3, 77.5)	3000
0.05	(85.5, 93.0)	3000
0.01	(82.8, 92.4)	3000
0.01	(90.5, 95.3)	10000

- For higher values of KL weight, we obtained a decreasing KL value. However, we get a low accuracy and the model tends to overfit.

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0.01	(82.8, 92.4)	3000
0.01	(90.5, 95.3)	10000

- For higher values of KL weight, we obtained a decreasing KL value. However, we get a low accuracy and the model tends to overfit.
- As we decrease the KL weight, we get an increasing KL value. The accuracy gets better, and our model learns from the data.

Comparison of Predictive Accuracy to previous work



The following table done by Paulo Breviglieri 2021 present the comparison of prediction accuracy using different techniques.

Prediction method	Accuracy (%)	Used system
XGBoost [23]	97.8	IEEE 39-bus test system
Bayesian rate (BR) [24]	91.6	IEEE 39-bus test system
DT [25]	90.3	IEEE 39-bus test system
CNN [26]	89.22	IEEE 118-bus and IEEE 145-bus systems
Long Short Term Memory (LSTM) [27]	99.98	IEEE 39-bus test system and 162 and 145 bus systems
FNN-based transient stability predictor [28]	99.2	IEEE 39-bus test system
CART [4]	80.0	4-node star architecture
Proposed	99.62	4-node star architecture





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- The hyperparameters in the Bayesian Neural Networks plays an important role on how the model learn the data. Analysis of hyperparameters tuning would give more insight on the power of Bayesian Neural Networks.
- Implementation could be done on an HPC system which could help in obtaining reliable and more accurate results.

-  Bowman, Samuel R. et al. (2016). "Generating Sentences from a Continuous Space". In.
-  Paulo Breviglieri Türkücan Erdem, Süleyman Eken (2021). "Predicting Smart Grid Stability with Optimized Deep Models". In: *SN Computer Science*, pp. 293–298. DOI: <https://doi.org/10.1007/s42979-021-00463-5>.



Thank you for your kind attention