

**Problem 1****(a)**

True, we can only do  $n-1$  times of iteration in Bellman-Ford algorithm, if it is larger than this, it has negative cycle and it is not accurate.

**(b)**

False, it can find the shortest path.

**(c)**

True, this is the rule of Floyd's algorithm.

**(d)**

True, the Dijkstra's algorithm is similar to BFS because it uses the smallest visited node and it will generate a shortest path tree. So the time complexity is the same as BFS.

**(e)**

True, because except from  $O$  and  $D$ , the flow will be conserved. So the maximum flow will be determined by these two values.

**(f)**

True, because we will update the temporary distance when we scan the next node.

**(g)**

False, first we can not judge whether Prim or Kruskal is faster because we donnot know the number of edges and vertices. Second, the time of Kruskal is  $N\log(N)$  but  $N$  is the number of edges not nodes.

**(h)**

True, the definition of the tree.

**(i)**

False,  $i$  and  $j$  will connect to other nodes, so the minimum weight connect to  $i$  and  $j$  can be that arc, not the arc between  $i$  and  $j$ .

**(j)**

True. These three are all greedy algorithms.

**Problem 2**

predecessor( $p(j)$ )	node	new distance
1	1	0
-	2	$\infty$
-	3	$\infty$
-	4	$\infty$
-	5	$\infty$
-	6	$\infty$
-	7	$\infty$
-	9	$\infty$

predecessor( $p(j)$ )	node	new distance
1	1	0
1	2	1
1	3	4
1	4	7
-	5	$\infty$
-	6	$\infty$
1	7	6
-	9	$\infty$

predecessor( $p(j)$ )	node	new distance
1	1	0
1	2	1
1	3	4
1	4	7
2	5	6
7	6	9
1	7	6
-	9	$\infty$

predecessor(p(j))	node	new distance
1	1	0
1	2	1
1	3	4
1	4	7
2	5	6
7	6	9
1	7	6
6	9	18

predecessor(p(j))	node	new distance
1	1	0
1	2	1
1	3	4
1	4	7
2	5	6
7	6	9
1	7	6
6	9	18

predecessor(p(j))	node	new distance
1	1	0
1	2	1
1	3	4
1	4	7
2	5	6
7	6	9
1	7	6
6	9	18

It will not change, so this is the final version.

**Problem 3**

initial,

node	distance
1	0
2	$\infty$
3	$\infty$
4	$\infty$
5	$\infty$
6	$\infty$
7	$\infty$
8	$\infty$
9	$\infty$
10	$\infty$
11	$\infty$

visited 1,

node	distance
1	0
2	1
3	2
4	13
5	$\infty$
6	$\infty$
7	2
8	$\infty$
9	$\infty$
10	$\infty$
11	$\infty$

visited 1, 2,

node	distance
1	0
2	1
3	3
4	13
5	6
6	$\infty$
7	2
8	$\infty$
9	$\infty$
10	$\infty$
11	$\infty$

visited 1, 2, 7,

node	distance
1	0
2	1
3	3
4	13
5	6
6	19
7	2
8	$\infty$
9	$\infty$
10	10
11	$\infty$

visited 1, 2, 7, 3,

node	distance
1	0
2	1
3	3
4	13
5	6
6	14
7	2
8	$\infty$
9	$\infty$
10	10
11	$\infty$

