

# An Al for Game Tokkun'99

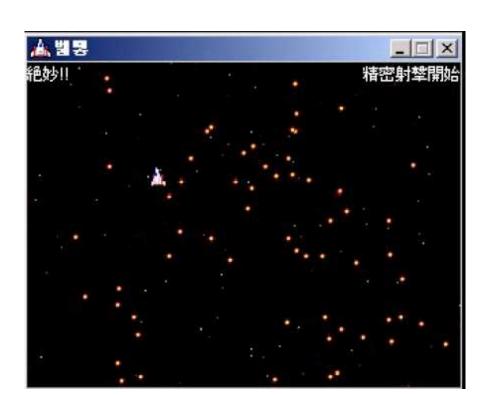
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## Introduction

### The Game

- Tokkun'99 is a game which requires quick reactions and thus challenging for human players.
- The objective for the player is to control the airplane to go along eight directions on a 2D map in order to dodge bullets.
- Most bullets move in a straight line with constant velocity, but some special ones can follow the agent (player), move along a parabola, or move at high speed.
- Once player is hit by any of the bullets, the game ends.





Screenshots of the Tokkun'99 Game

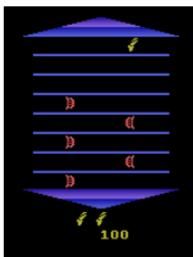
# Challenges

- To speed up the training, need to implement a game simulator to run in headless mode and return useful information
- Need to experiment and figure out which features are most useful to make the Al as good as or even better than an average human player

### **Related Work**

- M. G. Bellemare, Y. Naddaf, et al. "The arcade learning environment: An evaluation platform for general agents," J. Artif. Intell. Res., vol. 47, pp. 253–279, 2013.
- V. Mnih, K. Kavukcuoglu, et al., "Playing atari with deep reinforcement learning," in NIPS Deep Learning Workshop, 2013.
- V. Mnih, K. Kavukcuoglu, et al. "Human-level control through deep reinforcement learning," Nature, vol. 518, no. 7540, pp. 529–533,
- V. Mnih, A. P. Badia, et al. "Asynchronous methods for deep reinforcement learning," in International Conference on Machine Learning, 2016, pp. 1928–1937.



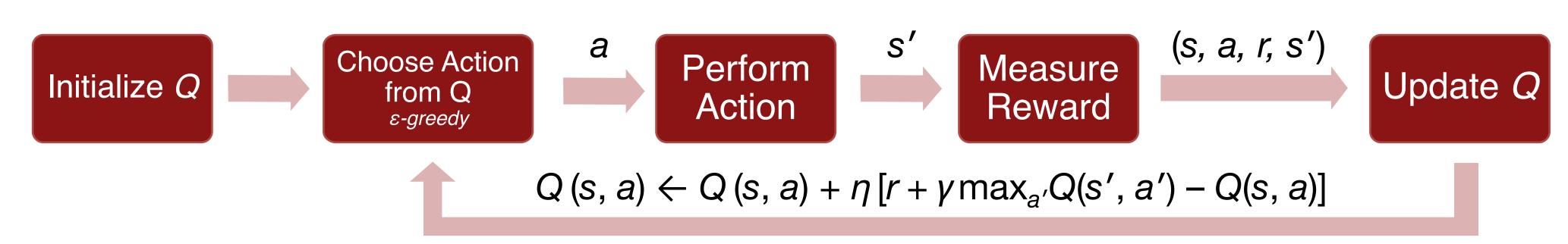






# Methods

## Framework – Q Learning



## **Q-Function Estimation**

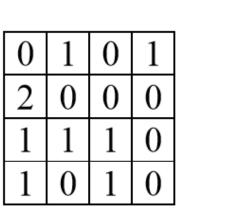
### A. Feature Extraction + Linear / Neural Network Approximation

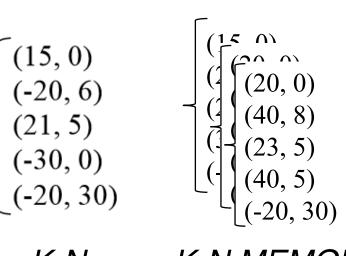
### **Features**

### **Hand-labeled Feature**

- HIST: Histogram of neighboring bullets of R\*R region in B\*B bins
- **K-N:** Relative offsets of *K* nearest bullets
- Variations of K-N:
- K-N INVERSE: K-N features including squared distance to player to highlight nearer bullets
- K-N MEMORY: Include K-N features of R recent frames to cover velocity information







# Raw Pixels

# K-N MEMORY

### **General Feature from Raw Pixels**

- Methods from (Bellamare et al., 2012) on Atari games
- BASS: Remove the background and use a 8-color palette to represent a downsampled image.
- LSH: Map raw game screens into a small set of binary features using a hashing algorithm such that similar screens have similar hashes.

