Fattah Hanafi

Robotics Engineer

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Profile

I am a Robotics Engineer with over a decade of extensive experience in mechanical analysis and software development for robotics applications. Throughout my career, I have held several positions where I designed and developed a wide range of robots, including industrial-grade 6DOF serial manipulators, 2500kg Stewart platforms, and mobile construction excavators. Most of the products I was involved in were designed as commercial products with tight deadlines and resulted in successful, profitable products. I have also demonstrated my ability to manage robotics teams, as seen in my previous role as robotics team manager at Hamgar Toos. My enthusiasm, professionalism, expertise, and experience in both mechanical and software development make me a valuable resource for your company.

Experience

Research Assistant
AVEC Lab - (2021-now)

- Utilized C++ programming to develop and implement real-time applications on a dSpace embedded controller, enabling autonomous control of mobile excavators at construction sites.
- Designed and implemented a real-time perception algorithm that effectively combines LiDAR and depth camera sensor data to capture and analyze the surrounding environment using PCL and OpenCV.
- Created a customized ROS2 package to provide comprehensive visualization, monitoring, and control capabilities for the excavators.
- Developed a customized GUI software using OpenGL to establish communication with an embedded controller via UDP, enabling comprehensive control of excavator operations.
- Developed a Python program capable of real-time route optimization in obstacle-filled environments, enhancing operational efficiency.

Engineering Team Manager
C1-Tech - (2017-2021)

- Designed and developed an advanced automation panel for surgery operation rooms, enabling centralized control of temperature, lighting, humidity, curtains, and inter-communication systems.
- Successfully marketed and sold the developed automation panel to seven hospitals, resulting in installations across more than 60 operation rooms.

Robotics Team Manager
Hamgar Toos Co. - (2016-2018)
FUM Robotics Lab - (2012-2016)

- Designed, analyzed, and developed C++ software on Beckhoff controller for a range of industrial-grade robots, including models such as FUM-6R-20, FUM-SCARA-V2, FUM-Stewart-M450, FUM-Stewart-2500kg, and FUM-Delta.
- Conducted kinematics and dynamics analysis, as well as simulation verification, for ten distinct industrial-grade serial and parallel robots, utilizing tools such as SolidWorks Motion, Simulink, and MATLAB.
- Developed trajectory generation algorithms specific to each robot, ensuring precise and efficient motion planning.
- Devised a vision-based calibration process to enhance the accuracy and calibration of the robots.
- Led a team of ten mechanical and software engineers in the development of a real-time software system from scratch, which encompassed program parsing, motion generation, interrupt handling, and IO control for the robots.
- Employed various communication protocols, including CANOpen, EtherCAT, Profibus, and RS-485, to effectively control different servo drives.

Education

Ph.D. in Mechanical Engineering
OntarioTech University - (2021-now)

- Autonomous excavators on construction sites. Perception, control, motion-planning, and safety.

M.Sc. in Mechanical Engineering
Ferdowsi University - (2010-2013)

- A real-time method to calculate the inverse dynamics equations of a three DOF parallere 3-PSP robot.

B.Sc. in Mechanical Engineering
Islamic Azad University - (2007-2009)

- Developed a multi-DOF four-bar mechanism to follow the desired trajectory.

Skills

Technical Skills

C/C++	★★★★★
ROS2	★★★★★
SolidWorks	★★★★★
Linux	★★★★☆
Git	★★★★☆

Technical Skills

MATLAB	★★★★☆
Embedded Systems	★★★★☆
Python	★★★☆☆
OpenGL	★★★☆☆

Soft Skills

Teamwork	★★★★★
Creative Thinking	★★★★★
Project Management	★★★★★
Leadership	★★★★☆
Strategic Planning	★★★☆☆