visited 1, 2, 7, 3, 5,

node	distance
1	0
2	1
3	3
4	13
5	6
6	10
7	2
8	20
9	21
10	10
11	$\infty$

visited 1, 2, 7, 3, 5, 6,

node	distance
1	0
2	1
3	3
4	13
5	6
6	10
7	2
8	20
9	19
10	10
11	$\infty$

visited 1, 2, 7, 3, 5, 6, 10

node	distance
1	0
2	1
3	3
4	13
5	6
6	10
7	2
8	20
9	18
10	10
11	17

visited 1, 2, 7, 3, 5, 6, 10, 4,

node	distance
1	0
2	1
3	3
4	13
5	6
6	10
7	2
8	20
9	18
10	10
11	17

visited 1, 2, 7, 3, 5, 6, 10, 4, 11,

node	distance
1	0
2	1
3	3
4	13
5	6
6	10
7	2
8	20
9	18
10	10
11	17

visited 1, 2, 7, 3, 5, 6, 10, 4, 11, 9,

node	distance
1	0
2	1
3	3
4	13
5	6
6	10
7	2
8	20
9	18
10	10
11	17

visited 1, 2, 7, 3, 5, 6, 10, 4, 11, 9, 8,

node	distance
1	0
2	1
3	3
4	13
5	6
6	10
7	2
8	20
9	18
10	10
11	17



**Problem 4**

Distance	1	2	3	4	Path	1	2	3	4
1	0	3	12	$\infty$	1	-1	-1	-1	-1
2	$\infty$	0	12	5	2	-1	-1	-1	-1
3	5	7	0	$\infty$	3	-1	-1	-1	-1
4	$\infty$	$\infty$	3	0	4	-1	-1	-1	-1

use 1 as intermediate point,

Distance	1	2	3	4	Path	1	2	3	4
1	0	3	12	$\infty$	1	-1	-1	-1	-1
2	$\infty$	0	12	5	2	-1	-1	-1	-1
3	5	7	0	$\infty$	3	-1	-1	-1	-1
4	$\infty$	$\infty$	3	0	4	-1	-1	-1	-1

use 2 as intermediate point,

Distance	1	2	3	4	Path	1	2	3	4
1	0	3	12	8	1	-1	-1	-1	2
2	$\infty$	0	12	5	2	-1	-1	-1	-1
3	5	7	0	12	3	-1	-1	-1	2
4	$\infty$	$\infty$	3	0	4	-1	-1	-1	-1

use 3 as intermediate point,

Distance	1	2	3	4	Path	1	2	3	4
1	0	3	12	8	1	-1	-1	-1	2
2	17	0	12	5	2	3	-1	-1	-1
3	5	7	0	12	3	-1	-1	-1	2
4	8	10	3	0	4	3	3	-1	-1

use 4 as intermediate point,

Distance	1	2	3	4	Path	1	2	3	4
1	0	3	11	8	1	-1	-1	4	2
2	13	0	8	5	2	4	-1	4	-1
3	5	7	0	12	3	-1	-1	-1	2
4	8	10	3	0	4	3	3	-1	-1

## Problem 5

First we need to initialize the distance from the original point  $n$  to other points and store these distances in an array  $\text{dist}[v]$ ,  $v$  is the number of vertices. The initial value from  $n$  to  $n$  will be 0 and other values will be infinity. And we need to add a counter to each vertex as  $\text{counter}[v]$ .

From original point  $n$ , we find all edges  $(n, v)$  and based on the weight, we change the value of  $\text{dist}[v]$  if  $\text{dist}[n] + \text{weight}(n, v) < \text{dist}[v]$ . If  $\text{dist}[n] + \text{weight}(n, v) = \text{dist}[v]$ , we let  $\text{counter}[v] = \text{counter}[v] + 1$ . Else, we let  $\text{counter}[v] = 1$ . Then we mark  $n$  as visited.

After this, we find the minimum value of  $\text{dist}[v]$ , we assume it as  $\text{dist}[k]$ . Also find all edges  $(k, v)$  and change the value if  $\text{dist}[k] + \text{weight}(k, v) < \text{dist}[v]$ . Then we do the same as above. Mark  $k$  as visited and do this step again.

Until all vertices are visited, we can find the shortest path to destination  $d$  and it will store in  $\text{dist}[d]$ . And we need to multiply all  $\text{counter}[v]$  through this shortest path, the result is the number of shortest path.

## Problem 6

Because you can't arrive earlier if you started later, the way is the same as Dijkstra's algorithm and it is a greedy algorithm. We just initial the time for all vertices and do it several steps we shown in Problem 5 and we can find the shortest path to each vertex. The counter part in Problem 5 can be cancelled because we donnot need it in this question.