## **Approximation Methods**

### **Linear Function Approximation**

Use linear combination of features to approximate Q function

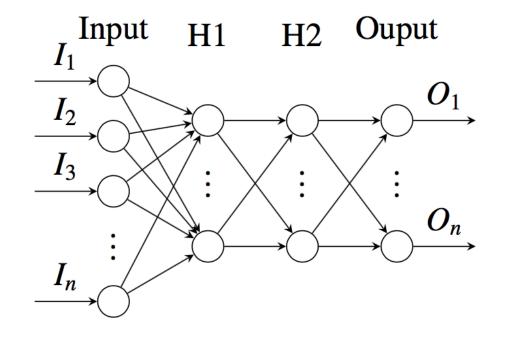
$$Q^+(s, a; \boldsymbol{\theta}) = \boldsymbol{\theta} \cdot \phi(s, a)$$

■ Train **0** using SGD:

$$\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \eta \left[ r + \gamma \max_{a'} Q^{+}(s', a'; \boldsymbol{\theta}) - \boldsymbol{\theta} \cdot \phi(s, a) \right]$$

#### **Neural Network Function Approx.**

- Train a 3-layer fully-connected neural network (multilayer perceptron) to approximate Q function
- Memorize N most recent (s, a, r, s') tuples, which are previous experiences.
- After each action taken, draw a mini-batch of previous experiences to perform the update step.



# B. Deep Q Learning

- Methods from (Mnih et al, 2013)
- Use Convolution Neural Network to estimate the Q function.
- Apart from the local memory features, we also keep a large replay memory of size **D** to save previous plays
- For each step we draw a minimatch of size B with (s, a, r, s') tuples to train the network
- In our experiments, D = 2000, B = 32

### 2nd hidden 3rd hidden layer layer layer 8x8x4 filter 84x84x4 20x20x16 4~18

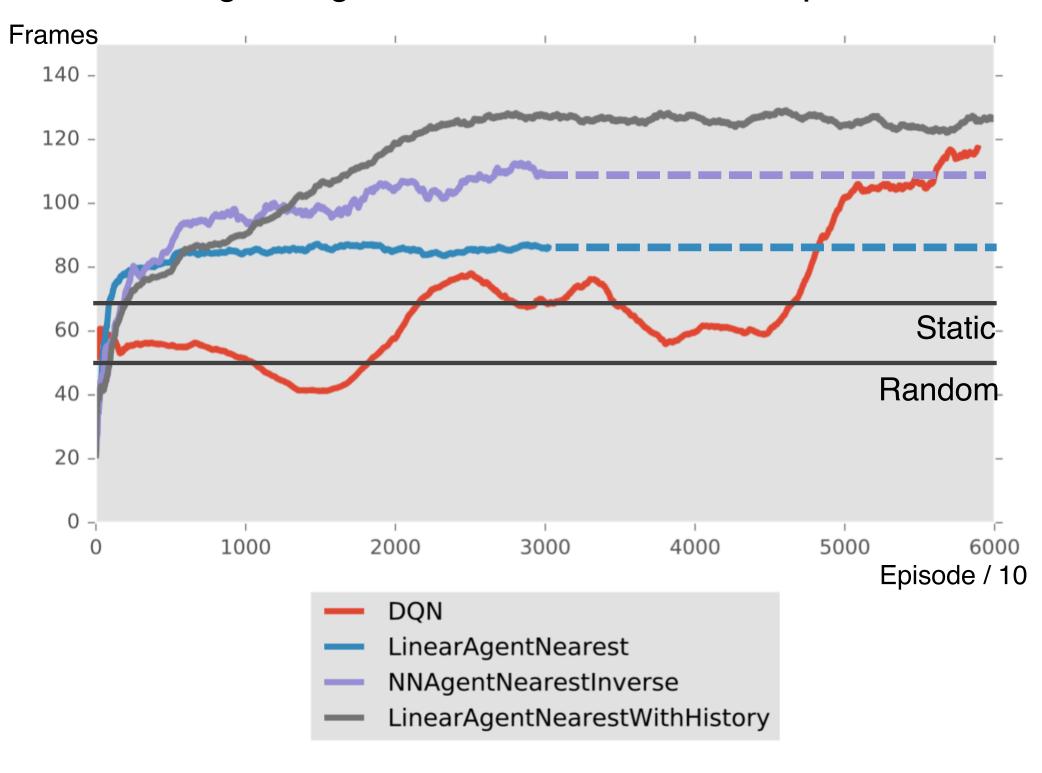
## Results

### Average # of Frames Using Different Methods

Feature	Params	Linear Approx.	3-Layer MLP
HIST	R = 25, B = 5	89.37	61.28
	R = 30, B = 6	89.34	80.50
K-N	K = 5	85.76	90.13
	INVERSE, K = 5	85.37	108.40
	MEMORY, K = 5	126.17	100.12
DQN	115.81		
Random	52.00		
Static	63.56		

### Comparison of the Top Methods

Sliding Average Frames of the Recent 1000 Episodes



Memory matters; DQN is not satisfactory

### **Future Work**

- Implement some general feature extracting methods to compare with current features
- Find the reason for Deep Q Learning's low performance
- Tune the network structure, network parameters (training η, decaying rate, etc.) and the memory parameters (D, B)
- Try Double DQN and Dueling Double DQN which have achieved better results on Atari games
- Now training and tuning is slow, try to implement methods like single-step SARSA / Q Learning and actor-critic based methods like A3C